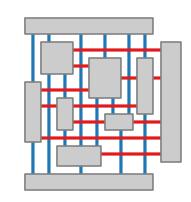


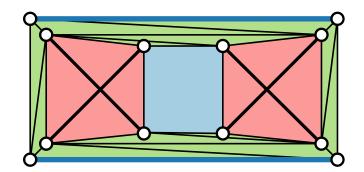
Visualization of Graphs

Lecture 11:

Beyond Planarity

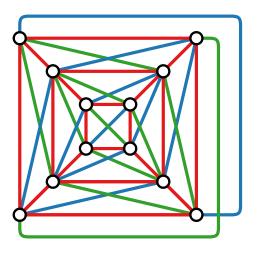
Drawing Graphs with Crossings





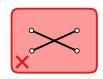
Part I: Graph Classes and Drawing Styles

Alexander Wolff



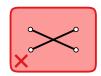
Planar graphs admit drawings in the plane without crossings.

Planar graphs admit drawings in the plane without crossings.



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Plane graph is a planar graph with a plane embedding = rotation system.



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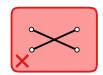
Planarity is recognizable in linear time.



Planar graphs admit drawings in the plane without crossings.

Plane graph is a planar graph with a plane embedding = rotation system.

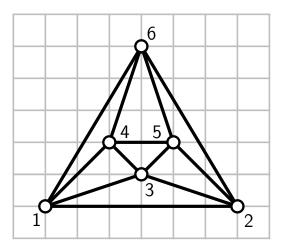
Planarity is recognizable in linear time.



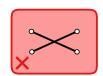
Planar graphs admit drawings in the plane without crossings.

Plane graph is a planar graph with a plane embedding = rotation system.

Planarity is recognizable in linear time.



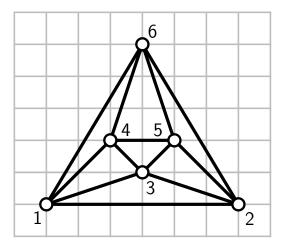
straight-line drawing



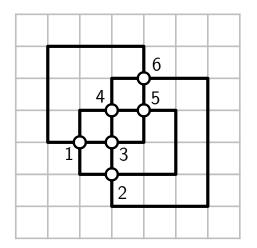
Planar graphs admit drawings in the plane without crossings.

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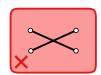
Planarity is recognizable in linear time.







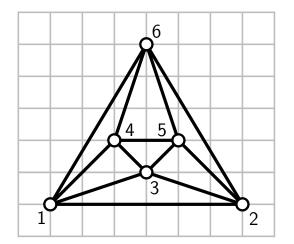
orthogonal drawing



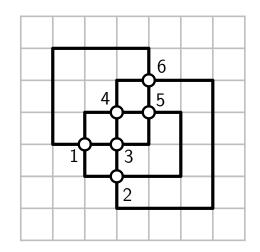
Planar graphs admit drawings in the plane without crossings.

Plane graph is a planar graph with a plane embedding = rotation system.

Planarity is recognizable in linear time.

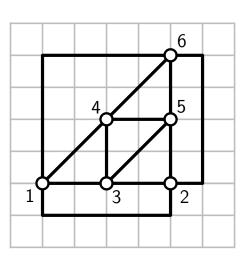






orthogonal drawing



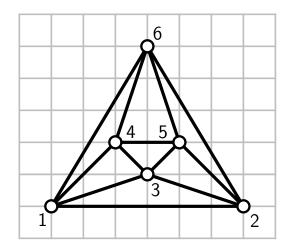


grid drawing with bends & 3 slopes

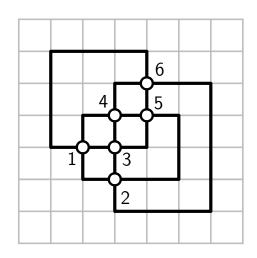
Planar graphs admit drawings in the plane without crossings.

Plane graph is a planar graph with a plane embedding = rotation system.

Planarity is recognizable in linear time.

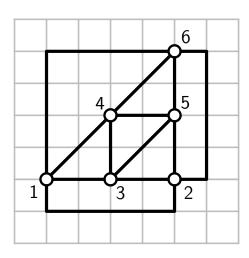


straight-line drawing

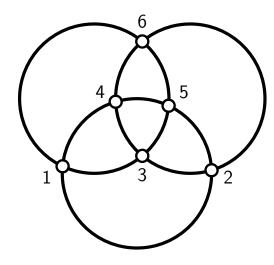


orthogonal drawing

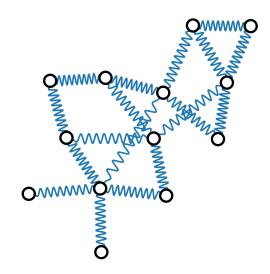




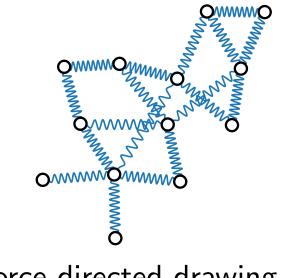
grid drawing with bends & 3 slopes



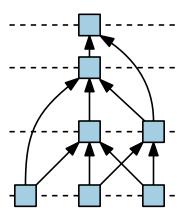
circular-arc drawing



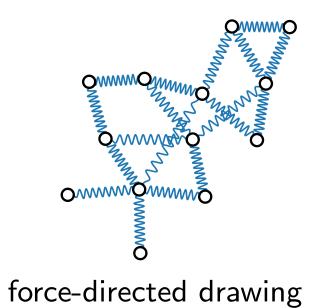
force-directed drawing



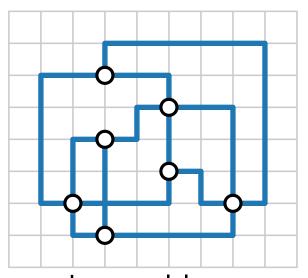
force-directed drawing



hierarchical drawing

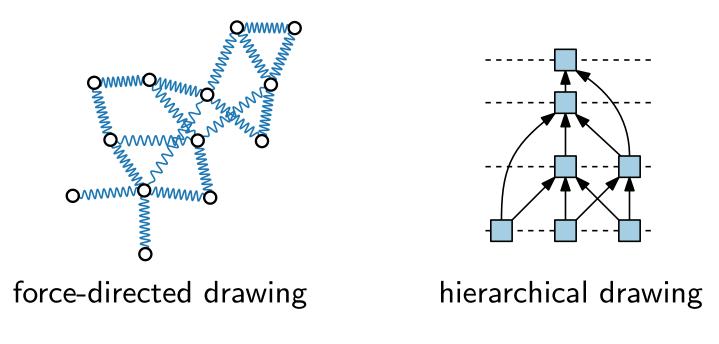


hierarchical drawing

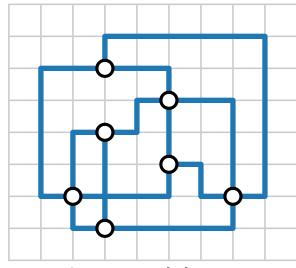


orthogonal layouts (via planarization)

We have seen a few drawing styles:

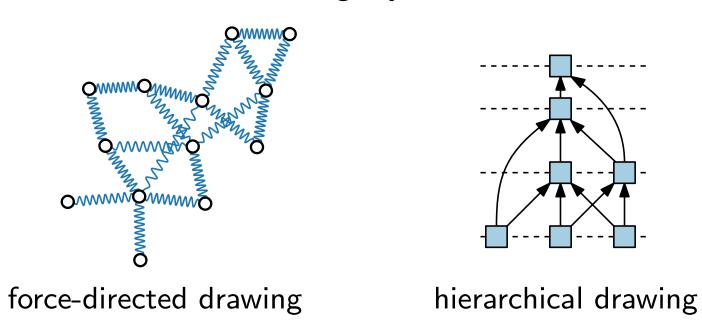


Maybe not all crossings are equally bad?



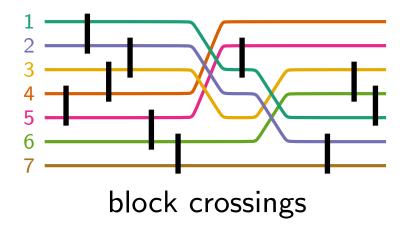
orthogonal layouts (via planarization)

We have seen a few drawing styles:

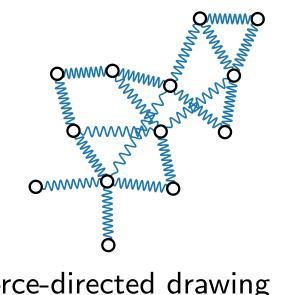


orthogonal layouts (via planarization)

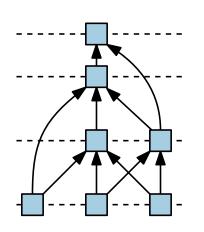
Maybe not all crossings are equally bad?



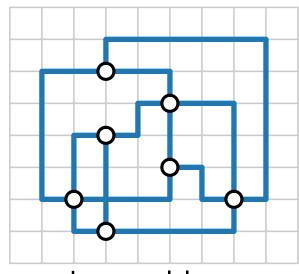
We have seen a few drawing styles:



force-directed drawing

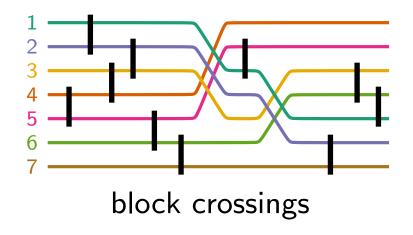


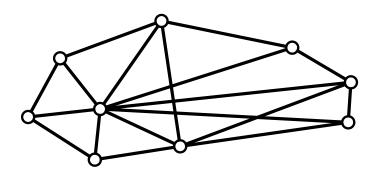
hierarchical drawing



orthogonal layouts (via planarization)

Maybe not all crossings are equally bad?

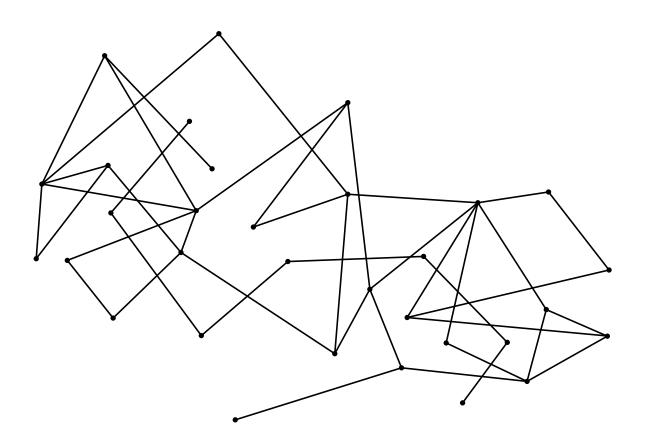




Which crossings feel worse?

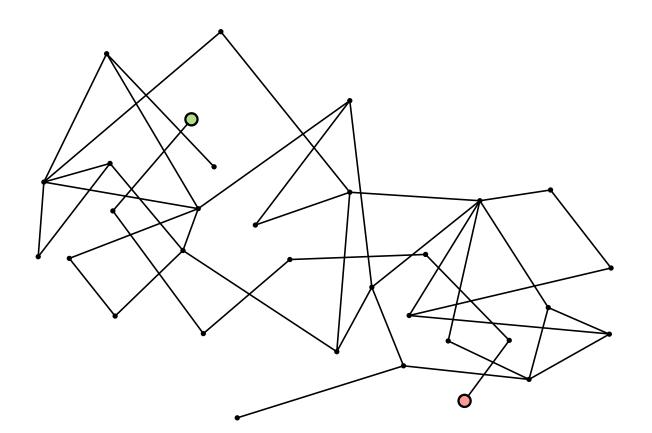
Eye-Tracking Experiment

Input: A graph drawing and designated path.



Eye-Tracking Experiment

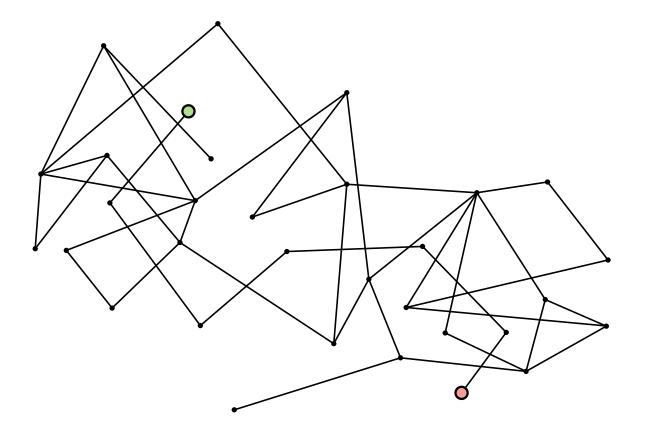
Input: A graph drawing and designated path.



Eye-Tracking Experiment

Input: A graph drawing and designated path.

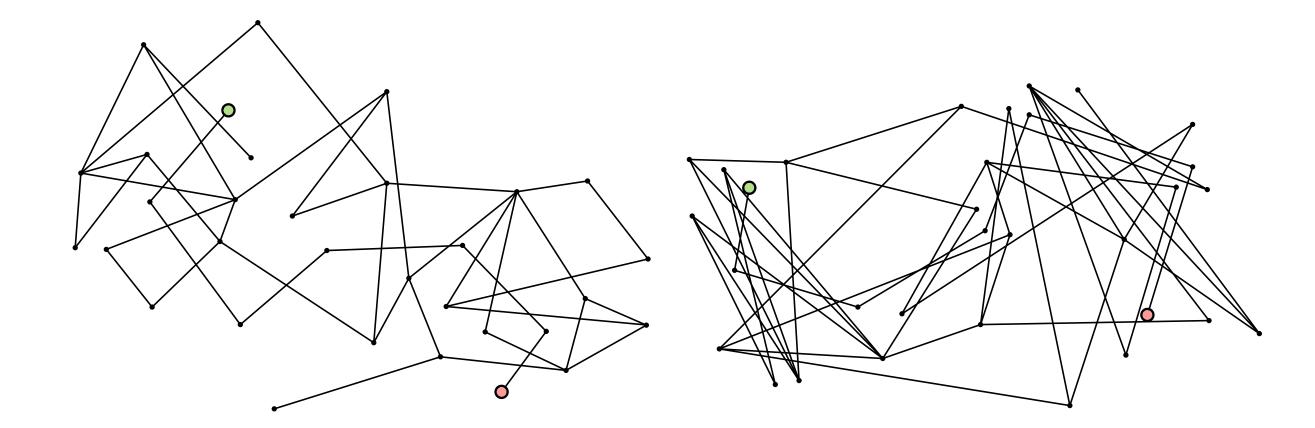
Task: Trace path and count number of edges.



Eye-Tracking Experiment

Input: A graph drawing and designated path.

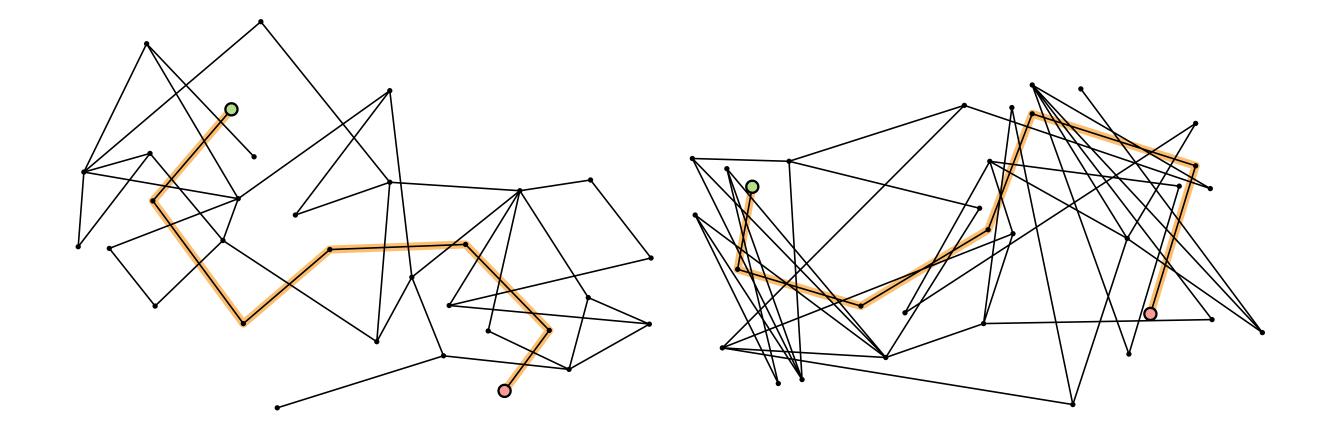
Task: Trace path and count number of edges.



Eye-Tracking Experiment

Input: A graph drawing and designated path.

Task: Trace path and count number of edges.

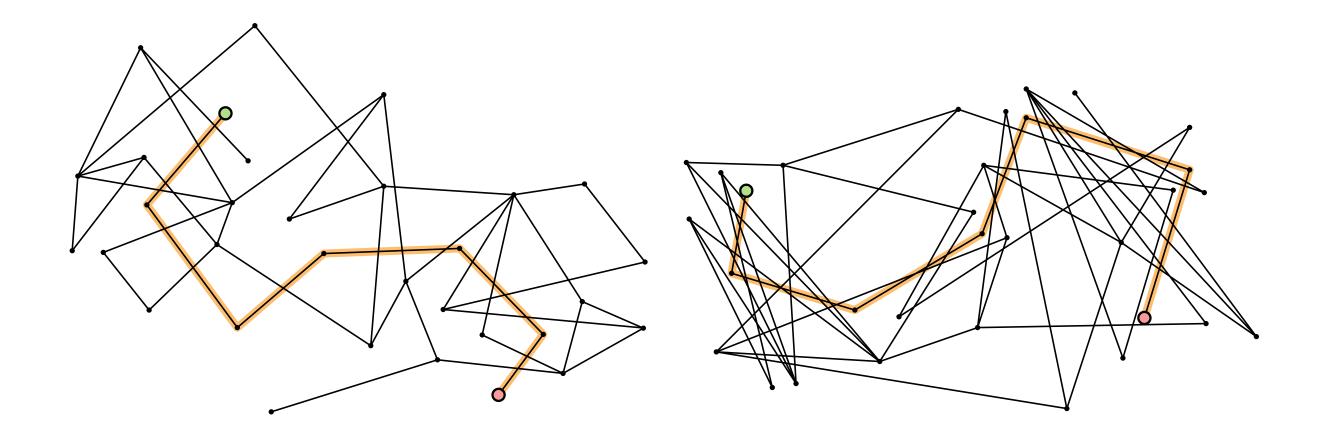


Eye-Tracking Experiment

Input: A graph drawing and designated path.

Task: Trace path and count number of edges.

Results:

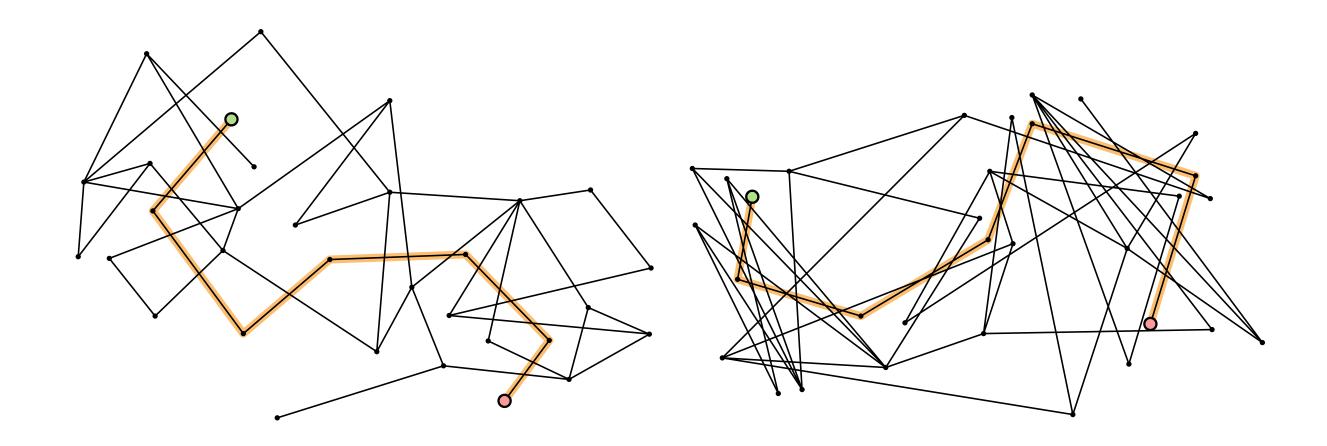


Eye-Tracking Experiment

Input: A graph drawing and designated path.

Task: Trace path and count number of edges.

Results: no crossings eye movements smooth and fast



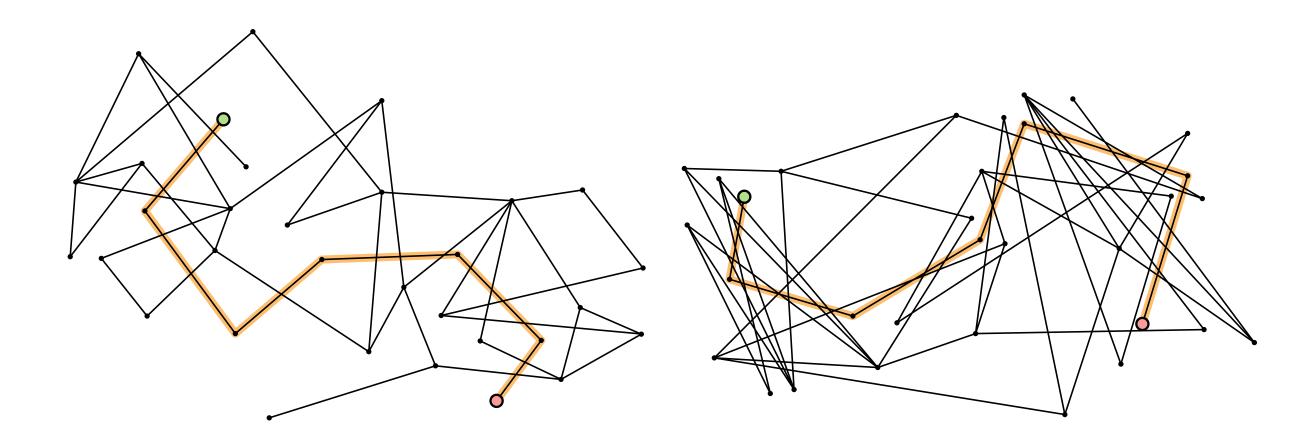
Eye-Tracking Experiment

Input: A graph drawing and designated path.

Task: Trace path and count number of edges.

Results: no crossings eye movements smooth and fast

large crossing angles eye movements smooth but slightly slower



Eye-Tracking Experiment

Input: A graph drawing and designated path.

Task: Trace path and count number of edges.

no crossings **Results:**

large crossing angles

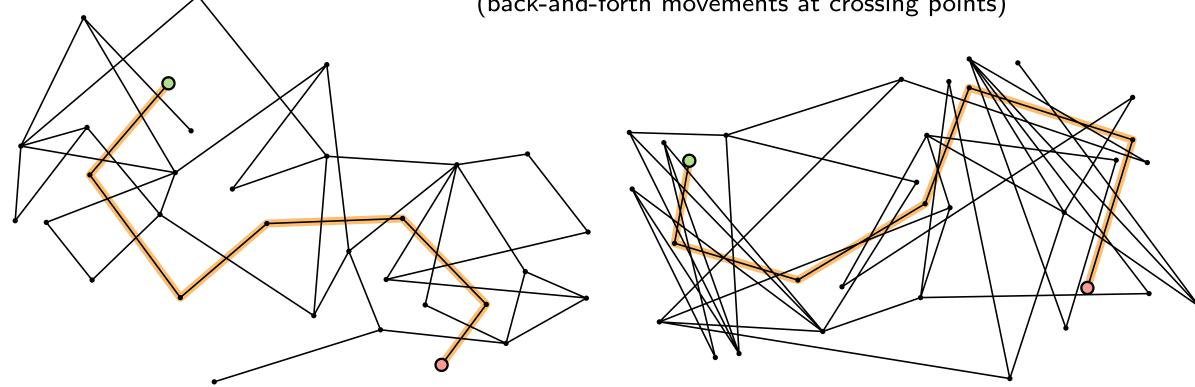
small crossing angles

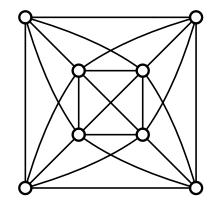
eye movements smooth and fast

eye movements smooth but slightly slower

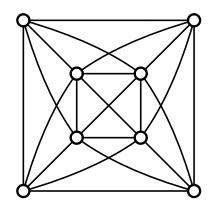
eye movements no longer smooth and very slow

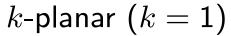
(back-and-forth movements at crossing points)



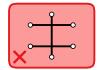


k-planar (k=1)

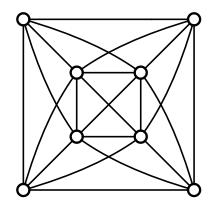


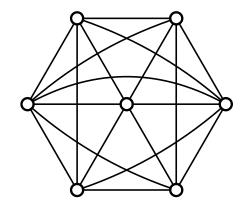






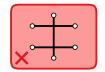


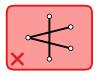


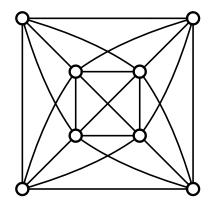


k-planar (k = 1) k-quasi-planar (k = 3)

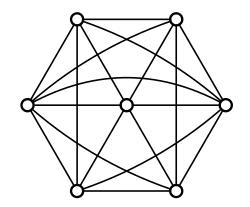






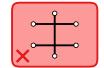


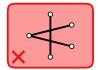
k-planar (k=1)

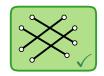


k-quasi-planar (k=3)

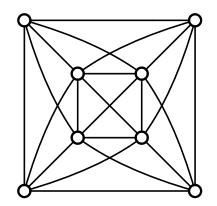


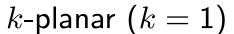


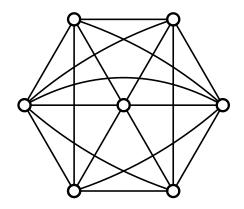




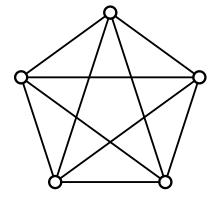






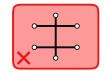


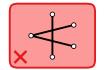
k-quasi-planar (k=3)

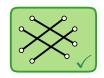




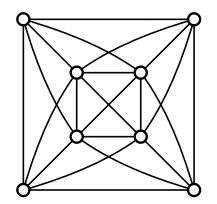




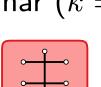




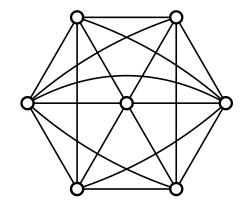




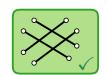
k-planar (k = 1)

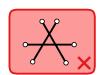


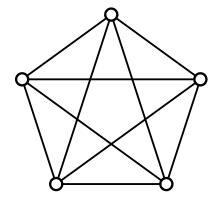




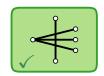
k-quasi-planar (k=3)



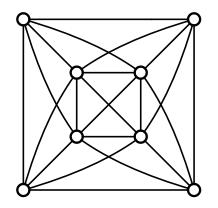




fan-planar



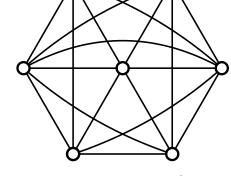




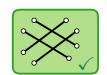
k-planar (k = 1)

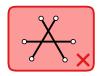


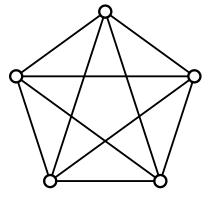




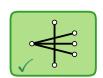
k-quasi-planar (k = 3)



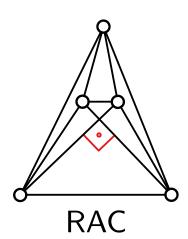


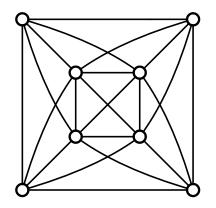


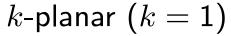
fan-planar

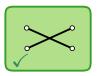


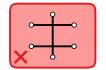


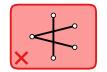


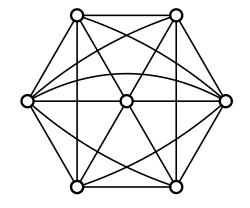




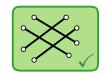




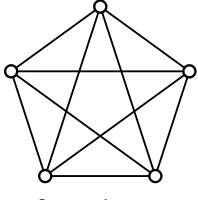




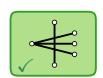
k-quasi-planar (k = 3)



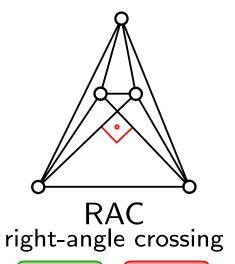


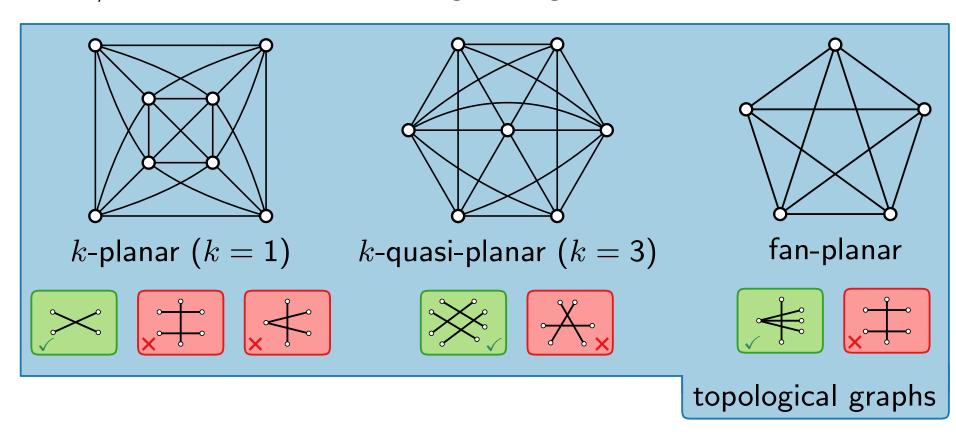


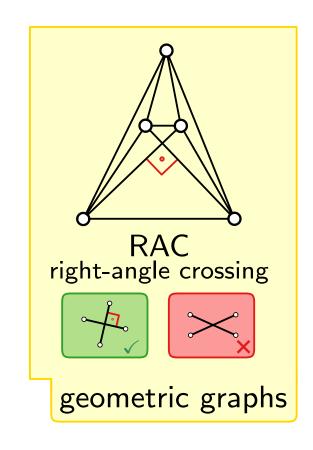
fan-planar



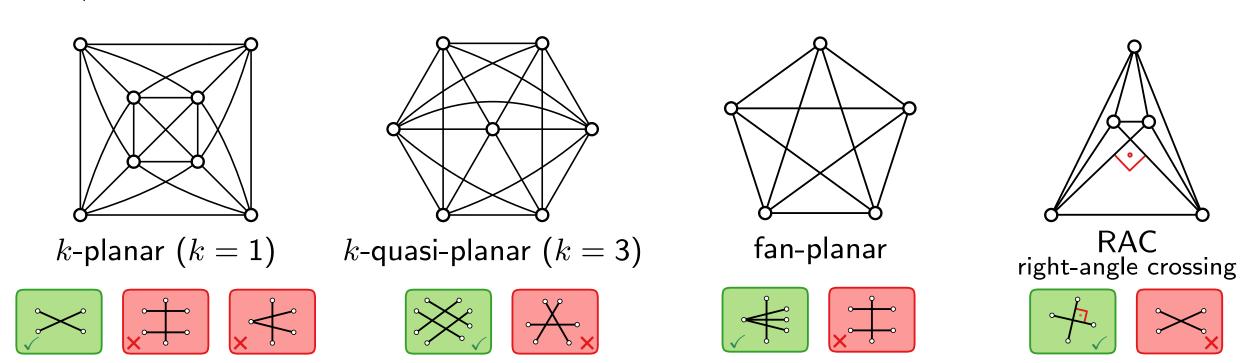






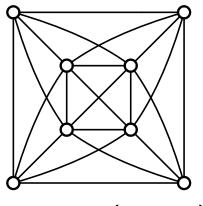


We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

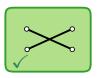


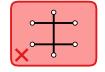
There are many more beyond-planar graph classes...

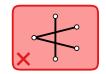
We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

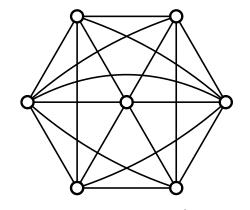


k-planar (k = 1)

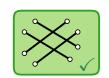


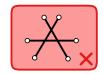


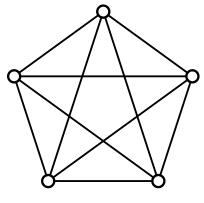




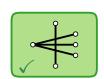
k-quasi-planar (k=3)



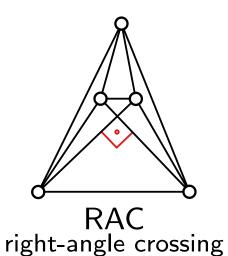


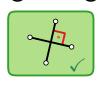


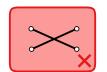
fan-planar



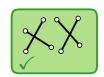


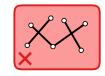






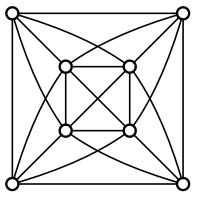
There are many more beyond-planar graph classes...





IC (independent crossing)

We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

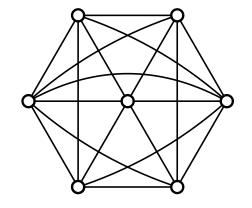


k-planar (k = 1)

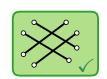


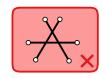


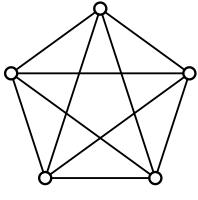




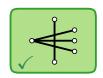
k-quasi-planar (k=3)



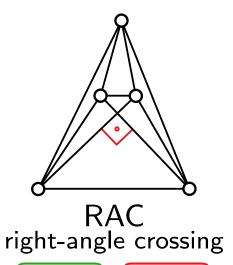




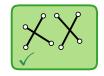
fan-planar

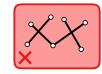




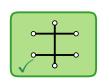


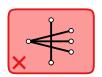
There are many more beyond-planar graph classes...





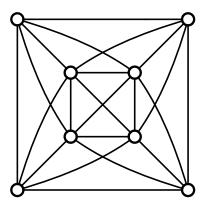
IC (independent crossing)



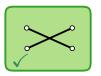


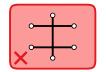
fan-crossing-free

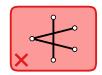
We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

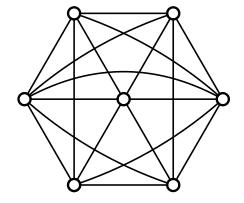


k-planar (k = 1)

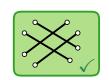


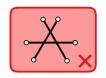


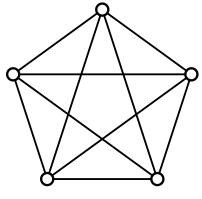




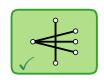
k-quasi-planar (k=3)

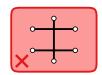


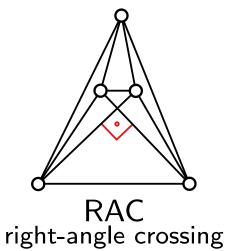




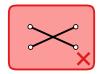
fan-planar



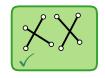


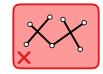




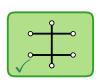


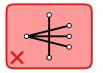
There are many more beyond-planar graph classes...



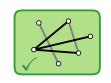


IC (independent crossing)





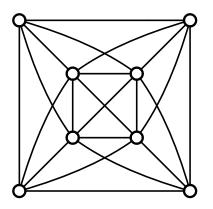
fan-crossing-free



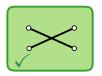


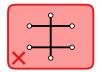
skewness-k (k = 2)

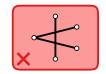
We define **aesthetics** for edge crossings and avoid/minimize "bad" crossing configurations.

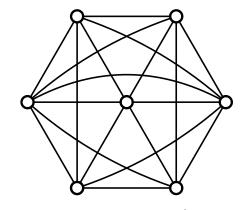


k-planar (k = 1)

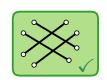


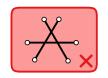


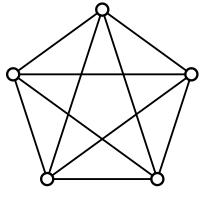




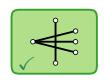
k-quasi-planar (k = 3)

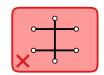


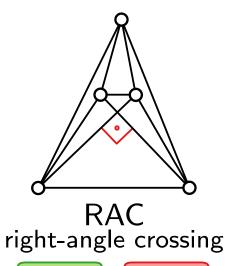




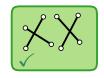
fan-planar

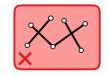




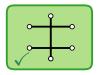


There are many more beyond-planar graph classes...

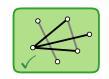


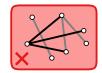


IC (independent crossing)



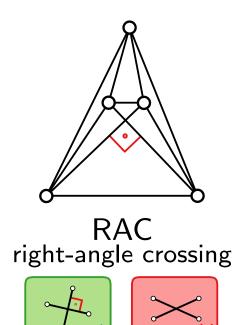
fan-crossing-free

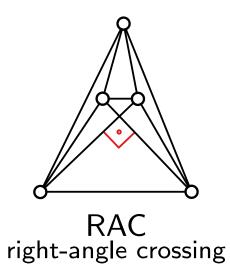


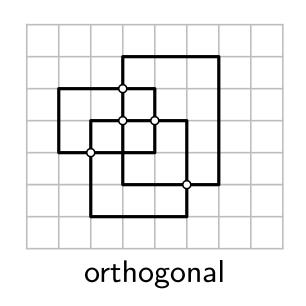


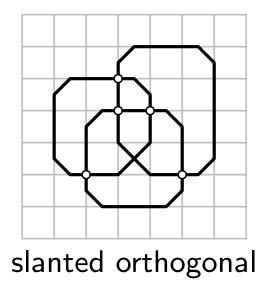
skewness-k (k = 2)

combinations, ...

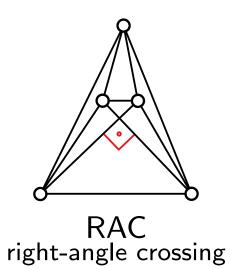


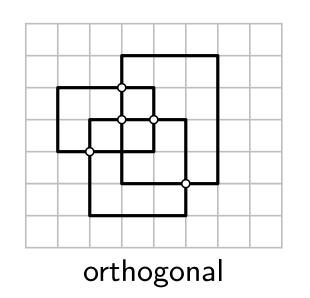


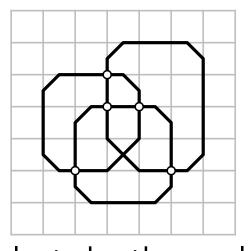


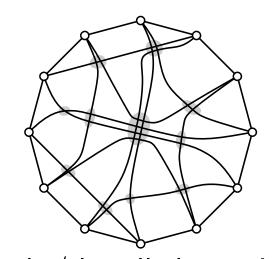








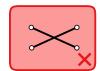




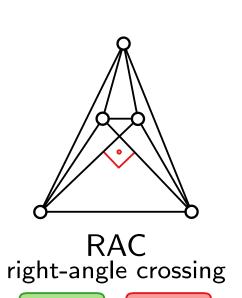
block / bundled crossings slanted orthogonal

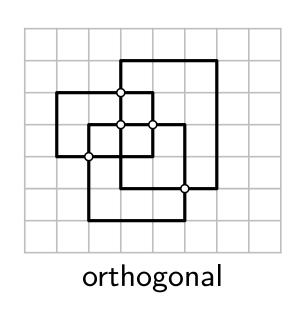
vs. 12 bundle crossings

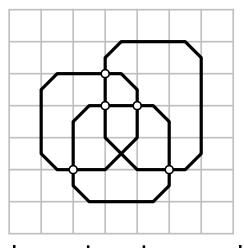


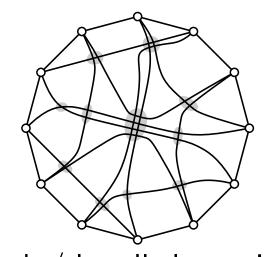


circular layout: 28 invididual





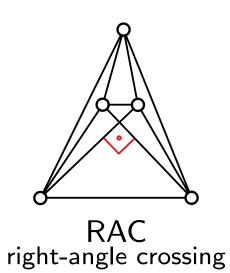


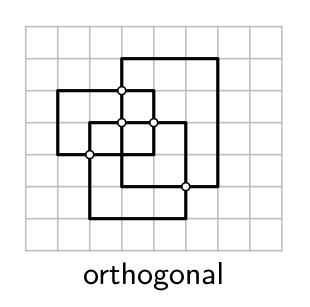


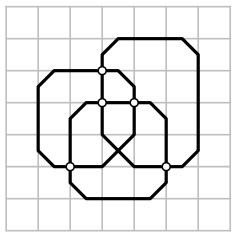
slanted orthogonal block / bundled crossings

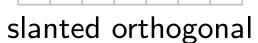
circular layout: 28 invididual vs. 12 bundle crossings

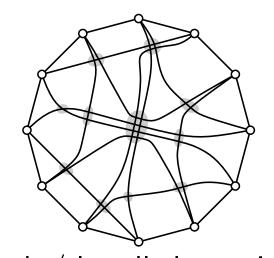






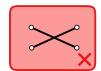


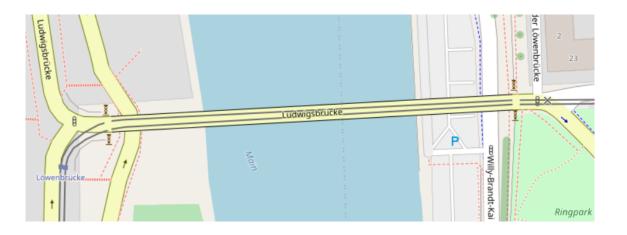


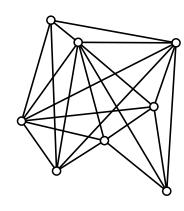


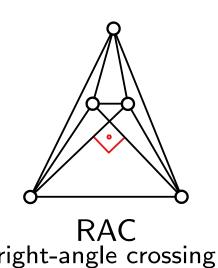
block / bundled crossings circular layout: 28 invididual vs. 12 bundle crossings

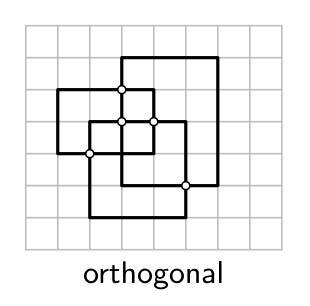


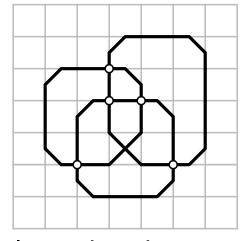


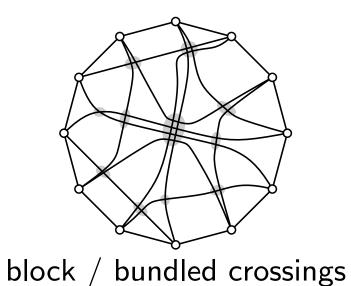




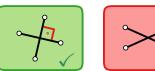








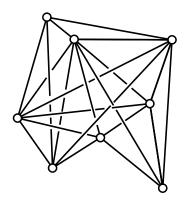
right-angle crossing



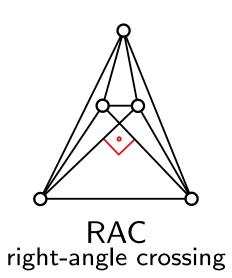
slanted orthogonal

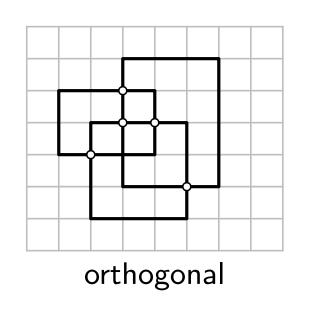
circular layout: 28 invididual vs. 12 bundle crossings

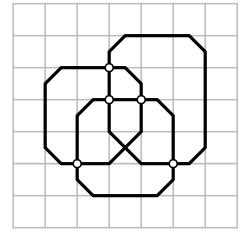


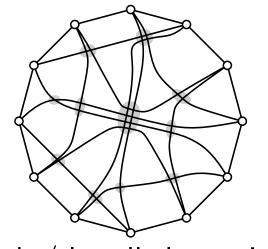


cased crossings







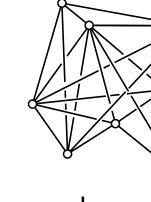


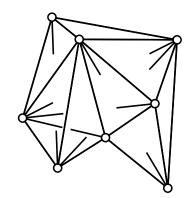
slanted orthogonal

block / bundled crossings circular layout: 28 invididual vs. 12 bundle crossings

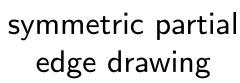




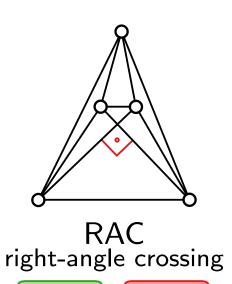


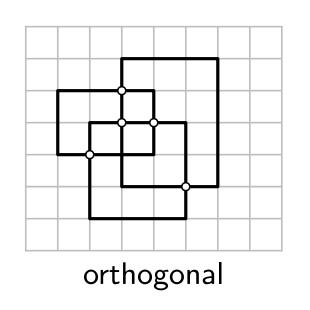


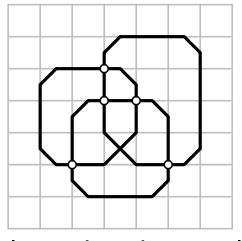
cased crossings

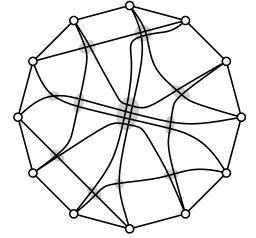






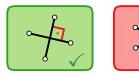


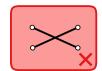


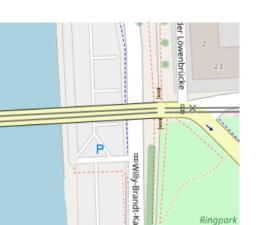


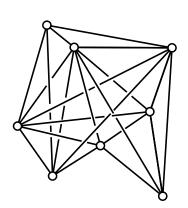
slanted orthogonal block / bundled crossings

circular layout: 28 invididual vs. 12 bundle crossings

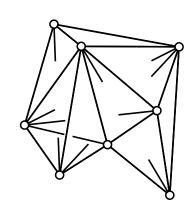




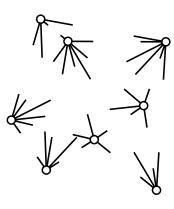




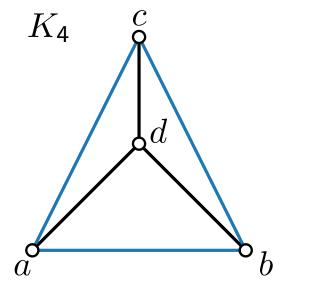
cased crossings

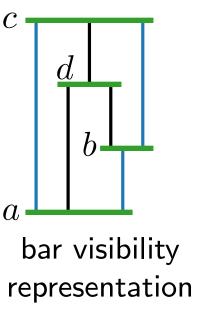


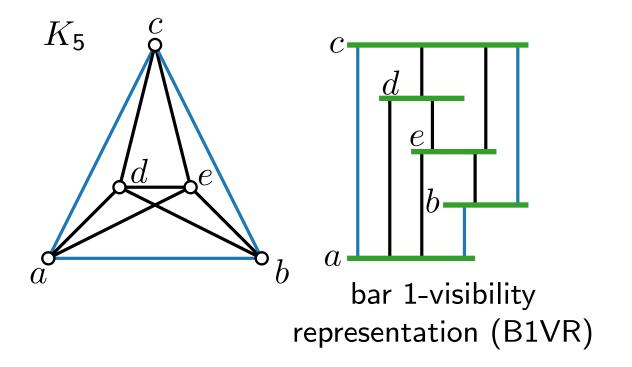
symmetric partial edge drawing

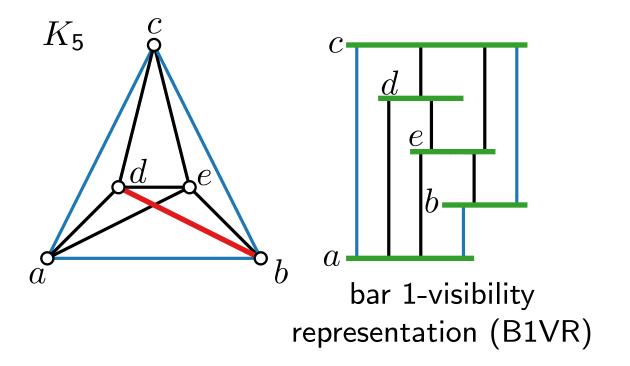


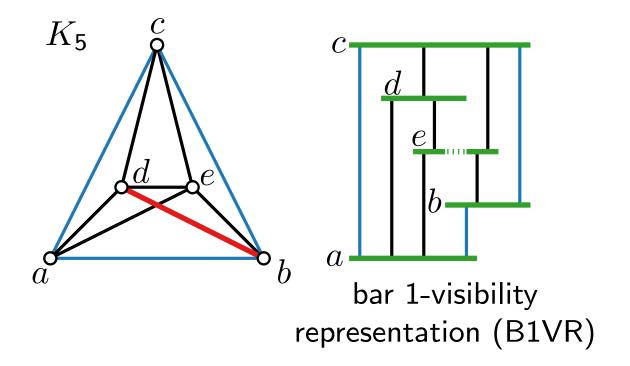
1/4-SHPED

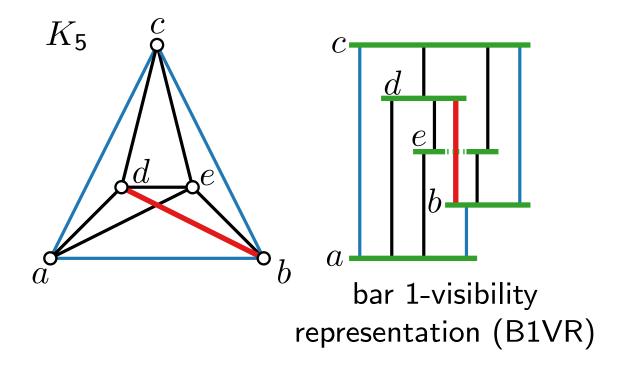


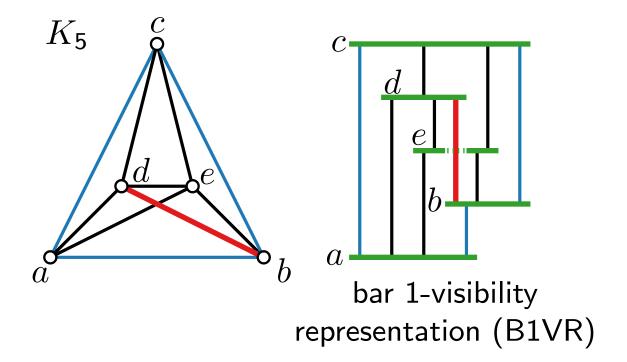




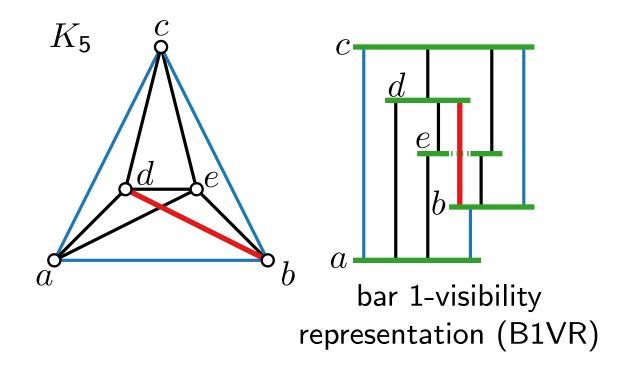


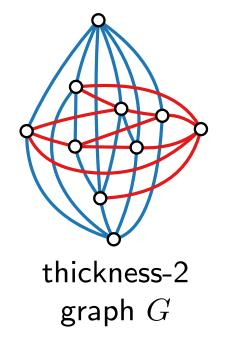




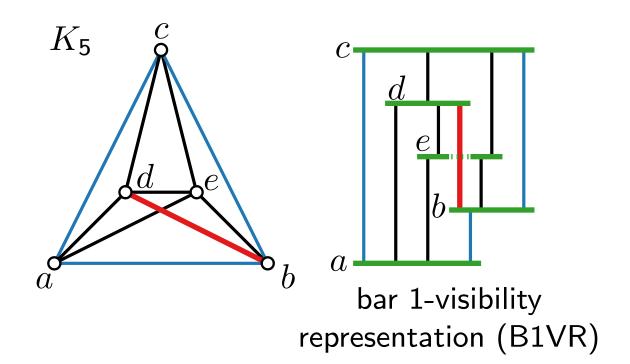


Every 1-planar graph admits a B1VR. [Brandenburg 2014; Evans et al. 2014; Angelini et al. 2018]

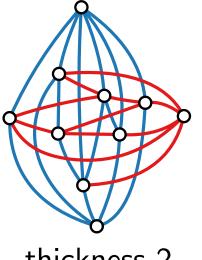




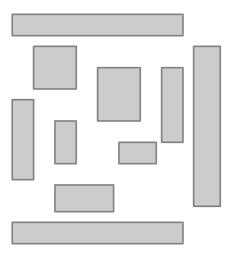
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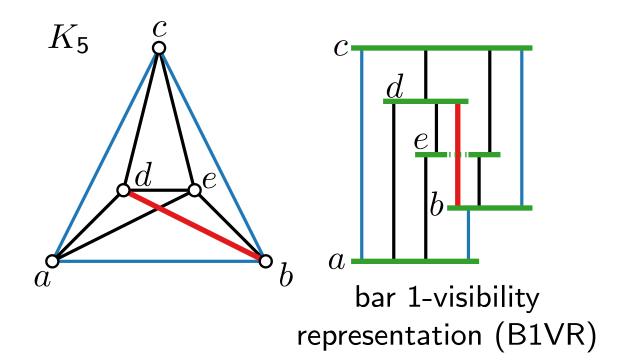


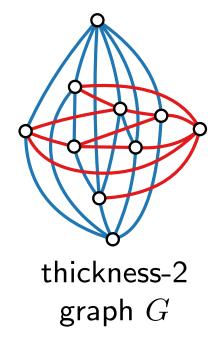


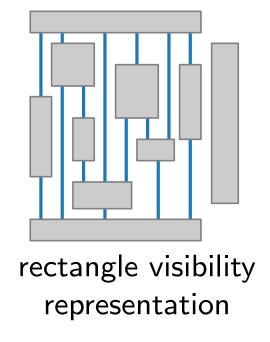
thickness-2 graph G



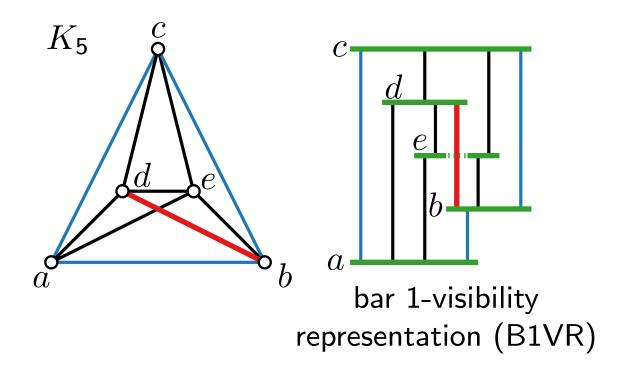
rectangle visibility representation



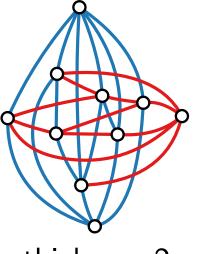




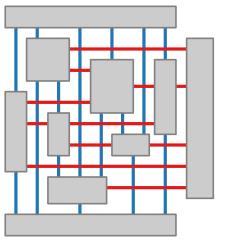
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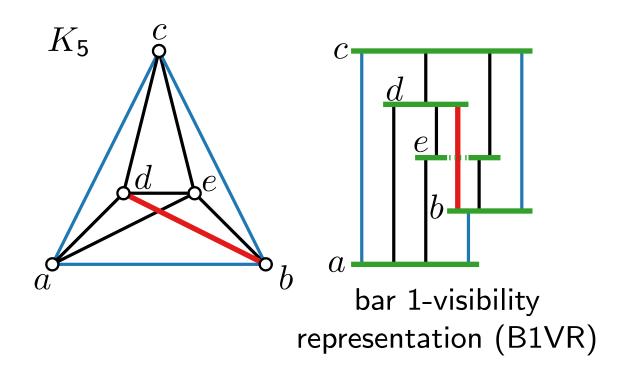




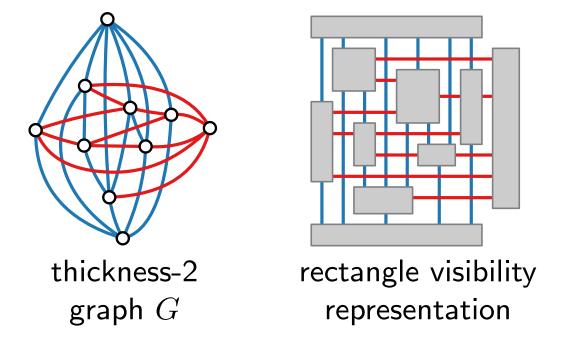
thickness-2 graph G



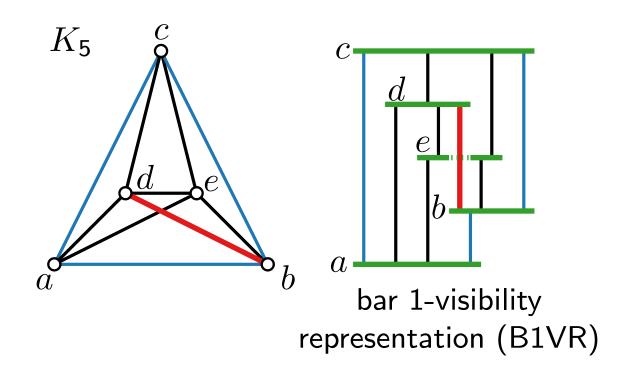
rectangle visibility representation



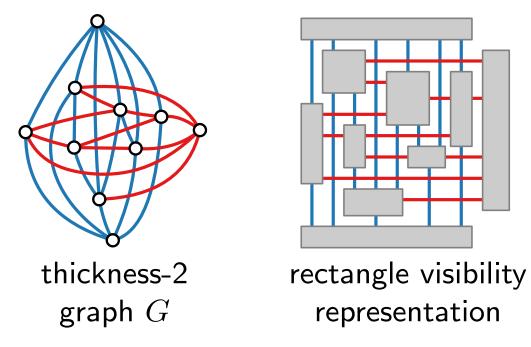
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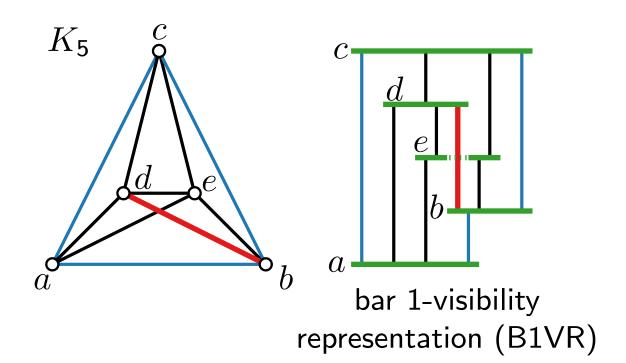
lacksquare G has at most 6n-20 edges. [Bose et al. 1997]



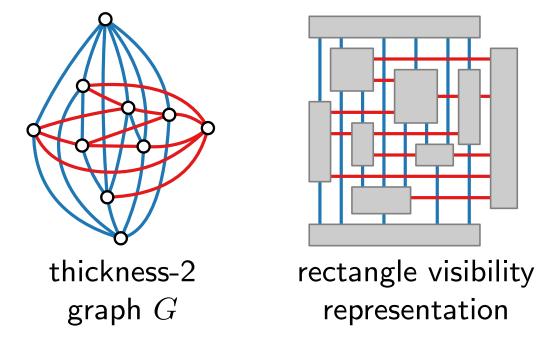
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- lacksquare G has at most 6n-20 edges. [Bose et al. 1997]
- Recognition is NP-complete. [Shermer 1996]



Every 1-planar graph admits a B1VR. [Brandenburg 2014; Evans et al. 2014; Angelini et al. 2018]



- lacksquare G has at most 6n-20 edges. [Bose et al. 1997]
- Recognition is NP-complete. [Shermer 1996]
- Recognition becomes polynomial if embedding is fixed. [Biedl et al. 2018]

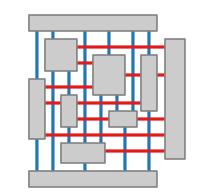


Visualization of Graphs

Lecture 11:

Beyond Planarity

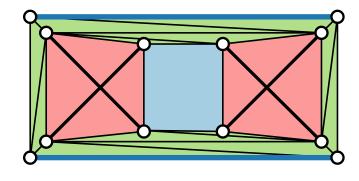
Drawing Graphs with Crossings

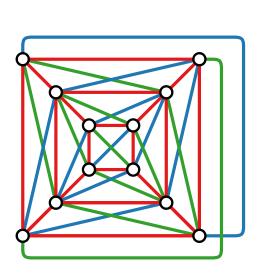




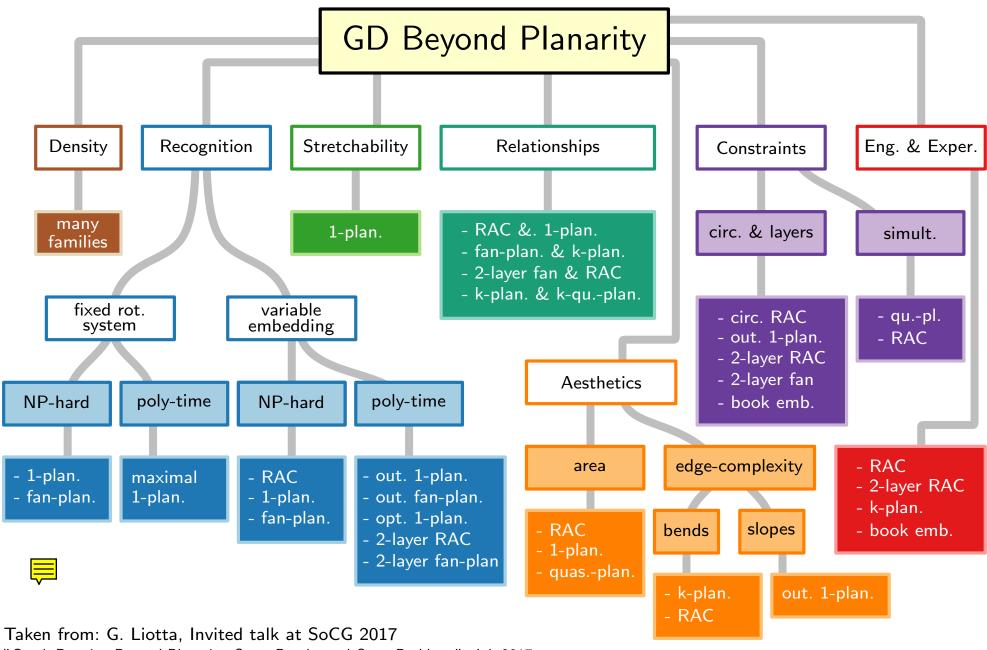
Density & Relationships

Alexander Wolff



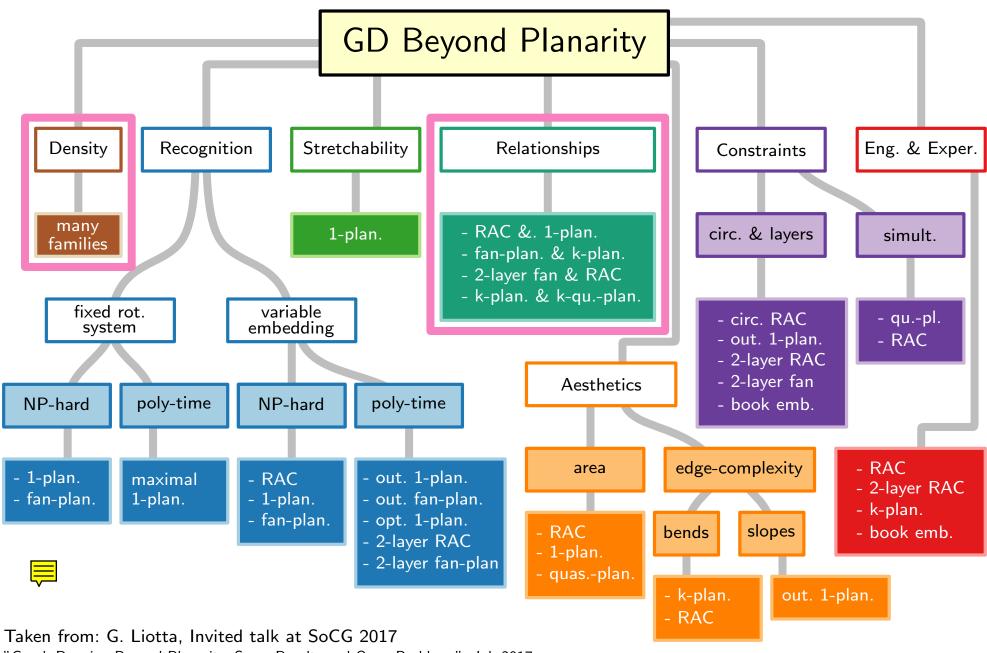


GD Beyond Planarity: a Taxonomy



[&]quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

GD Beyond Planarity: a Taxonomy



[&]quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

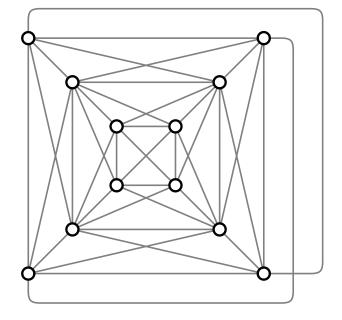
Theorem. [Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Theorem.

[Ringel 1965, Pach & Tóth 1997]

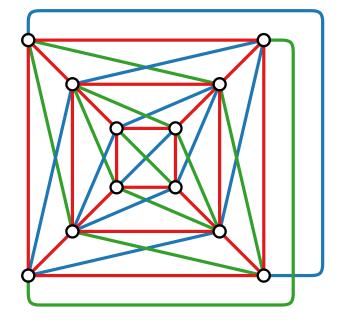
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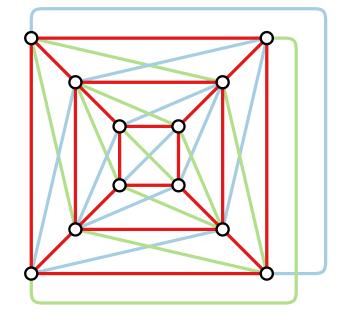
Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

■ Let the red edges be those that do not cross.

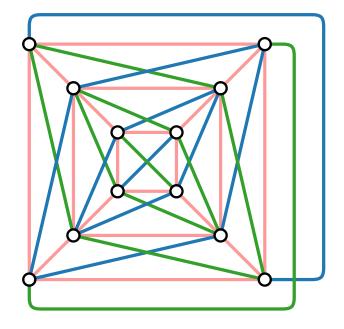


Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.

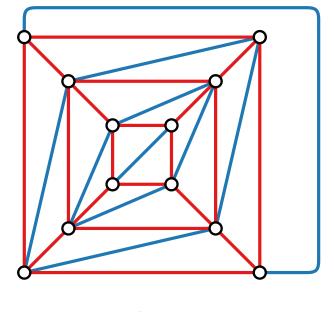


Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with



 G_{rb}

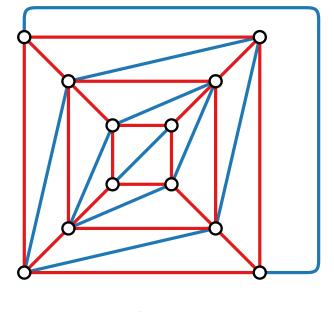
Theorem.

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A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with

$$m_{rb} \le 3n - 6$$



 G_{rb}

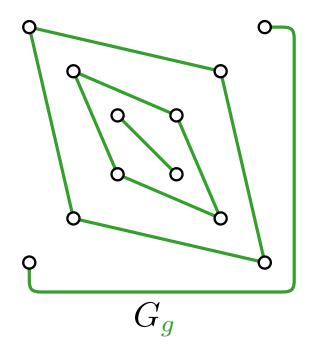
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[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with $m_{rb} \leq 3n-6$
- lacksquare and a green plane graph G_g with



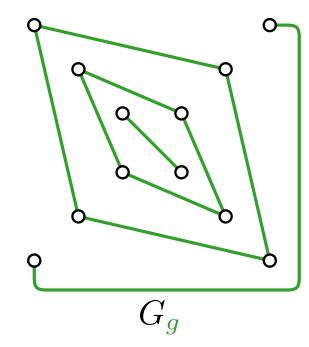
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A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with $m_{rb} \leq 3n-6$
- and a green plane graph G_g with $m_g \leq 3n-6$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

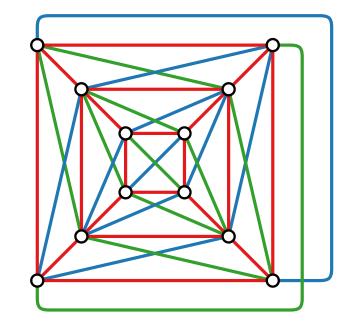
Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with

$$m_{rb} \leq 3n - 6$$

lacksquare and a green plane graph G_g with

$$m_g \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

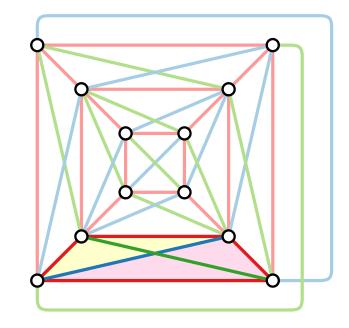
A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with $m_{rb} < 3n 6$



$$m_g \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

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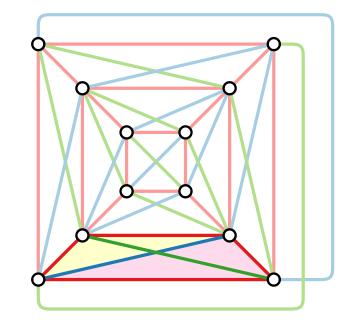
- Let the red edges be those that do not cross.
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lacksquare and a green plane graph G_g with

$$m_g \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$

$$m_g \leq f_{rb}/2$$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

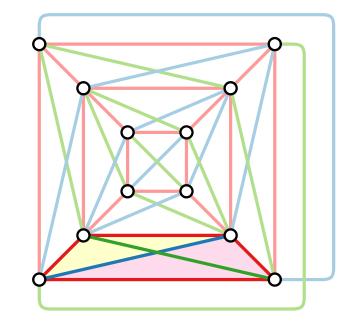
- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with

$$m_{rb} \le 3n - 6$$

lacksquare and a green plane graph G_g with

$$m_g \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$

$$m_g \le f_{rb}/2 \le (2n-4)/2$$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

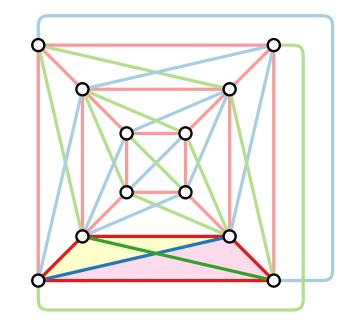
- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with

$$m_{rb} \le 3n - 6$$

lacksquare and a green plane graph G_q with

$$m_g \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$

$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with

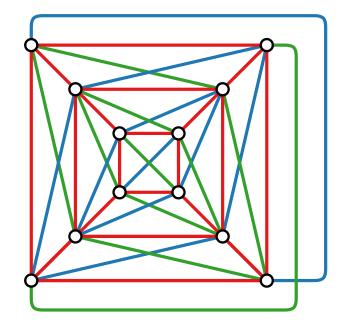
$$m_{rb} \leq 3n - 6$$

lacksquare and a green plane graph G_g with

$$m_g \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$

$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$

$$\Rightarrow m = m_{rb} + m_g$$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8 edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with

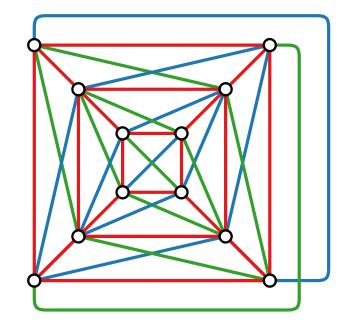
$$m_{rb} \leq 3n - 6$$

lacksquare and a green plane graph G_g with

$$m_g \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_g \leq 6n - 12$

$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$

 $\Rightarrow m = m_{rb} + m_g \le 3n - 6 + n - 2 = 4n - 8$



Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with $m_{rb} < 3n - 6$
- \blacksquare and a green plane graph G_q with

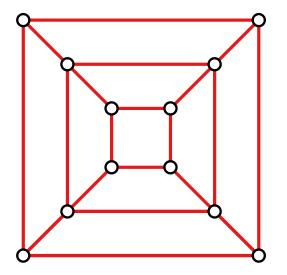
$$m_g \leq 3n-6$$

$$m_q \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_q \leq 6n - 12$

Observe that each green edge joins two faces in G_{rb} .

$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$

 $\Rightarrow m = m_{rb} + m_g \le 3n-6+n-2 = 4n-8$



$$2n-4$$
 edges $n-2$ faces

Theorem.

[Ringel 1965, Pach & Tóth 1997]

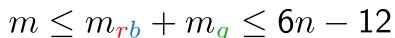
A 1-planar graph with n vertices has at most 4n-8edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with $m_{rb} < 3n - 6$
- \blacksquare and a green plane graph G_q with

$$m_a \leq 3n - 6$$

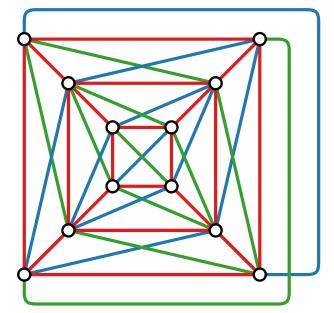
$$m_q \leq 3n-6$$
 $\Rightarrow m \leq m_{rb}+m_q \leq 6n-12$ Edges per face: 2 edges



Observe that each green edge joins two faces in G_{rb} .

$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$

 $\Rightarrow m = m_{rb} + m_g \le 3n-6+n-2 = 4n-8$



$$2n-4$$
 edges

$$n-2$$
 faces

Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8edges, which is a tight bound.

Proof sketch.

- Let the red edges be those that do not cross.
- Each blue edge crosses a green edge.
- This yields a red-blue plane graph G_{rb} with

$$m_{rb} \leq 3n - 6$$

 \blacksquare and a green plane graph G_q with

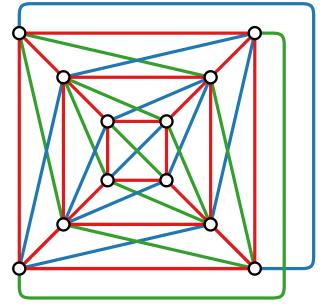
$$m_g \leq 3n-6$$

$$m_q \leq 3n - 6$$
 $\Rightarrow m \leq m_{rb} + m_q \leq 6n - 12$

Observe that each green edge joins two faces in G_{rb} .

$$m_g \le f_{rb}/2 \le (2n-4)/2 = n-2$$

$$\Rightarrow m = m_{rb} + m_g \le 3n - 6 + n - 2 = 4n - 8$$



$$2n-4$$
 edges

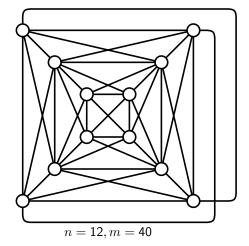
$$n-2$$
 faces

Total:
$$4n - 8$$
 edges

Theorem.

[Ringel 1965, Pach & Tóth 1997]

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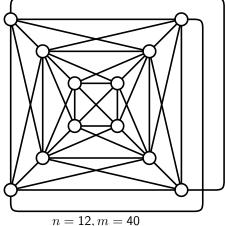


Theorem.

[Ringel 1965, Pach & Tóth 1997]

A 1-planar graph with n vertices has at most 4n-8edges, which is a tight bound.

A 1-planar graph with n vertices is called **optimal** if it has exactly 4n - 8 edges.



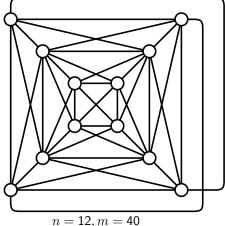
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A 1-planar graph with n vertices has at most 4n-8edges, which is a tight bound.

A 1-planar graph with n vertices is called **optimal** if it has exactly 4n-8 edges.

A 1-planar graph is called **maximal** if adding any edge would result in a non-1-planar graph.



Theorem.

[Ringel 1965, Pach & Tóth 1997]

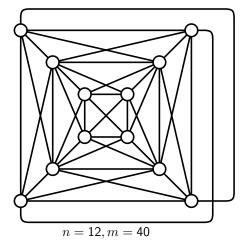
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Theorem.

[Brandenburg et al. 2013]



Theorem.

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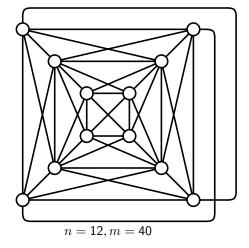
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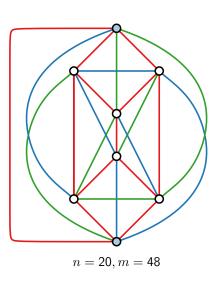
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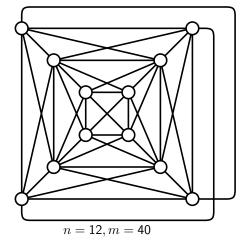
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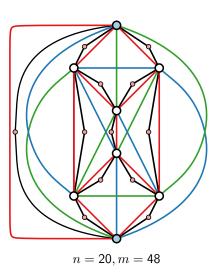
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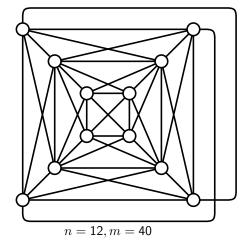
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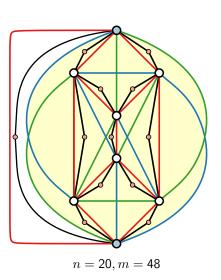
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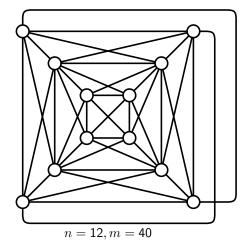
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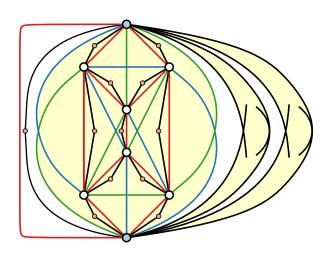
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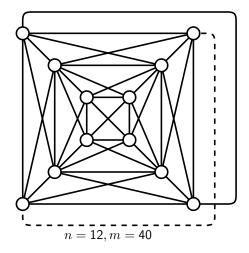
[Brandenburg et al. 2013]

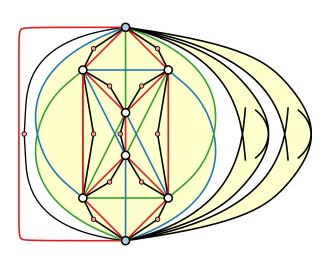
There are maximal 1-planar graphs with n vertices and 45/17n - O(1) edges.

Theorem.

[Didimo 2013]

A 1-planar graph with n vertices that admits a straight-line drawing has at most 4n-9 edges.





Theorem.

A k-planar graph with n vertices has at most:

k number of edges

Theorem.

A k-planar graph with n vertices has at most:

k number of edges

0 Euler's formula

Theorem.

A k-planar graph with n vertices has at most:

k number of edges

3(n-2)

Euler's formula

Theorem.

A k-planar graph with n vertices has at most:

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3(n-2)

Euler's formula

4(n-2)

[Ringel 1965]

Theorem.

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Euler's formula

[Ringel 1965]

[Pach and Tóth 1997]

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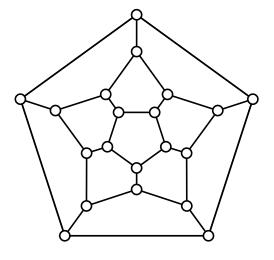
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optimal 2-planar

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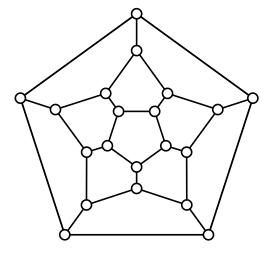
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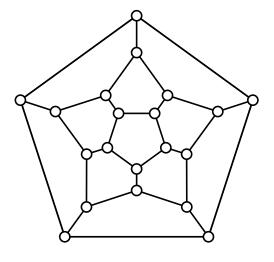
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optimal 2-planar

Planar structure:

Edges per face:

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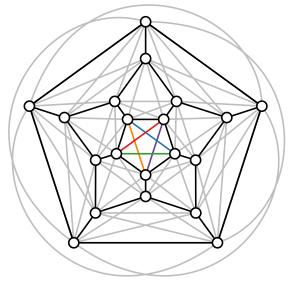
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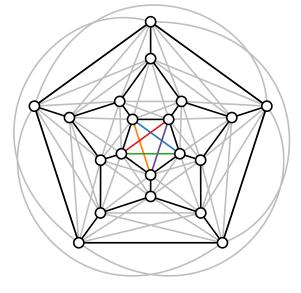
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Euler's formula

[Ringel 1965]

[Pach and Tóth 1997]



optimal 2-planar

Planar structure:

$$n - m + f = 2$$
$$m = c \cdot f ?$$

Edges per face:

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3(n-2)

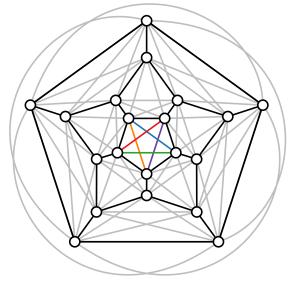
4(n-2)

2

Euler's formula

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$$m = \frac{5}{2}f$$

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A k-planar graph with n vertices has at most:

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3(n-2)

4(n-2)

2

Euler's formula

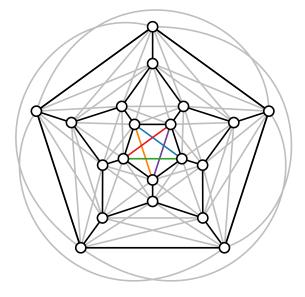
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optimal 2-planar

Planar structure:

$$\frac{5}{3}(n-2)$$
 edges $\frac{2}{3}(n-2)$ faces

Edges per face:

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4(n-2)

2

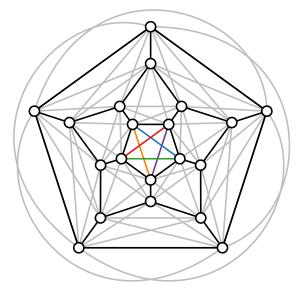
Euler's formula

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Planar structure:

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 edges $\frac{2}{3}(n-2)$ faces

Edges per face: 5 edges

Theorem.

A k-planar graph with n vertices has at most:

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4(n-2)

2

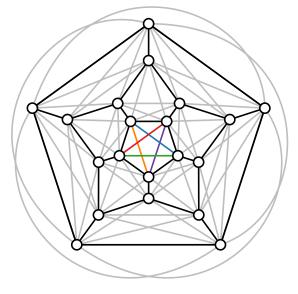
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 edges $\frac{2}{3}(n-2)$ faces

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Total: 5(n-2) edges

Theorem.

A k-planar graph with n vertices has at most:

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0 3(n-2)

4(n-2)

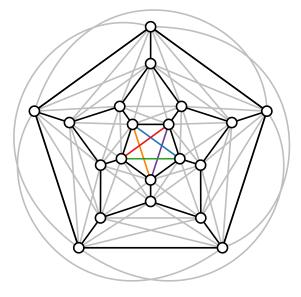
2 5(n-2)

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4(n-2)

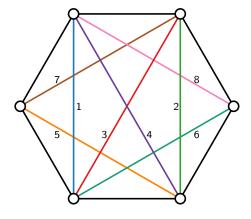
5(n-2)

3

Euler's formula

[Ringel 1965]

[Pach and Tóth 1997]



optimal 3-planar

Theorem.

A k-planar graph with n vertices has at most:

k number of edges

0 3(n-2)

1 4(n-2)

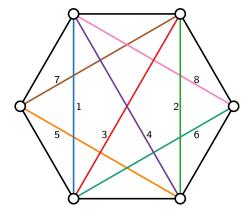
5(n-2)

5.5(n-2)

Euler's formula

[Ringel 1965]

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0 3(n-2)

4(n-2)

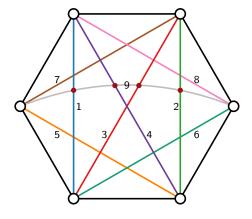
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4(n-2)

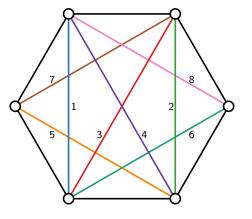
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0 3(n-2)

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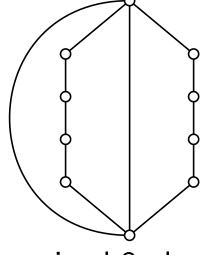
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5.5(n-2)

Euler's formula

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[Pach and Tóth 1997]



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Theorem.

A k-planar graph with n vertices has at most:

number of edges k

3(n-2)

4(n-2)

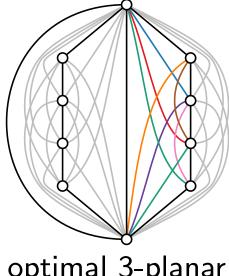
5(n-2)

5.5(n-2)3

Euler's formula

[Ringel 1965]

[Pach and Tóth 1997]



optimal 3-planar

Theorem.

A k-planar graph with n vertices has at most:

knumber of edges

3(n-2)0

4(n-2)

5(n-2)

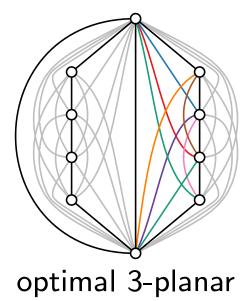
5.5(n-2)3

Euler's formula

[Ringel 1965]

[Pach and Toth 1997]

[Pach et al. 2006]



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 edges $\frac{1}{2}(n-2)$ faces

Edges per face: 8 edges

Total: 5.5(n-2) edges

Theorem.

A k-planar graph with n vertices has at most:

k number of edges

0 3(n-2)

4(n-2)

5(n-2)

5.5(n-2)

6(n-2)

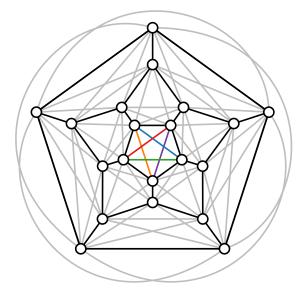
Euler's formula

[Ringel 1965]

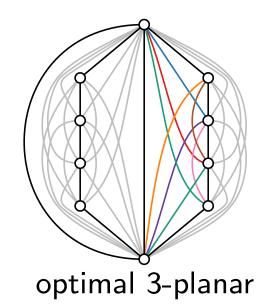
[Pach and Tóth 1997]

[Pach et al. 2006]

[Ackerman 2015]



optimal 2-planar



Theorem.

A k-planar graph with n vertices has at most:

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3(n-2)0

4(n-2)

5(n-2)

5.5(n-2)

6(n-2)

 $4.108\sqrt{k}n$

Euler's formula

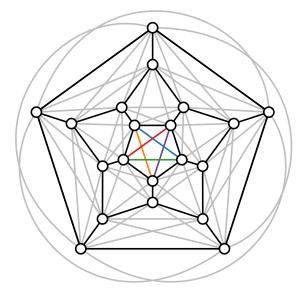
[Ringel 1965]

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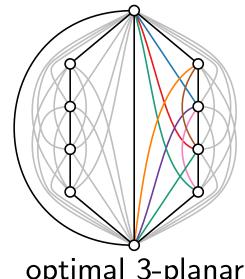
[Pach et al. 2006]

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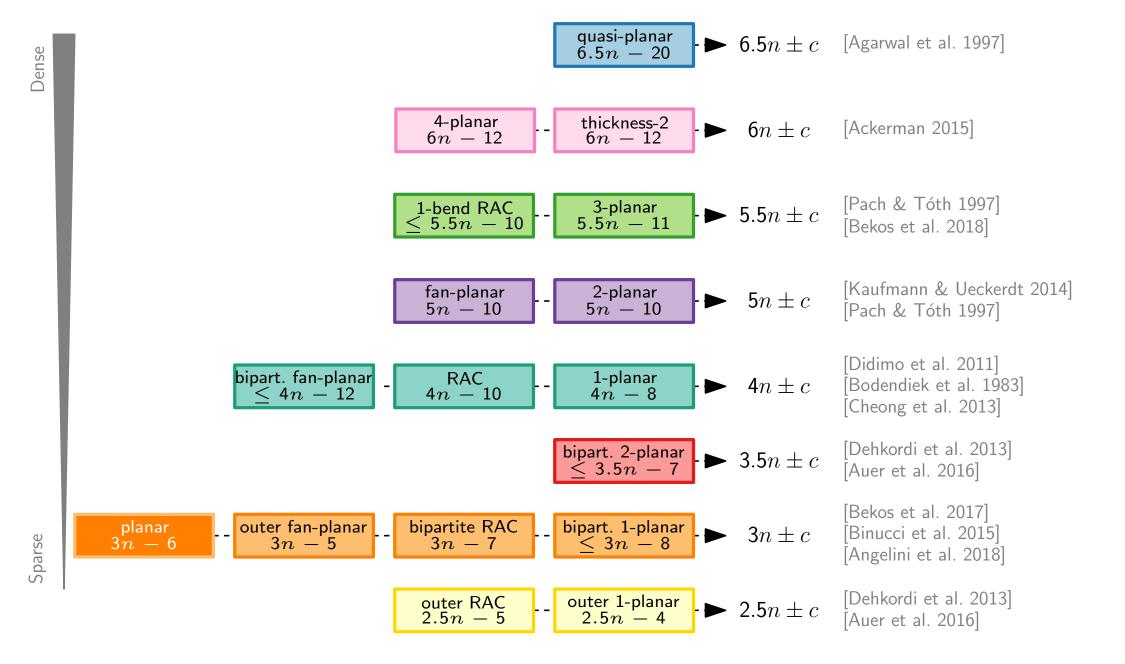
[Pach and Tóth 1997]

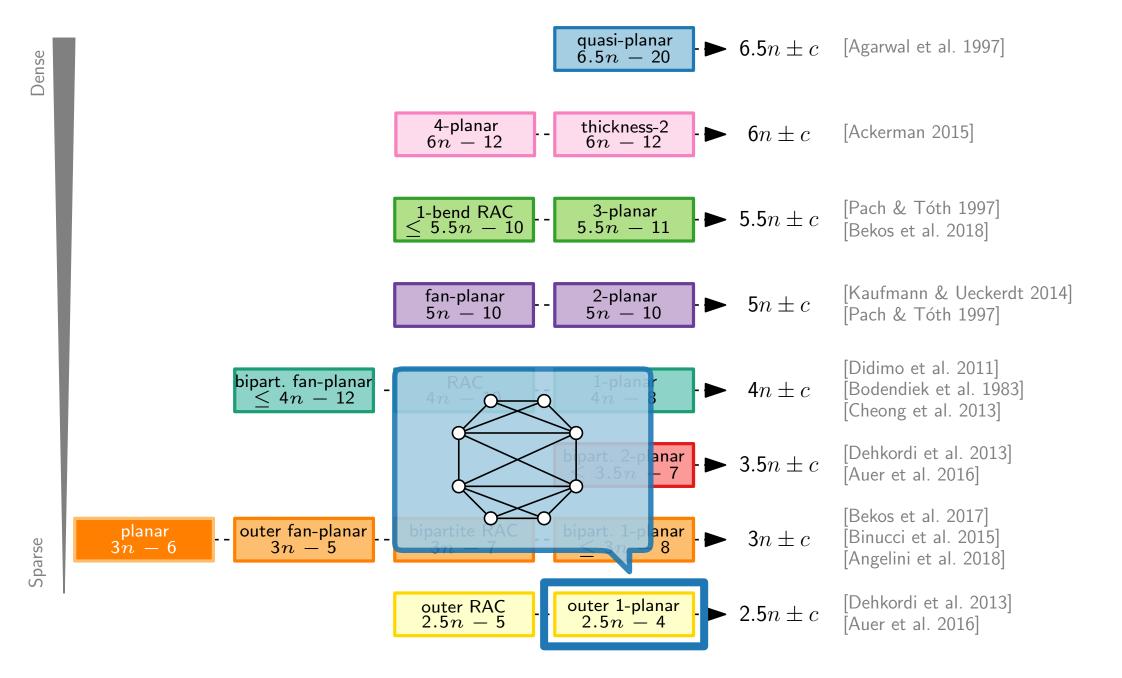


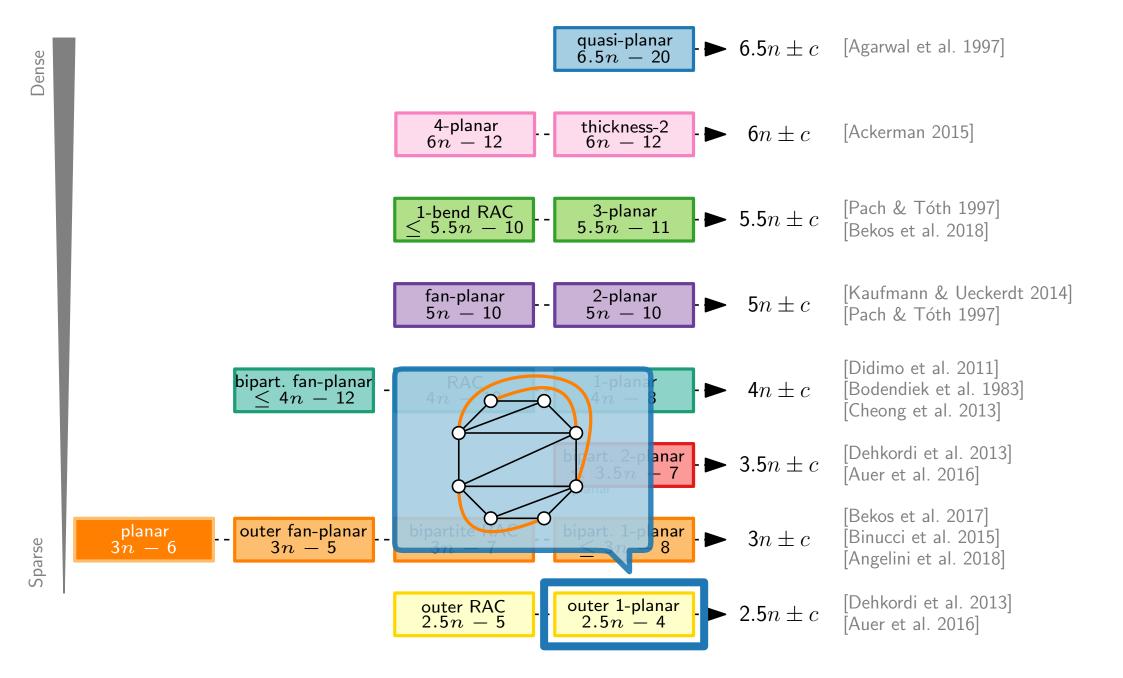
optimal 2-planar

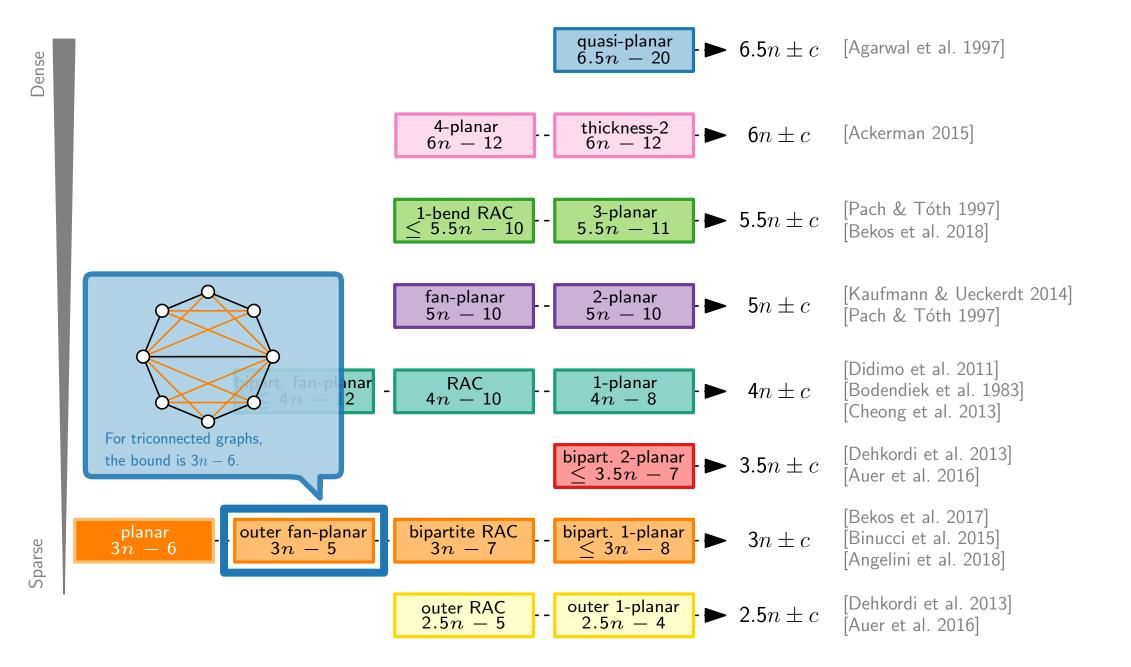


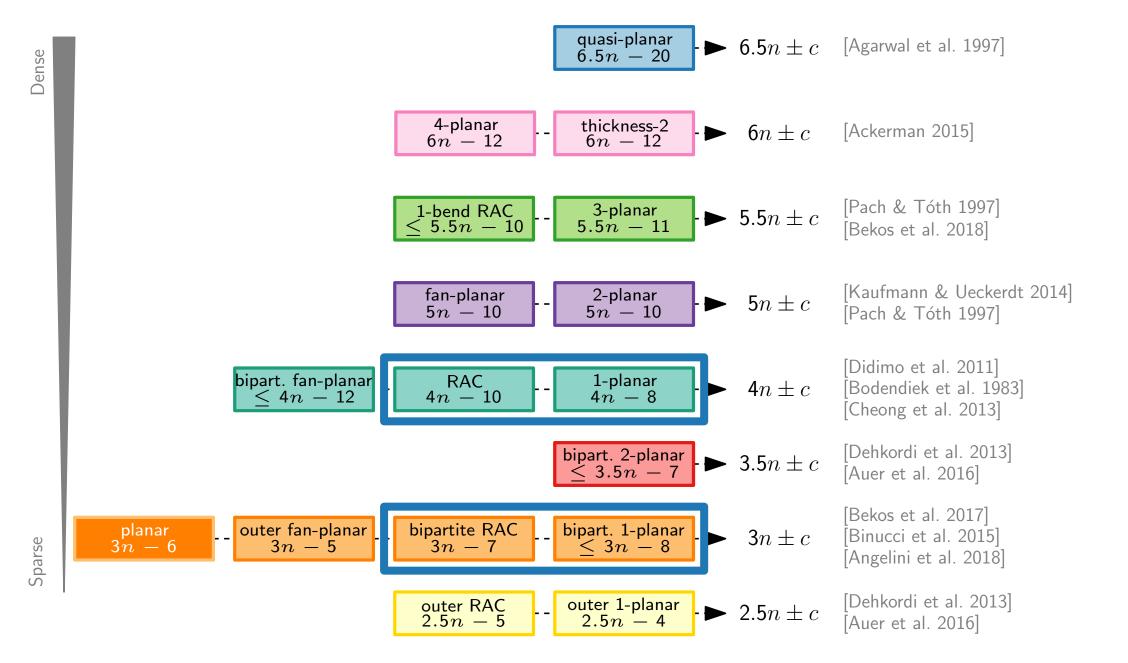
optimal 3-planar

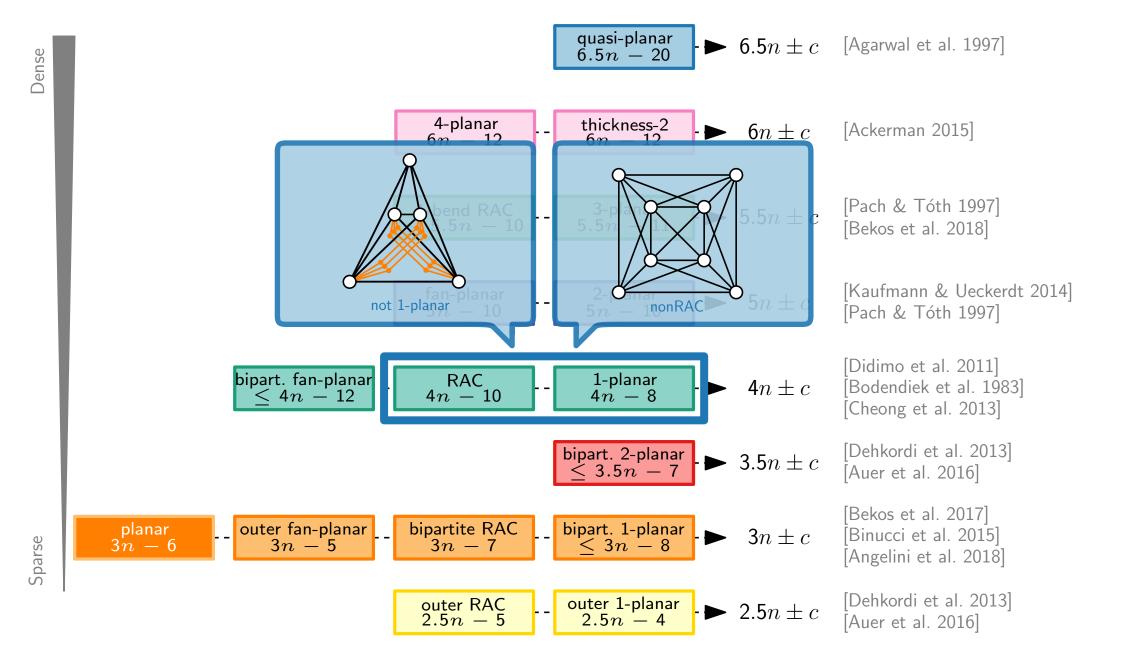


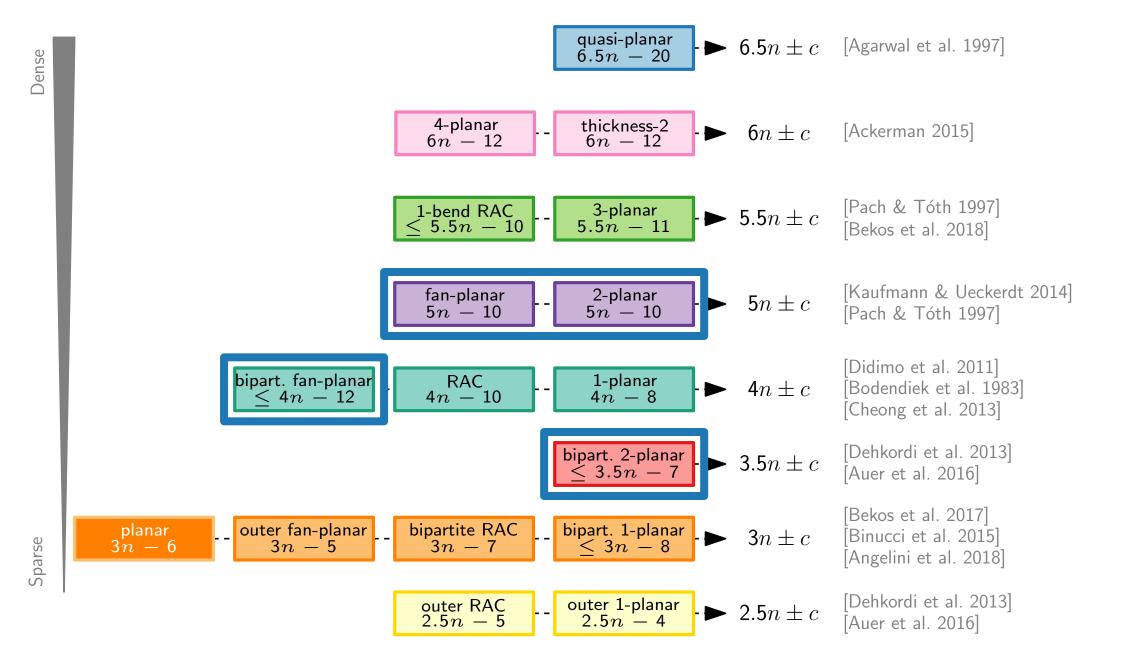


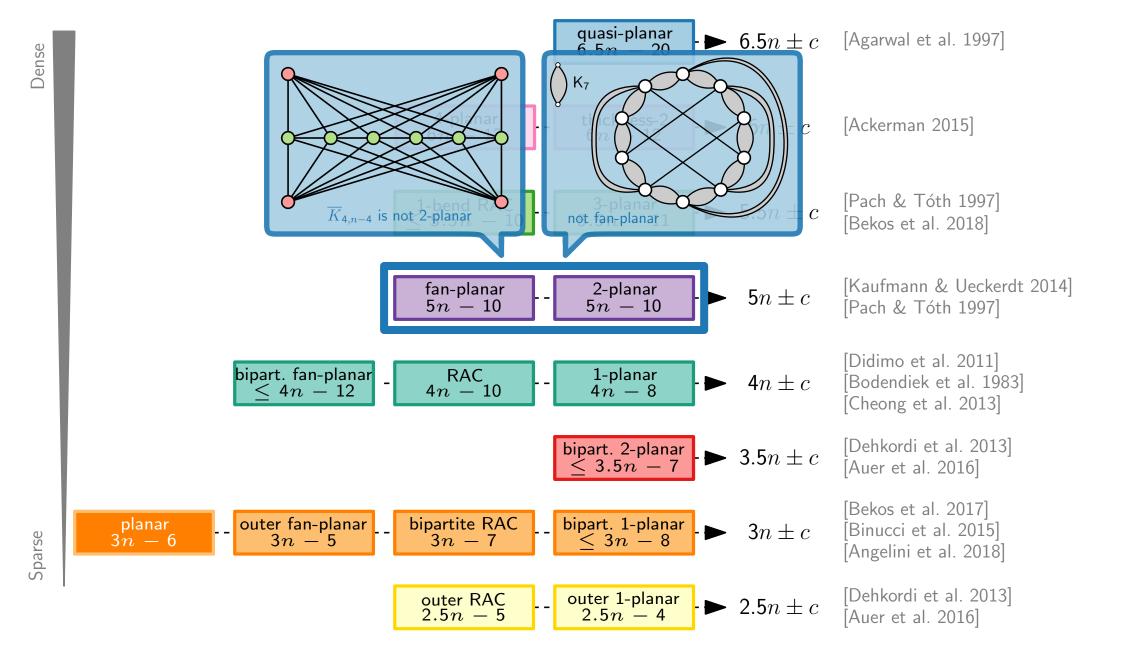


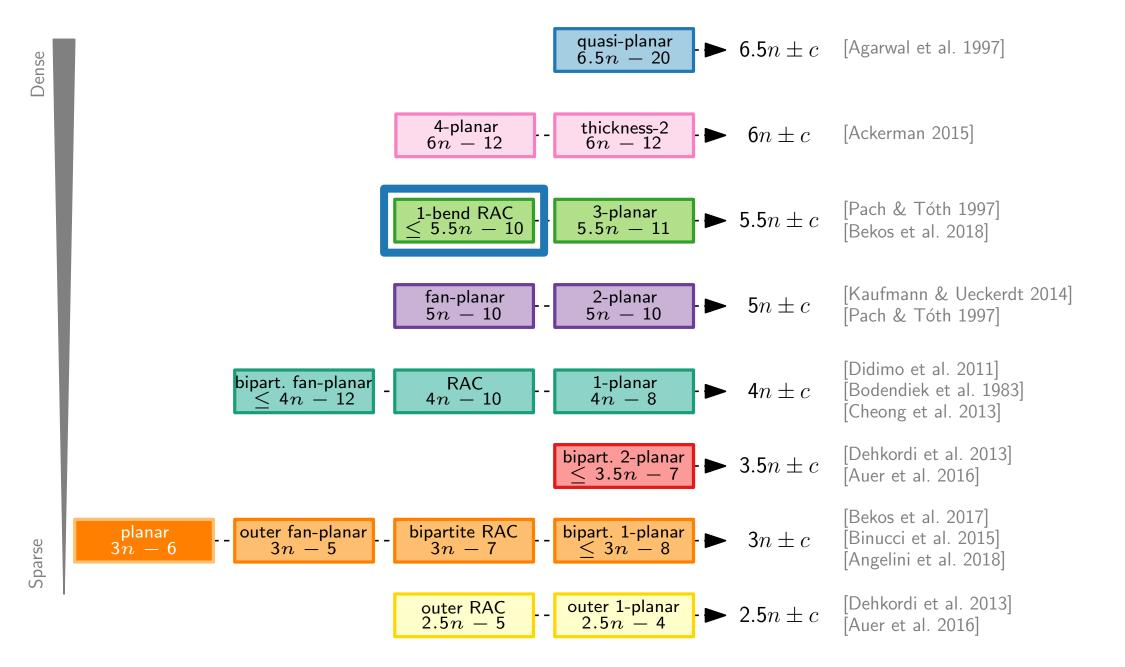


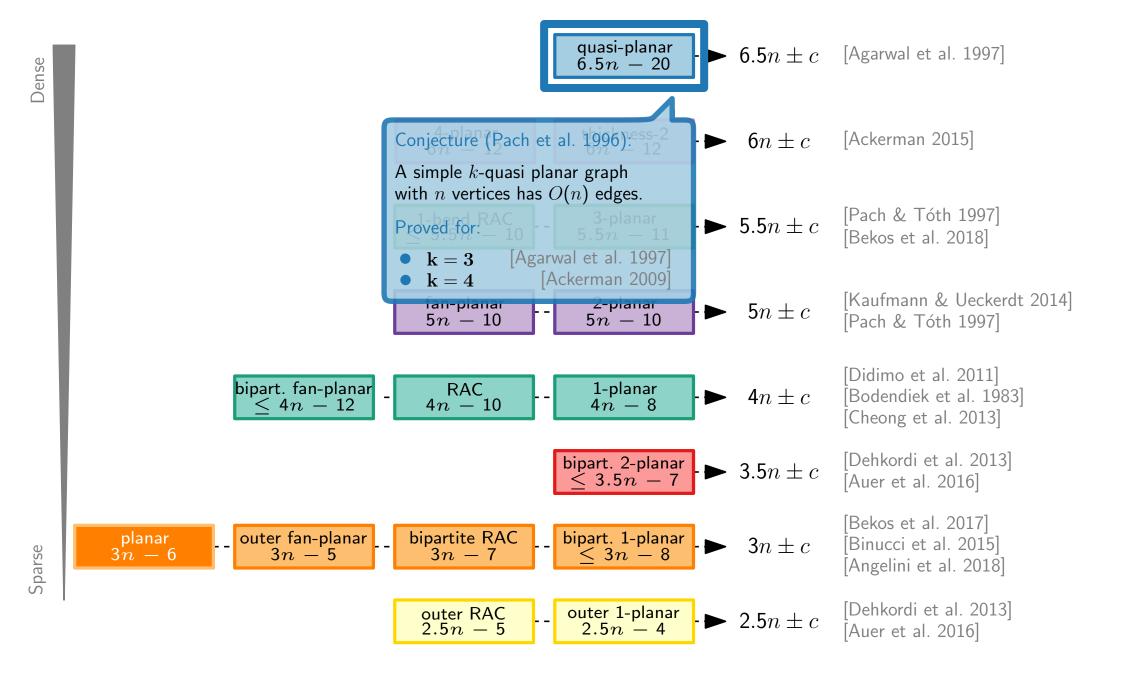












The k-planar crossing number $\operatorname{cr}_{k\text{-pl}}(G)$ of a graph G is the number of crossings required in any k-planar drawing of G.

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$$\operatorname{cr}_{1\text{-pl}}(G) \leq n-2$$

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- $\operatorname{cr}_{1\text{-pl}}(G) \leq n-2$
- $\operatorname{cr}(G) = 1 \Rightarrow \operatorname{cr}_{1-\operatorname{pl}}(G) = 1$

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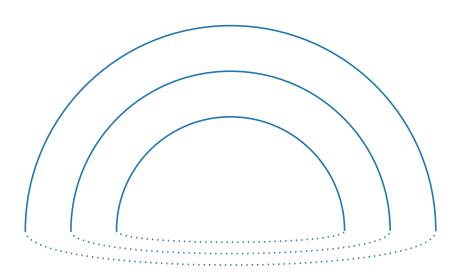
[Chimani, Kindermann, Montecchiani & Valtr 2019]

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Theorem.

[Chimani, Kindermann, Montecchiani & Valtr 2019]

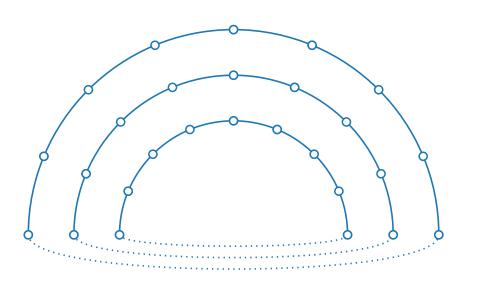


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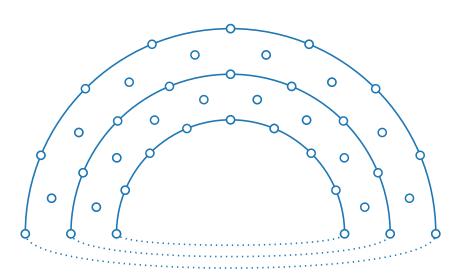


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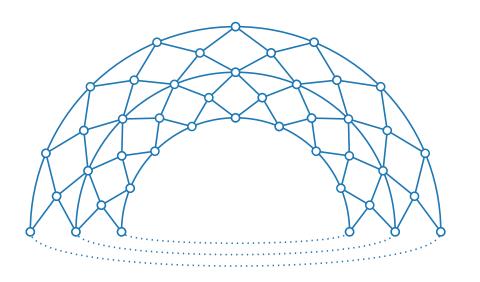


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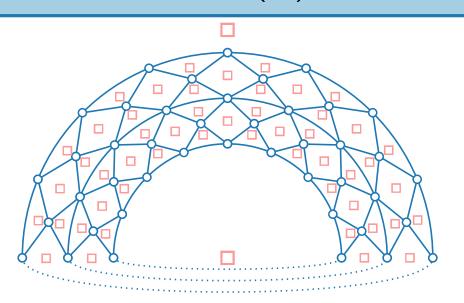


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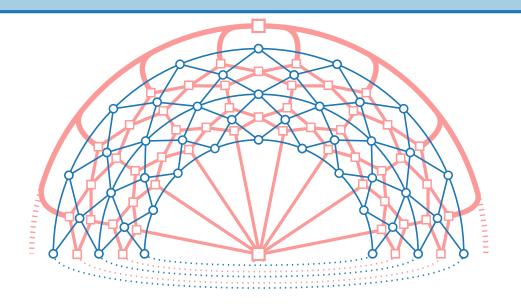


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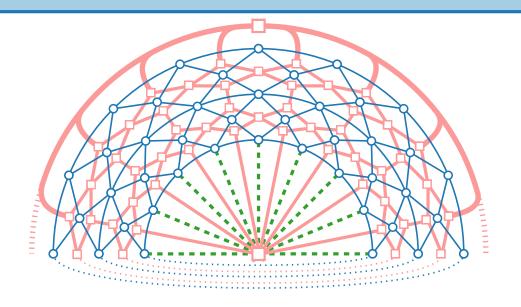


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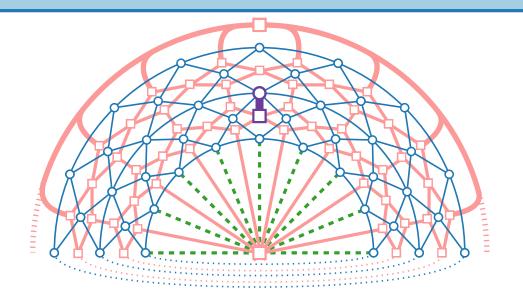
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For every $\ell \geq 7$, there is a 1-planar graph G with $n=11\ell+2$ vertices such that cr(G)=2 and $cr_{1-pl}(G)=n-2$.

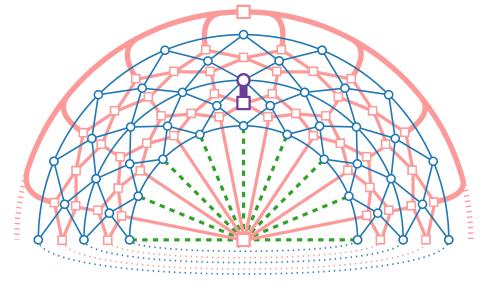


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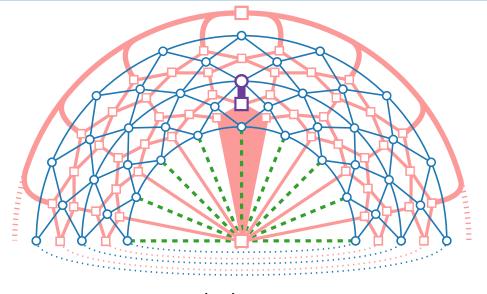
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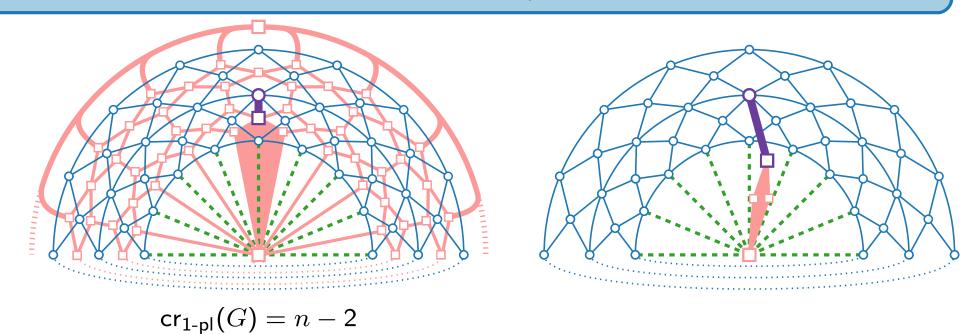
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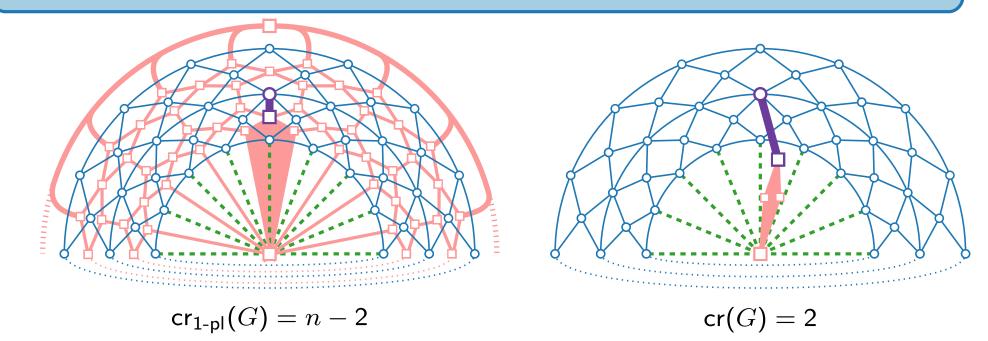


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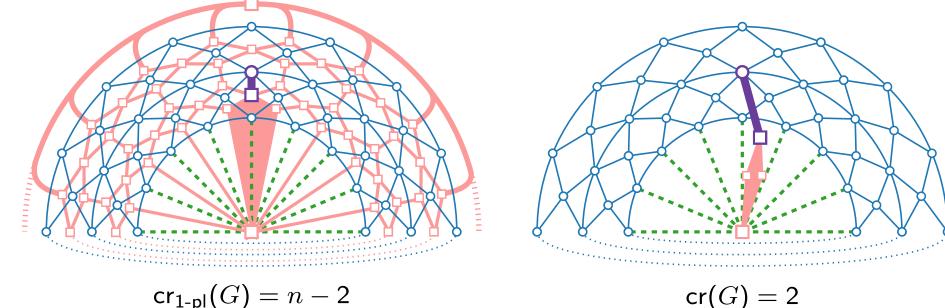
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Crossing ratio

$$\rho_{1\text{-pl}}(n) = (n-2)/2$$



$$\operatorname{cr}_{1\text{-pl}}(G) = n - 2$$

$$\operatorname{cr}(G) = 2$$

Table from "Crossing Numbers of Beyond-Planar Graphs Revisited" [van Beusekom, Parada & Speckmann 2021]

Crossing Ratios

Family	Forbidden Configurations			Lower	Upper
k-planar	An edge crossed more than k times	$\sum_{k=2}^{\infty} k = 2$		$\Omega(m{n}/m{k})$	$O(k\sqrt{k}n)$
<i>k</i> -quasi-planar	k pairwise crossing edges		k = 3	$\Omega(n/k^3)$	$f(k)n^2\log^2 n$
Fan-planar	Two independent edges crossing a third or two adjacent edges crossing another edge from different "side"	H		$\Omega(n)$	$O(n^2)$
(k,l)-grid-free	Set of k edges such that each edge crosses each edge from a set of l edges.		k, l = 2	$\Omega\left(\frac{n}{kl(k+l)}\right)$	$g(k,l)n^2$
k-gap-planar	More than k crossings mapped to an edge in an optimal mapping	k = 1		$\Omega(n/k^3)$	$O(k\sqrt{k}n)$
Skewness- k	Set of crossings not covered by at most k edges		k = 1	$\Omega(m{n}/m{k})$	$igg oldsymbol{O}(oldsymbol{k}oldsymbol{n}+oldsymbol{k}^2)$
k-apex	Set of crossings not covered by at most k vertices	0 k = 1		$\Omega(n/k)$	$O(k^2n^2+k^4)$
Planarly connected	Two crossing edges that do not have two of their endpoint connected by a crossing-free edge		X	$\Omega(n^2)$	$O(n^2)$
k-fan-crossing-free	An edge that crosses k adjacent edges	k = 2		$\Omega(n^2/k^3)$	$O(k^2n^2)$
Straight-line RAC	Two edges crossing at an angle $< \frac{\pi}{2}$		X	$\Omega(n^2)$	$O(n^2)$

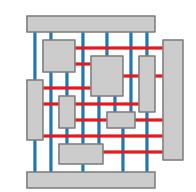


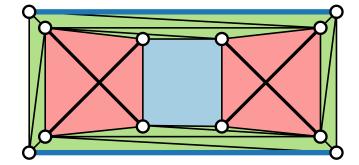
Visualization of Graphs

Lecture 11:

Beyond Planarity

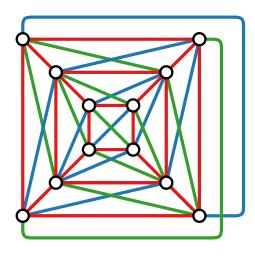
Drawing Graphs with Crossings



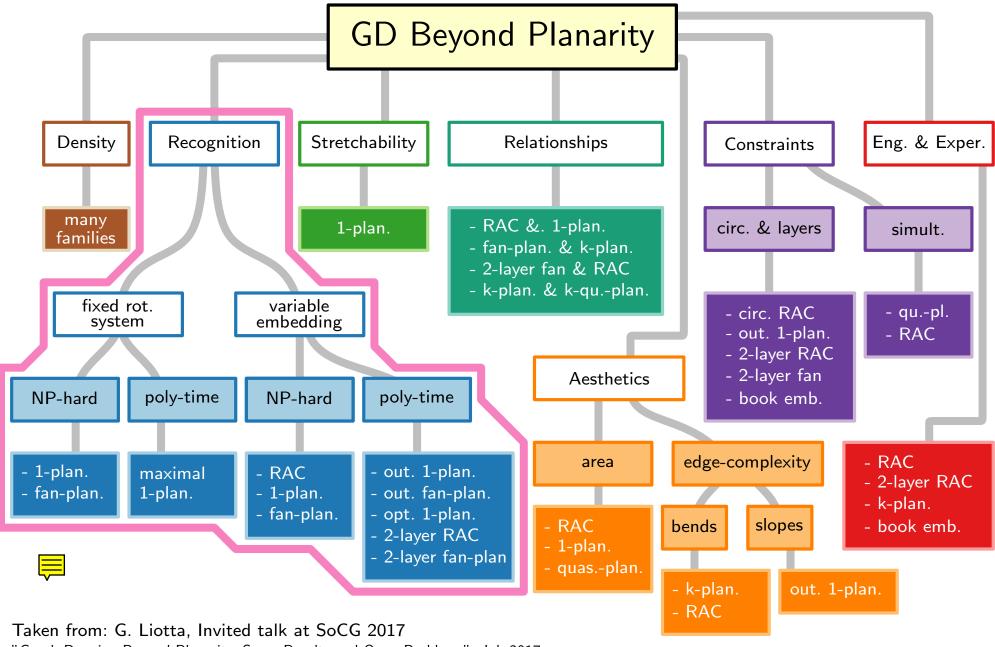


Part III: Recognition

Alexander Wolff



GD Beyond Planarity: a Taxonomy



[&]quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

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[Kuratowski 1930]

G planar \Leftrightarrow neither K_5 nor $K_{3,3}$ minor of G

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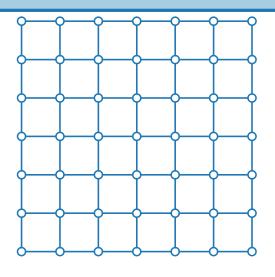
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 $n \times n$ grid

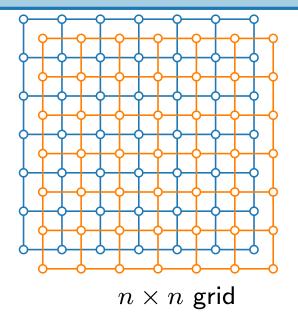
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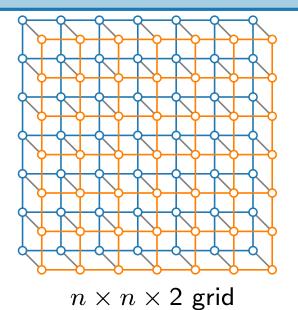
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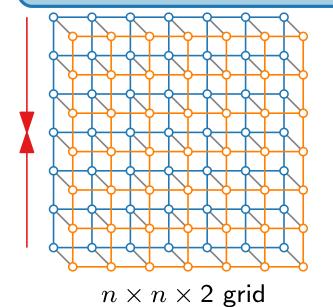
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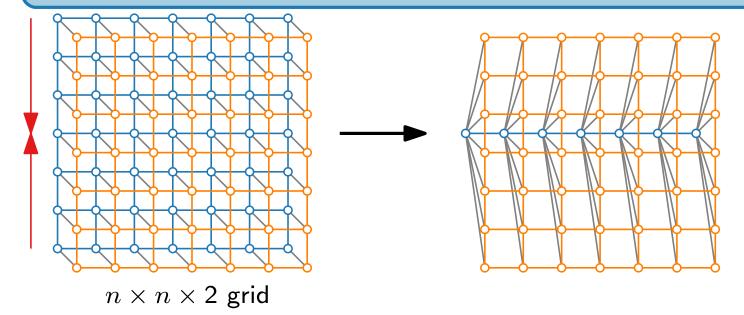
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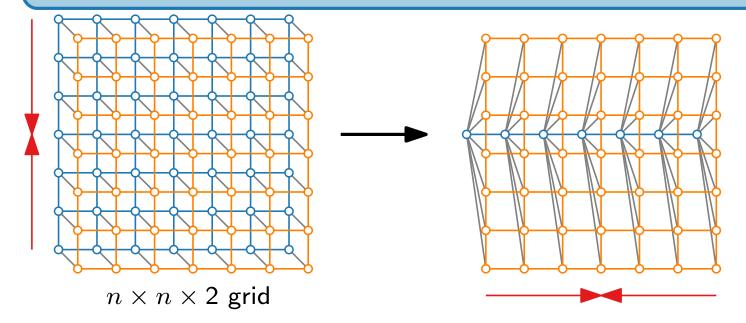
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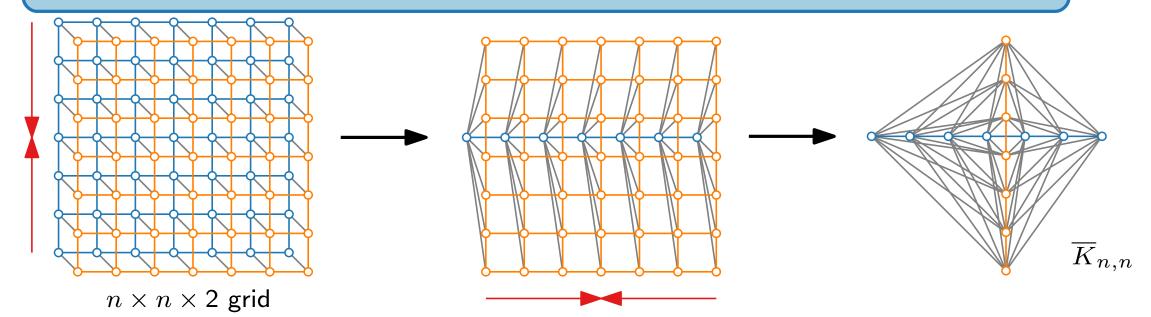
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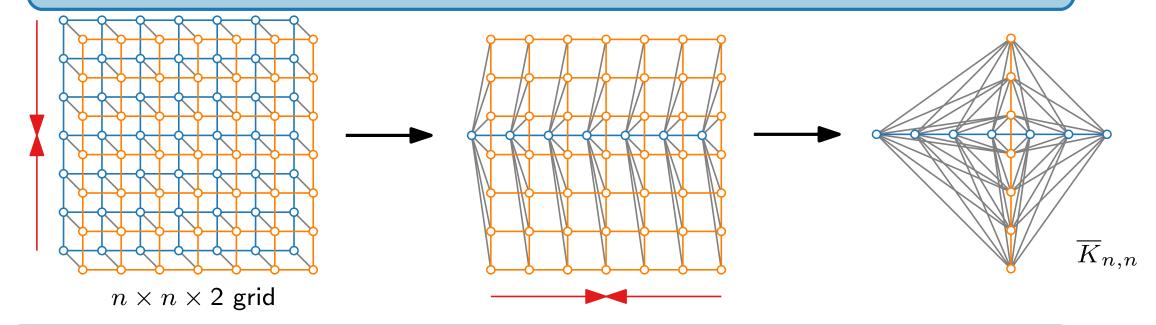
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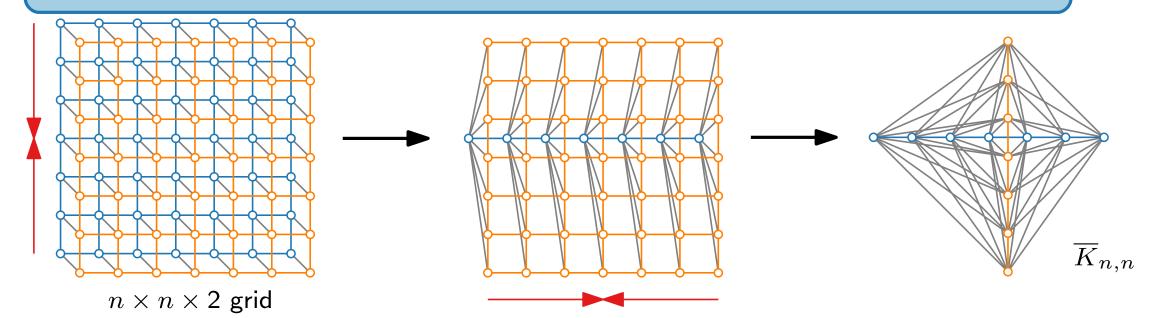
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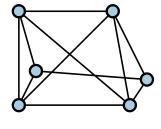
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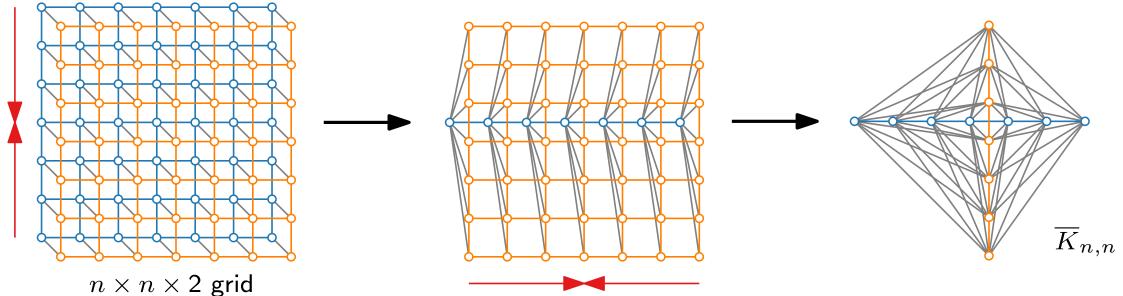
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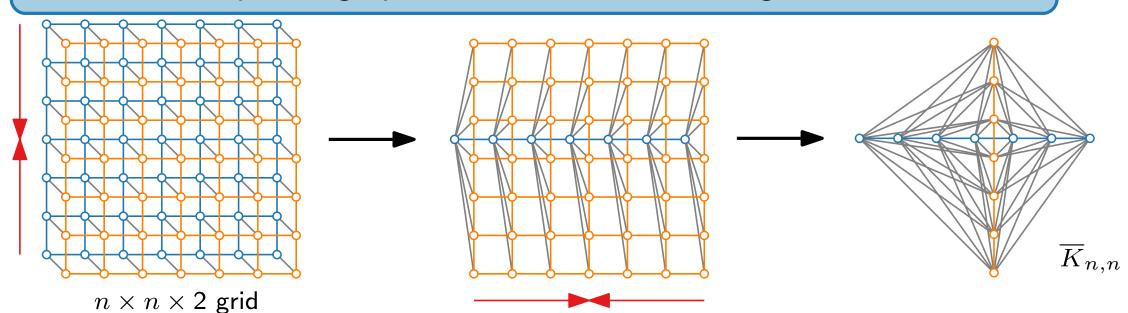
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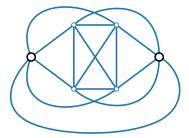
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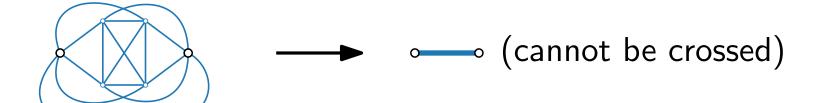
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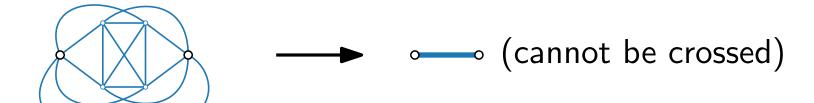
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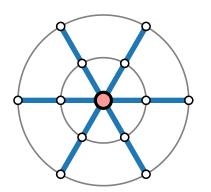
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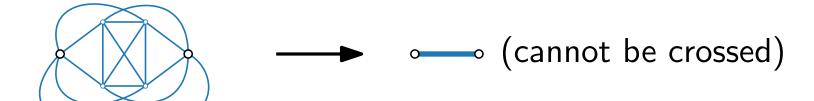
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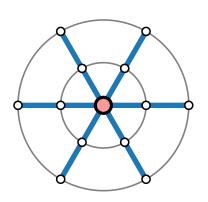
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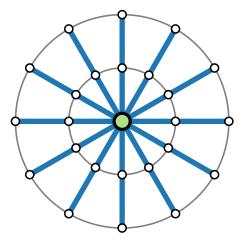
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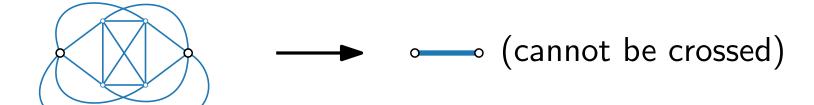
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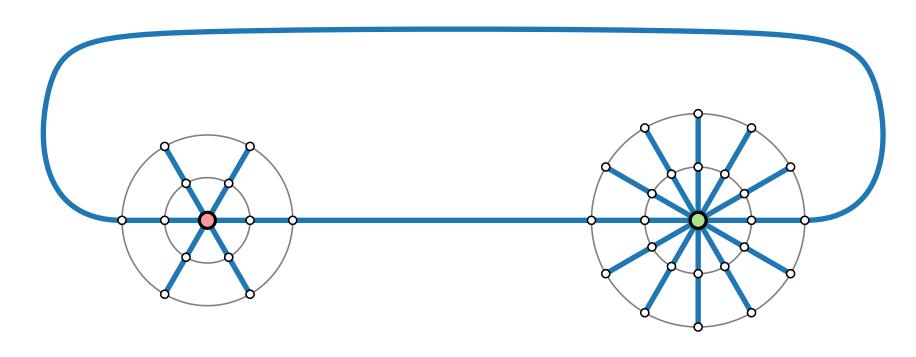
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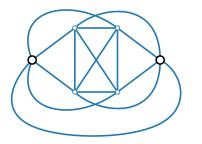
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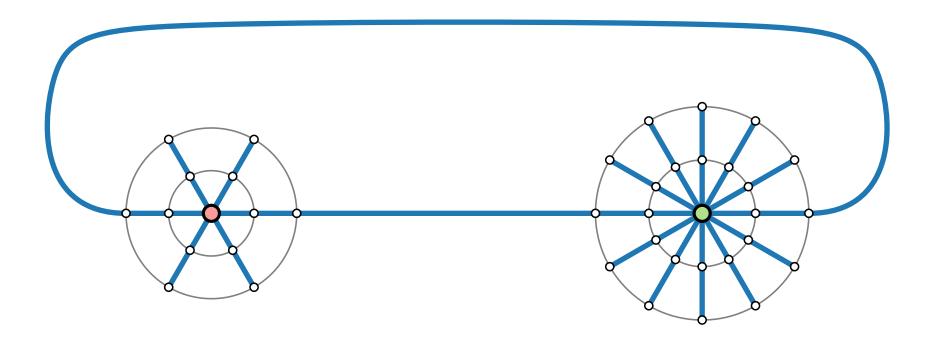
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$$A = \{1, 3, 2, 4, 1, 1\}$$



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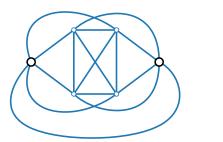
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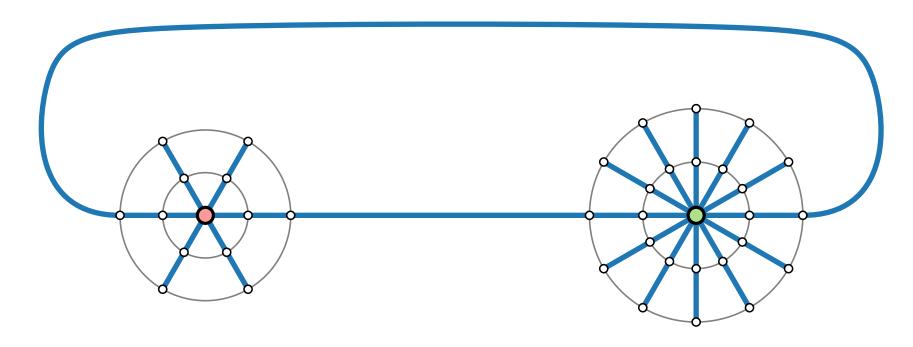
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Reduction from 3-Partition.

$$A = \{\overbrace{1, 3, 2, 4, 1, 1}^{6}\}$$



(cannot be crossed)



Theorem.

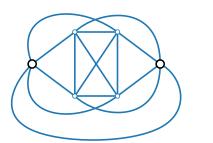
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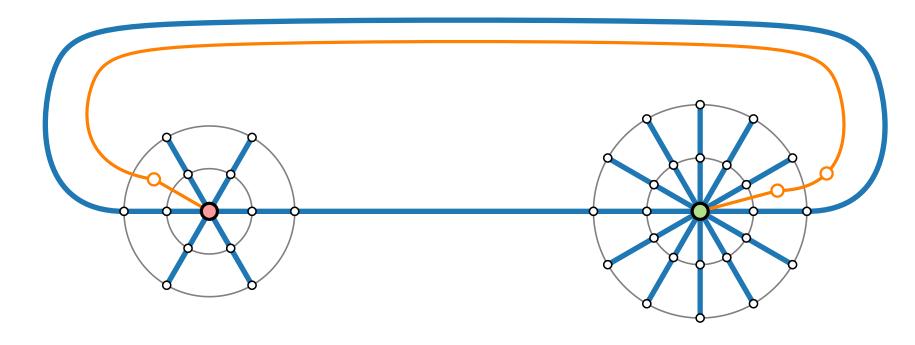
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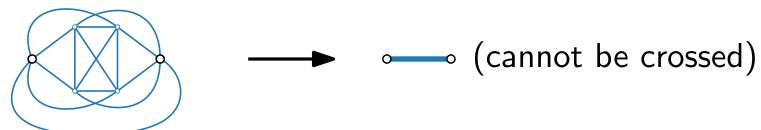
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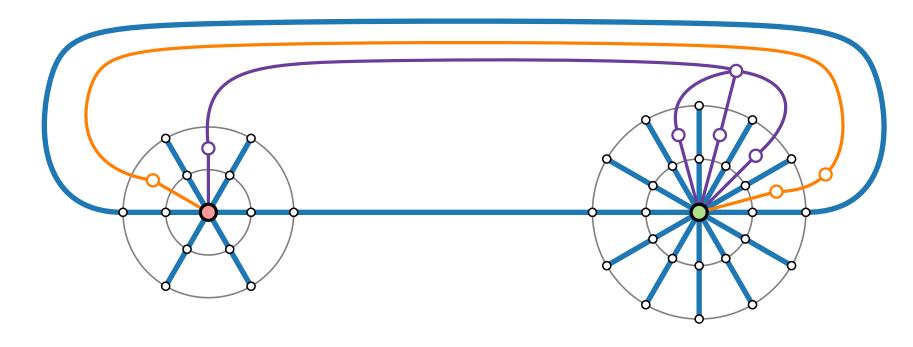
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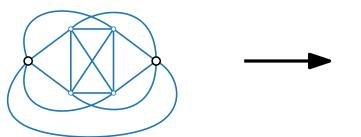
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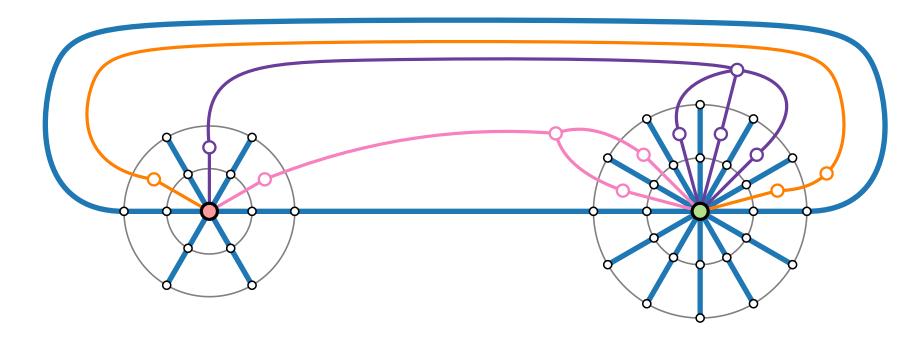
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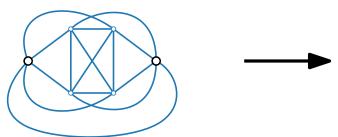
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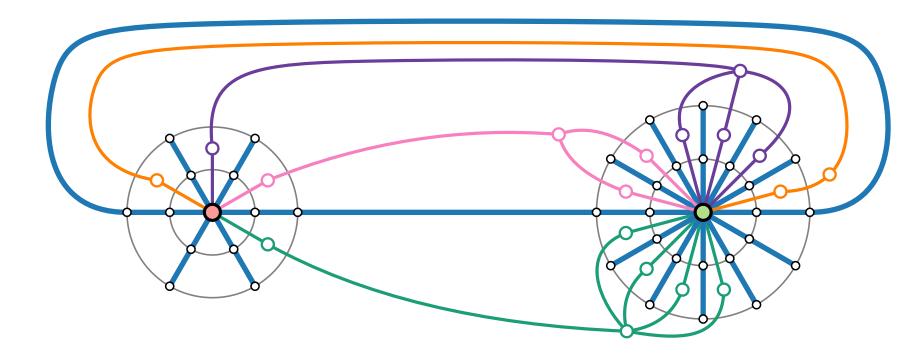
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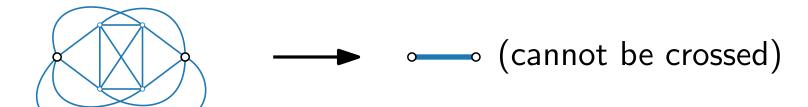
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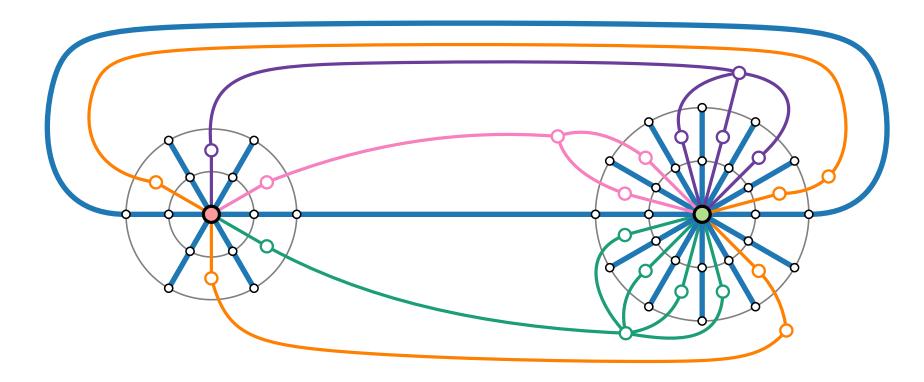
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Proof.

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Theorem.

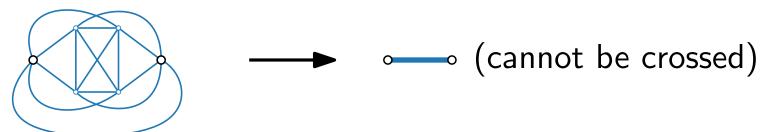
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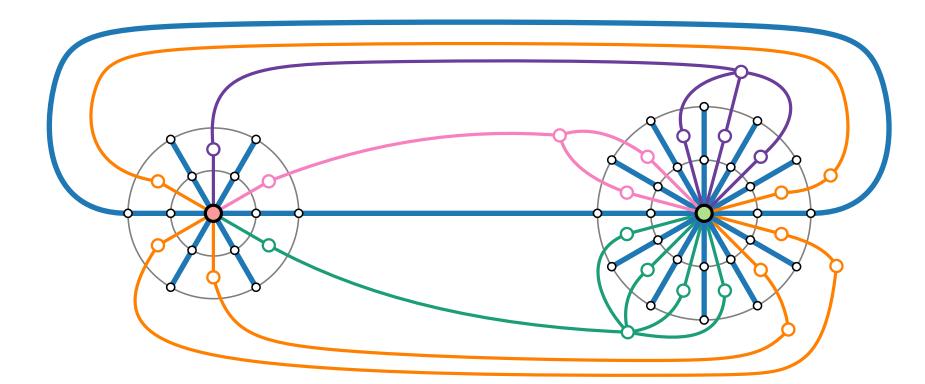
Testing 1-planarity is NP-complete.

Proof.

Reduction from 3-Partition.

$$A = \{1, 3, 2, 4, 1, 1\}$$





Theorem.

[Grigoriev & Bodlaender 2007, Korzhik & Mohar 2013]

Testing 1-planarity is NP-complete.

Theorem.

[Grigoriev & Bodlaender 2007, Korzhik & Mohar 2013]

Testing 1-planarity is NP-complete.

Theorem.

[Cabello & Mohar 2013]

Testing 1-planarity is NP-complete – even for almost planar graphs, i.e., planar graphs plus one edge.

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Theorem.

[Bannister, Cabello & Eppstein 2018]

Testing 1-planarity is NP-complete – even for graphs of bounded bandwidth (pathwidth, treewidth).

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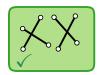
Theorem.

[Auer, Brandenburg, Gleißner & Reislhuber 2015]

Testing 1-planarity is NP-complete – even for 3-connected graphs with a fixed rotation system.

Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Testing IC-planarity is NP-complete.

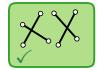




Theorem. [Bra

[Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Testing IC-planarity is NP-complete.

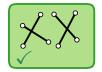




Proof.

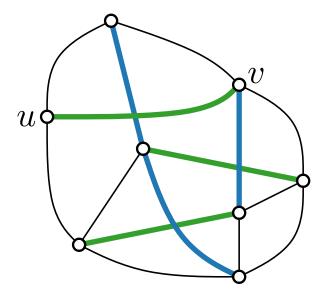
Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Testing IC-planarity is NP-complete.



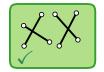


Proof.



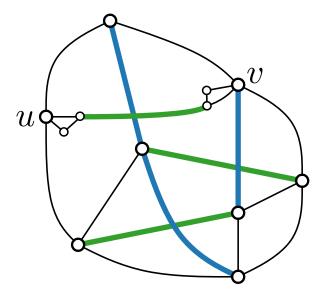
Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Testing IC-planarity is NP-complete.



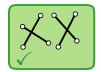


Proof.



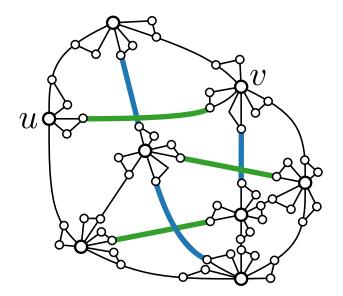
Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Testing IC-planarity is NP-complete.



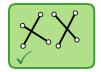


Proof.



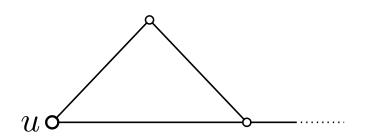
Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

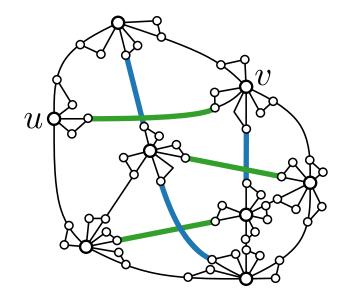
Testing IC-planarity is NP-complete.





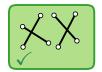
Proof.





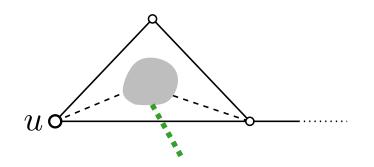
Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

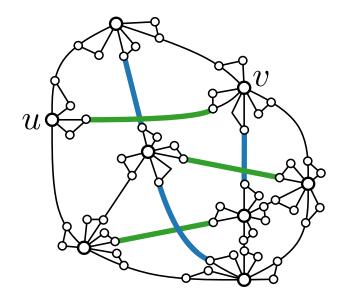
Testing IC-planarity is NP-complete.





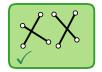
Proof.





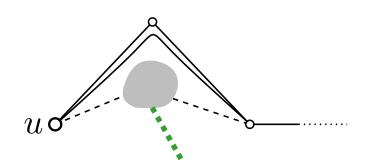
Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

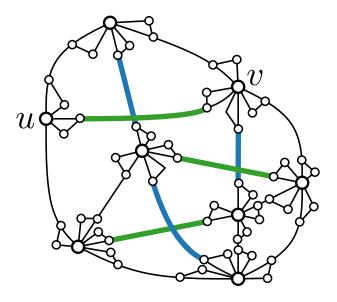
Testing IC-planarity is NP-complete.





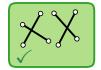
Proof.





Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

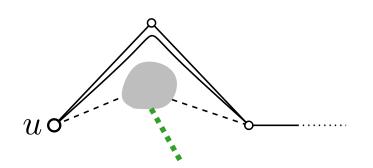
Testing IC-planarity is NP-complete.

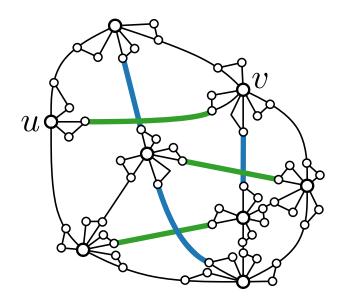




Proof.

Reduction from 1-planarity testing.

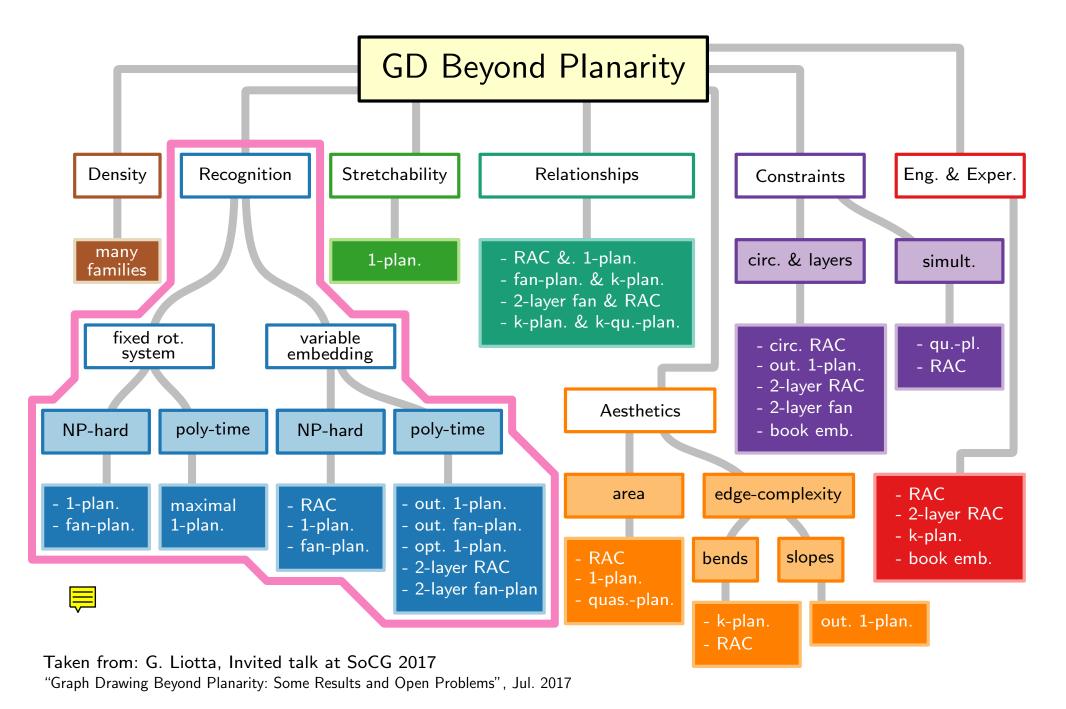




Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Testing IC-planarity is NP-complete, even if the rotation system is given.

GD Beyond Planarity: a Taxonomy



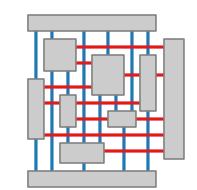


Visualization of Graphs

Lecture 11:

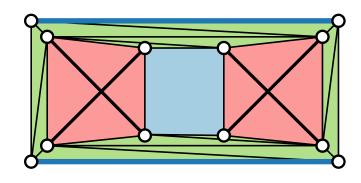
Beyond Planarity

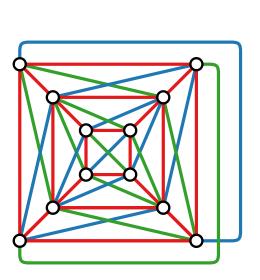
Drawing Graphs with Crossings



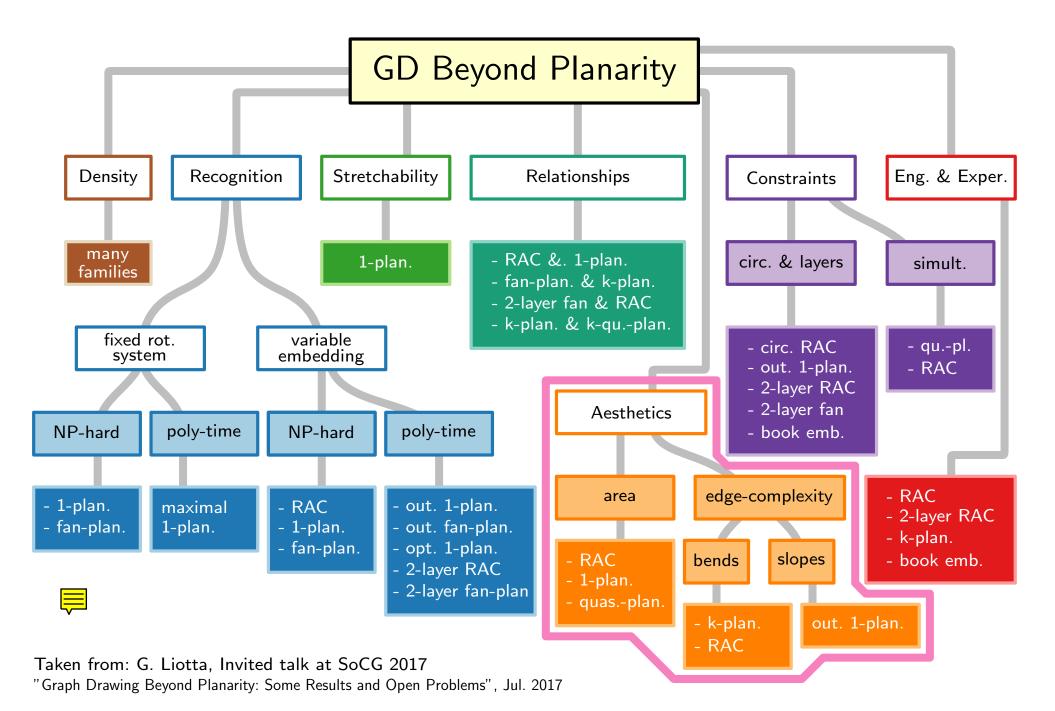


Alexander Wolff





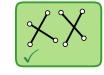
GD Beyond Planarity: a Taxonomy



Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]





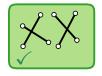




Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015] Some IC-planar straight-line RAC drawings require exponential area.







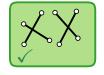




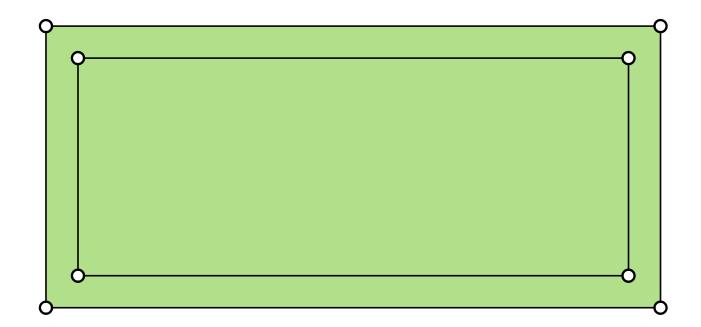
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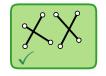




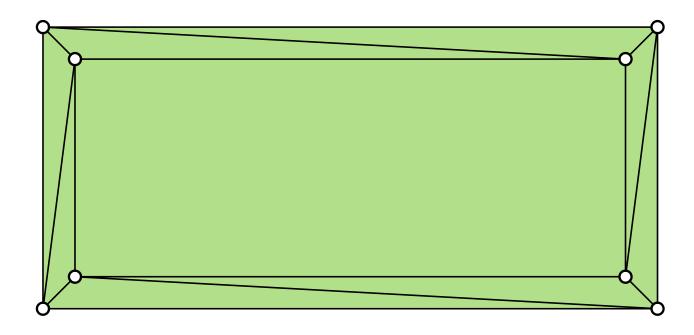
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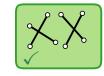




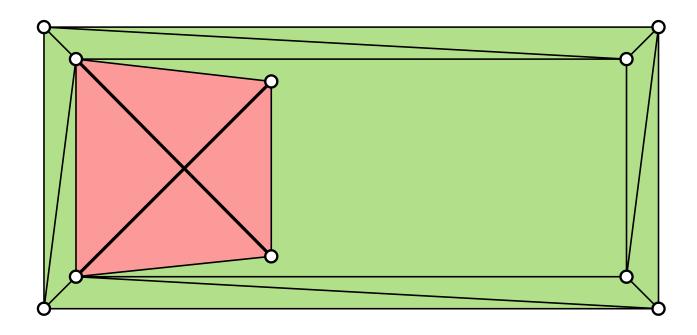
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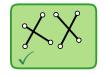




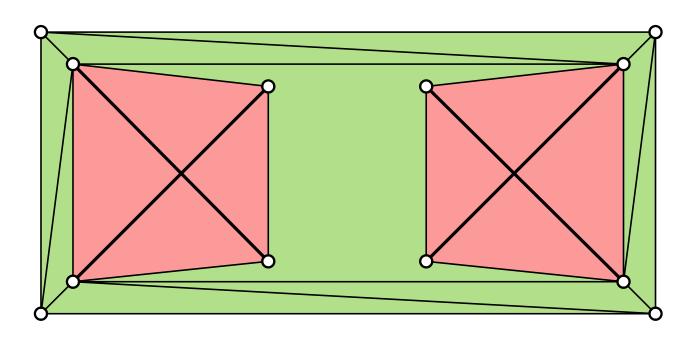
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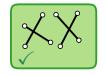




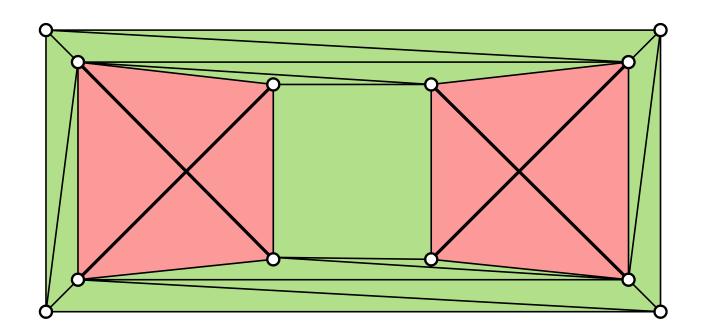
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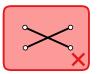


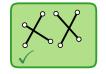


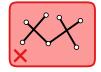


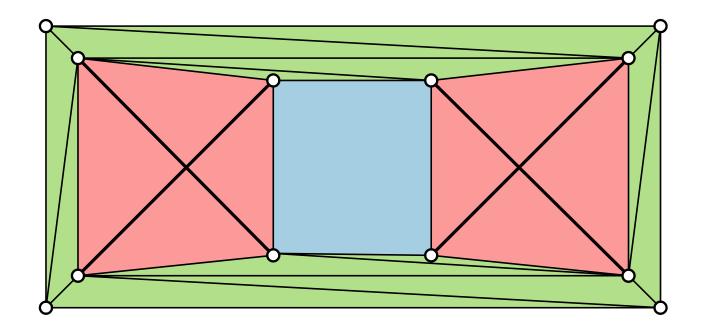
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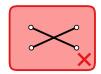


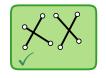




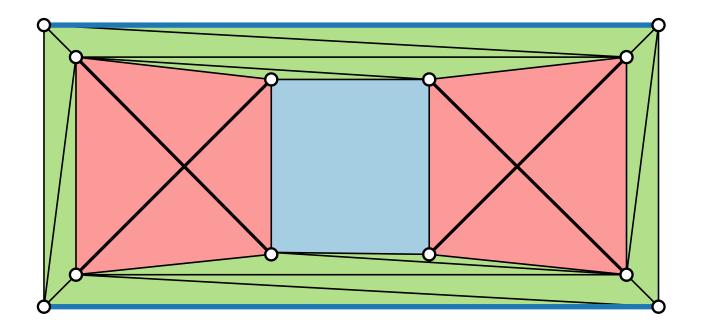
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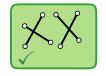




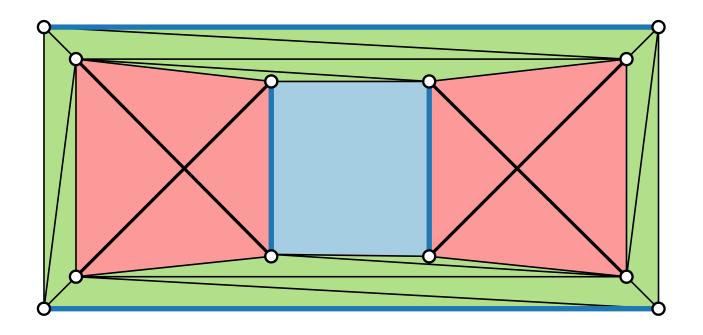
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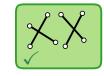




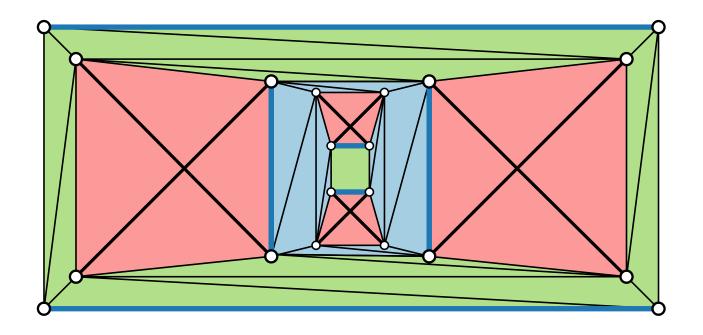
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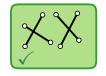




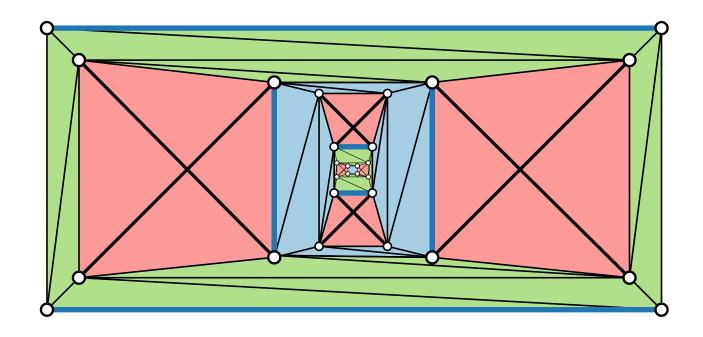
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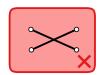


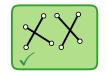


Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Some IC-planar straight-line RAC drawings require exponential area.



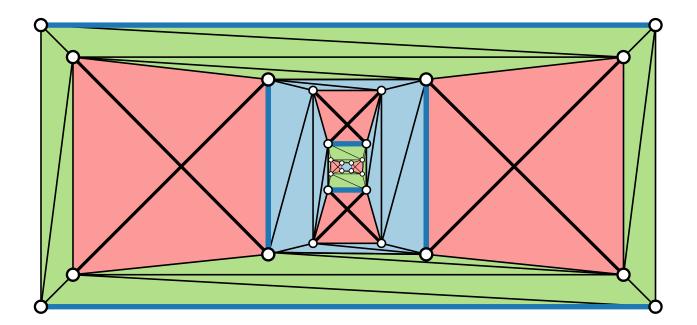






Theorem. [Brandenburg, Didimo, Evans, Kindermann, Liotta & Montecchiani 2015]

Every IC-planar graph has an IC-planar straight-line RAC drawing, and such a drawing can be found in polynomial time.

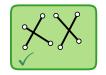


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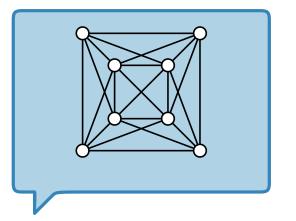


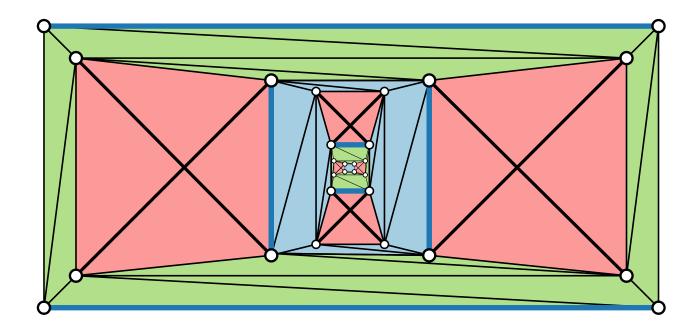




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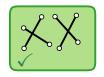


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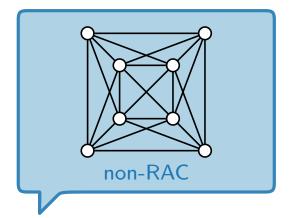


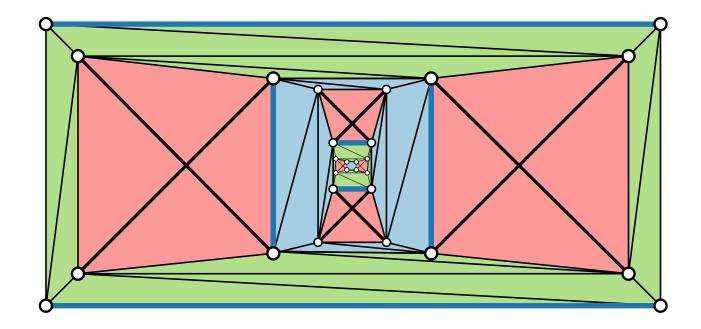




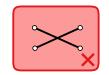
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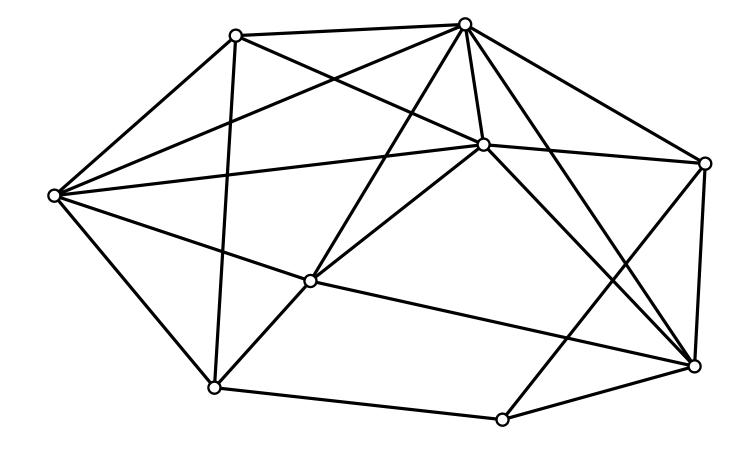
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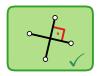


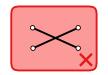


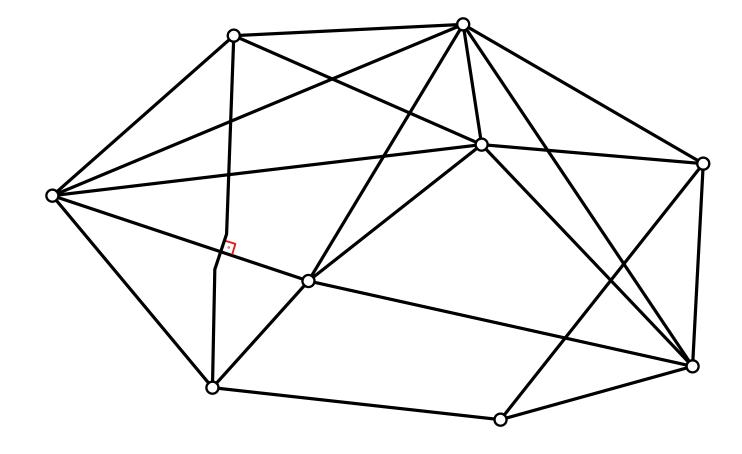




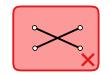


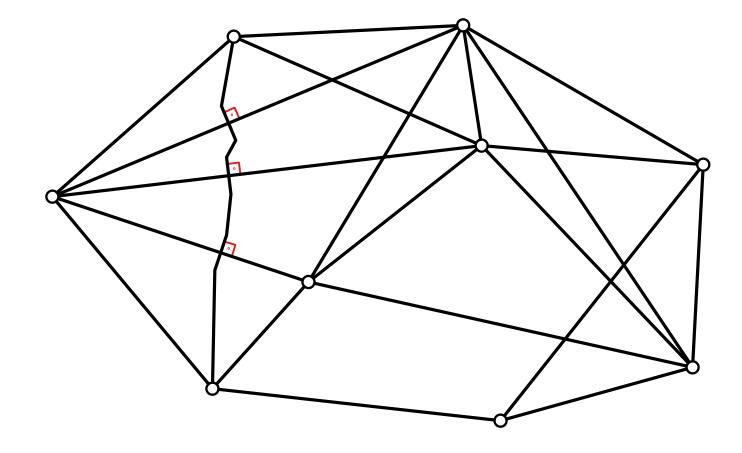


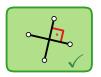


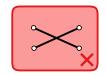


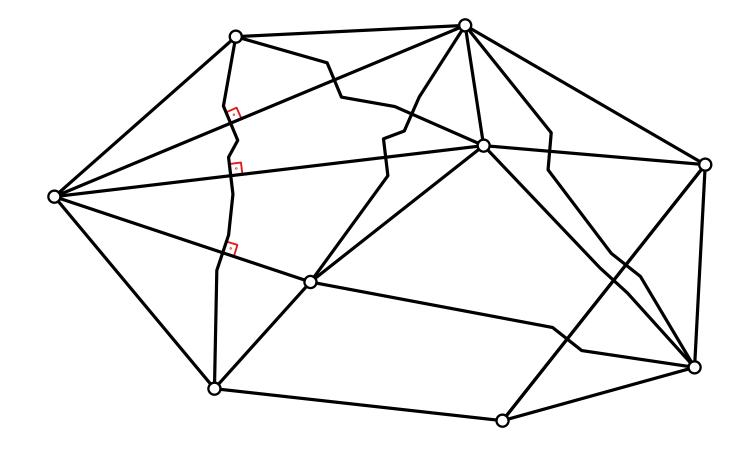


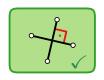


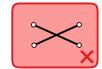


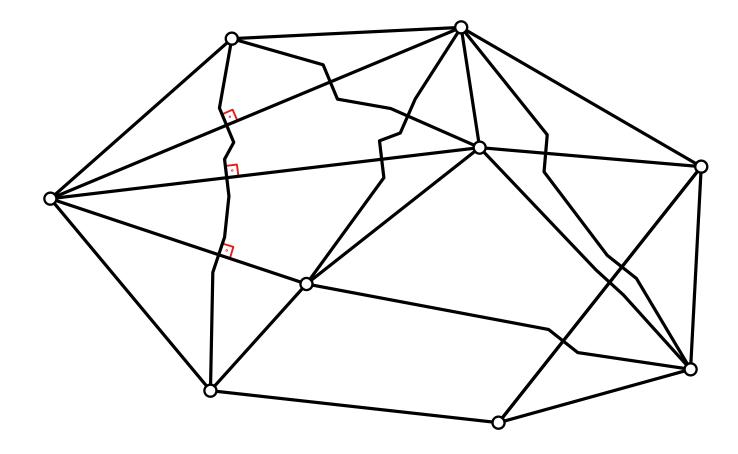






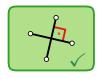


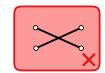


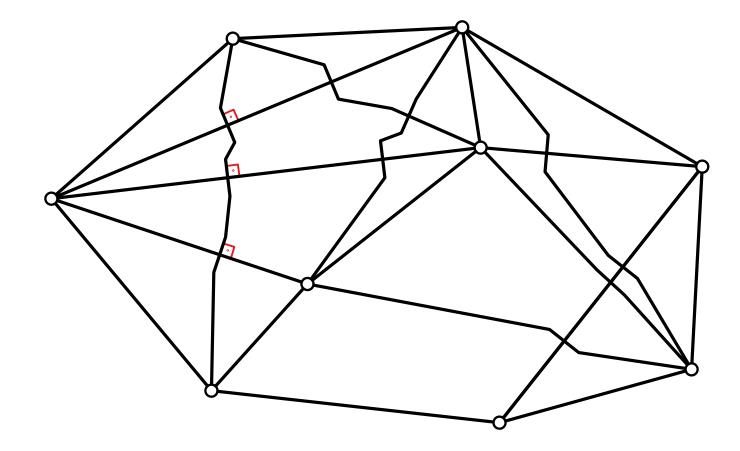


Every graph admits a RAC drawing ...

RAC Drawings With Enough Bends

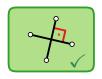


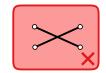


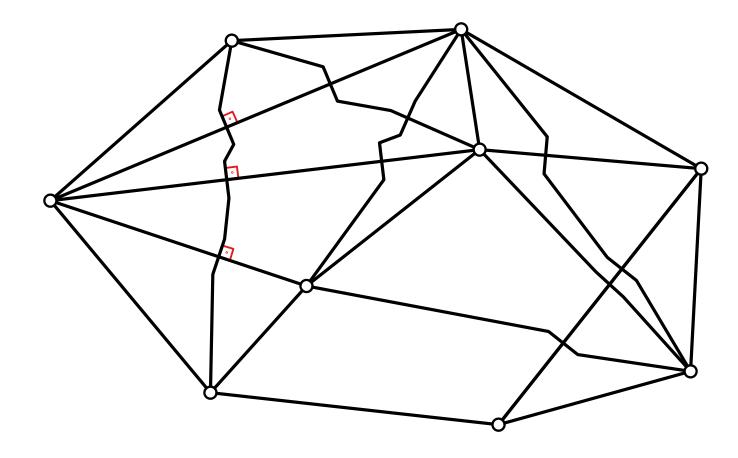


Every graph admits a RAC drawing ... if we use enough bends.

RAC Drawings With Enough Bends







Every graph admits a RAC drawing ...

... if we use enough bends.

How many do we need at most in total or per edge?

3-Bend RAC Drawings

Theorem.

[Didimo, Eades & Liotta 2017]

Every graph admits a 3-bend RAC drawing, that is, a RAC drawing where every edge has at most 3 bends.

3-Bend RAC Drawings

Theorem.

[Didimo, Eades & Liotta 2017]

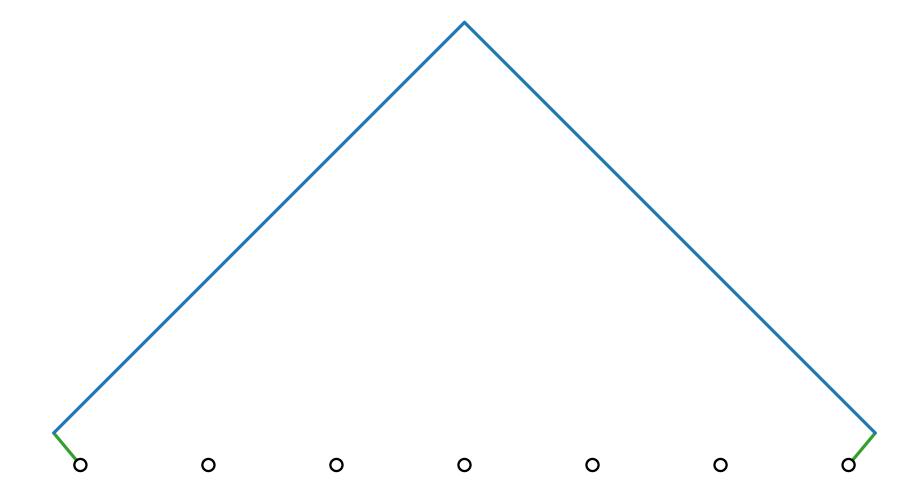
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3-Bend RAC Drawings

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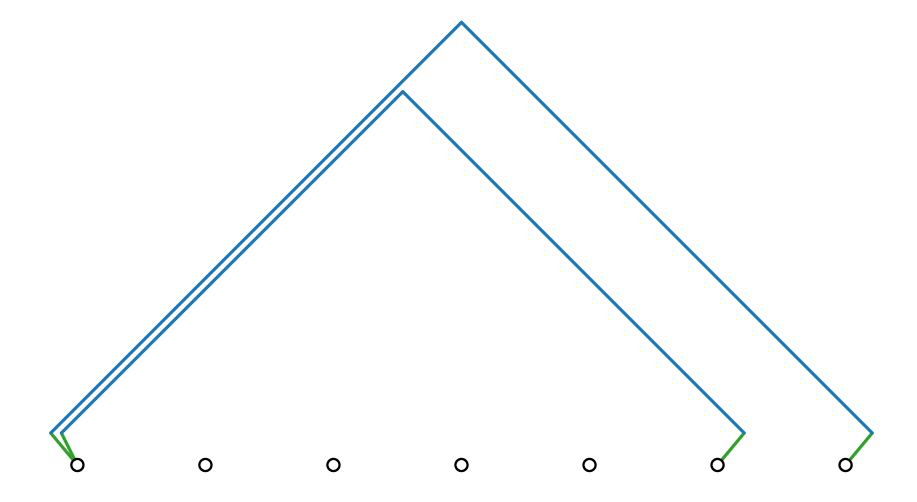


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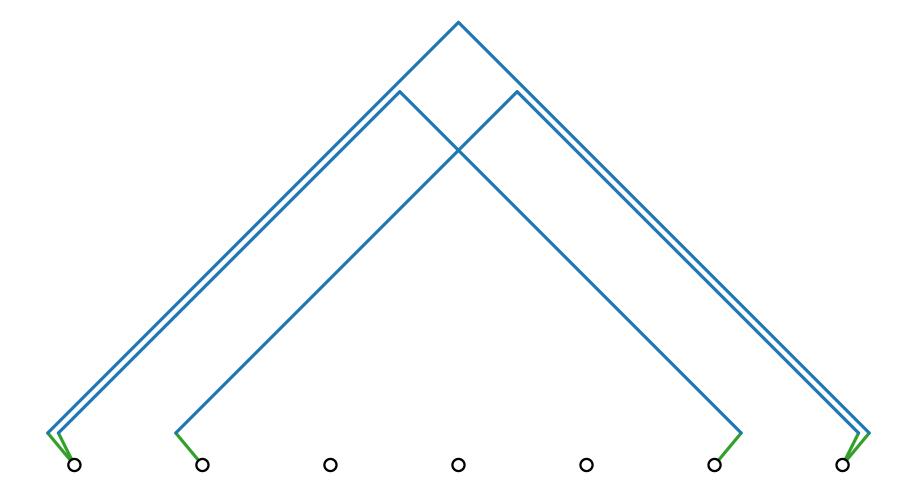


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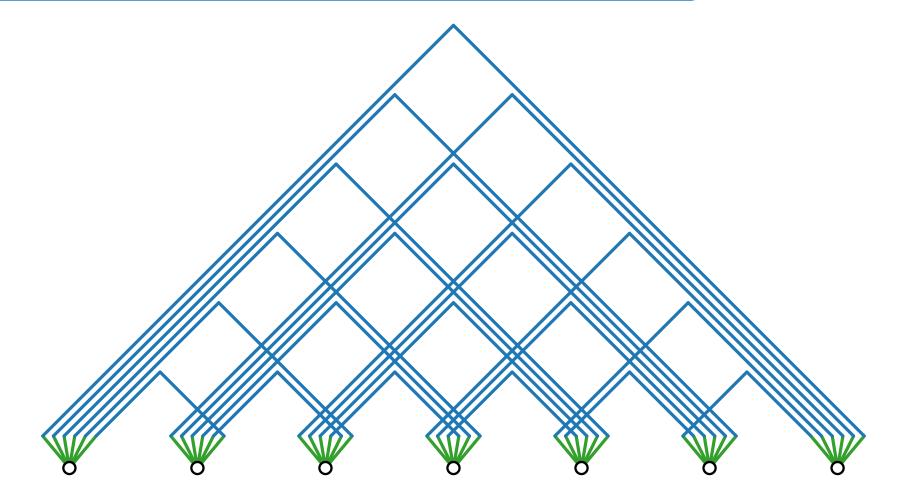


3-Bend RAC Drawings

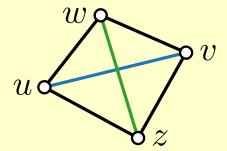
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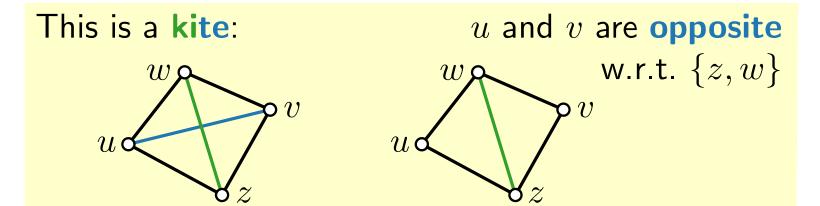
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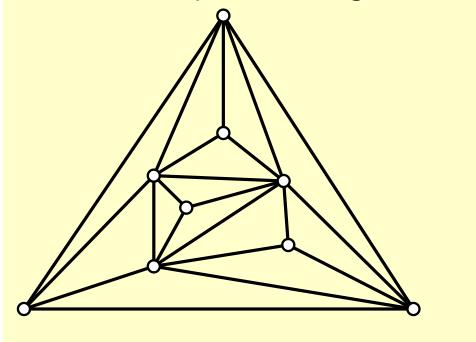
This is a **kite**:

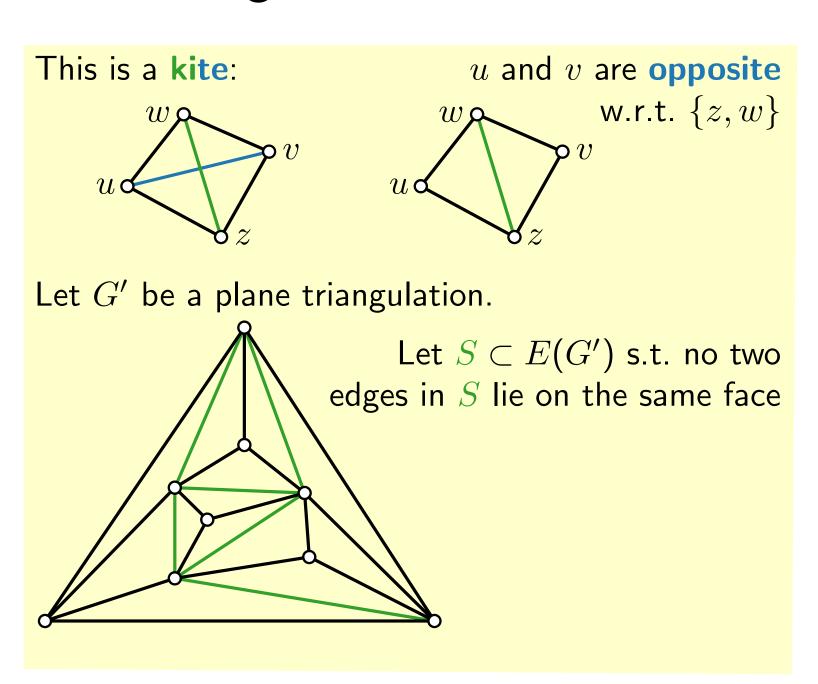


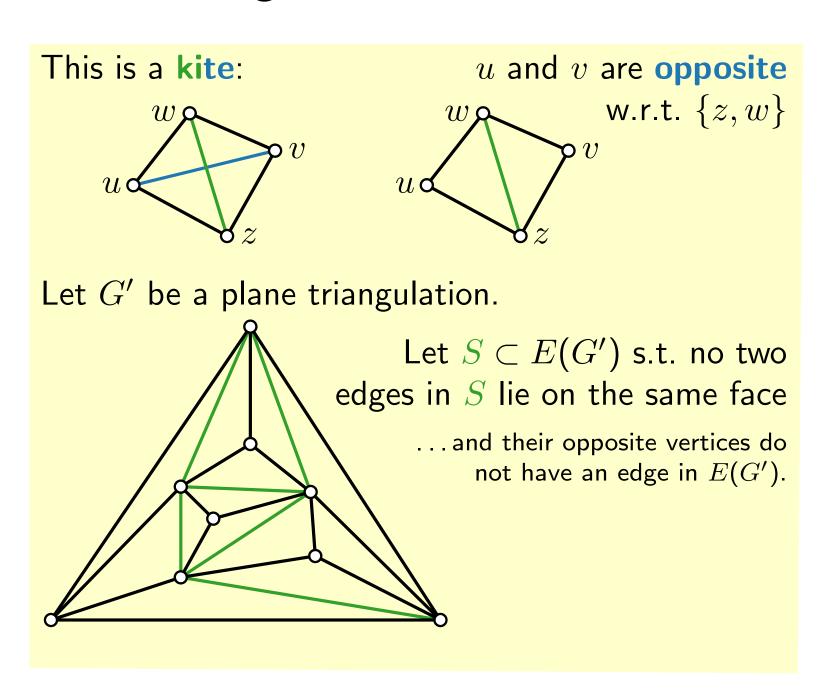
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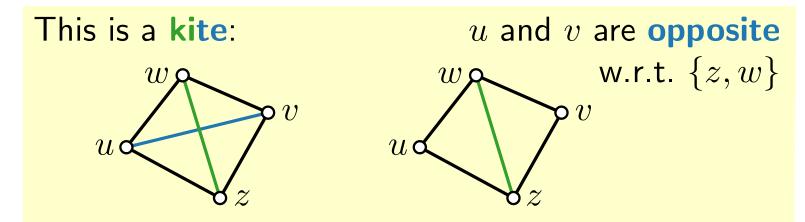


Let G' be a plane triangulation.

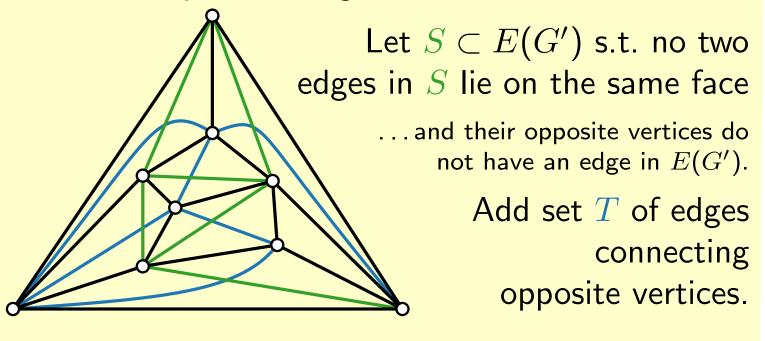


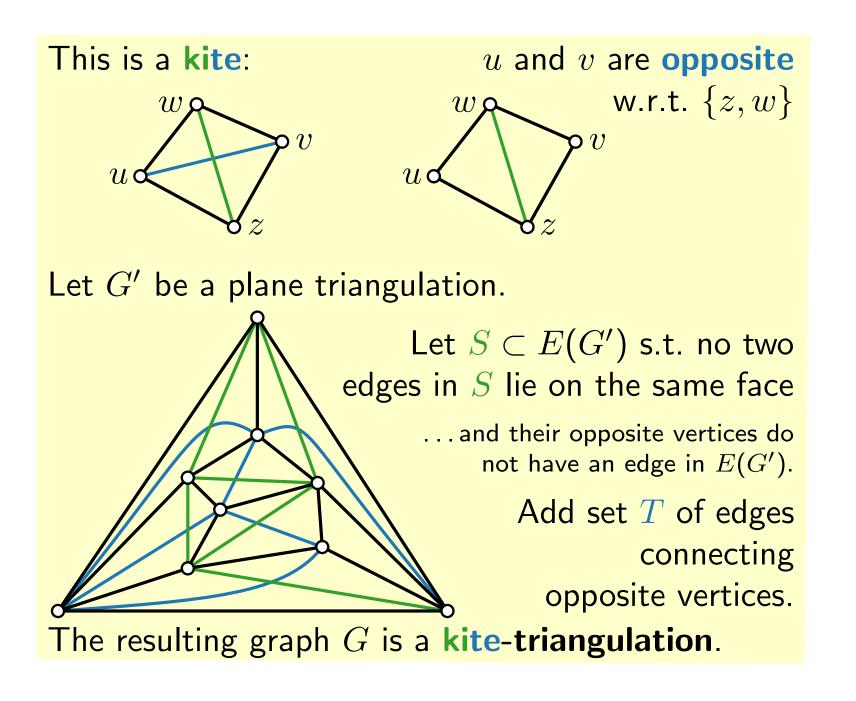


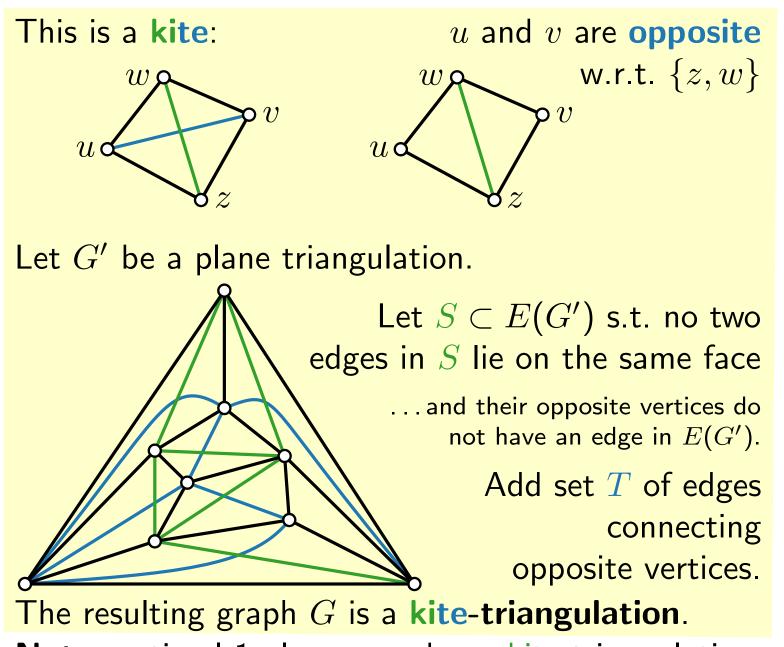




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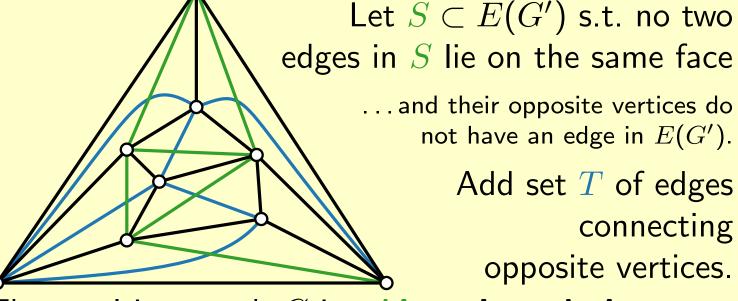




Note: optimal 1-planar graphs \subset kite-triangulations.

This is a **kite**: u and v are **opposite** w.r.t. $\{z, w\}$

Let G' be a plane triangulation.



The resulting graph G is a **kite-triangulation**. **Note:** optimal 1-planar graphs \subset kite-triangulations.

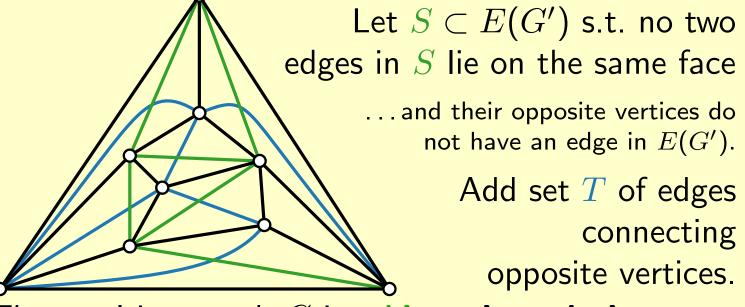
Theorem.

[Angelini et al. '11]

Every kite-triangulation G on n vertices admits a 1-planar 1-bend RAC drawing

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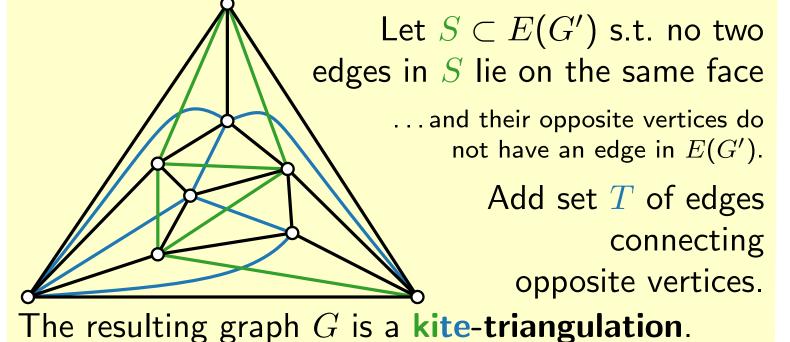
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Every kite-triangulation G on n vertices admits a 1-planar 1-bend RAC drawing, which can be constructed in $\mathcal{O}(n)$ time.

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Note: optimal 1-planar graphs \subset kite-triangulations.

Theorem.

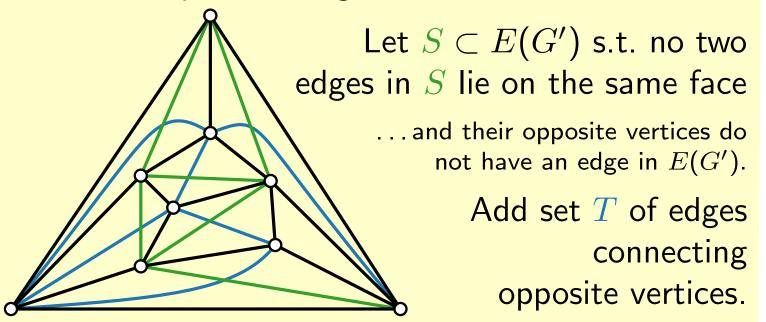
[Angelini et al. '11]

Every kite-triangulation G on n vertices admits a 1-planar 1-bend RAC drawing, which can be constructed in $\mathcal{O}(n)$ time.

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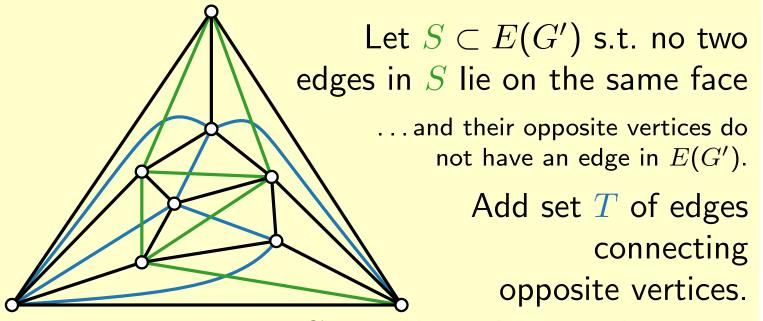
Every kite-triangulation G on n vertices admits a 1-planar 1-bend RAC drawing, which can be constructed in $\mathcal{O}(n)$ time.

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Let G' be the underlying plane triangulation of G.

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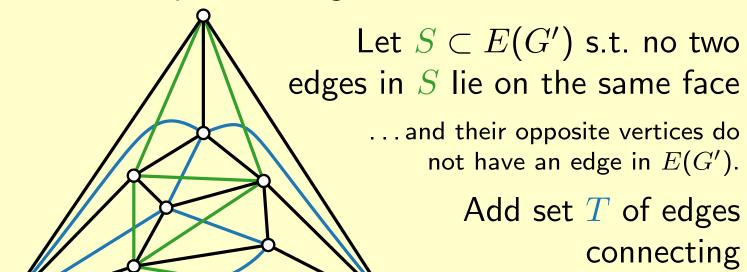
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Proof.

Let G' be the underlying plane triangulation of G. Let G'' = G' - S.

This is a **kite**: u and v are **opposite** w.r.t. $\{z, w\}$

Let G' be a plane triangulation.



The resulting graph G is a **kite-triangulation**.

Note: optimal 1-planar graphs \subset kite-triangulations.

opposite vertices.

Theorem.

[Angelini et al. '11]

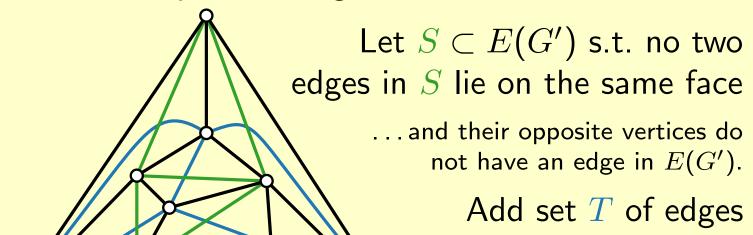
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Proof.

Let G' be the underlying plane triangulation of G. Let G'' = G' - S. Construct straight-line drawing of G''.

This is a **kite**: u and v are **opposite** w.r.t. $\{z,w\}$

Let G' be a plane triangulation.



The resulting graph G is a **kite-triangulation**.

Note: optimal 1-planar graphs \subset kite-triangulations.

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Every kite-triangulation G on n vertices admits a 1-planar 1-bend RAC drawing, which can be constructed in $\mathcal{O}(n)$ time.

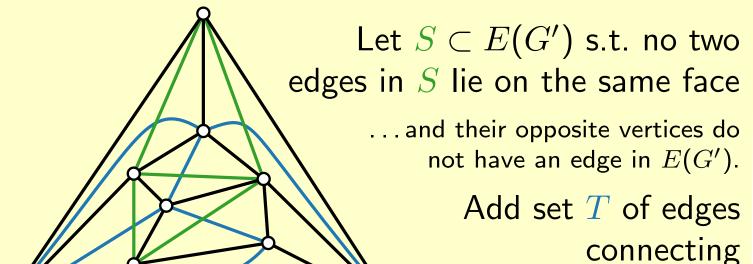
Proof.

connecting

opposite vertices.

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Let G' be a plane triangulation.



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Note: optimal 1-planar graphs \subset kite-triangulations.

opposite vertices.

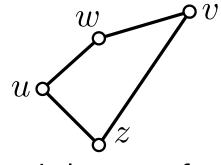
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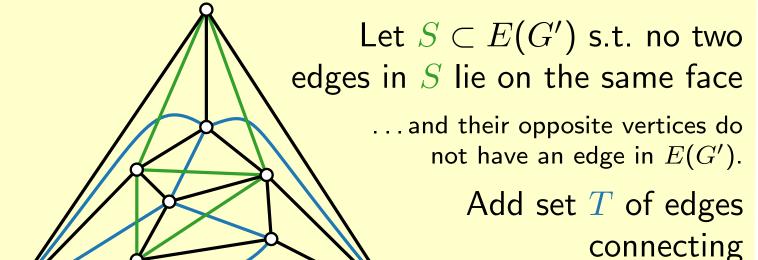
Let G' be the underlying plane triangulation of G. Let G'' = G' - S. Construct straight-line drawing of G''. Fill faces as follows:



strictly convex face

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Let G' be a plane triangulation.



The resulting graph G is a **kite-triangulation**.

Note: optimal 1-planar graphs \subset kite-triangulations.

opposite vertices.

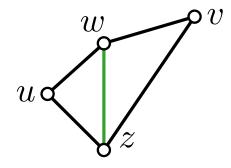
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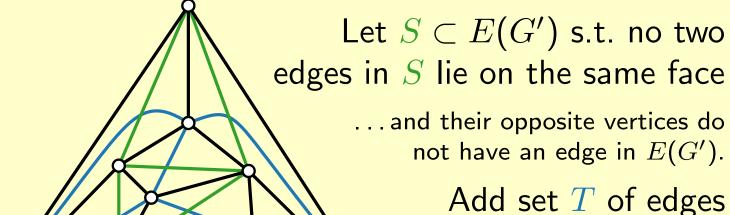
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strictly convex face

This is a **kite**: u and v are **opposite** w.r.t. $\{z, w\}$

Let G' be a plane triangulation.



Add set T of edges connecting opposite vertices.

The resulting graph G is a **kite-triangulation**.

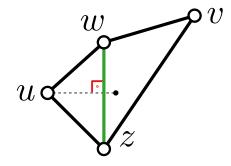
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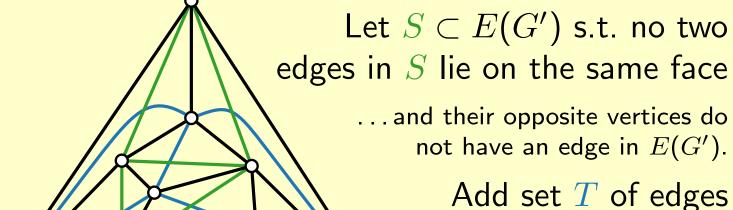
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Let G' be a plane triangulation.



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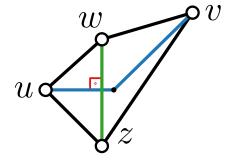
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Proof.



strictly convex face

Let $S\subset E(G')$ s.t. no two edges in S lie on the same face ... and their opposite vertices do not have an edge in E(G').

Add set *T* of edges connecting opposite vertices.

The resulting graph G is a **kite-triangulation**.

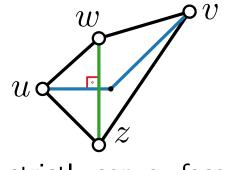
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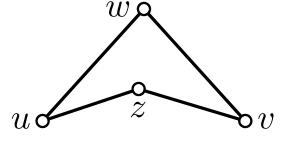
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Proof.







otherwise

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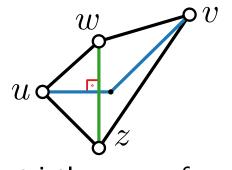
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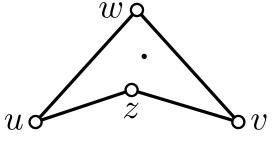
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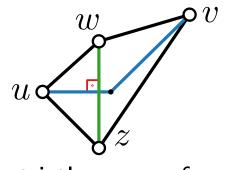
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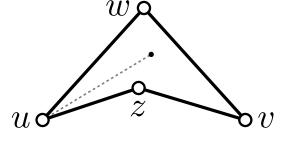
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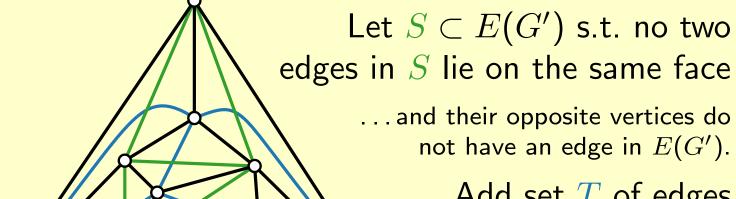




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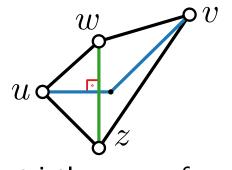
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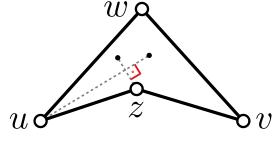
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Proof.







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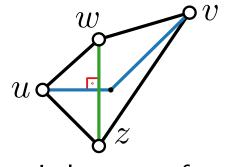
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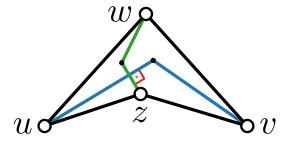
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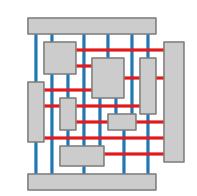


Visualization of Graphs

Lecture 11:

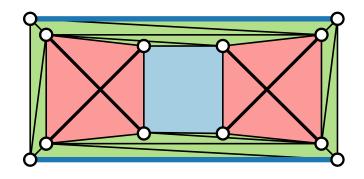
Beyond Planarity

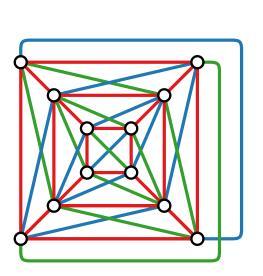
Drawing Graphs with Crossings





Alexander Wolff





Theorem. [Bekos, Didimo, Liotta, Mehrabi & Montecchiani 2017]

Every 1-planar graph G admits a 1-planar 1-bend RAC drawing.

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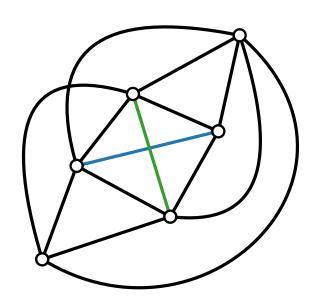
Every 1-planar graph G admits a 1-planar 1-bend RAC drawing. If a 1-planar embedding of G is given as part of the input, such a drawing can be computed in linear time.

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Observation.

In a triangulated 1-plane graph (not necessarily simple), each pair of crossing edges of G forms a(n empty) kite,

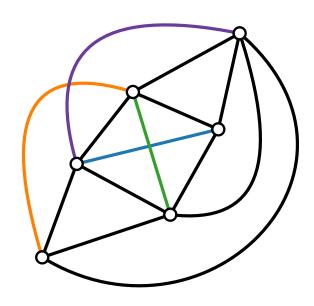


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In a triangulated 1-plane graph (not necessarily simple), each pair of crossing edges of G forms a(n empty) kite, except for at most one pair if their crossing point is on the outer face of G.

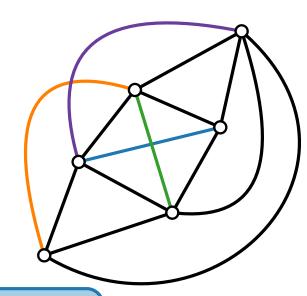


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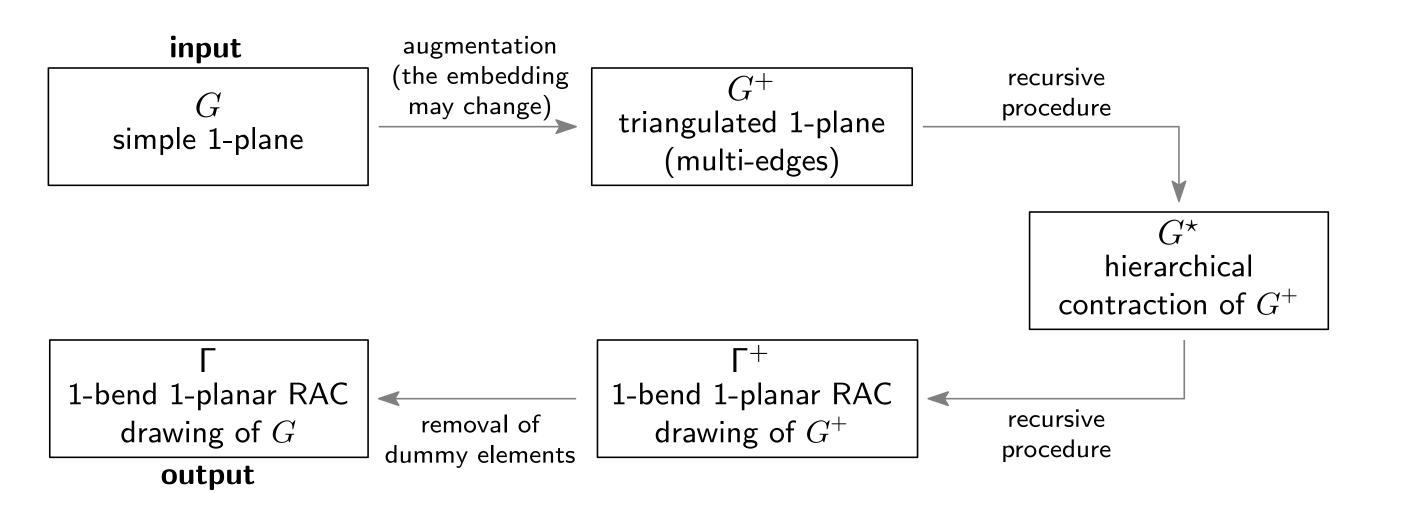


Theorem.

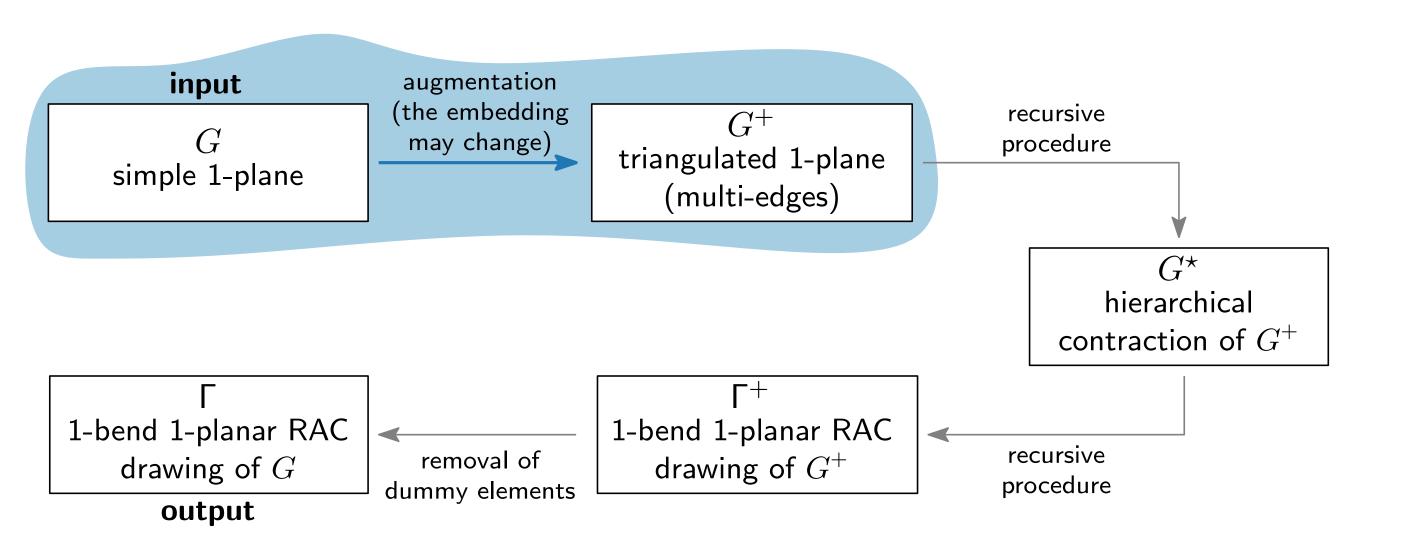
[Chiba, Yamanouchi & Nishizeki 1984]

For every plane graph G with outer face C_k and every convex k-gon P, there exists a strictly convex planar straight-line drawing of G whose outer face coincides with P. Such a drawing can be computed in linear time.

Algorithm Outline

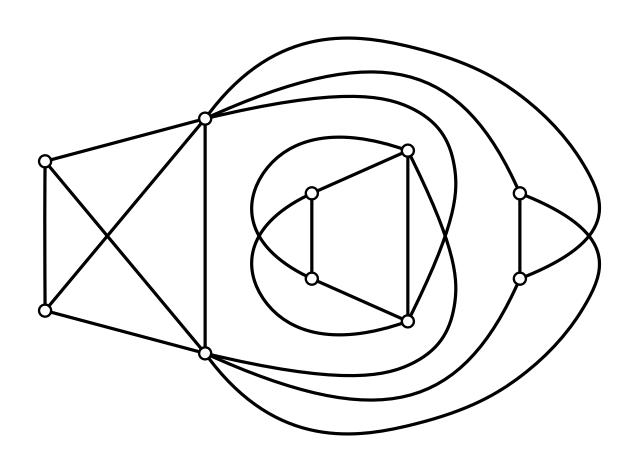


Algorithm Outline

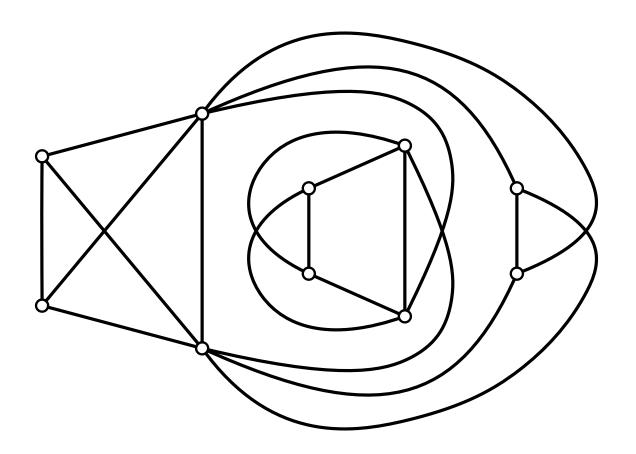


Algorithm Step 1: Augmentation

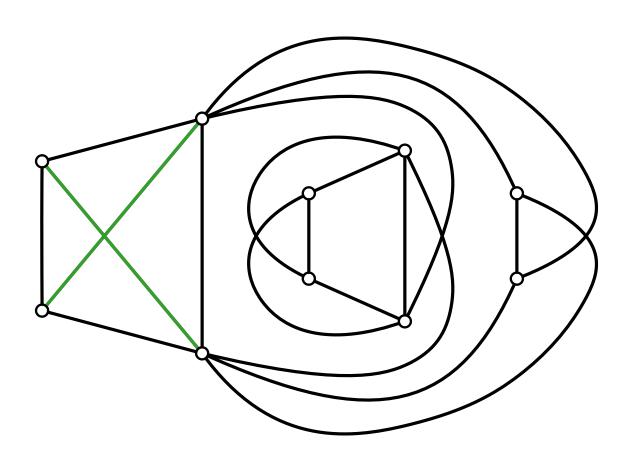
G: simple 1-plane graph



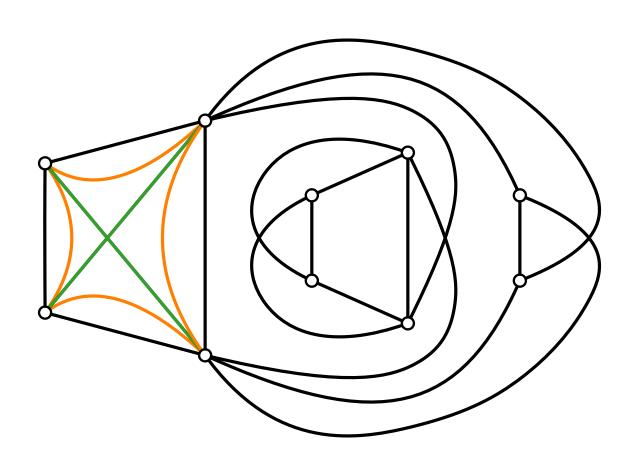
1. For each pair of crossing edges add an enclosing 4-cycle.



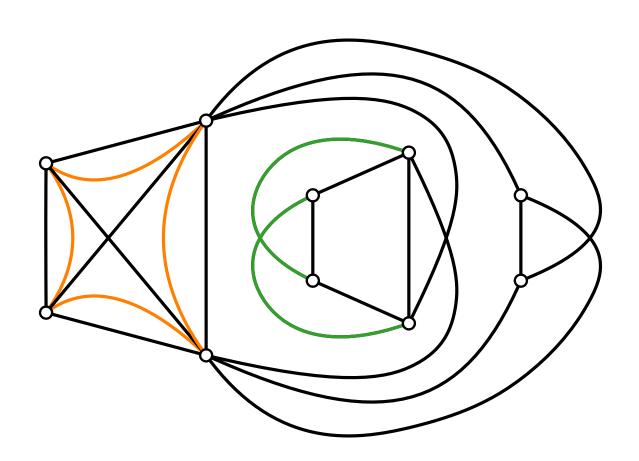
1. For each pair of crossing edges add an enclosing 4-cycle.



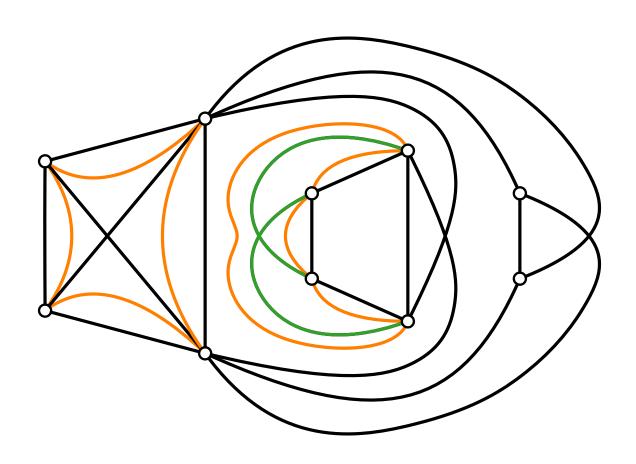
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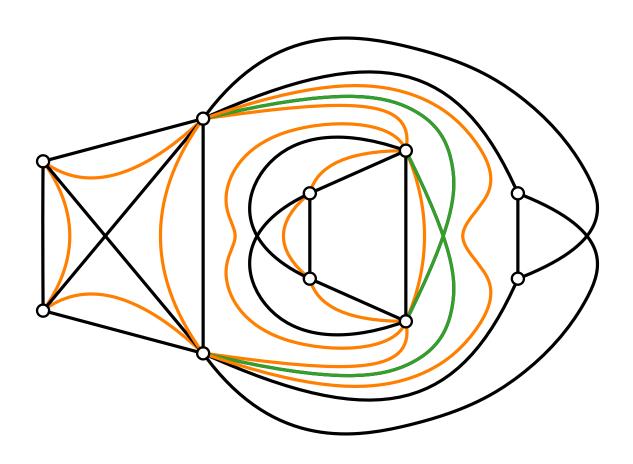
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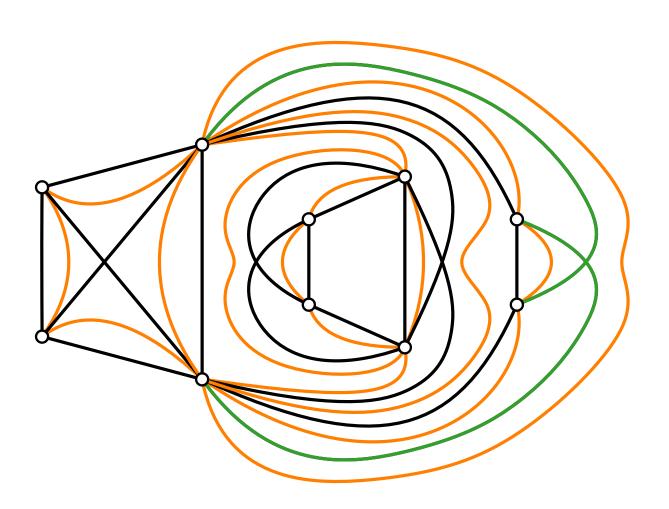
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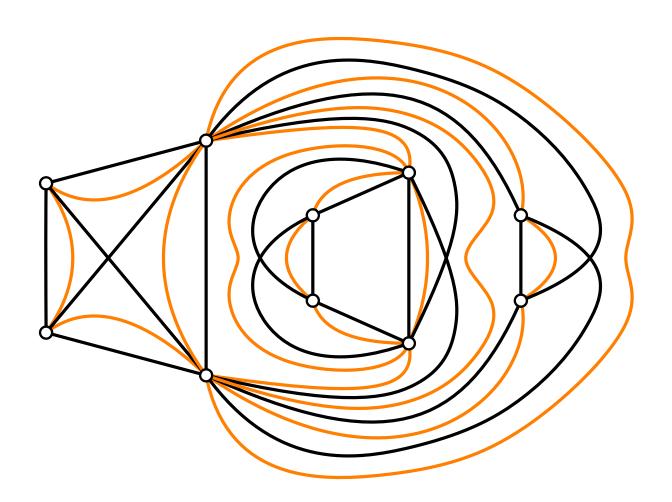
1. For each pair of crossing edges add an enclosing 4-cycle.



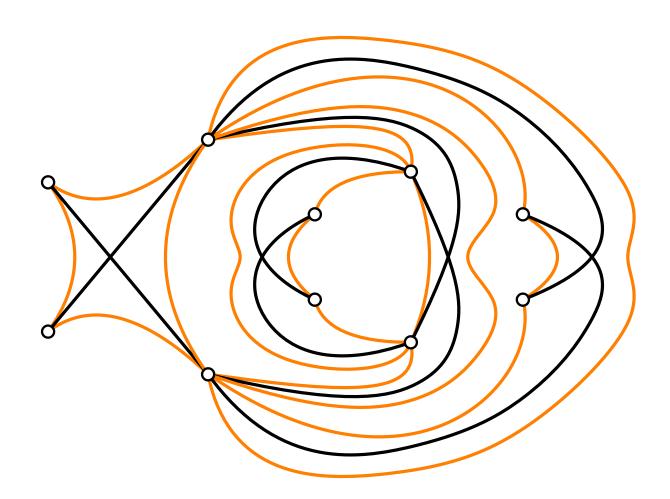
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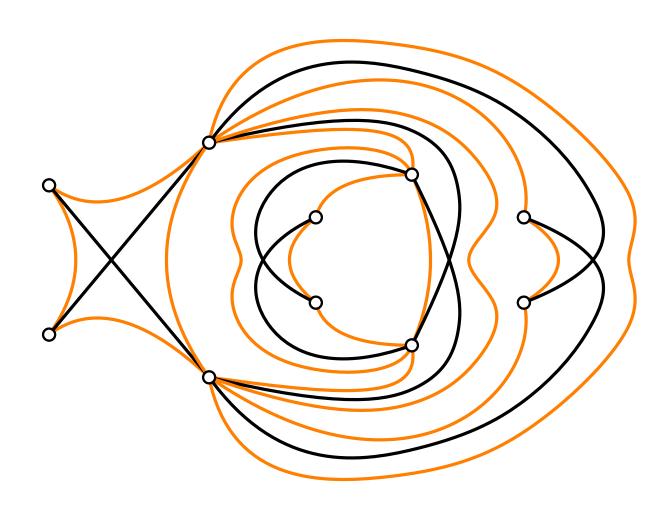
- 1. For each pair of crossing edges add an enclosing 4-cycle.
- 2. Remove those multiple edges that belong to G.



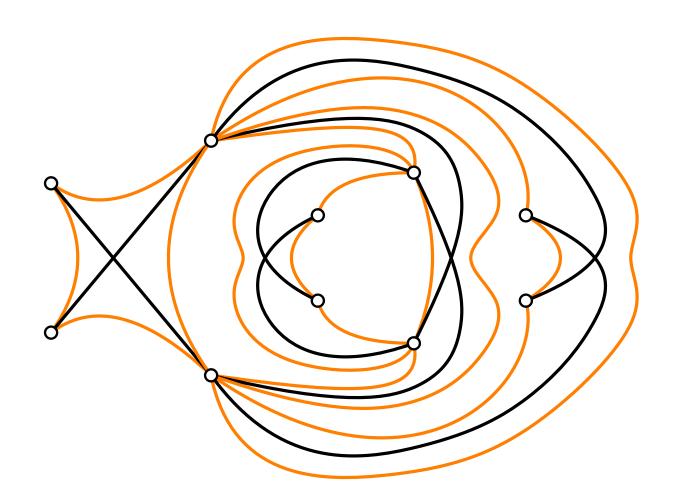
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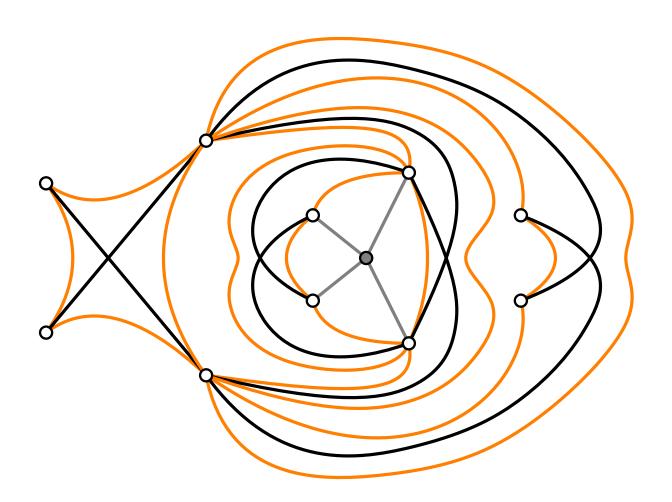
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- 4. Triangulate faces of degree > 3 by inserting a star inside them.

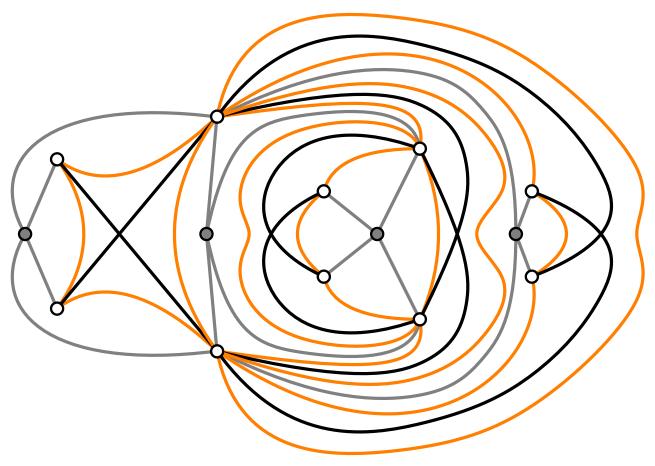


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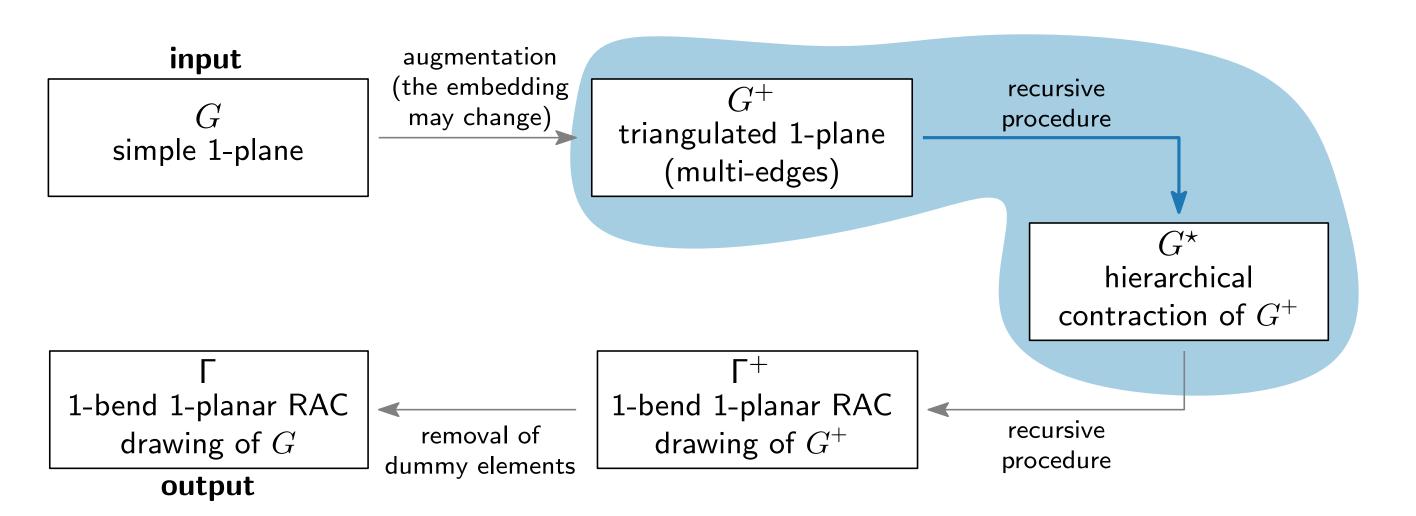


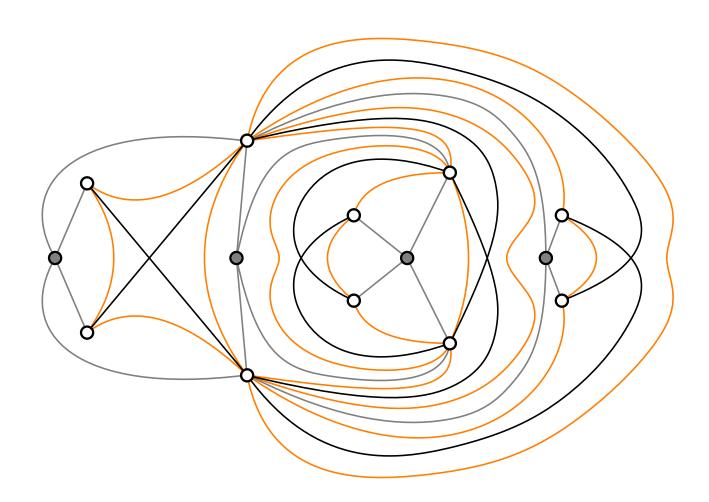
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G: simple 1-plane graph \longrightarrow G^+ : triangulated 1-plane (multi-edges)



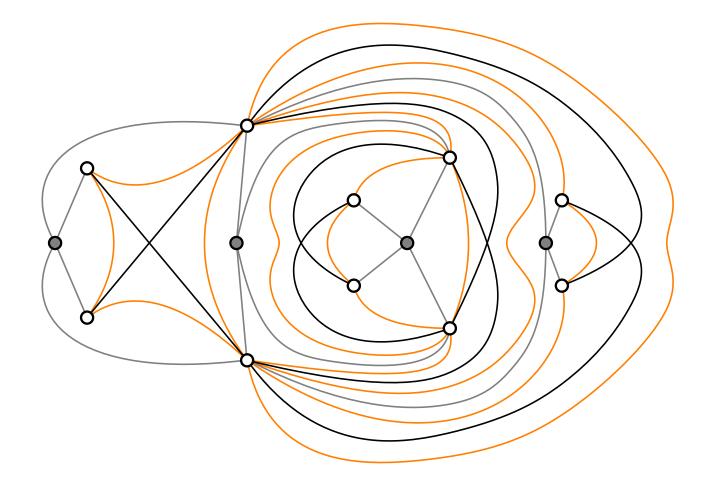
Algorithm Outline



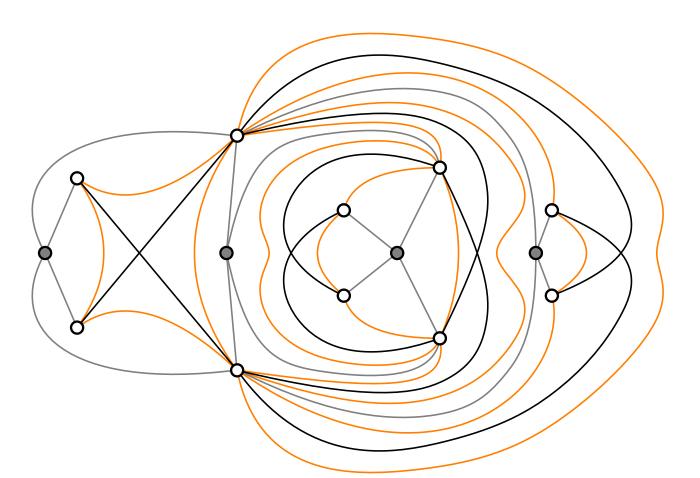


 G^+ triangulated 1-plane (multi-edges)

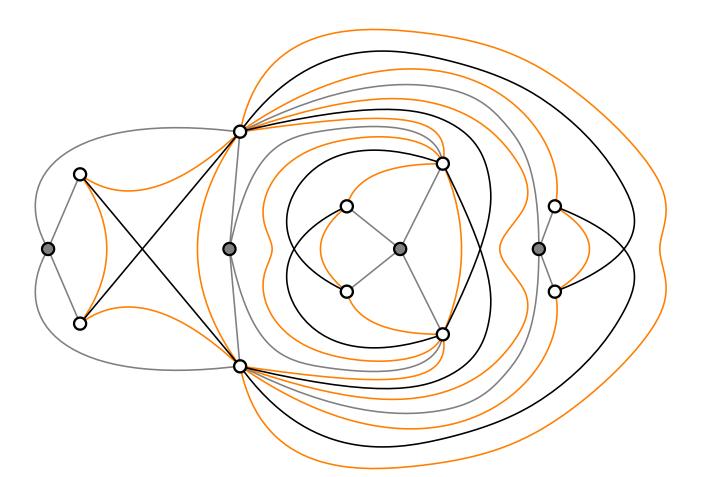
triangular faces



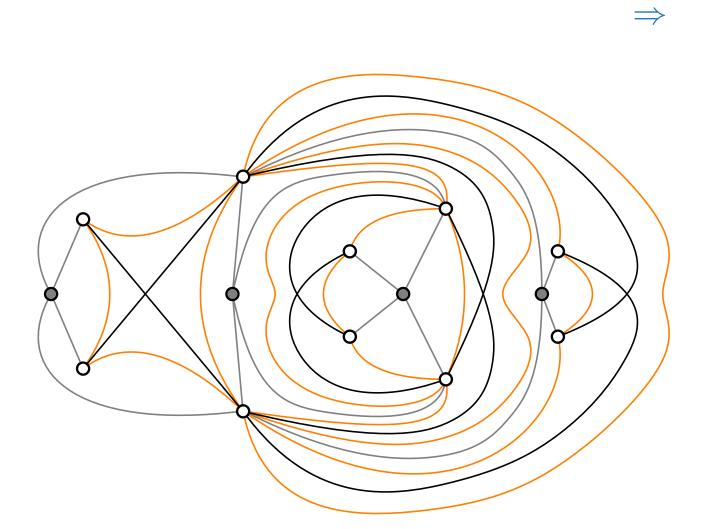
- triangular faces
- multiple edges never crossed

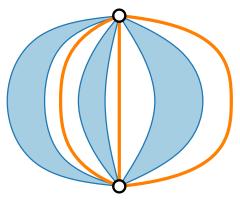


- triangular faces
- multiple edges never crossed
- only empty kites



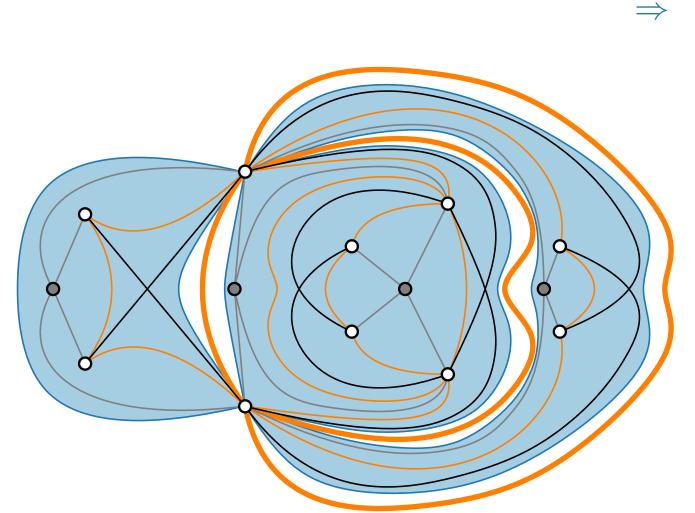
- triangular faces
- multiple edges never crossed
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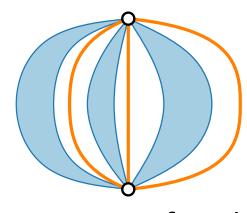




structure of each separation pair

- triangular faces
- multiple edges never crossed
- only empty kites

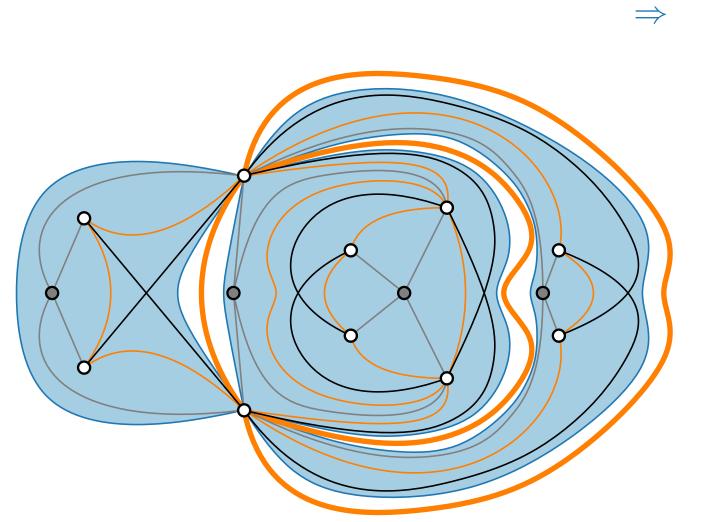


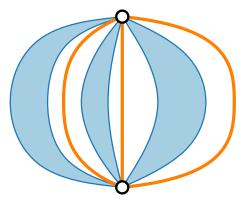


structure of each separation pair

 G^+ triangulated 1-plane (multi-edges)

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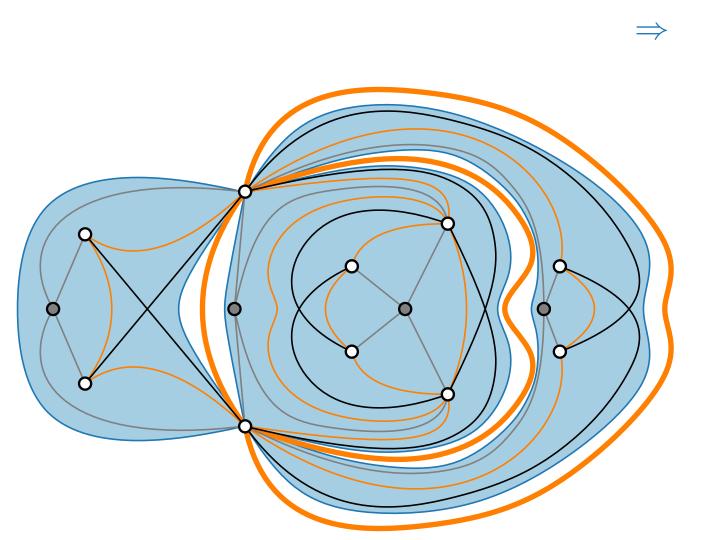


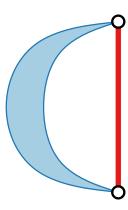


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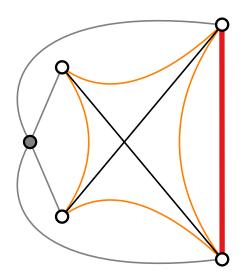




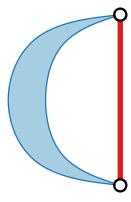
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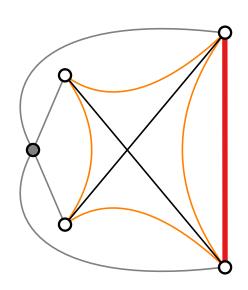


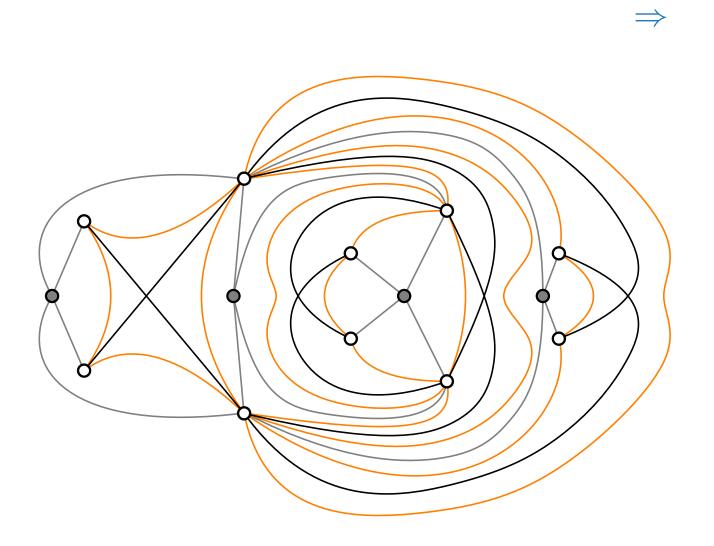


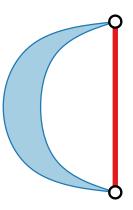
structure of each separation pair

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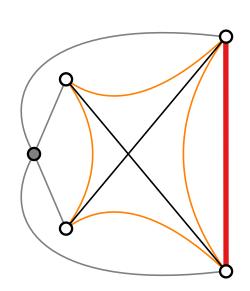


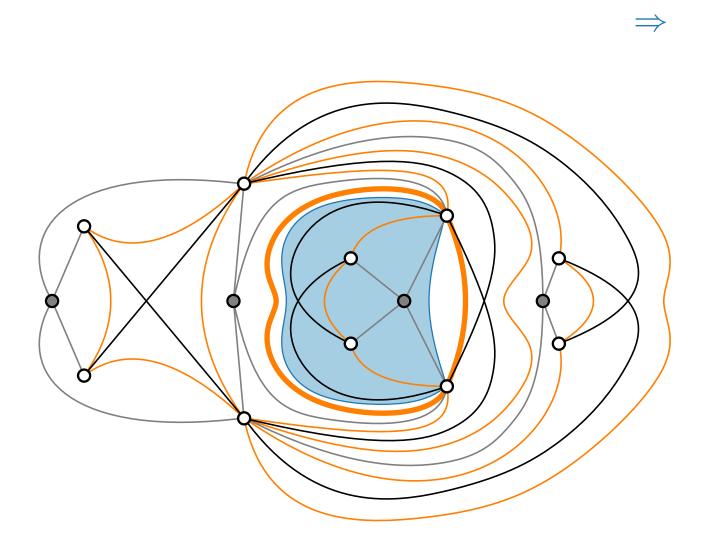


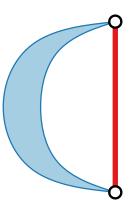
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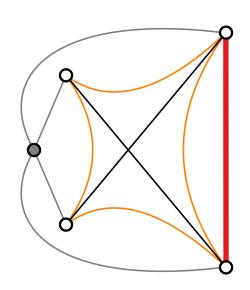


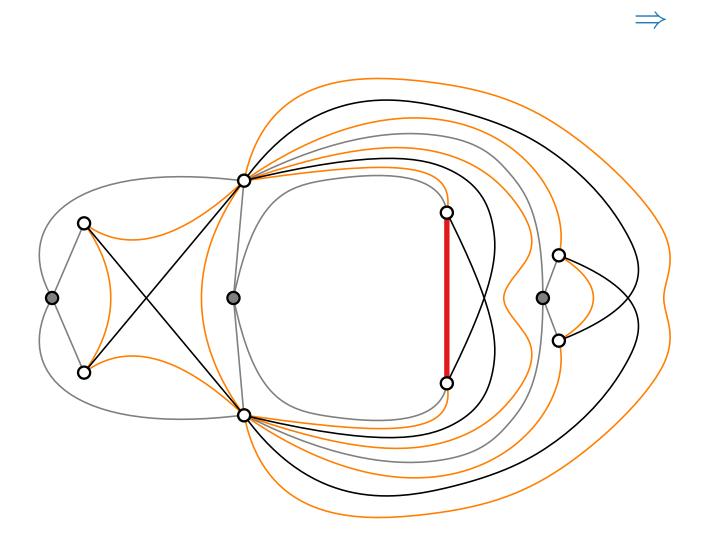


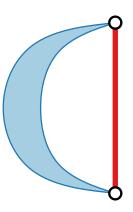
structure of each separation pair

 G^+ triangulated 1-plane (multi-edges)

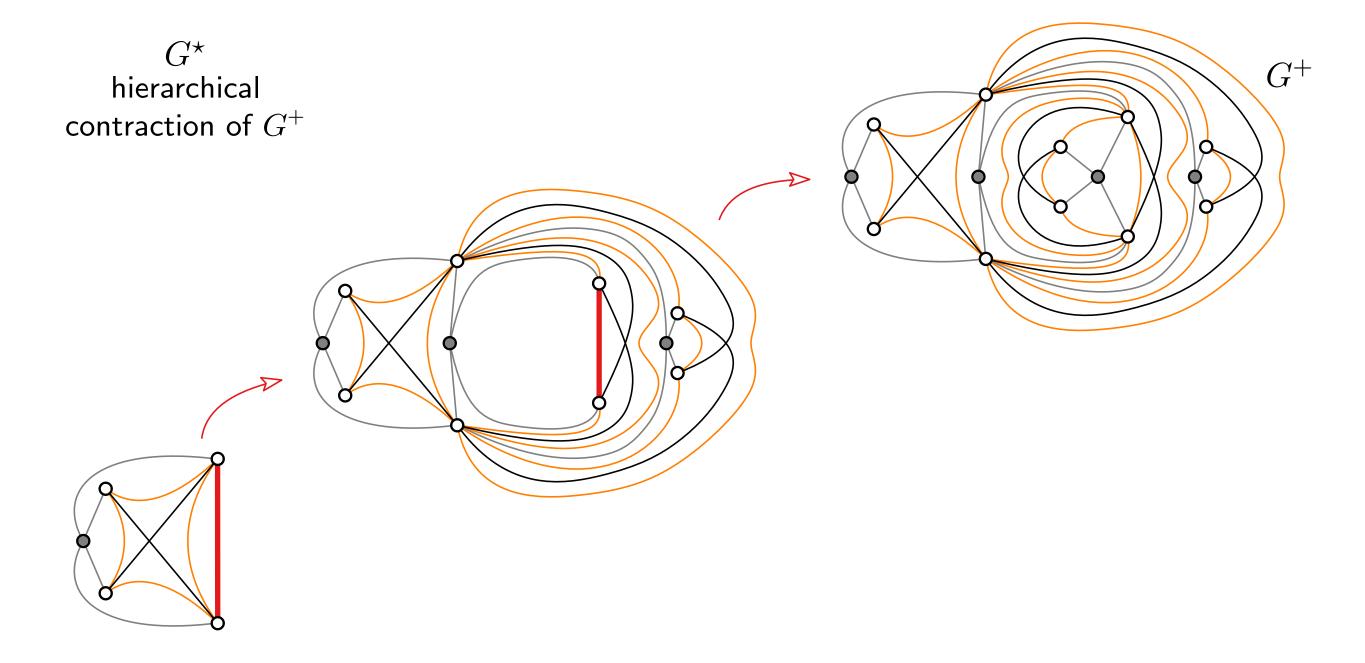
- triangular faces
- multiple edges never crossed
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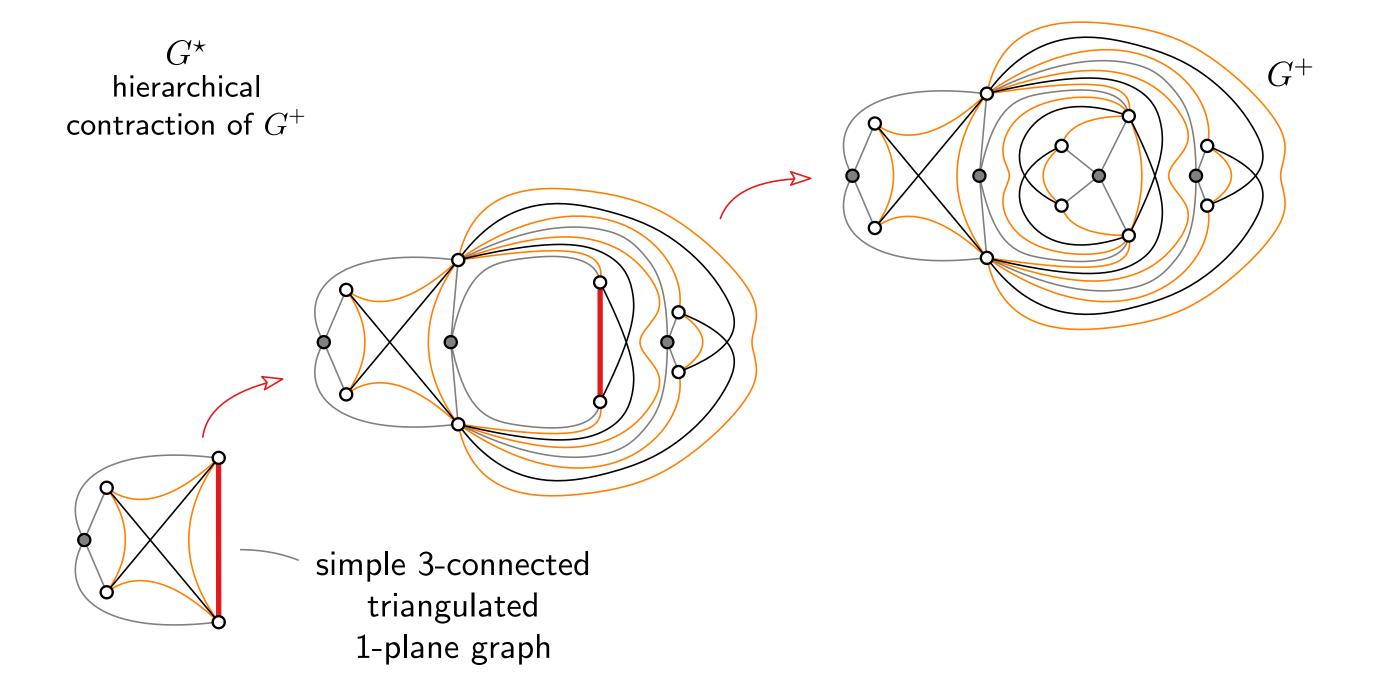




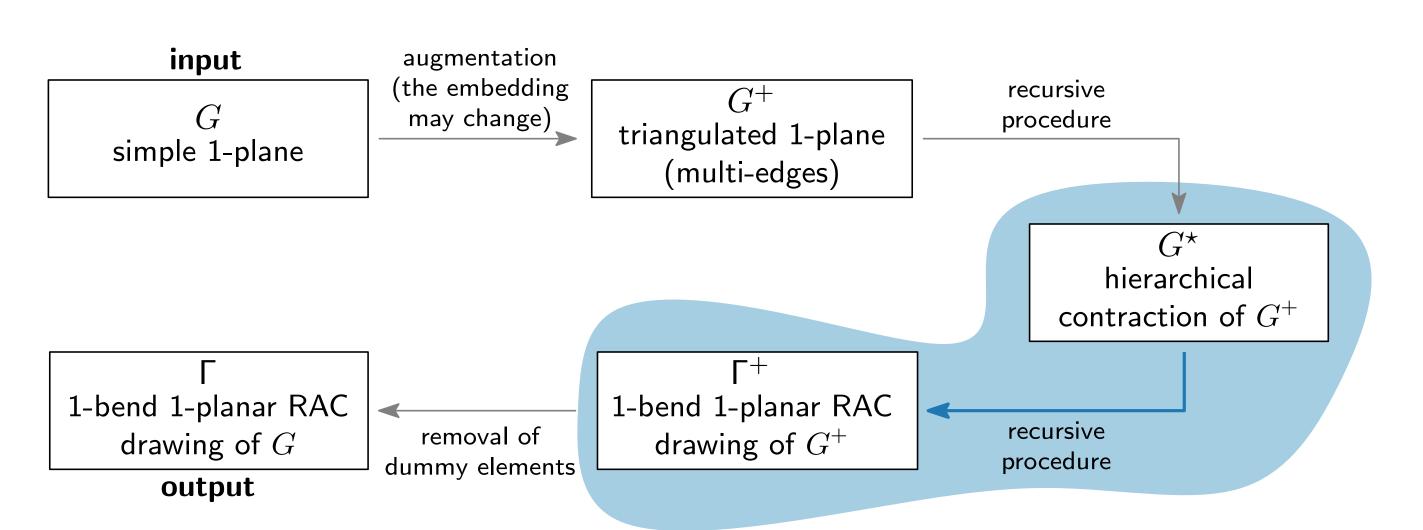


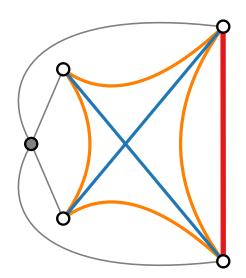
structure of each separation pair

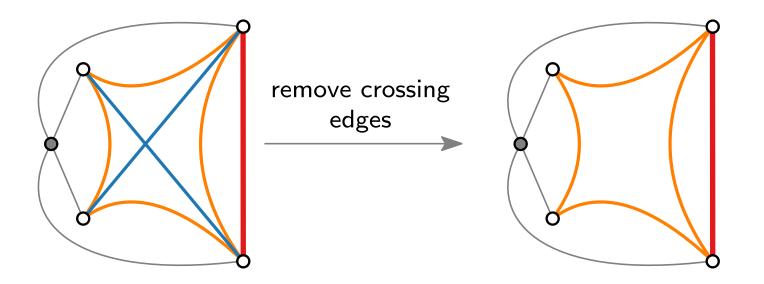


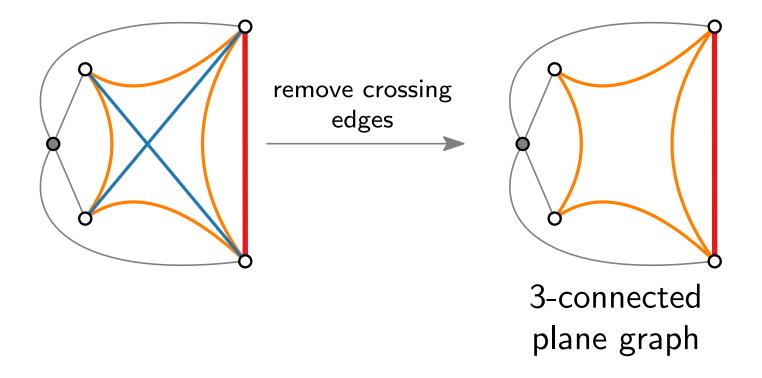


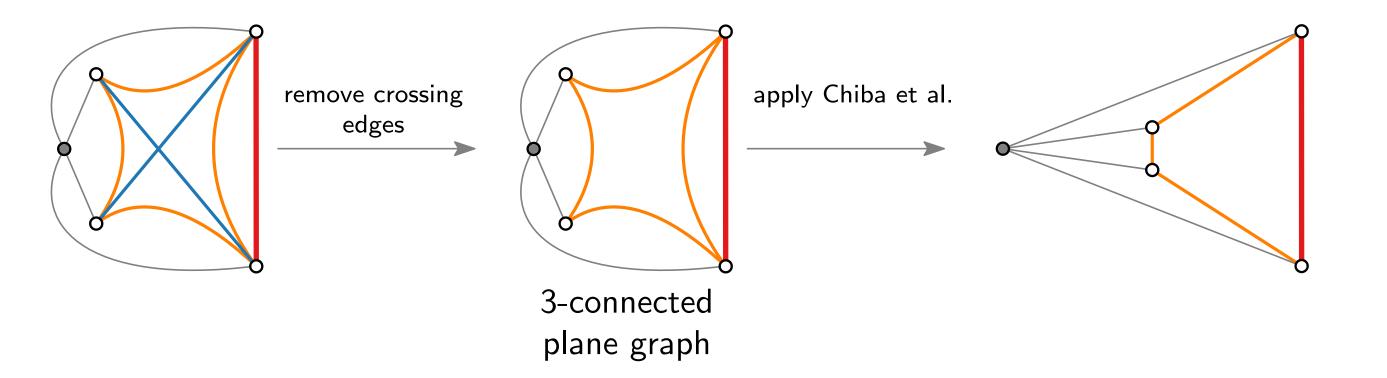
Algorithm Outline

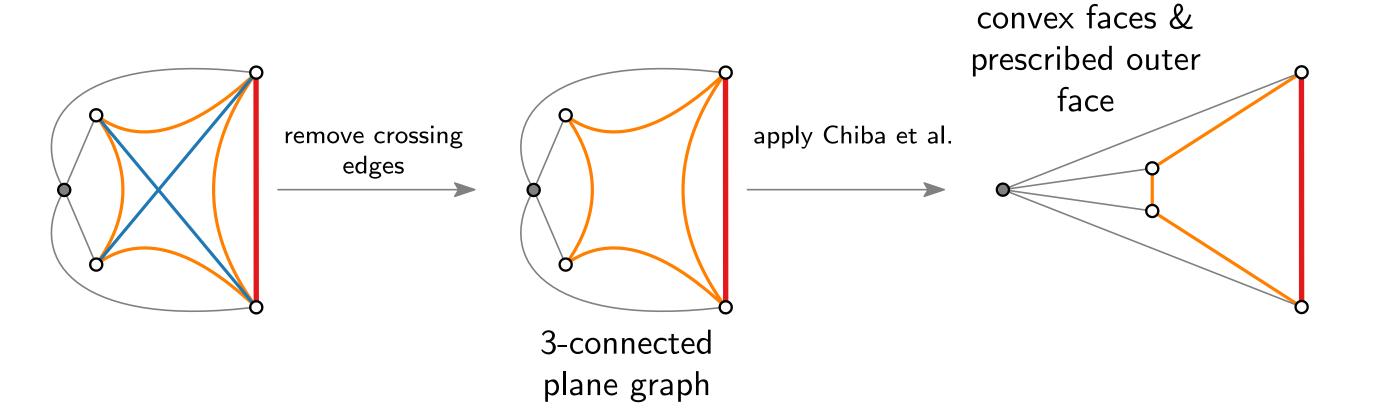


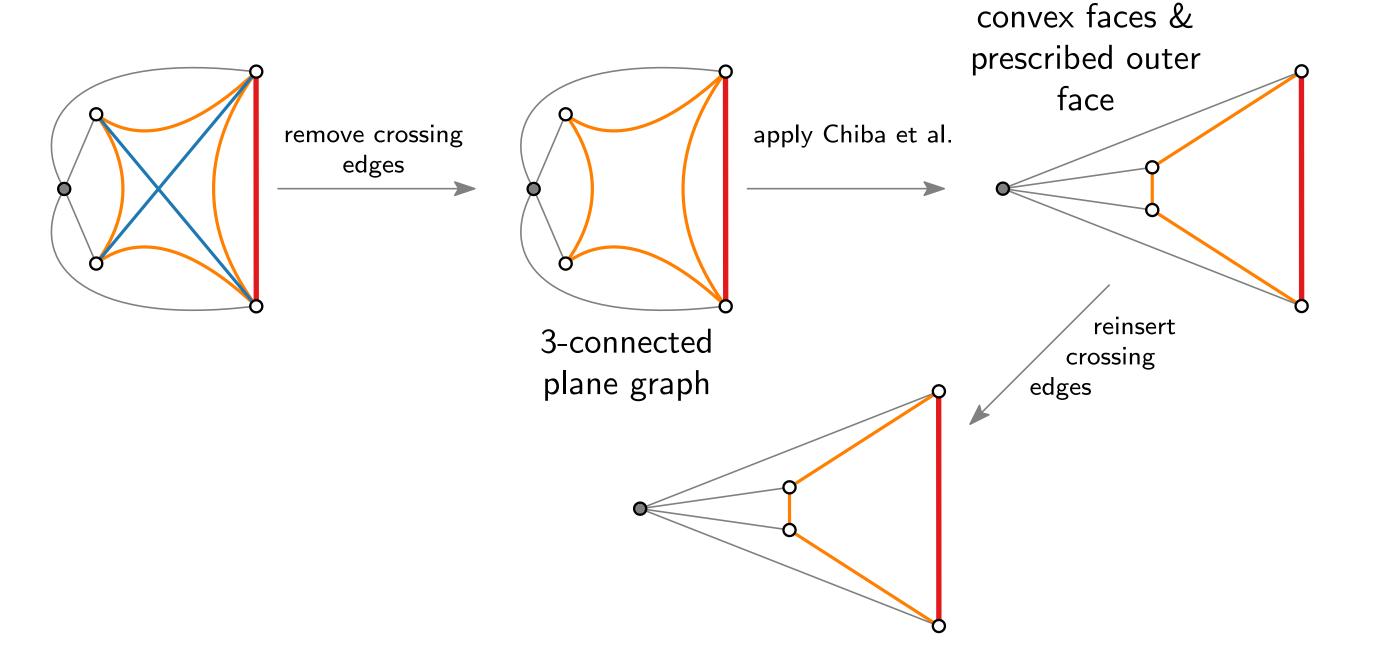


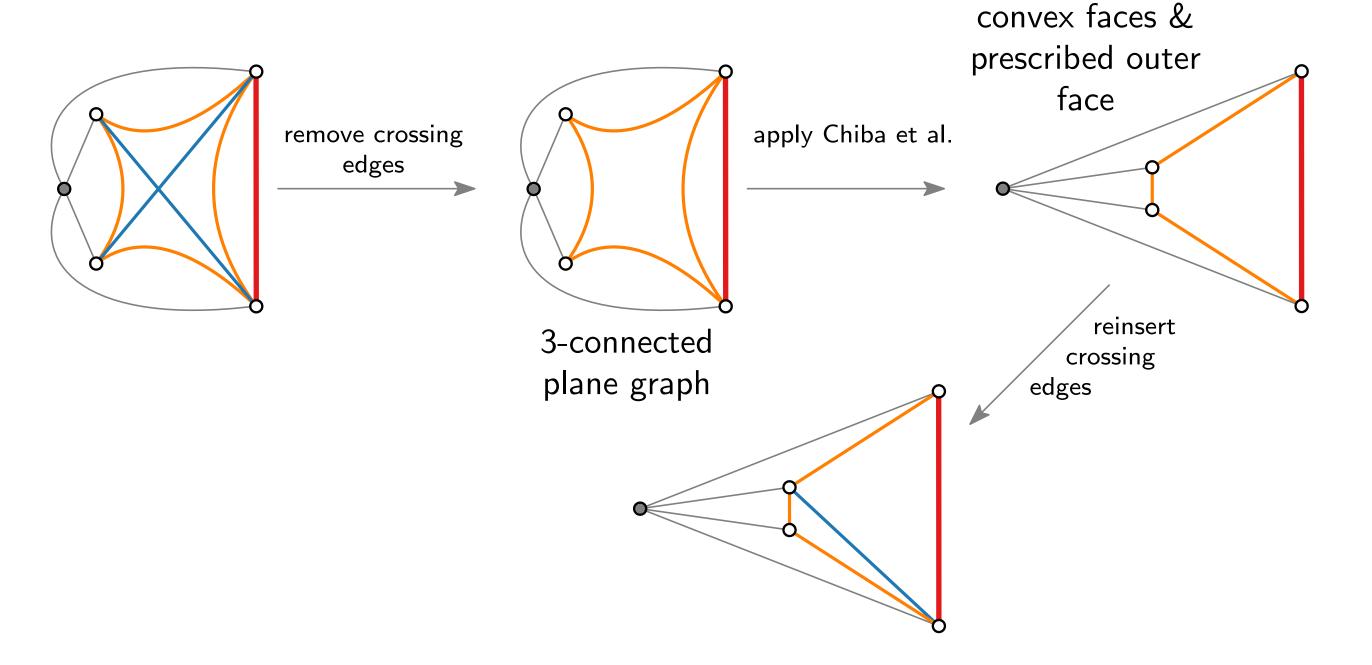


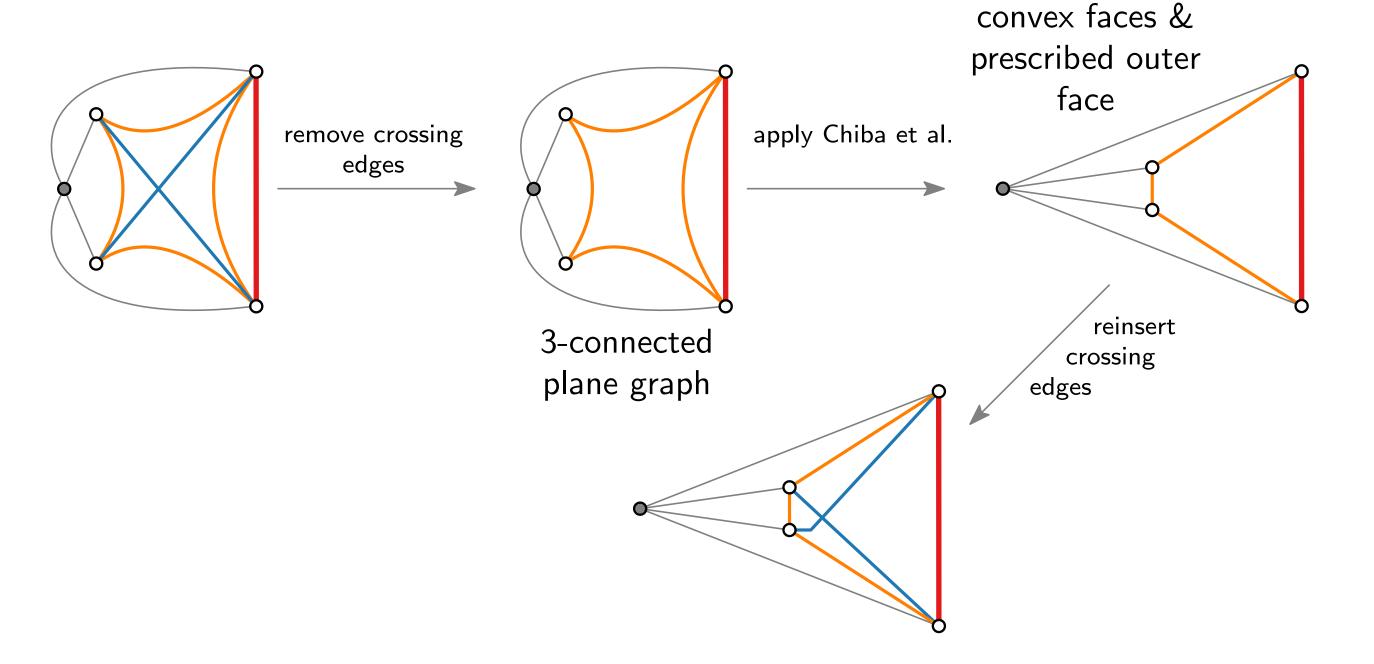


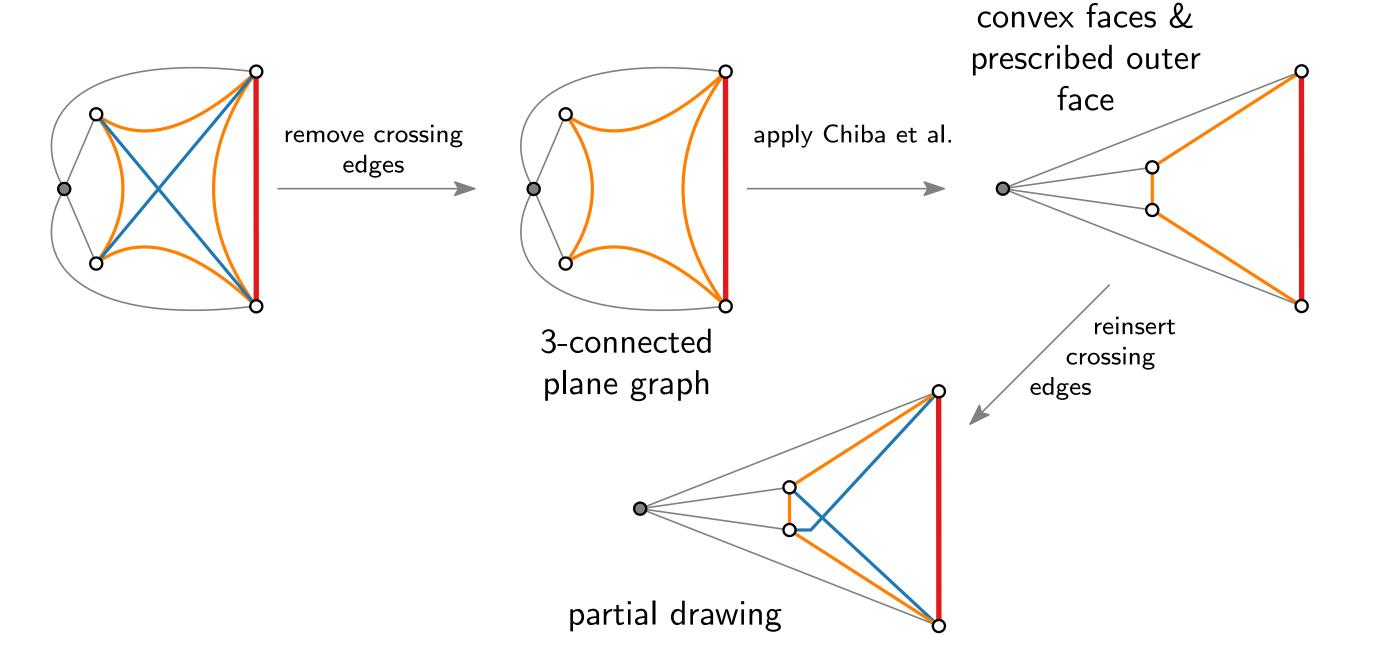


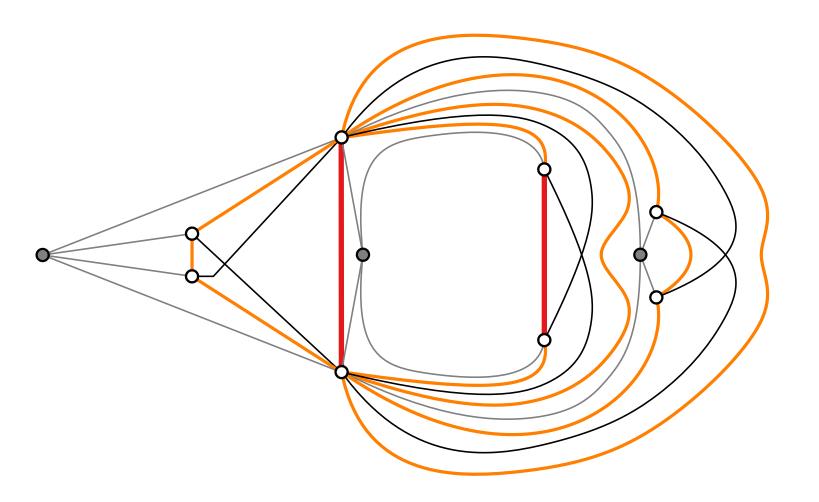


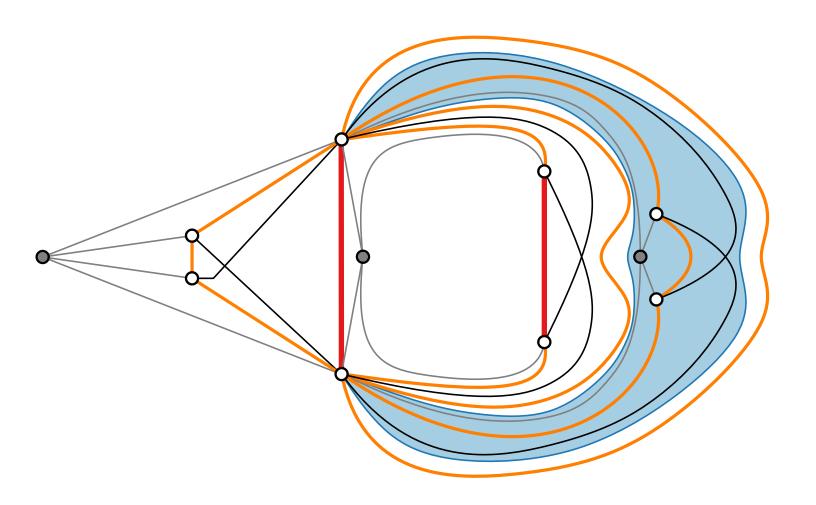


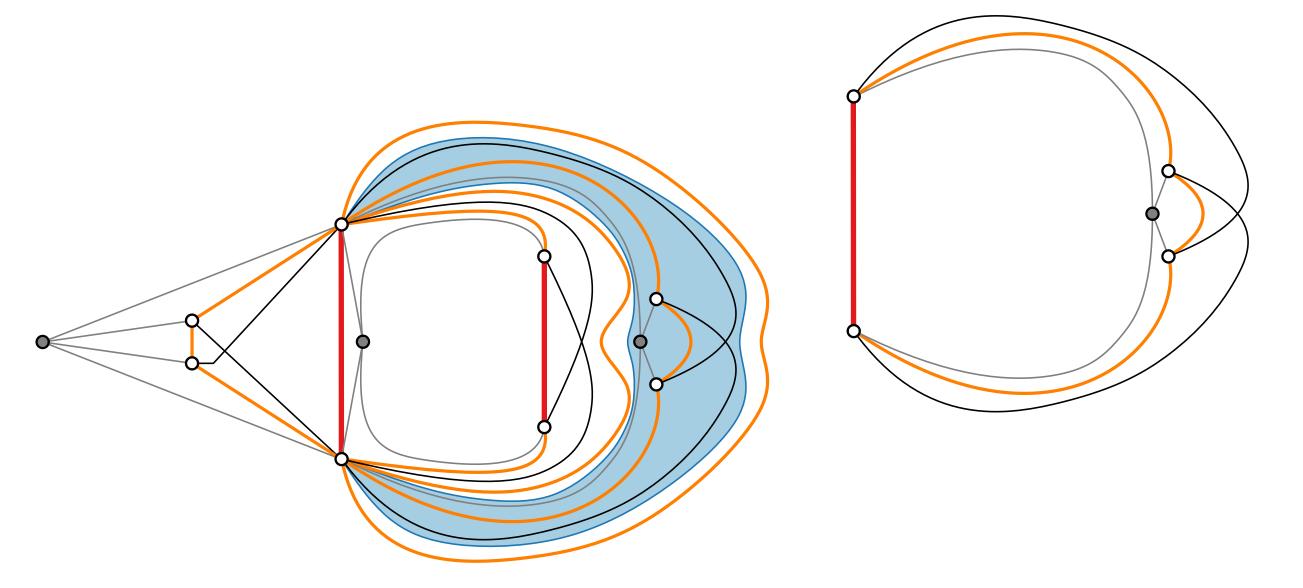


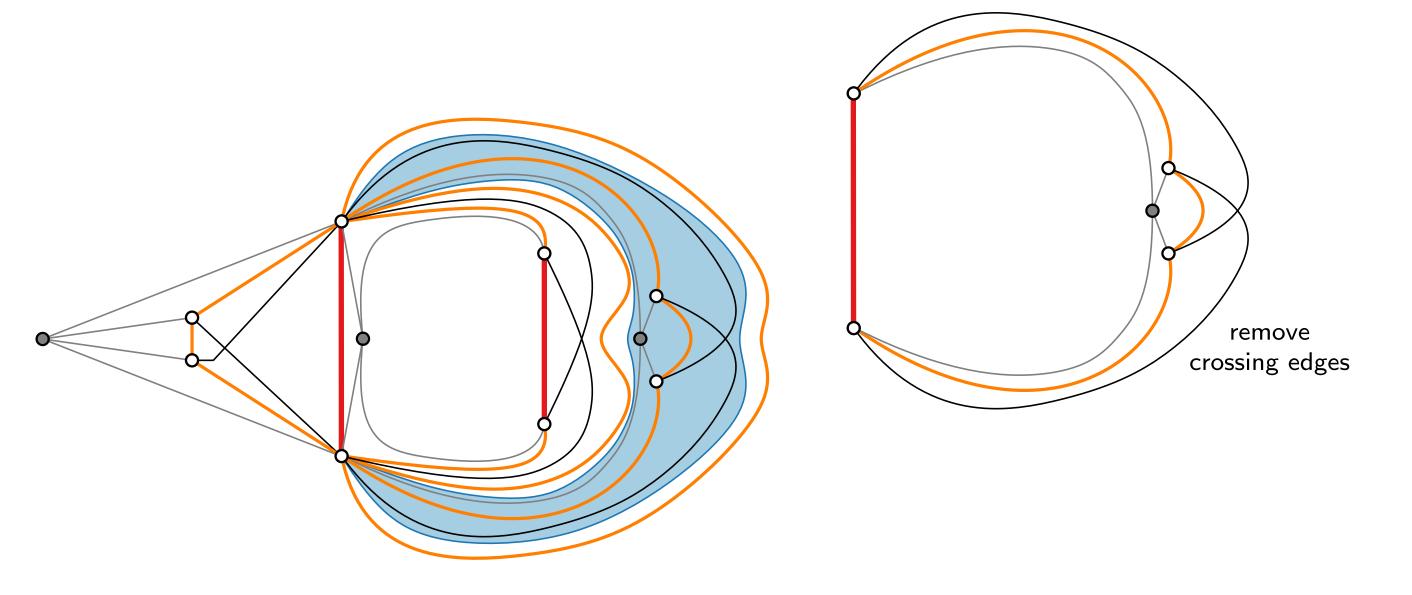


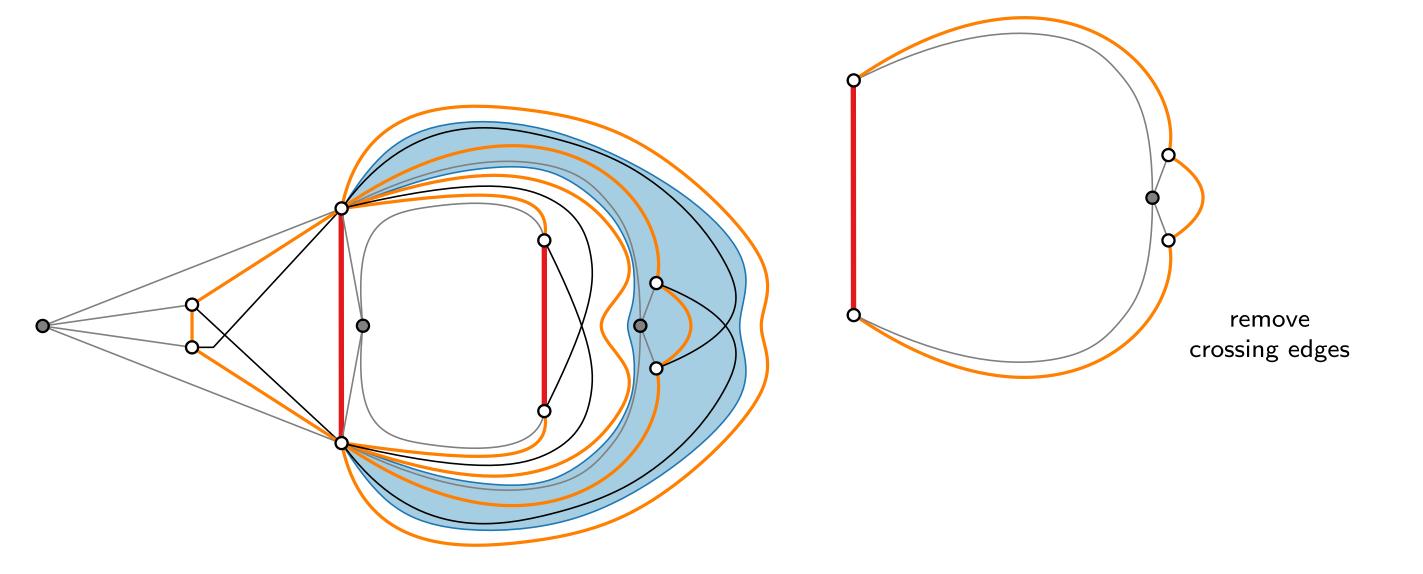


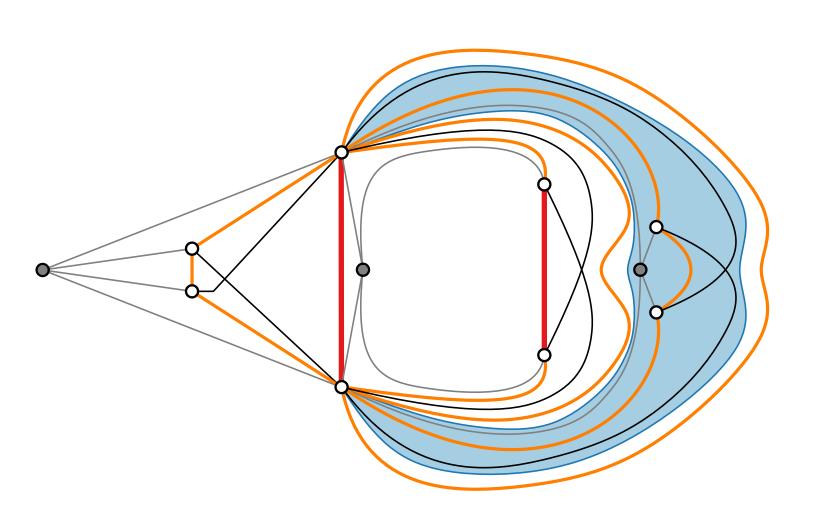


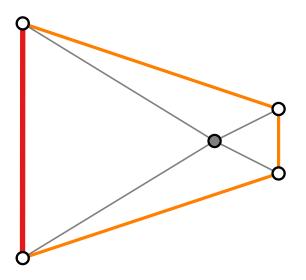




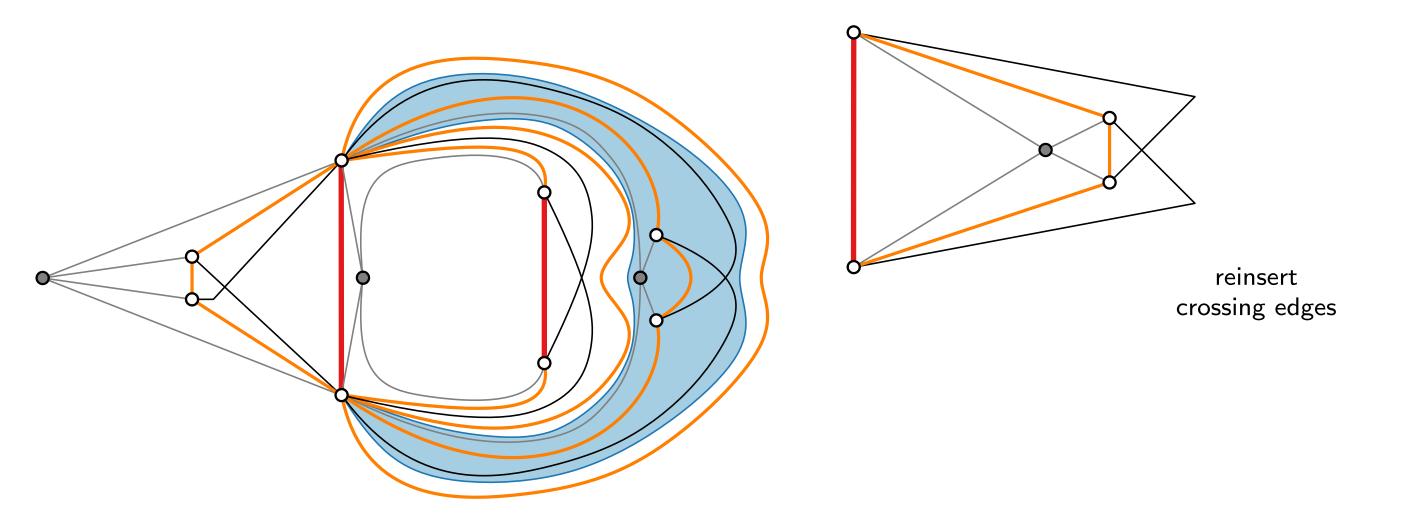


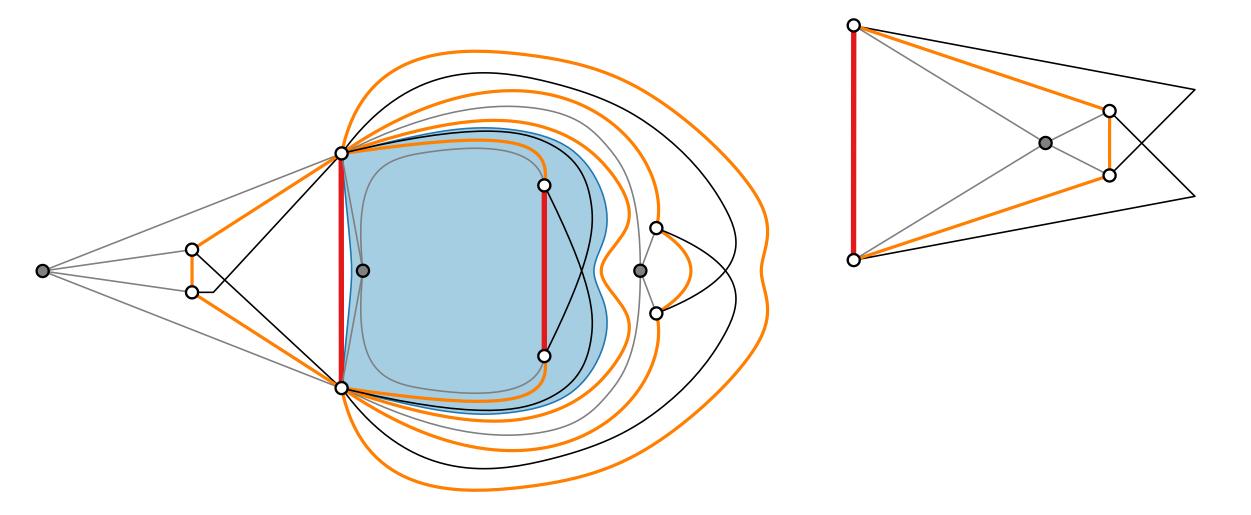


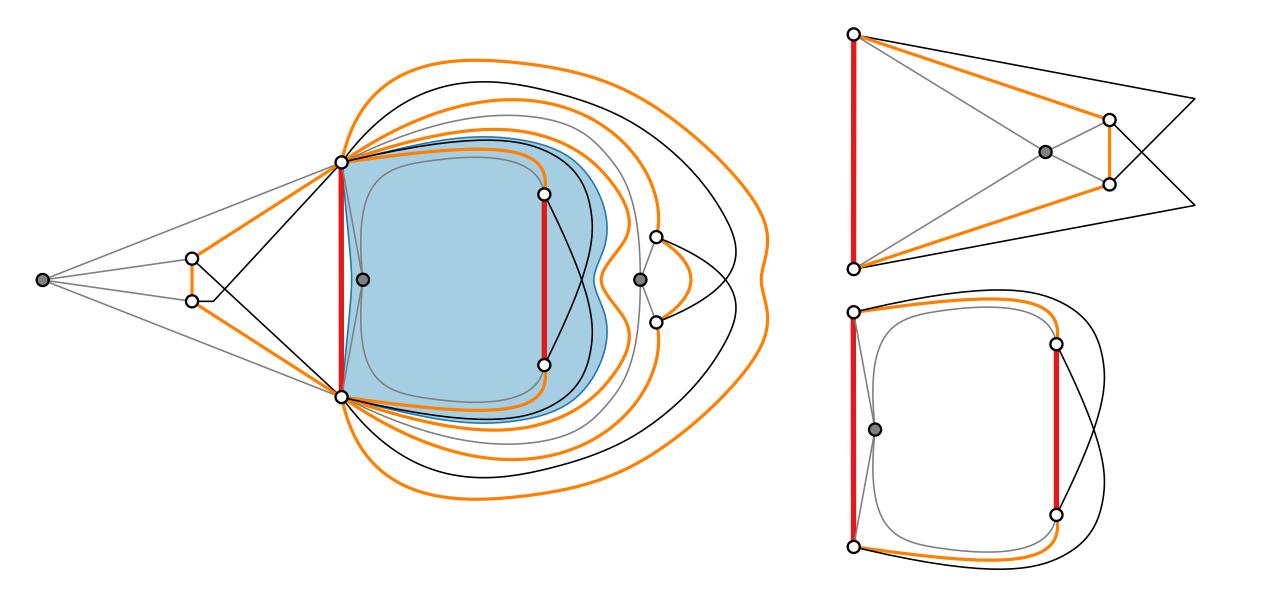


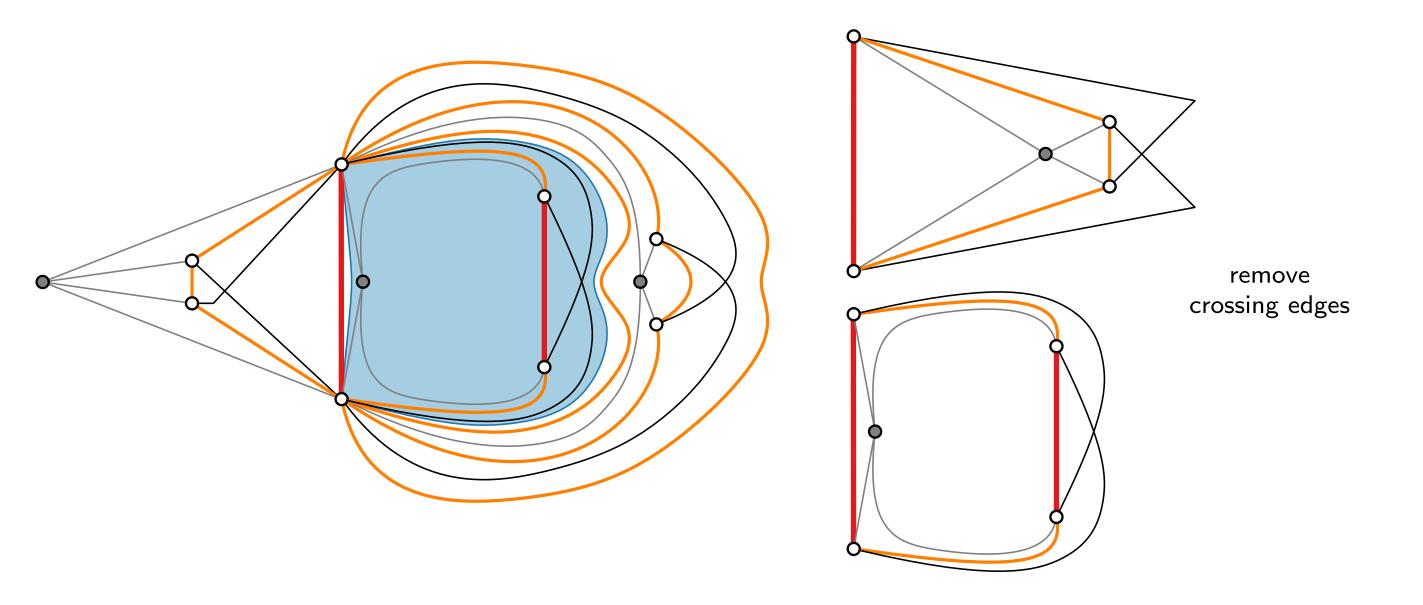


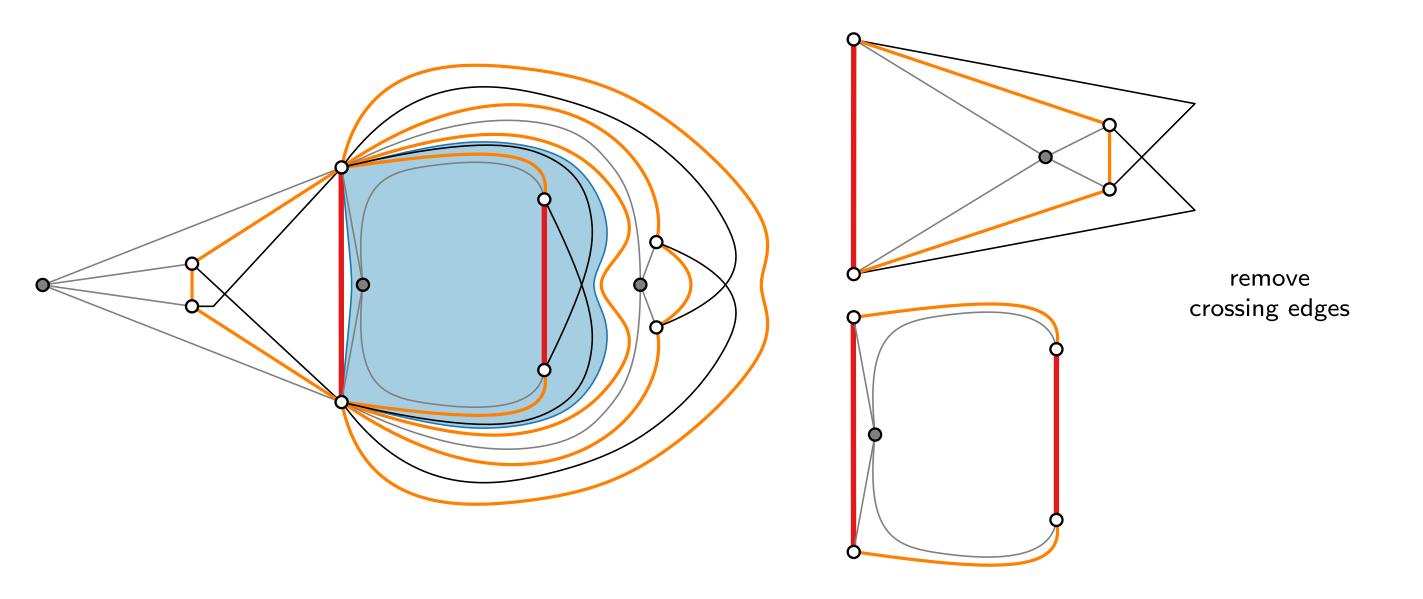
apply Chiba et al.

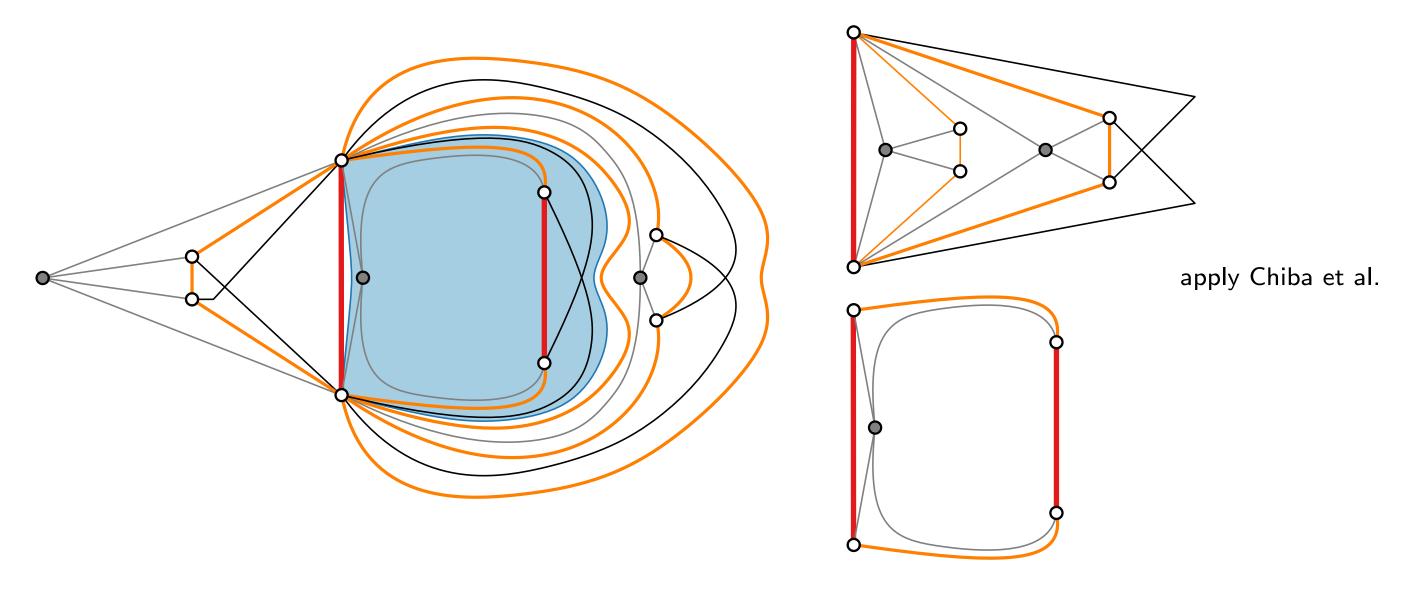


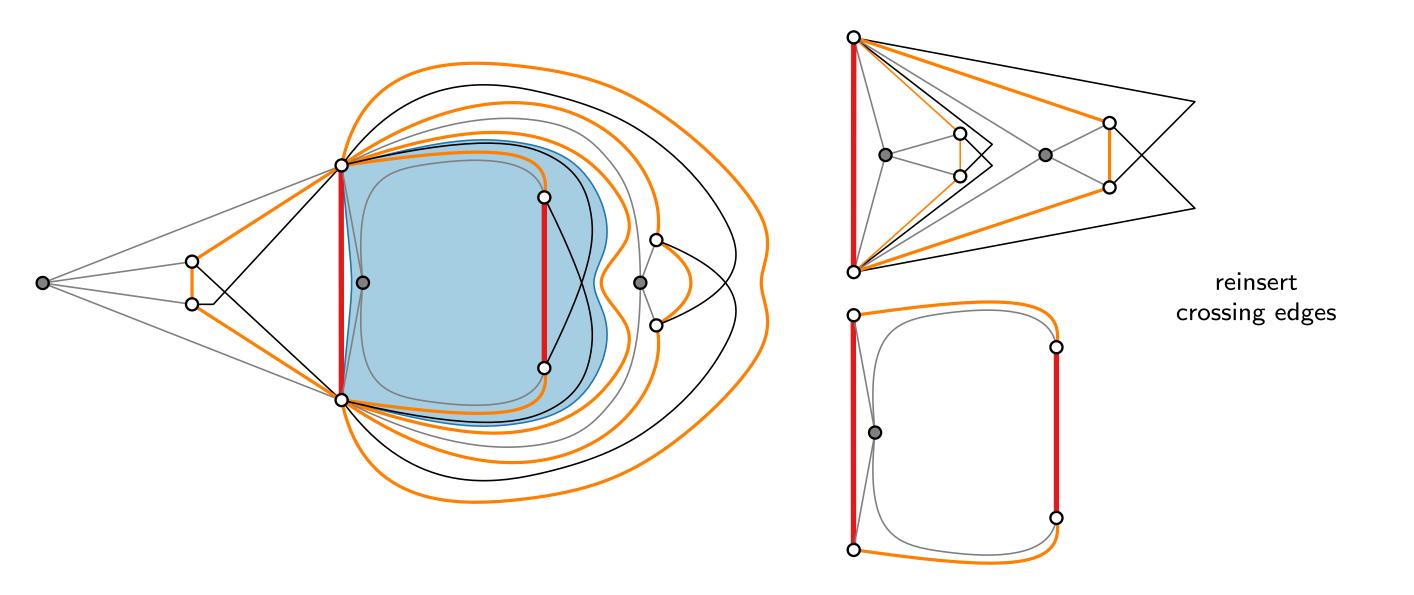


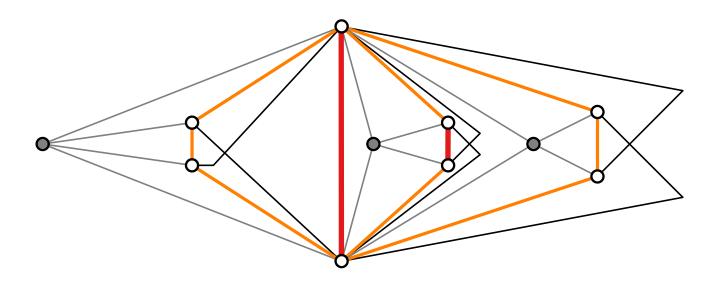


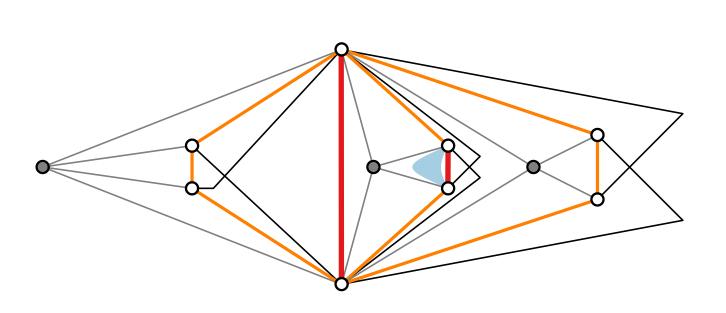


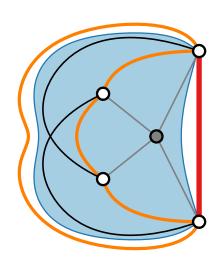


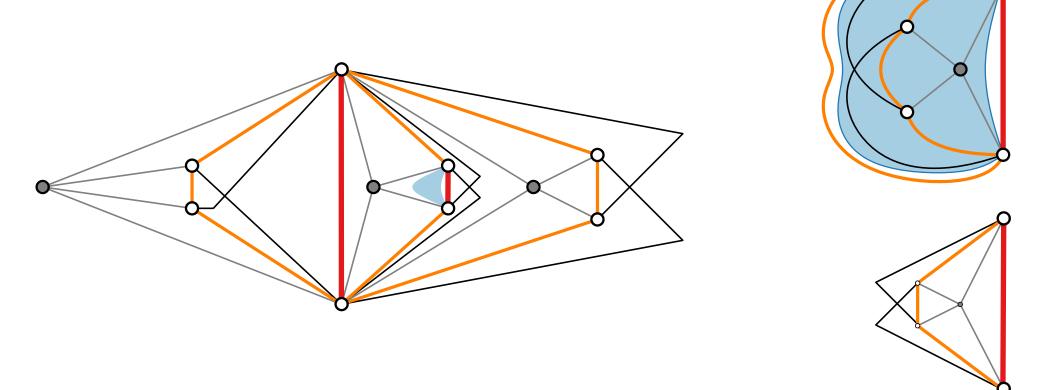


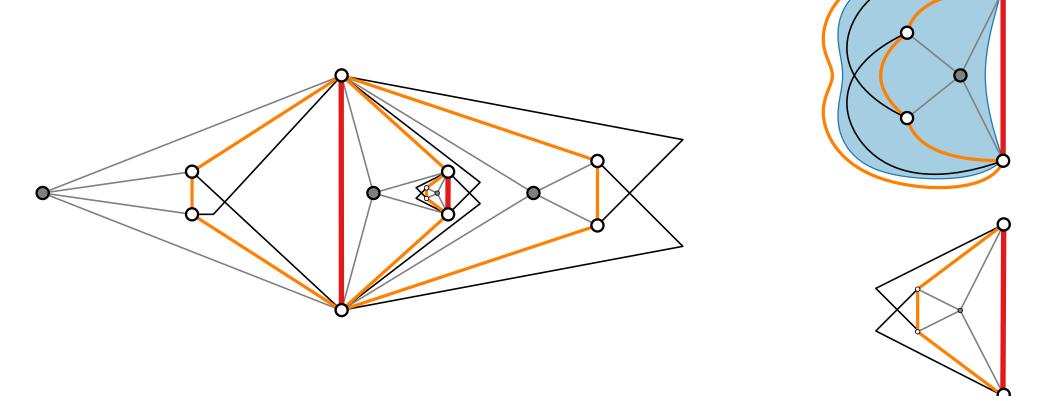




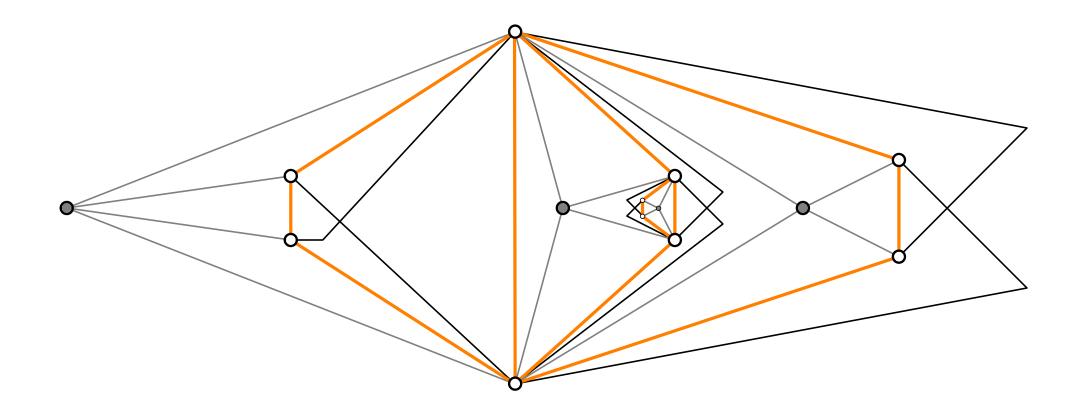




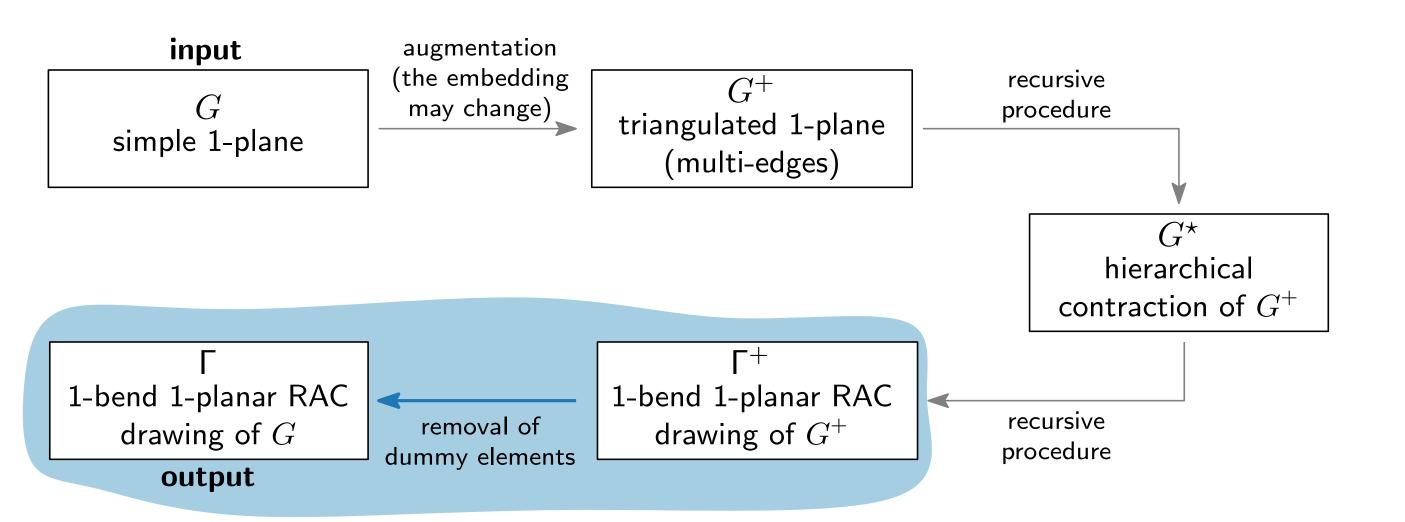




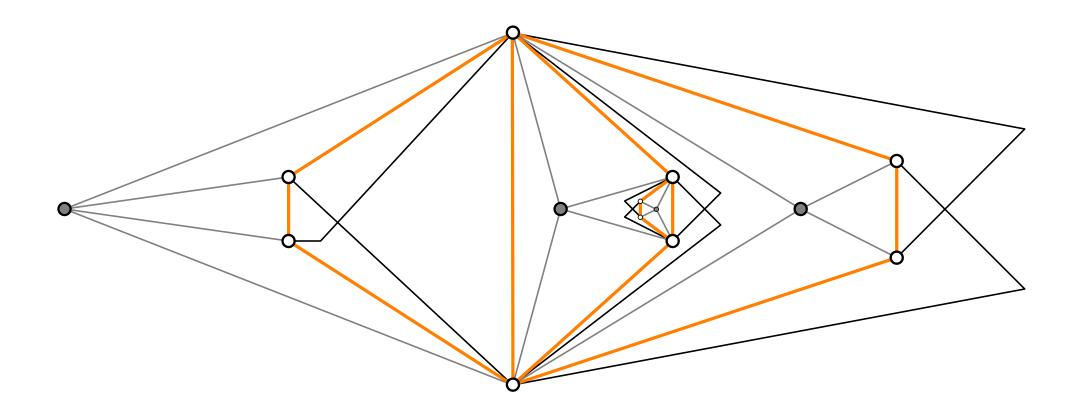
 Γ^+ : 1-bend 1-planar RAC drawing of G^+



Algorithm Outline

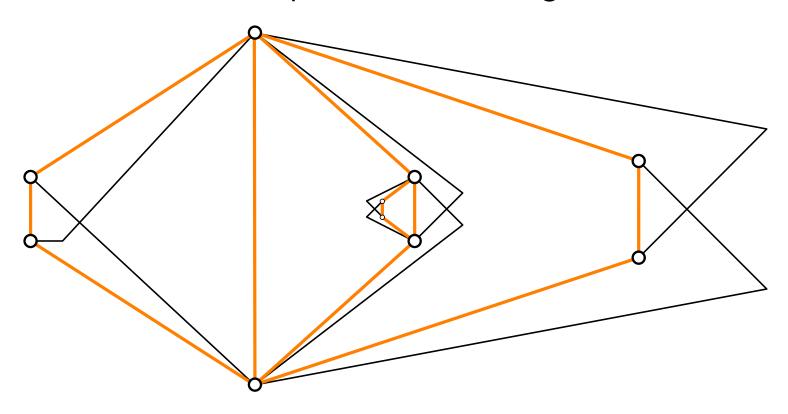


Algorithm Step 4: Removal of Dummy Vertices



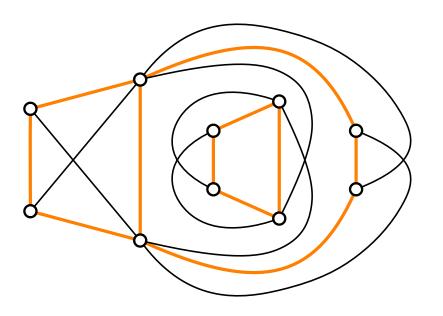
Algorithm Step 4: Removal of Dummy Vertices

 Γ : 1-bend 1-planar RAC drawing of G

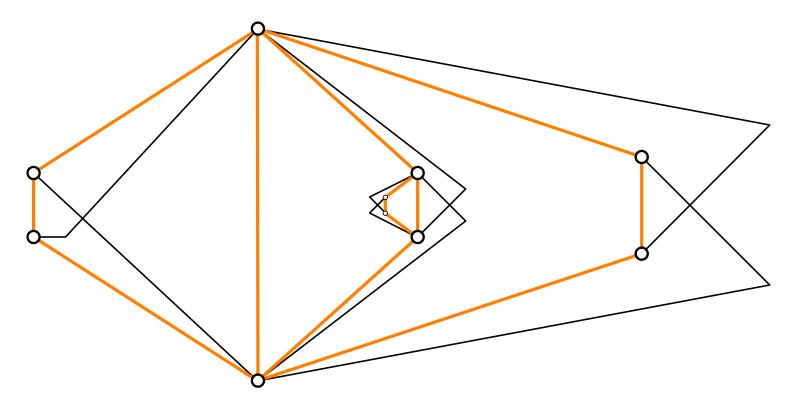


Algorithm Step 4: Removal of Dummy Vertices

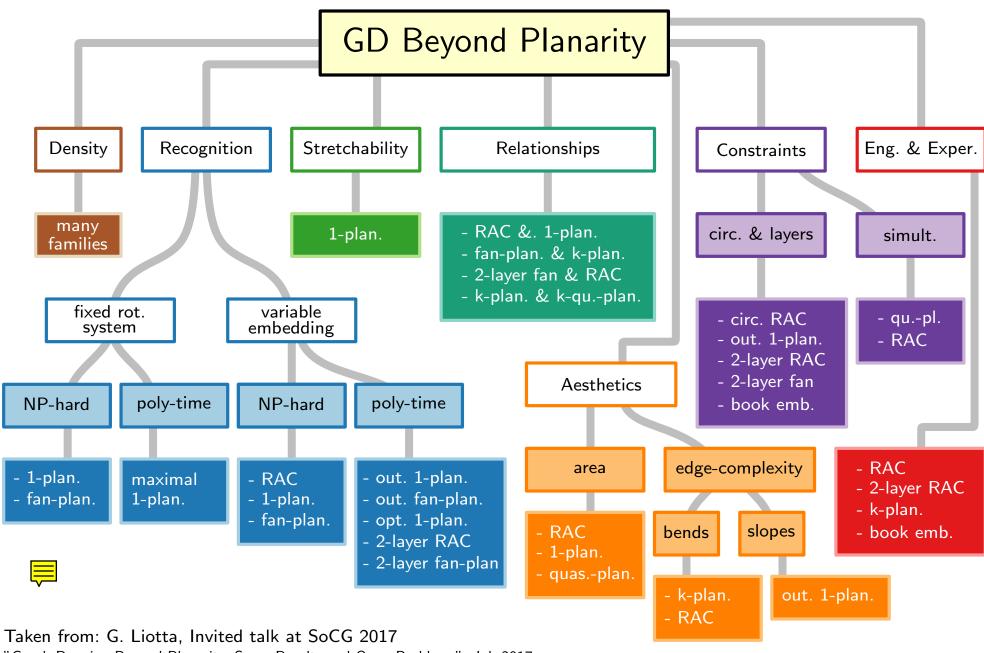
G: simple 1-plane graph



 Γ : 1-bend 1-planar RAC drawing of G

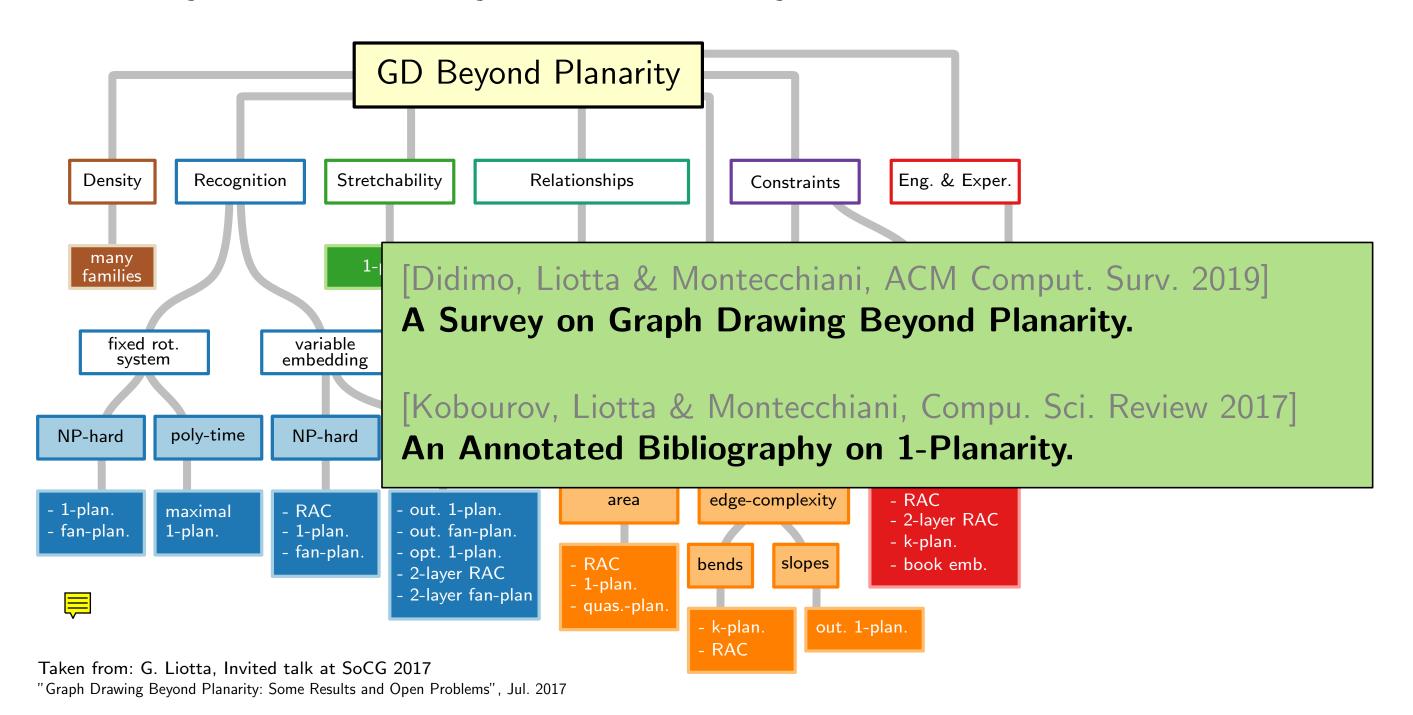


GD Beyond Planarity: a Taxonomy



[&]quot;Graph Drawing Beyond Planarity: Some Results and Open Problems", Jul. 2017

GD Beyond Planarity: a Taxonomy



Literature

Books and surveys:

- [Didimo, Liotta & Montecchiani 2019] A Survey on Graph Drawing Beyond Planarity
- [Kobourov, Liotta & Montecchiani '17] An Annotated Bibliography on 1-Planarity
- [Hong and Tokuyama, editors '20] Beyond Planar Graphs

Some references for proofs:

- [Eades, Huang, Hong '08] Effects of Crossing Angles
- [Brandenburg et al. '13] On the density of maximal 1-planar graphs
- [Chimani, Kindermann, Montecchani, Valtr '19] Crossing Numbers of Beyond-Planar Graphs
- [Grigoriev and Bodlaender '07] Algorithms for graphs embeddable with few crossings per edge
- [Angelini et al. '11] On the Perspectives Opened by Right Angle Crossing Drawings
- [Didimo, Eades, Liotta '17] Drawing graphs with right angle crossings
- [Bekos et al. '17] On RAC drawings of 1-planar graphs