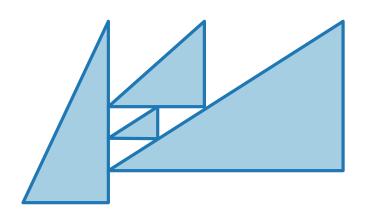


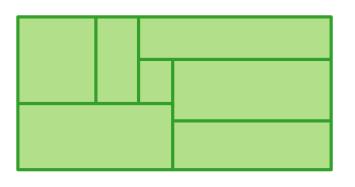
Visualization of Graphs

Lecture 7:

Contact Representations of Planar Graphs: Triangle Contacts and Rectangular Duals



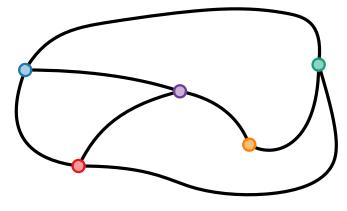
Alexander Wolff



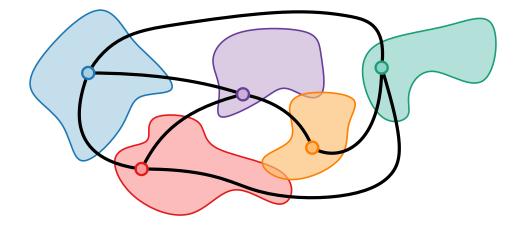
Summer term 2025

In an intersection representation of a graph,

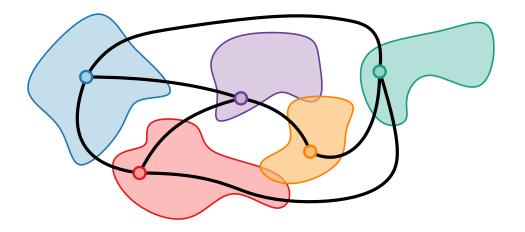
each vertex is represented by a set



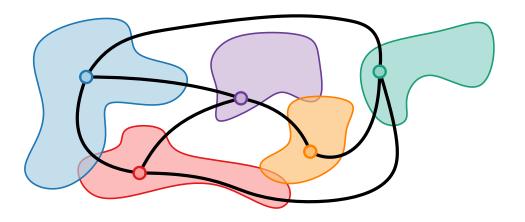
- each vertex is represented by a set
- such that



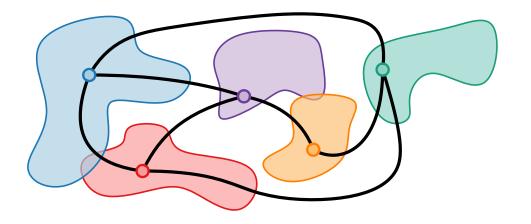
- each vertex is represented by a set
- such that two sets intersect ⇔
 the corresponding vertices are adjacent.



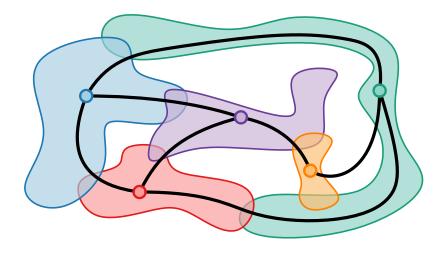
- each vertex is represented by a set
- such that two sets intersect ⇔
 the corresponding vertices are adjacent.



- each vertex is represented by a set
- such that two sets intersect ⇔
 the corresponding vertices are adjacent.



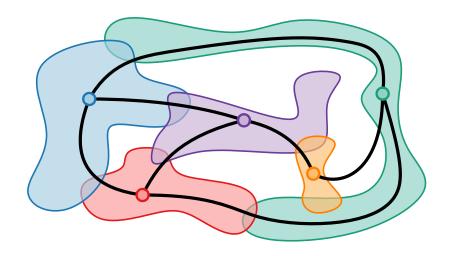
- each vertex is represented by a set
- such that two sets intersect ⇔
 the corresponding vertices are adjacent.

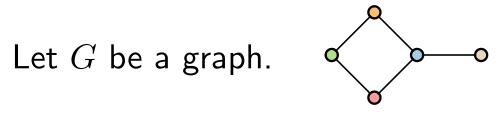


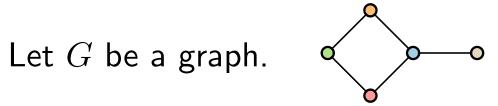
In an intersection representation of a graph,

- each vertex is represented by a set
- such that two sets intersect ⇔
 the corresponding vertices are adjacent.

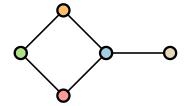
For a collection \mathcal{S} of sets, the **intersection graph** $G(\mathcal{S})$ of \mathcal{S} has vertex set \mathcal{S} and edge set $\{\{S,S'\}:S,S'\in\mathcal{S},S\neq S',\text{ and }S\cap S'\neq\emptyset\}.$

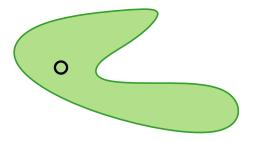




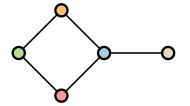


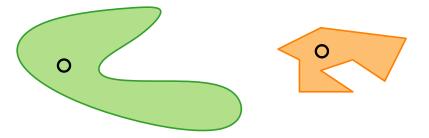
Let G be a graph.



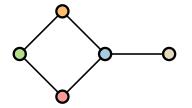


Let G be a graph.



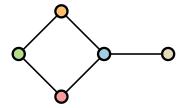


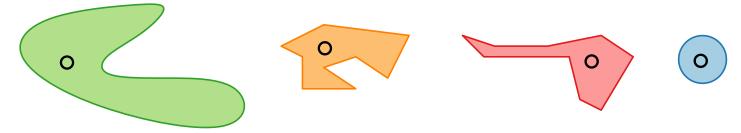
Let G be a graph.



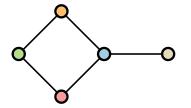


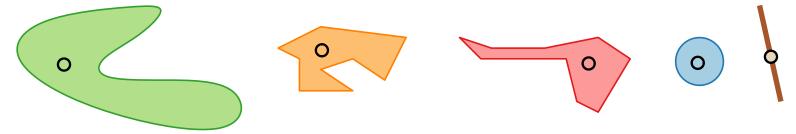
Let G be a graph.



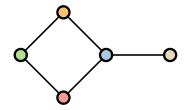


Let G be a graph.

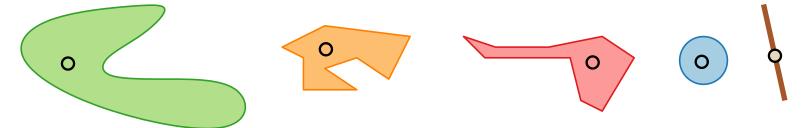




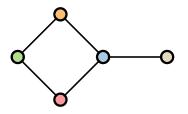
Let ${\cal G}$ be a graph.



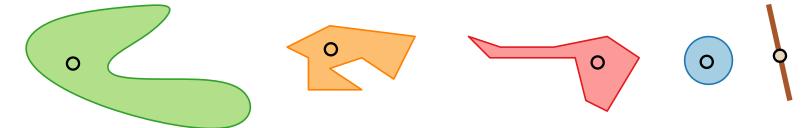
Represent each vertex v by a geometric object S(v)

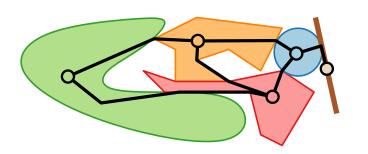


Let G be a graph.

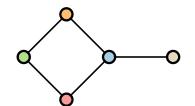


Represent each vertex v by a geometric object S(v)





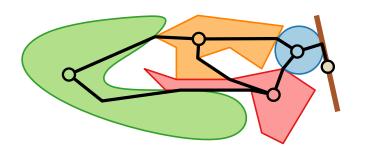
Let G be a graph.



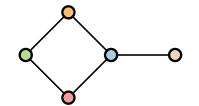
Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object S(v)





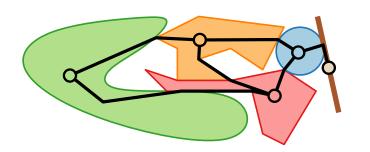
Let G be a graph.



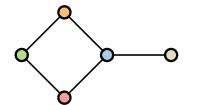
Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$





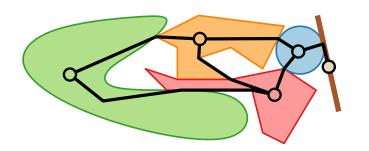
Let G be a graph.



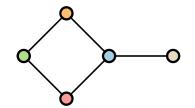
Let $\mathcal S$ be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$





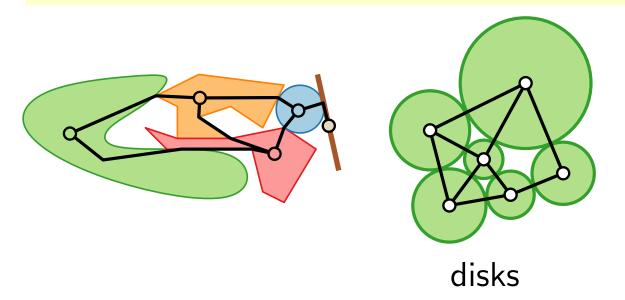
Let G be a graph.



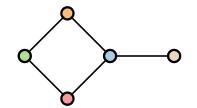
Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$





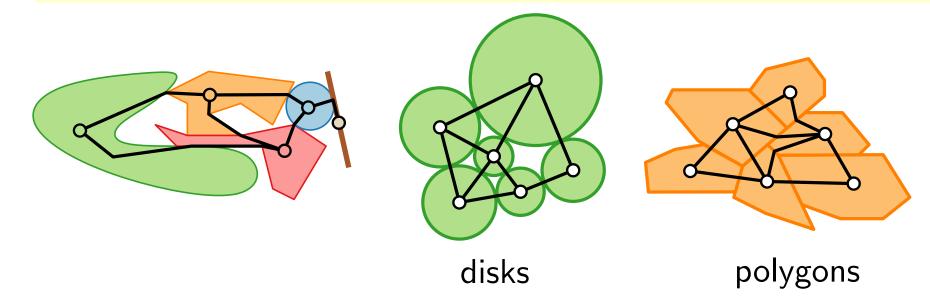
Let G be a graph.



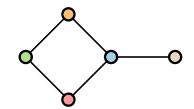
Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$





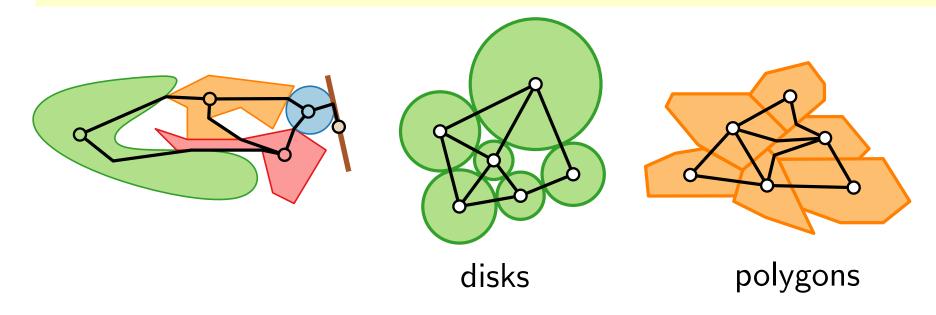
Let G be a graph.



Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$

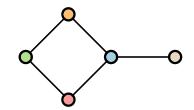






rectangular cuboids

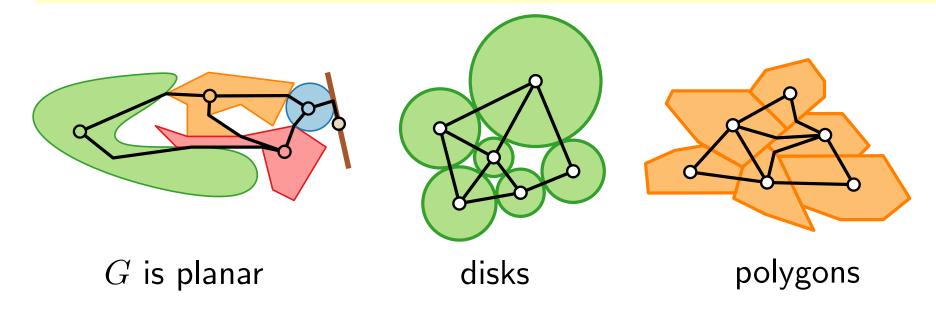
Let G be a graph.



Let S be a family of geometric objects (e.g., disks).

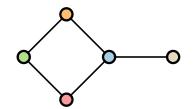
Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$





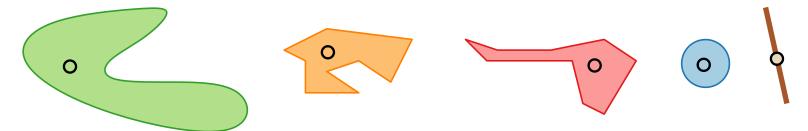


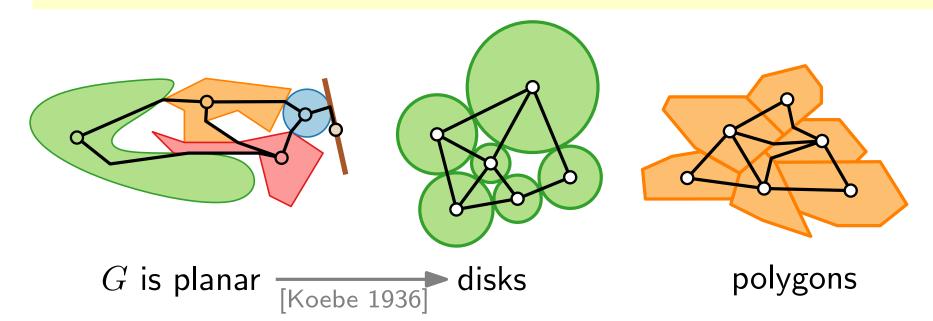
Let G be a graph.

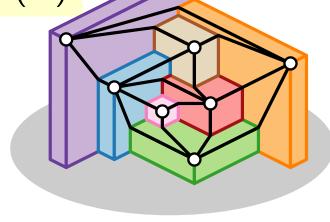


Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$

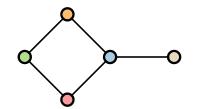






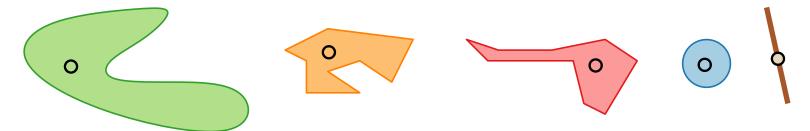
rectangular cuboids

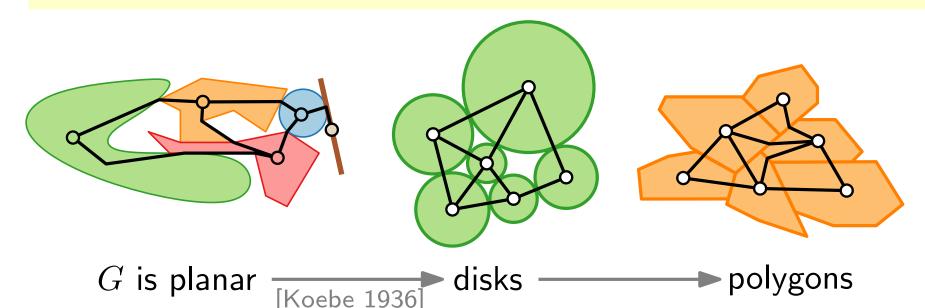
Let G be a graph.

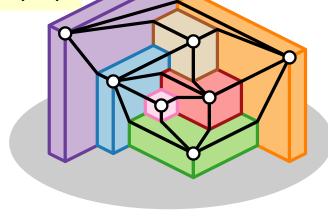


Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$

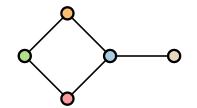






rectangular cuboids

Let G be a graph.

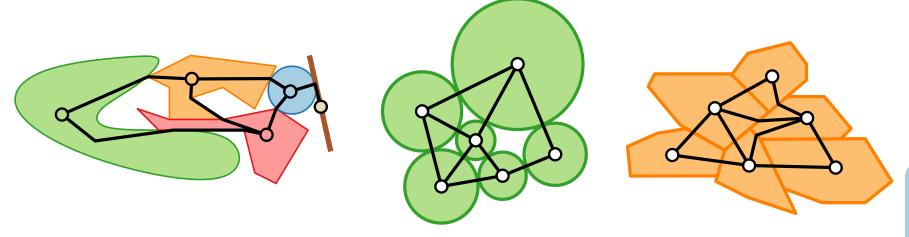


Let S be a family of geometric objects (e.g., disks).

Represent each vertex v by a geometric object $S(v) \in \mathcal{S}$



In an S-contact representation of G, S(u) and S(v) touch iff $uv \in E(G)$.



G is planar $\frac{}{[\text{Koebe 1936}]}$ disks — polygons

A contact representation is an intersection representation with interior-disjoint sets.

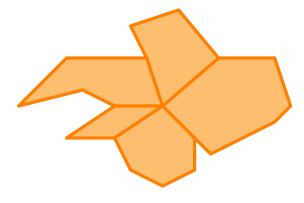
Is the intersection graph of a contact representation always planar?

Is the intersection graph of a contact representation always planar?

■ No, not even for connected object types in the plane.

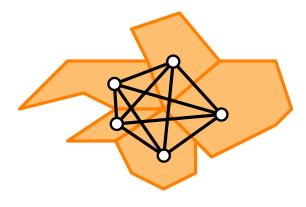
Is the intersection graph of a contact representation always planar?

■ No, not even for connected object types in the plane.



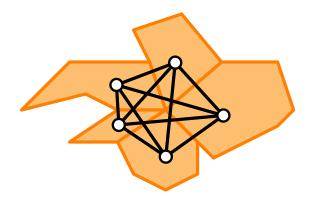
Is the intersection graph of a contact representation always planar?

■ No, not even for connected object types in the plane.



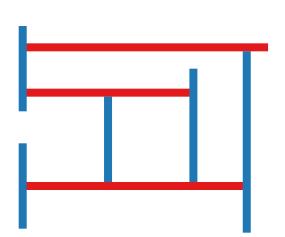
Is the intersection graph of a contact representation always planar?

■ No, not even for connected object types in the plane.

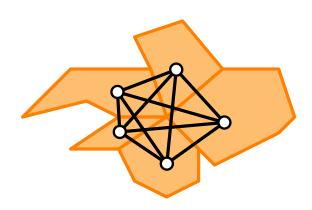


Is the intersection graph of a contact representation always planar?

■ No, not even for connected object types in the plane.

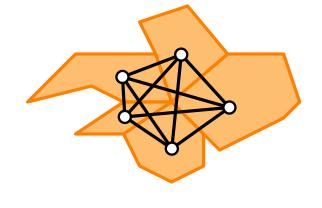


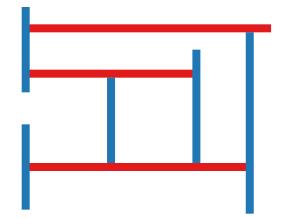
bipartite planar graphs



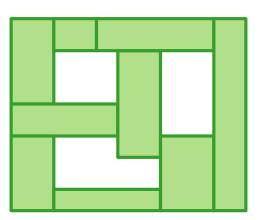
Is the intersection graph of a contact representation always planar?

■ No, not even for connected object types in the plane.





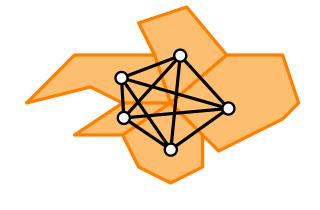


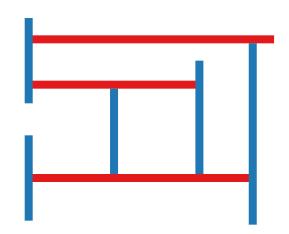


max. triangle-free planar graphs

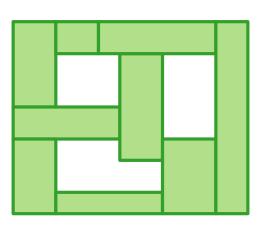
Is the intersection graph of a contact representation always planar?

■ No, not even for connected object types in the plane.

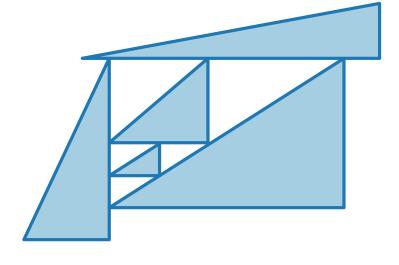




bipartite planar graphs



max. triangle-free planar graphs



planar triangulations

General Approach

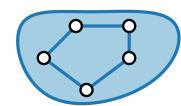
How to compute a contact representation of a given graph G?

How to compute a contact representation of a given graph G?

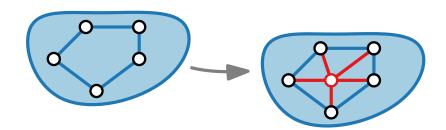
 Consider only inner triangulations (or maximal bipartite graphs, etc.)

- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges

- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges

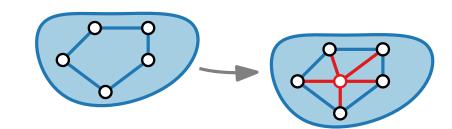


- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges



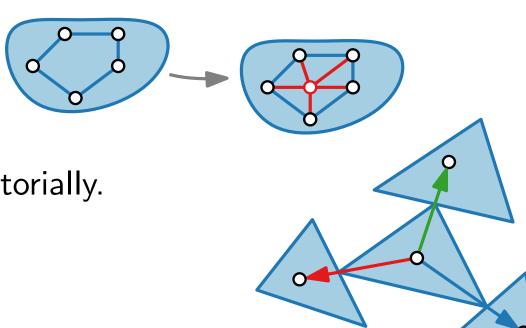
How to compute a contact representation of a given graph G?

- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges



Describe contact representation combinatorially.

- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges
- Describe contact representation combinatorially.

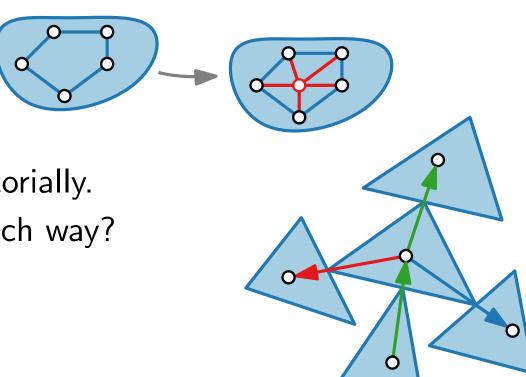


How to compute a contact representation of a given graph G?

- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges



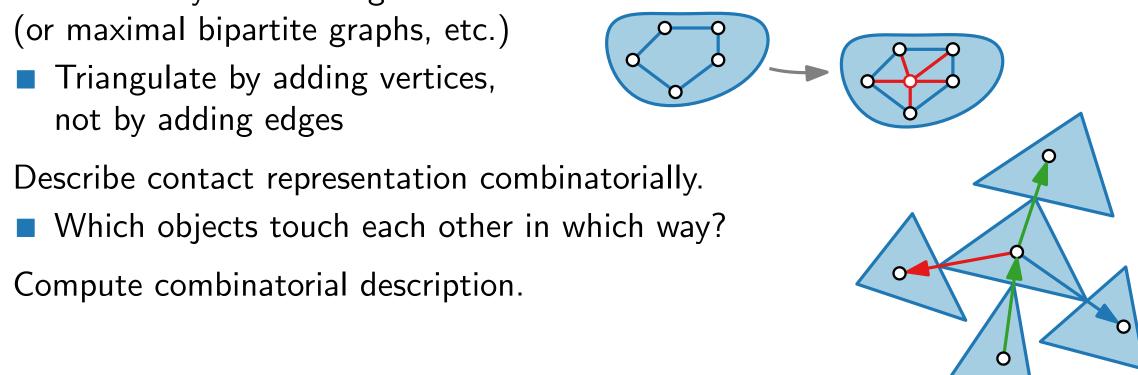
■ Which objects touch each other in which way?



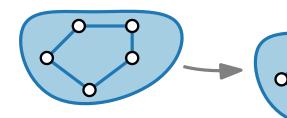
- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges



- Which objects touch each other in which way?
- Compute combinatorial description.

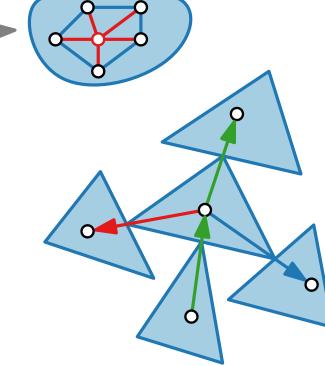


- Consider only inner triangulations (or maximal bipartite graphs, etc.)
 - Triangulate by adding vertices, not by adding edges

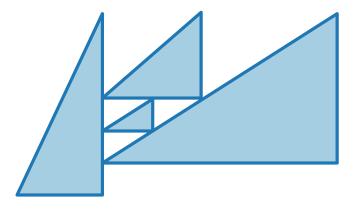




- Which objects touch each other in which way?
- Compute combinatorial description.
- Show that combinatorial description can be used to construct drawing.

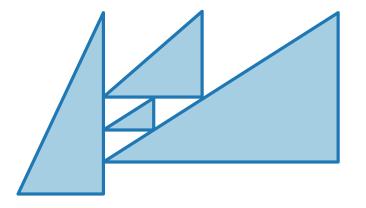


Representation with right-angled triangles and corner contact:



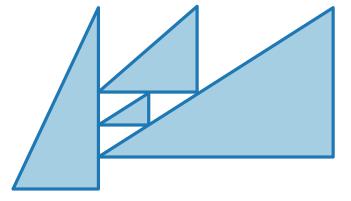
Representation with right-angled triangles and corner contact:

■ Use Schnyder realizer to describe contacts between triangles.



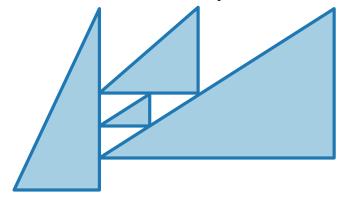
Representation with right-angled triangles and corner contact:

- Use Schnyder realizer to describe contacts between triangles.
- Use canonical order to compute drawing.

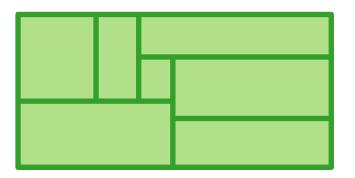


Representation with right-angled triangles and corner contact:

- Use Schnyder realizer to describe contacts between triangles.
- Use canonical order to compute drawing.

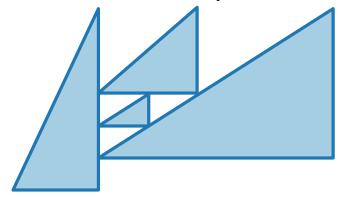


Representation with dissection of a rectangle, called rectangular dual:



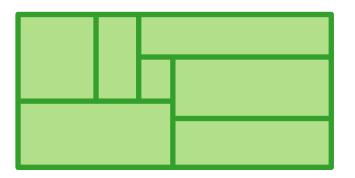
Representation with right-angled triangles and corner contact:

- Use Schnyder realizer to describe contacts between triangles.
- Use canonical order to compute drawing.



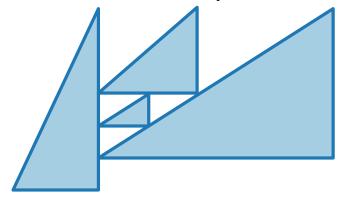
Representation with dissection of a rectangle, called rectangular dual:

■ Find a description similar to a Schnyder realizer for rectangles.



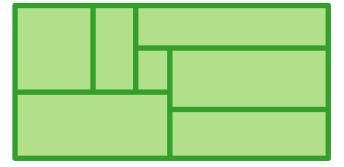
Representation with right-angled triangles and corner contact:

- Use Schnyder realizer to describe contacts between triangles.
- Use canonical order to compute drawing.



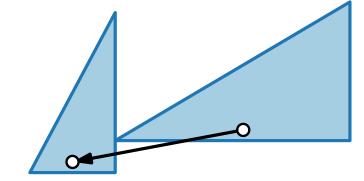
Representation with dissection of a rectangle, called rectangular dual:

- Find a description similar to a Schnyder realizer for rectangles.
- Construct drawing via st-digraphs, duals, and topological sorting.

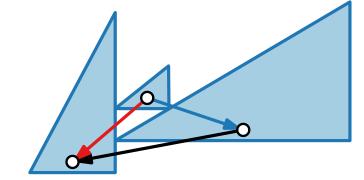


Main Idea.

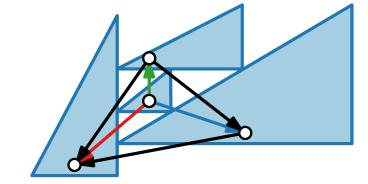
Main Idea.



Main Idea.

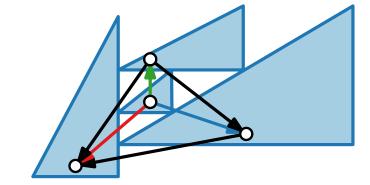


Main Idea.



Main Idea.

Use canonical order and Schnyder realizer to find coordinates for triangles.

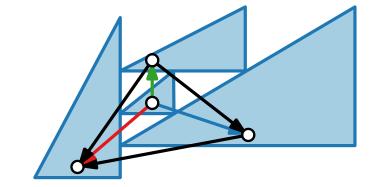


Detailed Idea.

■ Place base of triangle at height equal to position in canonical order.

Main Idea.

Use canonical order and Schnyder realizer to find coordinates for triangles.

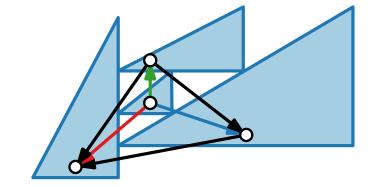


Detailed Idea.

- Place base of triangle at height equal to position in canonical order.
- Triangle tip is precisely at base of triangle corresponding to cover neighbor.

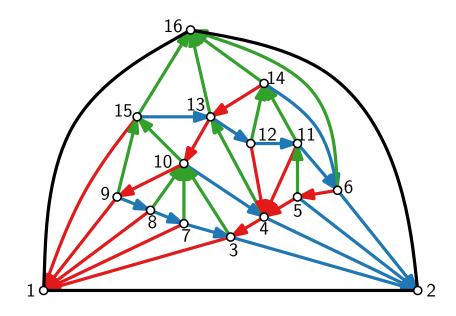
Main Idea.

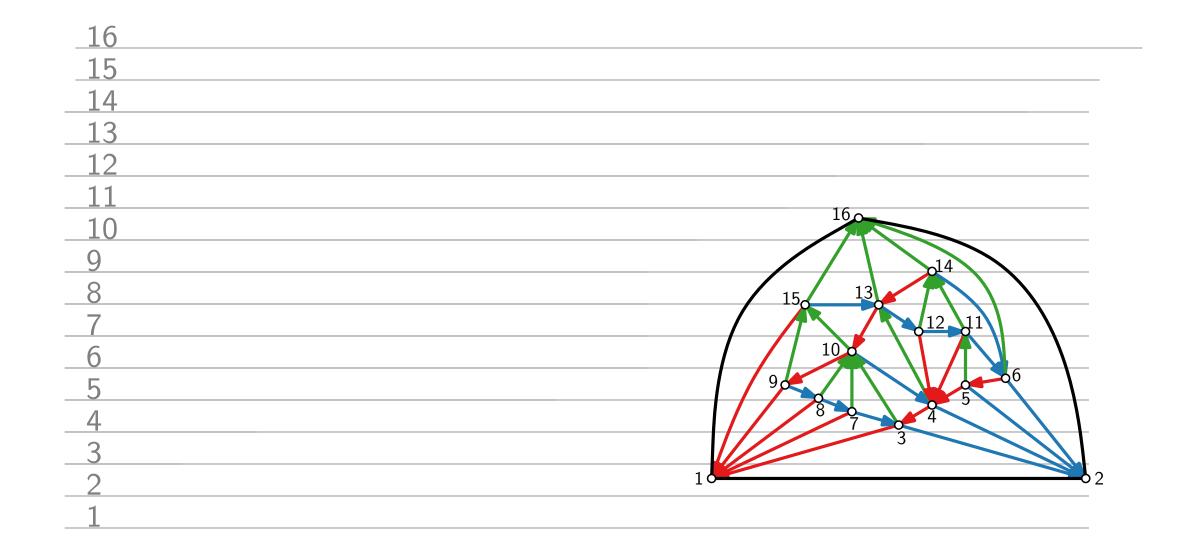
Use canonical order and Schnyder realizer to find coordinates for triangles.

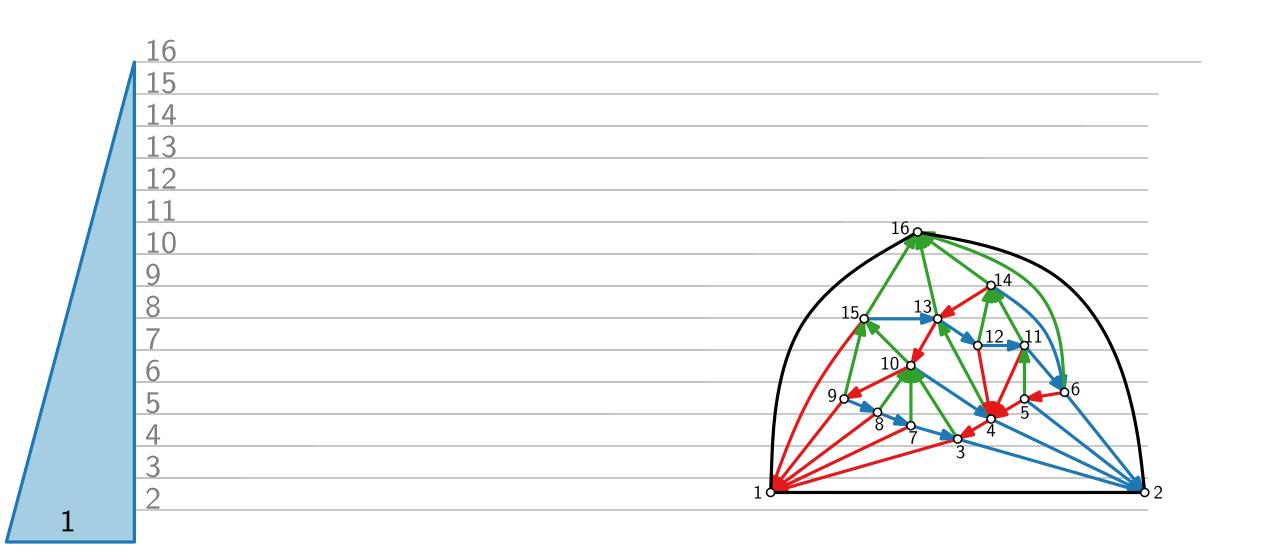


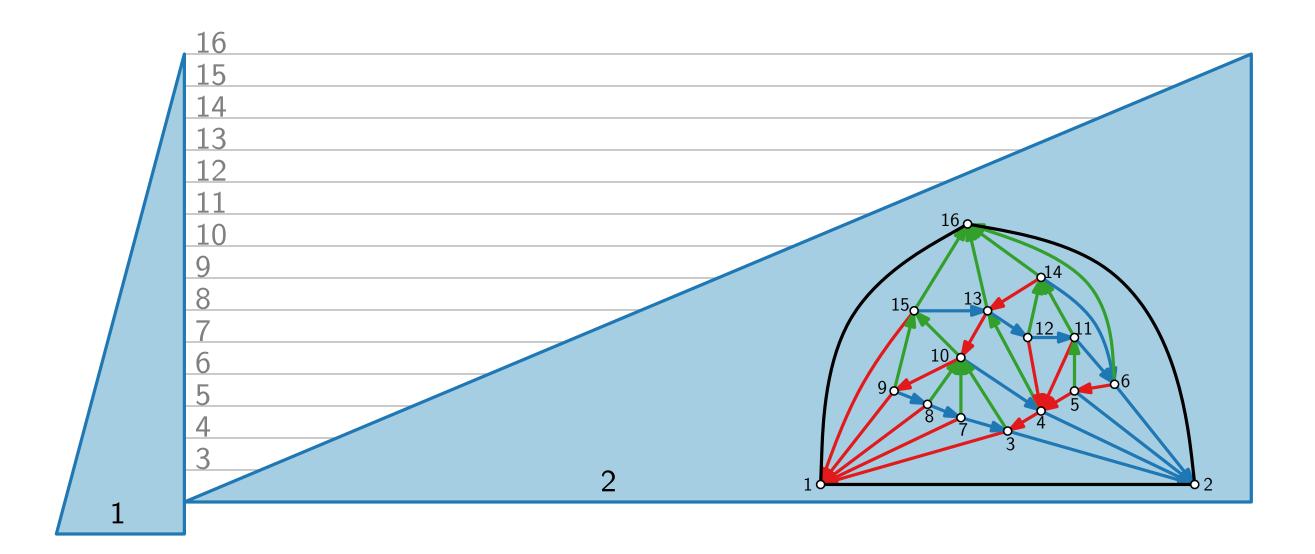
Detailed Idea.

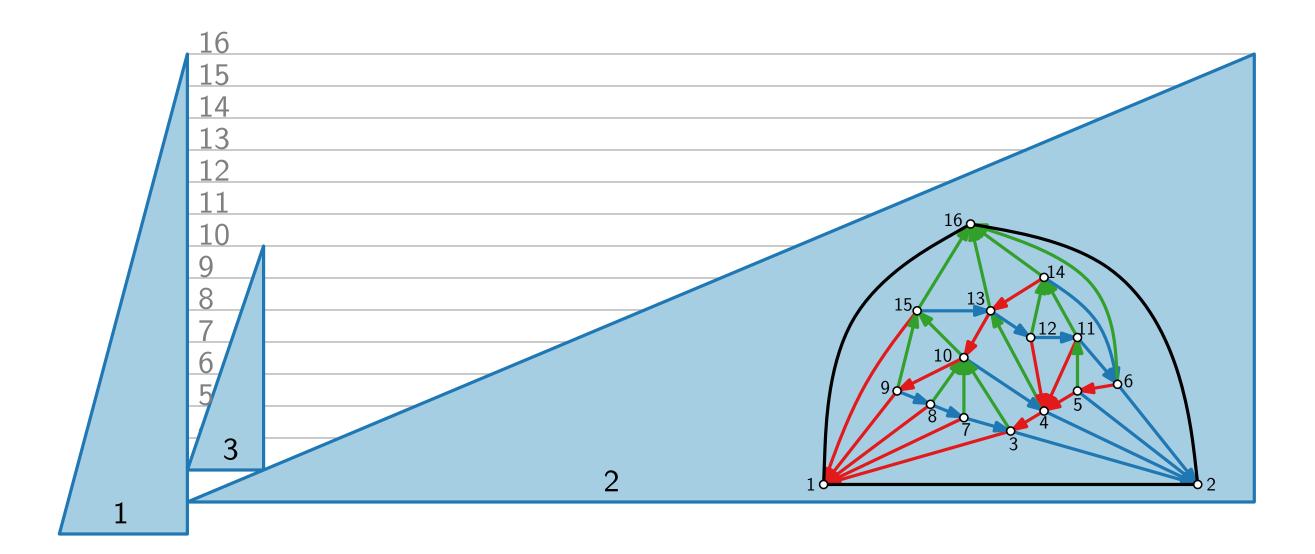
- Place base of triangle at height equal to position in canonical order.
- Triangle tip is precisely at base of triangle corresponding to cover neighbor.
- Outgoing edges in Schnyder forest indicate corner contacts.

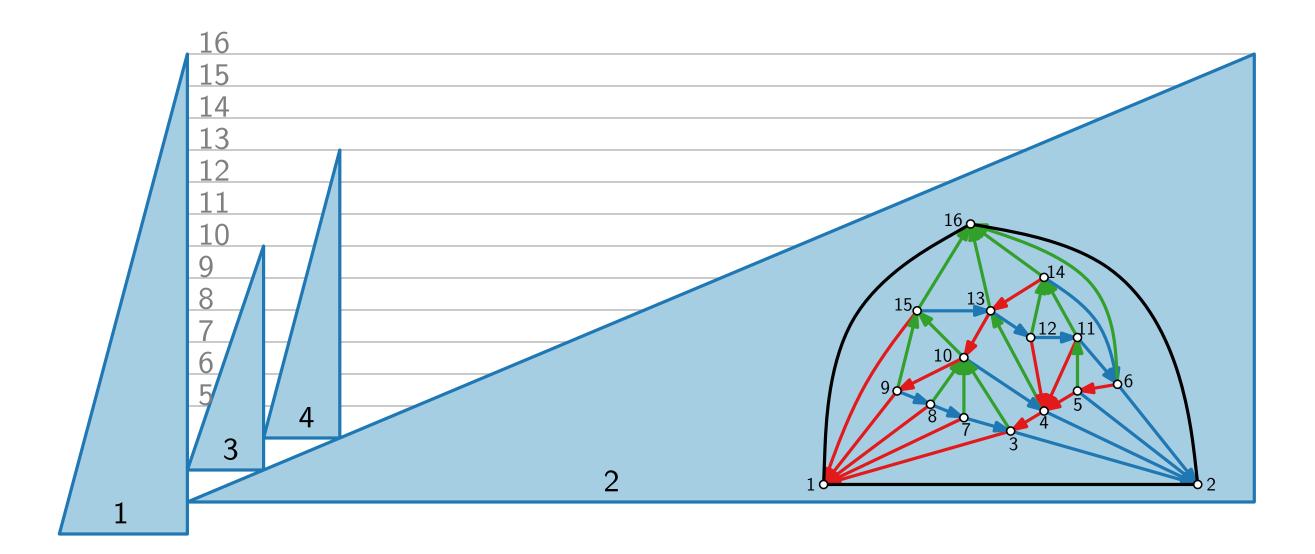


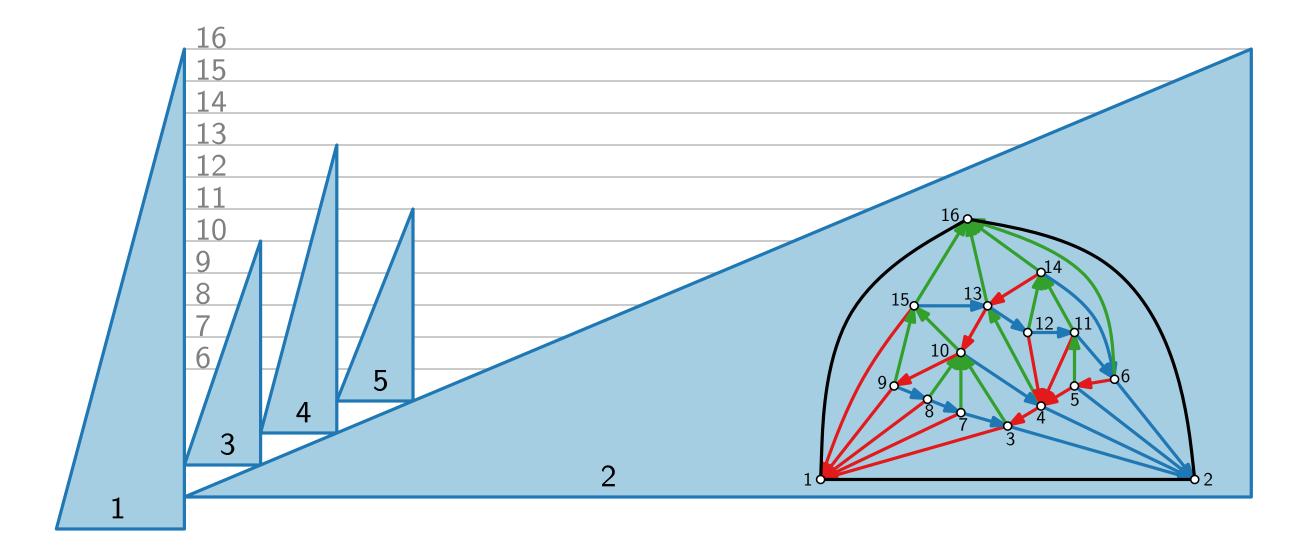


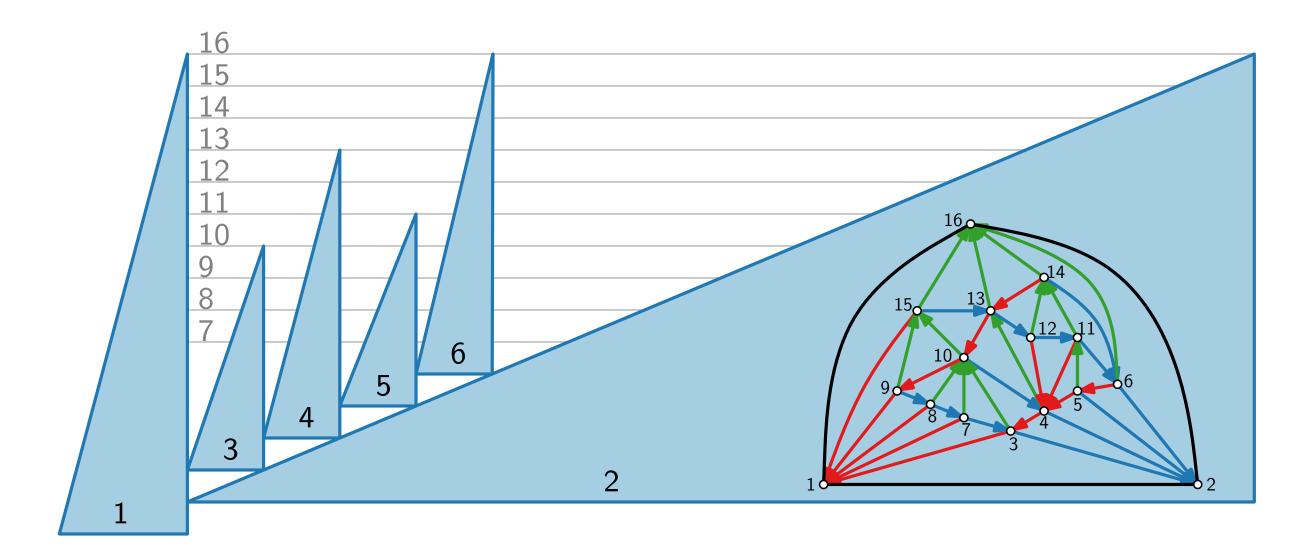


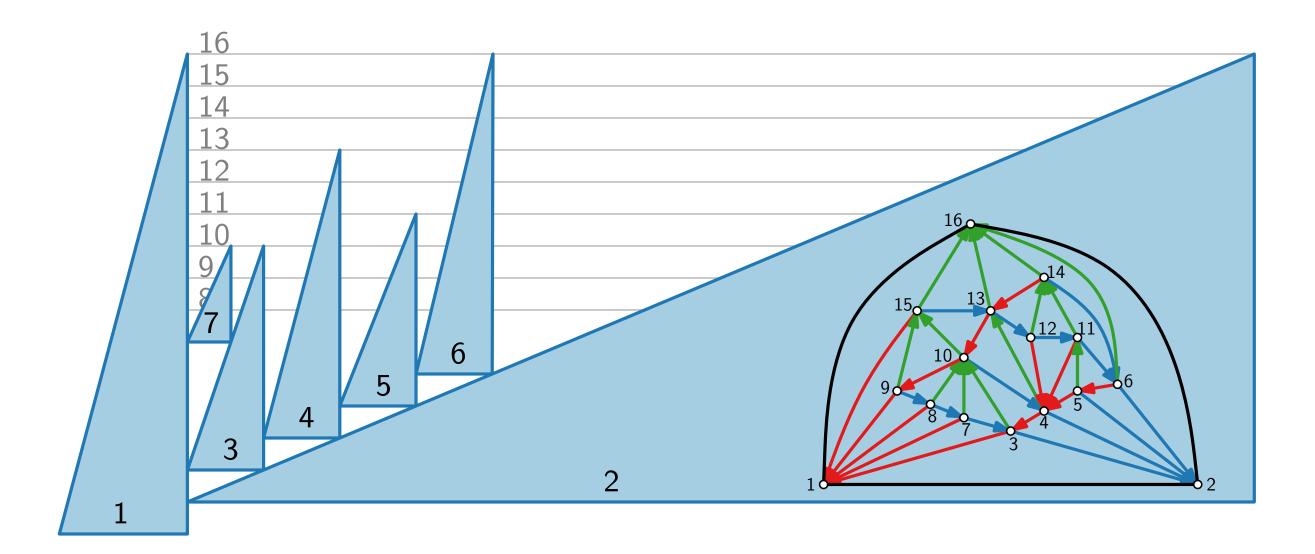


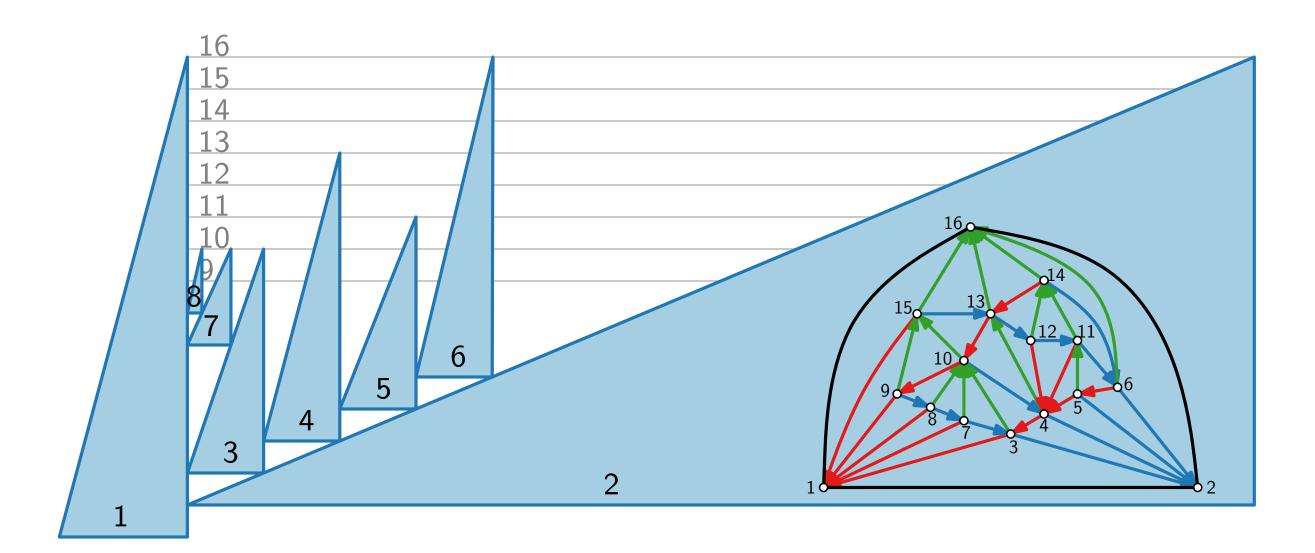


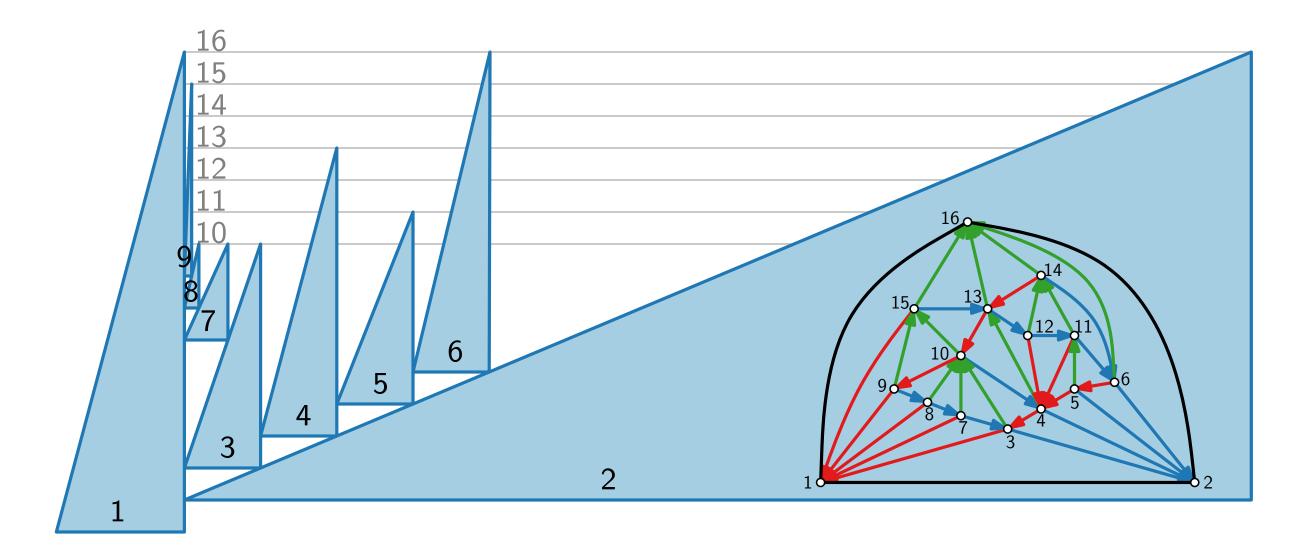


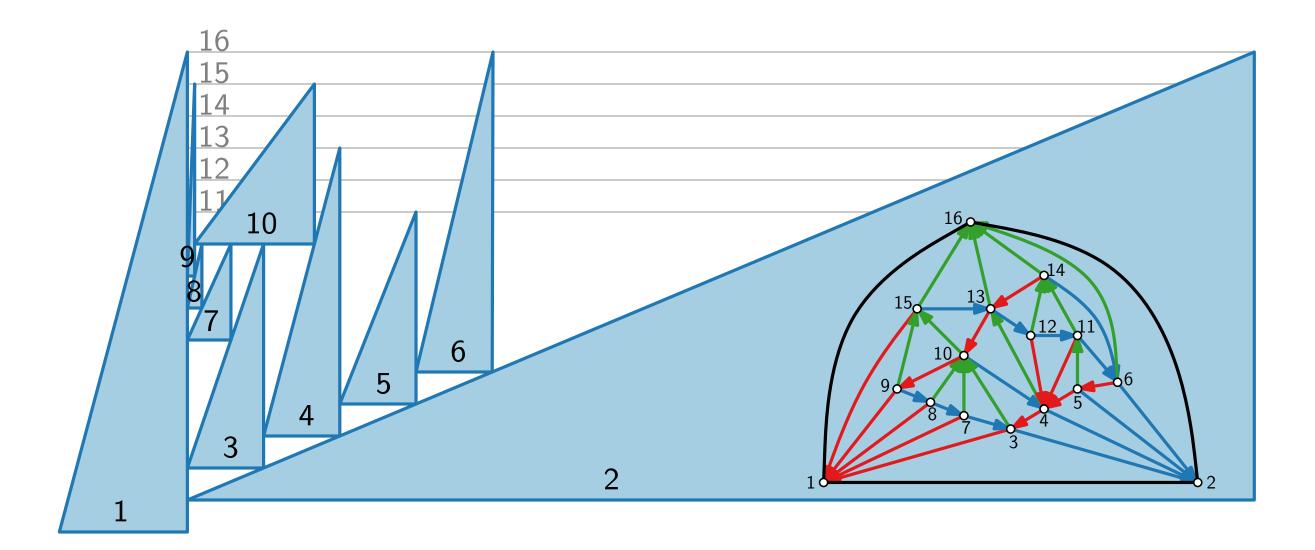


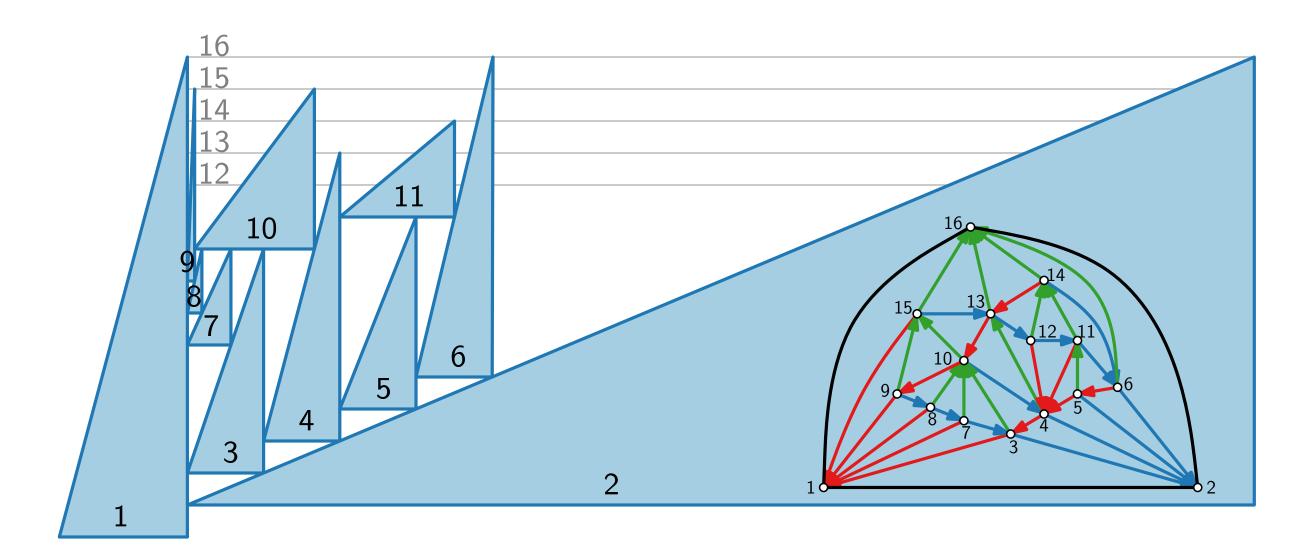


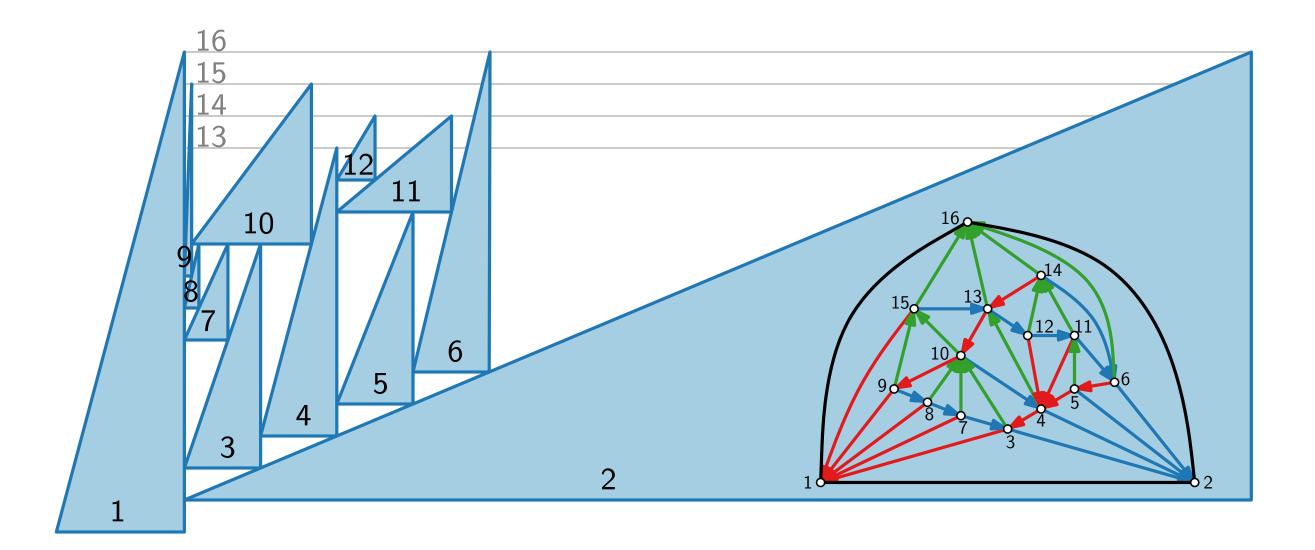


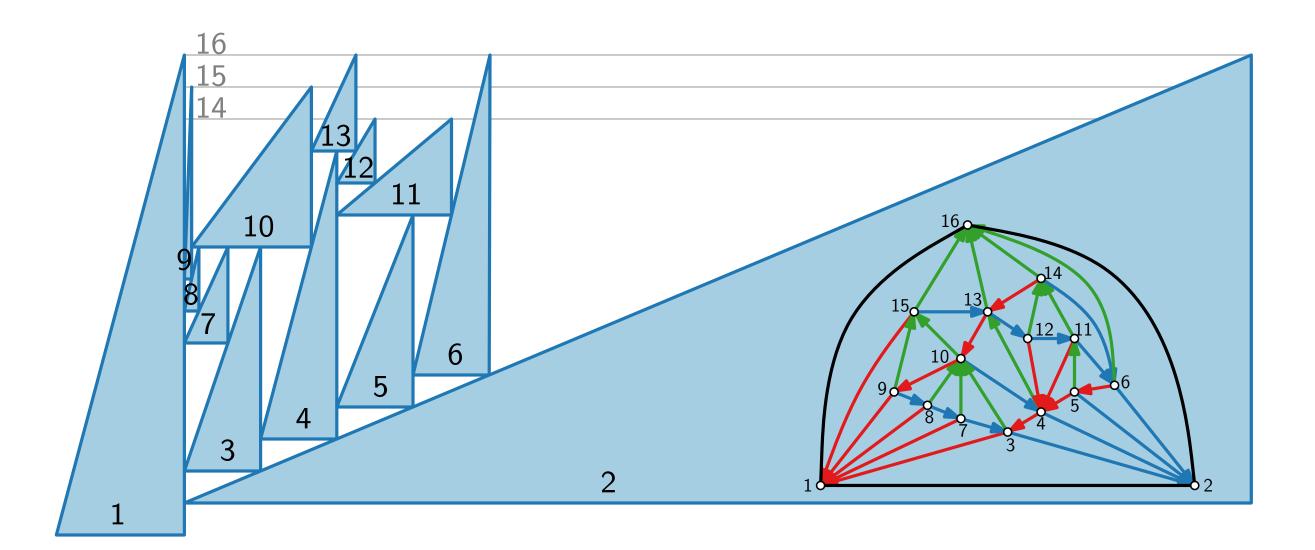


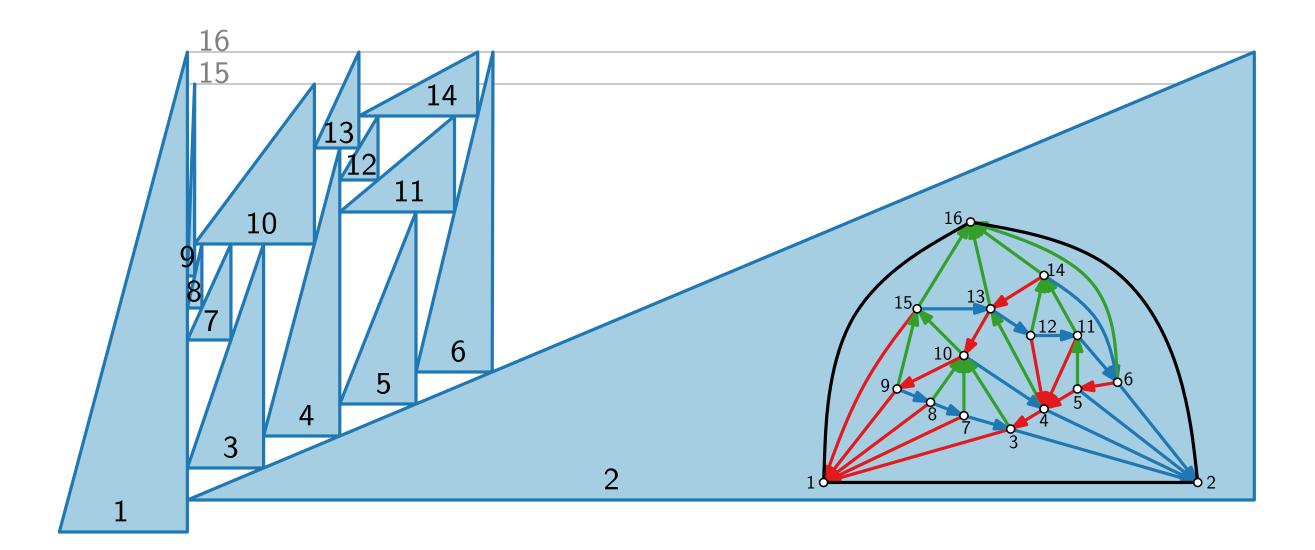


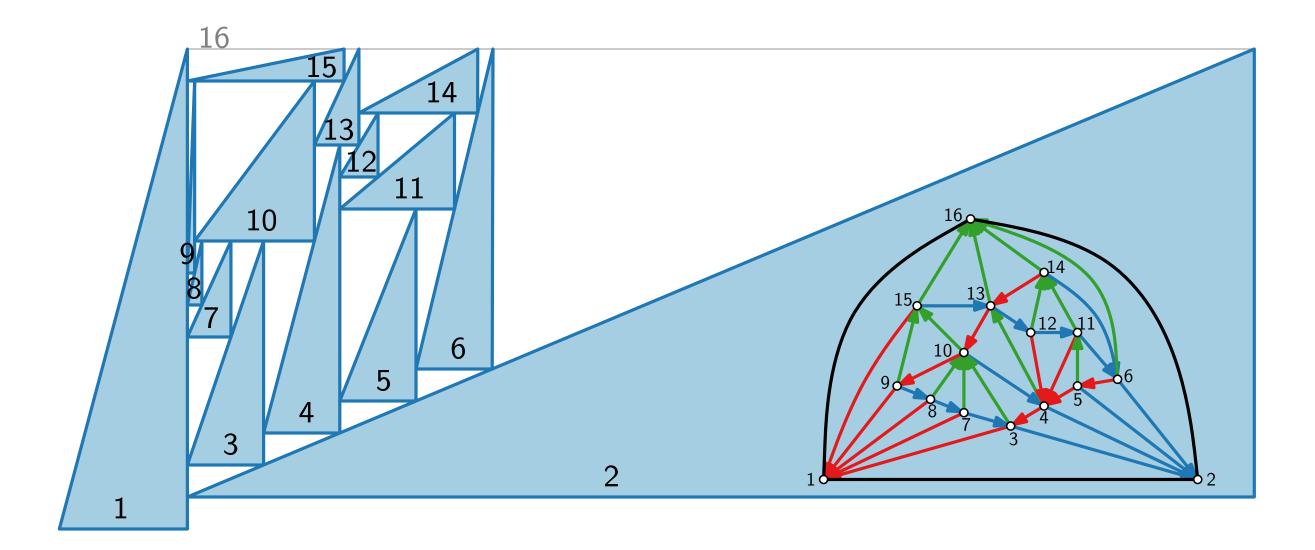


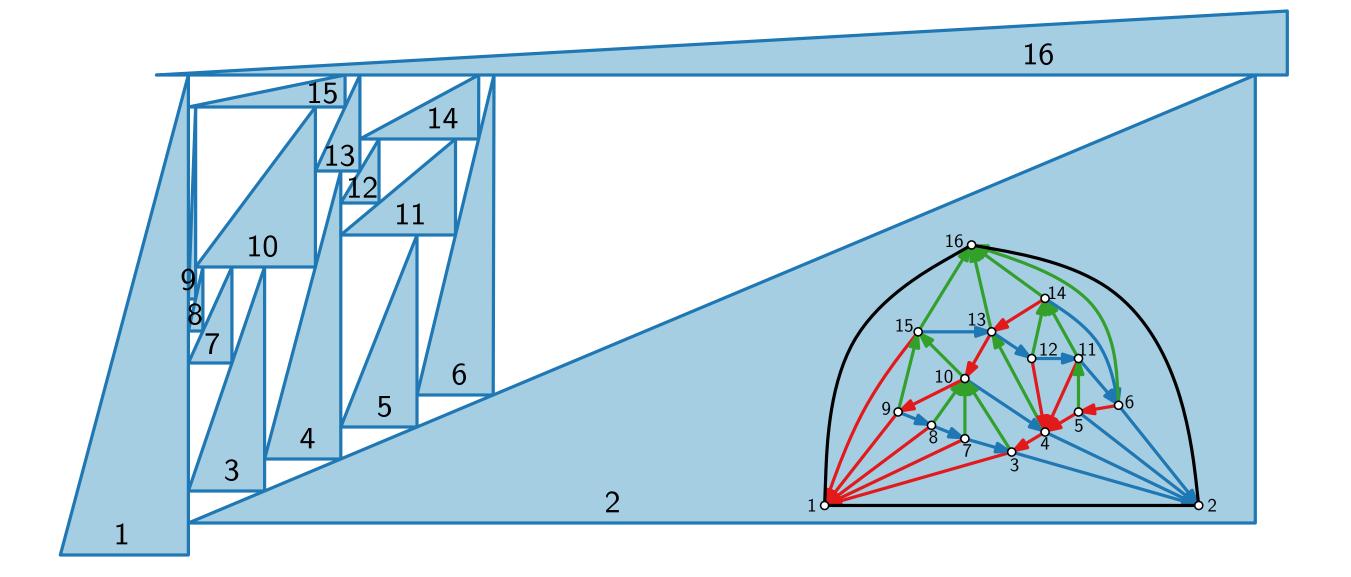


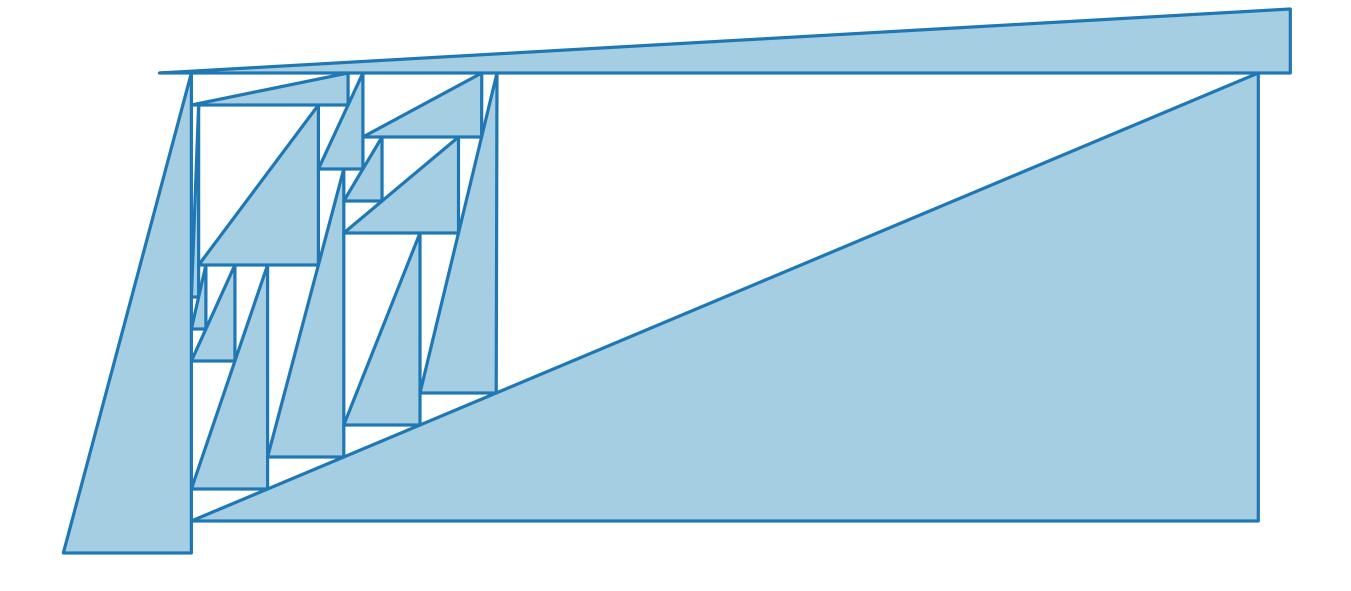


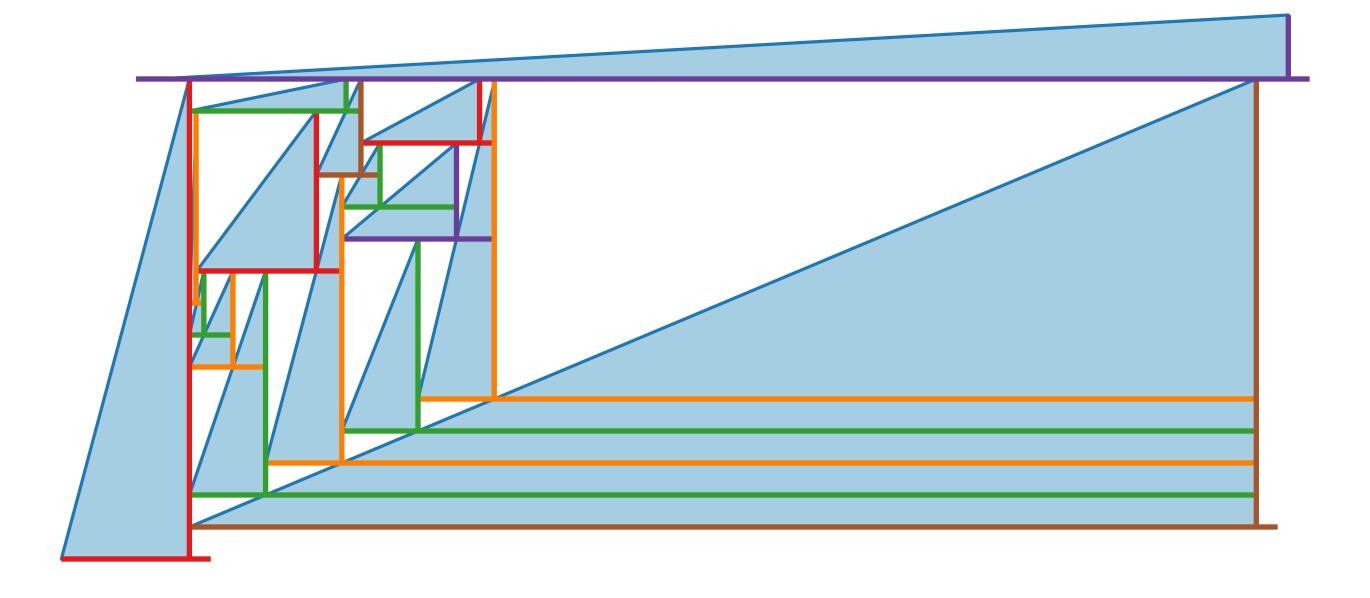


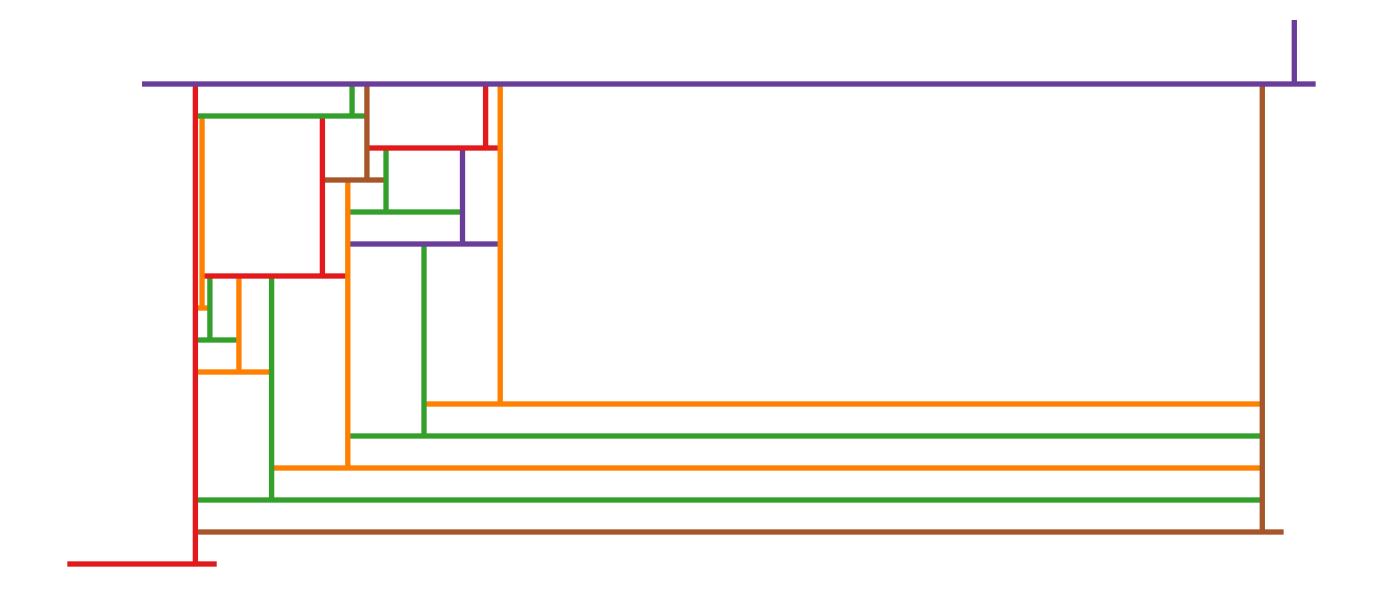


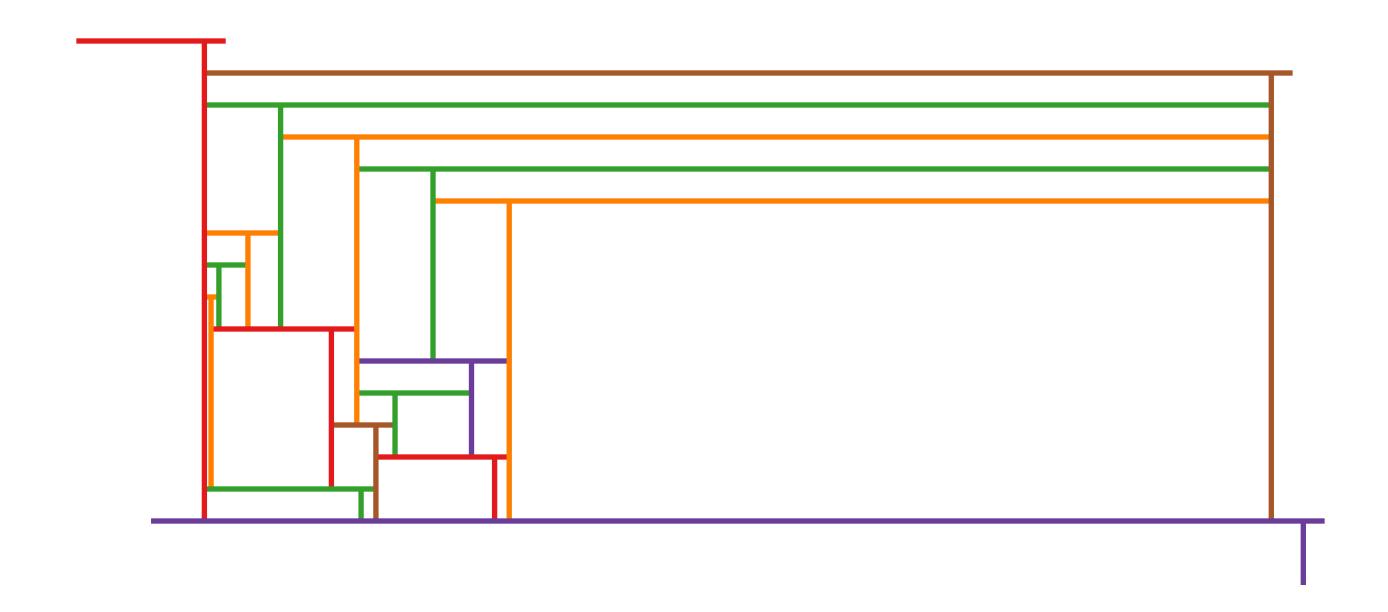


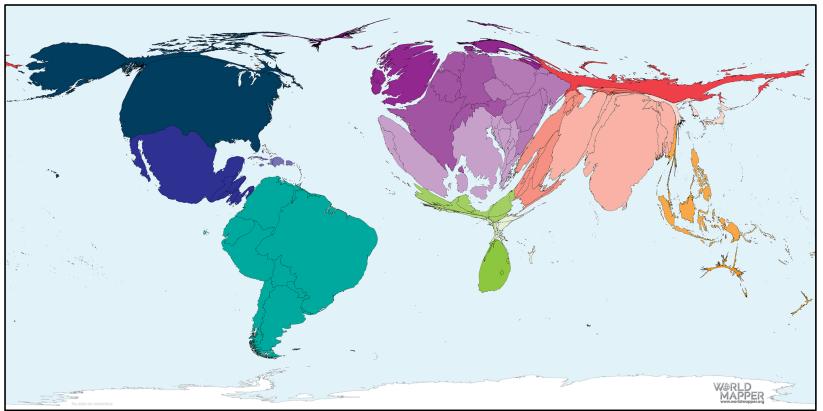




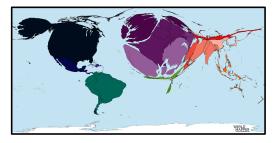




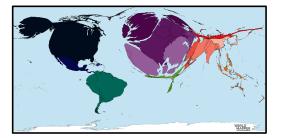




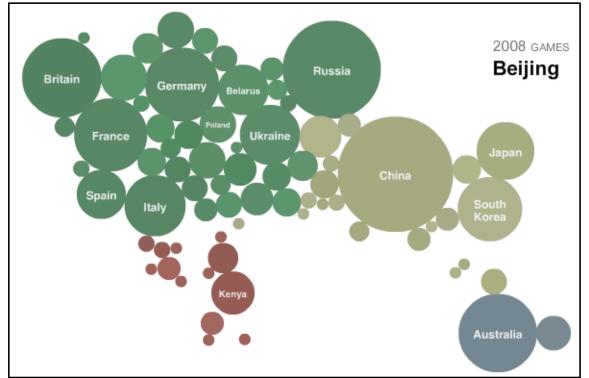
COVID19 reported deaths (January–December 2020)

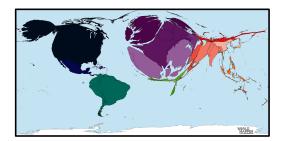


© worldmapper.org

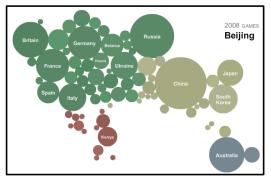


© worldmapper.org

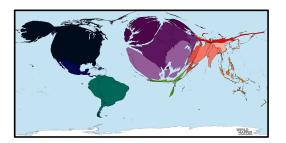




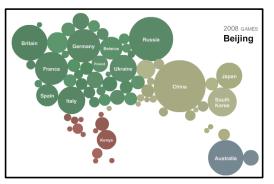
© worldmapper.org



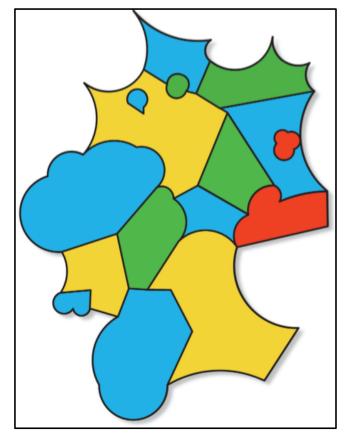
© New York Times

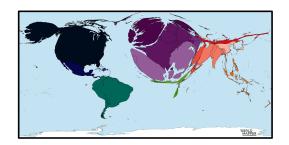


© worldmapper.org

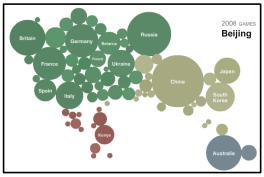


© New York Times

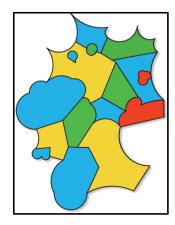


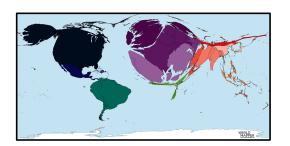


© worldmapper.org

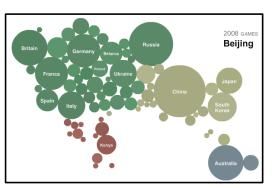


© New York Times

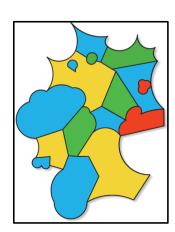


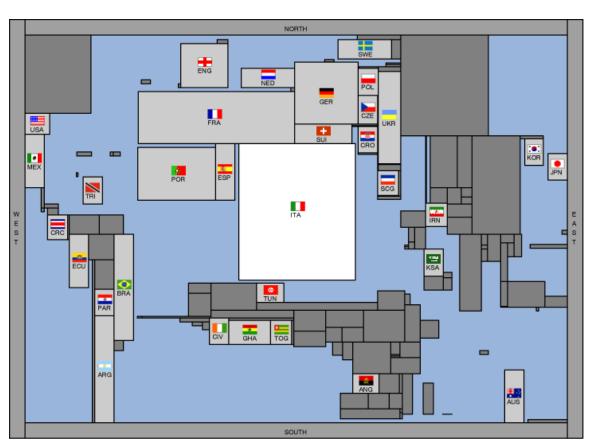


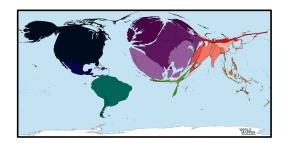
© worldmapper.org



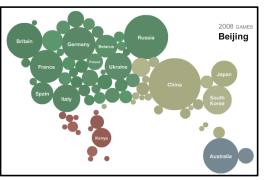
© New York Times



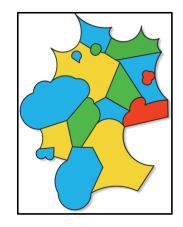


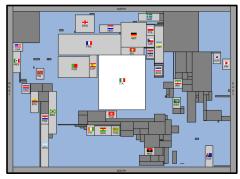


© worldmapper.org

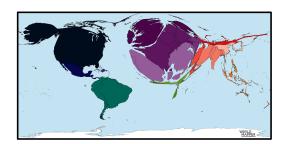


© New York Times

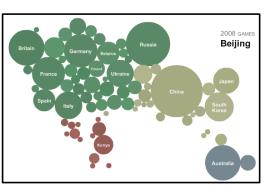




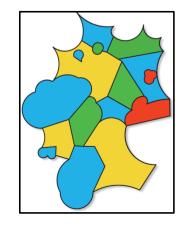
© Bettina Speckmann

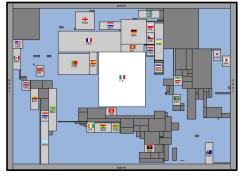


© worldmapper.org

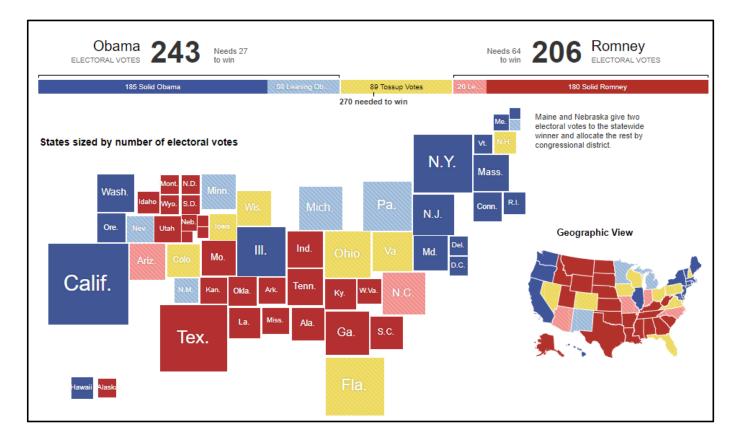


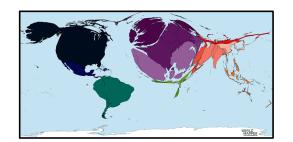
© New York Times



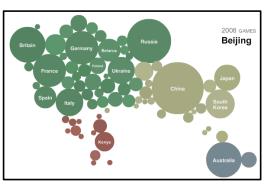


© Bettina Speckmann

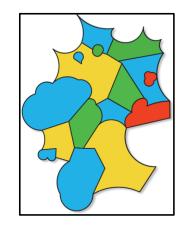




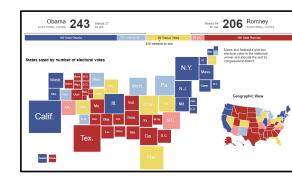
© worldmapper.org



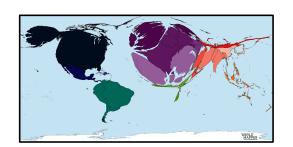
© New York Times



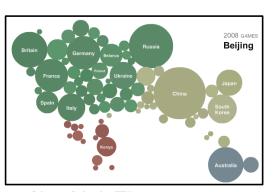
© Bettina Speckmann



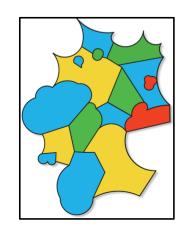
© New York Times



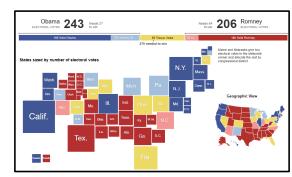
© worldmapper.org



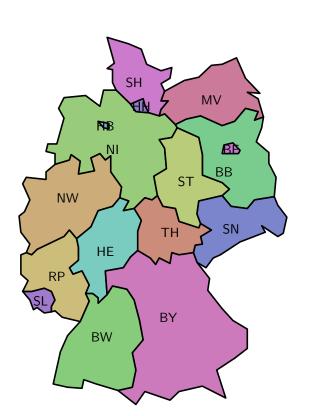
© New York Times

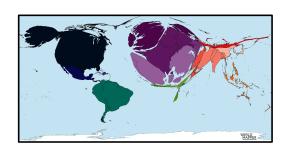


© Bettina Speckmann

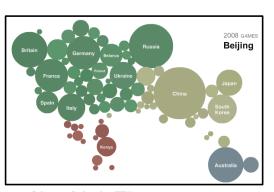


© New York Times

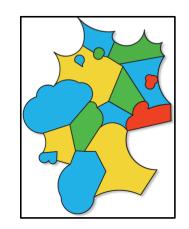




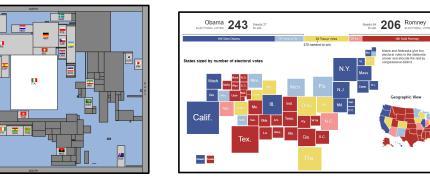
© worldmapper.org



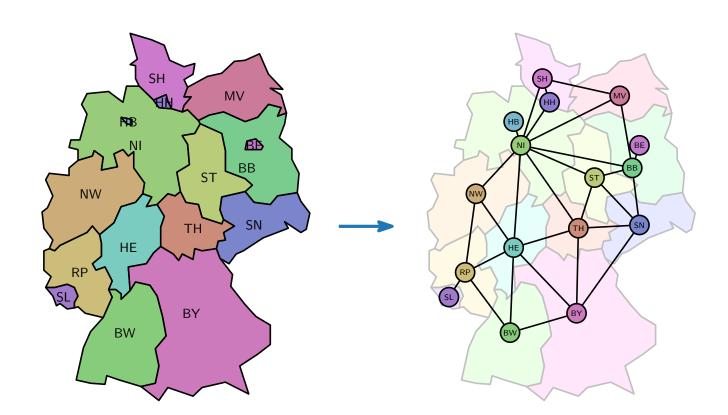
© New York Times



© Bettina Speckmann

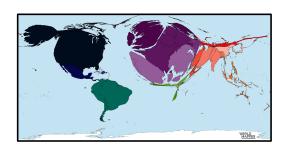


© New York Times

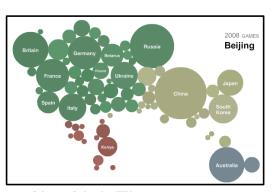


Needs 64 206 Romney ELECTORAL VOTE

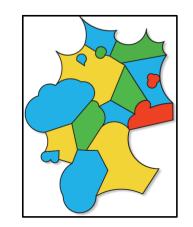
Cartograms



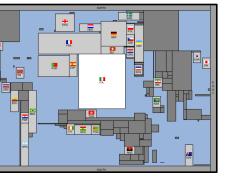
© worldmapper.org



© New York Times

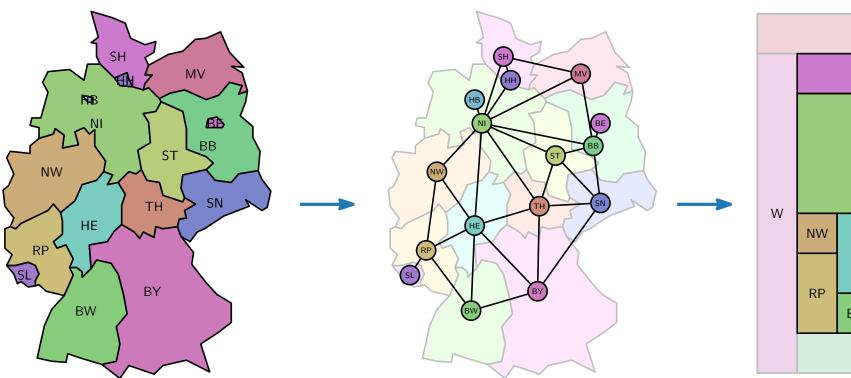


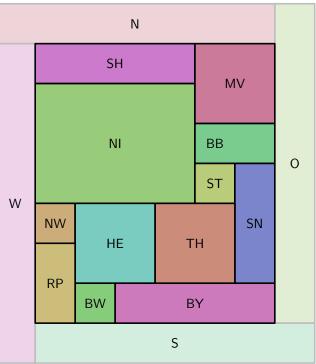
© Bettina Speckmann



© New York Times

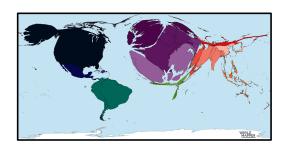
Obama 243 Needs 27 to win



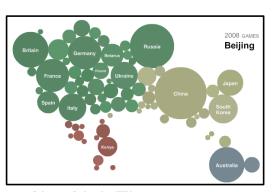


Needs 64 206 Romney ELECTORAL VOTE

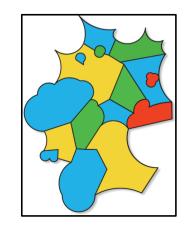
Cartograms



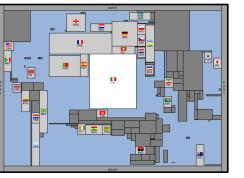
© worldmapper.org



© New York Times

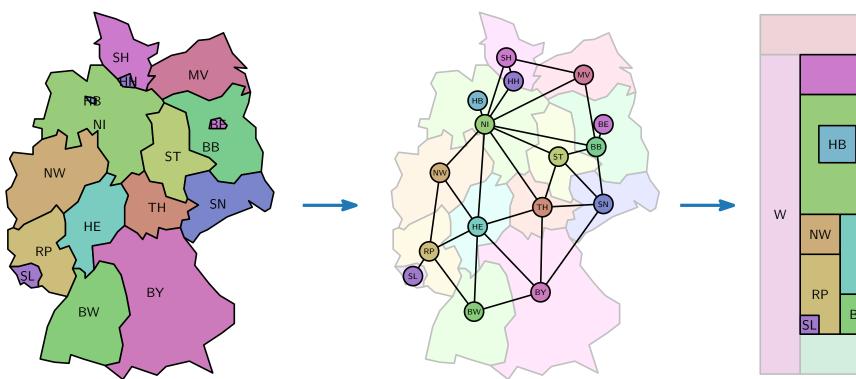


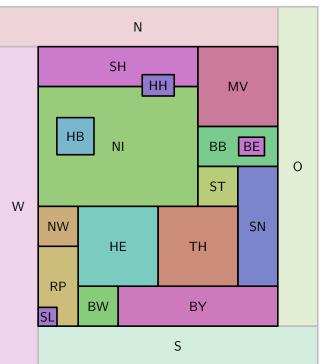
© Bettina Speckmann



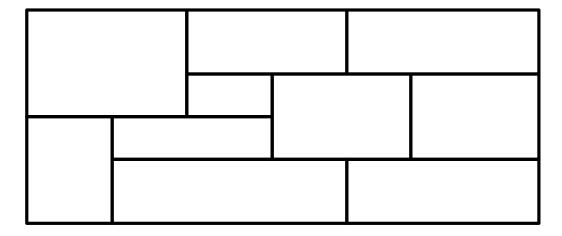
© New York Times

Obama 243 Needs 27 to win

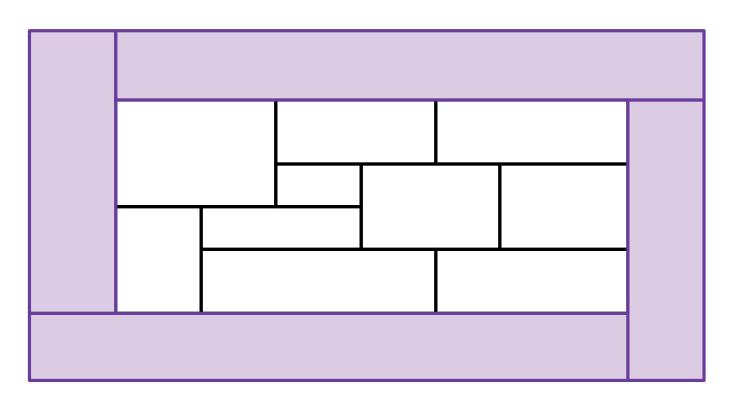


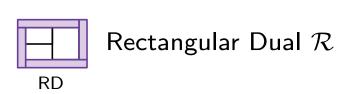


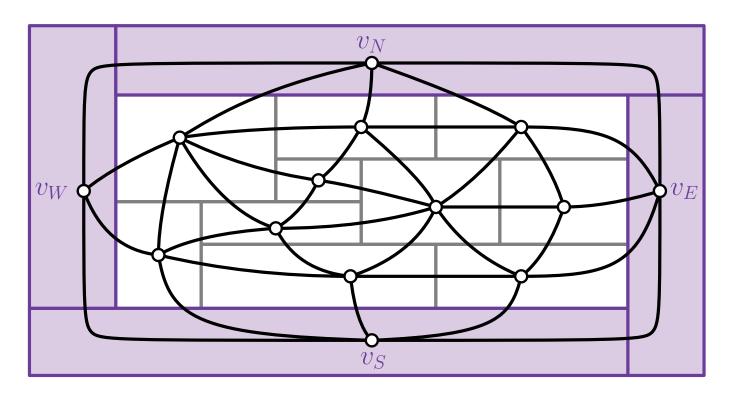


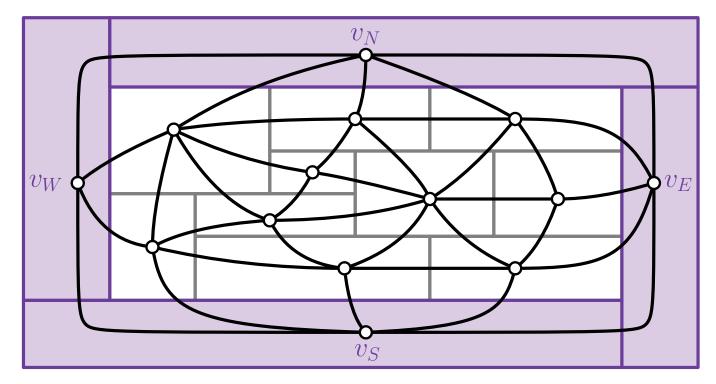


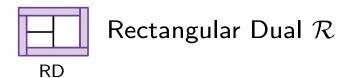




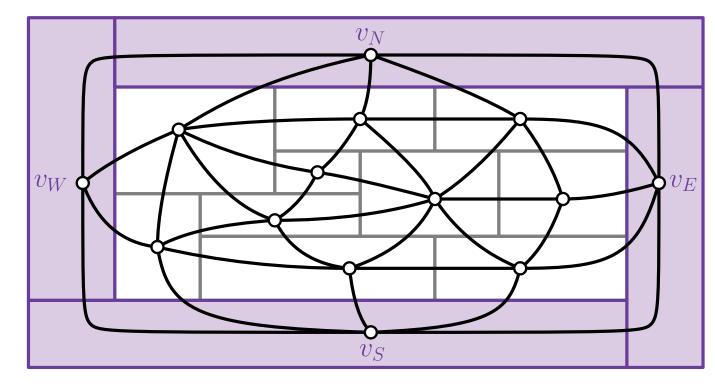








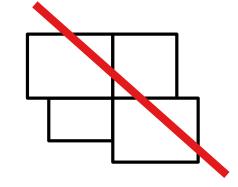
A **rectangular dual** of a graph G is a contact representation with axis-aligned rectangles s.t.

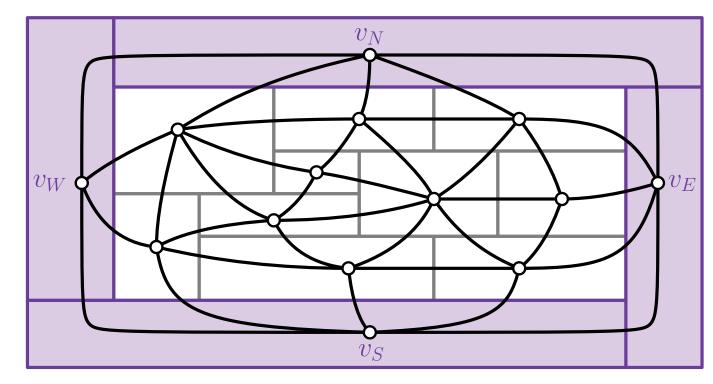


Rectangular Dual \mathcal{R}

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

no four rectangles share a point,

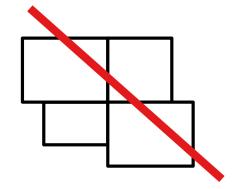


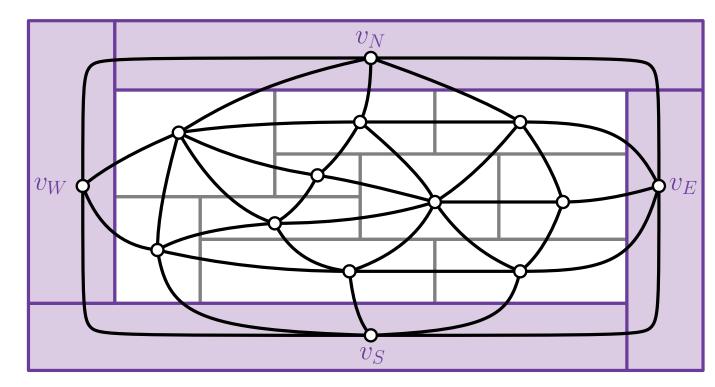


Rectangular Dual \mathcal{R}

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle

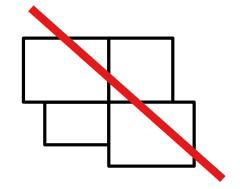




Rectangular Dual \mathcal{R}

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle



Theorem.

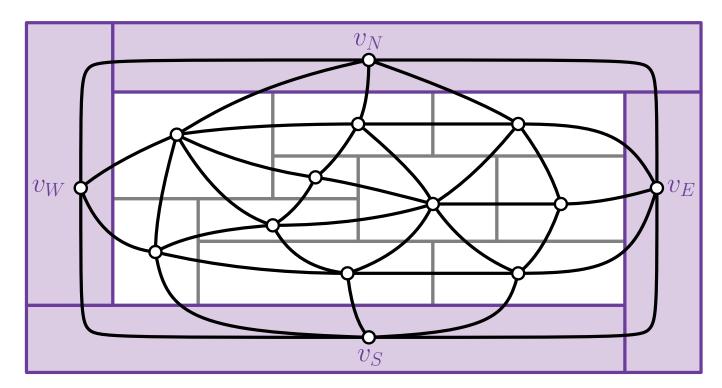
[Koźmiński, Kinnen '85]



Properly Triangulated Planar Graph ${\cal G}$

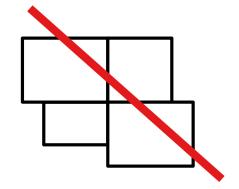


Rectangular Dual ${\cal R}$



A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle



Theorem.

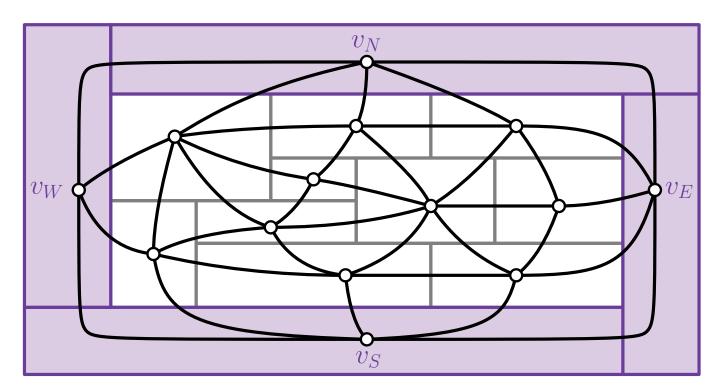
[Koźmiński, Kinnen '85]



Properly Triangulated Planar Graph G

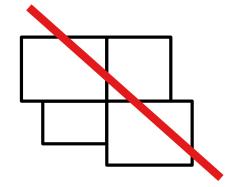


Rectangular Dual ${\mathcal R}$



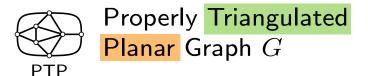
A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

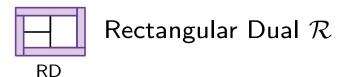
- no four rectangles share a point, and
- the union of all rectangles is a rectangle

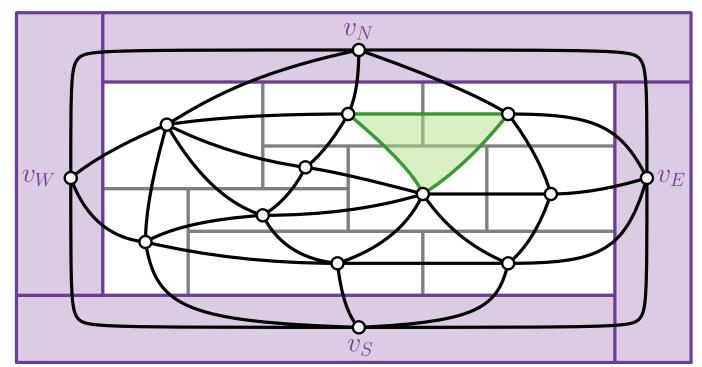


Theorem.

[Koźmiński, Kinnen '85]

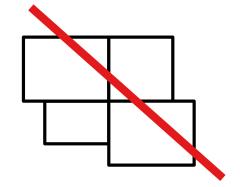






A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

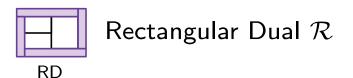
- no four rectangles share a point, and
- the union of all rectangles is a rectangle

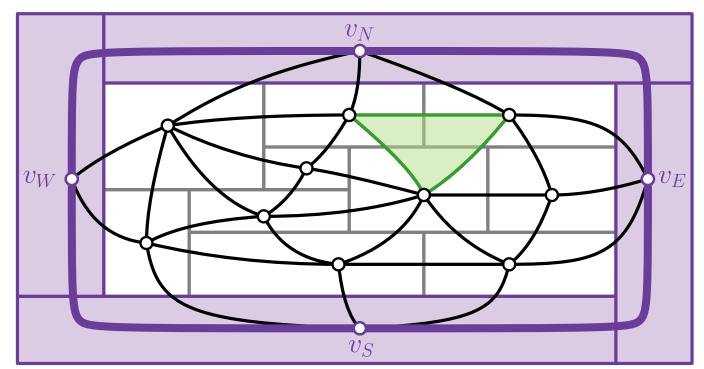


Theorem.

[Koźmiński, Kinnen '85]

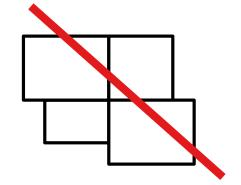






A **rectangular dual** of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle

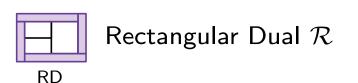


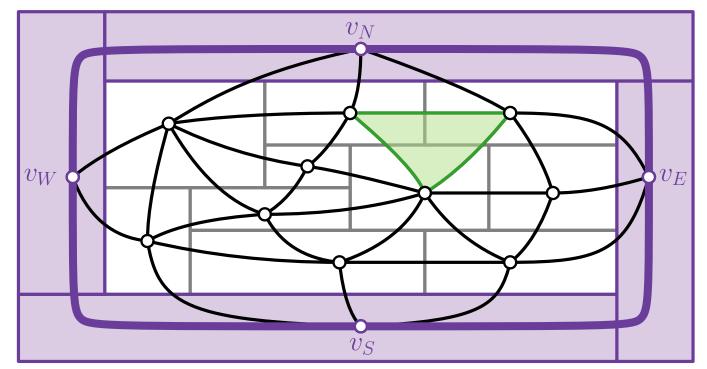
Theorem.

[Koźmiński, Kinnen '85]

Exactly four vertices on the outer face.

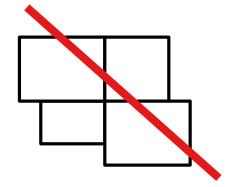






A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle



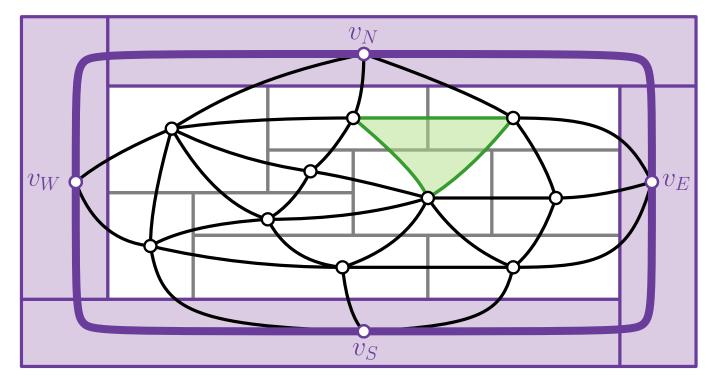
Theorem.

[Koźmiński, Kinnen '85]

Exactly four vertices on the outer face.



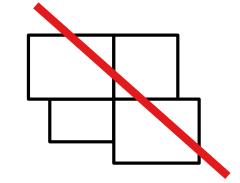




No separating triangle!

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle



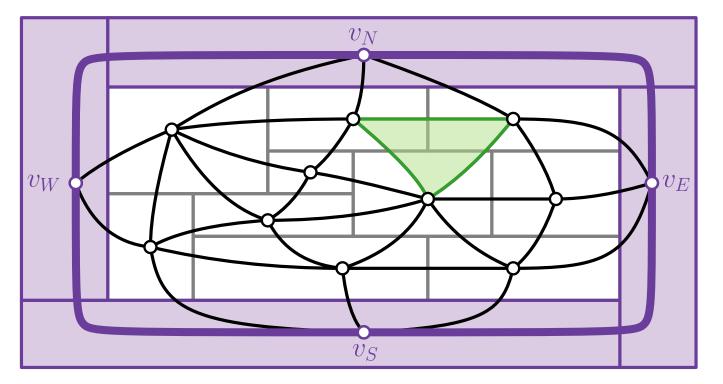
Theorem.

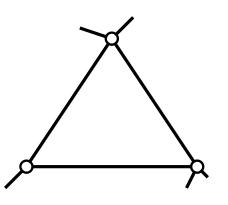
[Koźmiński, Kinnen '85]

Exactly four vertices on the outer face.





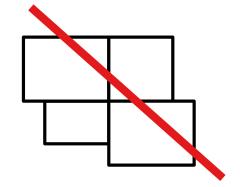




No separating triangle!

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle

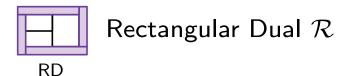


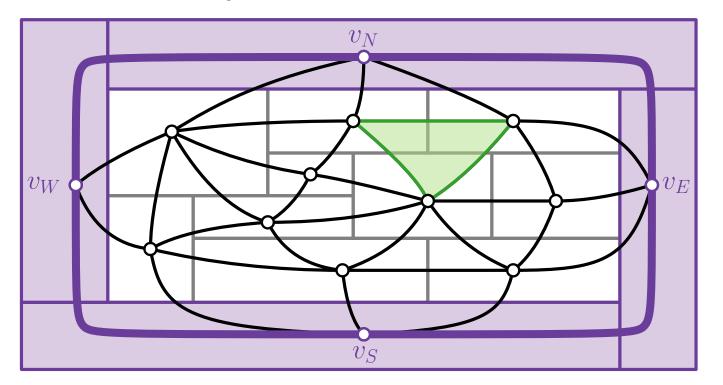
Theorem.

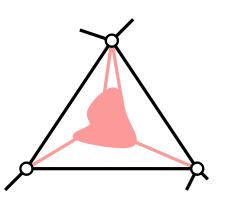
[Koźmiński, Kinnen '85]

Exactly four vertices on the outer face.





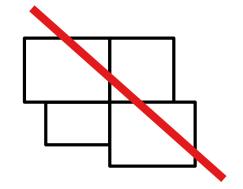




No separating triangle!

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle



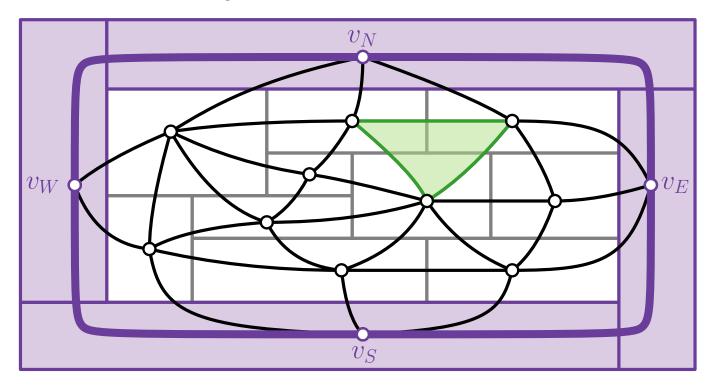
Theorem.

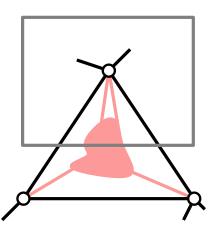
[Koźmiński, Kinnen '85]

Exactly four vertices on the outer face.





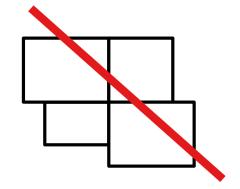




No separating triangle!

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

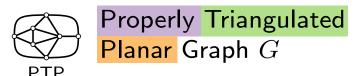
- no four rectangles share a point, and
- the union of all rectangles is a rectangle

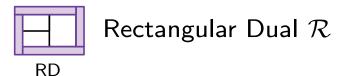


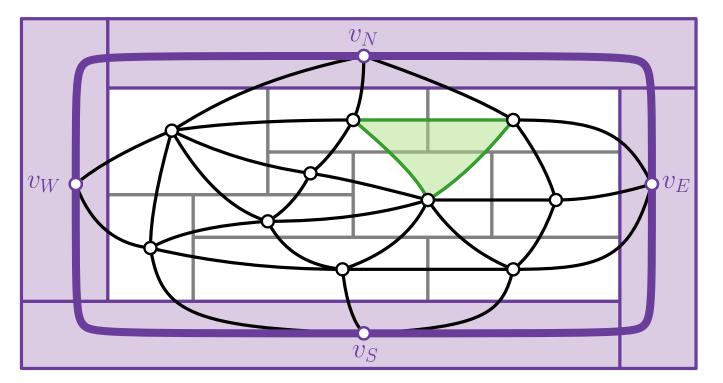
Theorem.

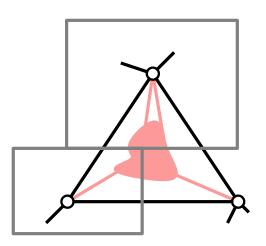
[Koźmiński, Kinnen '85]

Exactly four vertices on the outer face.





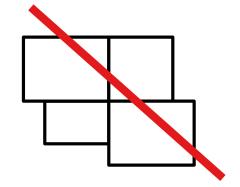




No separating triangle!

A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle

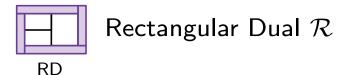


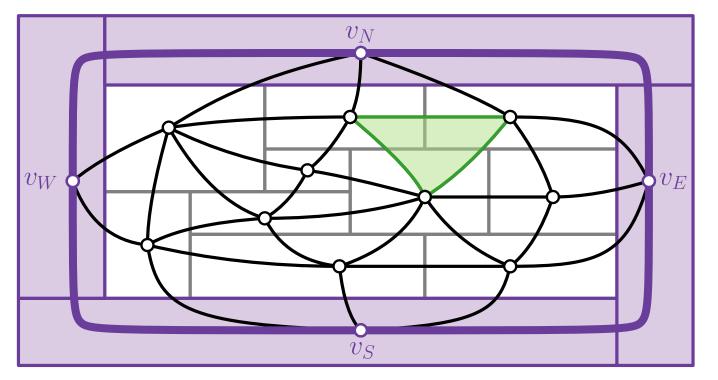
Theorem.

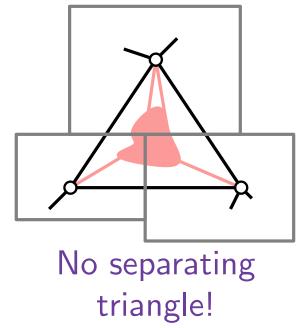
[Koźmiński, Kinnen '85]

Exactly four vertices on the outer face.



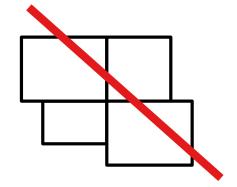






A rectangular dual of a graph G is a contact representation with axis-aligned rectangles s.t.

- no four rectangles share a point, and
- the union of all rectangles is a rectangle



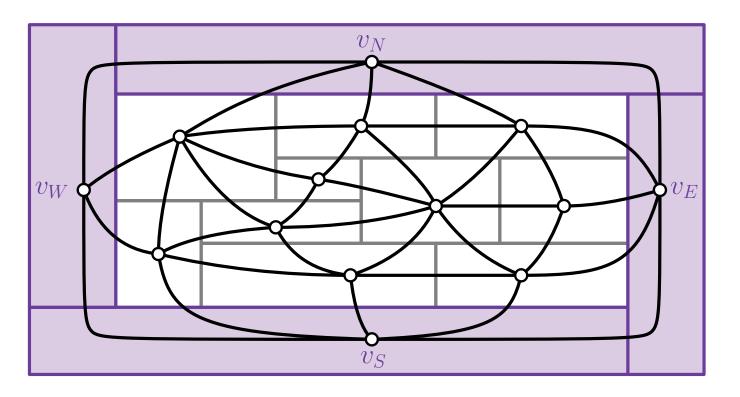
Theorem.

[Koźmiński, Kinnen '85]



Properly Triangulated Planar Graph ${\cal G}$

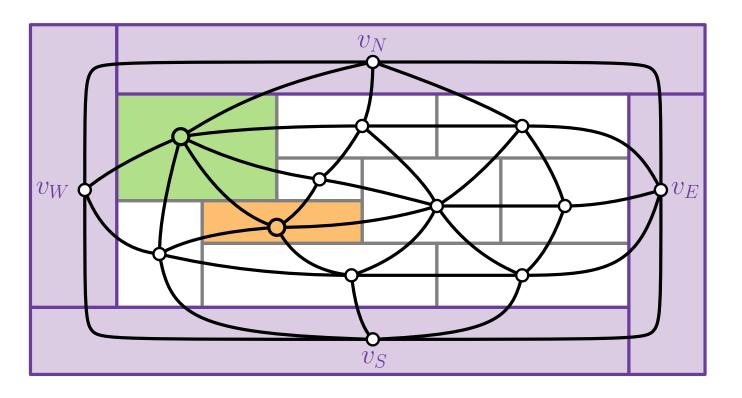






Properly Triangulated Planar Graph ${\cal G}$

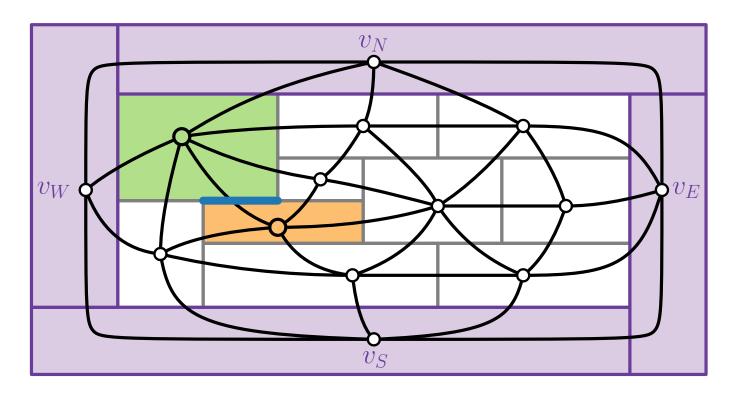






Properly Triangulated Planar Graph ${\cal G}$

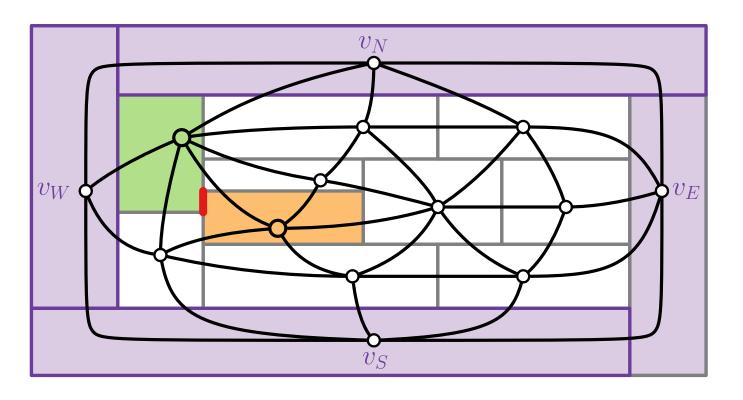






Properly Triangulated Planar Graph ${\cal G}$

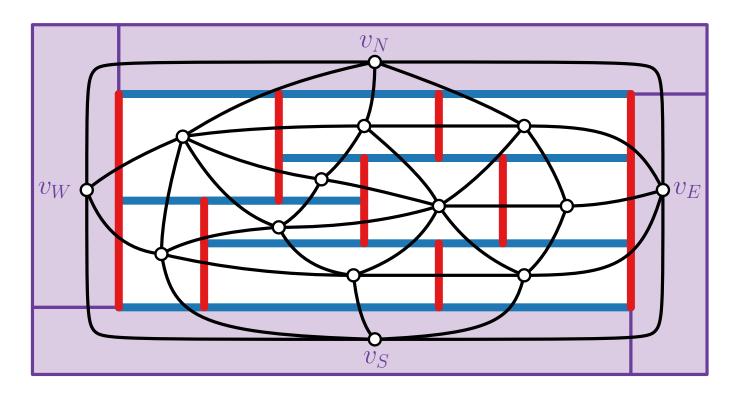






Properly Triangulated Planar Graph ${\cal G}$

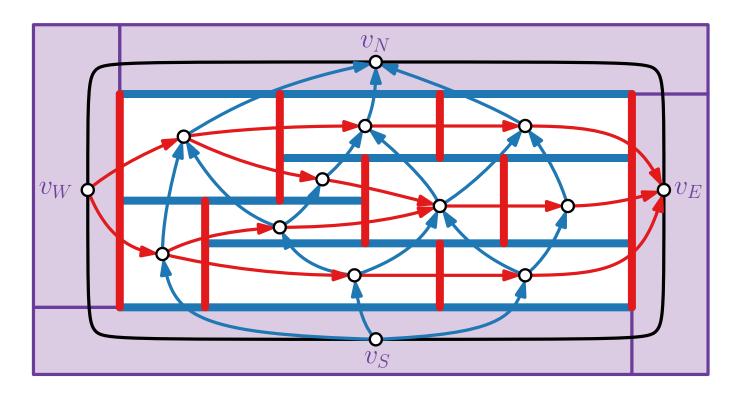






Properly Triangulated Planar Graph ${\cal G}$





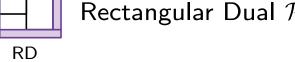


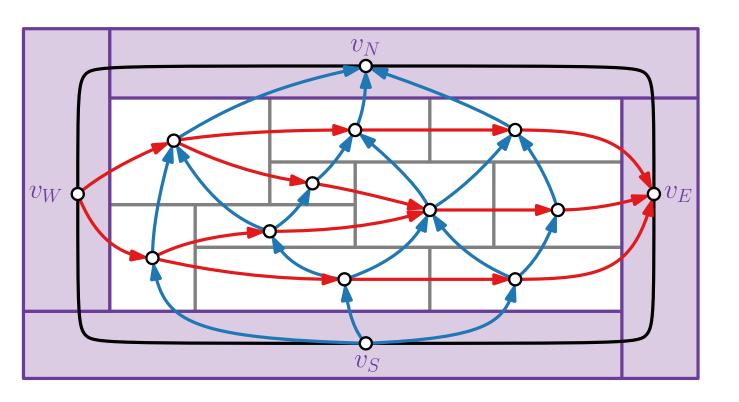
Properly Triangulated ${\sf Planar} \,\, {\sf Graph} \,\, G$



Regular Edge Labeling









Properly Triangulated ${\sf Planar} \,\, {\sf Graph} \,\, G$

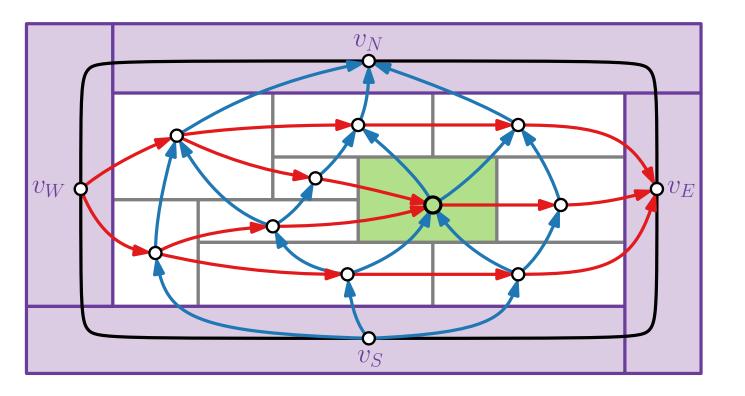


Regular Edge Labeling



Rectangular Dual ${\mathcal R}$







Properly Triangulated ${\sf Planar} \,\, {\sf Graph} \,\, G$

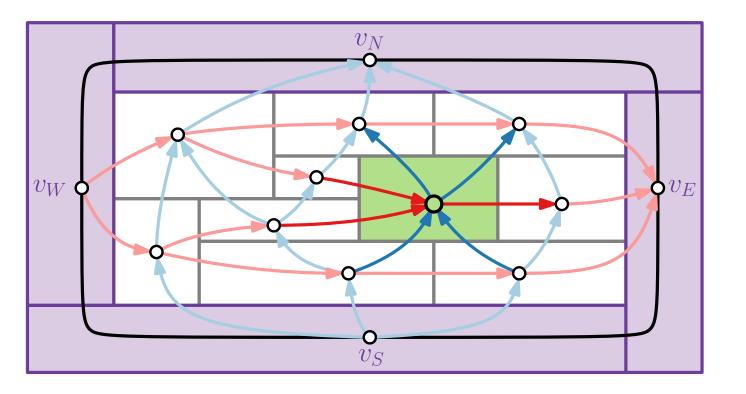


Regular Edge Labeling



Rectangular Dual ${\mathcal R}$







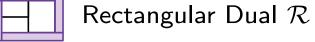
Properly Triangulated Planar Graph ${\cal G}$

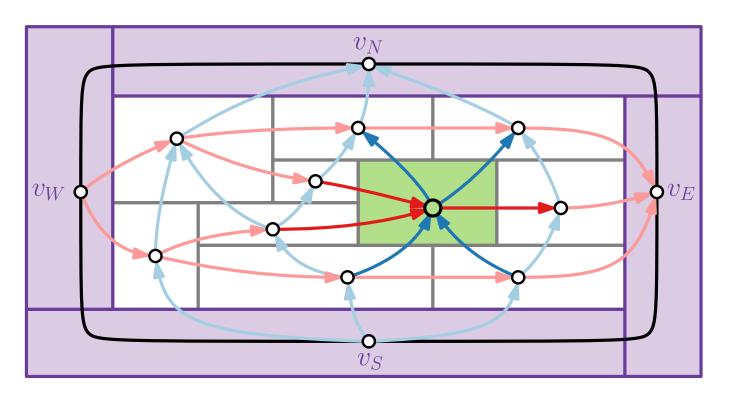


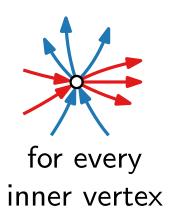
Regular Edge Labeling



RD









Properly Triangulated ${\sf Planar} \,\, {\sf Graph} \,\, G$

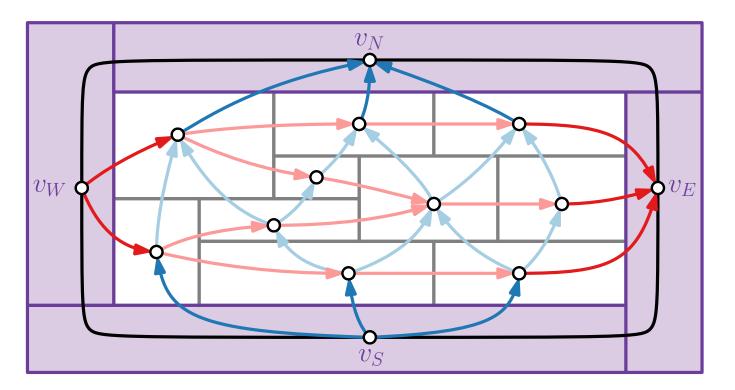


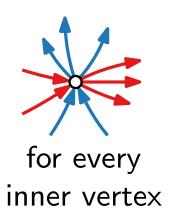
Regular Edge Labeling





Rectangular Dual ${\mathcal R}$







Properly Triangulated Planar Graph ${\cal G}$

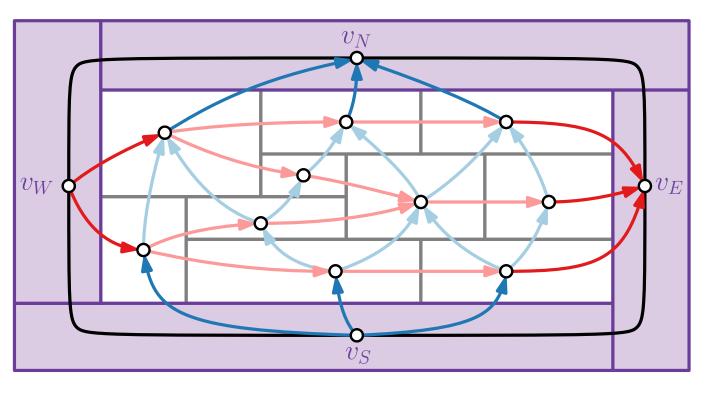


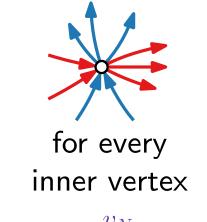
Regular Edge Labeling

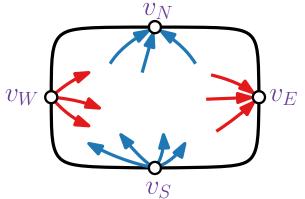


Rectangular Dual ${\cal R}$

RD







for four outer vertices



Properly Triangulated Planar Graph ${\cal G}$

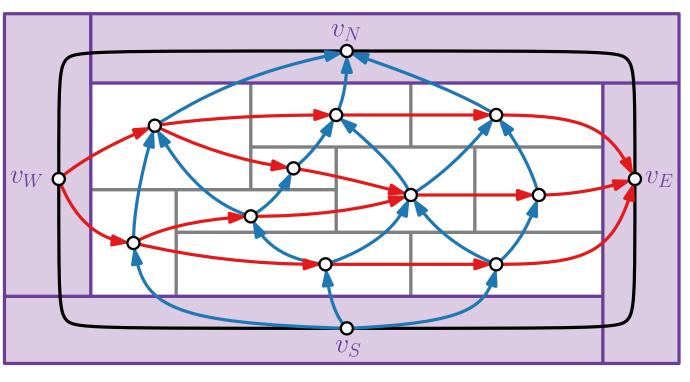


Regular Edge Labeling

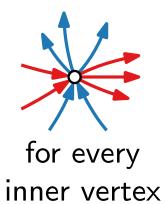
REL

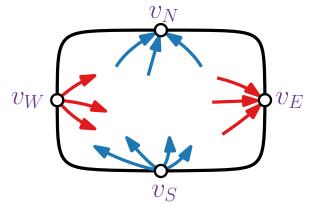
Rectangular Dual ${\mathcal R}$

RD



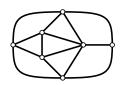
Properties:





for four outer vertices

[Kant, He '94]:



PTP



Properly Triangulated Planar Graph ${\cal G}$

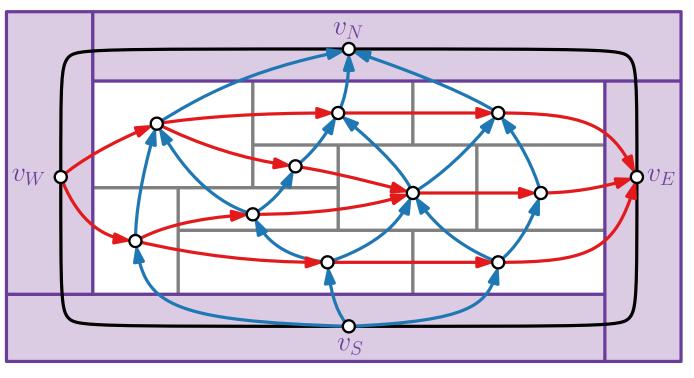


Regular Edge Labeling



Rectangular Dual ${\mathcal R}$

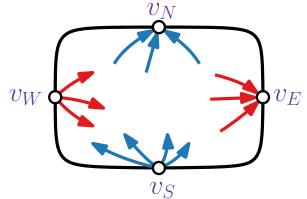
RD



Properties:

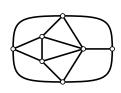


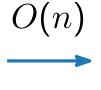
inner vertex

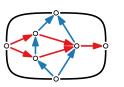


for four outer vertices

[Kant, He '94]:







PTP

REL



Properly Triangulated Planar Graph ${\cal G}$

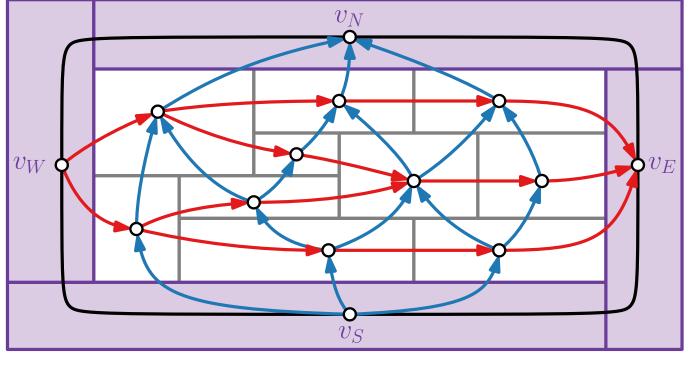


Regular Edge Labeling

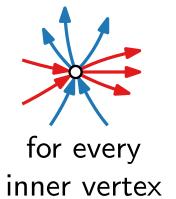


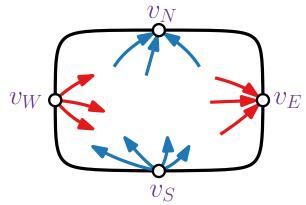
RD

Rectangular Dual ${\mathcal R}$



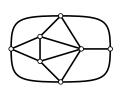
Properties:



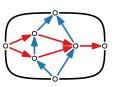


for four outer vertices

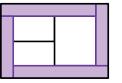
[Kant, He '94]:



O(n)







PTP

REL

RD

Theorem.

Let G be a PTP graph that is embedded in its unique planar embedding with counter-clockwise outer face $\langle v_W, v_S, v_E, v_N \rangle$.

Theorem.

Theorem.

Theorem.

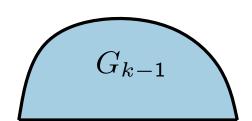
Let G be a PTP graph that is embedded in its unique planar embedding with counter-clockwise outer face $\langle v_W, v_S, v_E, v_N \rangle$. There exists a labeling $v_1 = v_S, v_2 = v_W, v_3, \ldots, v_n = v_N$ of the vertices of G such that for every $4 \le k \le n$:

■ The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected

Theorem.

Let G be a PTP graph that is embedded in its unique planar embedding with counter-clockwise outer face $\langle v_W, v_S, v_E, v_N \rangle$. There exists a labeling $v_1 = v_S, v_2 = v_W, v_3, \ldots, v_n = v_N$ of the vertices of G such that for every $4 \le k \le n$:

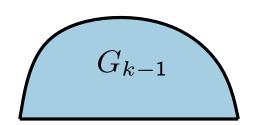
■ The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected



Theorem.

Let G be a PTP graph that is embedded in its unique planar embedding with counter-clockwise outer face $\langle v_W, v_S, v_E, v_N \rangle$. There exists a labeling $v_1 = v_S, v_2 = v_W, v_3, \dots, v_n = v_N$ of the vertices of G such that for every $4 \le k \le n$:

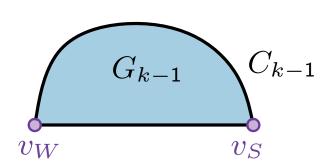
The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .



Theorem.

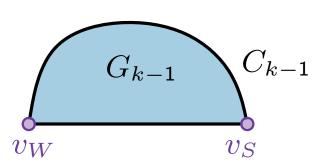
Let G be a PTP graph that is embedded in its unique planar embedding with counter-clockwise outer face $\langle v_W, v_S, v_E, v_N \rangle$. There exists a labeling $v_1 = v_S, v_2 = v_W, v_3, \ldots, v_n = v_N$ of the vertices of G such that for every $4 \le k \le n$:

The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .



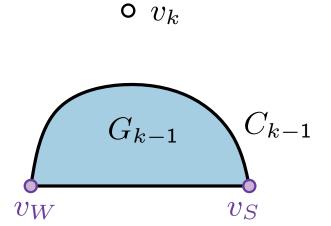
Theorem.

- The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .
- lacksquare v_k is in the outer face of G_{k-1}



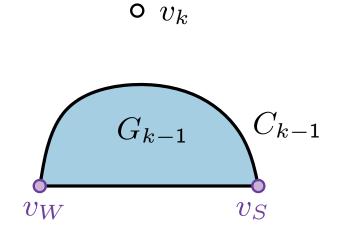
Theorem.

- The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .
- lacksquare v_k is in the outer face of G_{k-1}



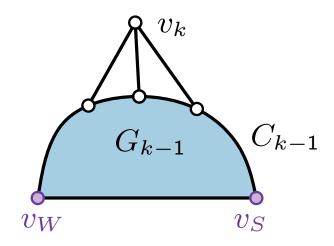
Theorem.

- The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .
- v_k is in the outer face of G_{k-1} , and its neighbors in G_{k-1} form an (at least 2-element) subinterval of the path $C_{k-1} \setminus (v_S, v_W)$.



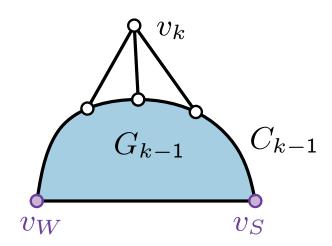
Theorem.

- The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .
- v_k is in the outer face of G_{k-1} , and its neighbors in G_{k-1} form an (at least 2-element) subinterval of the path $C_{k-1} \setminus (v_S, v_W)$.



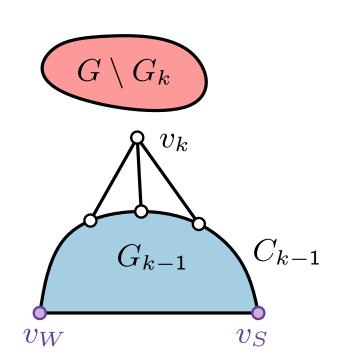
Theorem.

- The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .
- v_k is in the outer face of G_{k-1} , and its neighbors in G_{k-1} form an (at least 2-element) subinterval of the path $C_{k-1} \setminus (v_S, v_W)$.
- If $k \le n-2$, then v_k has at least two neighbors in $G \setminus G_k$.



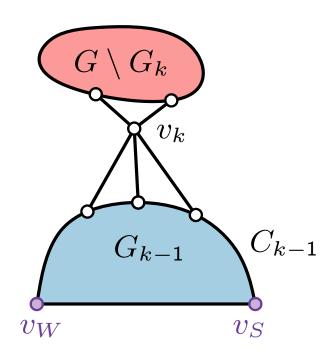
Theorem.

- The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .
- v_k is in the outer face of G_{k-1} , and its neighbors in G_{k-1} form an (at least 2-element) subinterval of the path $C_{k-1} \setminus (v_S, v_W)$.
- If $k \le n-2$, then v_k has at least two neighbors in $G \setminus G_k$.

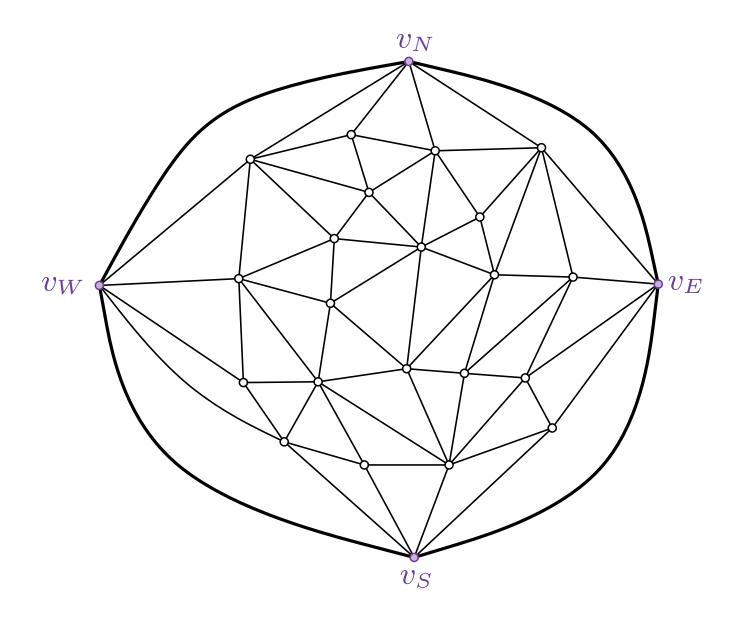


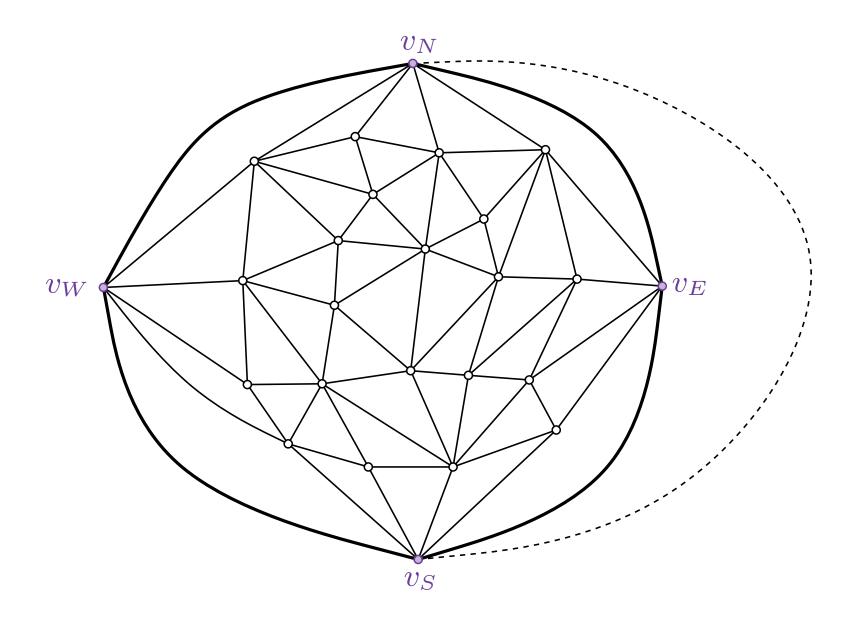
Theorem.

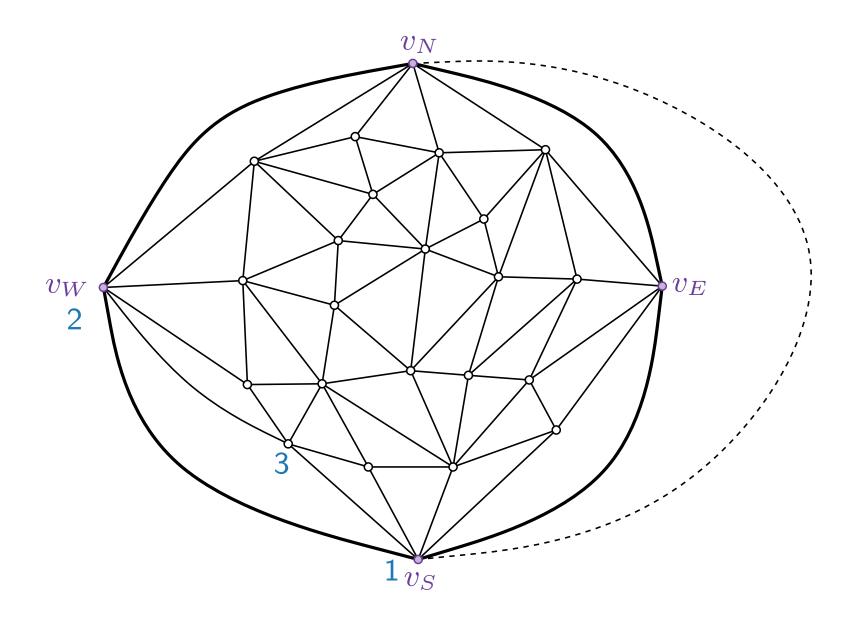
- The subgraph G_{k-1} induced by v_1, \ldots, v_{k-1} is biconnected and the boundary C_{k-1} of G_{k-1} contains the edge (v_S, v_W) .
- v_k is in the outer face of G_{k-1} , and its neighbors in G_{k-1} form an (at least 2-element) subinterval of the path $C_{k-1} \setminus (v_S, v_W)$.
- If $k \le n-2$, then v_k has at least two neighbors in $G \setminus G_k$.

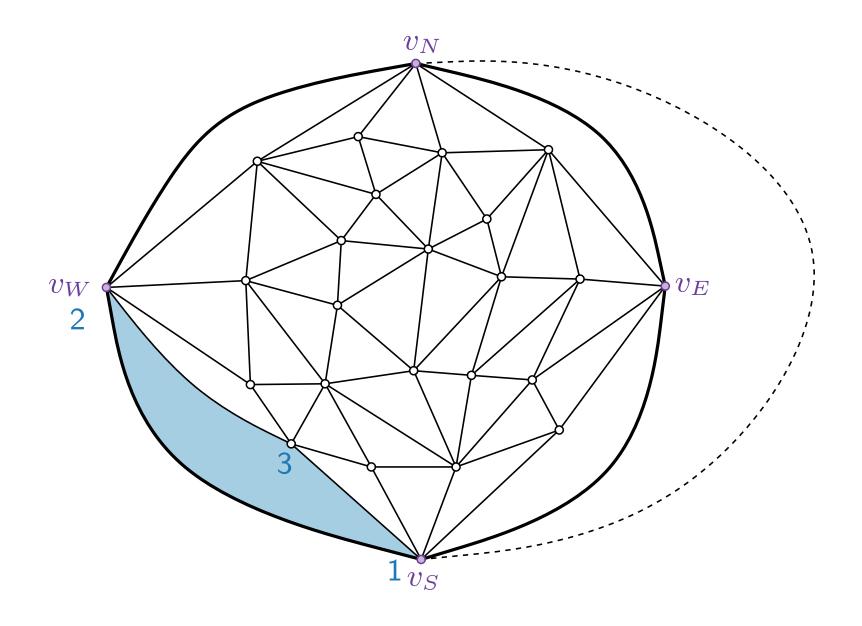


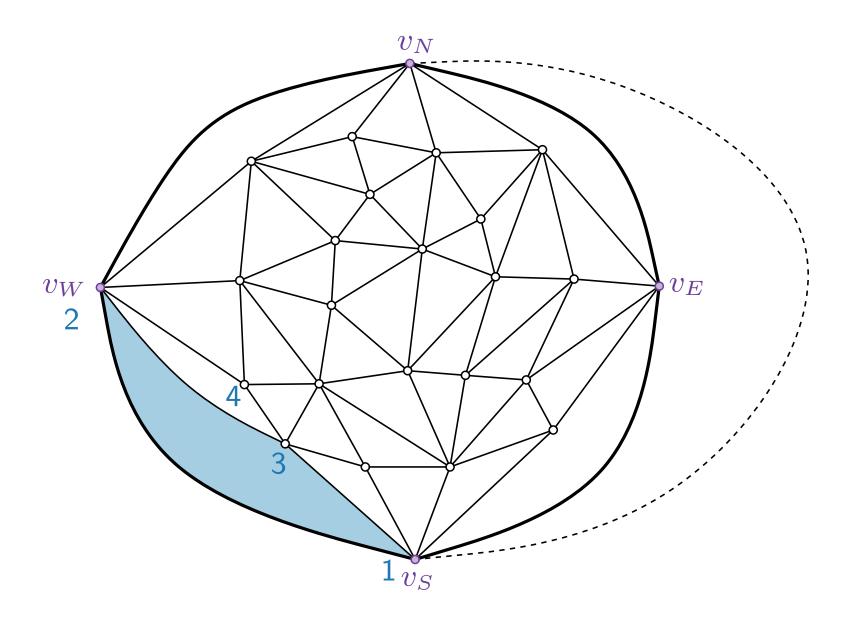
Refined Canonical Order Example

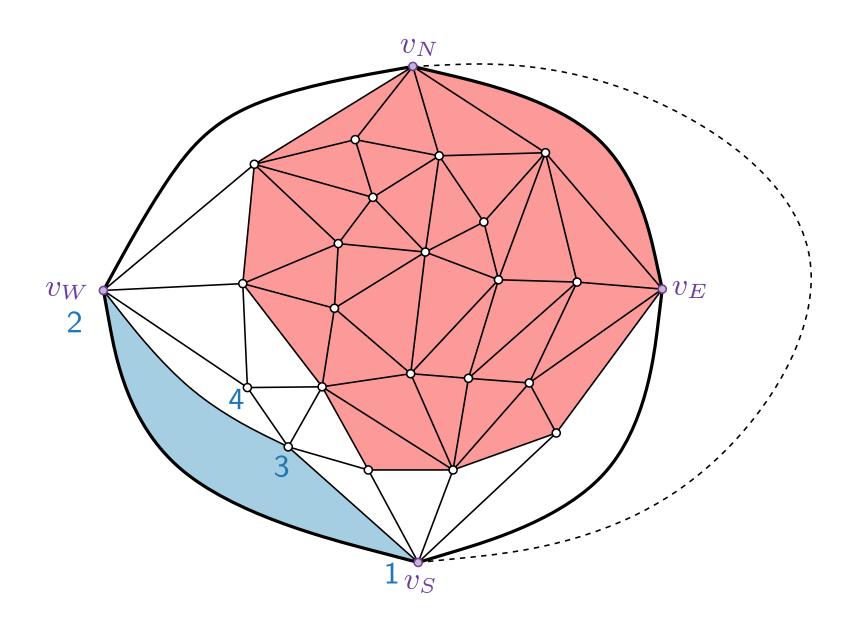


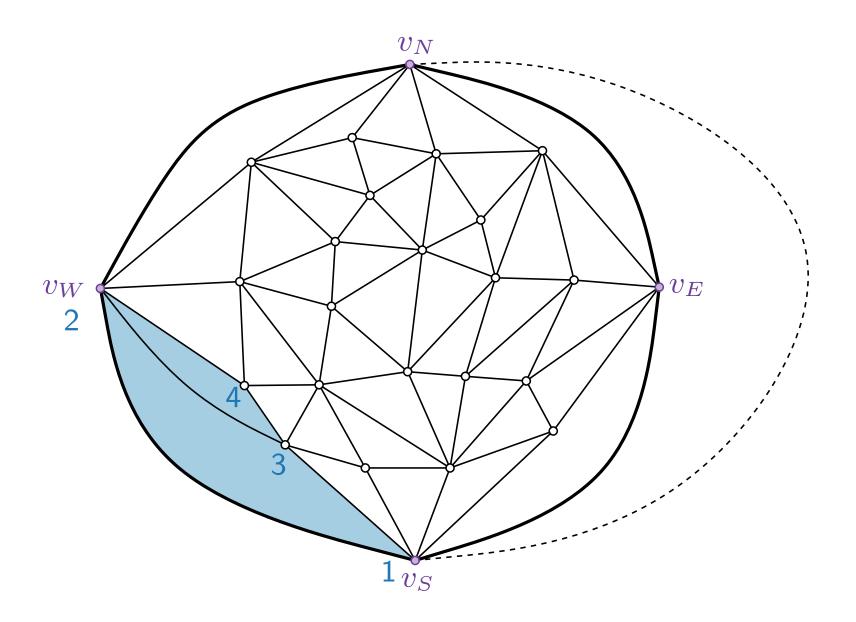


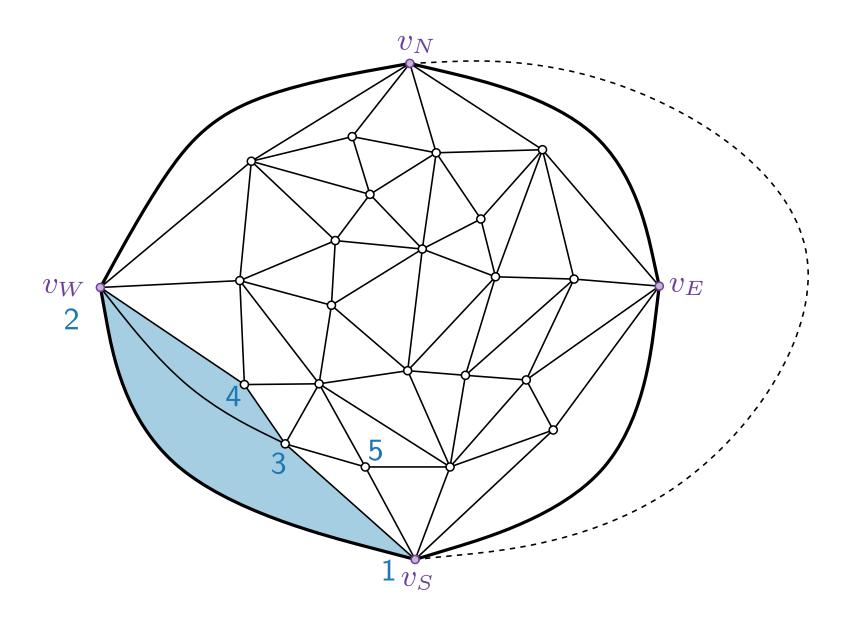


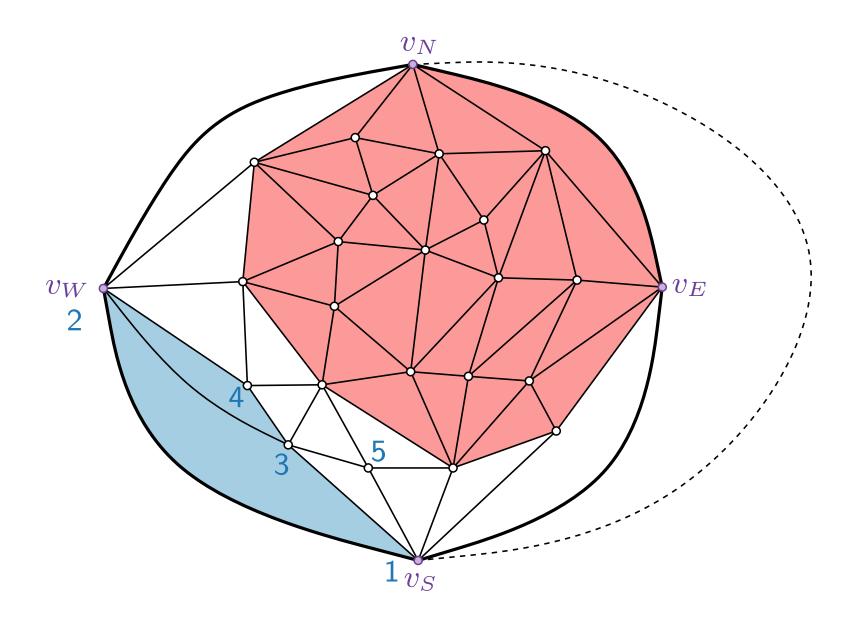


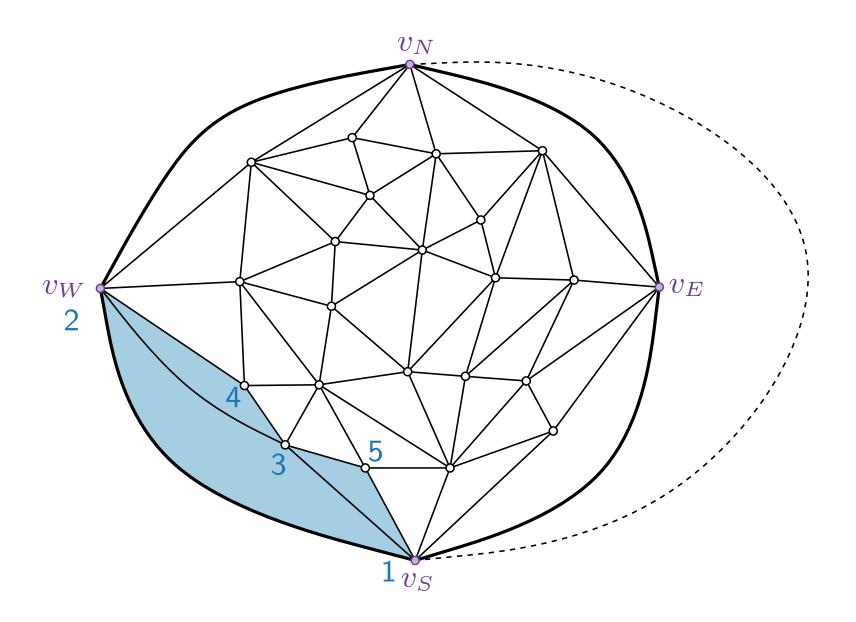


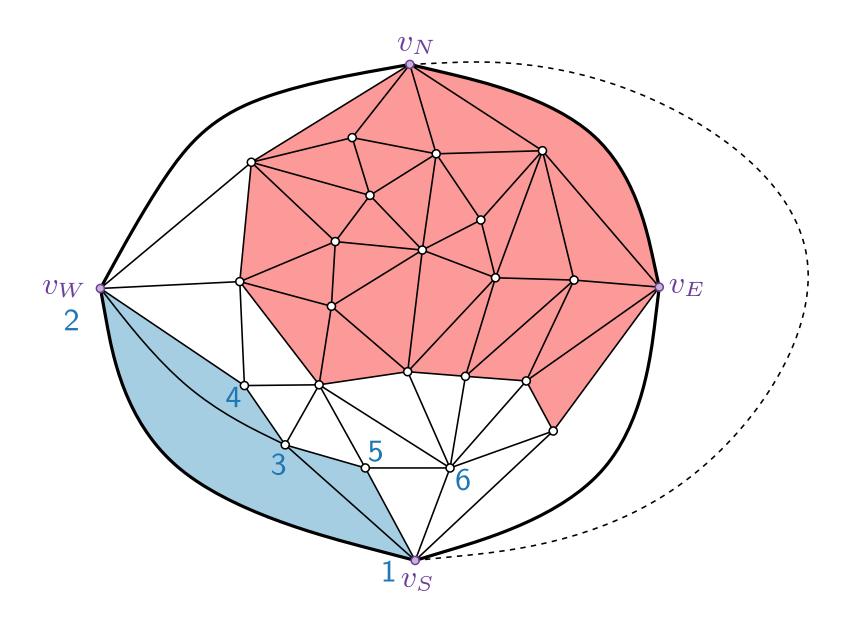


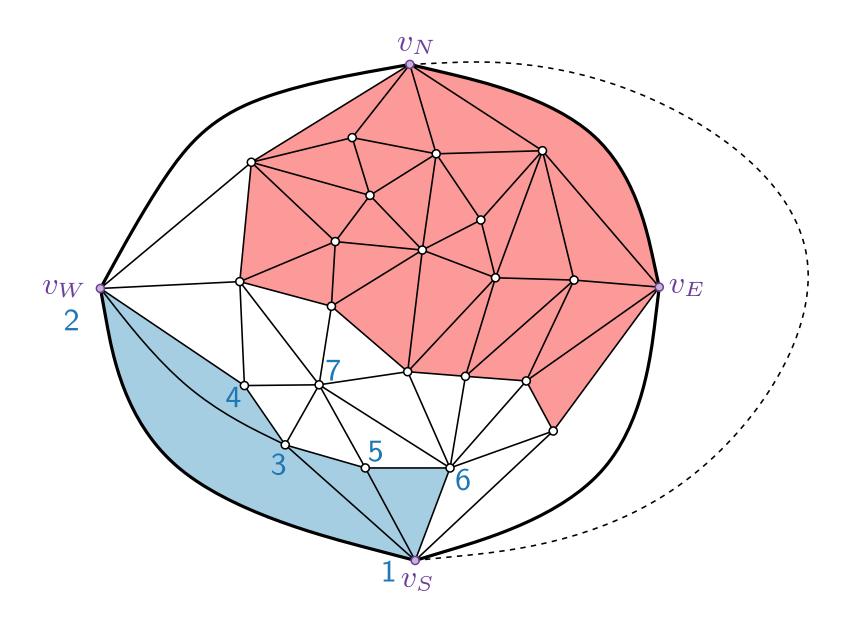


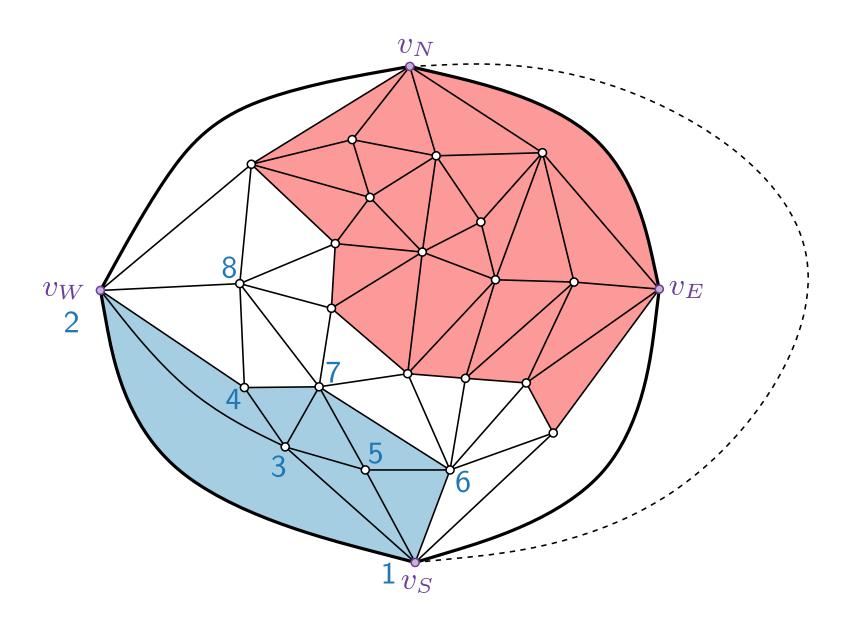


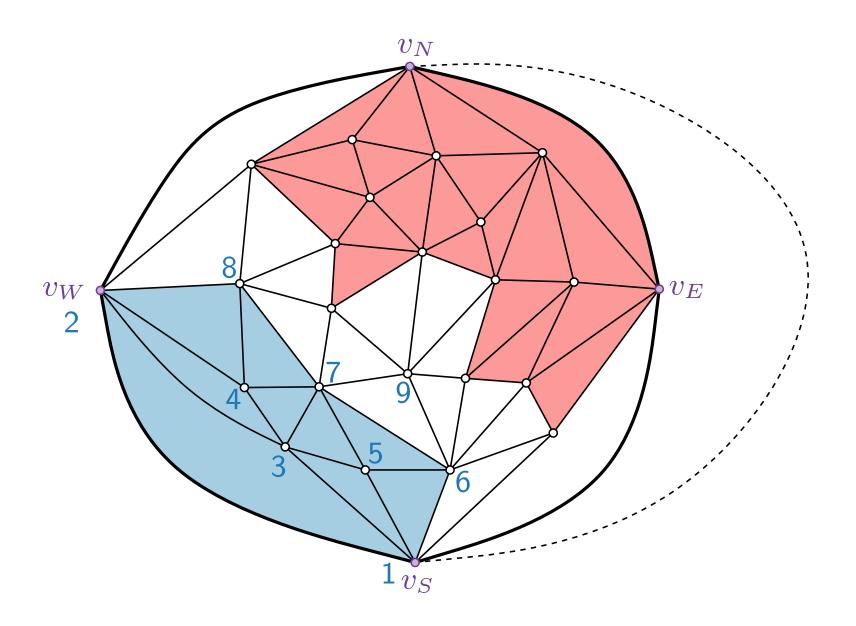


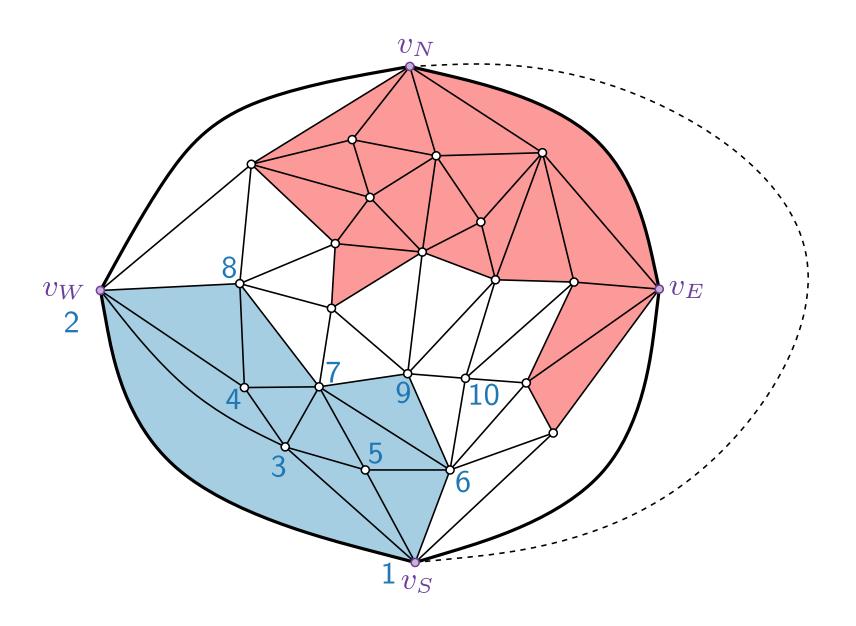


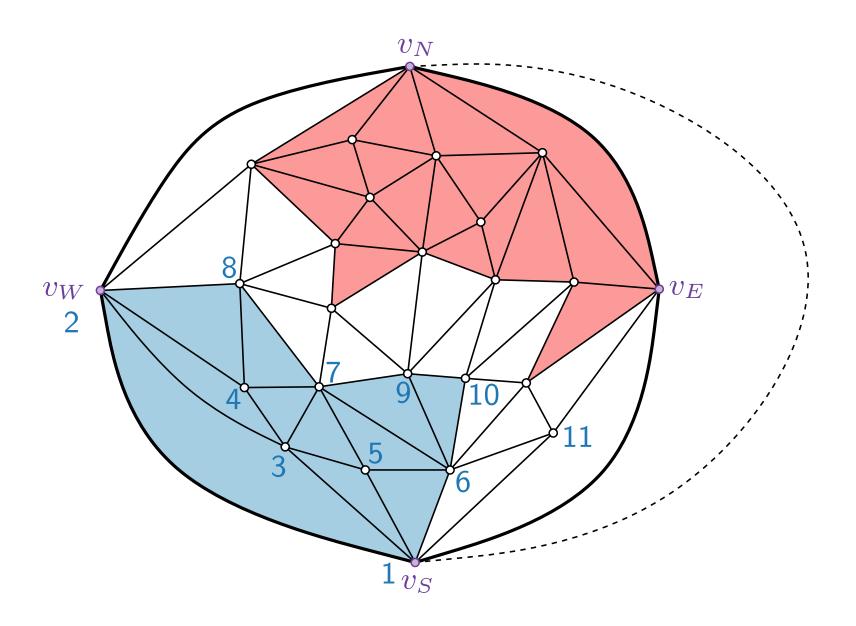


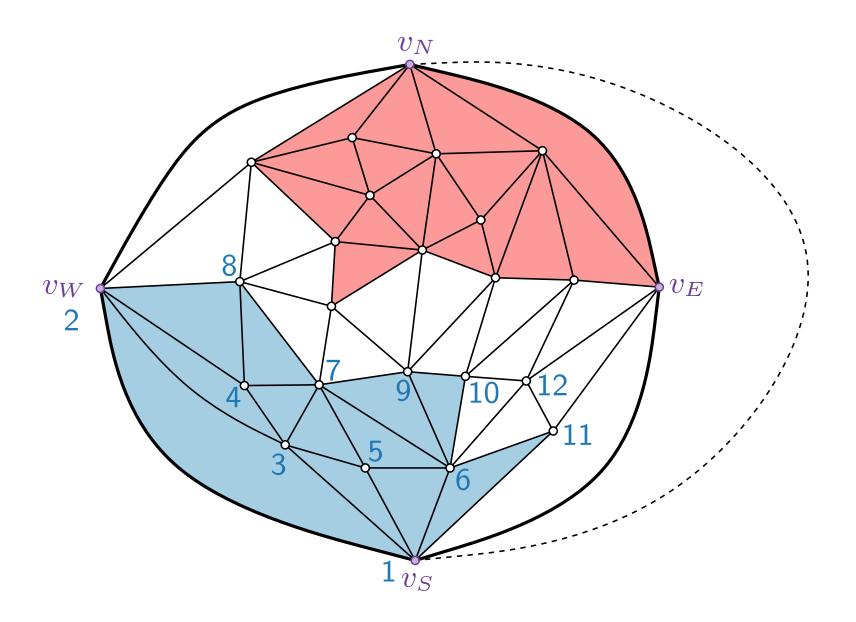


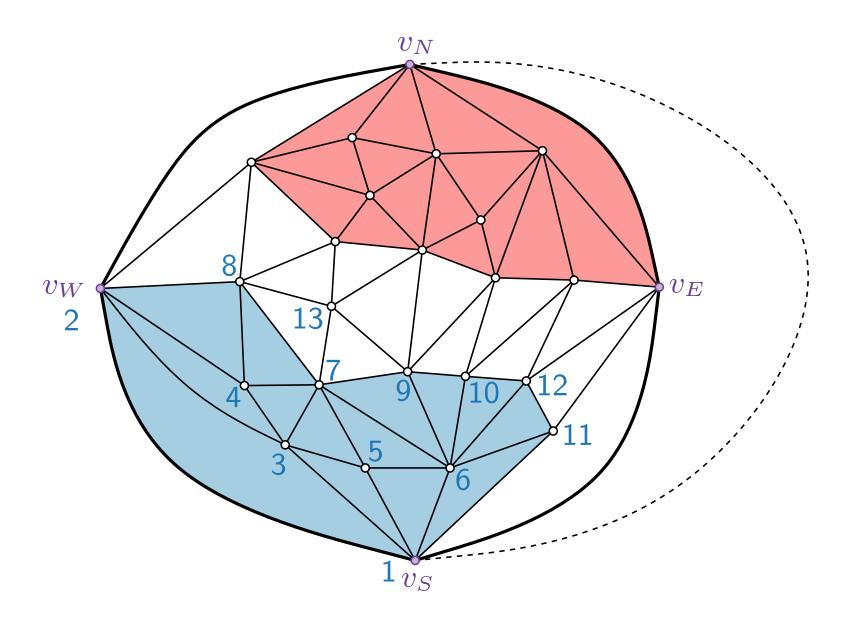


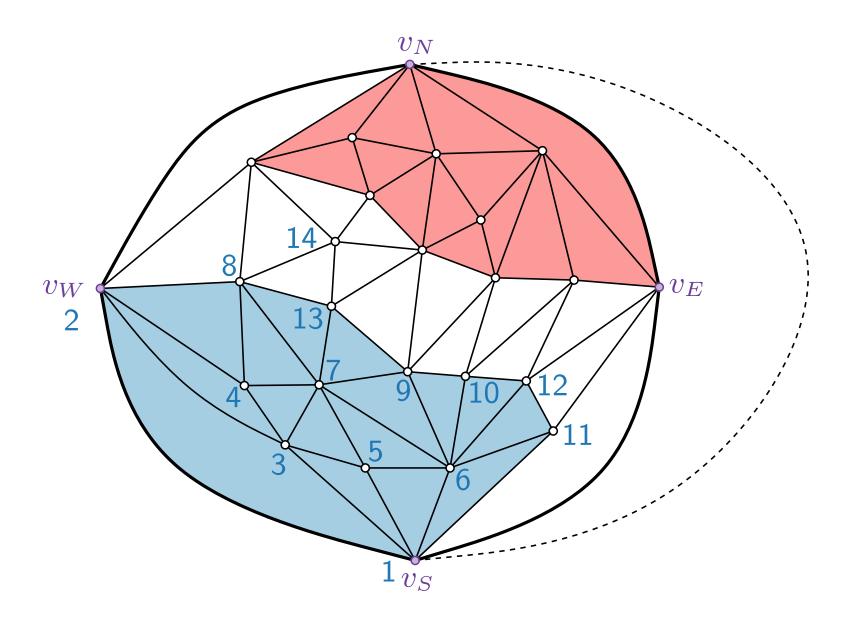


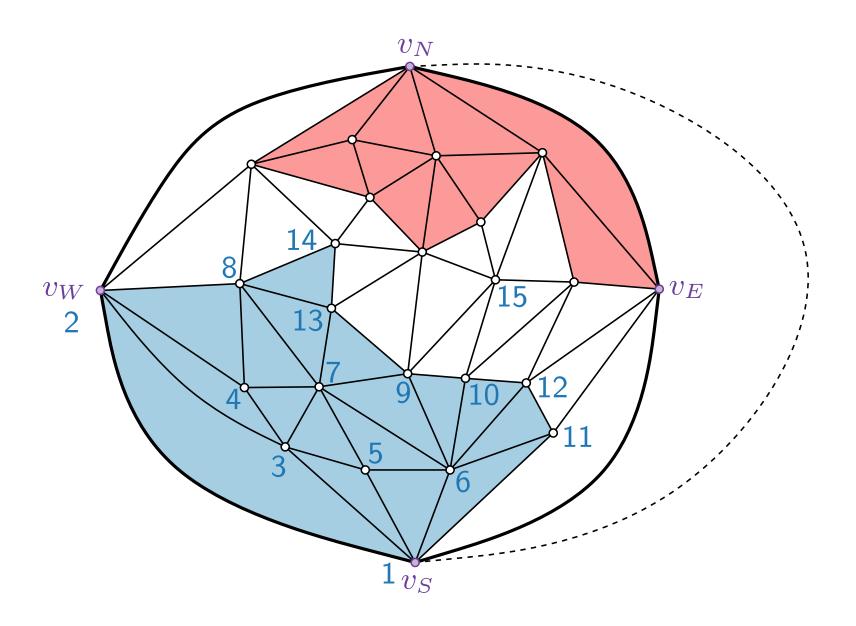


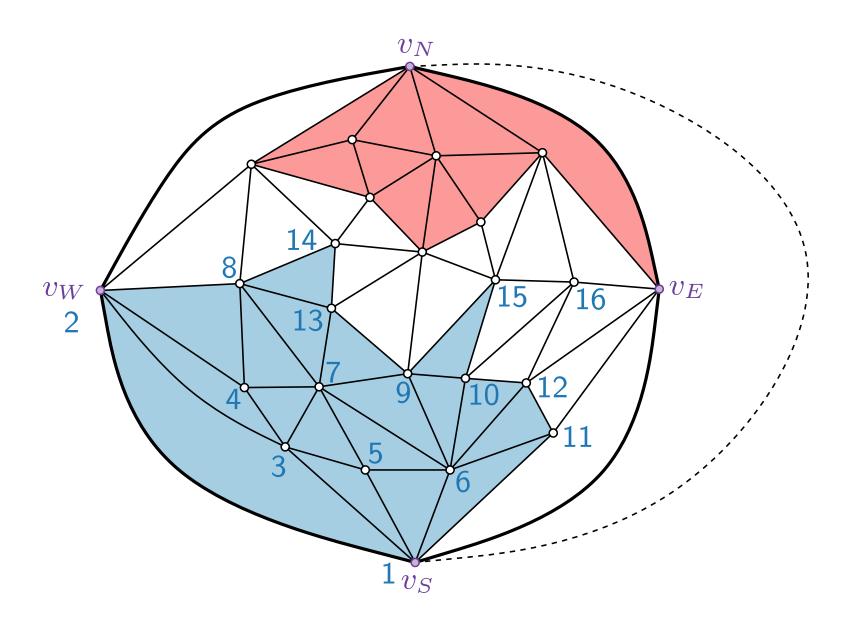


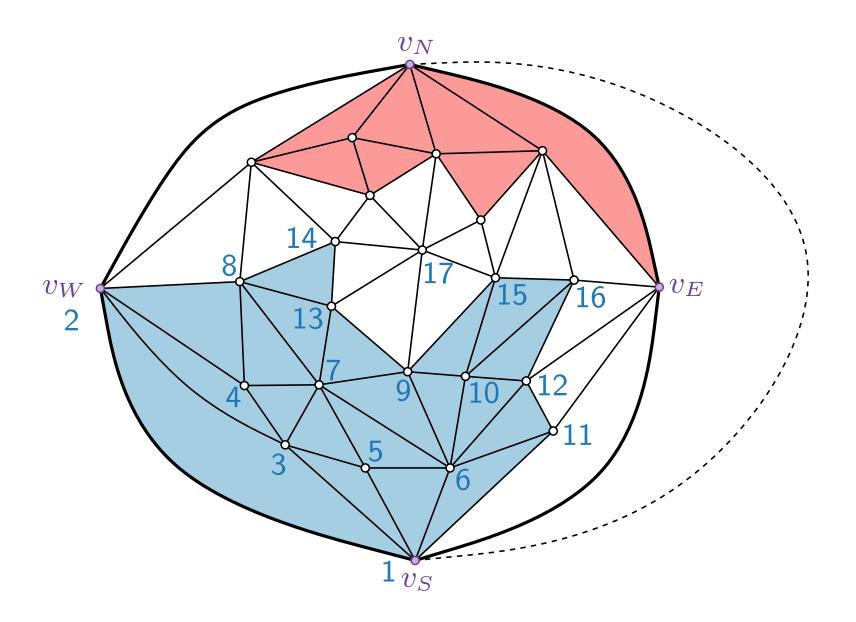


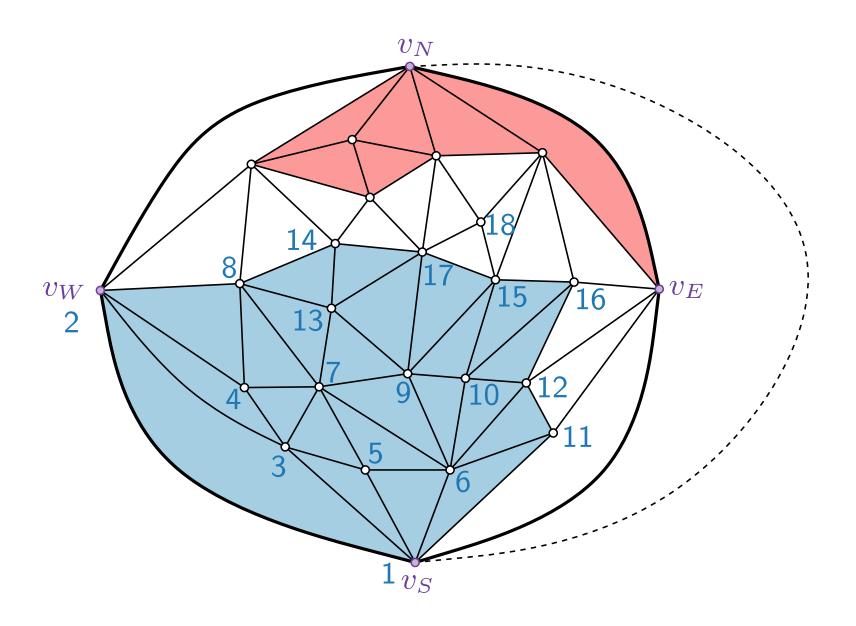


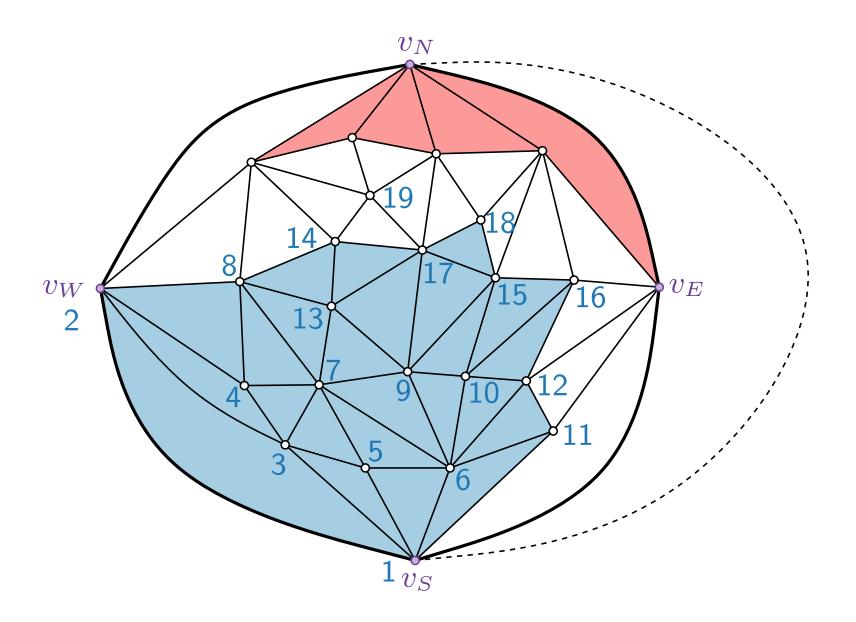


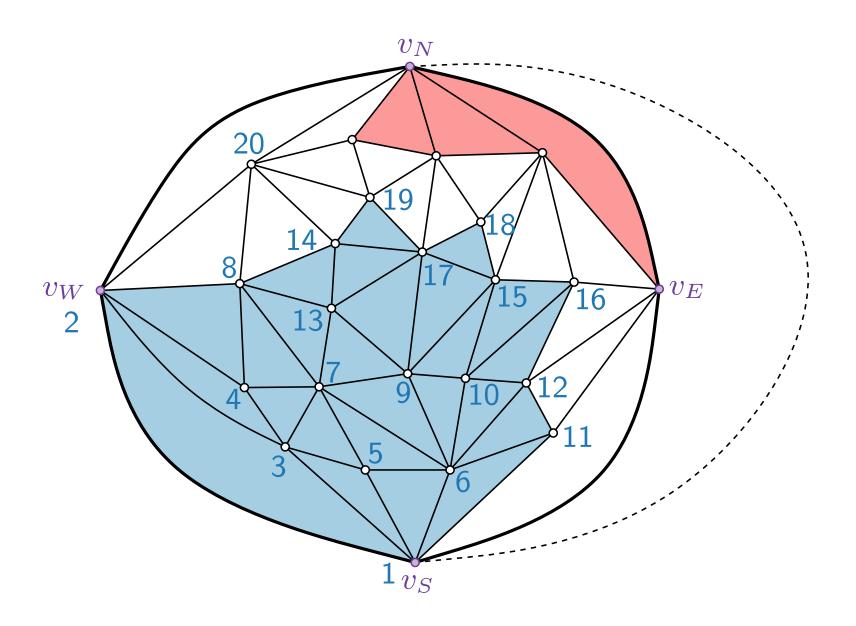


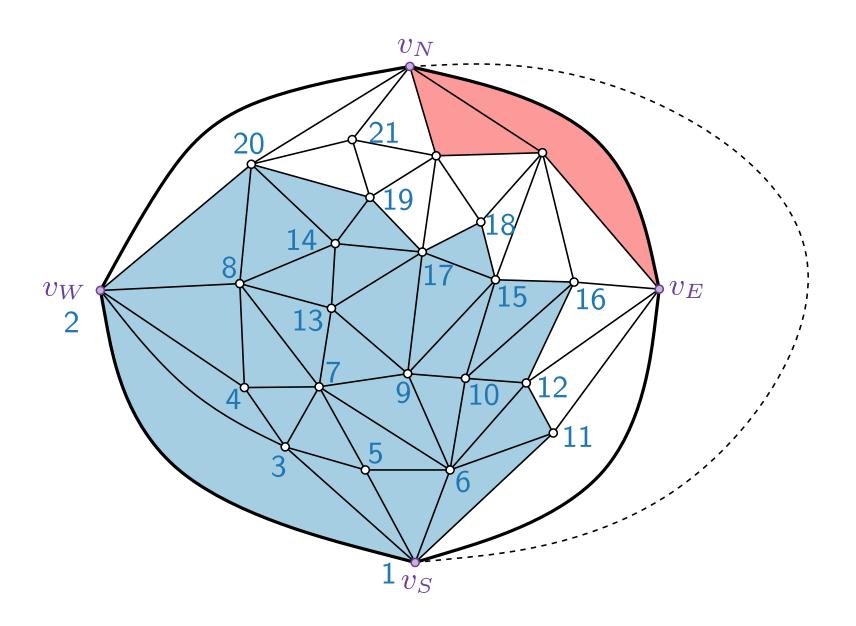


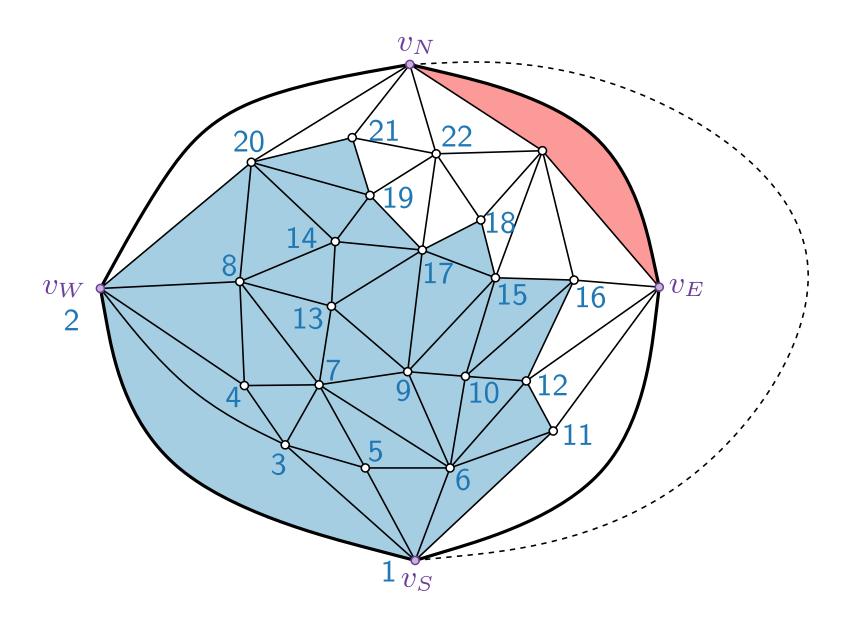


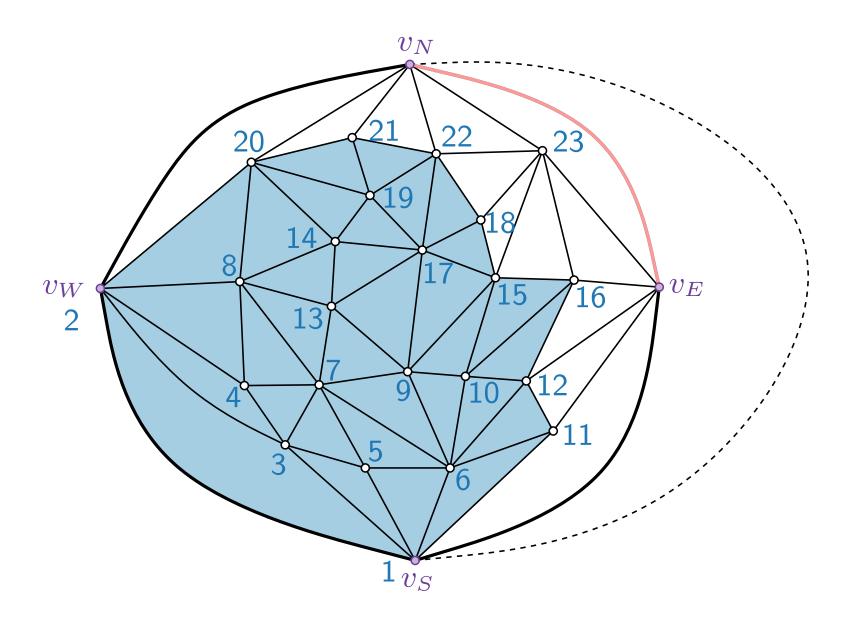


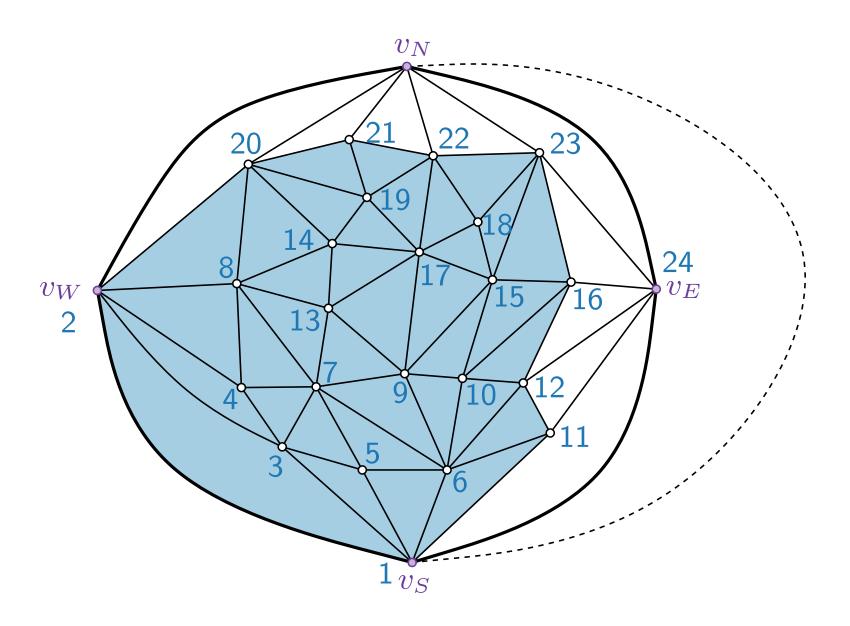


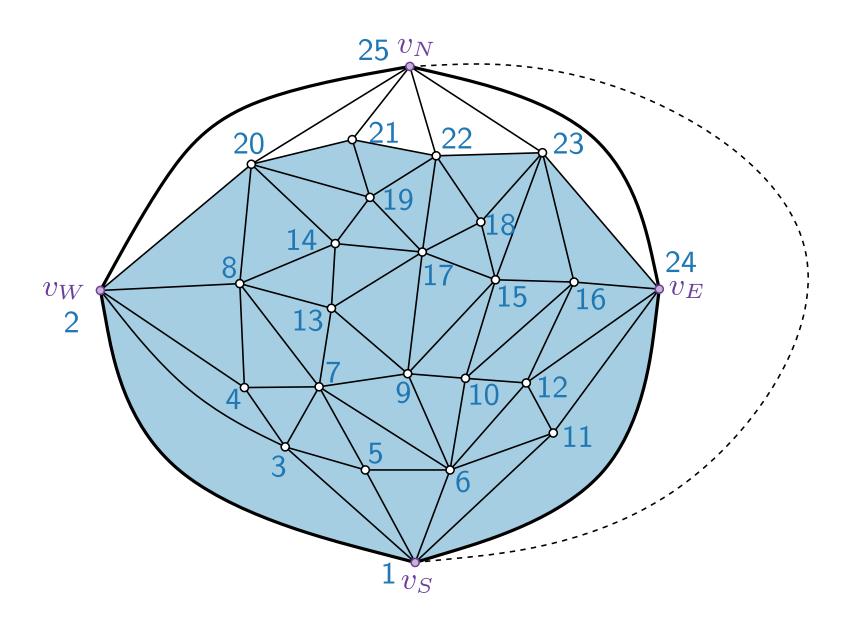


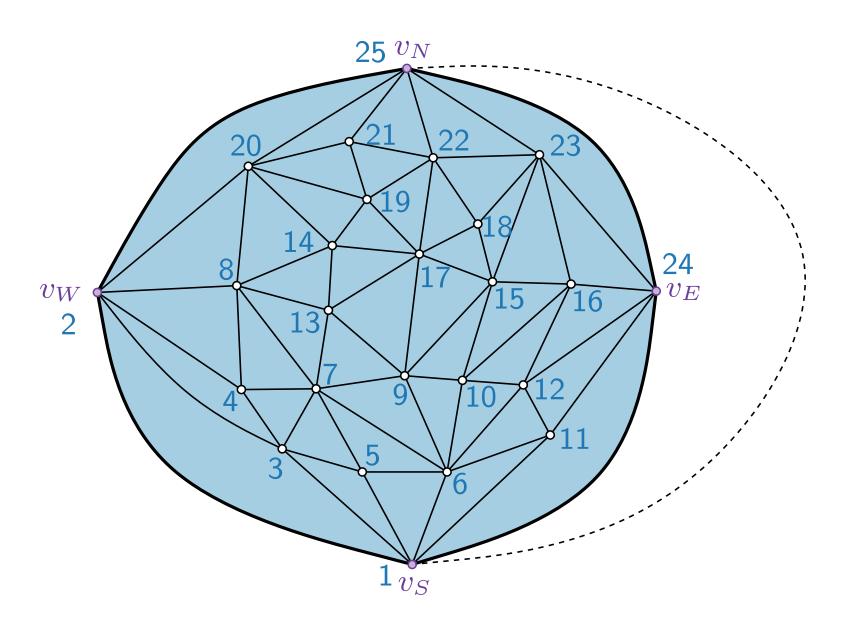


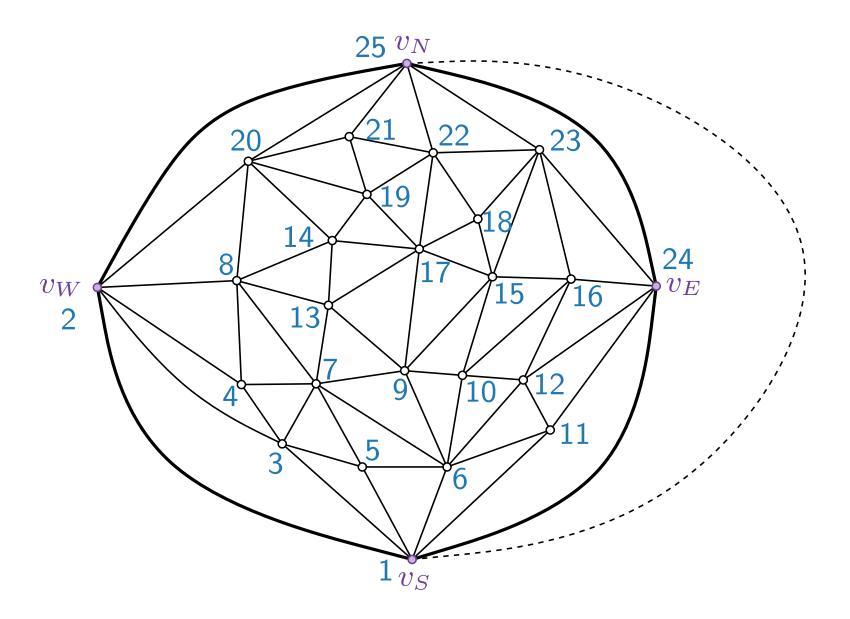






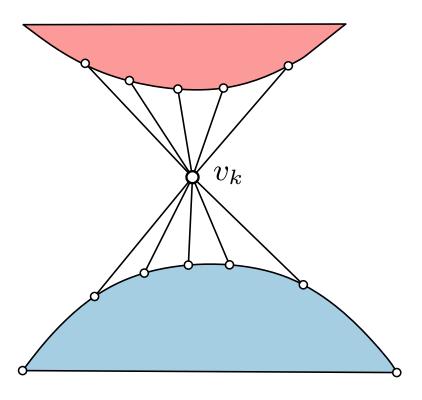






Refined Canonical Order \rightarrow REL

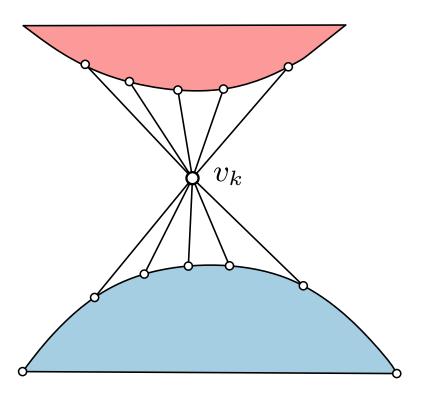
We construct a REL as follows:



Refined Canonical Order \rightarrow REL

We construct a REL as follows:

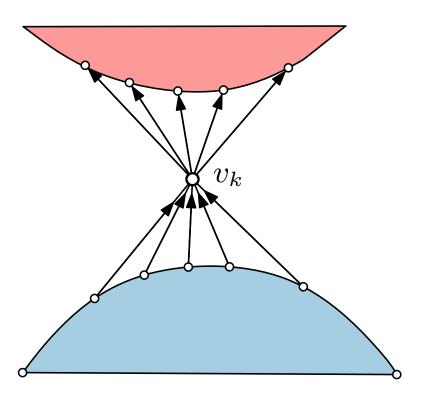
For i < j, orient (v_i, v_j) from v_i to v_j ;



Refined Canonical Order \rightarrow REL

We construct a REL as follows:

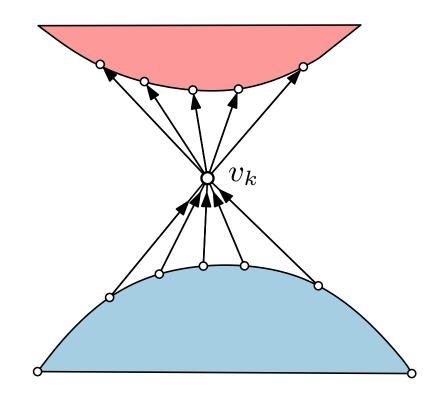
For i < j, orient (v_i, v_j) from v_i to v_j ;



Refined Canonical Order → REL

We construct a REL as follows:

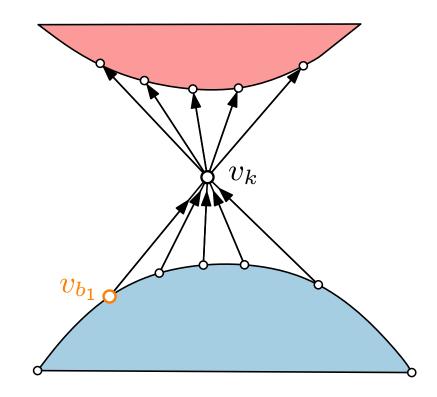
- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .



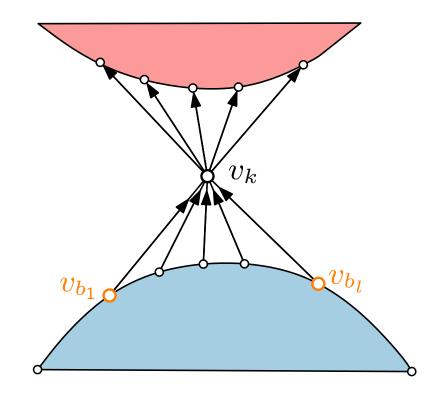
Refined Canonical Order → REL

We construct a REL as follows:

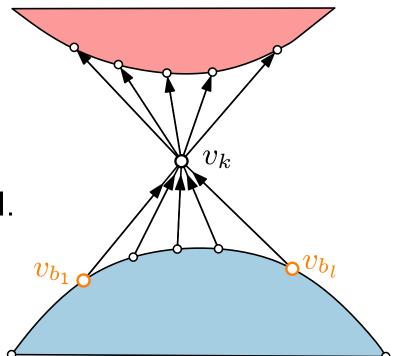
- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .



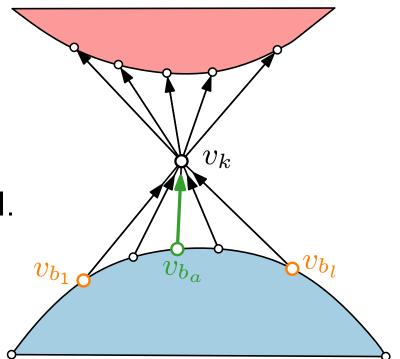
- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .



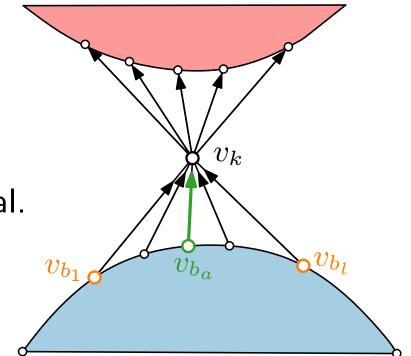
- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.



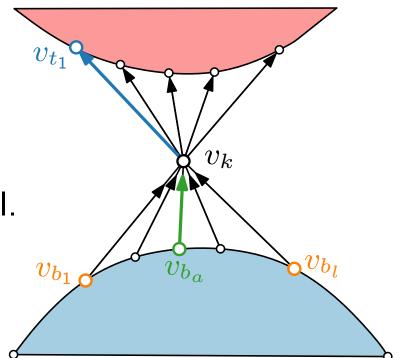
- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.



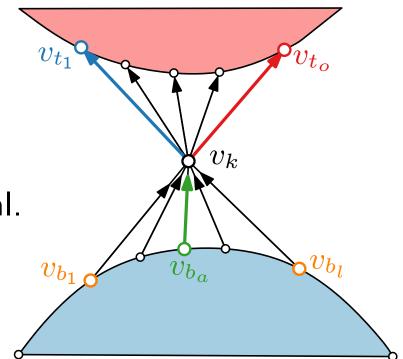
- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.
- If v_{t_1}, \ldots, v_{t_o} are higher numbered neighbors of v_k , we call (v_k, v_{t_1}) left edge and (v_k, v_{t_o}) right edge of v_k .



- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.
- If v_{t_1}, \ldots, v_{t_o} are higher numbered neighbors of v_k , we call (v_k, v_{t_1}) left edge and (v_k, v_{t_o}) right edge of v_k .



- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.
- If v_{t_1}, \ldots, v_{t_o} are higher numbered neighbors of v_k , we call (v_k, v_{t_1}) left edge and (v_k, v_{t_o}) right edge of v_k .

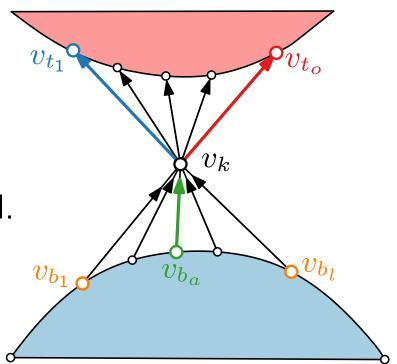


We construct a REL as follows:

- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.
- If v_{t_1}, \ldots, v_{t_o} are higher numbered neighbors of v_k , we call (v_k, v_{t_1}) left edge and (v_k, v_{t_o}) right edge of v_k .

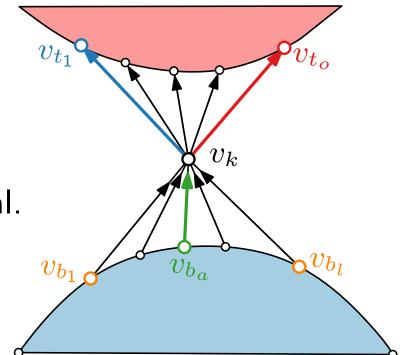


A left edge or right edge cannot be a base edge.



We construct a REL as follows:

- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.
- If v_{t_1}, \ldots, v_{t_o} are higher numbered neighbors of v_k , we call (v_k, v_{t_1}) left edge and (v_k, v_{t_o}) right edge of v_k .



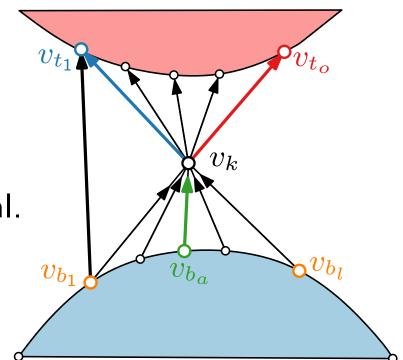
Lemma 1.

A left edge or right edge cannot be a base edge.

Proof. Suppose that the left edge (v_k, v_{t_1}) is the base edge of v_{t_1} .

We construct a REL as follows:

- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.
- If v_{t_1}, \ldots, v_{t_o} are higher numbered neighbors of v_k , we call (v_k, v_{t_1}) left edge and (v_k, v_{t_o}) right edge of v_k .



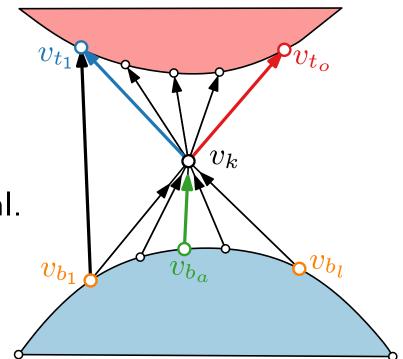
Lemma 1.

A left edge or right edge cannot be a base edge.

Proof. Suppose that the left edge (v_k, v_{t_1}) is the base edge of v_{t_1} . Since G is triangulated, $(v_{b_1}, v_{t_1}) \in E(G)$.

We construct a REL as follows:

- For i < j, orient (v_i, v_j) from v_i to v_j ;
- If v_k has incoming edges from v_{b_1}, \ldots, v_{b_l} , we say that v_{b_1} is the **left point** of v_k and v_{b_l} is the **right point** of v_k .
- Base edge of v_k is (v_{b_a}, v_k) , where $b_a \in \{b_1, \ldots, b_l\}$ is minimal.
- If v_{t_1}, \ldots, v_{t_o} are higher numbered neighbors of v_k , we call (v_k, v_{t_1}) left edge and (v_k, v_{t_o}) right edge of v_k .



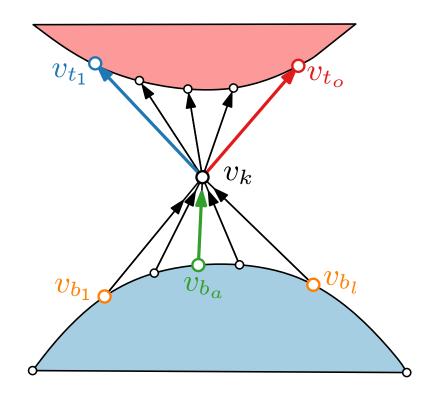
Lemma 1.

A left edge or right edge cannot be a base edge.

Proof. Suppose that the left edge (v_k, v_{t_1}) is the base edge of v_{t_1} . Since G is triangulated, $(v_{b_1}, v_{t_1}) \in E(G)$. Contradiction since $k > b_1$.

Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

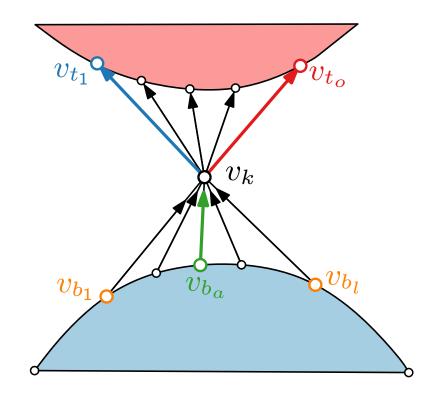


Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

Proof.

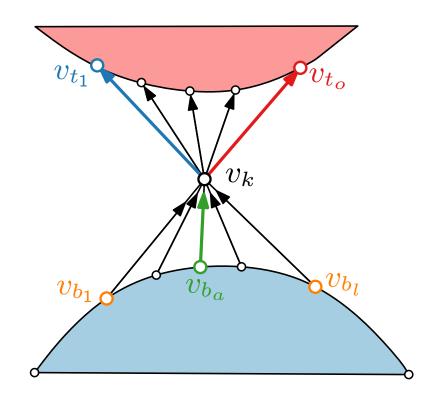
■ Exclusive "or" follows from Lemma 1.



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

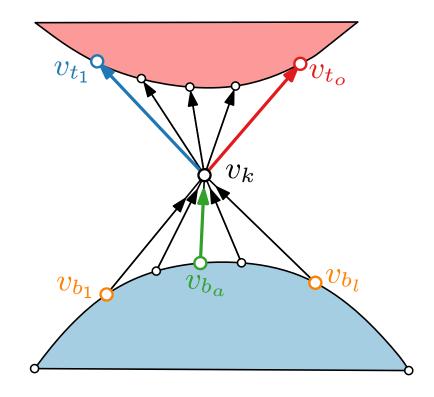
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

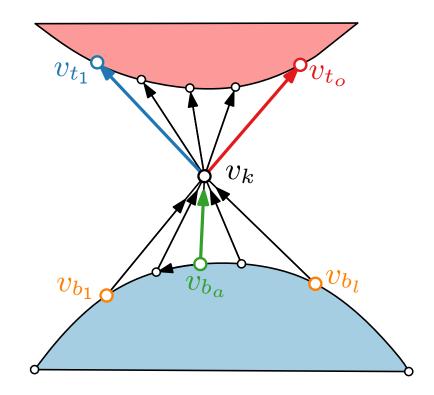
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

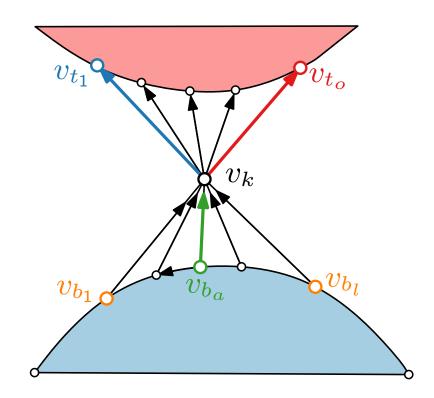
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

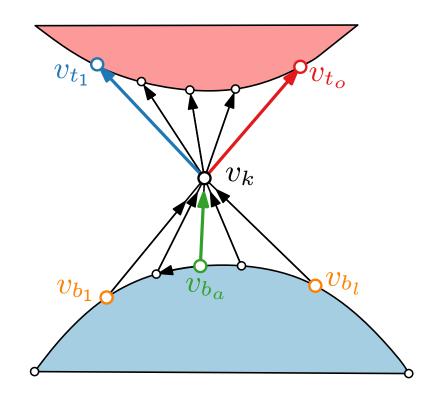
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.
 - lacksquare v_{b_i} has at least two higher-numbered neighbors.



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

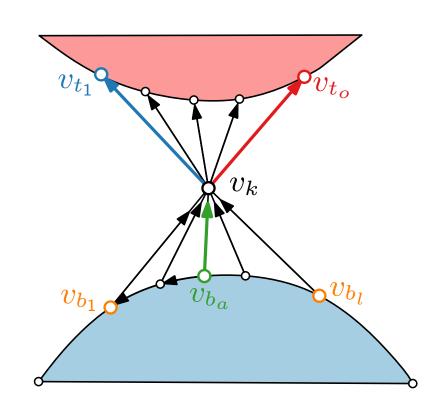
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.
 - $lacktriangleq v_{b_i}$ has at least two higher-numbered neighbors.
 - lacksquare One of them is v_k ; the other one is $v_{b_{i-1}}$ or $v_{b_{i+1}}$.



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

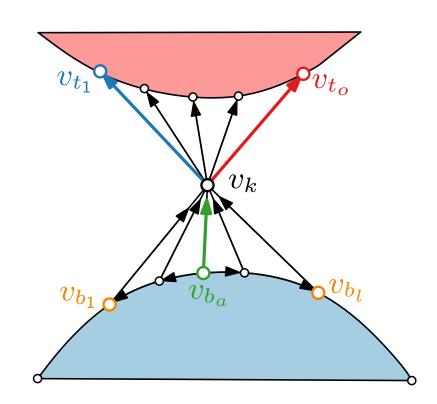
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.
 - lacksquare v_{b_i} has at least two higher-numbered neighbors.
 - lacksquare One of them is v_k ; the other one is $v_{b_{i-1}}$ or $v_{b_{i+1}}$.
 - For $1 \le i < a-1$, it is $v_{b_{i-1}}$. Thus, v_{b_i} is the right point of $v_{b_{i-1}}$.



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

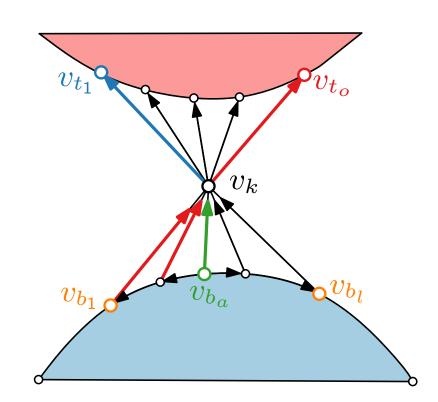
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.
 - lacksquare v_{b_i} has at least two higher-numbered neighbors.
 - lacksquare One of them is v_k ; the other one is $v_{b_{i-1}}$ or $v_{b_{i+1}}$.
 - For $1 \le i < a-1$, it is $v_{b_{i-1}}$. Thus, v_{b_i} is the right point of $v_{b_{i-1}}$.
- lacksquare Analogously, v_{b_i} is the left point of $v_{b_{i+1}}$ for $i\geq a$.



Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

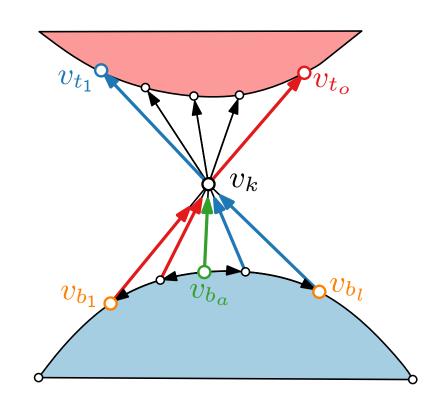
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.
 - lacksquare v_{b_i} has at least two higher-numbered neighbors.
 - lacksquare One of them is v_k ; the other one is $v_{b_{i-1}}$ or $v_{b_{i+1}}$.
 - For $1 \le i < a-1$, it is $v_{b_{i-1}}$. Thus, v_{b_i} is the right point of $v_{b_{i-1}}$.
- Analogously, v_{b_i} is the left point of $v_{b_{i+1}}$ for $i \geq a$.
- Edges (v_{b_i}, v_k) , $1 \le i < a 1$, are right edges.

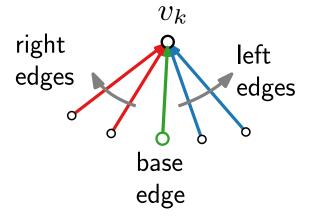


Lemma 2.

Every edge is either a left edge, a right edge or a base edge.

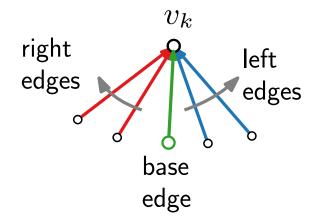
- Exclusive "or" follows from Lemma 1.
- Let (v_{b_a}, v_k) be the base edge of v_k .
- lacksquare v_{b_a} is the right point of $v_{b_{a-1}}$.
 - lacksquare v_{b_i} has at least two higher-numbered neighbors.
 - lacksquare One of them is v_k ; the other one is $v_{b_{i-1}}$ or $v_{b_{i+1}}$.
 - For $1 \le i < a-1$, it is $v_{b_{i-1}}$. Thus, v_{b_i} is the right point of $v_{b_{i-1}}$.
- Analogously, v_{b_i} is the left point of $v_{b_{i+1}}$ for $i \geq a$.
- Edges (v_{b_i}, v_k) , $1 \le i < a 1$, are right edges.
- Similarly, (v_{b_i}, v_k) , for $a + 1 \le i \le l$, are left edges.





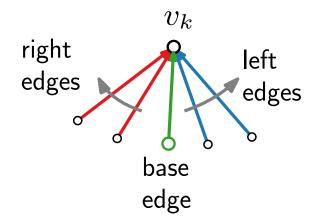
Coloring.

Color right (left) edges in red (blue).



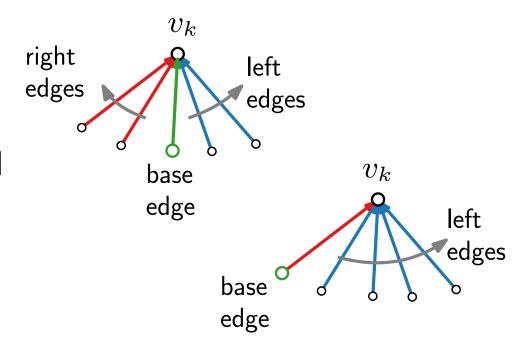
Coloring.

- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.



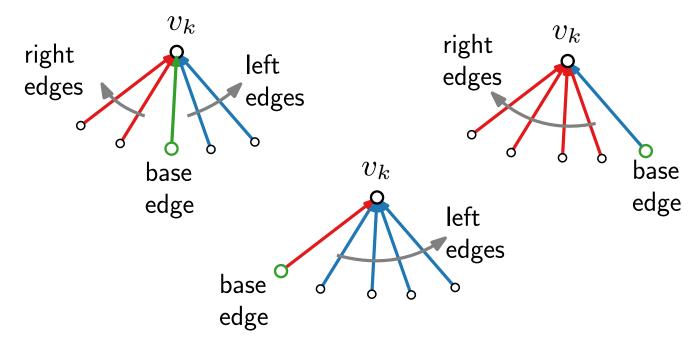
Coloring.

- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.



Coloring.

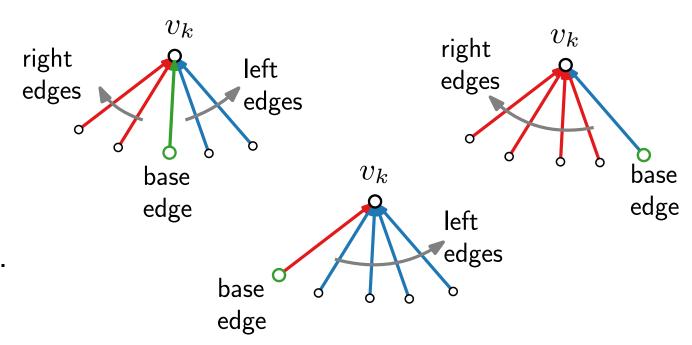
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.



Coloring.

- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

Let T_r be the red edges and T_b the blue edges.



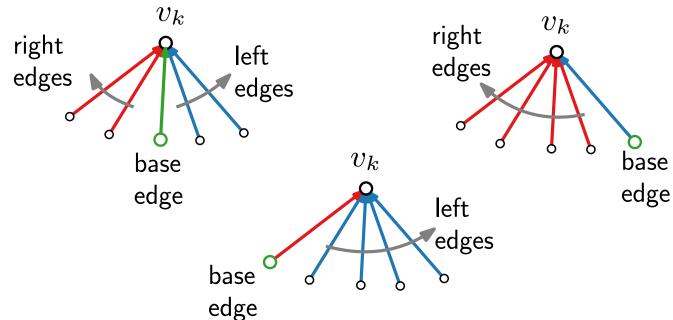
Coloring.

- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.



Coloring.

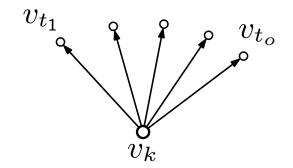
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

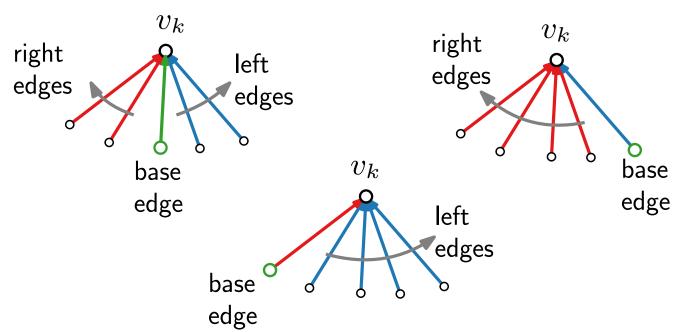
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





Coloring.

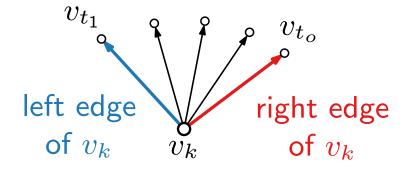
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

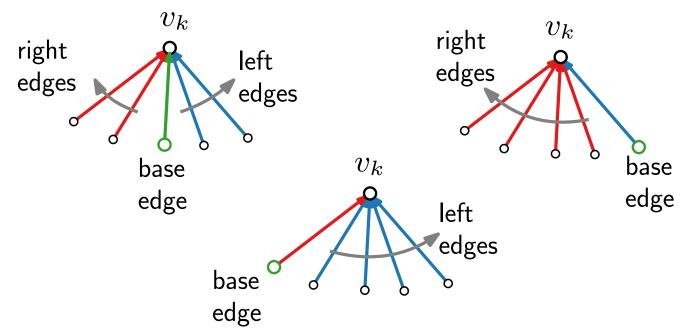
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





Coloring.

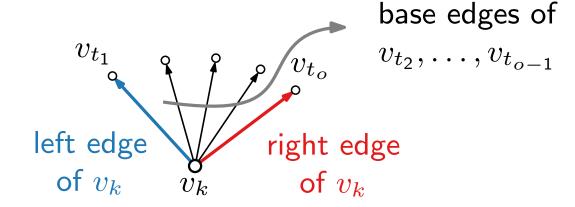
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

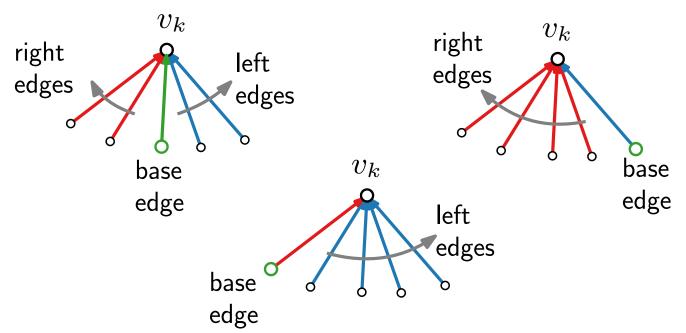
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





Coloring.

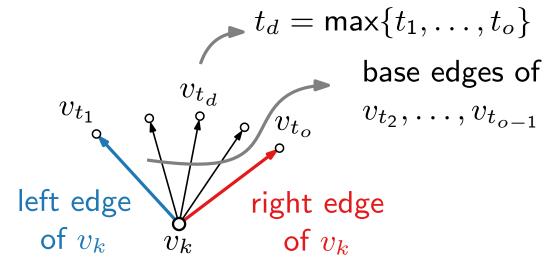
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

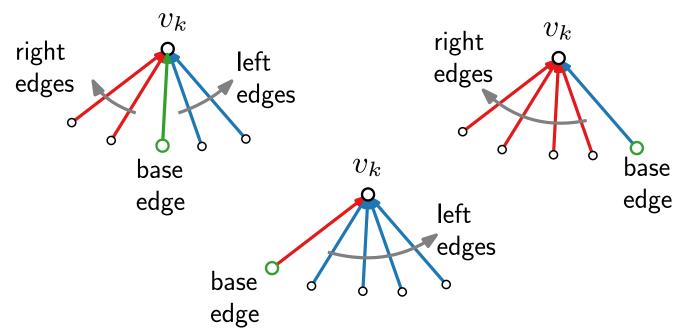
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





Coloring.

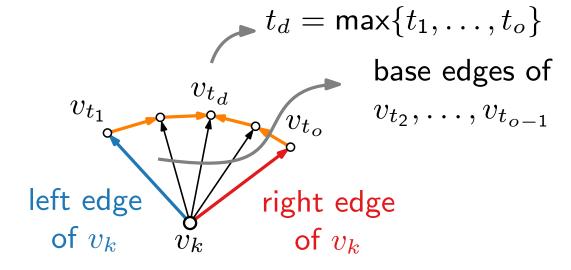
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

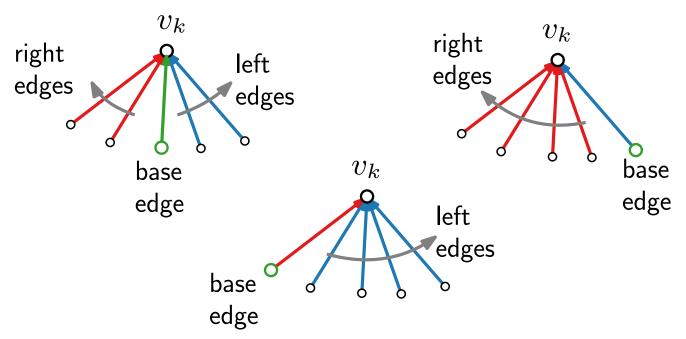
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





$$t_d = \max\{t_1,\ldots,t_o\}$$
 $\qquad \qquad t_1 < t_2 < \ldots < t_d \text{ and}$ base edges of $\qquad \qquad t_d > t_{d+1} > \ldots > t_o$

Coloring.

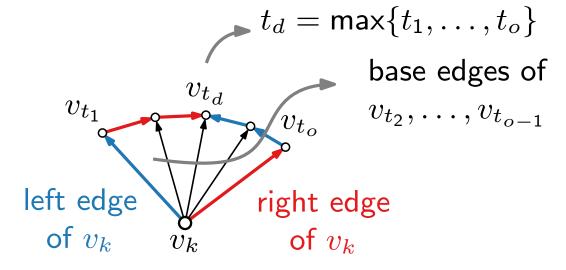
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

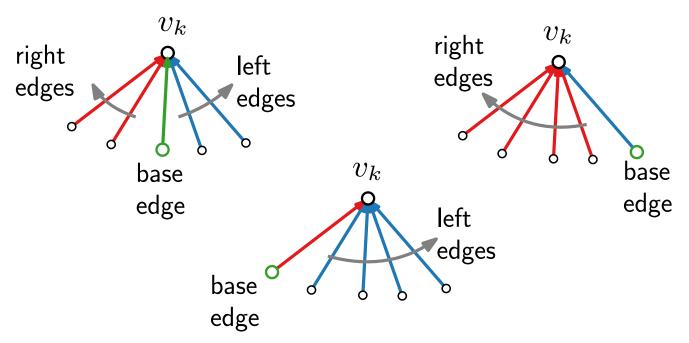
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





$$t_d = \max\{t_1,\ldots,t_o\}$$
 $\qquad \qquad t_1 < t_2 < \ldots < t_d \text{ and}$ base edges of $\qquad \qquad t_d > t_{d+1} > \ldots > t_o$

Coloring.

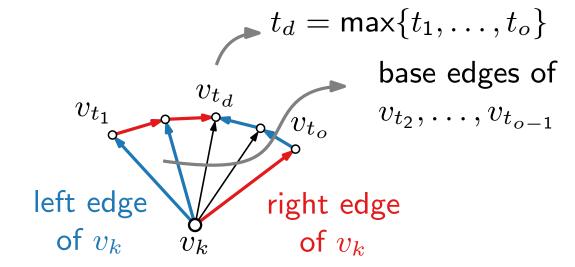
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

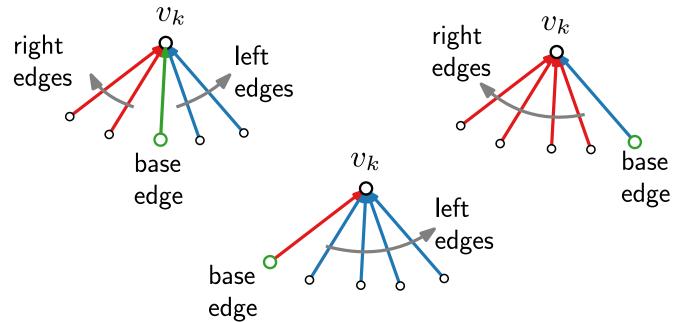
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





- $t_1 < t_2 < \ldots < t_d \text{ and } t_d > t_{d+1} > \ldots > t_o$
- (v_k, v_{t_i}) , $2 \le i \le d-1$ are blue

Coloring.

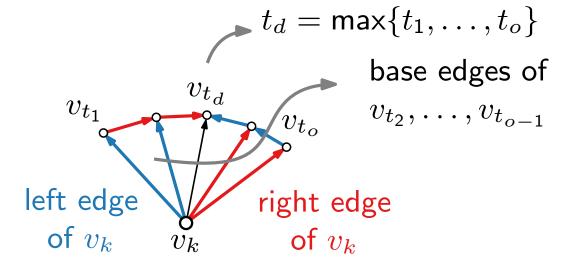
- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

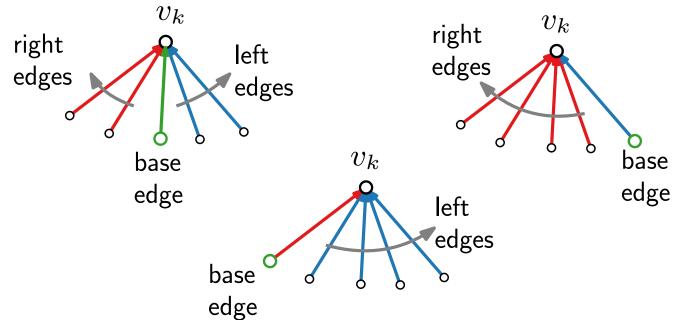
Let T_r be the red edges and T_b the blue edges.

Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

$$t_o \geq 2$$





- $t_1 < t_2 < \ldots < t_d \text{ and } t_d > t_{d+1} > \ldots > t_o$
- (v_k, v_{t_i}) , $2 \le i \le d-1$ are blue
- $(v_k, v_{t_i}), d+1 \le i \le o-1 \text{ are red}$

Refined Canonical Order \rightarrow REL

Coloring.

- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

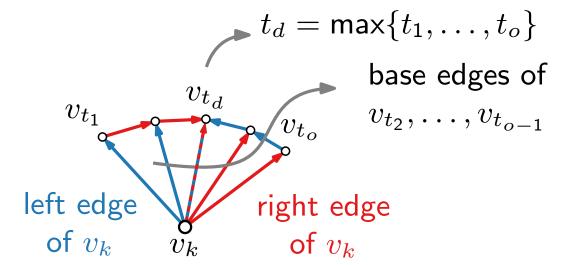
Let T_r be the red edges and T_b the blue edges.

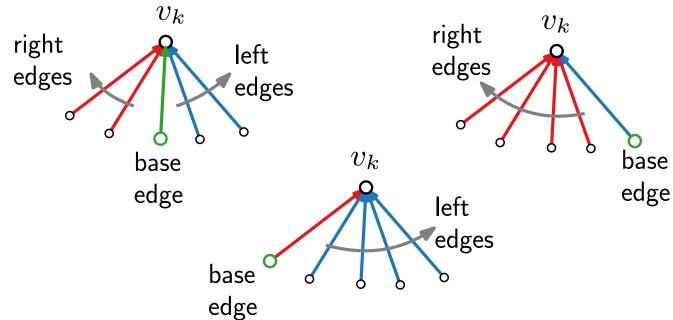
Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

Proof.

$$t_o \geq 2$$





- $t_1 < t_2 < \ldots < t_d \text{ and } t_d > t_{d+1} > \ldots > t_o$
- (v_k, v_{t_i}) , $2 \le i \le d-1$ are blue
- $(v_k, v_{t_i}), d+1 \leq i \leq o-1$ are red
- (v_k, v_{t_d}) is either red or blue

Refined Canonical Order \rightarrow REL

Coloring.

- Color right (left) edges in red (blue).
- Color a base edge (v_{b_i}, v_k) red if i = 1 and blue if i = l and otherwise arbitrarily.

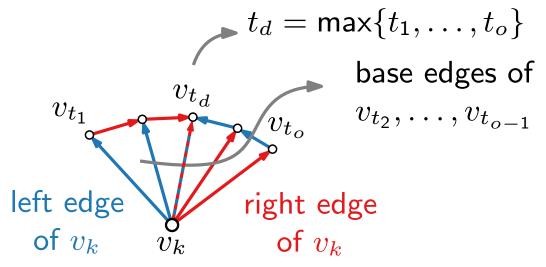
Let T_r be the red edges and T_b the blue edges.

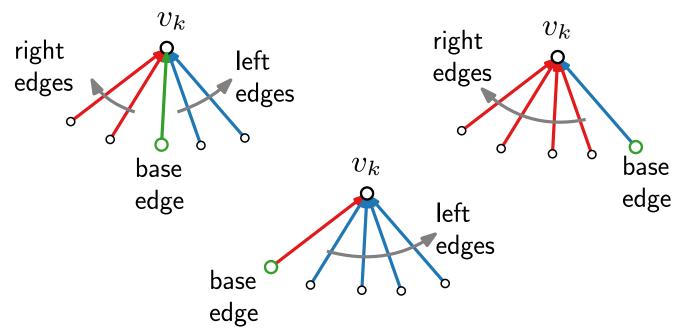
Lemma 3.

 $\{T_r, T_b\}$ is a regular edge labeling.

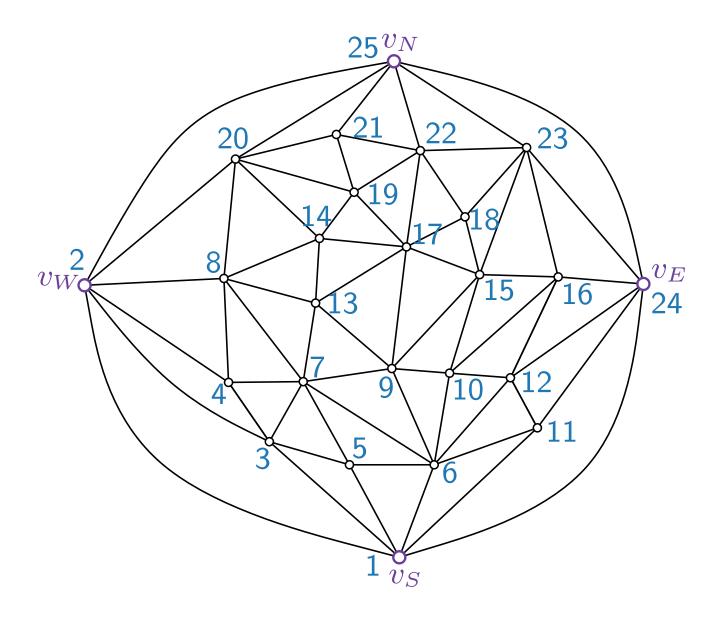
Proof.

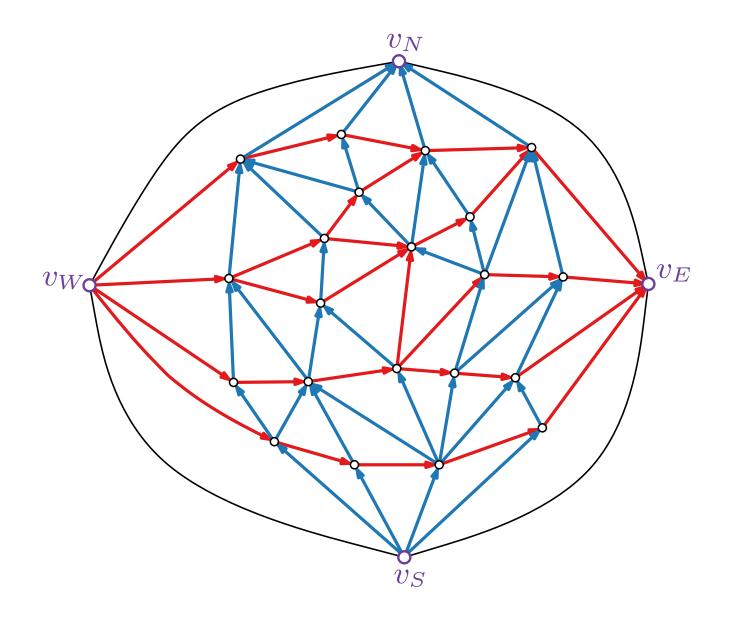
$$t_o \geq 2$$

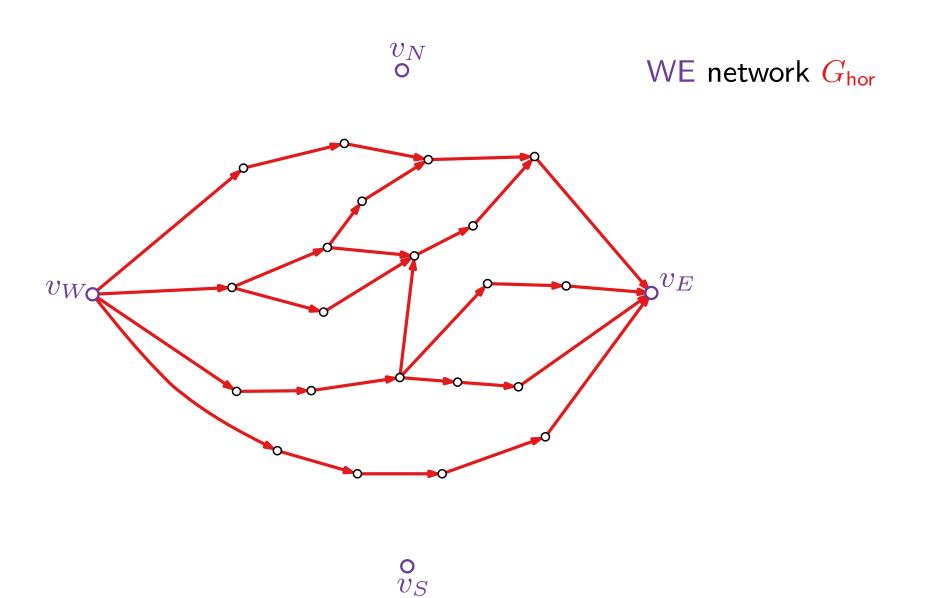


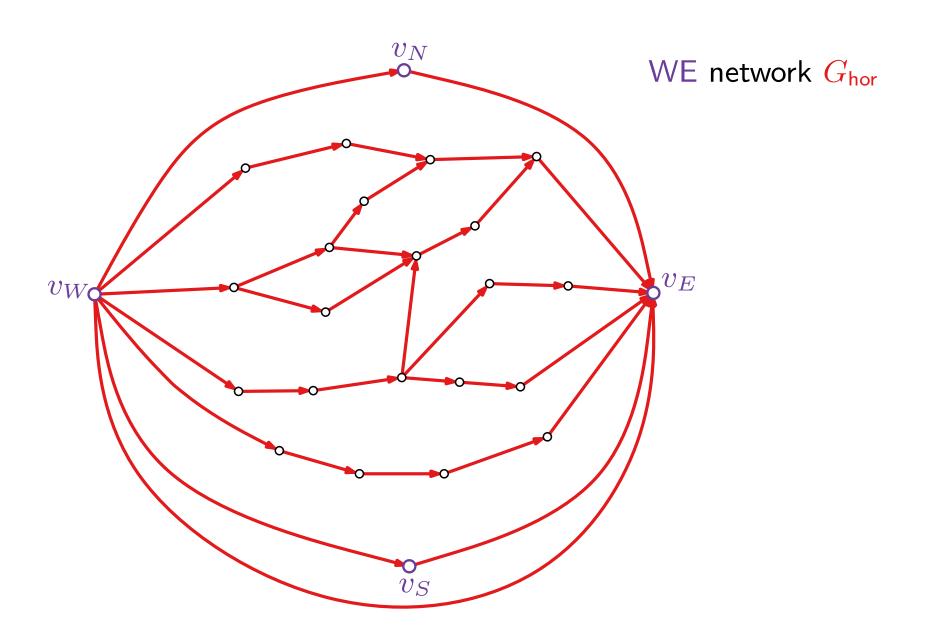


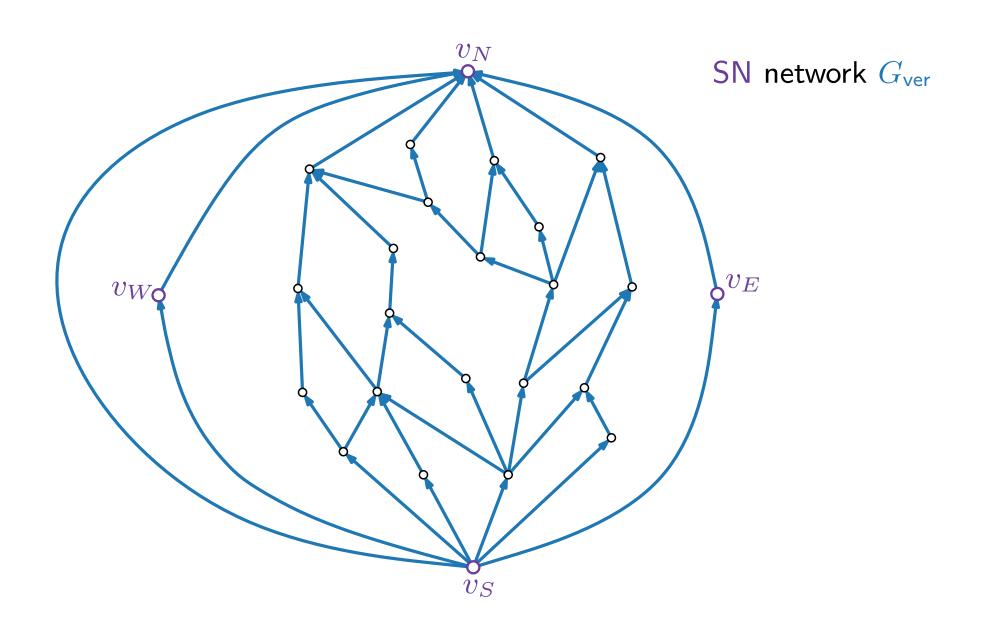
- $t_1 < t_2 < \ldots < t_d \text{ and } t_d > t_{d+1} > \ldots > t_o$
- (v_k, v_{t_i}) , $2 \le i \le d-1$ are blue
- $(v_k, v_{t_i}), d+1 \leq i \leq o-1$ are red
- \bullet (v_k, v_{t_d}) is either red or blue
- \Rightarrow Circular order of outgoing edges at v_k correct.

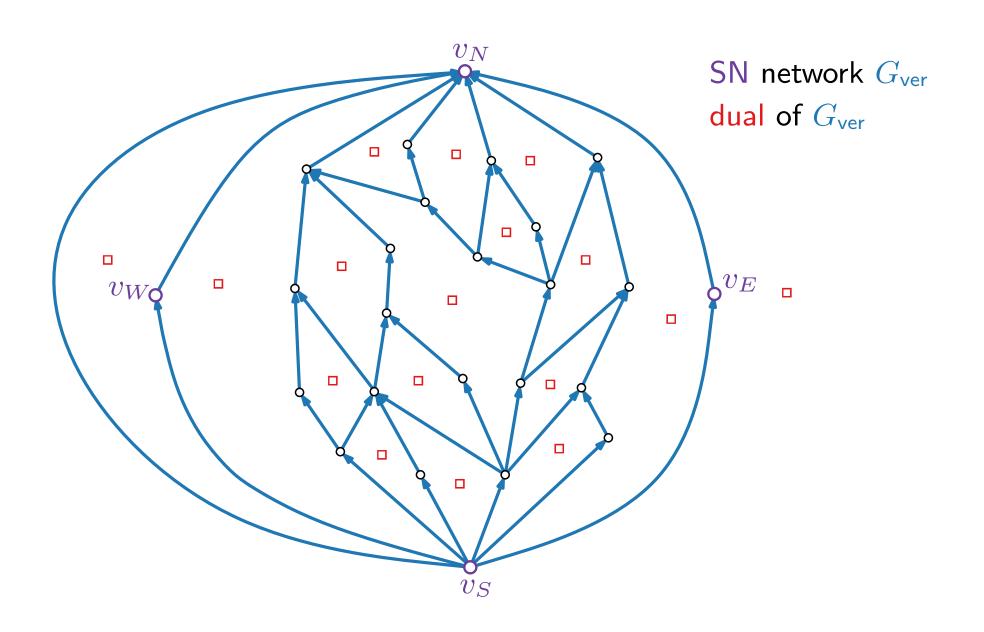


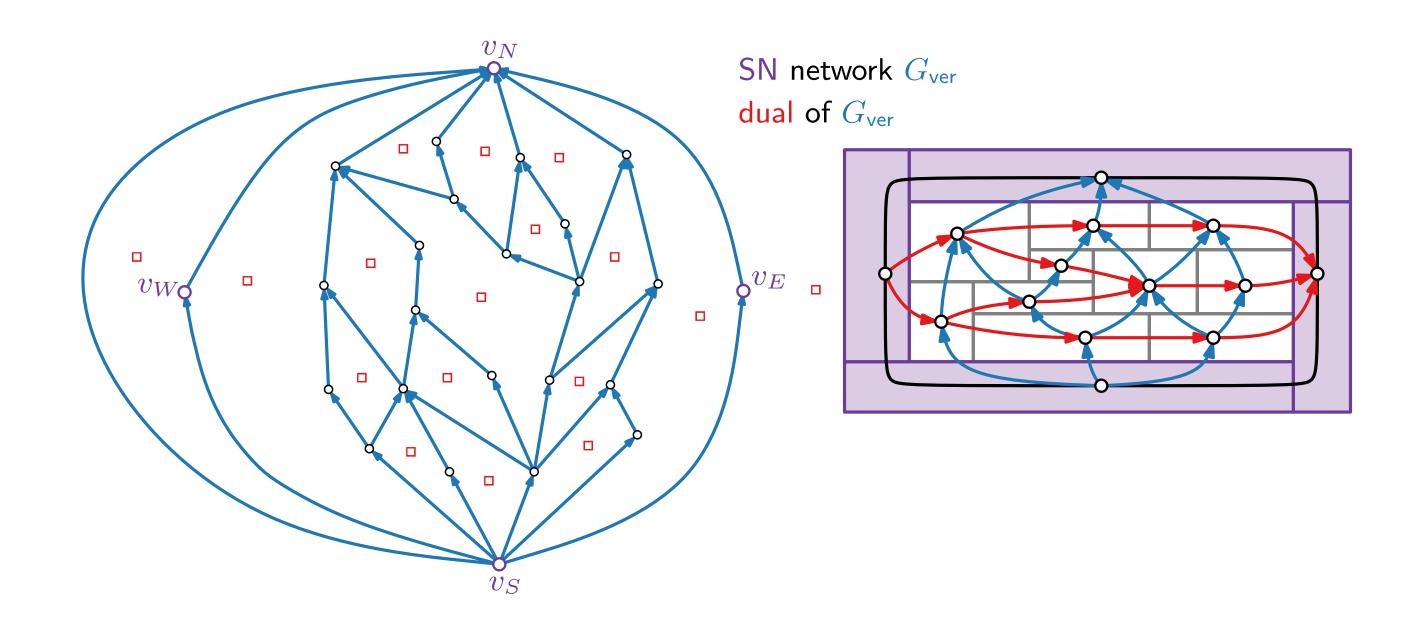


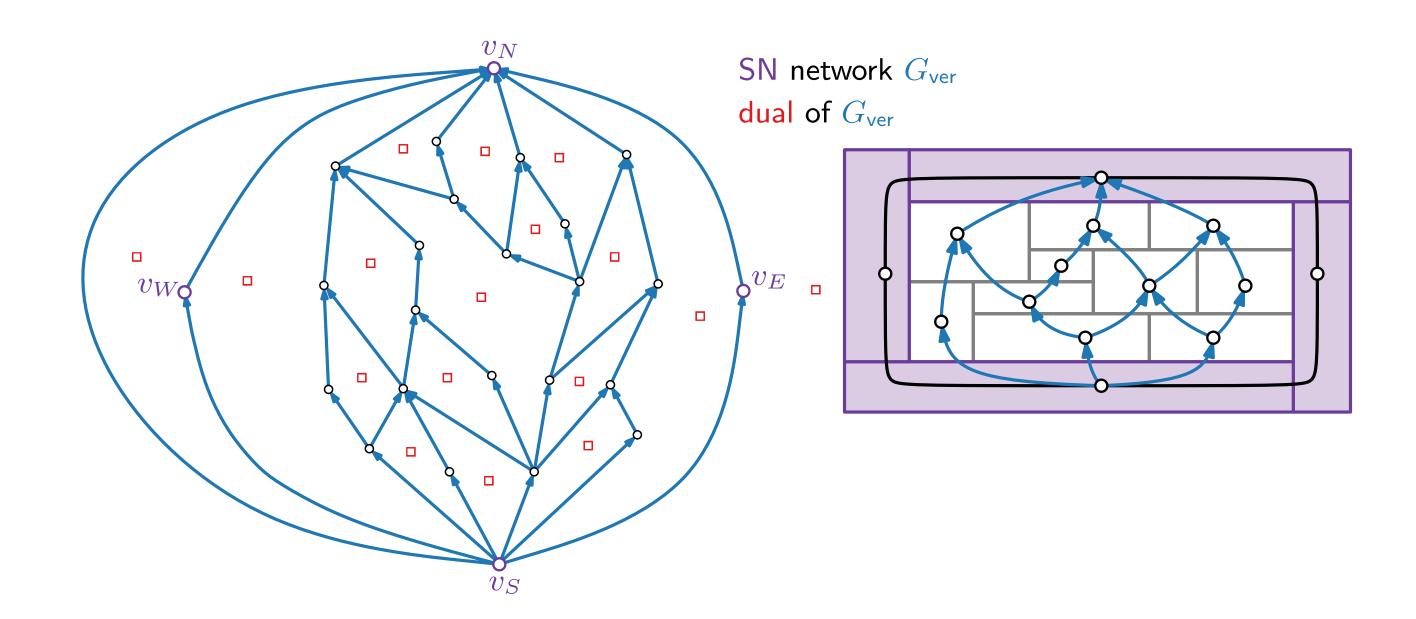


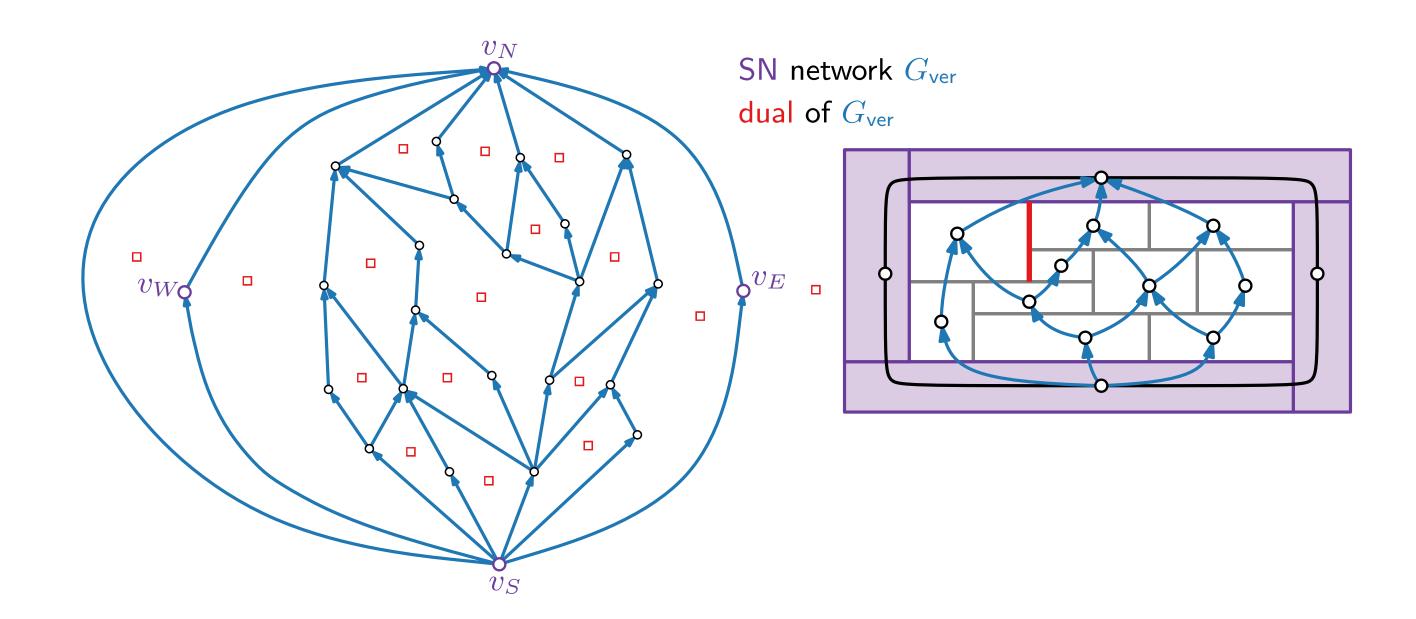


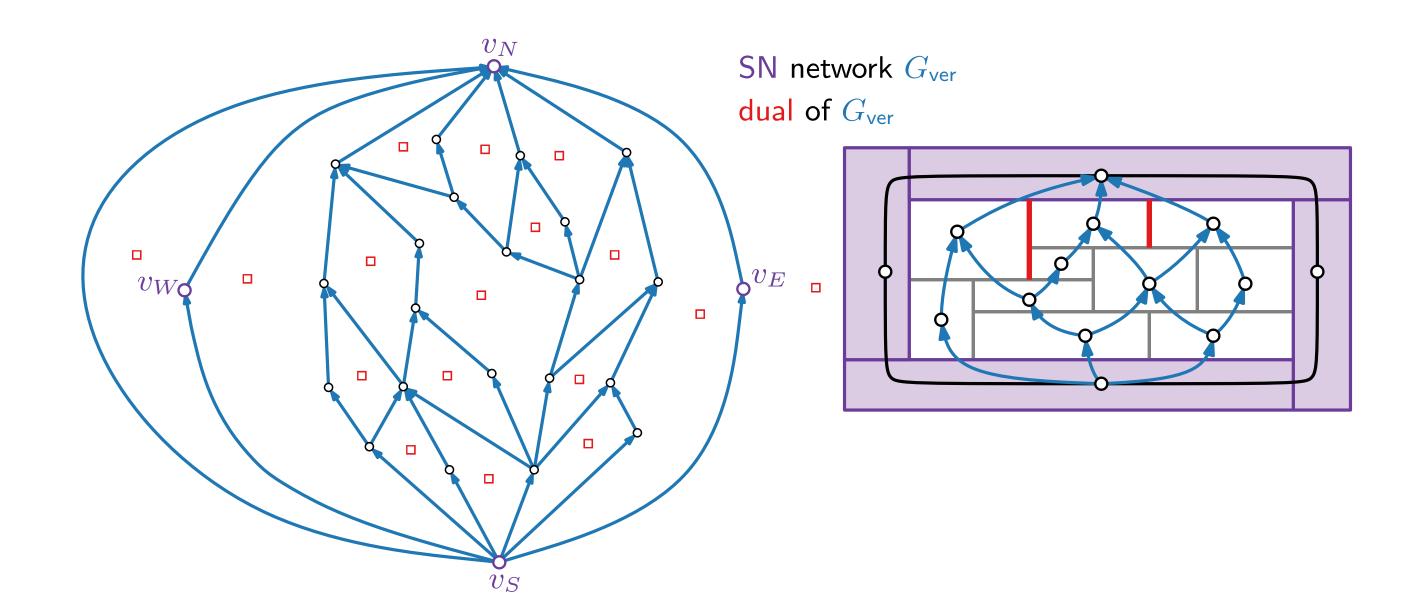


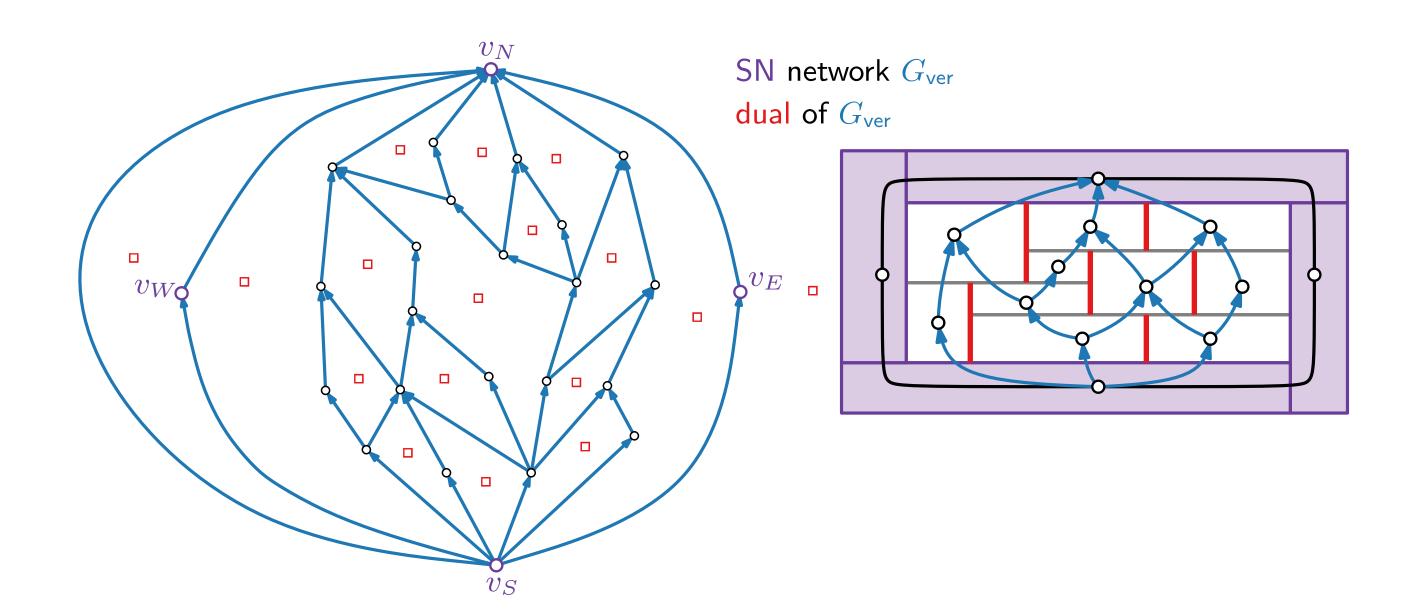


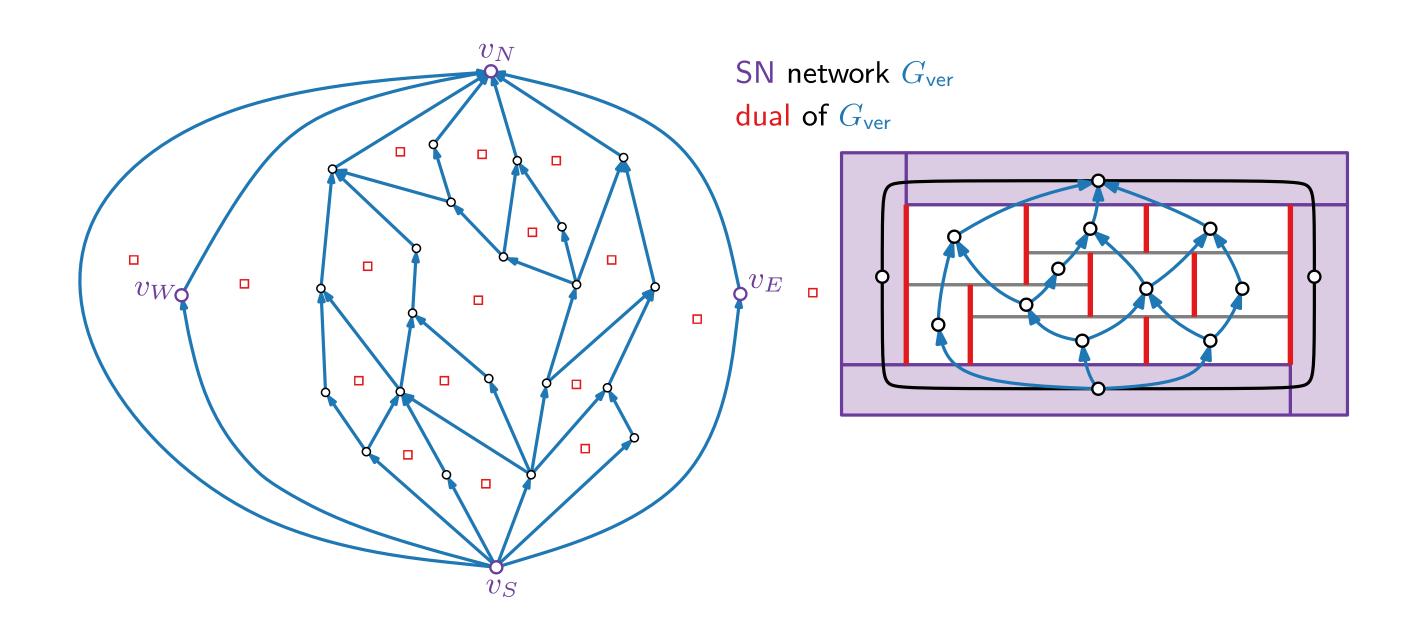


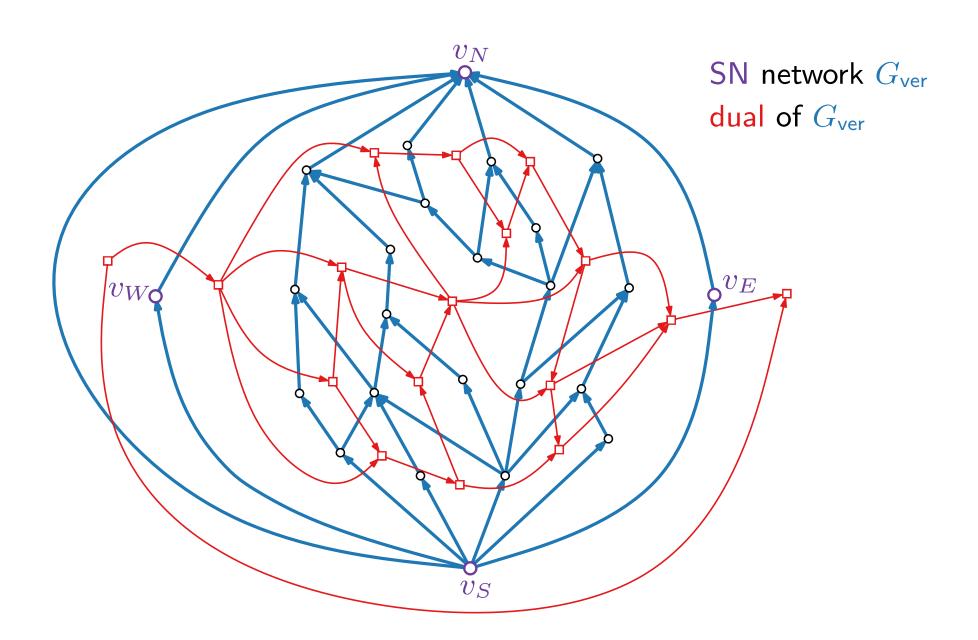


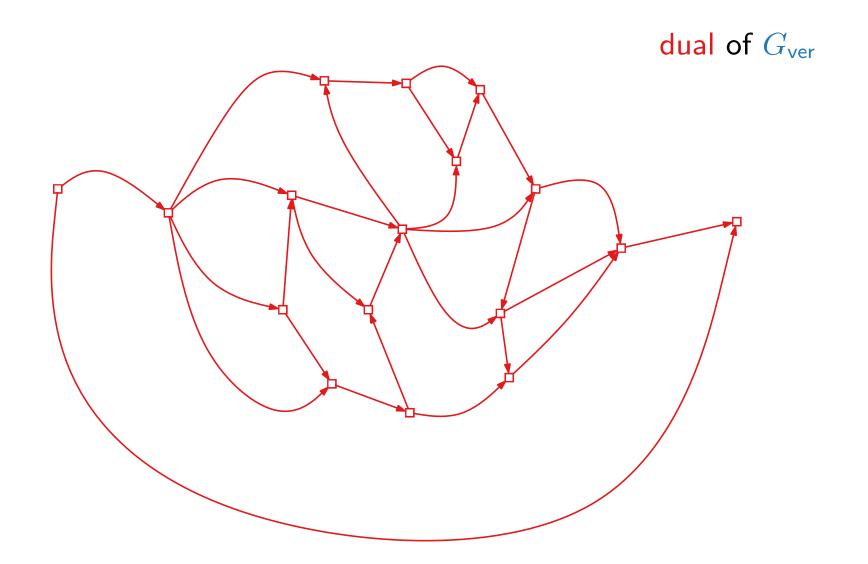


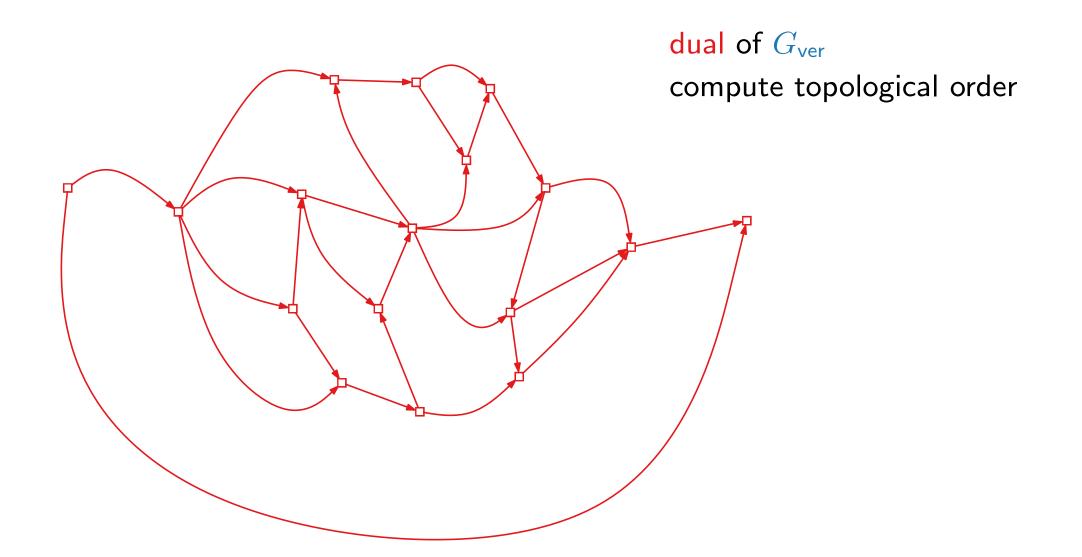


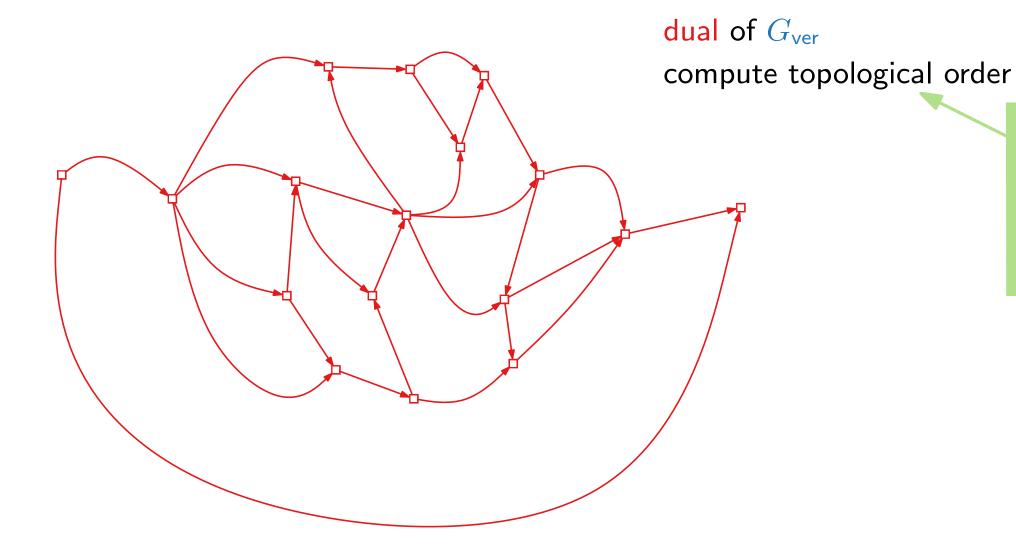




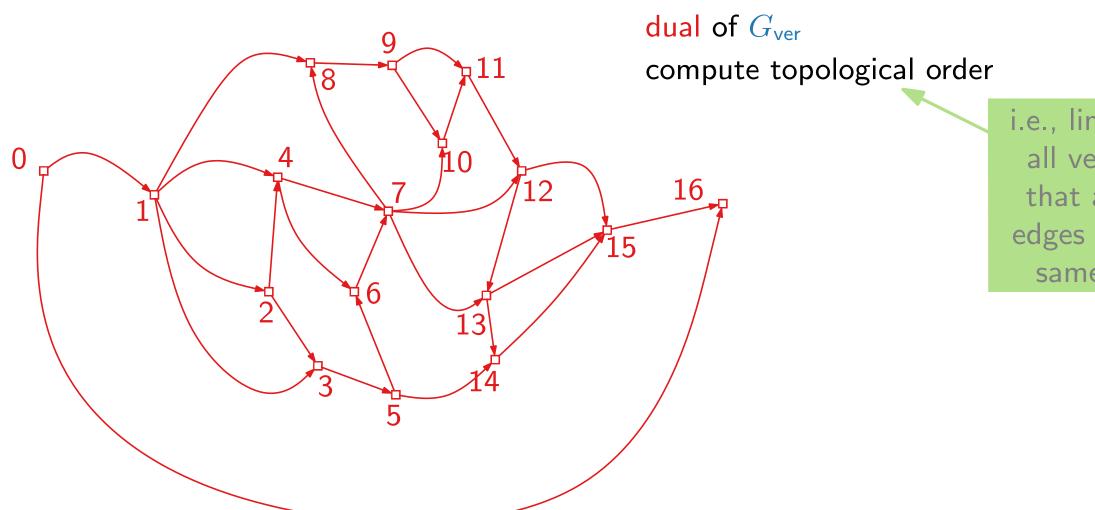




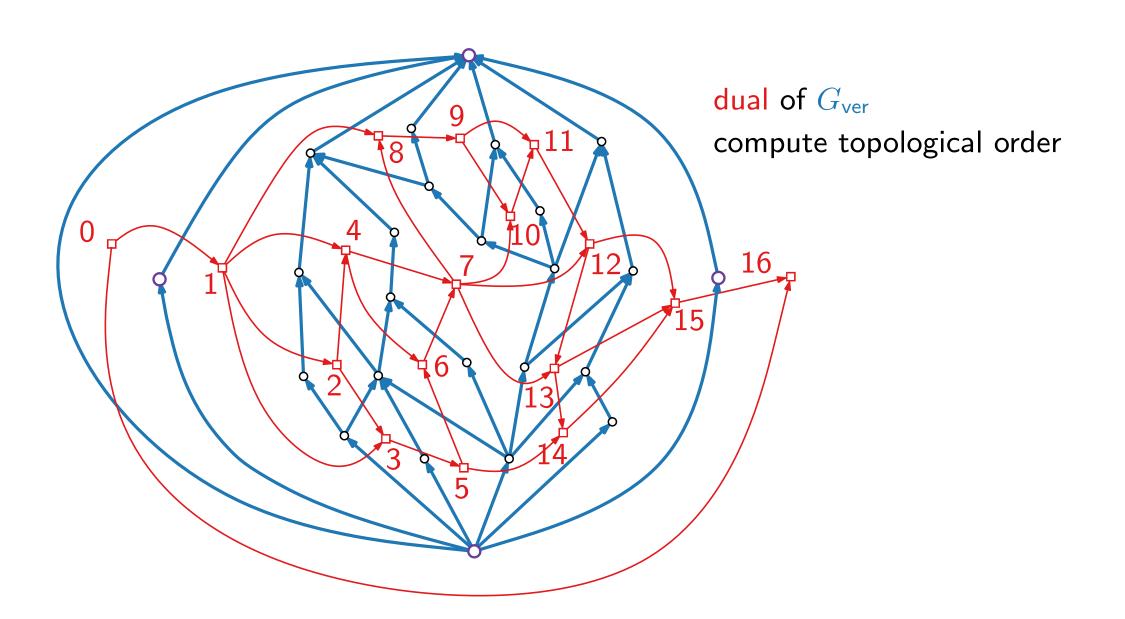


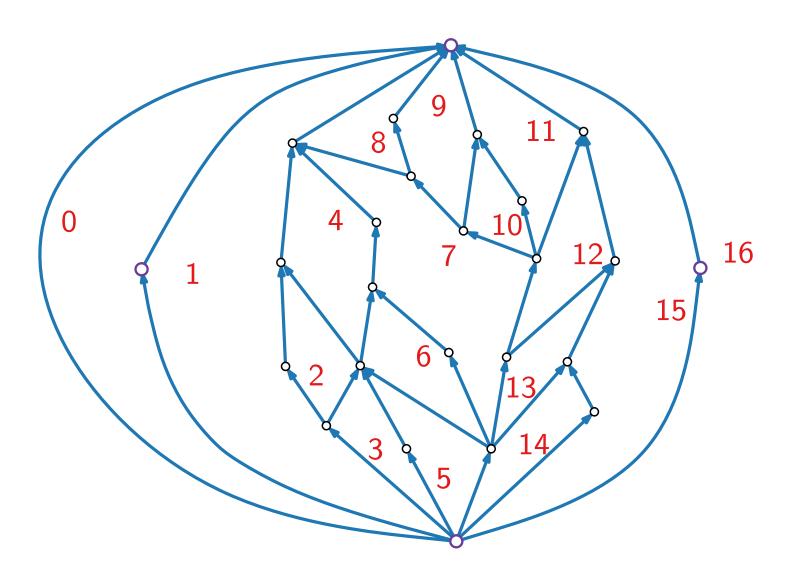


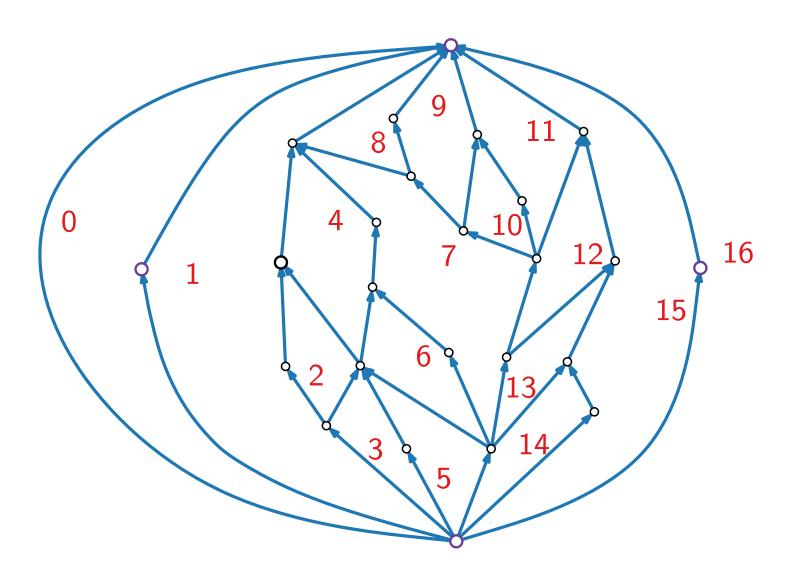
i.e., linear order of all vertices such that all directed edges point in the same direction

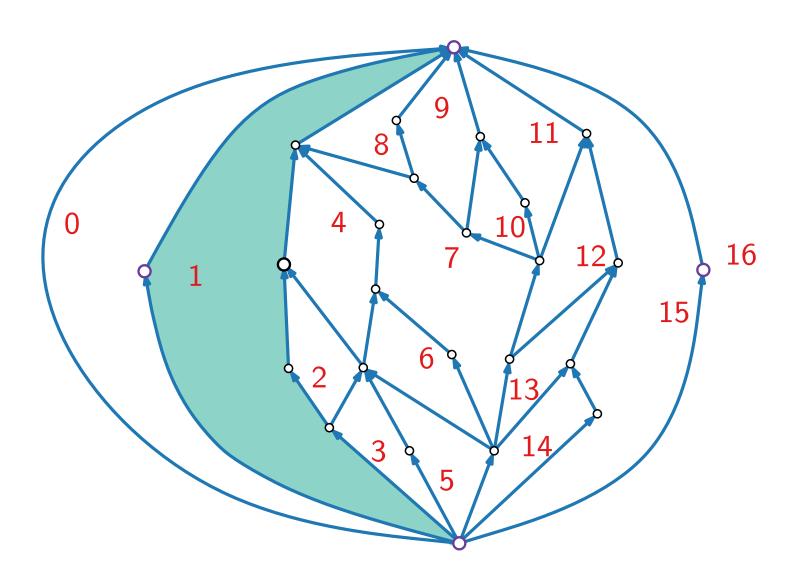


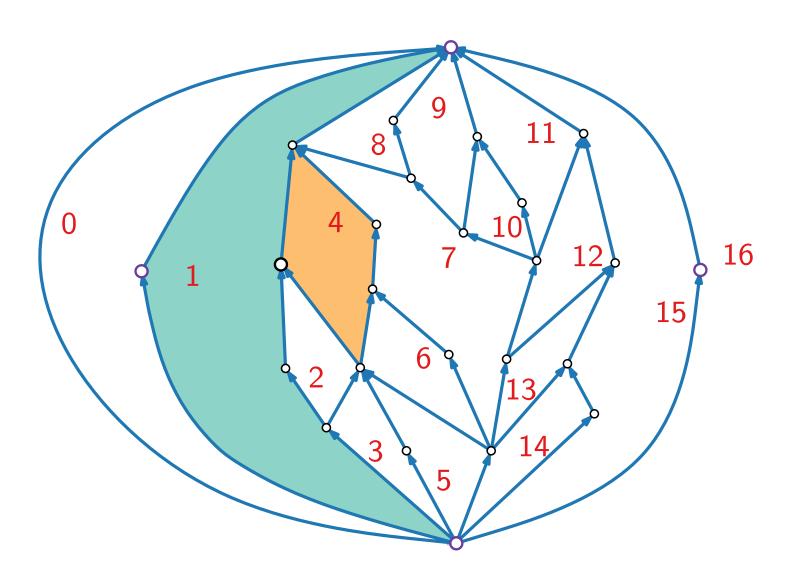
i.e., linear order of all vertices such that all directed edges point in the same direction

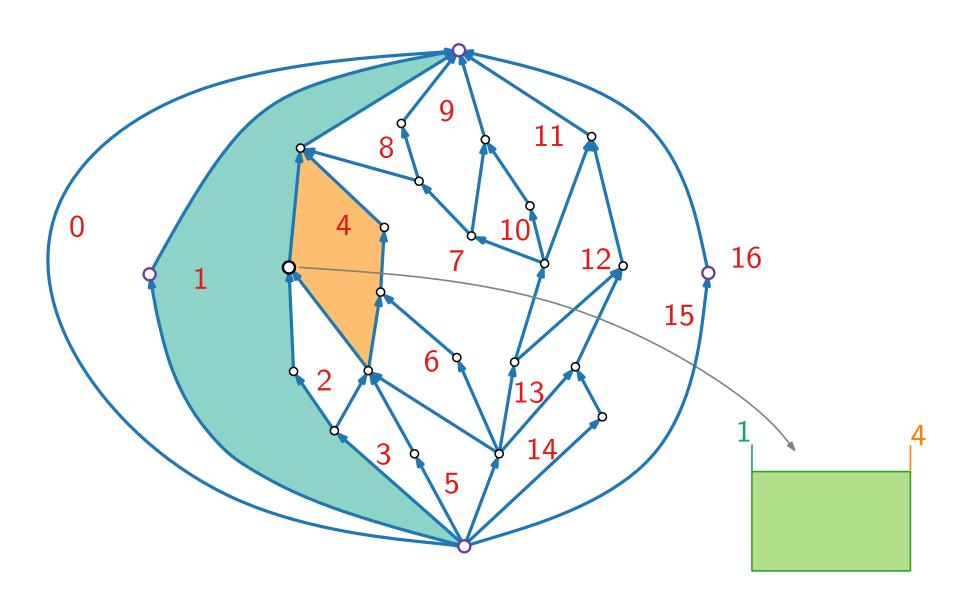


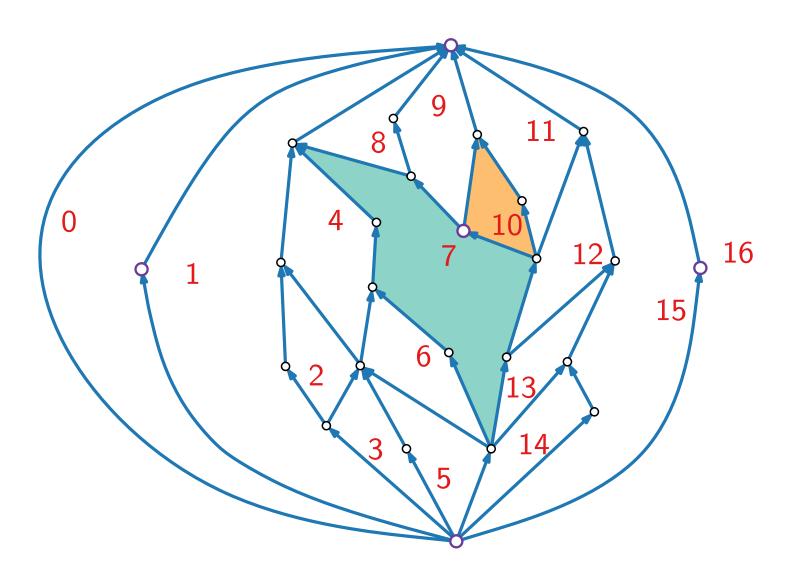


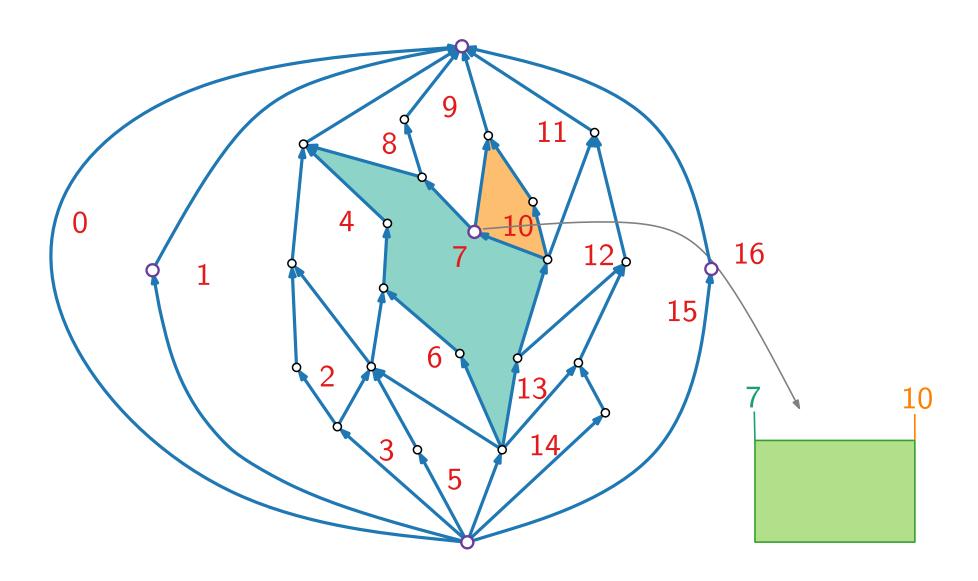












For a PTP graph G:

■ Find a REL $\{T_r, T_b\}$ of G.

- Find a REL $\{T_r, T_b\}$ of G.
- Construct a SN network G_{ver} of G (consists of T_b plus outer edges).

- Find a REL $\{T_r, T_b\}$ of G.
- Construct a SN network G_{ver} of G (consists of T_b plus outer edges).
- lacktriangle Construct the dual G_{ver}^{\star} of G_{ver} and compute a topological ordering f_{ver} of G_{ver}^{\star} .

- Find a REL $\{T_r, T_b\}$ of G.
- \blacksquare Construct a SN network G_{ver} of G (consists of T_b plus outer edges).
- lacktriangle Construct the dual G_{ver}^{\star} of G_{ver} and compute a topological ordering f_{ver} of G_{ver}^{\star} .
- lacktriangle For each vertex v of G, let g and h be the face on the left and face on the right of v.

- Find a REL $\{T_r, T_b\}$ of G.
- Construct a SN network G_{ver} of G (consists of T_b plus outer edges).
- lacktriangle Construct the dual G_{ver}^{\star} of G_{ver} and compute a topological ordering f_{ver} of G_{ver}^{\star} .
- For each vertex v of G, let g and h be the face on the left and face on the right of v. Set $x_1(v) = f_{\text{ver}}(g)$ and $x_2(v) = f_{\text{ver}}(h)$.

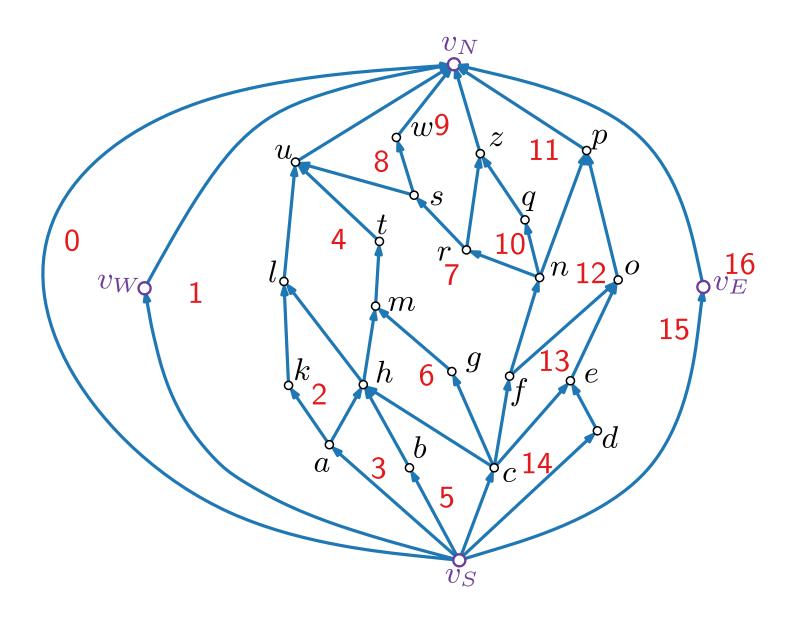
- Find a REL $\{T_r, T_b\}$ of G.
- \blacksquare Construct a SN network G_{ver} of G (consists of T_b plus outer edges).
- lacktriangle Construct the dual G_{ver}^{\star} of G_{ver} and compute a topological ordering f_{ver} of G_{ver}^{\star} .
- For each vertex v of G, let g and h be the face on the left and face on the right of v. Set $x_1(v) = f_{\text{ver}}(g)$ and $x_2(v) = f_{\text{ver}}(h)$.
- Define $x_1(v_N) = 0, x_1(v_S) = 1$ and $x_2(v_N) = \max f_{\text{ver}} 1, x_2(v_S) = \max f_{\text{ver}}$.

- Find a REL $\{T_r, T_b\}$ of G.
- \blacksquare Construct a SN network G_{ver} of G (consists of T_b plus outer edges).
- lacktriangle Construct the dual G_{ver}^{\star} of G_{ver} and compute a topological ordering f_{ver} of G_{ver}^{\star} .
- For each vertex v of G, let g and h be the face on the left and face on the right of v. Set $x_1(v) = f_{\text{ver}}(g)$ and $x_2(v) = f_{\text{ver}}(h)$.
- Define $x_1(v_N) = 0, x_1(v_S) = 1$ and $x_2(v_N) = \max f_{\text{ver}} 1, x_2(v_S) = \max f_{\text{ver}}$.
- lacksquare Analogously compute y_1 and y_2 with G_{hor} .

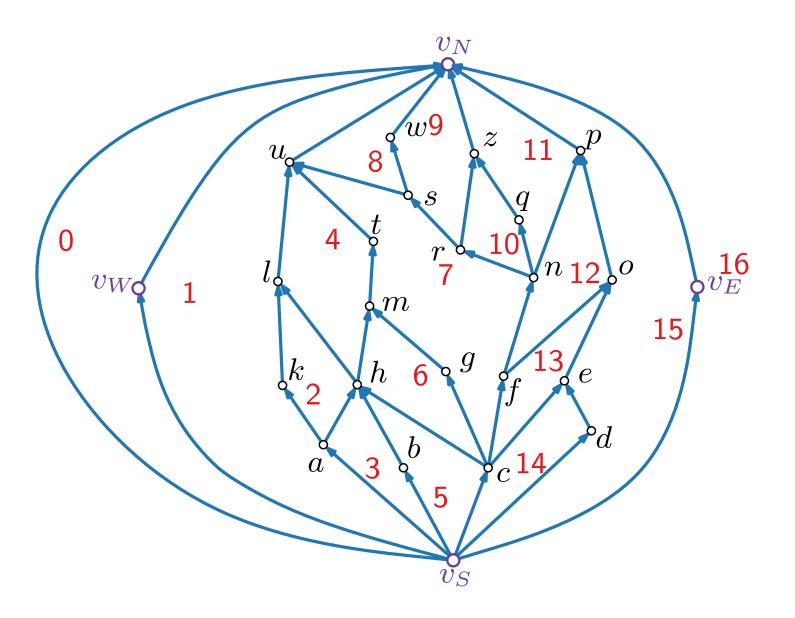
For a PTP graph G:

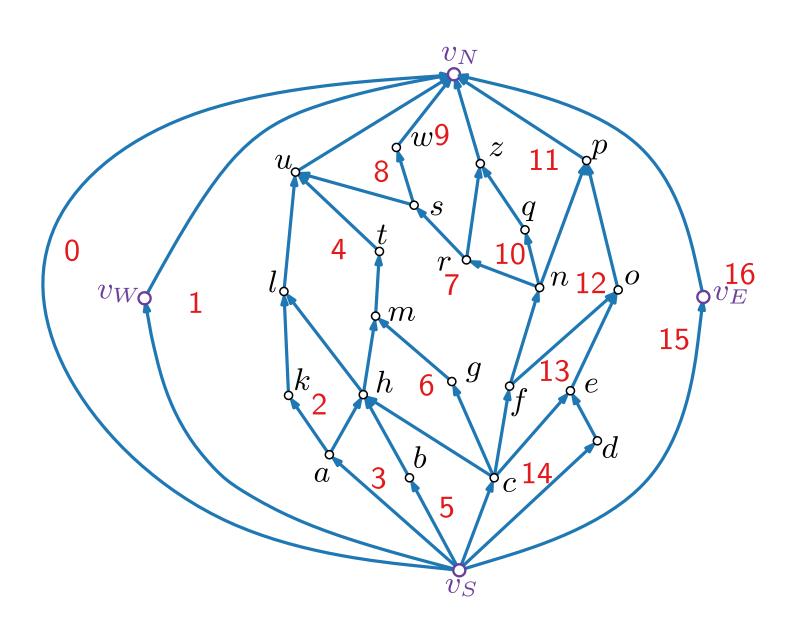
- Find a REL $\{T_r, T_b\}$ of G.
- Construct a SN network G_{ver} of G (consists of T_b plus outer edges).
- lacktriangle Construct the dual G_{ver}^{\star} of G_{ver} and compute a topological ordering f_{ver} of G_{ver}^{\star} .
- For each vertex v of G, let g and h be the face on the left and face on the right of v. Set $x_1(v) = f_{\text{ver}}(g)$ and $x_2(v) = f_{\text{ver}}(h)$.
- Define $x_1(v_N) = 0, x_1(v_S) = 1$ and $x_2(v_N) = \max f_{\text{ver}} 1, x_2(v_S) = \max f_{\text{ver}}$.
- \blacksquare Analogously compute y_1 and y_2 with G_{hor} .

For each vertex v of G, let $R(v) = [x_1(v), x_2(v)] \times [y_1(v), y_2(v)]$.



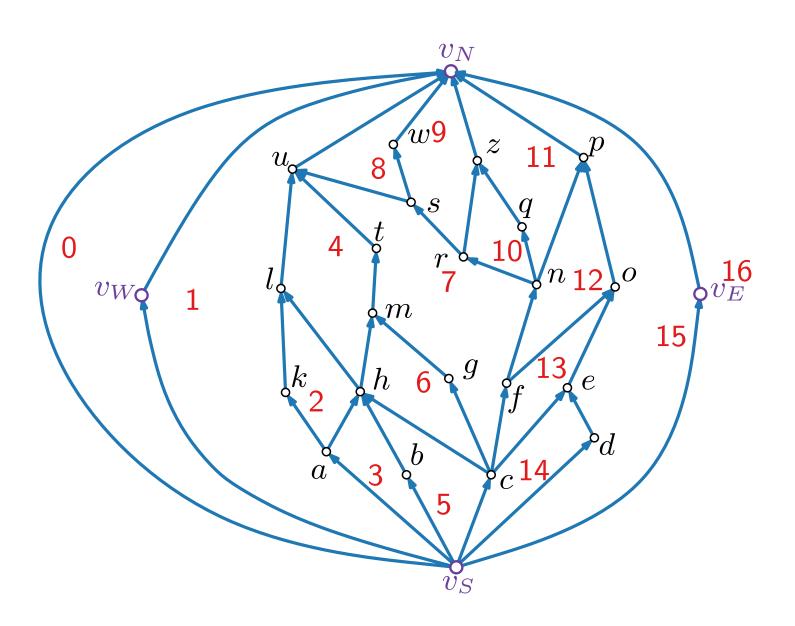
$$x_1(v_N) = 0, \ x_2(v_N) = 15$$





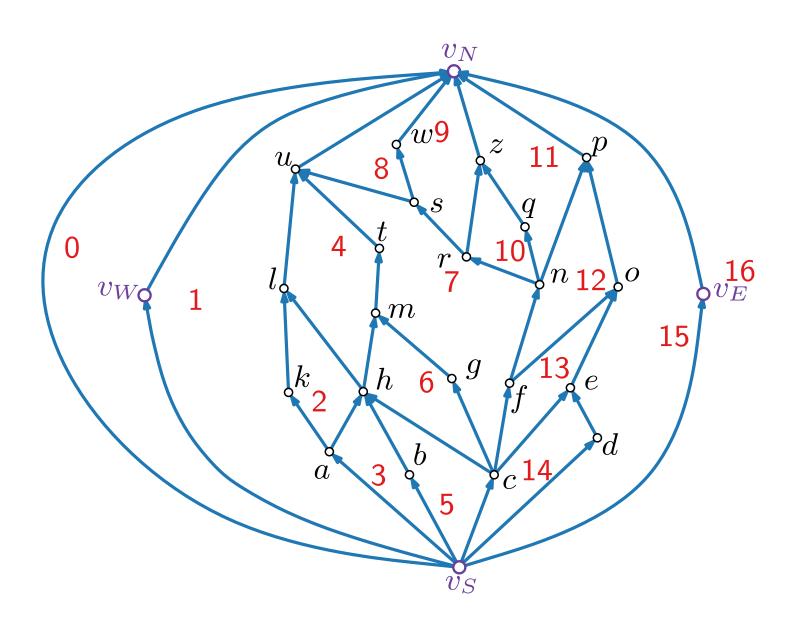
$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$



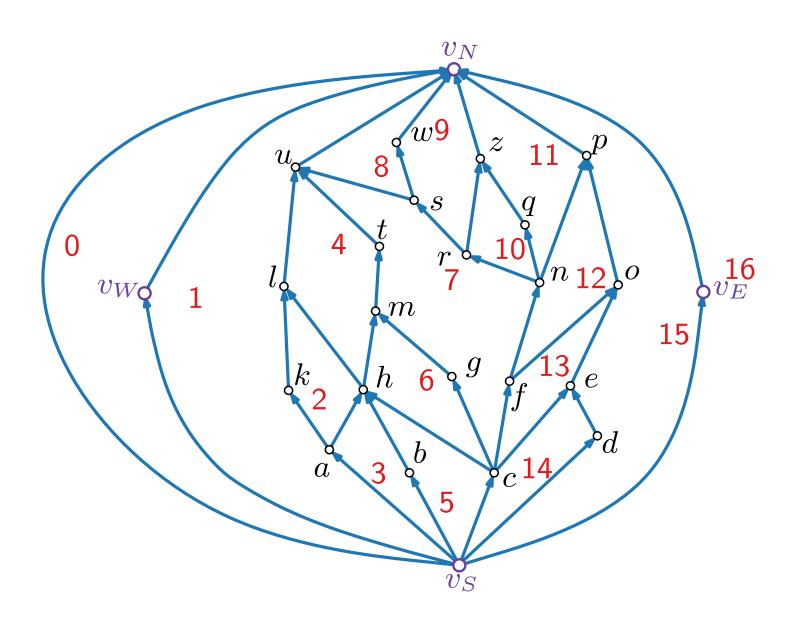
$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$



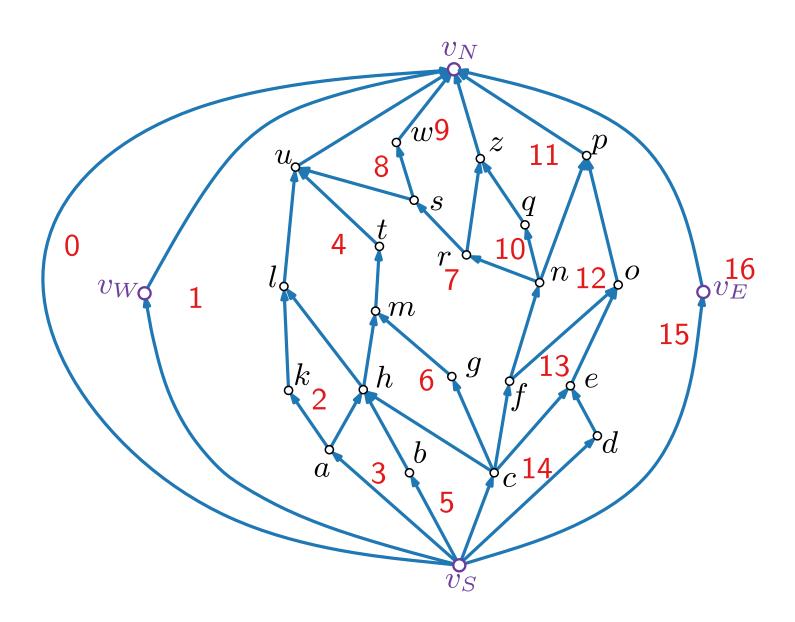
$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$

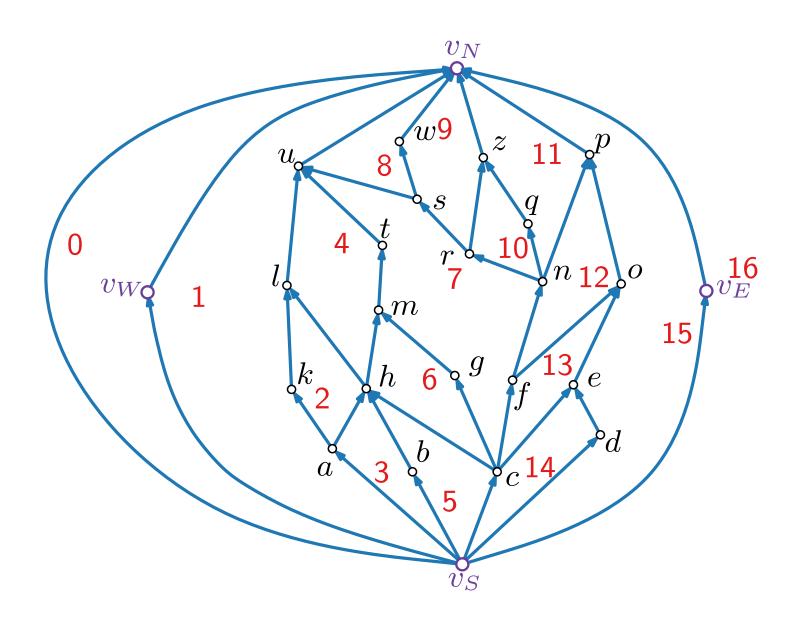


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

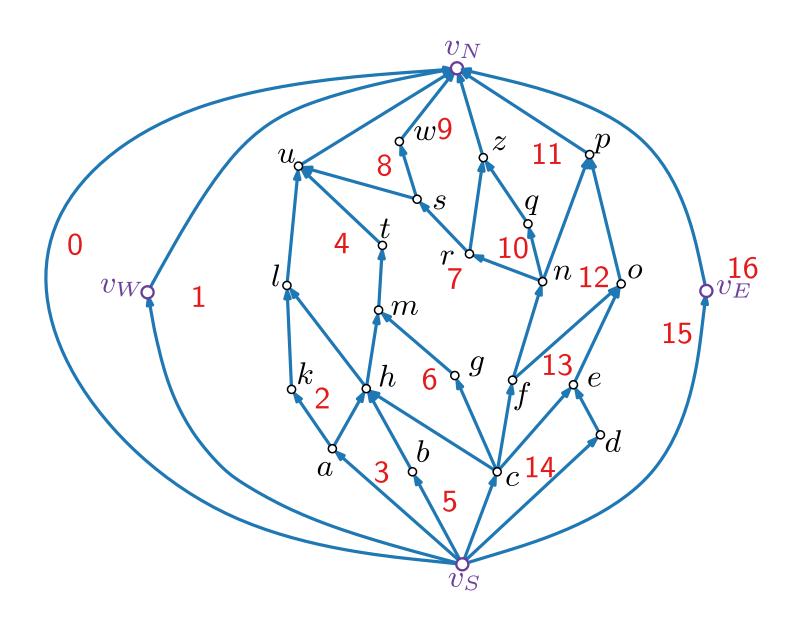
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$



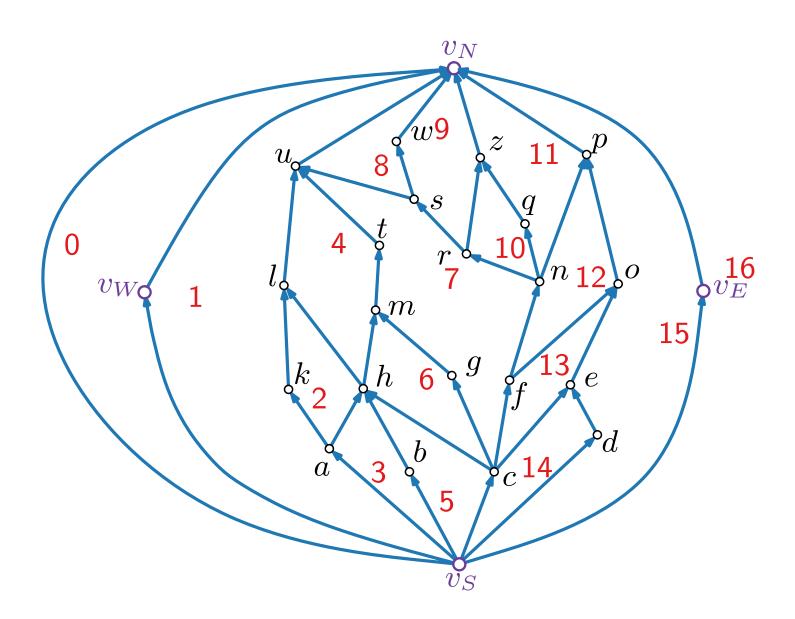
$$x_1(v_N) = 0, \ x_2(v_N) = 15$$
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$



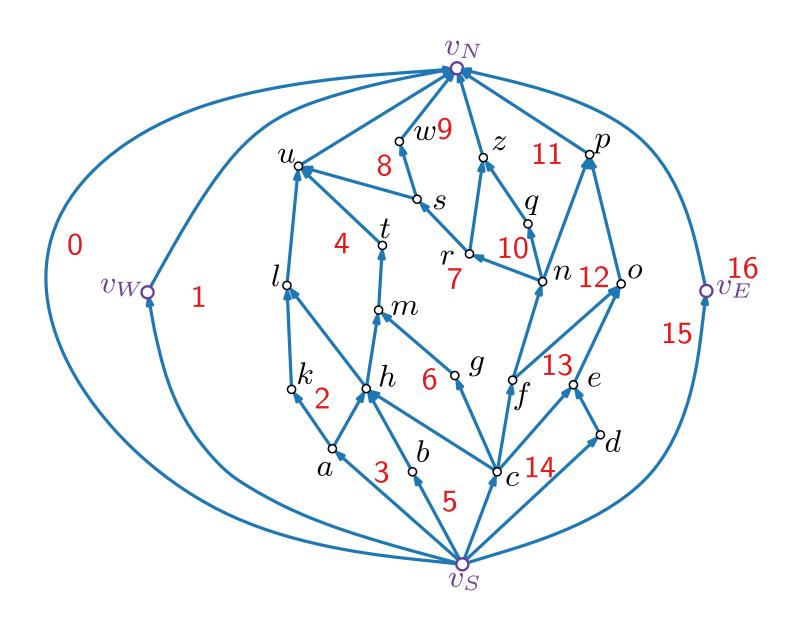
$$x_1(v_N) = 0, \ x_2(v_N) = 15$$
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$

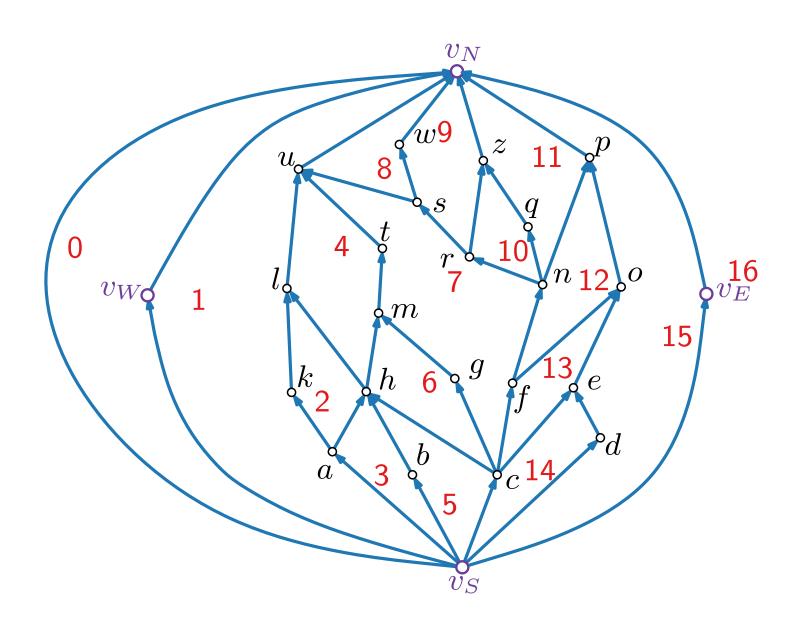


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

```
10
5
```

```
x_1(v_N) = 0, \ x_2(v_N) = 15

x_1(v_S) = 1, \ x_2(v_S) = 16

x_1(v_W) = 0, x_2(v_W) = 1

x_1(v_E) = 15, \ x_2(v_E) = 16

x_1(a) = 1, \ x_2(a) = 3

x_1(b) = 3, \ x_2(b) = 5

x_1(c) = 5, \ x_2(c) = 14

x_1(d) = 14, \ x_2(d) = 15

x_1(e) = 13, \ x_2(e) = 15
```

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

. .

```
10
5
```

```
x_1(v_N) = 0, \ x_2(v_N) = 15

x_1(v_S) = 1, \ x_2(v_S) = 16

x_1(v_W) = 0, x_2(v_W) = 1

x_1(v_E) = 15, \ x_2(v_E) = 16

x_1(a) = 1, \ x_2(a) = 3

x_1(b) = 3, \ x_2(b) = 5

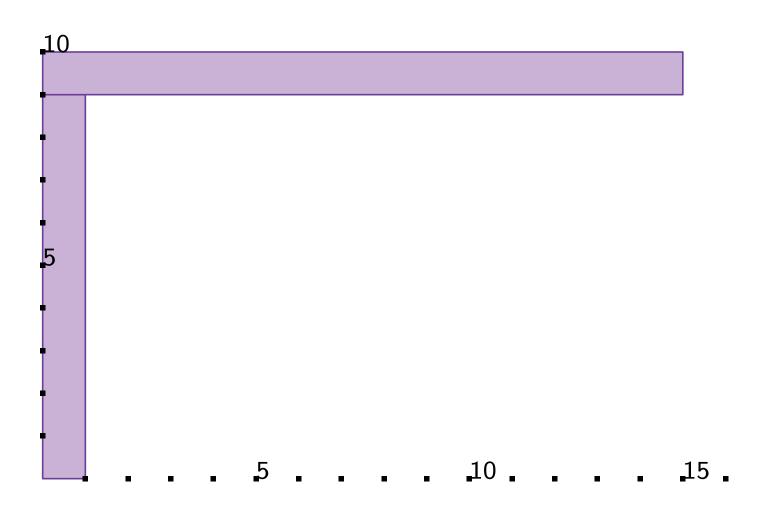
x_1(c) = 5, \ x_2(c) = 14

x_1(d) = 14, \ x_2(d) = 15

x_1(e) = 13, \ x_2(e) = 15
```

 $y_1(v_W) = 0, y_2(v_W) = 9$ $y_1(v_E) = 1, y_2(v_E) = 10$ $y_1(v_N) = 9, y_2(v_N) = 10$ $y_1(v_S) = 0, y_2(v_S) = 1$ $y_1(a) = 1, y_2(a) = 2$ $y_1(b) = 1, y_2(b) = 2$

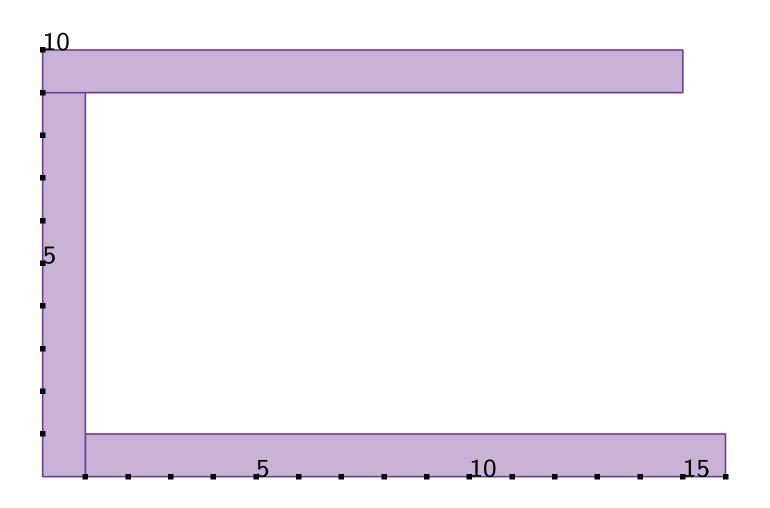
. .



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$
 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

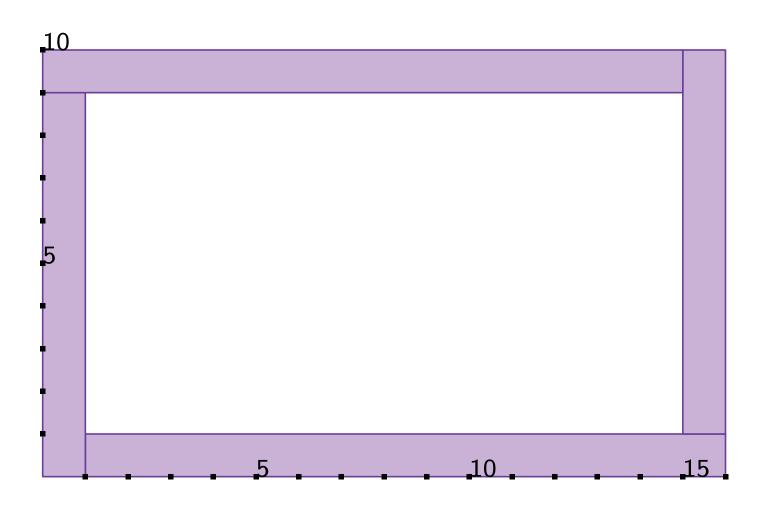


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

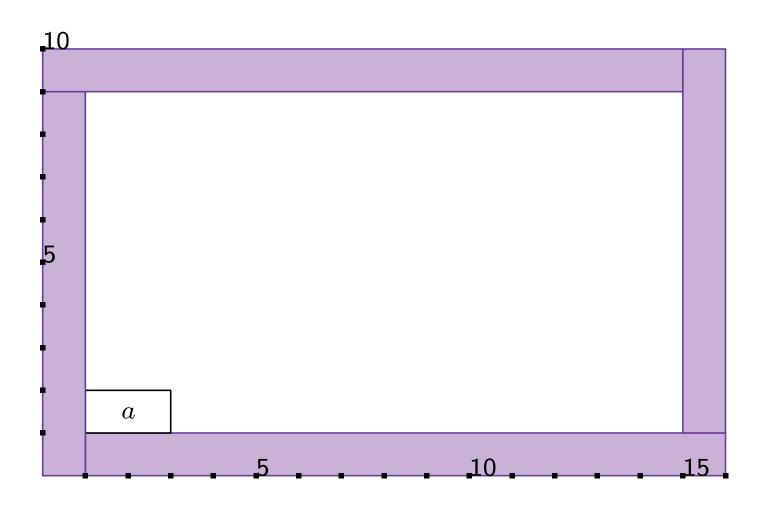


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

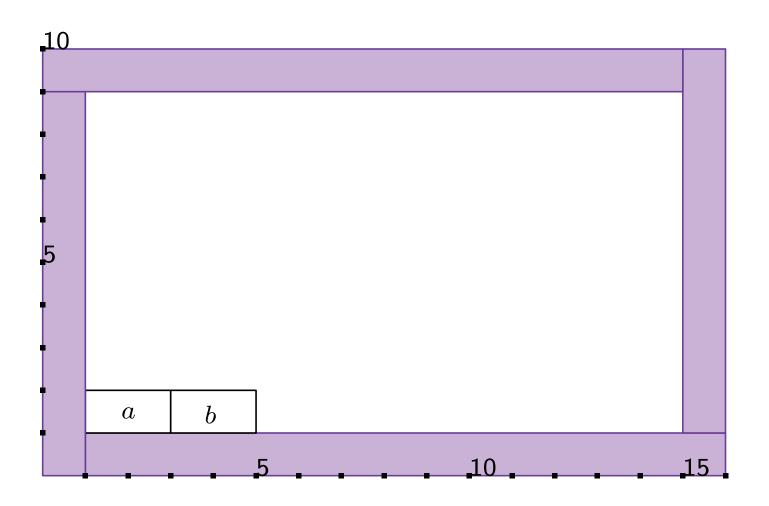


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

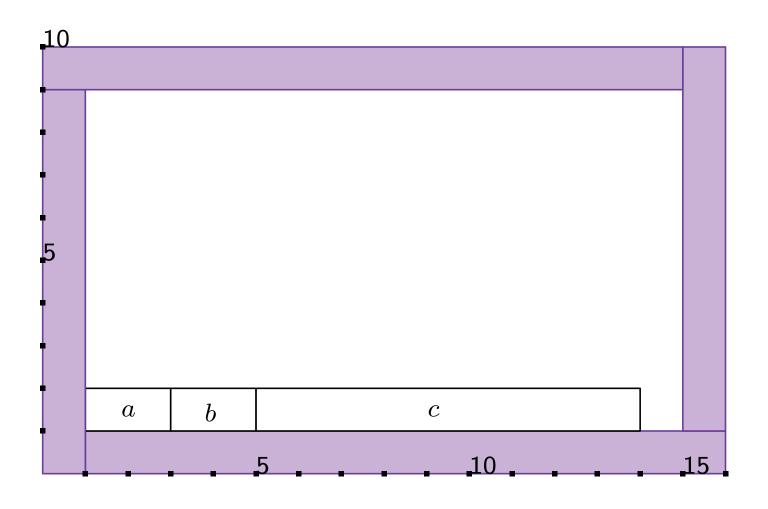
 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

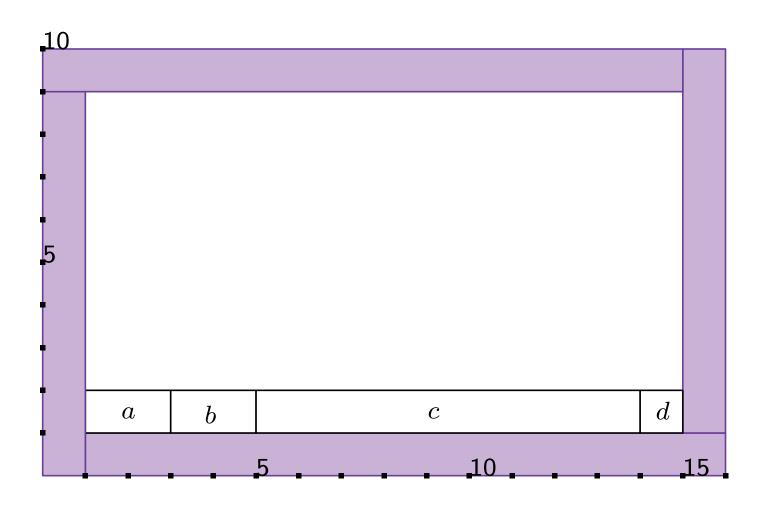
 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

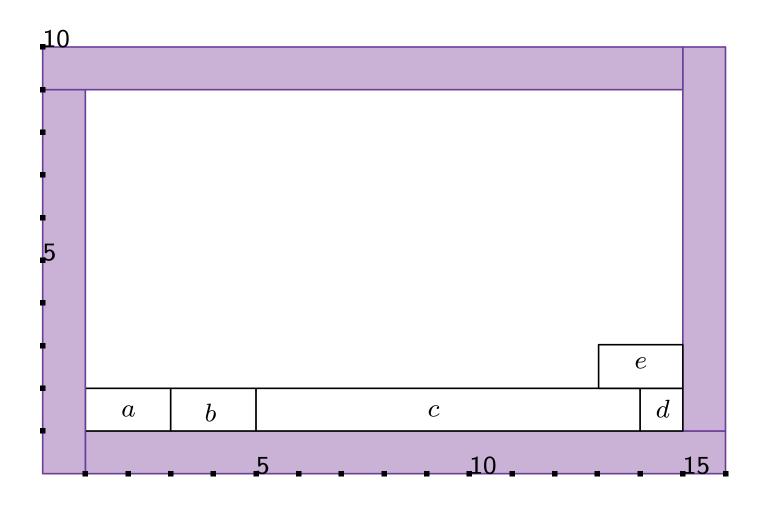
 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$



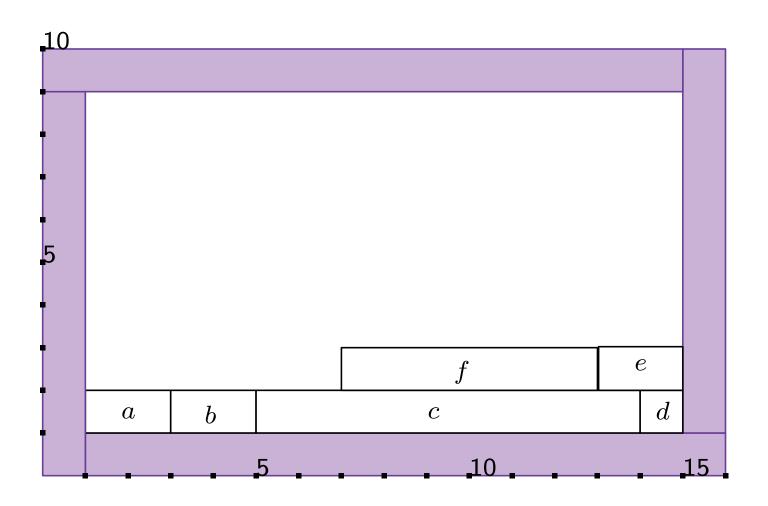
$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

. .

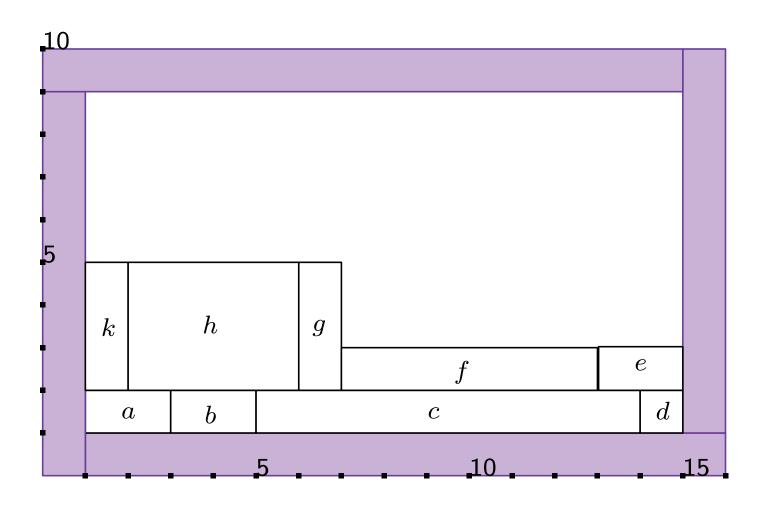


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

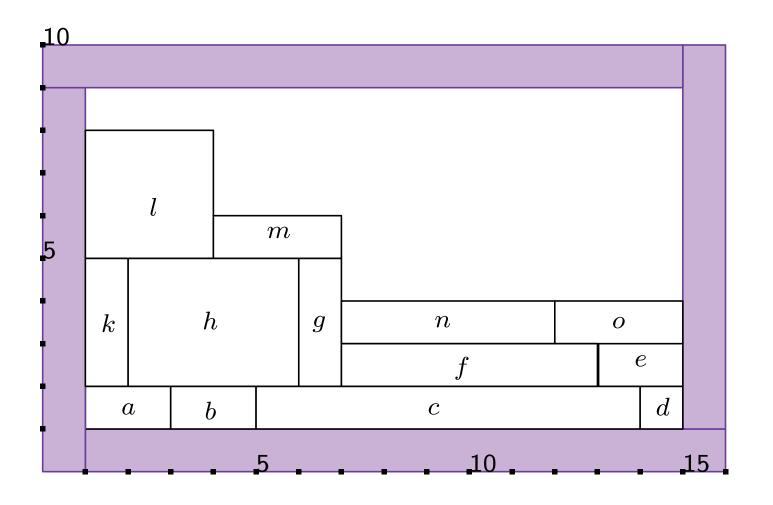


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

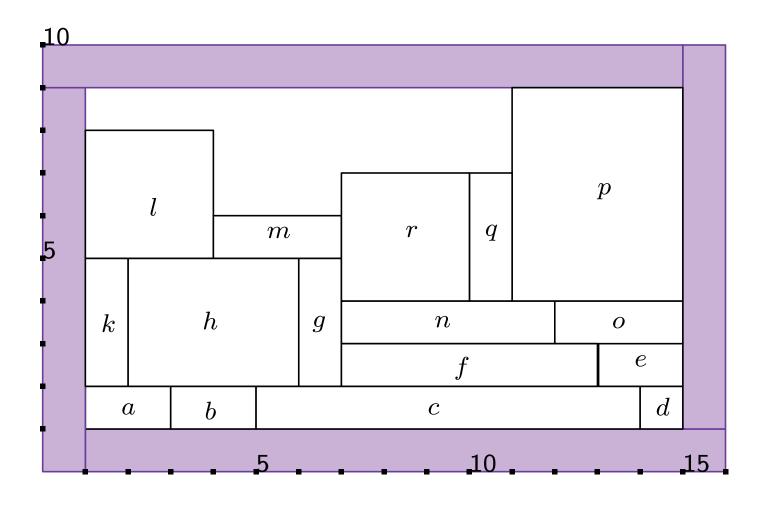
 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

 $y_1(v_W) = 0, y_2(v_W) = 9$ $y_1(v_E) = 1, y_2(v_E) = 10$ $y_1(v_N) = 9, y_2(v_N) = 10$ $y_1(v_S) = 0, y_2(v_S) = 1$ $y_1(a) = 1, y_2(a) = 2$ $y_1(b) = 1, y_2(b) = 2$

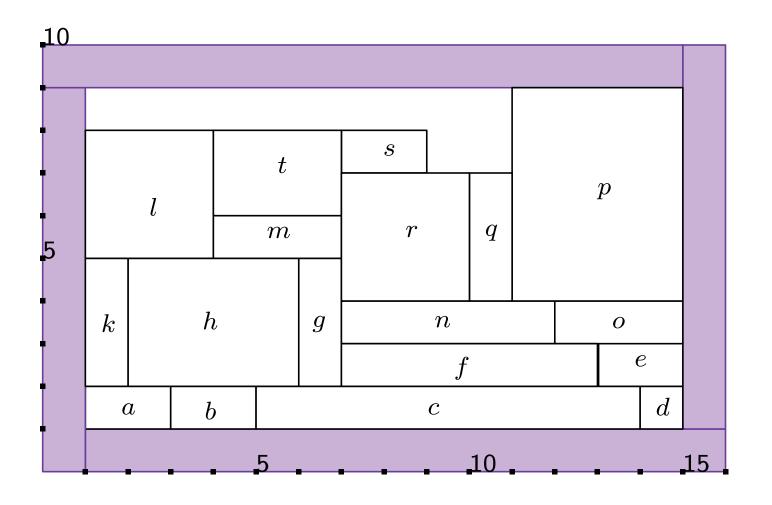


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$

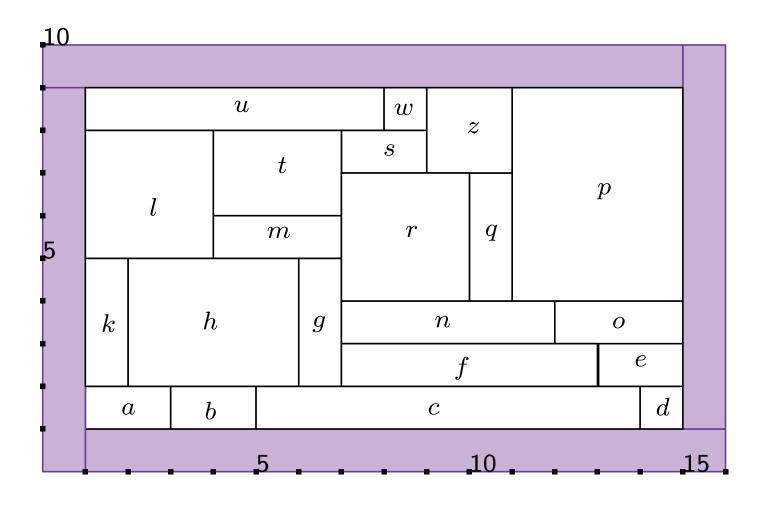


$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

$$y_1(v_W) = 0, y_2(v_W) = 9$$

 $y_1(v_E) = 1, y_2(v_E) = 10$
 $y_1(v_N) = 9, y_2(v_N) = 10$
 $y_1(v_S) = 0, y_2(v_S) = 1$
 $y_1(a) = 1, y_2(a) = 2$
 $y_1(b) = 1, y_2(b) = 2$



$$x_1(v_N) = 0, \ x_2(v_N) = 15$$

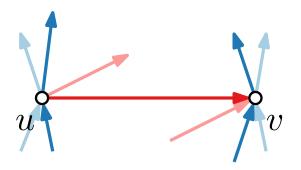
 $x_1(v_S) = 1, \ x_2(v_S) = 16$
 $x_1(v_W) = 0, x_2(v_W) = 1$
 $x_1(v_E) = 15, \ x_2(v_E) = 16$
 $x_1(a) = 1, \ x_2(a) = 3$
 $x_1(b) = 3, \ x_2(b) = 5$
 $x_1(c) = 5, \ x_2(c) = 14$
 $x_1(d) = 14, \ x_2(d) = 15$
 $x_1(e) = 13, \ x_2(e) = 15$

 $y_1(v_W) = 0, y_2(v_W) = 9$ $y_1(v_E) = 1, y_2(v_E) = 10$ $y_1(v_N) = 9, y_2(v_N) = 10$ $y_1(v_S) = 0, y_2(v_S) = 1$ $y_1(a) = 1, y_2(a) = 2$ $y_1(b) = 1, y_2(b) = 2$

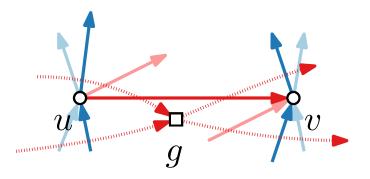
If edge (u, v) exists, then $x_2(u) = x_1(v)$



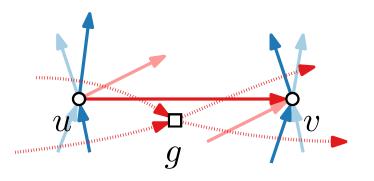
If edge (u, v) exists, then $x_2(u) = x_1(v)$



■ If edge (u, v) exists, then $x_2(u) = x_1(v)$

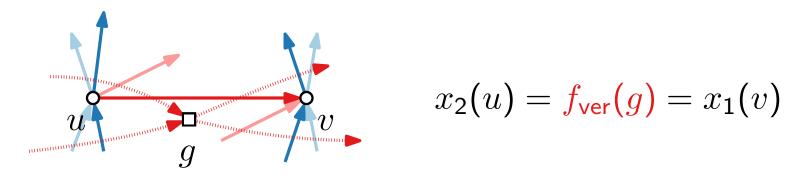


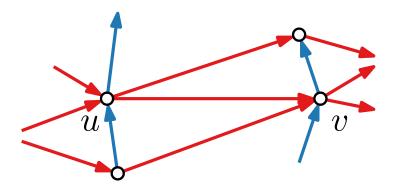
■ If edge (u, v) exists, then $x_2(u) = x_1(v)$



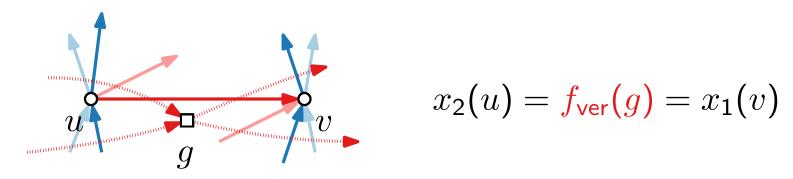
$$x_2(u) = f_{\text{ver}}(g) = x_1(v)$$

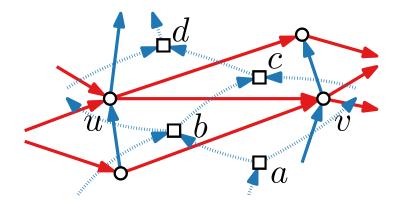
■ If edge (u, v) exists, then $x_2(u) = x_1(v)$



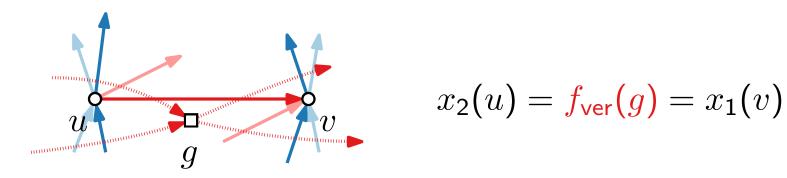


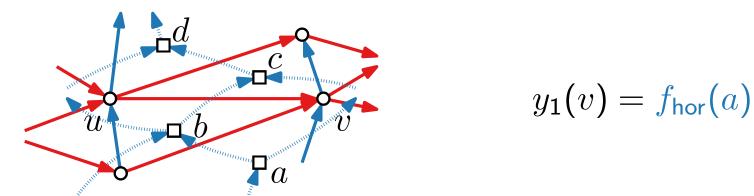
If edge (u, v) exists, then $x_2(u) = x_1(v)$



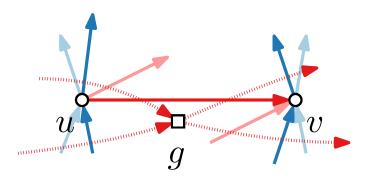


If edge (u, v) exists, then $x_2(u) = x_1(v)$

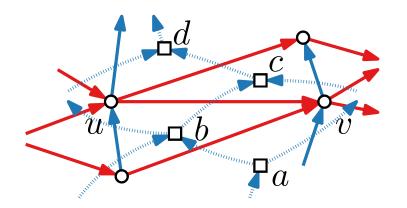




■ If edge (u, v) exists, then $x_2(u) = x_1(v)$

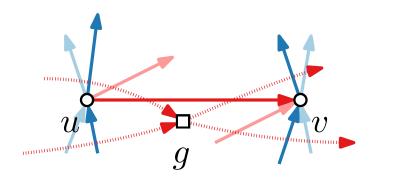


$$x_2(u) = f_{\text{ver}}(g) = x_1(v)$$



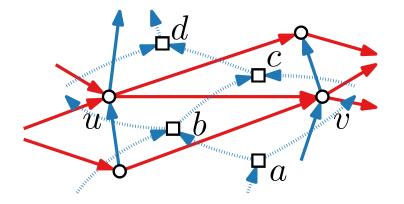
$$y_1(v) = f_{\text{hor}}(a) \le y_1(u) = f_{\text{hor}}(b)$$

If edge (u, v) exists, then $x_2(u) = x_1(v)$



$$x_2(u) = f_{\text{ver}}(g) = x_1(v)$$

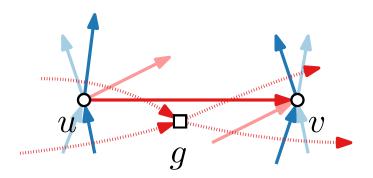
...and the vertical segments of their rectangles overlap.



$$y_1(v) = f_{hor}(a) \le y_1(u) = f_{hor}(b)$$

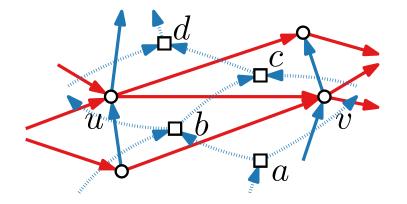
< $y_2(v) = f_{hor}(c)$

If edge (u, v) exists, then $x_2(u) = x_1(v)$



$$x_2(u) = f_{\text{ver}}(g) = x_1(v)$$

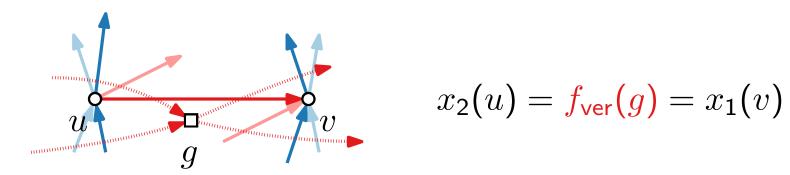
...and the vertical segments of their rectangles overlap.



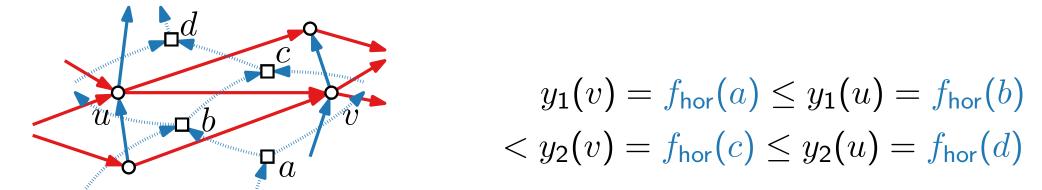
$$y_1(v) = f_{\text{hor}}(a) \le y_1(u) = f_{\text{hor}}(b)$$

$$< y_2(v) = f_{hor}(c) \le y_2(u) = f_{hor}(d)$$

If edge (u, v) exists, then $x_2(u) = x_1(v)$

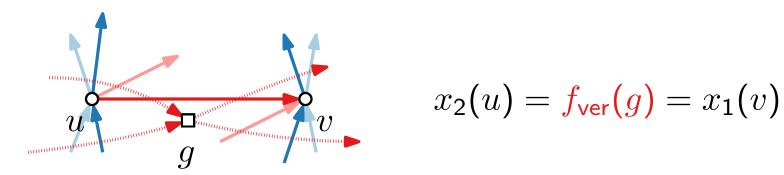


...and the vertical segments of their rectangles overlap.

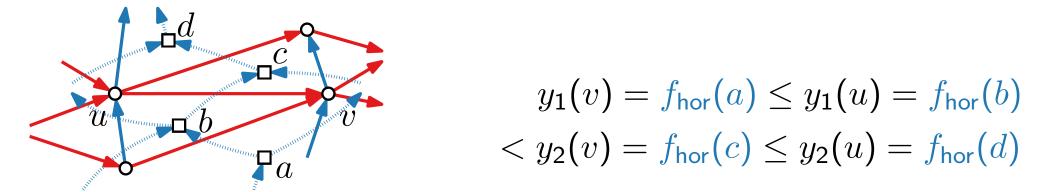


■ If the path from u to v in red is at least two edges long, then $x_2(u) < x_1(v)$.

If edge (u, v) exists, then $x_2(u) = x_1(v)$

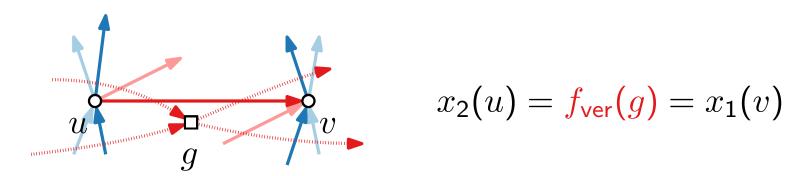


...and the vertical segments of their rectangles overlap.

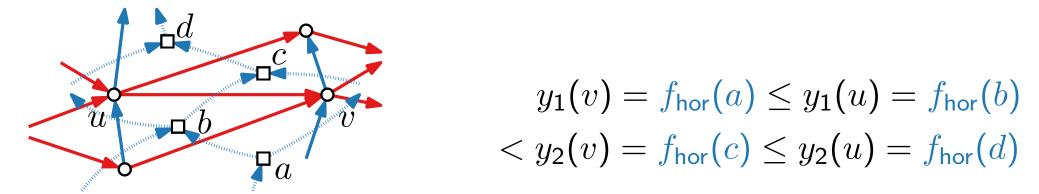


- If the path from u to v in red is at least two edges long, then $x_2(u) < x_1(v)$.
- No two boxes overlap.

If edge (u, v) exists, then $x_2(u) = x_1(v)$



...and the vertical segments of their rectangles overlap.



- If the path from u to v in red is at least two edges long, then $x_2(u) < x_1(v)$.
- No two boxes overlap.
- For details, see [He '93].

Theorem.

Every PTP graph G has a rectangular dual.

A rectangular dual can be computed in linear time.

Theorem.

Every PTP graph G has a rectangular dual. A rectangular dual can be computed in linear time.

Proof.

 \blacksquare Compute a planar embedding of G.

Theorem.

Every PTP graph G has a rectangular dual. A rectangular dual can be computed in linear time.

- \blacksquare Compute a planar embedding of G.
- \blacksquare Compute a refined canonical ordering of G.

Theorem.

Every PTP graph G has a rectangular dual. A rectangular dual can be computed in linear time.

- \blacksquare Compute a planar embedding of G.
- lacksquare Compute a refined canonical ordering of G.
- lacktriangle Traverse the graph and color the edges. ightarrow REL

Theorem.

Every PTP graph G has a rectangular dual. A rectangular dual can be computed in linear time.

- \blacksquare Compute a planar embedding of G.
- lacksquare Compute a refined canonical ordering of G.
- lacktriangle Traverse the graph and color the edges. ightarrow REL
- lacksquare Construct G_{ver} and G_{hor} .

Theorem.

Every PTP graph G has a rectangular dual. A rectangular dual can be computed in linear time.

- \blacksquare Compute a planar embedding of G.
- lacksquare Compute a refined canonical ordering of G.
- lacktriangle Traverse the graph and color the edges. ightarrow REL
- \blacksquare Construct G_{ver} and G_{hor} .
- \blacksquare Construct their duals G_{ver}^{\star} and G_{hor}^{\star} .

Theorem.

Every PTP graph G has a rectangular dual. A rectangular dual can be computed in linear time.

- \blacksquare Compute a planar embedding of G.
- \blacksquare Compute a refined canonical ordering of G.
- lacktriangle Traverse the graph and color the edges. ightarrow REL
- lacksquare Construct G_{ver} and G_{hor} .
- \blacksquare Construct their duals G_{ver}^{\star} and G_{hor}^{\star} .
- lacktriangle Compute topological orderings of $G_{
 m ver}^{\star}$ and $G_{
 m hor}^{\star}$.

Theorem.

Every PTP graph G has a rectangular dual. A rectangular dual can be computed in linear time.

- \blacksquare Compute a planar embedding of G.
- \blacksquare Compute a refined canonical ordering of G.
- $lue{}$ Traverse the graph and color the edges. ightarrow REL
- \blacksquare Construct G_{ver} and G_{hor} .
- \blacksquare Construct their duals G_{ver}^{\star} and G_{hor}^{\star} .
- lacktriangle Compute topological orderings of G_{ver}^{\star} and G_{hor}^{\star} .
- Assign coordinates to the rectangles representing vertices.

■ A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.

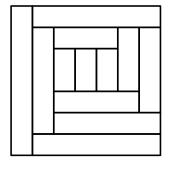
- A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.
- A rectangular layout is area-universal if and only if it is one-sided. [Eppstein et al., SIAM J. Comp. 2012]

- A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.
- A rectangular layout is area-universal if and only if it is one-sided. [Eppstein et al., SIAM J. Comp. 2012]

- A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.
- A rectangular layout is area-universal if and only if it is one-sided.

[Eppstein et al., SIAM J. Comp. 2012]

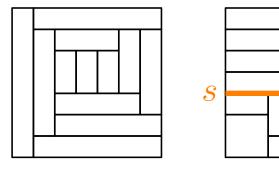
one-sided



- A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.
- A rectangular layout is area-universal if and only if it is one-sided.

[Eppstein et al., SIAM J. Comp. 2012]

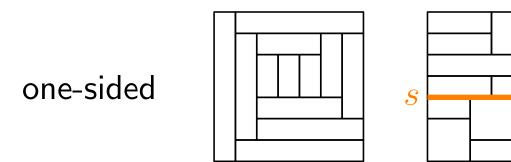
one-sided



not one-sided

- A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.
- A rectangular layout is area-universal if and only if it is one-sided.

[Eppstein et al., SIAM J. Comp. 2012]



not one-sided

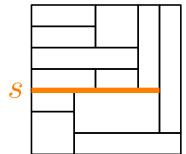
i.e., every segment belongs to exactly one rectangle

Area-universal rectlinear representation: possible for all planar graphs.

- A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.
- A rectangular layout is area-universal if and only if it is one-sided.

[Eppstein et al., SIAM J. Comp. 2012]

one-sided



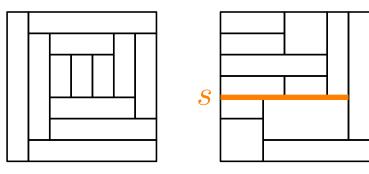
not one-sided

- Area-universal rectlinear representation: possible for all planar graphs.
- [Alam et al. 2013]: 8 sides (matches the lower bound)

- A layout is area-universal if any assignment of areas to rectangles can be realized by a combinatorially equivalent rectangular layout.
- A rectangular layout is area-universal if and only if it is one-sided.

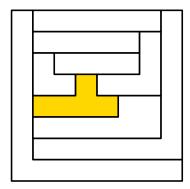
[Eppstein et al., SIAM J. Comp. 2012]

one-sided



not one-sided

- Area-universal rectlinear representation: possible for all planar graphs.
- [Alam et al. 2013]: 8 sides (matches the lower bound)



Literature

Construction of triangle contact representations based on

■ [de Fraysseix, Ossona de Mendez, Rosenstiehl '94] On Triangle Contact Graphs

Construction of rectangular dual based on

- [He '93] On Finding the Rectangular Duals of Planar Triangulated Graphs
- [Kant, He '94] Two algorithms for finding rectangular duals of planar graphs and originally from
- [Koźmiński, Kinnen '85] Rectangular Duals of Planar Graphs