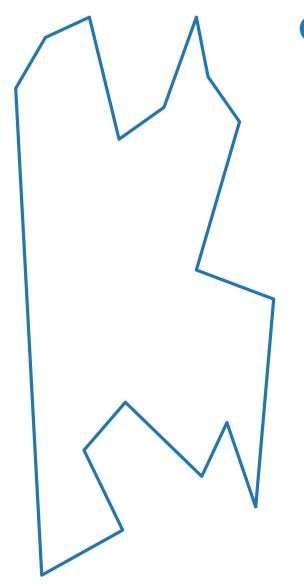




# Computational Geometry

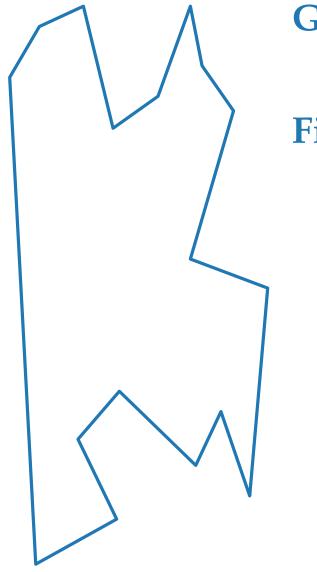
Seidel's Triangulation Algorithm

Lecture #13



Given: Polygon  $P = \langle p_1, \dots, p_n \rangle$ 

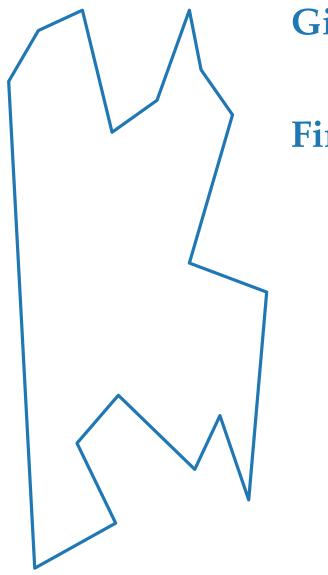
(list of vertices in cw order)



**Given:** Polygon  $P = \langle p_1, \dots, p_n \rangle$ 

(list of vertices in cw order)

**Find:** Triangulation of *P* 

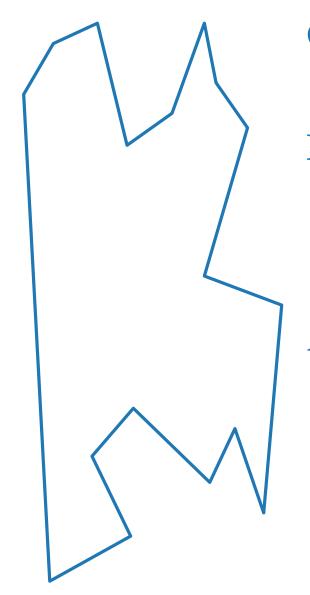


**Given:** Polygon  $P = \langle p_1, \dots, p_n \rangle$ 

(list of vertices in cw order)

**Find:** Triangulation of *P* 

i.e., a partition of P into triangles by diagonals (segments of type  $\overline{p_i p_i} \subset P$ )

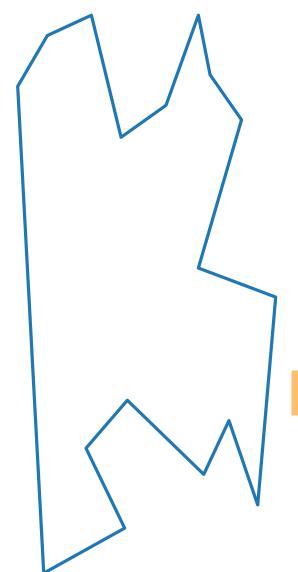


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**Find:** Triangulation of *P* 

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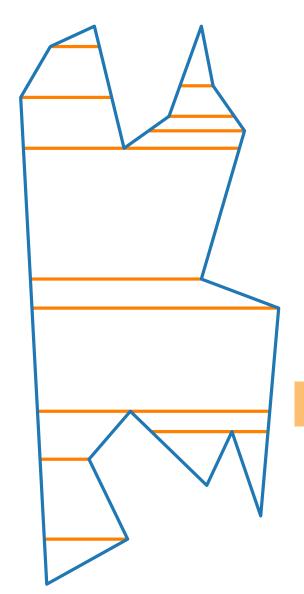
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**Find:** Triangulation of *P* 

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#### Approach:

1. Trapezoidize interior of *P*.



**Given:** Polygon  $P = \langle p_1, \dots, p_n \rangle$ 

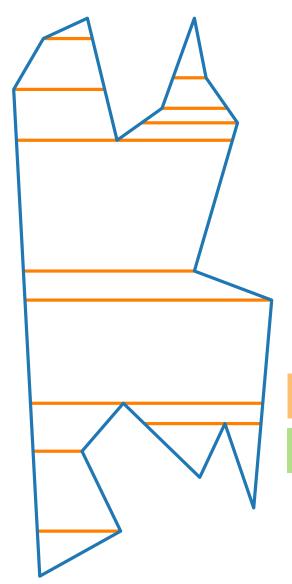
(list of vertices in cw order)

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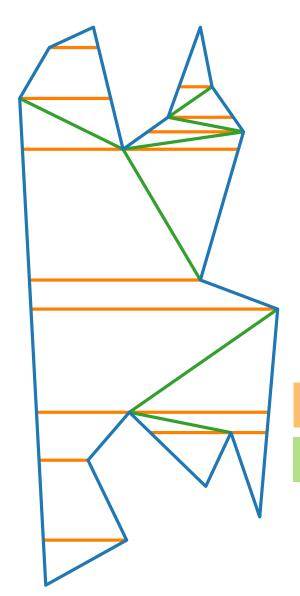
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(list of vertices in cw order)

**Find:** Triangulation of *P* 

i.e., a partition of P into triangles by diagonals (segments of type  $\overline{p_ip_j} \subset P$ )

- 1. Trapezoidize interior of *P*.
- 2. Draw diagonals inside trapezoids.



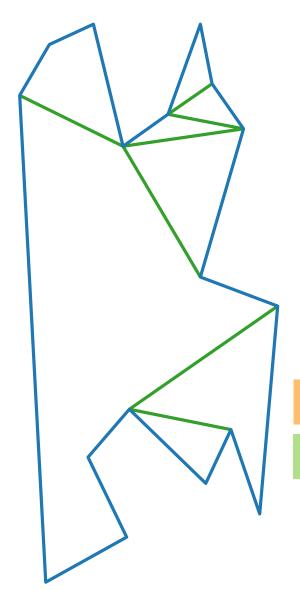
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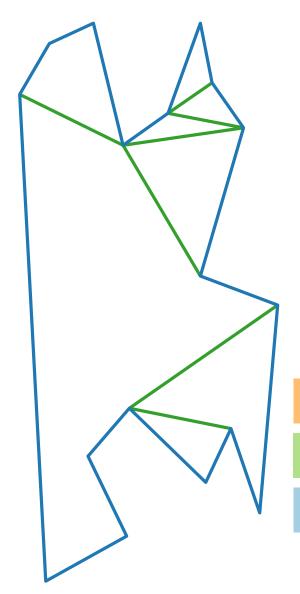
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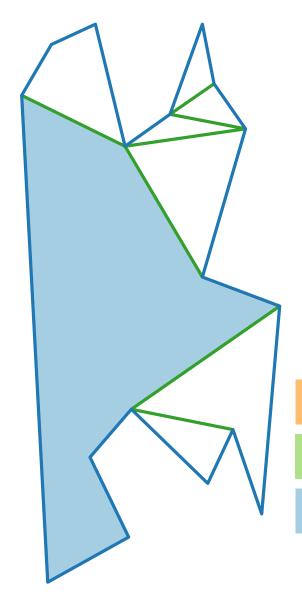
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**Find:** Triangulation of *P* 

i.e., a partition of P into triangles by diagonals (segments of type  $\overline{p_ip_j} \subset P$ )

- 1. Trapezoidize interior of *P*.
- 2. Draw diagonals inside trapezoids.
- 3. Triangulate *y*-monotone subpolygons.



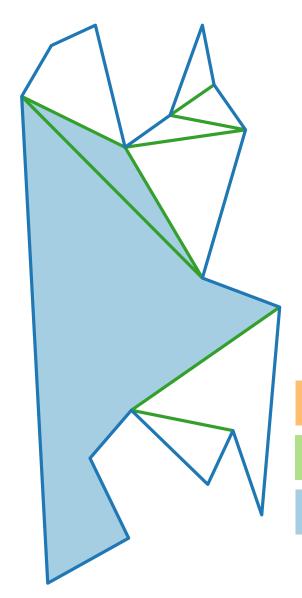
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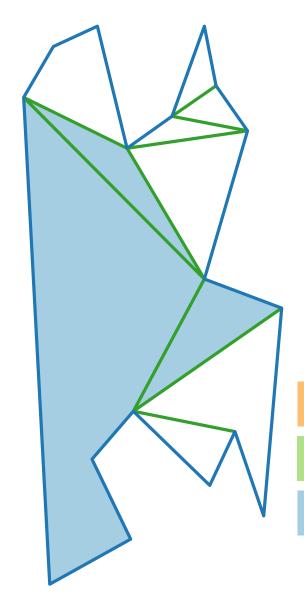
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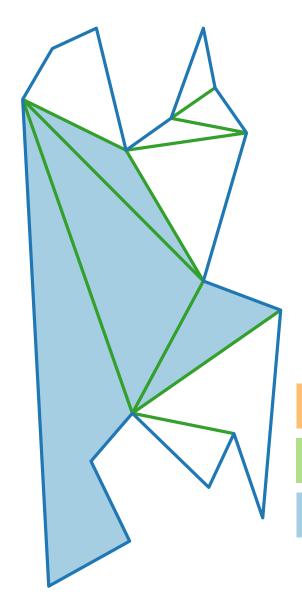
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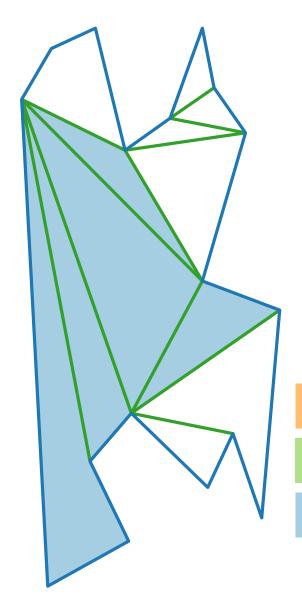
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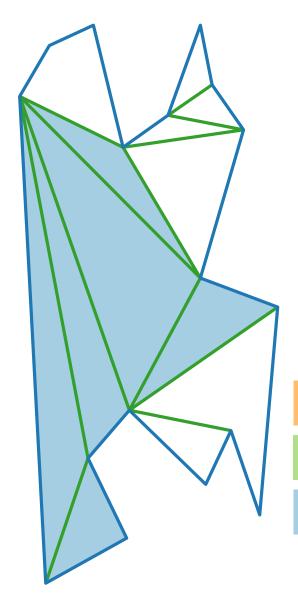
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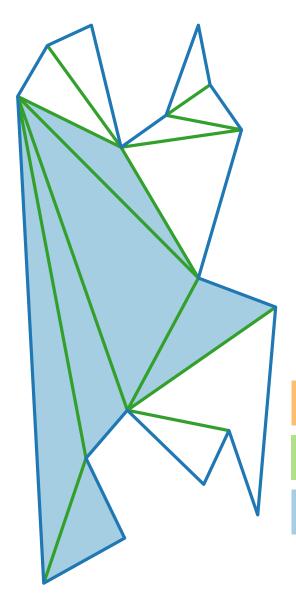
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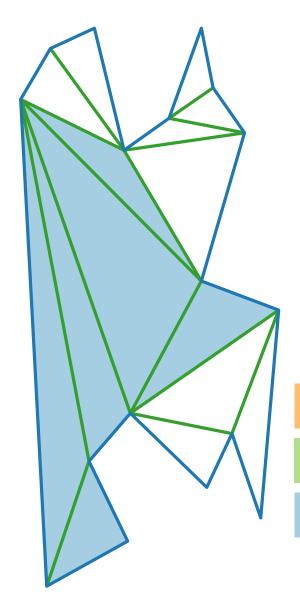
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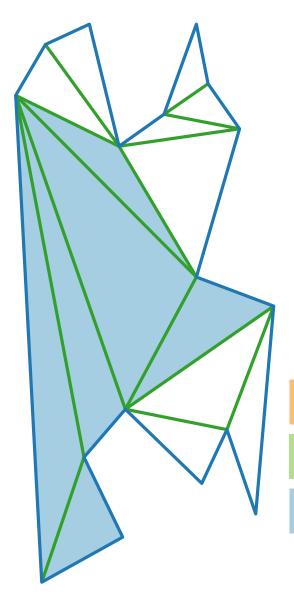
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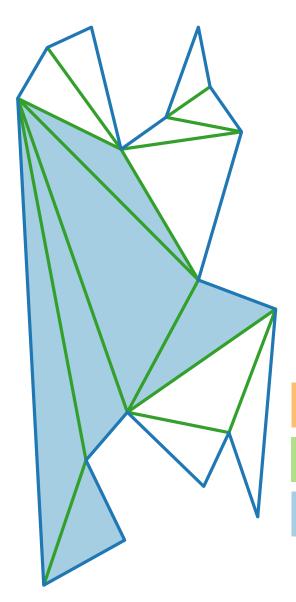
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Running time:

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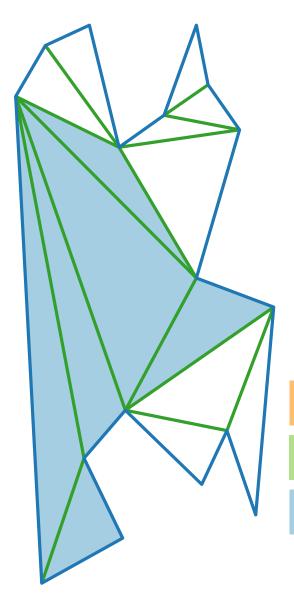
### Approach:

Running time:

1. Trapezoidize interior of *P*.

 $O(n \log n)$ 

- 2. Draw diagonals inside trapezoids.
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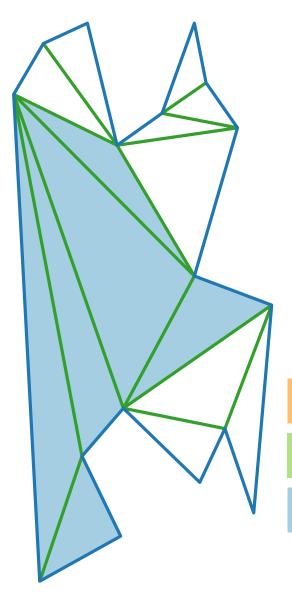
Running time:

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2. Draw diagonals inside trapezoids. O(n)

3. Triangulate *y*-monotone subpolygons.



Polygon  $P = \langle p_1, \dots, p_n \rangle$ Given:

(list of vertices in cw order)

Find: Triangulation of *P* 

> i.e., a partition of *P* into triangles by *diagonals* (segments of type  $\overline{p_i p_i} \subset P$ )

### Approach:

Running time:

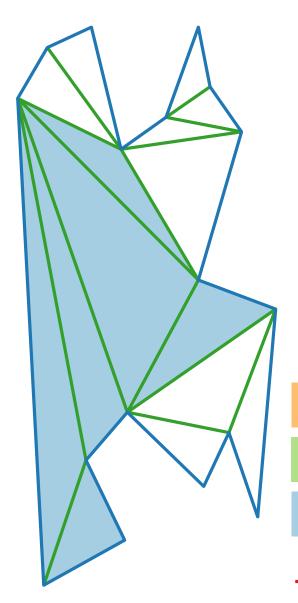
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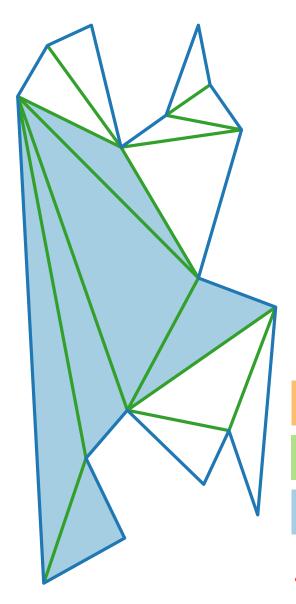
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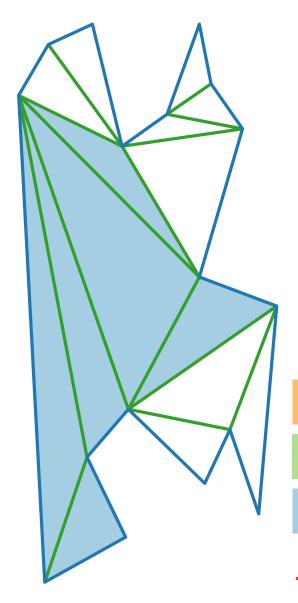
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O(n)

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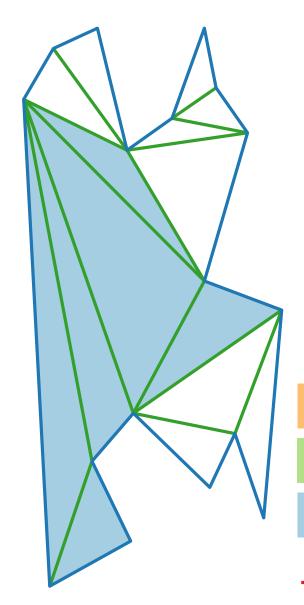
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O(n)

 $O(n \log n)$ 

**Lemma 1.** Given a trapezoidation, *P* can be triangulated in linear time.

Let *S* be a set of *n* non-crossing segments

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#### **WANTED:**

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– point-location data structure Q(S)

Let *S* be a set of *n* non-crossing segments

```
WANTED: – trapezoidation \mathcal{T}(S) of S – point-location data structure \mathcal{Q}(S)
```

Our construction is randomized-incremental:

Let *S* be a set of *n* non-crossing segments

**WANTED:** – trapezoidation  $\mathcal{T}(S)$  of S

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Our construction is randomized-incremental:

Trapezoidation (set *S* of *n* non-crossing line segments)

Let *S* be a set of *n* non-crossing segments

- **WANTED:** trapezoidation  $\mathcal{T}(S)$  of S
  - point-location data structure Q(S)

Our construction is randomized-incremental:

Trapezoidation (set *S* of *n* non-crossing line segments)

 $\langle s_1, s_2, \ldots, s_n \rangle \leftarrow \text{random ordering of } S$ 

Let *S* be a set of *n* non-crossing segments

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Trapezoidation (set *S* of *n* non-crossing line segments)

$$\langle s_1, s_2, \dots, s_n \rangle \leftarrow \text{random ordering of } S$$
  
 $S_0 \leftarrow \emptyset$ 

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Our construction is randomized-incremental:

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Trapezoidation (set S of n non-crossing line segments) \langle s_1, s_2, \ldots, s_n \rangle \leftarrow \text{random ordering of } S
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for i = 1 to n do
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for i = 1 to n do
S_i \leftarrow S_{i-1} \cup \{s_i\}
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Let *S* be a set of *n* non-crossing segments

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WANTED: – trapezoidation \mathcal{T}(S) of S – point-location data structure \mathcal{Q}(S)
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WANTED: – trapezoidation \mathcal{T}(S) of S – point-location data structure \mathcal{Q}(S)
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Our construction is randomized-incremental:

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Trapezoidation (set S of n non-crossing line segments)
\langle s_1, s_2, \dots, s_n \rangle \leftarrow \text{random ordering of } S
S_0 \leftarrow \emptyset
\mathbf{for } i = 1 \mathbf{ to } n \mathbf{ do}
S_i \leftarrow S_{i-1} \cup \{s_i\}
\mathbf{use } \mathcal{T}(S_{i-1}) \mathbf{ and } \mathcal{Q}(S_{i-1}) \mathbf{ to construct } \mathcal{T}(S_i) \mathbf{ and } \mathcal{Q}(S_i)
```

Total cost of one step:

Let *S* be a set of *n* non-crossing segments

```
WANTED: – trapezoidation \mathcal{T}(S) of S – point-location data structure \mathcal{Q}(S)
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Our construction is randomized-incremental:

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```

Total cost of one step: – location time

Let *S* be a set of *n* non-crossing segments

```
WANTED: – trapezoidation \mathcal{T}(S) of S – point-location data structure \mathcal{Q}(S)
```

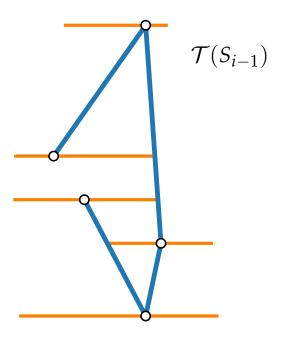
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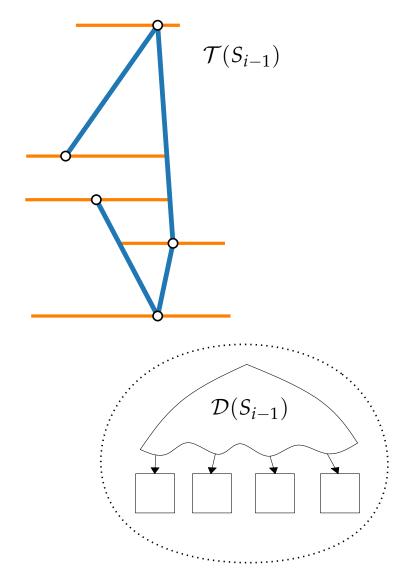
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Trapezoidation (set S of n non-crossing line segments) \langle s_1, s_2, \ldots, s_n \rangle \leftarrow \text{random ordering of } S
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S_i \leftarrow S_i \cap S_i
```

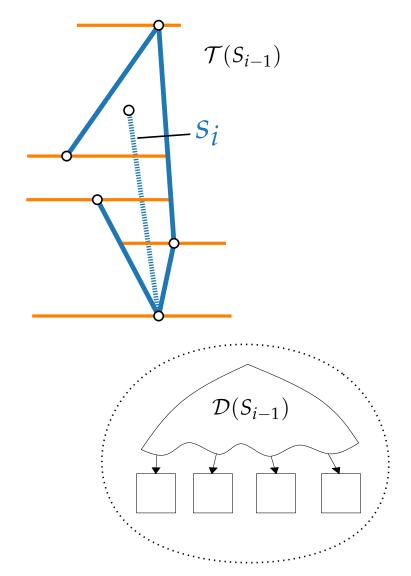
Total cost of one step: – location time – "threading" (updating) time

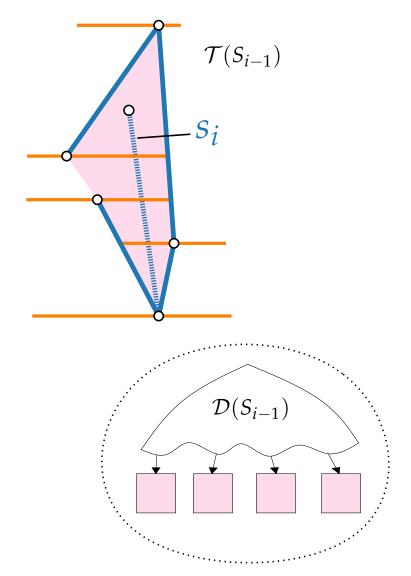
We assume general position (no two points have the same *y*-coordinate).

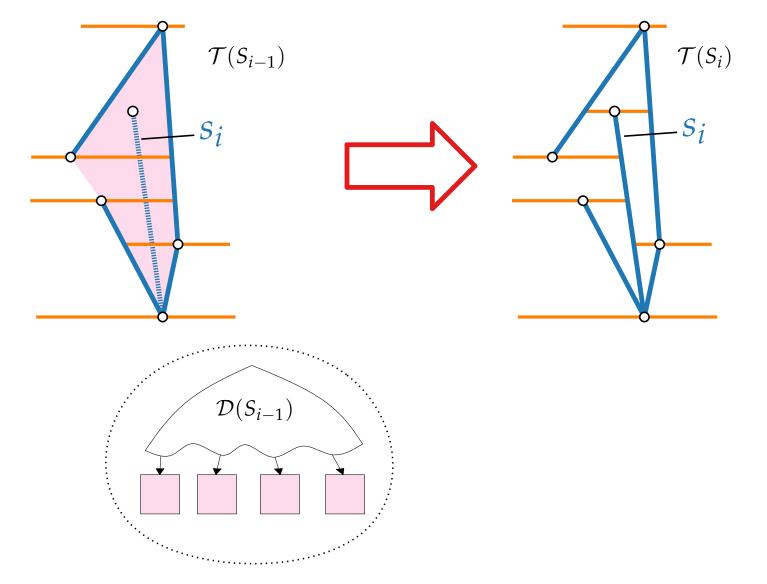
We assume general position (no two points have the same *y*-coordinate). Use lexicographic order!

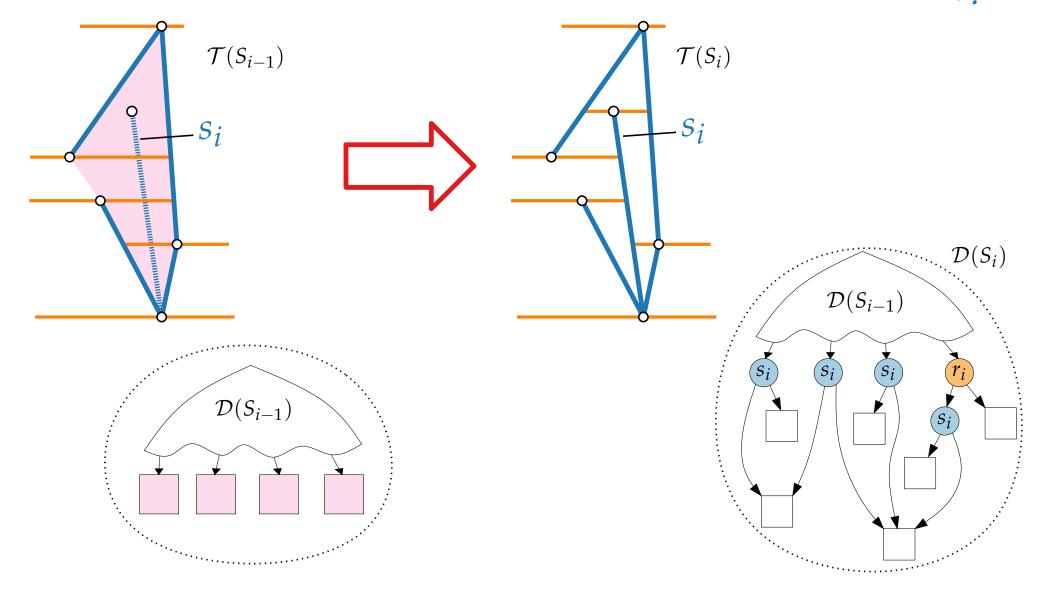


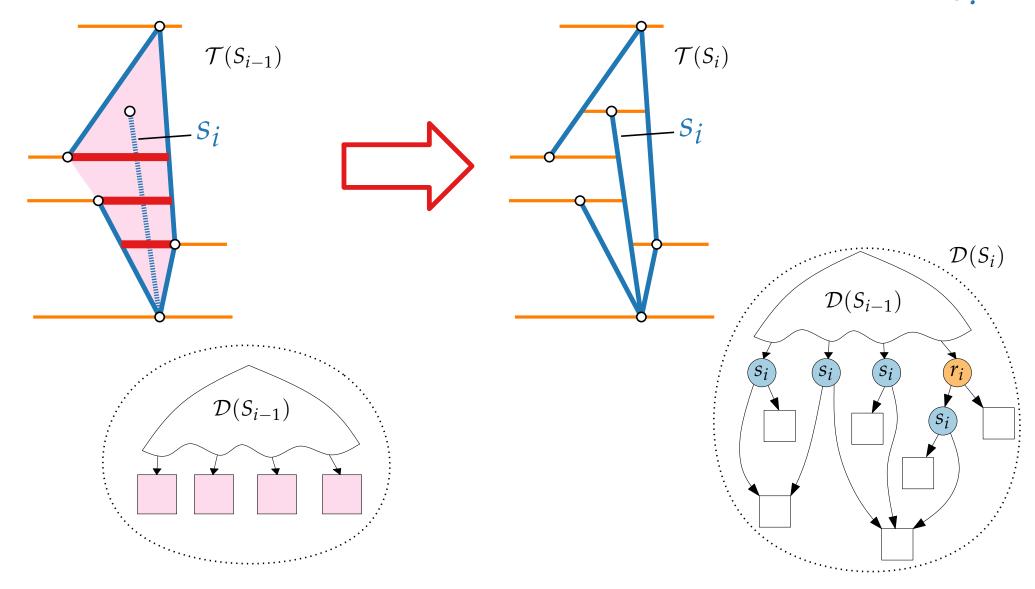












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**Lemma 2.** For i = 1, ..., n, the expected number of rays of  $\mathcal{T}(S_{i-1})$  that are intersected by  $s_i$  is at most 4.

We assume general position (no two points have the same *y*-coordinate).

We assume general position

**Lemma 2.** For i = 1, ..., n, the expected number of rays of  $\mathcal{T}(S_{i-1})$  that are intersected by  $s_i$  is at most 4.

Proof.

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*Proof.* For  $s \in S_i$ , let  $deg(s, \mathcal{T}(S_i)) = \#$  rays of  $\mathcal{T}(S_i)$  that hit the relative interior of s.

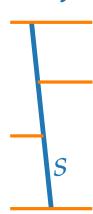
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We assume general position

Order!

**Lemma 2.** For i = 1, ..., n, the expected number of rays of  $\mathcal{T}(S_{i-1})$  that are intersected by  $s_i$  is at most 4.

### Proof.



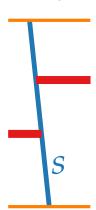
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We assume general position

**Lemma 2.** For i = 1, ..., n, the expected number of rays of  $\mathcal{T}(S_{i-1})$  that are intersected by  $s_i$  is at most 4.

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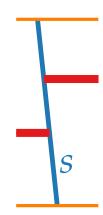
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Order!

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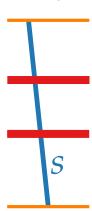
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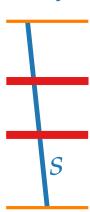
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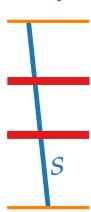
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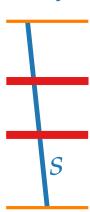
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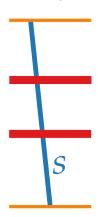
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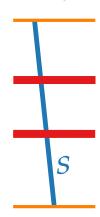
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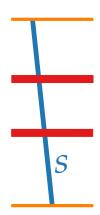
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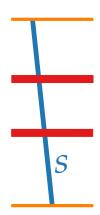
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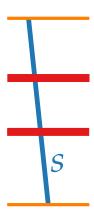
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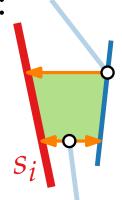
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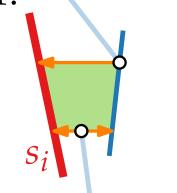
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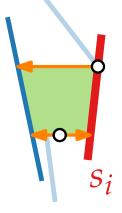
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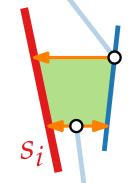
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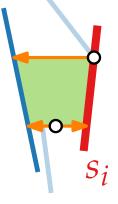
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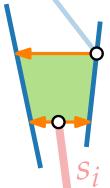
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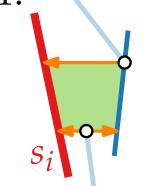
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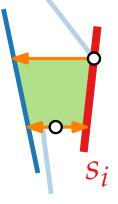
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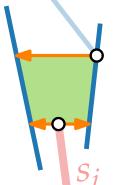
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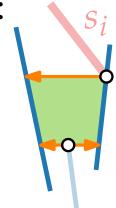
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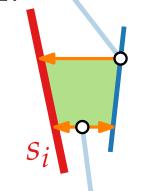
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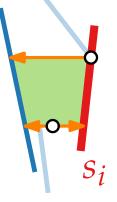
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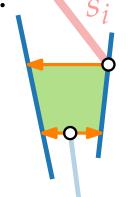
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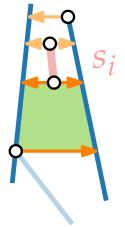
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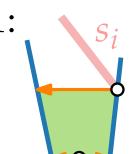
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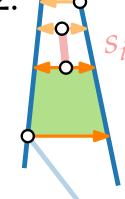
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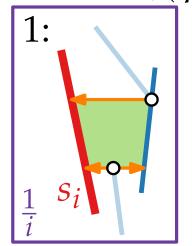
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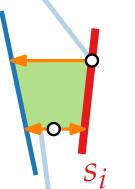
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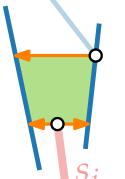
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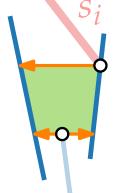
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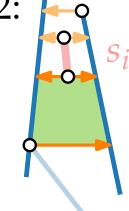


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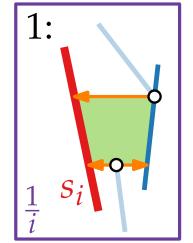
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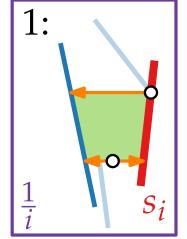
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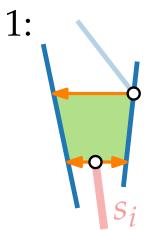
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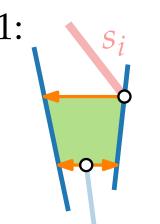
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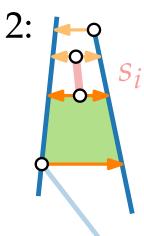
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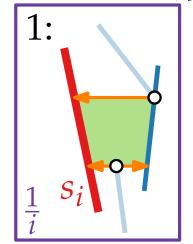
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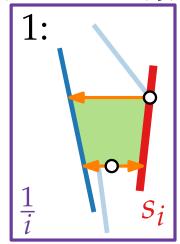
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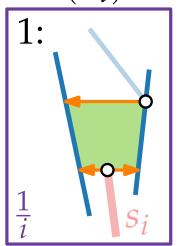
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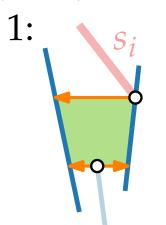
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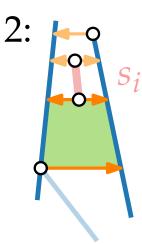
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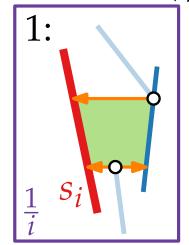
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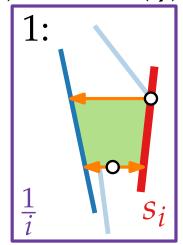
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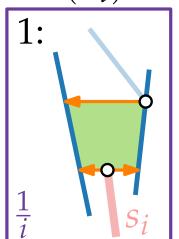
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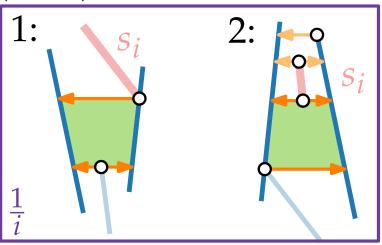
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• We can build  $\mathcal{T}(S)$  and  $\mathcal{Q}(S)$  in  $O(n \log n)$  expected time.

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Aim:

Speed-up construction for simple polygons.

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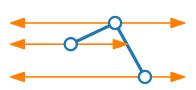
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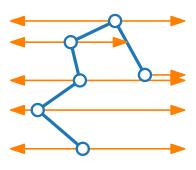


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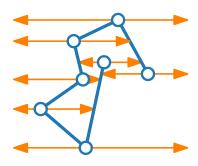


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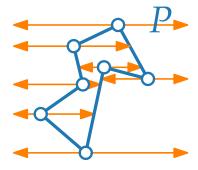


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by walking along the polygon!

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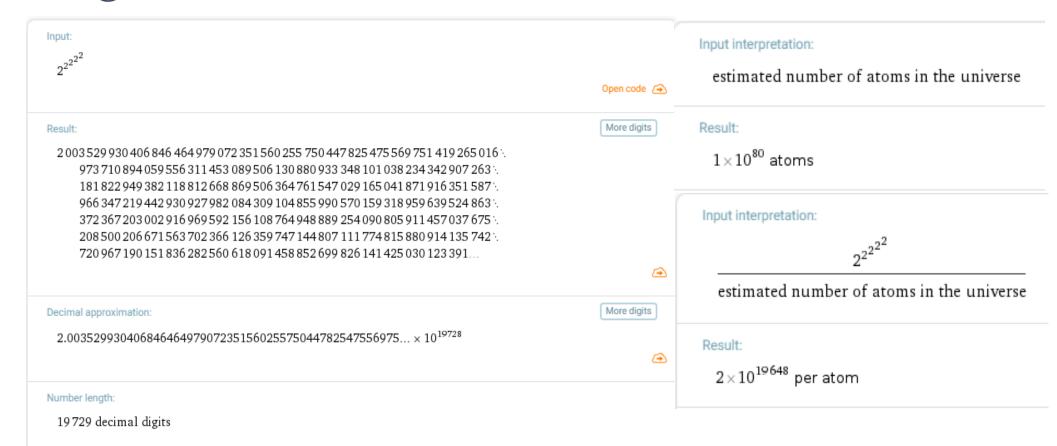
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N(0) = 1,  $N(1) = [n/\log n]$ ,  $N(\log^* n) > n/2$ .

PolygonTrapezoidation ((edges along) simple polygon P)

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3.2

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Step 1: Random permutation

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O(n)

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O(n)

Step 2: Setting up  $\mathcal{T}_1$ ,  $\mathcal{Q}_1$ , and  $\pi(v)$ 

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Step 3: Phases 1 to  $\log^* n$ 

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O(n)

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Lemma  $5 \Rightarrow$ 

**Lemma 5.** *S* as before,  $R \subseteq S$  random subset, r := |R|. Let *I* be the number of intersections between rays of  $\mathcal{T}(R)$  and segments in  $S \setminus R$ . Then  $E[I] \leq 4(n-r)$ , where the expectation is over all size-r subsets of S.

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- threading cost:
- locating cost:

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Step 3.2: Walking the polygon Lemma  $5 \Rightarrow O(n)$ 

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O(n)

Lemma  $5 \Rightarrow$ 

 $(\log^{\star} n)$ .

O(n)

O(n)

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O(n)

# Time Complexity

Step 1: Random permutation

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Lem.  $4 \Rightarrow$  expected location cost

Lemma  $5 \Rightarrow$ 

**Lemma 4.** Let  $1 \le j \le k \le n$  and  $q \in \mathbb{R}^2$ . Suppose location of q in  $\mathcal{Q}(S_j)$  is known, then q can be located in  $\mathcal{Q}(S_k)$  in expected time  $5(H_k - H_j) \in O(\log k/j)$ .

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O(n)

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# Time Complexity

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Step 3.1: Inserting  $s_i = v_i w_i$  using  $Q_{N(h-1)}$ 

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$$N(h) := \lceil n / \log^{(h)} n \rceil$$

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Step 3.2: Walking the polygon

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- threading cost: Lem. 2  $\Rightarrow$  expected O(1) per segm.
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#### The Results

**Theorem.** Let *S* be the edge set of a polygon, |S| = n.

- We can build  $\mathcal{T}(S)$  and  $\mathcal{Q}(S)$  in  $O(n \log^* n)$  expected time.
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**Theorem.** Let *S* be the edge set of a plane straight-line graph with *k* connected components, |S| = n.

- We can build  $\mathcal{T}(S)$  and  $\mathcal{Q}(S)$  in  $O(n \log^* n + k \log n)$  expected time.
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