



Exact Algorithms

Sommer Term 2020

Lecture 4. Measure & Conquer Based on: [Exact Exponential Algorithms: §6]

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What is Measure & Conquer?

- Method to analyse branching algorithms
- So far: Measure progress via instance size (|V|, |E|, ...).
- Now: Finer measure \Rightarrow improved timing estimates.
- Many of the fastest algorithms use branching and have their time guarantees established via M & C.

Requirements for such a Measure

- The measure of an subinstance obtained by a reduction rule or a branching rule is smaller than the measure of the original instance.
- The measure of each instance is nonnegative.
- Measure of input is upperbounded by function of "natural parameters" of the input, e.g., measure(G) ≤ |V(G)|.
 ⇒ runtime bounds.

Example: Maximum Independent Set



Better Measure than *n*?

Obs. Only vertices with degree ≥ 3 lead to branching. Measure: $k_1(G) = n_{\geq 3} = \#$ vertices of degree ≥ 3

– discarding v reduces the size by \geq 1.

– and (in the worst-case) picking v only removes a single vertex of degree \geq 3 from G

 \Rightarrow branching vector: (1,1) \Rightarrow runtime $O^*(2^n)$:-(

Idea. Since degree-2-vertices are not removed immediately, they should be considered in our measure! (for some weighting $0 < w_2 \le 1$) New measure: $k_2(G) = w_2n_2 + n_{\ge 3} \le n$ (!!)

Lemma. Algorithm MIS runs in $O^*(1.3248^n)$ time.

Proof. Let's try $w_2 = 1/2$ and see ...

Analysis with M & C

*) Balancing lemma: $\tau(i,j) > \tau(i+\epsilon,j-\epsilon)$ for 0 < i < j and $0 < \epsilon < \frac{j-i}{2}$

return
$$\max(1 + MIS(G - N[v]), MIS(G - v))$$

IN := decrease of $k_2(G)$ if N[v] is deleted. OUT := decrease of $k_2(G)$ if v is deleted. \Rightarrow IN, OUT \ge 1, since v is always deleted and deg(v) \ge 3. Consider $w \in N(v)$. Recall: $k_2(G) = n_2/2 + n_{>3}$ 1. If $\deg(w) \geq 3 \Rightarrow w$ holds the value 1 for IN. $\frac{1}{2}$ for IN & OUT. 2. If deg(w) = 2 \Rightarrow IN + OUT $\ge 2 + \deg(v)$. Back to $v \dots$ 1. If $\deg(v) \ge 4 \implies \tau(\mathsf{OUT},\mathsf{IN}) \stackrel{\scriptscriptstyle(\star)}{\le} \tau(1,5) < 1.3248$ 2. If $deg(v) = 3 \Rightarrow G$ has only vertices of degree 2 or 3. \Rightarrow Deleting v or N[v] reduces $k_2(G)$ by $\geq \frac{1}{2}$ per neighbor. \Rightarrow IN, OUT $\ge 1 + \frac{3}{2} \Rightarrow \tau(OUT, IN) \le \tau(\frac{5}{2}, \frac{5}{2}) < 1.3196$.

Further Fine Tuning

General measure: $k(G) = \sum_{i=0}^{n-1} w_i n_i \leq n$ if all $w_i \in [0, 1]$. Set $w_0 = w_1 = 0$ because vertices of degree 0 or 1 do not occur when branching. Pick $0 \le w_2 \le w_3 \le 1$ and set $w_4 = w_5 = \cdots = w_n = 1$. Best choices: $w_2 = 0.596601$ $w_3 = 0.928643$ Algorithm MIS runs in $O^*(1.2905^n)$ time. Lemma. Proof. Exercise :-)

Back to Dominating Set. . .

- Best algorithm from Lecture #3: $O^*(1.7088^n)$.
- Next slide: simple branching algorithm
 - "Convential" analysis: runtime $O^*(1.9052^n)$
 - Measure & Conquer: runtime $O^*(1.5259^n)$
- Model instances of DS as instances (U, S) of Set Cover, where -U = V and $-S = \{N[v]: v \in V\}.$
- There are faster SC algorithms for large |S|: runtime $O^*(2^n)$.
- Our Goal: runtime $O^*(c^{|U|+|S|})$ for some $c \ll 2$ for SC. \Rightarrow runtime $O^*(c^{2n})$ for Dom. Set, where n = |V|.
- W.I.o.g. $U = \bigcup S \Rightarrow$ input given by S.
- Define frequency f(v) = number of sets that contain v.

Algorithm for Set Cover

```
int SC(set family S)
  if S = \emptyset then return 0
  if \exists S, R \in S and S \subset R then return SC(S \setminus \{S\})
  if \exists v \in \bigcup S with f(v) = 1 then
       S \ni v
       return 1 + SC(del(S,S)) // del(S,S) = {R \setminus S \neq \emptyset \mid R \in S}
  S = \arg \max\{|S'| \colon S' \in \mathcal{S}\}
  if |S| = 2 then solve S in polytime.
                                                                 // Exercise!
  if |S| \ge 3 then return min(SC(S \setminus \{S\}), 1 + SC(del(S,S)))
Standard analysis: Measure k(S) = |S| + |\bigcup S|
T(k) \leq T(k-1) + T(k-4), T(1,2,3,4) \in O(1)
\Rightarrow T(k) \in O^*(1.3803^k)
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 \Rightarrow Runtime for DS: $O^*(1.3803^{2n}) = O^*(1.9052^n)$

Idea for a Finer Analysis

- Deleting large sets reduces the frequency of many elements.
- Reducing the frequency of an element can eventually lead to a frequency of 1 → selecting a set.
- Deleting a high-frequency element reduces the size of *many* sets.
- Reducing the size of sets is useful since sets contained in other sets are removed.

 $n_i = \#$ sets of size i in S

 $m_j = \#$ elements of frequency j in $U = \bigcup \mathcal{S}$

New measure: $k(S) = \sum_{i \ge 1} w_i n_i + \sum_{j \ge 1} v_j m_j$ $w_i, v_j \in [0, 1]$ Note: $k(S) \le |S| + |U| \Rightarrow$ Runtime depends on |S| + |U|as desired.

Simplifying Observations

Our new measure $k(S) = \sum_{i \ge 1} w_i n_i + \sum_{j \ge 1} v_j m_j$: $n_i = \#$ sets of size i in S $m_j = \#$ elements of frequency j in U

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$$w_i \leq w_{i+1}$$
, and $v_i \leq v_{i+1}$

- $w_1 = v_1 = 0$
- $w_i = v_i = 1$ for every $i \ge 6$
- $\Delta w_i \geq \Delta w_{i+1}$, where $\Delta w_i = w_i w_{i-1}$ and $\Delta v_i = v_i v_{i-1}$

The analysis breaks into two branches: IN and OUT.

Analysis of $S_{OUT} := S \setminus \{S\}$ Our new measure $k(S) = \sum_{i>1}^{k_w(S)} w_i n_i + \sum_{j>1}^{k_v(S)} v_j m_j$: (a) Reduction in $k_w(S)$ from deleting S: $w_{|S|}$ (b) $r_i := \#$ elements in S of frequency i $\Rightarrow \sum_{i \ge 1} r_i = |S|$ Reduction in $k_v(S)$ from deleting S: $\sum_{i=2}^{6} r_i \cdot \Delta v_i$ $\Delta v_i = 0$ for i > 7(c) If $r_2 > 0$: Let R_1, \ldots, R_h be the sets $\neq S$ that share at least one element of frequency 2 with S. $\Rightarrow 1 \leq h \leq r_2$. Removing $S \Rightarrow$ selects R_1, \ldots, R_h without branching! $r_{2,i} := \#$ frequency-2 elements in $R_i \cap S \implies \sum_{i=1}^h r_{2,i} = r_2$ $R_i \not\subseteq S \Rightarrow |R_i| \geq r_{2,i} + 1$. S largest $\Rightarrow |S| \geq \max_i r_{2,i} + 1$. Selecting $R_i \Rightarrow$ reduction in $\frac{k_w(\mathcal{S})}{|R_i|} \ge w_{r_{2,i}+1}$. At least one element $e_i \in R_i \setminus S$ is covered. \Rightarrow Reduction in $k_v(\mathcal{S})$: at least $v_{f(e_i)} \ge v_2$.

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Analysis of S_{OUT} (cont'd)

 $\Delta k' = \begin{cases} 0 & \text{when } r_2 = 0, \\ v_2 + w_2 & r_2 = 1, \\ v_2 + \min\{2w_2, w_3\} & r_2 = 2, \\ v_2 + \min\{3w_2, w_2 + w_3\} & r_2 \ge 3, |S| = 3, \\ v_2 + \min\{3w_2, w_2 + w_3, w_4\} & r_2 \ge 3, |S| \ge 4. \end{cases}$

Total reduction for \mathcal{S}_{OUT} is:

$$\Delta_{\text{OUT}} = w_{|S|} + \sum_{i=2}^{6} r_i \cdot \Delta v_i + \Delta k'$$
(a) size of S
(b) freq. of elements in S
(c) freq. & size of frequency-2 elements in S

Analysis of $S_{IN} := del(S, S)$

(a) Reduction in $k_w(S)$ by dropping $S: w_{|S|}$ (b) Reduction in $k_v(S)$ by dropping S: $\sum_{i=2}^{6} r_i v_i + r_{>7}$ (c) Reduction in $k_w(S)$ from shrinking sets that intersect S: Let R be a set with $S \cap R \neq \emptyset$, and $v \in R \cap S$. Then v contributes to the reduction: $\Delta w_{|R|} \ge \Delta w_{|S|}$. i.e. reduction $\geq \Delta k'' := \Delta w_{|S|} \cdot \left(\sum_{i=2}^{6} (i-1)r_i + 6r_{\geq 7} \right)$ Each element of frequency i belongs to i - 1 sets $\neq S$.

$$\Rightarrow \Delta_{\mathsf{IN}} = w_{|S|} + \sum_{i=2}^{6} r_i v_i + r_{\geq 7} + \Delta k''.$$

$$\Rightarrow \text{Recurrence for fixed weights } v \text{ and } w:$$

$$\text{For each } |S| \geq 3 \text{ and } (r_i)_i \text{ with } |S| = \sum r_i:$$

$$T(k) \leq T(k - \Delta_{\mathsf{OUT}}) + T(k - \Delta_{\mathsf{IN}}). \text{ What's the worst case?}$$

Optimizing the Branching Vector

Obs. Every branching vector for $|S| \ge 7$ is dominated by some branching vector for |S| = 7.

Reason: Consider formulas for Δ_{OUT} and Δ_{IN} :

 $\begin{array}{lll} \Delta_{\mathsf{OUT}} = w_{|S|} &+& \sum_{i=2}^{6} r_i \Delta v_i &+& \Delta k' \\ \Delta_{\mathsf{IN}} &= w_{|S|} + \left(\sum_{i=2}^{6} r_i v_i + r_{\geq 7}\right) + \Delta w_{|S|} \cdot (\dots). \\ \text{Shrinking } |S| \text{ will only reduce the terms.} \\ \text{Important point here is } \Delta w_{|S|} \text{ in } \Delta_{\mathsf{IN}} \dots \\ \text{but } \Delta w_{|S|} \text{ is 0 when } |S| \geq 7. \end{array}$

Obs. Hence it is sufficient to consider configurations with $3 \le |S| \le 7$, and all possible combinations of $(r_i)_i$'s.

Wrap-Up

For each fixed 8-tuple $(w, v) = (w_2, \ldots, w_5, v_2, \ldots, v_5)$, the runtime is bounded by α^k , where α is the largest root of

$$x^t - x^{t - \Delta_{\text{OUT}}} - x^{t - \Delta_{\text{IN}}} = 0$$

and $t = \max(\Delta_{OUT}, \Delta_{IN})$ over all choices of $|S|, r_1, \ldots, r_{|S|}$. Each (w, v) yields the runtime bound $O^*(\alpha_{(w,v)}^{k})$. Goal: Find (w, v) that minimizes $\alpha_{(w,v)}!$ (Use quasi-convex optimization.)

The approximate best solution found here is $\alpha_{(w^{\star},v^{\star})} < 1.2353$.

Thm. SC can be solved in $O^*(1.2353^{|U|+|S|})$ time. Corollary. DS can be solved in $O^*(1.2353^{2n}) = O^*(1.5259^n)$ time.