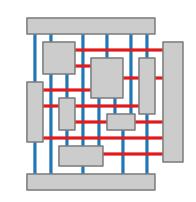


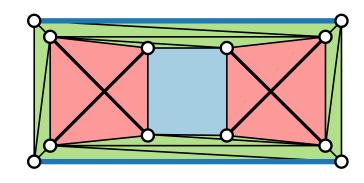
# Visualization of Graphs

Lecture 11:

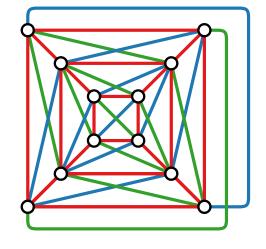
Beyond Planarity

Drawing Graphs with Crossings





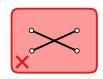
Alexander Wolff



Summer semester 2025

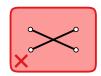
Planar graphs admit drawings in the plane without crossings.

Planar graphs admit drawings in the plane without crossings.



Planar graphs admit drawings in the plane without crossings.

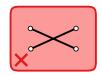
Plane graph is a planar graph with an embedding (fixed rotation system and fixed outer face).



Planar graphs admit drawings in the plane without crossings.

Plane graph is a planar graph with an embedding (fixed rotation system and fixed outer face).

Planarity is recognizable in linear time.

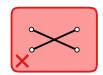


Planar graphs admit drawings in the plane without crossings.

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Planarity is recognizable in linear time.

Different drawing styles . . .

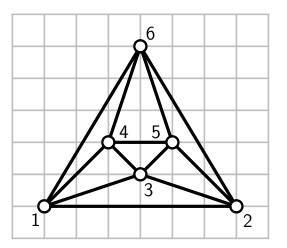


Planar graphs admit drawings in the plane without crossings.

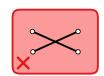
Plane graph is a planar graph with an embedding (fixed rotation system and fixed outer face).

Planarity is recognizable in linear time.

Different drawing styles ....



straight-line drawing

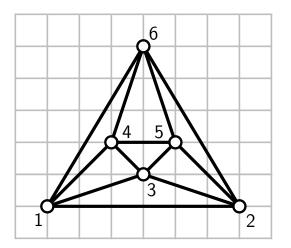


Planar graphs admit drawings in the plane without crossings.

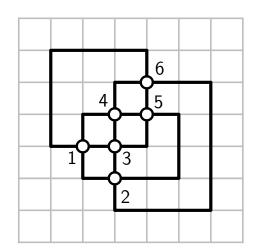
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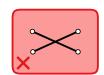
Different drawing styles ....



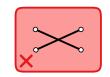




orthogonal drawing



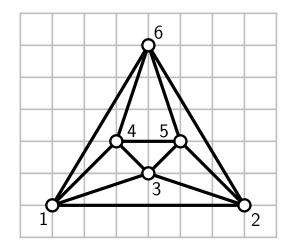
Planar graphs admit drawings in the plane without crossings.



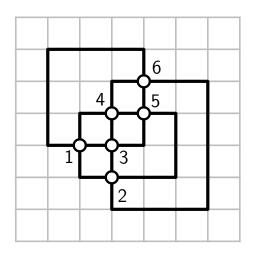
Plane graph is a planar graph with an embedding (fixed rotation system and fixed outer face).

Planarity is recognizable in linear time.

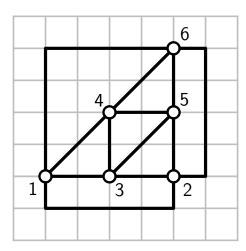
Different drawing styles ....







orthogonal drawing



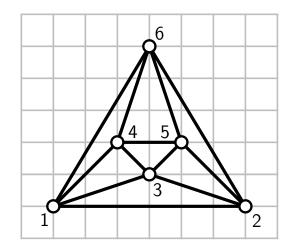
grid drawing with bends & 3 slopes

Planar graphs admit drawings in the plane without crossings.

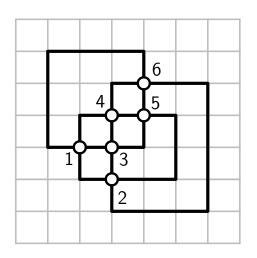
Plane graph is a planar graph with an embedding (fixed rotation system and fixed outer face).

Planarity is recognizable in linear time.

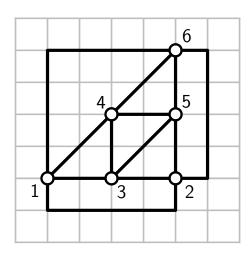
Different drawing styles . . .



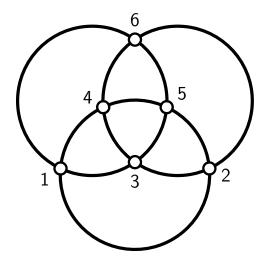
straight-line drawing



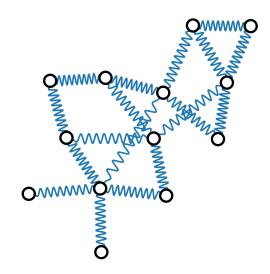
orthogonal drawing



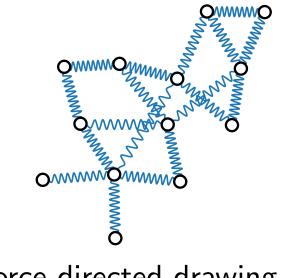
grid drawing with bends & 3 slopes



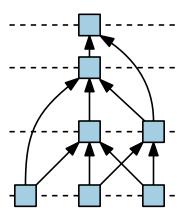
circular-arc drawing



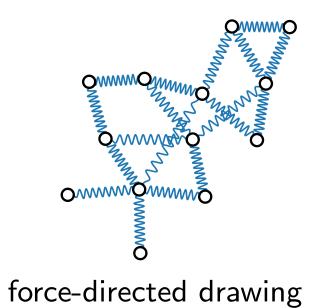
force-directed drawing



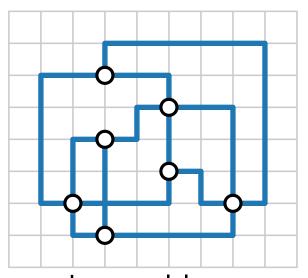
force-directed drawing



hierarchical drawing

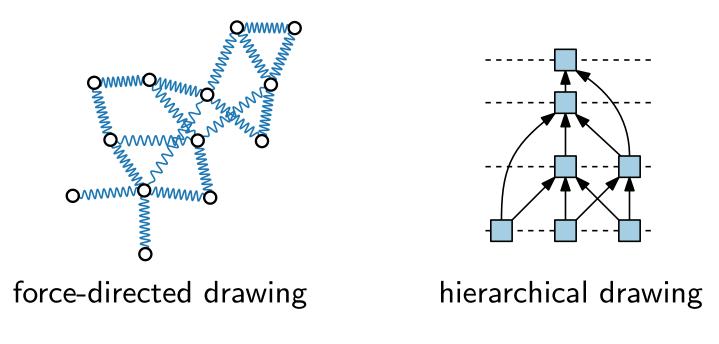


hierarchical drawing

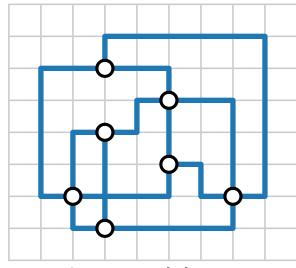


orthogonal layouts (via planarization)

We have seen a few drawing styles:

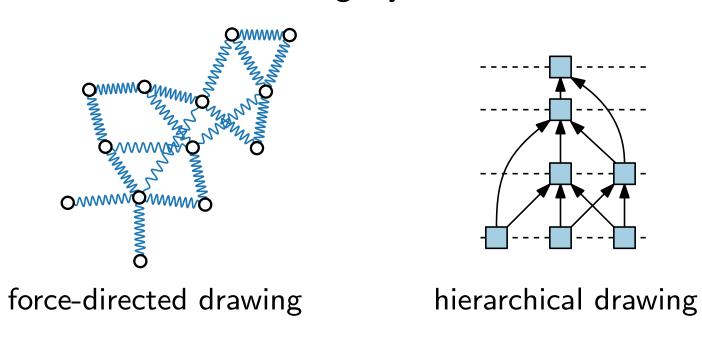


Maybe not all crossings are equally bad?



orthogonal layouts (via planarization)

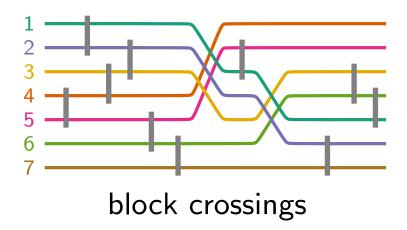
We have seen a few drawing styles:



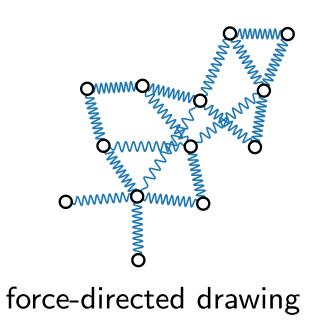
orthogonal layouts

(via planarization)

Maybe not all crossings are equally bad?



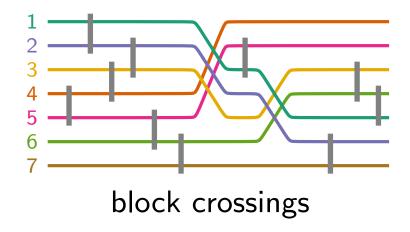
We have seen a few drawing styles:

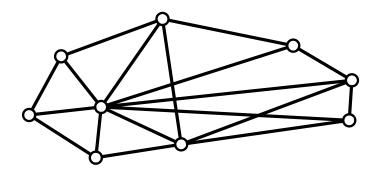


hierarchical drawing

orthogonal layouts (via planarization)

Maybe not all crossings are equally bad?

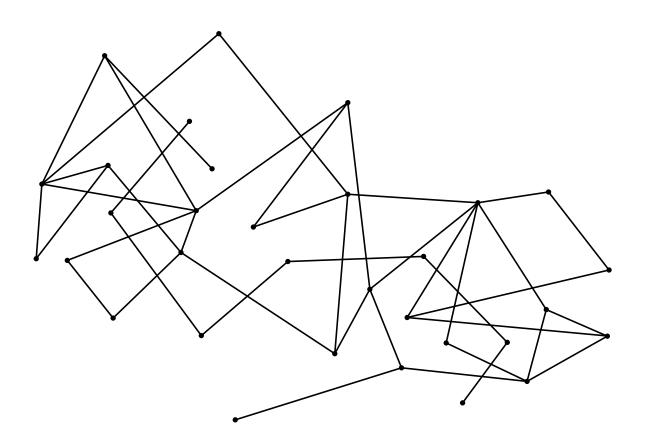




Which crossings feel worse?

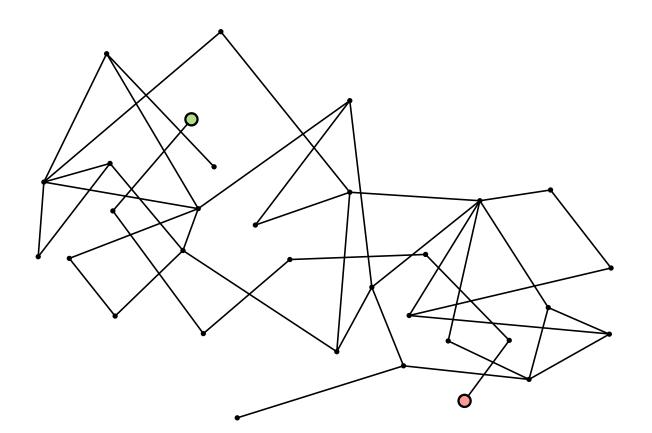
# Eye-Tracking Experiment

**Input:** A graph drawing and designated path.



# Eye-Tracking Experiment

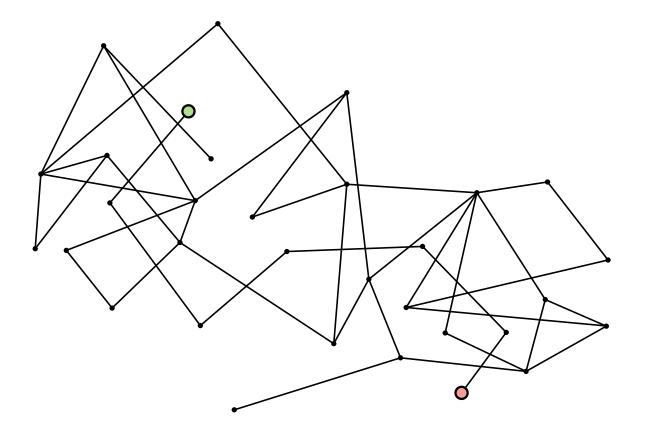
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# Eye-Tracking Experiment

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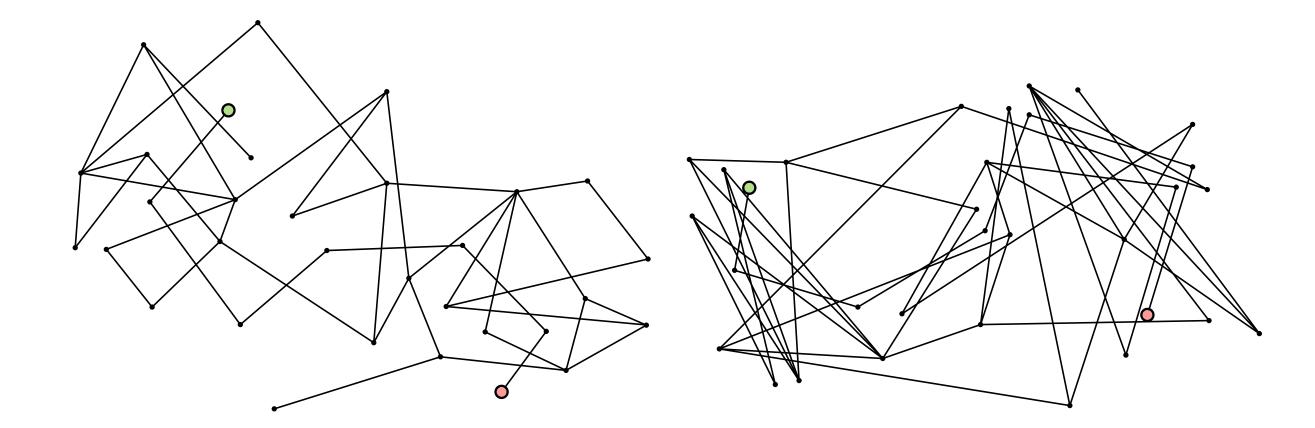
Task: Trace path and count number of edges.



# Eye-Tracking Experiment

**Input:** A graph drawing and designated path.

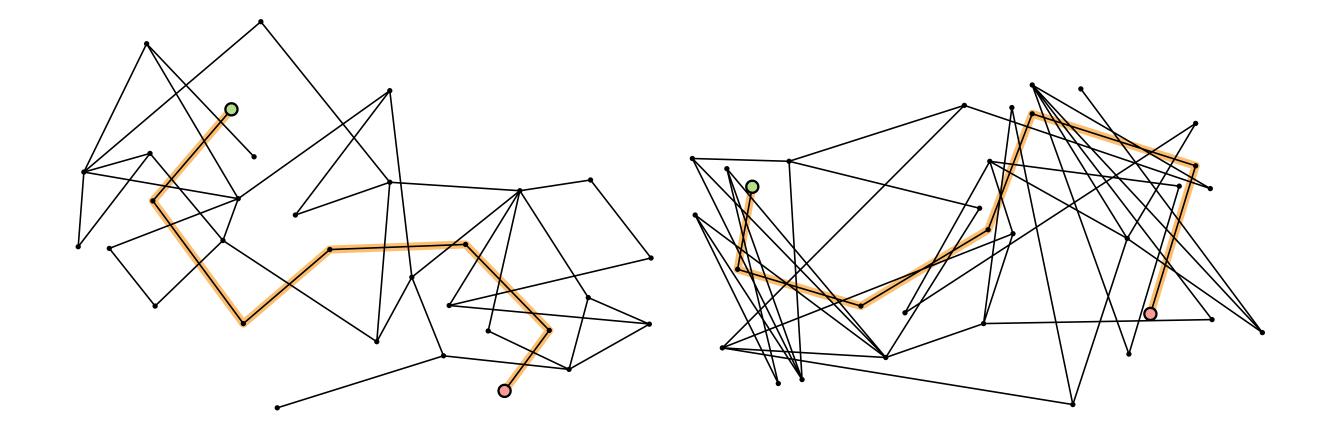
Task: Trace path and count number of edges.



# Eye-Tracking Experiment

**Input:** A graph drawing and designated path.

Task: Trace path and count number of edges.

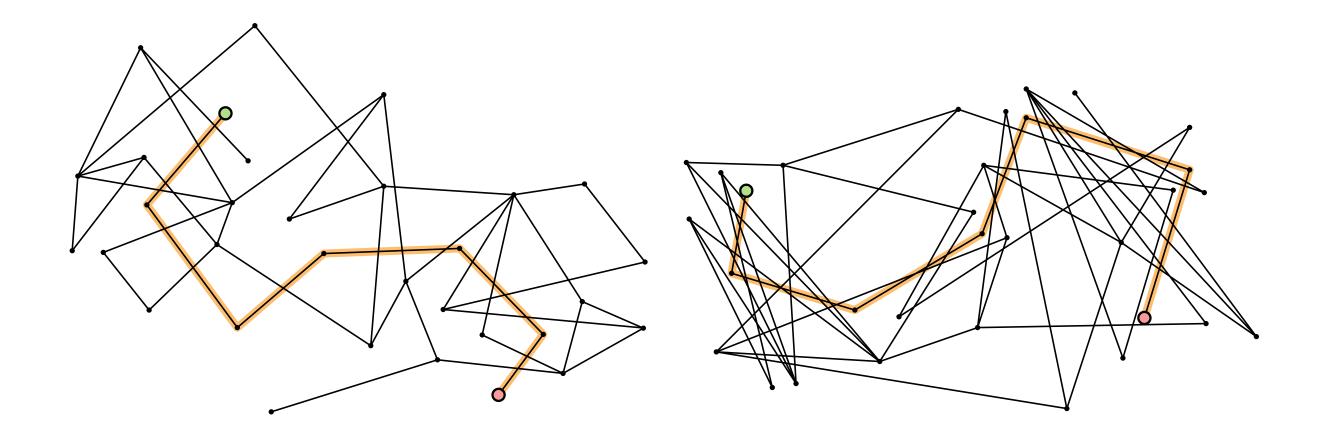


# Eye-Tracking Experiment

**Input:** A graph drawing and designated path.

Task: Trace path and count number of edges.

**Results:** 

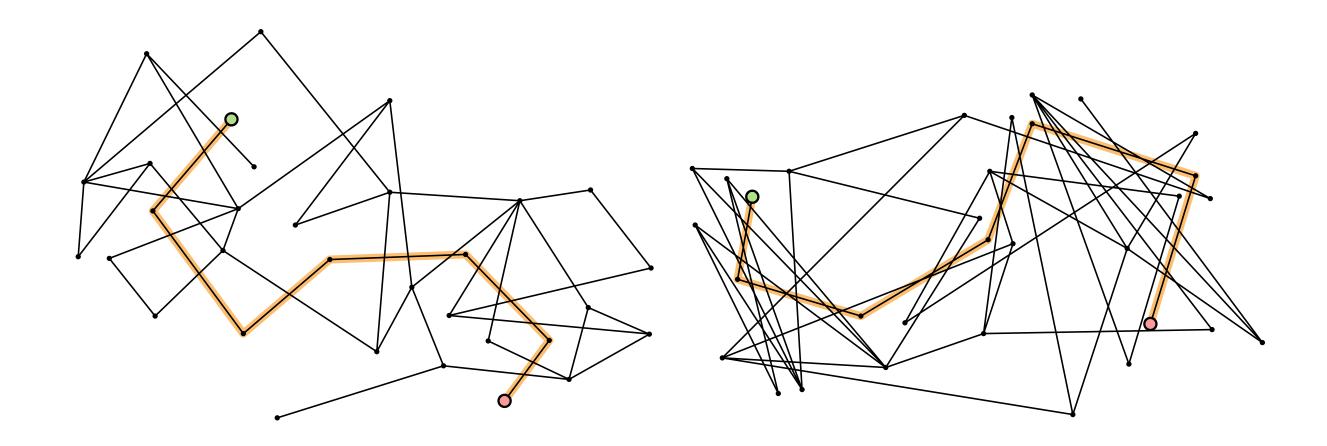


# Eye-Tracking Experiment

**Input:** A graph drawing and designated path.

Task: Trace path and count number of edges.

Results: no crossings eye movements smooth and fast



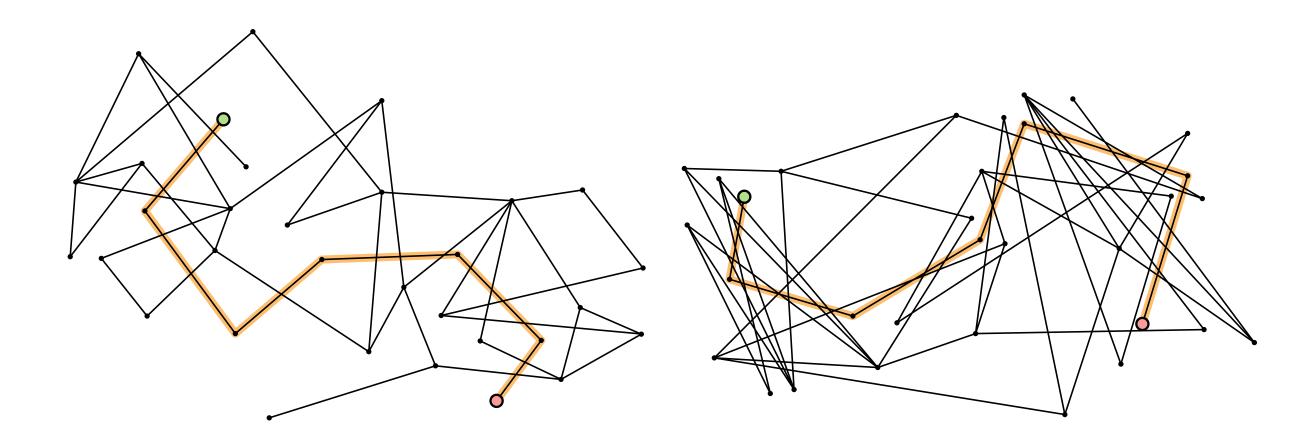
# Eye-Tracking Experiment

**Input:** A graph drawing and designated path.

Task: Trace path and count number of edges.

**Results:** no crossings eye movements smooth and fast

large crossing angles eye movements smooth but slightly slower



### Eye-Tracking Experiment

**Input:** A graph drawing and designated path.

Task: Trace path and count number of edges.

no crossings **Results:** 

large crossing angles

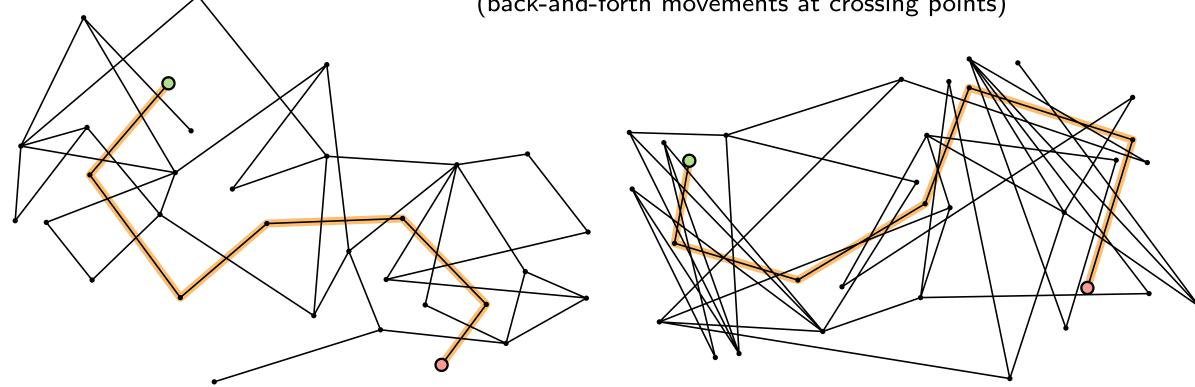
small crossing angles

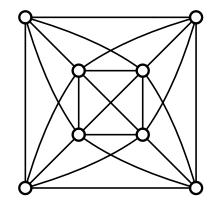
eye movements smooth and fast

eye movements smooth but slightly slower

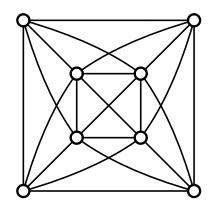
eye movements no longer smooth and very slow

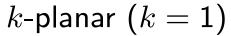
(back-and-forth movements at crossing points)



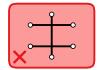


k-planar (k=1)

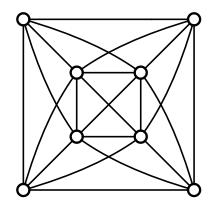


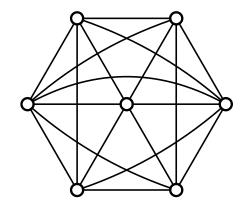






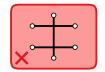


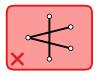


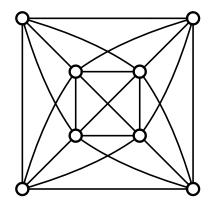


k-planar (k = 1) k-quasi-planar (k = 3)

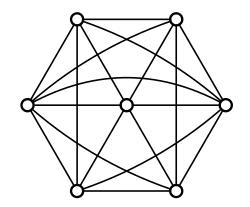






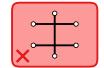


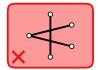
k-planar (k = 1)

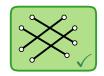


k-quasi-planar (k=3)

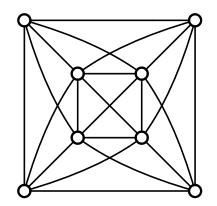


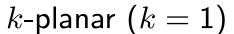


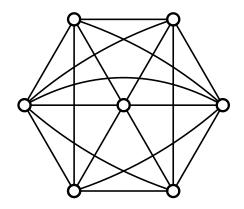




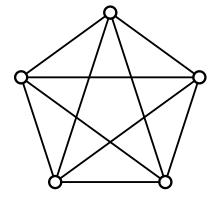






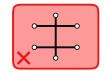


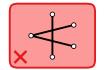
k-quasi-planar (k=3)

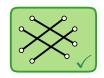




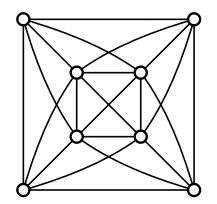




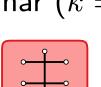




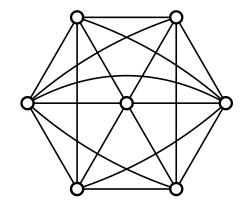




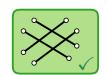
k-planar (k = 1)

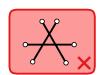


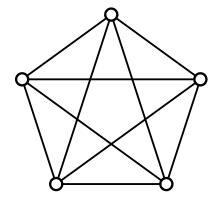




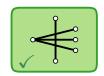
k-quasi-planar (k=3)



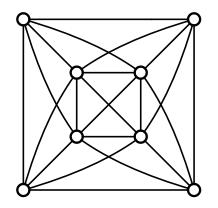




fan-planar



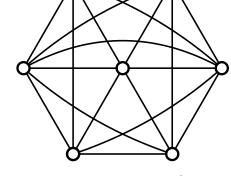




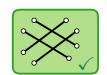
k-planar (k = 1)

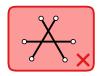


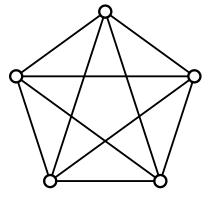




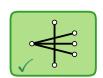
k-quasi-planar (k = 3)



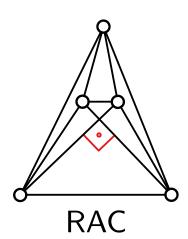


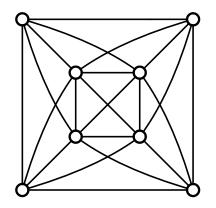


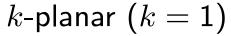
fan-planar

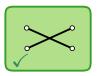


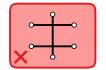


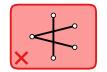


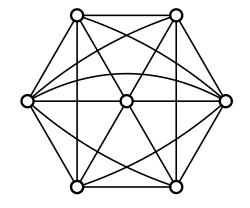




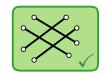




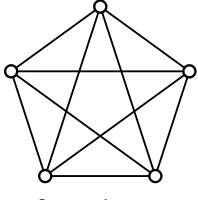




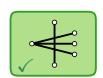
k-quasi-planar (k = 3)



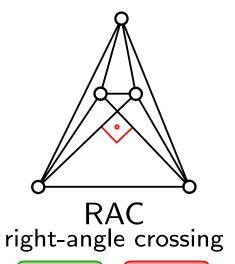


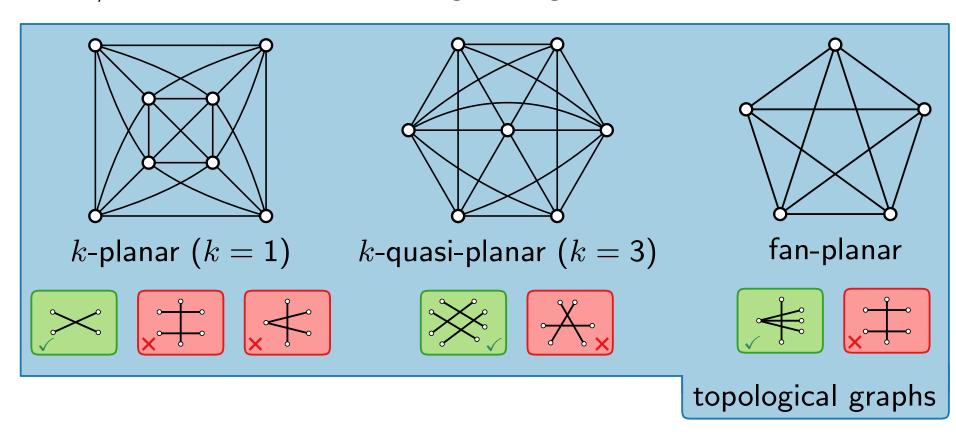


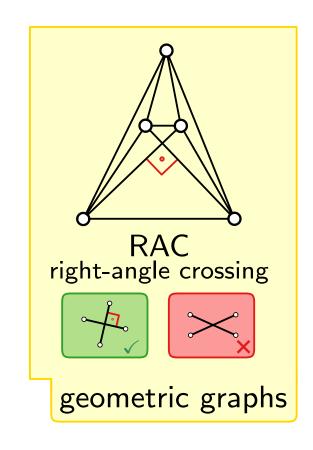
fan-planar



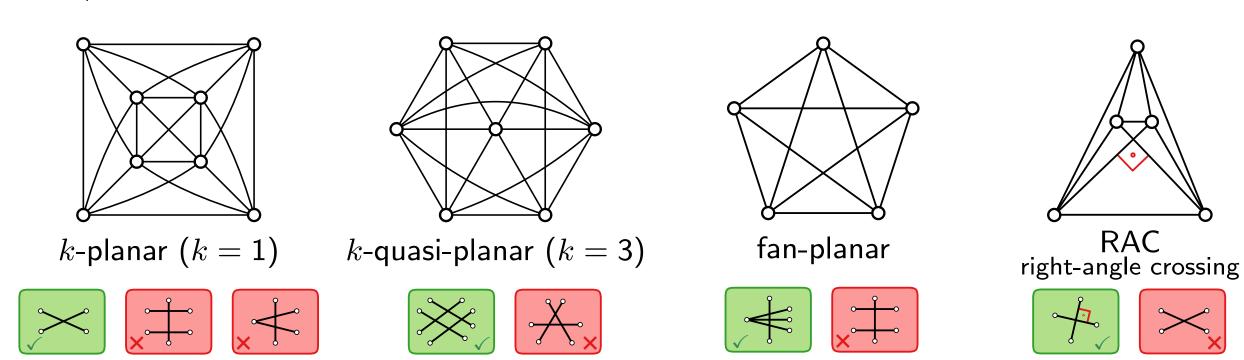






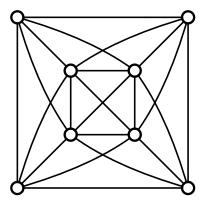


We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

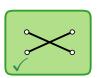


There are many more beyond-planar graph classes...

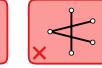
We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

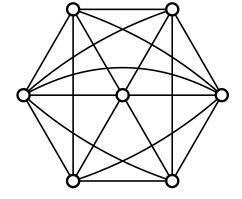


k-planar (k = 1)

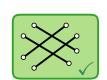


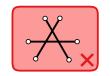


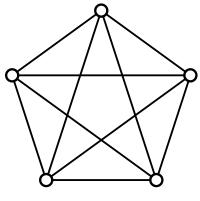




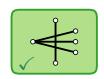
k-quasi-planar (k=3)



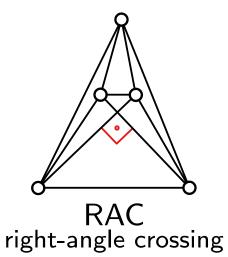




fan-planar



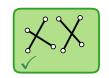


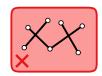






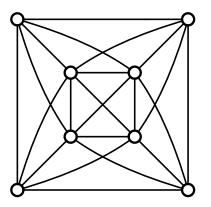
There are many more beyond-planar graph classes...





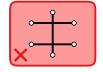
IC (independent crossing)

We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

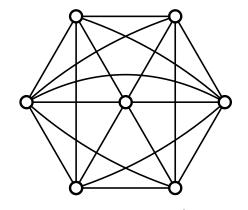


k-planar (k = 1)

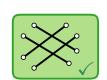


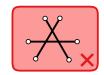


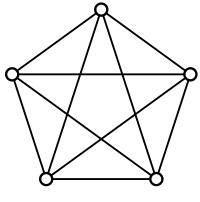




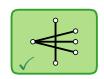
k-quasi-planar (k=3)

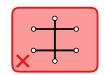


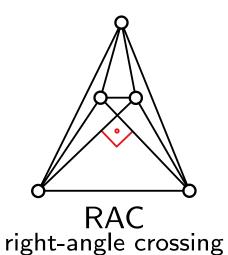


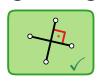


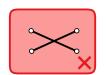
fan-planar



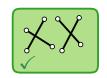


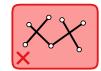




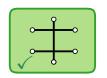


There are many more beyond-planar graph classes...





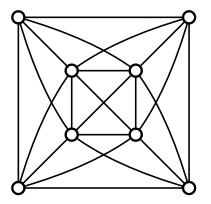


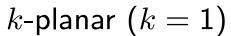




fan-crossing-free

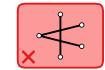
We define aesthetics for edge crossings and avoid/minimize "bad" crossing configurations.

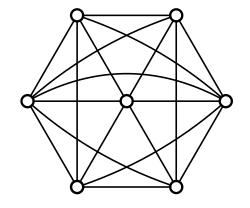




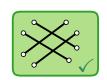


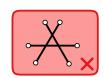


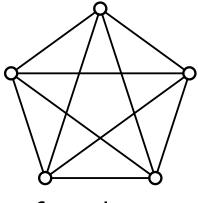




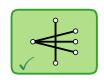
k-quasi-planar (k = 3)

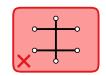


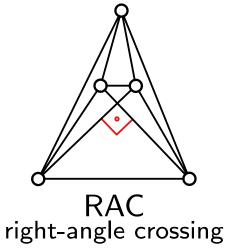




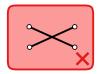
fan-planar



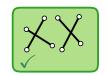


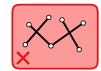




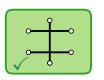


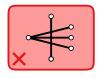
There are many more beyond-planar graph classes...



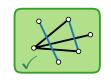


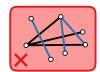
IC (independent crossing)





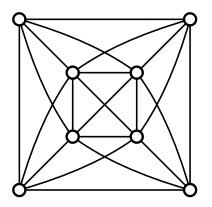
fan-crossing-free



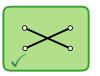


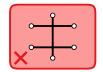
skewness-k (k = 2)

We define aesthetics for edge crossings and avoid/minimize "bad" crossing configurations.

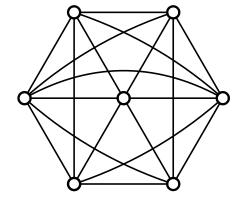


k-planar (k=1)

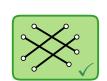


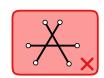


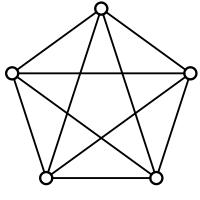




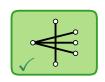
k-quasi-planar (k = 3)

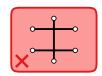


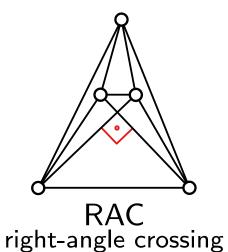




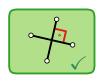
fan-planar

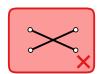




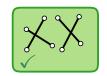


combinations, ...



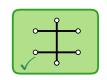


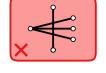
There are many more beyond-planar graph classes...



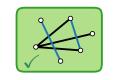


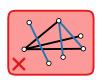
IC (independent crossing)





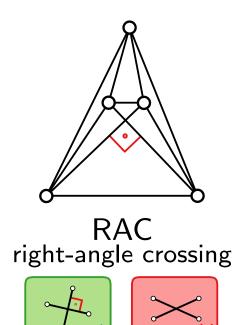
fan-crossing-free

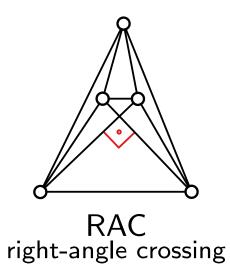


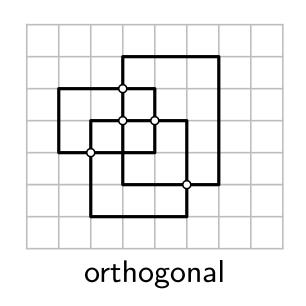


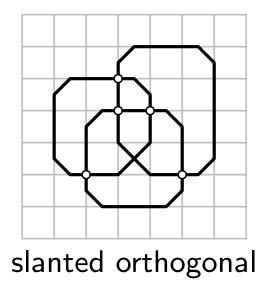
skewness-k (k = 2)

remove  $\leq k$  edges to make it planar

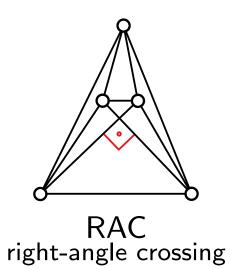


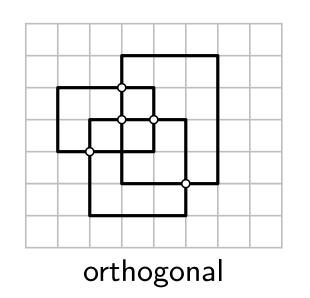


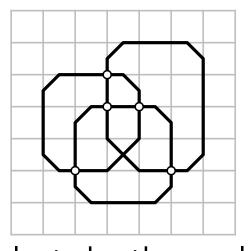


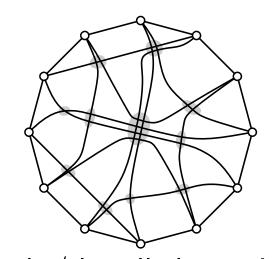








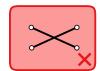




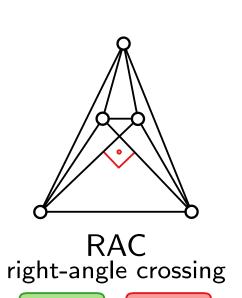
block / bundled crossings slanted orthogonal

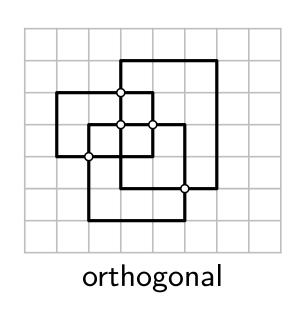
vs. 12 bundle crossings

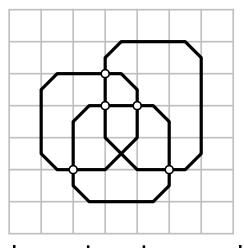


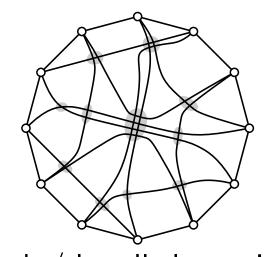


circular layout: 28 invididual





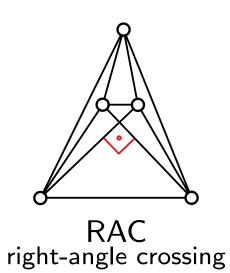


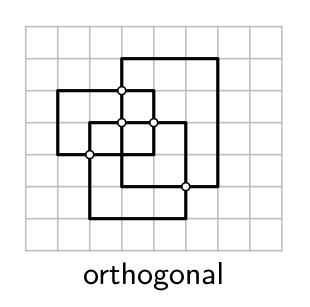


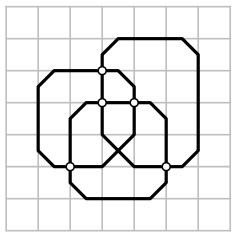
slanted orthogonal block / bundled crossings

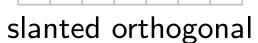
circular layout: 28 invididual vs. 12 bundle crossings

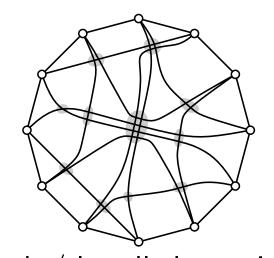






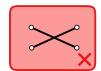


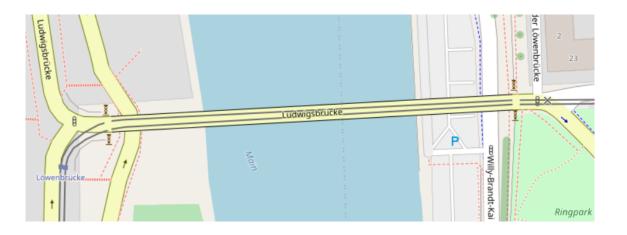


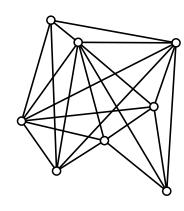


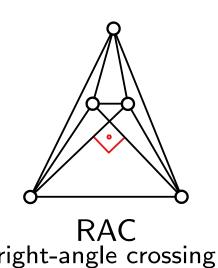
block / bundled crossings circular layout: 28 invididual vs. 12 bundle crossings

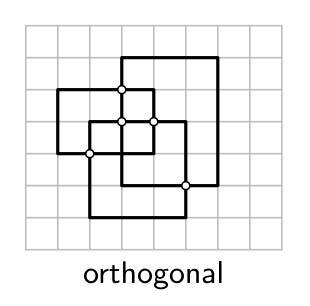


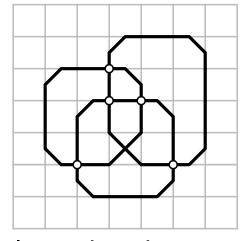


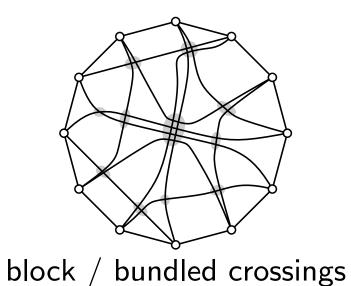




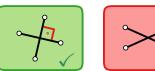








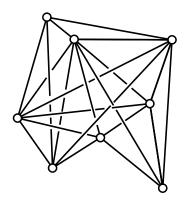
right-angle crossing



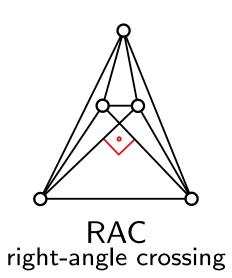
slanted orthogonal

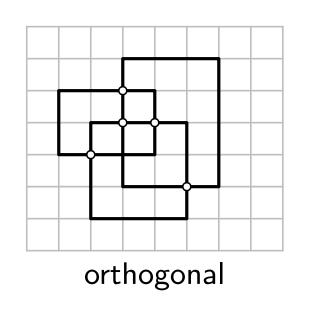
circular layout: 28 invididual vs. 12 bundle crossings

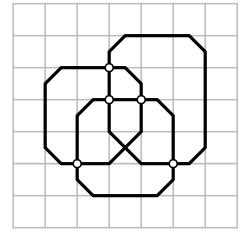


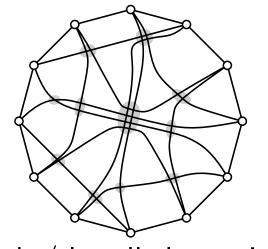


cased crossings







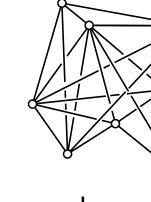


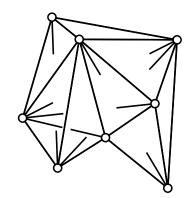
slanted orthogonal

block / bundled crossings circular layout: 28 invididual vs. 12 bundle crossings

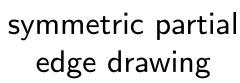




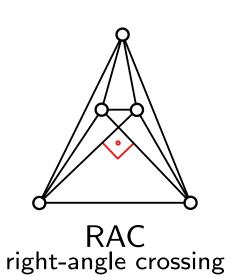


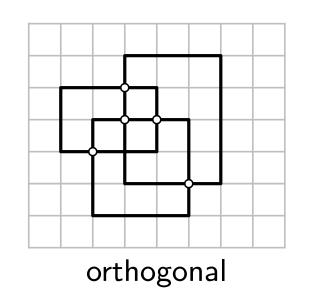


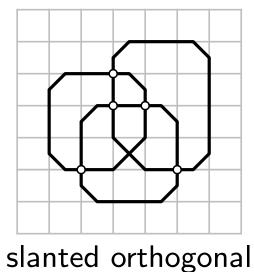
cased crossings

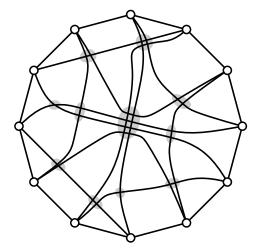




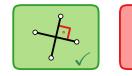




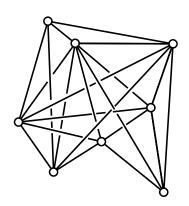


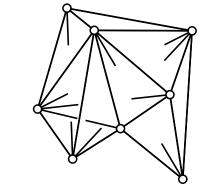


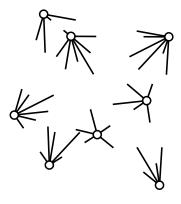
block / bundled crossings circular layout: 28 invididual vs. 12 bundle crossings









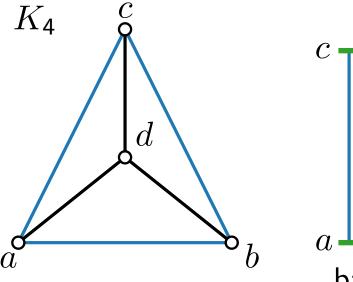


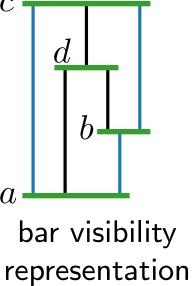
cased crossings

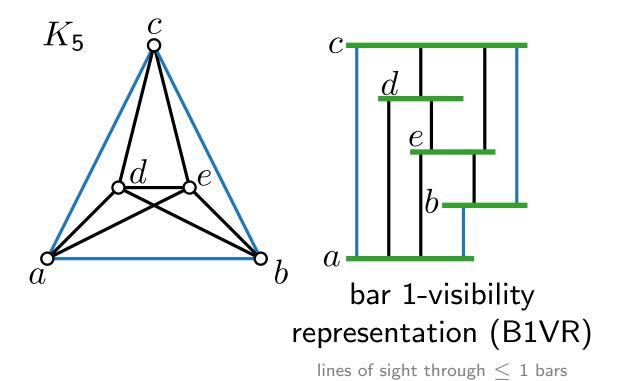
symmetric partial edge drawing

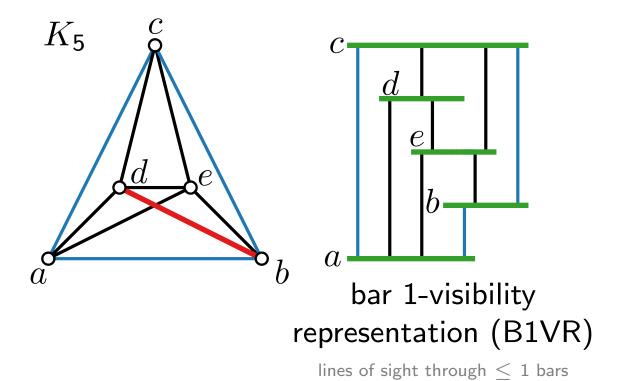
1/4-SHPED

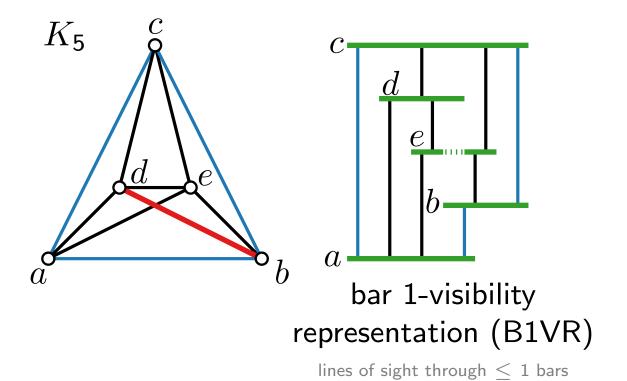
symmetric homogenous partial edge drawing

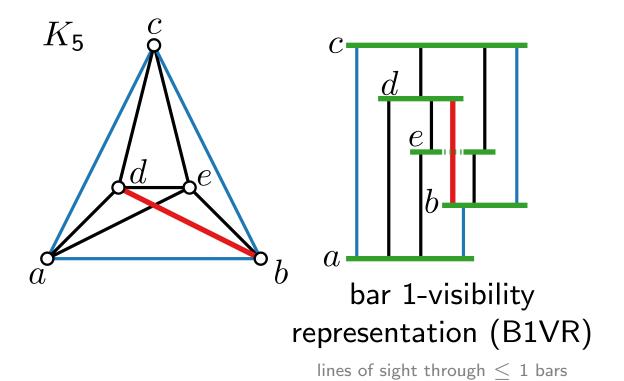


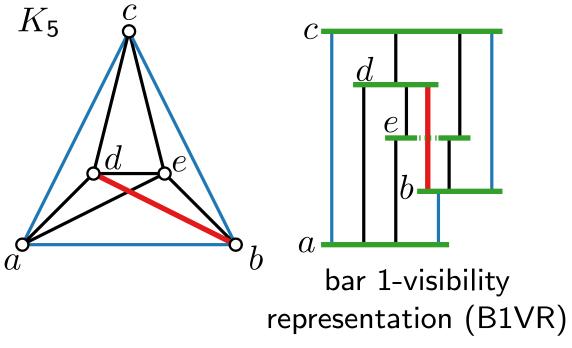






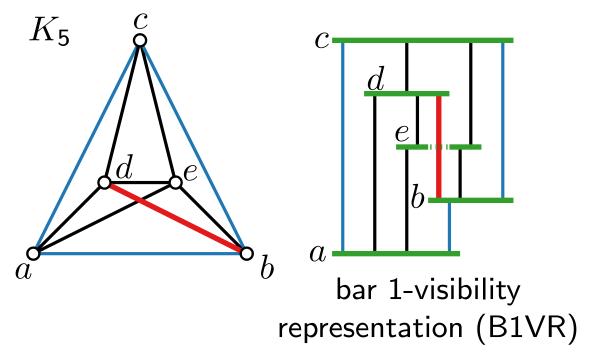






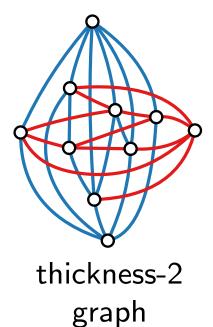
lines of sight through  $\leq 1$  bars

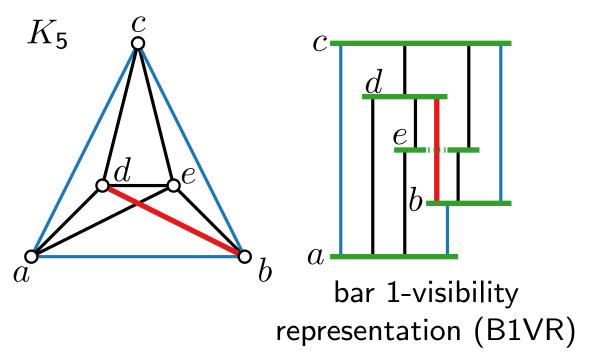
Every 1-planar graph admits a B1VR. [Brandenburg 2014; Evans et al. 2014; Angelini et al. 2018]



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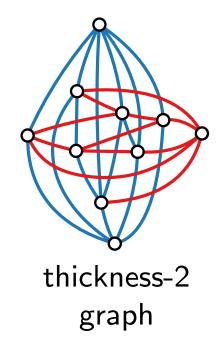
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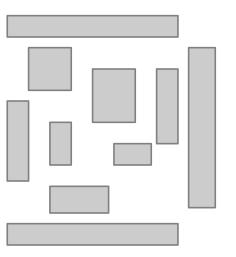




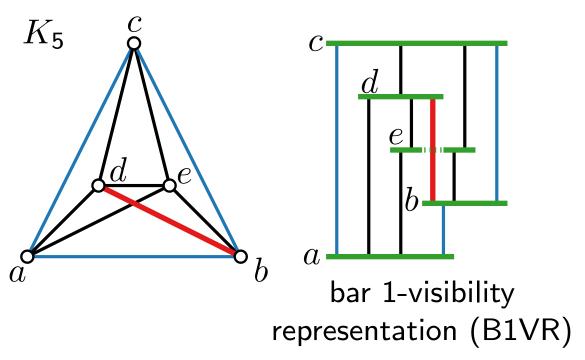
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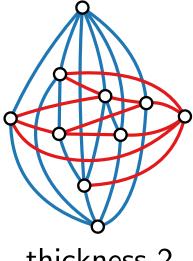


rectangle visibility representation

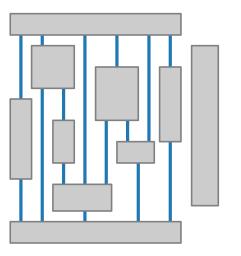


lines of sight through  $\leq 1$  bars

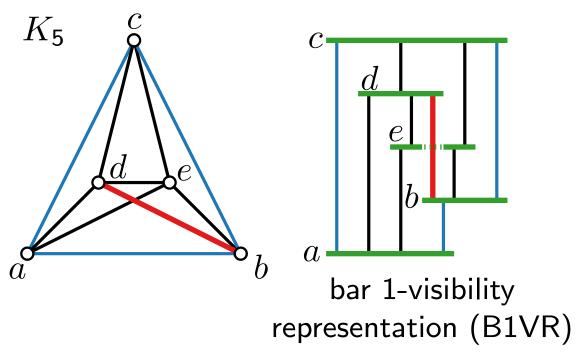
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thickness-2 graph

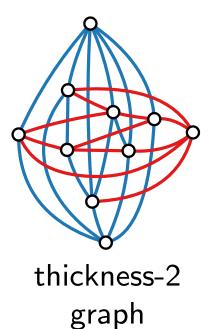


rectangle visibility representation

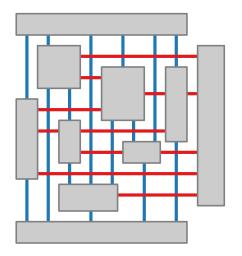


lines of sight through  $\leq 1$  bars

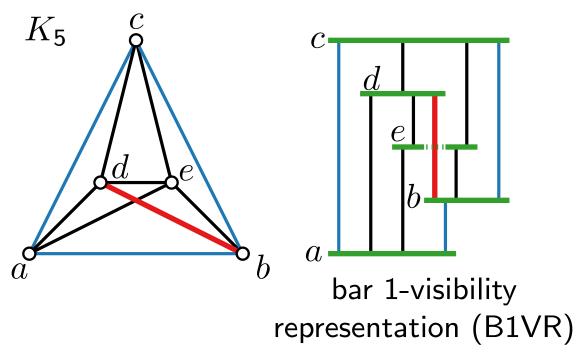
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decompose into 2 planar graphs

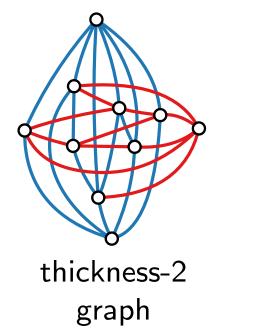


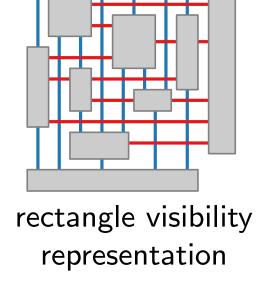
rectangle visibility representation



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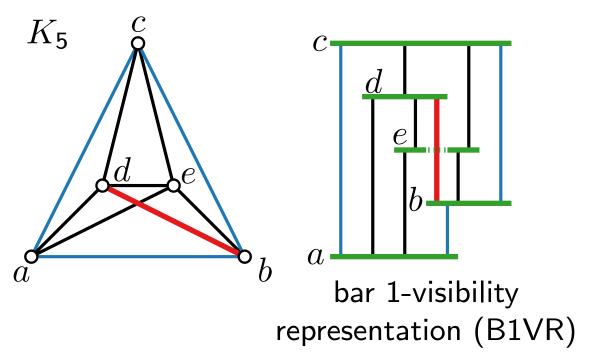
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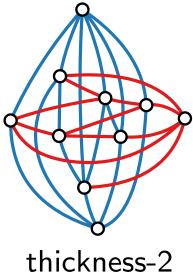
decompose into 2 planar graphs

Rectangle visibility graphs (RVGs) have  $\leq 6n-20$  edges. [Hutchinson, Shermer, Vince 1996]

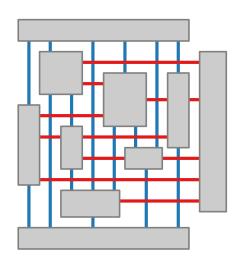


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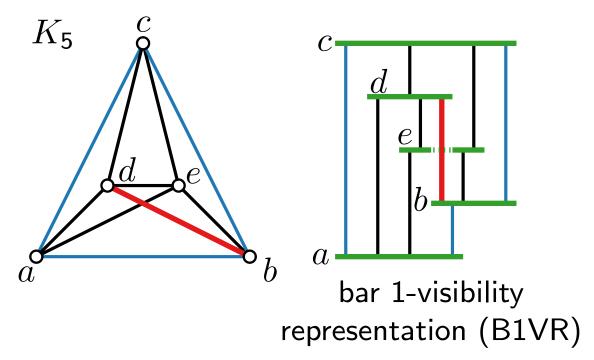






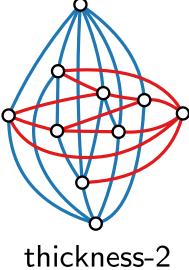
rectangle visibility representation

- Rectangle visibility graphs (RVGs) have  $\leq 6n-20$  edges. [Hutchinson, Shermer, Vince 1996]
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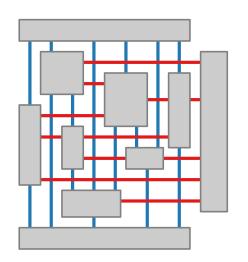


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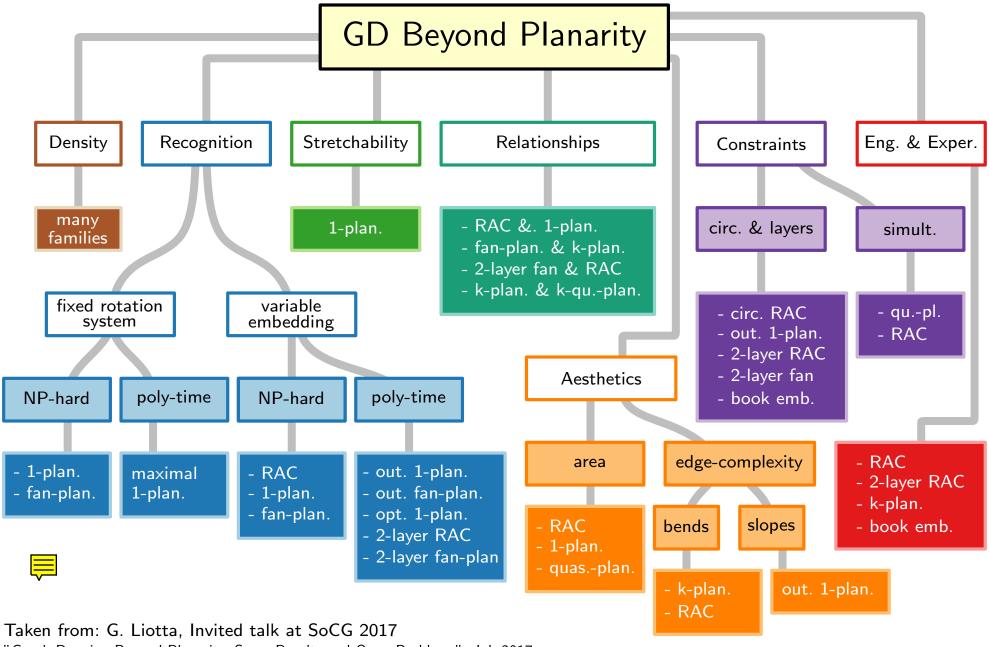
graph



rectangle visibility representation

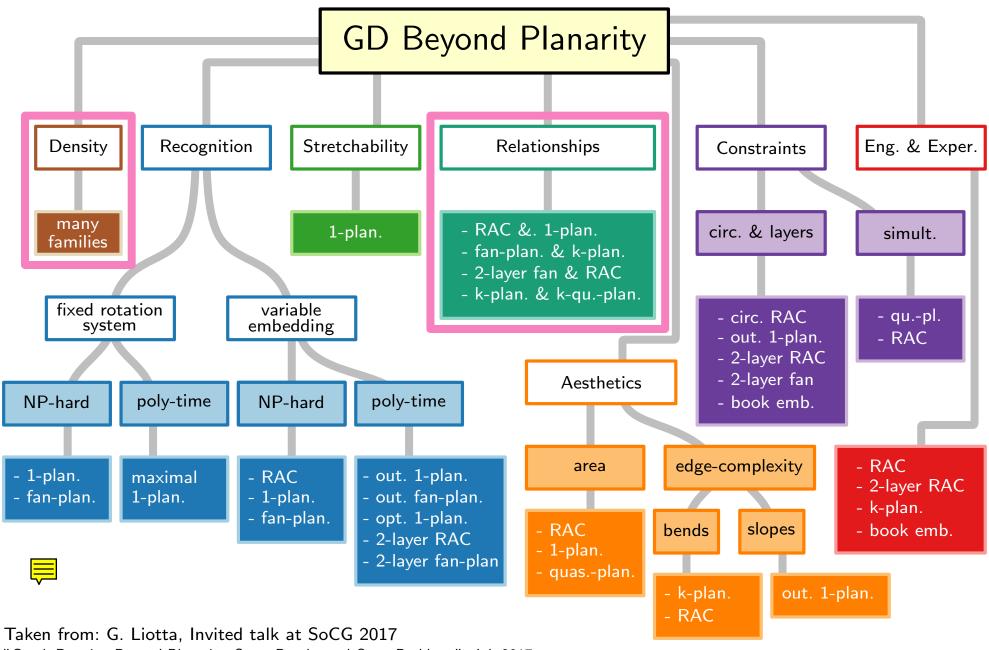
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- RVGs can be recognized efficiently if embedding is fixed. [Biedl, Liotta, Montecchiani 2018]

### GD Beyond Planarity: a Taxonomy



<sup>&</sup>quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

### GD Beyond Planarity: a Taxonomy



<sup>&</sup>quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

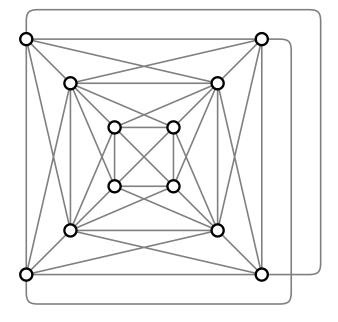
#### **Theorem.** [Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges.

#### Theorem.

[Ringel 1965, Pach & Tóth 1997]

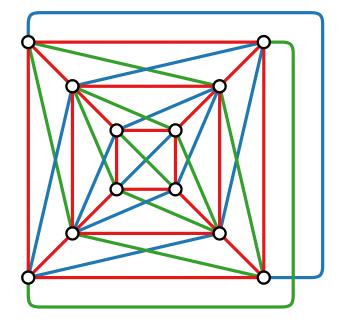
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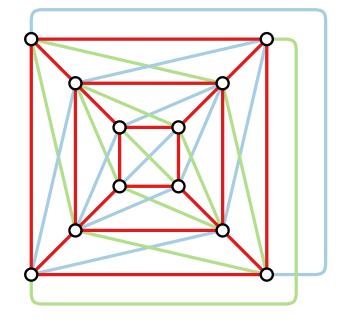
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[Ringel 1965, Pach & Tóth 1997]

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#### Proof sketch.

■ Let the red edges be those that do not cross.

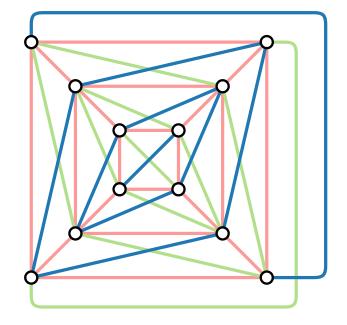


#### Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges.

- Let the red edges be those that do not cross.
- Each blue edge

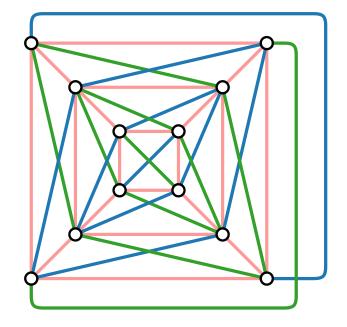


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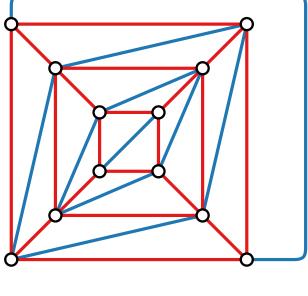
- Let the red edges be those that do not cross.
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#### **Theorem.** [Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph  $G_{rb}$  with



 $G_{rb}$ 

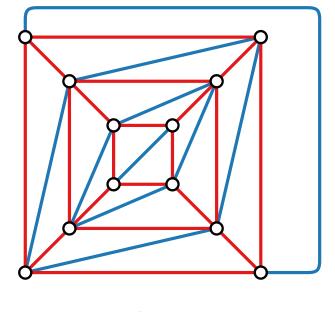
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$$m_{rb} \leq 3n - 6$$



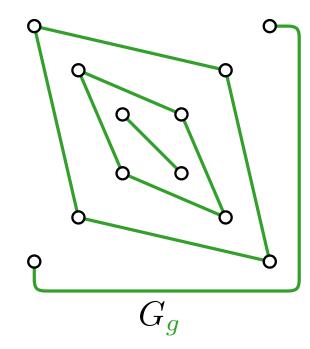
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- lacksquare and a green plane graph  $G_g$  with



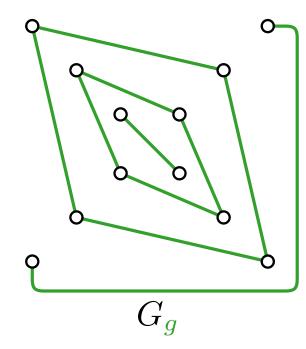
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- Let the red edges be those that do not cross.
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- and a green plane graph  $G_g$  with  $m_g \leq 3n-6$



### Theorem.

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A 1-planar graph with n vertices has at most 4n-8 edges.

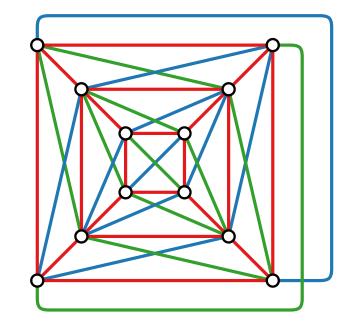
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lacksquare and a green plane graph  $G_g$  with

$$m_g \leq 3n - 6$$
  $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$ 



#### Theorem.

[Ringel 1965, Pach & Tóth 1997]

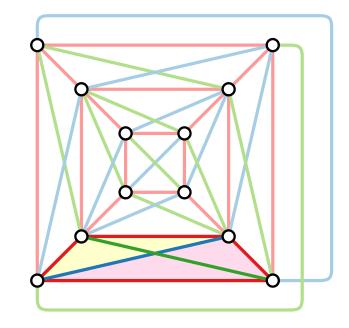
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#### Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph  $G_{rb}$  with  $m_{rb} < 3n 6$



$$m_g \leq 3n - 6$$
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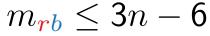
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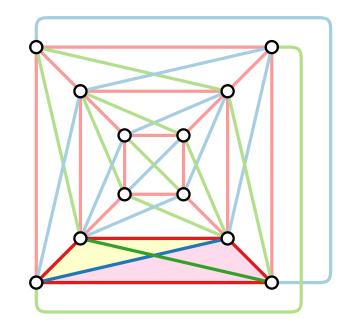
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$$m_g \leq f_{rb}/2$$



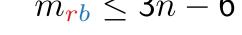
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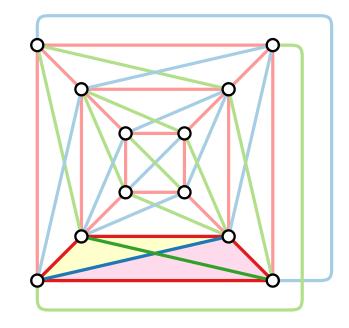
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$$m_g \le f_{rb}/2 \le (2n-4)/2$$



### Theorem.

[Ringel 1965, Pach & Tóth 1997]

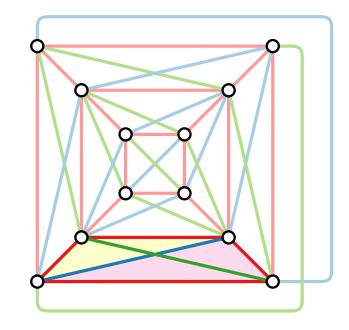
A 1-planar graph with n vertices has at most 4n-8 edges.

#### Proof sketch.

- Let the red edges be those that do not cross.
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- lacksquare and a green plane graph  $G_g$  with

$$m_g \leq 3n - 6$$
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$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$



### Theorem.

[Ringel 1965, Pach & Tóth 1997]

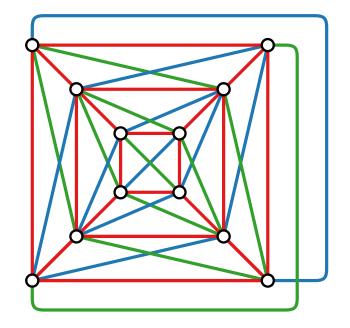
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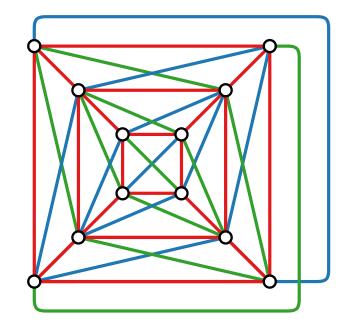
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$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$
  
 $\Rightarrow m = m_{rb} + m_g \le 3n - 6 + n - 2 = 4n - 8$ 



### Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

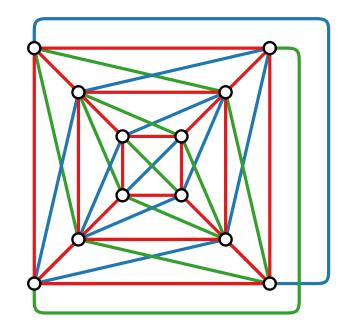
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$$m_g \leq 3n - 6$$
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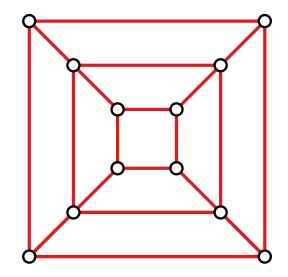
#### Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph  $G_{rb}$  with  $m_{rb} < 3n 6$
- lacksquare and a green plane graph  $G_g$  with

$$m_g \leq 3n - 6$$
  $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$ 

lacksquare Observe that each green edge joins two faces in  $G_{rb}$ .

$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$
  
 $\Rightarrow m = m_{rb} + m_g \le 3n-6+n-2 = 4n-8$ 



Lower-bound construction:

$$2n-4$$
 edges

$$n-2$$
 faces

### Theorem.

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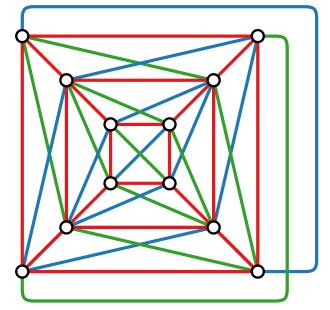
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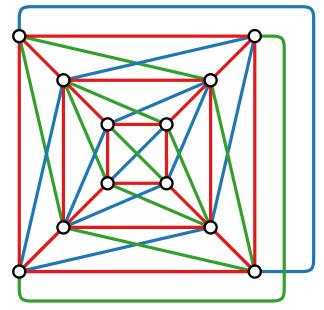
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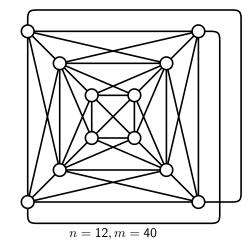
Total: 
$$4n - 8$$
 edges

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### Theorem.

[Ringel 1965, Pach & Tóth 1997]

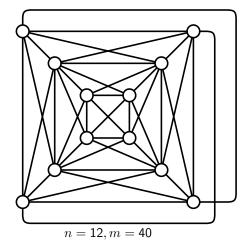
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### **Theorem.** [Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

A 1-planar graph with n vertices is called **optimal** if it has exactly 4n-8 edges.

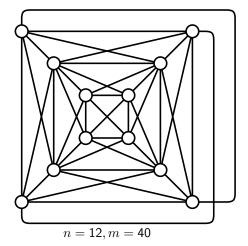


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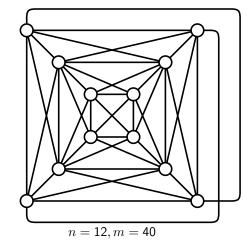
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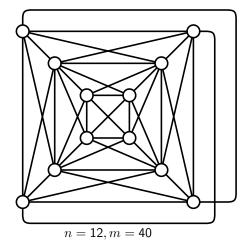
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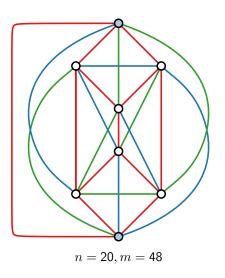
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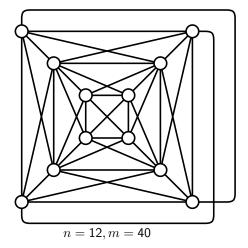
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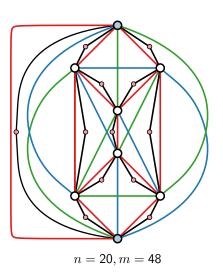
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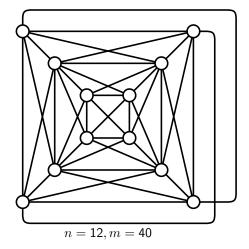
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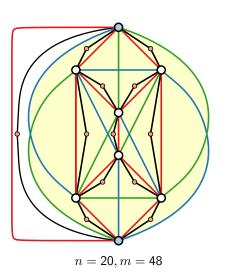
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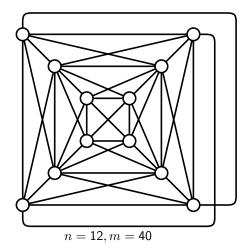
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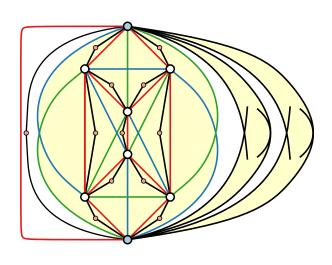
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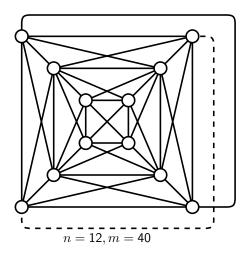
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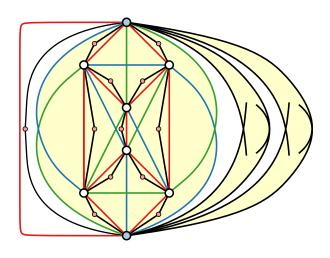
There are maximal 1-planar graphs with n vertices and  $45/17n - O(1) \approx 2.65n - O(1)$  edges.

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[Didimo 2013]

A 1-planar graph with n vertices that admits a **straight-line drawing** has at most 4n - 9 edges.





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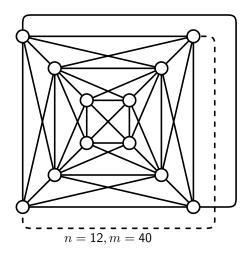
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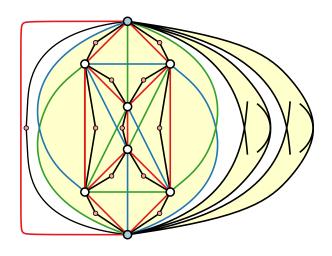
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Idea: in a drawing of an optimal 1-planar graph, we cannot realize the crossing on the outer face with two straight-line edges.

### Theorem.

A k-planar graph with n vertices has at most:

k number of edges

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4(n-2)

Euler's formula

[Ringel 1965]

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A k-planar graph with n vertices has at most:

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Euler's formula

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[Pach and Tóth 1997]

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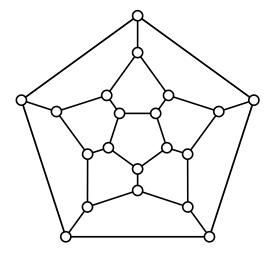
4(n-2)

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Planar structure:

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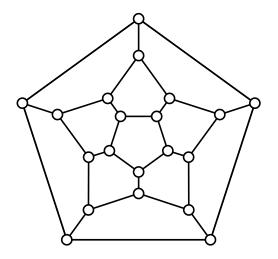
Euler's formula

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2

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Planar structure:

Edges per face:

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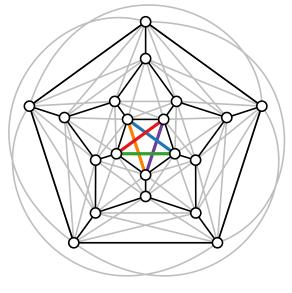
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optimal 2-planar

Planar structure:

Edges per face:

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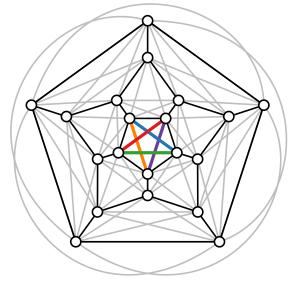
4(n-2)

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optimal 2-planar

Planar structure:

$$n - m + f = 2$$
$$m = c \cdot f ?$$

Edges per face:

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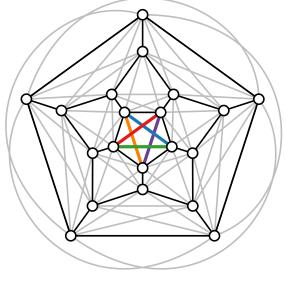
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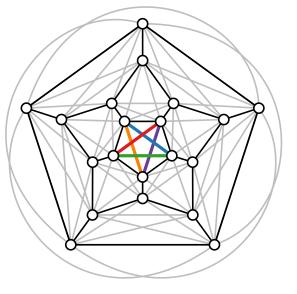
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optimal 2-planar

Planar structure:

$$\frac{5}{3}(n-2)$$
 edges  $\frac{2}{3}(n-2)$  faces

Edges per face:

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A k-planar graph with n vertices has at most:

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4(n-2)

2

Euler's formula

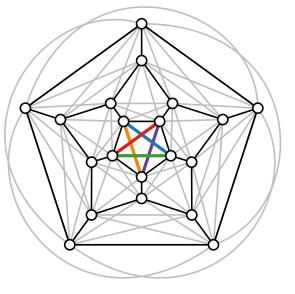
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Planar structure:

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 edges

$$\frac{2}{3}(n-2)$$
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4(n-2)

2

Euler's formula

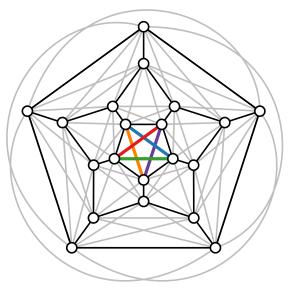
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optimal 2-planar

Planar structure:

$$\frac{5}{3}(n-2)$$
 edges

$$\frac{2}{3}(n-2)$$
 faces

Edges per face: 5 edges

Total: 
$$5(n-2)$$
 edges

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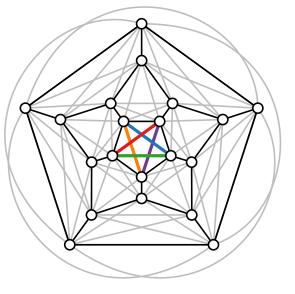
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optimal 2-planar

Planar structure:

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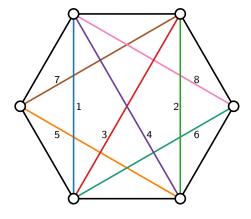
5(n-2)

3

Euler's formula

[Ringel 1965]

[Pach and Tóth 1997]



optimal 3-planar

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0 3(n-2)

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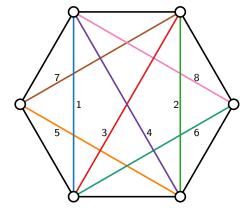
5(n-2)

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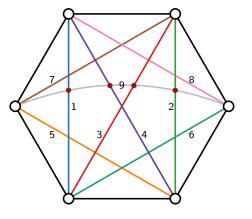
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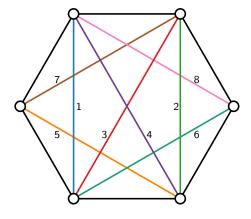
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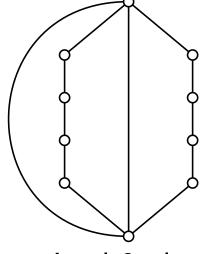
5(n-2)

3 5.5(n-2)

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optimal 3-planar

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4(n-2)

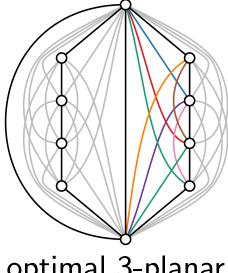
5(n-2)

5.5(n-2)3

Euler's formula

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3(n-2)

4(n-2)

5(n-2)

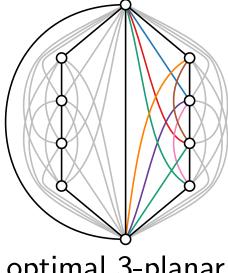
5.5(n-2)3

Euler's formula

[Ringel 1965]

[Pach and Toth 1997]

[Pach et al. 2006]



optimal 3-planar

Planar structure:

$$\frac{3}{2}(n-2)$$
 edges  $\frac{1}{2}(n-2)$  faces

Edges per face: 8 edges

Total: 5.5(n-2) edges

#### Theorem.

A k-planar graph with n vertices has at most:

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3(n-2)

4(n-2)

5(n-2)

5.5(n-2)

6(n-2)4

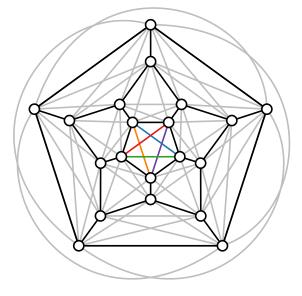
Euler's formula

[Ringel 1965]

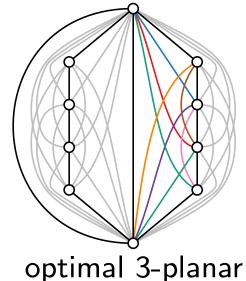
[Pach and Toth 1997]

[Pach et al. 2006]

[Ackerman 2015]



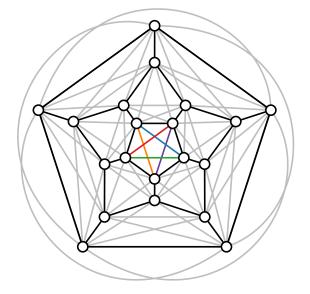
optimal 2-planar



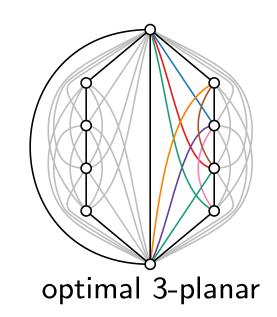
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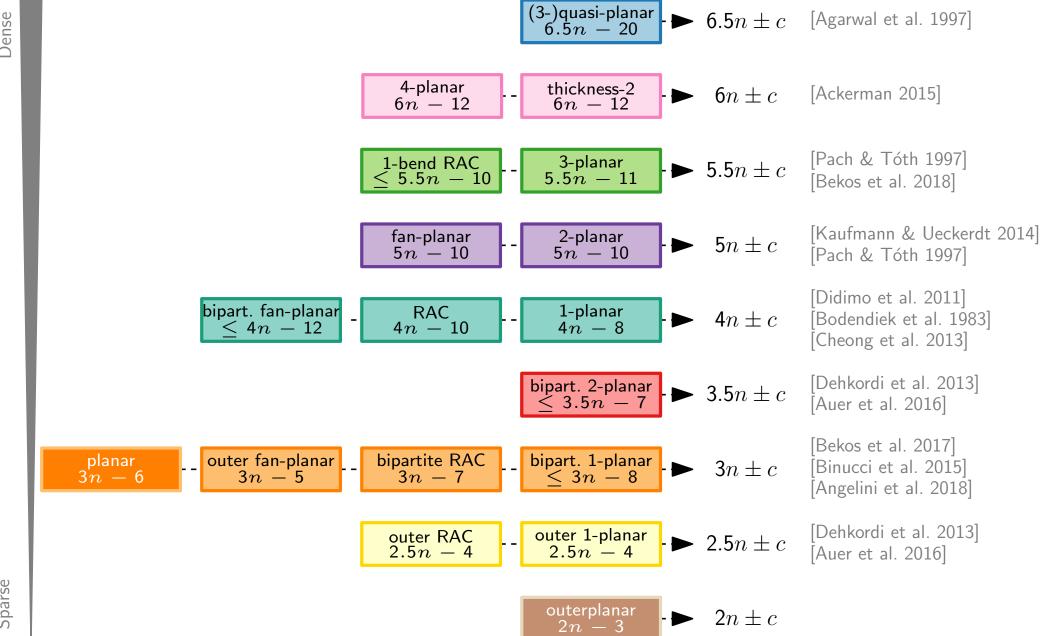
A k-planar graph with n vertices has at most:

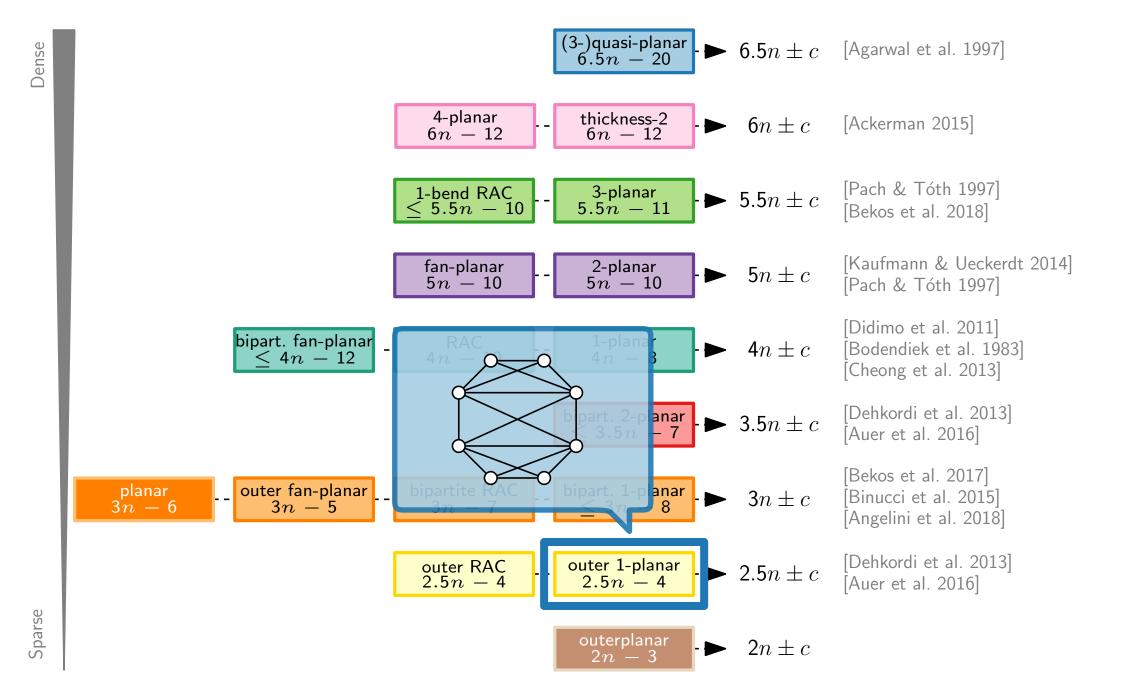
$\kappa$ $\kappa$ -planar graph with $n$ vertices has at most.		
k	number of edges	
0	3(n-2)	Euler's formula
1	<b>4</b> ( <i>n</i> – 2)	[Ringel 1965]
2	5(n-2)	[Pach and Tóth 1997]
3	5.5(n-2)	[Pach et al. 2006]
4	6(n-2)	[Ackerman 2015]
> 4	$4.108\sqrt{k}n$	[Pach and Tóth 1997]

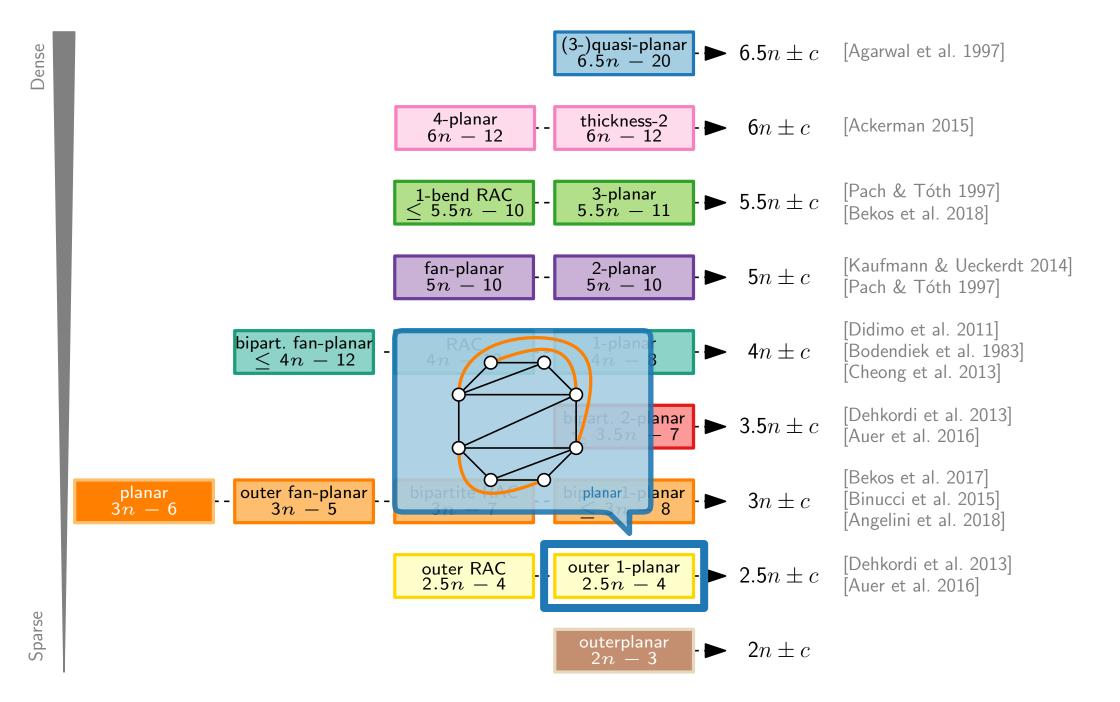


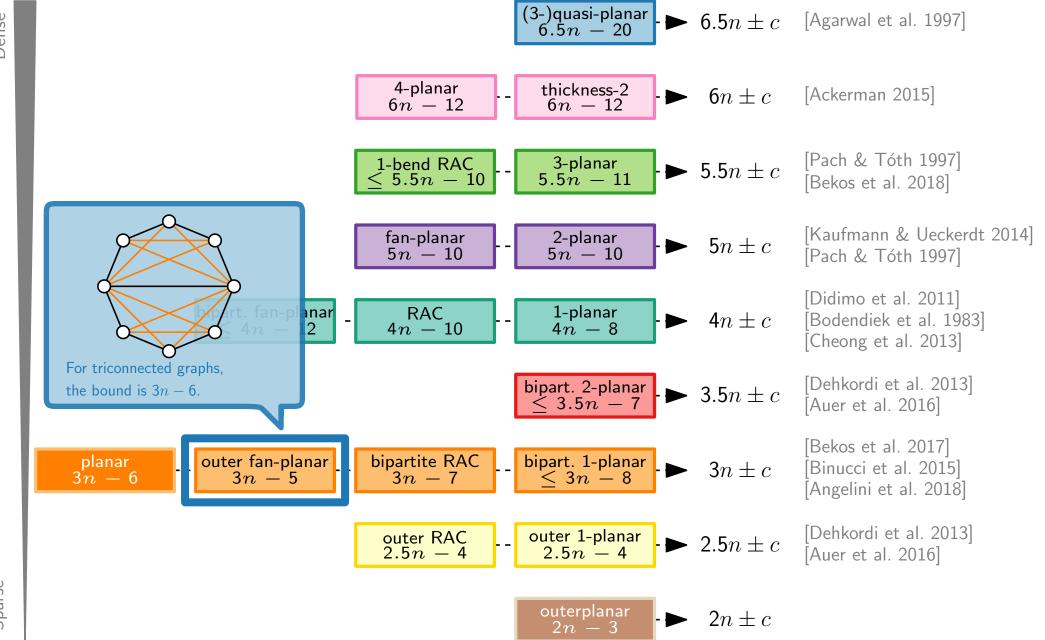
optimal 2-planar



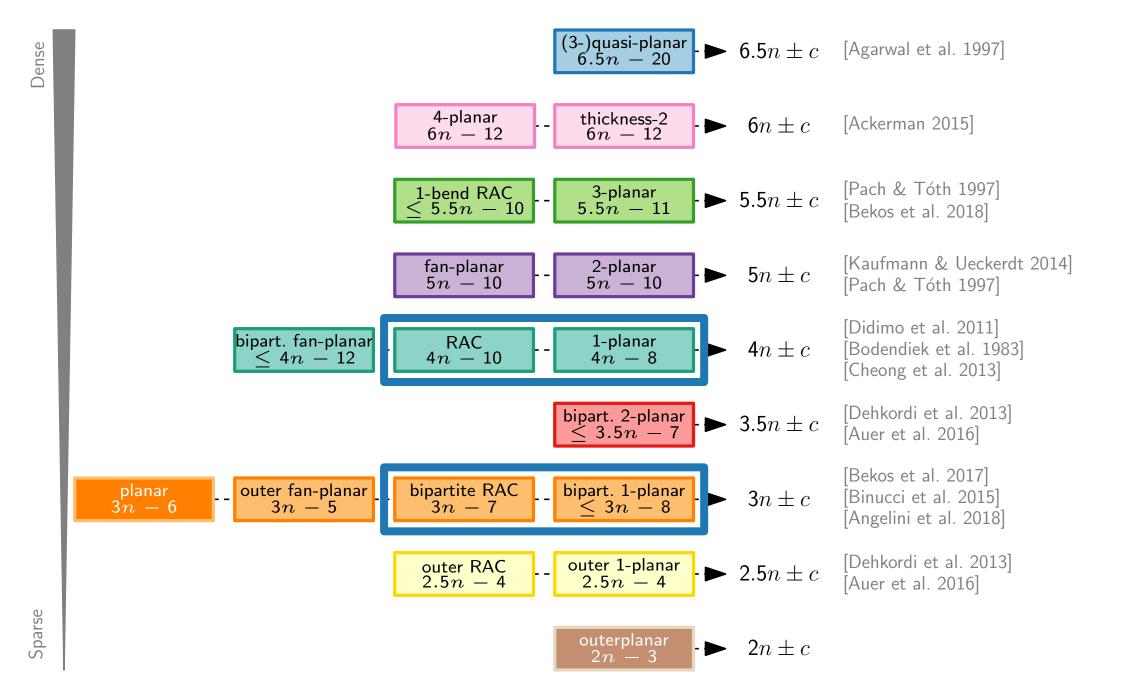


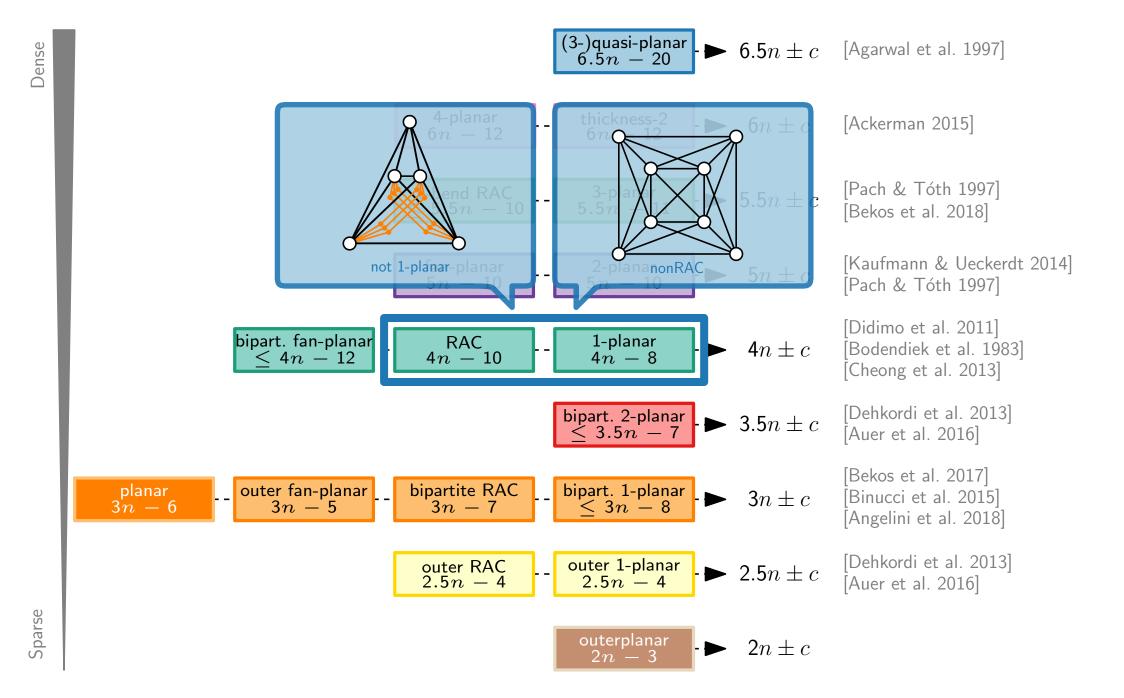


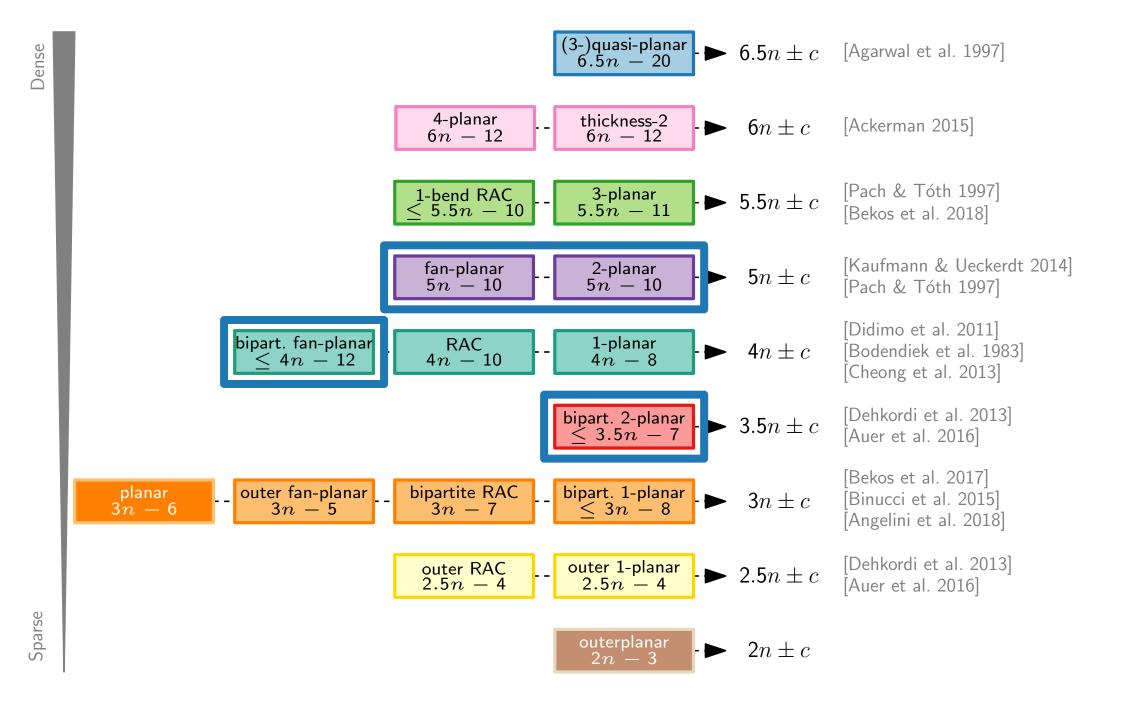


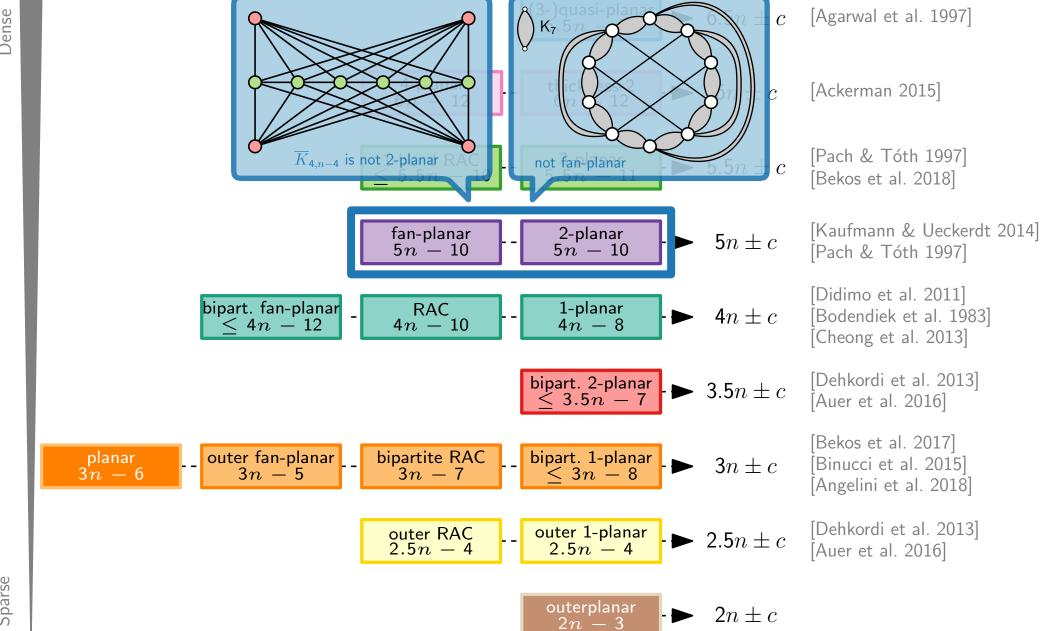


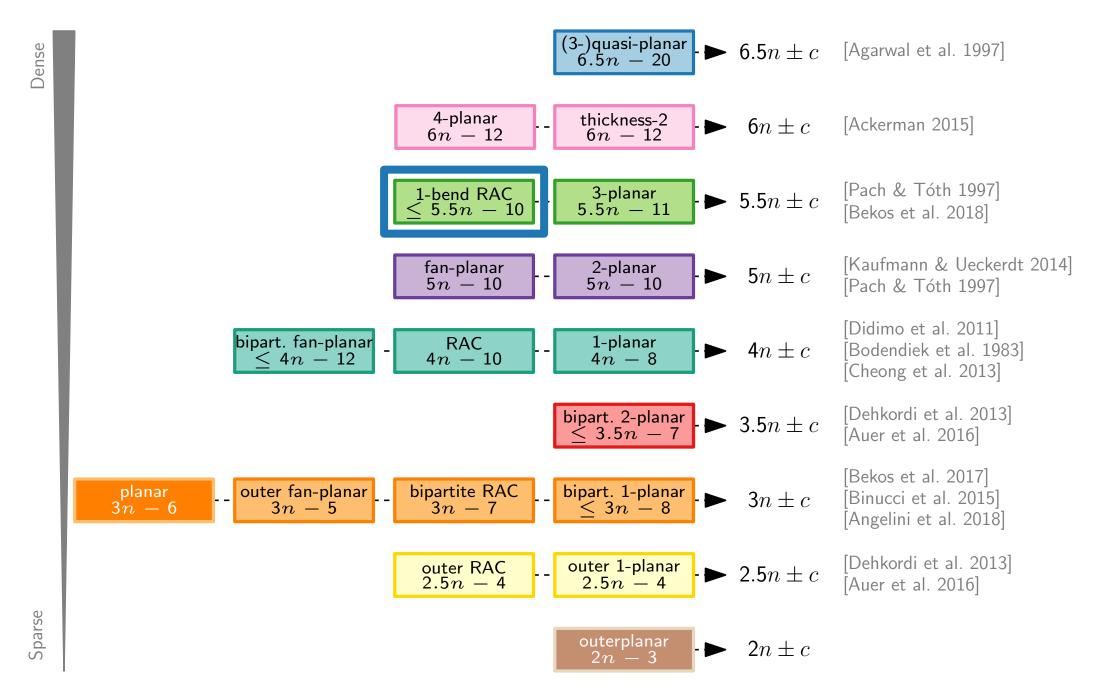
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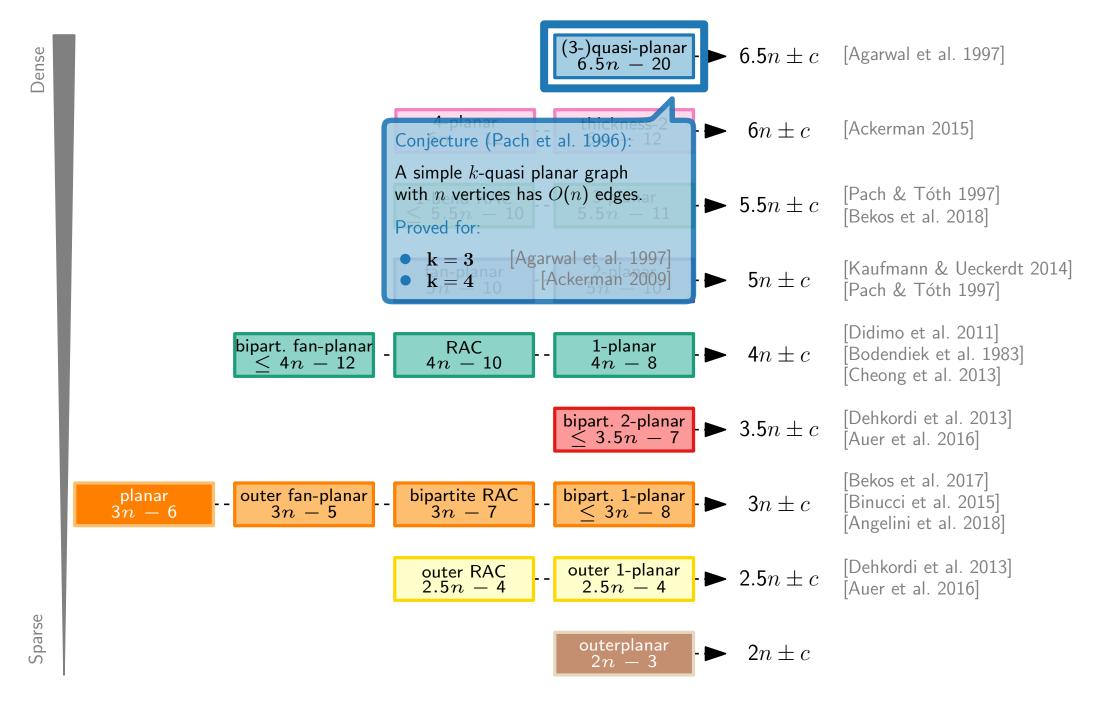












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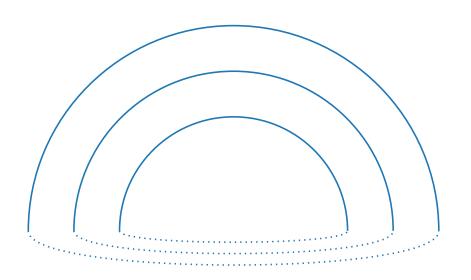
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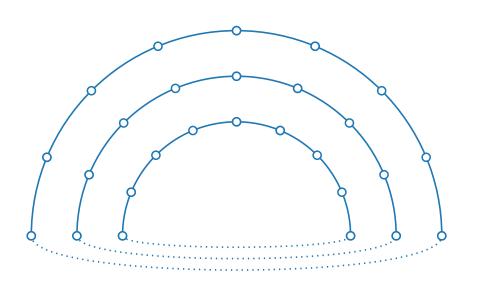


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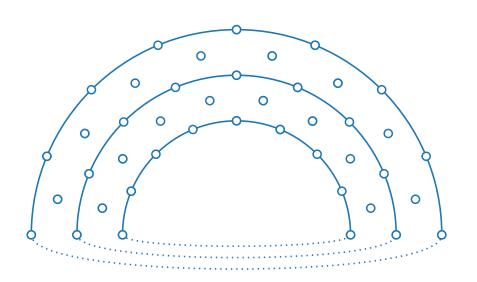


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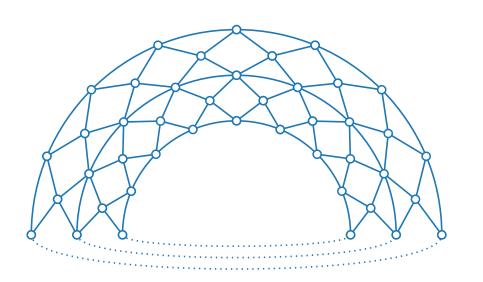


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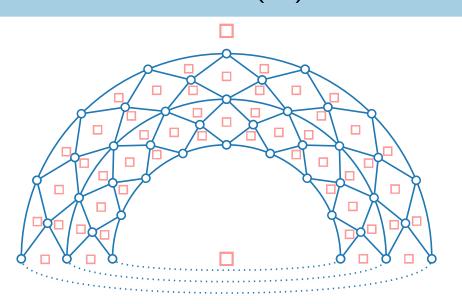


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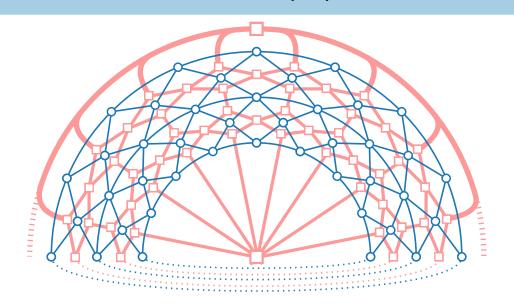


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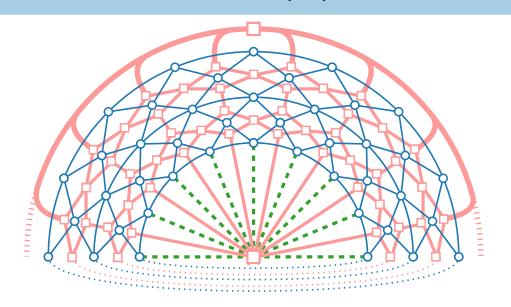


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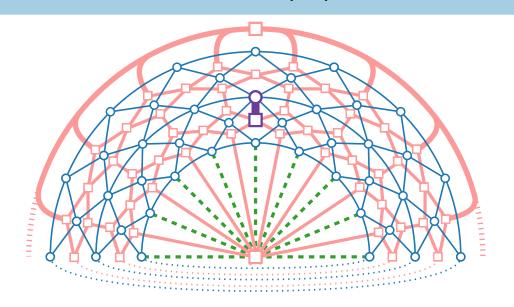


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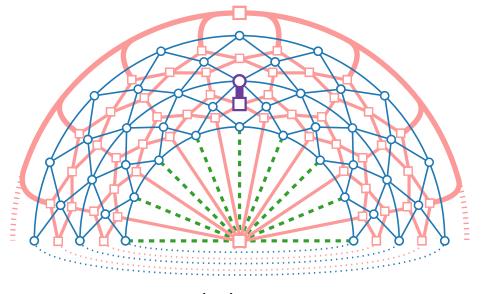


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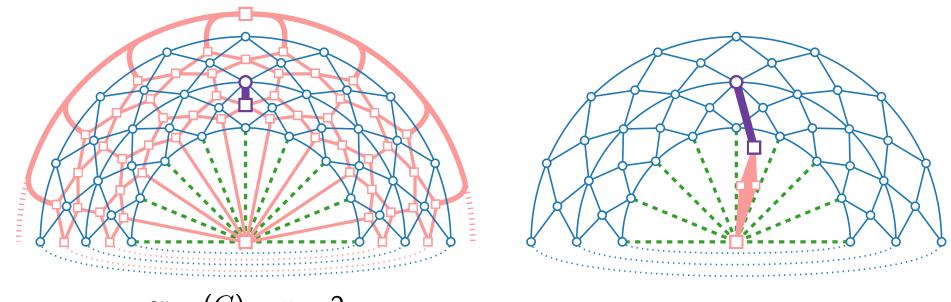
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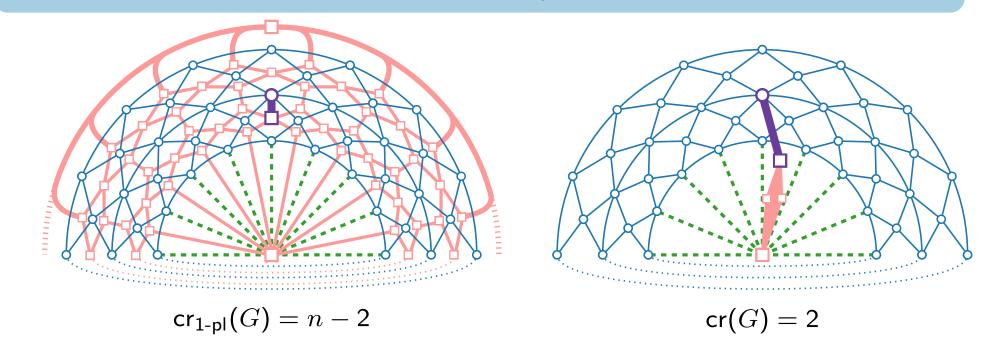
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## Crossing Numbers

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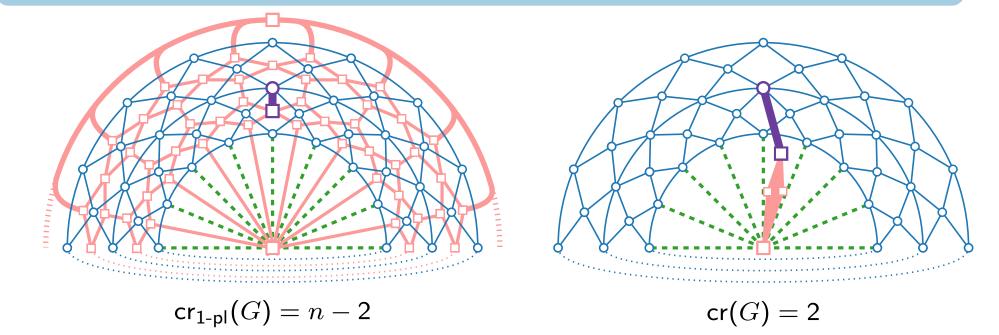
### Theorem.

[Chimani, Kindermann, Montecchiani & Valtr 2019]

For every  $\ell \geq 7$ , there is a 1-planar graph G with  $n=11\ell+2$  vertices such that  $\operatorname{cr}(G)=2$  and  $\operatorname{cr}_{1-\operatorname{pl}}(G)=n-2$ .

### **Crossing ratio**

$$\rho_{1-\mathsf{pl}}(n) = (n-2)/2$$

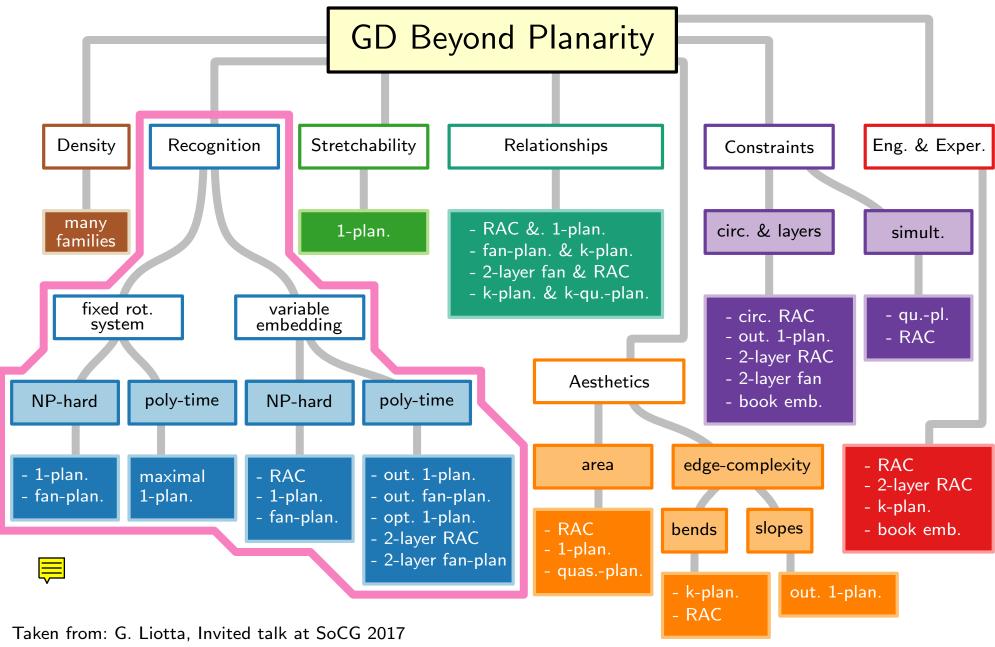


# Table from "Crossing Numbers of Beyond-Planar Graphs Revisited" [van Beusekom, Parada & Speckmann 2021]

# Crossing Ratios

Family	Forbidden Configurations			Lower	Upper
k-planar	An edge crossed more than $k$ times	k = 2		$\Omega(n/k)$	$O(k\sqrt{k}n)$
k-quasi-planar	k pairwise crossing edges		k = 3	$\Omega(n/k^3)$	$\int f(k)n^2 \log^2 n$
Fan-planar	Two independent edges crossing a third or two adjacent edges crossing another edge from different "side"	H		$\Omega(n)$	$O(n^2)$
(k,l)-grid-free	Set of $k$ edges such that each edge crosses each edge from a set of $\ell$ edges.		k, l = 2	$\int \Omega\left(\frac{n}{kl(k+l)}\right)$	$g(k,l)n^2$
k-gap-planar	More than $k$ crossings mapped to an edge in an optimal mapping	k = 1		$\Omega(n/k^3)$	$O(k\sqrt{k}n)$
Skewness- $k$	Set of crossings not covered by at most $k$ edges		k = 1	$\Omega(m{n}/m{k})$	$oldsymbol{O(kn+k^2)}$
k-apex	Set of crossings not covered by at most $k$ vertices	0  k = 1		$\bigcap (n/k)$	$O(k^2n^2+k^4)$
Planarly connected	Two crossing edges that do not have two of their endpoint connected by a crossing-free edge		X	$\Omega(n^2)$	$O(n^2)$
k-fan-crossing-free	An edge that crosses $k$ adjacent edges	k = 2		$\Omega(n^2/k^3)$	$O(k^2n^2)$
Straight-line RAC	Two edges crossing at an angle $< \frac{\pi}{2}$		X	$\Omega(\boldsymbol{n}^2)$	$O(n^2)$

## GD Beyond Planarity: a Taxonomy



<sup>&</sup>quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

### Theorem.

[Kuratowski 1930]

G planar  $\Leftrightarrow$  neither  $K_5$  nor  $K_{3,3}$  minor of G

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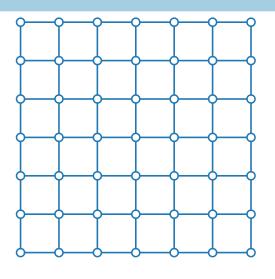
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The class of 1-planar graphs is not closed under edge contraction.



 $n \times n$  grid

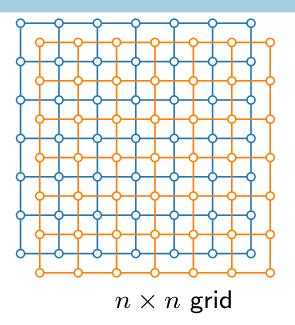
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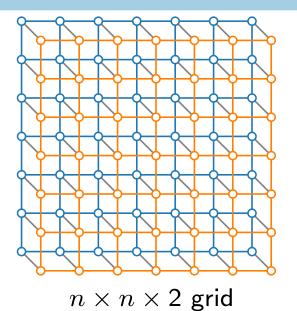
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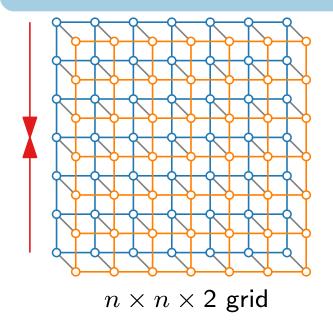
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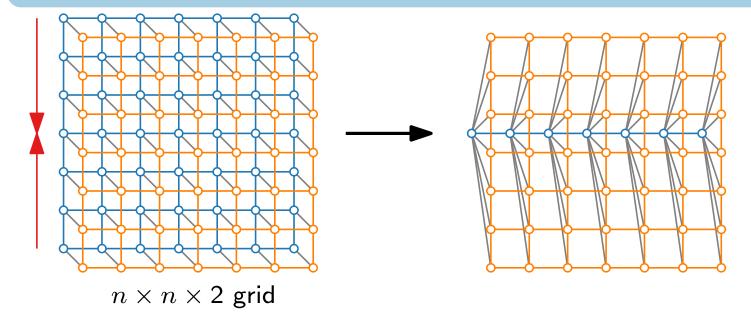
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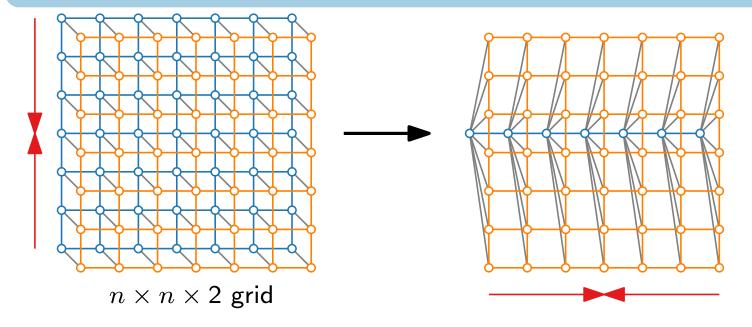
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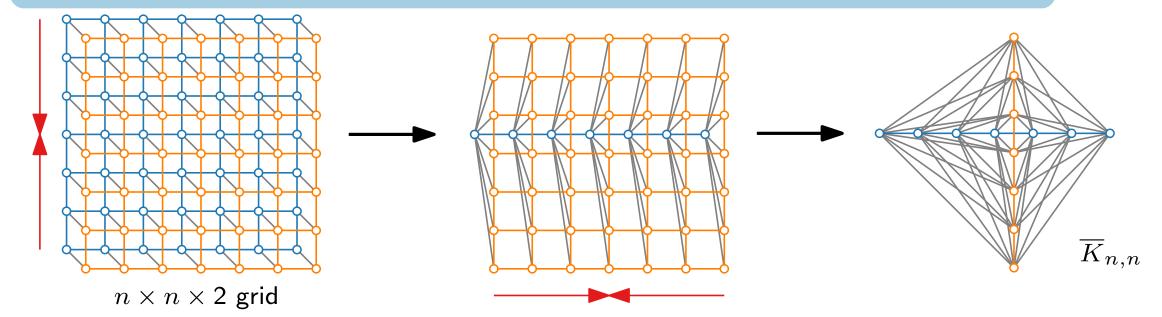
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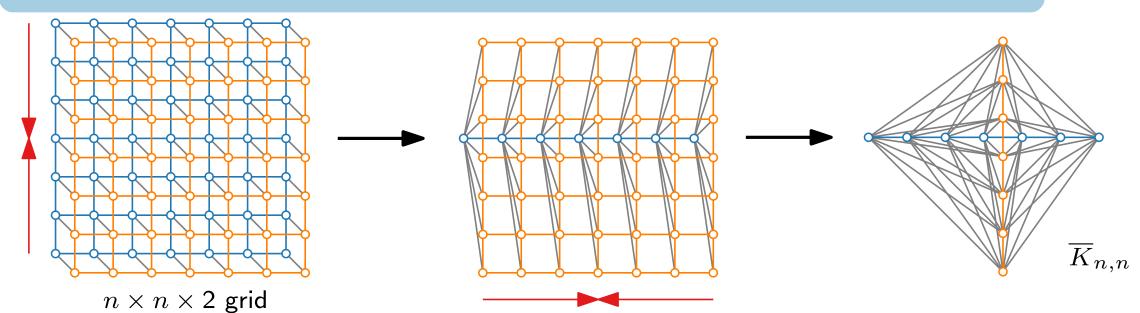
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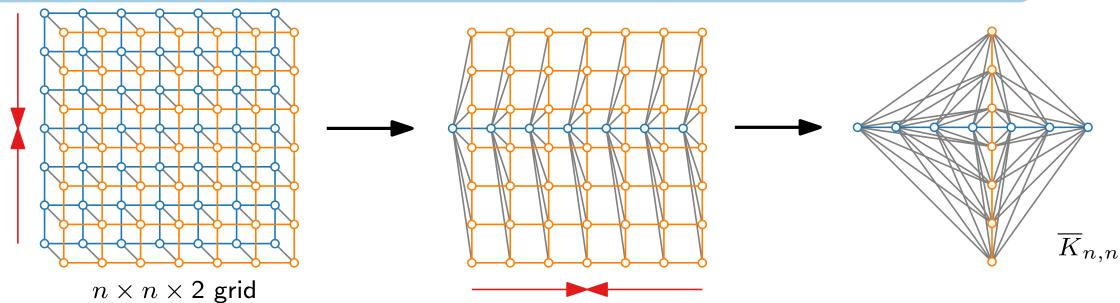
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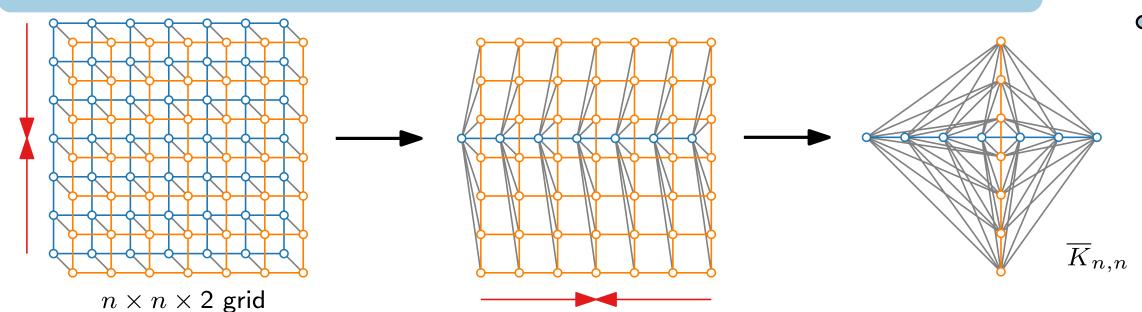
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#### Theorem.

[Korzhik & Mohar 2013]

For any n, there exist  $\Omega(2^n)$  distinct n-vertex graphs that are not 1-planar but all their proper subgraphs are 1-planar.

Theorem.

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Testing 1-planarity

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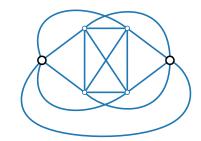
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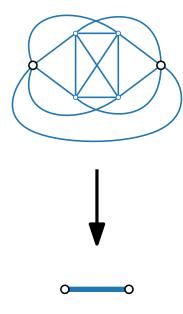
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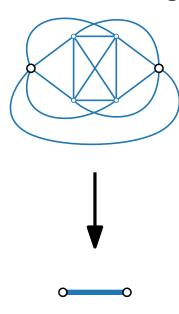
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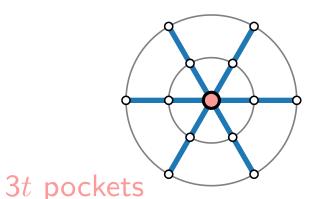
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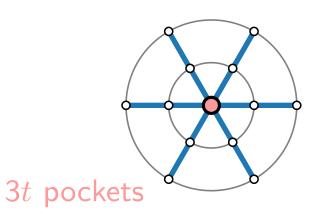
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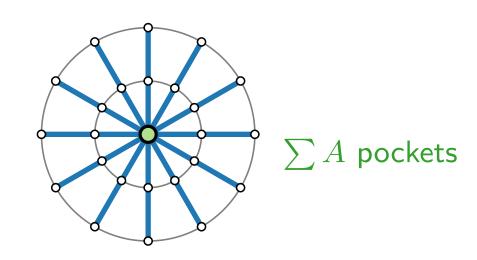
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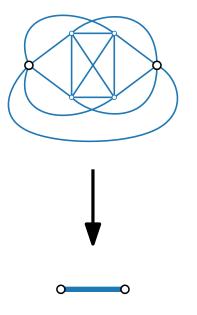
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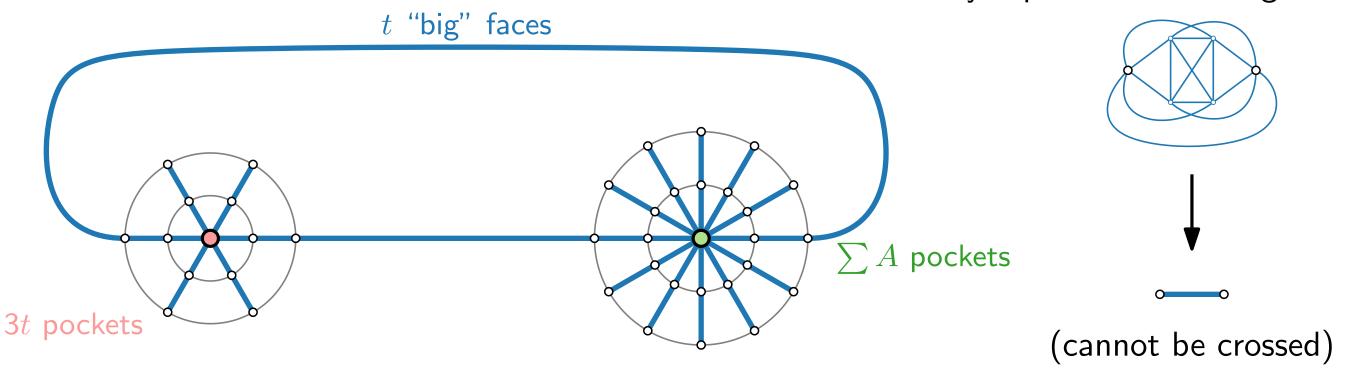
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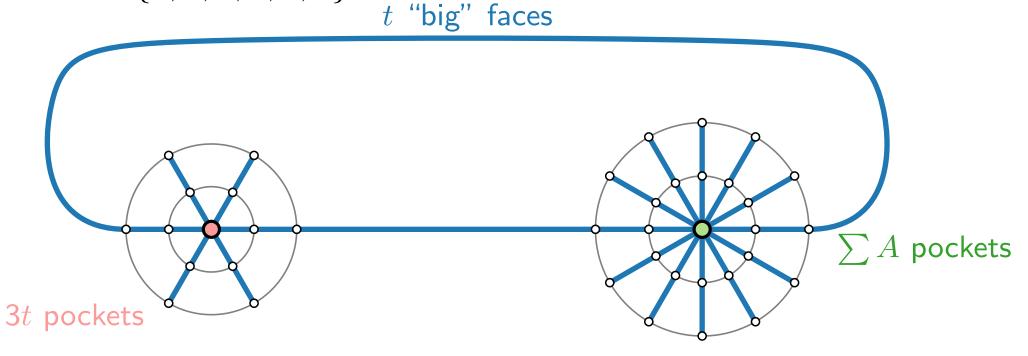
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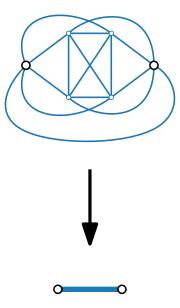
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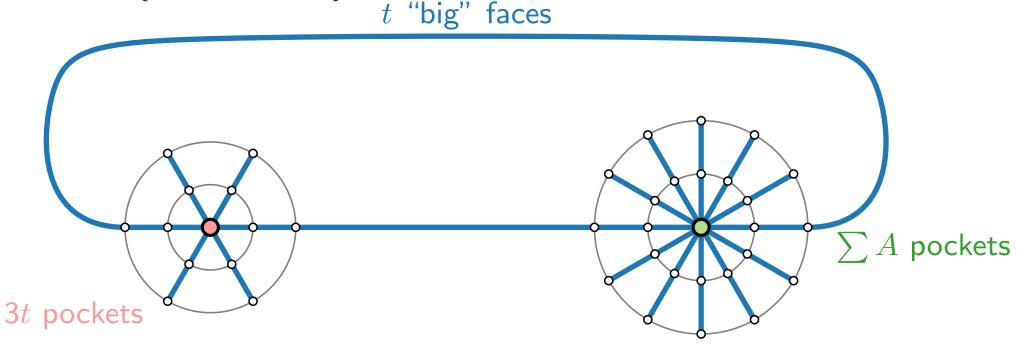
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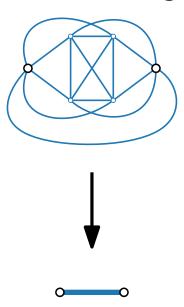
Reduction from 3-Partition.

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The only 1-planar embedding of  $K_6$ :





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[Grigoriev & Bodlaender 2007, Korzhik & Mohar 2013]

Testing 1-planarity is NP-complete.

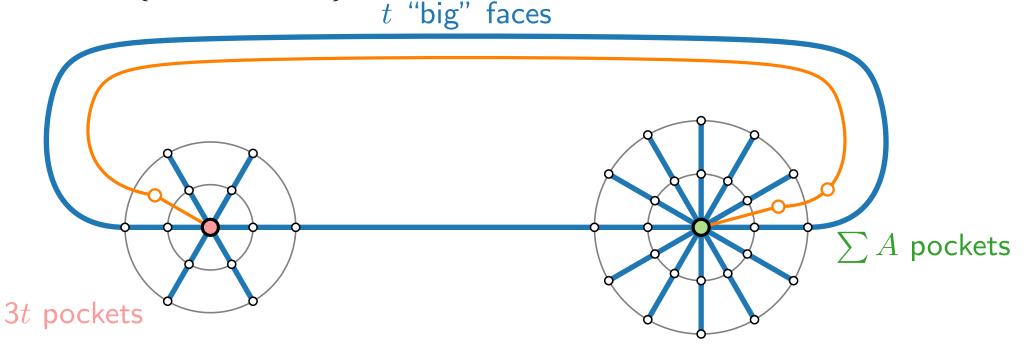
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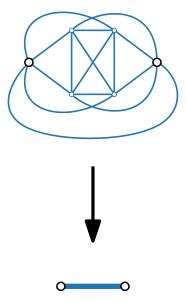
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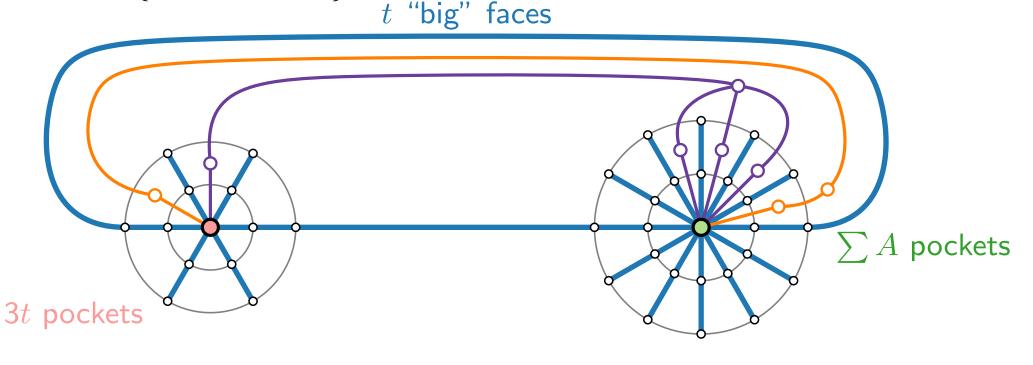
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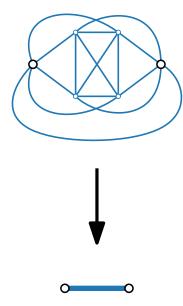
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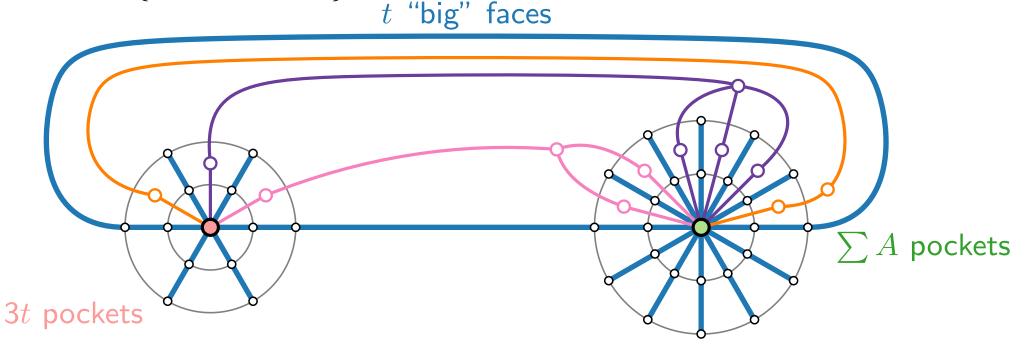
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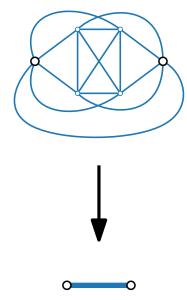
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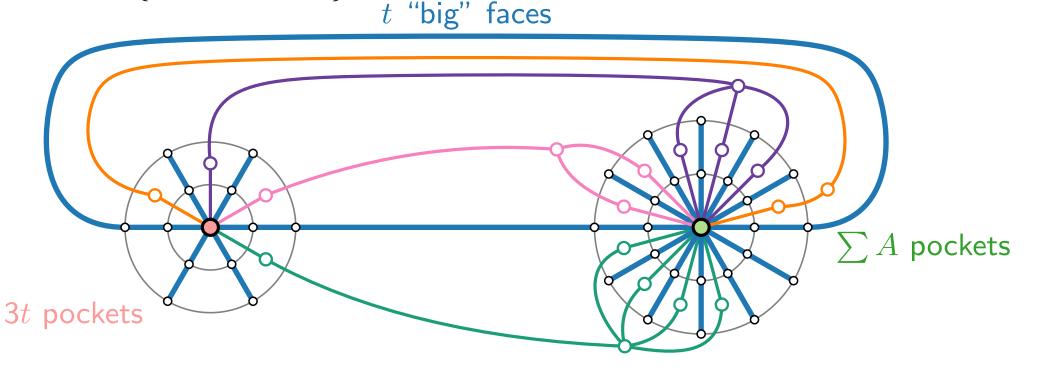
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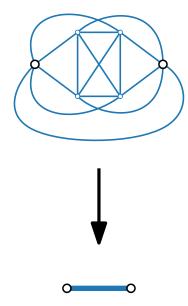
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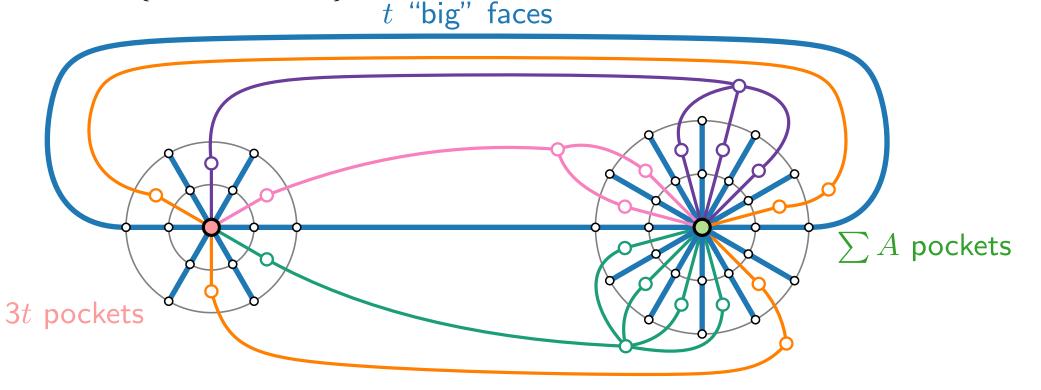
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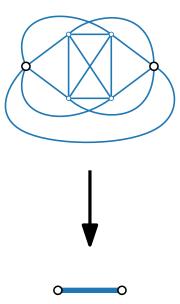
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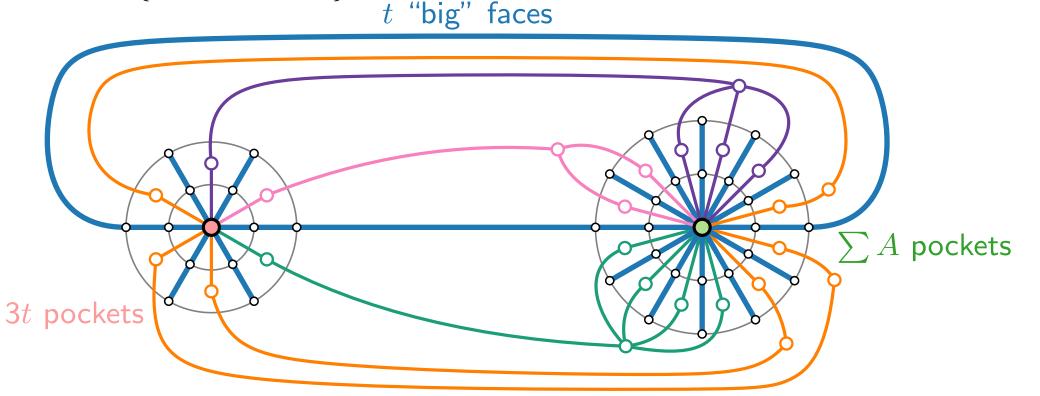
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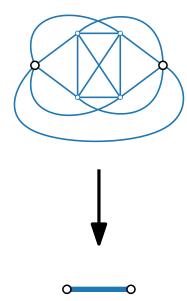
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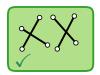
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[Auer, Brandenburg, Gleißner & Reislhuber 2015]

Testing 1-planarity is NP-complete – even for 3-connected graphs with a fixed rotation system.

**Theorem.** [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

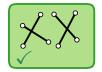
Testing IC-planarity is NP-complete.





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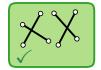




#### Proof.

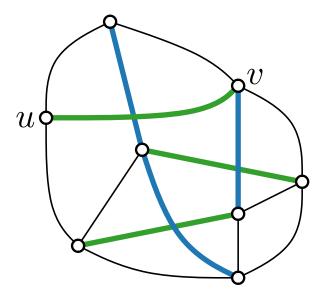
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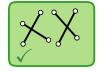


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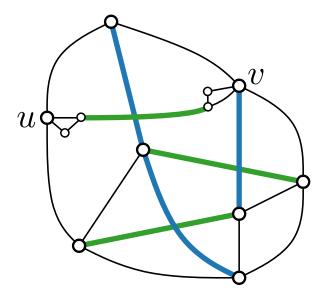
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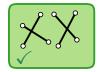


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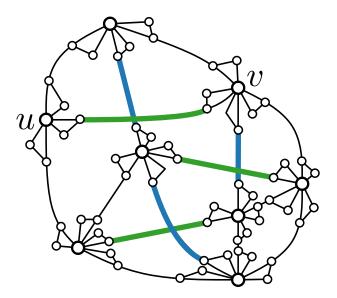
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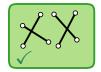


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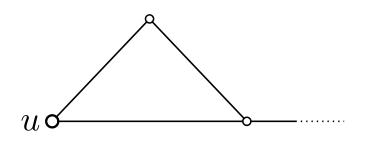
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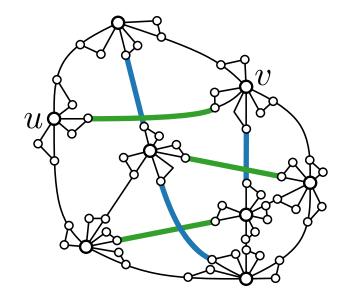
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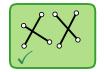
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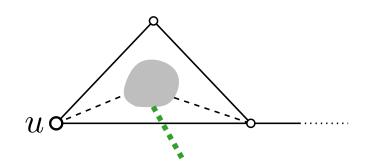
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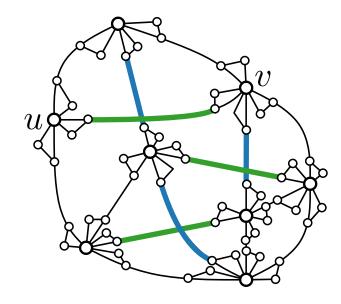
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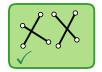
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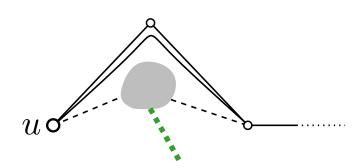
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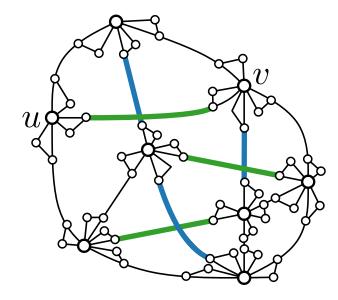
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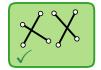
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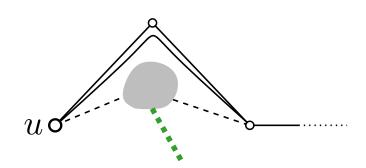
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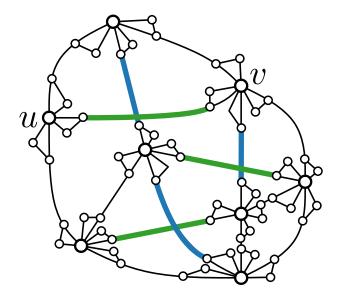




#### Proof.

Reduction from 1-planarity testing.

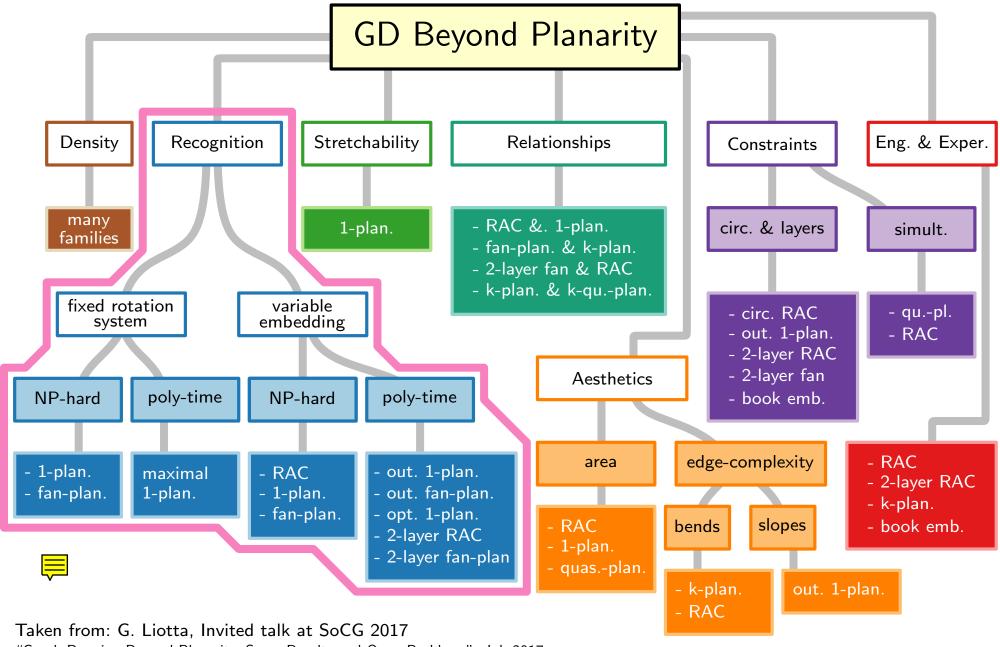




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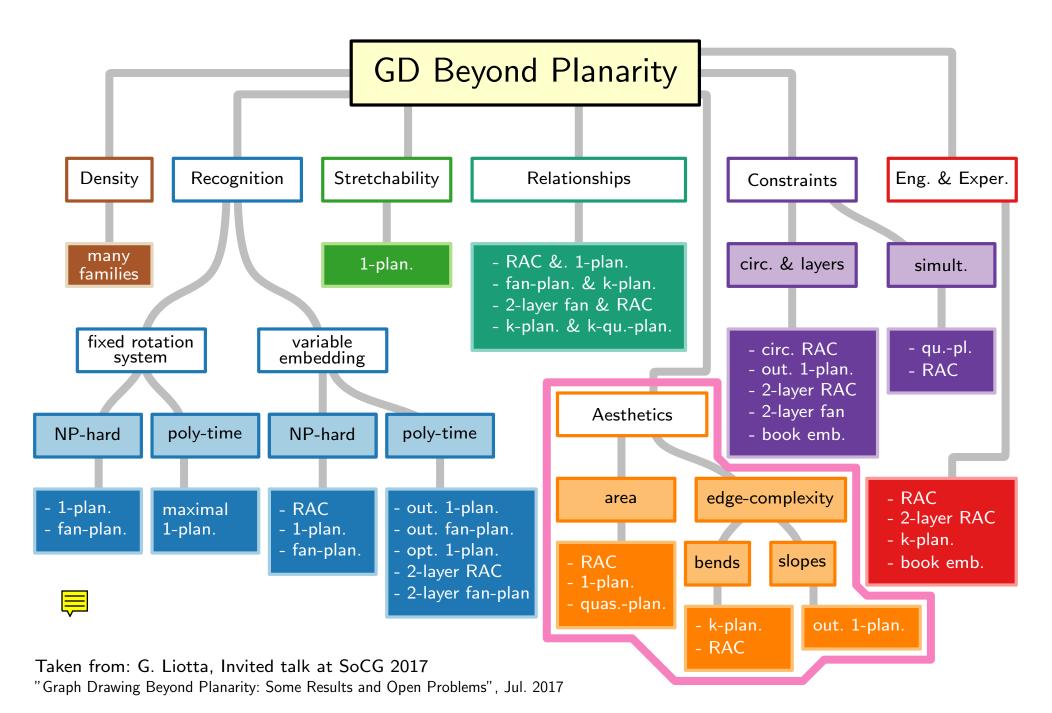
Testing IC-planarity is NP-complete, even if the rotation system is given.

#### GD Beyond Planarity: a Taxonomy



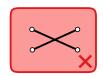
<sup>&</sup>quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

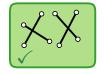
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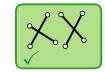


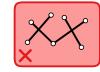


**Theorem.** [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015] Some IC-planar straight-line RAC drawings require exponential area.







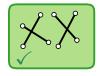




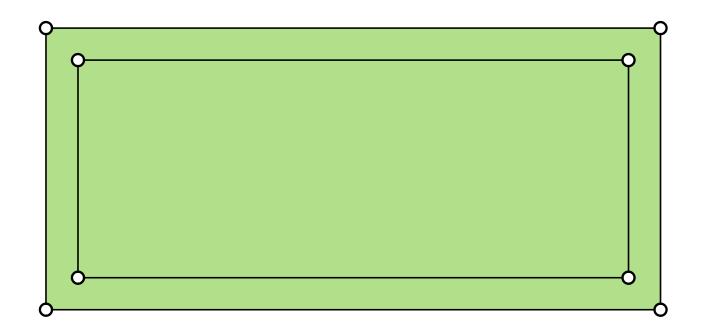
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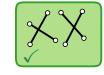




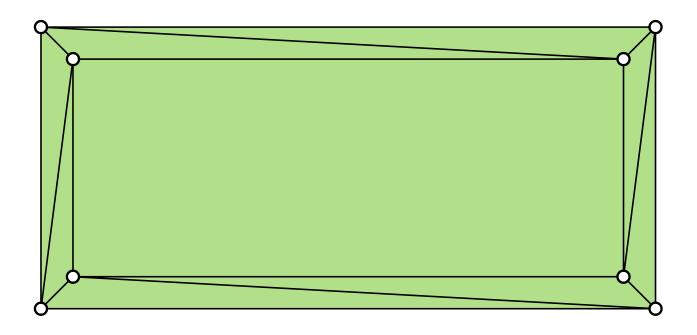
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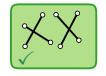




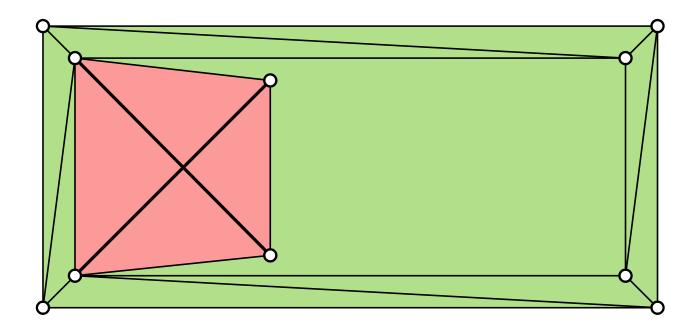
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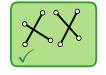




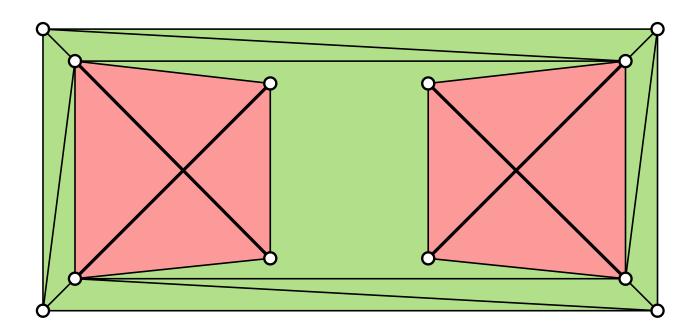
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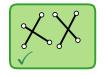




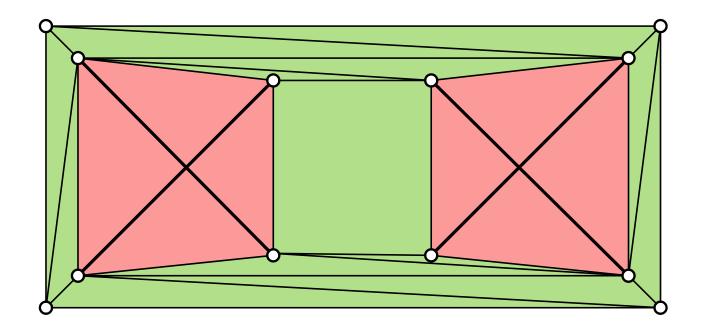
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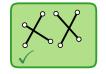




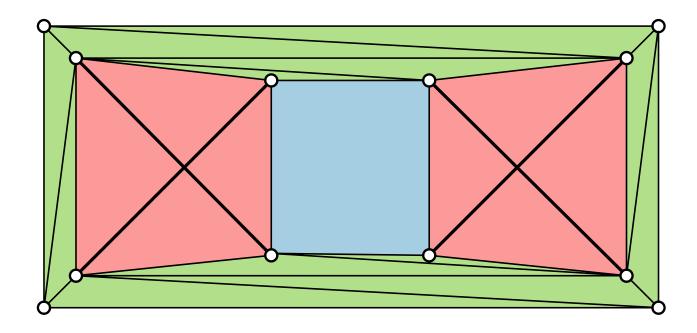
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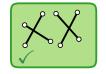




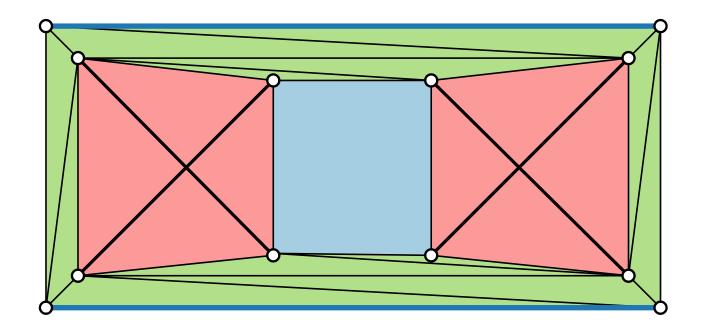
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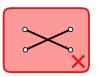






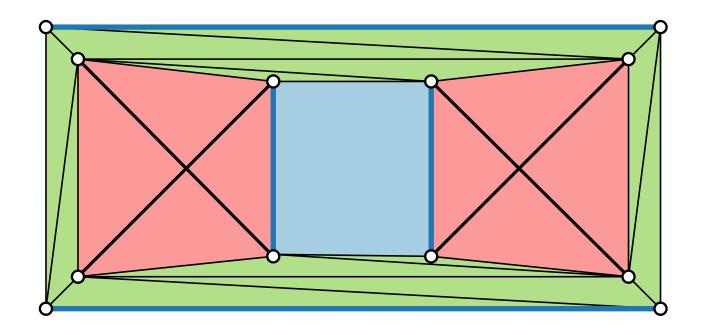
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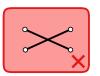


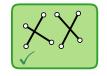




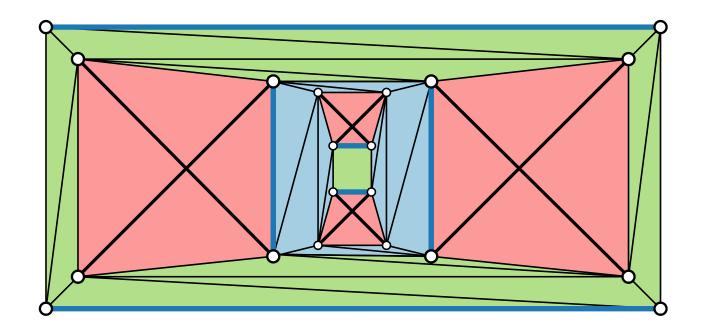
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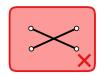


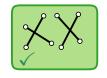




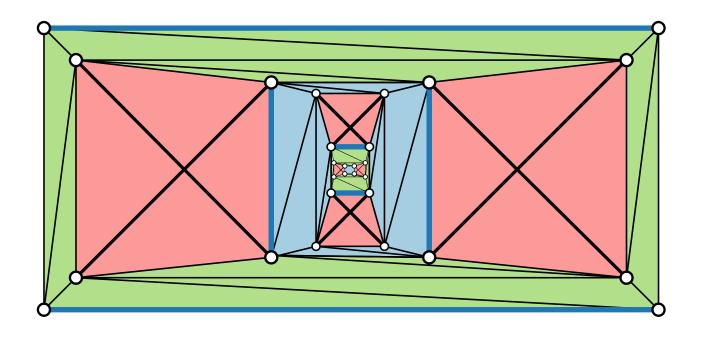
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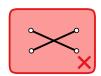


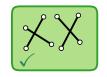


**Theorem.** [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Some IC-planar straight-line RAC drawings require exponential area.



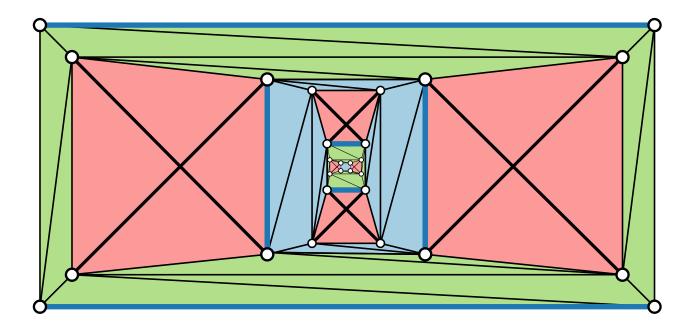






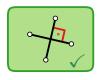
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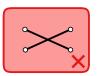
Every IC-planar graph has an IC-planar straight-line RAC drawing, and such a drawing can be found in polynomial time.

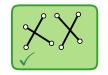


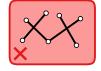
**Theorem.** [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Some IC-planar straight-line RAC drawings require exponential area.



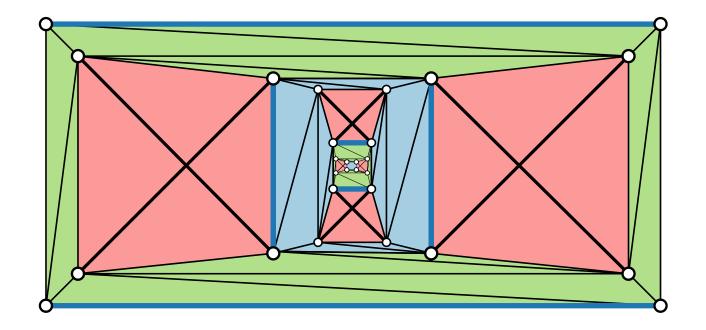






**Theorem.** [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

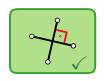
Every IC-planar graph has an IC-planar straight-line RAC drawing, and such a drawing can be found in polynomial time.



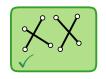
In constrast:
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RAC drawing

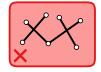
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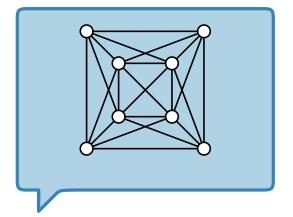


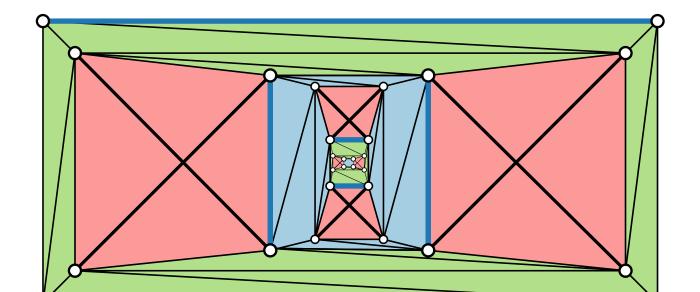




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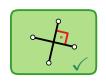


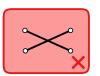


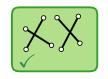
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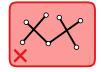
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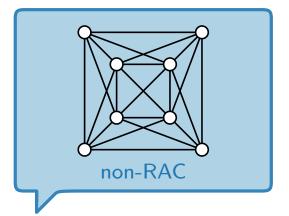


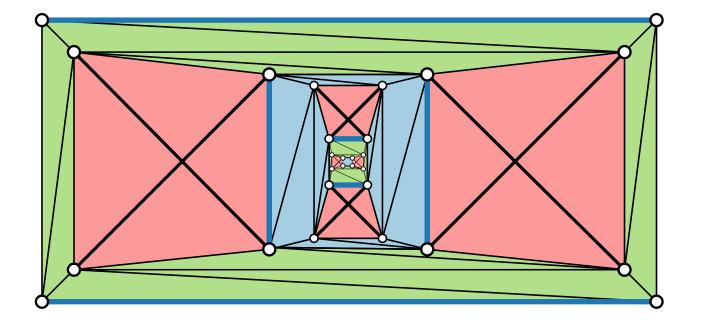




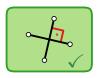
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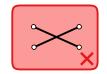
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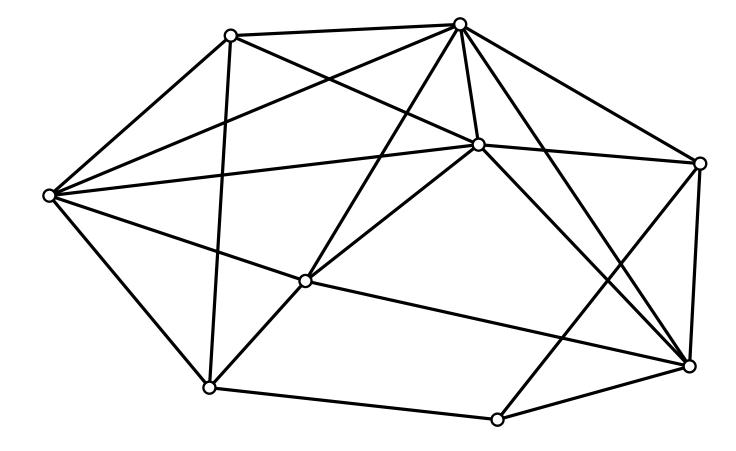


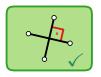


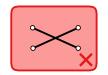
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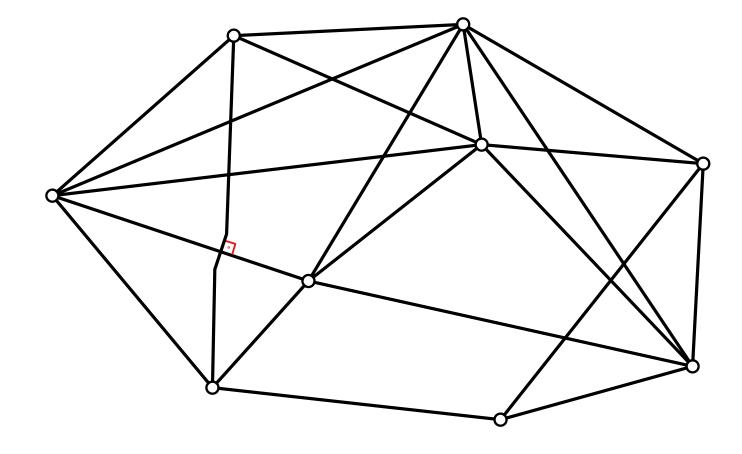




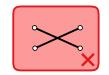


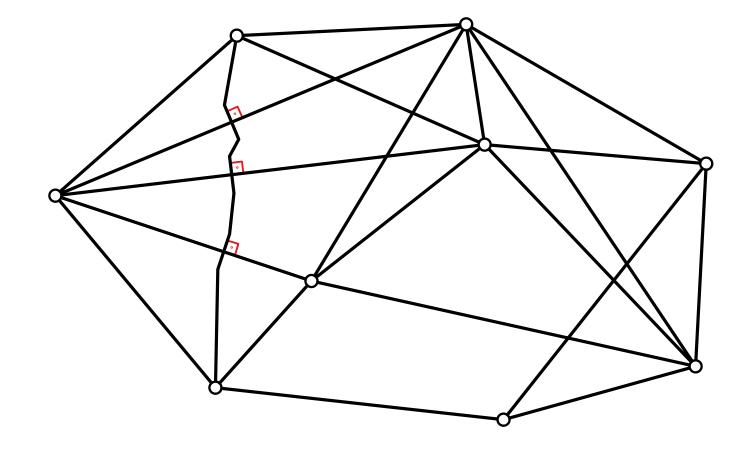


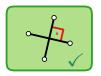


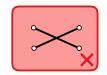


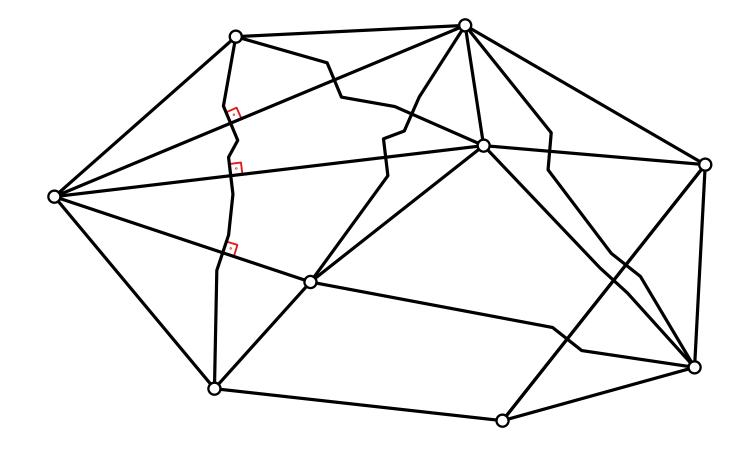


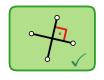


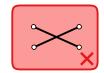


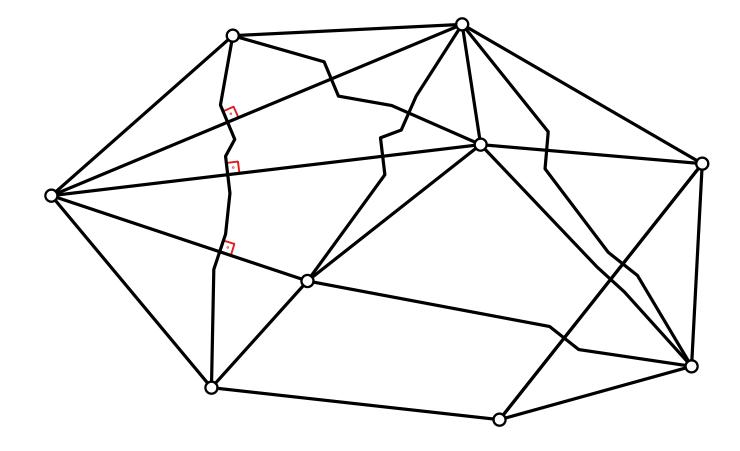






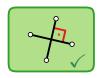


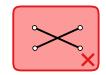


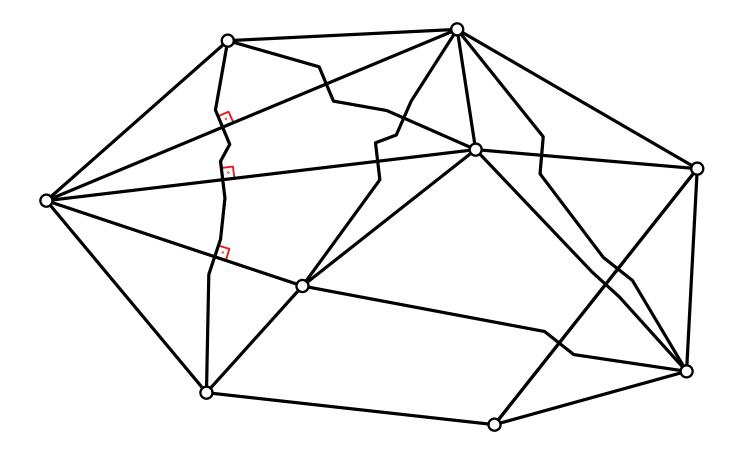


Every graph admits a RAC drawing ...

## RAC Drawings With Enough Bends



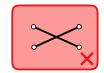


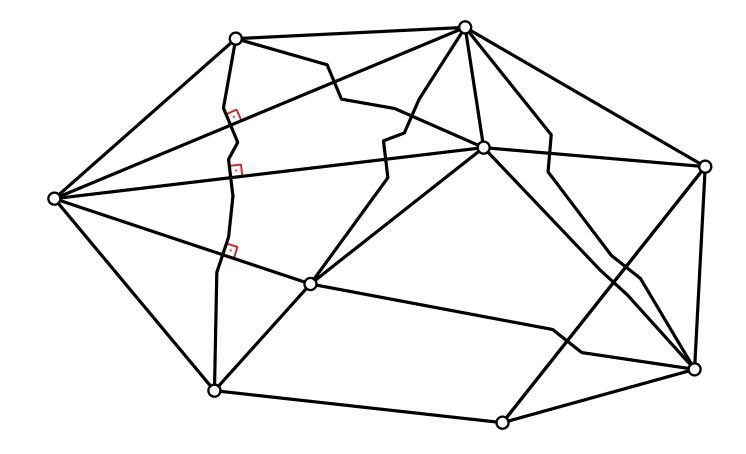


Every graph admits a RAC drawing ... if we use enough bends.

## RAC Drawings With Enough Bends







Every graph admits a RAC drawing ... if we use enough bends.

How many do we need – in total or per edge?

#### 3-Bend RAC Drawings

#### Theorem.

[Didimo, Eades & Liotta 2017]

Every graph admits a 3-bend RAC drawing, that is, a RAC drawing where every edge has at most three bends.

#### 3-Bend RAC Drawings

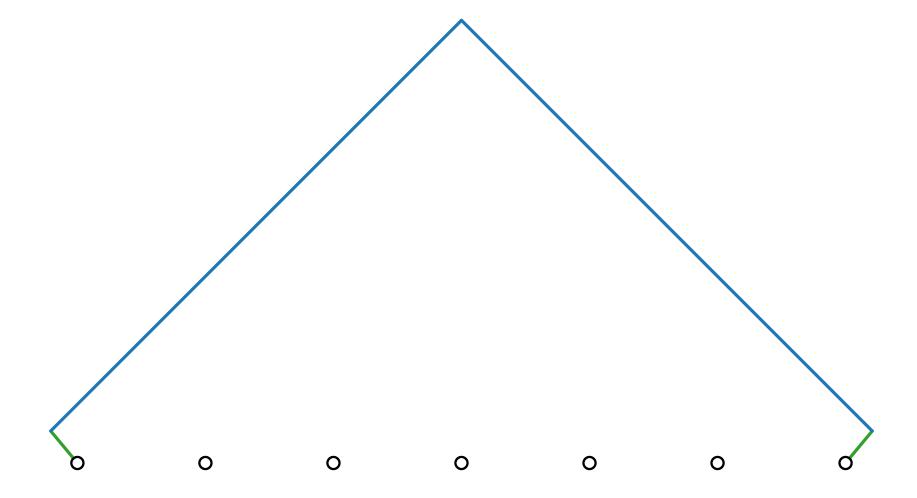
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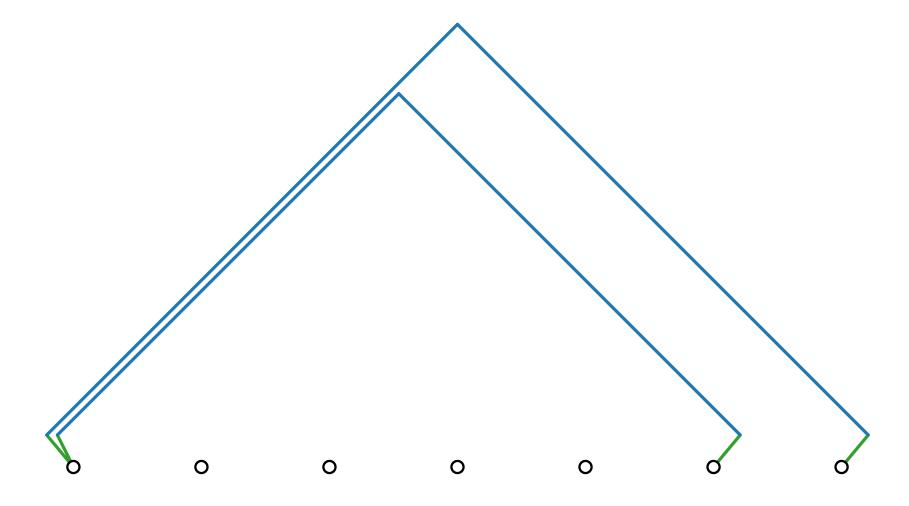
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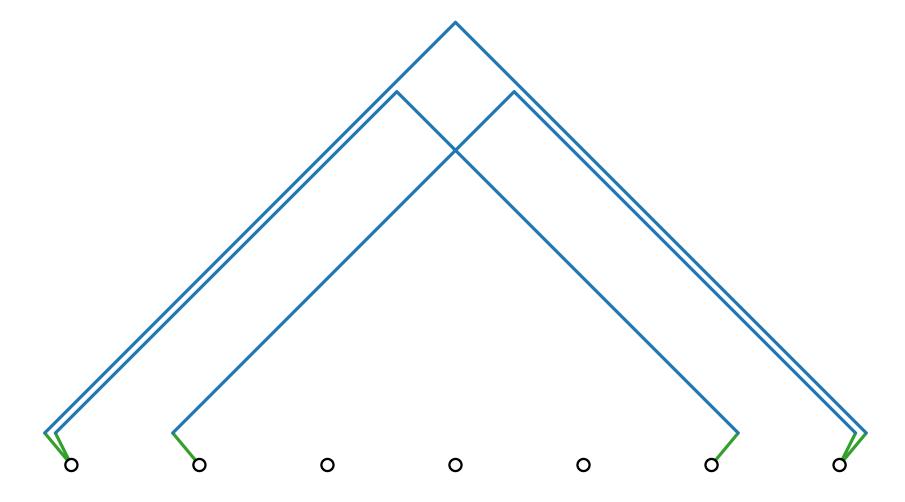
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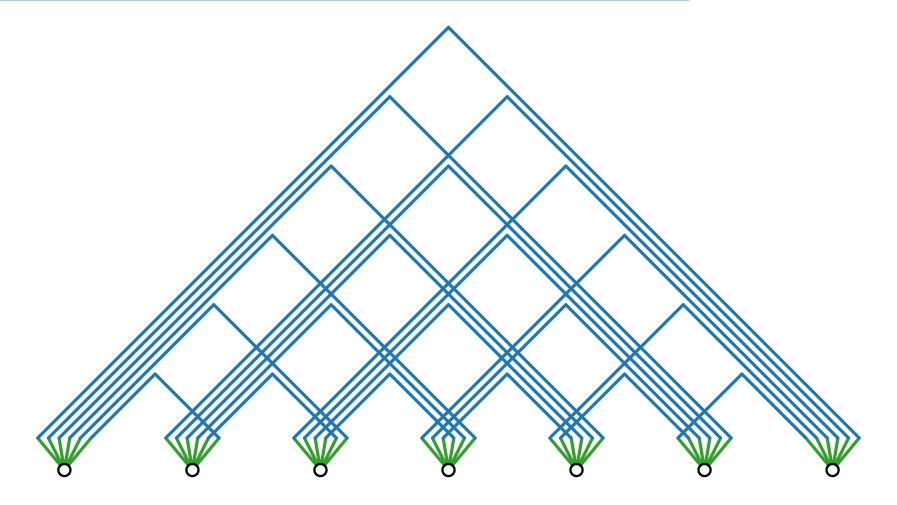
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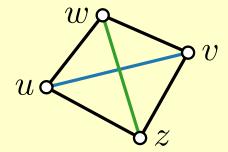


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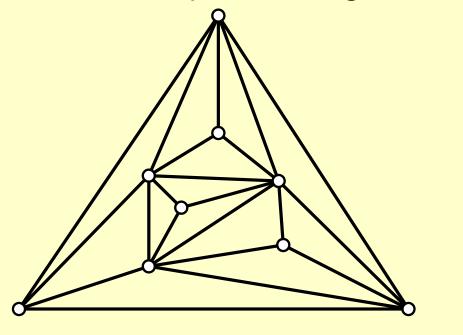
### This is a **kite**:

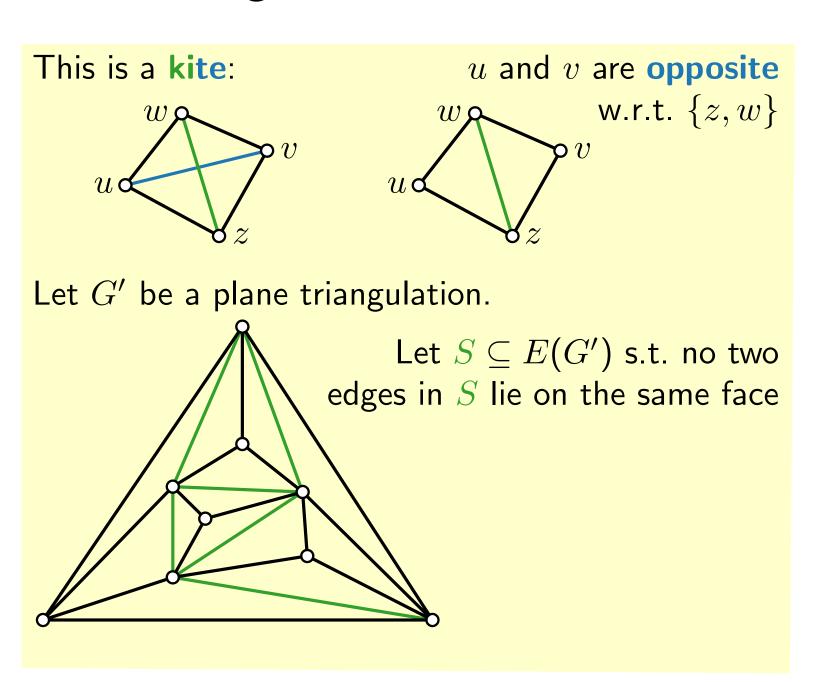


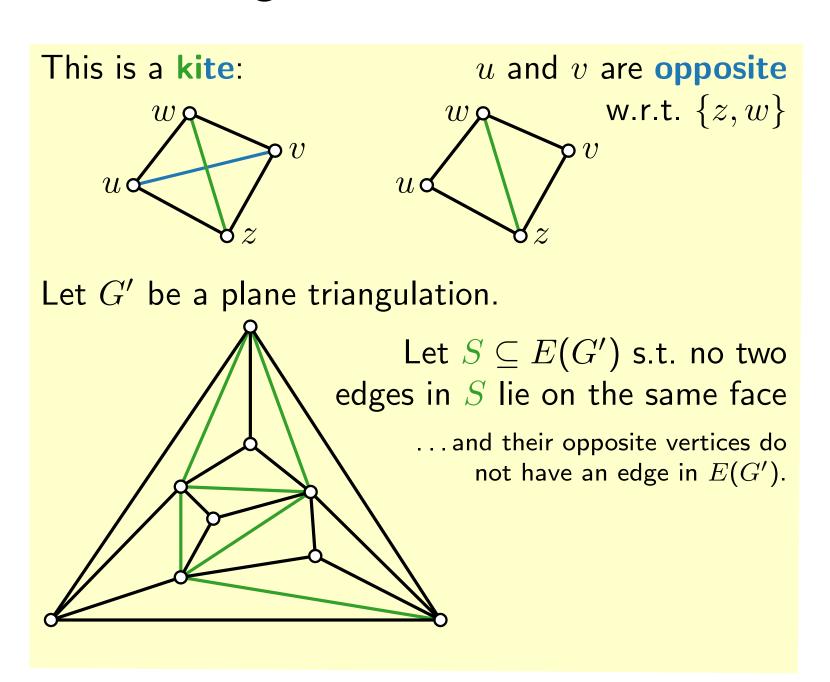
# This is a **kite**: u and v are **opposite** w.r.t. $\{z,w\}$

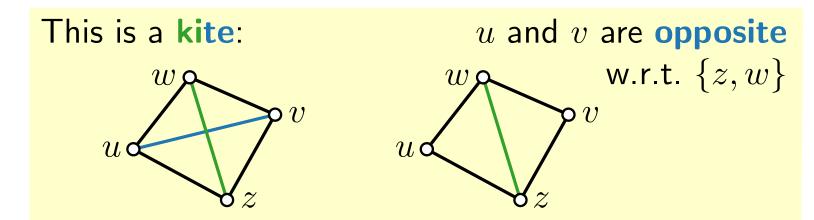
This is a **kite**: u and v are **opposite** w.r.t.  $\{z,w\}$ 

Let G' be a plane triangulation.

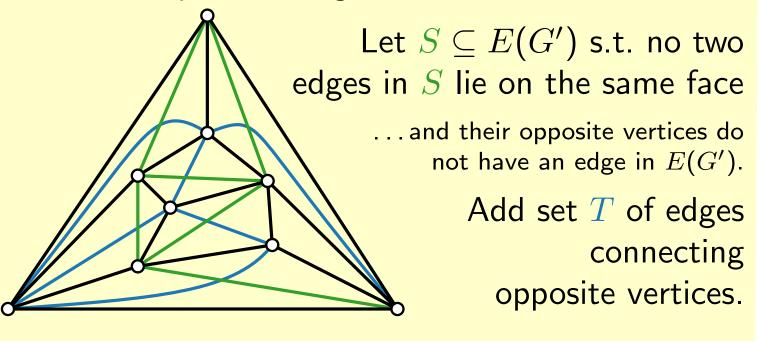


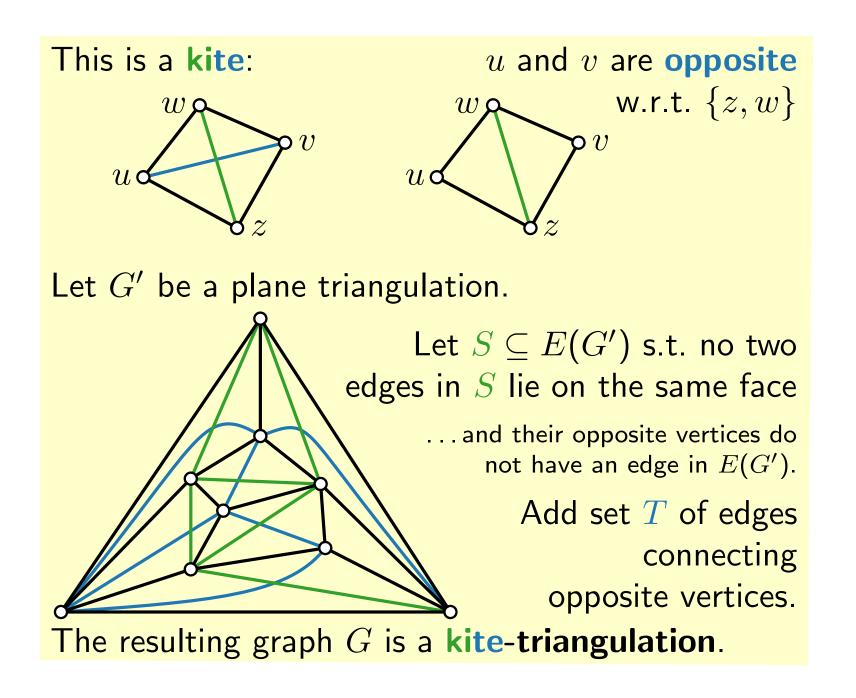


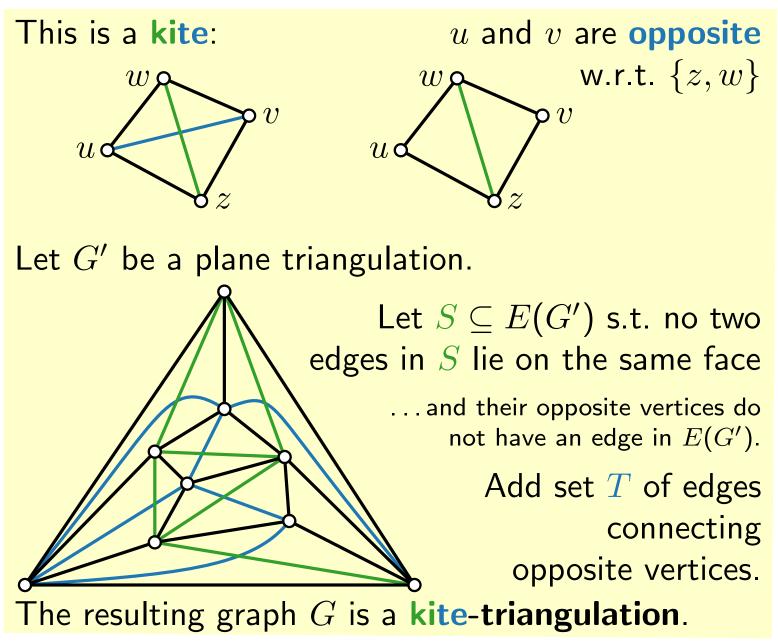




Let G' be a plane triangulation.



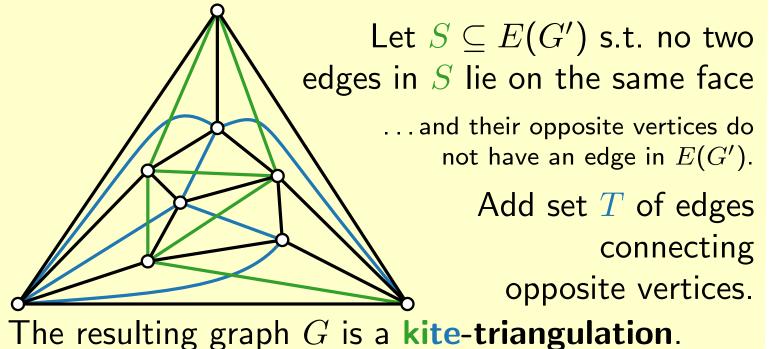




**Note:** optimal 1-planar graphs  $\subseteq$  kite-triangulations.

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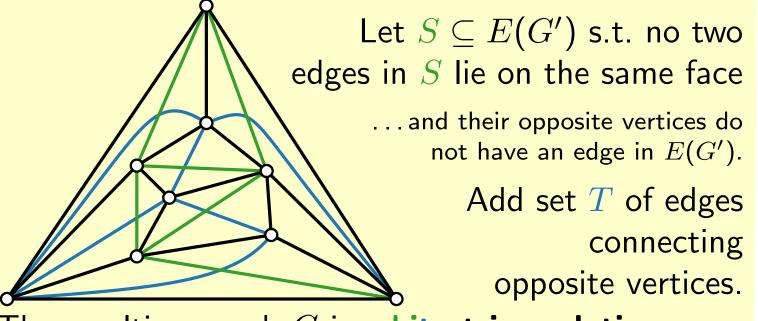
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**Theorem.** [Angelini et al. 2011]

Every kite-triangulation G admits a 1-planar 1-bend RAC drawing

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The resulting graph G is a kite-triangulation.

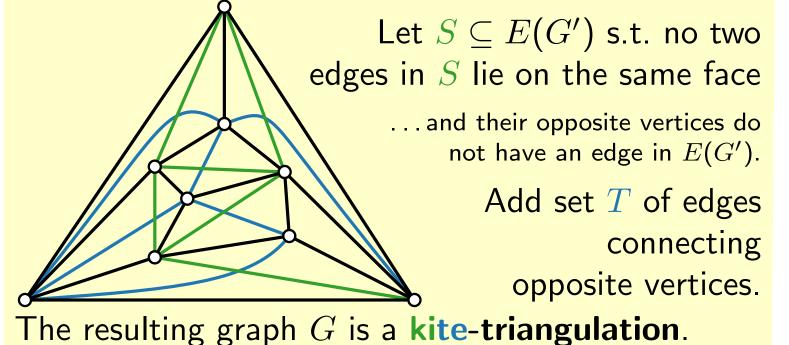
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Every kite-triangulation G admits a 1-planar 1-bend RAC drawing, which can be constructed in linear time.

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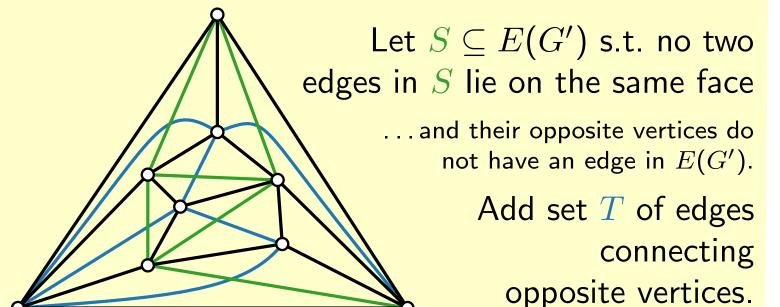
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Proof.

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**Note:** optimal 1-planar graphs  $\subseteq$  kite-triangulations.

### **Theorem.** [Angelini et al. 2011]

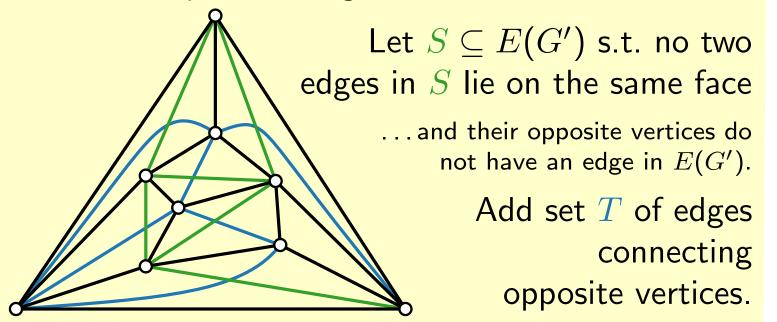
Every kite-triangulation G admits a 1-planar 1-bend RAC drawing, which can be constructed in linear time.

#### Proof.

Let G' be the underlying plane triangulation of G.

This is a **kite**: u and v are **opposite** w.r.t.  $\{z, w\}$ 

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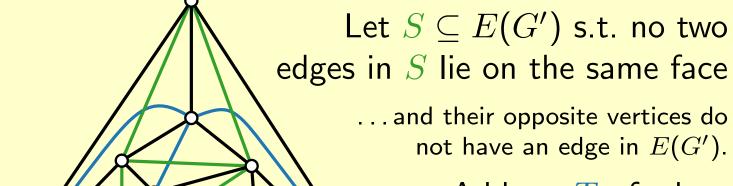
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#### Proof.

Let G' be the underlying plane triangulation of G. Let G'' = G' - S.

This is a **kite**: u and v are **opposite** w.r.t.  $\{z, w\}$ 

Let G' be a plane triangulation.



Add set *T* of edges connecting opposite vertices.

The resulting graph G is a **kite-triangulation**.

**Note:** optimal 1-planar graphs  $\subseteq$  kite-triangulations.

### **Theorem.** [Angelini et al. 2011]

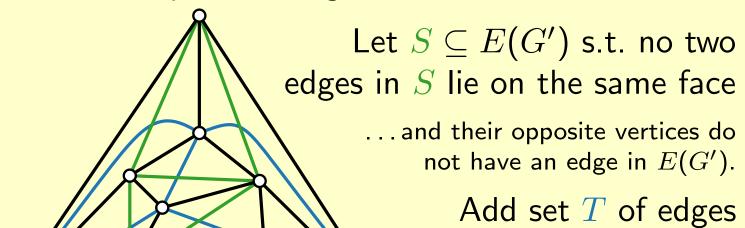
Every kite-triangulation G admits a 1-planar 1-bend RAC drawing, which can be constructed in linear time.

#### Proof.

Let G' be the underlying plane triangulation of G. Let G'' = G' - S. Construct straight-line drawing of G''.

This is a **kite**: u and v are **opposite** w.r.t.  $\{z, w\}$ 

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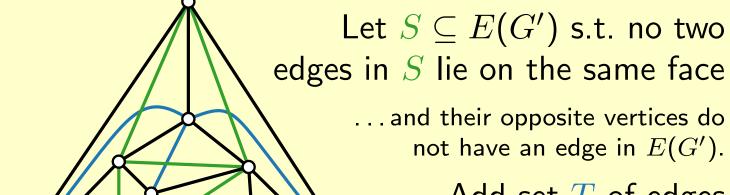
#### Proof.

connecting

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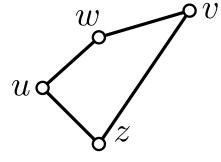
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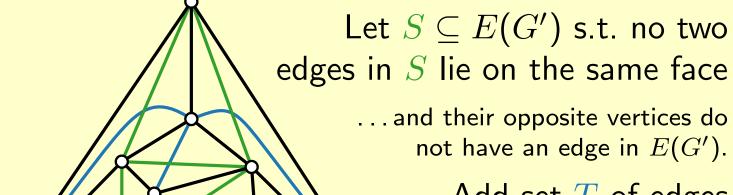
Let G' be the underlying plane triangulation of G. Let G'' = G' - S. Construct straight-line drawing of G''. Fill faces as follows:



strictly convex face

This is a **kite**: u and v are **opposite** w.r.t.  $\{z, w\}$ 

Let G' be a plane triangulation.



Add set *T* of edges connecting opposite vertices.

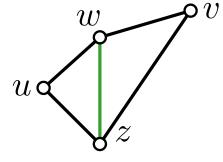
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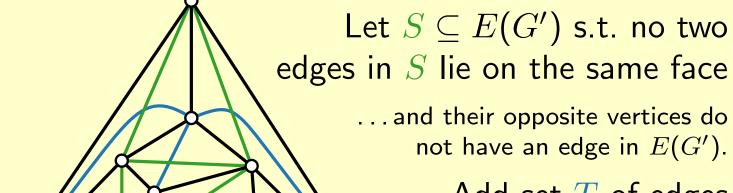
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Let G' be a plane triangulation.



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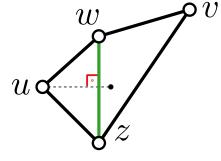
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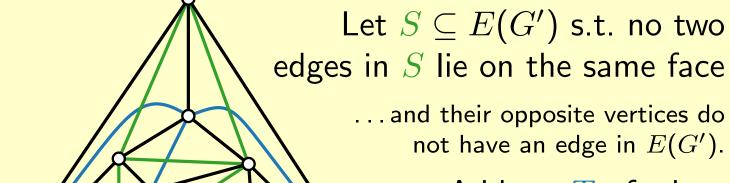
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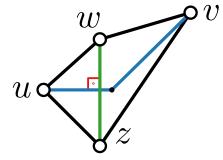
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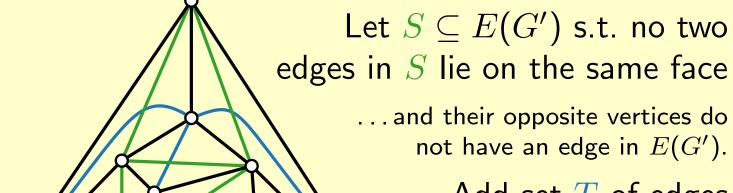
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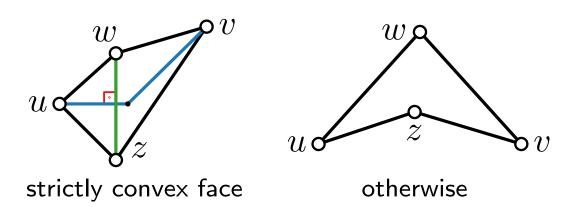
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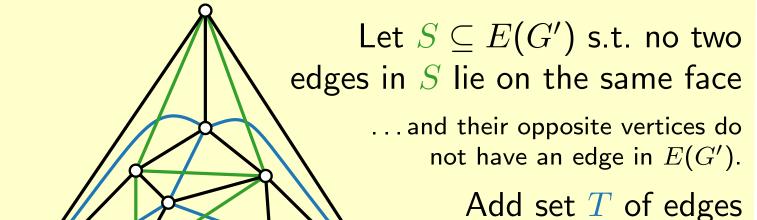
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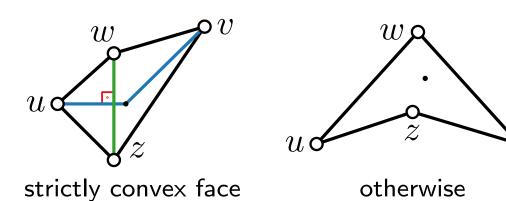
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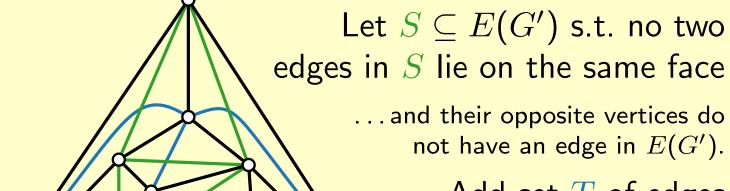
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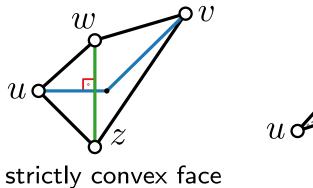
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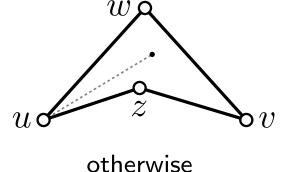
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Every kite-triangulation G admits a 1-planar 1-bend RAC drawing, which can be constructed in linear time.

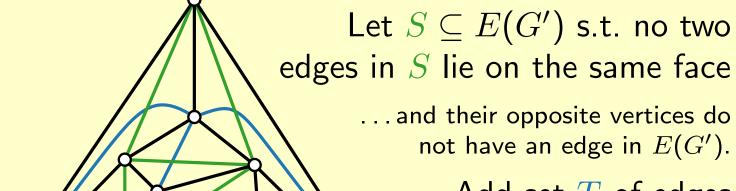
#### Proof.





This is a **kite**: u and v are **opposite** w.r.t.  $\{z, w\}$ 

Let G' be a plane triangulation.



Add set *T* of edges connecting opposite vertices.

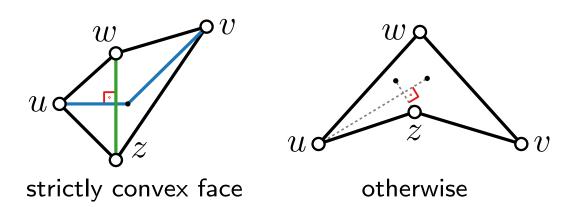
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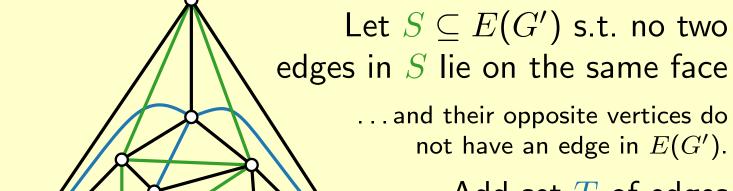
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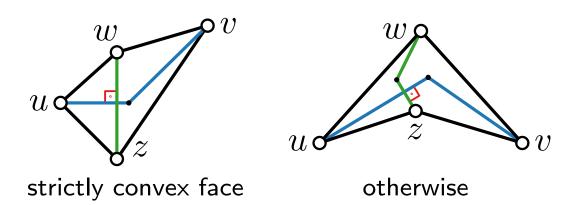
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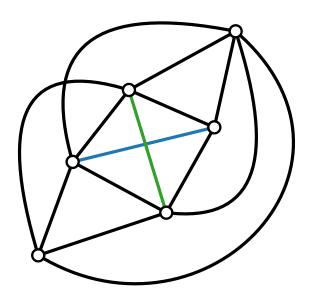
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In a triangulated 1-plane graph (not necessarily simple), each pair of crossing edges of G forms an empty kite,

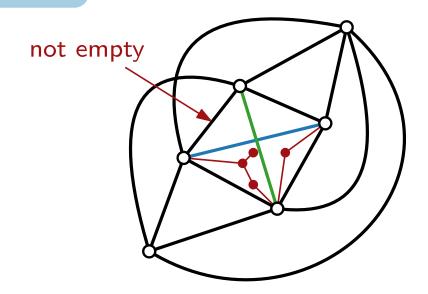


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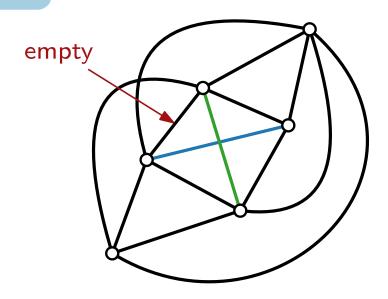


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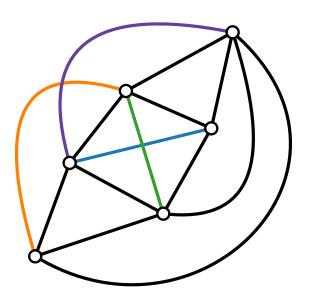


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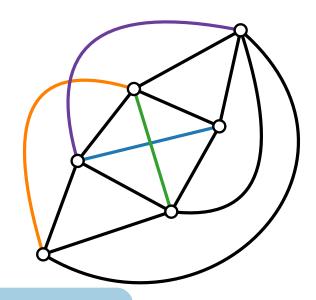


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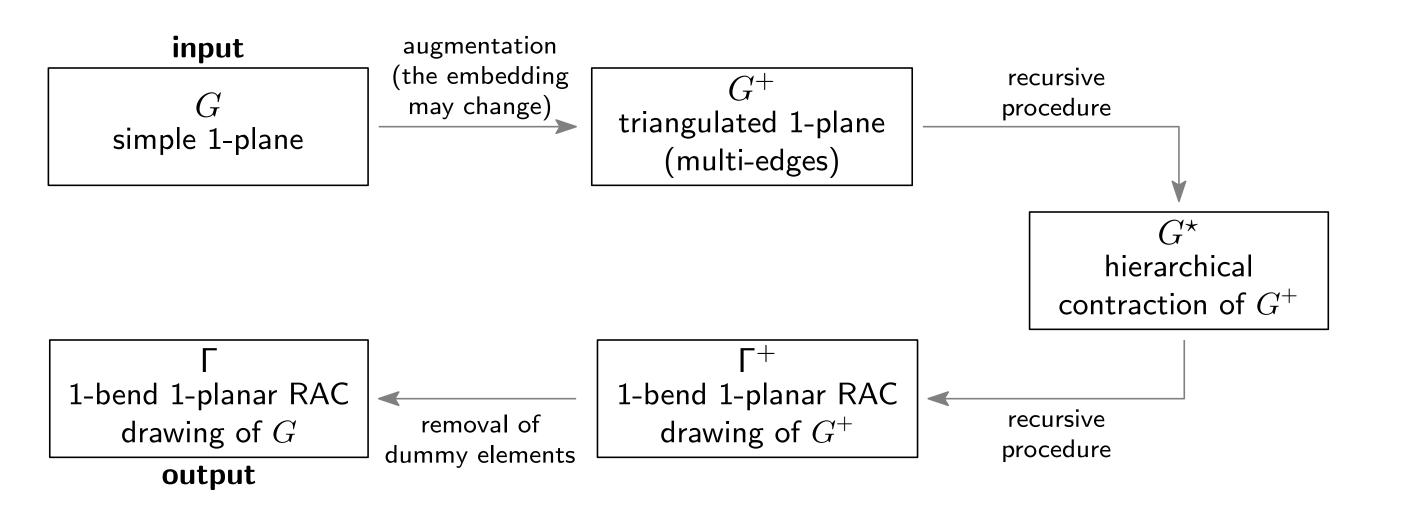


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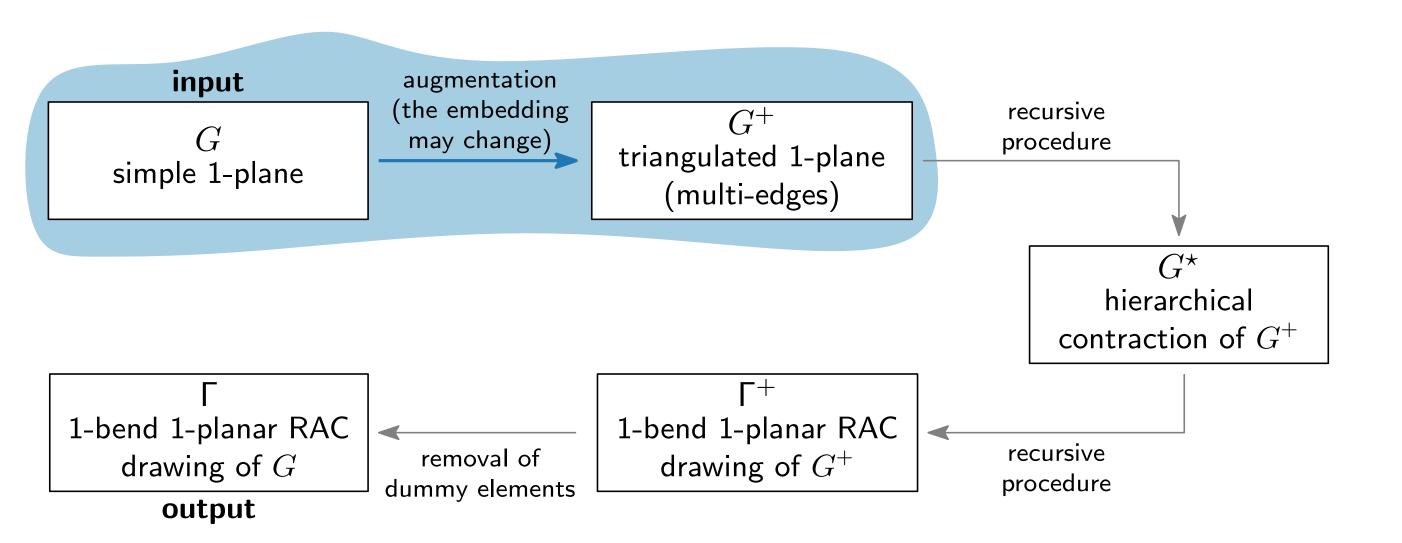
[Chiba, Yamanouchi & Nishizeki 1984]

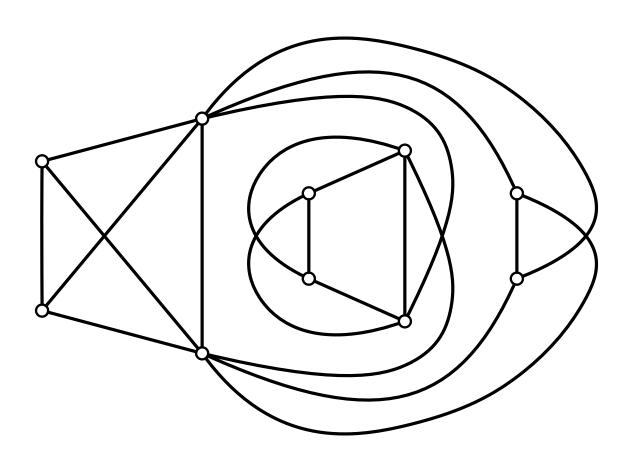
For every 2-connected plane graph G with outer face  $C_k$  and every convex k-gon P, there is a strictly convex planar straight-line drawing of G whose outer face coincides with P. Such a drawing can be computed in linear time.

## Algorithm Outline

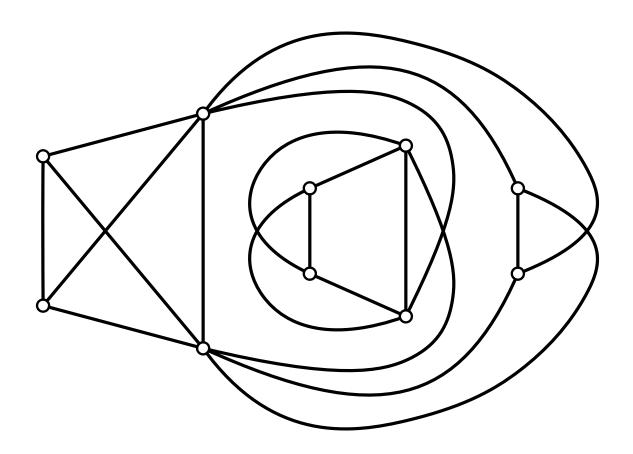


### Algorithm Outline

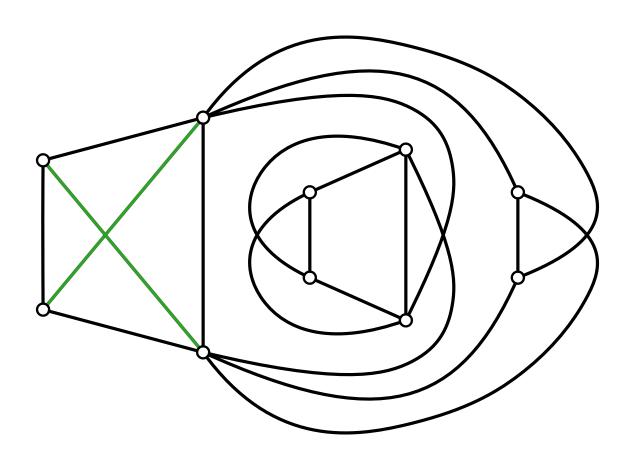




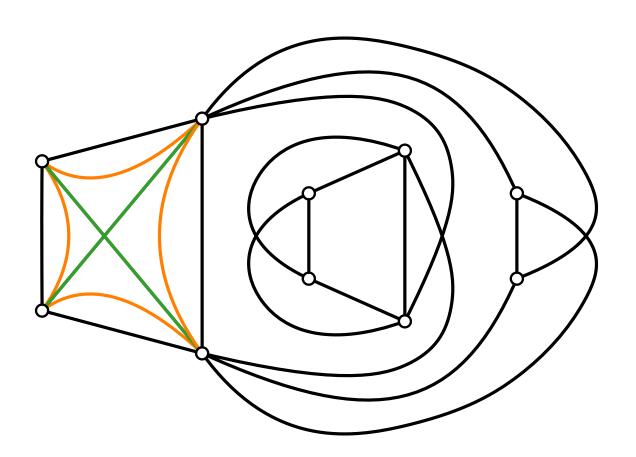
1. For each pair of crossing edges add an enclosing 4-cycle.



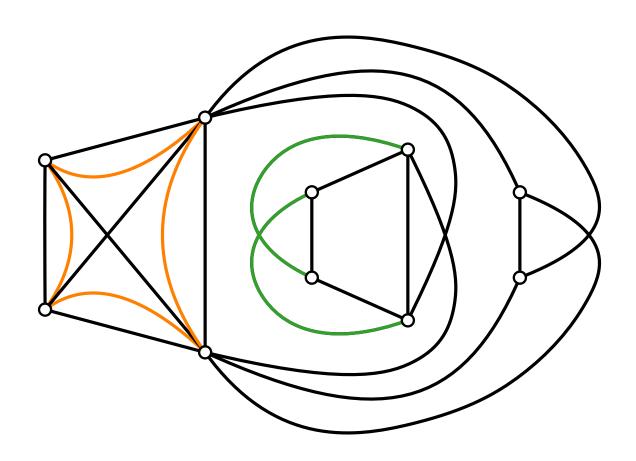
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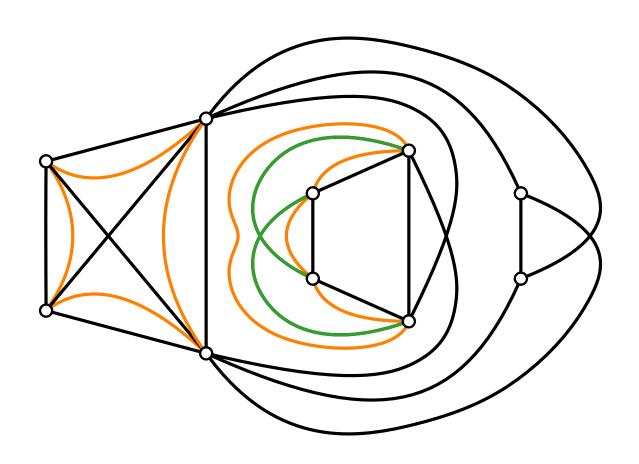
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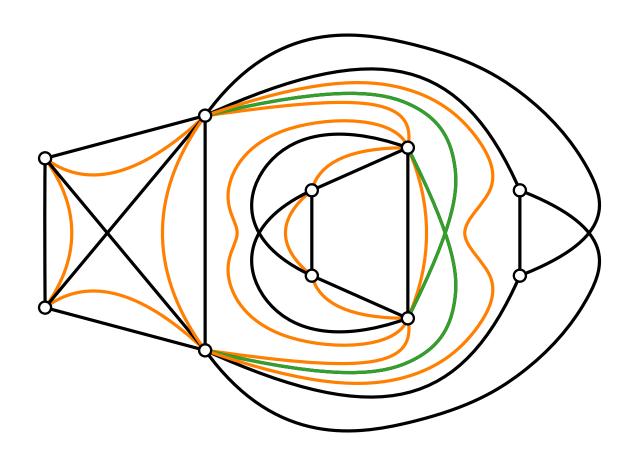
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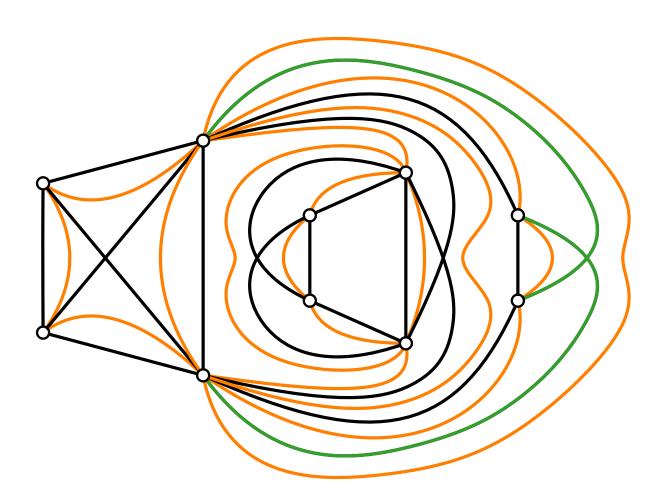
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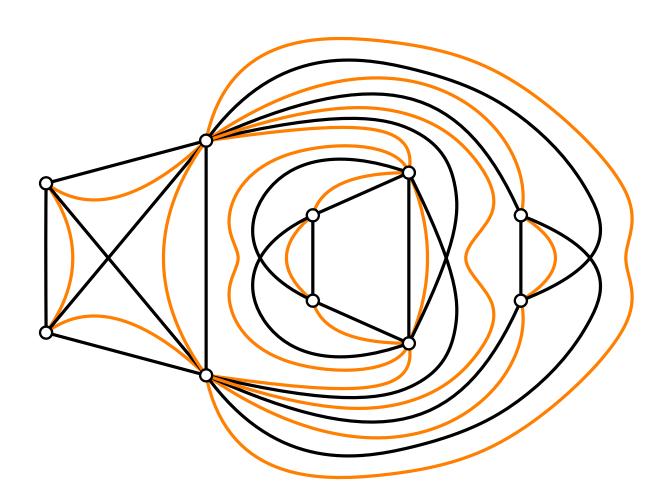
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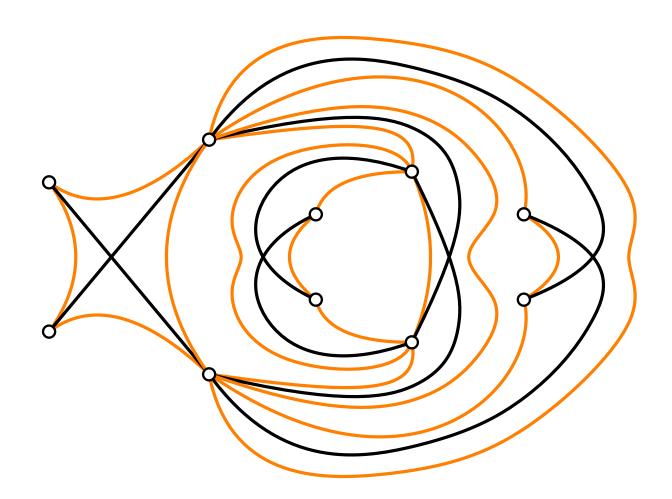
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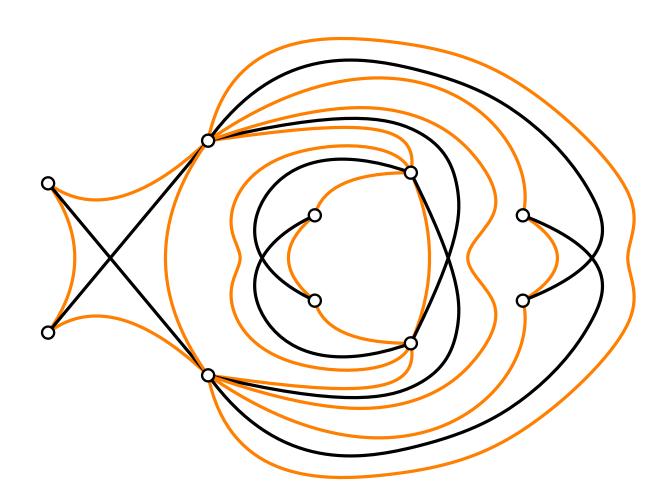
- 1. For each pair of crossing edges add an enclosing 4-cycle.
- 2. Remove those multiple edges that belong to G.



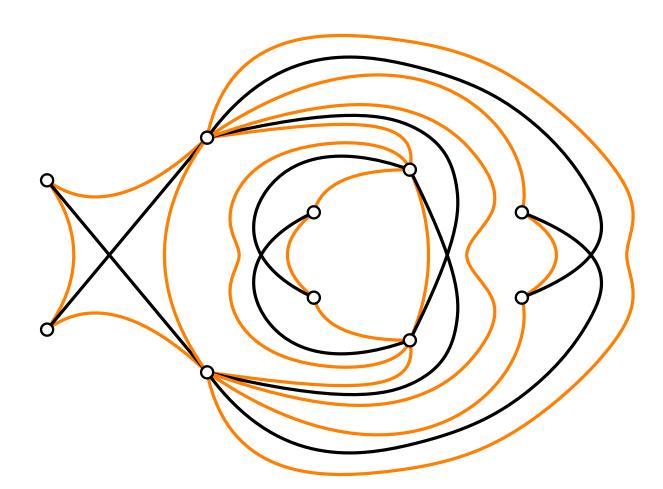
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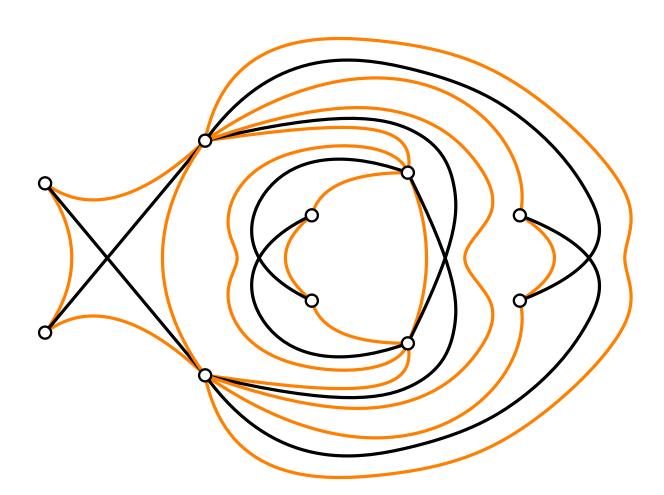


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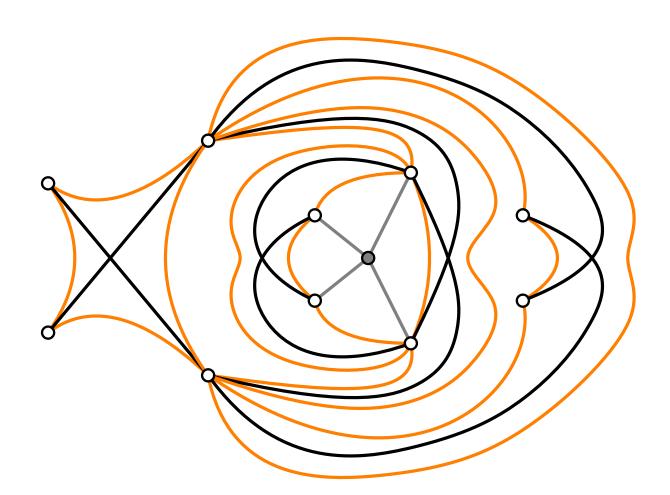
G: simple 1-plane graph



Note that we can still have parallel (orange) edges

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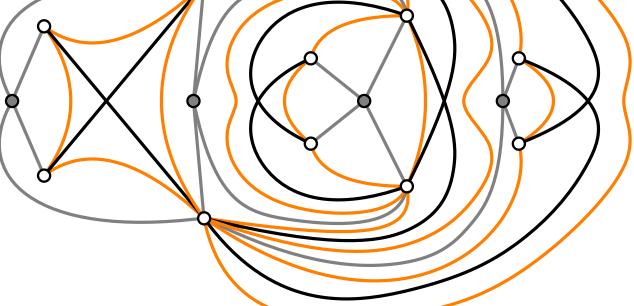
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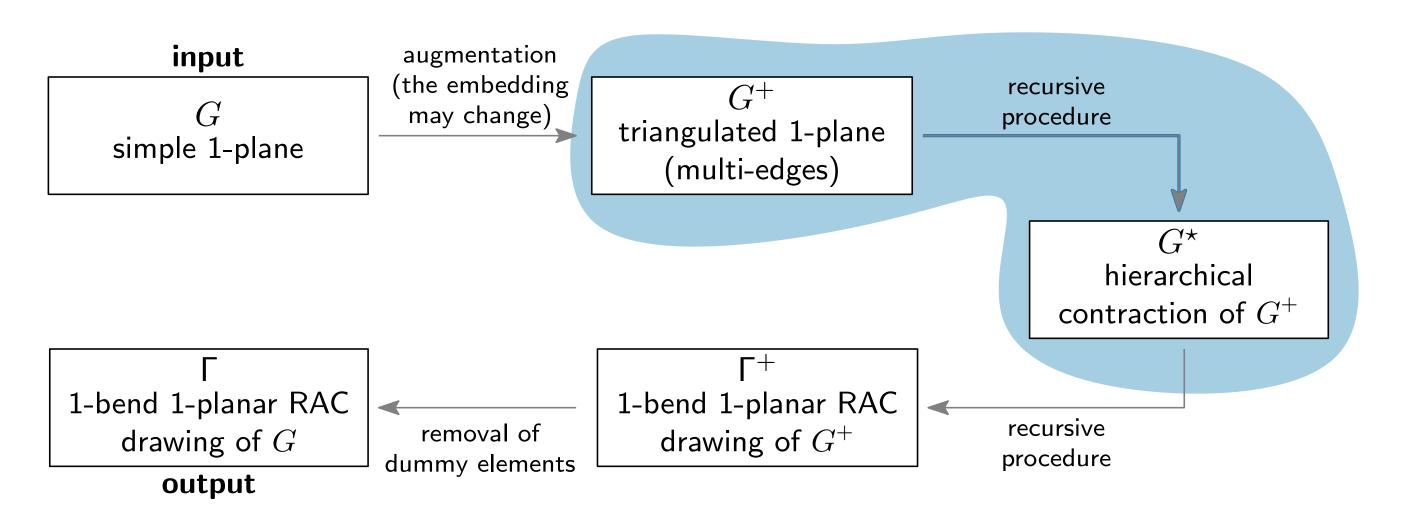
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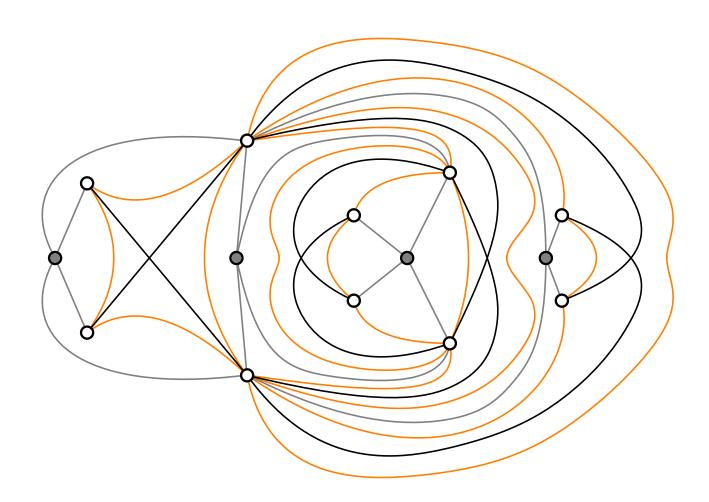
 $ightharpoonup G^+$ : triangulated 1-plane G: simple 1-plane graph (possibly with multi-edges)



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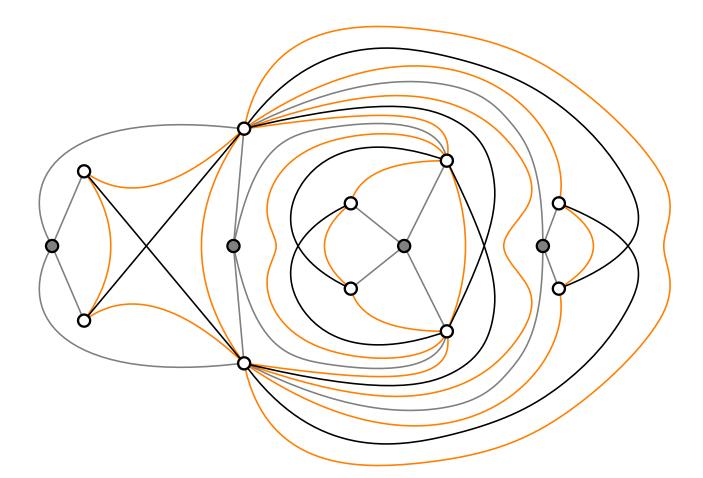
### Algorithm Outline



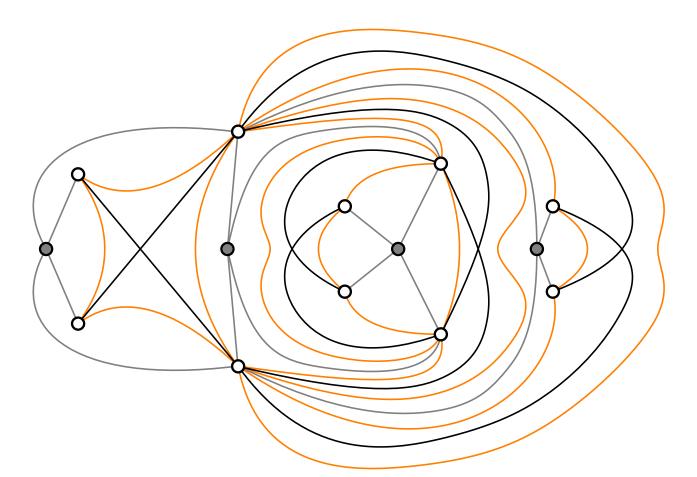


 $G^+$  triangulated 1-plane (multi-edges)

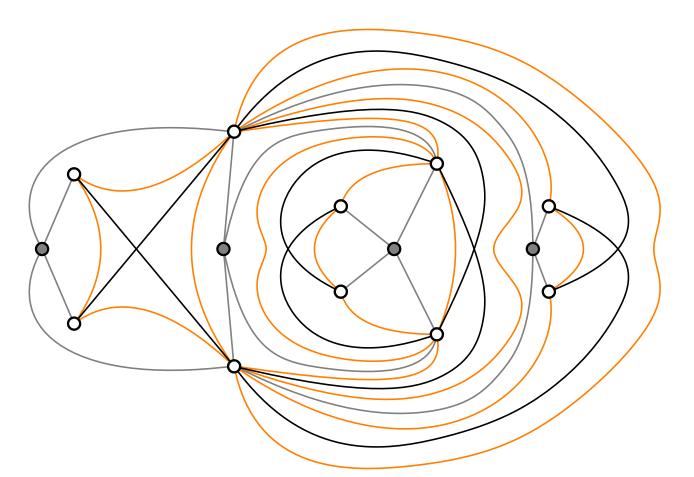
triangular faces



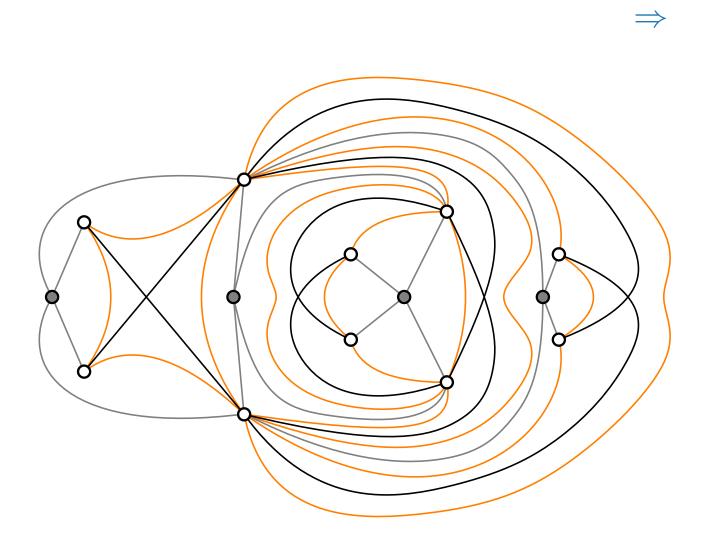
- triangular faces
- multiple edges never crossed

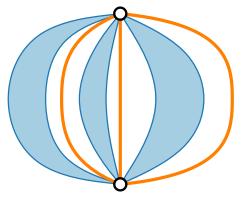


- triangular faces
- multiple edges never crossed
- only empty kites



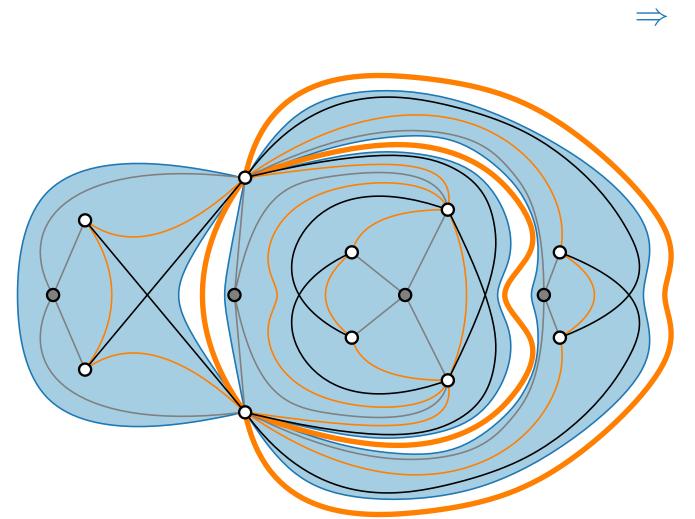
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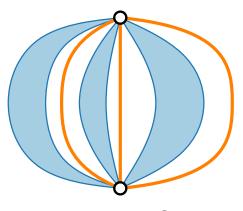




structure of each separation pair

- triangular faces
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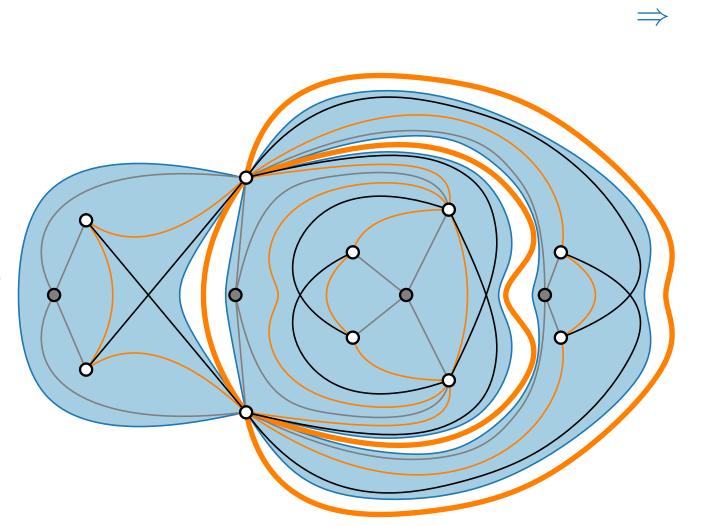


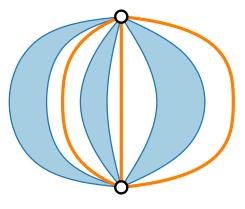


structure of each separation pair

 $G^+$  triangulated 1-plane (multi-edges)

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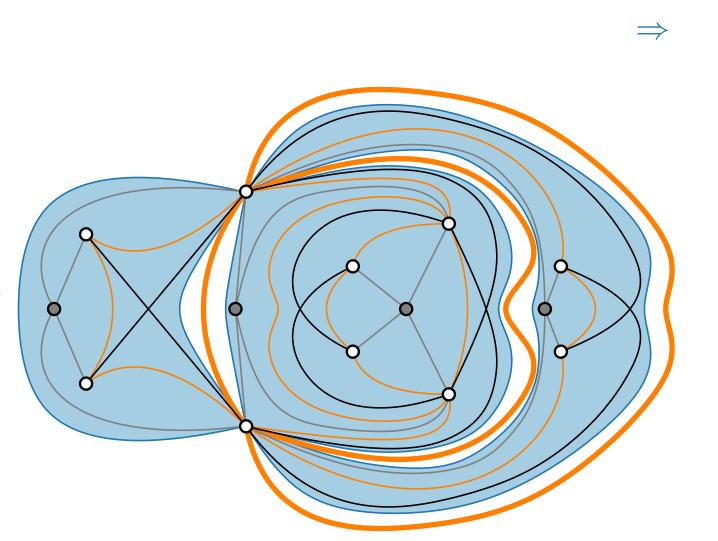


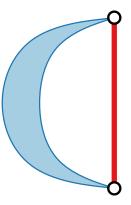


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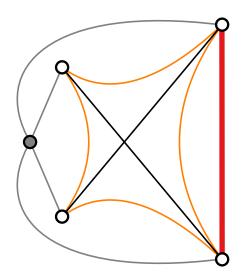




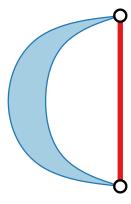
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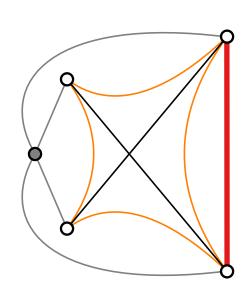


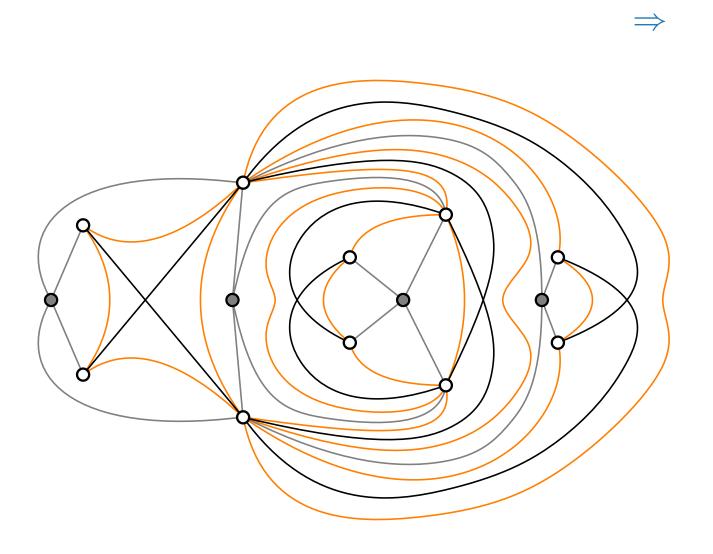


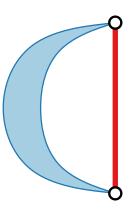
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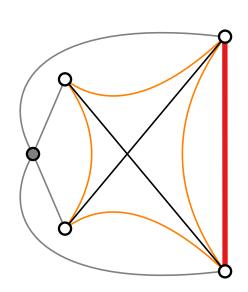


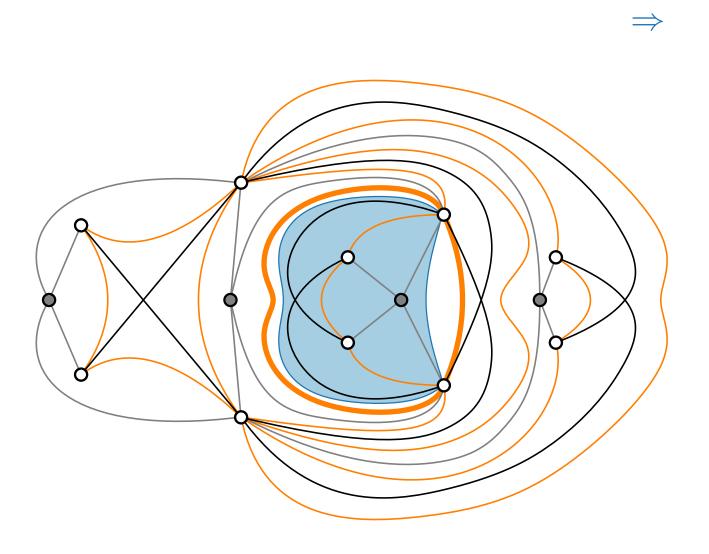


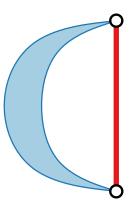
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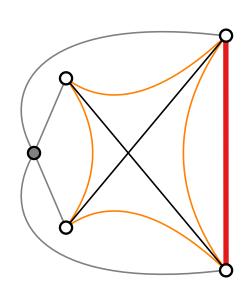


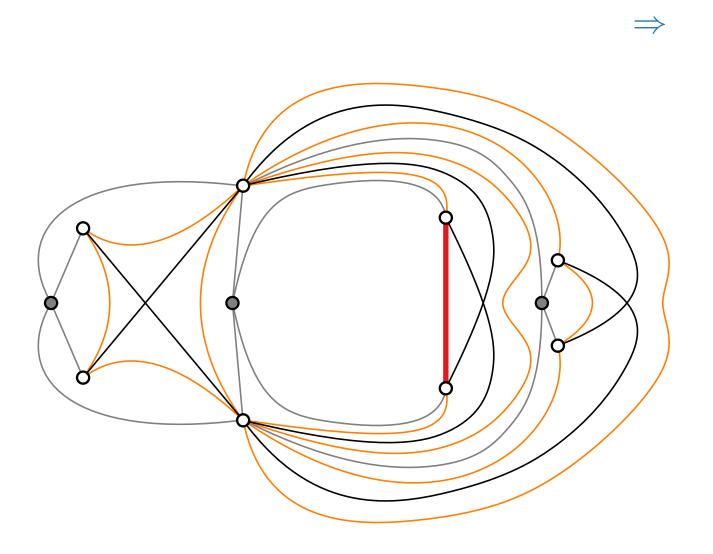


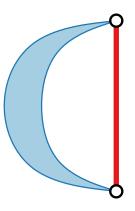
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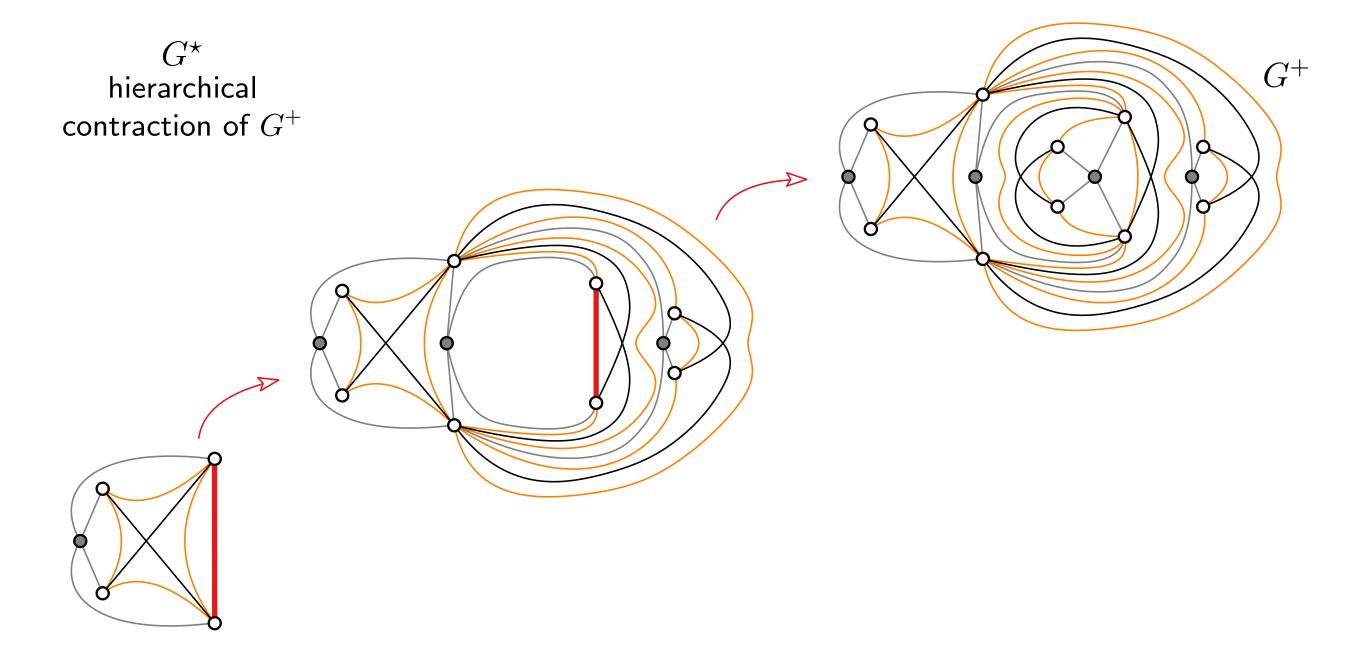
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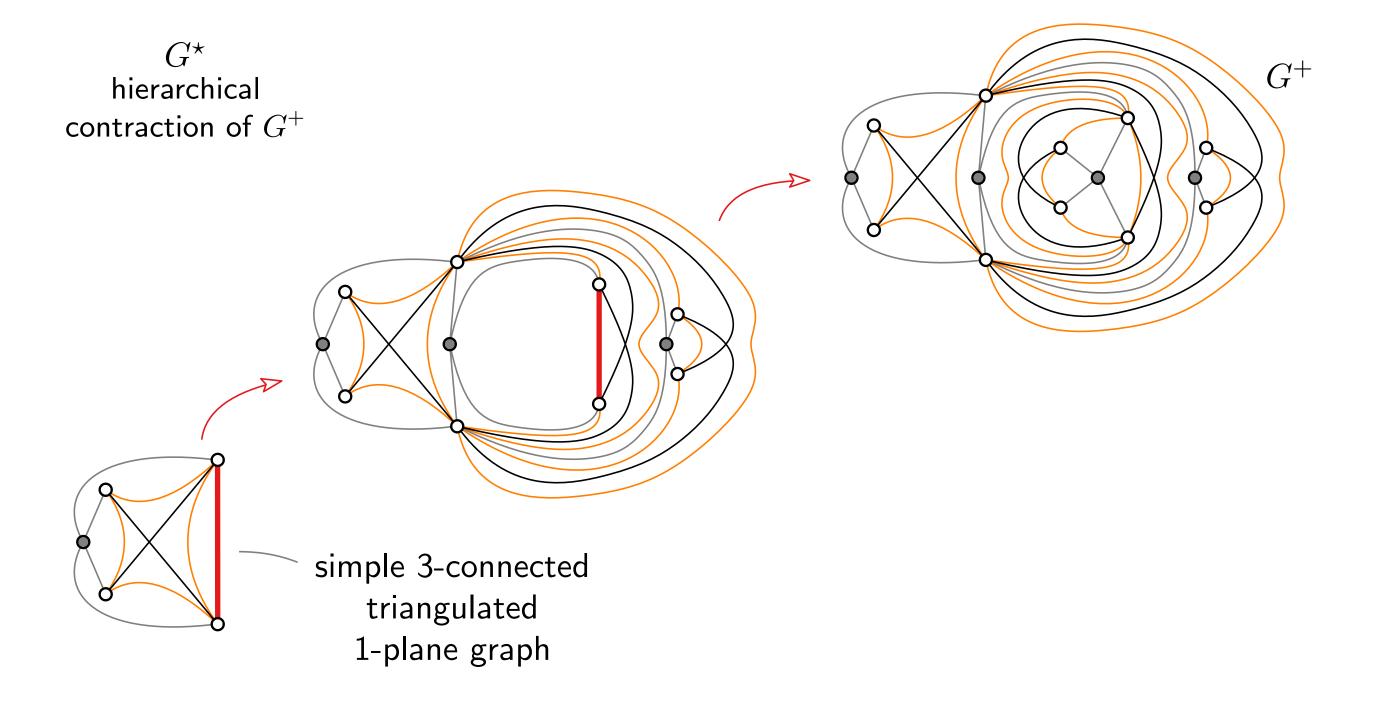




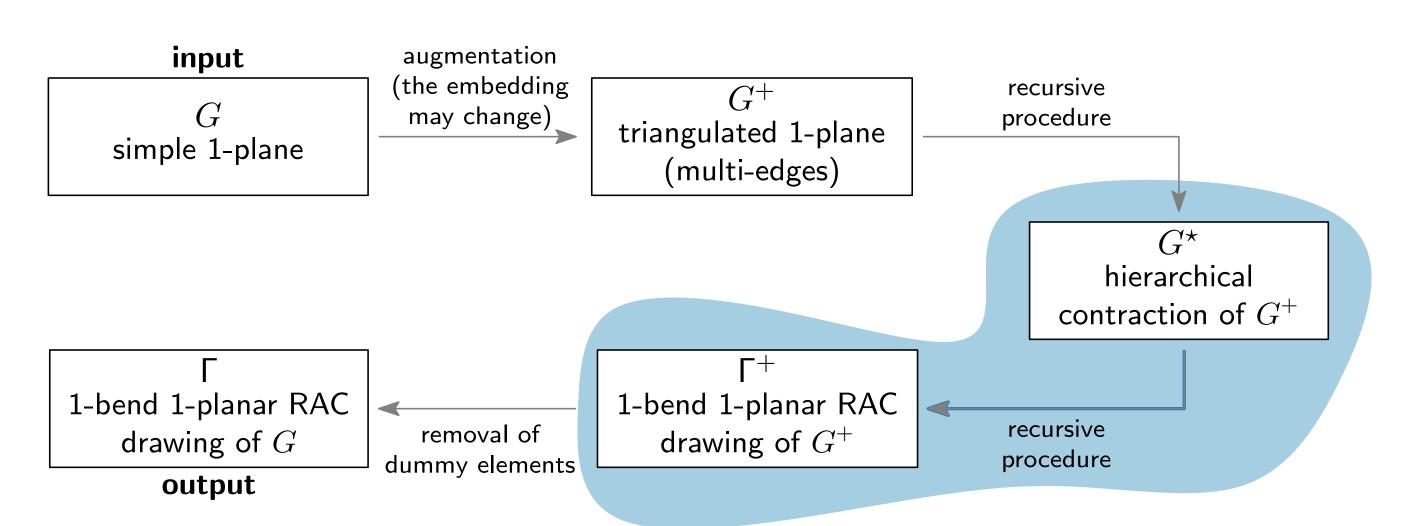


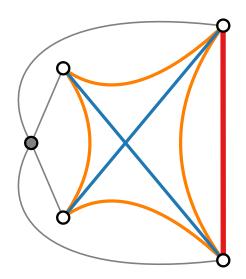
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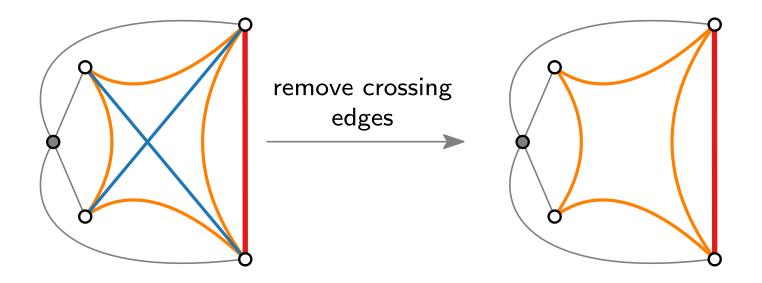


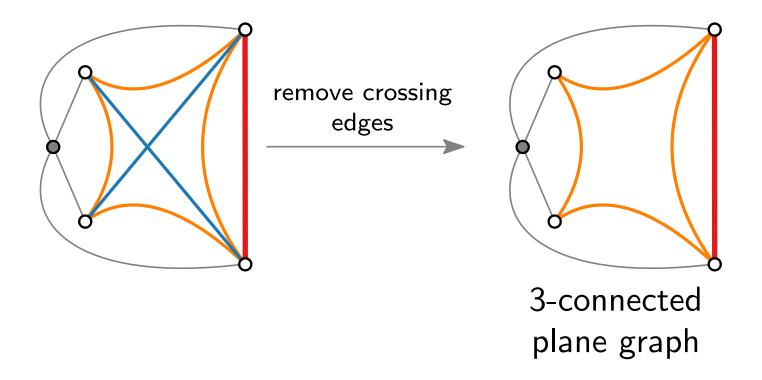


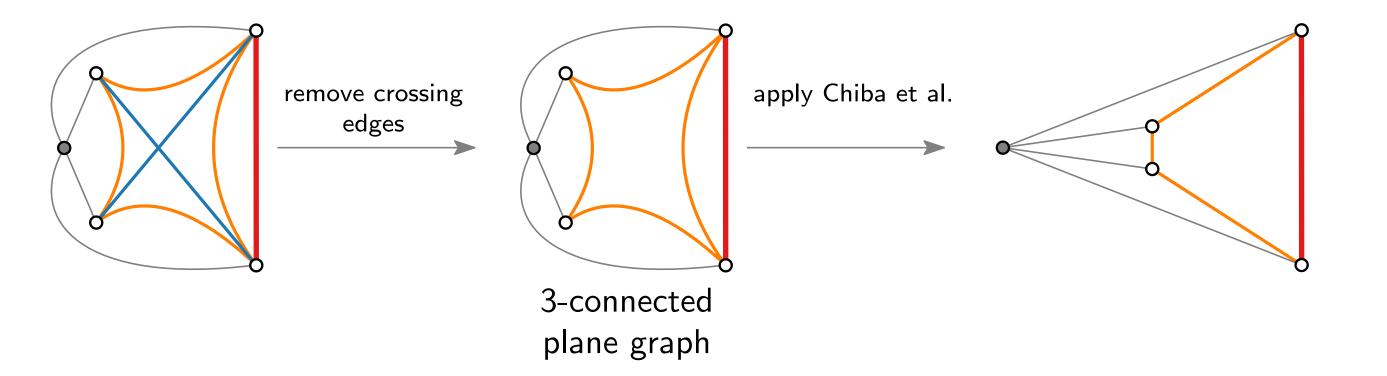
### Algorithm Outline

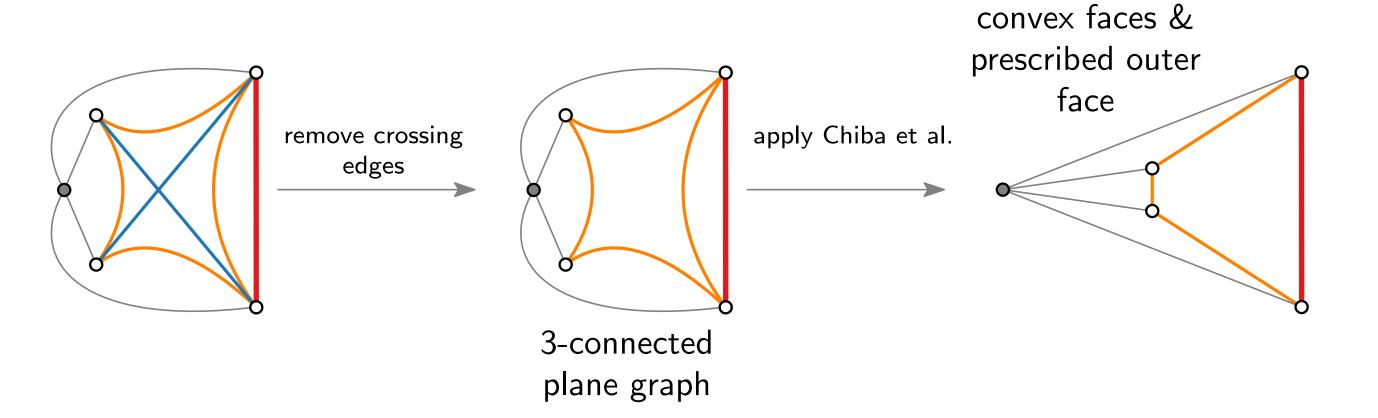


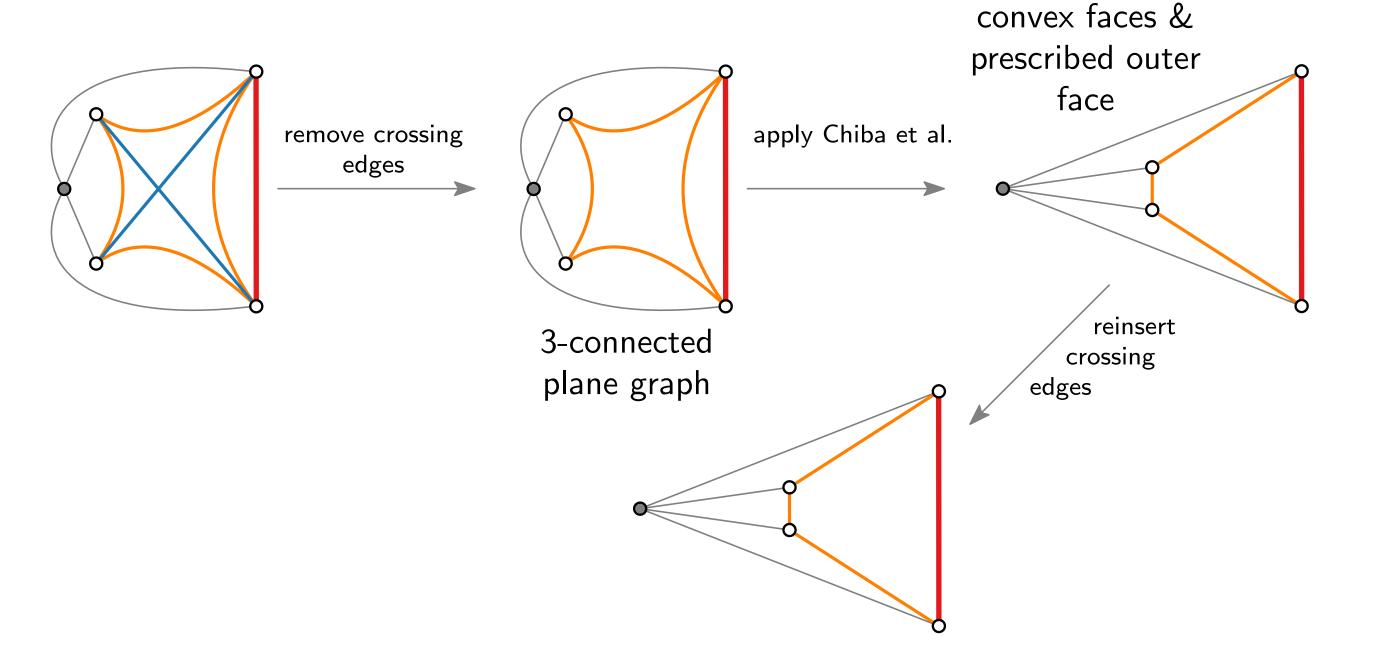


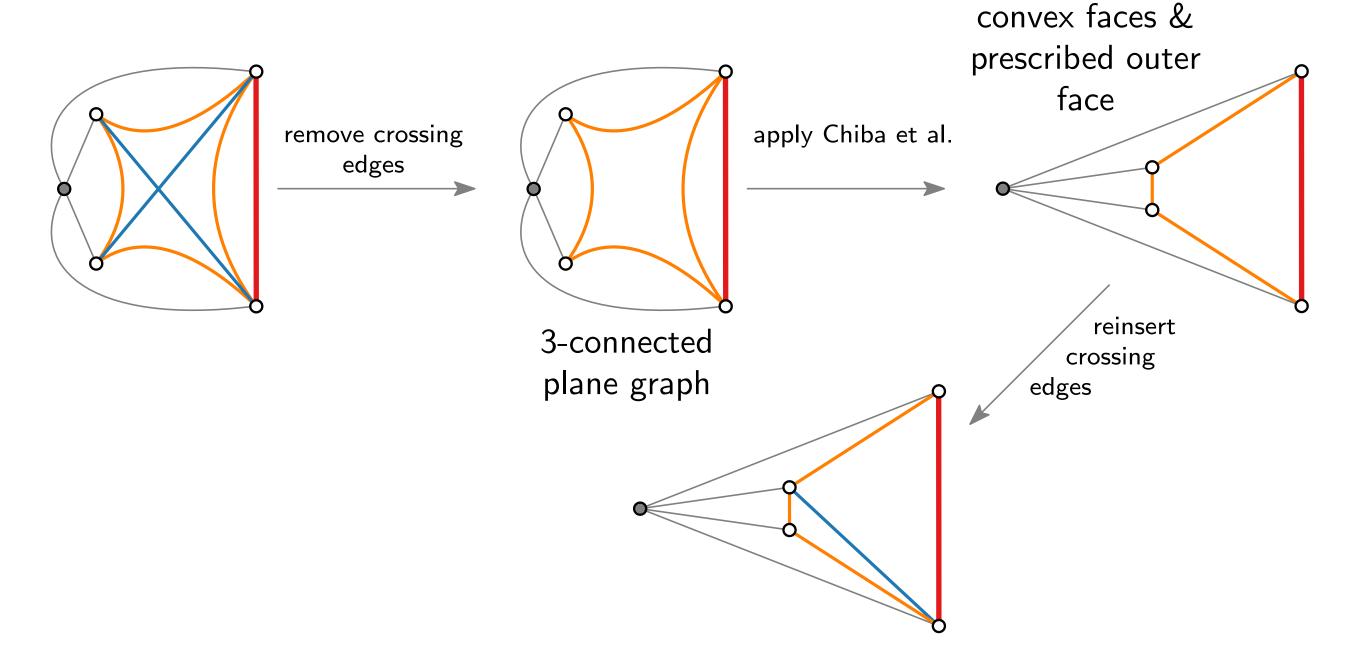


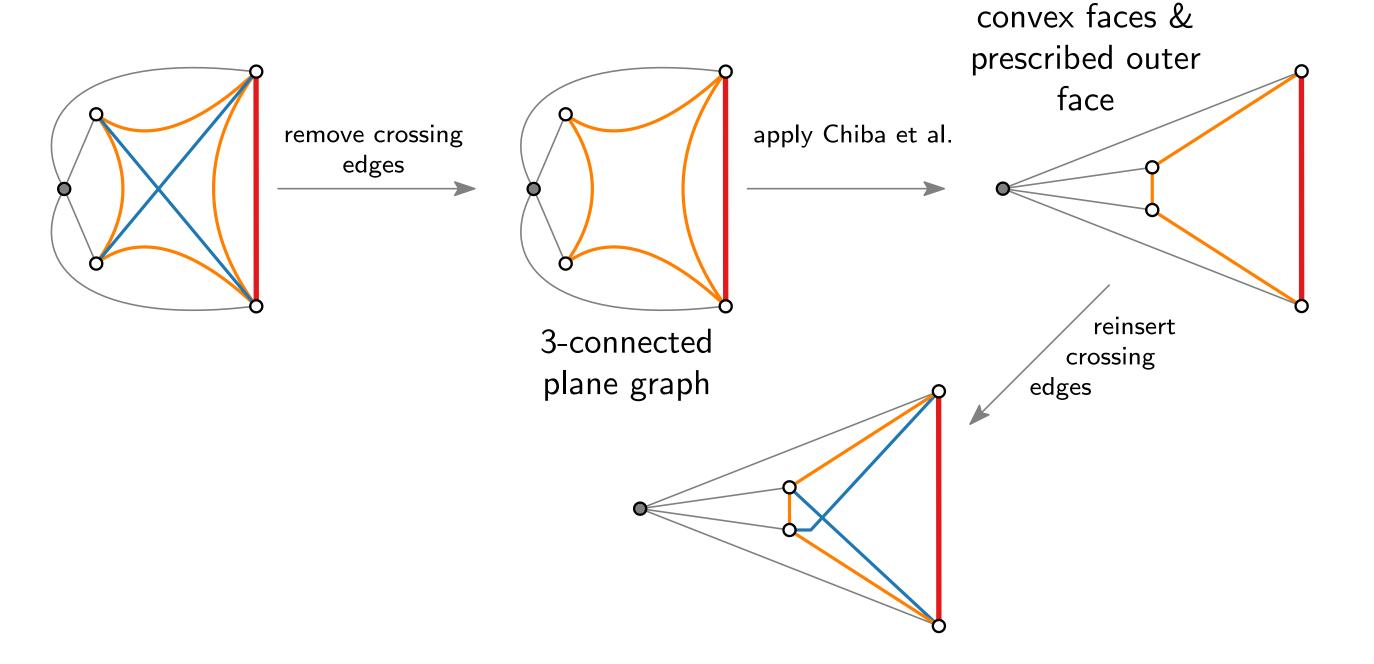


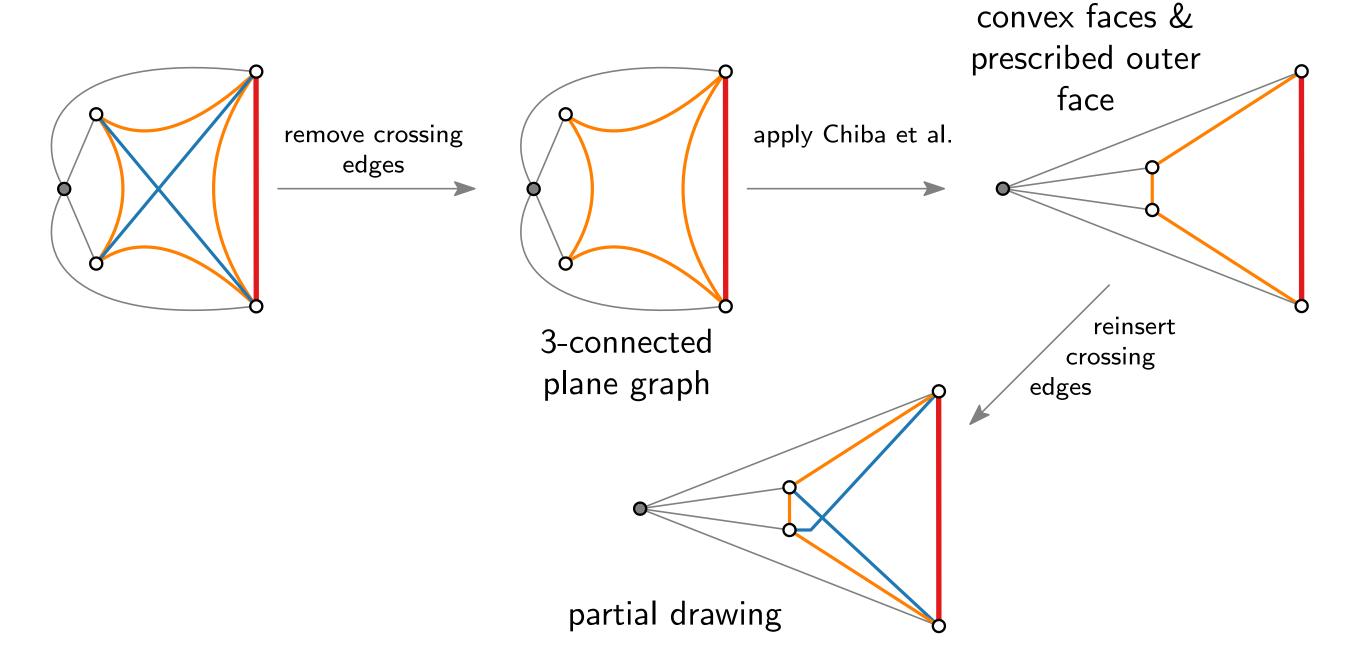


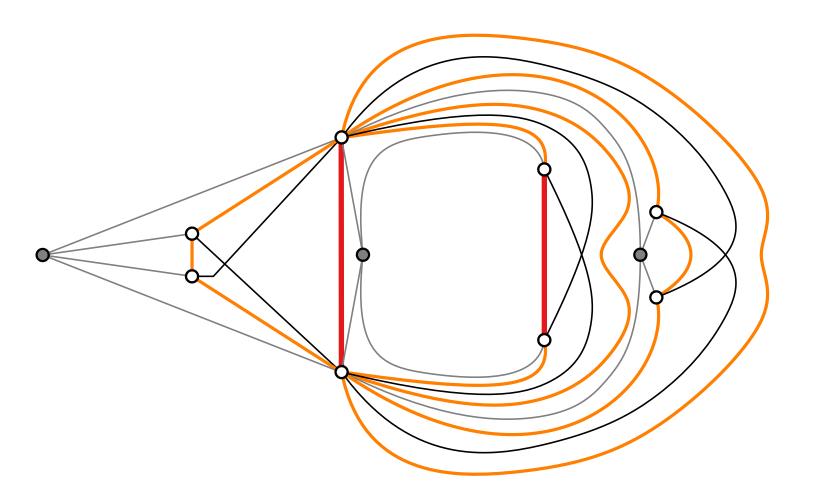


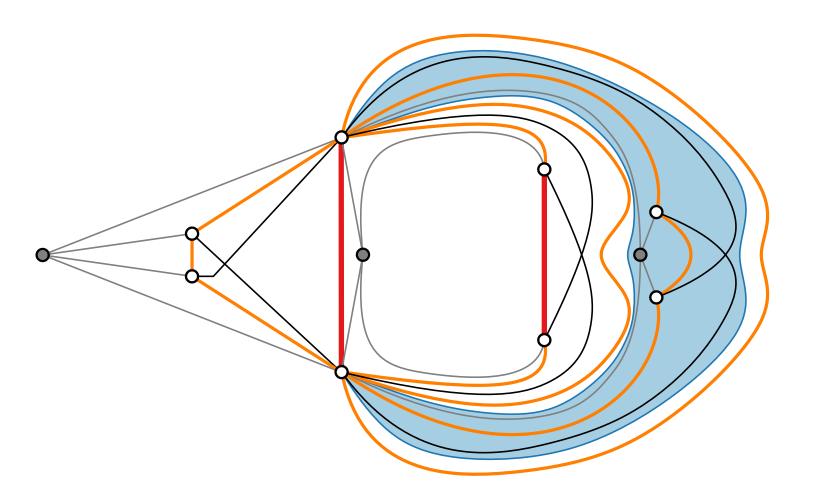


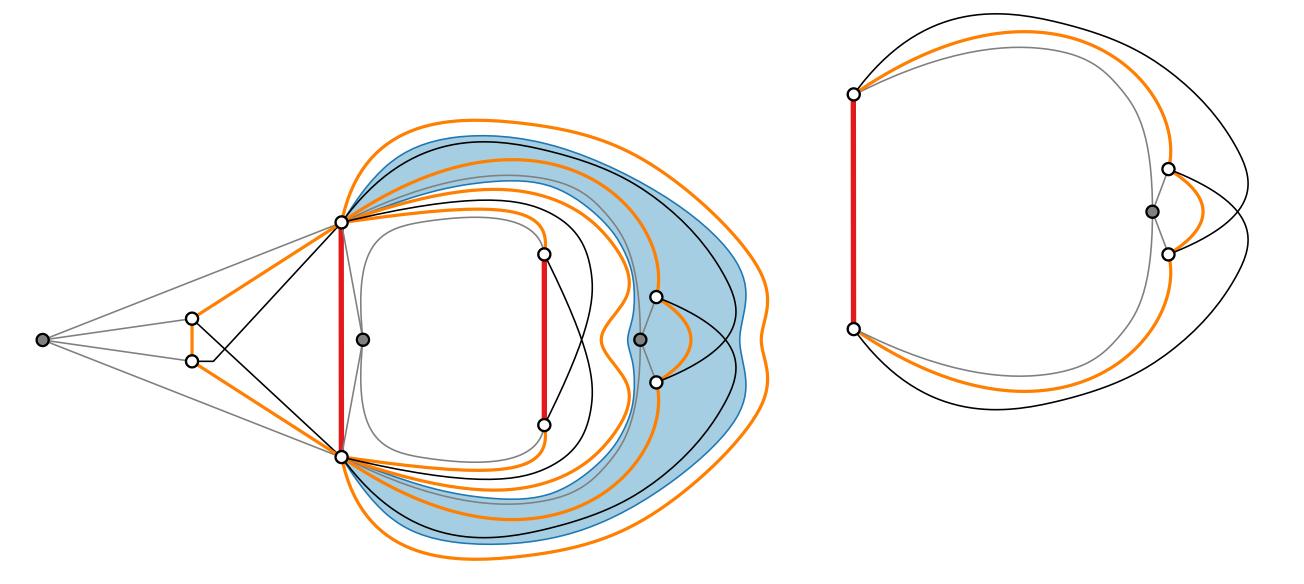


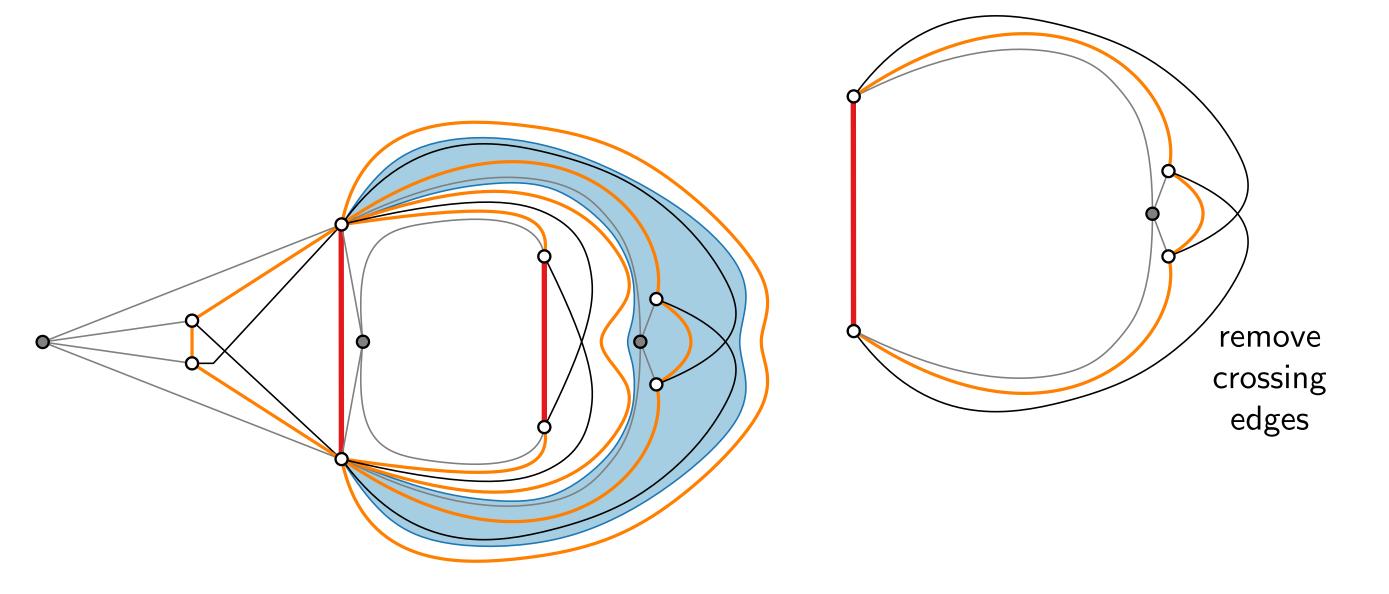


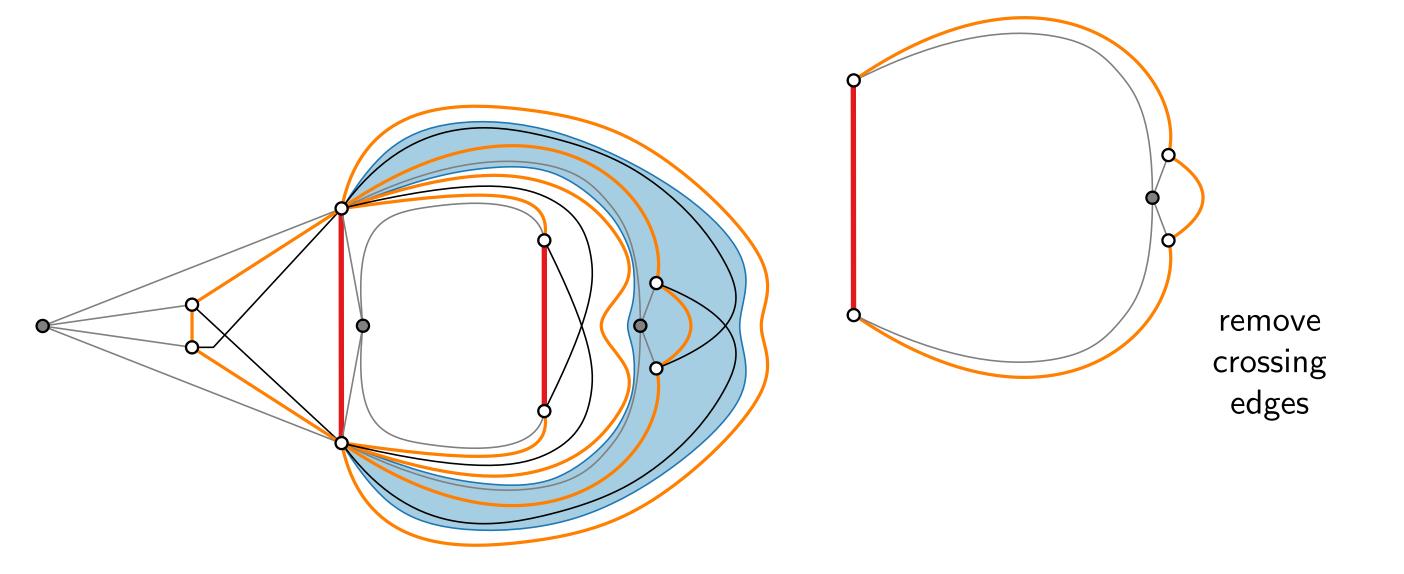


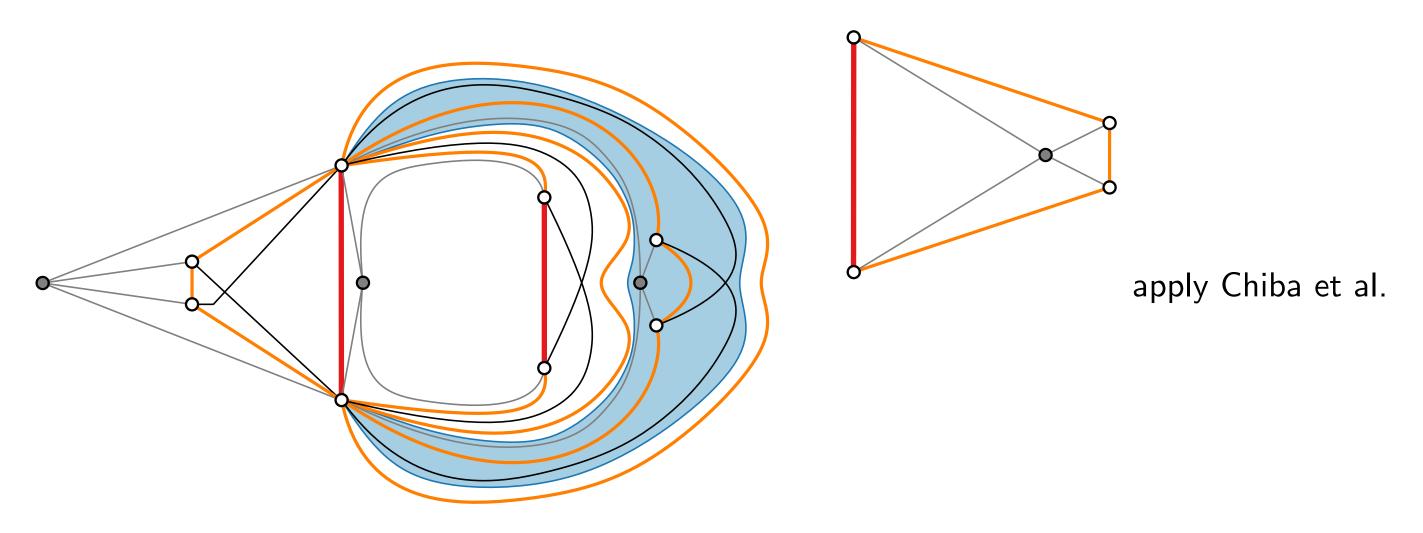


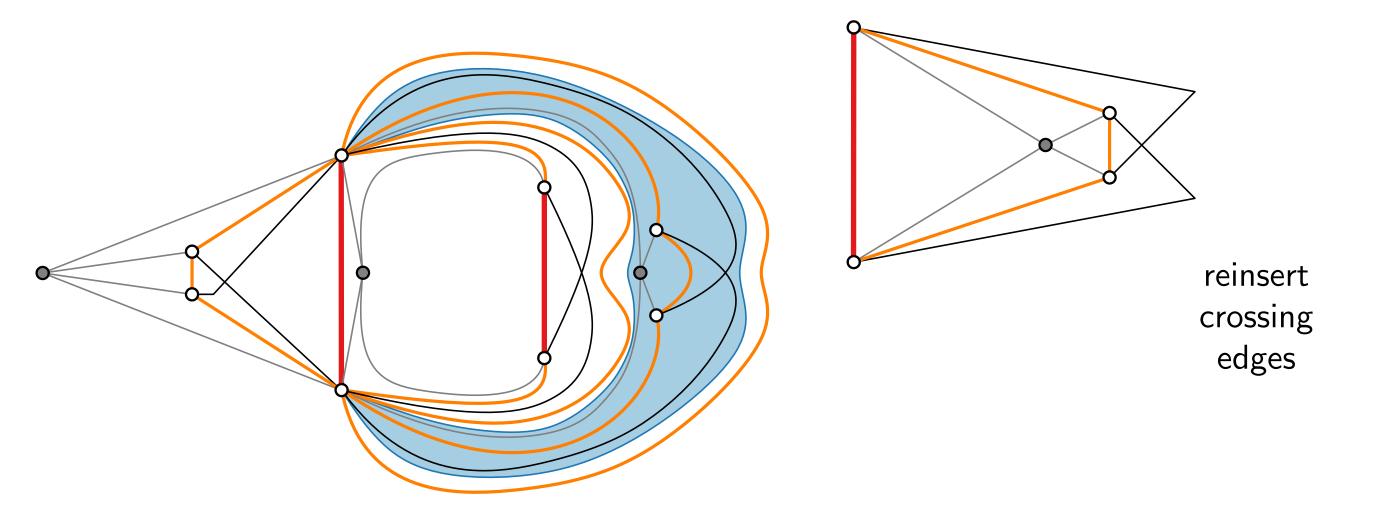


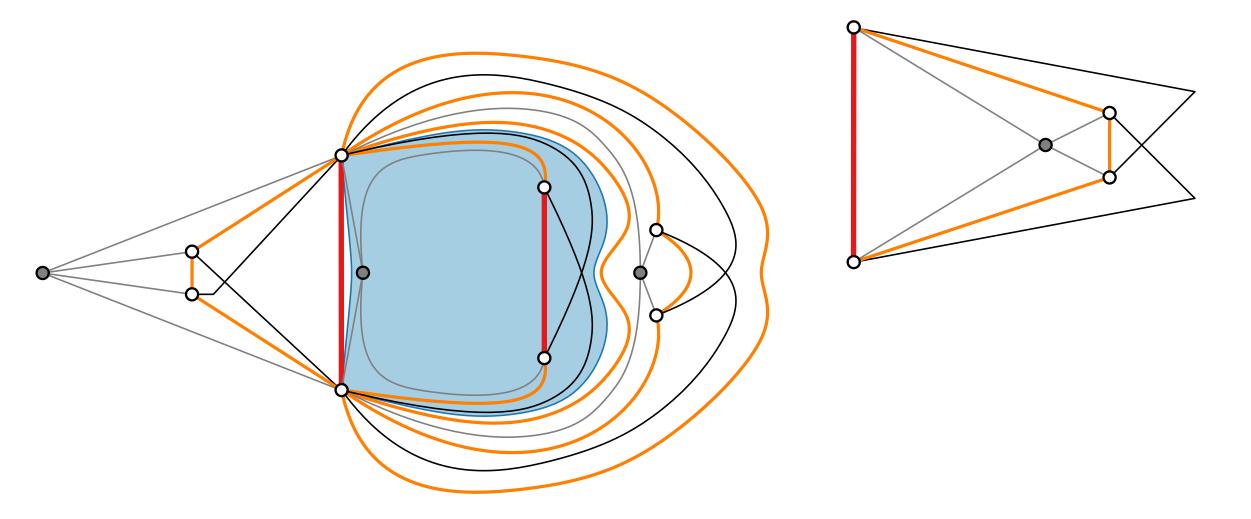


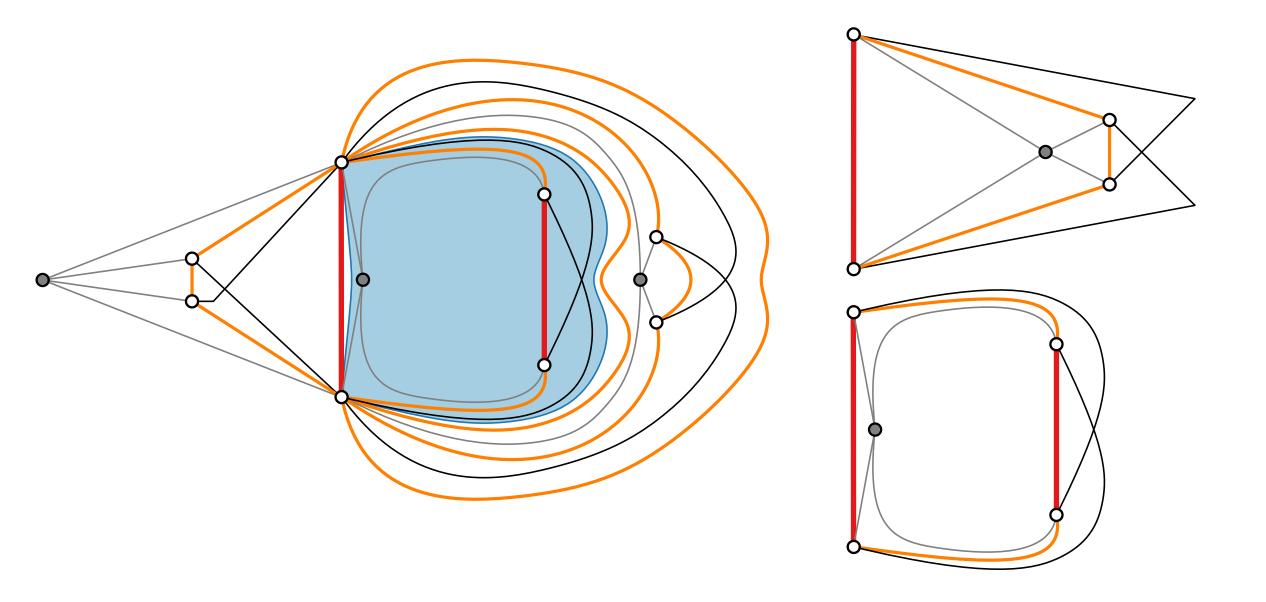


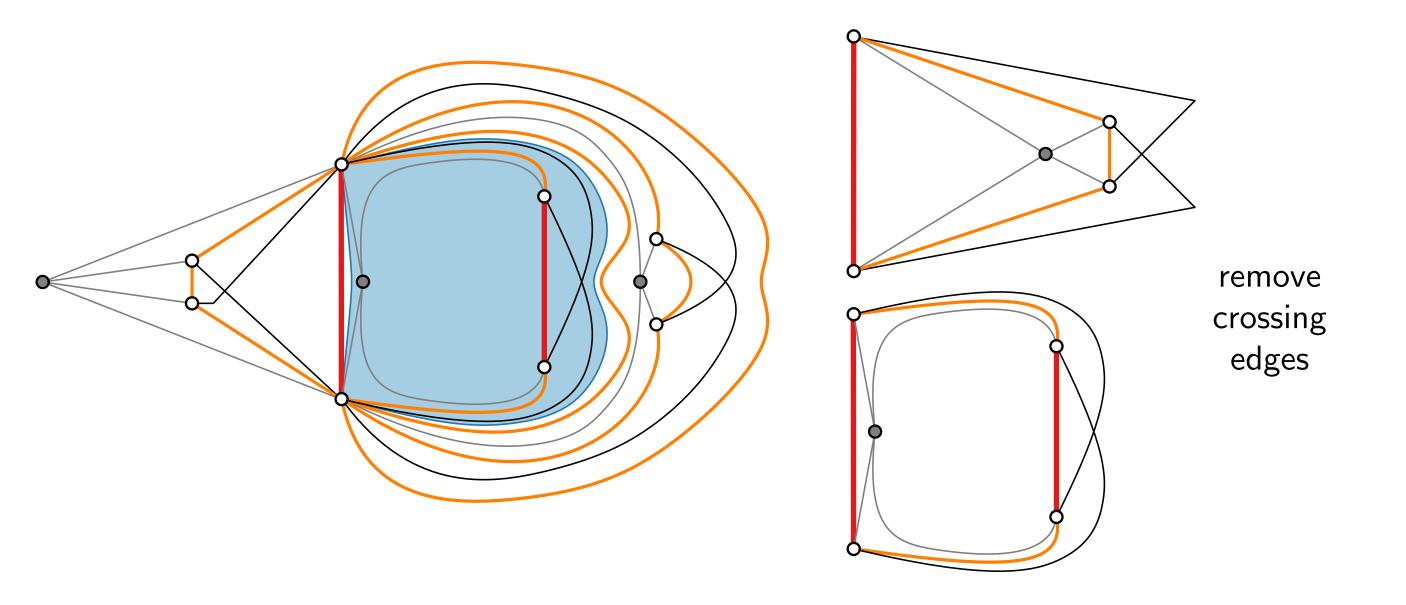


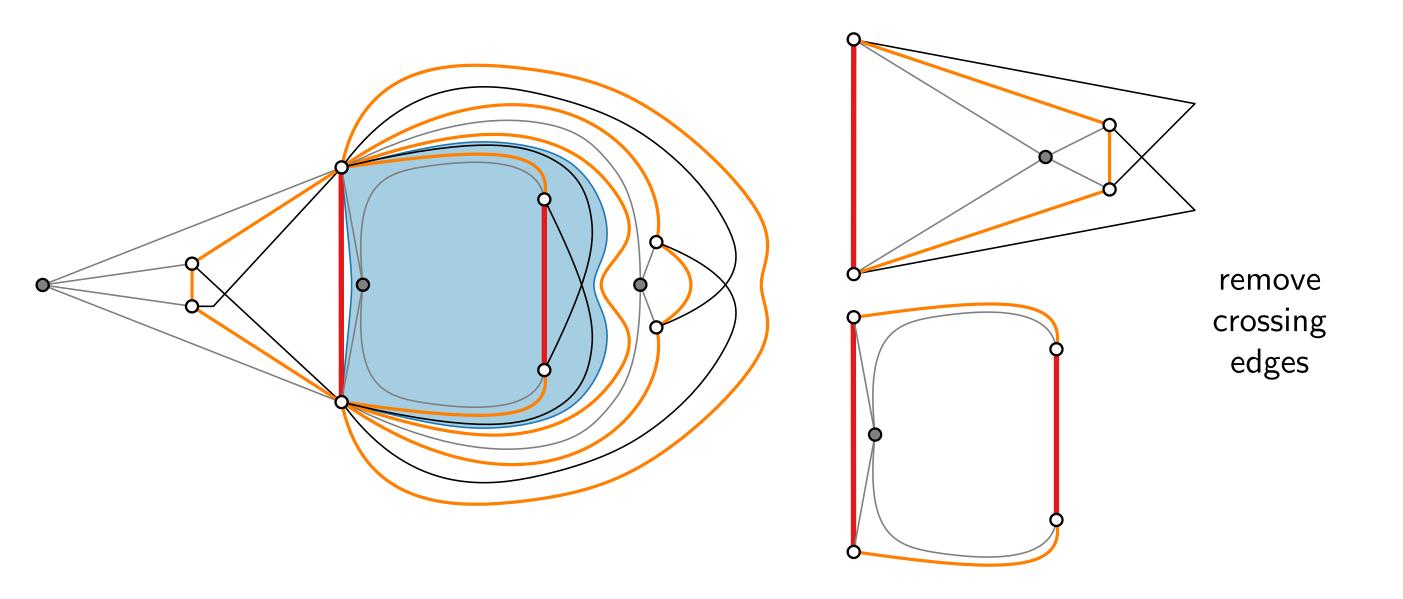


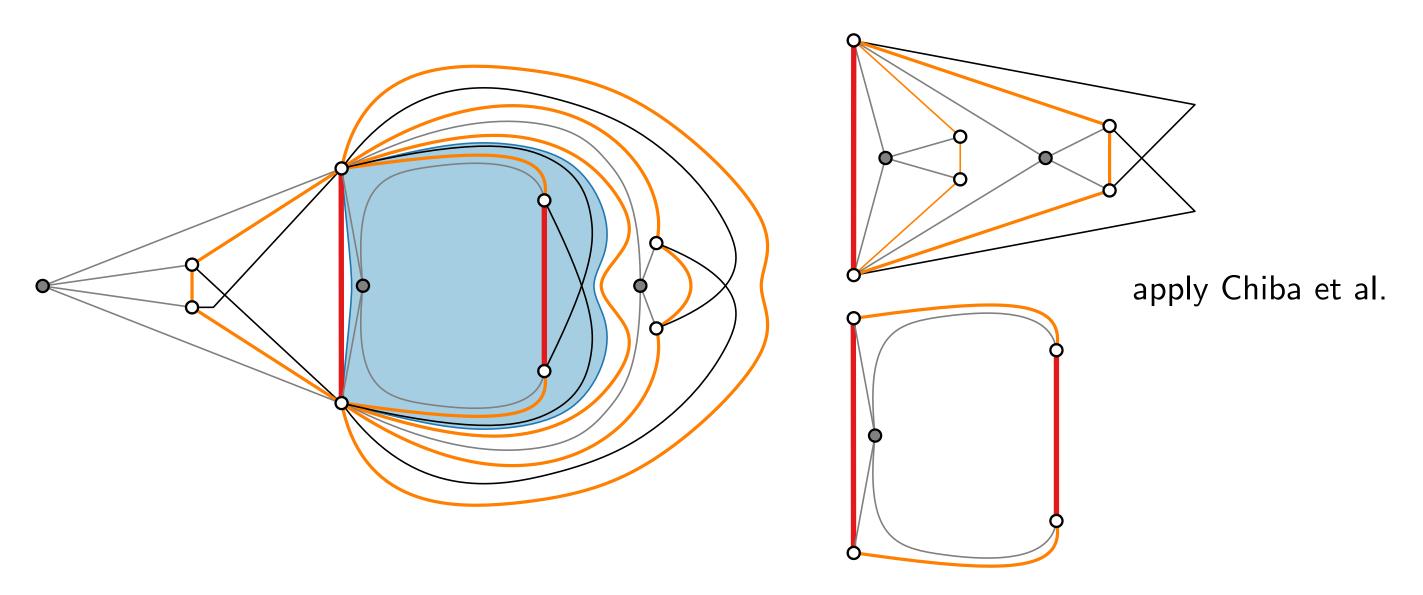


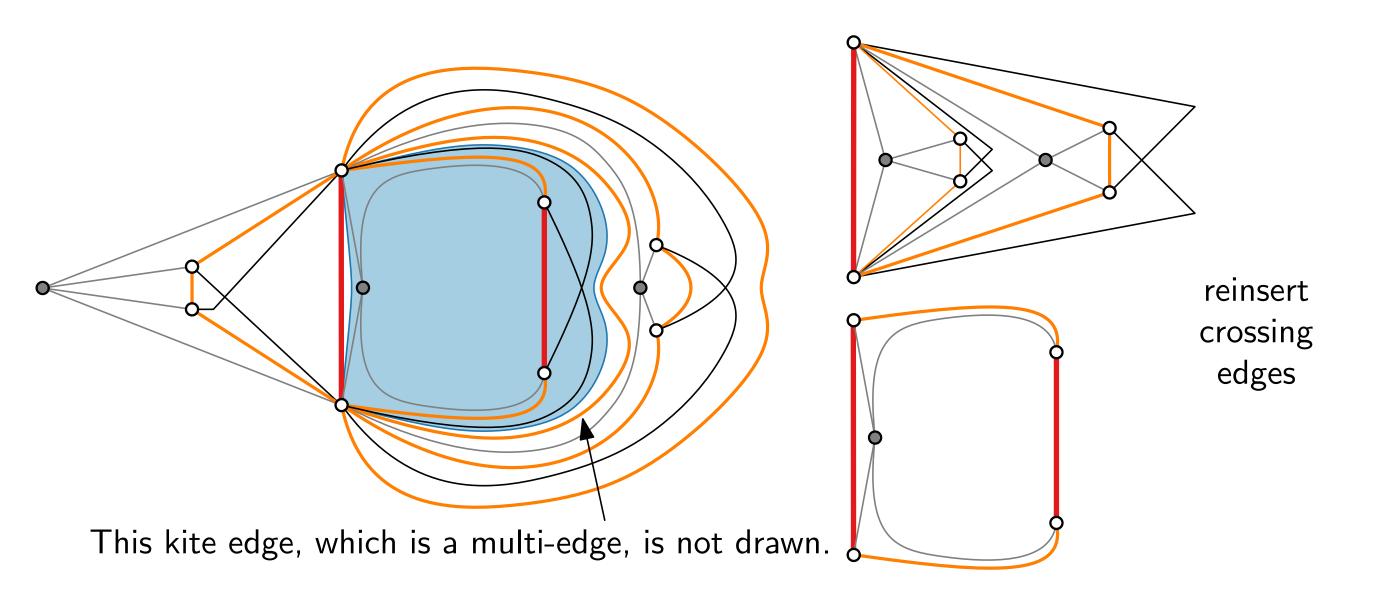


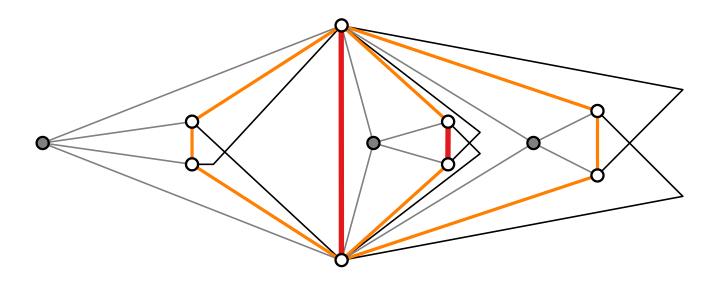


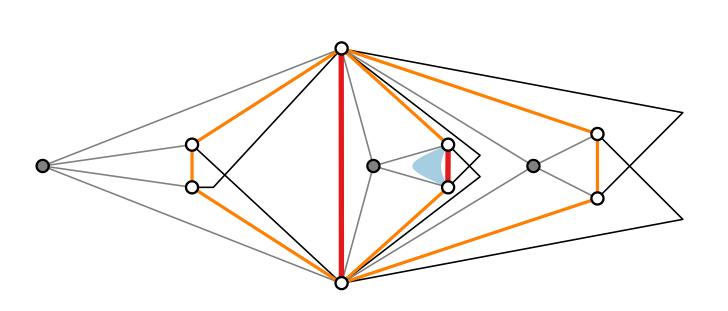


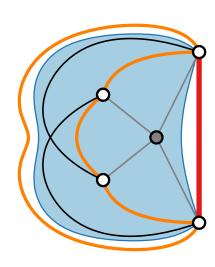


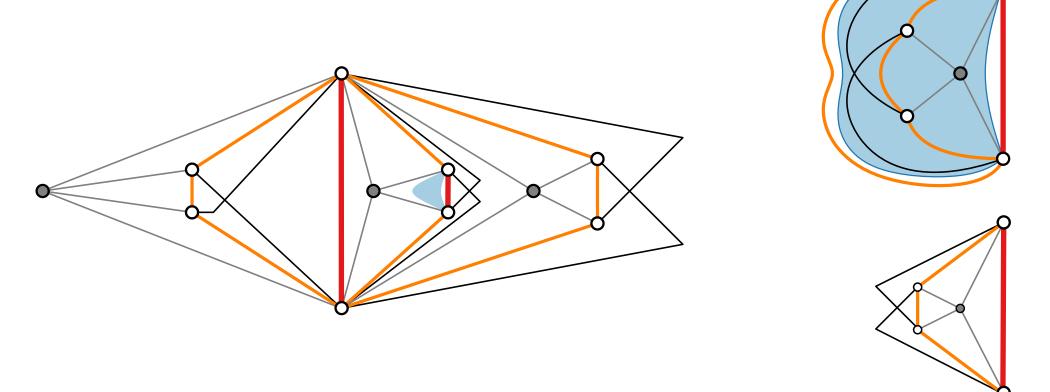


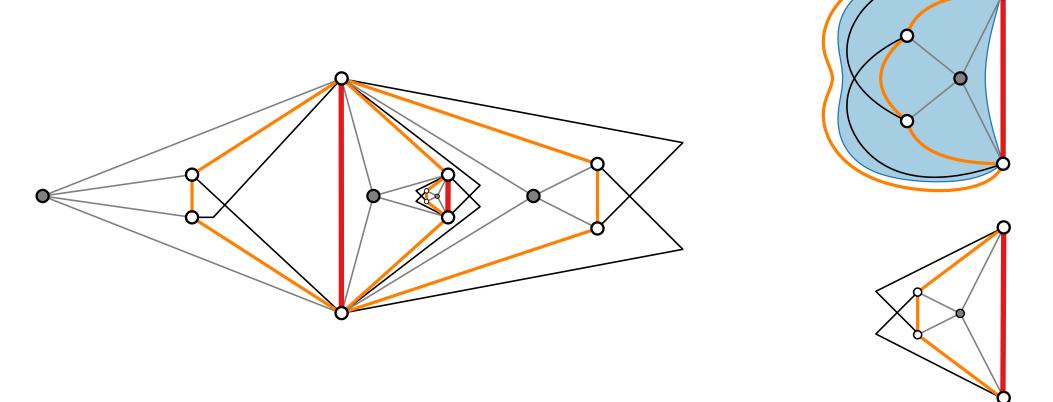




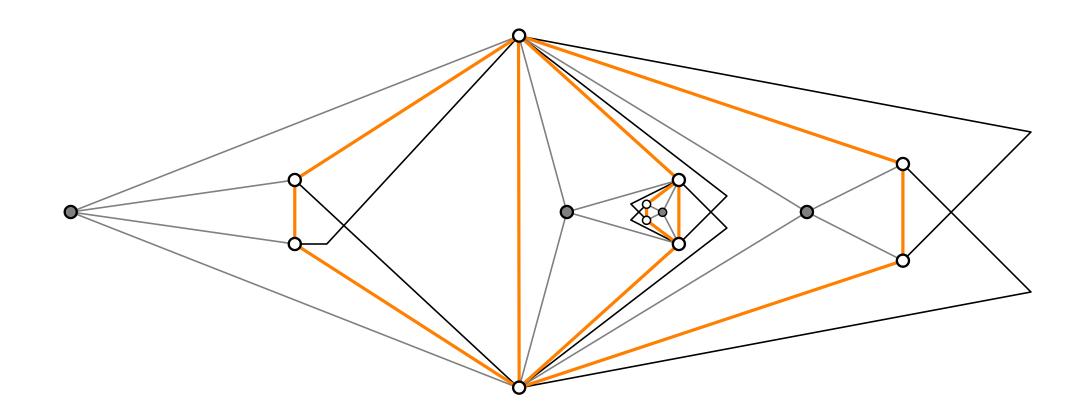




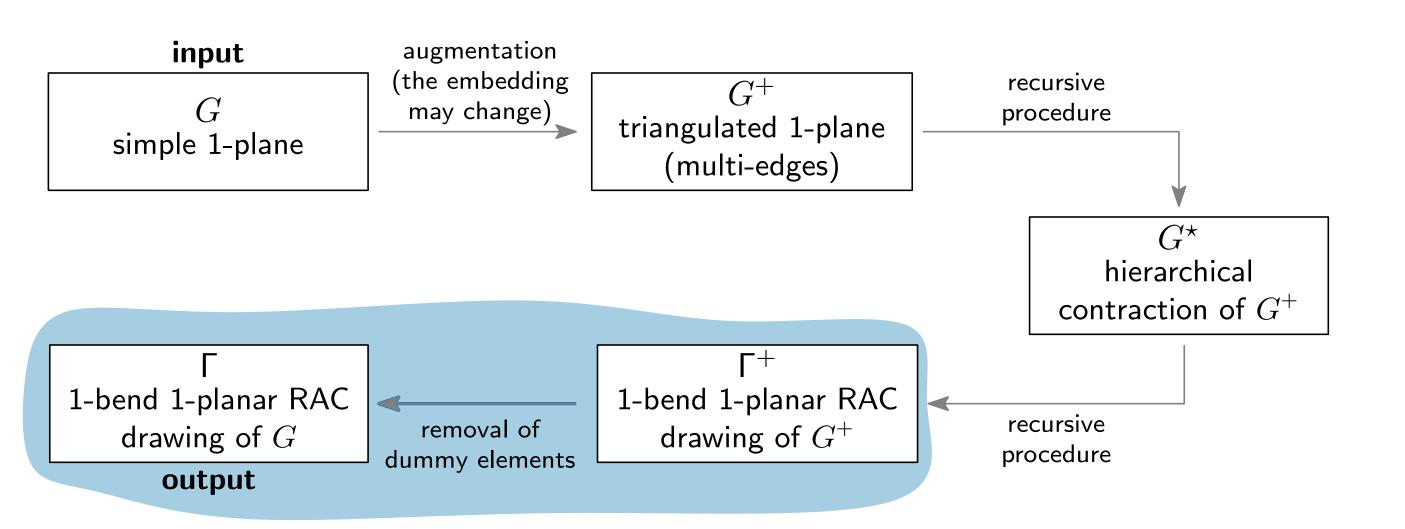


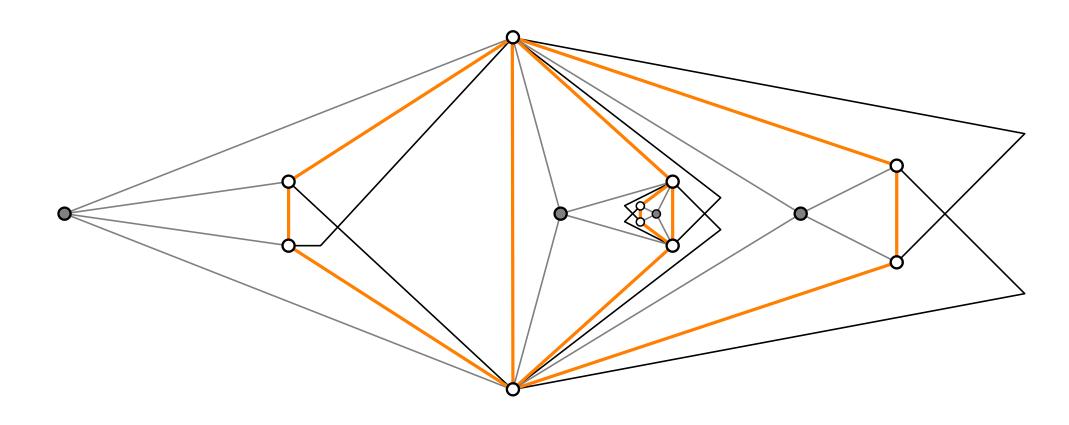


 $\Gamma^+$ : 1-bend 1-planar RAC drawing of  $G^+$ 

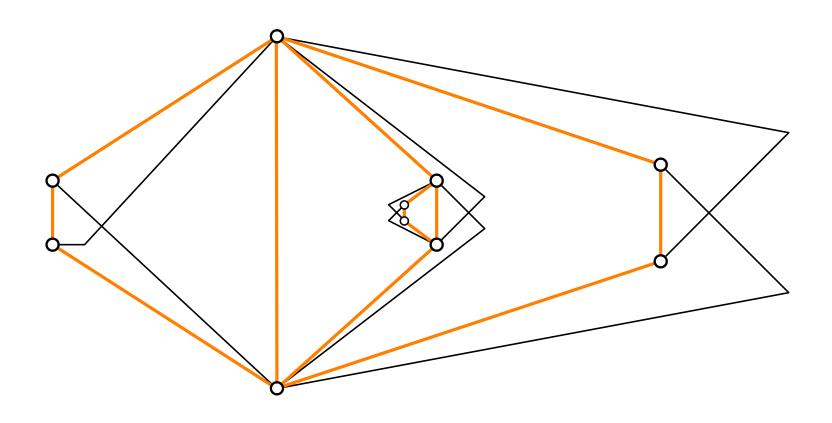


#### Algorithm Outline





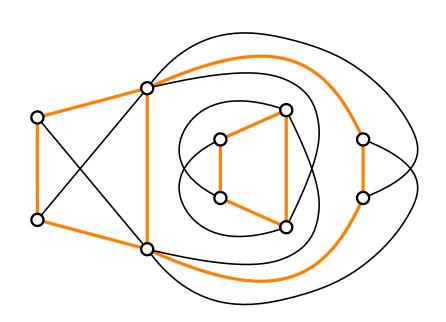
 $\Gamma$ : 1-bend 1-planar RAC drawing of G

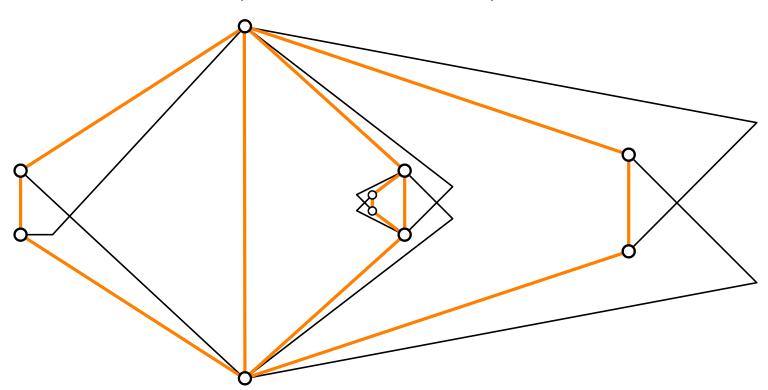


G: simple 1-plane graph

 $\Gamma$ : 1-bend 1-planar RAC drawing of G

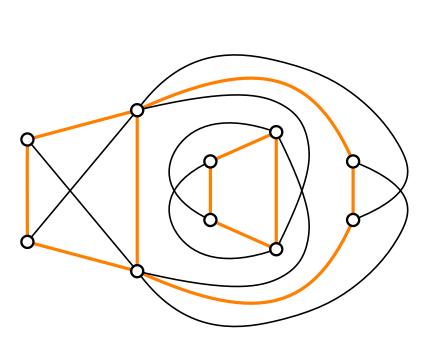
(embedding may differ)

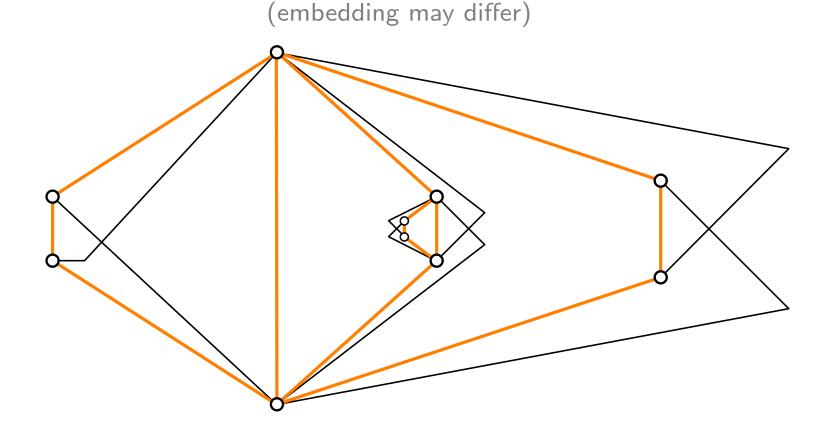




G: simple 1-plane graph

 $\Gamma$ : 1-bend 1-planar RAC drawing of G



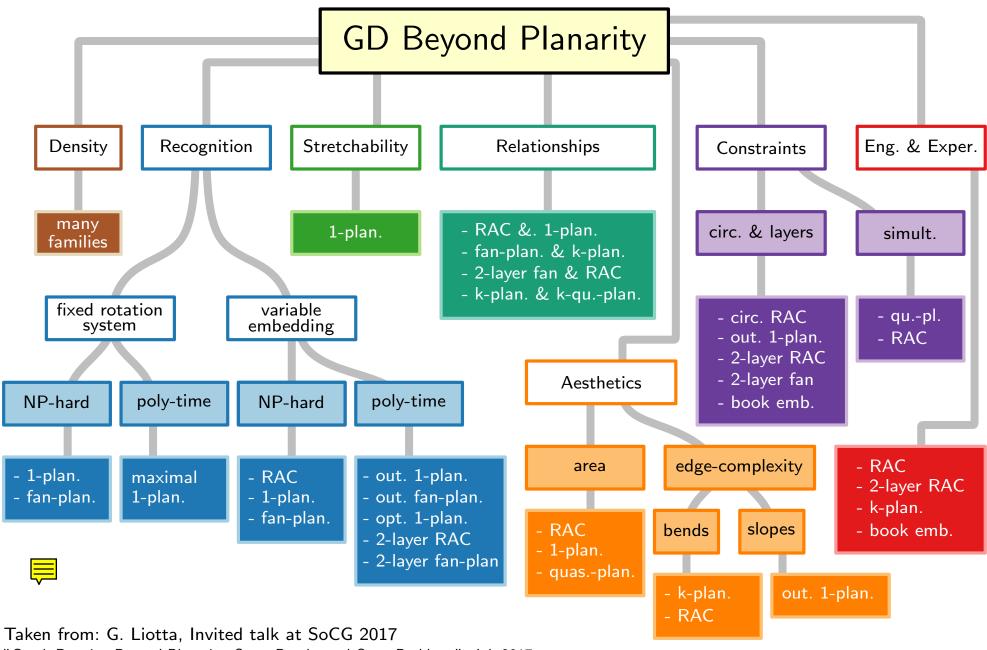


#### Remark.

By modifying the algorithm slightly, the given input embedding can be preserved.

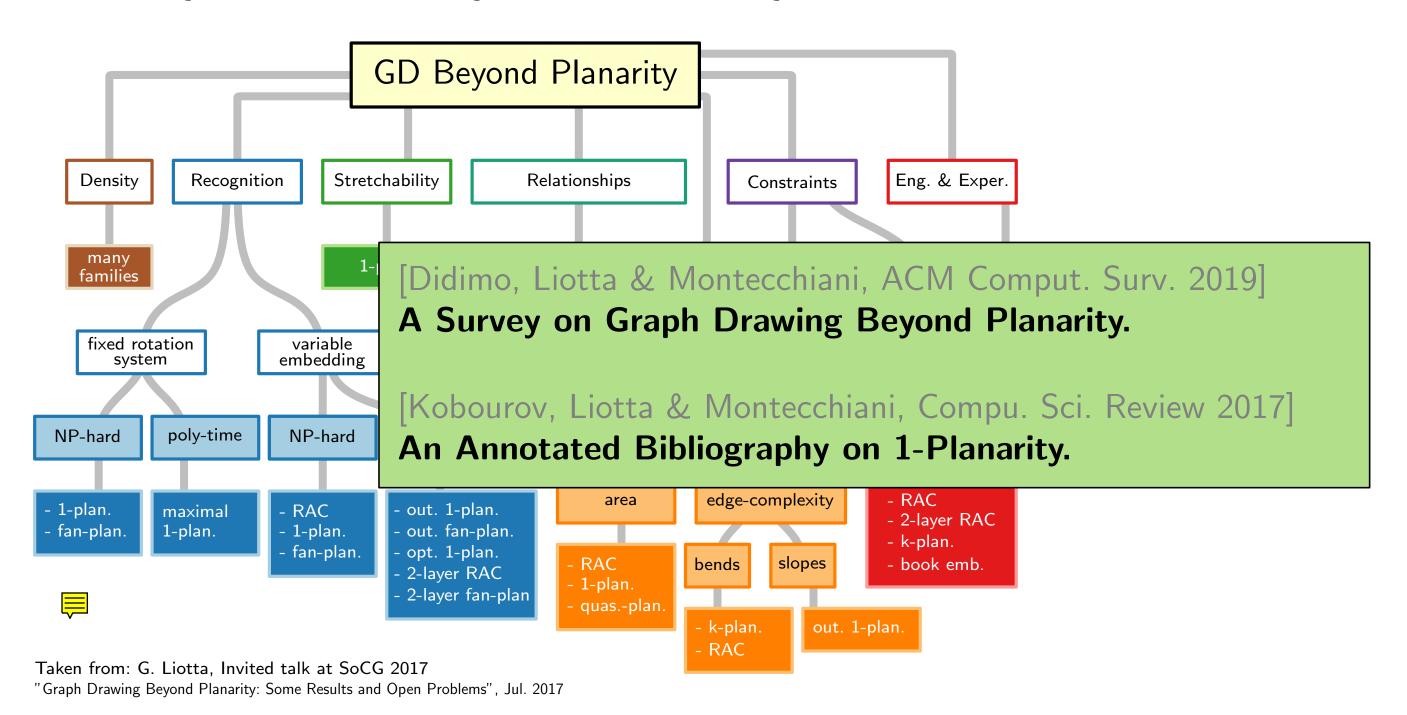
[Chaplick, Lipp, Wolff, Zink 2019]

#### GD Beyond Planarity: a Taxonomy



<sup>&</sup>quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

#### GD Beyond Planarity: a Taxonomy



#### Literature

#### Books and surveys:

- [Didimo, Liotta & Montecchiani 2019] A Survey on Graph Drawing Beyond Planarity
- [Kobourov, Liotta & Montecchiani '17] An Annotated Bibliography on 1-Planarity
- [Hong and Tokuyama, editors '20] Beyond Planar Graphs

#### Some references for proofs:

- [Eades, Huang, Hong '08] Effects of Crossing Angles
- [Brandenburg et al. '13] On the density of maximal 1-planar graphs
- [Chimani, Kindermann, Montecchani, Valtr '19] Crossing Numbers of Beyond-Planar Graphs
- [Grigoriev and Bodlaender '07] Algorithms for graphs embeddable with few crossings per edge
- [Angelini et al. '11] On the Perspectives Opened by Right Angle Crossing Drawings
- [Didimo, Eades, Liotta '17] Drawing graphs with right angle crossings
- [Bekos et al. '17] On RAC drawings of 1-planar graphs