## Lecture 1: Introduction and Vertex Cover

## Part I: Organizational

Joachim Spoerhase

## Organizational

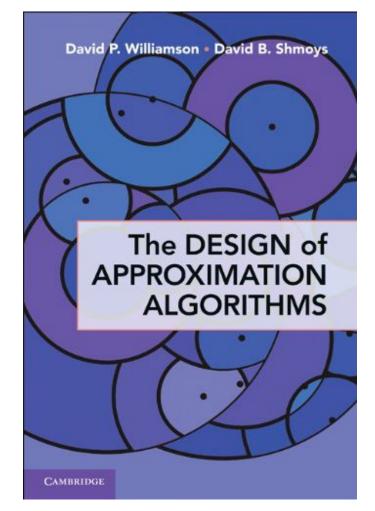
Lectures: Zoom (in German or English) Synchronous (key material) More technical lectures via inverted classroom Tutorials: One exercise sheet per lecture Solving assignments and presenting solutions Tuesdays 10:15 - 11:45 (SE I) Bonus (+0.3 on final grade) for  $\geq$  50% points

Questions/Tasks during the lecture

## Textbooks

VIJAY V. VAZIRAN Approximation Algorithms Springer

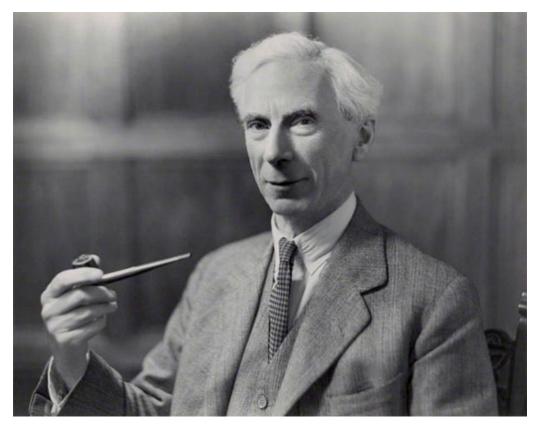
Vijay V. Vazirani: Approximation Algorithms Springer-Verlag, 2003.



D. P. Williamson & D. B. Shmoys: The Design of Approximation Algorithms Cambridge-Verlag, 2011. http://www.designofapproxalgs.com/

"All exact science is dominated by the idea of approximation." – Bertrand Russell

(1872 - 1970)



- Many optimization problems are NP-hard (e.g. the traveling salesperson problem)
- $\rightarrow$  an optimal solution cannot be efficiently computed unless P=NP.
- However, good approximate solutions can often be found efficiently!
- Techniques for the design and analysis of approximation algorithms arise from studying specific optimization problems.

## Overview

### **Combinatorial Algorithms**

- Introduction (Vertex Cover)
- Set Cover via Greedy
- Shortest Superstring via reduction to SC
- Steiner Tree via MST
- Multiway Cut via Greedy
- *k*-Center via param. Pruning
- Min-Deg-Spanning-Tree & local search
- Knapsack via DP & Scaling
- Euclidean TSP via Quadtrees

### LP-based Algorithms

- introduction to LP-Duality
- Set Cover via LP Rounding
- Set Cover via Primal-Dual Schema
- Maximum Satisfiability
- Scheduling und Extreme Point Solutions
- Steiner Forest via Primal-Dual

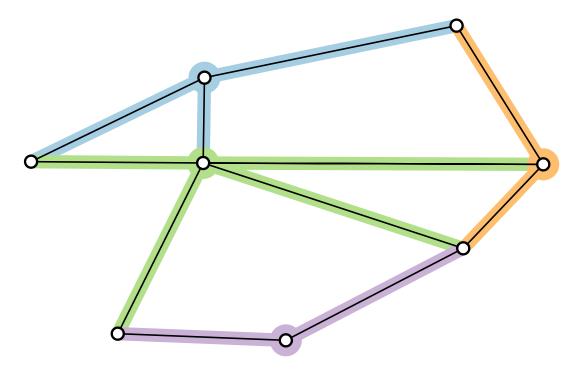
## Lecture 1: Introduction and Vertex Cover

### Part II: Vertex Cover (card.)

Joachim Spoerhase

VERTEXCOVER (card.)

- In: Graph G = (V, E)
- **Out:** a minimum **vertex cover**: a minimum vertex set  $V' \subseteq V$  such that every edge is **covered** (i.e., for every  $uv \in E$ , either  $u \in V'$  or  $v \in V'$ ).



**Optimum** (OPT = 4) – but in general NP-hard to find :-(

## Lecture 1: Introduction and Vertex Cover

## Part III: NP-Optimization Problem

Joachim Spoerhase

## NP-Optimization Problem

### An **NP-optimization problem** $\Pi$ is given by:

#### A set $D_{\Pi}$ of **instances**. We denote the size of an instance $I \in D_{\Pi}$ by |I|.

- For each instance  $I \in D_{\Pi}$  a set  $S_{\Pi}(I) \neq \emptyset$  of **feasible solutions** for *I* such that:
  - for each solution  $s \in S_{\Pi}(I)$ , its size |s| is polynomially bounded in |I|, and
  - for each pair (*s*, *I*), there is a polynomial time algorithm to decide whether  $s \in S_{\Pi}(I)$ .
- A polynomial time computable objective function  $obj_{\Pi}$ which assigns a positive objective value  $obj_{\Pi}(I,s) \ge 0$ to any given pair (s, I) with  $s \in S_{\Pi}(I)$ .
- $\blacksquare$   $\Pi$  is either a minimization or maximization problem.

## **VERTEXCOVER:** NP-Optimization Problem

- Task: Fill in the gaps for  $\Pi = \text{Vertex Cover}$ .
- $D_{\Pi}$  = Set of all graphs

For  $I \in D_{\Pi}$ : |I| = Number of vertices |V|G = (V, E)  $S_{\Pi}(I) =$  Set of all vertex covers of G

- Why is  $|s| \in \text{poly}(|I|)$  for every  $s \in S_{\Pi}(I)$ ?  $s \subseteq V \Rightarrow |s| \leq |V| = |I|$
- For a given pair (s, I), how can we efficiently decide whether  $s \in S_{\Pi}(I)$ ? Test whether all edges are covered.

 $\operatorname{obj}_{\Pi}(I,s) = |s|$ 

 $\Pi$  is M in imization problem.

## Optimum and optimal objective value

maximization problem Let  $\Pi$  be a minimization problem and  $I \in D_{\Pi}$  be an instance of  $\Pi$ . A feasible solution  $s^* \in S_{\Pi}(I)$  is **optimal** if  $obj_{\Pi}(I, s^*)$  is minimal among objective values attained by the feasible solutions of I.

The optimal value  $obj_{\Pi}(I, s^*)$  of the objective function is also denoted by  $OPT_{\Pi}(I)$  or simply OPT in context.

maximization problem  $\alpha : \mathbb{N} \to \mathbb{Q}$ Let  $\Pi$  be a minimization problem and  $\alpha \in \mathbb{Q}^+$ . A factor- $\alpha$ -approximation algorithm for  $\Pi$  is an efficient algorithm which provides for **any** instance  $I \in D_{\Pi}$  a feasible solution  $s \in S_{\Pi}(I)$  such that

 $\frac{\operatorname{obj}_{\Pi}(I,s)}{\operatorname{OPT}_{\Pi}(I)} \stackrel{\geq}{\leq} \mathscr{P} \ \alpha(|I|)$ 

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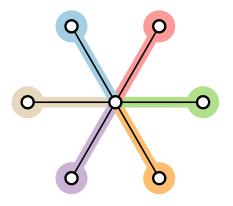
Part IV: Approximation Algorithm for VERTEXCOVER

Joachim Spoerhase

## Approximation Alg. for VERTEXCOVER

Ideas?

- Edge-Greedy
- Vertex-Greedy



### Quality?

**Problem:** How can we estimate  $obj_{\Pi}(I,s)/OPT$ , when it is hard to calculate OPT?

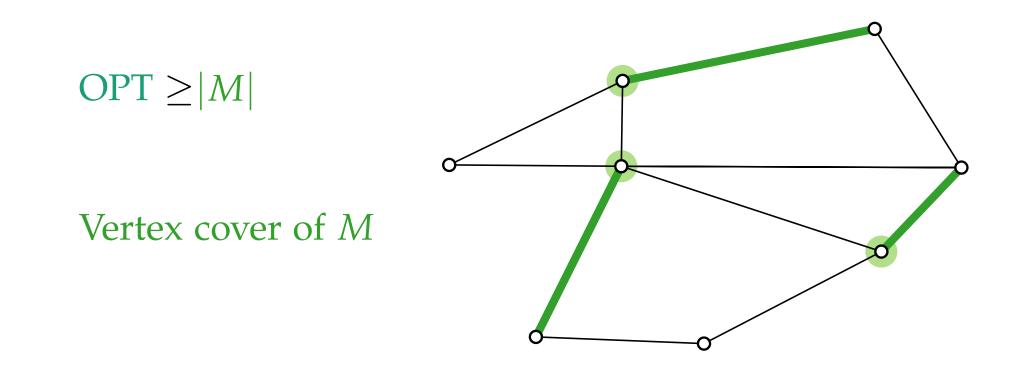
Idea:Find a "good" lower bound  $L \leq OPT$  for OPTand compare it to our approximate solution.

$$\frac{\operatorname{obj}_{\Pi}(I,s)}{\operatorname{OPT}} \le \frac{\operatorname{obj}_{\Pi}(I,s)}{L}$$

## Lower Bound by Matchings

An edge set  $M \subseteq E$  of a graph G = (V, E) is a **matching** if no two edges of M are adjacent (i.e., share an end vertex).

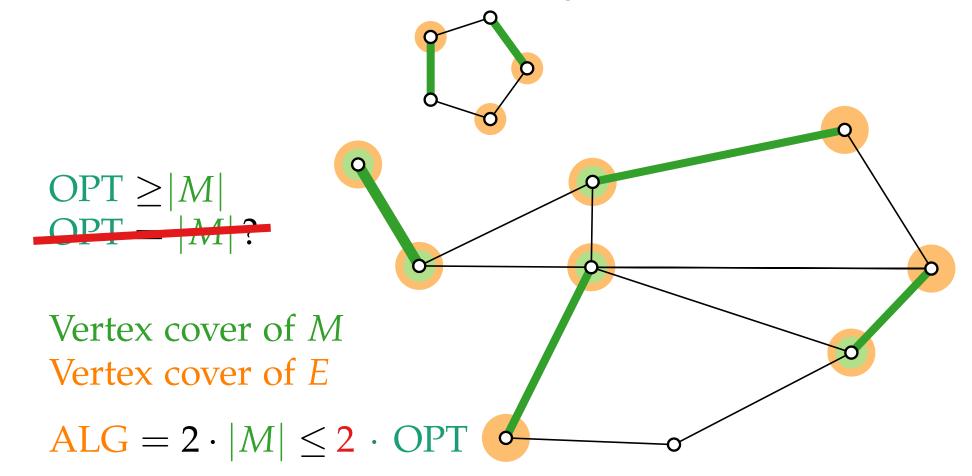
*M* is **maximal** if there is no matching *M*' with  $M' \supseteq M$ .



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Approximation Alg. for VERTEXCOVER

Algorithm VertexCover(*G*)

 $M \leftarrow \emptyset$ 

foreach  $e \in E(G)$  do

if *e* not adjacent to edge in *M* then

 $\ \ \, M \leftarrow M \cup \{e\}$ 

return  $\{ u, v \mid uv \in M \}$ 

**Theorem.** The above algorithm is a factor-2-approximation algorithm for VERTEXCOVER.

The best-known approximation factor for  $V_{1}$ 

VERTEXCOVER is  $2 - \Theta(1/\sqrt{\log n})$ 

VERTEXCOVER cannot be approximated within factor 1.3606 (unless P=NP)

VERTEXCOVER cannot be approximated within factor  $2 - \Theta(1)$ , if "Unique Games Conjecture" holds.