

# Approximation Algorithms

## Lecture 1: Introduction and Vertex Cover

### Part I: Organizational

# Organizational

Lectures: Fri, 10:15–11:45 (ÜR I)

English/German, depending on audience.

hands-on, with tasks/questions for audience

Tutorials: Tue, 10:15–11:45 (SE I), starting Oct. 21, 2025.

discussing old solutions and solving new tasks

roughly one exercise sheet per lecture

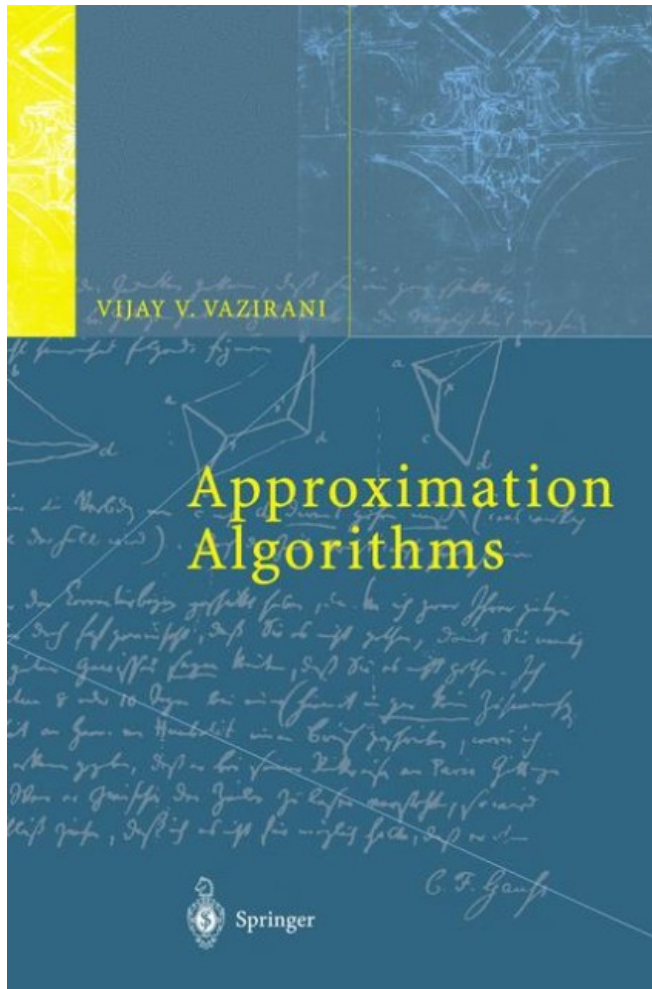
bonus (+0.3 on final grade) for  $\geq 50\%$  points

Up to two students can hand in solutions together.

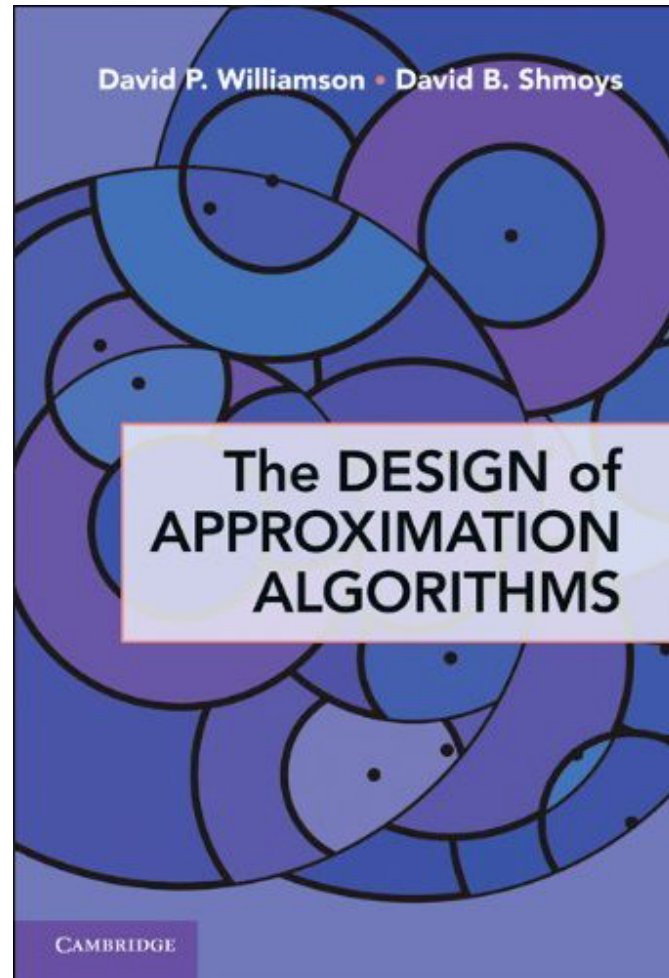
Make sure to write both names!

Most slides are due to Joachim Spoerhase,  
polishing & colors are due to Philipp Kindermann – thanks!

# Textbooks



Vijay V. Vazirani:  
Approximation Algorithms  
Springer-Verlag, 2003.



D. P. Williamson & D. B. Shmoys:  
The Design of Approximation Algorithms  
Cambridge-Verlag, 2011.

<http://www.designofapproxalgs.com/> 

# Approximation Algorithms

„All exact science is dominated by the idea of approximation.“



Bertrand Russell  
(1872–1970)

# Approximation Algorithms

- Many optimization problems are NP-hard!  
(For example, the traveling salesperson problem.)
- $\rightsquigarrow$  an optimal solution cannot be efficiently computed unless  $P=NP$ .
- However, good approximate solutions can often be found efficiently!
- **Techniques** for the design and analysis of approximation algorithms arise from studying specific optimization problems.

# Overview

## Combinatorial algorithms

- Introduction (Vertex Cover)
- Set Cover via Greedy
- Shortest Superstring via reduction to SC
- Steiner Tree via MST
- Multiway Cut via Greedy
- $k$ -Center via Parametrized Pruning
- Min-Degree Spanning Tree and local search
- Knapsack via DP and Scaling
- Euclidean TSP via Quadtrees

## LP-based algorithms

- Introduction to LP-Duality
- Set Cover via LP Rounding
- Set Cover via Primal–Dual Schema
- Maximum Satisfiability
- Scheduling und Extreme Point Solutions
- Steiner Forest via Primal–Dual

# Approximation Algorithms

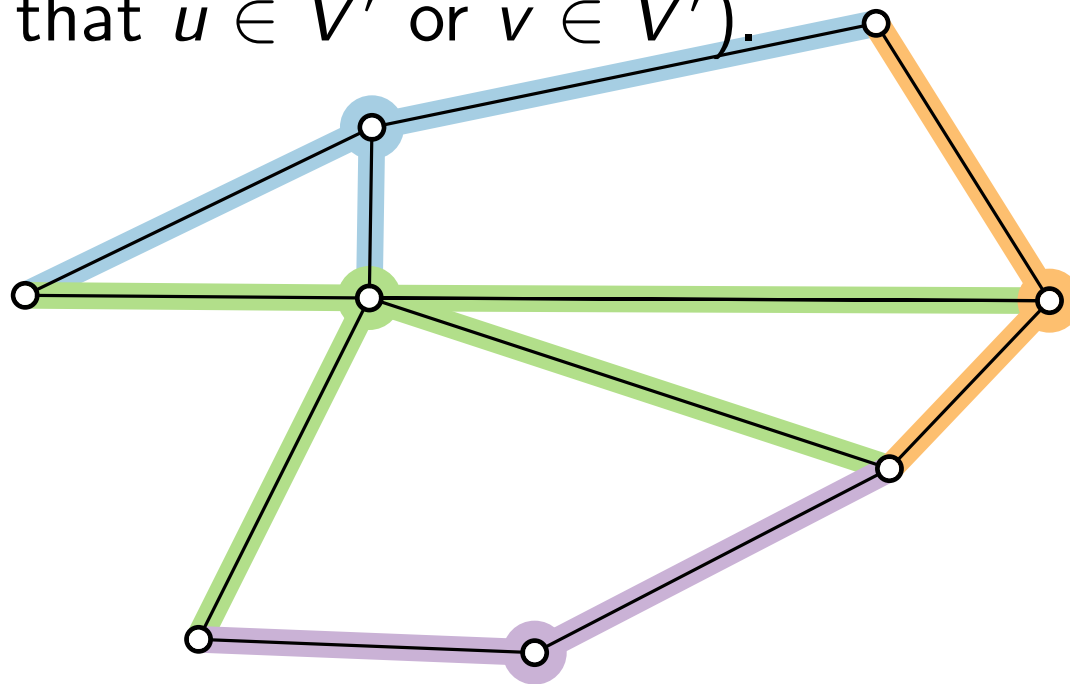
## Lecture 1: Introduction and Vertex Cover

### Part II: (Cardinality) Vertex Cover

# VERTEXCOVER (card.)

**Input:** graph  $G$

**Output:** a minimum **vertex cover**, that is,  
a minimum-cardinality vertex set  $V' \subseteq V(G)$  s. t.  
every edge is **covered** (i.e., for every  $uv \in E(G)$ , it  
holds that  $u \in V'$  or  $v \in V'$ ).



**Optimum** ( $\text{OPT} = 4$ ) – but in general NP-hard to find :-)

# Approximation Algorithms

## Lecture 1: Introduction and Vertex Cover

### Part III: NP-Optimization Problem

# NP-Optimization Problem

An **NP-optimization problem**  $\Pi$  is given by:

- A set  $D_\Pi$  of **instances**.


We denote the size of an instance  $I \in D_\Pi$  by  $|I|$ .

- For each instance  $I \in D_\Pi$ ,  
a set  $S_\Pi(I) \neq \emptyset$  of **feasible solutions** for  $I$  such that:
  - for each solution  $s \in S_\Pi(I)$ ,  
its size  $|s|$  is polynomially bounded in  $|I|$ , and
  - there is a polynomial-time algorithm that decides,  
for each pair  $(s, I)$ , whether  $s \in S_\Pi(I)$ .
- A polynomial time computable **objective function**  $\text{obj}_\Pi$   
which assigns a positive objective value  $\text{obj}_\Pi(I, s) \geq 0$  to  
any given pair  $(s, I)$  with  $s \in S_\Pi(I)$ .
- $\Pi$  is either a minimization or maximization problem.

# VERTEXCOVER: NP-Optimization Problem

Task: Fill in the gaps for  $\Pi = \text{VERTEX COVER}$ .

$D_\Pi =$  set of all graphs

For  $I \in D_\Pi$ :  $|I| =$  number of vertices of  $G$   
  
graph  $G$

$S_\Pi(I) =$  set of all vertex covers of  $G$

■ Why is  $|s| \in \text{poly}(|I|)$  for every  $s \in S_\Pi(I)$ ?

$$s \subseteq V \Rightarrow |s| \leq |V(G)| = |I|$$

■ For a given pair  $(s, I)$ , how can we efficiently decide whether  $s \in S_\Pi(I)$ ? Test whether all edges are covered.

$$\text{obj}_\Pi(I, s) = |s|$$

$\Pi$  is a minimization problem.

# Optimum and Optimal Objective Value

Let  $\Pi$  be a  $\overset{\text{maximization problem}}{\text{minimization problem}}$  and  $I \in D_\Pi$  an instance of  $\Pi$ .

A feasible solution  $s^* \in S_\Pi(I)$  is **optimal** if  $\text{obj}_\Pi(I, s^*)$  is  $\overset{\text{maximum}}{\text{minimum}}$  among the objective values attained by the feasible solutions of  $I$ .

The optimal value  $\text{obj}_\Pi(I, s^*)$  of the objective function is denoted by  $\text{OPT}_\Pi(I)$  or simply by  $\text{OPT}$  in context.

# Approximation Algorithms

maximization problem  $\alpha: \mathbb{N} \rightarrow \mathbb{Q}$

Let  $\Pi$  be a minimization problem and  ~~$\alpha \in \mathbb{Q}^+$~~ .

A factor- $\alpha$  approximation algorithm for  $\Pi$  is an efficient algorithm that provides, for **any** instance  $I \in D_\Pi$ , a feasible solution  $s \in S_\Pi(I)$  such that

$$\frac{\text{obj}_\Pi(I, s)}{\text{OPT}_\Pi(I)} \begin{matrix} \geq \\ \leq \end{matrix} \cancel{\alpha} \cdot \alpha(|I|)$$

# Approximation Algorithms

Lecture 1:

Introduction and Vertex Cover

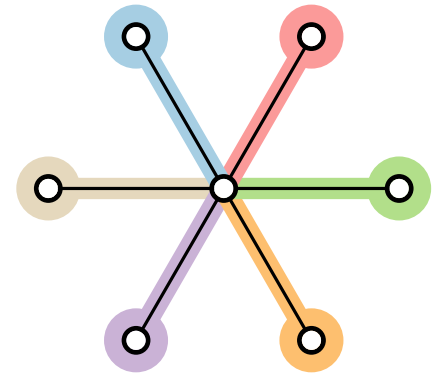
Part IV:

Approximation Algorithm for VERTEXCOVER

# Approximation Alg. for VERTEXCOVER

Ideas?

- Edge-Greedy
- Vertex-Greedy



Quality?

**Problem:** How can we estimate  $\text{obj}_\Pi(I, s) / \text{OPT}$  – if it is hard to compute  $\text{OPT}$ ?

**Idea:** Find a “good” lower bound  $L \leq \text{OPT}$  for  $\text{OPT}$  and compare it to our approximate solution.

$$\frac{\text{obj}_\Pi(I, s)}{\text{OPT}} \leq \frac{\text{obj}_\Pi(I, s)}{L}$$

# Lower Bound by Matchings

Given a graph  $G$ , a set  $M$  of edges of  $G$  is a **matching** if no two edges of  $M$  are adjacent (i.e., share an end vertex).

$M$  is **maximal** if there is no matching  $M'$  with  $M' \supsetneq M$ .

$$\text{OPT} \geq |M|$$

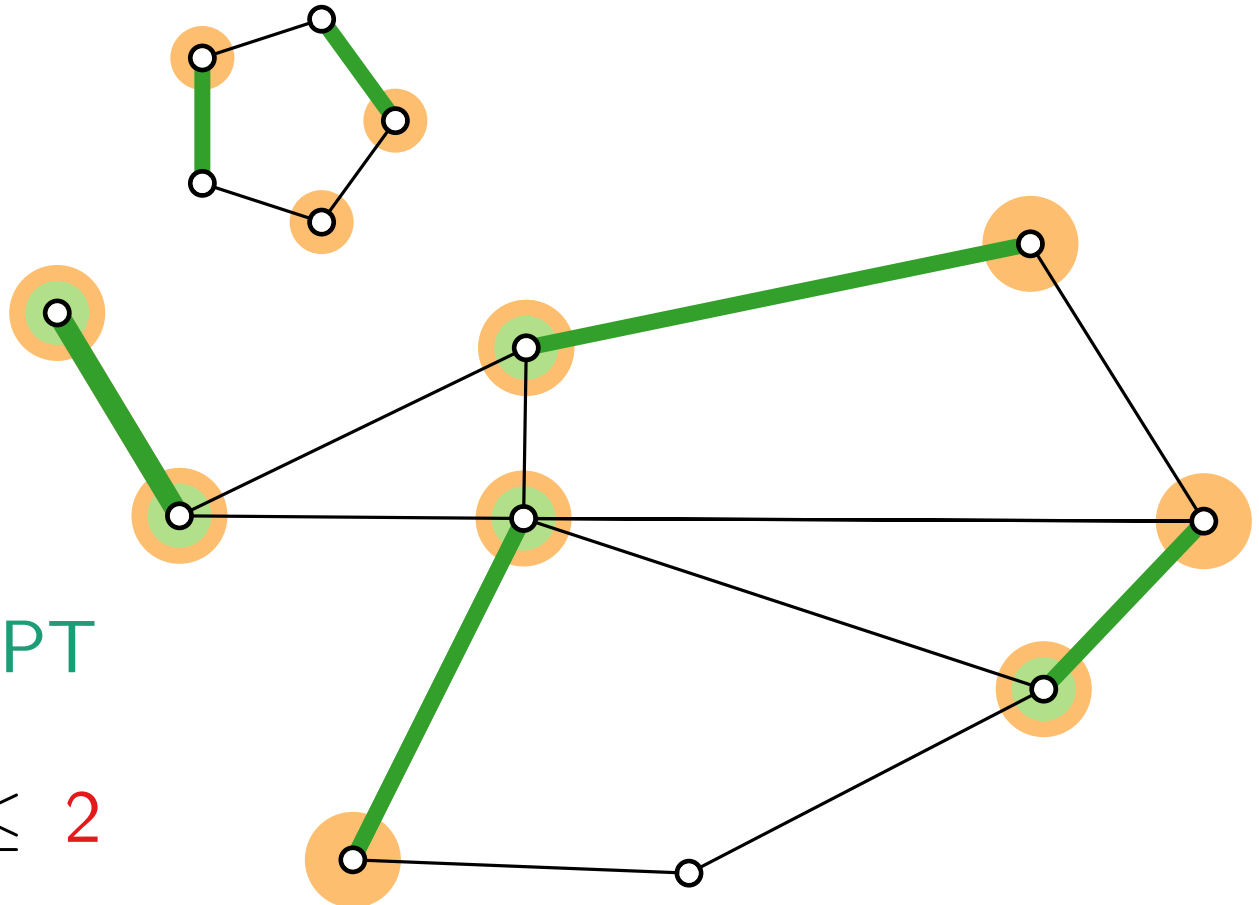
~~$$\text{OPT} = |M| ?$$~~

Vertex cover of  $M$

Vertex cover of  $E(G)$

$$\text{ALG} = 2 \cdot |M| \leq 2 \cdot \text{OPT}$$

$$\Rightarrow \frac{\text{obj}_{\Pi}(I, s)}{\text{OPT}} = \frac{\text{ALG}}{\text{OPT}} \leq 2$$



# Approximation Alg. for VERTEXCOVER

Algorithm VertexCover( $G$ )

$M \leftarrow \emptyset$

**foreach**  $e \in E(G)$  **do**

**if**  $e$  is not adjacent to any edge in  $M$  **then**  
         $M \leftarrow M \cup \{e\}$

**return**  $\{u, v \mid uv \in M\}$

**Theorem.** The above algorithm is a factor-2 approximation algorithm for VERTEXCOVER.

*Proof.*  $ALG = 2 \cdot |M| \leq 2 \cdot OPT$



# Approximability of VERTEX COVER

The best known approximation factor for VERTEXCOVER is  $2 - \Theta(1/\sqrt{\log n})$ .

If  $P \neq NP$ , VERTEXCOVER cannot be approximated within a factor of 1.3606.

VERTEXCOVER cannot be approximated within a factor of  $2 - \Theta(1)$  – if the *Unique Games Conjecture* holds.

# Approximation Algorithms

Lecture 1:

Introduction and Vertex Cover

Part V:

An LP-based Algorithm for VERTEXCOVER

# Task

Write an integer linear program (ILP) for VERTEXCOVER:

Using integer (and/or real) variables, express the problem using

- linear constraints and
- a linear objective function.

You can iterate over the vertices / edges of the given graph  $G$ .

**Variables:** for each vertex  $v$  of  $G$ , we introduce  $x_v \in \{0, 1\}$ .

**Objective:** minimize  $\sum_{v \in V(G)} x_v$

*$v$  not in the solution*  
 *$v$  in the solution*

**Constraints:** for each edge  $uv$  of  $G$ , we require that

$$x_u + x_v \geq 1.$$

# Standard ILP Format

LP relaxation

minimize  $\sum_{v \in V(G)} x_v$

subject to  $x_u + x_v \geq 1$  for each  $uv \in E(G)$

$x_v \geq 0$   ~~$x_v \in \{0, 1\}$~~  for each  $v \in V(G)$

**Problem:** It's NP-hard to solve ILPs in general.

**But:** LPs can be solved efficiently (in  $O(L \cdot n^{3.5})$  time),  
where  $n = \#$  variables and  $L =$  total bit complexity of coefficients.

**Problem':** Now we can get fractional solutions, i.e.,  $x_v \in (0, 1)$ .

**Task:** Find a graph  $G$  with  $\text{OPT}_{\text{LP}} \neq \text{OPT}_{\text{ILP}}$ !

**Solution?** Round the LP solution to get an integral solution!

# Rounding the LP Solution

$$\begin{array}{ll}\text{minimize} & \sum_{v \in V(G)} x_v \\ \text{subject to} & x_u + x_v \geq 1 \quad \text{for each } uv \in E(G) \\ & x_v \geq 0 \quad \text{for each } v \in V(G)\end{array}$$

For each  $v \in V(G)$ : Set  $x'_v = \begin{cases} 1 & \text{if } x_v \geq 0.5, \\ 0 & \text{otherwise.} \end{cases}$

**Need to check:** Is  $(x'_v)_{v \in V(G)}$  a feasible solution?

**In other words:** Is  $\{v \in V(G) : x'_v = 1\}$  a vertex cover of  $G$ ?

Need to make sure that every edge  $uv$  of  $G$  is covered.

Is  $x'_u = 0 = x'_v$  possible? But then  $x_u < 0.5$  and  $x_v < 0.5$ .

This contradicts  $x_u + x_v \geq 1 \Rightarrow x'_u = 1$  or  $x'_v = 1 \Rightarrow (x'_v)$   
feasible!

# Cost of the Solution

$$\begin{array}{ll} \text{minimize} & \sum_{v \in V(G)} x_v \\ \text{subject to} & x_u + x_v \geq 1 \quad \text{for each } uv \in E(G) \\ & x_v \geq 0 \quad \text{for each } v \in V(G) \end{array}$$

For each  $v \in V(G)$ : Set  $x'_v = \begin{cases} 1 & \text{if } x_v \geq 0.5, \\ 0 & \text{otherwise.} \end{cases}$

$$\text{ALG} = \sum_{v \in V(G)} x'_v \leq 2 \cdot \sum_{v \in V(G)} x_v = 2 \cdot \text{OPT}_{\text{LP}} \leq 2 \cdot \text{OPT}_{\text{ILP}}$$

**Theorem.** The LP rounding algorithm is a factor-2 approximation algorithm for VERTEXCOVER.

# Cost of the Solution

$$\begin{array}{ll}\text{minimize} & \sum_{v \in V(G)} x_v \cdot w(v) \\ \text{subject to} & x_u + x_v \geq 1 \quad \text{for each } uv \in E(G) \\ & x_v \geq 0 \quad \text{for each } v \in V(G)\end{array}$$

For each  $v \in V(G)$ : Set  $x'_v = \begin{cases} 1 & \text{if } x_v \geq 0.5, \\ 0 & \text{otherwise.} \end{cases}$

$$\text{ALG} = \sum_{v \in V(G)} x'_v \cdot w(v) \leq 2 \cdot \sum_{v \in V(G)} x_v \cdot w(v) = 2 \cdot \text{OPT}_{\text{LP}} \leq 2 \cdot \text{OPT}_{\text{ILP}}$$

**Theorem.** The LP rounding algorithm is a factor-2 approximation algorithm for **WEIGHTED VERTEX COVER**.

# Approximation Algorithms

## Lecture 1: Introduction and Vertex Cover

### Part VI: The Vertex Cover Polytope

# The Vertex Cover Polytope

minimize  $\sum_{v \in V(G)} x_v$

subject to  $x_u + x_v \geq 1$

$x_v \geq 0$

for each  $uv \in E(G)$

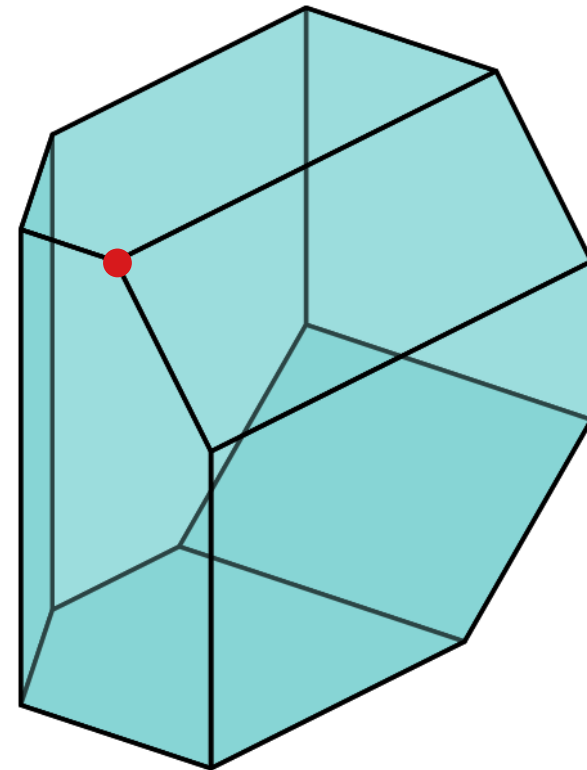
for each  $v \in V(G)$

The solution space of an LP is a *convex* polytope in  $\mathbb{R}^n$ , where  $n$  is the number of variables.

The number of facets corresponds to the number of “relevant” constraints.

An *extreme point* of the polytope is a point that is extreme in some direction.

Most LP solvers return extreme-point solutions.



# Half-Integrality

**Thm.** The extreme points of the vertex cover polytope are half-integral, that is, their coordinates are in  $\{0, 0.5, 1\}$ .

*Proof.* Let  $x$  be an LP solution that is not half-integral.

$$\Rightarrow \exists v \in V(G): x_v \in (0, 0.5) \cup (0.5, 1).$$

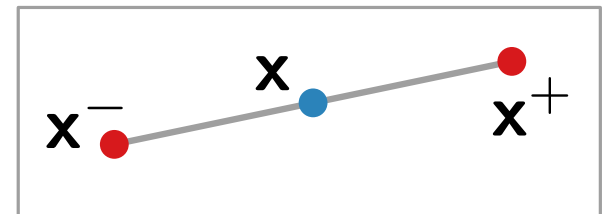
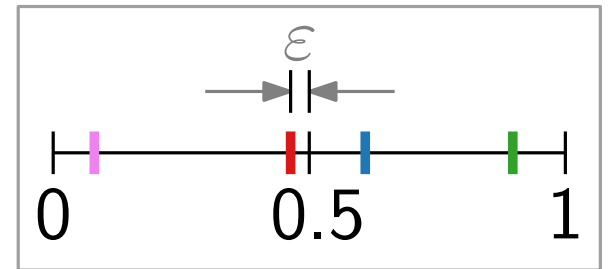
$$\text{Let } \varepsilon = \min_{u \in V(G)} \{x_u, 1 - x_u, |x_u - 0.5|\} \setminus \{0\}.$$

For every  $v \in V(G)$ , let

$$x_v^+ = \begin{cases} x_v + \varepsilon & \text{if } x_v \in (0.5, 1) \\ x_v - \varepsilon & \text{if } x_v \in (0, 0.5) \\ x_v & \text{else.} \end{cases}$$

$$x_v^- = \begin{cases} x_v - \varepsilon & \text{if } x_v \in (0.5, 1) \\ x_v + \varepsilon & \text{if } x_v \in (0, 0.5) \\ x_v & \text{else.} \end{cases}$$

$$\Rightarrow \frac{x^+ + x^-}{2} = x$$



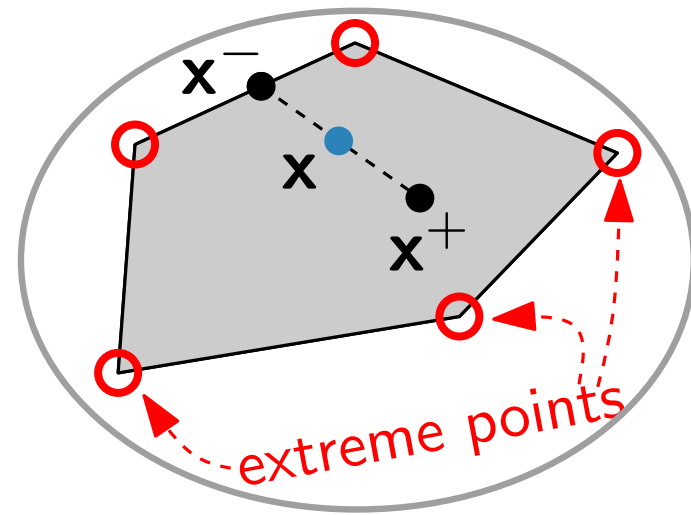
# Extreme Points

**Claim:**  $\mathbf{x}^+$  is feasible.

Need to show: For every edge  $uv$ , we have  $x_u^+ + x_v^+ \geq 1$ .

Assume  $x_u^+ < 0.5 \Rightarrow x_v^+ > 0.5 \Rightarrow x_u^+ + x_v^+ = x_u + x_v \geq 1$  ✓

**Symmetrically:**  $\mathbf{x}^-$  is feasible.



**We have shown:**

If a solution is not half-integral, it cannot be extreme.

**In other words:**

All extreme-point solutions are half-integral.

For VC, standard LP solvers return half-integral solutions. :-)