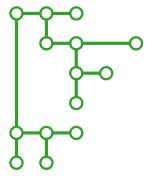


# Visualization of Graphs

Lecture 1b:

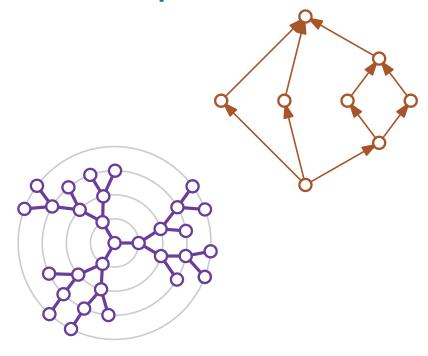
Drawing Trees and Series-Parallel Graphs

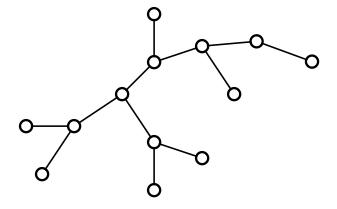


Part I: Layered Drawings

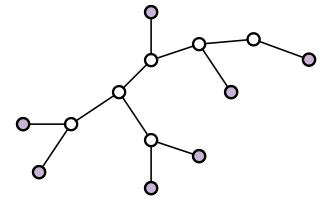


Jonathan Klawitter



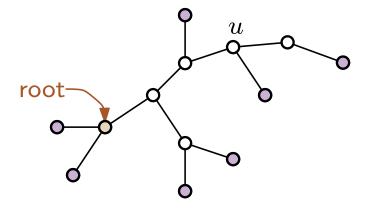


**Leaf:** Vertex of degree 1



**Leaf:** Vertex of degree 1

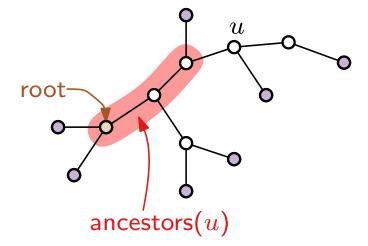
Rooted tree: tree with designated root



**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

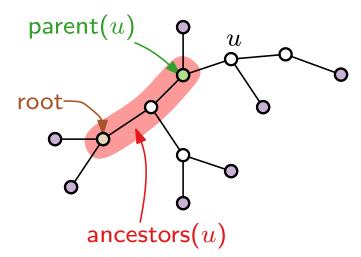


**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root



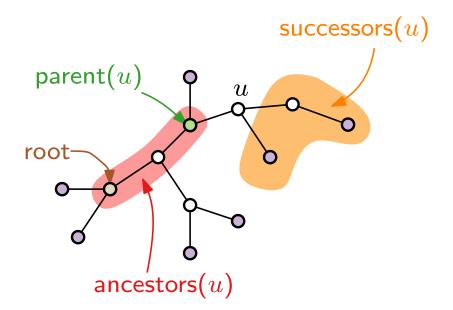
**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root

Successor: Vertex on path away from root



**Leaf:** Vertex of degree 1

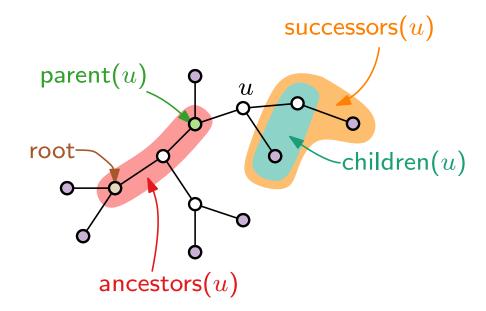
Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root

Successor: Vertex on path away from root

Child: Neighbor not on path to root



**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

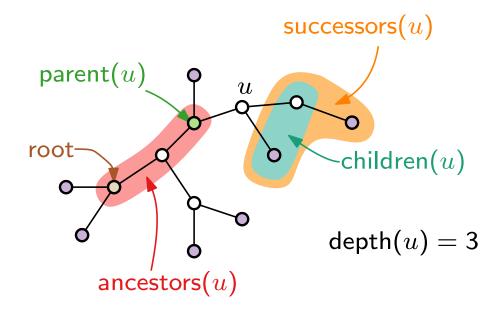
**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root

Successor: Vertex on path away from root

Child: Neighbor not on path to root

**Depth**: Length of path to root



**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

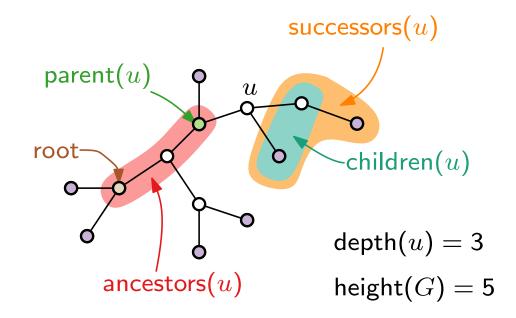
Parent: Neighbor on path to root

Successor: Vertex on path away from root

Child: Neighbor not on path to root

**Depth**: Length of path to root

**Height**: Maximum depth of a leaf



**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root

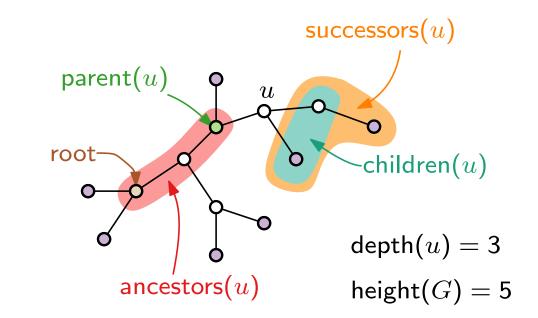
Successor: Vertex on path away from root

Child: Neighbor not on path to root

**Depth**: Length of path to root

Height: Maximum depth of a leaf

**Binary Tree**: At most two children per vertex (left / right child)



**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root

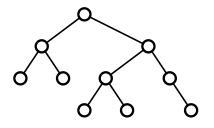
Successor: Vertex on path away from root

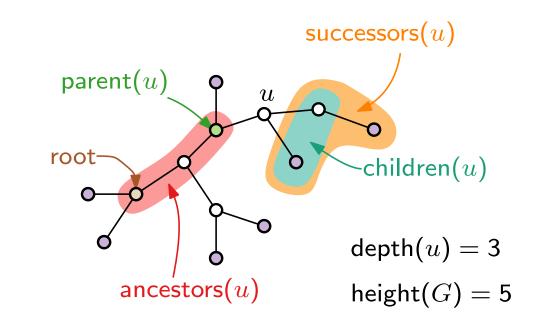
Child: Neighbor not on path to root

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Parent: Neighbor on path to root

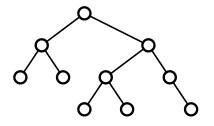
Successor: Vertex on path away from root

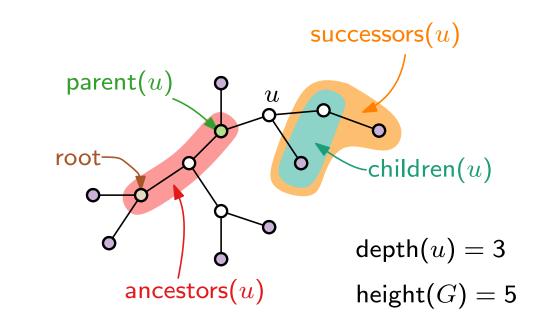
Child: Neighbor not on path to root

**Depth**: Length of path to root

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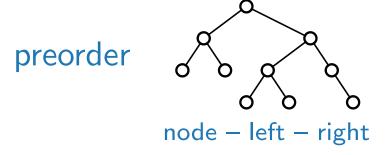
Successor: Vertex on path away from root

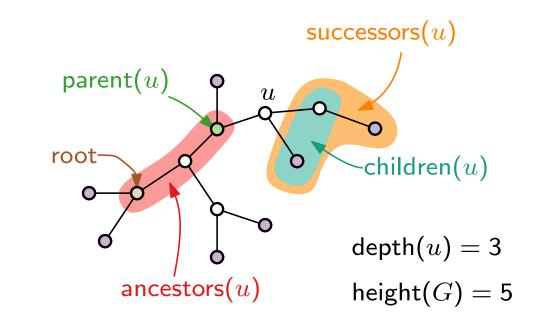
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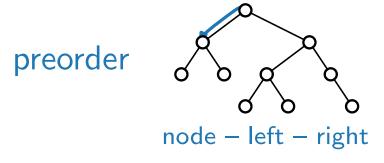
Successor: Vertex on path away from root

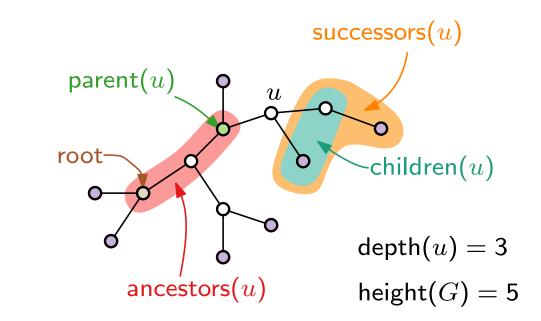
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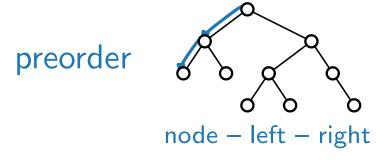
Successor: Vertex on path away from root

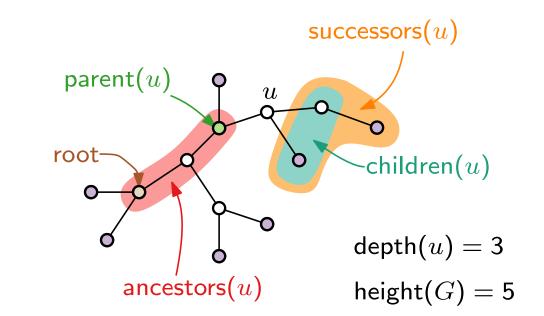
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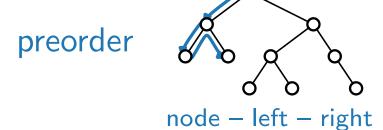
Successor: Vertex on path away from root

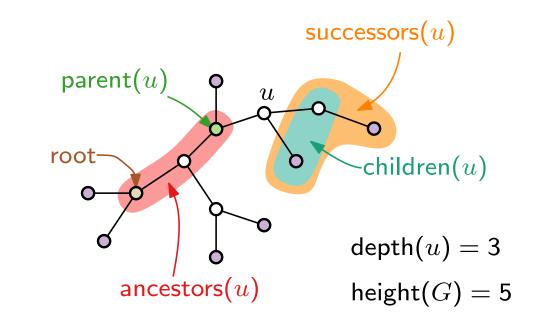
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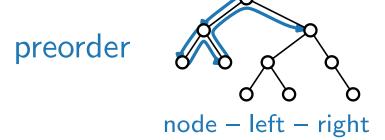
Successor: Vertex on path away from root

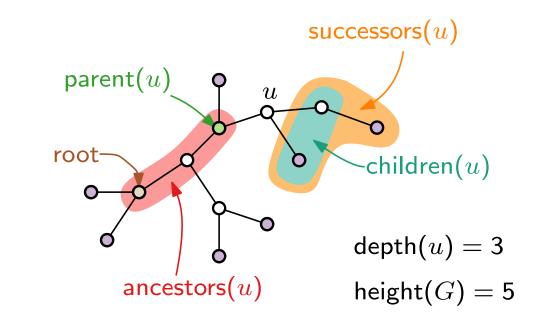
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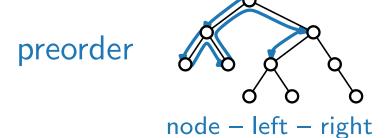
Successor: Vertex on path away from root

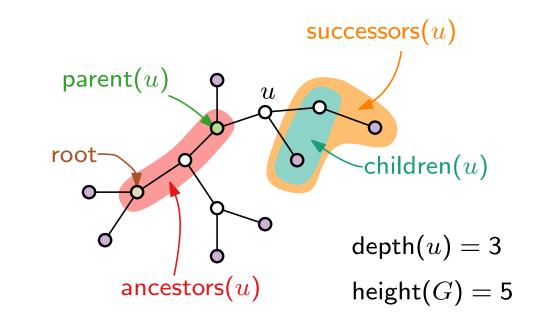
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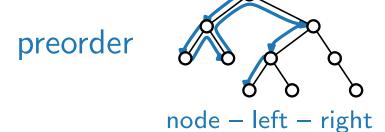
Successor: Vertex on path away from root

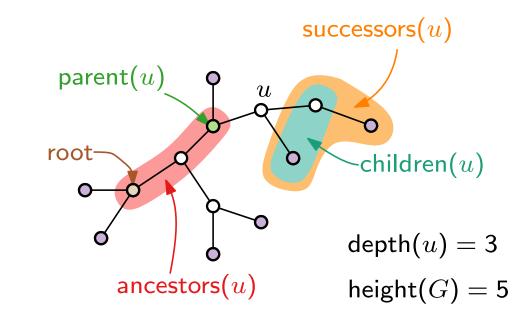
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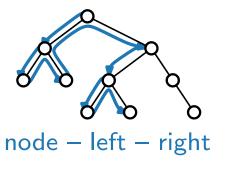
Child: Neighbor not on path to root

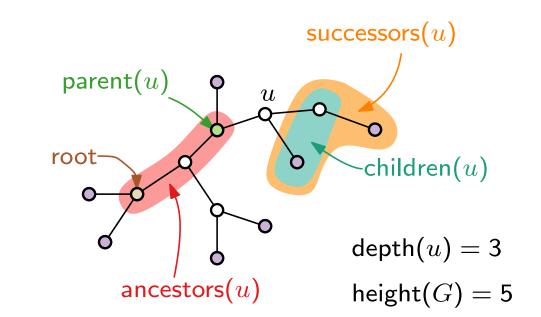
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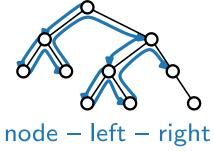
Child: Neighbor not on path to root

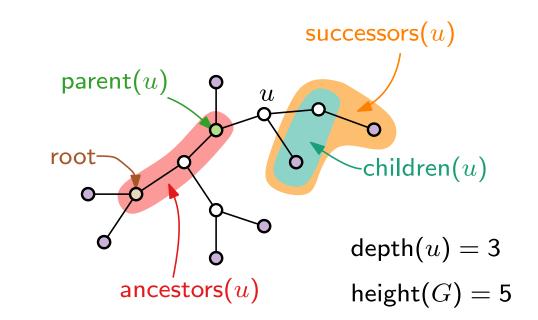
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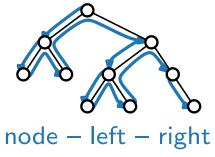
Child: Neighbor not on path to root

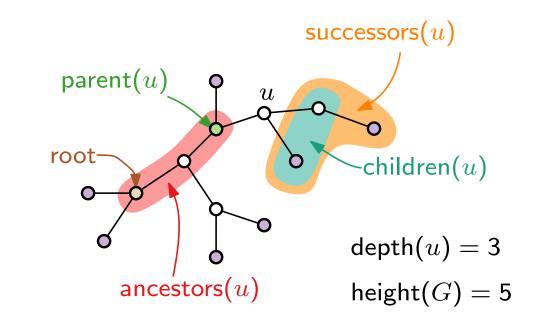
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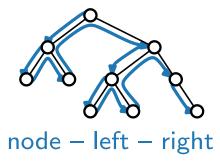
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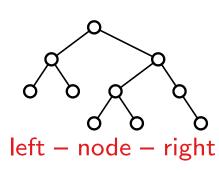
**Height**: Maximum depth of a leaf

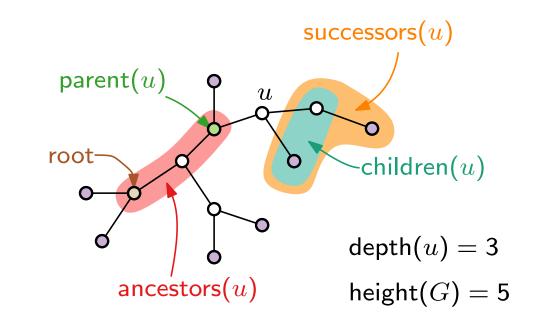
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

preorder







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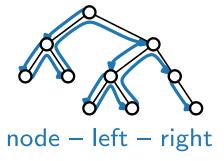
**Depth**: Length of path to root

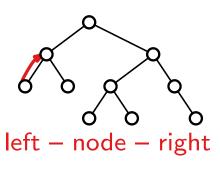
**Height**: Maximum depth of a leaf

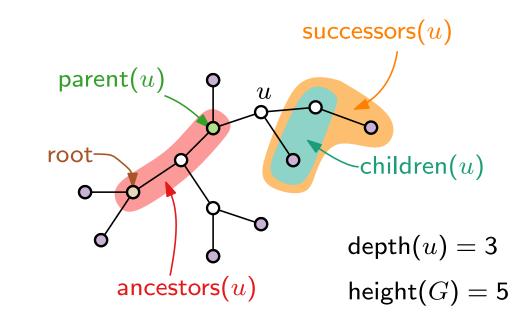
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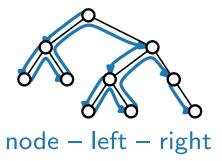
**Depth**: Length of path to root

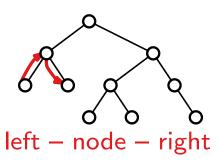
**Height**: Maximum depth of a leaf

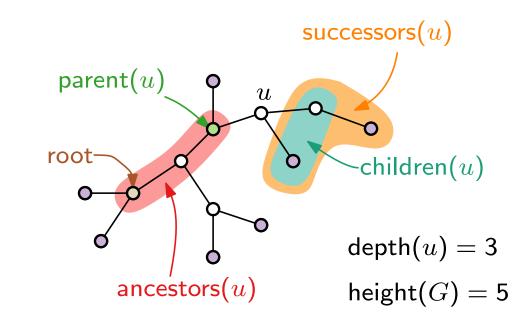
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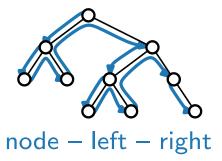
**Depth**: Length of path to root

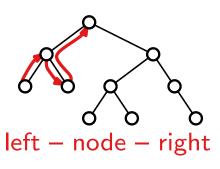
**Height**: Maximum depth of a leaf

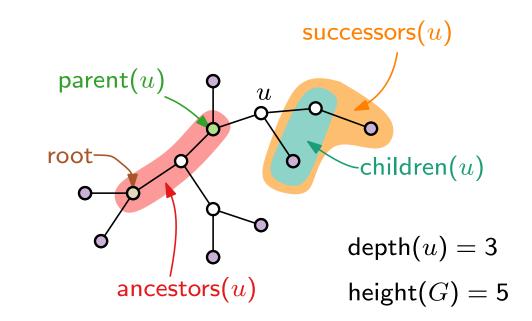
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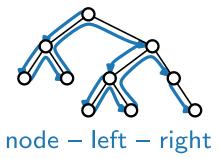
**Depth**: Length of path to root

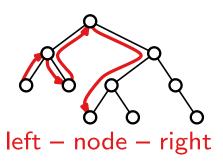
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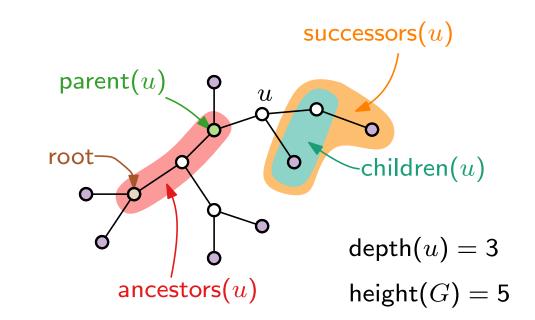
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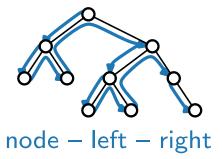
**Depth**: Length of path to root

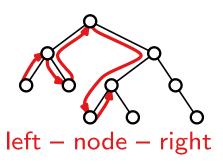
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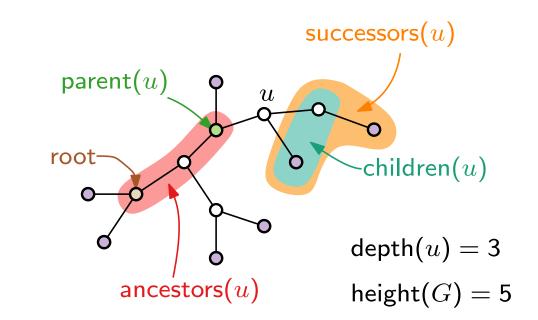
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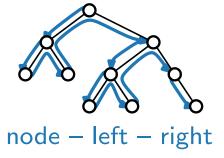
**Depth**: Length of path to root

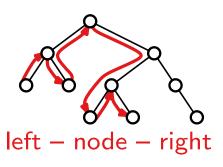
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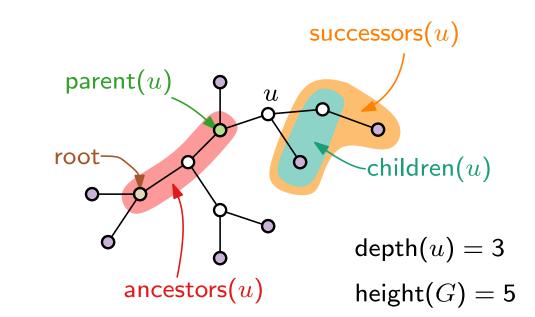
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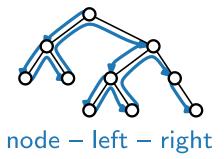
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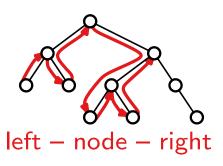
**Height**: Maximum depth of a leaf

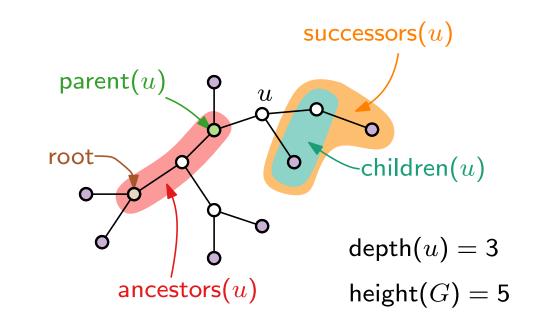
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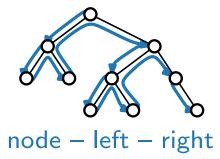
**Depth**: Length of path to root

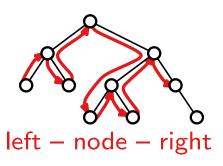
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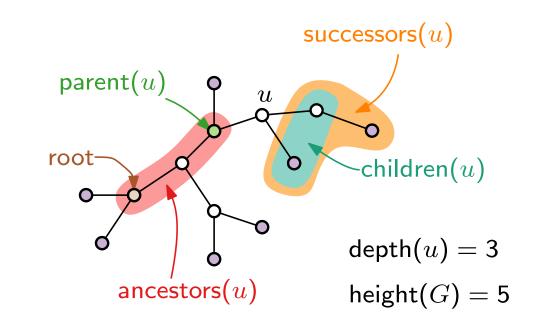
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Successor: Vertex on path away from root

Child: Neighbor not on path to root

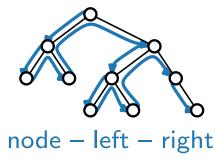
**Depth**: Length of path to root

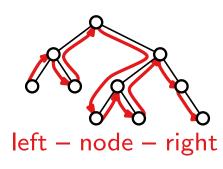
**Height**: Maximum depth of a leaf

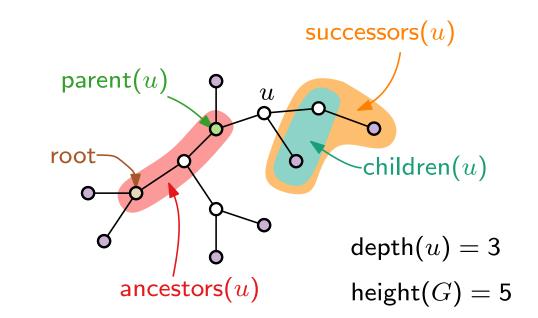
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

preorder







**Leaf:** Vertex of degree 1

**Rooted tree:** tree with designated **root** 

**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root

Successor: Vertex on path away from root

Child: Neighbor not on path to root

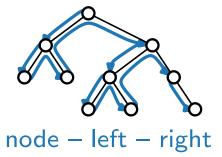
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

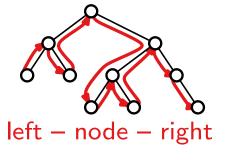
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

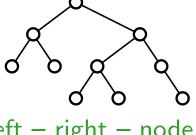
preorder



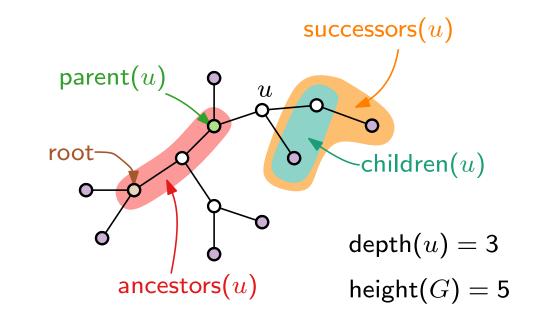
inorder



postorder



left – right – node



**Leaf:** Vertex of degree 1

**Rooted tree:** tree with designated **root** 

**Ancestor:** Vertex on path to root

Parent: Neighbor on path to root

Successor: Vertex on path away from root

Child: Neighbor not on path to root

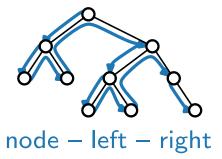
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

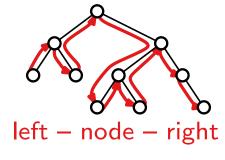
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

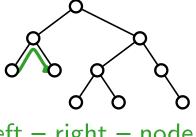
preorder



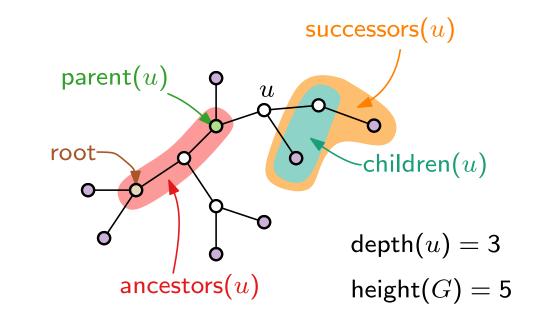
inorder



postorder



left – right – node



**Leaf:** Vertex of degree 1

Rooted tree: tree with designated root

**Ancestor:** Vertex on path to root

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Successor: Vertex on path away from root

Child: Neighbor not on path to root

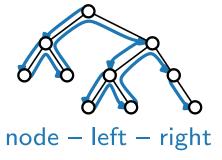
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

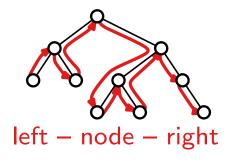
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

preorder



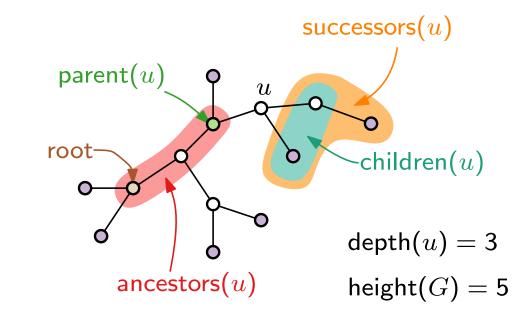
inorder



postorder



left – right – node



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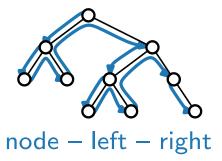
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

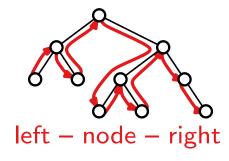
**Binary Tree**: At most two children per vertex (left / right child)

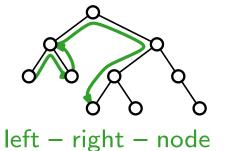
3 traversals:

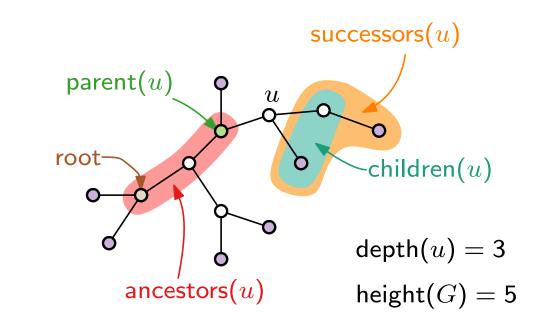
preorder



inorder







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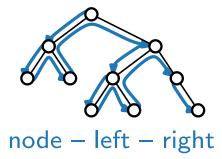
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

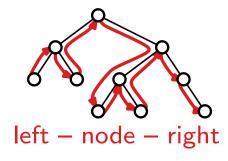
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

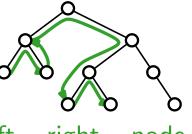
preorder

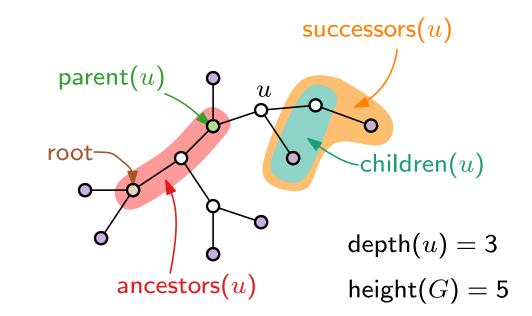


inorder



postorder





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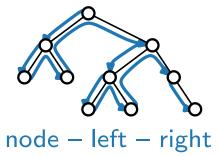
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

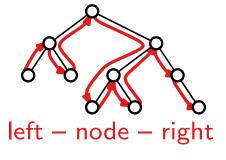
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

preorder

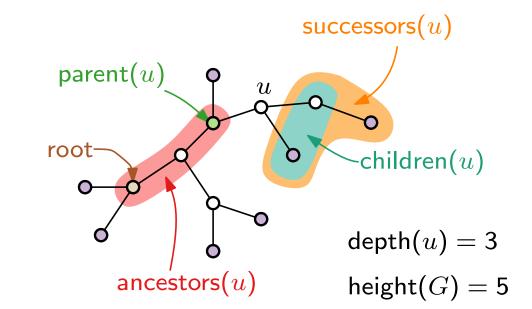


inorder



postorder





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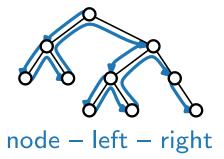
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**Height**: Maximum depth of a leaf

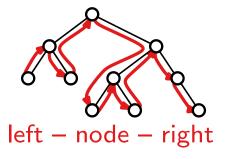
**Binary Tree**: At most two children per vertex (left / right child)

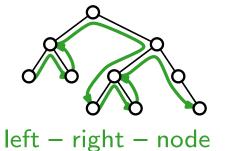
3 traversals:

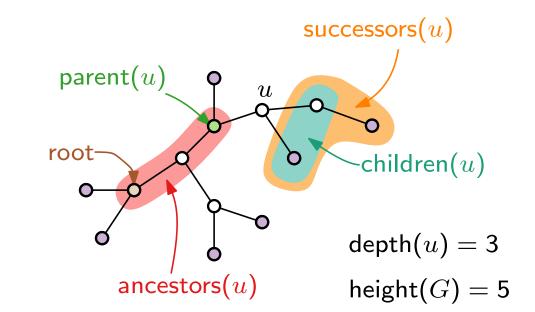
preorder



inorder







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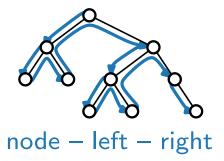
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

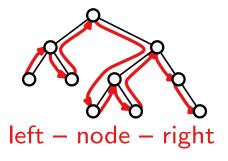
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preorder

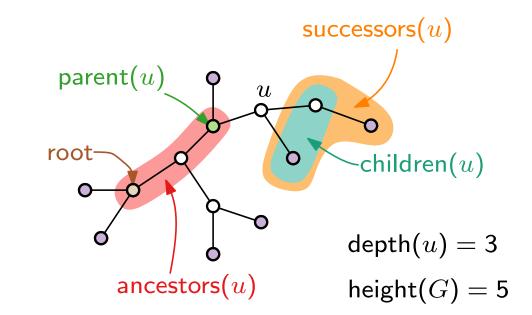


inorder



postorder





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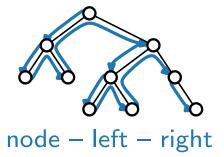
**Depth**: Length of path to root

Height: Maximum depth of a leaf

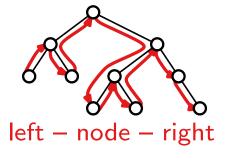
**Binary Tree**: At most two children per vertex (left / right child)

3 traversals:

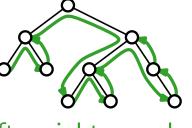
preorder

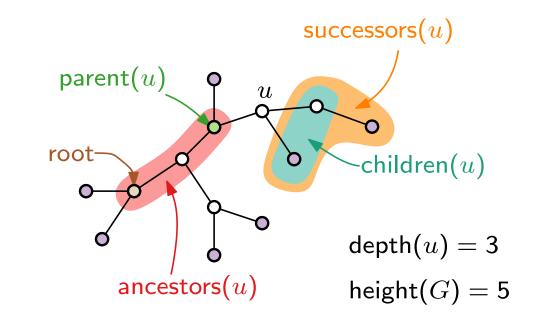


inorder



postorder





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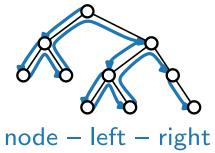
**Depth**: Length of path to root

**Height**: Maximum depth of a leaf

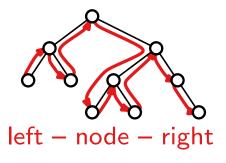
**Binary Tree**: At most two children per vertex (left / right child)

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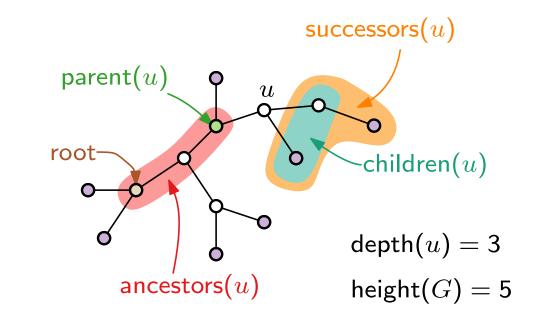


inorder



postorder

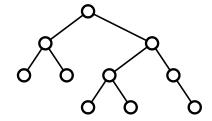




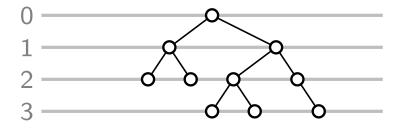
1. Choose *y*-coordinates:

1. Choose y-coordinates: y(u) = depth(u)

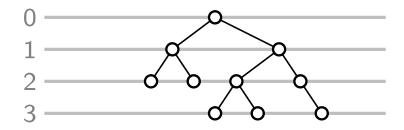
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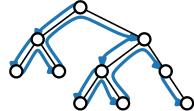


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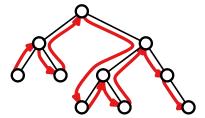


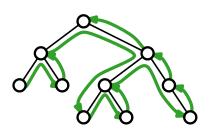
2. Choose *x*-coordinates:



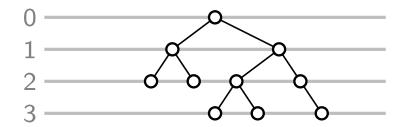


inorder

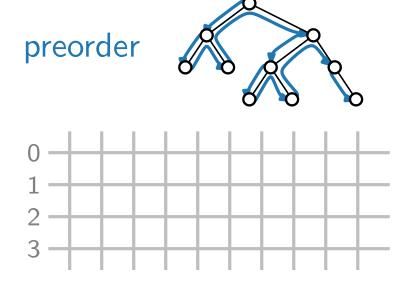




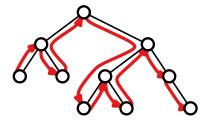
1. Choose y-coordinates: y(u) = depth(u)

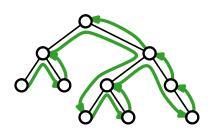


2. Choose *x*-coordinates:

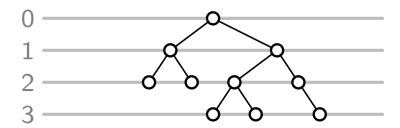


inorder

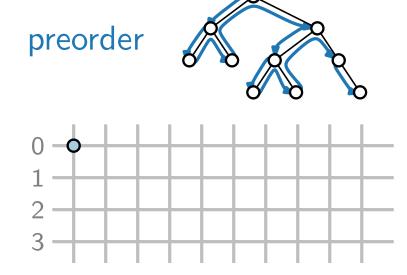




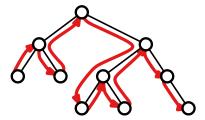
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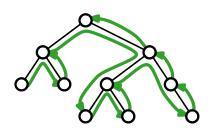


2. Choose *x*-coordinates:

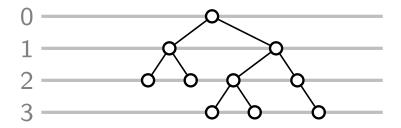


inorder

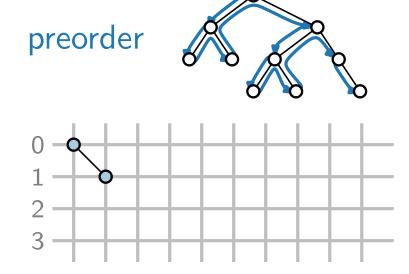




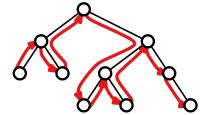
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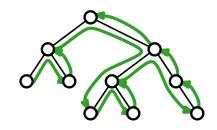


2. Choose *x*-coordinates:

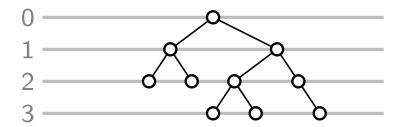


inorder

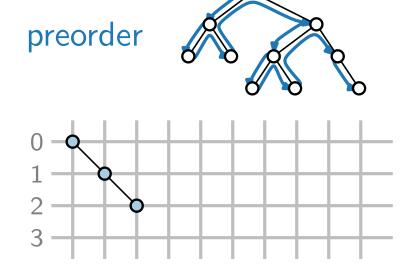




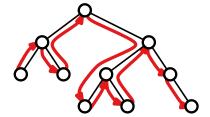
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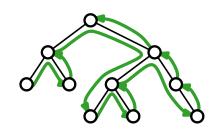


2. Choose *x*-coordinates:

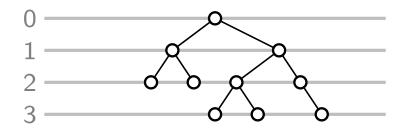


inorder

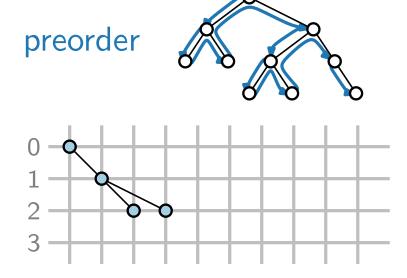




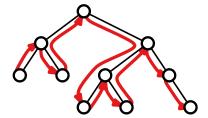
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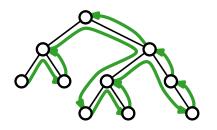


2. Choose *x*-coordinates:

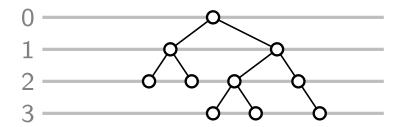


inorder

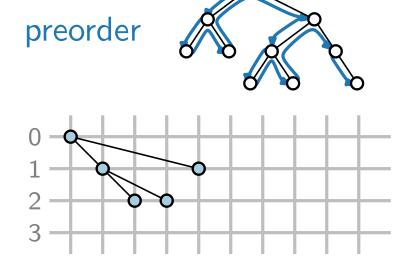




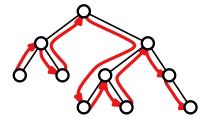
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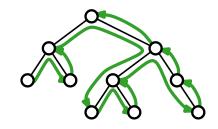


2. Choose *x*-coordinates:

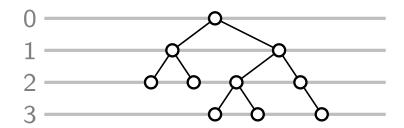


inorder

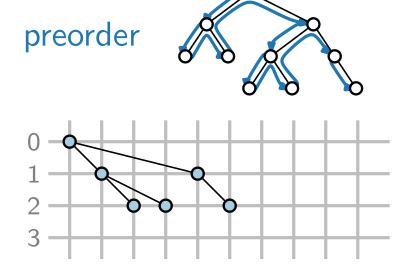




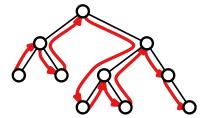
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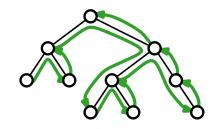


2. Choose *x*-coordinates:

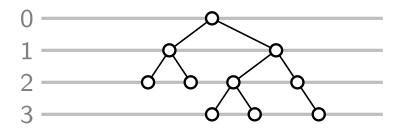


inorder

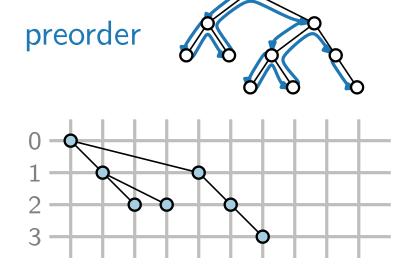




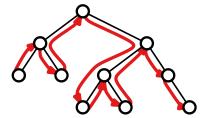
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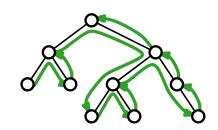


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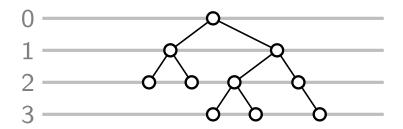


inorder

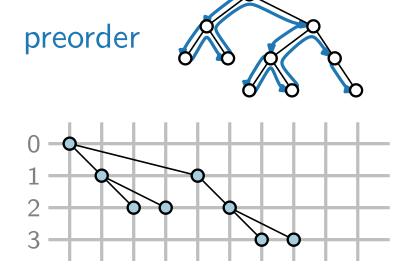




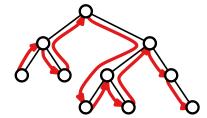
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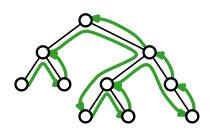


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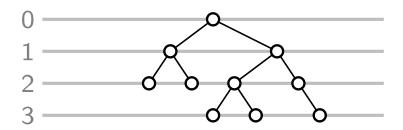


inorder

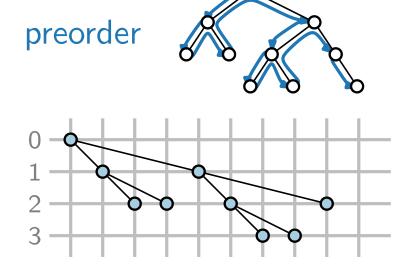




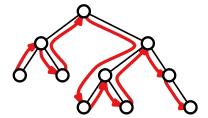
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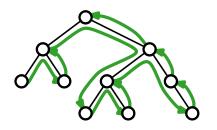


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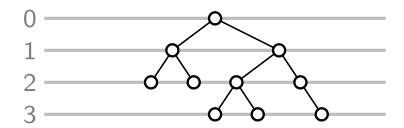


inorder





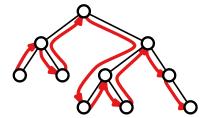
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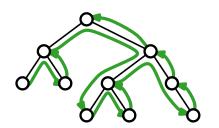


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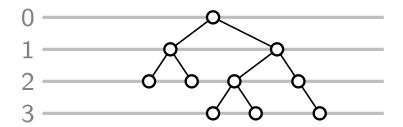


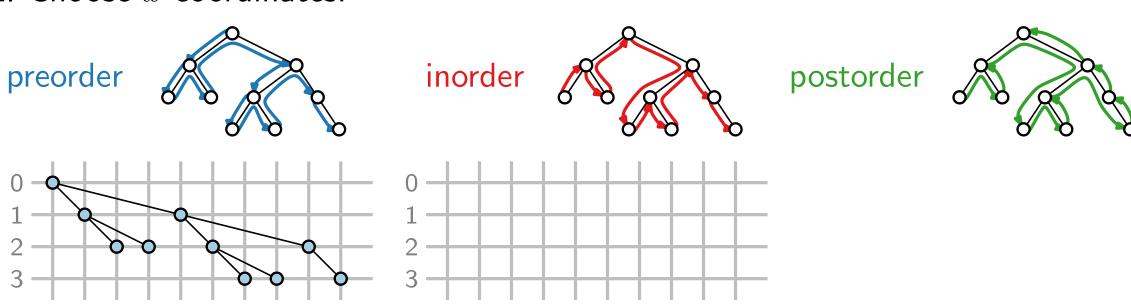
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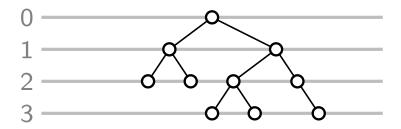


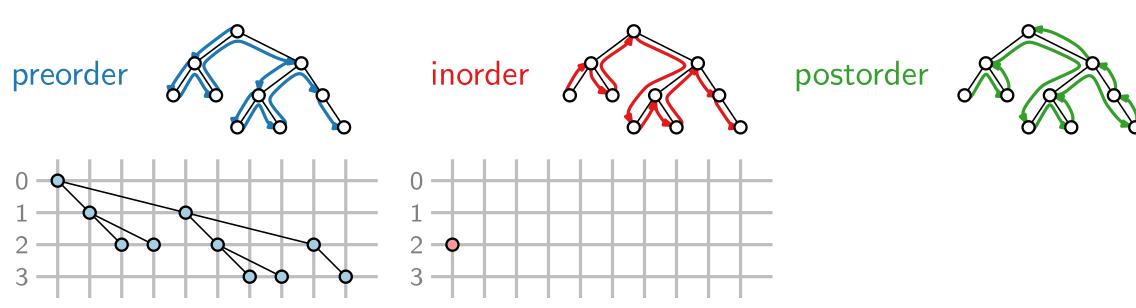
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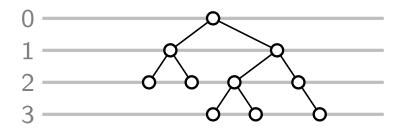


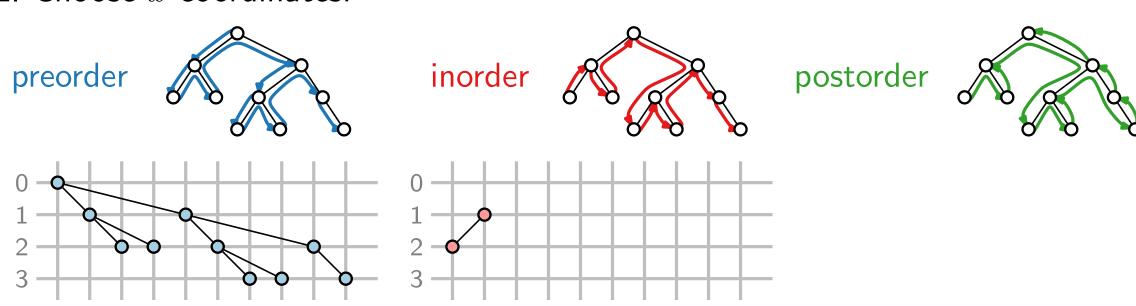
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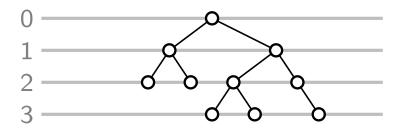


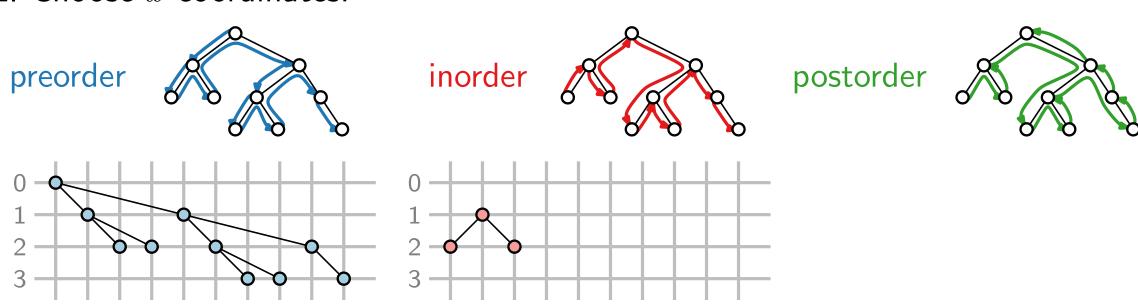
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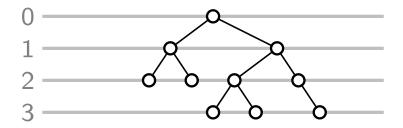


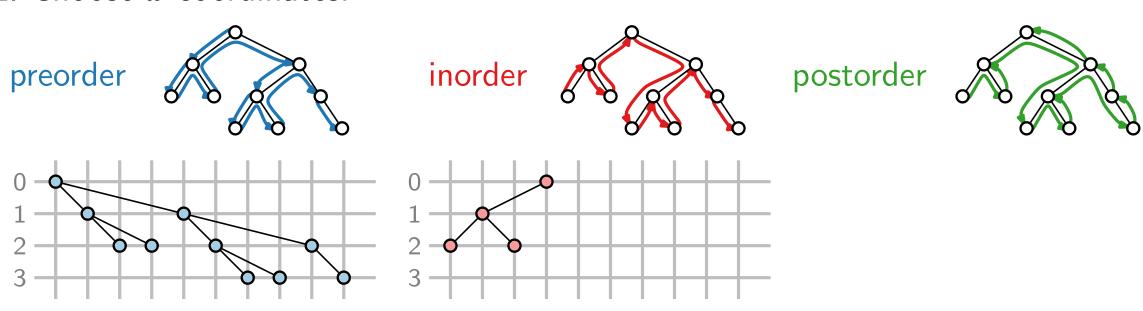
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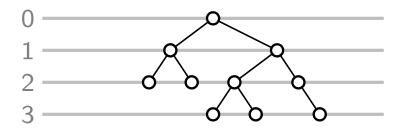


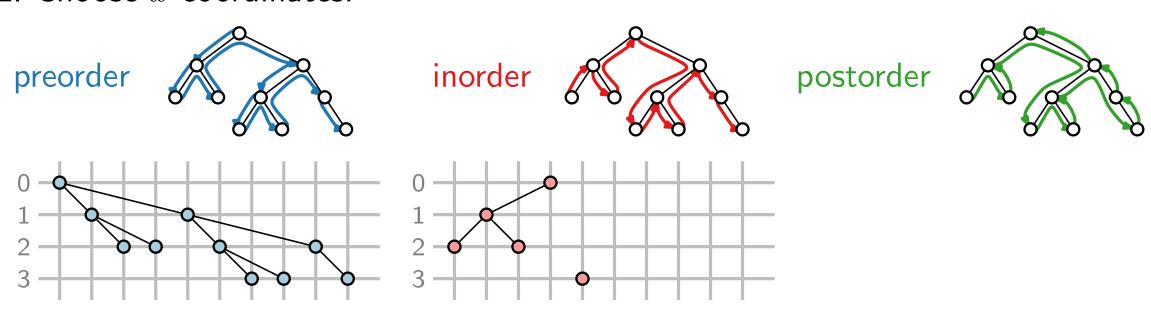
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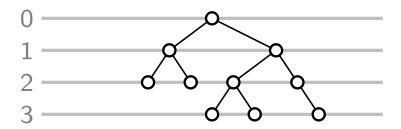


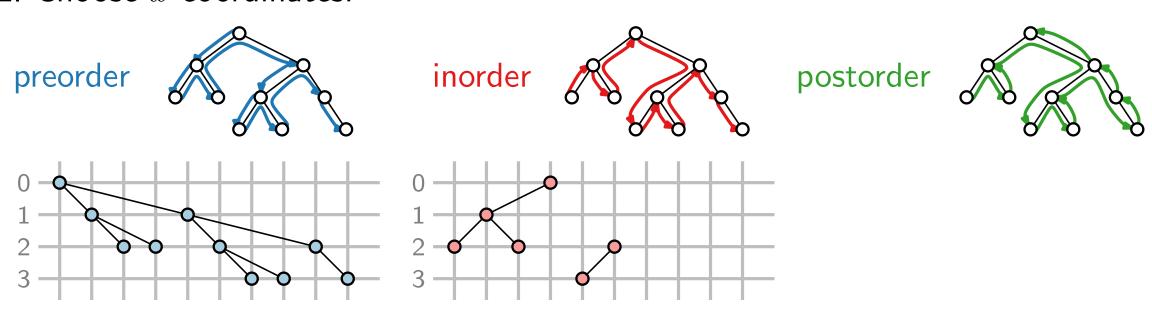
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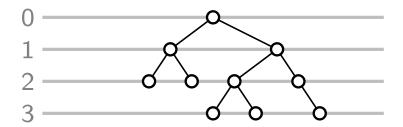


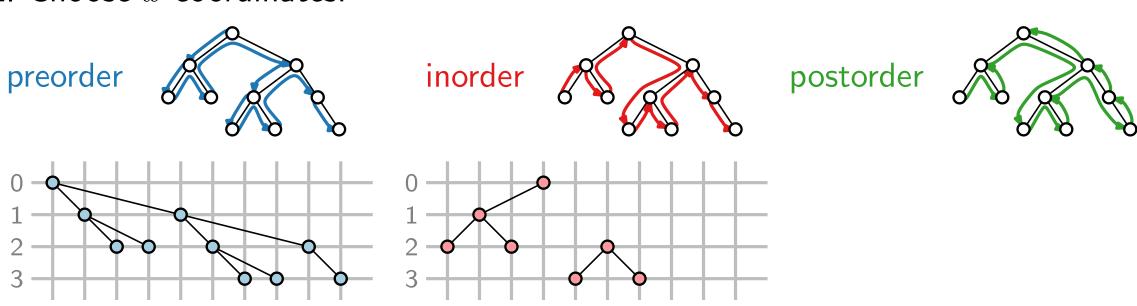
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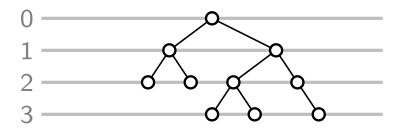


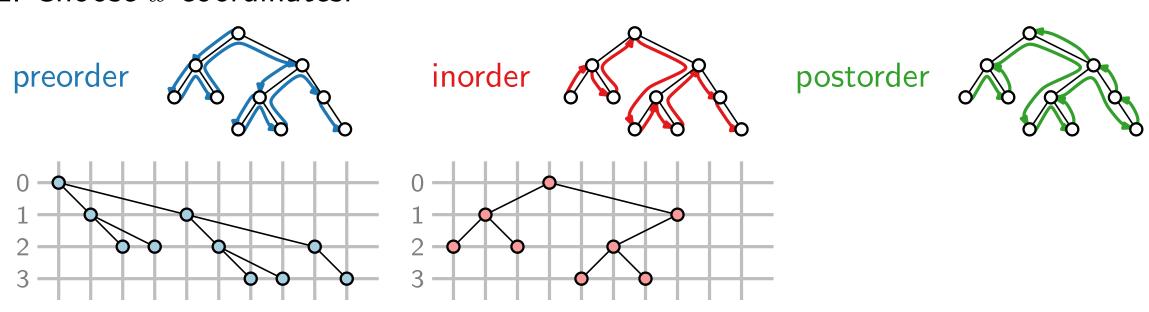
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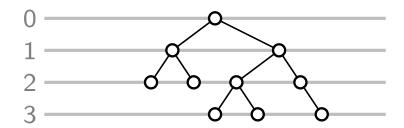


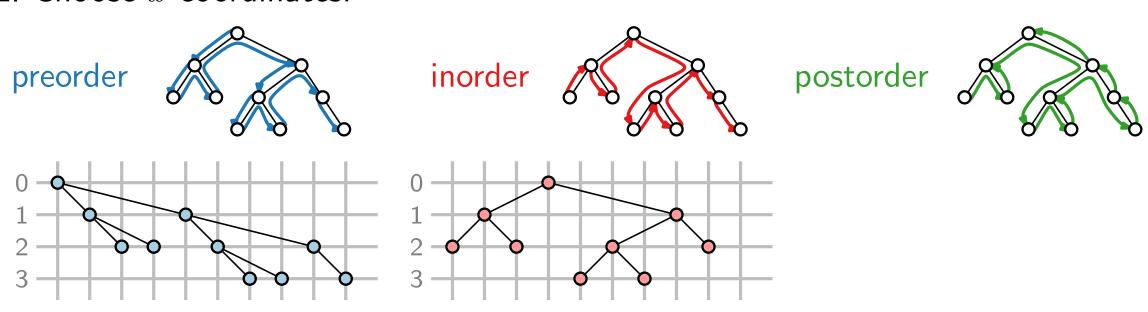
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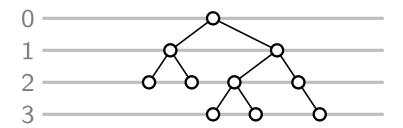


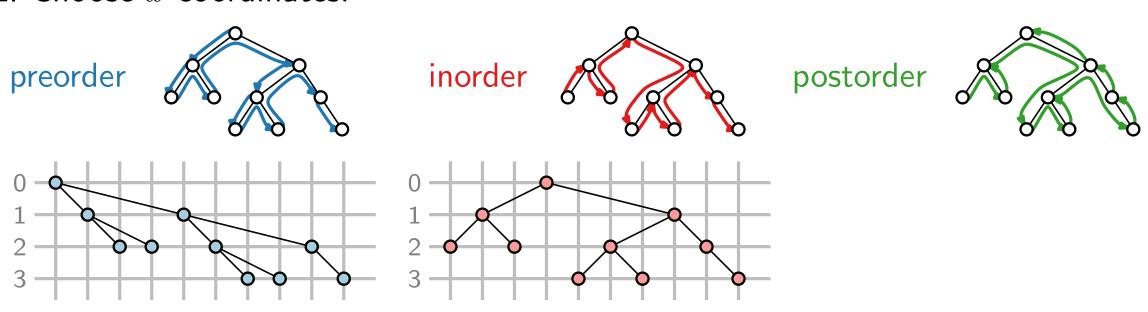
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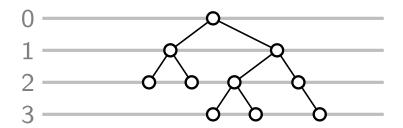


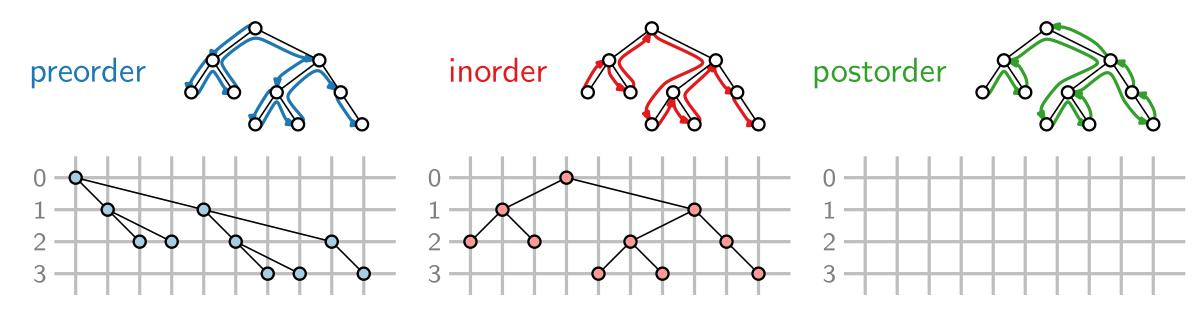
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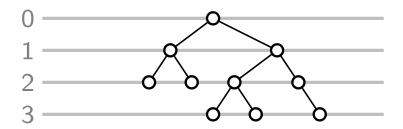


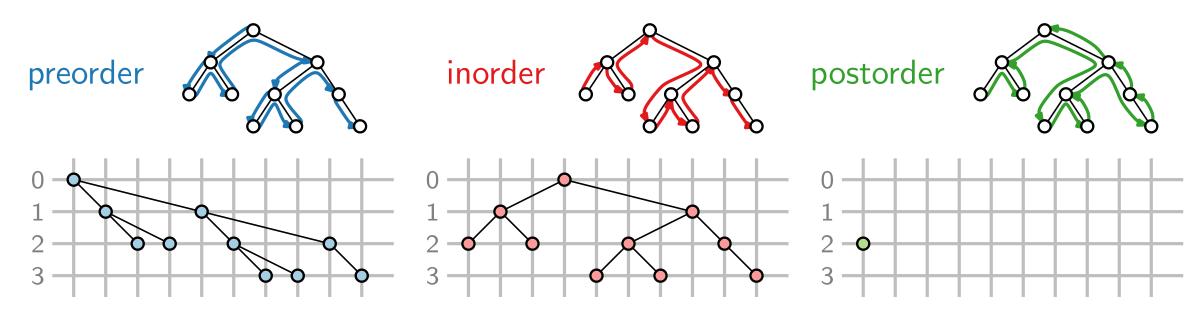
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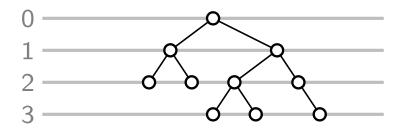


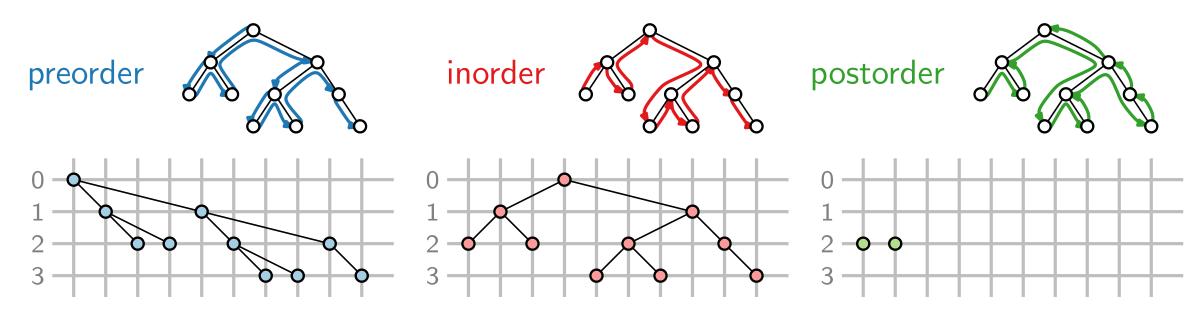
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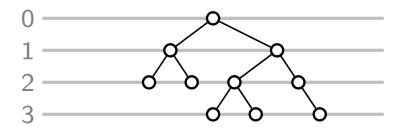


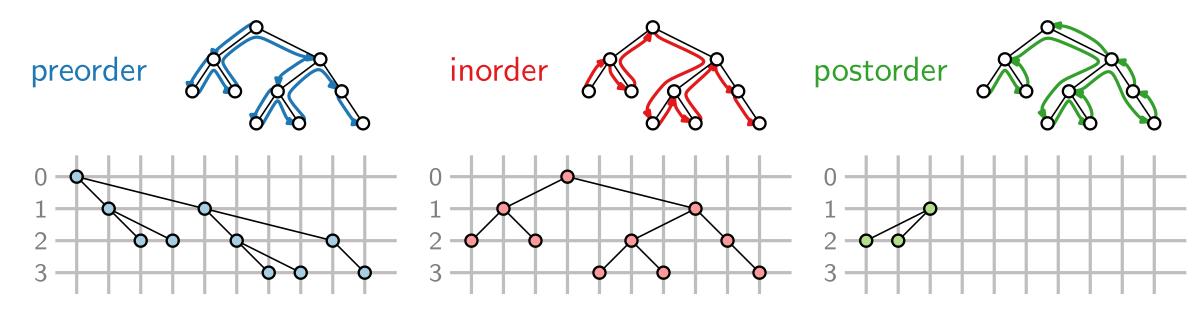
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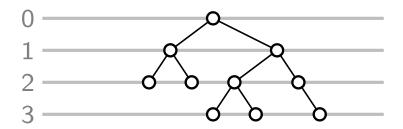


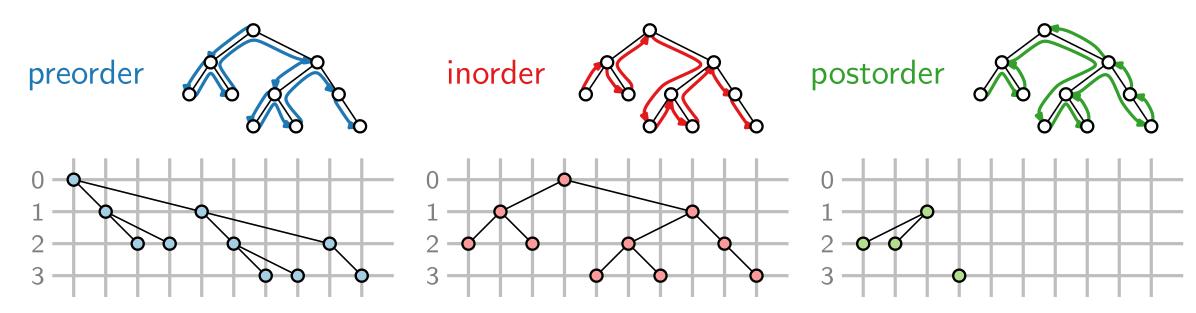
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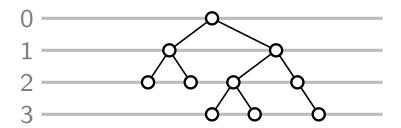


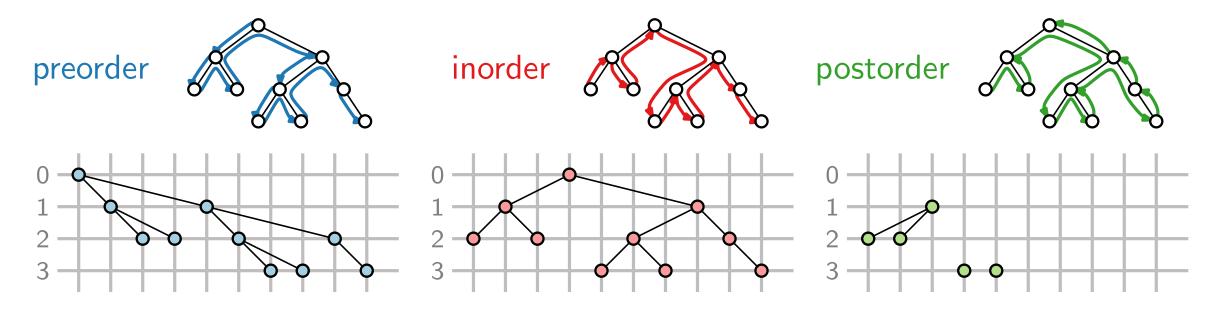
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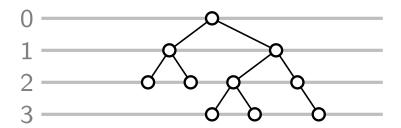


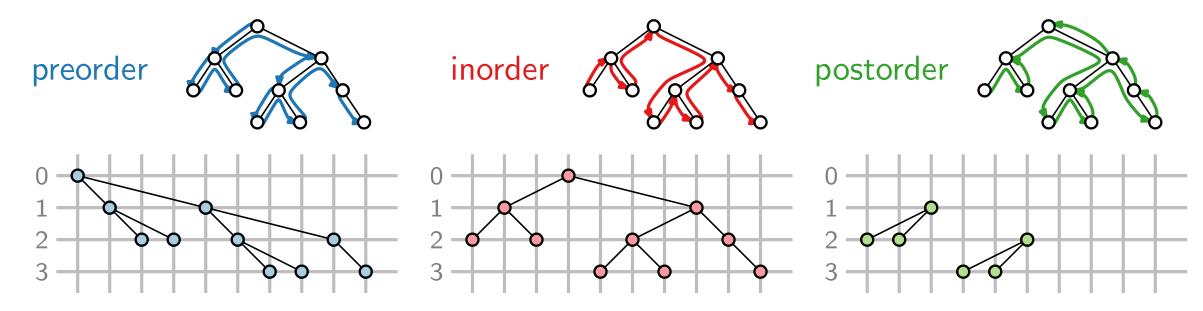
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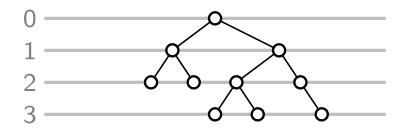


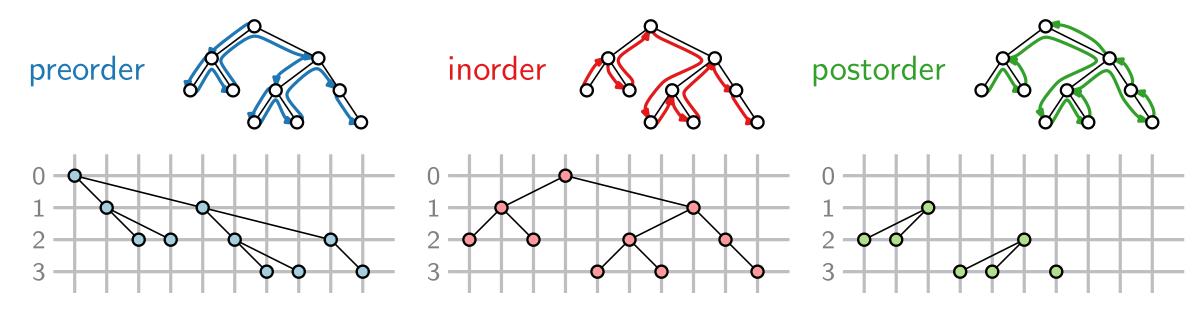
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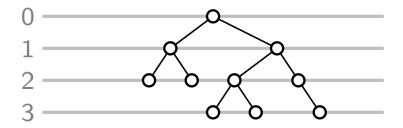


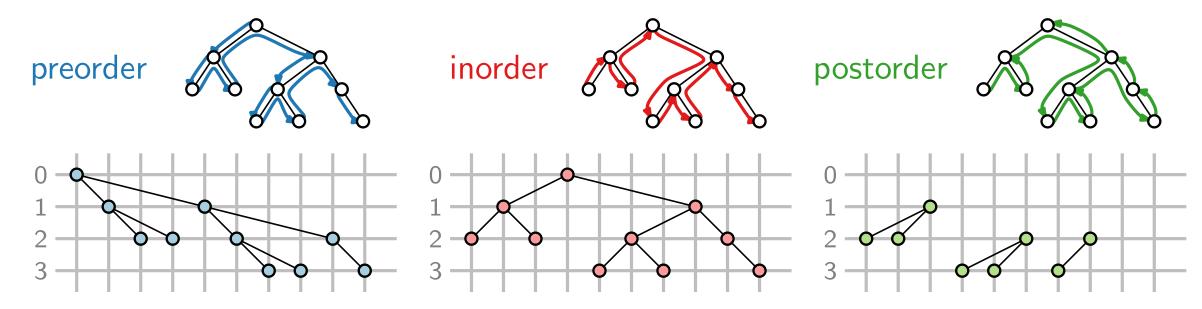
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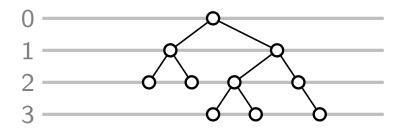


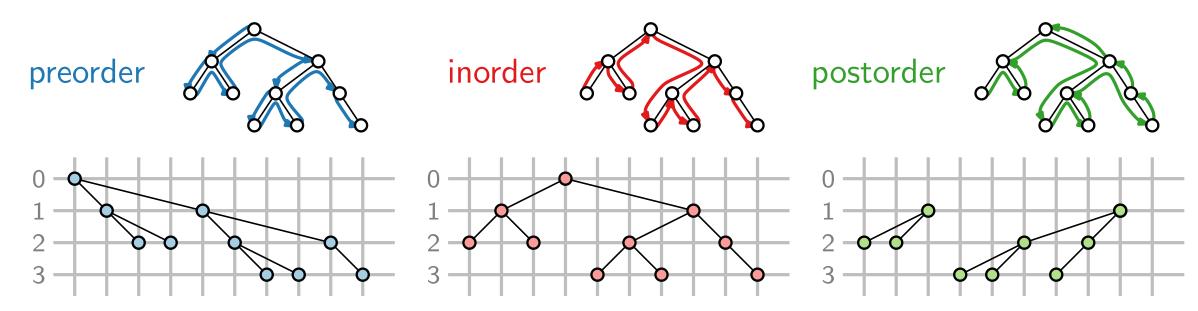
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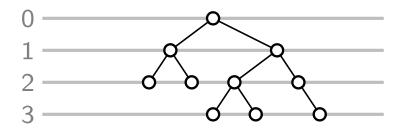


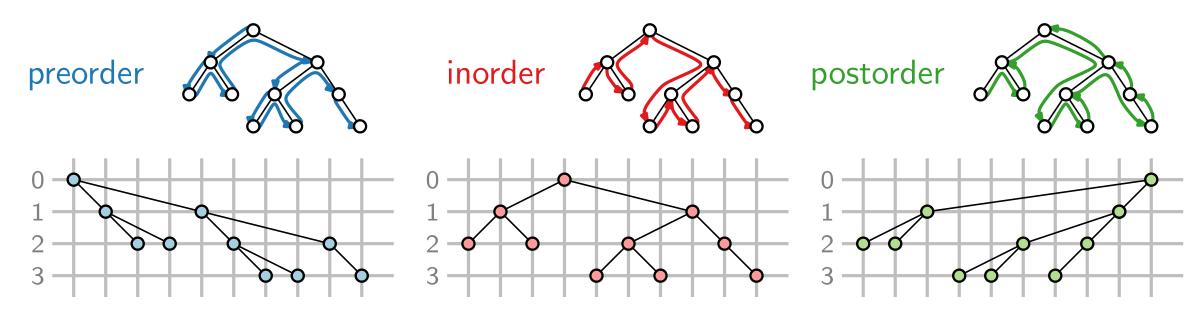
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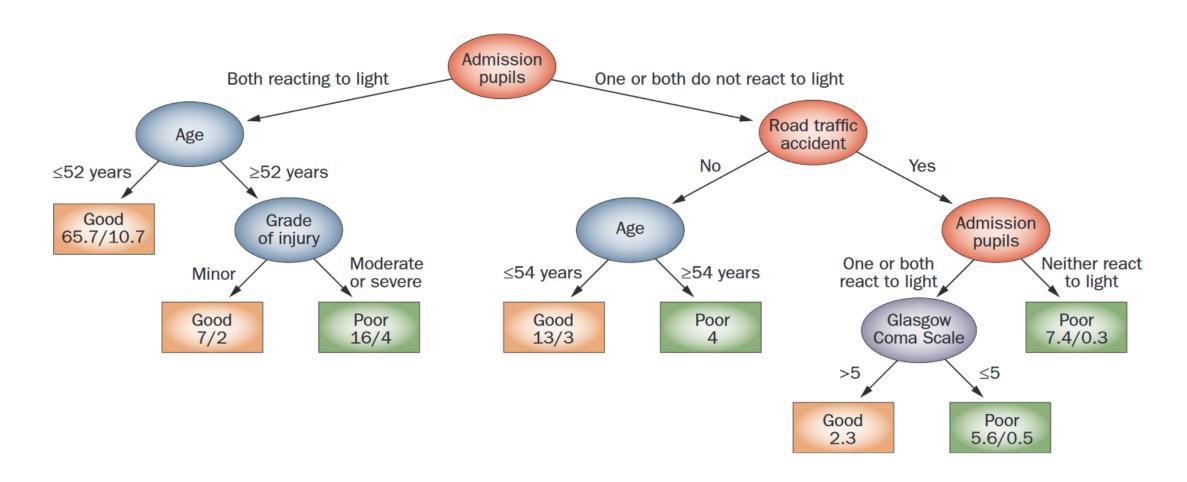


1. Choose y-coordinates: y(u) = depth(u)





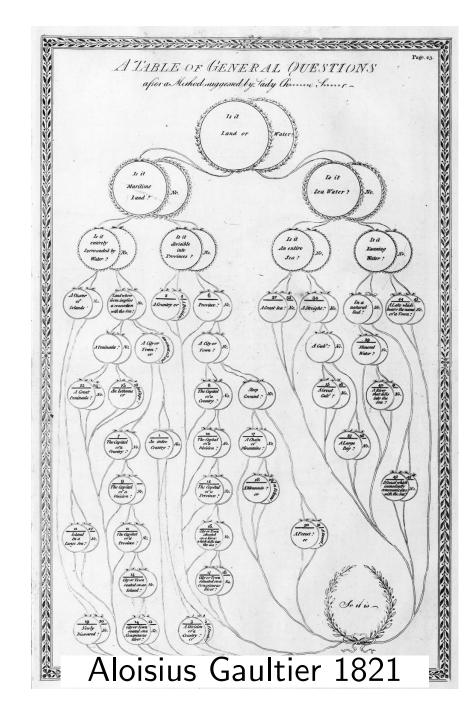
### Layered Drawings – Applications

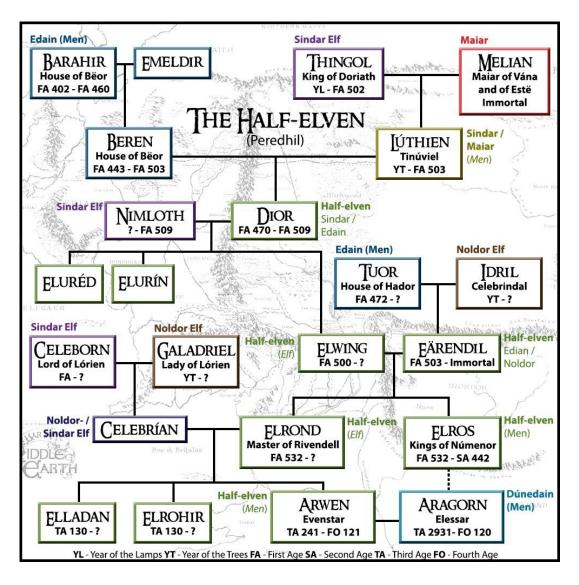


Decision tree for outcome prediction after traumatic brain injury

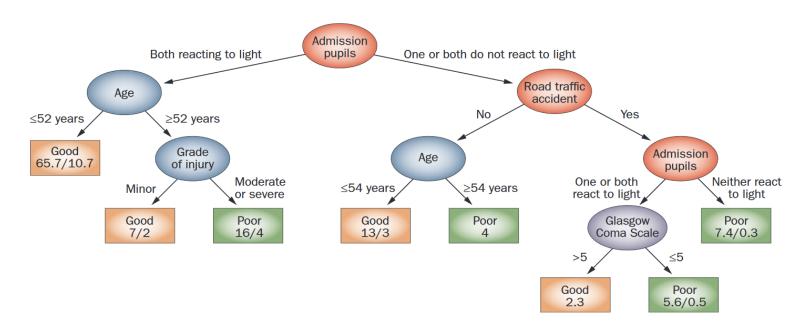
Source: Nature Reviews Neurology

### Layered Drawings – Applications

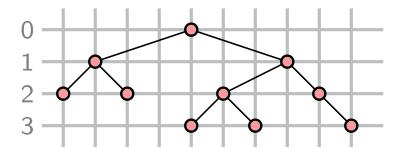




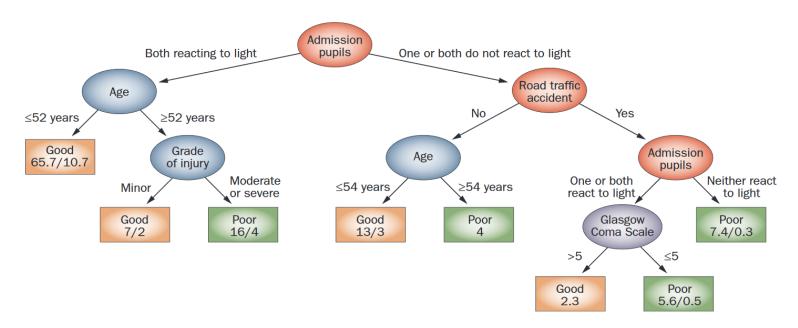
Family tree of LOTR elves and half-elves



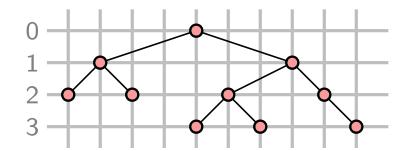
What are properties of the layout?



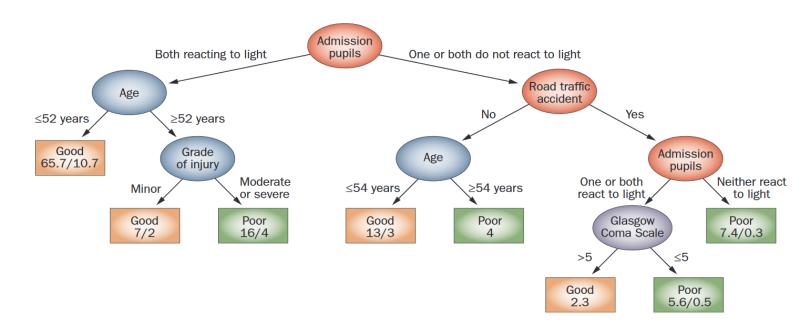
5 - 1



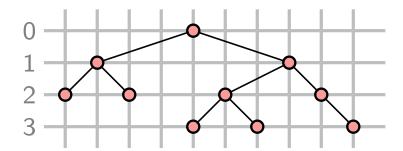
- What are properties of the layout?
- What are the drawing conventions?

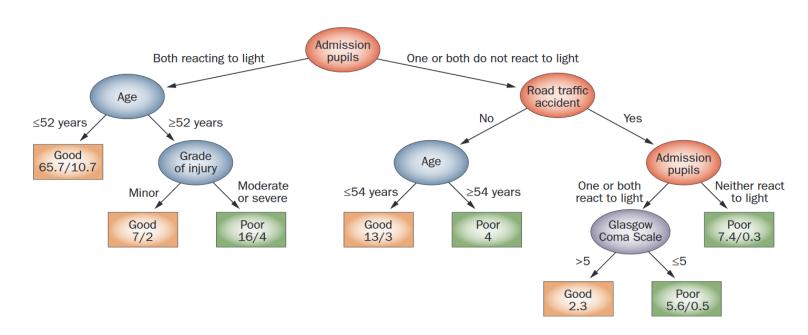


5 - 2

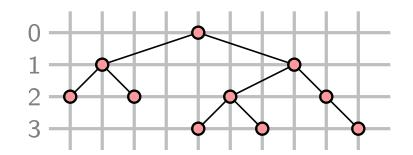


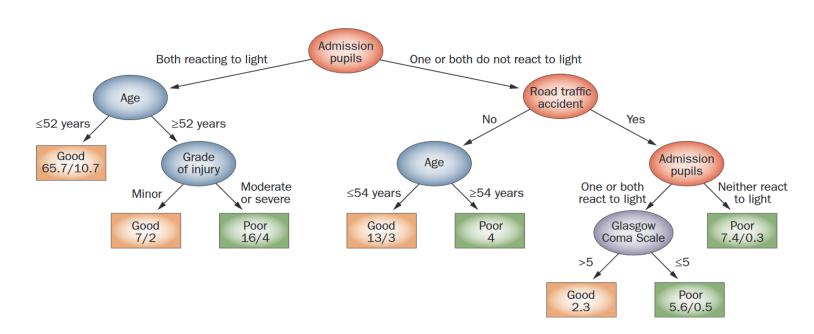
- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?



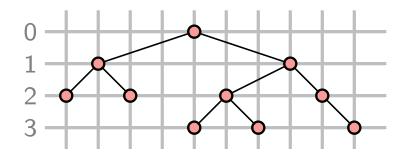


- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?



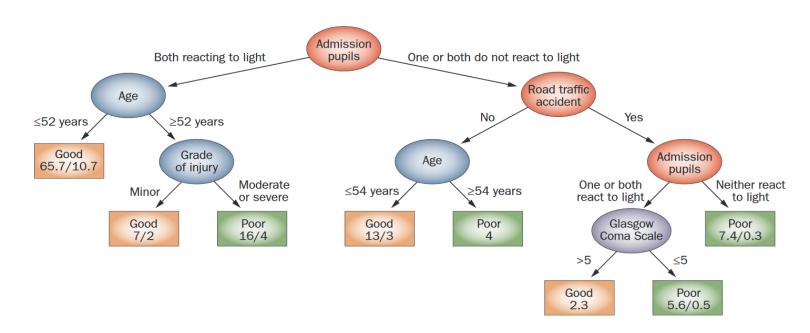


- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?

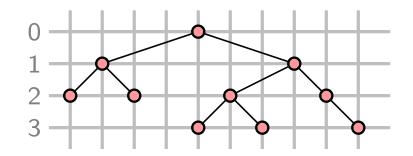


### **Drawing conventions**

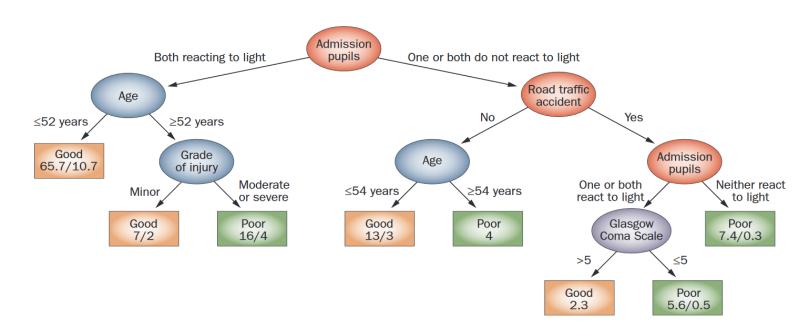
Vertices lie on layers and have integer coordinates



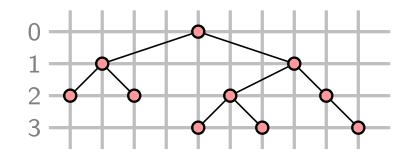
- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?



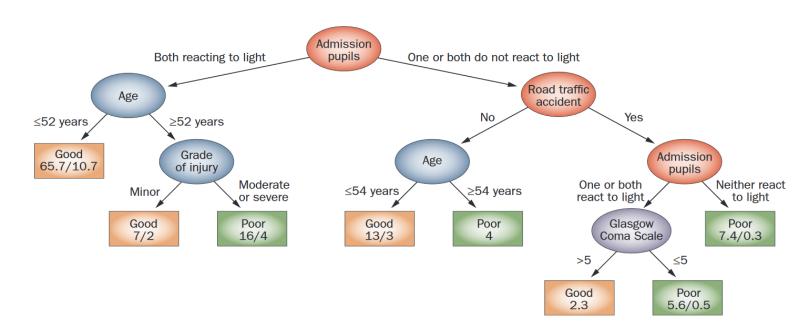
- Vertices lie on layers and have integer coordinates
- Parent centered above children



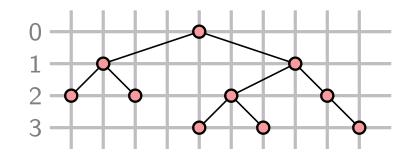
- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?



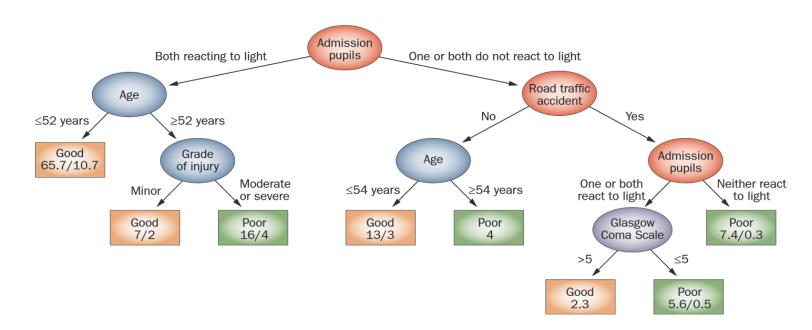
- Vertices lie on layers and have integer coordinates
- Parent centered above children
- Edges are straight-line segments



- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?

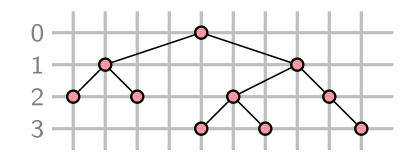


- Vertices lie on layers and have integer coordinates
- Parent centered above children
- Edges are straight-line segments
- Isomorphic subtrees have identical drawings

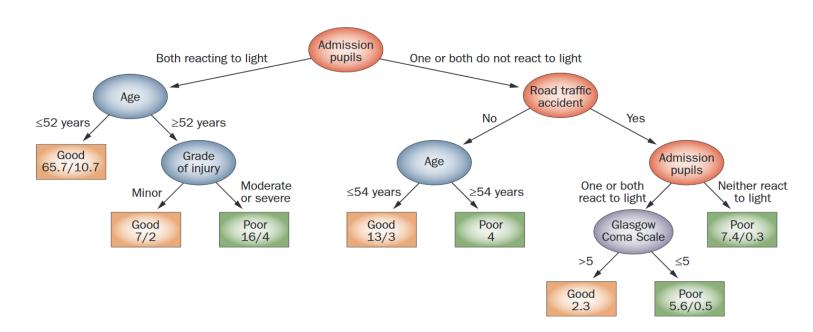


- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?



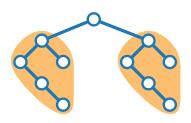


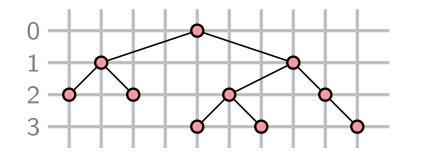
- Vertices lie on layers and have integer coordinates
- Parent centered above children
- Edges are straight-line segments
- Isomorphic subtrees have identical drawings



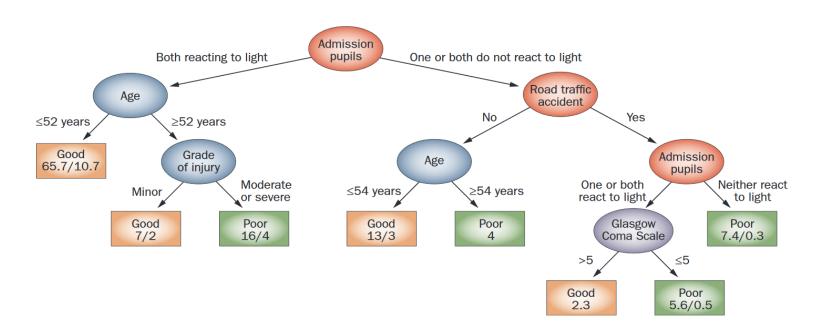
- What are properties of the layout?
- What are the drawing conventions?
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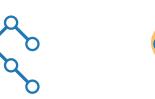


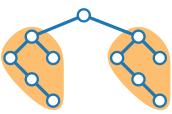


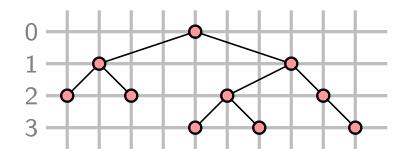
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- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?



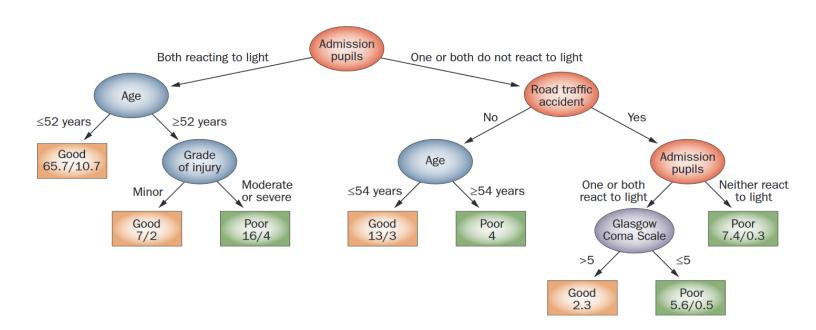




### **Drawing conventions**

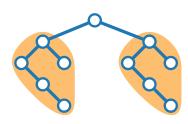
- Vertices lie on layers and have integer coordinates
- Parent centered above children
- Edges are straight-line segments
- Isomorphic subtrees have identical drawings

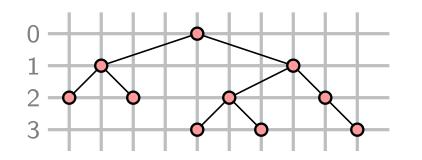
#### **Drawing aesthetics**



- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?





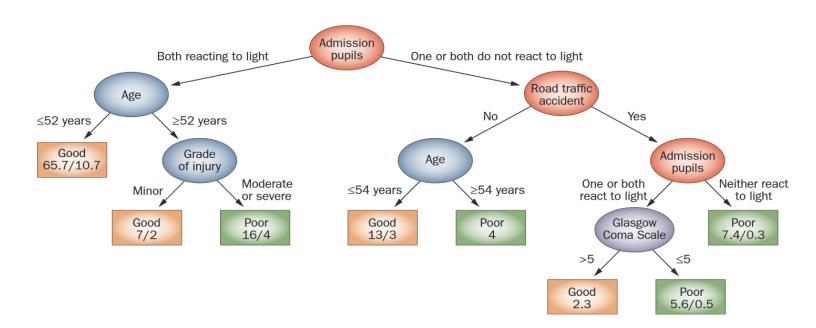


### **Drawing conventions**

- Vertices lie on layers and have integer coordinates
- Parent centered above children
- Edges are straight-line segments
- Isomorphic subtrees have identical drawings

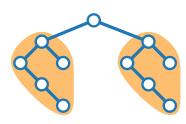
### **Drawing aesthetics**

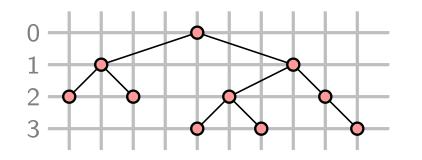
Area



- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?







### **Drawing conventions**

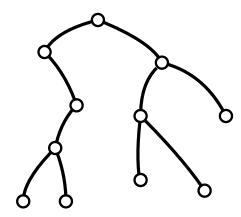
- Vertices lie on layers and have integer coordinates
- Parent centered above children
- Edges are straight-line segments
- Isomorphic subtrees have identical drawings

### **Drawing aesthetics**

- Area
- Symmetries

Input: A binary tree T

Output: A layered drawing of T

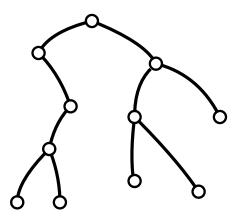


Input: A binary tree T

Output: A layered drawing of T

Base case:

Divide:

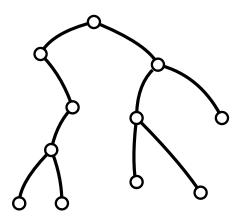


Input: A binary tree T

**Output:** A layered drawing of T

Base case: A single vertex

Divide:



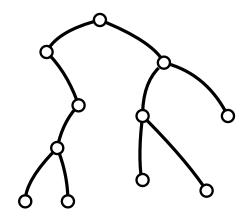
Input: A binary tree T

**Output:** A layered drawing of T

Base case: A single vertex

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees



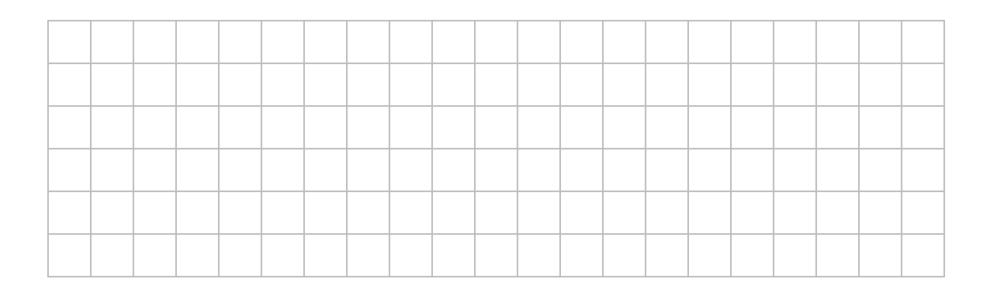
Input: A binary tree T

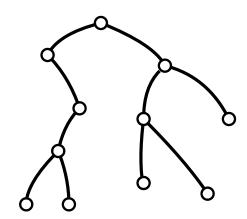
**Output:** A layered drawing of T

Base case: A single vertex

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees





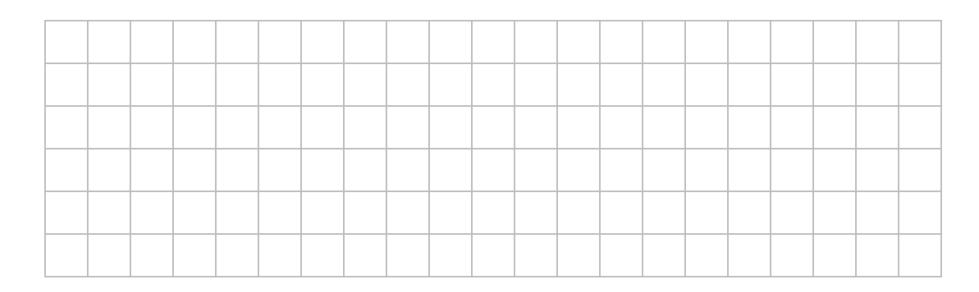
Input: A binary tree T

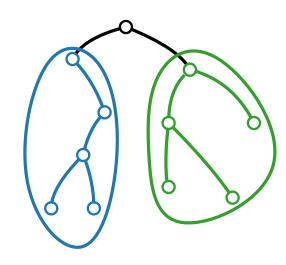
**Output:** A layered drawing of T

Base case: A single vertex o

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees





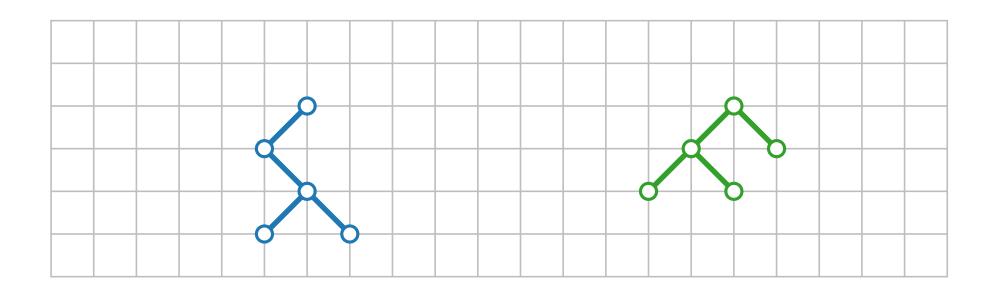
Input: A binary tree T

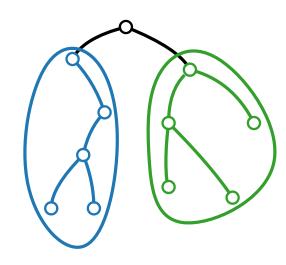
**Output:** A layered drawing of T

Base case: A single vertex

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees





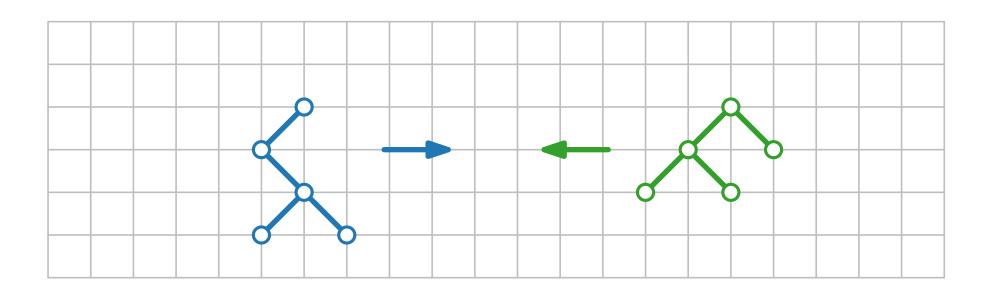
Input: A binary tree T

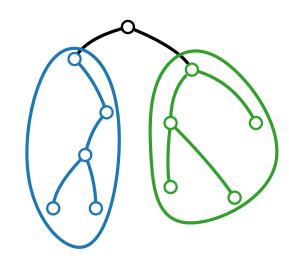
**Output:** A layered drawing of T

Base case: A single vertex

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees





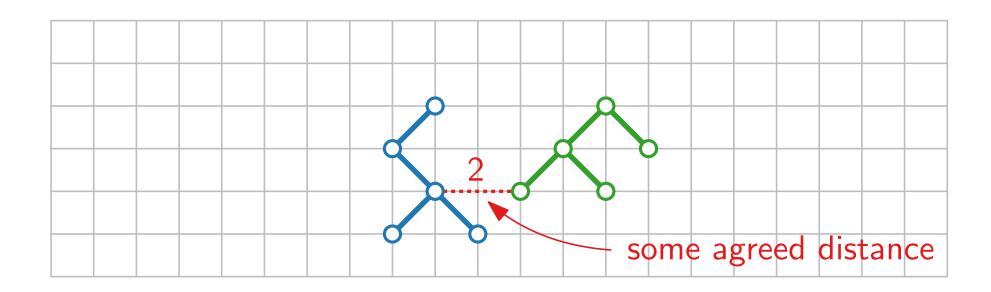
Input: A binary tree T

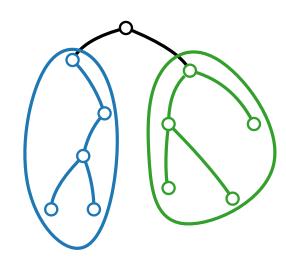
**Output:** A layered drawing of T

Base case: A single vertex

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees





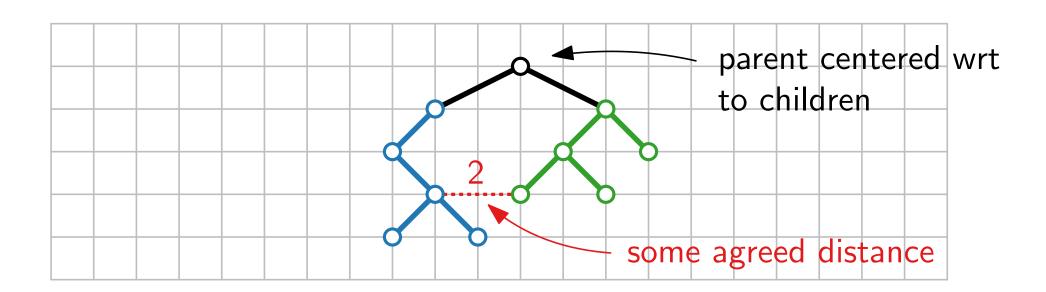
Input: A binary tree T

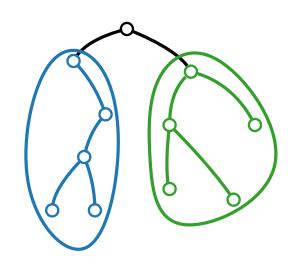
**Output:** A layered drawing of T

Base case: A single vertex

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees





Input: A binary tree T

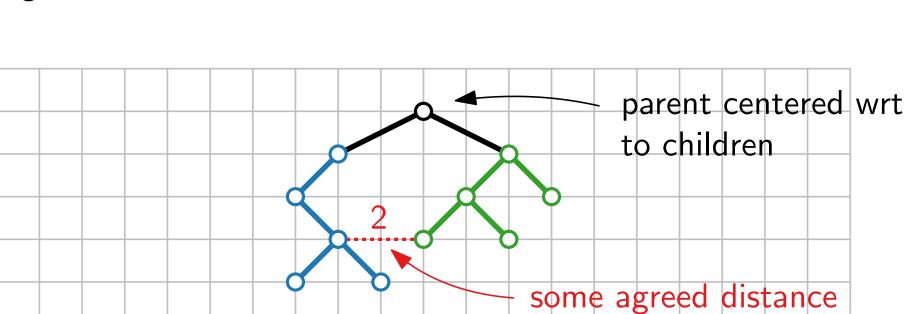
**Output:** A layered drawing of T

Base case: A single vertex o

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees

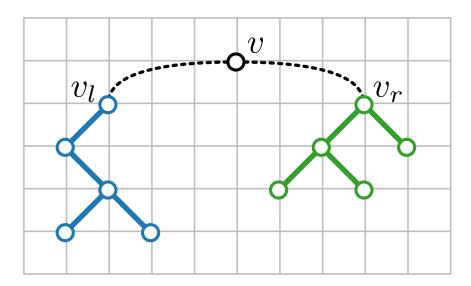
### **Conquer:**



sometimes 3 apart for grid drawing!

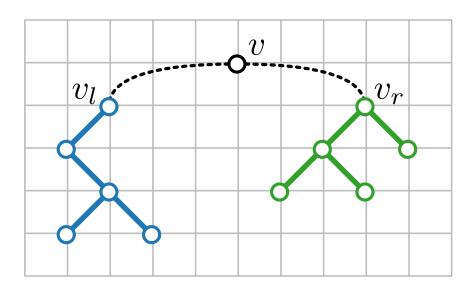
### Phase 1 – postorder traversal:

■ For each vertex compute horizontal displacement of left and right child



### Phase 1 – postorder traversal:

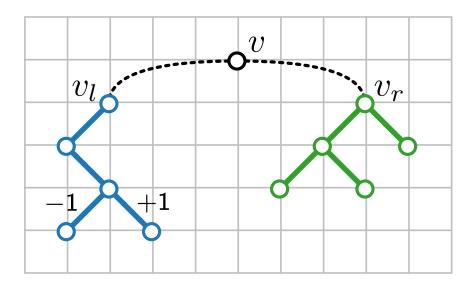
■ For each vertex compute horizontal displacement of left and right child



### Phase 2 – preorder traversal:

### Phase 1 – postorder traversal:

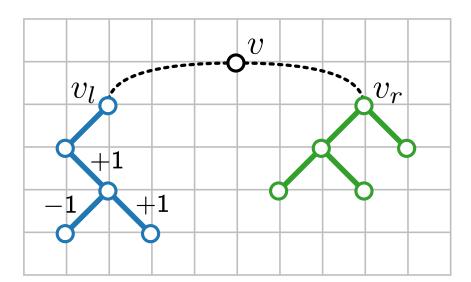
■ For each vertex compute horizontal displacement of left and right child



### Phase 2 – preorder traversal:

### Phase 1 – postorder traversal:

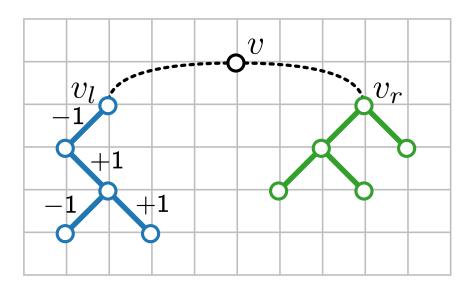
■ For each vertex compute horizontal displacement of left and right child



### Phase 2 – preorder traversal:

### Phase 1 – postorder traversal:

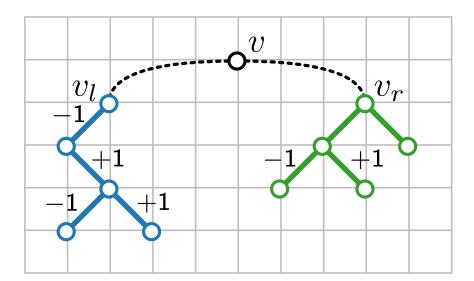
■ For each vertex compute horizontal displacement of left and right child



### Phase 2 – preorder traversal:

### Phase 1 – postorder traversal:

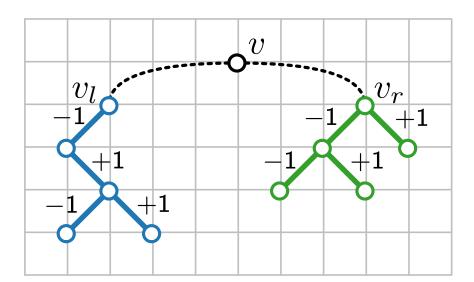
■ For each vertex compute horizontal displacement of left and right child



### Phase 2 – preorder traversal:

### Phase 1 – postorder traversal:

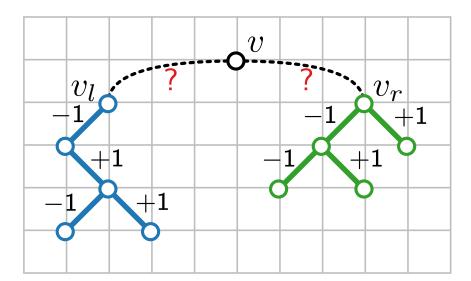
■ For each vertex compute horizontal displacement of left and right child



### Phase 2 – preorder traversal:

### Phase 1 – postorder traversal:

■ For each vertex compute horizontal displacement of left and right child

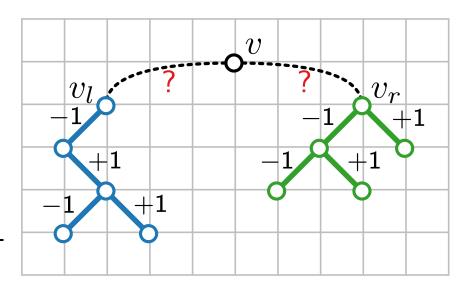


### Phase 2 – preorder traversal:

### Phase 1 – postorder traversal:

■ For each vertex compute horizontal displacement of left and right child

- At vertex u (below v) store left and right contour of subtree T(u)
- Contour is linked list of vertex coordinates/offsets



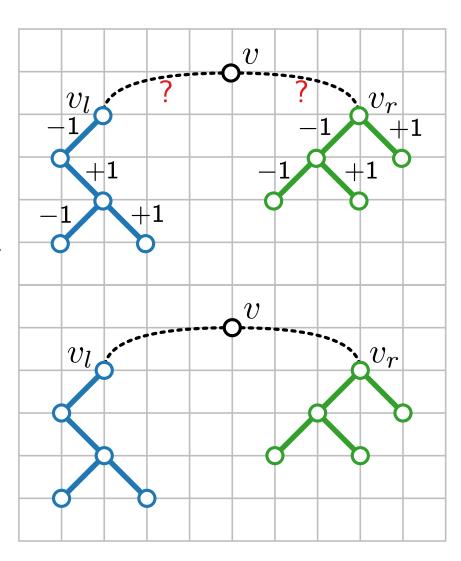
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### Phase 2 – preorder traversal:

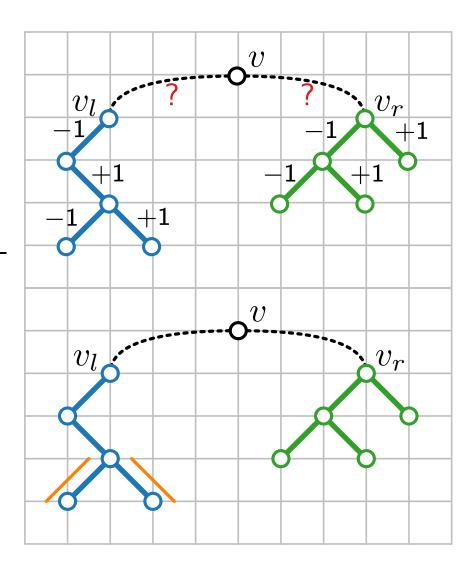


### Phase 1 – postorder traversal:

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### Phase 2 – preorder traversal:

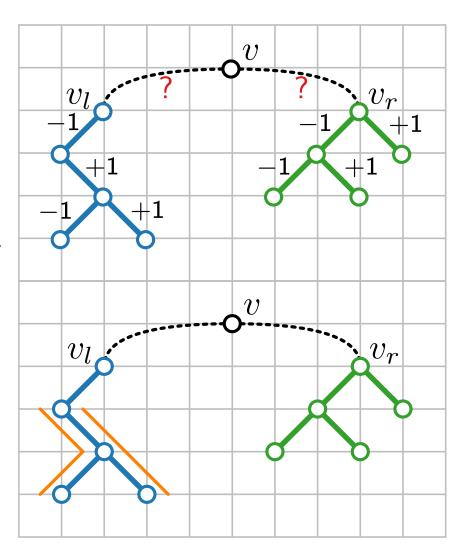


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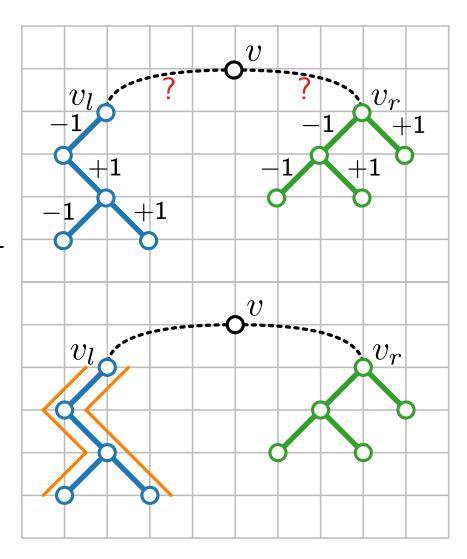


### Phase 1 – postorder traversal:

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### Phase 2 – preorder traversal:

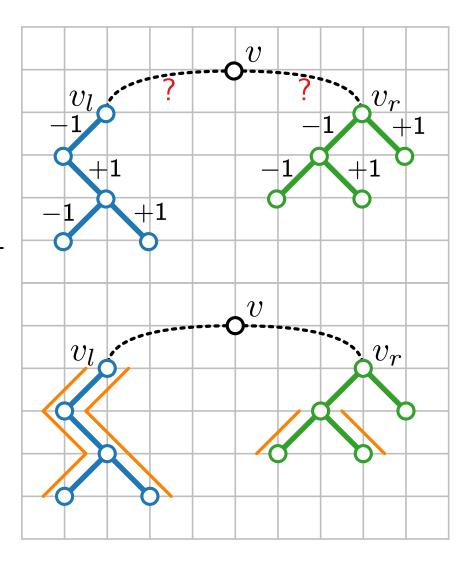


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### Phase 2 – preorder traversal:

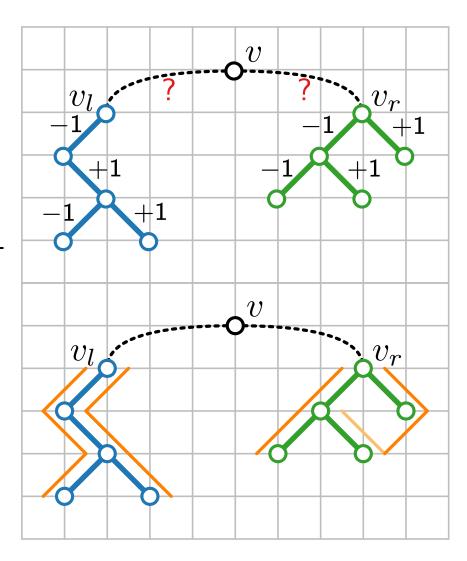


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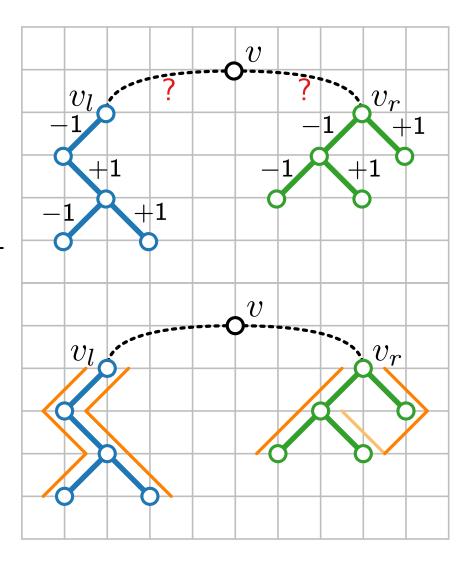


### Phase 1 – postorder traversal:

■ For each vertex compute horizontal displacement of left and right child

- At vertex u (below v) store left and right contour of subtree T(u)
- Contour is linked list of vertex coordinates/offsets
- Find  $d_v = \min$ . horiz. distance between  $v_l$  and  $v_r$

### Phase 2 – preorder traversal:

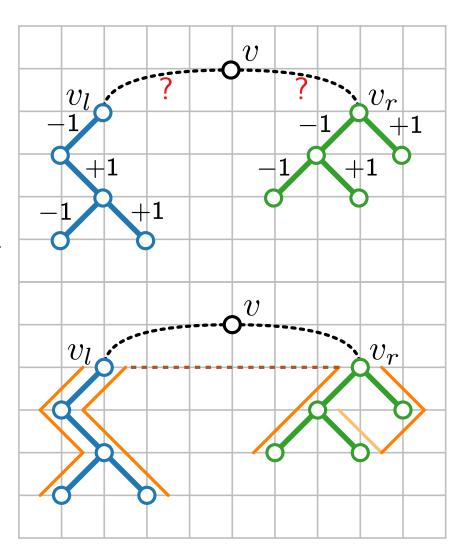


### Phase 1 – postorder traversal:

■ For each vertex compute horizontal displacement of left and right child

- At vertex u (below v) store left and right contour of subtree T(u)
- Contour is linked list of vertex coordinates/offsets
- lacktriangle Find  $d_v = \min$ . horiz. distance between  $v_l$  and  $v_r$

### Phase 2 – preorder traversal:

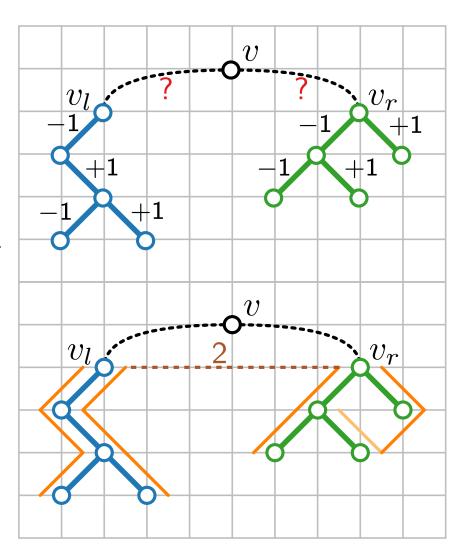


### Phase 1 – postorder traversal:

■ For each vertex compute horizontal displacement of left and right child

- At vertex u (below v) store left and right contour of subtree T(u)
- Contour is linked list of vertex coordinates/offsets
- Find  $d_v = \min$ . horiz. distance between  $v_l$  and  $v_r$

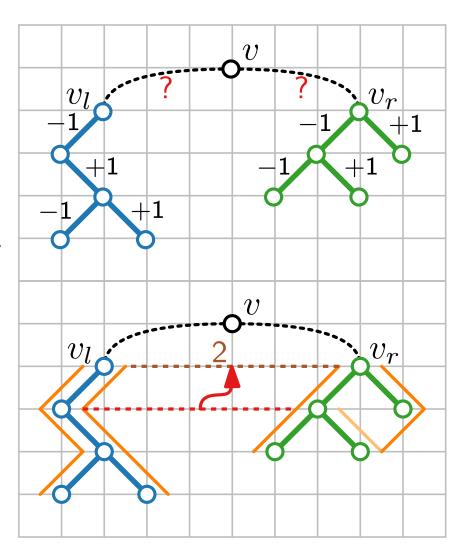
### Phase 2 – preorder traversal:



### Phase 1 – postorder traversal:

- For each vertex compute horizontal displacement of left and right child
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### Phase 2 – preorder traversal:

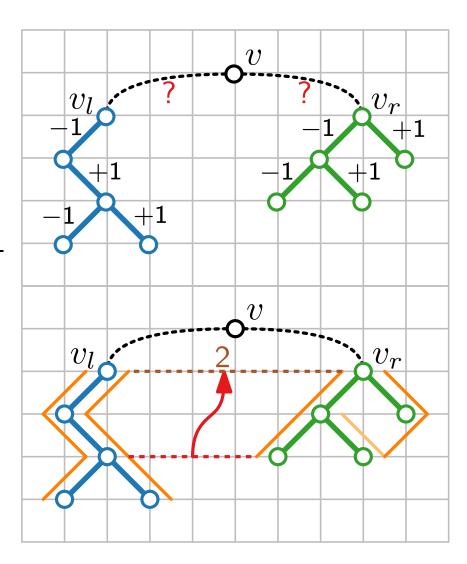


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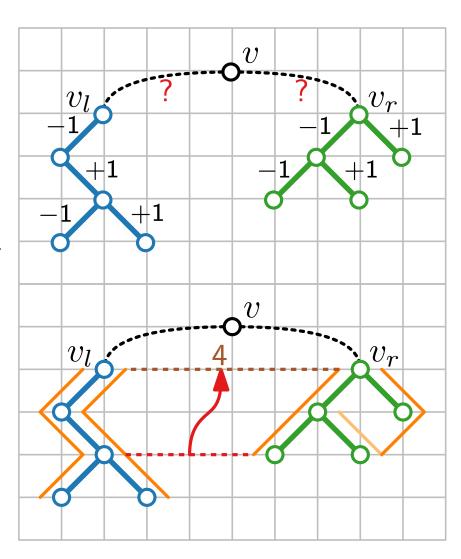


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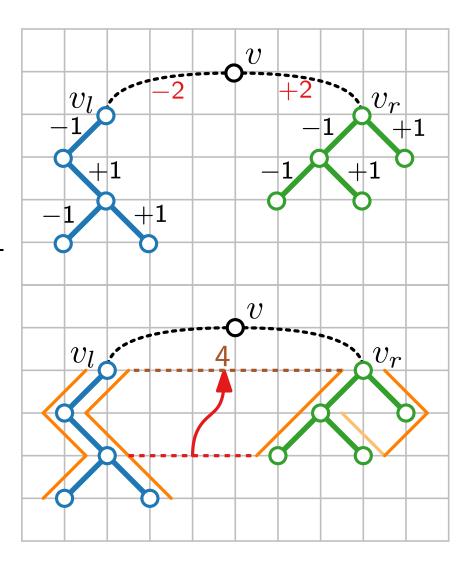
### Phase 2 – preorder traversal:



### Phase 1 – postorder traversal:

- For each vertex compute horizontal displacement of left and right child
- $\blacksquare$  x-offset $(v_l) = -\lceil \frac{d_v}{2} \rceil$ , x-offset $(v_r) = \lceil \frac{d_v}{2} \rceil$
- At vertex u (below v) store left and right contour of subtree T(u)
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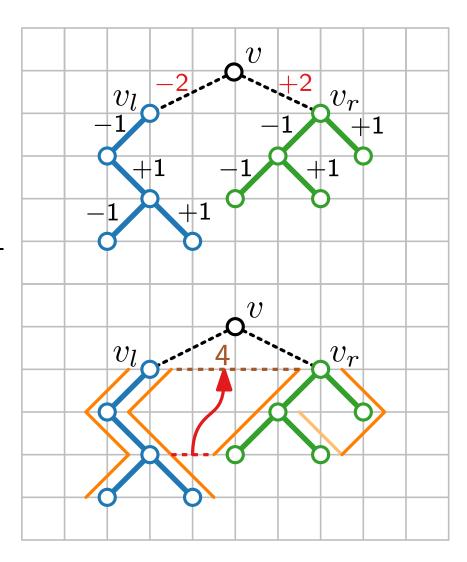
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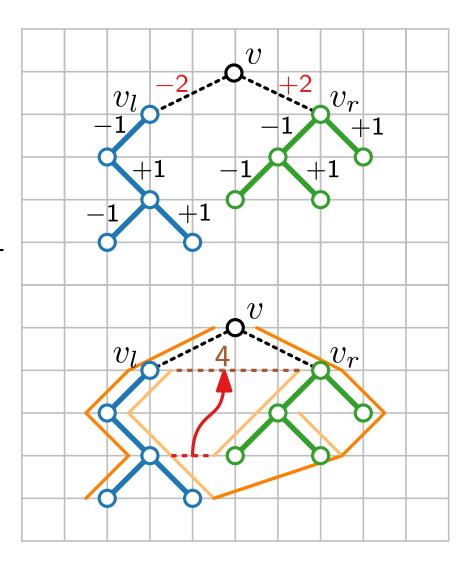
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### Phase 2 – preorder traversal:



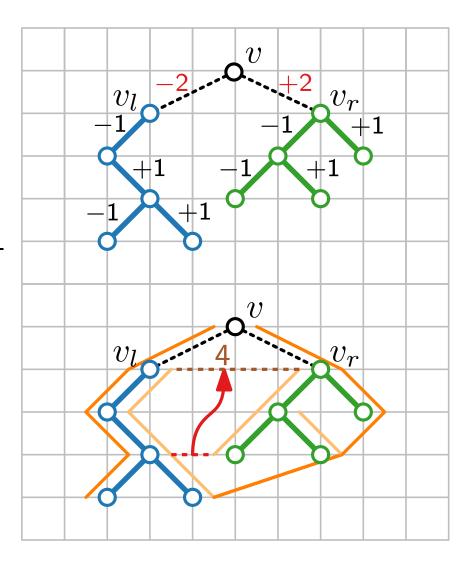
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### Phase 2 – preorder traversal:

Compute x- and y-coordinates

#### Runtime?



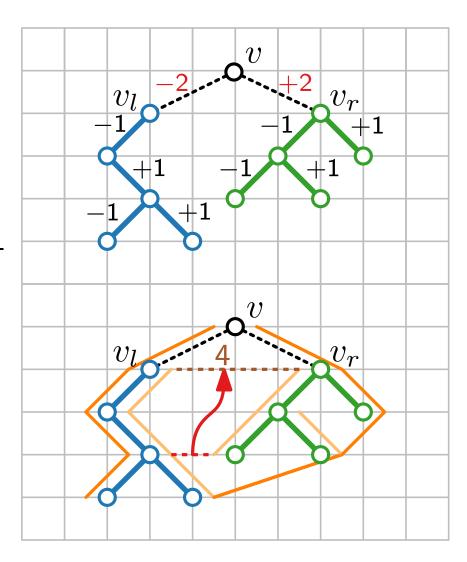
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#### Runtime?



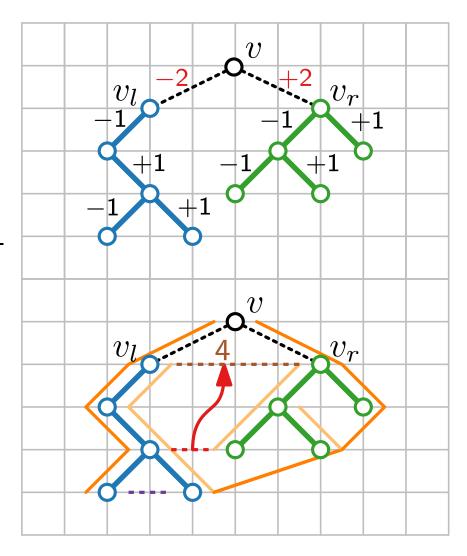
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#### **Runtime?**



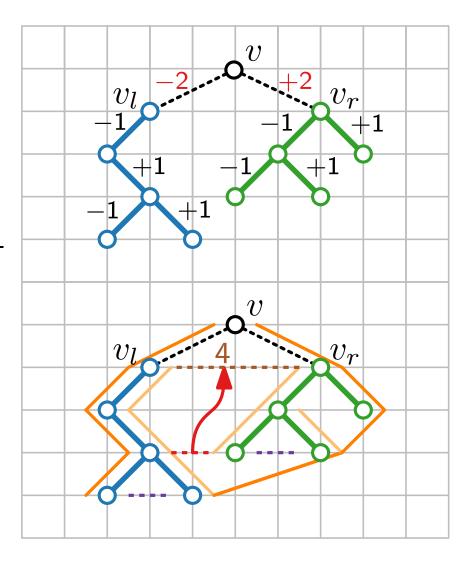
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### Phase 2 – preorder traversal:

Compute x- and y-coordinates

#### **Runtime?**



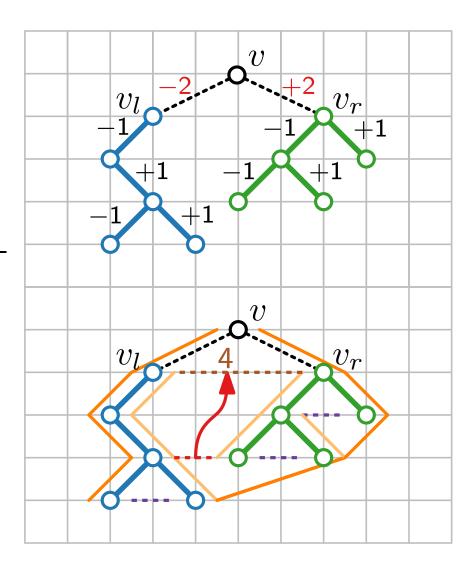
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### Phase 2 – preorder traversal:

Compute x- and y-coordinates

#### Runtime?



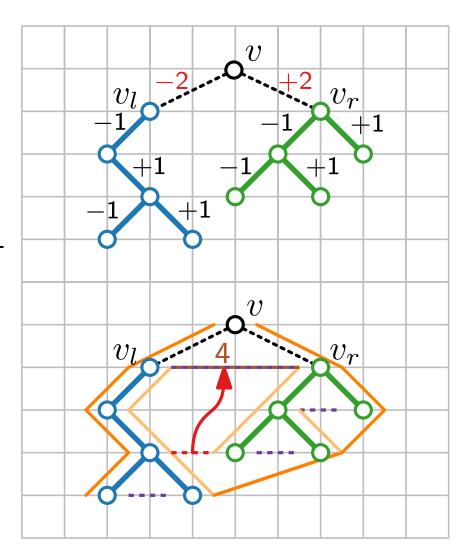
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### Phase 2 – preorder traversal:

Compute x- and y-coordinates

#### Runtime?



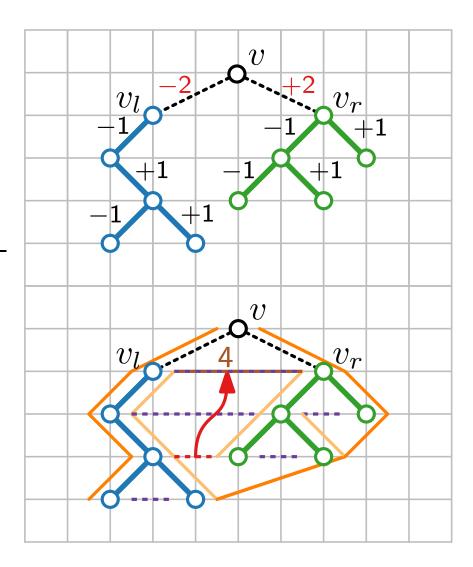
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Compute x- and y-coordinates

#### **Runtime?**



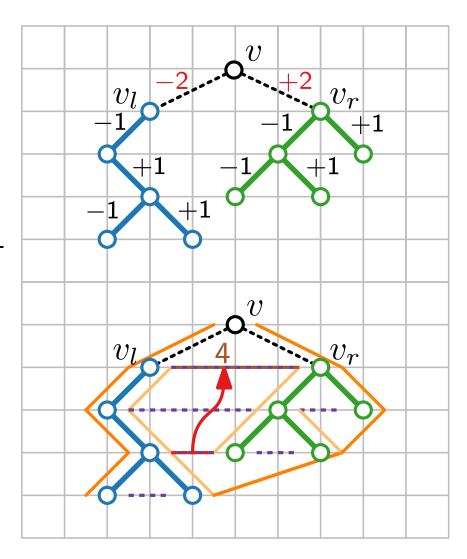
### Phase 1 – postorder traversal:

- For each vertex compute horizontal displacement of left and right child
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- At vertex u (below v) store left and right contour of subtree T(u)
- Contour is linked list of vertex coordinates/offsets
- Find  $d_v = \min$ . horiz. distance between  $v_l$  and  $v_r$

### Phase 2 – preorder traversal:

Compute x- and y-coordinates

#### Runtime?



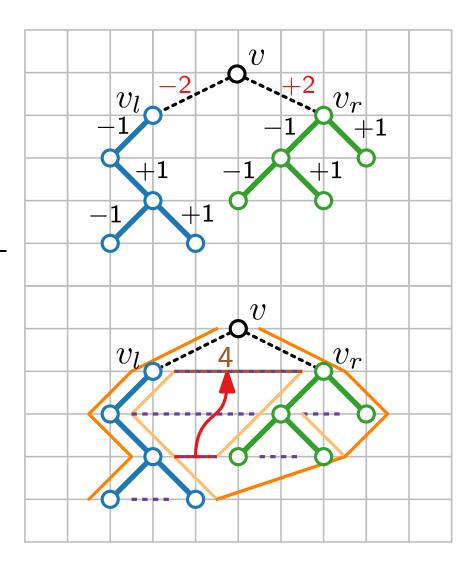
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$$\Rightarrow \mathcal{O}(n)$$

### Layered Drawings – Result

#### Theorem.

[Reingold & Tilford '81]

Let T be a binary tree with n vertices. We can construct a drawing  $\Gamma$  of T in  $\mathcal{O}(n)$  time, such that:

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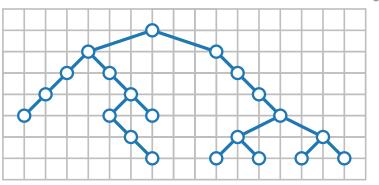
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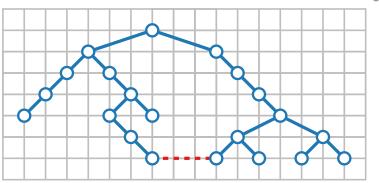
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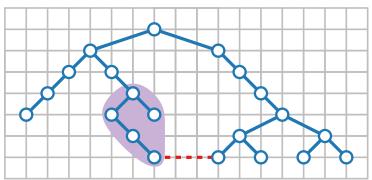
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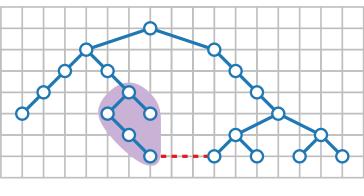
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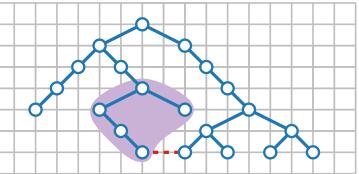


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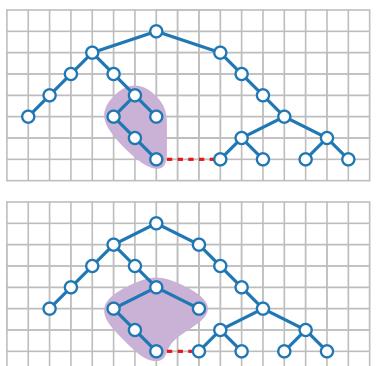
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NP-hard

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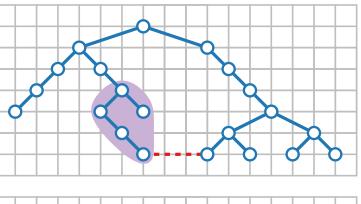
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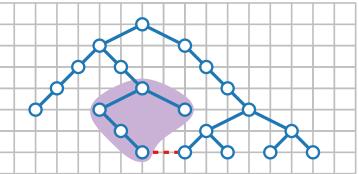
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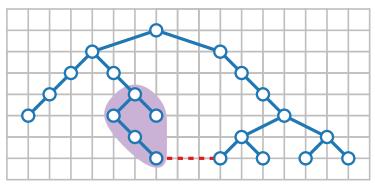
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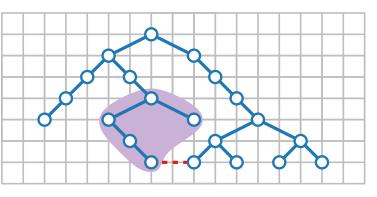
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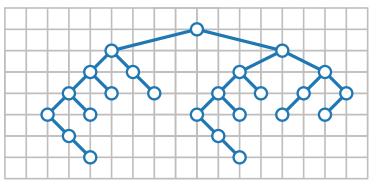
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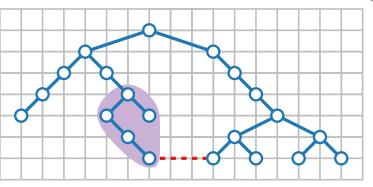
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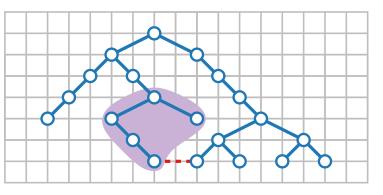
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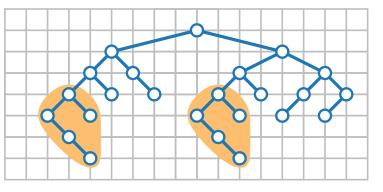
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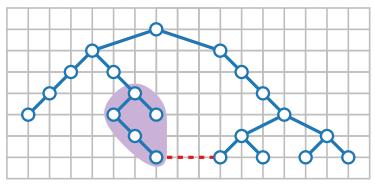
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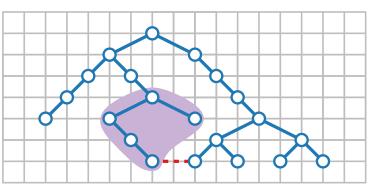
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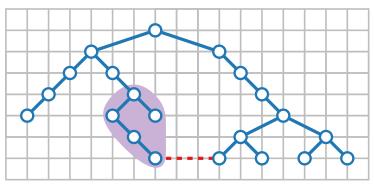
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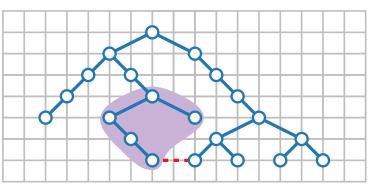
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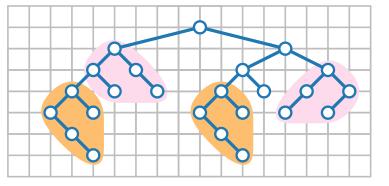
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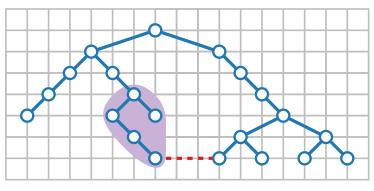
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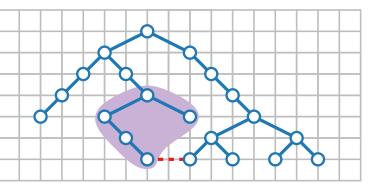
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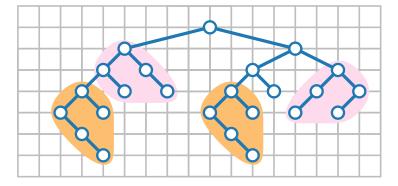
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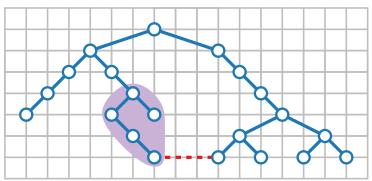
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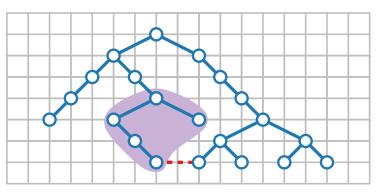
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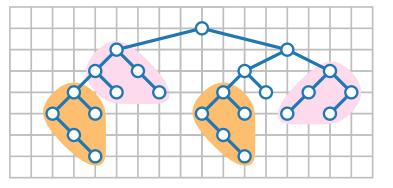
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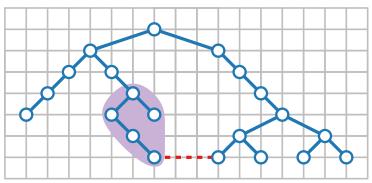
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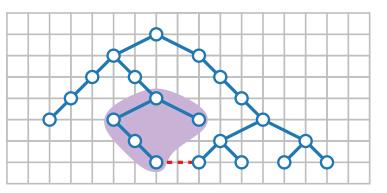
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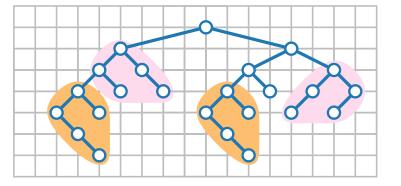
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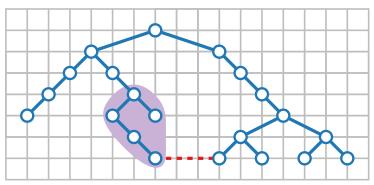
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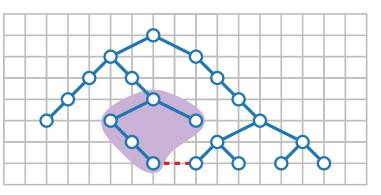
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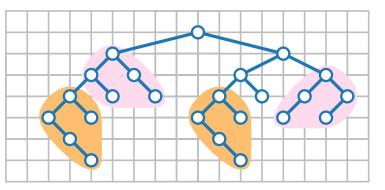
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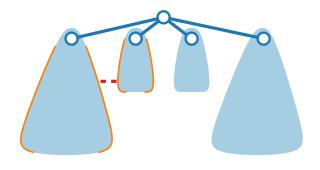
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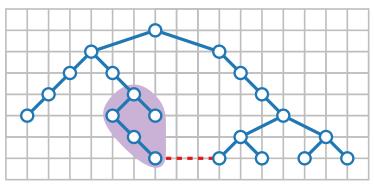
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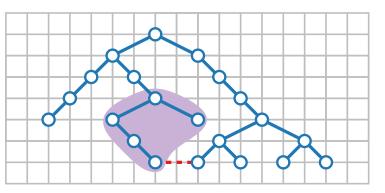
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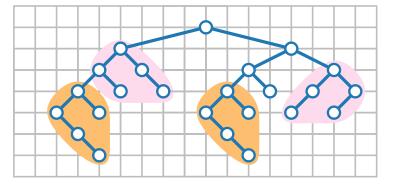
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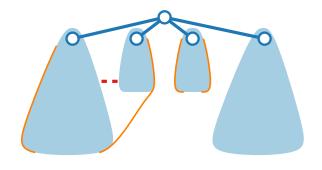
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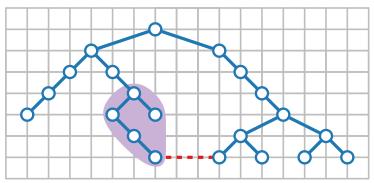
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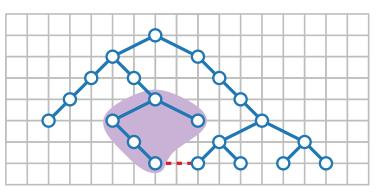
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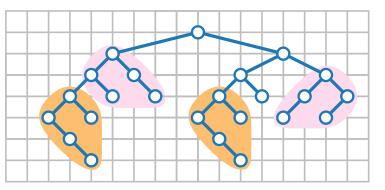
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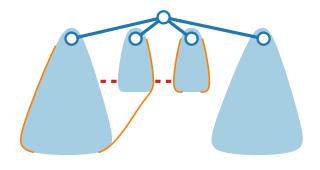
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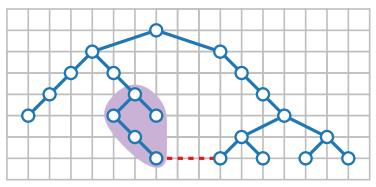
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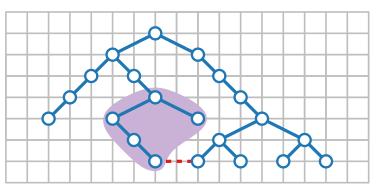
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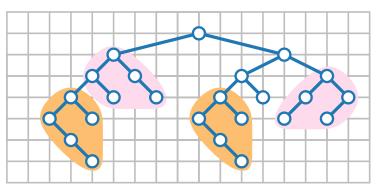
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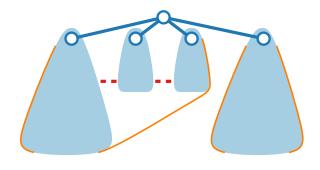
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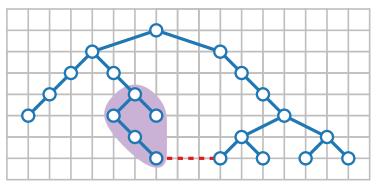
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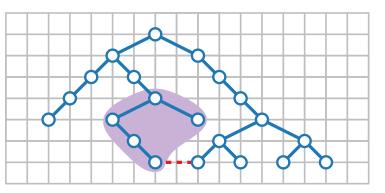
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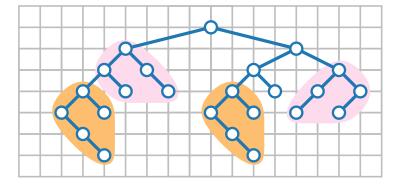
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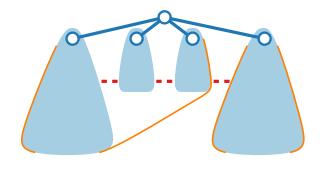
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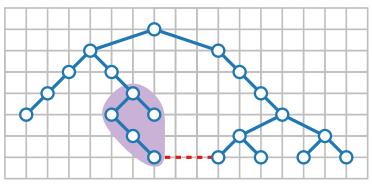
### Theorem. rooted

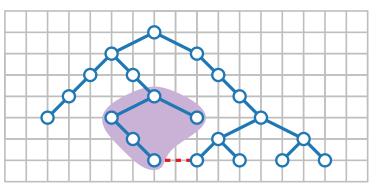
[Reingold & Tilford '81]

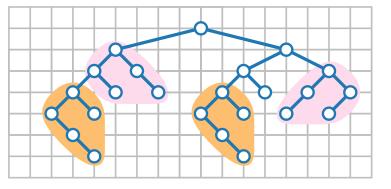
Let T be a binary tree with n vertices. We can construct a drawing  $\Gamma$  of T in  $\mathcal{O}(n)$  time, such that:

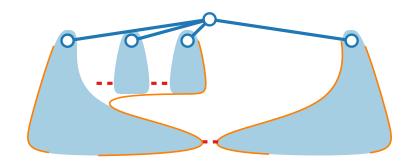
- Γ is planar, straight-line and strictly downward
- $\blacksquare$   $\Gamma$  is layered: y-coordinate of vertex v is -depth(v)
- Horizontal and Vertical distances are at least 1
- Each vertex is centred wrt its children

- Area of  $\Gamma$  is in  $\mathcal{O}(n^2)$  but not optimal!
- Simply isomorphic subtrees have congruent drawings, up to translation
- Axially isomorphic subtrees have congruent drawings, up to translation and reflection









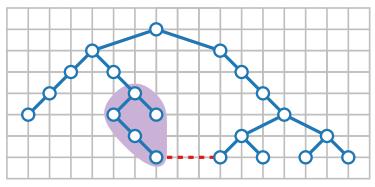
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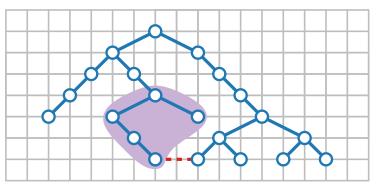
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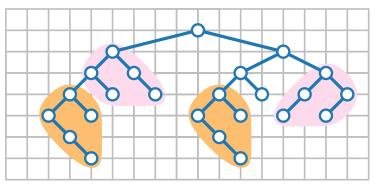
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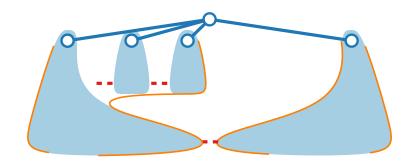
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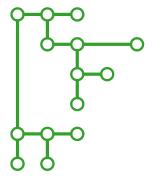




# Visualization of Graphs

Lecture 1b:

Drawing Trees and Series-Parallel Graphs

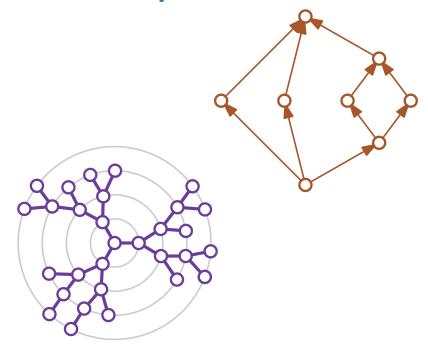


Part II:

**HV-Drawings** 



Jonathan Klawitter



### **Applications**

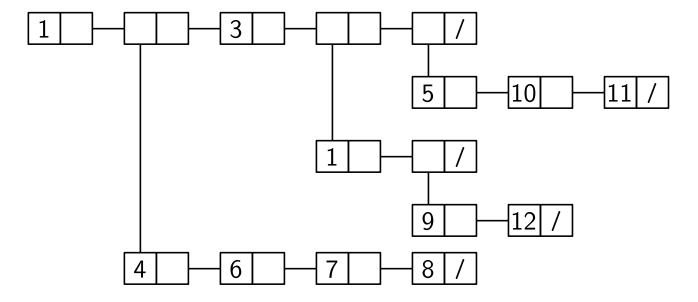
Cons cell diagram in LISP

### **Applications**

- Cons cell diagram in LISP
- Cons(constructs) are memory objects which hold two values or pointers to values

### **Applications**

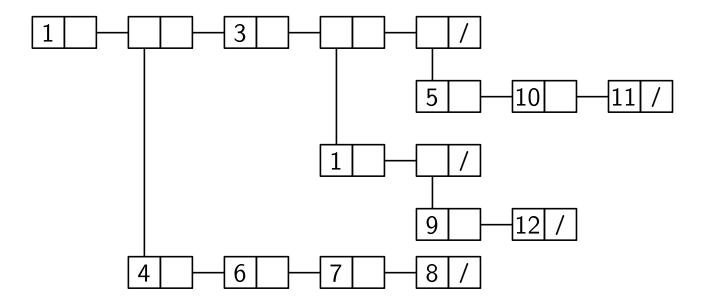
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- Cons(constructs) are memory objects which hold two values or pointers to values



Source: after gajon.org/trees-linked-lists-common-lisp/

### **Applications**

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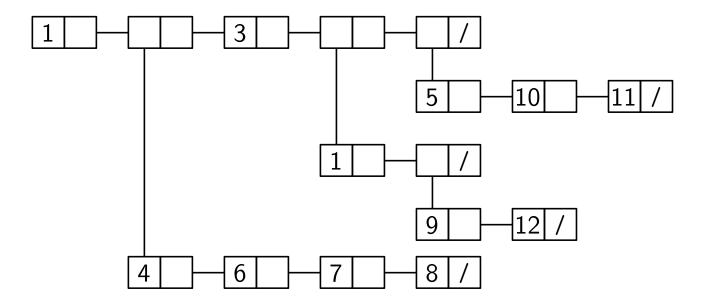


Source: after gajon.org/trees-linked-lists-common-lisp/

### **Drawing conventions**

### **Applications**

- Cons cell diagram in LISP
- Cons(constructs) are memory objects which hold two values or pointers to values



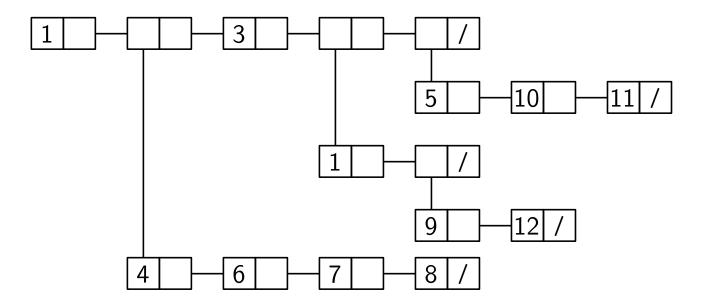
Source: after gajon.org/trees-linked-lists-common-lisp/

### **Drawing conventions**

Children are vertically or horizontally aligned with their parent

### **Applications**

- Cons cell diagram in LISP
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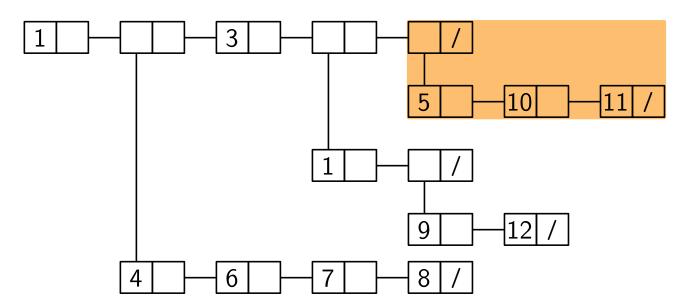
Source: after gajon.org/trees-linked-lists-common-lisp/

### **Drawing conventions**

- Children are vertically or horizontally aligned with their parent
- The bounding boxes of the subtrees of the children are disjoint

### **Applications**

- Cons cell diagram in LISP
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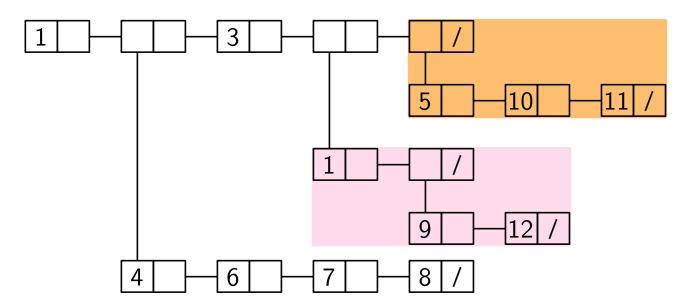
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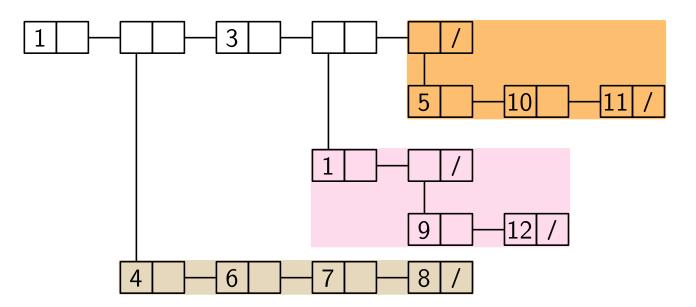
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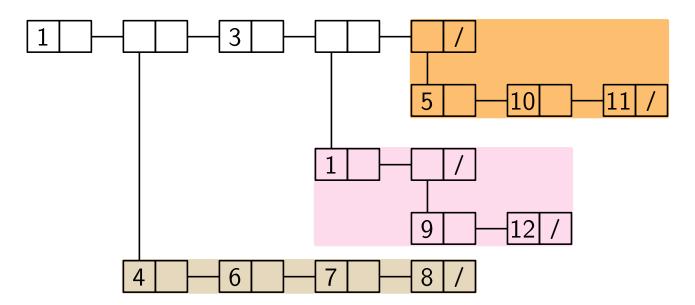
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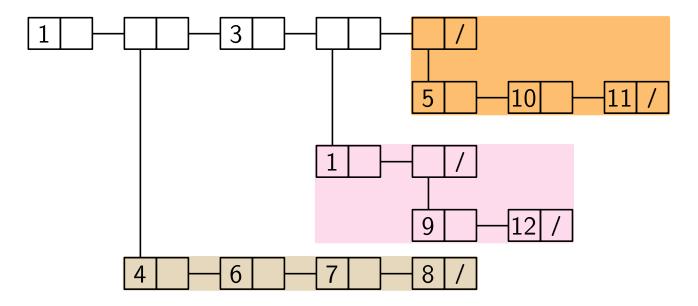
Source: after gajon.org/trees-linked-lists-common-lisp/

### **Drawing conventions**

- Children are vertically or horizontally aligned with their parent
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### **Applications**

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Source: after gajon.org/trees-linked-lists-common-lisp/

### **Drawing conventions**

- Children are vertically or horizontally aligned with their parent
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- Edges are strictly down- or rightwards

### **Drawing aesthetics**

■ Height, width, area

Input: A binary tree T

Output: An HV-drawing of T

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Base case: 9

Input: A binary tree T

Output: An HV-drawing of T

Base case: **Q** 

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees

Input: A binary tree T

Output: An HV-drawing of T

Base case: 9

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees

#### **Conquer:**



Input: A binary tree T

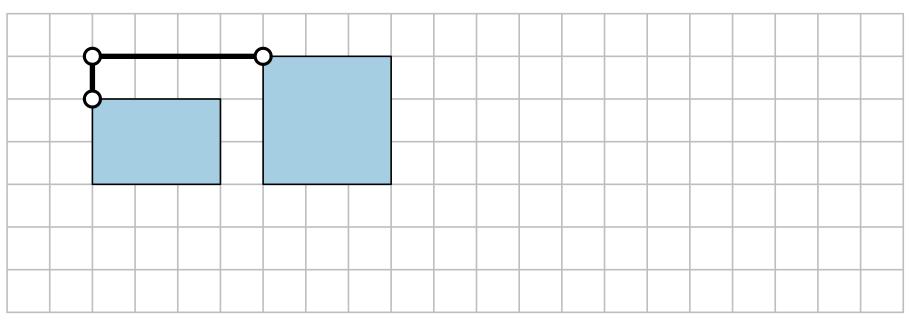
Output: An HV-drawing of T

Base case: Q

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees

**Conquer:** horizontal combination



Input: A binary tree T

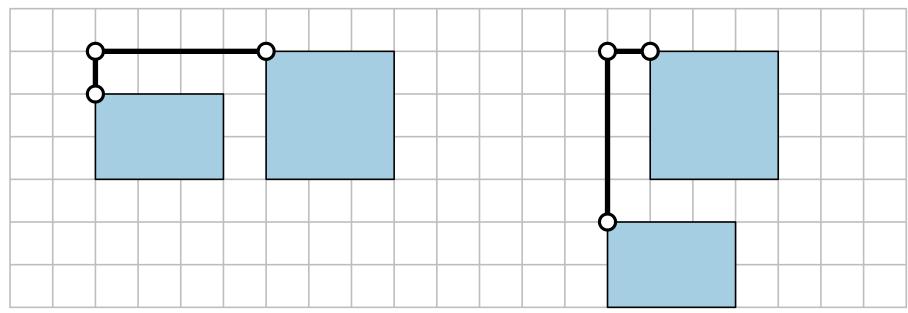
Output: An HV-drawing of T

Base case: Q

**Divide:** Recursively apply the algorithm to

draw the left and right subtrees

**Conquer:** horizontal combination vertical combination



#### Right-heavy approach

Always apply horizontal combination

- Always apply horizontal combination
- Place the larger subtree to the right

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- Place the larger subtree to the right Size of subtree := number of vertices

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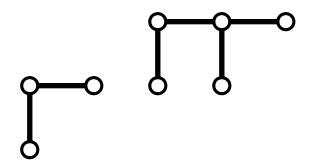
0

 $\mathsf{C}$ 

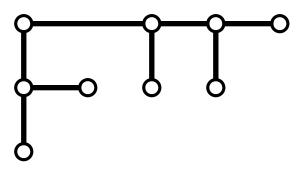
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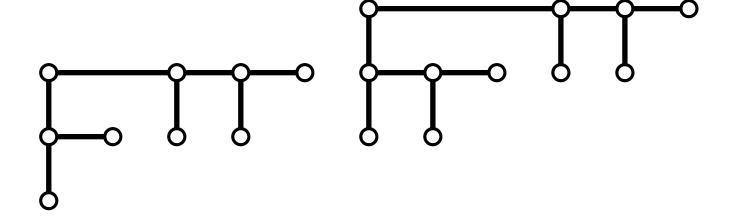
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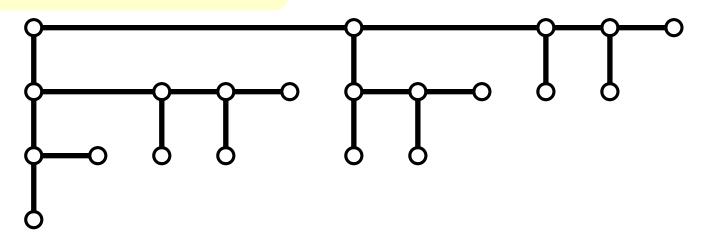
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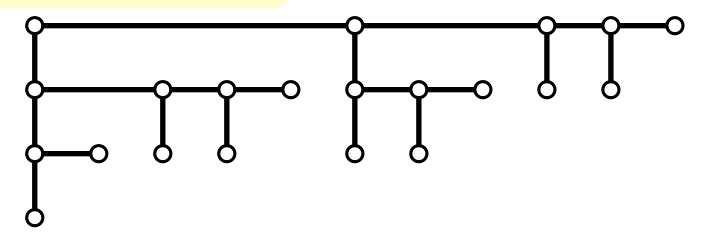


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#### Right-heavy approach

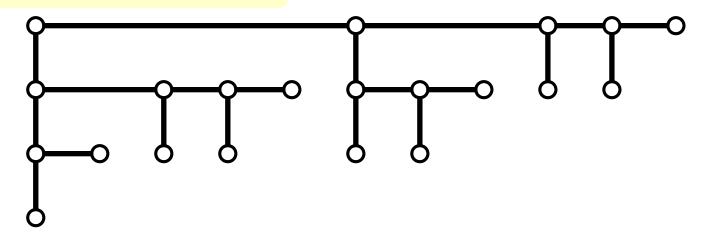
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- width at most and
- height at most

#### Right-heavy approach

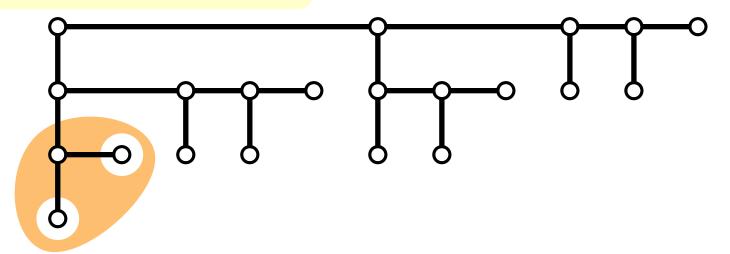
- Always apply horizontal combination
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- lacksquare width at most n-1 and
- height at most

#### Right-heavy approach

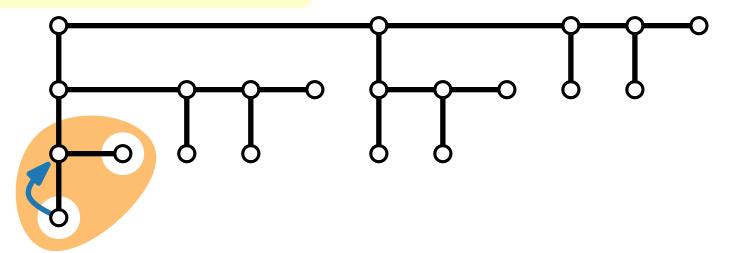
- Always apply horizontal combination
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- $\blacksquare$  width at most n-1 and
- height at most

#### Right-heavy approach

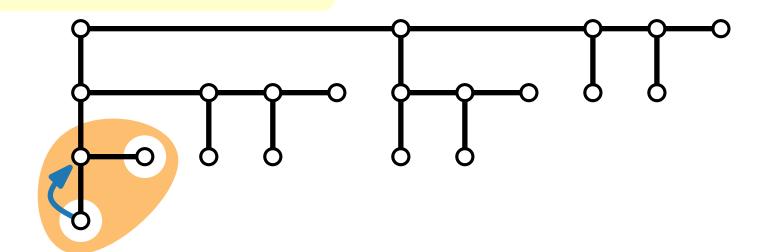
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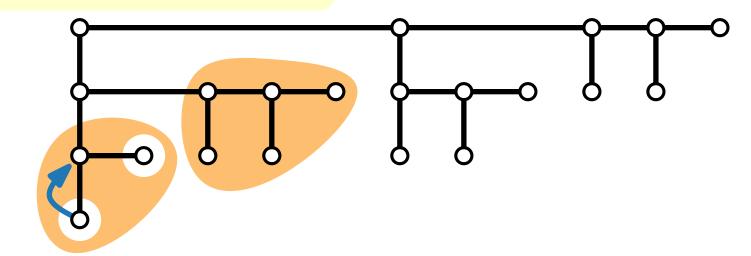


at least ·2

- lacksquare width at most n-1 and
- height at most

#### Right-heavy approach

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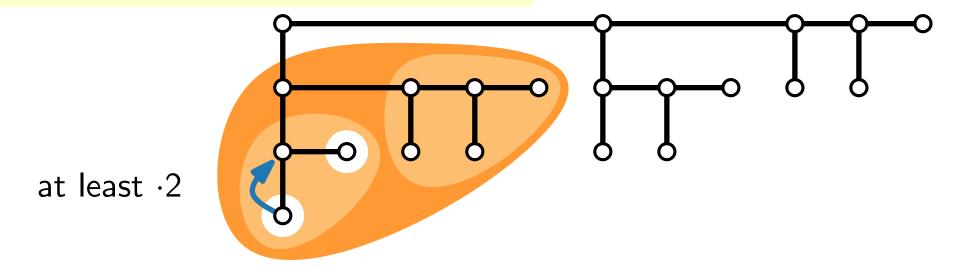


at least ·2

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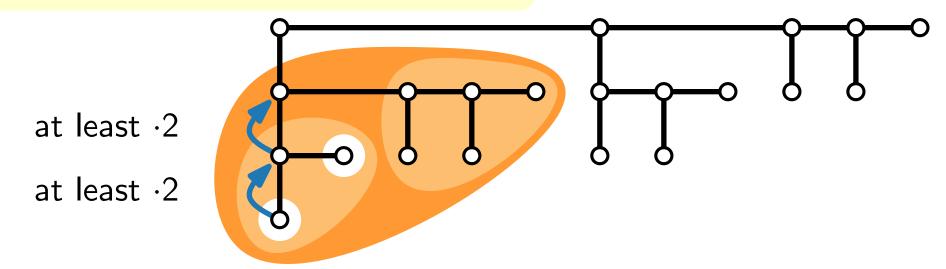
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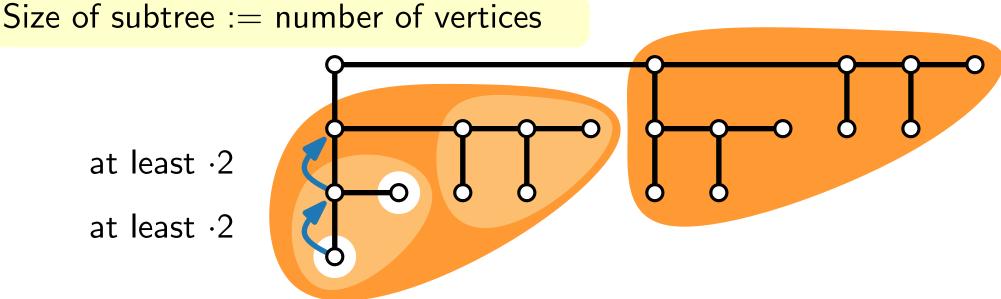
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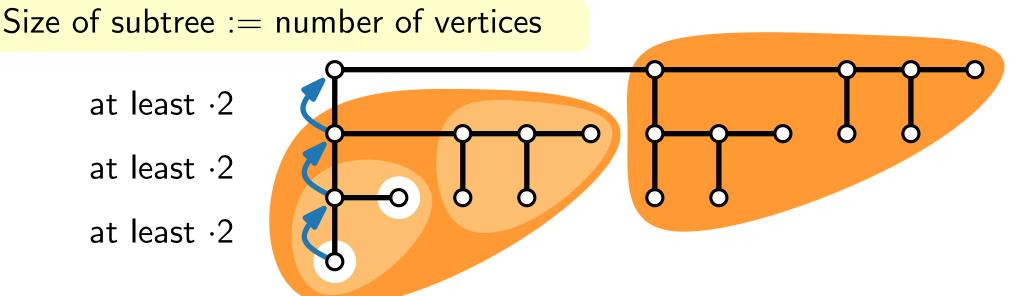
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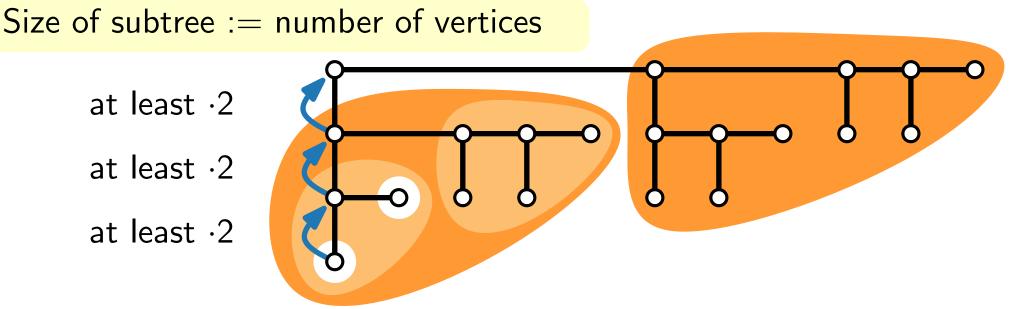
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#### Right-heavy approach

- Always apply horizontal combination
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- $\blacksquare$  width at most n-1 and
- $\blacksquare$  height at most  $\log n$ .

#### Right-heavy approach

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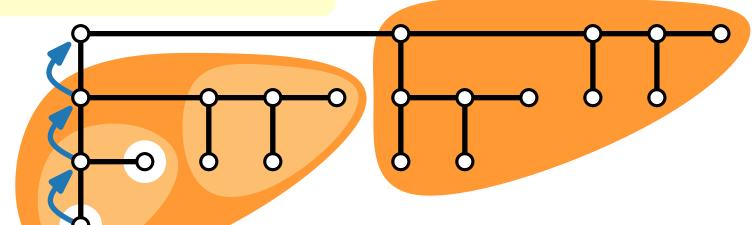
Place the larger subtree to the right

Size of subtree := number of vertices

at least ·2

at least ·2

at least ·2



Lemma. Let T be a binary tree. The drawing constructed by the right-heavy approach has

- $\blacksquare$  width at most n-1 and
- $\blacksquare$  height at most  $\log n$ .

How to implement this in linear time?

#### Theorem.

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Let T be a binary tree with n vertices. The right-heavy algorithm constructs in O(n) time a drawing  $\Gamma$  of T s.t.:

Γ is an HV-drawing (planar, orthogonal, strictly right-/downward)

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#### General rooted tree

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#### **General rooted tree**

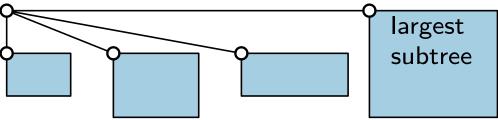
largest subtree

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#### **General rooted tree**

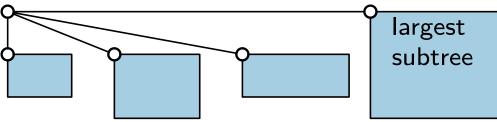


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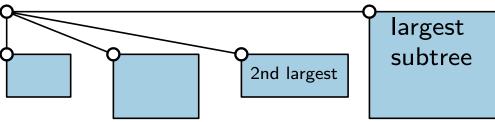


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# General rooted tree | largest | subtree |

#### **Optimal area?**

#### Theorem. rooted

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## General rooted tree | largest | subtree |

#### **Optimal area?**

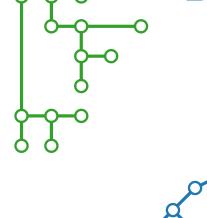
Not with divide & conquer approach, but can be computed with Dynamic Programming.



### Visualization of Graphs

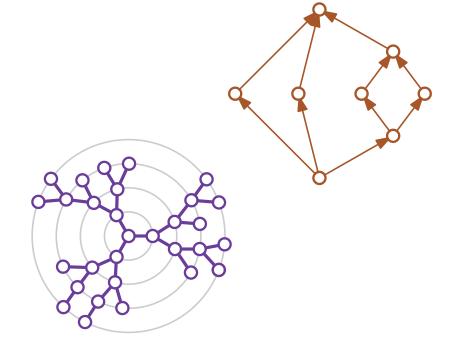
Lecture 1b:

Drawing Trees and Series-Parallel Graphs

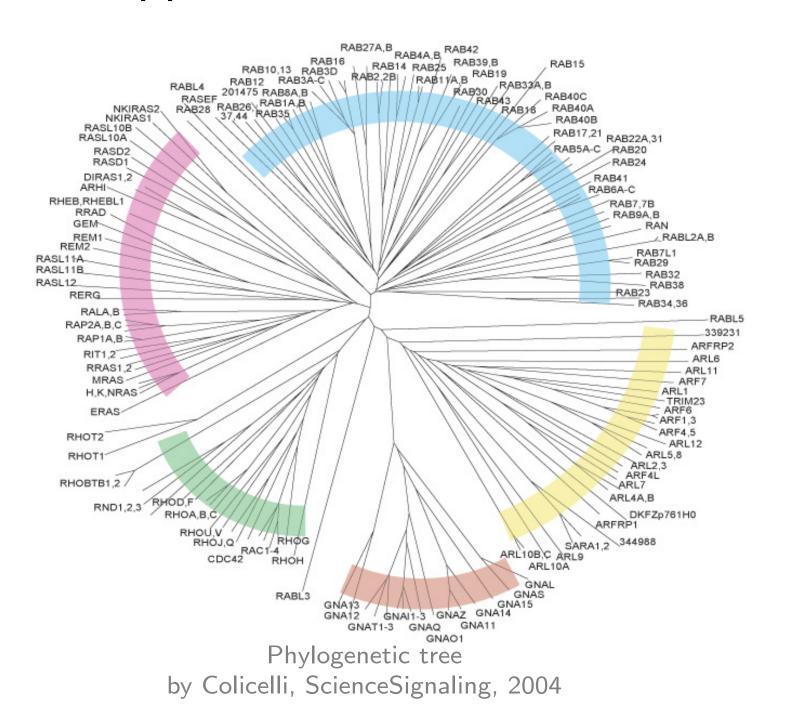


Part III: Radial Layouts

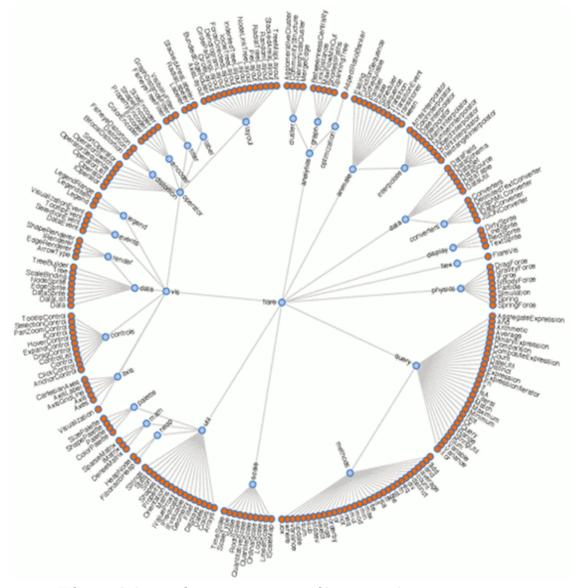
Jonathan Klawitter



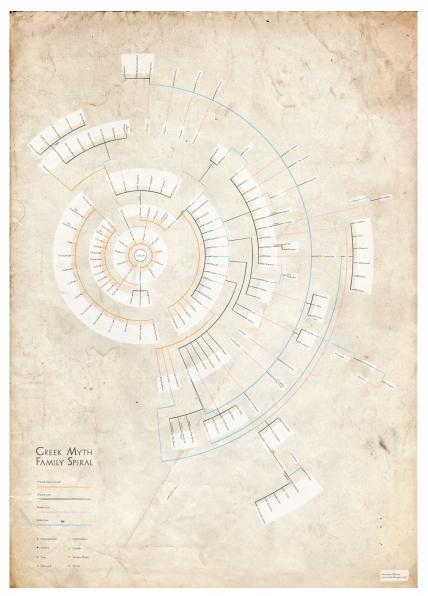
### Radial Layouts – Applications



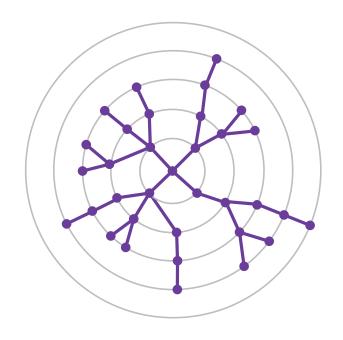
### Radial Layouts – Applications



Flare Visualization Toolkit code structure by Heer, Bostock and Ogievetsky, 2010

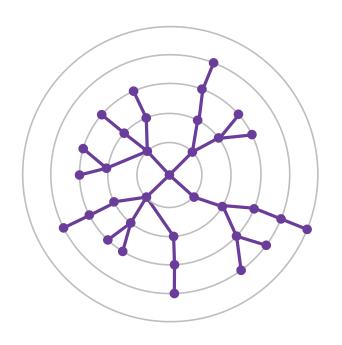


Greek Myth Family by Ribecca, 2011



**Drawing conventions** 

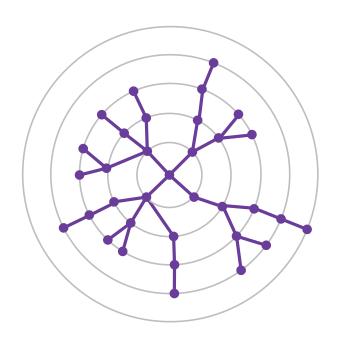
**Drawing aesthetics** 



#### **Drawing conventions**

Vertices lie on circular layers according to their depth

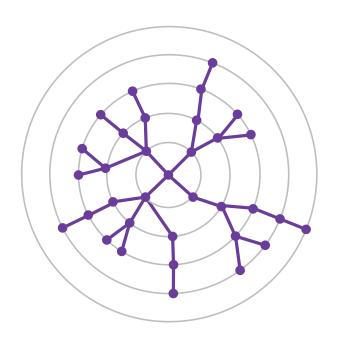
**Drawing aesthetics** 



#### **Drawing conventions**

- Vertices lie on circular layers according to their depth
- Drawing is planar

**Drawing aesthetics** 

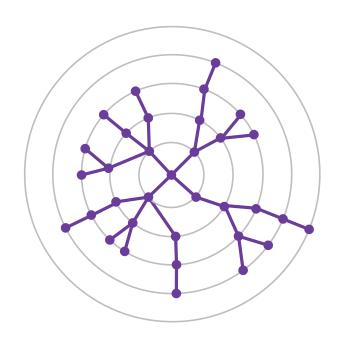


#### **Drawing conventions**

- Vertices lie on circular layers according to their depth
- Drawing is planar

#### **Drawing aesthetics**

Distribution of the vertices



#### **Drawing conventions**

- Vertices lie on circular layers according to their depth
- Drawing is planar

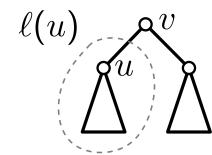
#### **Drawing aesthetics**

Distribution of the vertices

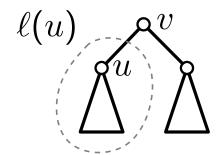
How can an algorithm optimize the distribution of the vertices?

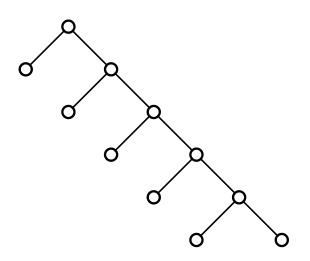
#### Idea

#### Idea

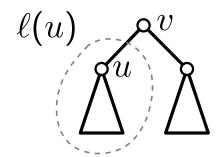


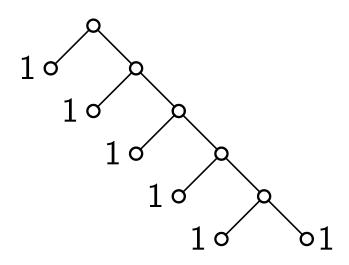
#### Idea



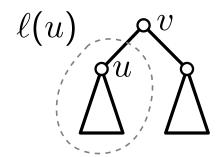


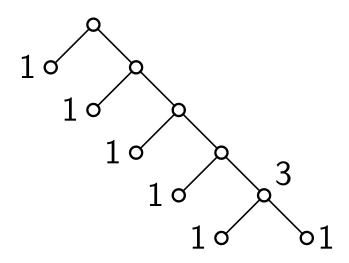
#### Idea



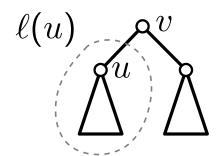


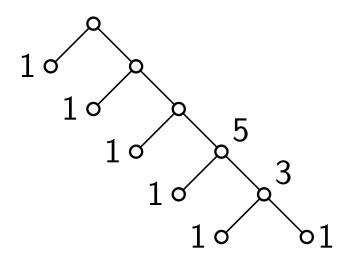
#### Idea



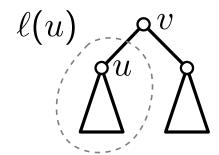


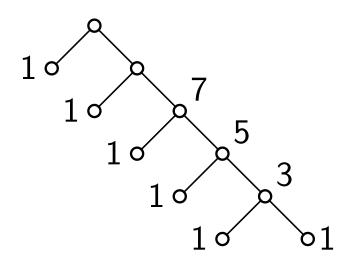
#### Idea



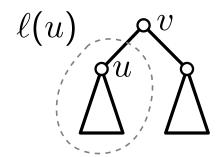


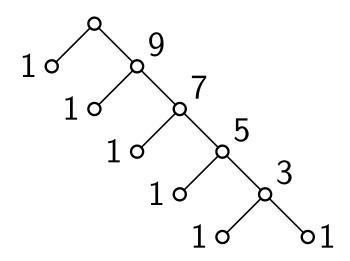
#### Idea



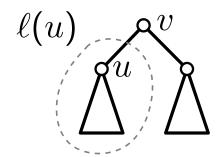


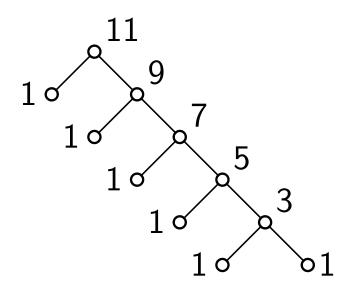
#### Idea





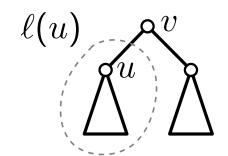
#### Idea

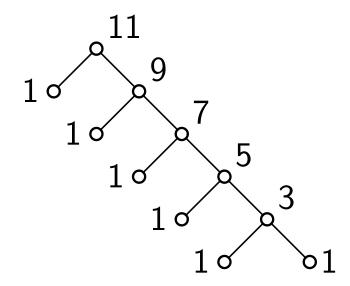




#### Idea

$$\tau_u = \frac{\ell(u)}{\ell(v) - 1}$$

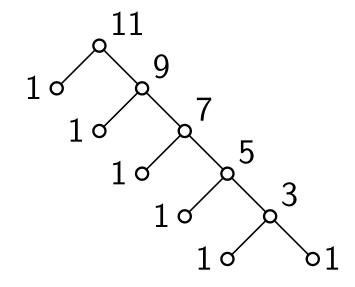


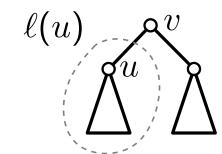


#### Idea

Reserve area corresponding to size  $\ell(u)$  of T(u):

$$\tau_u = \frac{\ell(u)}{\ell(v) - 1}$$

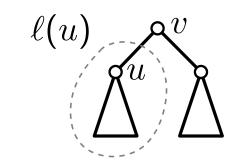


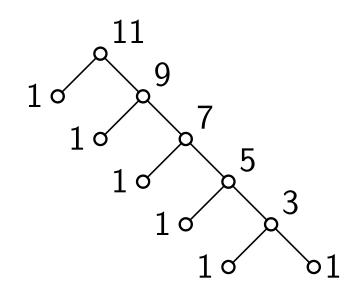


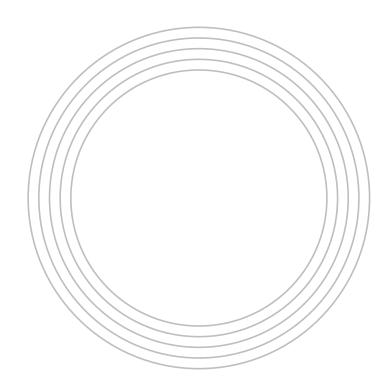
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Reserve area corresponding to size  $\ell(u)$  of T(u):

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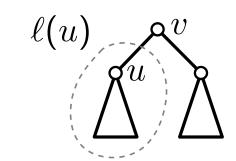


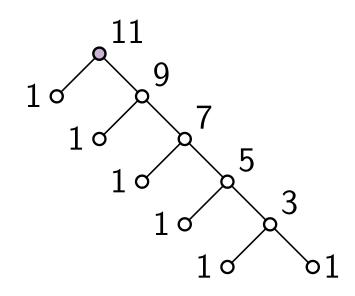


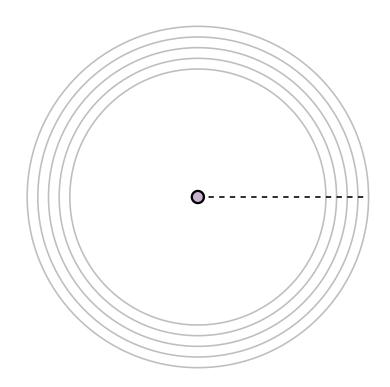
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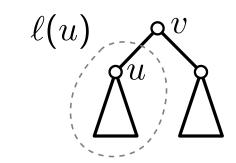


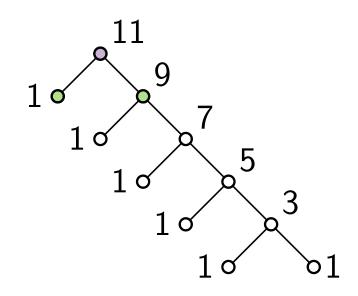


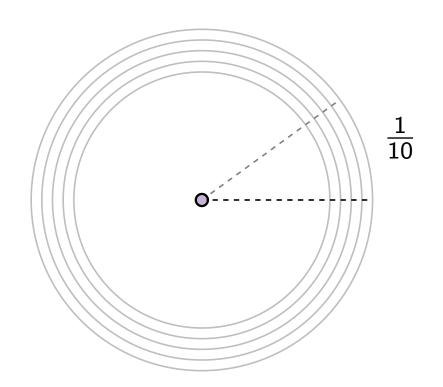
#### Idea

Reserve area corresponding to size  $\ell(u)$  of T(u):

$$au_u = rac{\ell(u)}{\ell(v) - 1}$$



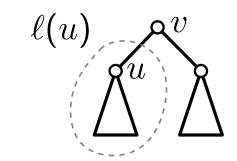


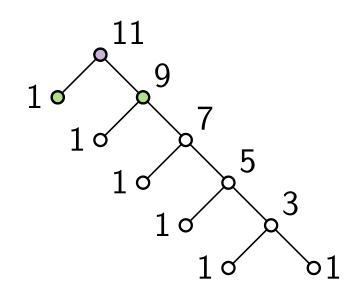


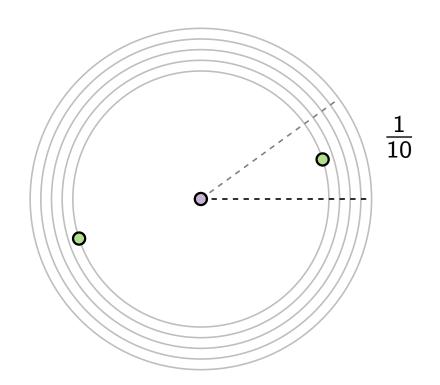
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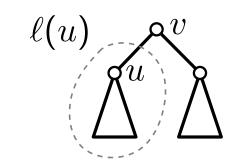


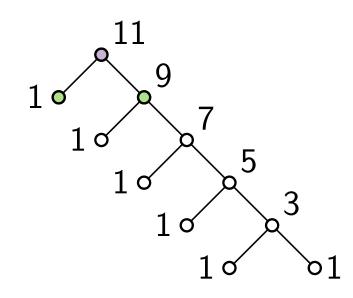


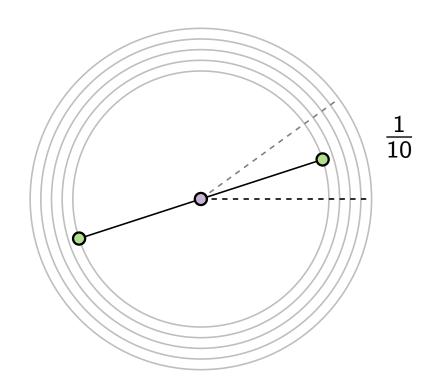
#### Idea

Reserve area corresponding to size  $\ell(u)$  of T(u):

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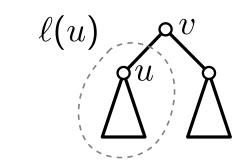


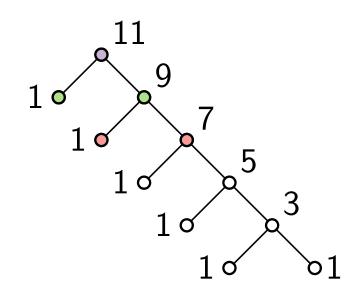


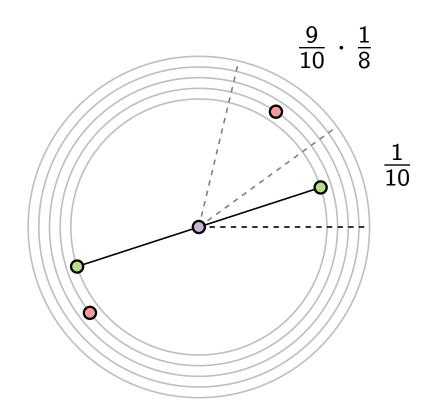
#### Idea

Reserve area corresponding to size  $\ell(u)$  of T(u):

$$au_u = rac{\ell(u)}{\ell(v) - 1}$$



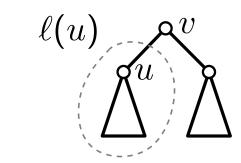


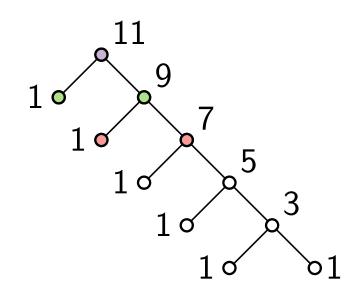


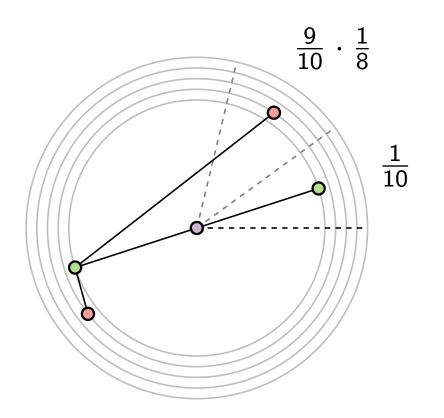
#### Idea

Reserve area corresponding to size  $\ell(u)$  of T(u):

$$au_u = rac{\ell(u)}{\ell(v) - 1}$$



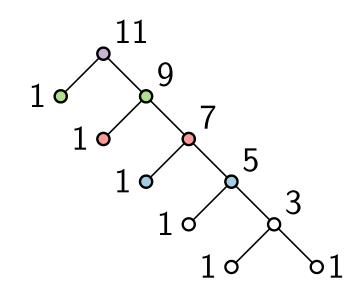


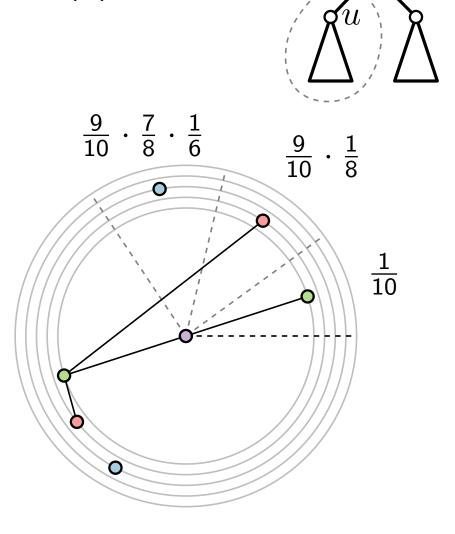


#### Idea

Reserve area corresponding to size  $\ell(u)$  of T(u):

$$au_u = rac{\ell(u)}{\ell(v) - 1}$$

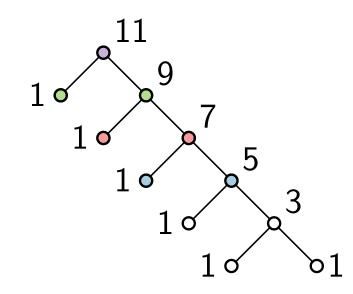


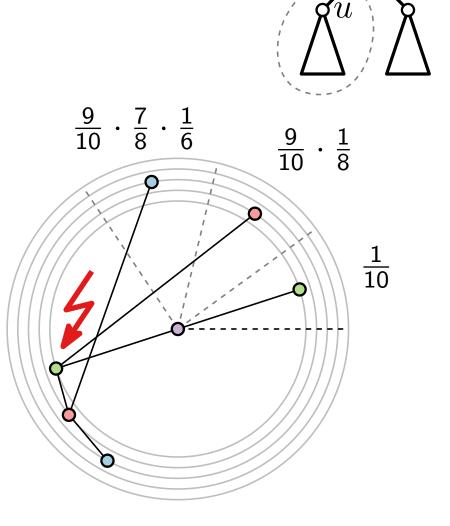


#### Idea

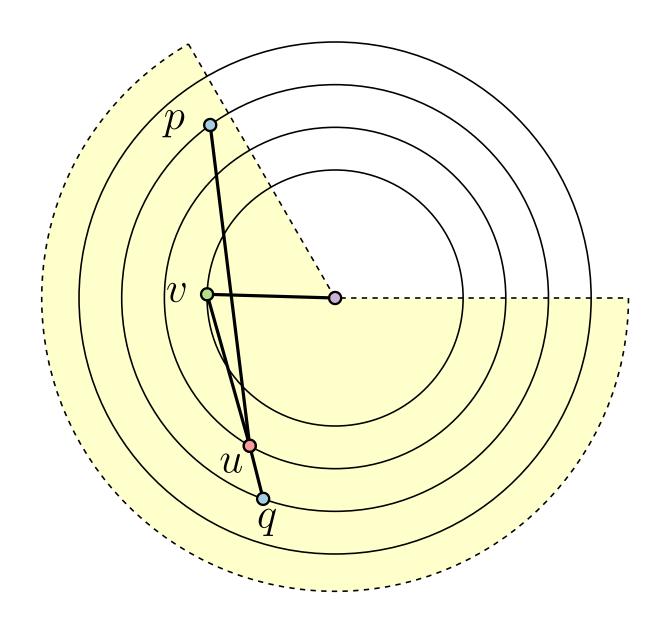
Reserve area corresponding to size  $\ell(u)$  of T(u):

$$au_u = rac{\ell(u)}{\ell(v) - 1}$$

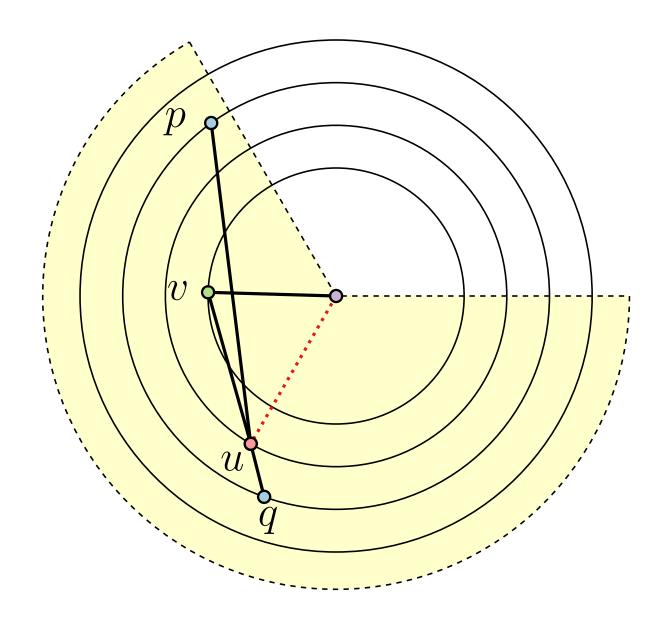




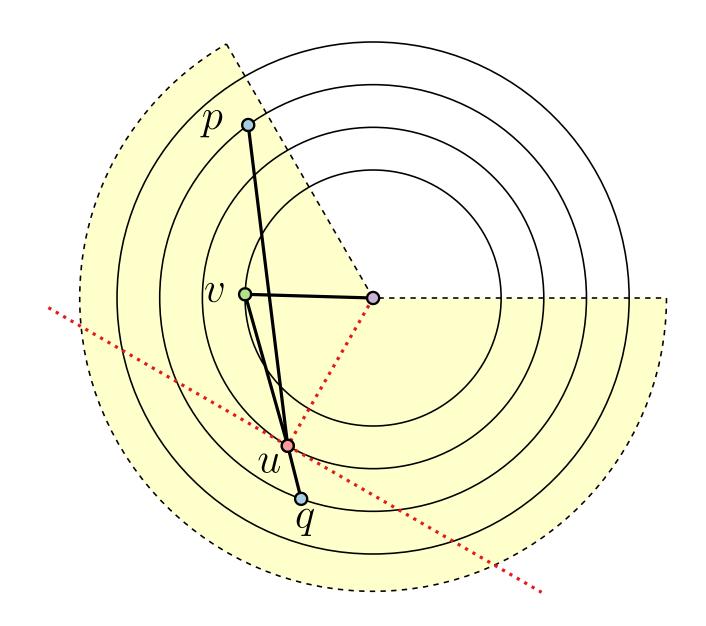
### Radial Layouts – How To Avoid Crossings

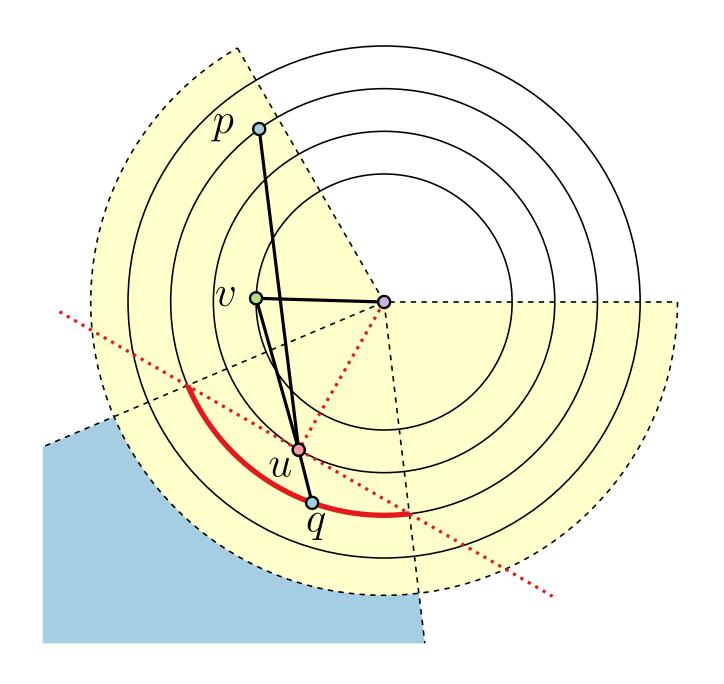


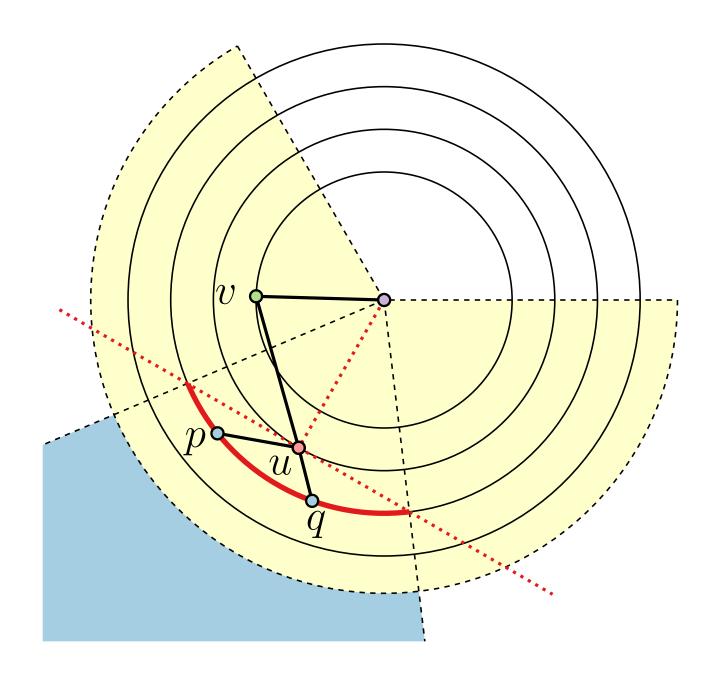
### Radial Layouts – How To Avoid Crossings

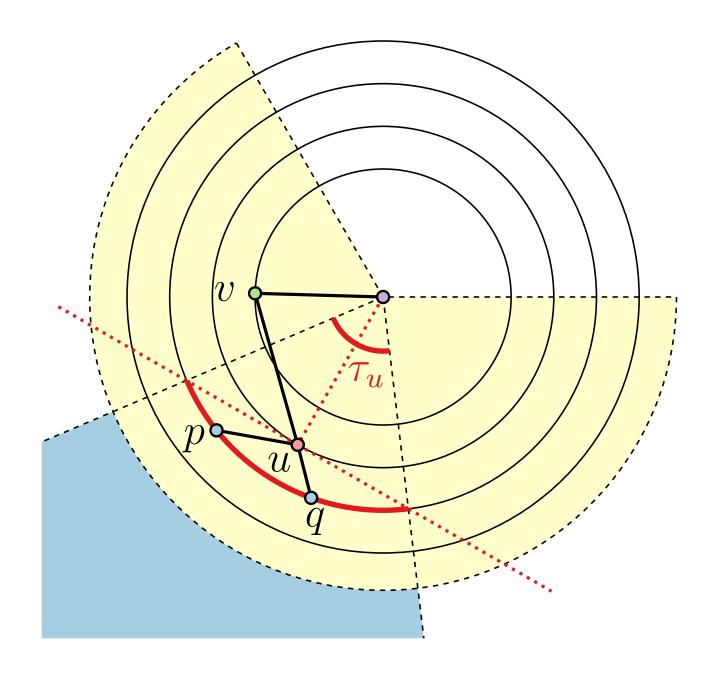


### Radial Layouts – How To Avoid Crossings

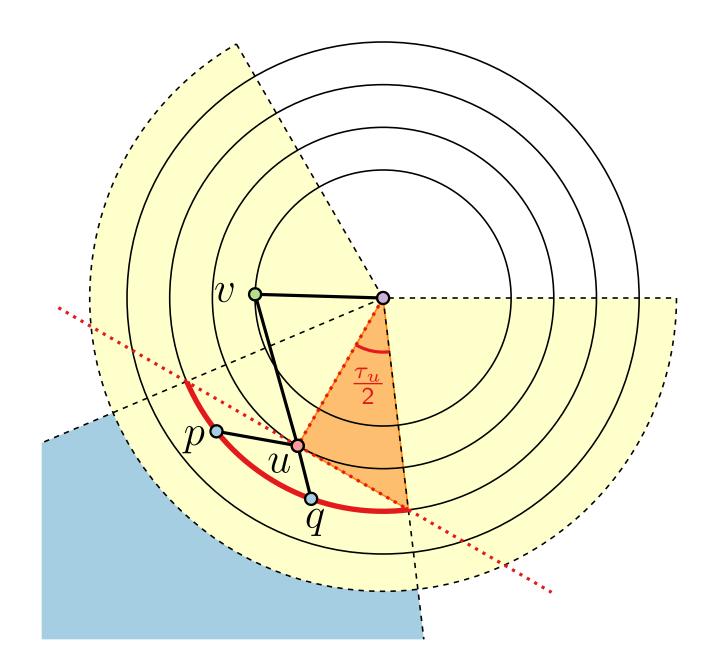




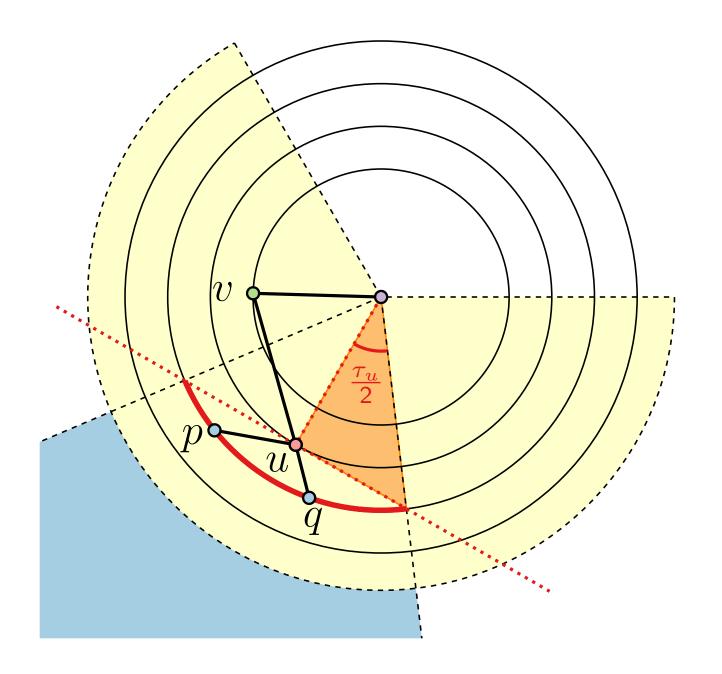




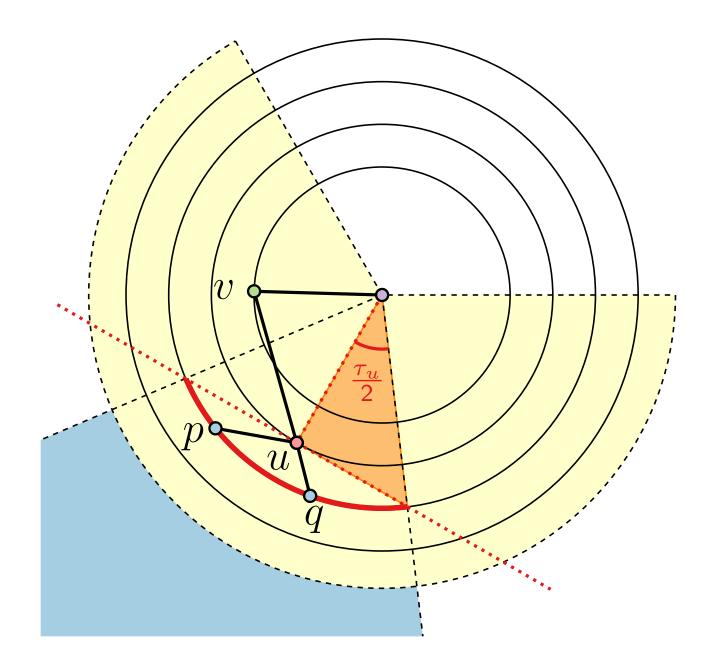
 $au_u$  — angle of the wedge corresponding to vertex u



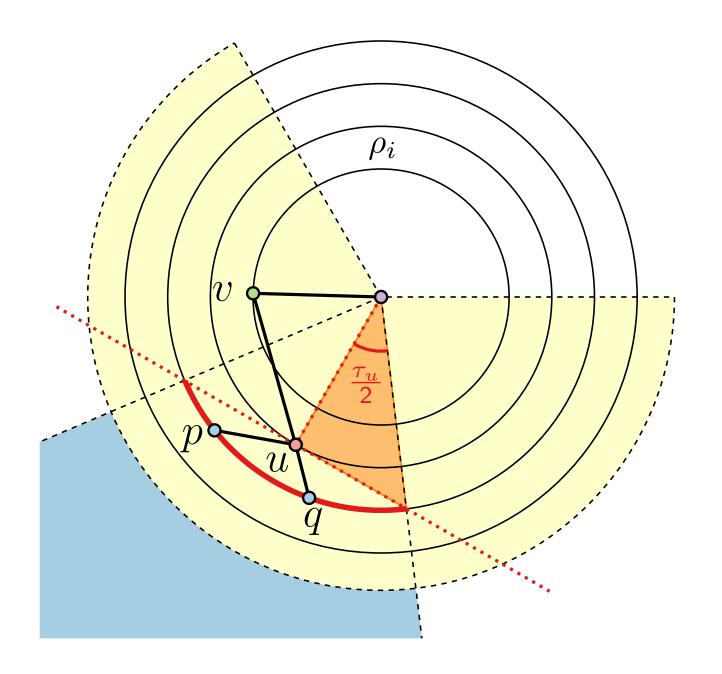
 $\tau_u$  - angle of the wedge corresponding to vertex u



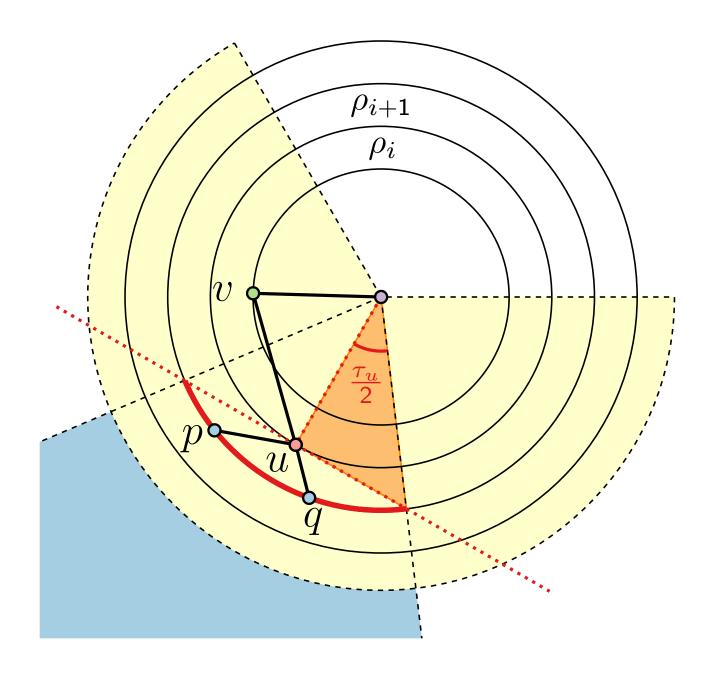
- $\tau_u$  angle of the wedge corresponding to vertex u
- $\ell(u)$  number of nodes in the subtree rooted at u



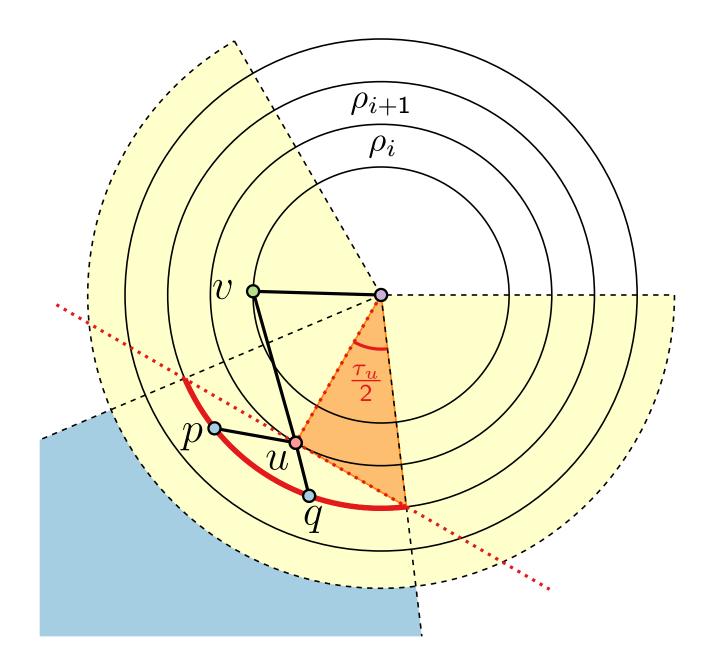
- $au_u$  angle of the wedge corresponding to vertex u
- $\ell(u)$  number of nodes in the subtree rooted at u
- $ho_i$  radius of layer i



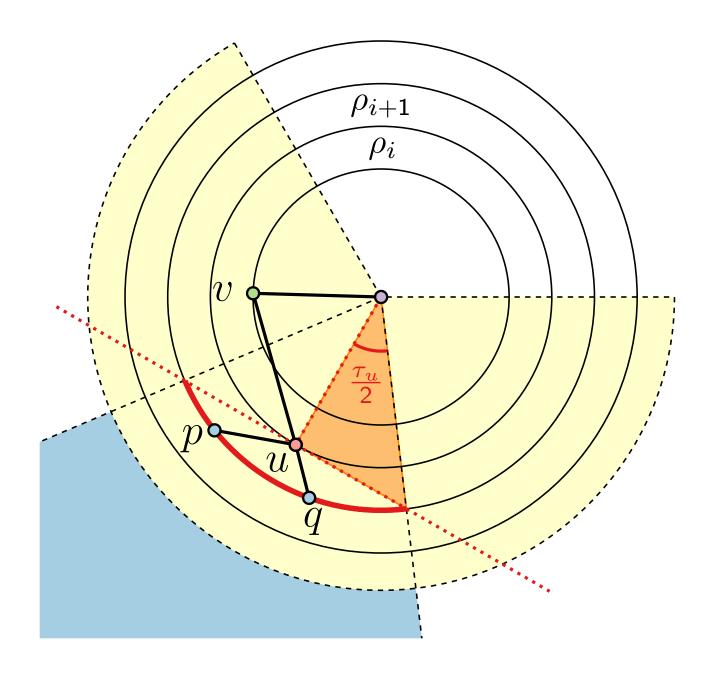
- $au_u$  angle of the wedge corresponding to vertex u
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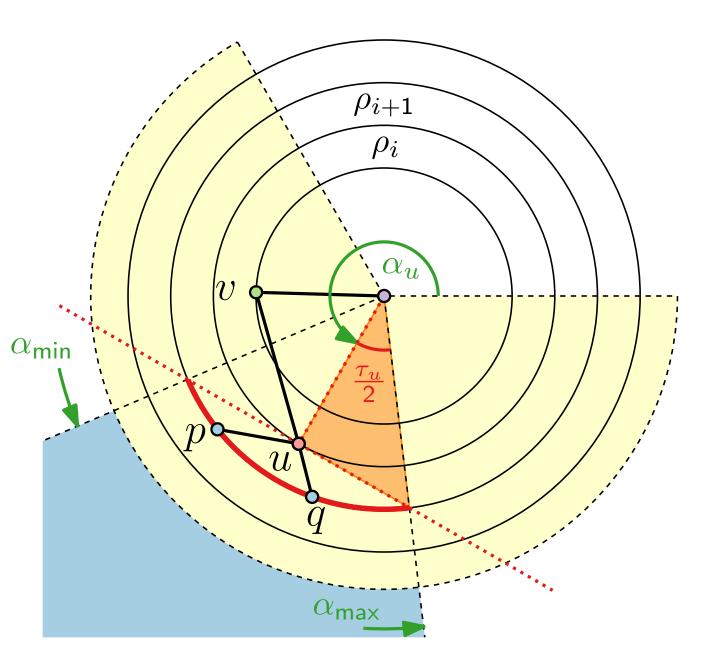
- $\tau_u$  angle of the wedge corresponding to vertex u
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- $au_u$  angle of the wedge corresponding to vertex u
- $\ell(u)$  number of nodes in the subtree rooted at u
- $ightharpoonup 
  ho_i$  radius of layer i
- $\cos \frac{ au_u}{2} = rac{
  ho_i}{
  ho_{i+1}}$



- $au_u$  angle of the wedge corresponding to vertex u
- $\ell(u)$  number of nodes in the subtree rooted at u
- $ightharpoonup 
  ho_i$  radius of layer i
- lacksquare  $\cos rac{ au_u}{2} = rac{
  ho_i}{
  ho_{i+1}}$
- $au_u = \min\{\frac{\ell(u)}{\ell(v)-1}, 2\arccos\frac{\rho_i}{\rho_{i+1}}\}$



- $au_u$  angle of the wedge corresponding to vertex u
- $\ell(u)$  number of nodes in the subtree rooted at u
- $ightharpoonup 
  ho_i$  radius of layer i

$$lacksquare$$
  $\cos rac{ au_u}{2} = rac{
ho_i}{
ho_{i+1}}$ 

- $au_u = \min\{\frac{\ell(u)}{\ell(v)-1}, 2\arccos\frac{\rho_i}{\rho_{i+1}}\}$
- Alternative:

$$\alpha_{\min} = \alpha_u - \arccos \frac{\rho_i}{\rho_{i+1}}$$

$$\alpha_{\max} = \alpha_u + \arccos \frac{\rho_i}{\rho_{i+1}}$$

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

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// vertex pos./polar coord.
```

```
 \begin{array}{c|c} \mathsf{postorder}(\mathsf{vertex}\ v) \\ \hline & \ell(v) \leftarrow 1 \\ & \mathbf{foreach}\ \mathsf{child}\ w\ \mathsf{of}\ v\ \mathbf{do} \\ \hline & postorder(w) \\ \hline & \ell(v) \leftarrow \ell(v) + \ell(w) \end{array}
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)
begin
   postorder(r)
   preorder(r, 0, 0, 2\pi)
   return (d_v, \alpha_v)_{v \in V(T)}
    // vertex pos./polar coord.
postorder(vertex v)
   \ell(v) \leftarrow 1
   foreach child w of v do
       postorder(w)
      \ell(v) \leftarrow \ell(v) + \ell(w)
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)
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RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

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postorder(vertex v)
 \ell(v) \leftarrow 1
foreach child w of v do
 postorder(w)
 \ell(v) \leftarrow \ell(v) + \ell(w)
```

preorder(vertex v, t,  $\alpha_{\min}$ ,  $\alpha_{\max}$ )  $d_v \leftarrow \rho_t$   $\alpha_v \leftarrow (\alpha_{\min} + \alpha_{\max})/2$ 

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)
                                                                                       preorder(vertex v, t, \alpha_{\sf min}, \alpha_{\sf max})
                                                                                           d_v \leftarrow \rho_t
\alpha_v \leftarrow (\alpha_{\min} + \alpha_{\max})/2
begin
    postorder(r)
    preorder(r, 0, 0, 2\pi)
    return (d_v, \alpha_v)_{v \in V(T)}
   // vertex pos./polar coord.
postorder(vertex v)
    \ell(v) \leftarrow 1
    foreach child w of v do
       postorder(w)
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```

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RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)
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   postorder(r)
   preorder(r, 0, 0, 2\pi)
   return (d_v, \alpha_v)_{v \in V(T)}
  // vertex pos./polar coord.
postorder(vertex v)
   \ell(v) \leftarrow 1
   foreach child w of v do
     postorder(w)
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
    d_v \leftarrow \rho_t
\alpha_v \leftarrow (\alpha_{\min} + \alpha_{\max})/2
                                                            //output
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)
begin
   postorder(r)
   preorder(r, 0, 0, 2\pi)
   return (d_v, \alpha_v)_{v \in V(T)}
   // vertex pos./polar coord.
postorder(vertex v)
   \ell(v) \leftarrow 1
   foreach child w of v do
      postorder(w)
      \ell(v) \leftarrow \ell(v) + \ell(w)
```

```
preorder(vertex v, t, lpha_{\sf min}, lpha_{\sf max})
                                                      //output
    \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
     if t > 0 then
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
```

```
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 0
\ell(v) \leftarrow \ell(v) \leftarrow \ell(v)
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                               //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
           \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
         \alpha_{\max} \leftarrow \min\{\alpha_{\max}, \alpha_v + \arccos\frac{\rho_t}{\rho_{t+1}}\}
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

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return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
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```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                                      //output
      \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
       if t > 0 then
             \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
           \alpha_{\mathsf{max}} \leftarrow \mathsf{min}\{\alpha_{\mathsf{max}}, \alpha_v + \mathsf{arccos}\,\frac{\rho_t}{\rho_{t+1}}\}
       left \leftarrow \alpha_{\min}
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                                //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
            \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
          \alpha_{\mathsf{max}} \leftarrow \mathsf{min}\{\alpha_{\mathsf{max}}, \alpha_v + \mathsf{arccos}\,\frac{\rho_t}{\rho_{t+1}}\}
      left \leftarrow \alpha_{\min}
      foreach child w of v do
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
```

```
preorder(vertex v, t, \alpha_{\sf min}, \alpha_{\sf max})
                                                                    //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
            \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
          \alpha_{\mathsf{max}} \leftarrow \mathsf{min}\{\alpha_{\mathsf{max}}, \alpha_v + \mathsf{arccos}\,\frac{\rho_t}{\rho_{t+1}}\}
       left \leftarrow \alpha_{\min}
       foreach child w of v do
            right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\mathsf{max}} - \alpha_{\mathsf{min}})
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
```

```
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 0
\ell(v) \leftarrow 0
\ell(v) \leftarrow \ell(v) \leftarrow \ell(v)
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                           //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
           \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
         \alpha_{\max} \leftarrow \min\{\alpha_{\max}, \alpha_v + \arccos\frac{\rho_t}{\rho_{t+1}}\}
      left \leftarrow \alpha_{\min}
      foreach child w of v do
           right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\mathsf{max}} - \alpha_{\mathsf{min}})
          preorder(w, t + 1, left, right)
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                          //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
           \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
         \alpha_{\max} \leftarrow \min\{\alpha_{\max}, \alpha_v + \arccos\frac{\rho_t}{\rho_{t+1}}\}
     left \leftarrow \alpha_{\min}
     foreach child w of v do
           right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\mathsf{max}} - \alpha_{\mathsf{min}})
          preorder(w, t + 1, left, right)
           left \leftarrow right
```

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

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// vertex pos./polar coord.
```

```
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 0
\ell(v) \leftarrow 0
\ell(v) \leftarrow \ell(v) \leftarrow \ell(v)
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                           //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
           \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
         \alpha_{\max} \leftarrow \min\{\alpha_{\max}, \alpha_v + \arccos\frac{\rho_t}{\rho_{t+1}}\}
     left \leftarrow \alpha_{\min}
     foreach child w of v do
           right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\mathsf{max}} - \alpha_{\mathsf{min}})
          preorder(w, t + 1, left, right)
            left \leftarrow right
```

Runtime?

//output

#### Radial Layouts — Pseudocode

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)
begin
   postorder(r)
   preorder(r, 0, 0, 2\pi)
   return (d_v, \alpha_v)_{v \in V(T)}
  // vertex pos./polar coord.
```

```
postorder(vertex v)
   \ell(v) \leftarrow 1
   foreach child w of v do
      postorder(w)
     \ell(v) \leftarrow \ell(v) + \ell(w)
```

```
\alpha_{\mathsf{max}} \leftarrow \mathsf{min}\{\alpha_{\mathsf{max}}, \alpha_v + \mathsf{arccos}\,\frac{\rho_t}{\rho_{t+1}}\}
left \leftarrow \alpha_{\min}
foreach child w of v do
     right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\mathsf{max}} - \alpha_{\mathsf{min}})
    preorder(w, t + 1, left, right)
      left \leftarrow right
```

preorder(vertex v,  $t, \alpha_{\sf min}, \alpha_{\sf max}$ )

 $\alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}$ 

 $\alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2$ 

if t > 0 then

Runtime?  $\mathcal{O}(n)$ 

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

preorder(r, 0, 0, 2\pi)

return (d_v, \alpha_v)_{v \in V(T)}

// vertex pos./polar coord.
```

```
\ell(v) \leftarrow 1 \ell(v) \leftarrow 1 foreach child w of v do \ell(v) \leftarrow \ell(v) \leftarrow \ell(v)
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                            //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
           \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
         \alpha_{\mathsf{max}} \leftarrow \mathsf{min}\{\alpha_{\mathsf{max}}, \alpha_v + \mathsf{arccos}\,\frac{\rho_t}{\rho_{t+1}}\}
      left \leftarrow \alpha_{\min}
      foreach child w of v do
           right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\mathsf{max}} - \alpha_{\mathsf{min}})
          preorder(w, t + 1, left, right)
            left \leftarrow right
```

Runtime?  $\mathcal{O}(n)$ Correctness?

```
RadialTreeLayout(tree T, root r \in T, radii \rho_1 < \cdots < \rho_k)

begin

postorder(r)

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return (d_v, \alpha_v)_{v \in V(T)}

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```

```
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 1
\ell(v) \leftarrow 0
\ell(v) \leftarrow 0
\ell(v) \leftarrow \ell(v) \leftarrow \ell(v)
```

```
preorder(vertex v, t, \alpha_{\min}, \alpha_{\max})
                                                         //output
     \alpha_v \leftarrow (\alpha_{\mathsf{min}} + \alpha_{\mathsf{max}})/2
      if t > 0 then
           \alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos\frac{\rho_t}{\rho_{t+1}}\}
        \alpha_{\mathsf{max}} \leftarrow \mathsf{min}\{\alpha_{\mathsf{max}}, \alpha_v + \mathsf{arccos}\,\frac{\rho_t}{\rho_{t+1}}\}
      left \leftarrow \alpha_{\min}
      foreach child w of v do
           right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\mathsf{max}} - \alpha_{\mathsf{min}})
          preorder(w, t + 1, left, right)
            left \leftarrow right
```

Runtime?  $\mathcal{O}(n)$ Correctness?

#### Theorem.

Let T be a tree with n vertices. The RadialTreeLayout algorithm constructs in O(n) time a drawing  $\Gamma$  of T s.t.:

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Γ is radial drawing

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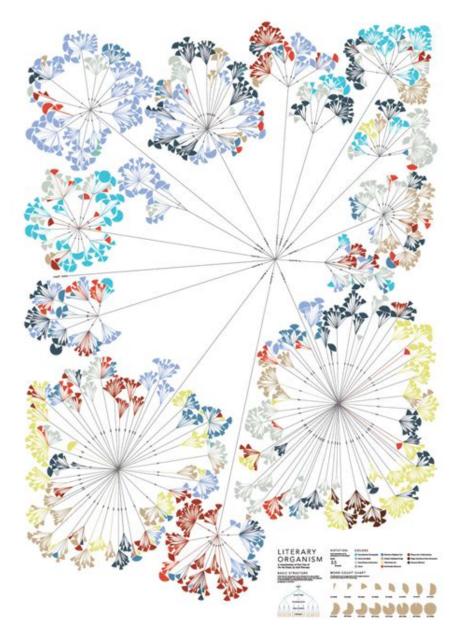
- Γ is radial drawing
- Vertices lie on circle according to their depth

#### Theorem.

Let T be a tree with n vertices. The RadialTreeLayout algorithm constructs in O(n) time a drawing  $\Gamma$  of T s.t.:

- Γ is radial drawing
- Vertices lie on circle according to their depth
- Area quadratic in max degree times height of T (see [GD Ch. 3.1.3] if interested)

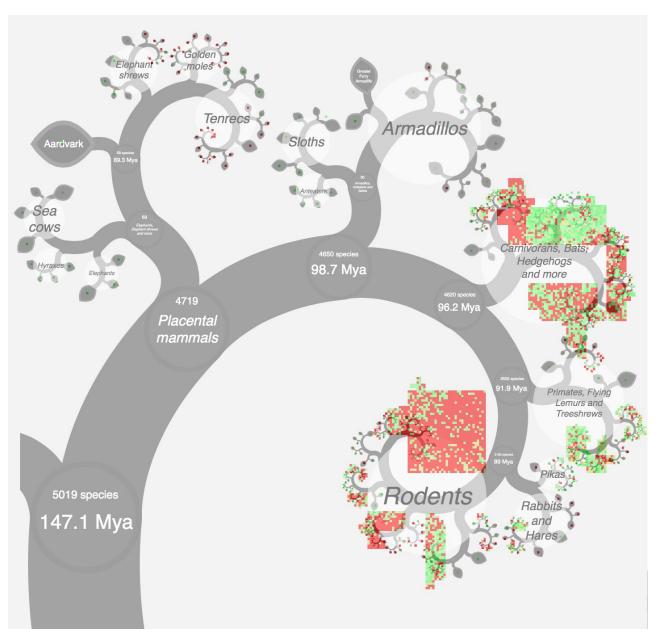
# Other tree visualisation styles



Writing Without Words:
The project explores methods to visualises the differences in writing styles of different authors.

Similar to ballon layout

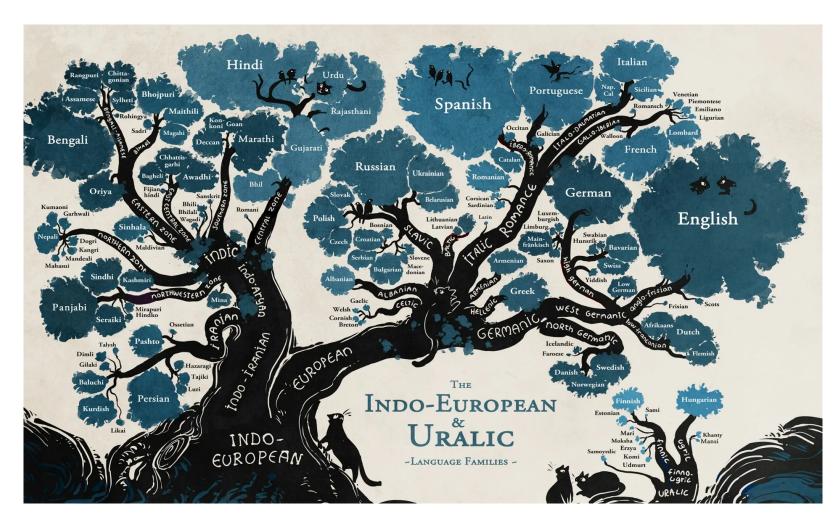
# Other tree visualisation styles



A phylogenetically organised display of data for all placental mammal species.

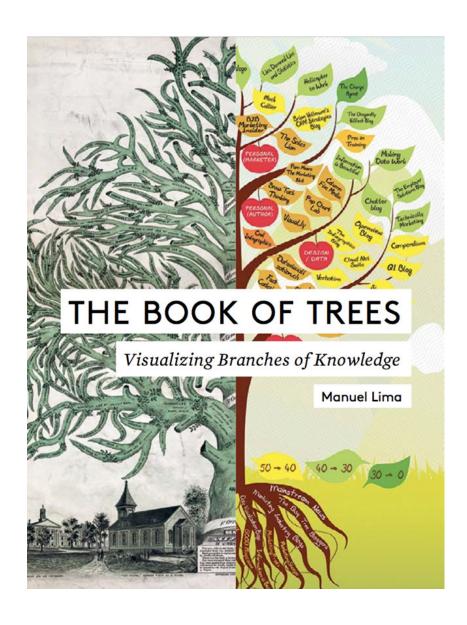
Fractal layout

# Other tree visualisation styles

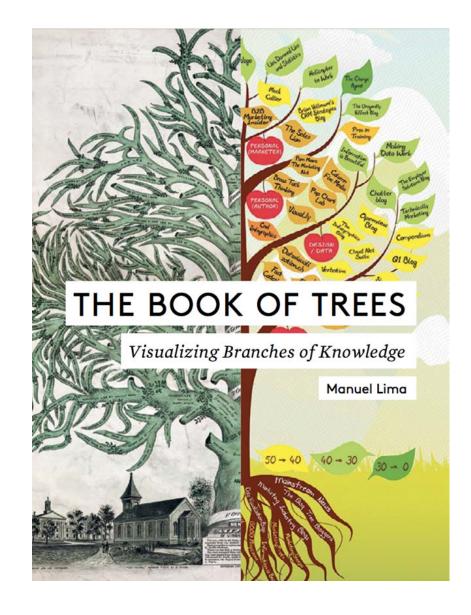


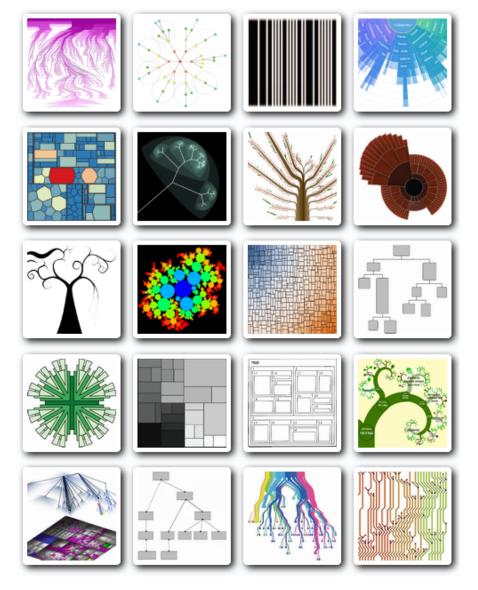
A language family tree – in pictures

# Other tree visualisation styles



#### Other tree visualisation styles





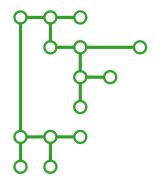
treevis.net



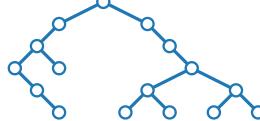
# Visualization of Graphs

Lecture 1b:

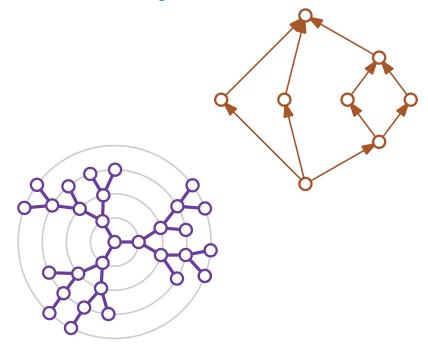
Drawing Trees and Series-Parallel Graphs



Part IV: Series-Parallel Graphs



Jonathan Klawitter

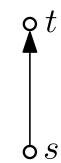


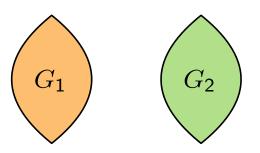
A graph G is series-parallel, if

 $\blacksquare$  it contains a single (directed) edge (s, t), or

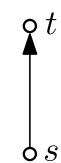


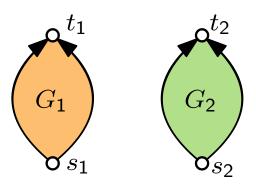
- $\blacksquare$  it contains a single (directed) edge (s, t), or
- $\blacksquare$  it consists of two series-parallel graphs  $G_1$ ,  $G_2$





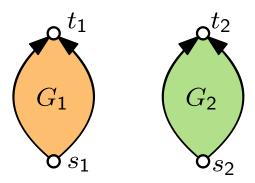
- $\blacksquare$  it contains a single (directed) edge (s, t), or
- it consists of two series-parallel graphs  $G_1$ ,  $G_2$  with sources  $s_1$ ,  $s_2$  and sinks  $t_1$ ,  $t_2$





- $\blacksquare$  it contains a single (directed) edge (s, t), or
- it consists of two series-parallel graphs  $G_1$ ,  $G_2$  with sources  $s_1$ ,  $s_2$  and sinks  $t_1$ ,  $t_2$  that are combined using one of the following rules:



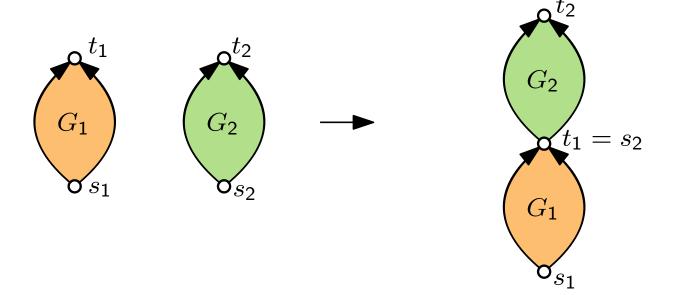


A graph G is series-parallel, if

- $\blacksquare$  it contains a single (directed) edge (s, t), or
- it consists of two series-parallel graphs  $G_1$ ,  $G_2$  with sources  $s_1$ ,  $s_2$  and sinks  $t_1$ ,  $t_2$  that are combined using one of the following rules:

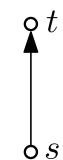


#### **Series composition**

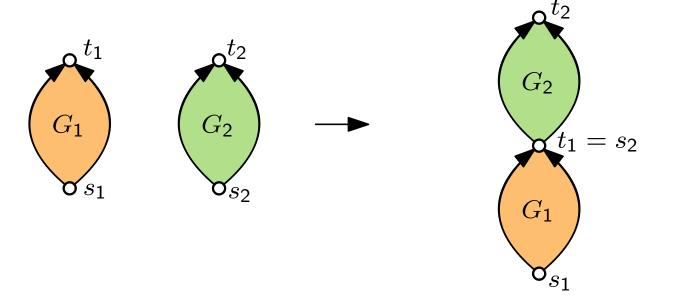


A graph G is series-parallel, if

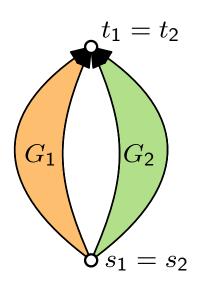
- $\blacksquare$  it contains a single (directed) edge (s, t), or
- it consists of two series-parallel graphs  $G_1$ ,  $G_2$  with sources  $s_1$ ,  $s_2$  and sinks  $t_1$ ,  $t_2$  that are combined using one of the following rules:



#### **Series composition**



#### **Parallel composition**



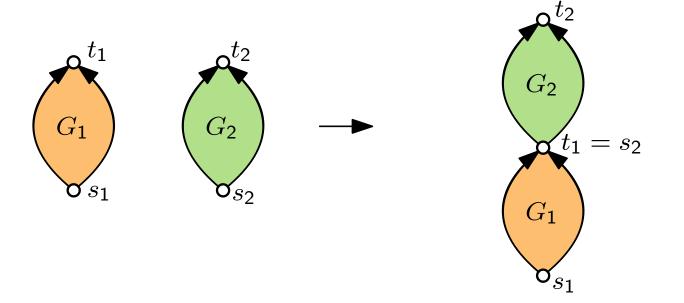
A graph G is series-parallel, if

- $\blacksquare$  it contains a single (directed) edge (s, t), or
- it consists of two series-parallel graphs  $G_1$ ,  $G_2$  with sources  $s_1$ ,  $s_2$  and sinks  $t_1$ ,  $t_2$  that are combined using one of the following rules:

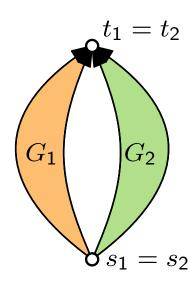


convince yourself that series-parallel graphs are planar

#### **Series composition**



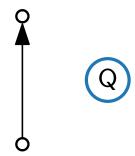
#### **Parallel composition**



A decomposition tree of G is a binary tree T with nodes of three types: S, P and Q-type

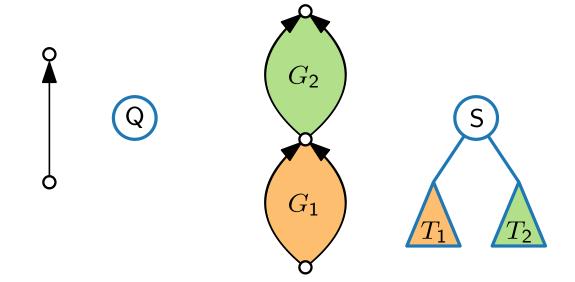
A decomposition tree of G is a binary tree T with nodes of three types: S, P and Q-type

■ A Q-node represents a single edge



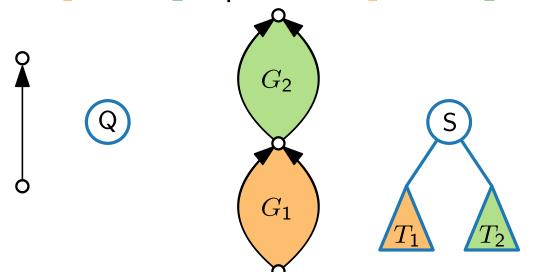
A decomposition tree of G is a binary tree T with nodes of three types: S, P and Q-type

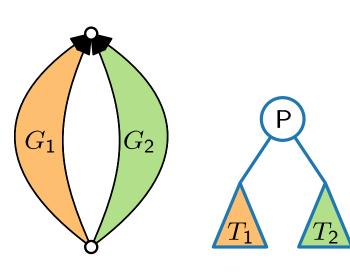
- A Q-node represents a single edge
- An S-node represents a series composition; its children  $T_1$  and  $T_2$  represent  $G_1$  and  $G_2$

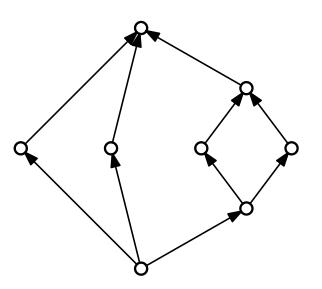


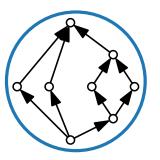
A decomposition tree of G is a binary tree T with nodes of three types: S, P and Q-type

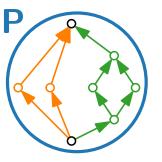
- A Q-node represents a single edge
- An S-node represents a series composition; its children  $T_1$  and  $T_2$  represent  $G_1$  and  $G_2$
- A P-node represents a parallel composition; its children  $T_1$  and  $T_2$  represent  $G_1$  and  $G_2$

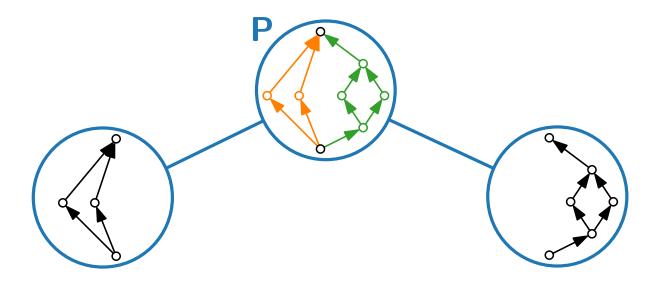


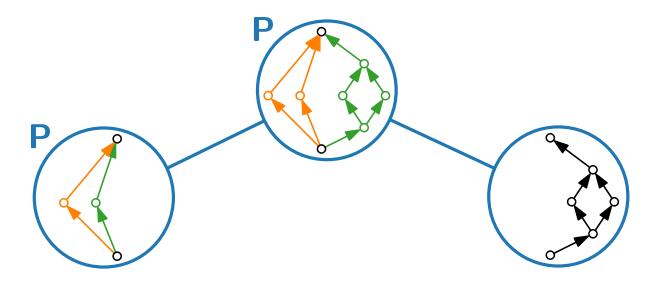


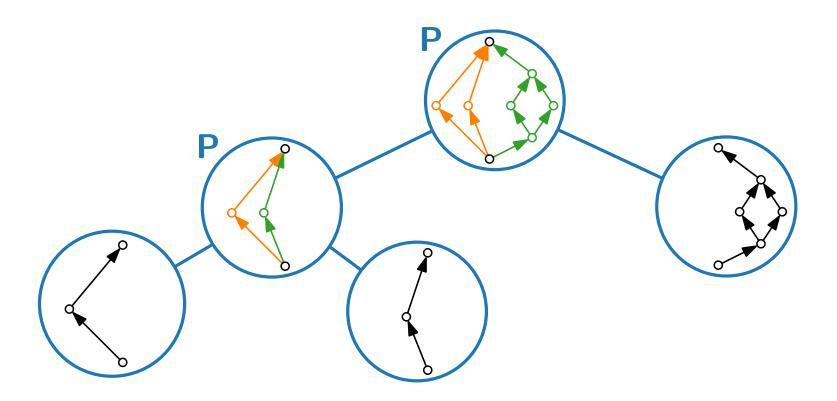


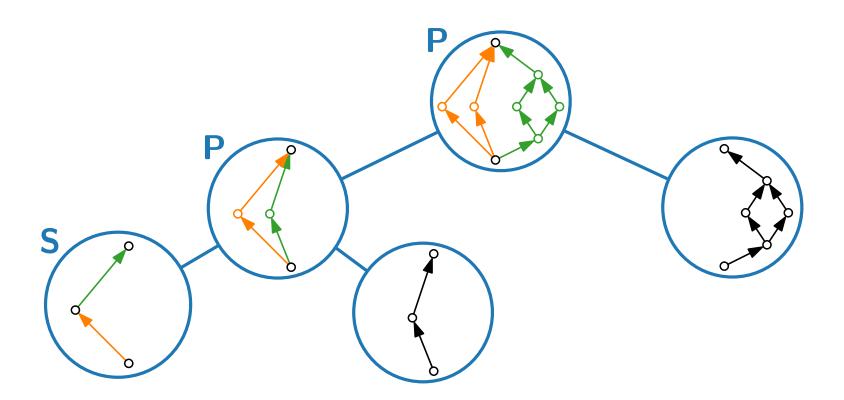


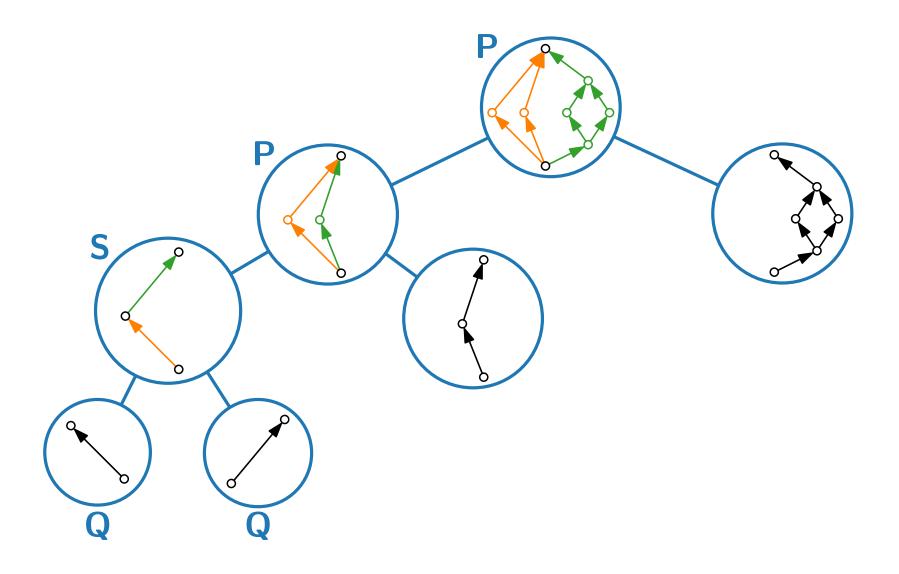


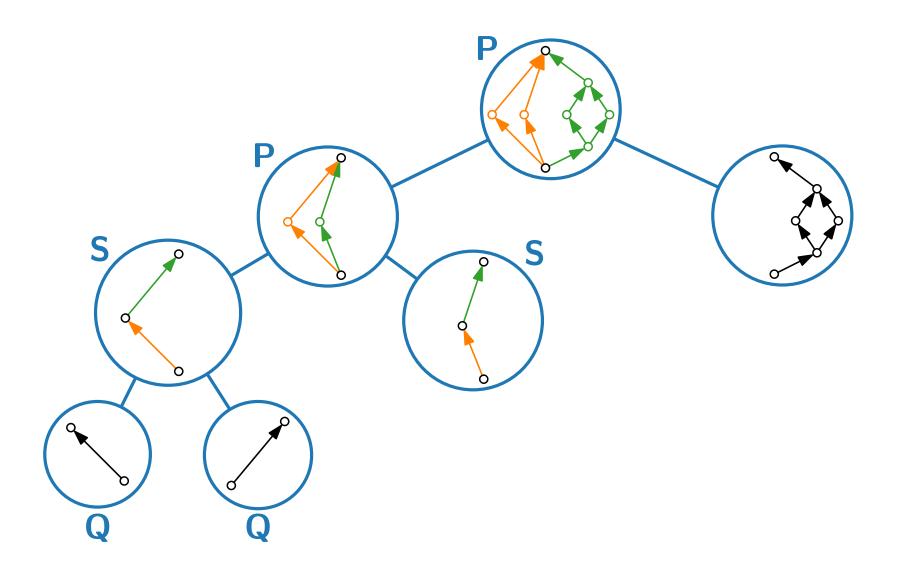


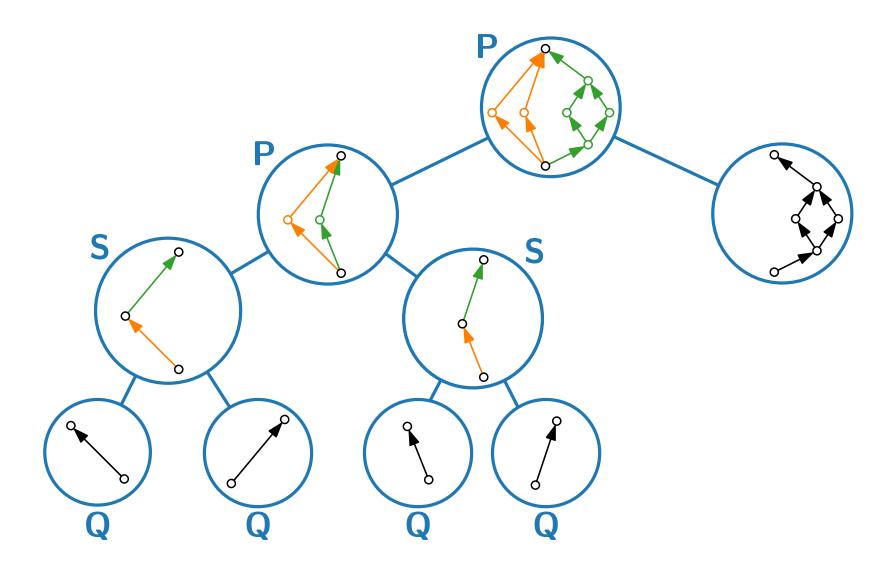


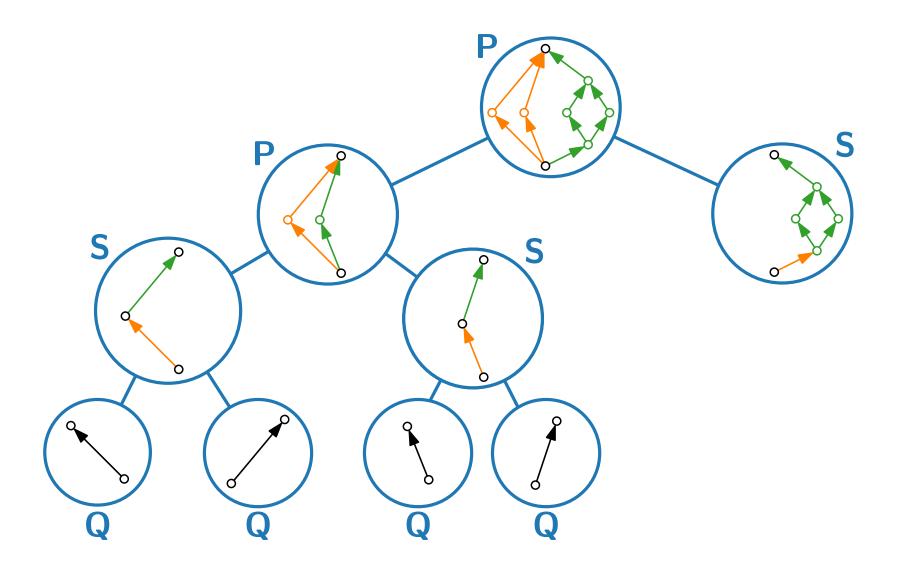


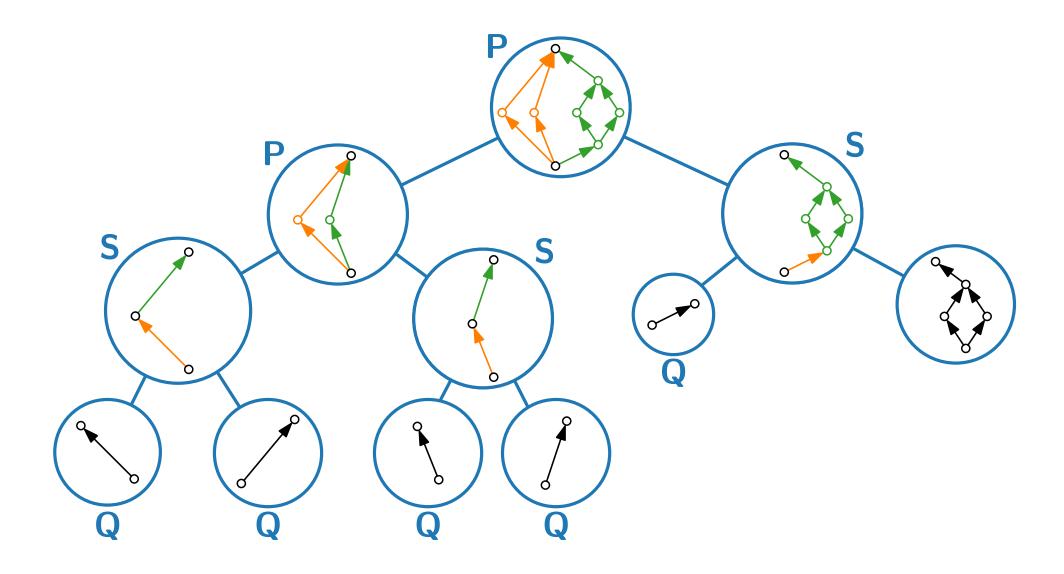


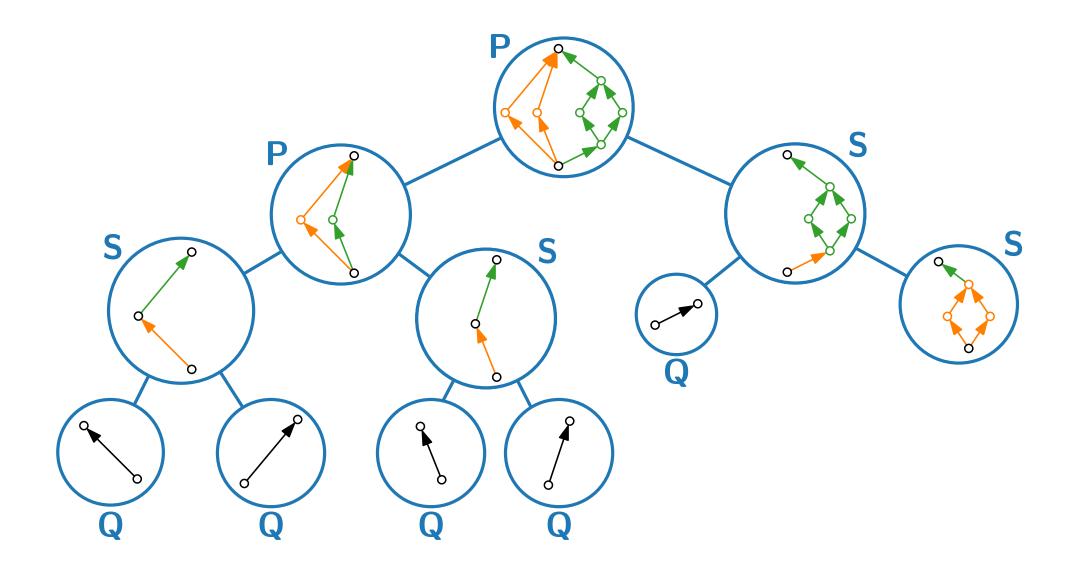


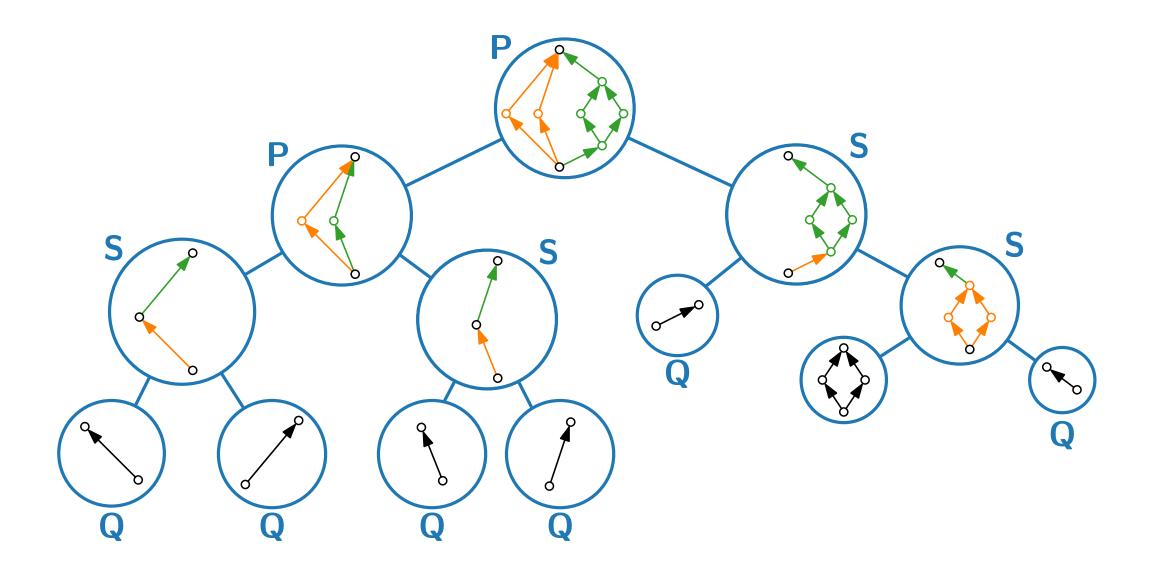


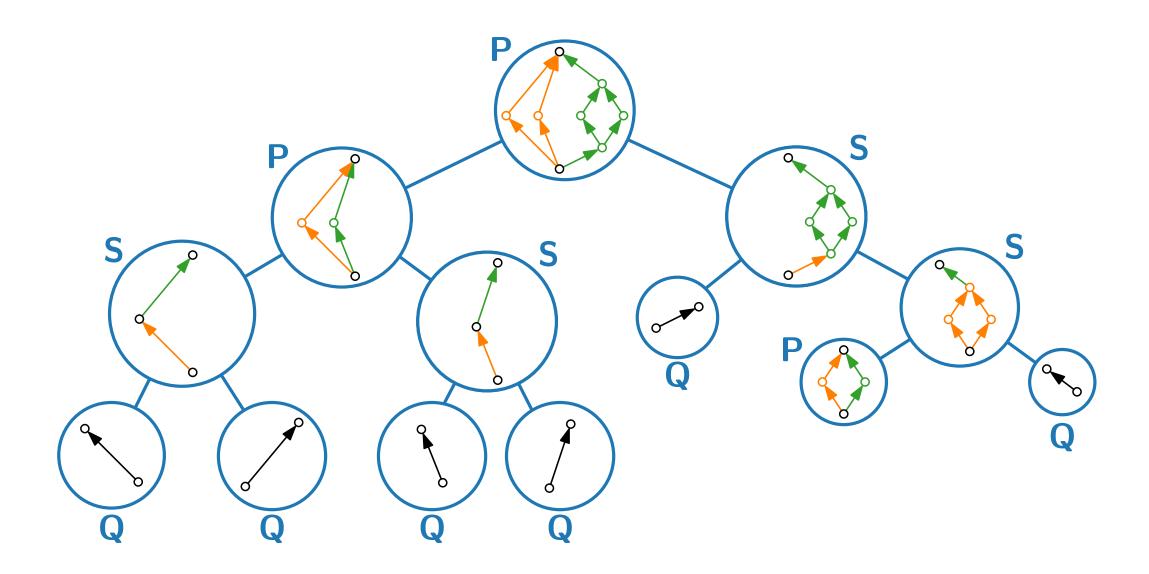


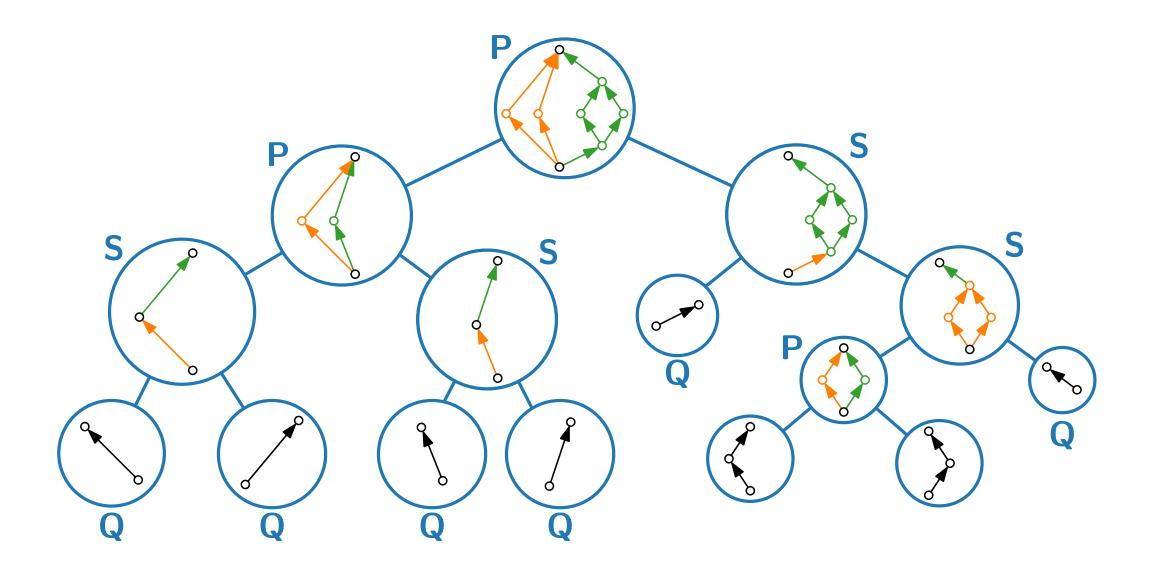


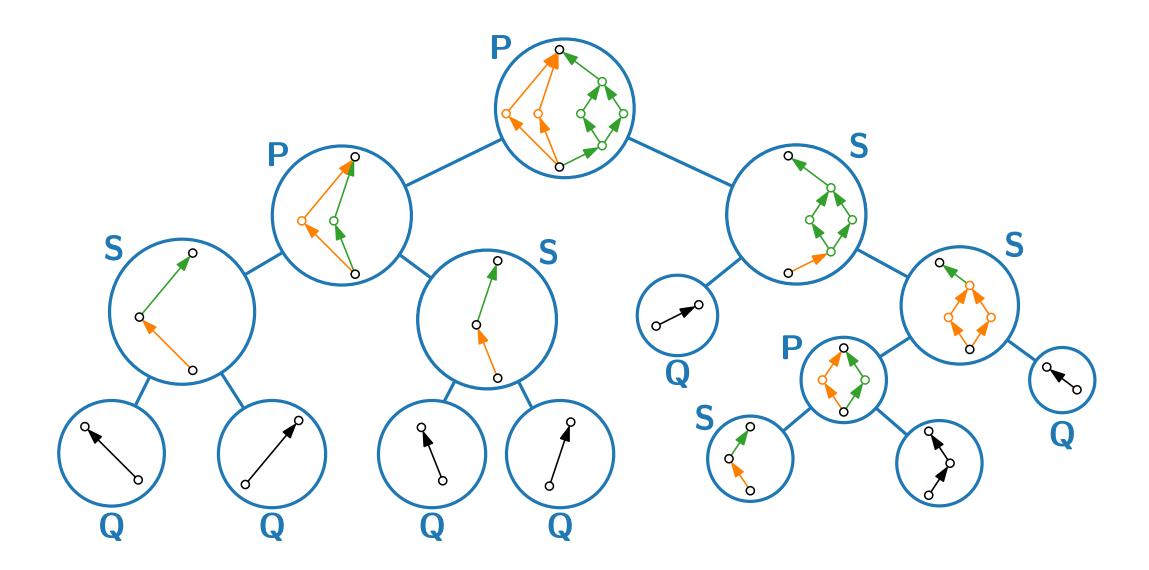


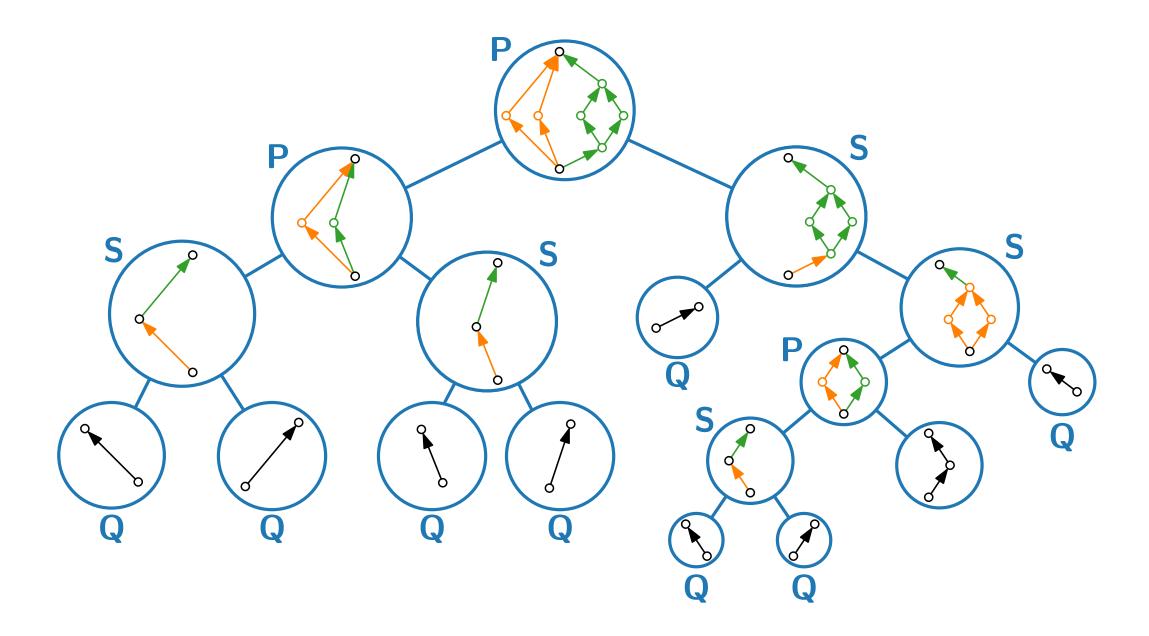


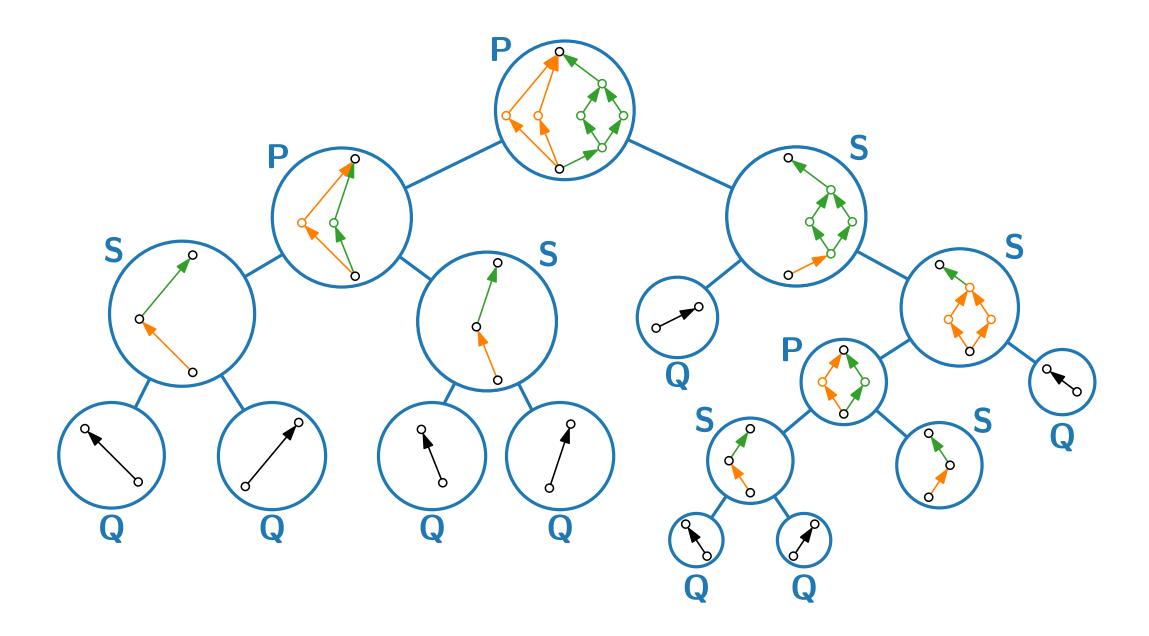


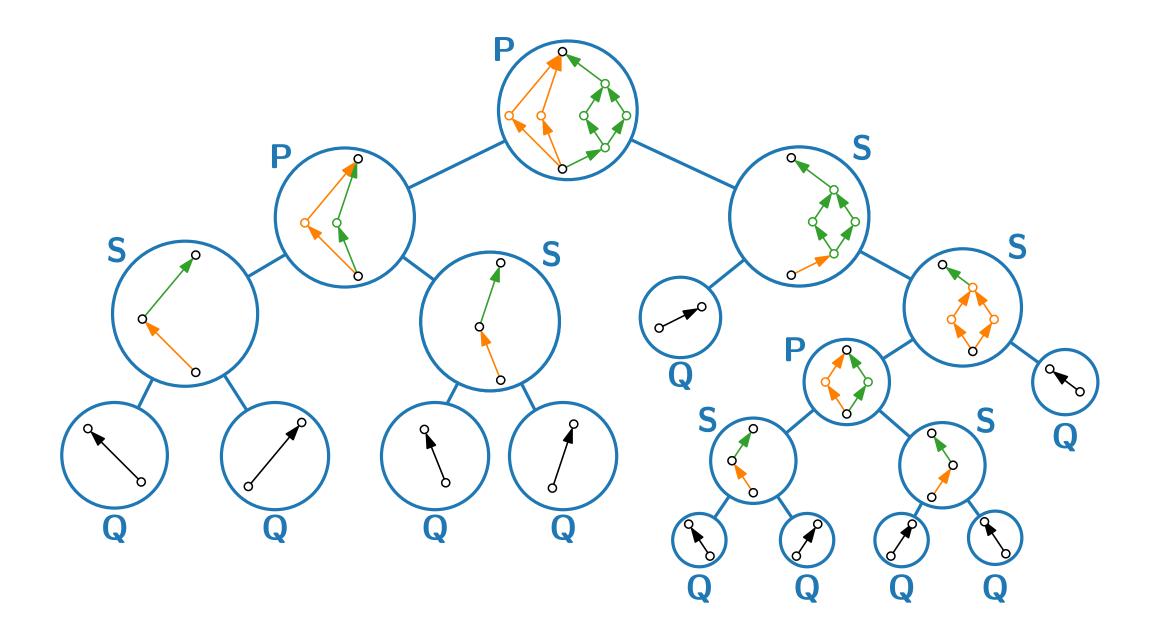




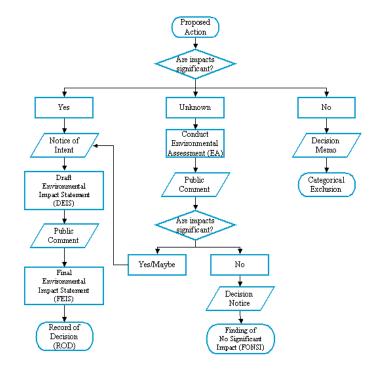




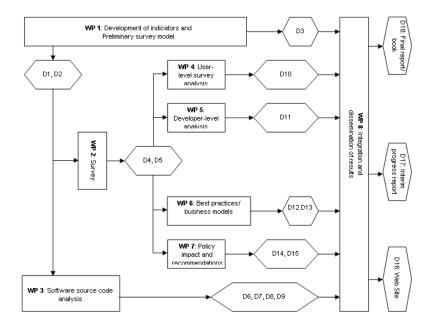




# Series-Parallel Graphs – Applications



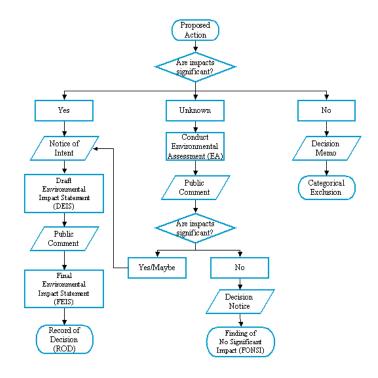
**Flowcharts** 



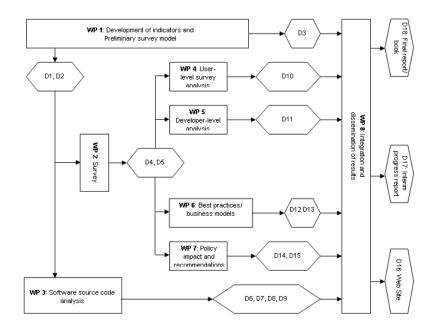
PERT-Diagrams

(Program Evaluation and Review Technique)

## Series-Parallel Graphs – Applications



**Flowcharts** 



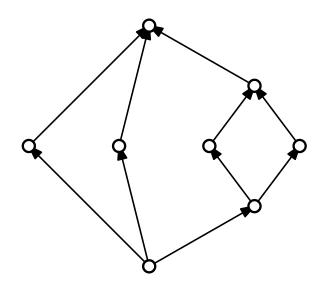
PERT-Diagrams

(Program Evaluation and Review Technique)

#### **Computational complexity:**

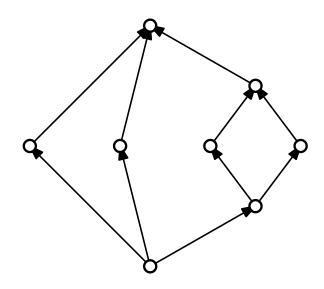
Linear time algorithms for  $\mathcal{NP}$ -hard problems (e.g. Maximum Matching, MIS, Hamiltonian Completion)

**Drawing conventions** 



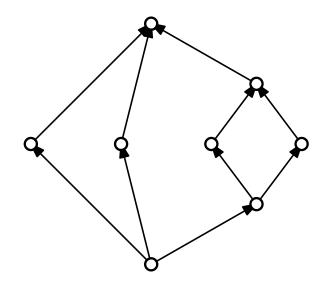
### **Drawing conventions**

Planarity



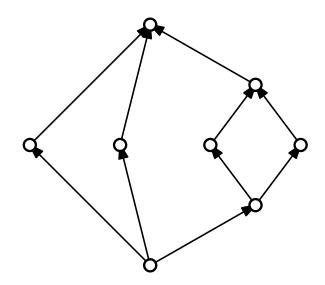
### **Drawing conventions**

- Planarity
- Straight-line edges



### **Drawing conventions**

- Planarity
- Straight-line edges
- Upward

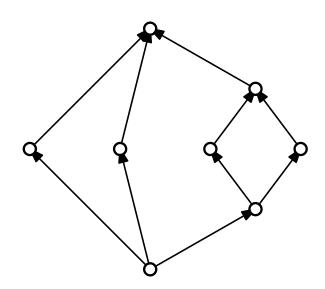


### **Drawing conventions**

- Planarity
- Straight-line edges
- Upward

#### **Drawing aesthetics**

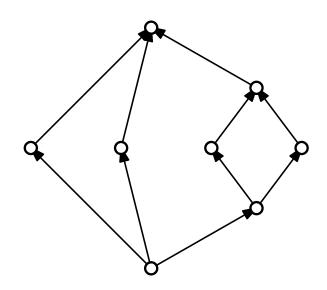
Area



### **Drawing conventions**

- Planarity
- Straight-line edges
- Upward

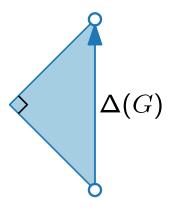
- Area
- Symmetry



Divide & conquer algorithm using the decomposition tree

#### Divide & conquer algorithm using the decomposition tree

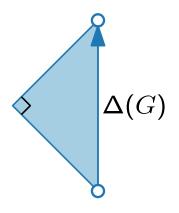
■ Draw G inside a right-angled isosceles bounding triangle  $\Delta(G)$ 

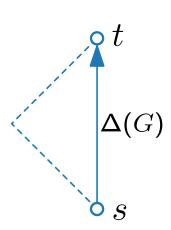


#### Divide & conquer algorithm using the decomposition tree

■ Draw G inside a right-angled isosceles bounding triangle  $\Delta(G)$ 

Base case: Q-nodes

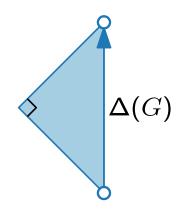


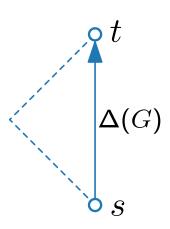


#### Divide & conquer algorithm using the decomposition tree

lacktriangleright Draw G inside a right-angled isosceles bounding triangle  $\Delta(G)$ 

Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first





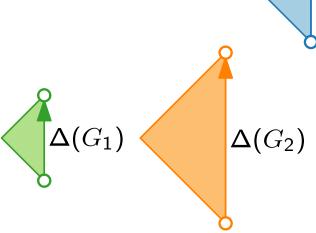
## Series-Parallel Graphs – Straight-Line Drawings

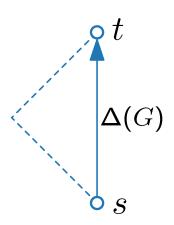
### Divide & conquer algorithm using the decomposition tree

■ Draw G inside a right-angled isosceles bounding triangle  $\Delta(G)$ 

Base case: Q-nodes

**Divide:** Draw  $G_1$  and  $G_2$  first



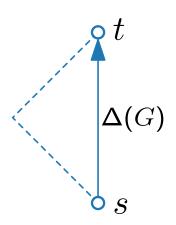


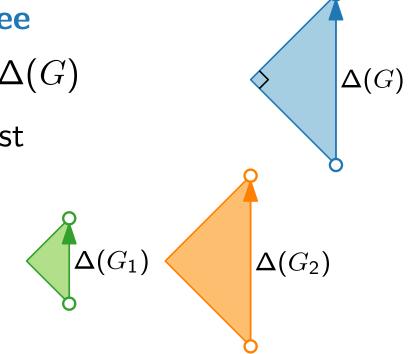
#### Divide & conquer algorithm using the decomposition tree

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Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

#### **Conquer:**





## Series-Parallel Graphs – Straight-Line Drawings

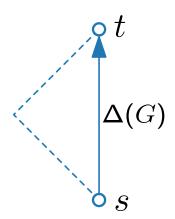
### Divide & conquer algorithm using the decomposition tree

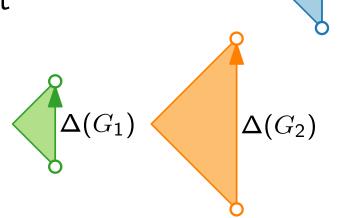
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Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

#### **Conquer:**

S-nodes / series composition





## Series-Parallel Graphs – Straight-Line Drawings

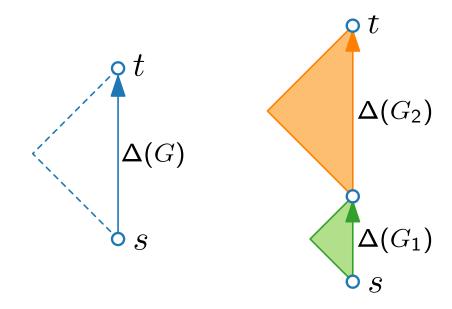
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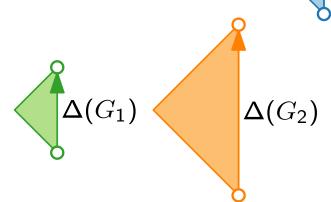
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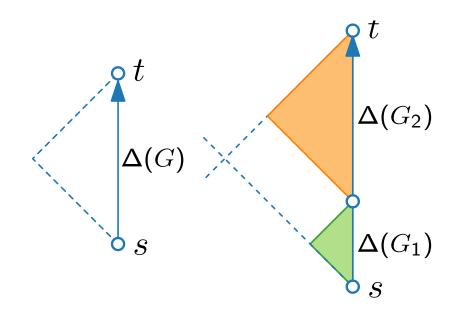
■ Draw G inside a right-angled isosceles bounding triangle  $\Delta(G)$ 

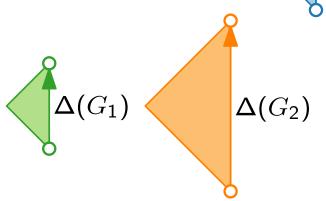
Base case: Q-nodes

**Divide:** Draw  $G_1$  and  $G_2$  first

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S-nodes / series composition





## Series-Parallel Graphs – Straight-Line Drawings

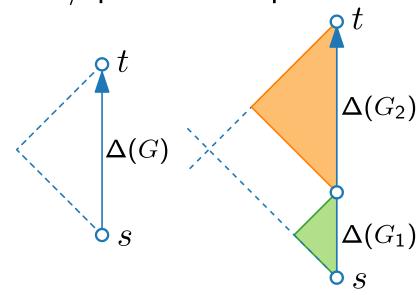
### Divide & conquer algorithm using the decomposition tree

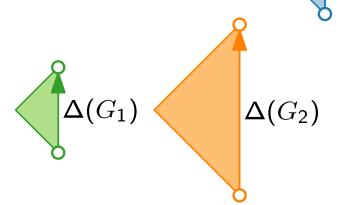
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Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

#### **Conquer:**

- S-nodes / series composition
- P-nodes / parallel composition





## Series-Parallel Graphs – Straight-Line Drawings

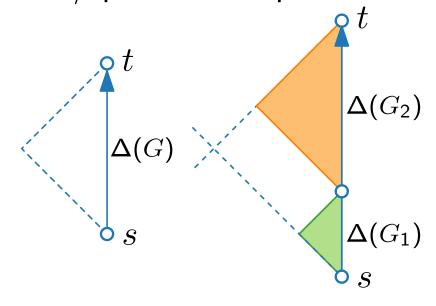
### Divide & conquer algorithm using the decomposition tree

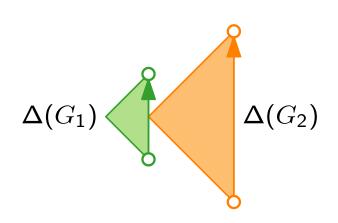
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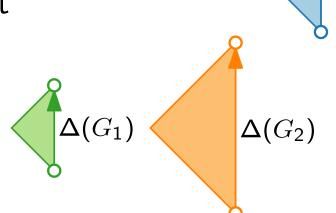
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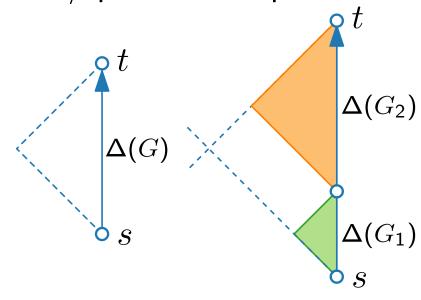
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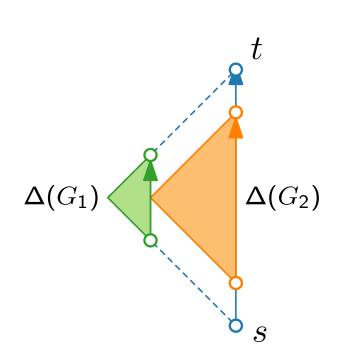
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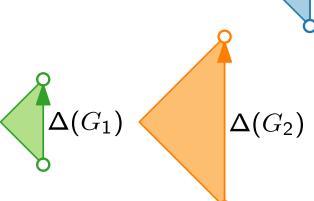
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S-nodes / series composition

P-nodes / parallel composition







## Series-Parallel Graphs – Straight-Line Drawings

### Divide & conquer algorithm using the decomposition tree

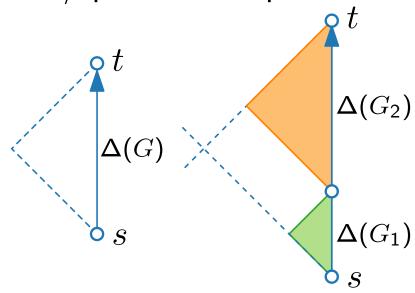
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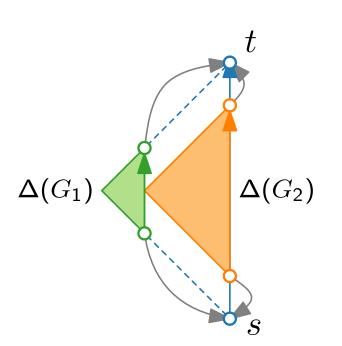
Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

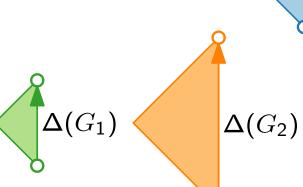
#### **Conquer:**

S-nodes / series composition

P-nodes / parallel composition







 $\Delta(G_2)$ 

## Series-Parallel Graphs – Straight-Line Drawings

### Divide & conquer algorithm using the decomposition tree

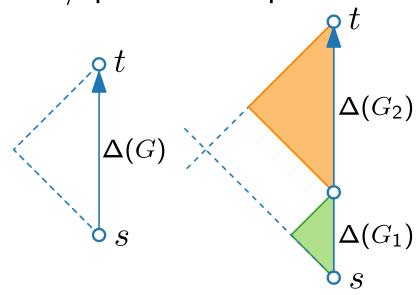
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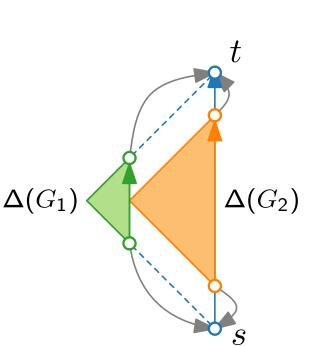
Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

#### **Conquer:**

S-nodes / series composition

P-nodes / parallel composition







 $\Delta(G_1)$ 

## Series-Parallel Graphs – Straight-Line Drawings

### Divide & conquer algorithm using the decomposition tree

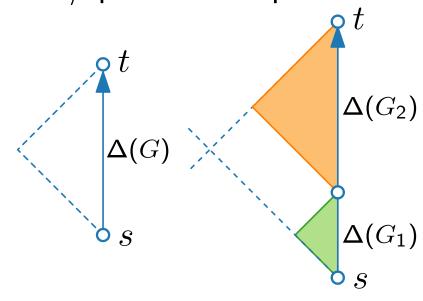
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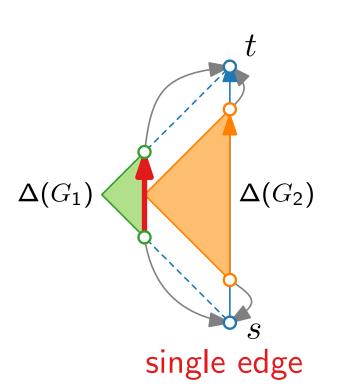
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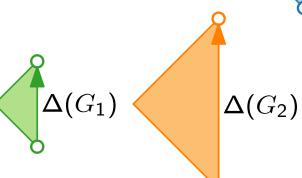
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## Series-Parallel Graphs – Straight-Line Drawings

### Divide & conquer algorithm using the decomposition tree

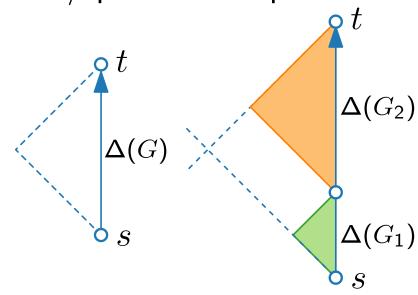
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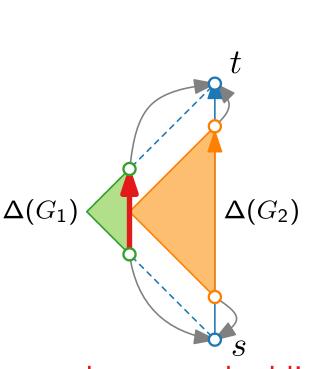
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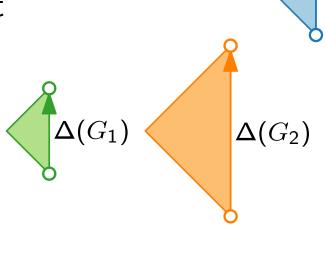
#### **Conquer:**

S-nodes / series composition

P-nodes / parallel composition







change embedding!

## Series-Parallel Graphs – Straight-Line Drawings

### Divide & conquer algorithm using the decomposition tree

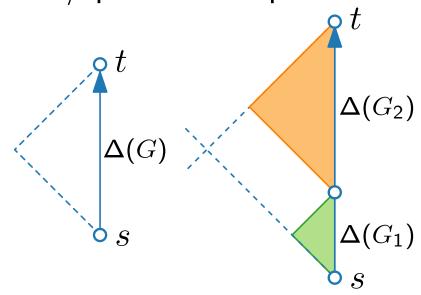
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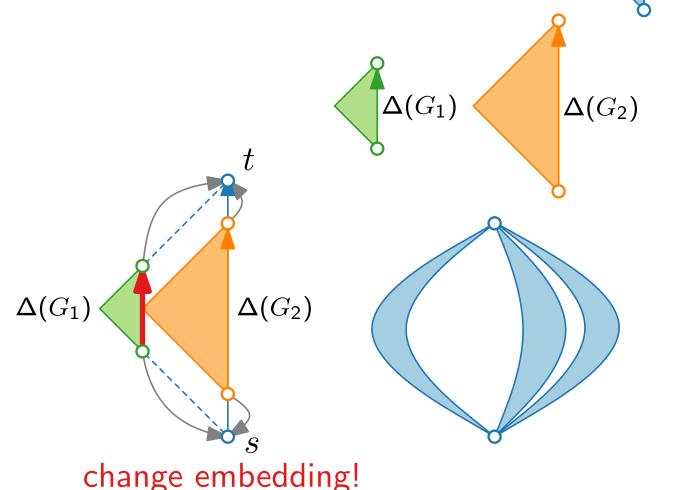
Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

#### **Conquer:**

S-nodes / series composition

P-nodes / parallel composition





## Series-Parallel Graphs – Straight-Line Drawings

### Divide & conquer algorithm using the decomposition tree

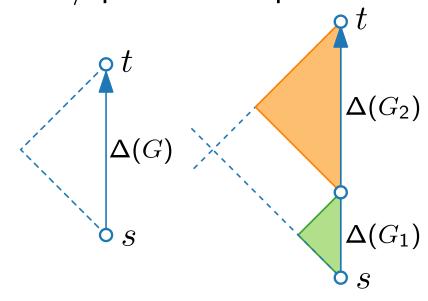
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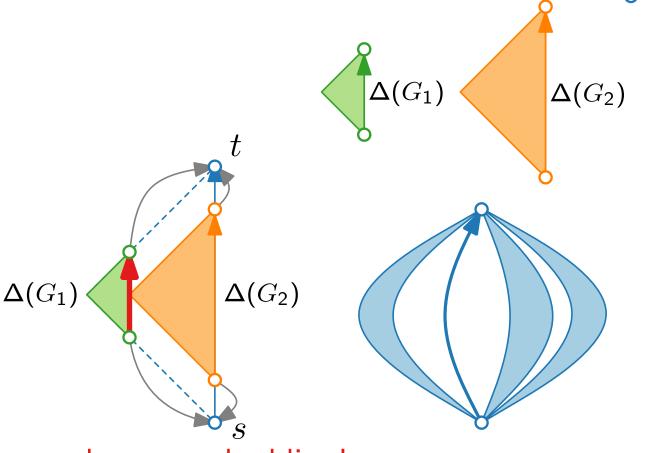
Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

#### **Conquer:**

S-nodes / series composition

P-nodes / parallel composition





change embedding!

## Series-Parallel Graphs – Straight-Line Drawings

### Divide & conquer algorithm using the decomposition tree

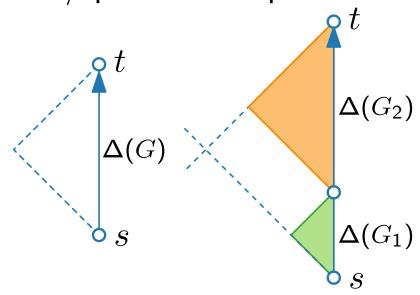
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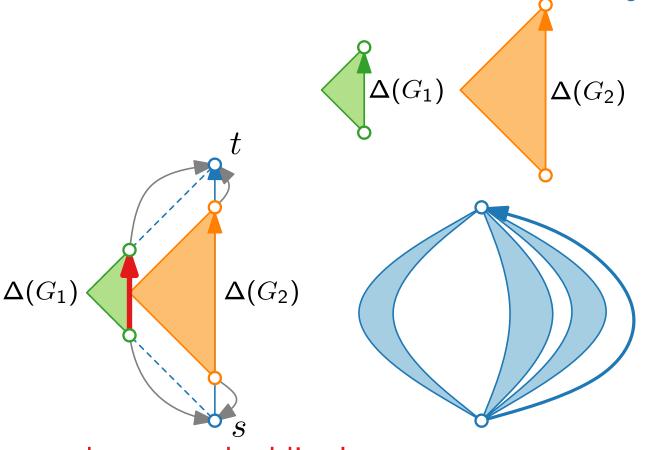
Base case: Q-nodes Divide: Draw  $G_1$  and  $G_2$  first

#### **Conquer:**

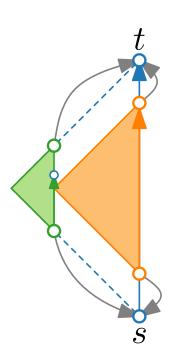
S-nodes / series composition

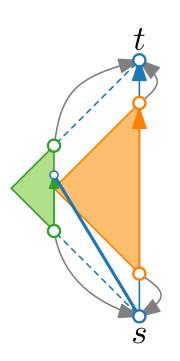
P-nodes / parallel composition

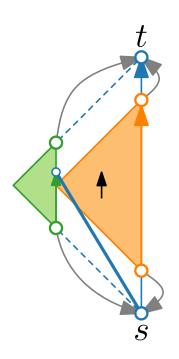


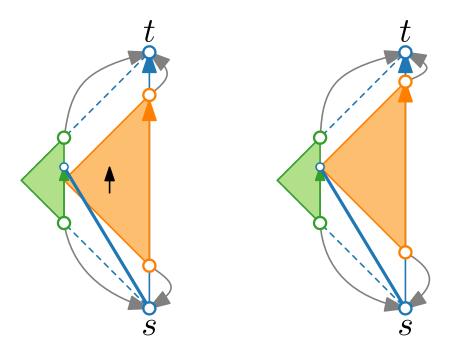


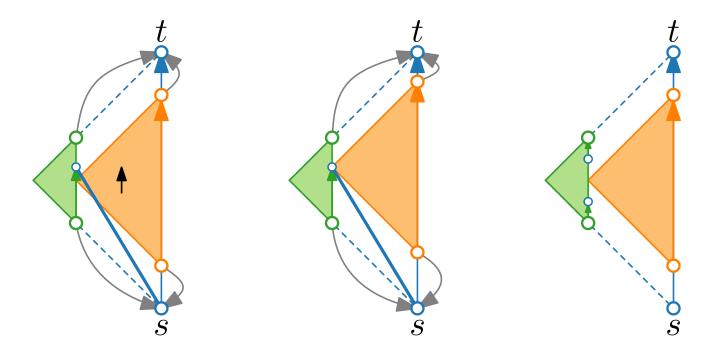
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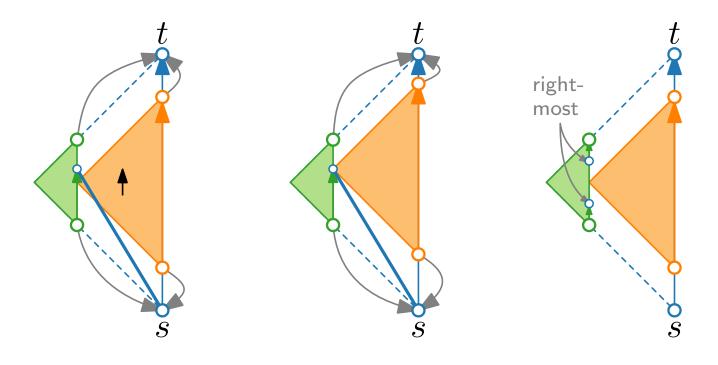


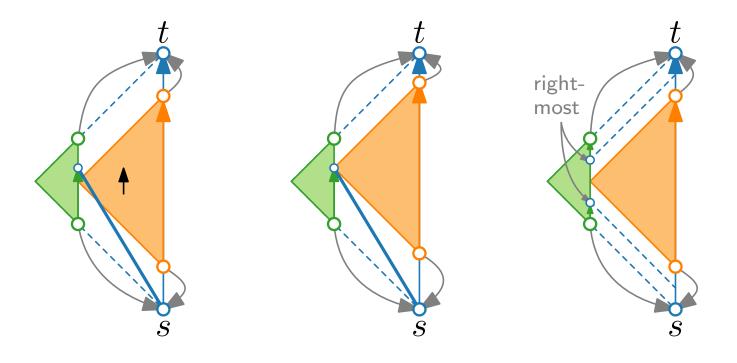


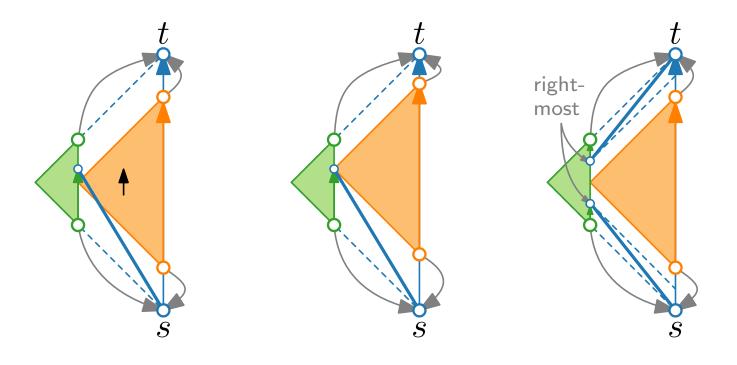


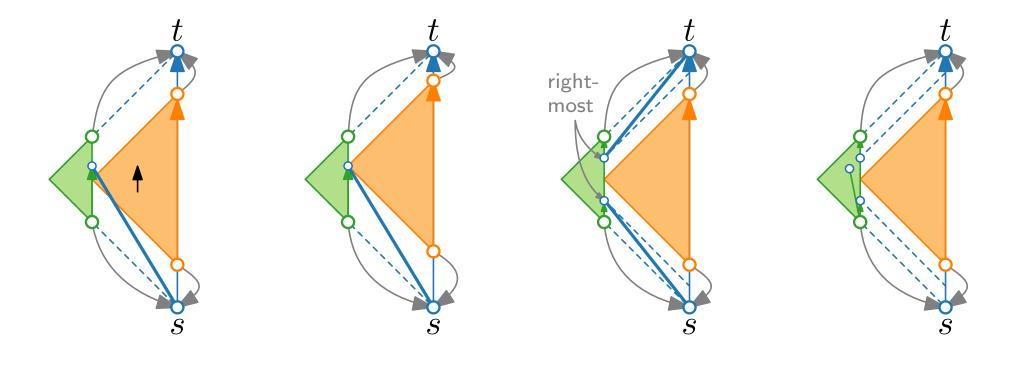


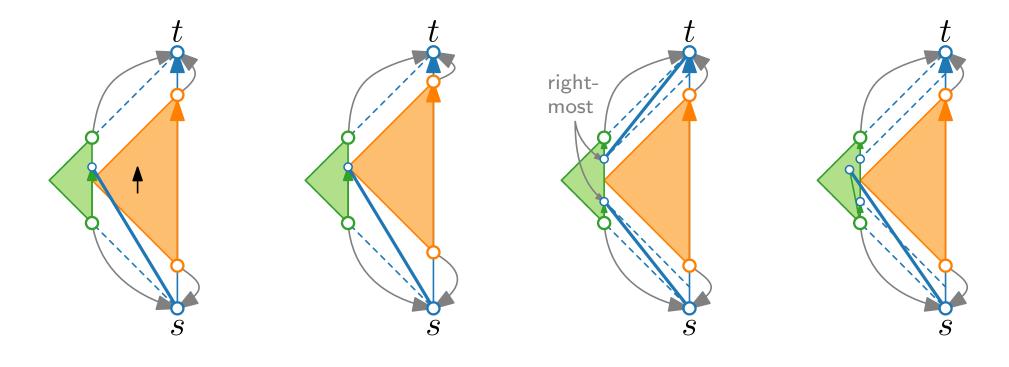


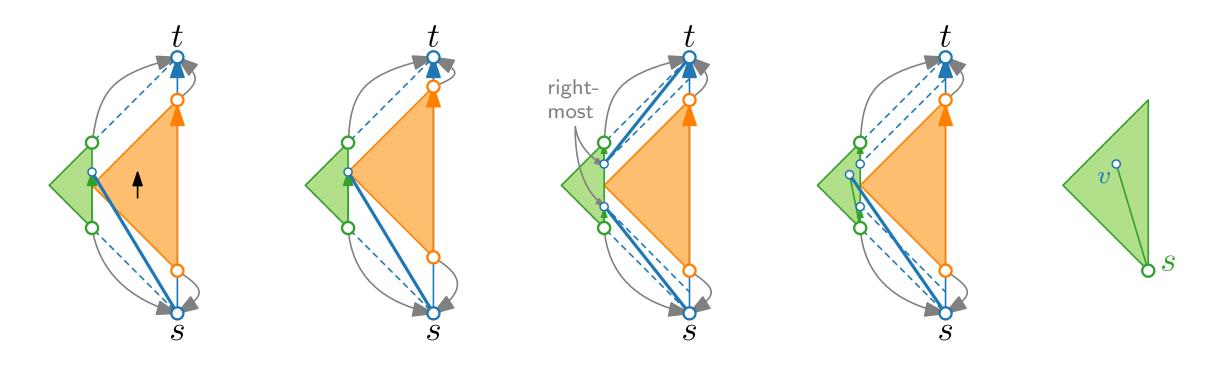


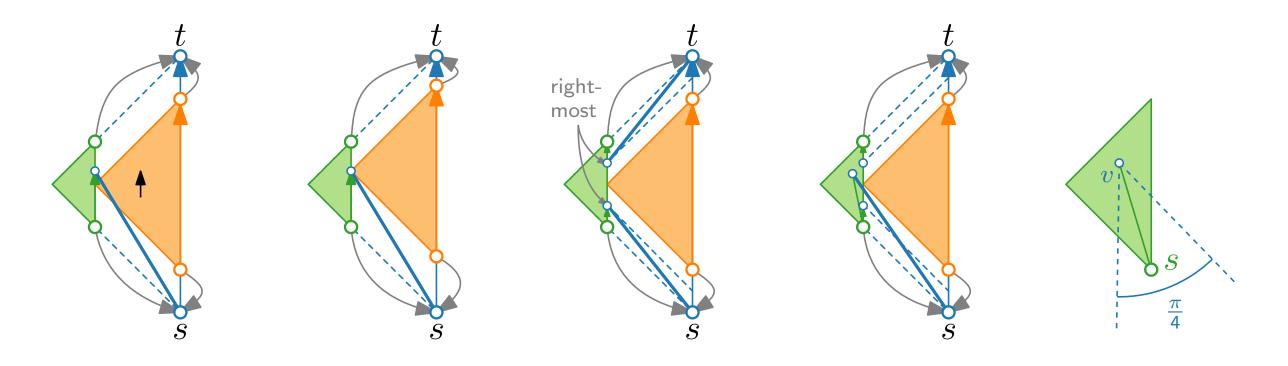


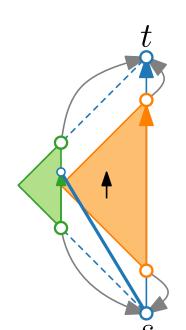


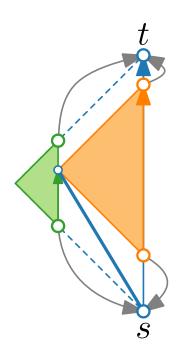


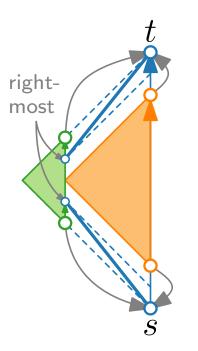


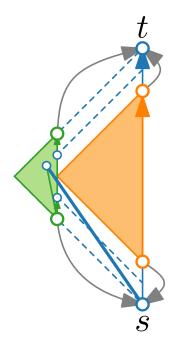


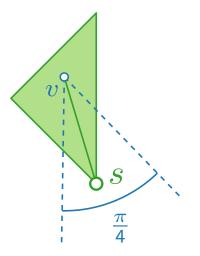






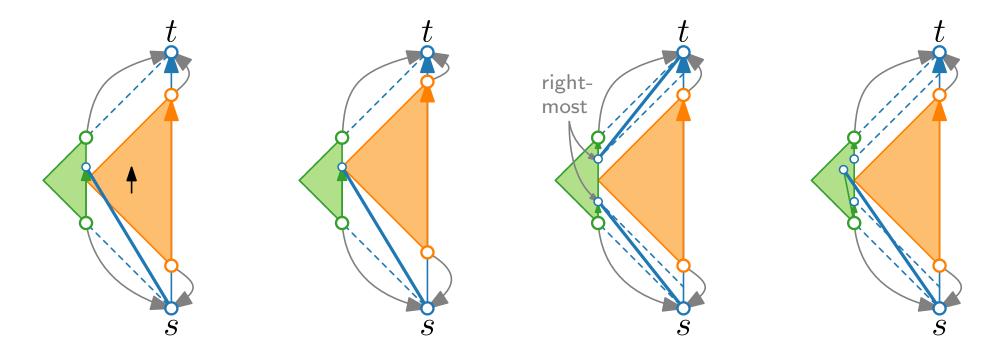




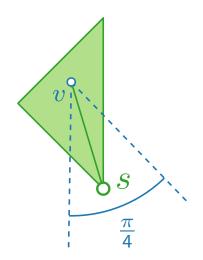


Assume the following holds: the only vertex in angle(v) is s

What makes parallel composition possible without creating crossings?

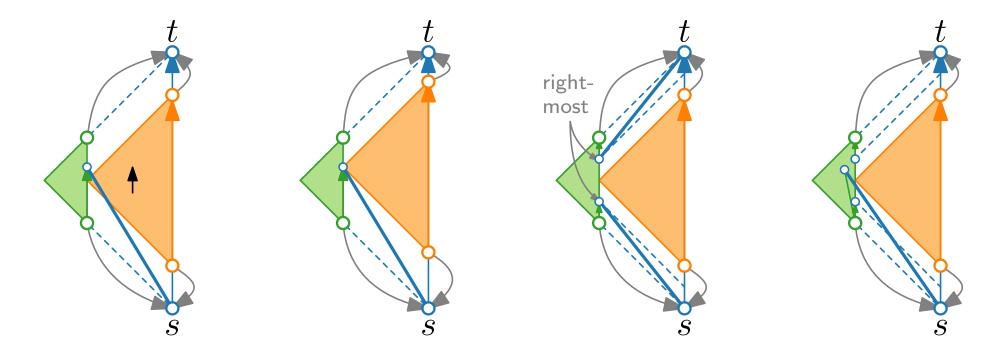


■ This condition **is** preserved during the induction step.



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What makes parallel composition possible without creating crossings?



Assume the following holds: the only vertex in angle(v) is s

■ This condition **is** preserved during the induction step.

#### Lemma.

The drawing produced by the algorithm is planar.

#### Theorem.

#### Theorem.

Let G be a series-parallel graph. Then G (with **variable embedding**) admits a drawing  $\Gamma$  that

is upward planar and

#### Theorem.

- is upward planar and
- a straight-line drawing

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- is upward planar and
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- with area in  $\mathcal{O}(n^2)$ .

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- Isomorphic components of G have congruent drawings up to translation.

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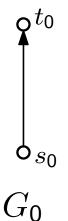
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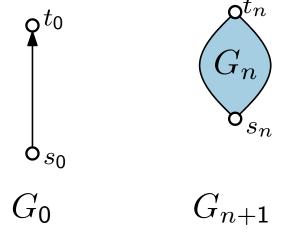
 $\Gamma$  can be computed in  $\mathcal{O}(n)$  time.

#### Theorem. [Bertolazzi et al. 94]

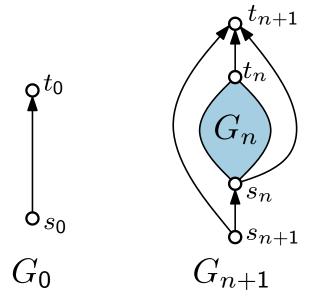
#### Theorem. [Bertolazzi et al. 94]



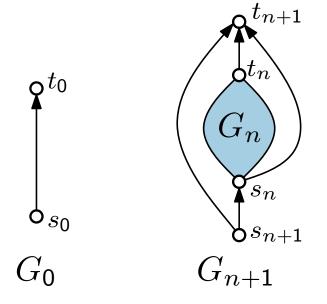
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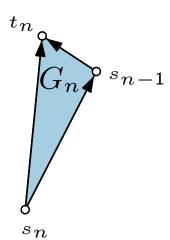


#### Theorem. [Bertolazzi et al. 94]

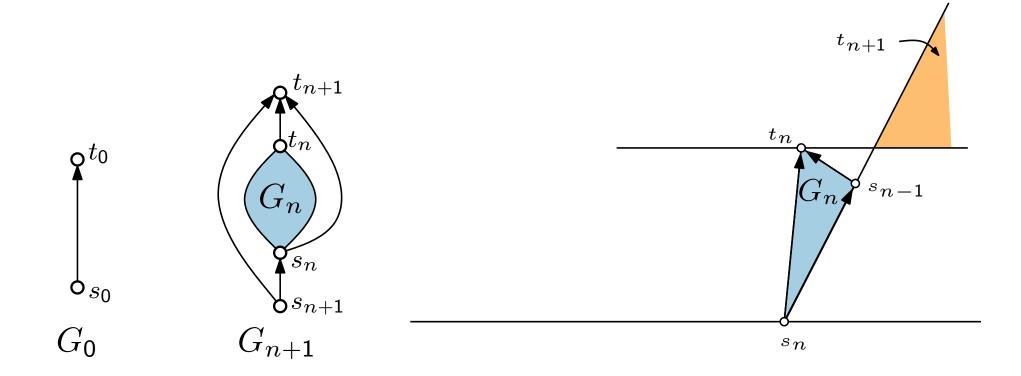


#### Theorem. [Bertolazzi et al. 94]

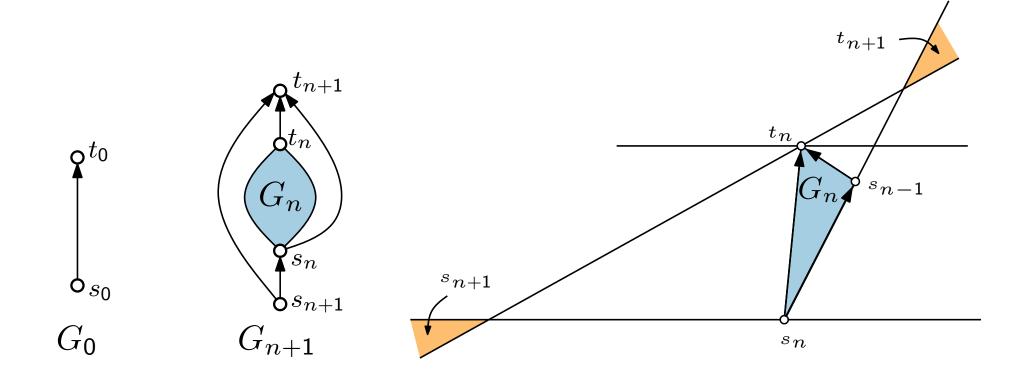




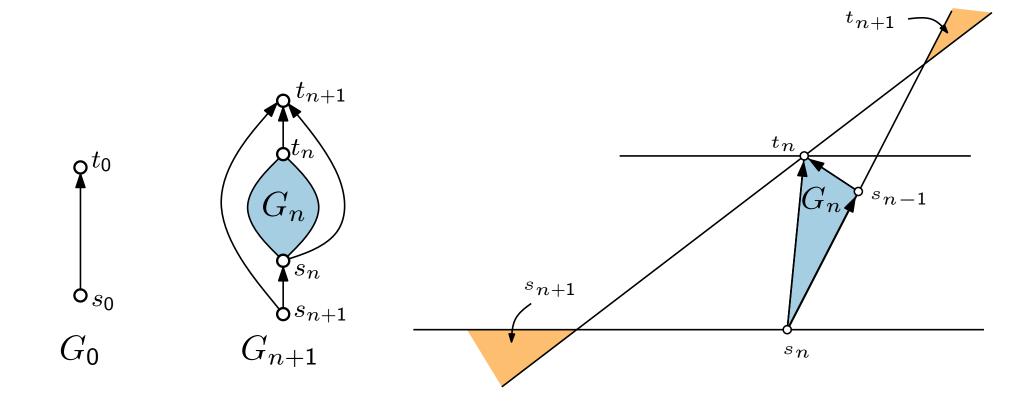
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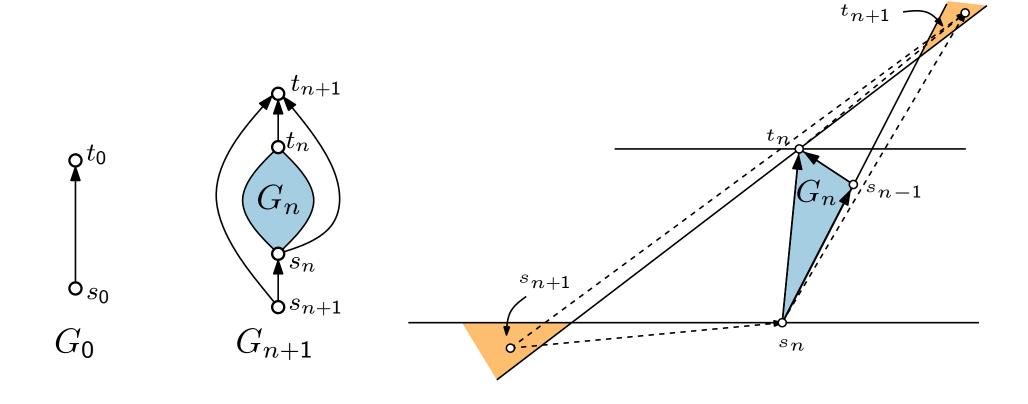
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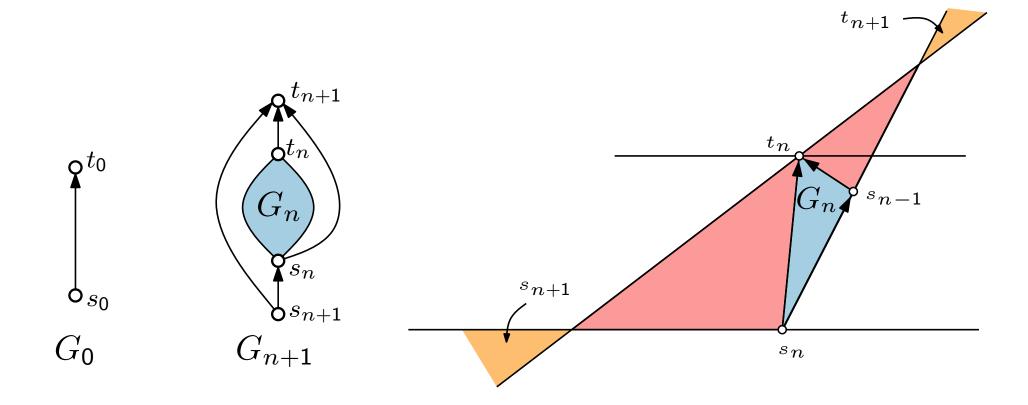
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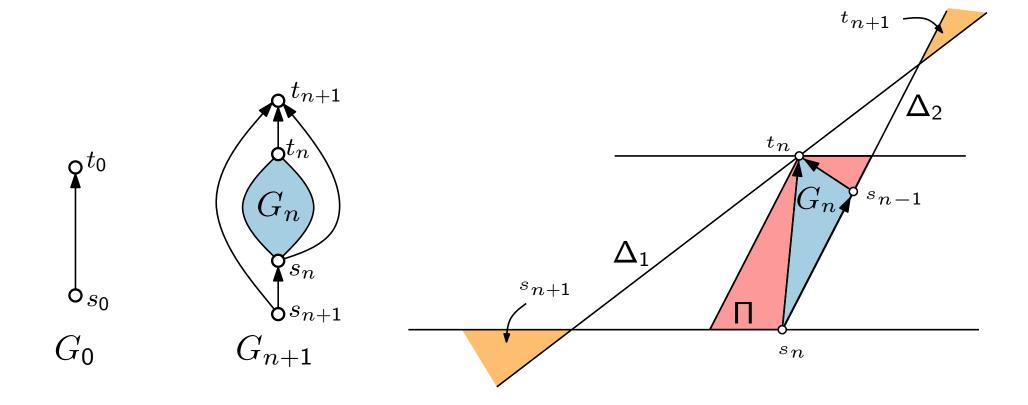
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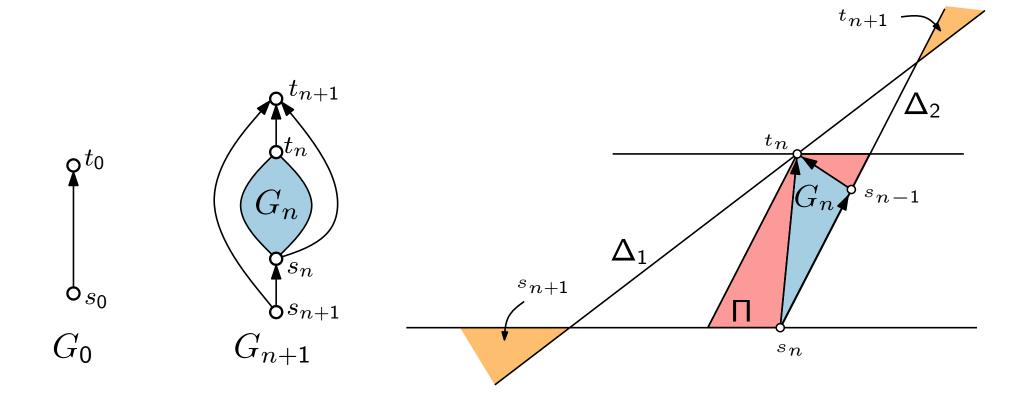


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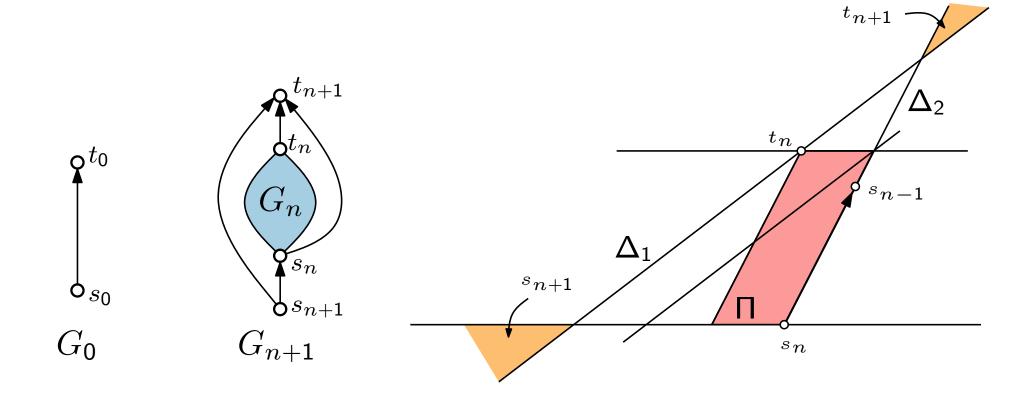
### Theorem. [Bertolazzi et al. 94]

There exists a 2n-vertex series-parallel graph  $G_n$  such that any upward planar drawing of  $G_n$  that respects the embedding requires  $\Omega(4^n)$  area.



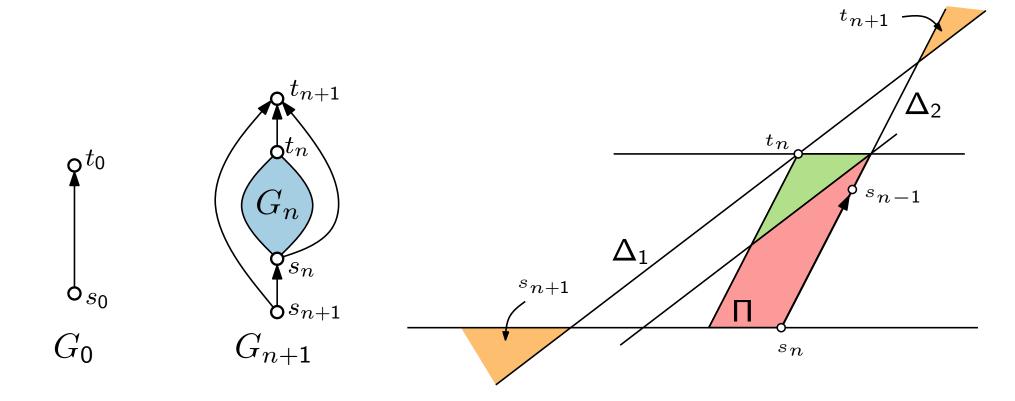
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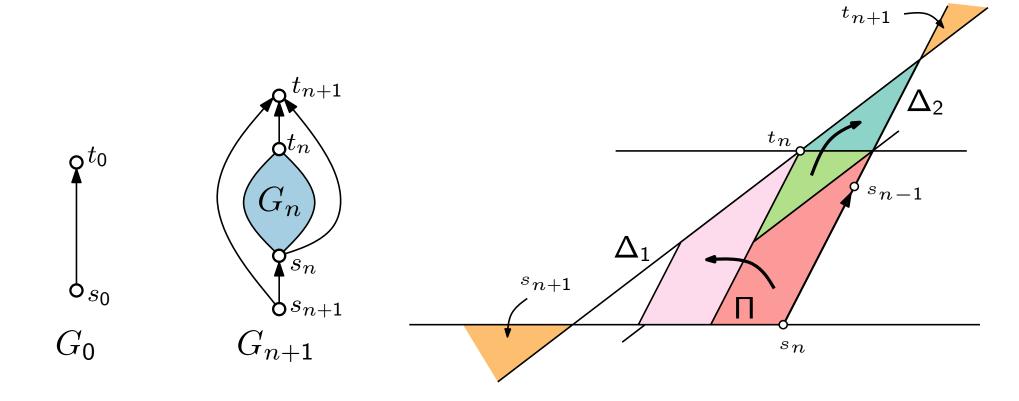
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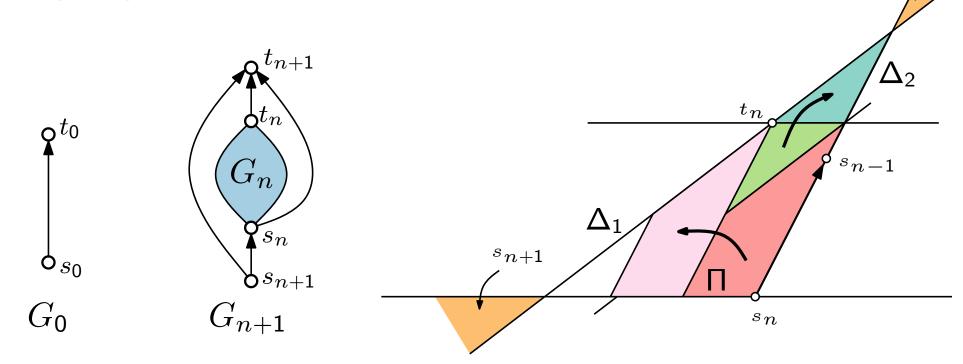
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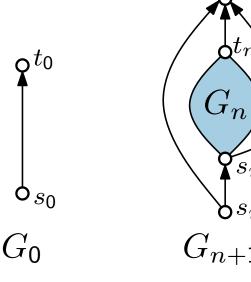
- $2 \cdot Area(G_n) < Area(\Pi)$
- $\mathbf{2} \cdot Area(\Pi) \leq Area(G_{n+1})$

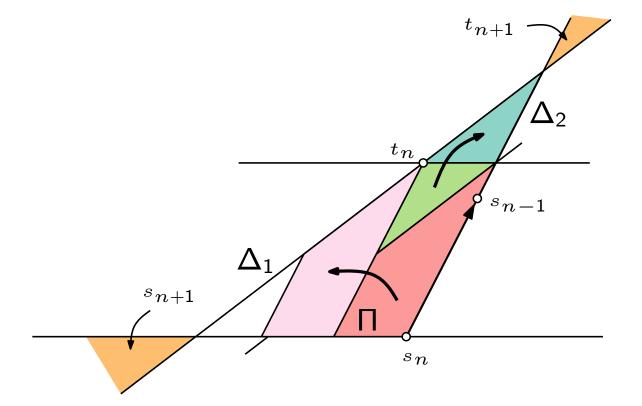


 $t_{n+1}$ 

### Theorem. [Bertolazzi et al. 94]

- $2 \cdot Area(G_n) < Area(\Pi)$
- $2 \cdot Area(\Pi) \leq Area(G_{n+1})$
- $4 \cdot Area(G_n) \le Area(G_{n+1})$





### Literature

- [GD Chapter 3] for divide and conquer methods for rooted trees and series-parallel graphs
- [Reingold, Tilford '81] "Tidier Drawings of Trees" original paper for level-based layout algo
- [Reingold, Supowit '83] "The complexity of drawing trees nicely" NP-hardness proof for area minimisation & LP
- treevis.net compendium of drawing methods for trees