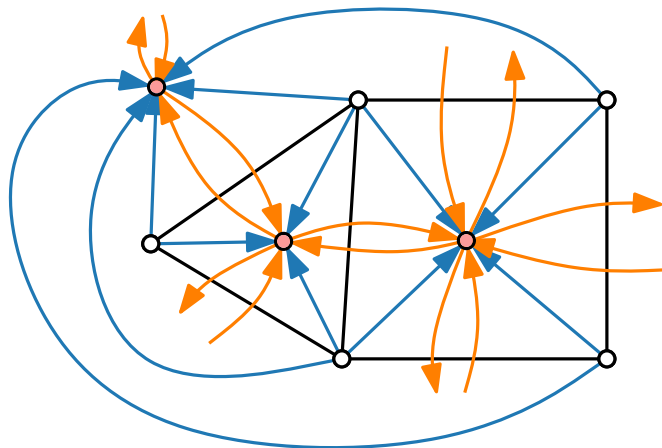
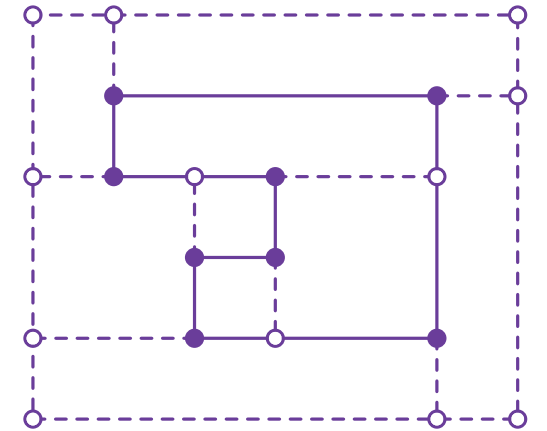
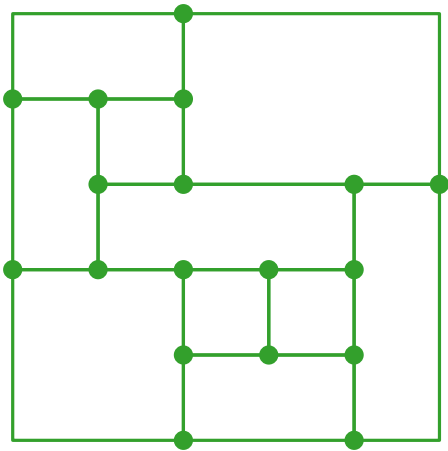


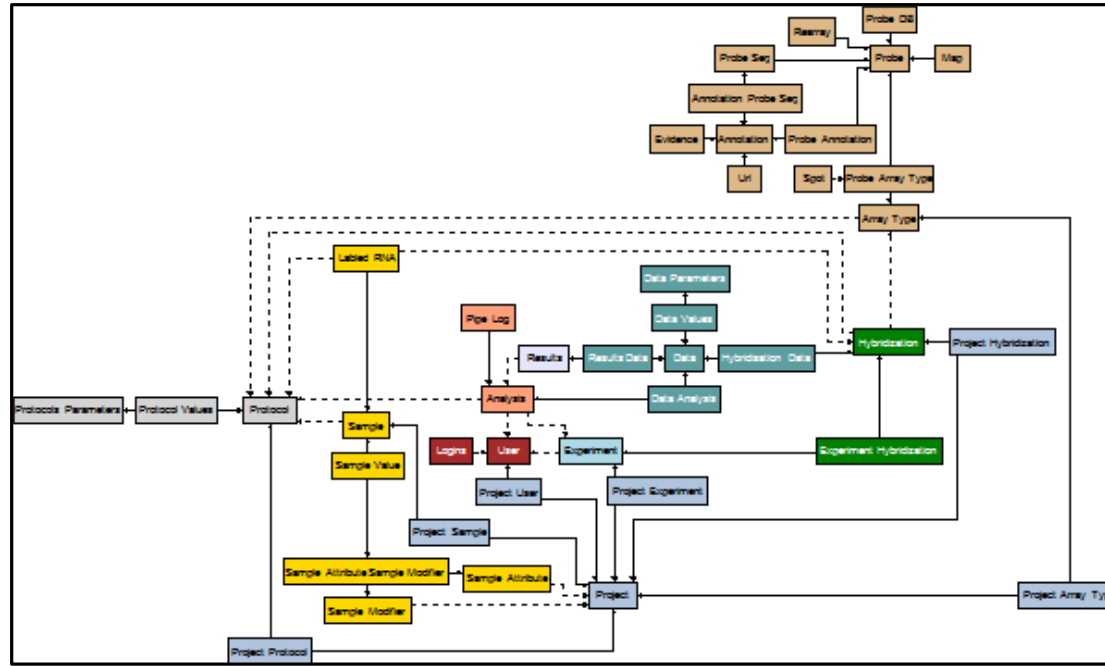
Visualization of Graphs

Lecture 6: Orthogonal Layouts

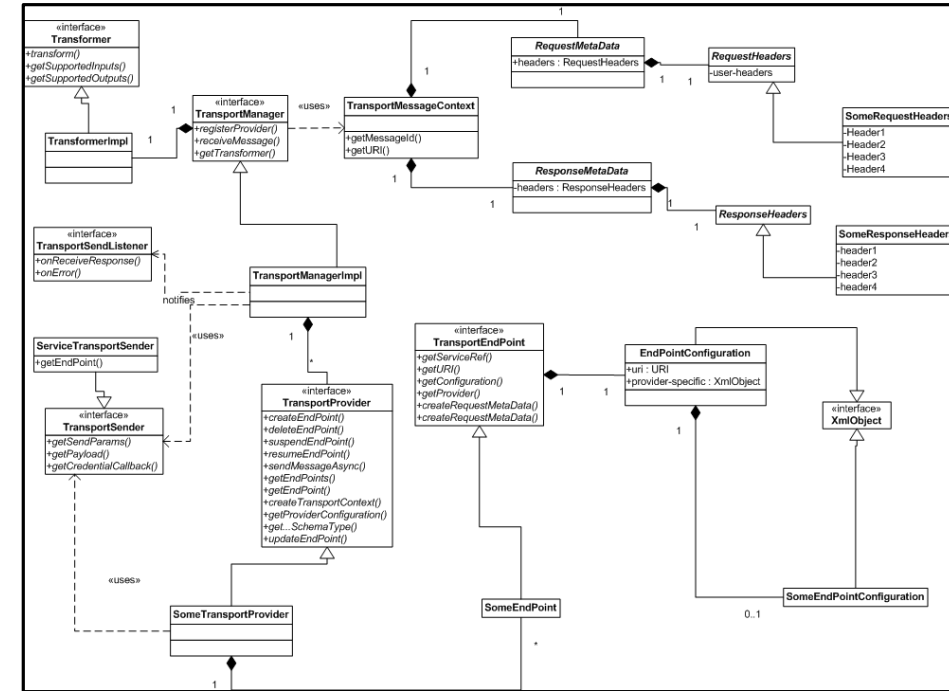


Alexander Wolff

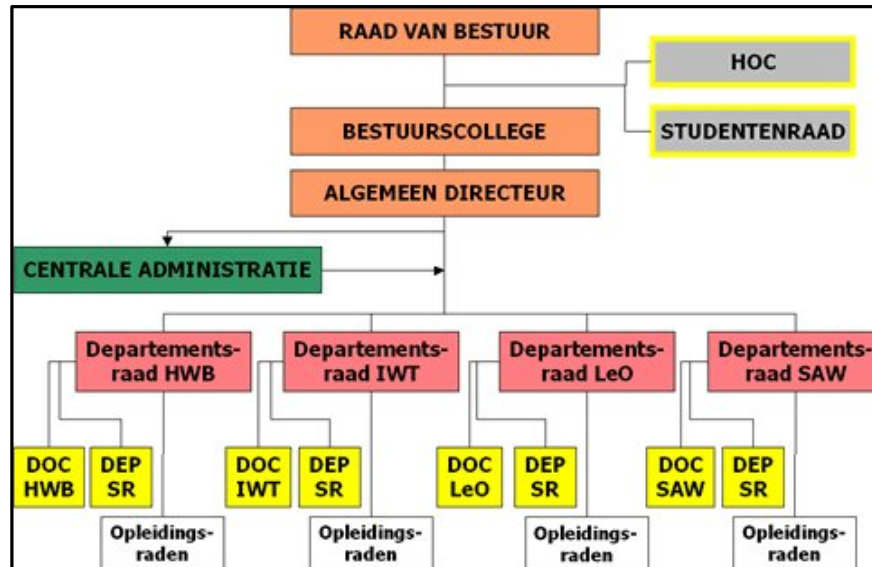
Summer term 2025



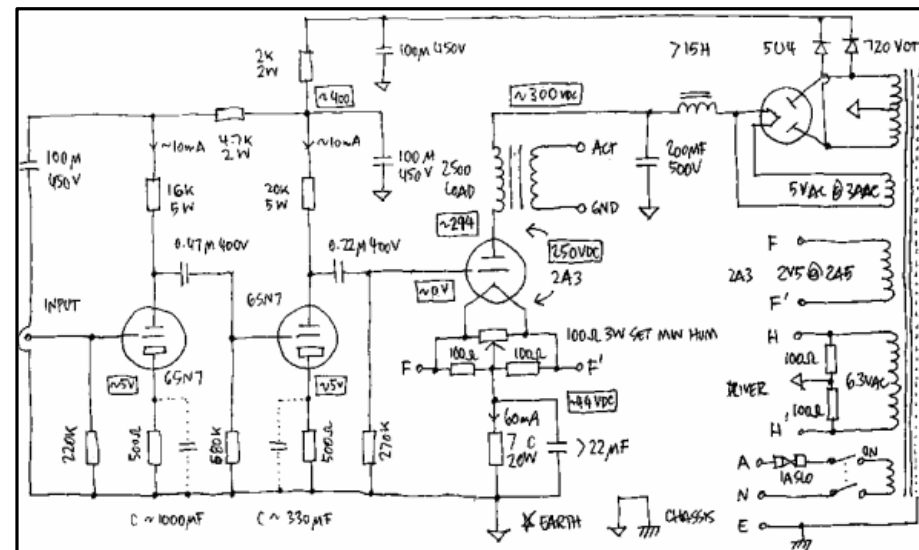
Entity-Relationship (ER) diagram in OGDF



UML diagram by Oracle

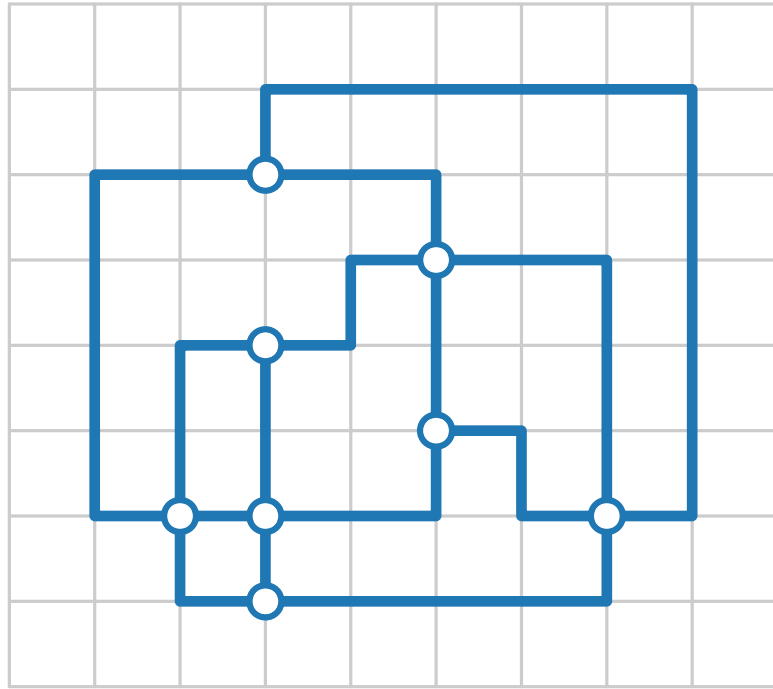


Organigram of HS Limburg



Circuit diagram by Jeff Atwood

Orthogonal Layout – Definition



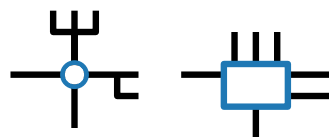
Definition.

A drawing Γ of a graph G is called **orthogonal** if

- vertices are drawn as points on a grid,
- each edge is represented as a sequence of alternating horizontal and vertical line segments of the grid, and
- pairs of edges are disjoint or cross orthogonally.

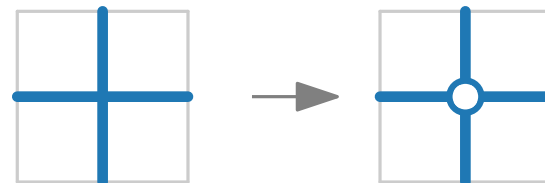
Observations.

- Edges lie on a grid \Rightarrow **bends** lie on grid points
- Max. degree of each vertex is at most 4
- Otherwise



Planarization.

- Fix embedding
- Crossings become vertices



Aesthetic criteria to optimize.

- Number of bends
- Length of edges
- Width, height, area
- Monotonicity of edges
- ...

Topology – Shape – Metrics

Three-step approach:

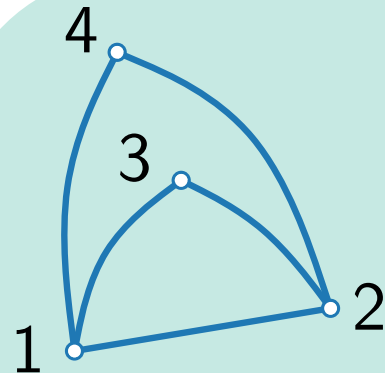
[Tamassia 1987]

$$V(G) = \{v_1, v_2, v_3, v_4\}$$

$$E(G) = \{v_1v_2, v_1v_3, v_1v_4, v_2v_3, v_2v_4\}$$

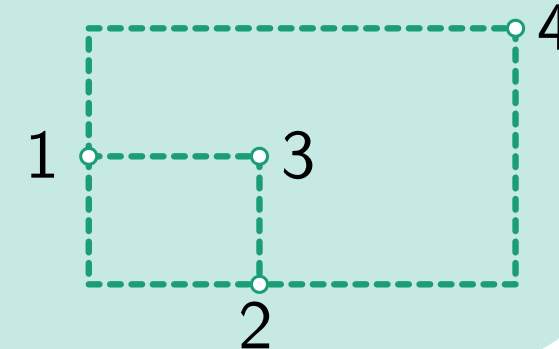
reduce
crossings

combinatorial
embedding/
planarization

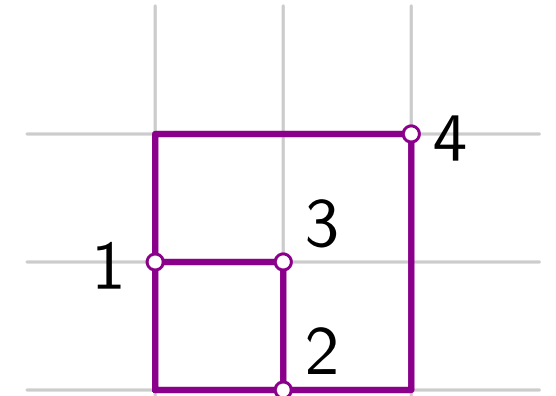


bend minimization

orthogonal
representation



planar
orthogonal
drawing



area mini-
mization

TOPOLOGY

—

SHAPE

—

METRICS

Orthogonal Representation

Idea.

Describe orthogonal drawing combinatorially.

Definitions.

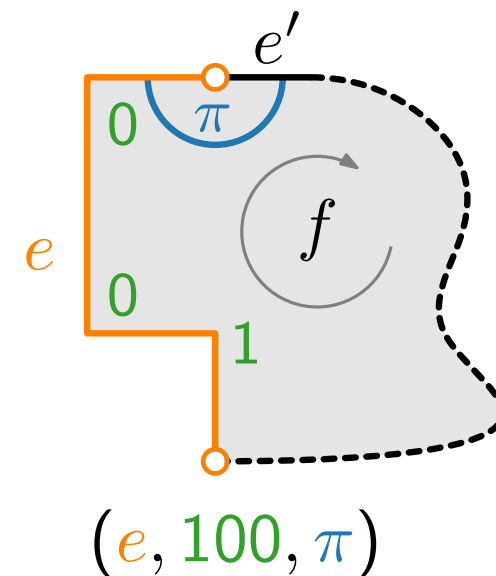
Let G be a plane graph with set F of faces and outer face $f_0 \in F$.

- Let e be an edge with the face f to the right.

An **edge description** of e w.r.t. f is a triple (e, δ, α) where

- $\delta \in \{0, 1\}^*$ (where 0 = right bend, 1 = left bend)
- α is angle $\in \{\frac{\pi}{2}, \pi, \frac{3\pi}{2}, 2\pi\}$ between e and next edge e'
- A **face representation** $H(f)$ of a face f is a clockwise ordered sequence $(e_1, \delta_1, \alpha_1), (e_2, \delta_2, \alpha_2), \dots, (e_{\deg(f)}, \delta_{\deg(f)}, \alpha_{\deg(f)})$ of edge descriptions w.r.t. f .
- An **orthogonal representation** $H(G)$ of G is defined as

$$H(G) = \{H(f) \mid f \in F\}.$$

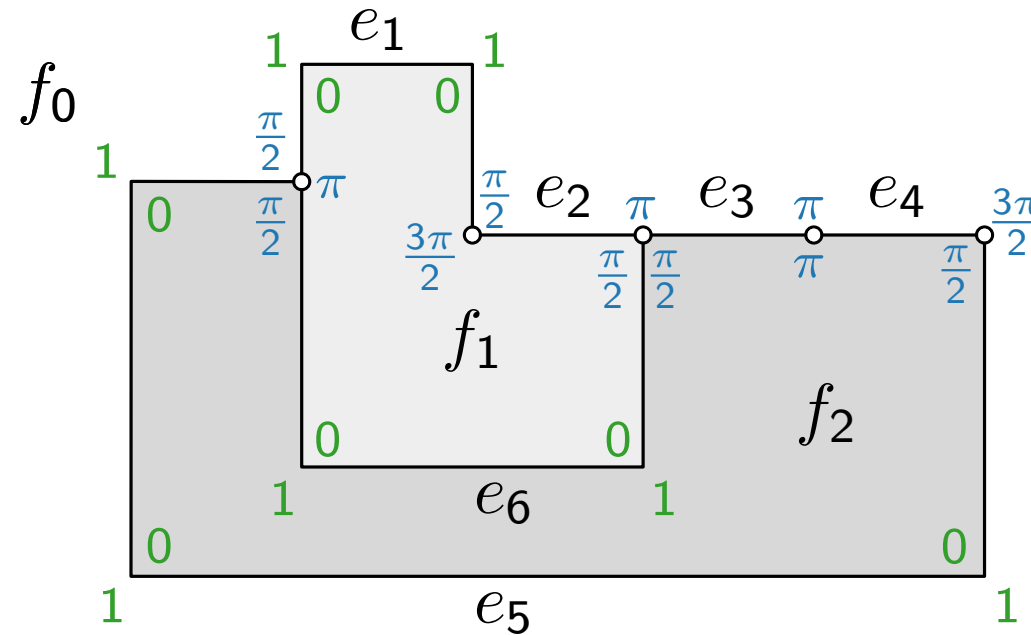
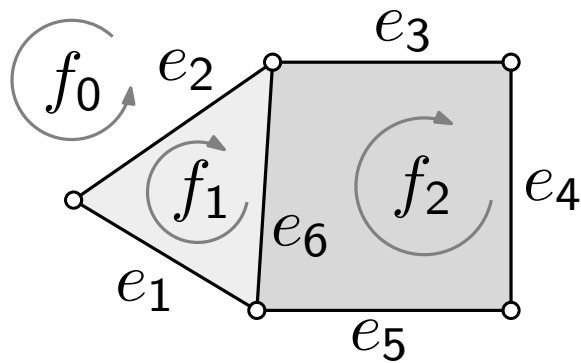


Orthogonal Representation – Example

$$H(f_0) = ((e_1, 11, \frac{\pi}{2}), (e_5, 111, \frac{3\pi}{2}), (e_4, \emptyset, \pi), (e_3, \emptyset, \pi), (e_2, \emptyset, \frac{\pi}{2}))$$

$$H(f_1) = ((e_1, 00, \frac{3\pi}{2}), (e_2, \emptyset, \frac{\pi}{2}), (e_6, 00, \pi))$$

$$H(f_2) = ((e_5, 000, \frac{\pi}{2}), (e_6, 11, \frac{\pi}{2}), (e_3, \emptyset, \pi), (e_4, \emptyset, \frac{\pi}{2}))$$



Coordinates are not fixed yet!

Correctness of an Orthogonal Representation

(H1) $H(G)$ corresponds to F, f_0 .

(H2) For each **edge** $\{u, v\}$ shared by faces f and g with $((u, v), \delta_1, \alpha_1) \in H(f)$ and $((v, u), \delta_2, \alpha_2) \in H(g)$, the sequence δ_1 is like δ_2 , but reversed and inverted.

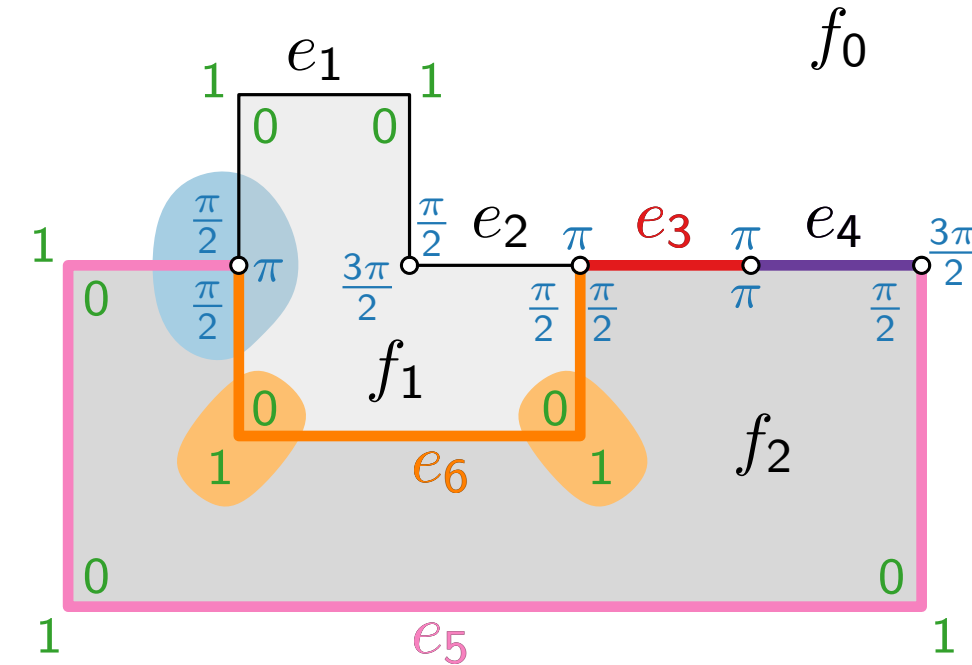
(H3) Let $|\delta|_0$ (resp. $|\delta|_1$) be the number of zeros (resp. ones) in δ , and let $r = (e, \delta, \alpha)$.

Let $C(r) := |\delta|_0 - |\delta|_1 - \alpha/\frac{\pi}{2} + 2$.

For each **face** f , it holds that:

$$\sum_{r \in H(f)} C(r) = \begin{cases} -4 & \text{if } f = f_0 \\ +4 & \text{otherwise.} \end{cases}$$

(H4) For each **vertex** v , the sum of incident angles is 2π .



$$C((e_3, \emptyset, \pi)) = 0 - 0 - 2 + 2 = 0$$

$$C((e_4, \emptyset, \frac{\pi}{2})) = 0 - 0 - 1 + 2 = 1$$

$$C((e_5, 000, \frac{\pi}{2})) = 3 - 0 - 1 + 2 = 4$$

$$C((e_6, 11, \frac{\pi}{2})) = 0 - 2 - 1 + 2 = -1$$

$$\sum_{r \in H(f_2)} C(r) = +4$$

Reminder: s - t Flow Networks

Flow network $(G; S, T; u)$ with

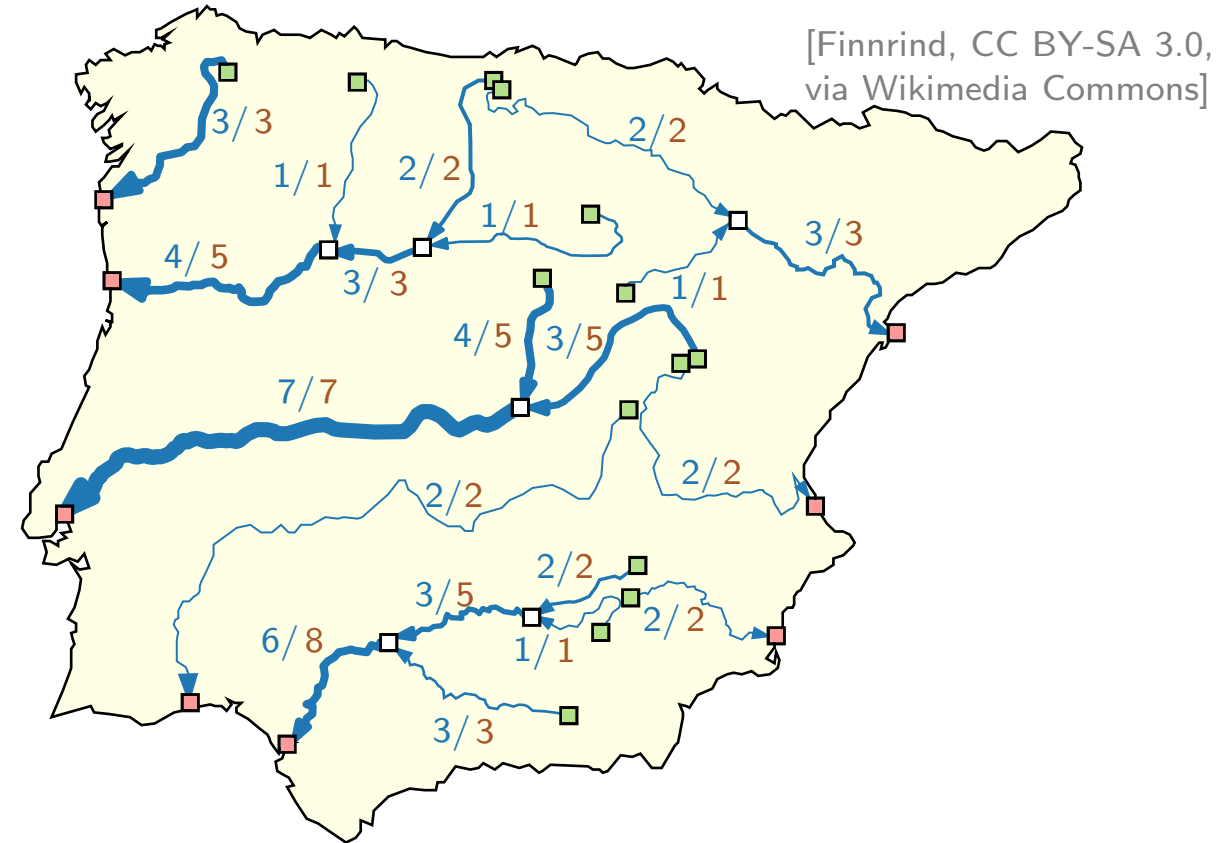
- directed graph G
- *sources* $S \subseteq V(G)$, *sinks* $T \subseteq V(G)$
- edge *capacity* $u: E(G) \rightarrow \mathbb{R}_0^+ \cup \{\infty\}$

A function $X: E(G) \rightarrow \mathbb{R}_0^+$ is called **S - T flow** if:

$$0 \leq X(i, j) \leq u(i, j) \quad \forall (i, j) \in E(G)$$

$$\sum_{(i,j) \in E(G)} X(i, j) - \sum_{(j,i) \in E(G)} X(j, i) = 0 \quad \forall i \in V(G) \setminus (S \cup T)$$

A **maximum S - T flow** is an S - T flow where $\sum_{(i,j) \in E(G), i \in S} X(i, j) - \sum_{(j,i) \in E(G), i \in S} X(j, i)$ is maximized.



Reminder: s - t Flow Networks

Flow network $(G; s, t; u)$ with

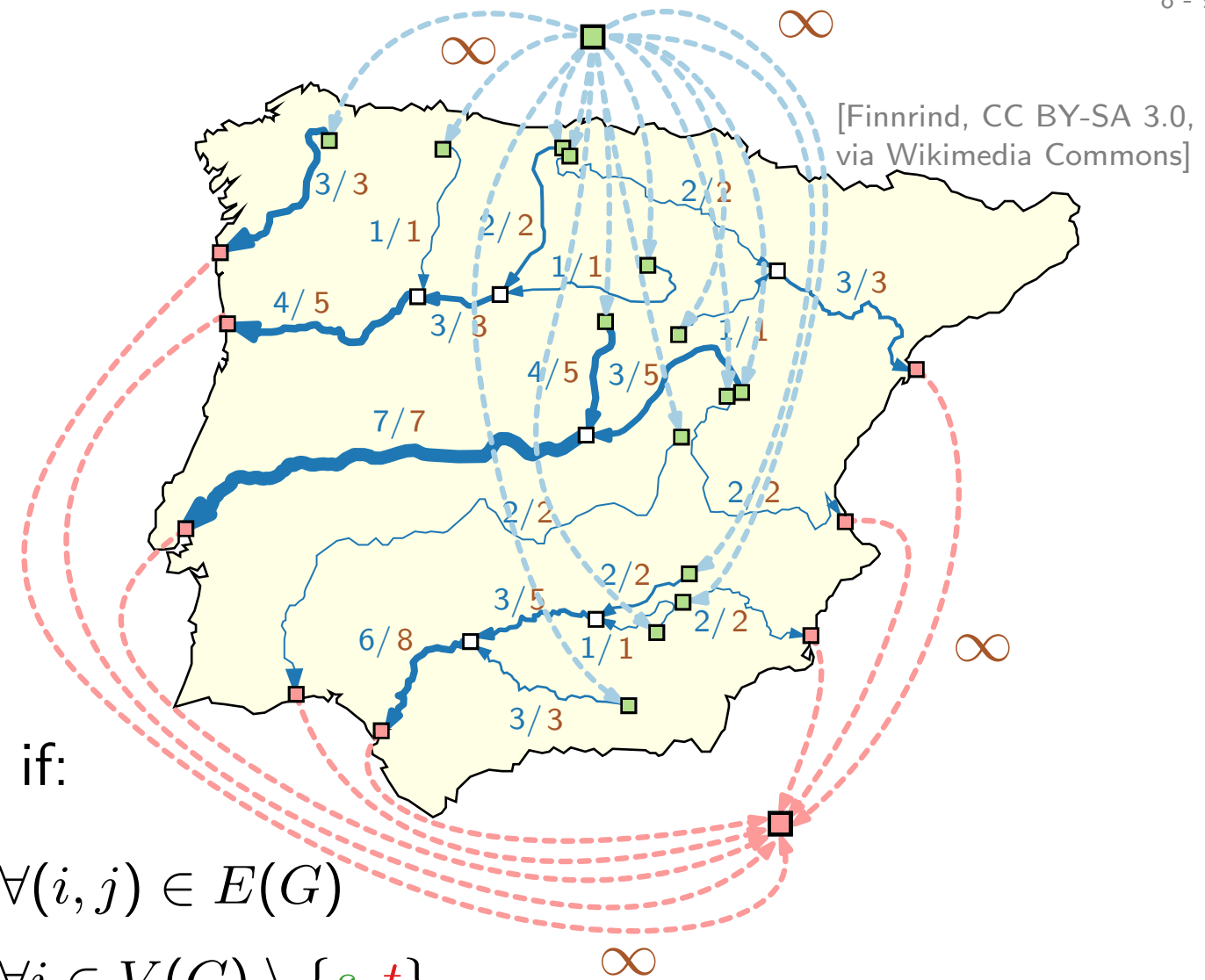
- directed graph G
- **source** $s \in V(G)$, **sink** $t \in V(G)$
- edge **capacity** $u: E(G) \rightarrow \mathbb{R}_0^+ \cup \{\infty\}$

A function $X: E(G) \rightarrow \mathbb{R}_0^+$ is called **s - t flow** if:

$$0 \leq X(i, j) \leq u(i, j) \quad \forall (i, j) \in E(G)$$

$$\sum_{(i,j) \in E(G)} X(i, j) - \sum_{(j,i) \in E(G)} X(j, i) = 0 \quad \forall i \in V(G) \setminus \{s, t\}$$

A **maximum** s - t flow is an s - t flow where $\sum_{(s,j) \in E(G)} X(s, j) - \sum_{(j,s) \in E(G)} X(j, s)$ is maximized.



General Flow Network

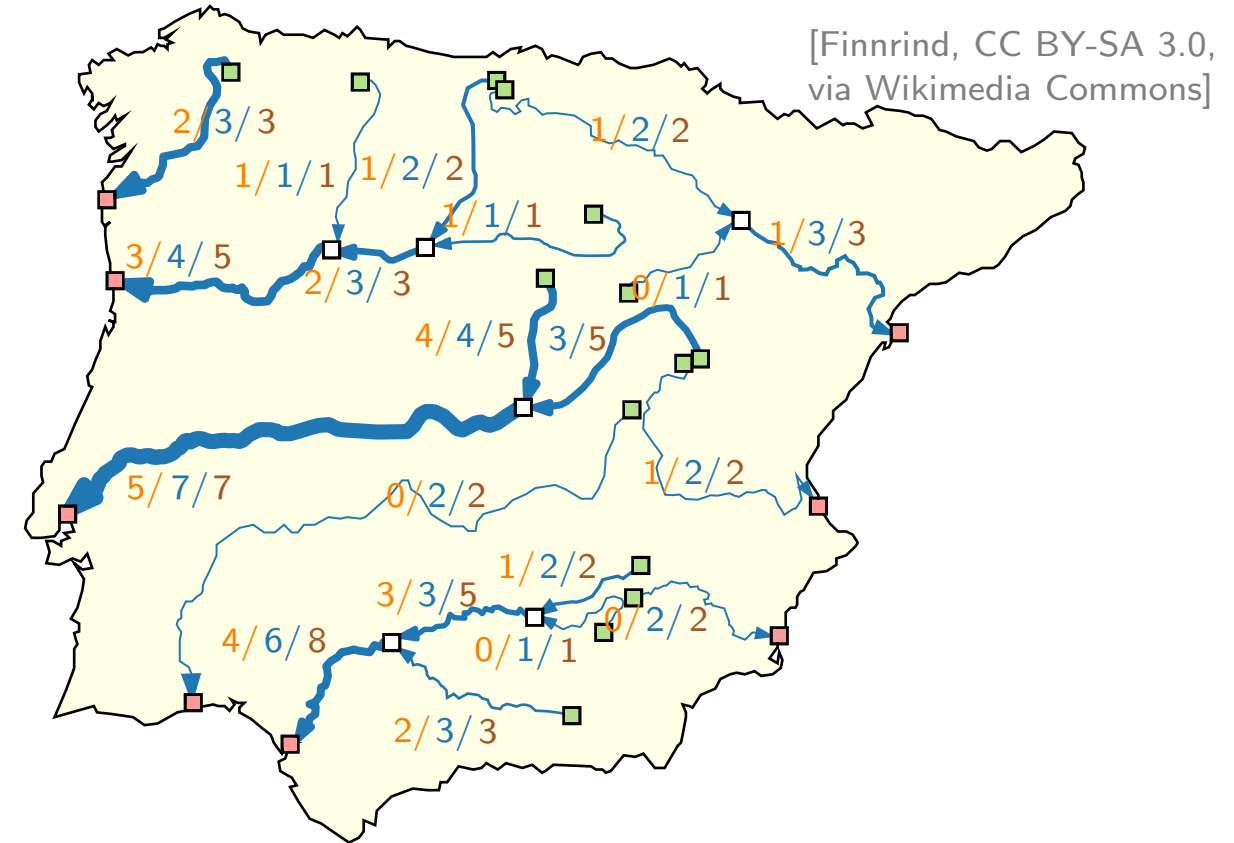
Flow network $(G; S, T; \ell; u)$ with

- directed graph G
- *sources* $S \subseteq V(G)$, *sinks* $T \subseteq V(G)$
- edge *lower bound* $\ell: E(G) \rightarrow \mathbb{R}_0^+$
- edge *capacity* $u: E(G) \rightarrow \mathbb{R}_0^+ \cup \{\infty\}$

A function $X: E(G) \rightarrow \mathbb{R}_0^+$ is called **S – T flow** if:

$$\begin{aligned} \ell(i, j) &\leq X(i, j) \leq u(i, j) & \forall (i, j) \in E(G) \\ \sum_{(i, j) \in E(G)} X(i, j) - \sum_{(j, i) \in E(G)} X(j, i) &= 0 & \forall i \in V(G) \setminus (S \cup T) \end{aligned}$$

A **maximum** S – T flow is an S – T flow where $\sum_{(i, j) \in E(G), i \in S} X(i, j) - \sum_{(j, i) \in E(G), i \in S} X(j, i)$ is maximized.



General Flow Network

Flow network $(G; b; \ell; u)$ with

- directed graph G
- node *production/consumption* $b: V(G) \rightarrow \mathbb{R}$ with $\sum_{i \in V(G)} b(i) = 0$
- edge *lower bound* $\ell: E(G) \rightarrow \mathbb{R}_0^+$
- edge *capacity* $u: E(G) \rightarrow \mathbb{R}_0^+ \cup \{\infty\}$

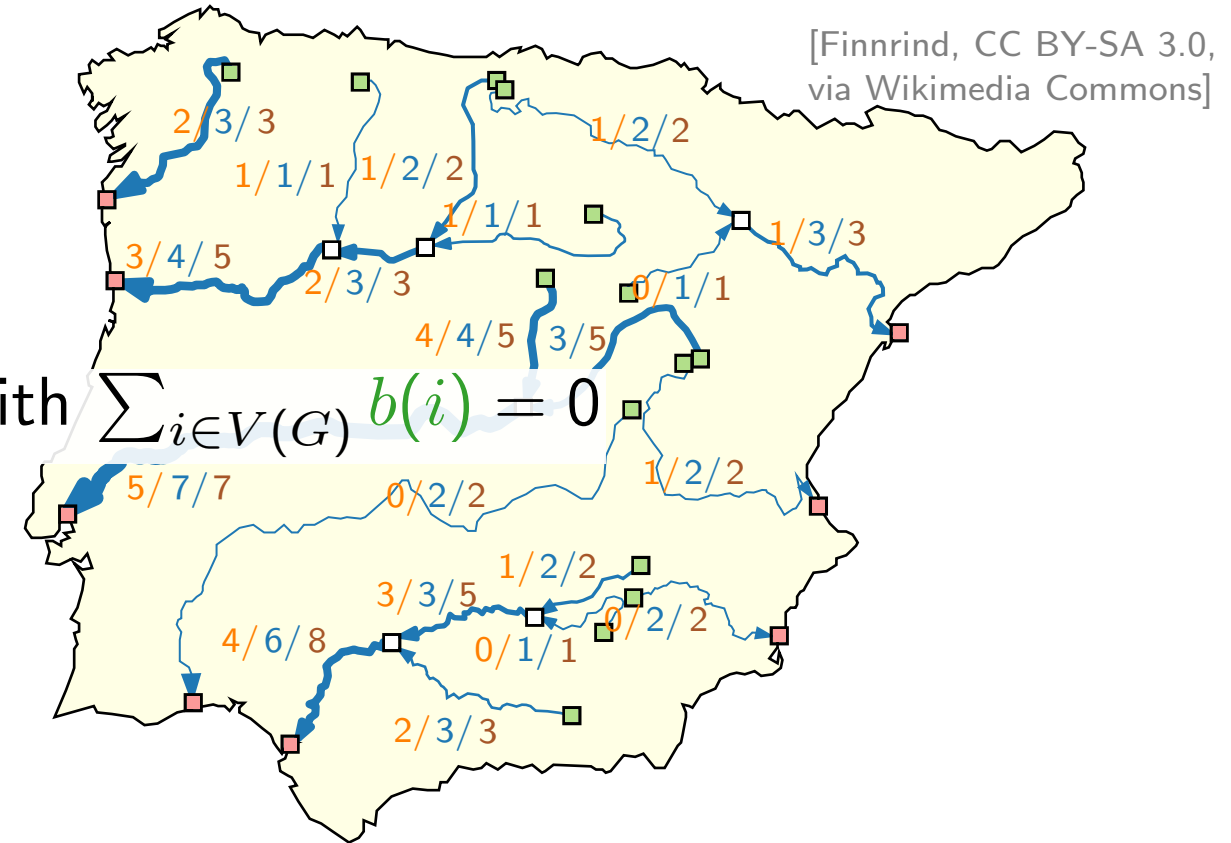
A function $X: E(G) \rightarrow \mathbb{R}_0^+$ is called **valid flow** if:

$$\ell(i, j) \leq X(i, j) \leq u(i, j) \quad \forall (i, j) \in E(G)$$

$$\sum_{(i, j) \in E(G)} X(i, j) - \sum_{(j, i) \in E(G)} X(j, i) = b(i) \quad \forall i \in V(G)$$

- **Cost function**: $\text{cost}: E(G) \rightarrow \mathbb{R}_0^+$ and $\text{cost}(X) := \sum_{(i, j) \in E(G)} \text{cost}(i, j) \cdot X(i, j)$

X is a **minimum-cost flow** if X is a valid flow that minimizes $\text{cost}(X)$.



General Flow Network – Algorithms

n : #vertices

m : #edges

Polynomial Algorithms

#	Due to	Year	Running Time
1	Edmonds and Karp	1972	$O((n + m') \log U S(n, m, nC))$
2	Rock	1980	$O((n + m') \log U S(n, m, nC))$
3	Rock	1980	$O(n \log C M(n, m, U))$
4	Bland and Jensen	1985	$O(m \log C M(n, m, U))$
5	Goldberg and Tarjan	1987	$O(nm \log (n^2/m) \log (nC))$
6	Goldberg and Tarjan	1988	$O(nm \log n \log (nC))$
7	Ahuja, Goldberg, Orlin and Tarjan	1988	$O(nm \log \log U \log (nC))$

Strongly Polynomial Algorithms

#	Due to	Year	Running Time
1	Tardos	1985	$O(m^4)$
2	Orlin	1984	$O((n + m')^2 \log n S(n, m))$
3	Fujishige	1986	$O((n + m')^2 \log n S(n, m))$
4	Galil and Tardos	1986	$O(n^2 \log n S(n, m))$
5	Goldberg and Tarjan	1987	$O(nm^2 \log n \log (n^2/m))$
6	Goldberg and Tarjan	1988	$O(nm^2 \log^2 n)$
7	Orlin (this paper)	1988	$O((n + m') \log n S(n, m))$

$S(n, m)$	$= O(m + n \log n)$	Fredman and Tarjan [1984]
$S(n, m, C)$	$= O(\min(m + n\sqrt{\log C}, (m \log \log C)))$	Ahuja, Mehlhorn, Orlin and Tarjan [1990] Van Emde Boas, Kaas and Zijlstra [1977]
$M(n, m)$	$= O(\min(nm + n^{2+\epsilon}, nm \log n))$ where ϵ is any fixed constant.	King, Rao, and Tarjan [1991]
$M(n, m, U)$	$= O(nm \log (\frac{n}{m} \sqrt{\log U} + 2))$	Ahuja, Orlin and Tarjan [1989]

[Orlin 1991]

Theorem.

[Orlin 1991]

The minimum-cost flow problem can be solved in $O(n^2 \log^2 n + m^2 \log n)$ time.

Theorem.

[Cornelsen & Karrenbauer 2011]

The minimum-cost flow problem for planar graphs with bounded costs and face sizes can be solved in $O(n^{3/2})$ time.

Theorem.

[van den Brand, Chen, Kyng, Liu, Peng, Probst, Sachdeva, Sidford 2023]

The minimum-cost flow problem with integral vertex demands, edge capacities, and edge costs can be solved in $O(m^{1+o(1)} \log U \log C)$ time, where U is the maximum capacity and C are the maximum costs.

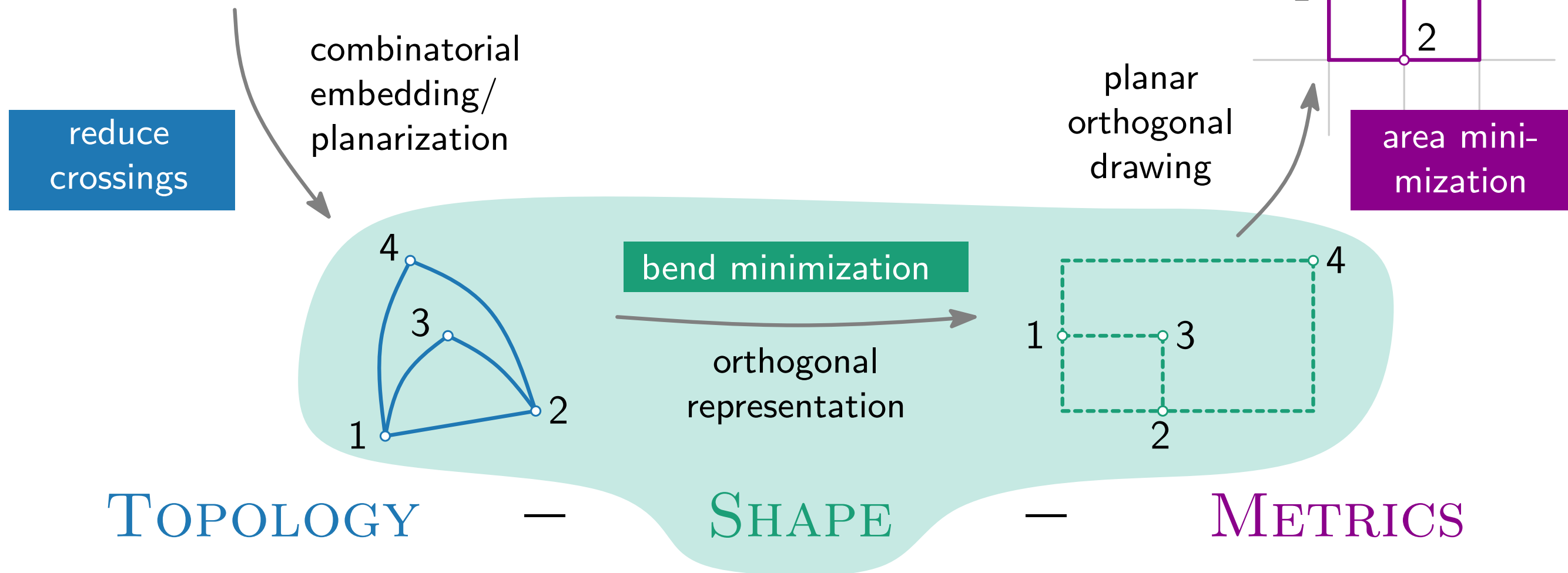
Topology – Shape – Metrics

Three-step approach:

[Tamassia 1987]

$$V(G) = \{v_1, v_2, v_3, v_4\}$$

$$E(G) = \{v_1v_2, v_1v_3, v_1v_4, v_2v_3, v_2v_4\}$$



Bend Minimization with Given Embedding

Geometric orthogonal bend minimization.

Given: ■ Plane graph G with maximum degree 4
 ■ Combinatorial embedding F and outer face f_0

Find: Orthogonal drawing with minimum number of bends that preserves the embedding.

Compare with the following variant:

Combinatorial orthogonal bend minimization.

Given: ■ Plane graph G with maximum degree 4
 ■ Combinatorial embedding F and outer face f_0

Find: **Orthogonal representation** $H(G)$ with minimum number of bends that preserves the embedding.

Bend Minimization with Given Embedding

How to solve the combinatorial orthogonal bend minimization problem?

Idea.

Formulate as a network-flow problem:

- a unit of flow = $\angle \frac{\pi}{2}$
- vertices $\xrightarrow{\angle}$ faces ($\# \angle \frac{\pi}{2}$ per face)
- faces $\xrightarrow{\angle}$ neighboring faces ($\#$ bends toward the neighbor)

Combinatorial orthogonal bend minimization.

Given:

- Plane graph G with maximum degree 4
- Combinatorial embedding F and outer face f_0

Find: **Orthogonal representation** $H(G)$ with minimum number of bends that preserves the embedding.

Flow Network for Bend Minimization

(H1) $H(G)$ corresponds to F, f_0 .

(H2) For each **edge** $\{u, v\}$ shared by faces f and g , the sequence δ_1 is reversed and inverted copy of δ_2 .

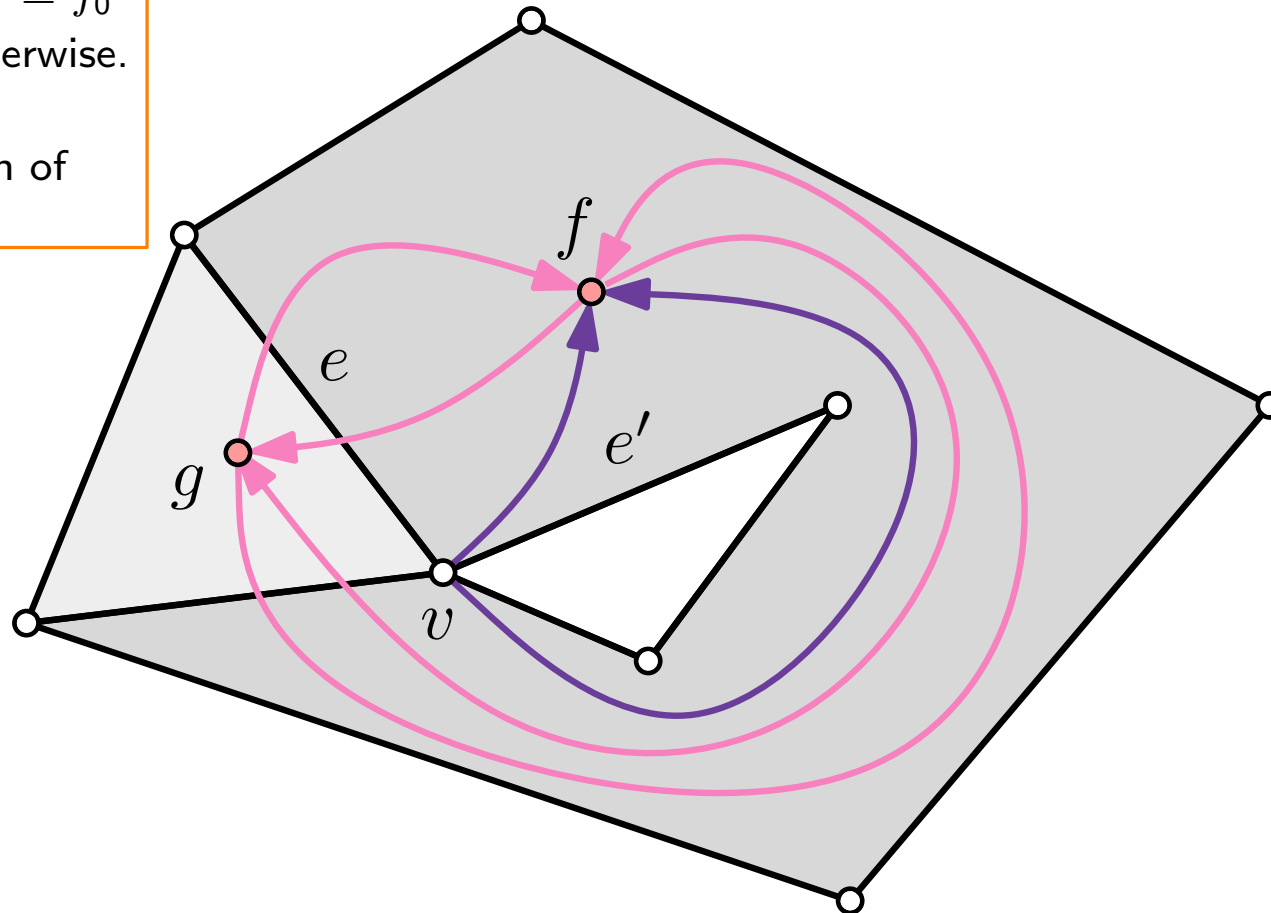
(H3) For each **face** f , it holds that:

$$\sum_{r \in H(f)} C(r) = \begin{cases} -4 & \text{if } f = f_0 \\ +4 & \text{otherwise.} \end{cases}$$

(H4) For each **vertex** v , the sum of incident angles is 2π .

Define flow network $N(G) = ((V(G) \cup F, E'); b; \ell; u; \text{cost})$:

$$E' = \{(v, f)_{ee'} \in V(G) \times F \mid v \text{ between edges } e, e' \text{ of } \partial f\} \cup \{(f, g)_e \in F \times F \mid f, g \text{ have common edge } e\}$$



Directed multigraph!

Flow Network for Bend Minimization

(H1) $H(G)$ corresponds to F, f_0 .

(H2) For each **edge** $\{u, v\}$ shared by faces f and g , the sequence δ_1 is reversed and inverted copy of δ_2 .

(H3) For each **face** f , it holds that:

$$\sum_{r \in H(f)} C(r) = \begin{cases} -4 & \text{if } f = f_0 \\ +4 & \text{otherwise.} \end{cases}$$

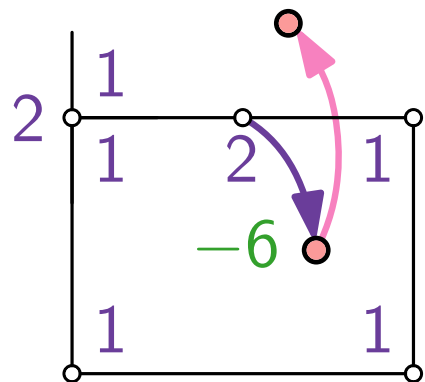
(H4) For each **vertex** v , the sum of incident angles is 2π .

Define flow network $N(G) = ((V(G) \cup F, E'); b; \ell; u; \text{cost})$:

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$$b(v) = 4 \quad \forall v \in V(G)$$

$$b(f) = -2 \deg_G(f) + \begin{cases} -4 & \text{if } f = f_0, \\ +4 & \text{otherwise} \end{cases} \Rightarrow \sum_{w \in V(G) \cup F} b(w) = 0 \quad (\text{Euler})$$



$$\forall (v, f) \in E', v \in V(G), f \in F$$

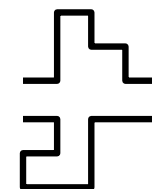
$$\forall (f, g) \in E', f, g \in F$$

$$\ell(v, f) := 1 \leq X(v, f) \leq 4 =: u(v, f)$$

$$\text{cost}(v, f) = 0$$

$$\ell(f, g) := 0 \leq X(f, g) \leq \infty =: u(f, g)$$

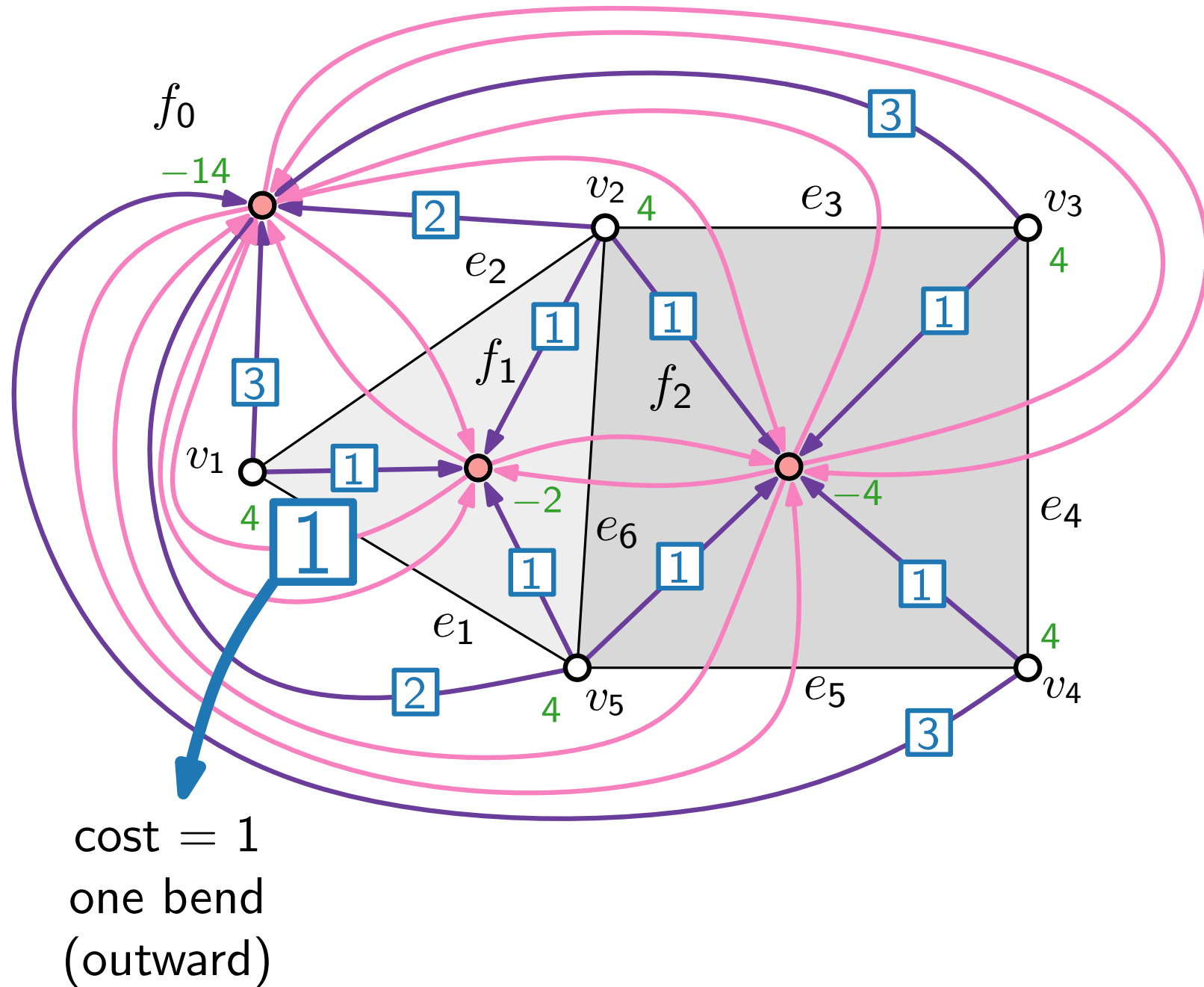
$$\text{cost}(f, g) = 1$$



We model only the number of bends.
Why is it enough?

→ *Exercise!*

Flow Network Example



Legend

$V(G)$ \circ

F \bullet

$\ell/u/\text{cost}$

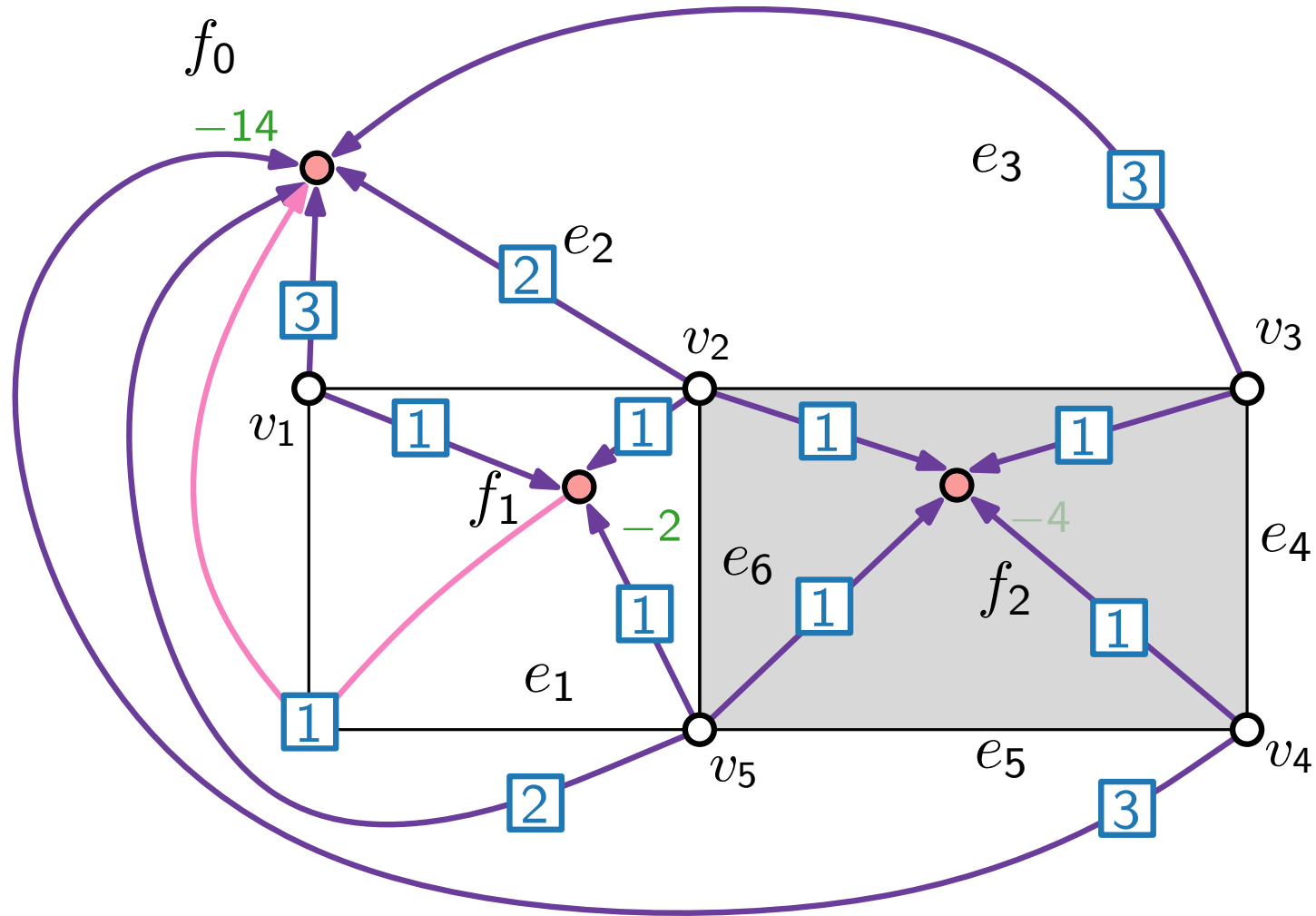
$V(G) \times F \supseteq \frac{1}{4}/0$

$F \times F \supseteq \frac{0}{\infty}/1$

$4 = b\text{-value}$

3 flow

Flow Network Example



Legend

$V(G)$ \circ

F \bullet

$\ell/u/\text{cost}$

$V(G) \times F \supseteq \xrightarrow{1/4/0}$

$F \times F \supseteq \xrightarrow{0/\infty/1}$

4 = b -value

3 flow

Bend Minimization – Result

Theorem.

[Tamassia '87]

A plane graph (G, F, f_0) has a valid orthogonal representation $H(G)$ with k bends. \Leftrightarrow

The flow network $N(G)$ has a valid flow X with cost k .

Proof.

“ \Leftarrow ”: Given a valid flow X in $N(G)$ of cost k ,
construct an orthogonal representation $H(G)$ with k bends.

■ Transform from flow to orthogonal description.

■ Show properties (H1)–(H4).

(H1) $H(G)$ matches F, f_0



(H2) Bend order inverted and reversed on opposite sides



(H3) Angle sum of $f = \pm 4$



→ Exercise.

(H4) Total angle at each vertex $= 2\pi$



(H1) $H(G)$ corresponds to F, f_0 .

(H2) For each **edge** $\{u, v\}$ shared by faces f and g , sequence δ_1 is reversed and inverted δ_2 .

(H3) For each **face** f it holds that:

$$\sum_{r \in H(f)} C(r) = \begin{cases} -4 & \text{if } f = f_0 \\ +4 & \text{otherwise.} \end{cases}$$

(H4) For each **vertex** v the sum of incident angles is 2π .

Bend Minimization – Result

Theorem.

[Tamassia '87]

A plane graph (G, F, f_0) has a valid orthogonal representation $H(G)$ with k bends. \Leftrightarrow

The flow network $N(G)$ has a valid flow X with cost k .

$$\blacksquare \quad b(v) = 4 \quad \forall v \in V(G)$$

$$\blacksquare \quad b(f) = -2 \deg_G(f) + \begin{cases} -4 & \text{if } f = f_0, \\ +4 & \text{otherwise} \end{cases}$$

$$\blacksquare \quad \begin{aligned} \ell(v, f) &:= 1 \leq X(v, f) \leq 4 =: u(v, f) \\ \text{cost}(v, f) &= 0 \\ \ell(f, g) &:= 0 \leq X(f, g) \leq \infty =: u(f, g) \\ \text{cost}(f, g) &= 1 \end{aligned}$$

Proof.

“ \Rightarrow ”: Given an orthogonal representation $H(G)$ with k bends, construct a valid flow X in $N(G)$ of cost k .

■ Define flow $X: E' \rightarrow \mathbb{R}_0^+$.

■ Show that X is a valid flow and has cost k .

$$(N1) \quad X(vf) = 1/2/3/4$$



$$(N2) \quad X((fg)_e) = |\delta|_0, \text{ where } (e, \delta, x) \text{ describes edge } e \text{ in } H(f)$$



$$(N3) \quad \text{capacities, deficit/demand coverage}$$



$$(N4) \quad \text{cost} = k$$



Bend Minimization – Remarks

- The theorem implies that the combinatorial orthogonal bend minimization problem for plane graphs can be solved using an algorithm for min-cost flow.

Theorem.

[Garg & Tamassia 1996]

The min-cost flow problem for planar graphs with bounded costs and vertex degrees can be solved in $O(n^{7/4} \sqrt{\log n})$ time.

Theorem.

[van den Brand, Chen, Kyng, Liu, Peng, Probst, Sachdeva, Sidford 2023]

The minimum-cost flow problem with integral vertex demands, edge capacities & costs can be solved in $O(m^{1+o(1)} \log U \log C)$ time, where U is max. capacity and C are max. costs.

$m \in O(n)$ for planar graphs
 $C \in \{0, 1\}$
 Further, $\log n = n^{\log n \log n} = n^{\log \log n / \log n} \in n^{o(1)}$ since $\lim_{n \rightarrow \infty} \frac{\log \log n}{\log n} = 0$

$U \in O(n)$ because $2n + 4$ bends in total are always sufficient [Storer 1984]

Corollary.

The combinatorial orthogonal bend minimization problem can be solved in $O(n^{1+o(1)})$ time.

Theorem.

[Garg & Tamassia 2001]

Bend minimization without given combinatorial embedding is NP-hard.

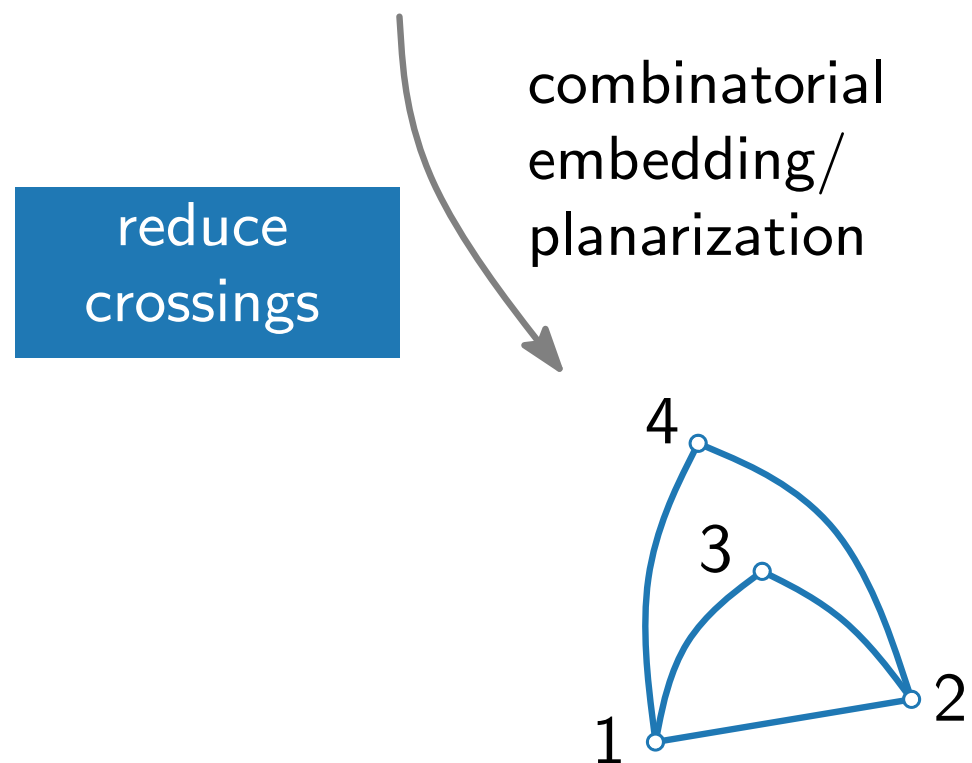
Topology – Shape – Metrics

Three-step approach:

[Tamassia 1987]

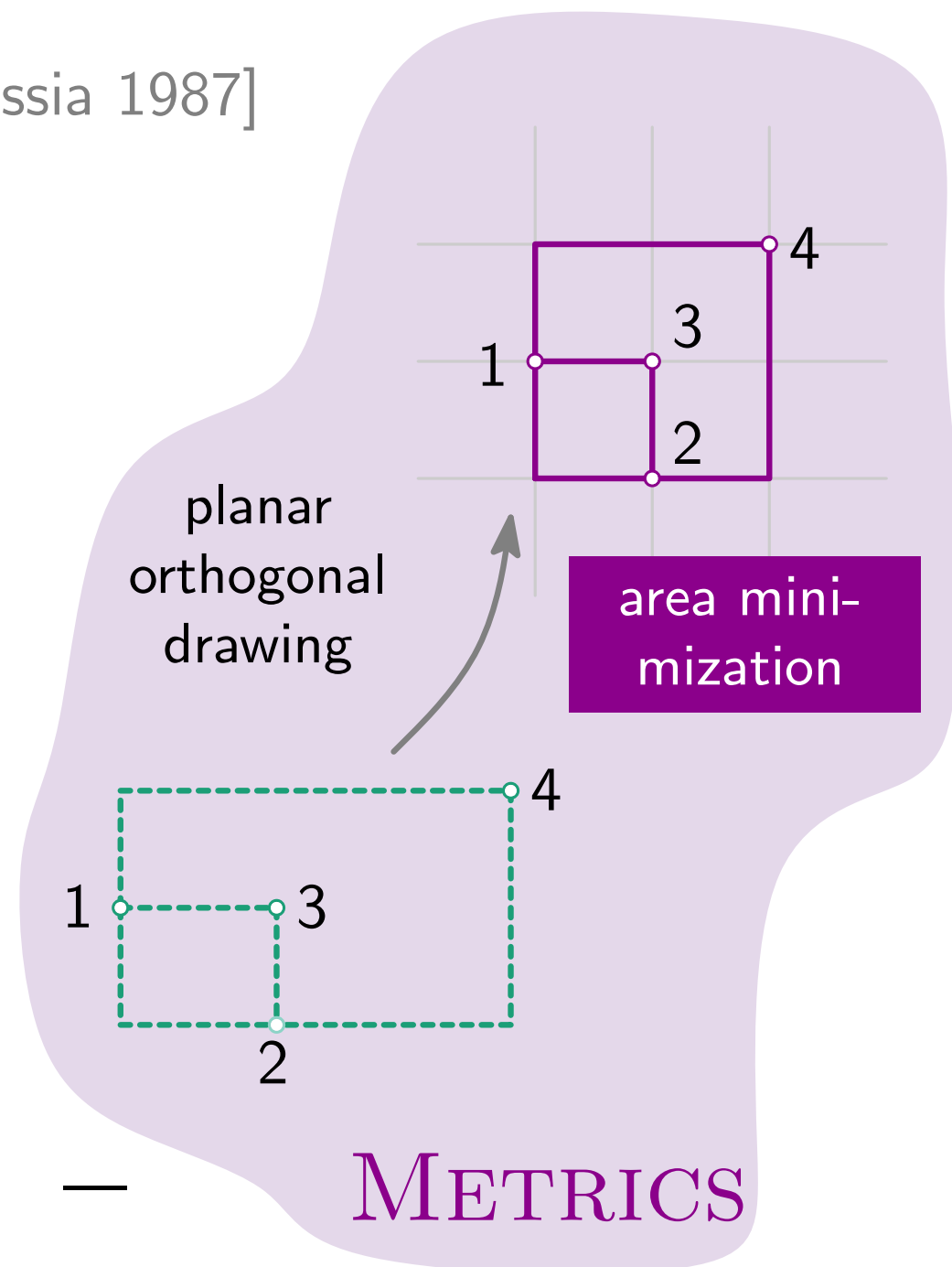
$$V(G) = \{v_1, v_2, v_3, v_4\}$$

$$E(G) = \{v_1v_2, v_1v_3, v_1v_4, v_2v_3, v_2v_4\}$$



bend minimization

orthogonal
representation



TOPOLOGY

—

SHAPE

—

METRICS

Compaction

Compaction problem.

Given: ■ Plane graph G with maximum degree 4

■ Orthogonal representation $H(G)$

Find: Compact orthogonal layout of G that realizes $H(G)$

Special case.

All faces are rectangles.

This guarantees: ■ minimum total edge length

■ minimum area

Properties.

■ bends only on the outer face

■ opposite sides of a face have the same length

Idea.

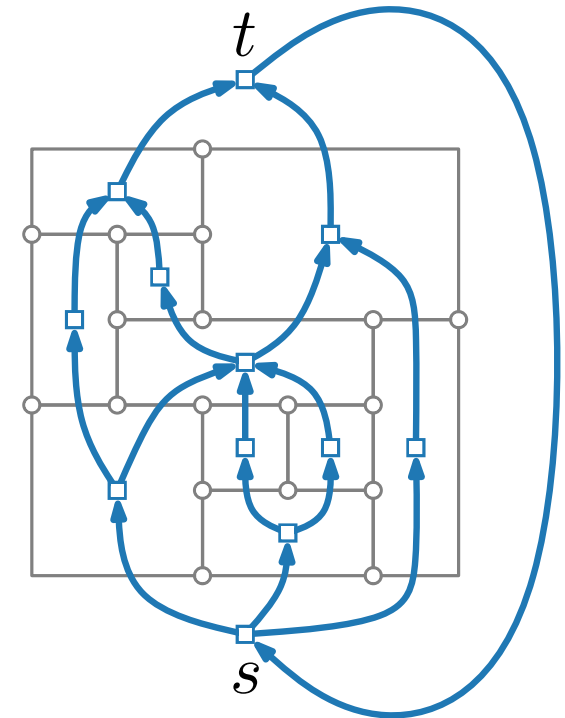
■ Formulate flow network for horizontal/vertical compaction

Flow Network for Edge-Length Assignment

Definition.

Flow Network $N_{\text{hor}} = ((W_{\text{hor}}, E_{\text{hor}}); b; \ell; u; \text{cost})$

- $W_{\text{hor}} = F \setminus \{f_0\} \cup \{s, t\}$ □
- $E_{\text{hor}} = \{(f, g) \mid f, g \text{ share a horizontal segment and } f \text{ lies below } g\} \cup \{(t, s)\}$
- $\ell(a) = 1 \quad \forall a \in E_{\text{hor}}$
- $u(a) = \infty \quad \forall a \in E_{\text{hor}}$
- $\text{cost}(a) = 1 \quad \forall a \in E_{\text{hor}}$
- $b(f) = 0 \quad \forall f \in W_{\text{hor}}$

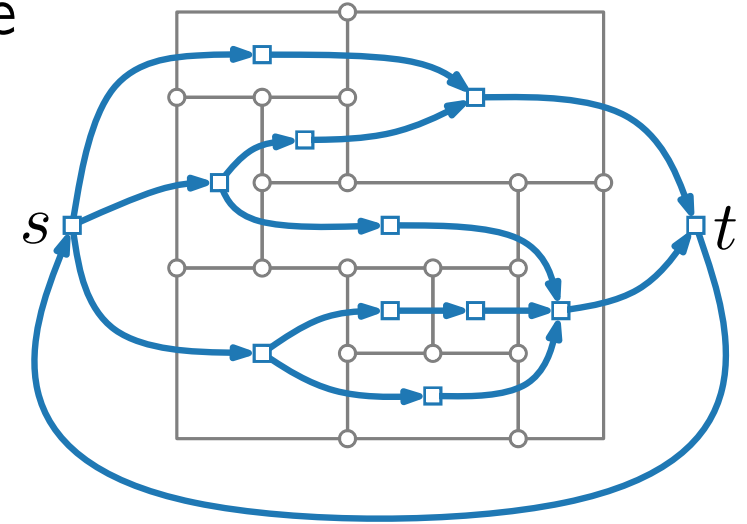


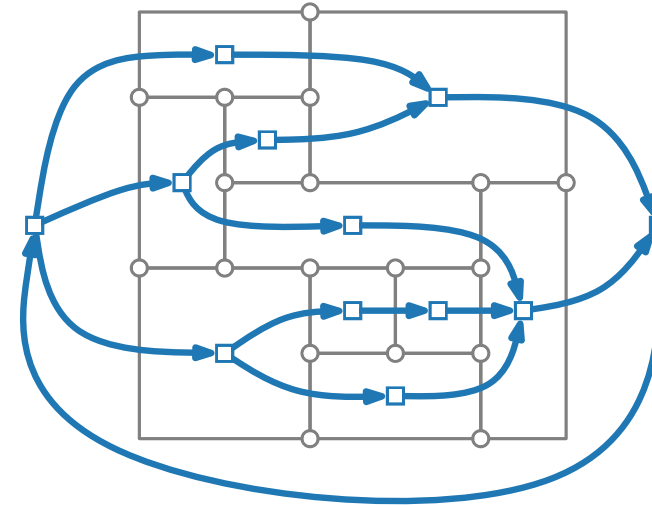
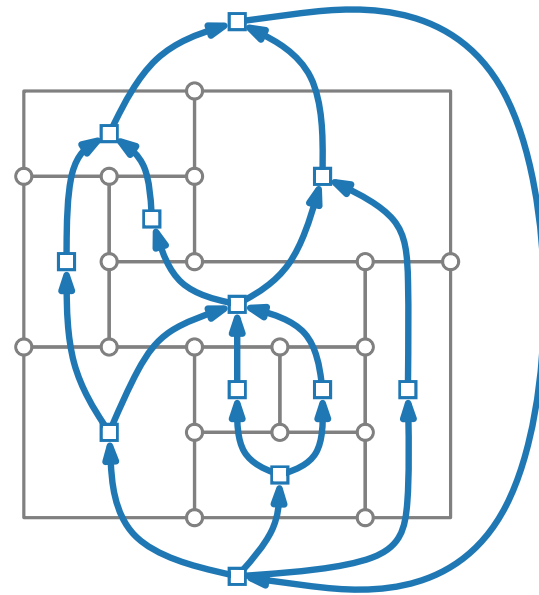
Flow Network for Edge-Length Assignment

Definition.

Flow Network $N_{\text{ver}} = ((W_{\text{ver}}, E_{\text{ver}}); b; \ell; u; \text{cost})$

- $W_{\text{ver}} = F \setminus \{f_0\} \cup \{s, t\}$ □
- $E_{\text{ver}} = \{(f, g) \mid f, g \text{ share a } \textcolor{red}{\text{vertical}} \text{ segment and } f \text{ lies to the } \textcolor{red}{\text{left}} \text{ of } g\} \cup \{(t, s)\}$
- $\ell(a) = 1 \quad \forall a \in E_{\text{ver}}$
- $u(a) = \infty \quad \forall a \in E_{\text{ver}}$
- $\text{cost}(a) = 1 \quad \forall a \in E_{\text{ver}}$
- $b(f) = 0 \quad \forall f \in W_{\text{ver}}$





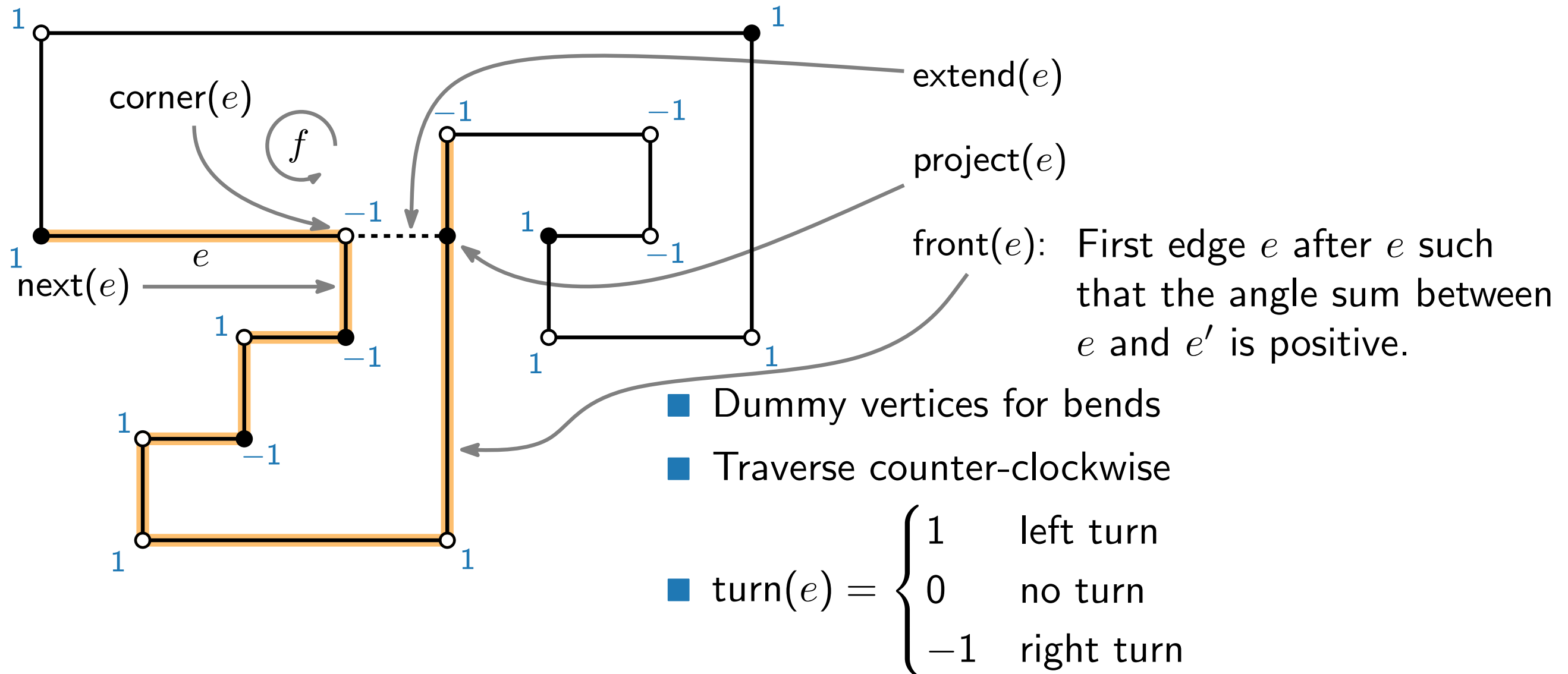
Theorem.

A valid flow for N_{hor} and N_{ver} exists \Leftrightarrow
corresponding edge lengths induce an orthogonal drawing.

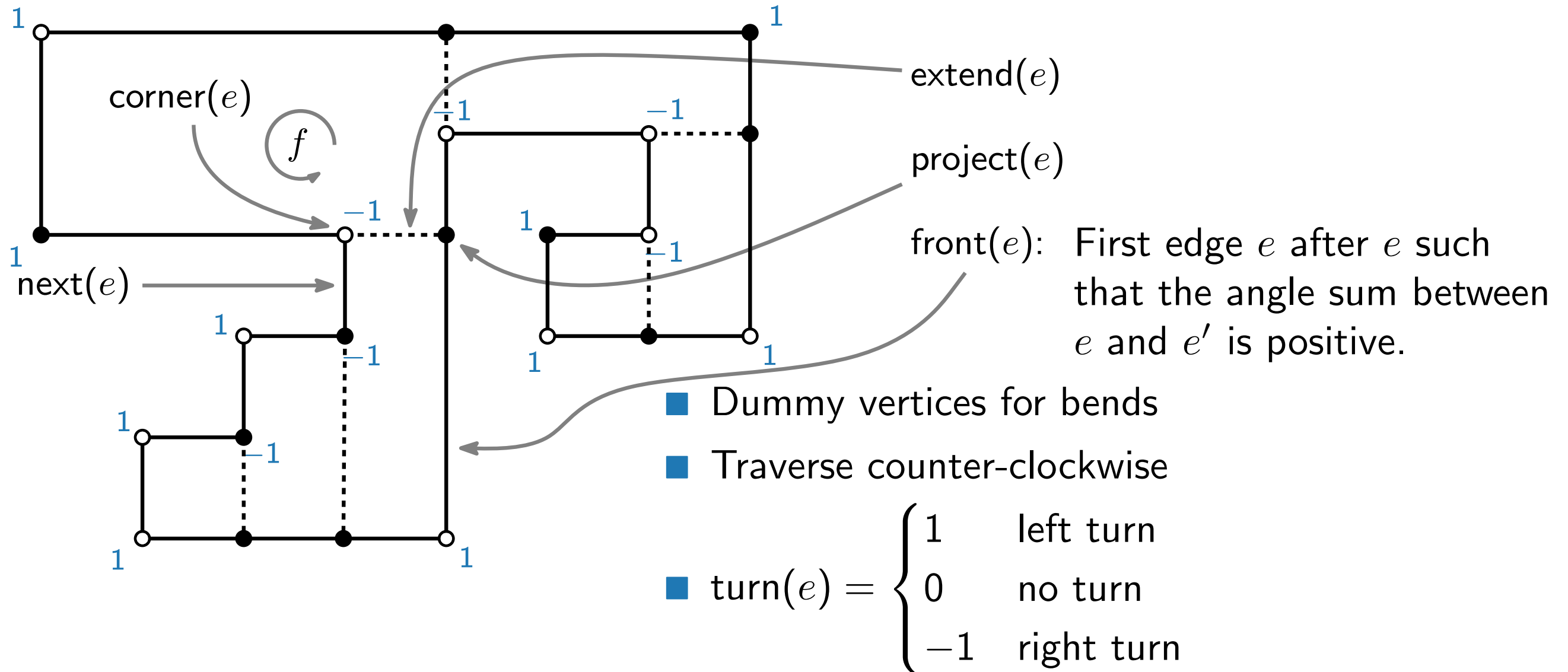
What values of the drawing do the following quantities represent?

- $|X_{\text{hor}}(t, s)|$ and $|X_{\text{ver}}(t, s)|$? width and height of the drawing
- $\sum_{e \in E_{\text{hor}}} X_{\text{hor}}(e) + \sum_{e \in E_{\text{ver}}} X_{\text{ver}}(e)$ total edge length

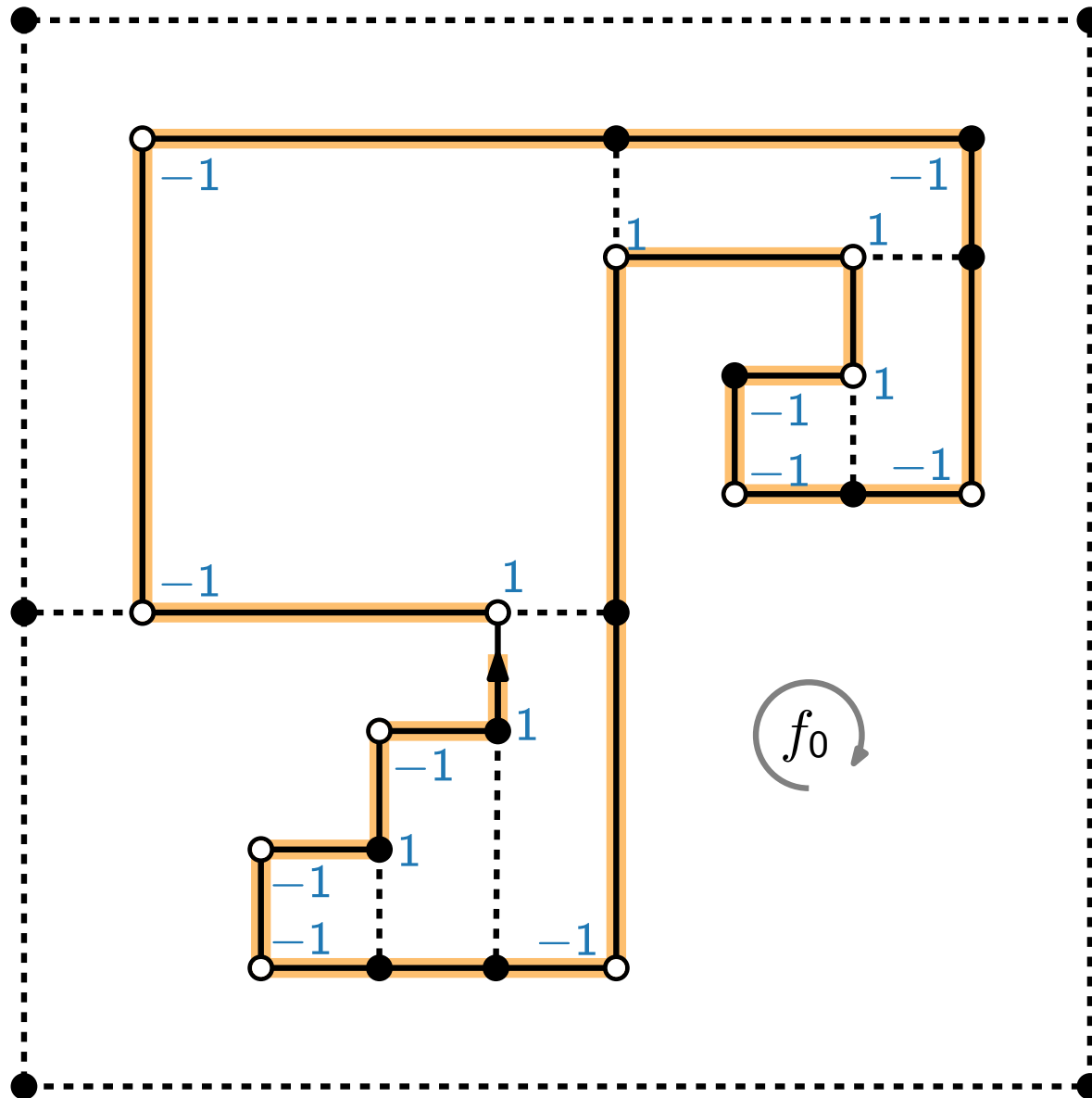
Refinement of G and $H(G)$ – Inner Face



Refinement of G and $H(G)$ – Inner Face

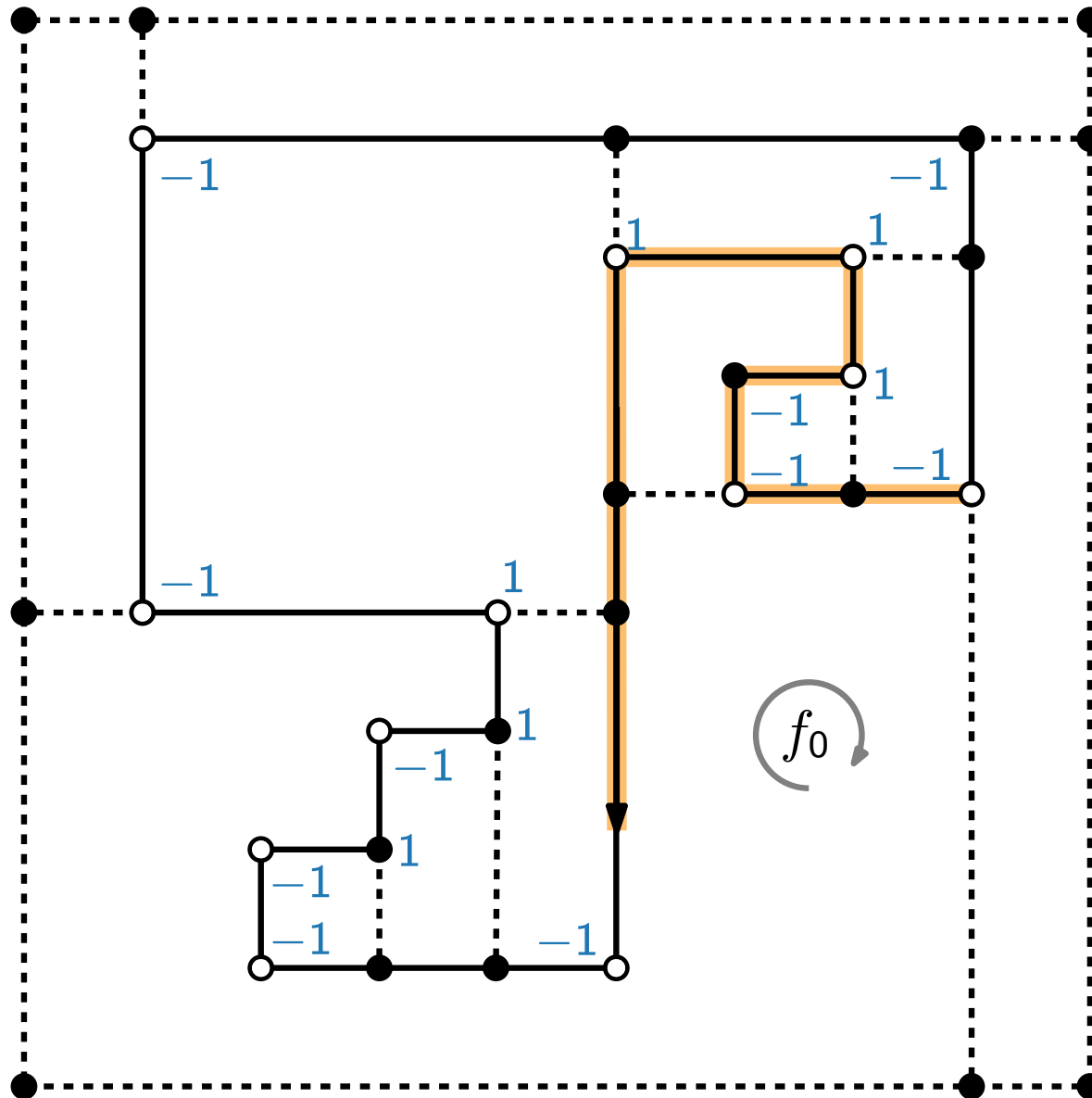


Refinement of G and $H(G)$ – Outer Face



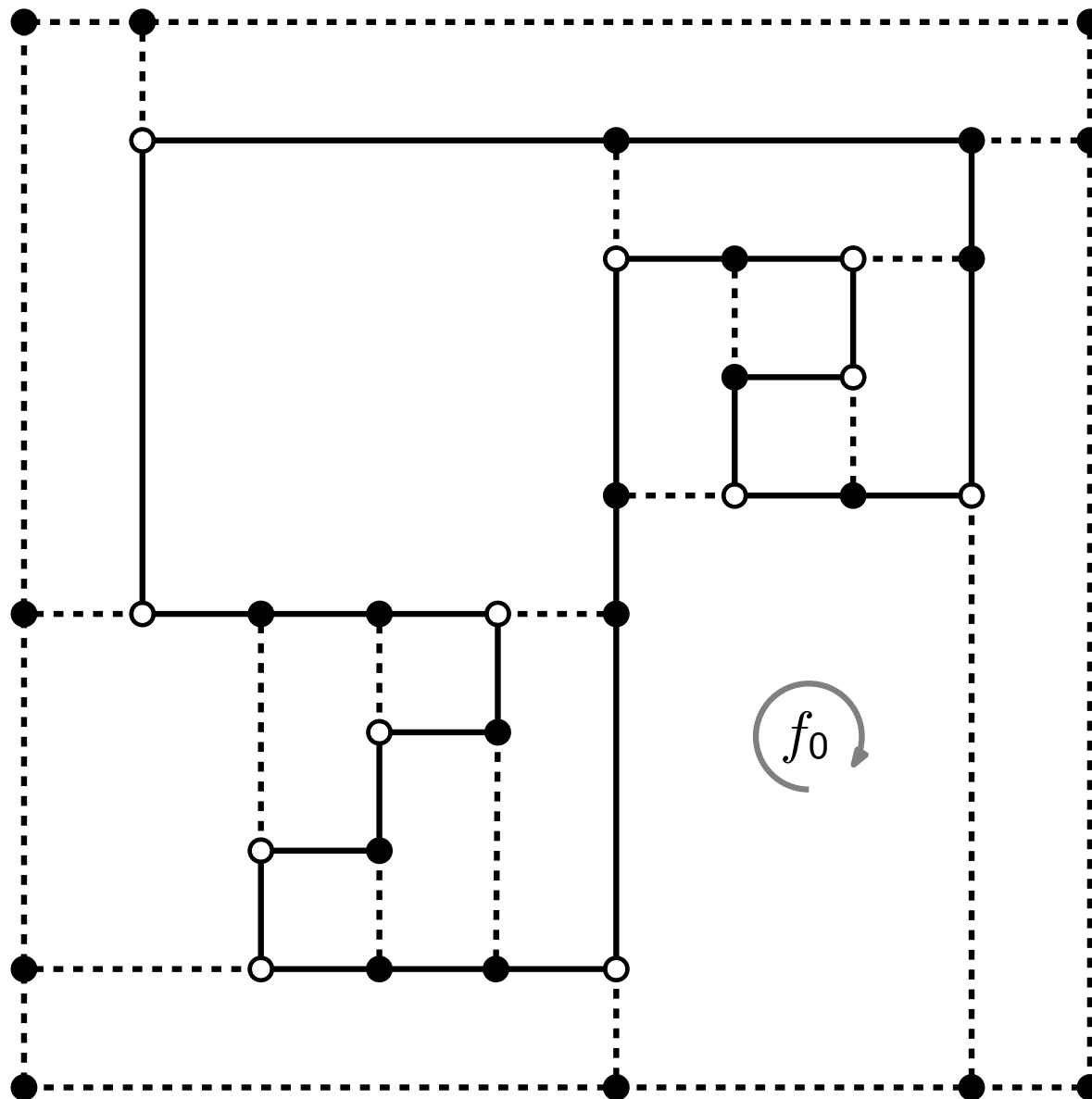
- Add an outer rectangle
- Traverse clockwise

Refinement of G and $H(G)$ – Outer Face



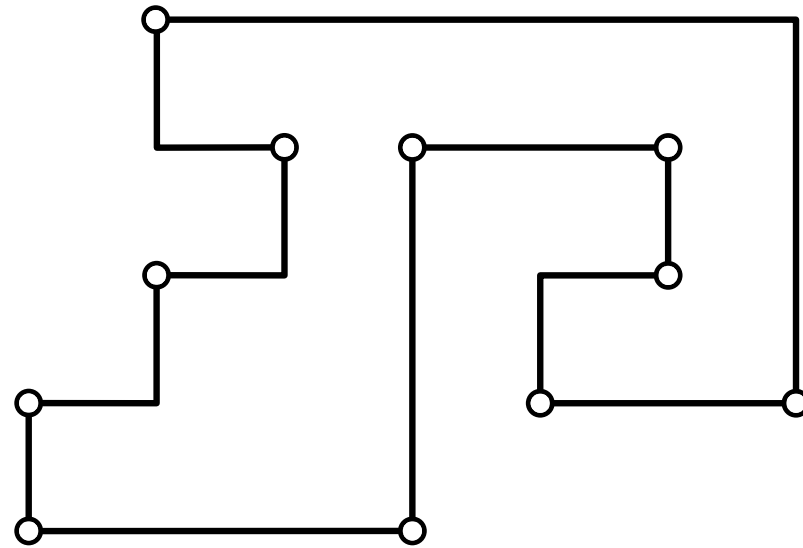
- Add an outer rectangle
- Traverse clockwise

Refinement of G and $H(G)$ – Outer Face



- Add an outer rectangle
- Traverse clockwise

Refinement of G and $H(G)$ – Outer Face



Area minimized? **No!**

vertices

bends

But we get bound $O((n + b)^2)$ on the area.

Theorem. [Patrignani 2001]

Compaction for a given orthogonal representation is NP-hard in general.


Theorem. [EFKSSW 2022]

Compaction is NP-hard even for orthogonal representations of *cycles*.

Compaction is NP-hard

Polynomial-time reduction from the NP-complete satisfiability problem (SAT).

In an instance of the SAT problem we have:

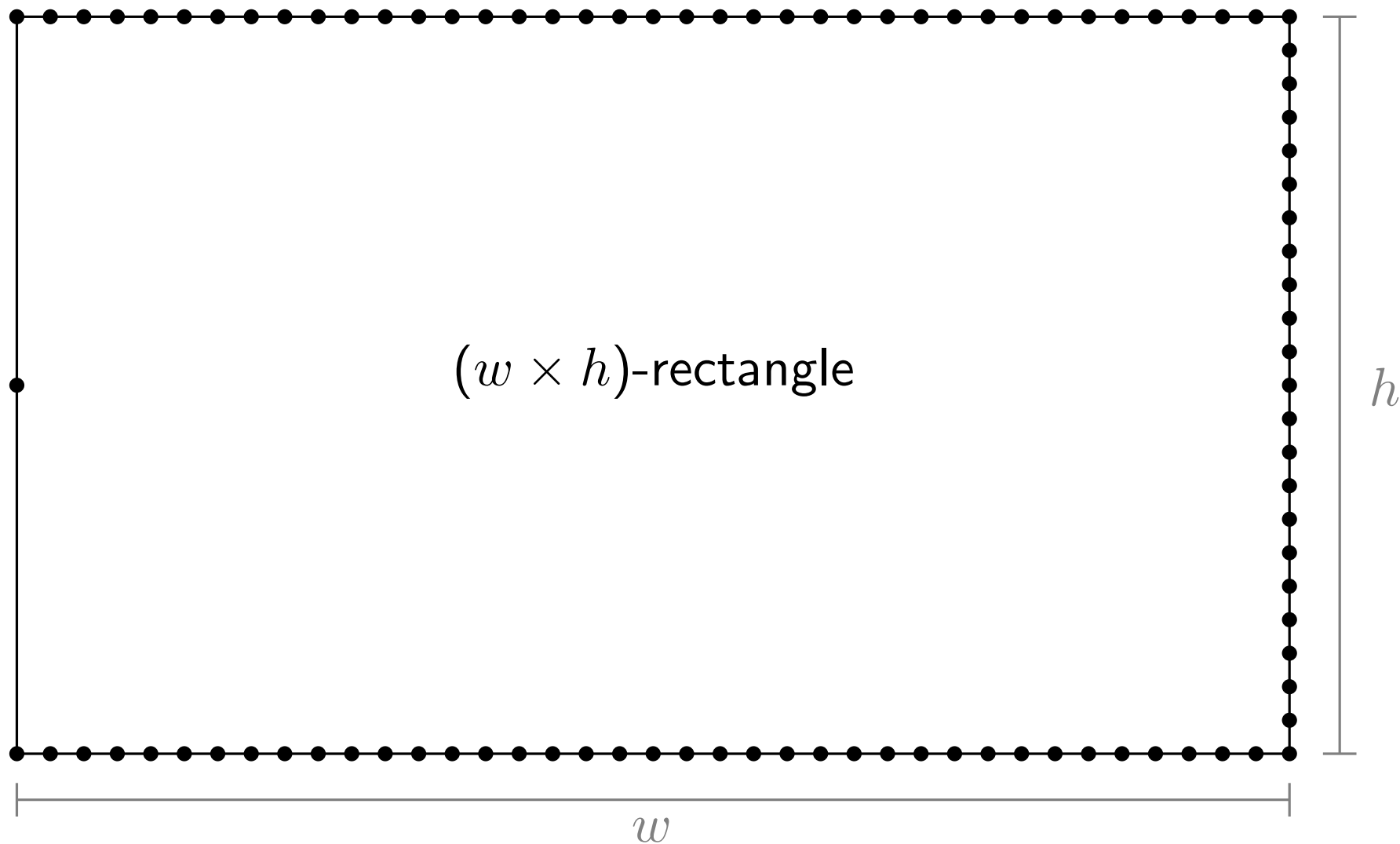
- set of n Boolean variables $X = \{x_1, x_2, \dots, x_n\}$
- m clauses C_1, C_2, \dots, C_m , where each clause is a disjunction of **literals** from X ,
e.g., $C_1 = x_1 \vee \neg x_2 \vee x_3$
 a literal is a variable x or a negated variable $\neg x$
- Boolean formula $\Phi = C_1 \wedge C_2 \wedge \dots \wedge C_m$

Question: Is there an assignment of truth values to the variables in X such that Φ is true?

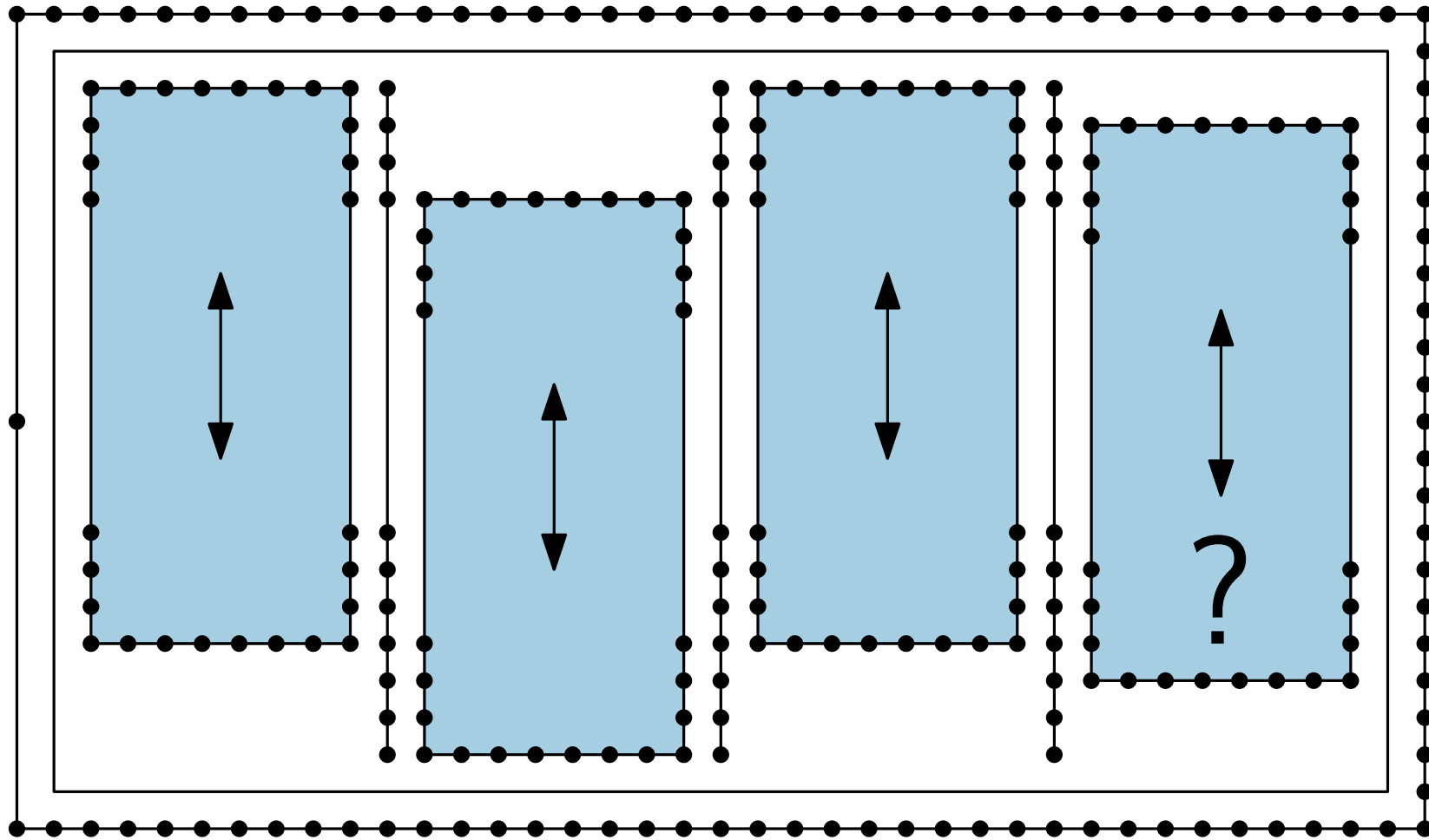
Idea of the reduction:

- Given SAT instance $\Phi \Rightarrow$ construct a plane graph G and a orthogonal description $H(G)$
- Φ is satisfiable $\Leftrightarrow G$ can be drawn w.r.t. $H(G)$ in area K for some specific number K

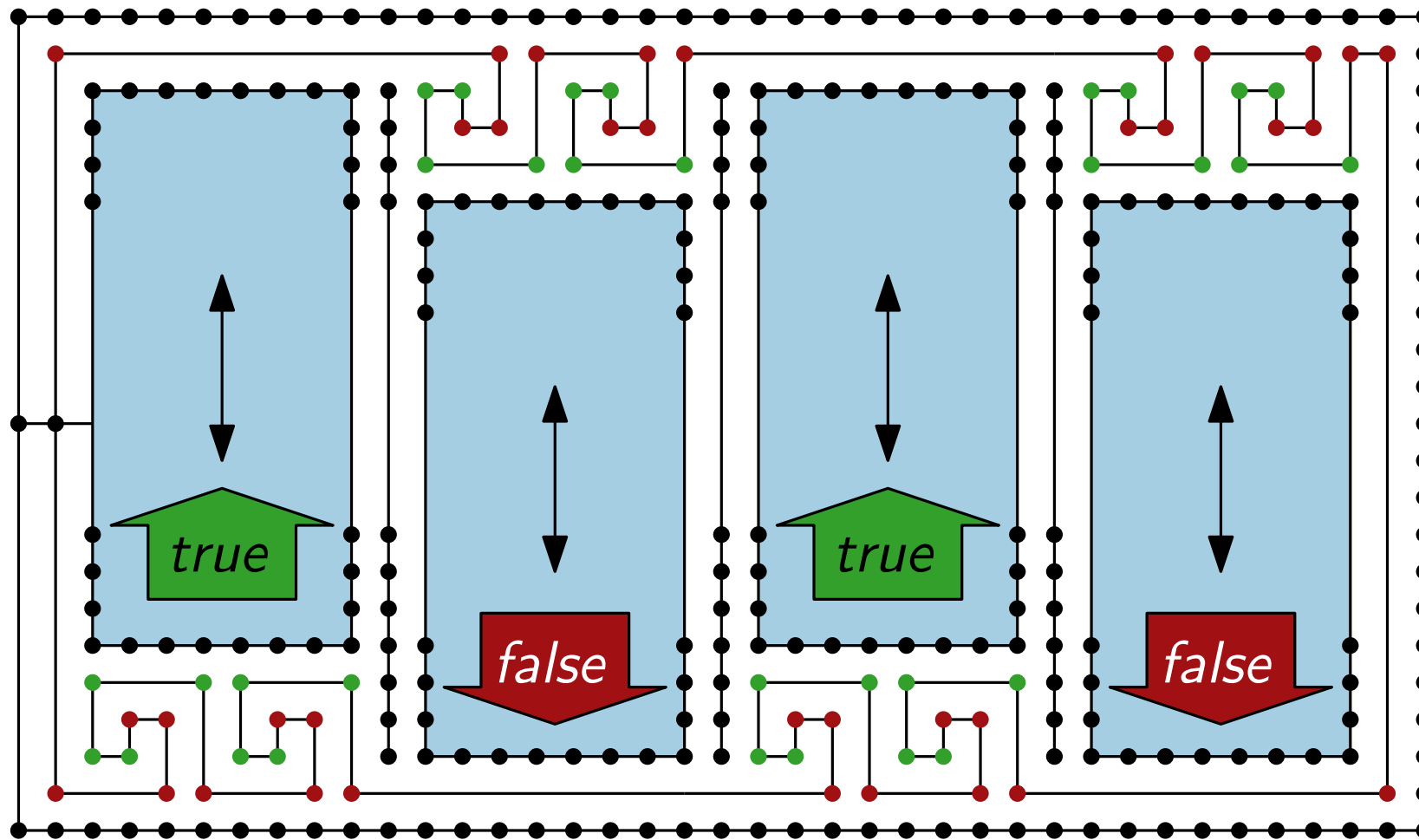
Boundary, Belt, and “Piston” Gadget



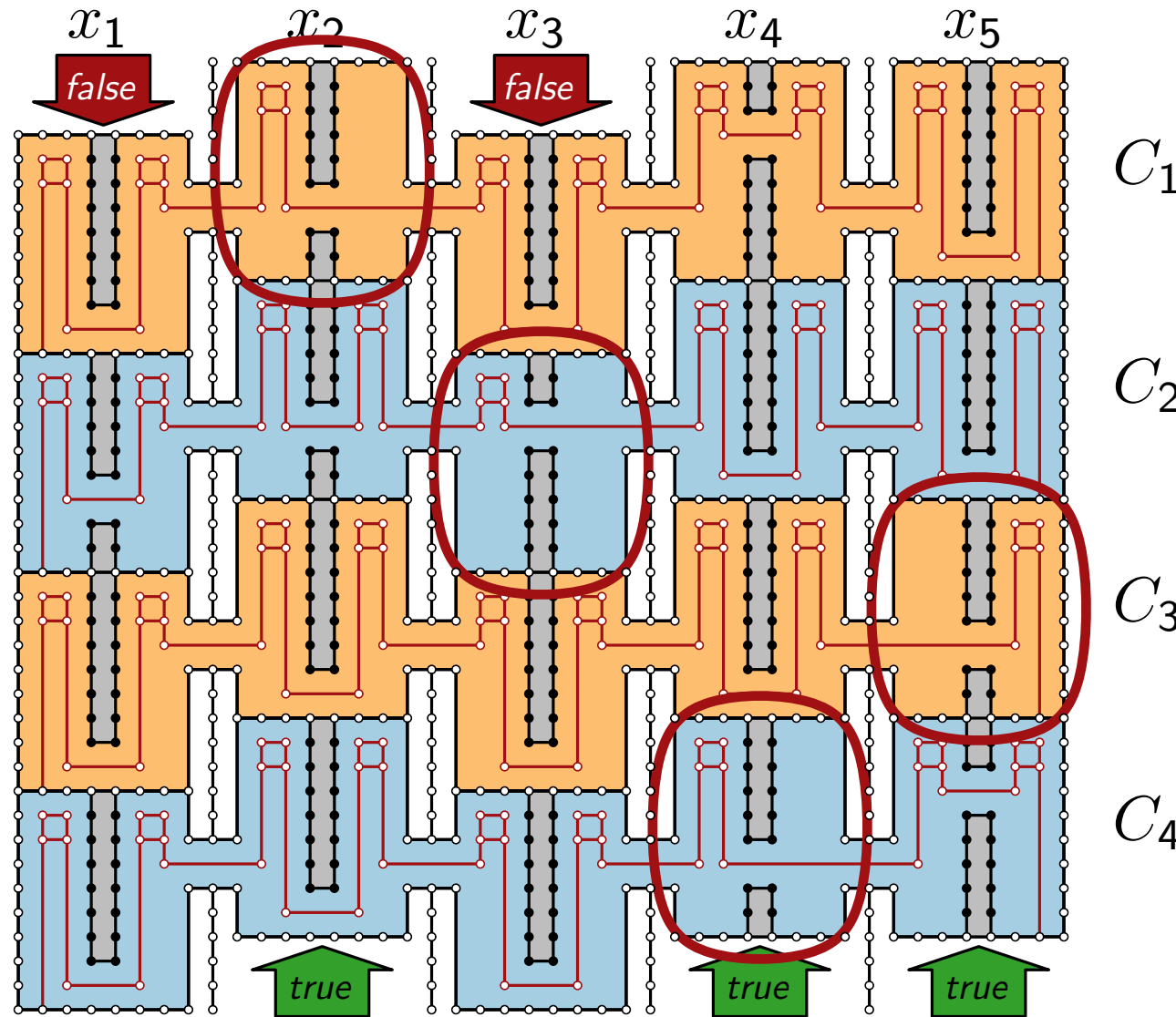
Boundary, Belt, and “Piston” Gadget



Boundary, Belt, and “Piston” Gadget



Clause Gadgets



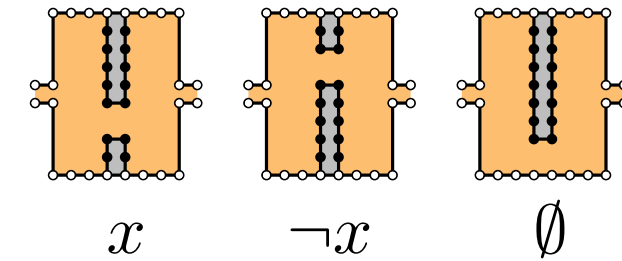
Example:

$$C_1 = x_2 \vee \neg x_4$$

$$C_2 = x_1 \vee x_2 \vee \neg x_3$$

$$C_3 = x_5$$

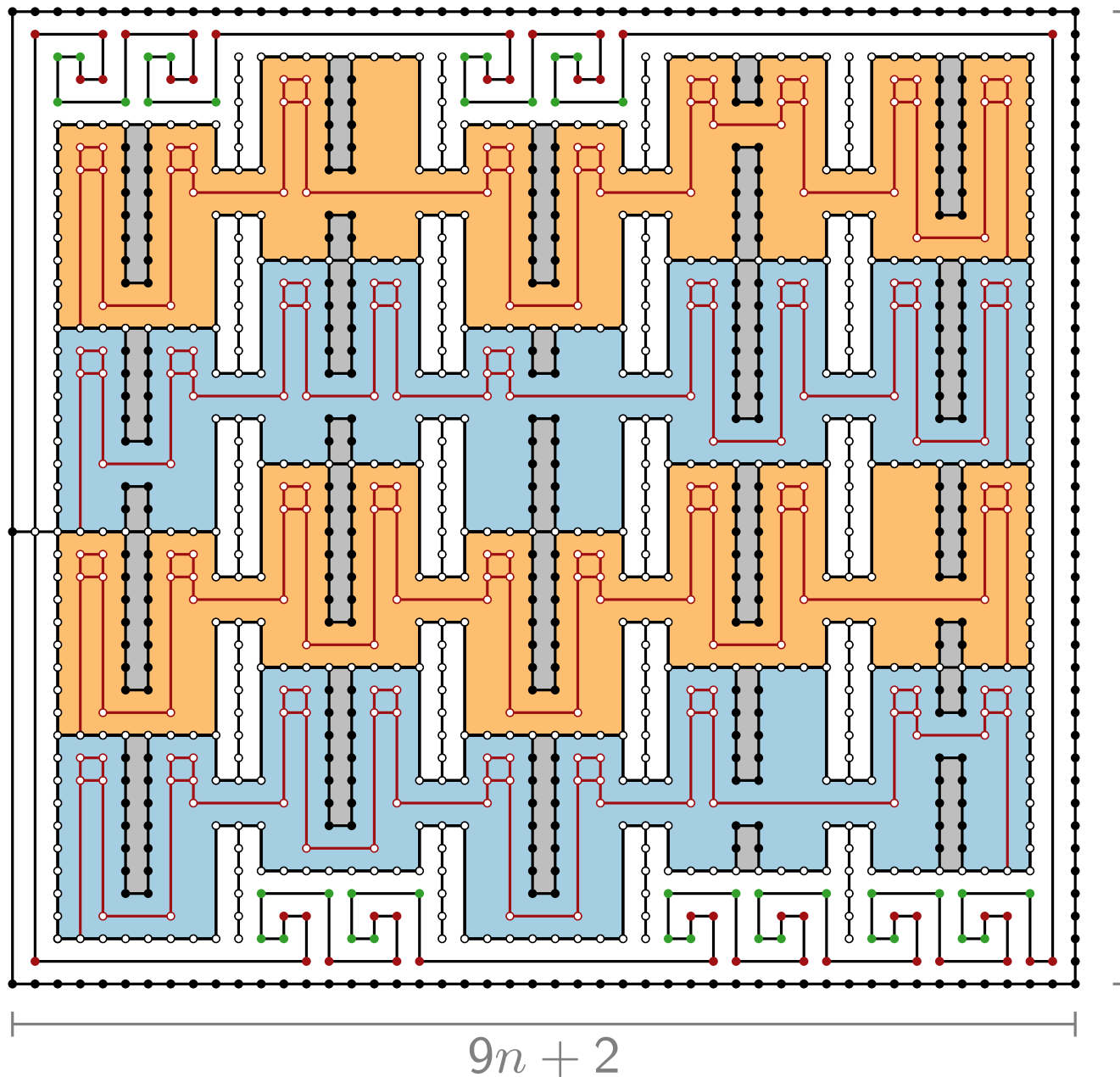
$$C_4 = x_4 \vee \neg x_5$$



insert $(2n - 1)$ -chain
through each clause

→ for every clause, there needs to be ≥ 1 “gap of a literal” to be on the same height as the “tunnel” to the next literal

Complete Reduction



Pick

$$K = (9n + 2) \times (9m + 7)$$

$$9m + 7$$

Then:

G under $H(G)$ has an
orthogonal drawing in area K

\Leftrightarrow

Φ satisfiable



Literature

- [GD Ch. 5] for detailed explanation
- [Tamassia 1987] “On embedding a graph in the grid with the minimum number of bends”
Original paper on flow for bend minimization.
- [van den Brand, Chen, Kyng, Liu, Peng, Probst, Sachdeva, Sidford 2023]
“A Deterministic Almost-Linear Time Algorithm for Minimum-Cost Flow”
State-of-the-art algorithm for solving the minimum-cost flow problem
(published recently in the proceedings of the FOCS 2023 conference).
- [Patrignani 2001] “On the complexity of orthogonal compaction”
NP-hardness proof for orthogonal representation of planar max-degree-4 graphs.
- [Evans, Fleszar, Kindermann, Saeedi, Shin, Wolff 2022]
“Minimum rectilinear polygons for given angle sequences”: Compacting cycles is NP-hard.
- [Antić, Liotta, Masařík Ortali, Pfretzschner, Stumpf, Wolff, Zink 2025]
“Unbent Collections of Orthogonal Drawings”: It is NP-hard to find two drawings such that each edge is straight in one and the total number of bends is minimum.