

Approximation Algorithms

Lecture 8: Approximation Schemes and the KNAPSACK Problem

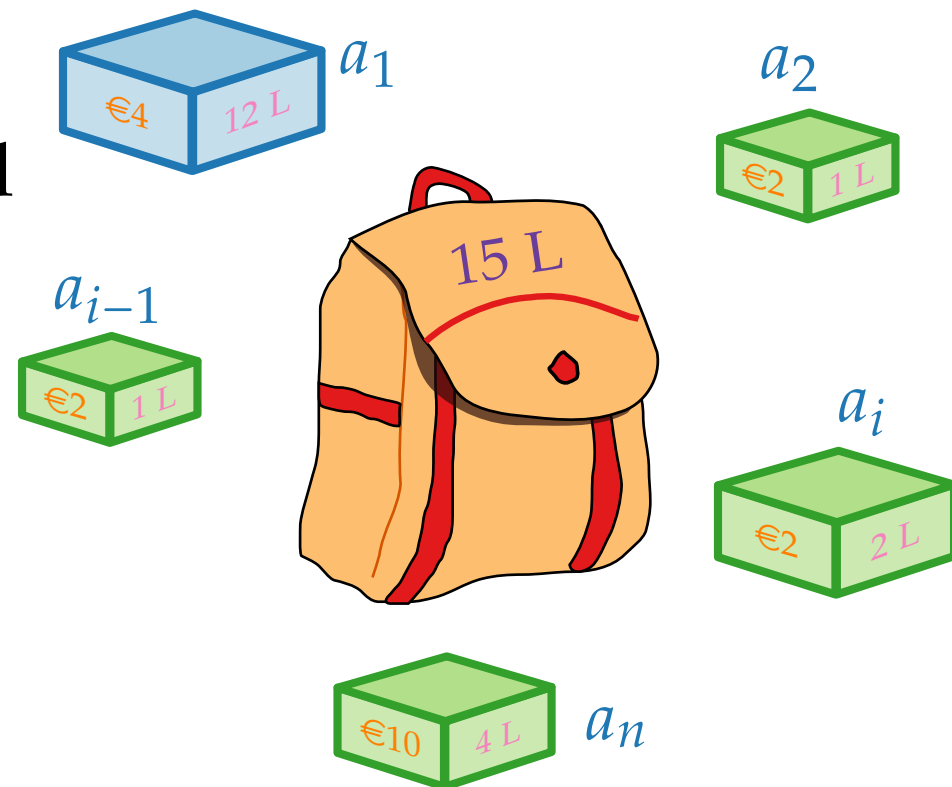
Part I: KNAPSACK

KNAPSACK

- Given:**
- A set $S = \{a_1, \dots, a_n\}$ of **objects**.
 - For every object a_i a **size** $\text{size}(a_i) \in \mathbb{N}^+$
 - For every object a_i a **Profit** $\text{profit}(a_i) \in \mathbb{N}^+$
 - A knapsack **capacity** $B \in \mathbb{N}^+$

Task: Find a subset of objects whose **total size** is at most B and whose **total profit** is maximum.

NP-hard



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Part II:

Pseudo-Polynomial Algorithms and
Strong NP-Hardness

Pseudo-Polynomial Algorithms

Let Π be an optimization problem whose instances can be represented by **objects** (such as sets, elements, edges, nodes) and **numbers** (such as costs, weights, profits).

$|I|$: The size of an instance $I \in D_{\Pi}$, where all numbers in I are encoded in **binary**. ($5 \hat{=} 101 \Rightarrow |I| = 3$)

$|I|_{\mathbf{u}}$: The size of an instance $I \in D_{\Pi}$, where all numbers in I are encoded in **unary**. ($5 \hat{=} 11111 \Rightarrow |I|_{\mathbf{u}} = 5$)

The running time of a polynomial algorithm for Π is polynomial in $|I|$.

The running time of a **pseudo-polynomial algorithm** is polynomial in $|I|_{\mathbf{u}}$.

The running time of a pseudo-polynomial algorithm may not be polynomial in $|I|$.

Strong NP-Hardness

An optimization problem is called **strongly NP-hard** if it remains NP-hard under unary encoding.

An optimization problem is called **weakly NP-hard** if it is NP-hard under binary encoding but has a pseudo-polynomial algorithm.

Theorem. A strongly NP-hard problem has no pseudo-polynomial algorithm unless $P = NP$.

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Part III: Pseudo-Polynomial Algorithm for KNAPSACK

Pseudo-Polynomial Alg. for KNAPSACK

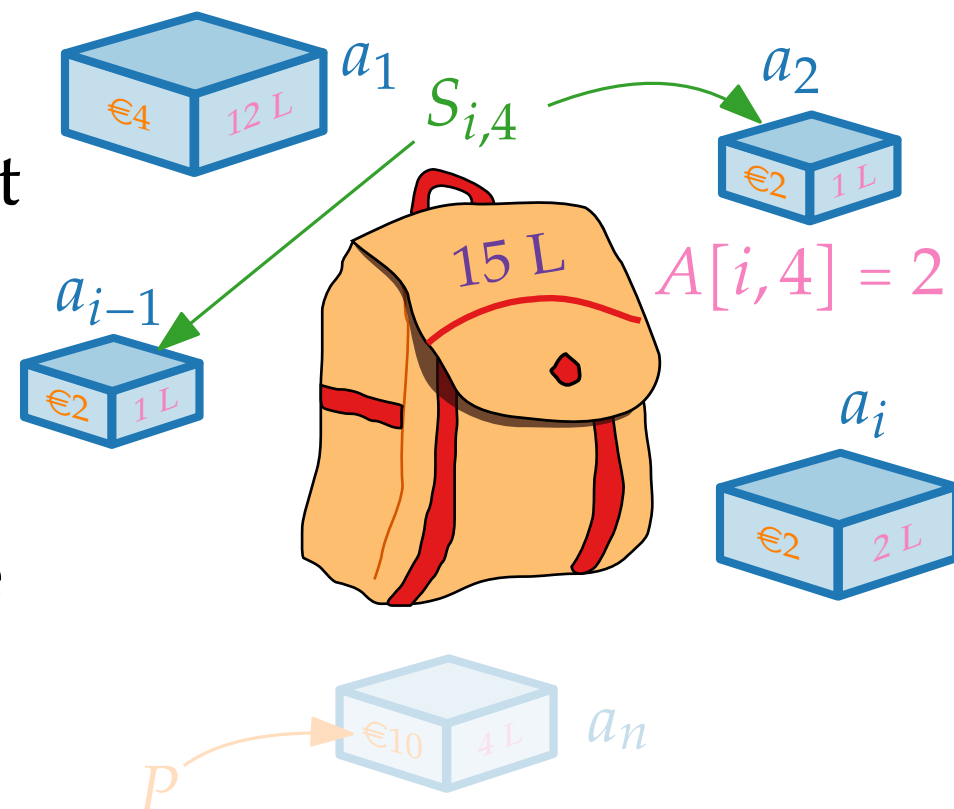
Let $P := \max_i \text{profit}(a_i) \Rightarrow P \leq \text{OPT} \leq nP$

For every $i = 1, \dots, n$ and every $p \in \{1, \dots, nP\}$, let $S_{i,p}$ be a subset of $\{a_1, \dots, a_i\}$ whose total profit is precisely p and whose total size is minimum among all subsets with these properties. Such a set may not exist.

Let $A[i, p]$ be the total size of set $S_{i,p}$ (set $A[i, p] = \infty$ if no such set exists).

If all $A[i, p]$ are known, then we can compute

$$\text{OPT} = \max\{p \mid A[n, p] \leq B\}.$$



Pseudo-Polynomial Alg. for KNAPSACK

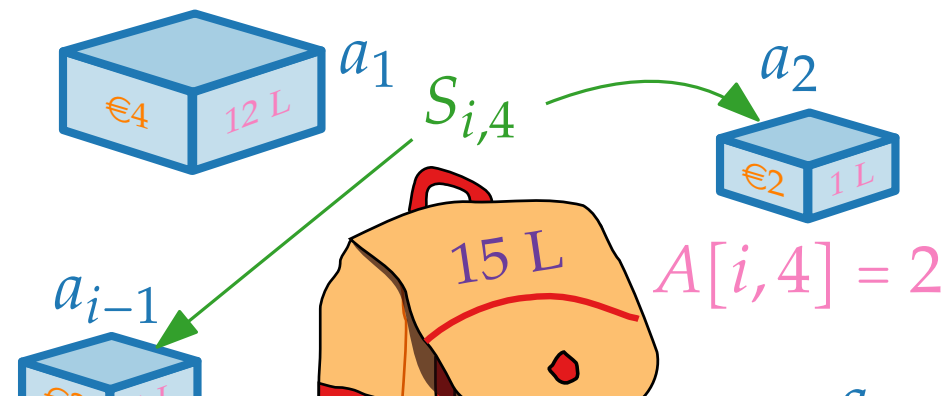
$A[1, p]$ can be computed for all $p \in \{0, \dots, nP\}$.

Set $A[i, p] := \infty$ for $p < 0$

$A[i+1, p] = \min\{A[i, p], \text{size}(a_{i+1}) + A[i, p - \text{profit}(a_{i+1})]\}$

\Rightarrow All values $A[i, p]$ can be computed in total time $O(n^2 P)$.

\Rightarrow **OPT** can be computed in $O(n^2 P)$ time.



Theorem. KNAPSACK can be solved optimally in pseudo-polynomial time $O(n^2 P)$.

Corollary. KNAPSACK is weakly NP-hard.

Pseudo-Polynomial Alg. for KNAPSACK

Theorem. KNAPSACK can be solved optimally in pseudo-polynomial time $O(n^2 P)$.

Examples.

$P = n^5$

- \Rightarrow running time $O(n^7)$
- (Bin.) instance size $|I| \geq n \log P = \Omega(n \log n)$
- $\Rightarrow n \in O(|I| / \log |I|)$
- \Rightarrow running time $O(|I|^7 / \log^7 |I|) = \text{poly}(|I|)$

$P = 2^n$

- \Rightarrow running time $O(n^2 2^n)$
- (Bin.) instance size $|I| \leq n \log P = O(n^2)$
- \Rightarrow running time $O(|I| 2^{\sqrt{|I|}}) \neq \text{poly}(|I|)$
- (Un.) instance size $|I|_{\mathbf{u}} \leq nP = O(n 2^n)$
- $\Rightarrow n \in O(\log |I|_{\mathbf{u}} - \log \log |I|_{\mathbf{u}})$
- \Rightarrow running time $O(|I|_{\mathbf{u}} \log |I|_{\mathbf{u}}) = \text{poly}(|I|_{\mathbf{u}})$

Observe. Running time $O(n^2 P)$ poly in n if P poly in n .

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Part IV: Approximation Schemes

Approximation Schemes

Let Π be an optimization problem. An algorithm \mathcal{A} is called a **polynomial-time approximation scheme (PTAS)**, if it outputs for every input (I, ε) with $I \in D_{\Pi}$ and $\varepsilon > 0$ a solution $s \in S_{\Pi}(I)$ such that the following holds:

- $\text{obj}_{\Pi}(I, s) \leq (1 + \varepsilon) \cdot \text{OPT}$, if Π min problem,
- $\text{obj}_{\Pi}(I, s) \geq (1 - \varepsilon) \cdot \text{OPT}$, if Π max problem.

The runtime of \mathcal{A} is polynomial in $|I|$ for **every fixed** $\varepsilon > 0$.

\mathcal{A} is called **fully polynomial-time approximation scheme (FPTAS)** if its running time is polynomial in $|I|$ and $1/\varepsilon$.

Example running times

- $O(n^{1/\varepsilon}) \rightsquigarrow$ PTAS
- $O(2^{1/\varepsilon} n^4) \rightsquigarrow$ PTAS
- $O(n^3/\varepsilon^2) \rightsquigarrow$ FPTAS

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Part V: FPTAS for KNAPSACK

FPTAS for KNAPSACK via Scaling

KnapsackScaling (I, ε)

$K \leftarrow \varepsilon P / n$ // scaling factor

$\text{profit}'(a_i) := \lfloor \text{profit}(a_i) / K \rfloor$

Compute optimal solution S' for I w.r.t. $\text{profit}'(\cdot)$

return S'

Lemma. $\text{profit}(S') \geq (1 - \varepsilon) \cdot \text{OPT}$.

Proof. Let $\text{OPT} = \{o_1, \dots, o_k\}$.

Obs. 1. For $i = 1, \dots, k$, $\text{profit}(o_i) - K \leq K \cdot \text{profit}'(o_i) \leq \text{profit}(o_i)$

$\Rightarrow K \cdot \sum_i \text{profit}'(o_i) \geq \text{OPT} - kK \geq \text{OPT} - nK = \text{OPT} - \varepsilon P$

Obs. 2. $\text{profit}(S') \geq K \cdot \text{profit}'(S') \geq K \cdot \sum_i \text{profit}'(o_i)$

$\Rightarrow \text{profit}(S') \geq \text{OPT} - \varepsilon P \geq \text{OPT} - \varepsilon \text{OPT} = (1 - \varepsilon) \cdot \text{OPT} \quad \square$

Theorem. KnapsackScaling is an FPTAS for KNAPSACK with running time $O(n^3 / \varepsilon) = O\left(n^2 \cdot \frac{P}{\varepsilon P / n}\right)$.

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Part VI: Connections

FPTAS and Pseudo-Poly. Algorithms

Theorem. Let p be a polynomial and let Π be an NP-hard minimization problem with integral objective function and $\text{OPT}(I) < p(|I|_{\mathbf{u}})$ for all instances I of Π . If Π has an FPTAS, then there is a pseudo-polynomial algorithm for Π .

Proof.

Assuming there is an FPTAS for Π (in $q(|I|, 1/\varepsilon)$ time).

Set $\varepsilon = 1/p(|I|_{\mathbf{u}})$.

$\Rightarrow \text{ALG} \leq (1 + \varepsilon)\text{OPT} < \text{OPT} + \varepsilon p(|I|_{\mathbf{u}}) = \text{OPT} + 1.$

$\Rightarrow \text{ALG} = \text{OPT}.$

Running time: $q(|I|, p(|I|_{\mathbf{u}}))$, so $\text{poly}(|I|_{\mathbf{u}})$.

FPTAS and Strong NP-Hardness

Theorem. A strongly NP-hard problem has no pseudo-polynomial algorithm unless $P = NP$.

Theorem. Let p be a polynomial and let Π be an NP-hard minimization problem with integral objective function and $\text{OPT}(I) < p(|I|_u)$ for all instances I of Π . If Π has an FPTAS, then there is a pseudo-polynomial algorithm for Π .

Corollary. Let Π be an NP-hard optimization problem that fulfils the restrictions above. If Π is strongly NP-hard, then there is no FPTAS for Π (unless $P = NP$).