

Coloring Mixed and Directional Interval Graphs

GD 2022, Tokyo

Grzegorz
Gutowski

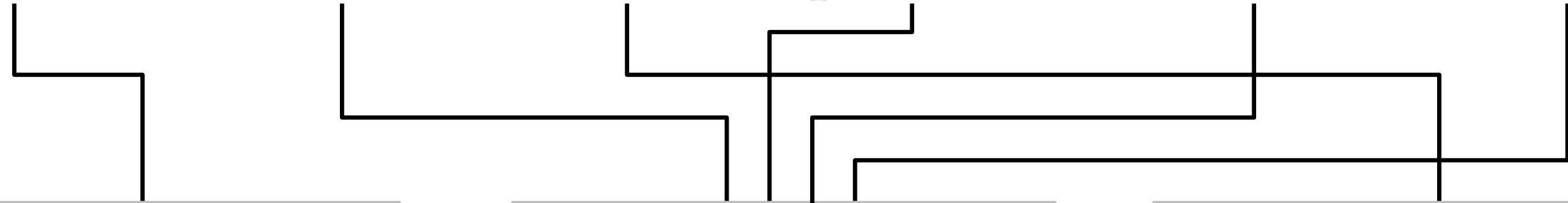
Florian
Mittelstädt

Ignaz
Rutter

Joachim
Spoerhase

Alexander
Wolff

Johannes
Zink



Uniwersytet
Jagielloński
Kraków



Motivation

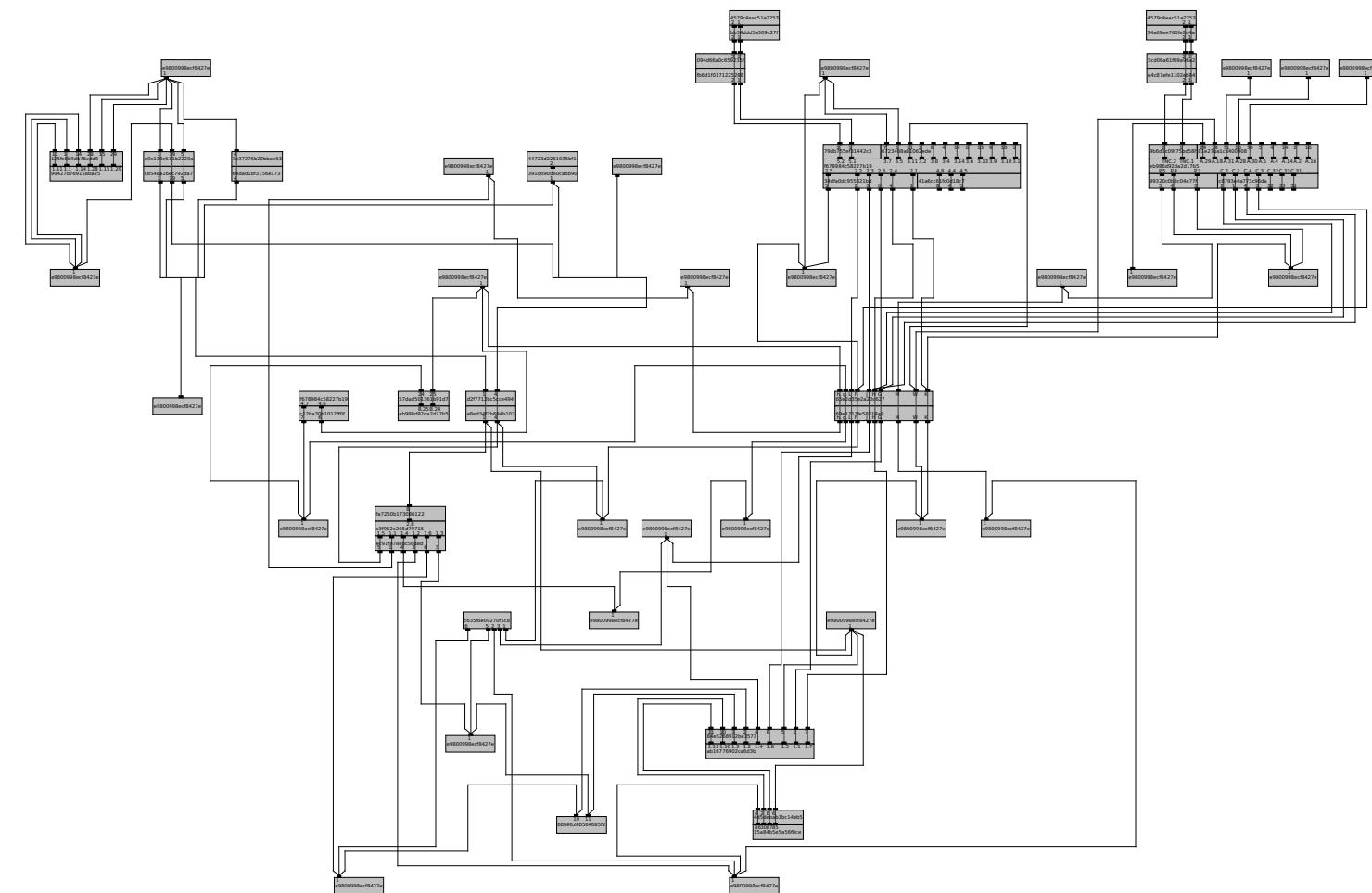
Framework for layered graphs

Input: directed graph G

Consists of five phases:

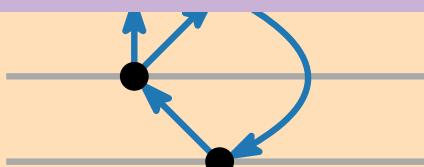
1. cycle elimination
2. layer assignment
3. crossing minimization
4. node placement

5. edge routing



cable plan

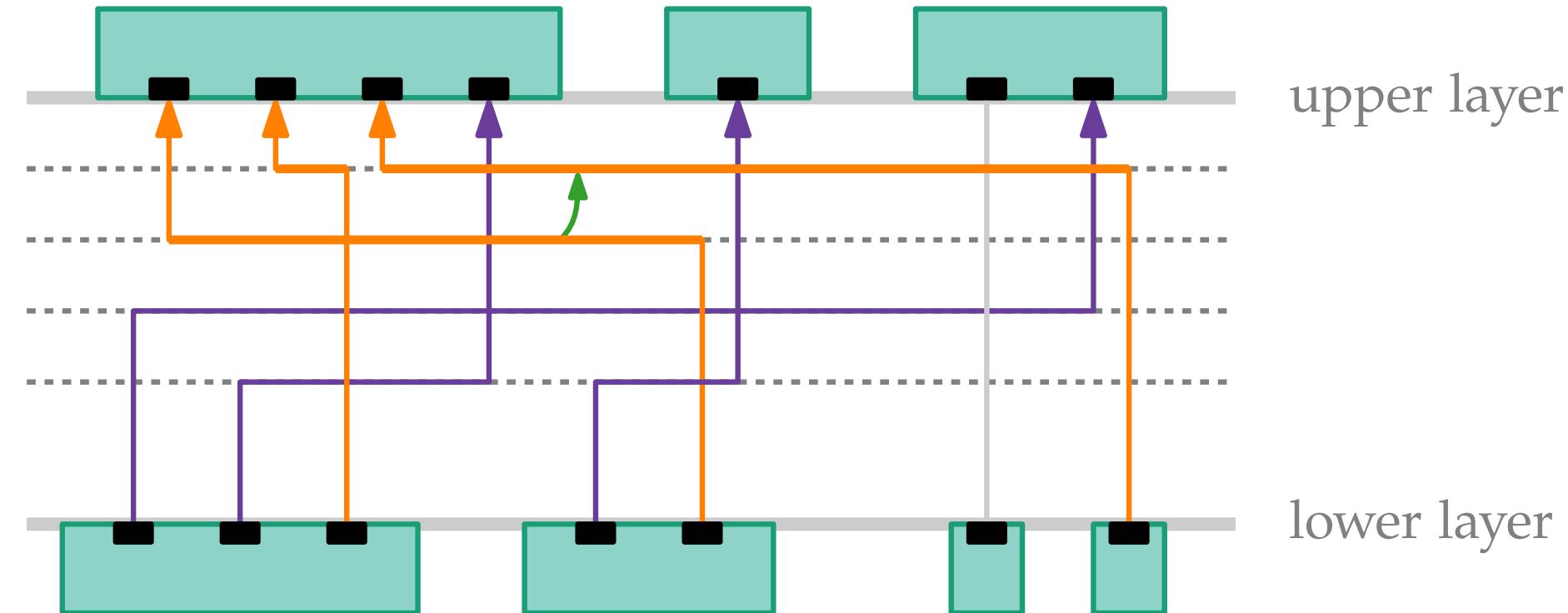
[Zink, Walter, Baumeister, Wolff; CGTA'22]



we want orthogonal edges!

Motivation – Layered Orthogonal Edge Routing

- Distinguish between *left-going* and *right-going* edges.
- Only edges going in the same direction and overlapping partially in x-dimension can cross twice.
 - ⇒ They induce a vertical order for the horizontal middle segments.

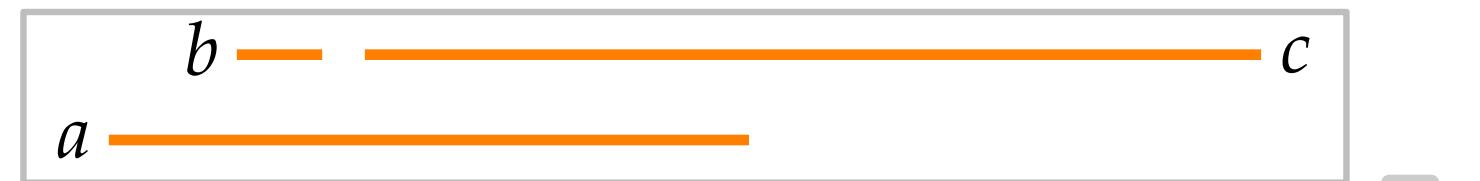


Definition – Directional Interval Graphs

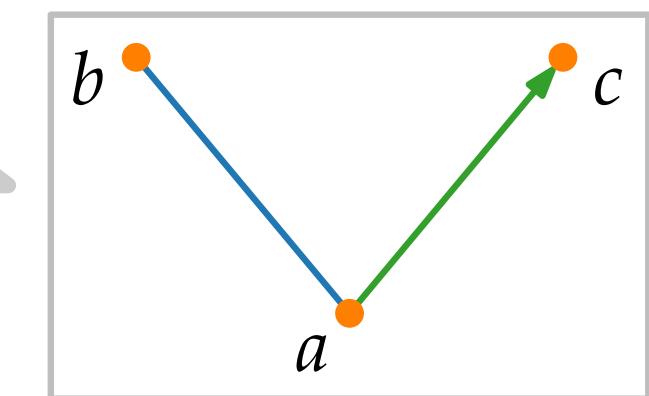
Interval representation: set of intervals

Directional interval graph:

- vertex for each interval
- undirected edge if one interval contains another
- directed edge (towards the right interval) if the intervals overlap partially



Mixed interval graph:



- vertex for each interval
- for each two overlapping intervals: undirected or arbitrarily directed edge

Coloring Mixed Graphs

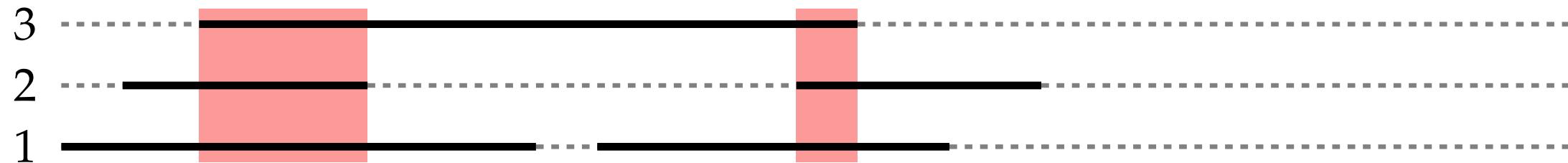
NP	<i>bipartite graphs</i>
P	<i>trees series-parallel graphs</i>

Given a graph G , find a coloring $c: V(G) \rightarrow \mathbb{N}$ s.t. [Sotskov, Tanaev '76; Hansen, Kuplinsky, de Werra '97]

- undirected edge uv : $c(u) \neq c(v)$,
- directed edge uv : $c(u) < c(v)$,
- $\max_{v \in V(G)} c(v)$ is minimized.

Interval graphs (no directed edges):

- sort by left endpoints, color greedily (in linear time given sorted intervals)



Coloring Mixed Graphs

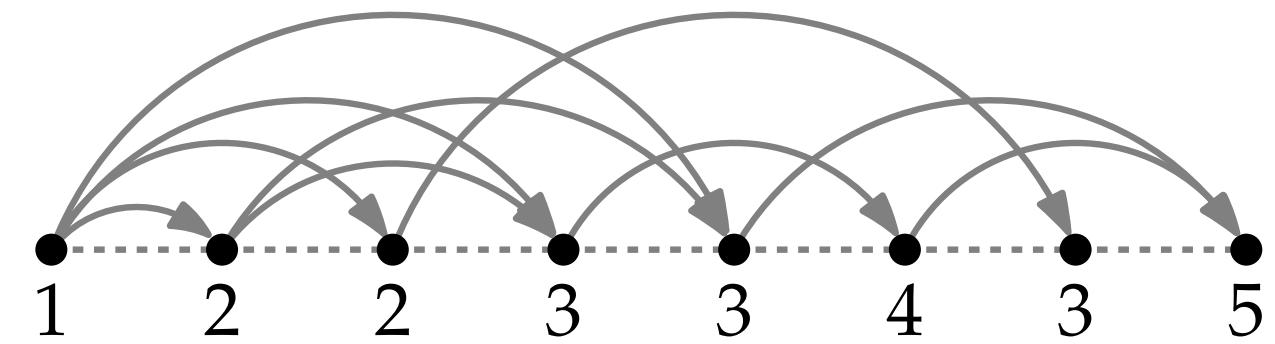
NP	bipartite graphs
P	trees series-parallel graphs

Given a graph G , find a coloring $c: V(G) \rightarrow \mathbb{N}$ s.t. [Sotskov, Tanaev '76; Hansen, Kuplinsky, de Werra '97]

- ★ undirected edge uv : $c(u) \neq c(v)$,
- ★ directed edge uv : $c(u) < c(v)$,
- ★ $\max_{v \in V(G)} c(v)$ is minimized.

Interval graphs (no directed edges):

- sort by left endpoints, color greedily (in linear time given sorted intervals)



Directed acyclic graphs (only directed edges):

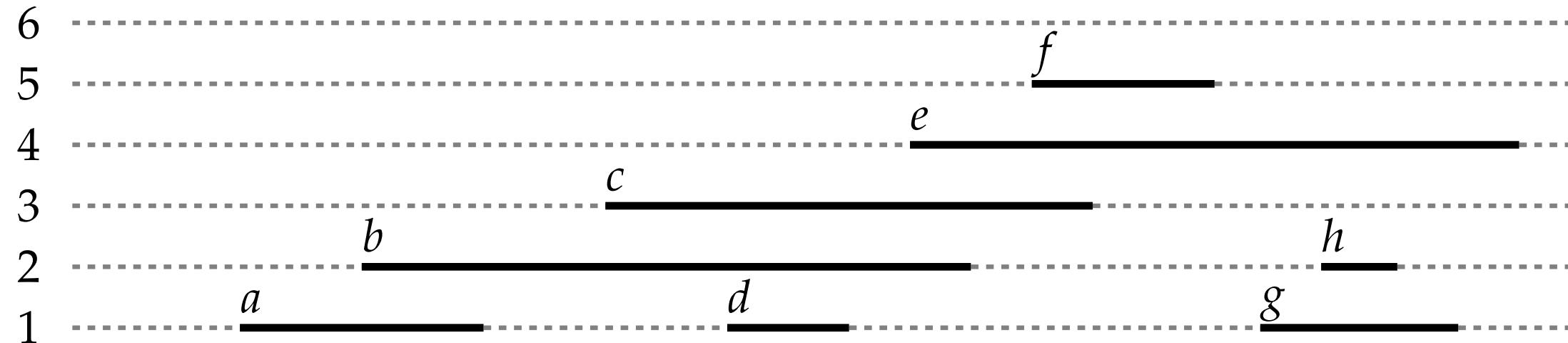
- sort topologically, color greedily (in linear time)

Coloring Directional Interval Graphs

Given: an interval representation of a directional interval graph G

GreedyColoring:

1. sort all intervals by left endpoint
2. for each interval, assign the smallest available color respecting incident edges



Coloring Directional Interval Graphs

Theorem 1:

A coloring c computed by GreedyColoring has the minimum number of colors.

Proof sketch:

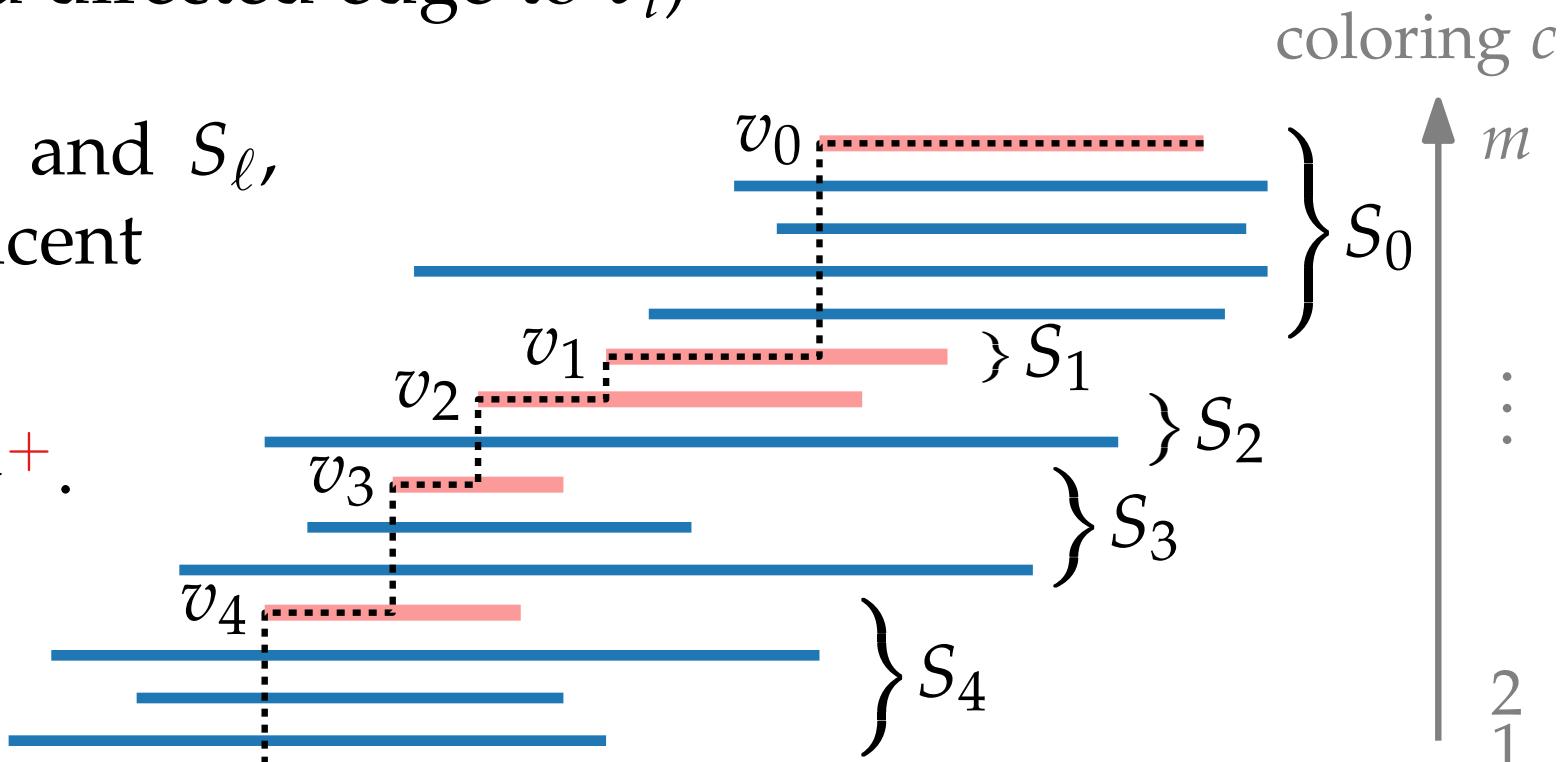
- Hence, for every step S_i , all intervals contain v_i .
(otherwise they would have a directed edge to v_i)

- **Claim:** for any two steps S_i and S_ℓ ,
every pair of intervals is adjacent
in the transitive closure G^+ .

$\Rightarrow S = \bigcup S_i$ is a clique in G^+ .

$\Rightarrow S$ alone requires
 m colors in G .

□



Proof of the Claim

Claim: Any two intervals $u \in S_i$ and $w \in S_\ell$ are adjacent in G^+ .

Proof. W.l.o.g., $u \cap w = \emptyset$ and $i < \ell$.

Let j be the largest index s.t. $v_j \cap u \neq \emptyset$.

Let k be the smallest index s.t. $v_k \cap w \neq \emptyset$.

$$\begin{array}{l} u \cap v_{i+1} \neq \emptyset \\ w \cap v_{\ell-1} \neq \emptyset \end{array} \Rightarrow \begin{array}{l} i < j < \ell \\ u \cap w = \emptyset \quad i < k < \ell \end{array}$$

By definition, $u \cap v_{j+1} = \emptyset$.

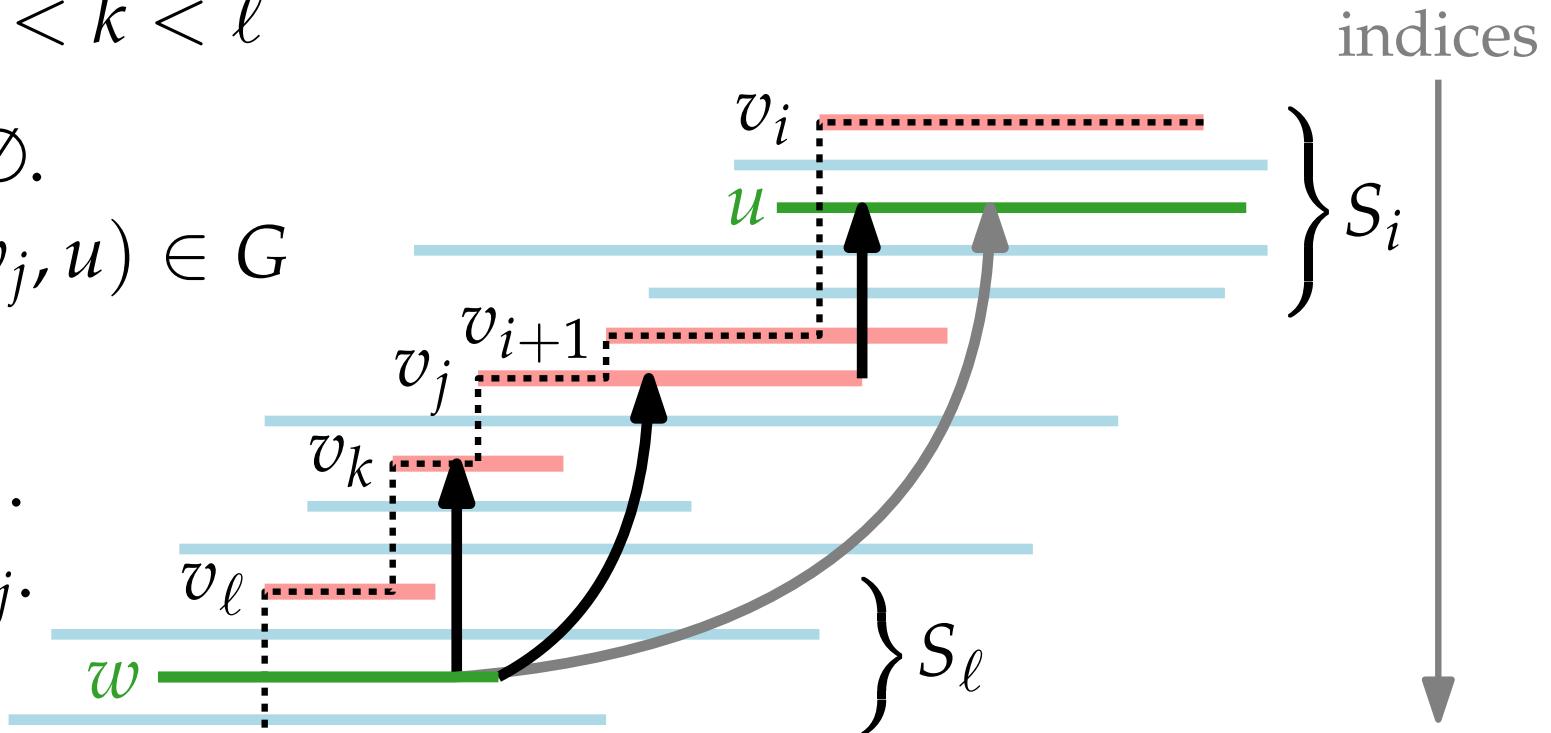
$\Rightarrow u$ and v_j overlap $\Rightarrow (v_j, u) \in G$

Similarly, $(w, v_k) \in G$.

If $j < k$, then $(v_k, v_j) \in G^+$.

If $j \geq k$, then w overlaps v_j .

Transitivity \Rightarrow claim.



Conclusion and Open Problems

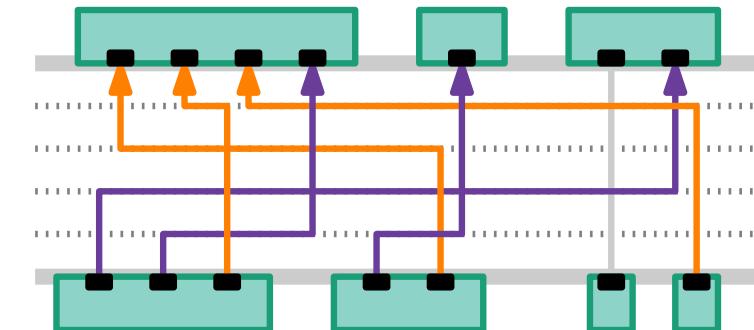


- We have introduced the natural concept of directional interval graphs.
??? Reviewer: Consider containment interval graphs!
- A simple greedy algorithm colors these graphs optimally in $O(n \log n)$ time.
 $n := \# \text{ vertices}$
- In layered graph drawing, this corresponds to routing “left-going” edges orthogonally to the fewest horizontal tracks. (Symmetrically “right-going”.)

⇒ Combining the drawings of left-going and right-going edges yields a 2-approximation for the number of tracks. (bidirectional interval graphs)

can we do better?

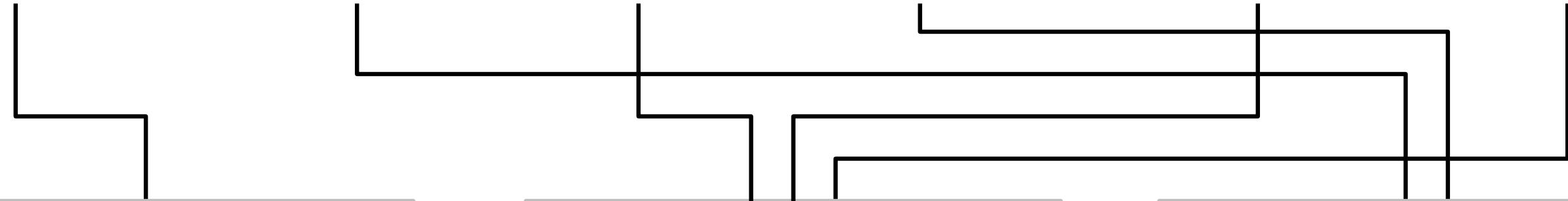
- In our paper, we present a constructive $O(n^2)$ -time algorithm for recognizing directional interval graphs, which is based on PQ-trees.
bidirectional?
- For the more general case of mixed interval graphs, coloring is NP-hard.
(Remark: NP-hardness requires both directed and undirected edges.)



Coloring and Recognizing Mixed Interval Graphs

ISAAC 2023, Kyoto

Grzegorz Konstanty Felix Paweł Alexander Johannes
Gutowski Szaniawski Klesen Rzążewski Wolff Zink



Uniwersytet
Jagielloński
Kraków



Some Observation about Interval Containment Graphs



Let \mathcal{I} be a set of intervals. Let $G = \mathcal{C}[\mathcal{I}]$ be the containment graph induced by \mathcal{I} . Let $M(\mathcal{I})$ be the set of inclusion-wise maximum elements in \mathcal{I} .

Then $\mathcal{C}[M(\mathcal{I})]$ is a *proper* interval graph – no interval contains another interval.

Also note that $\bigcup M(\mathcal{I}) = \bigcup \mathcal{I}$.

Let R be an inclusion-wise minimal subset of $M(\mathcal{I})$ such that $\bigcup R = \bigcup \mathcal{I}$.

Claim. $\mathcal{C}[R]$ is an undirected linear forest.

Proof. $\mathcal{C}[R]$ is proper \Rightarrow contains no induced $K_{1,3}$ and no induced C_ℓ for $\ell \geq 4$.

It remains to show that $\mathcal{C}[R]$ contains no triangle. ✓

A 2-Approximation Algorithm for Coloring

Theorem. For any set \mathcal{I} of intervals, the graph $\mathcal{C}[\mathcal{I}]$ admits a coloring with at most $2 \cdot \overbrace{\omega(\mathcal{C}[\mathcal{I}])}^{\omega = \text{clique number}} - 1$ colors.

Since $\mathcal{C}[R]$ is a linear forest, it admits a coloring $f_1: R \rightarrow \{1, 2\}$.

If $R = \mathcal{I}$, we are done (using only ω many colors), so we assume $\mathcal{I} \setminus R \neq \emptyset$.

Let $G' := \mathcal{C}[\mathcal{I} \setminus R]$.

Claim. $\omega(G') \leq \omega - 1$.

Proof. Suppose that there is a clique S in G' of size ω .

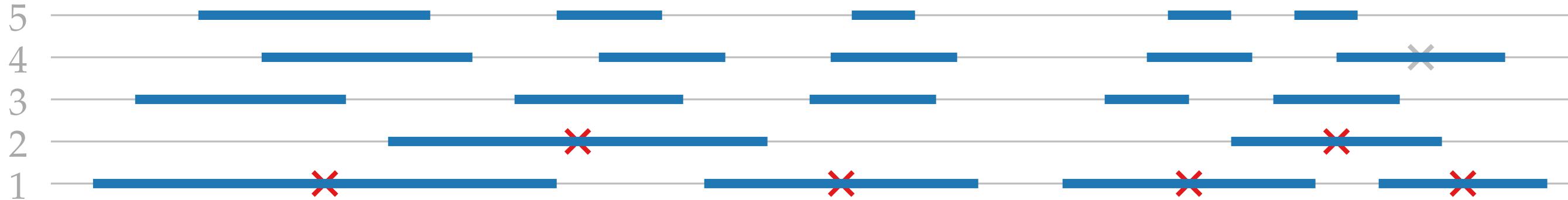
Helly property of intervals $\Rightarrow \bigcap S \neq \emptyset$. Let $p \in \bigcap S$.

Pick an $r \in R$ that contains p . $\Rightarrow S \cup \{r\}$ is a clique of size $\omega + 1$ in G . 

Induction $\Rightarrow G'$ admits a coloring f_2 using at most $2 \cdot \omega(G') - 1$ colors.

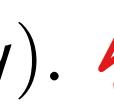
With f_1 and f_2 , we construct a coloring f of G using colors $\{1, \dots, 2\omega - 1\}$.

An Inductive Coloring



Let $f(x) = \begin{cases} f_1(x) & \text{if } x \in R, \\ f_2(x) + 2 & \text{else.} \end{cases}$

This defines a coloring of G :

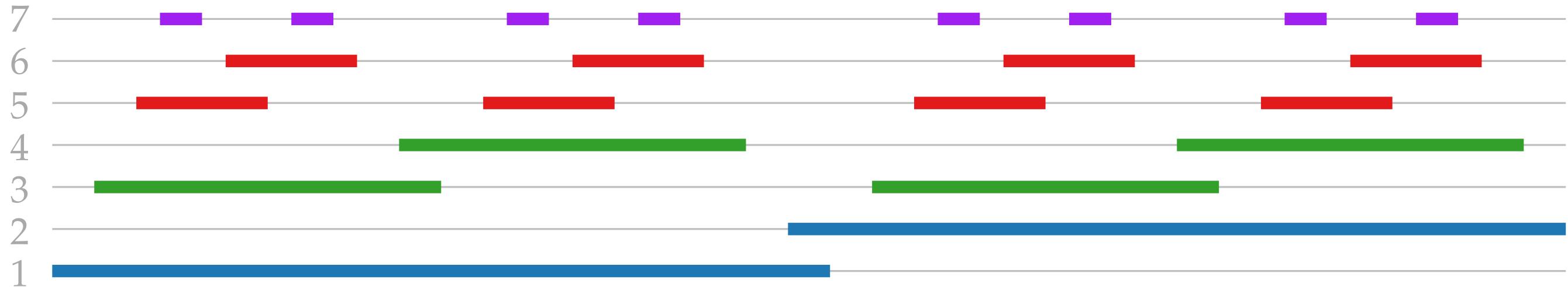
1. If $x \cap y \neq \emptyset$, then $f(x) \neq f(y)$. Check: $x, y \in R$; $x, y \neq R$; $x \in R$ and $y \neq R$.
2. If $x \subseteq y$, then $f(x) > f(y)$. Observe that $x \neq R \Rightarrow f(x) \geq 3$
Suppose $f(y) > f(x) \Rightarrow y \neq R$, but $f_2(x) > f_2(y)$. 

Corollary. There is a 2-approximation for coloring interval containment graphs.
Given n intervals, the algorithm runs in $O(n \log n)$ time.

A Lower Bound Example

Proposition. There is an infinite family $(\mathcal{I}_n)_{n \geq 1}$ of sets of intervals with $|\mathcal{I}_n| = 3 \cdot 2^{n-1} - 2$, $\chi(\mathcal{C}[\mathcal{I}_n]) = 2n - 1$, and $\omega(\mathcal{C}[\mathcal{I}_n]) = n$.

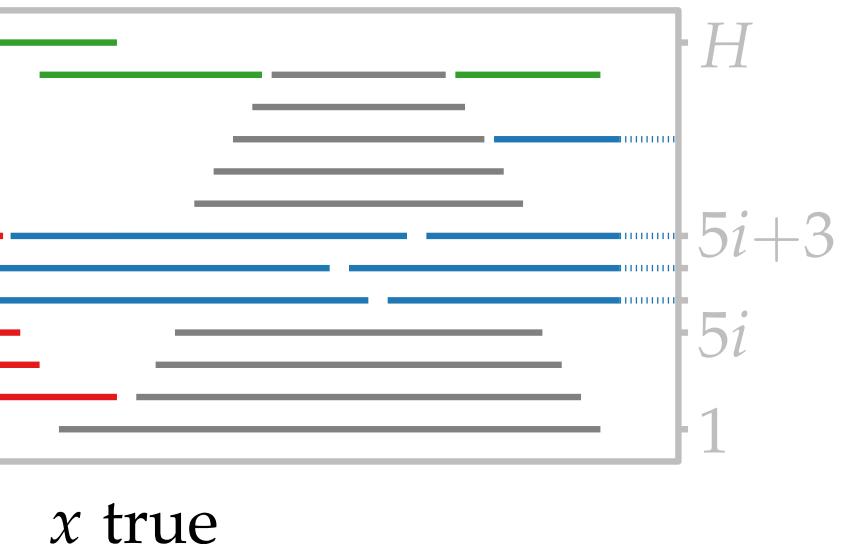
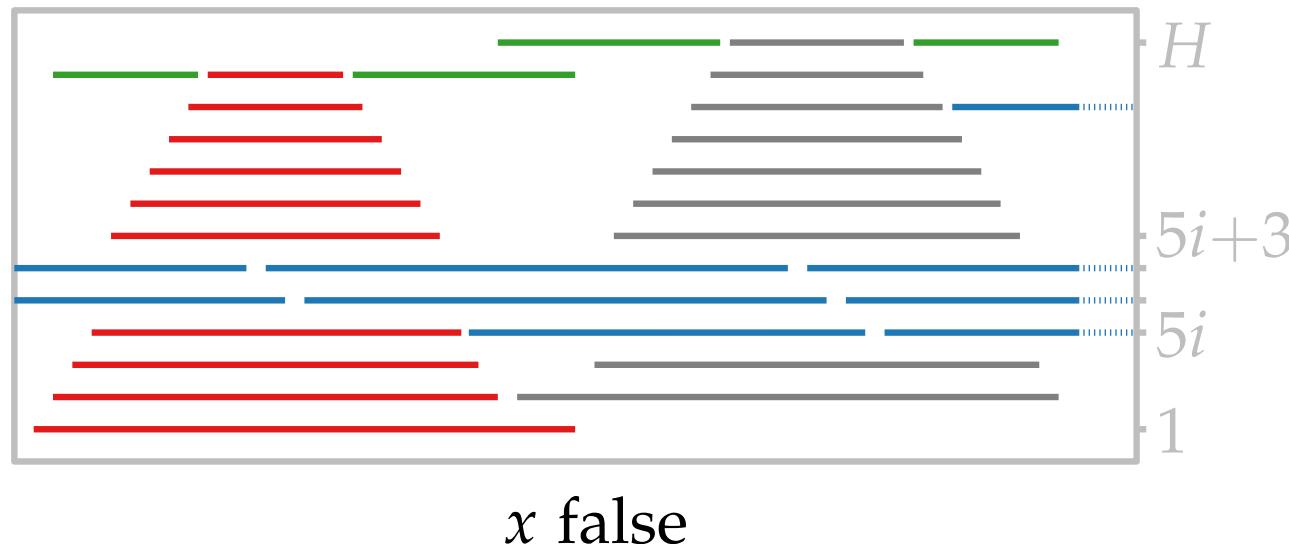
This yields $\lim_{n \rightarrow \infty} \chi(\mathcal{I}_n)/\omega(\mathcal{I}_n) = 2$.



Computational Complexity

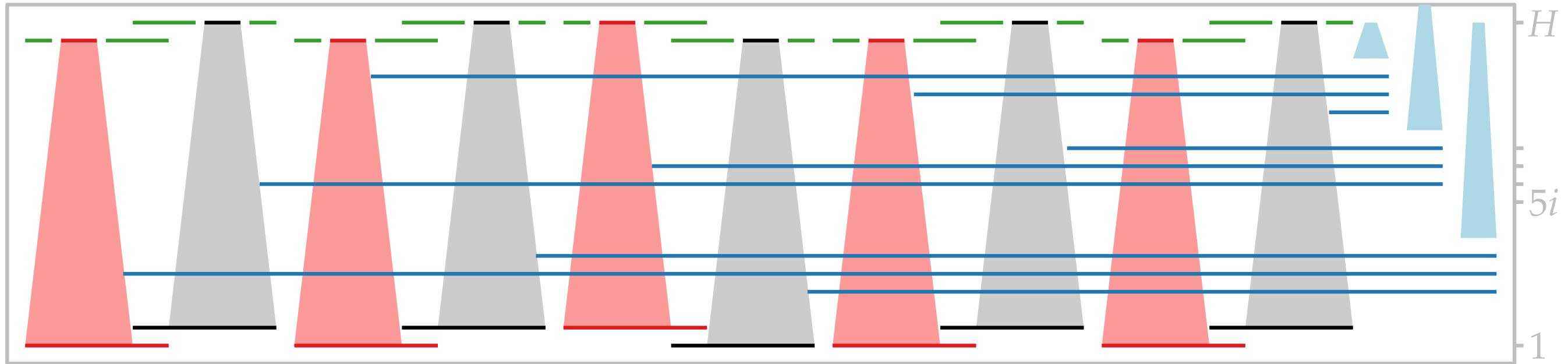
Theorem. Given a set \mathcal{I} of intervals and a positive integer k , it is NP-hard to decide whether $\chi(\mathcal{C}[\mathcal{I}]) \leq k$.

Proof. By reduction from (exact) 3-SAT, where each clause has exactly 3 literals.



Let $\varphi = C_1 \wedge C_2 \wedge \dots \wedge C_m$ be an instance of 3-SAT with variables $\{x_1, x_2, \dots, x_n\}$, and let $H = 5m + 1$. We construct a set \mathcal{I}_φ of intervals.

Clause Gadget



$x_1 \text{ false}$ $x_2 \text{ false}$ $x_3 \text{ true}$ $x_4 \text{ false}$ $x_5 \text{ false}$

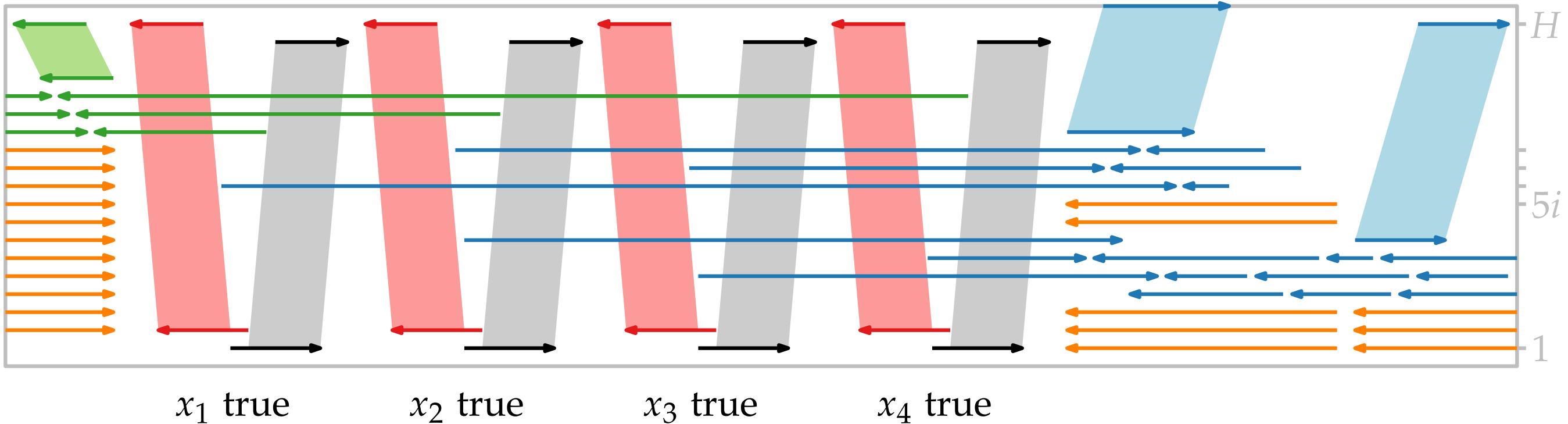
Example for $(\neg x_2 \vee \neg x_4 \vee x_5) \wedge (x_1 \vee \neg x_3 \vee x_4) \wedge (\neg x_1 \vee x_2 \vee x_3)$.

The graph $\mathcal{C}[\mathcal{I}_\varphi]$ admits a coloring with H colors $\Leftrightarrow \varphi$ is satisfiable. \square

Bidirectional Intervals

Theorem. Given a set \mathcal{I} of intervals, $\varphi: \mathcal{I} \rightarrow \{\text{left, right}\}$, and $k \in \mathbb{N}$, it is NP-hard to decide whether $\chi(\underbrace{\mathcal{B}[\mathcal{I}, \varphi]}_{\text{mixed intersection graph of bidirectional intervals}}) \leq k$.

Proof sketch.



Mixed Interval Graphs

Recall that a *mixed interval graph* is an interval graph where two intersecting intervals are connected by an edge or an arc in either direction.

If G is a mixed interval graph, then clearly $\chi(G) \geq \omega(G)$.

Let $\lambda(G)$ denote the length of a longest directed path in G .

Then clearly $\chi(G) \geq \lambda(G) + 1$. Hence, $\chi(G) \geq \max\{\omega(G), \lambda(G) + 1\}$.

Theorem. Let G be a mixed interval graph without directed cycles.
Then $\chi(G) \leq (\lambda(G) + 1) \cdot \omega(G)$.

Our constructive proof yields a $\min\{\omega(G), \lambda(G) + 1\}$ -approximation algorithm.

A Constructive Proof

Theorem. Let G be a mixed interval graph without directed cycles. Then $\chi(G) \leq (\lambda(G) + 1) \cdot \omega(G)$.

Proof. Let $c: V \rightarrow \{1, 2, \dots, \omega(U(G))\}$ be an optimal coloring of $U(G)$.

Define a mapping f . For a vertex x of G , let $f(x) = \ell(x) \cdot \omega(G) + c(x)$.

Note that $1 \leq f(x) \leq (\lambda(G) + 1) \cdot \omega(G)$. We claim that f colors G .

If $\{x, y\}$ is an edge of G , then $c(x) \neq c(y)$ and hence, $f(x) \neq f(y)$.

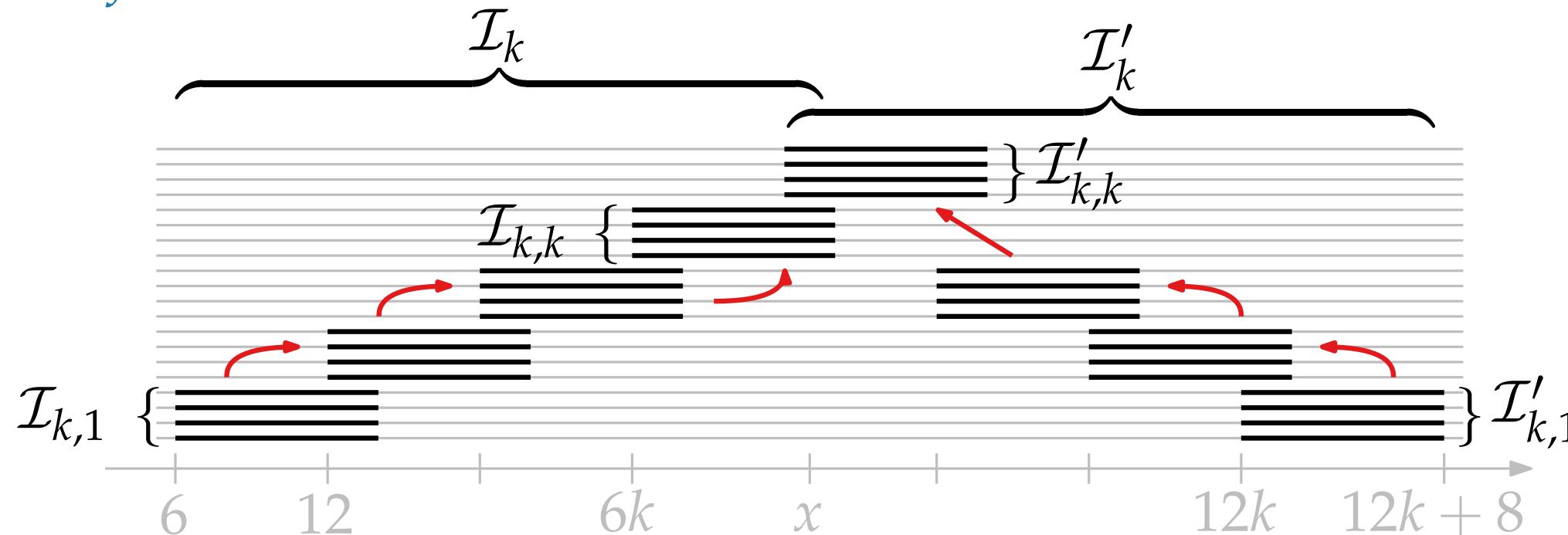
If (x, y) is an arc of G , then $\ell(x) < \ell(y)$ and hence, $f(x) < f(y)$. □

A Lower Bound Example

Proposition. There is an infinite family $(G_k)_{k \geq 1}$ of mixed interval graphs with $|V(G_k)| = 2k^2$, $\lambda(G_k) = k - 1$, $\omega(G_k) = 2k$, and $\chi(G_k) = (k + 1) \cdot k = (\lambda(G_k) + 2) \cdot \omega(G_k)/2$.

That is, our upper bound for $\chi(G)$, $(\lambda(G) + 1) \cdot \omega(G)$, is asymptotically tight.

Proof.



Summary

Mixed interval graph class	complexity	lower bound	upper bound	Coloring approximation	Recognition
containment	NP-hard	$2\omega - 1$	$2\omega - 1$	2	$O(nm)$
directional	$O(n \log n)$			1	$O(n^2)$
bidirectional	NP-hard			2	open
general	NP-hard	$(\lambda+2)\omega/2$	$(\lambda+1)\omega$	$\min\{\omega, \lambda+1\}$	$O(n+m)$ [LB79]

Follow-up Work

- Given a mixed graph G with an orientation φ , we can decide in linear time whether G admits an oriented interval representation that complies with φ .
- In particular, we can recognize directional interval graphs in linear time.