



# Exact Algorithms

#### Sommer Term 2020

#### Lecture 11 Tree Decomposition

Based on: [Parameterized Algorithms: §7.2, 7.3.1]

(slides by J. Spoerhase, Th. van Dijk, S. Chaplick, and A. Wolff)

Alexander Wolff

Lehrstuhl für Informatik I

# (Weighted) Independent Set

Given:

graph G, weight function  $\omega: V \to \mathbb{N}$ **Question:** What is the maximum weight of a set  $S \subseteq V$ where no pair in S is adjacent in G?

## (Weighted) Independent Set

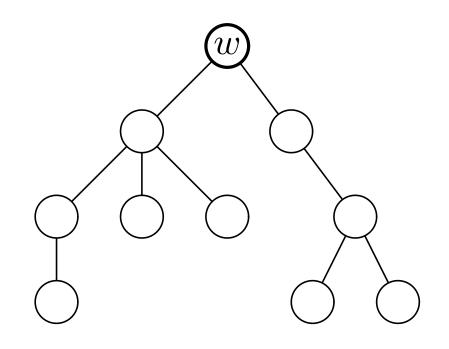
Thm. Independent Set is NP-complete.

## (Weighted) Independent Set

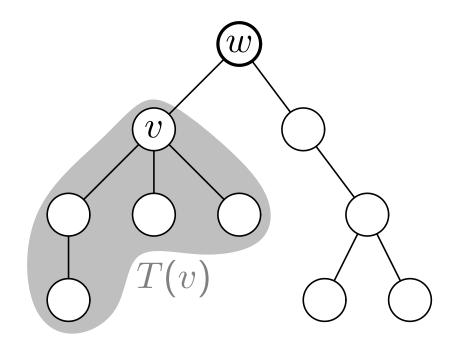
Thm. Independent Set is NP-complete.

Thm. On trees, Independent Set can be solved in linear time.

Choose an arbitrary root w.

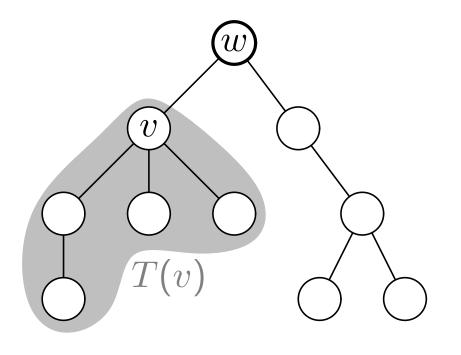


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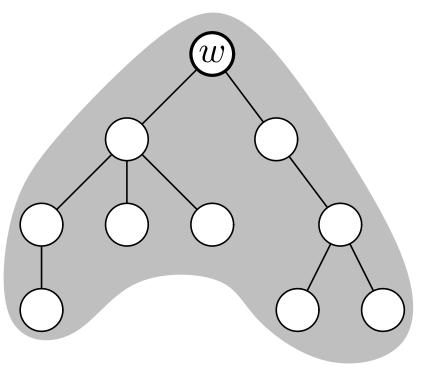
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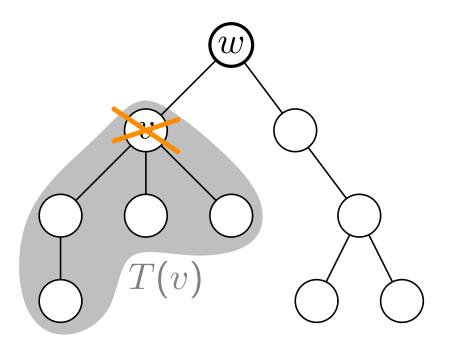
A(w) =solution



Choose an arbitrary root w. Let T(v) := subtree rooted at v

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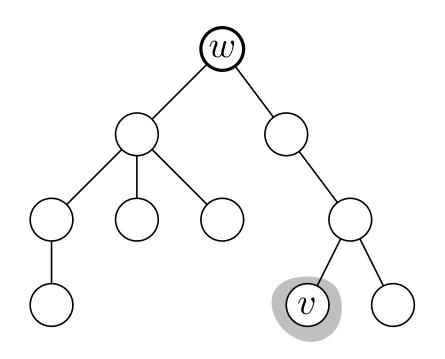


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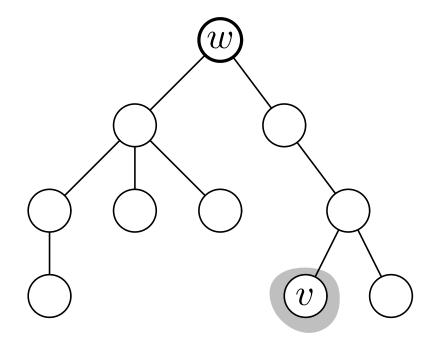




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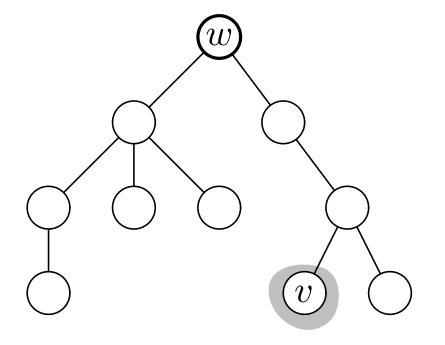


- If v is a leaf: B(v) = 0 and A(v) =

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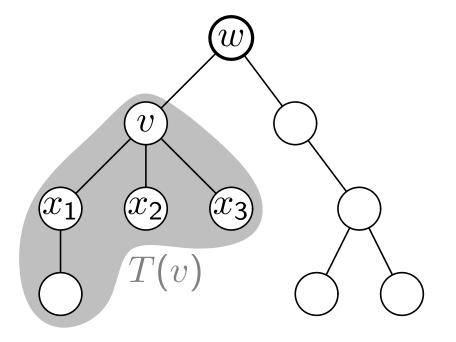
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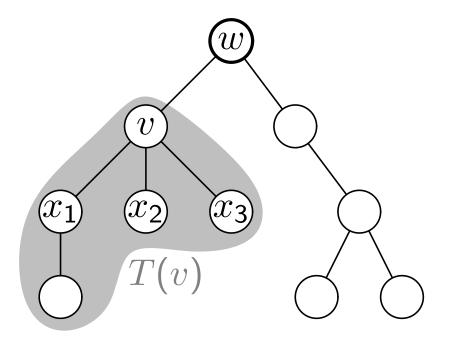


- If 
$$v$$
 has children  $x_1, \ldots, x_r$ :  
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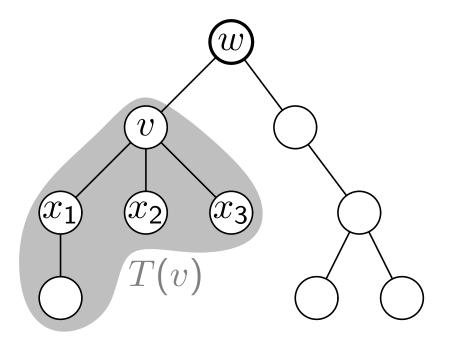


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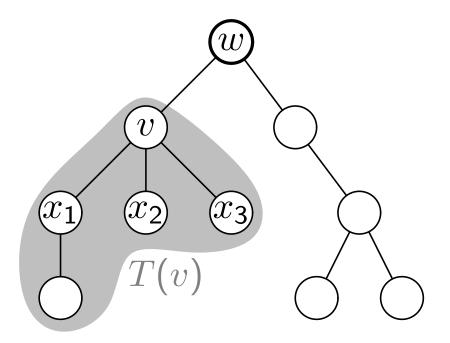


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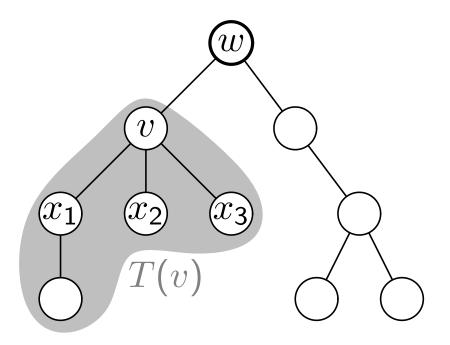


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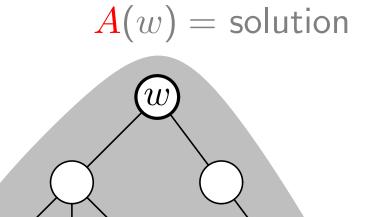
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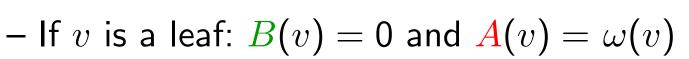
$$B(v) = \sum_{i=1}^r A(x_i); \ \mathbf{A}(v) = \max\{B(v), \omega(v) + \sum_{i=1}^r B(x_i)\}$$

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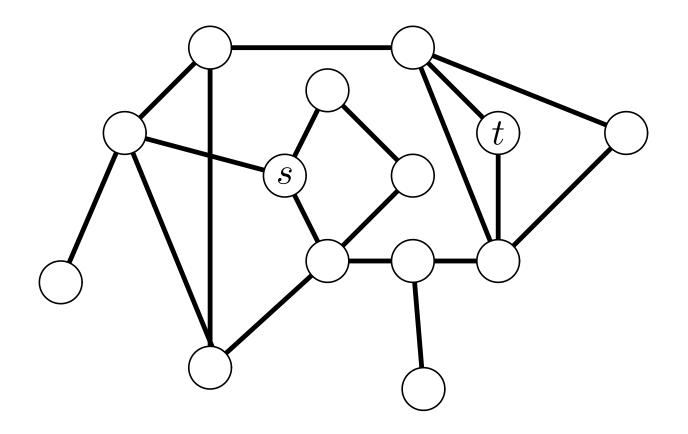




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**Algorithm:** Compute  $A(\cdot)$  and  $B(\cdot)$  bottom-up!

**Def.** A graph G = (V, E) is 2-terminal if it contains two special vertices s and t.



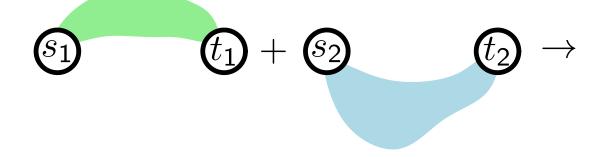
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(5) (
$$t_1$$
) + (S2) ( $t_2$ )  $\rightarrow$  (S1) ( $t_2$ ) ( $t_1$ ) ( $t_2$ ) (

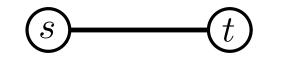
$$\begin{array}{cccc} s_1 & t_1 + s_2 & t_2 \rightarrow & & \\ & s_1 = s_2 & t_1 = t_2 \end{array}$$

- **Def.** A graph G = (V, E) is 2-terminal if it contains two special vertices s and t. Series-parallel graphs have a natural tree structure!
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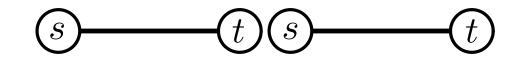
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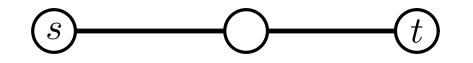
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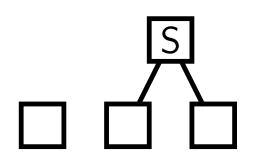


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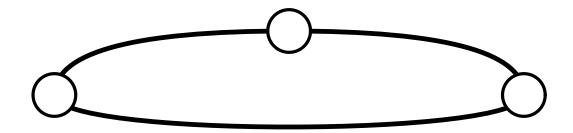


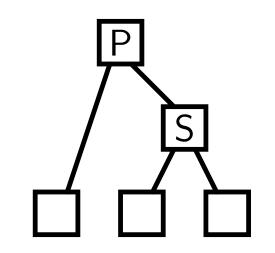


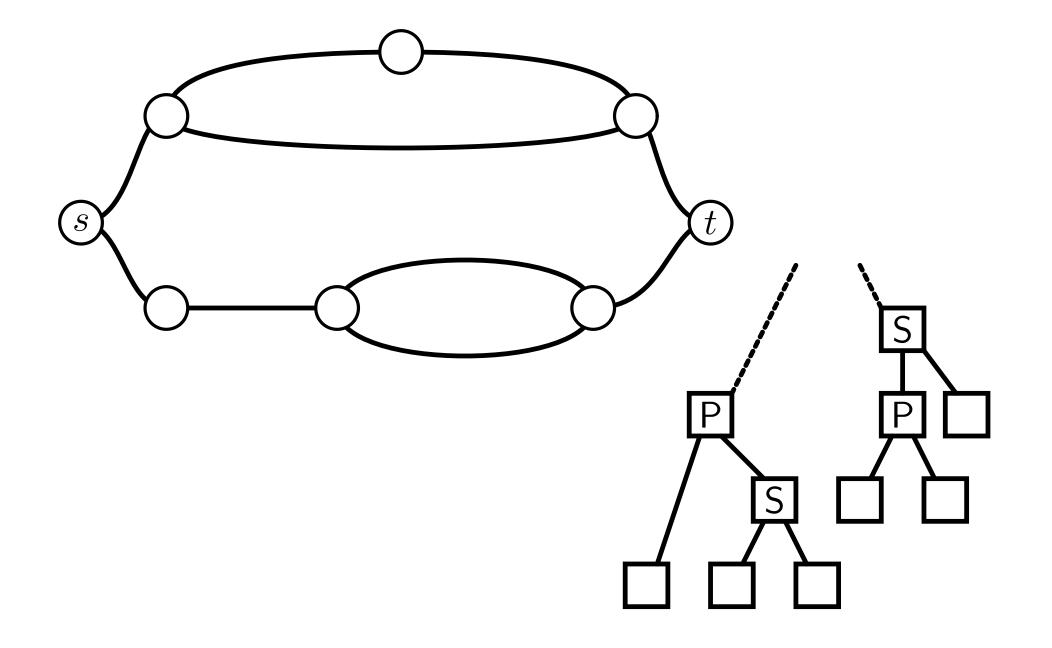


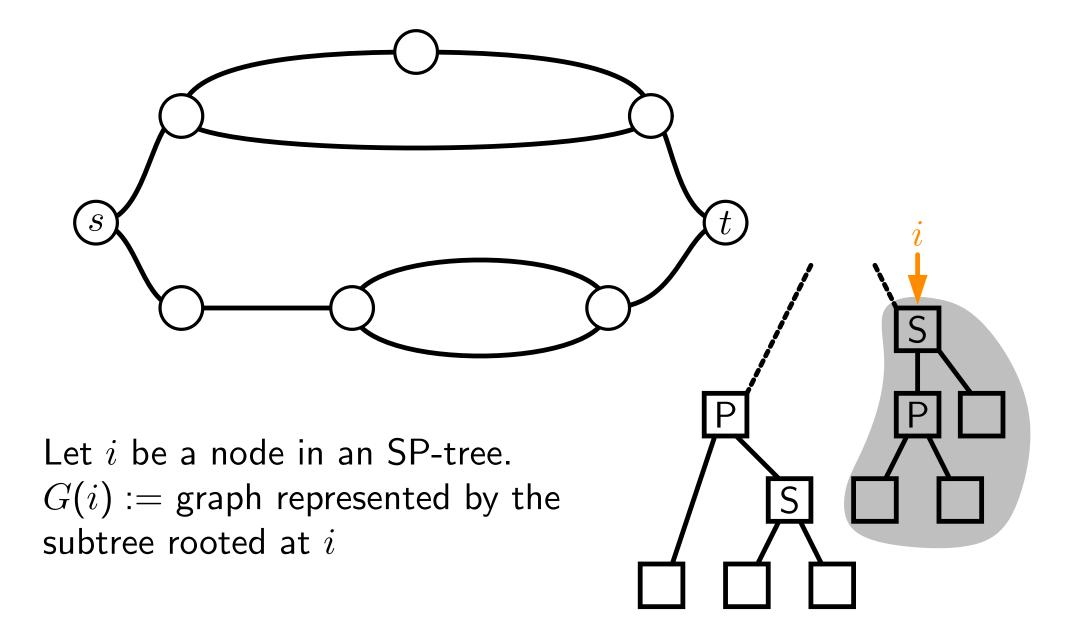


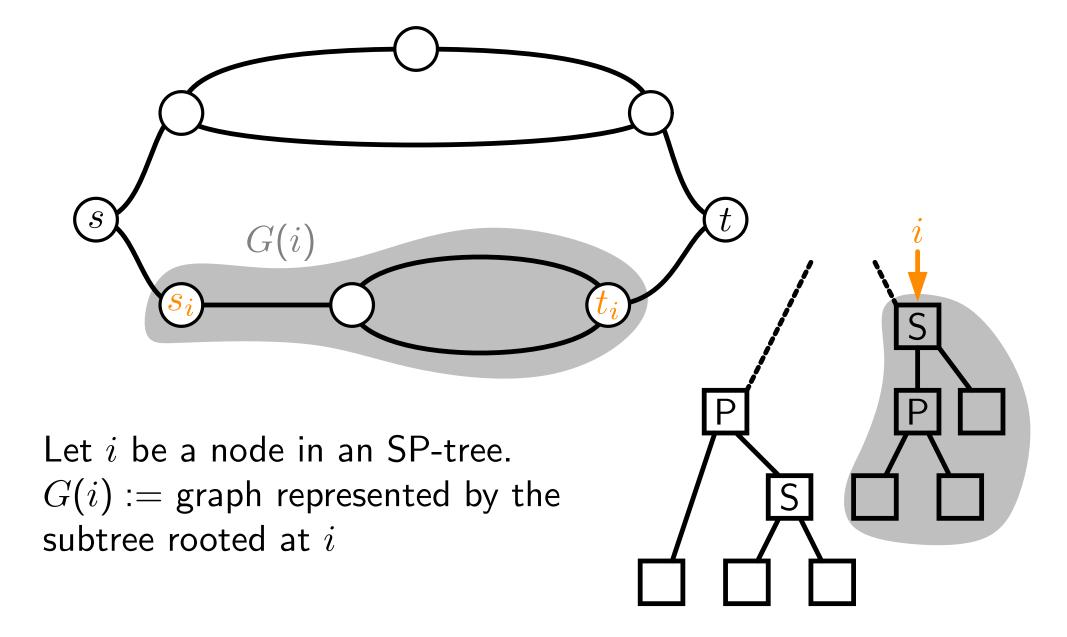






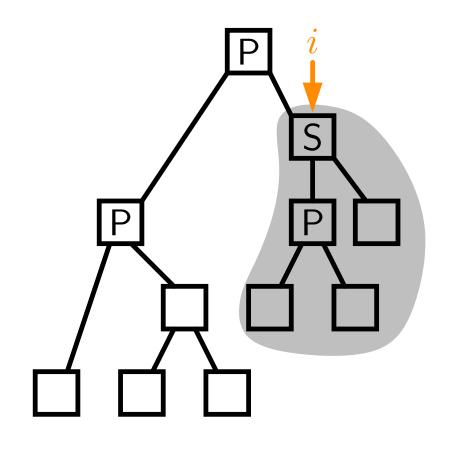






#### Independent Set on SP-Trees

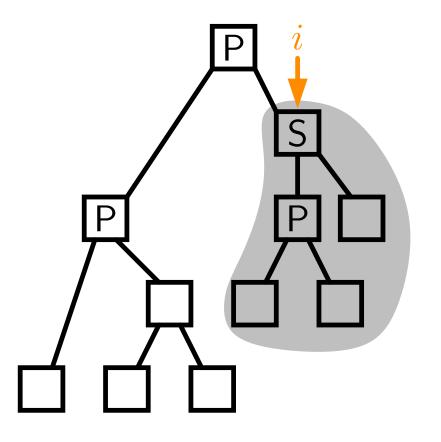
Dynamic program on SP-tree indexed by G(i)



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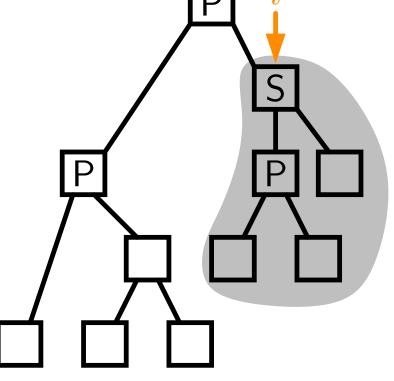
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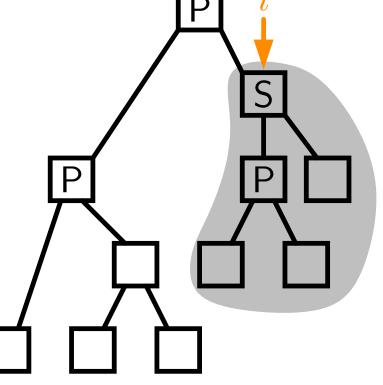


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AB(i) and BB(i) are defined similarly.



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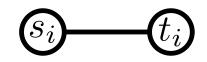
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- If i is a leaf...



#### BB(i) = 0

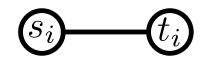
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BA(i) = BB(i) = 0

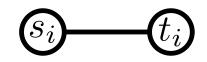
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 $BA(i) = \omega(t_i)$ BB(i) = 0

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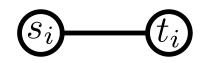
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$$AA(i) =$$

$$AB(i) = \omega(s_i)$$

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$$BB(i) = 0$$



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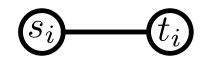
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AB(i) and BB(i) are defined similarly.

- If i is a leaf...

 $AA(i) = -\infty$   $AB(i) = \omega(s_i)$   $BA(i) = \omega(t_i)$ BB(i) = 0



Dynamic program on SP-tree indexed by G(i)

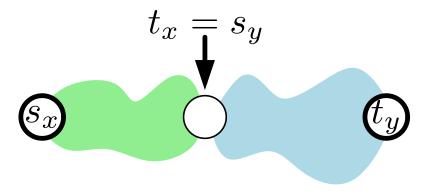
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- If i is a series composition with children x and y, ...

AA(i) =



Dynamic program on SP-tree indexed by G(i)

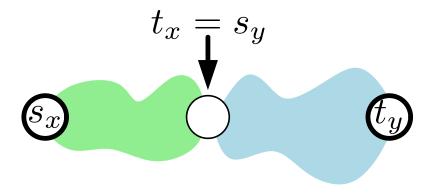
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$$AA(i) = \max\{$$



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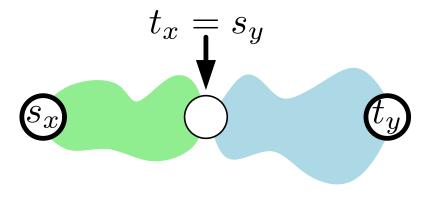
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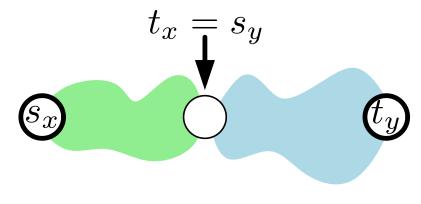
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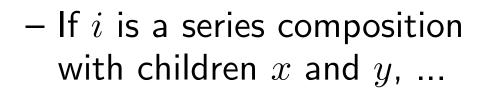


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 $AA(i) = \max\{AB(x) + BA(y), AA(x) + AA(y) - \omega(t_x)\}$ 

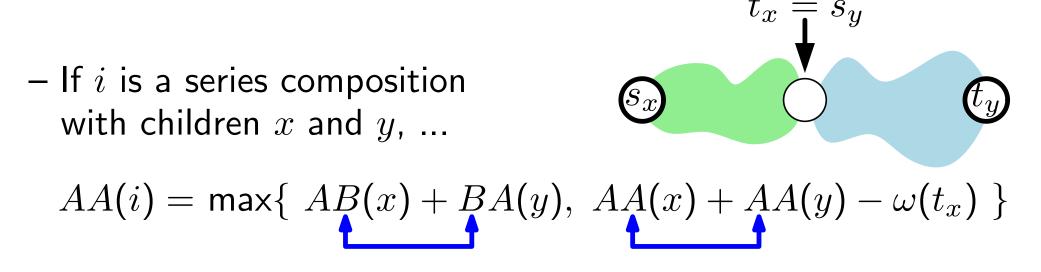
 $(s_x)$ 

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- -O(1) time per SP-node.

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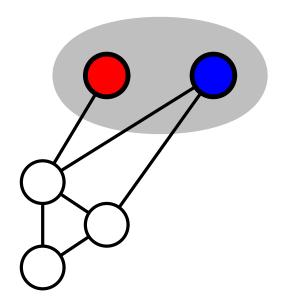
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- Other cases omitted... (easy exercise).
- -O(1) time per SP-node.
- **Thm.** Given an *n*-vertex series-parallel graph G with its SP-tree, INDEPENDENT SET on G can be solved in O(n) time.

Many ways to generalize the concept of having a "tree structure"

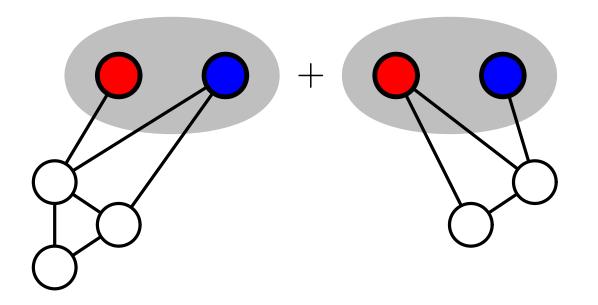
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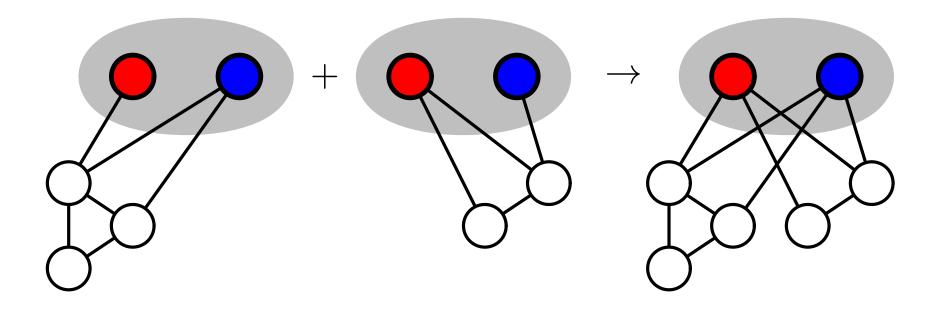


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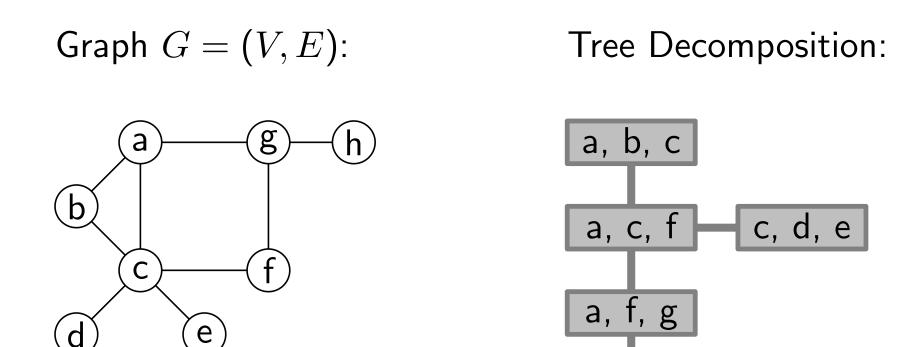


Many ways to generalize the concept of having a "tree structure"

#### **Example:** k-terminal graph G = (V, E, T), |T| = kOperation: "gluing"



A *tree decomposition* is a tree whose nodes map to subsets of V so that...

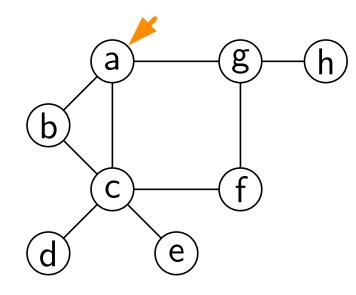


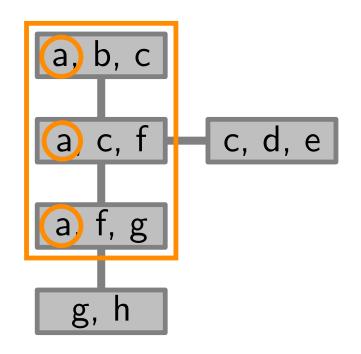
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'bags"

- each vertex belongs to at least one bag
- 1 these bags are connected

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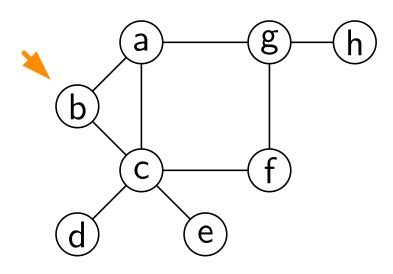


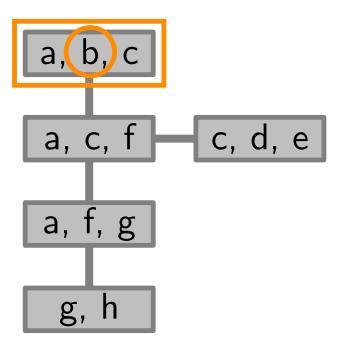


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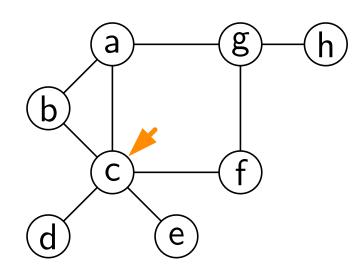


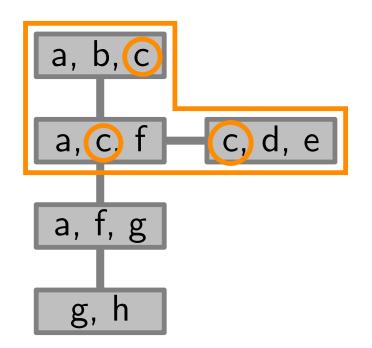




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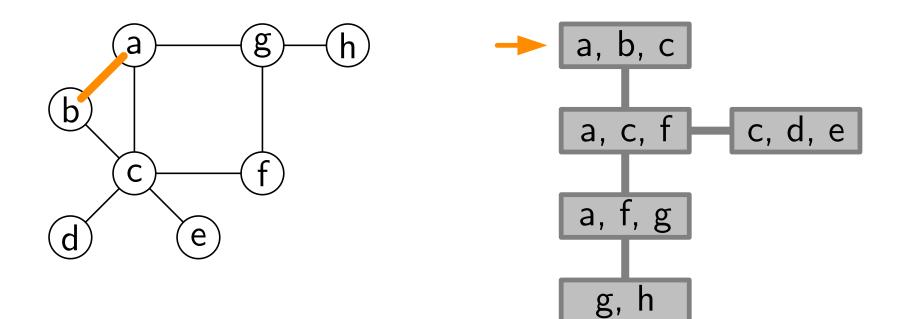




2

each edge is contained in at least one bag

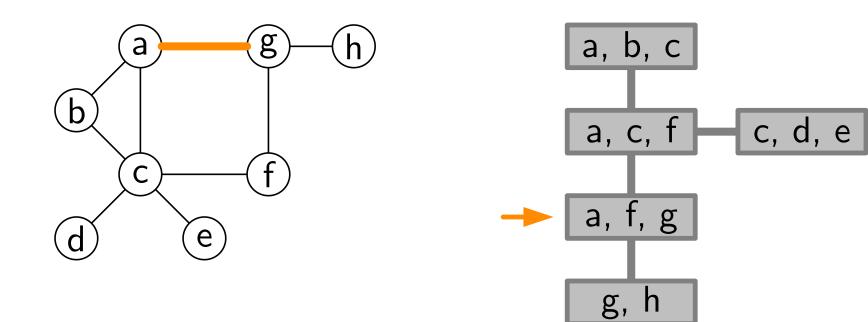
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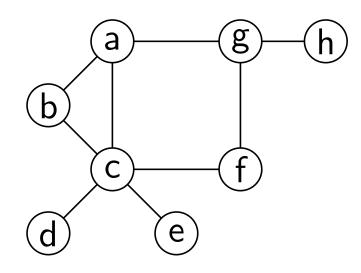
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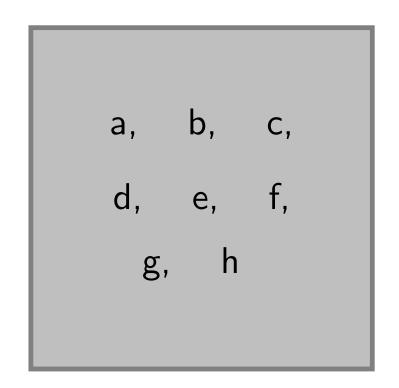
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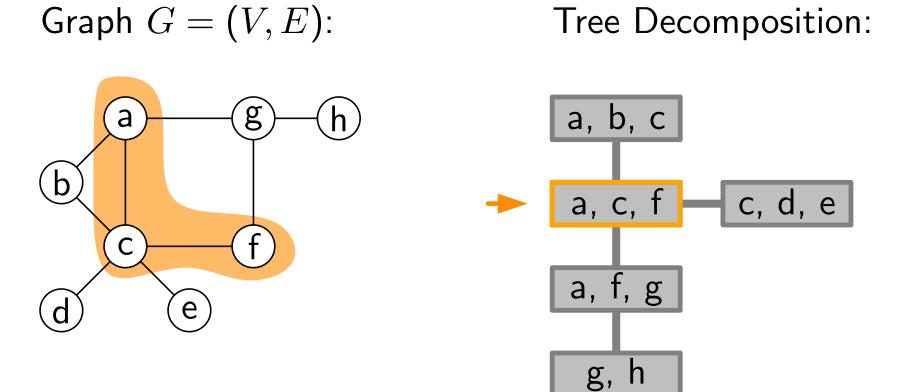
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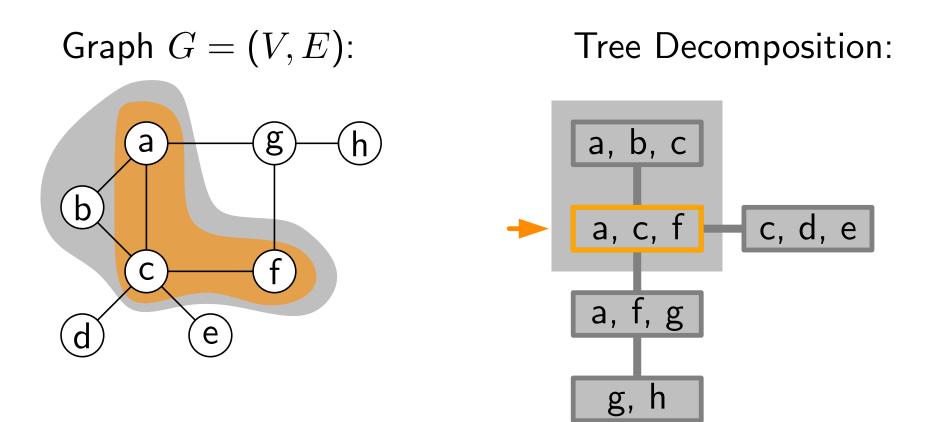


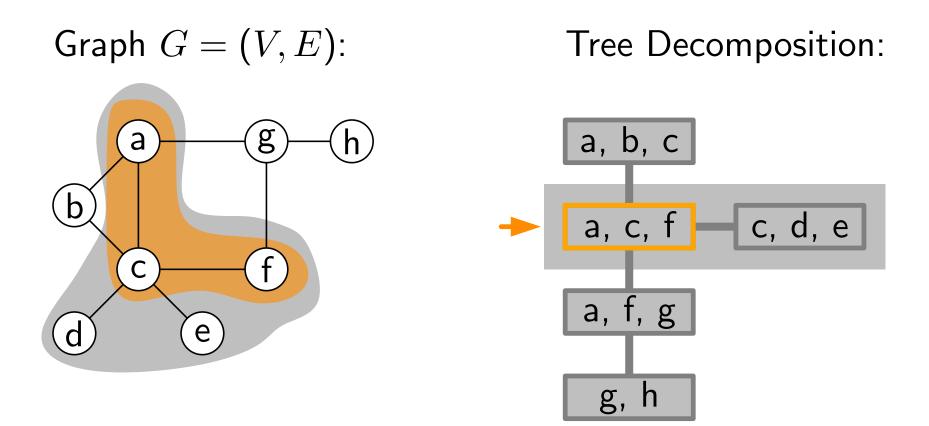
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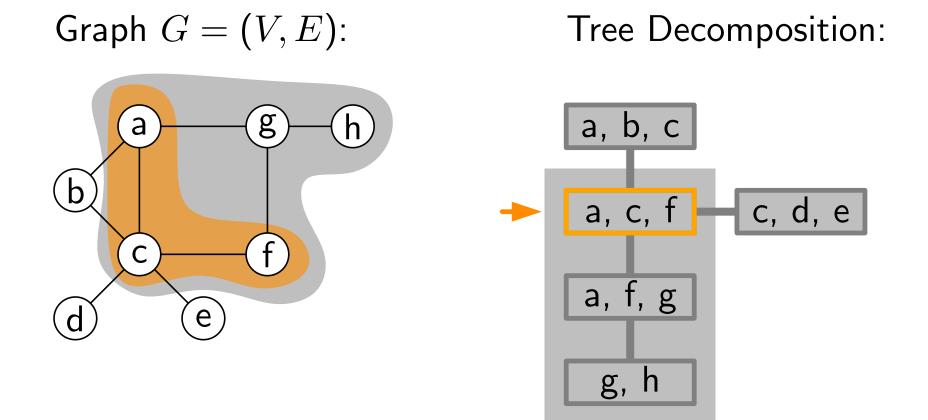


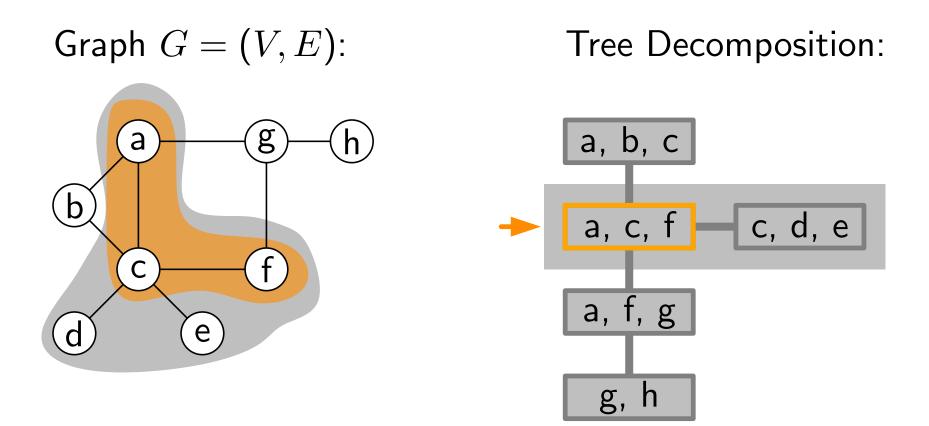


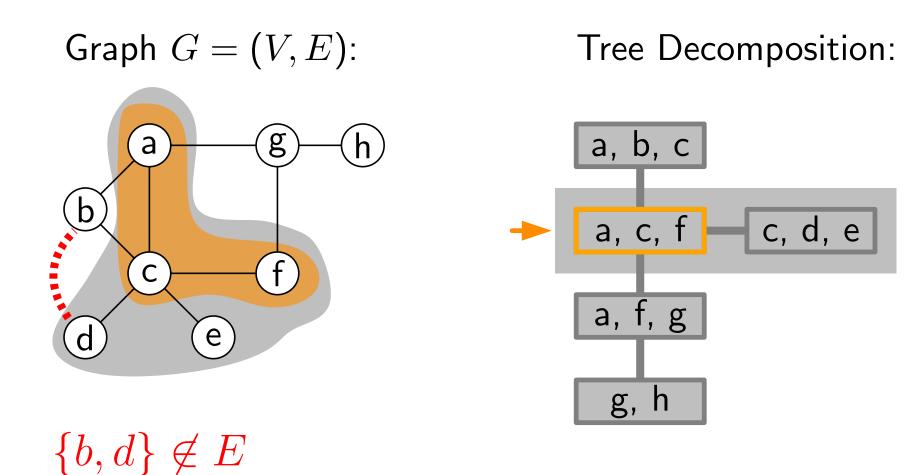




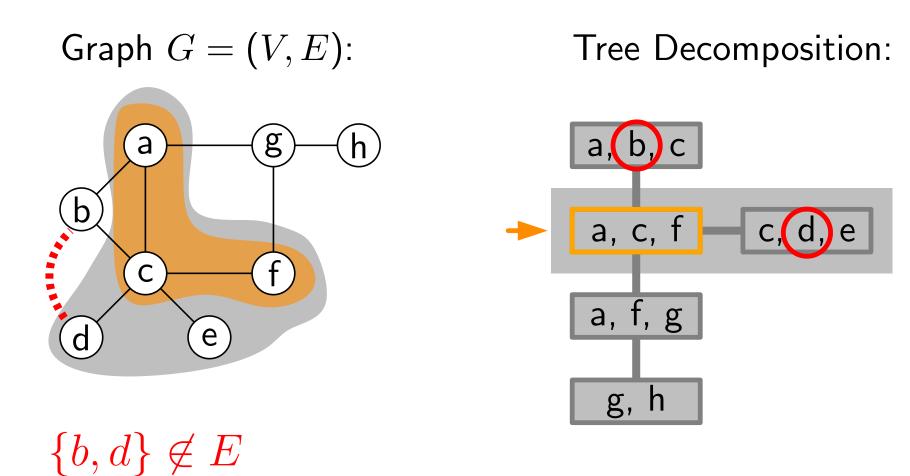






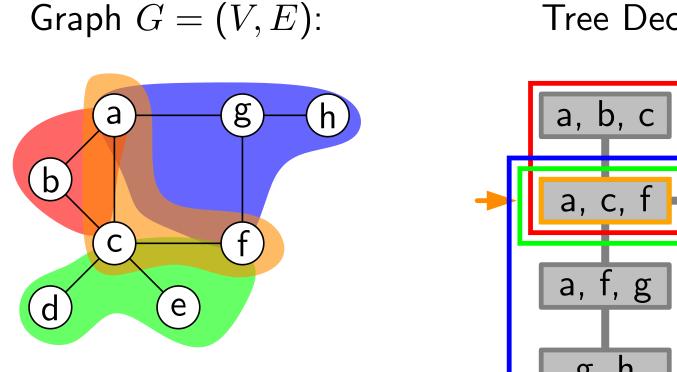


#### **Example:** Tree Decomposition

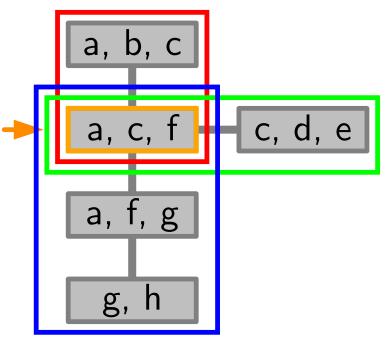


#### 8

#### **Example:** Tree Decomposition



#### Tree Decomposition:



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 \* natural parameterization"

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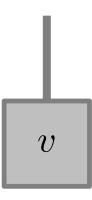
#### Thm. k-TREEWIDTH is FPT.

- Actually fixed-parameter linear: runtime  $O(f(k) \cdot n)$
- Algorithm is constructive (provides an optimal tree decomp.)
- How can we make "fixed-treewidth-tractable" algorithms?

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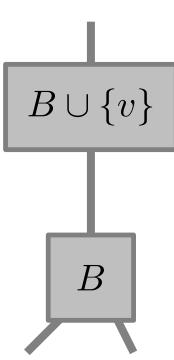


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The bag has exactly one child and contains the child's vertices and exactly one new vertex.



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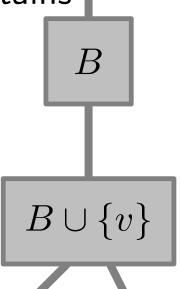
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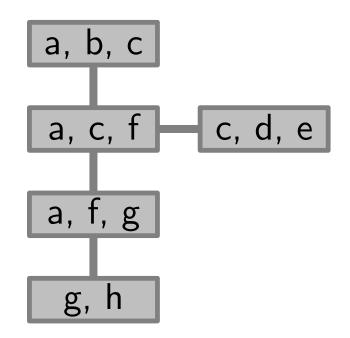
The bag has exactly two children and these three nodes have exactly the same vertices

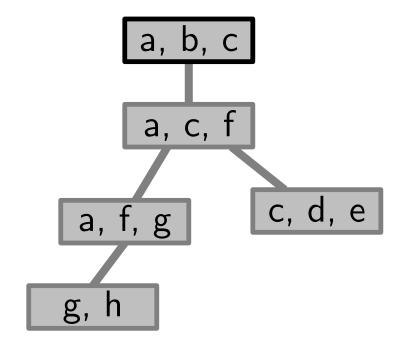
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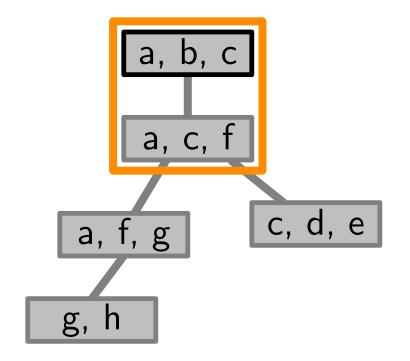
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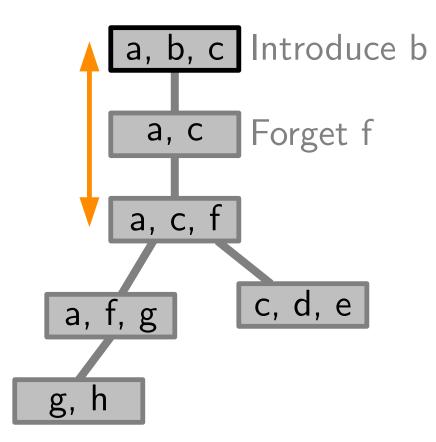
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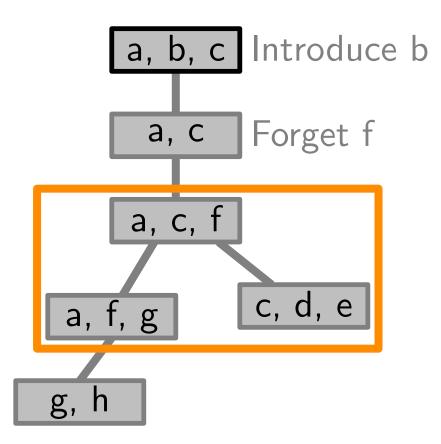
**Thm.** For each tree decomposition, there is a nice tree decomposition of the same width and polynomially many more bags. The nice decomposition can be constructed in polynomial time.

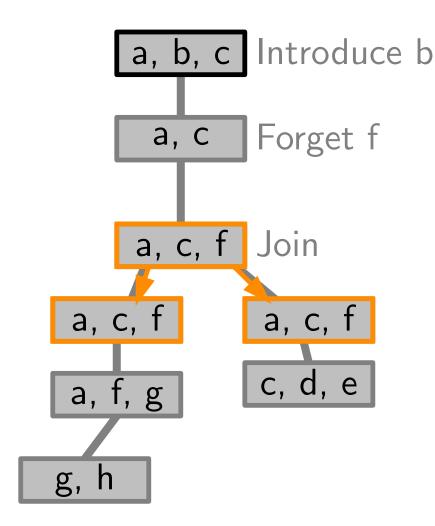


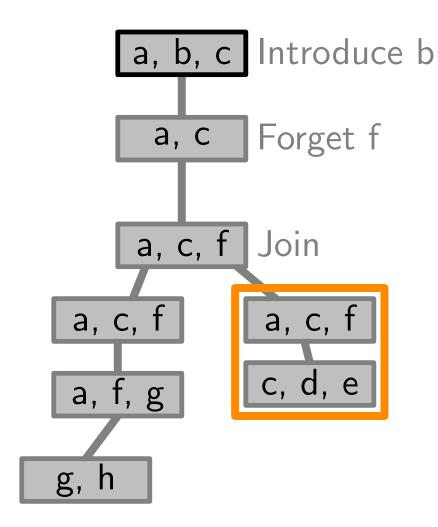


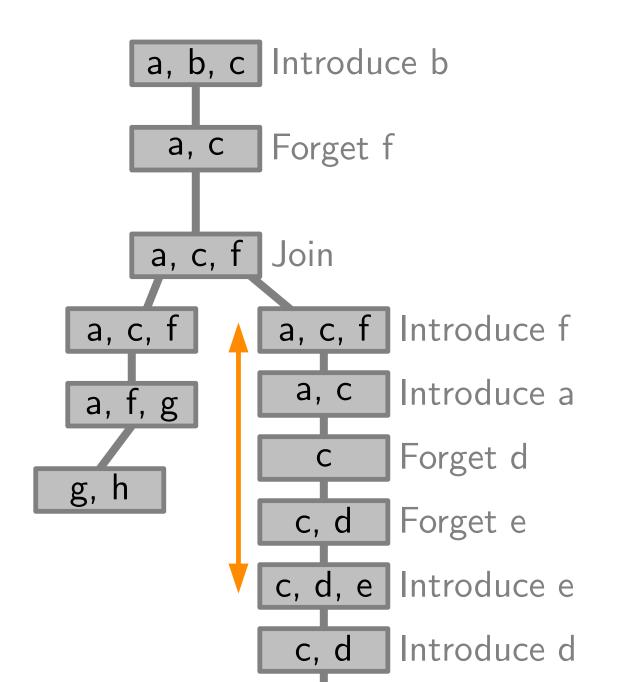


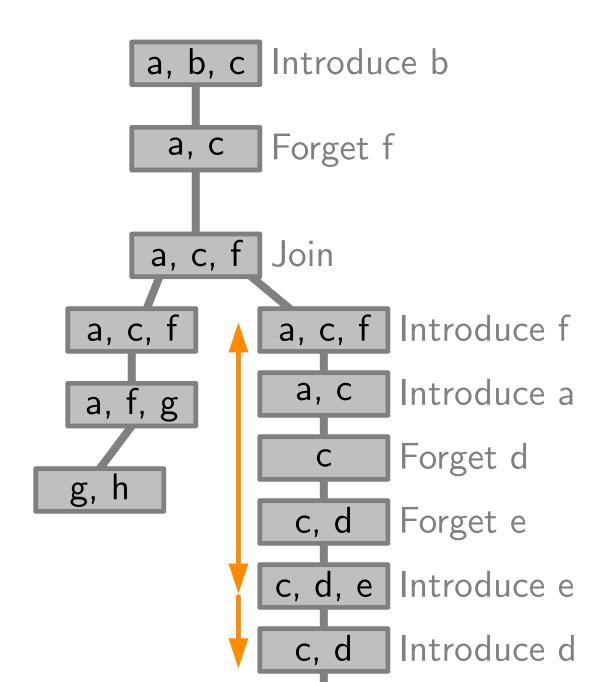


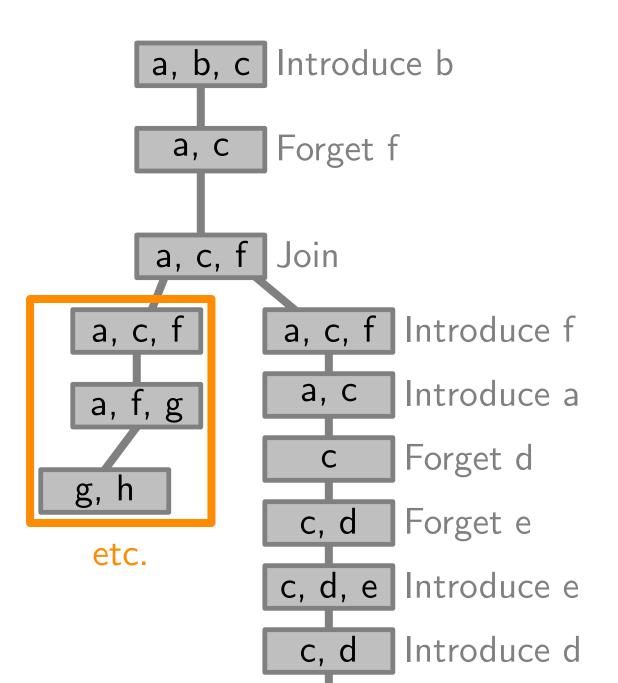












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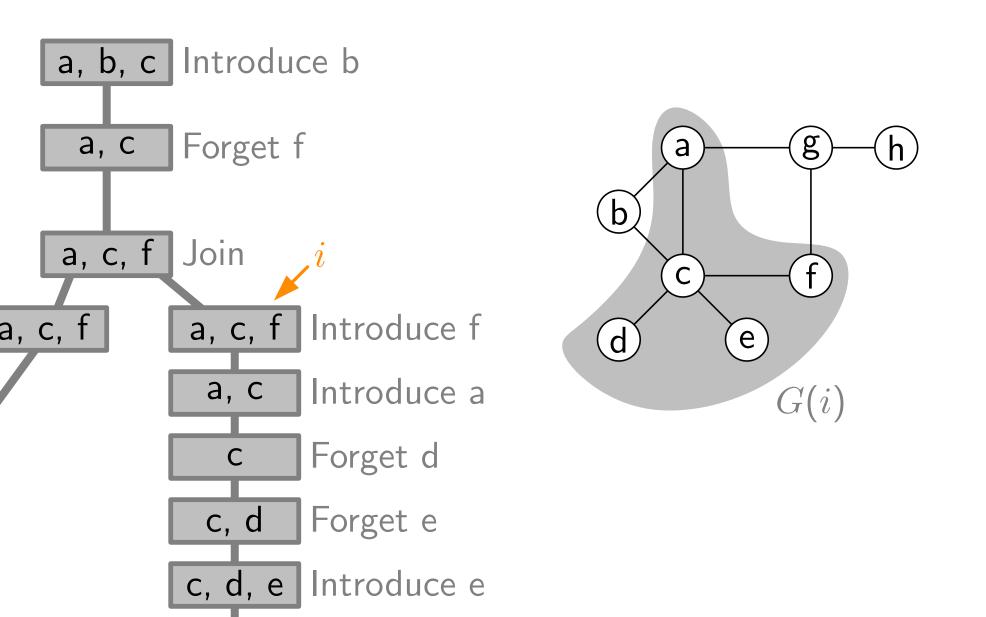
Thm. Tree decompositions can be made *nice* in poly-time.

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**Strategy:** Build a recurrence for each type of bag, and use dynamic programming.

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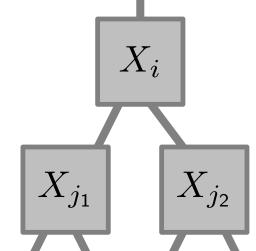
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$$X_i = \{v\}$$
.  
 $R(i, \{v\}) = \omega(v)$   
 $R(i, \emptyset) = 0$ 

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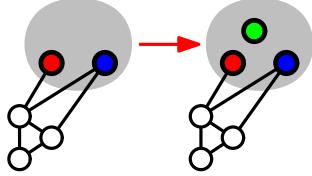


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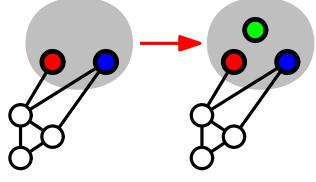
If i is an **Introduce** ... with child j and  $X_i = X_j \cup \{v\}$ 



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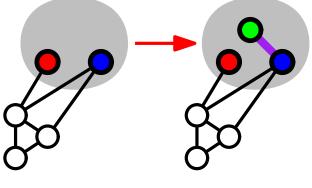


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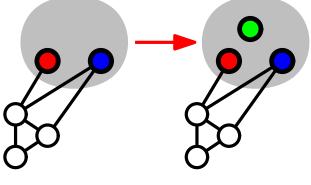
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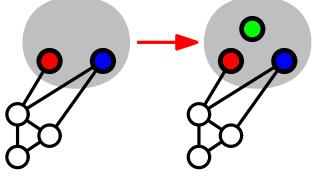
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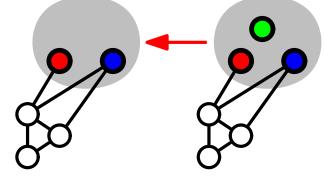
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Otherwise if v has neighbors in S,  $R(i, S) = -\infty$ if v has no neighbors in S,  $R(i, S) = R(j, S \setminus \{v\}) + \omega(v)$ 

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If *i* is a **Forget** ...

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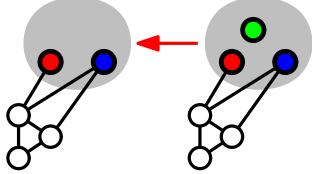
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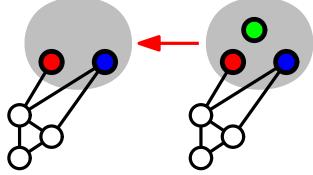


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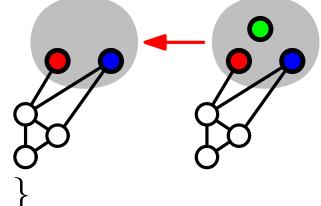


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 $R(i,S) = \max\{ R(j,S), R(j,S \cup \{v\}) \}$ 



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Algorithm: Compute R(i, S) for all i and corresponding S.

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Runtime: ?