

# Approximation Algorithms

Lecture 12:

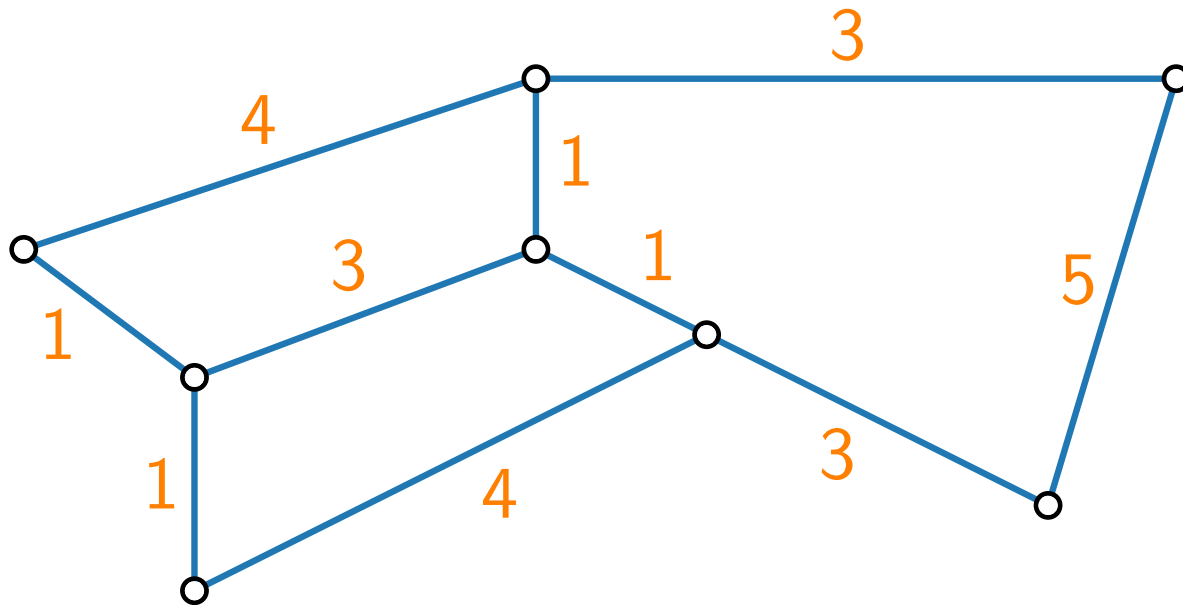
STEINERFOREST via Primal–Dual

Part I:

STEINERFOREST

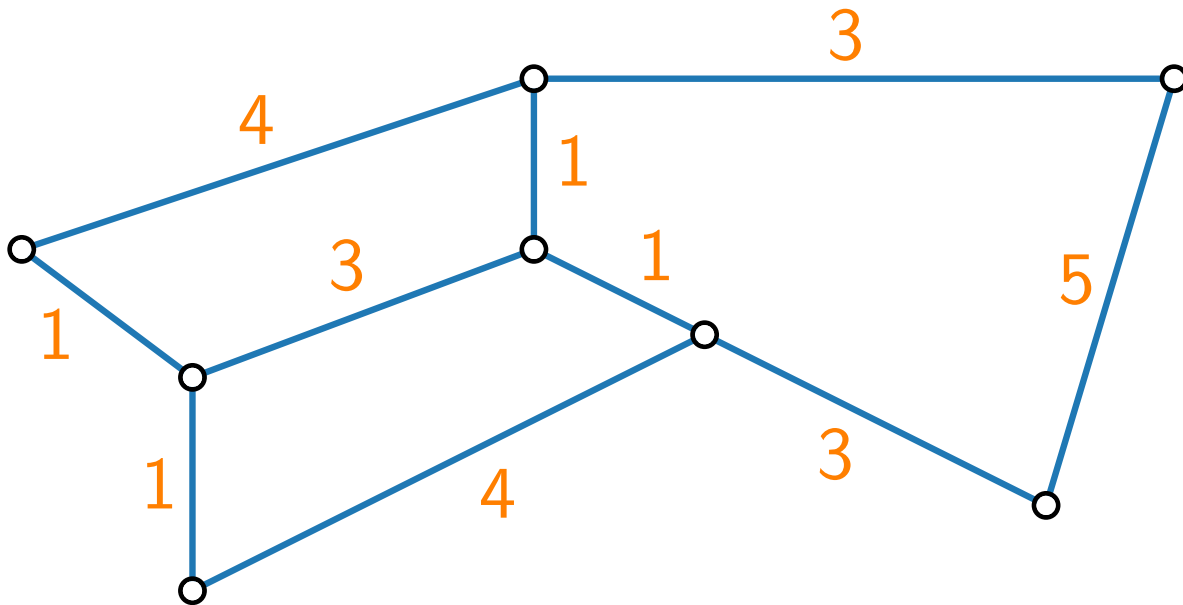
# STEINERFOREST

**Given:** A graph  $G$  with edge costs  $c: E(G) \rightarrow \mathbb{N}$



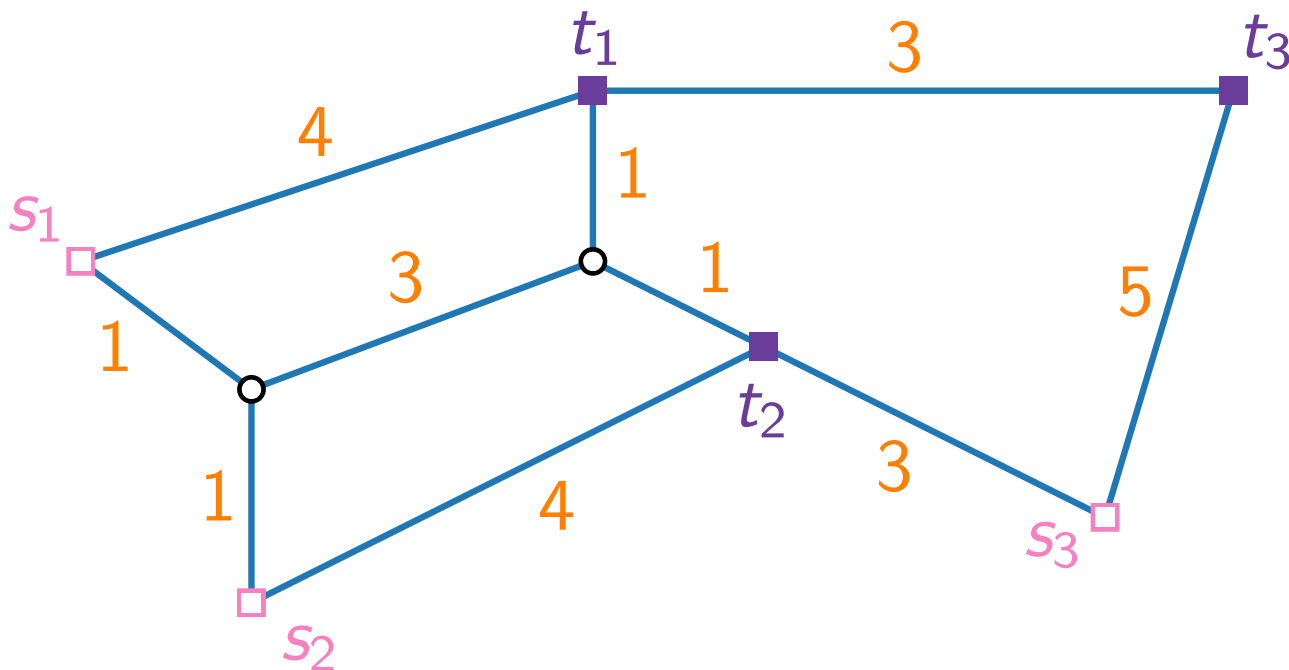
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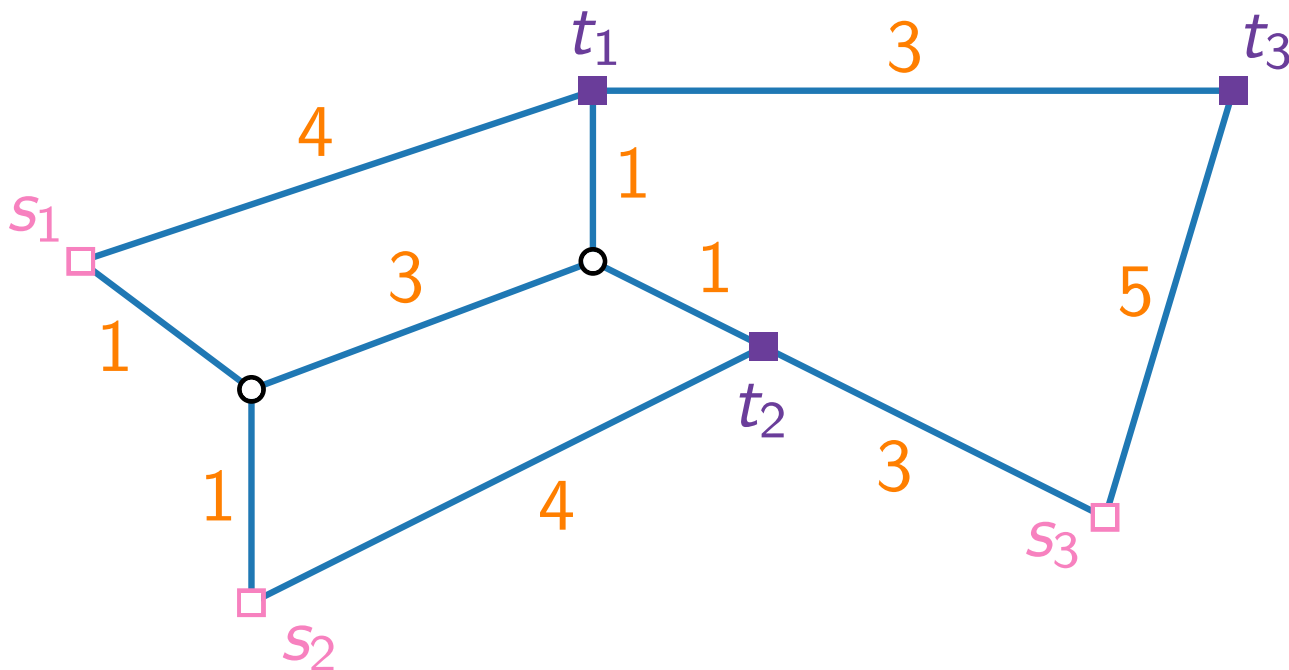
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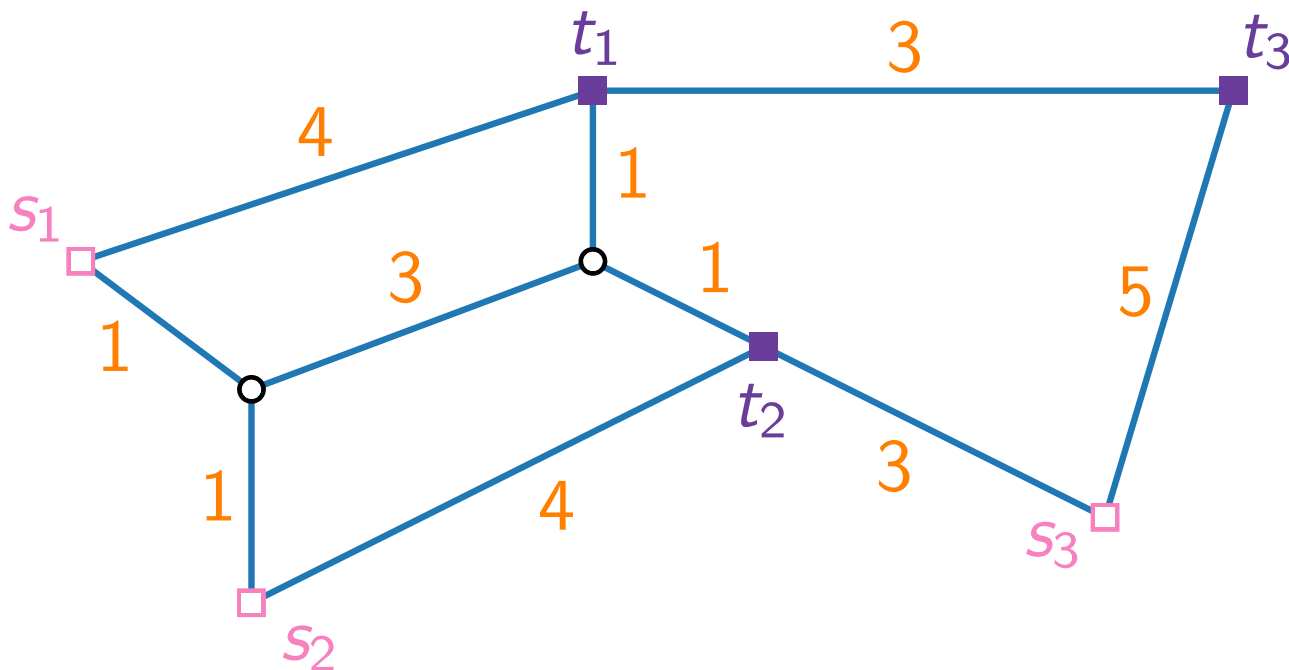
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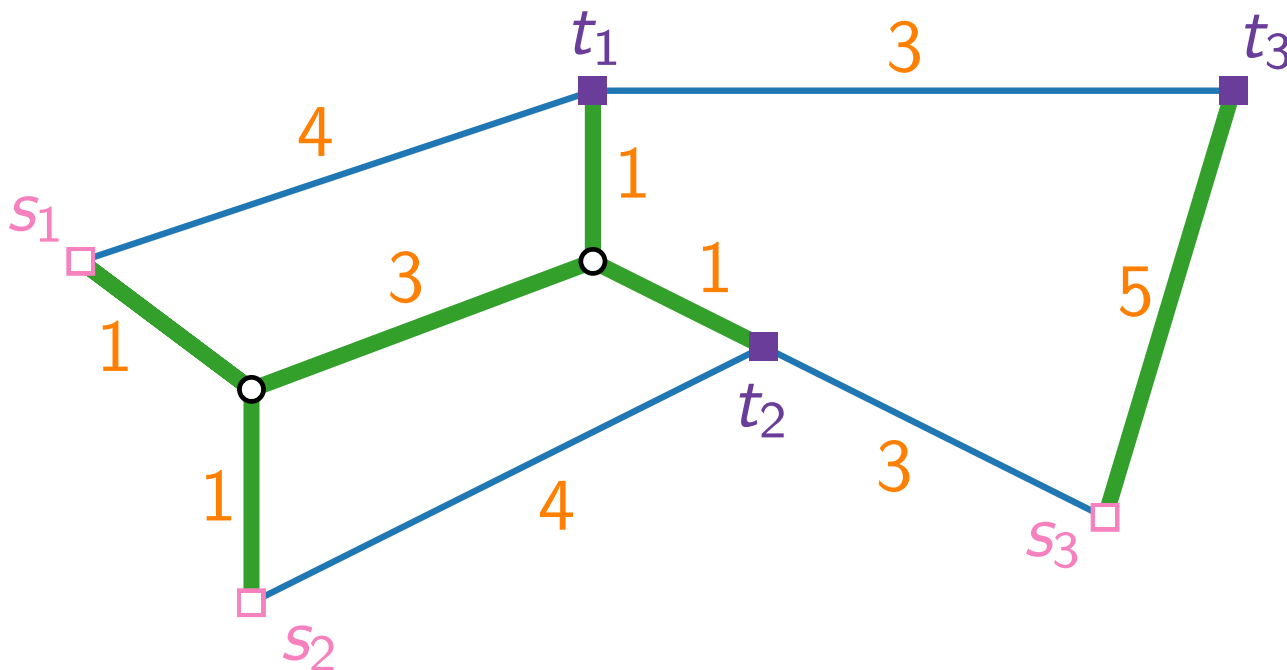
**Task:** Find an edge set  $F \subseteq E(G)$  of minimum total cost  $c(F)$  such that the subgraph  $(V(G), F)$  connects all vertex pairs  $(s_1, t_1), \dots, (s_k, t_k)$ .



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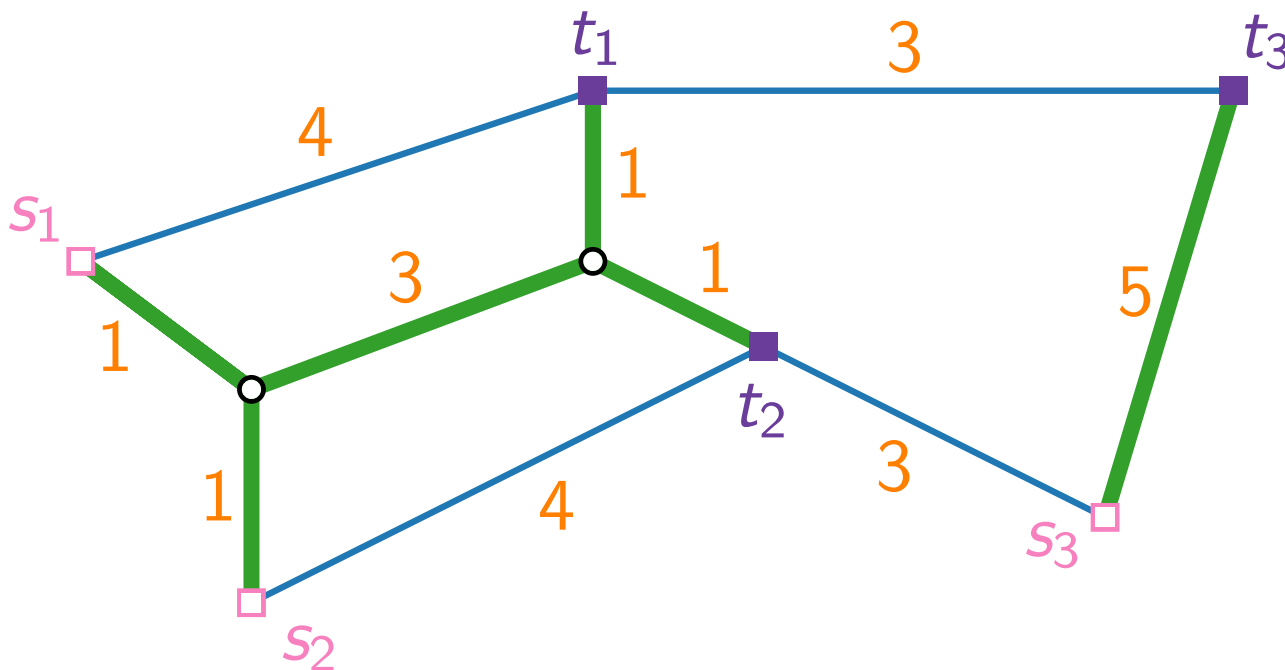
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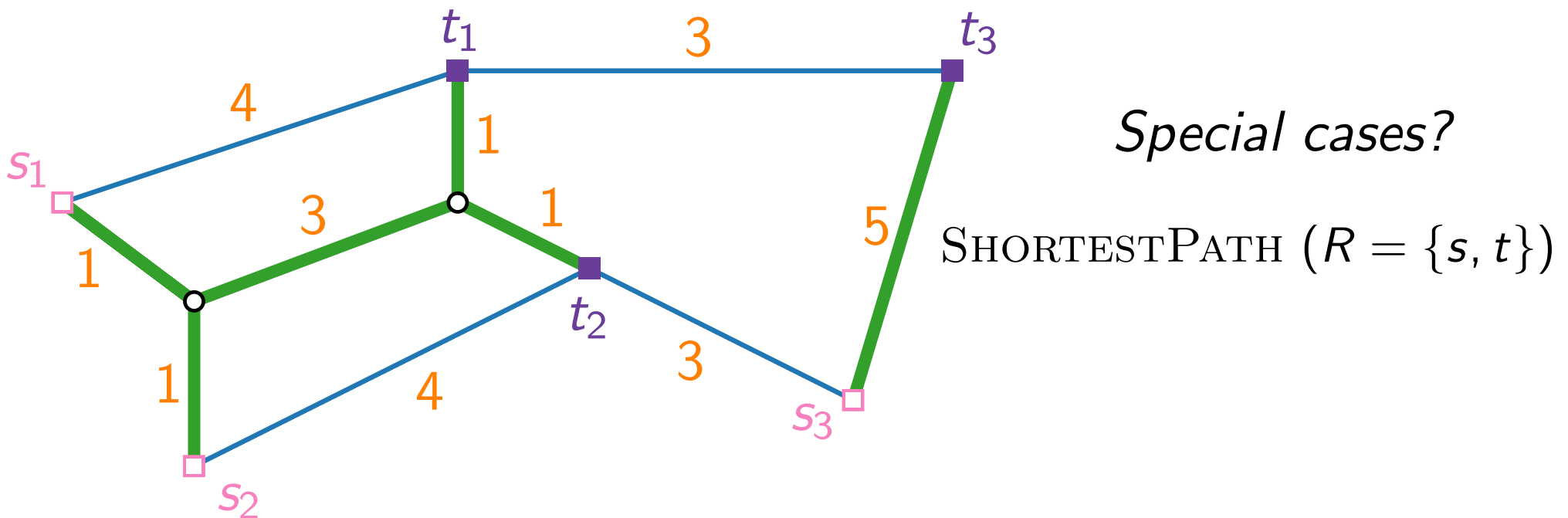
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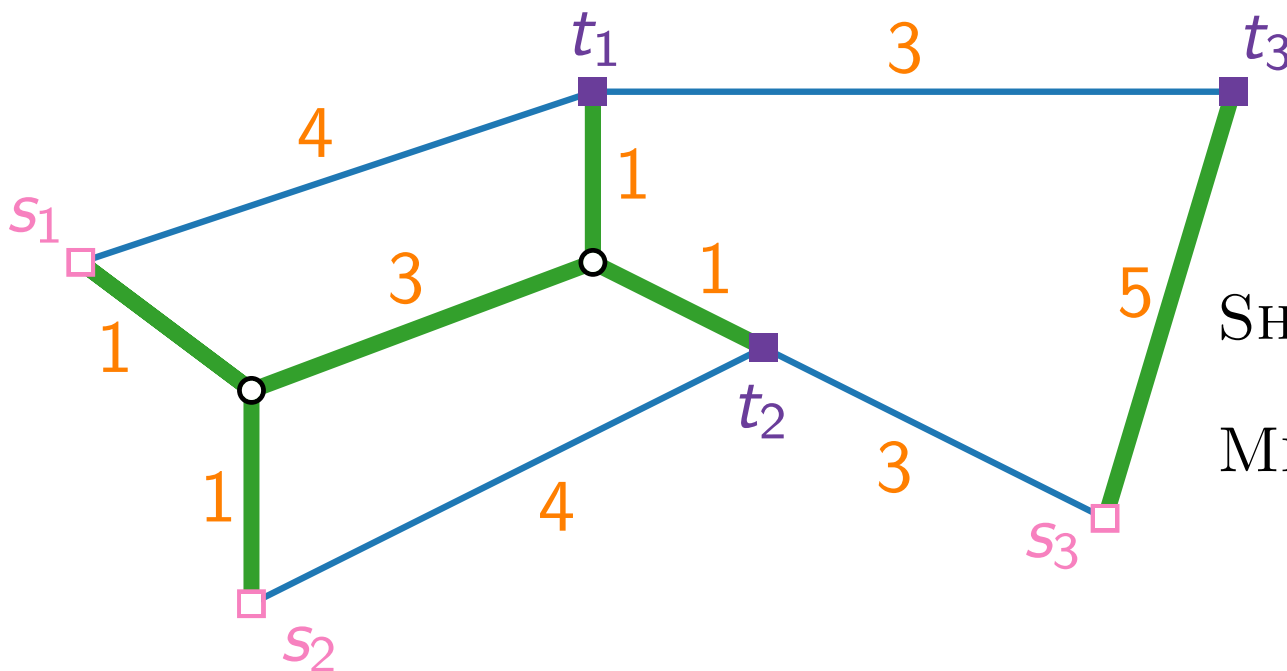
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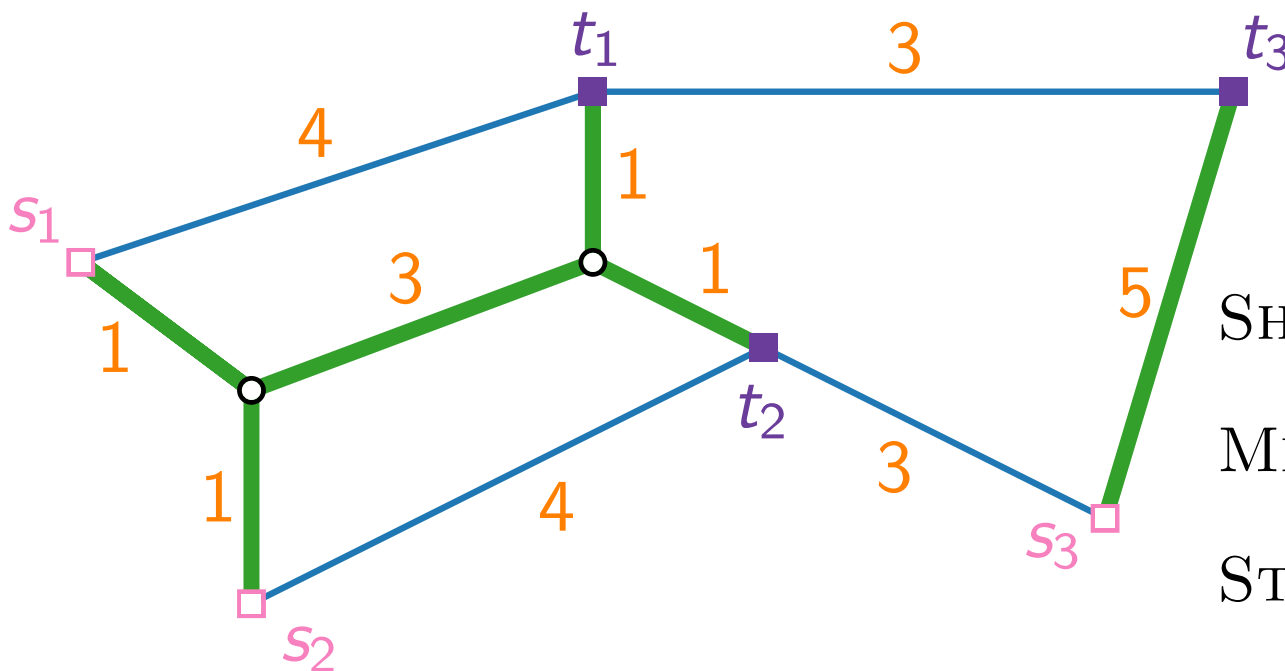
SHORTESTPATH ( $R = \{s, t\}$ )

MINSPANNINGTREE ( $R = E(G)$ )

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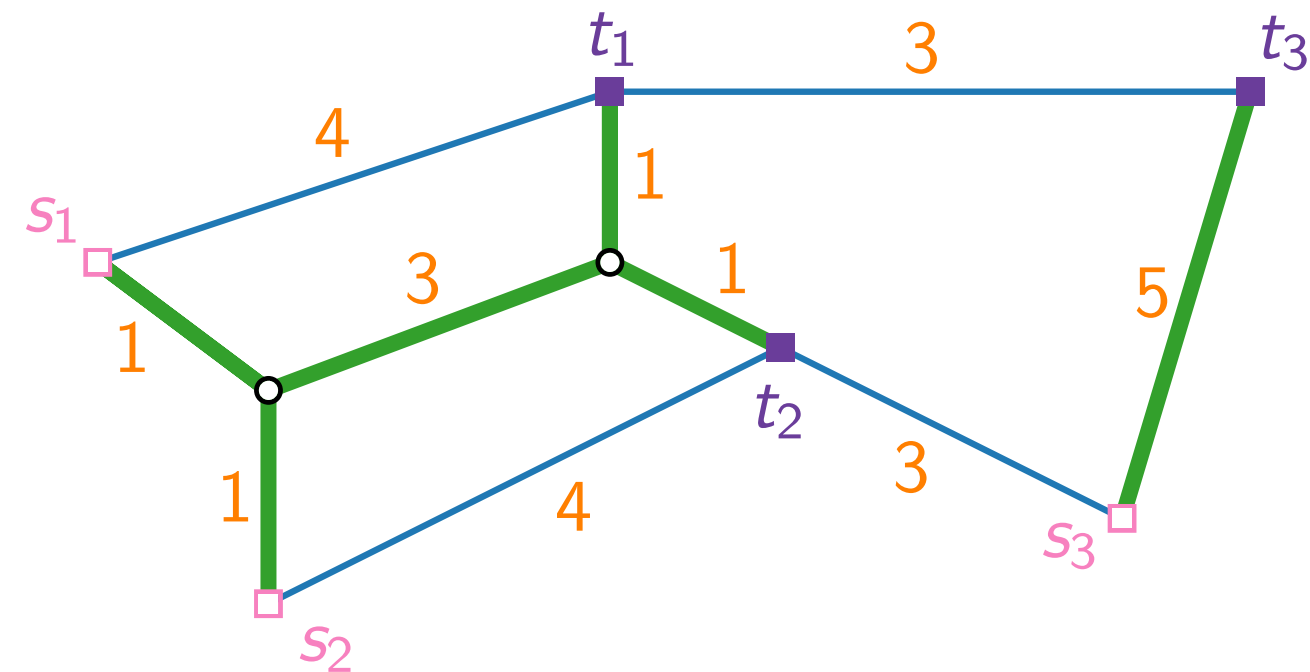
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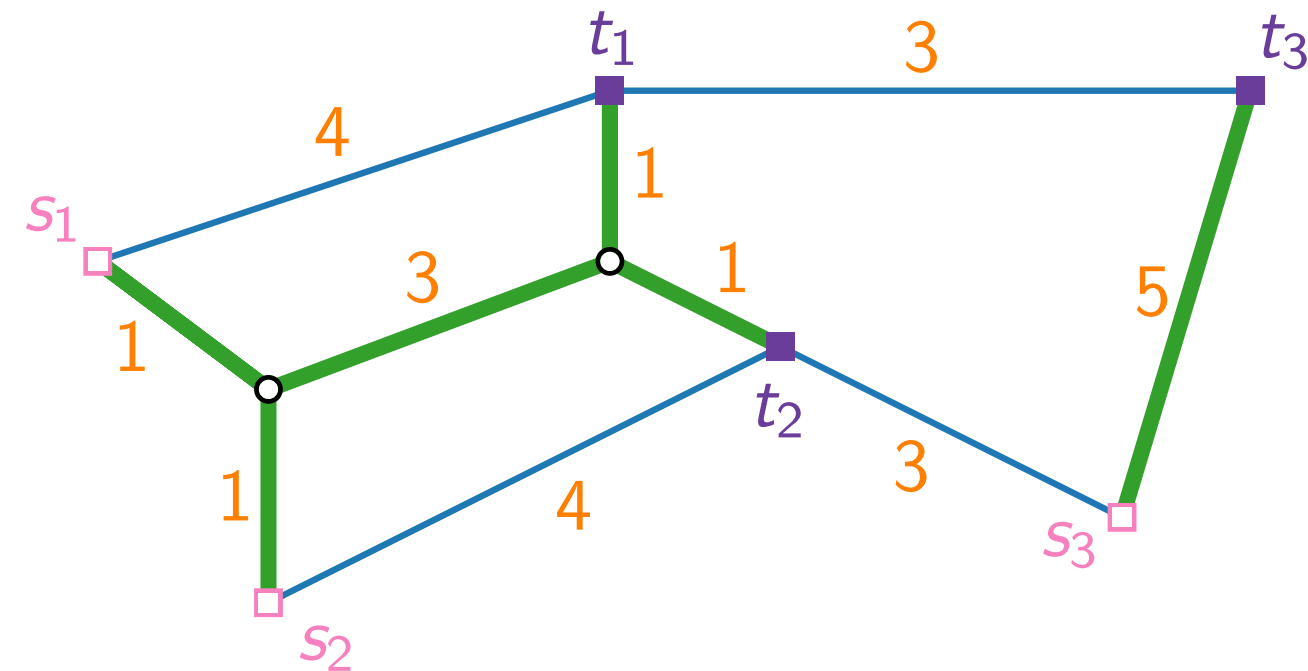
STEINERTREE ( $R = T \times T$ )

# Computational Approaches?



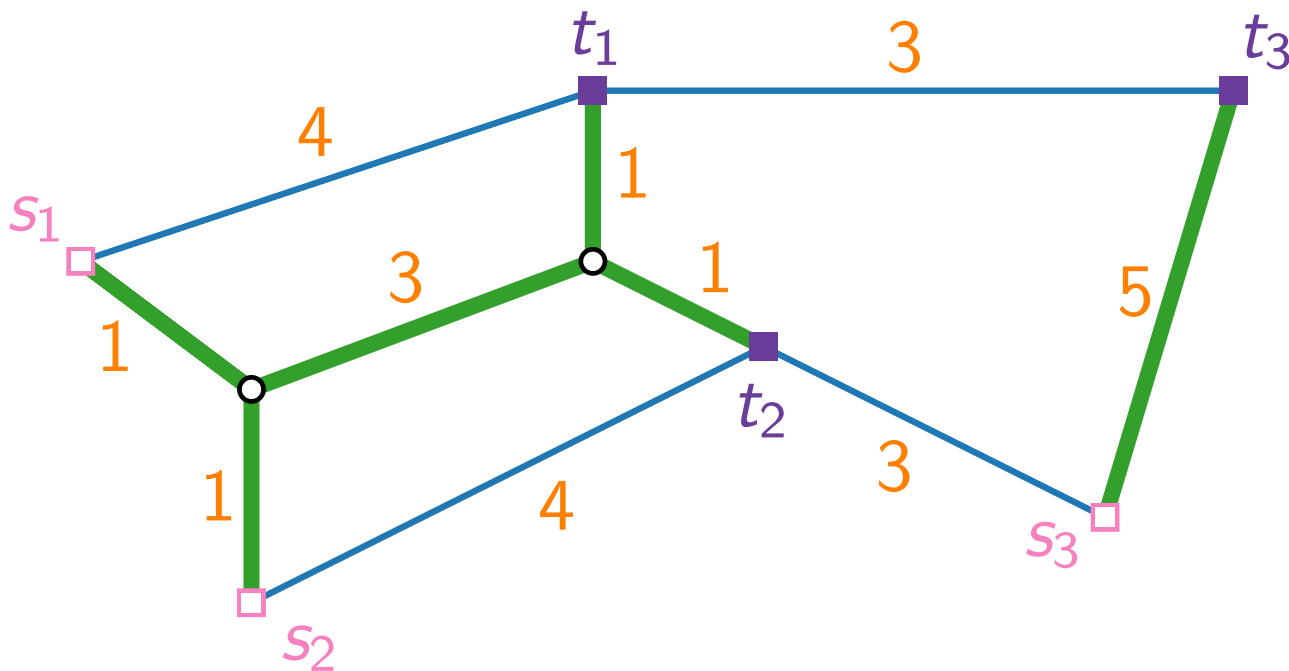
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- Merge  $k$  shortest  $s_i-t_i$  paths



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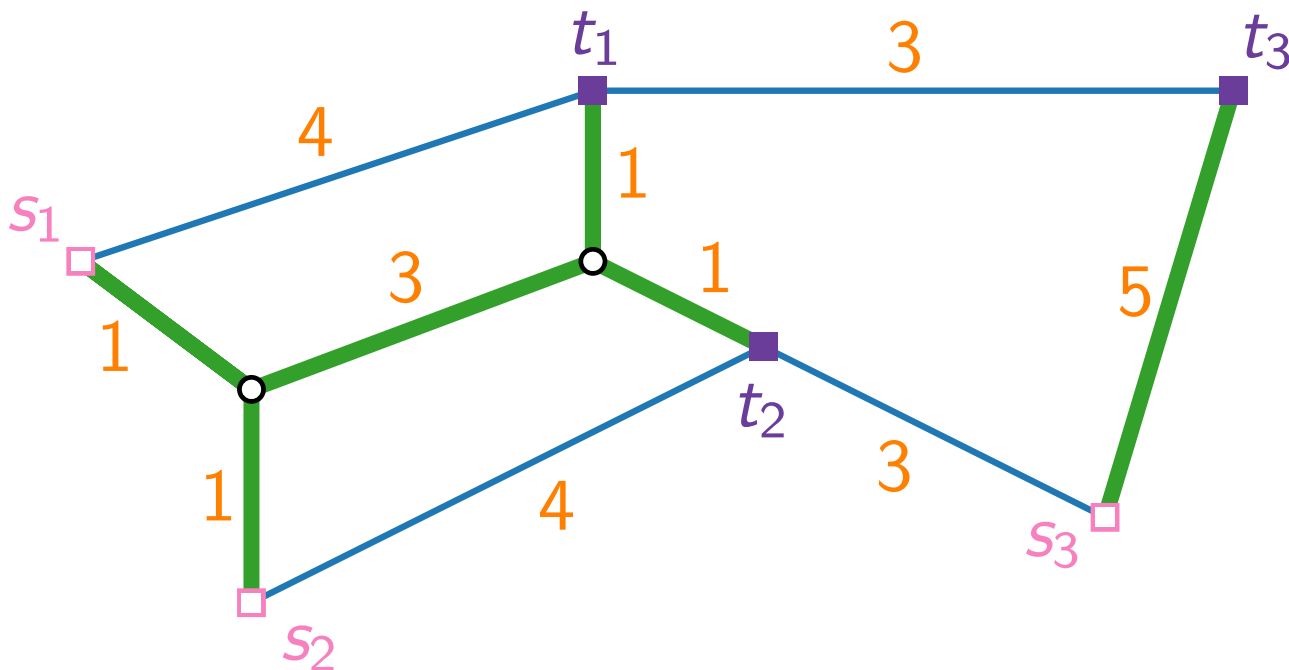
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**Homework:** Both above approaches perform poorly :-)



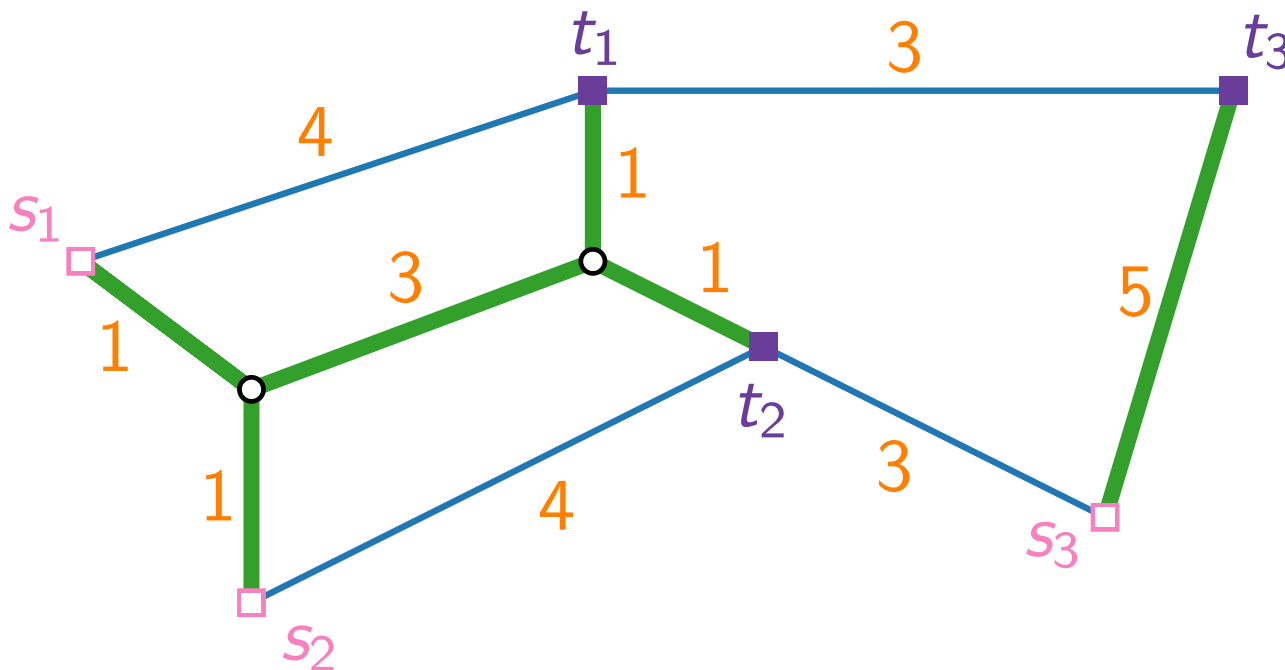
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**Homework:** Both above approaches perform poorly :-)

**Difficulty:**

Which terminals belong to the same tree of the forest?





# Approximation Algorithms

Lecture 12:

STEINERFOREST via Primal–Dual

Part II:

Primal and Dual LP

# An ILP

**minimize**

**subject to**

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$$x_e \in \{0, 1\} \quad e \in E(G)$$

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■  $t_i$

□  $s_i$

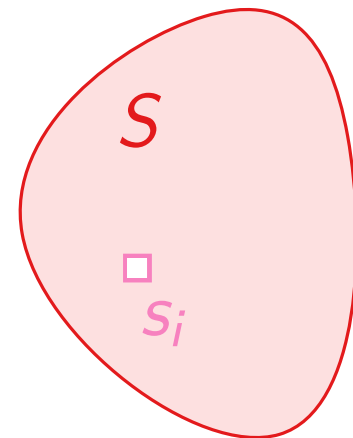
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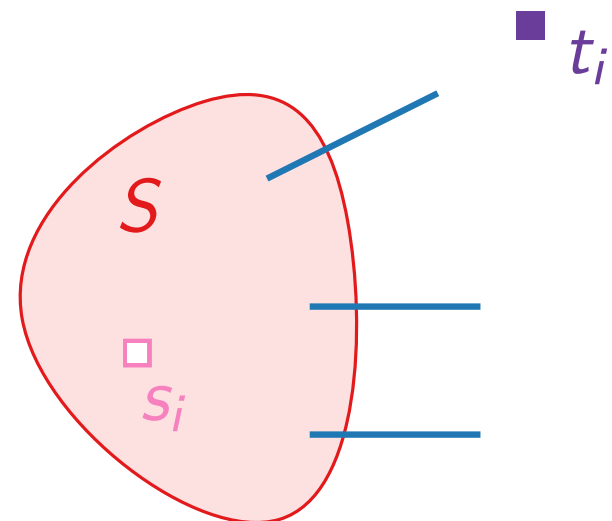


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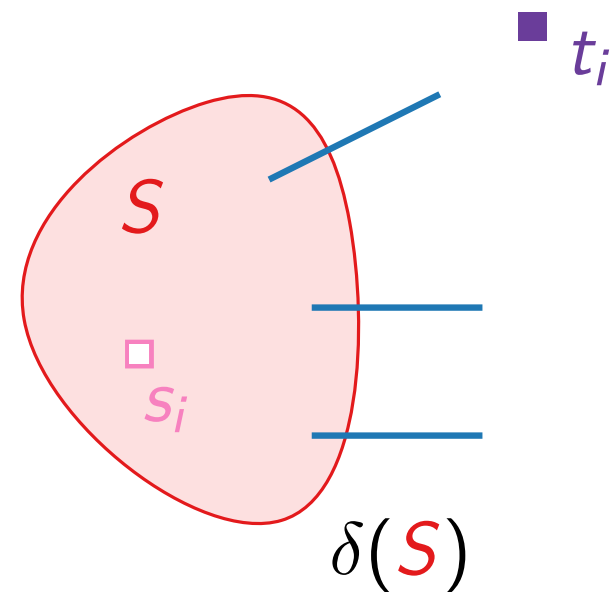


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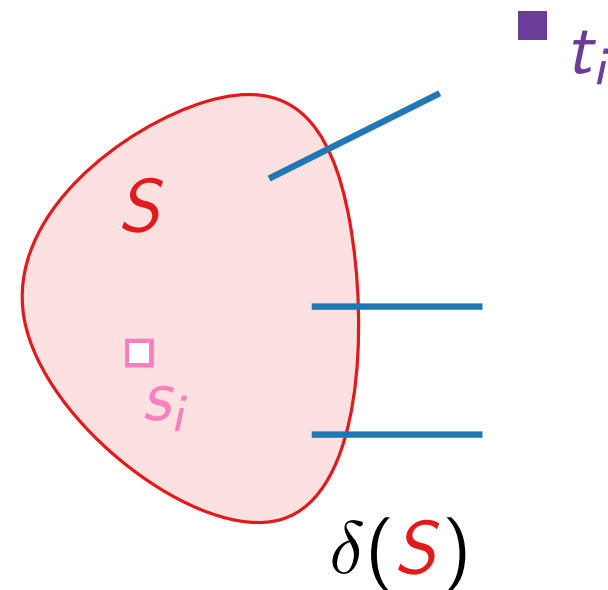
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$$\delta(S) := \{(u, v) \in E : u \in S \text{ and } v \notin S\}$$



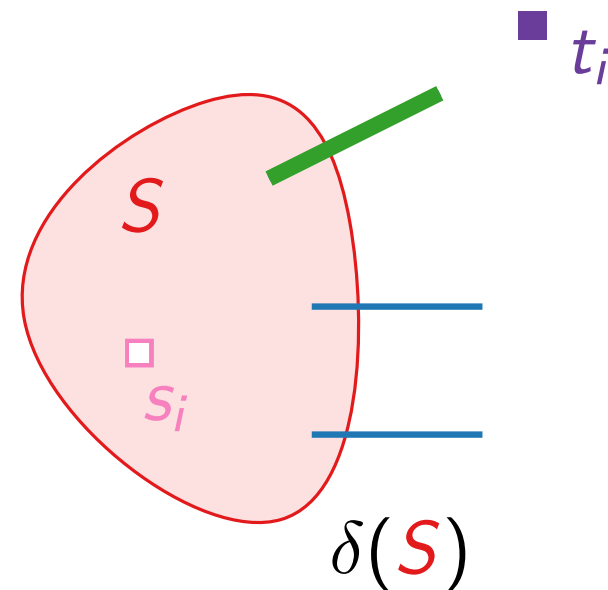
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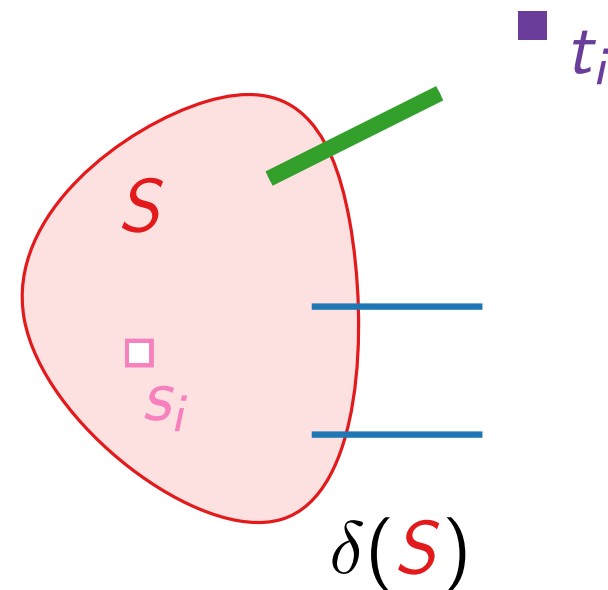
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 \text{minimize} & \sum_{e \in E(G)} c_e x_e \\
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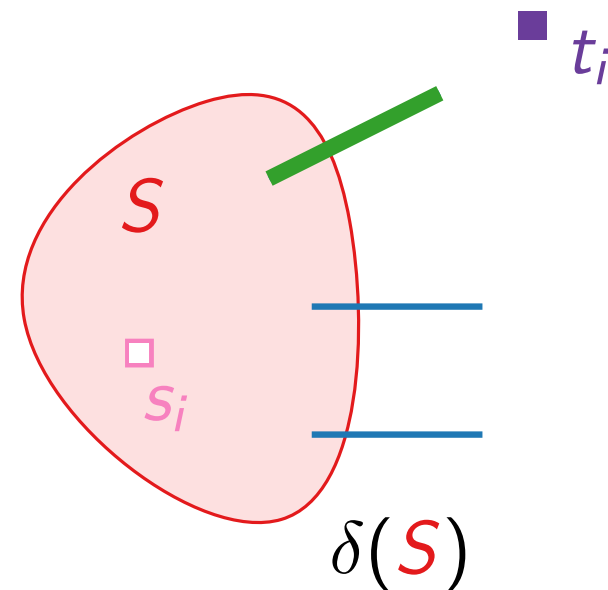
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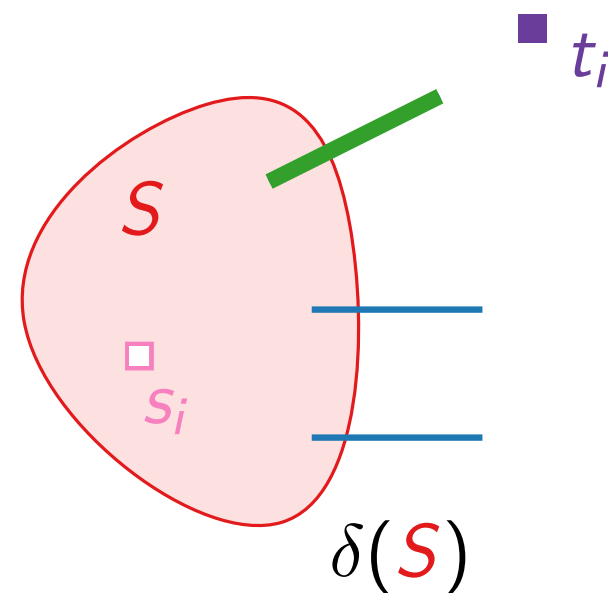


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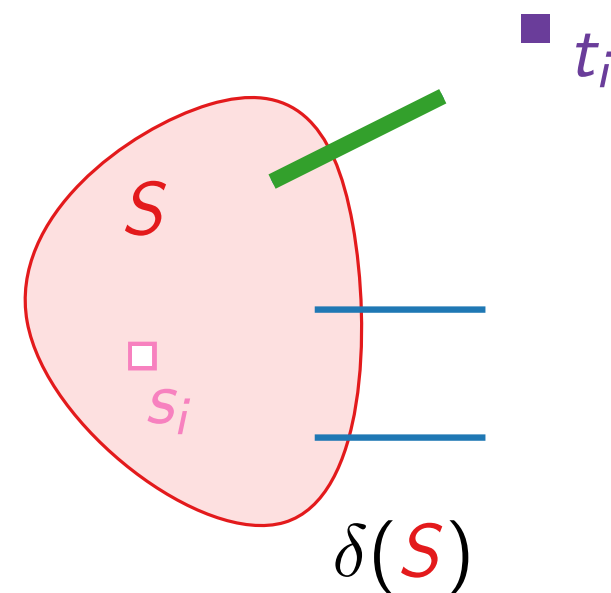
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$\Rightarrow$  exponentially many constraints!



# LP-Relaxation and Dual LP

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maximize

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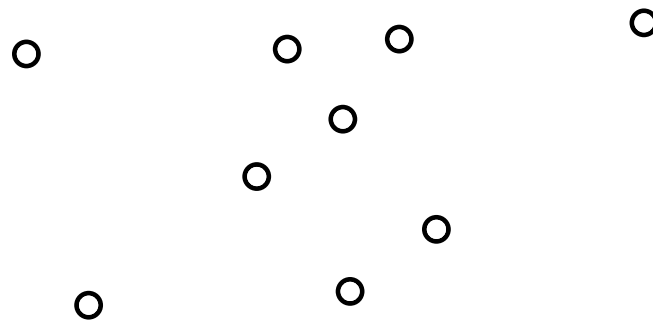
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The graph is a network of **bridges**, spanning the **moats**.

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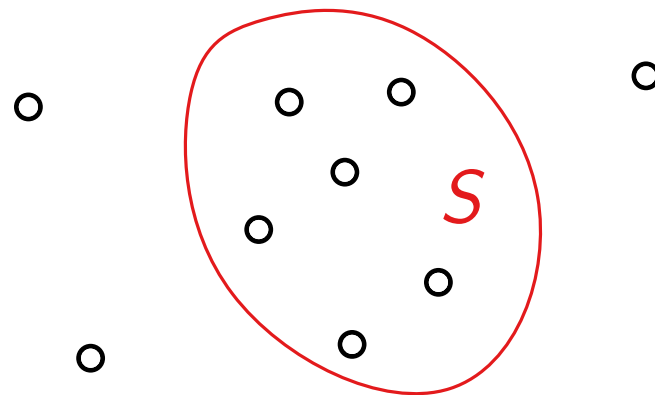
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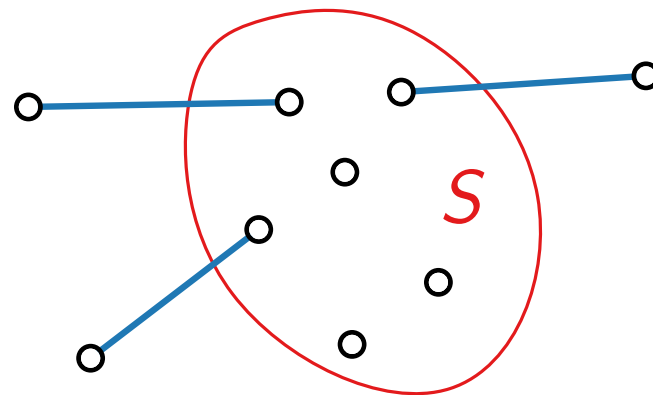
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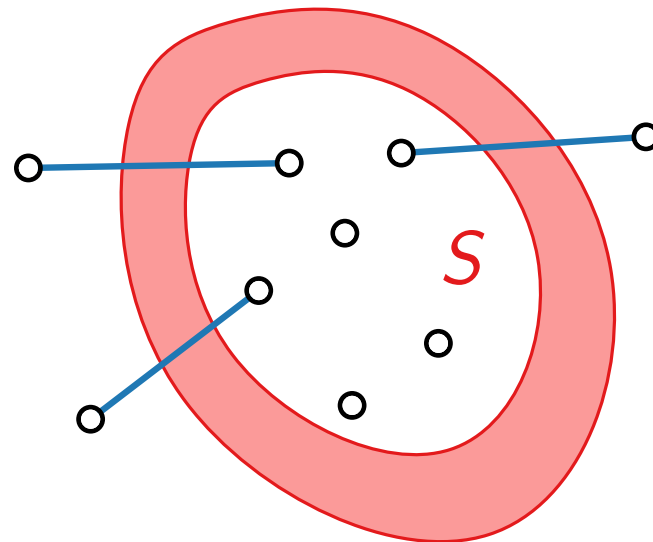




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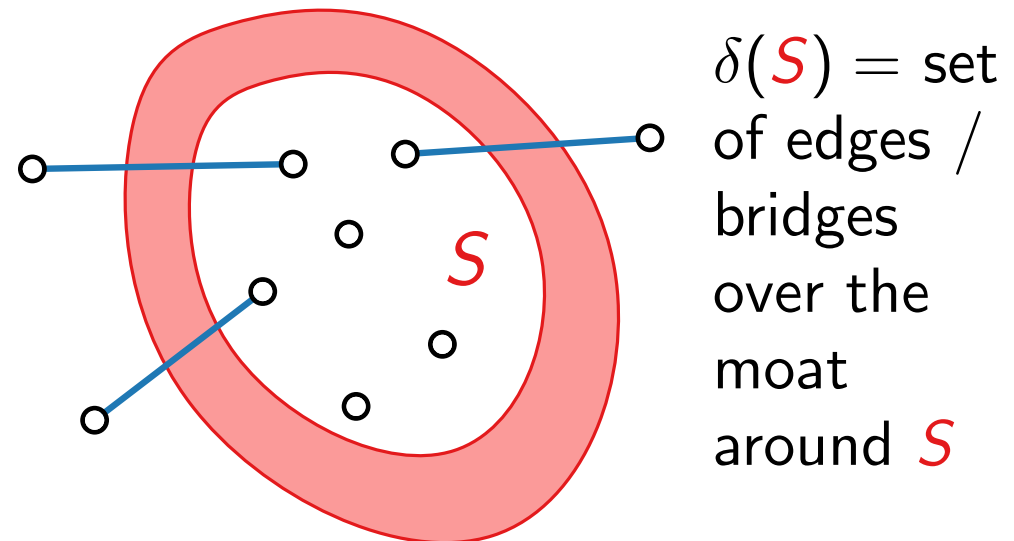
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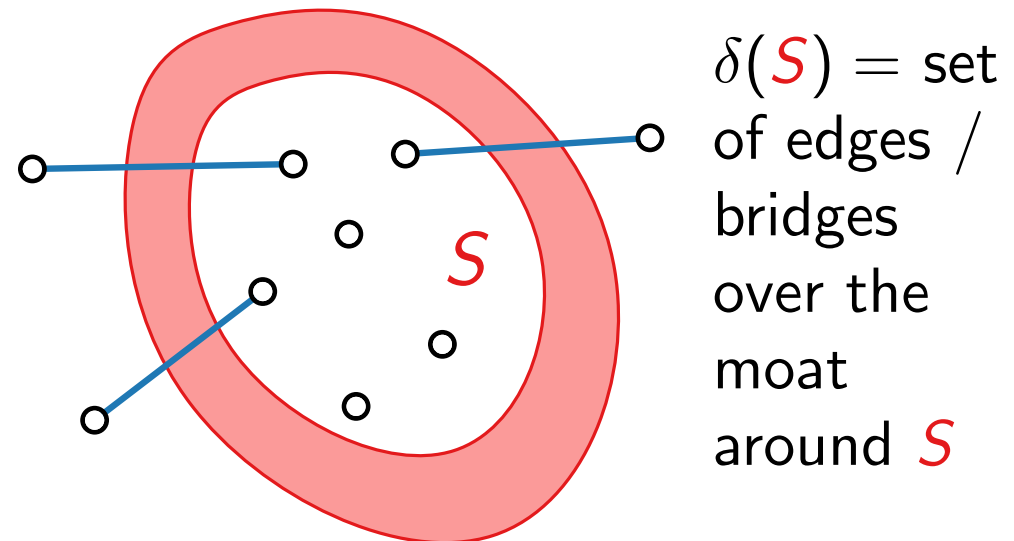
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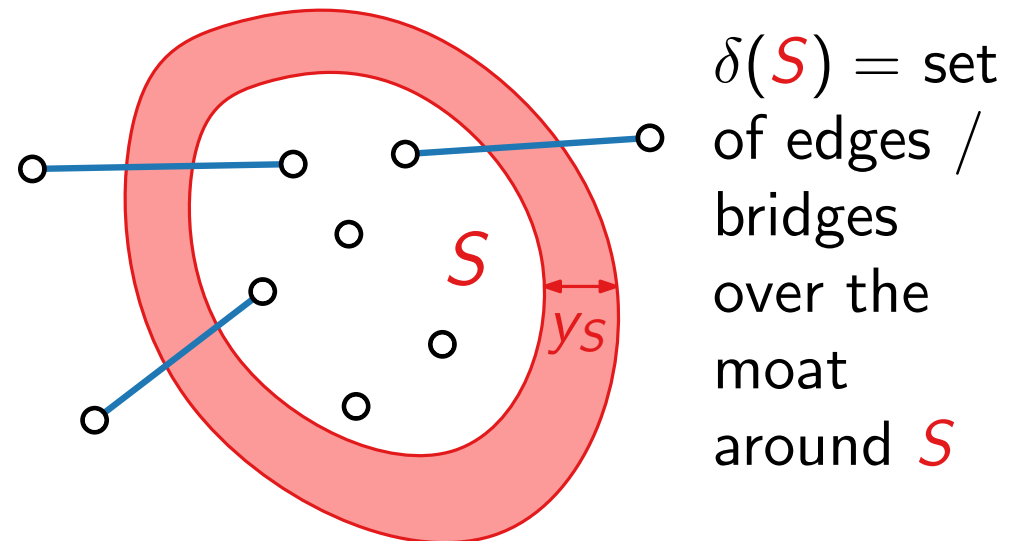


$y_S$  = width of the **moat** around  $S$

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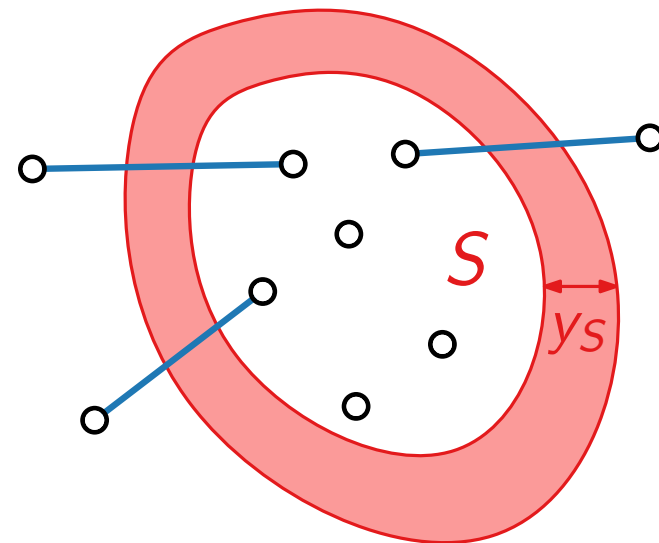
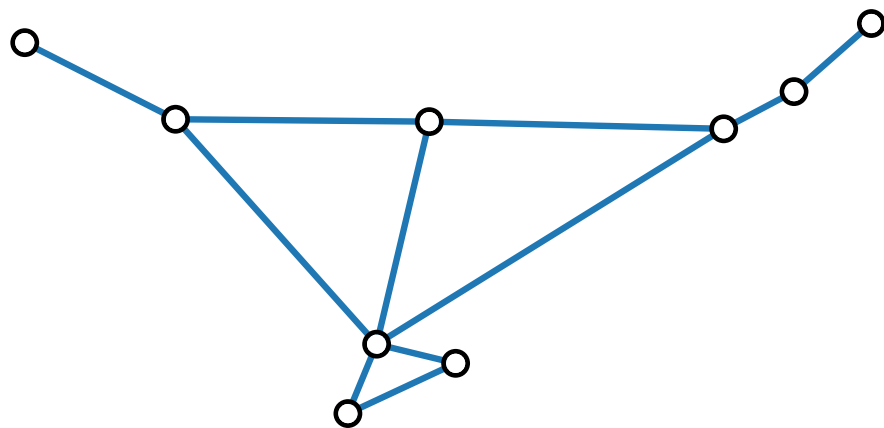


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$\delta(S)$  = set of edges / bridges over the moat around  $S$

$y_S$  = width of the **moat** around  $S$

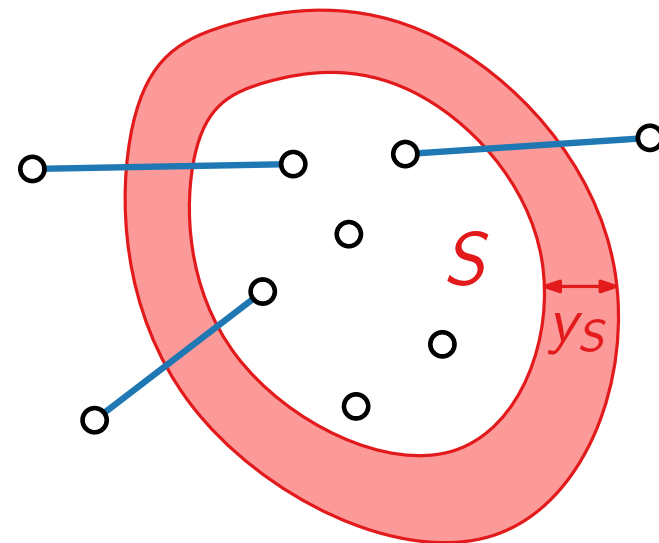
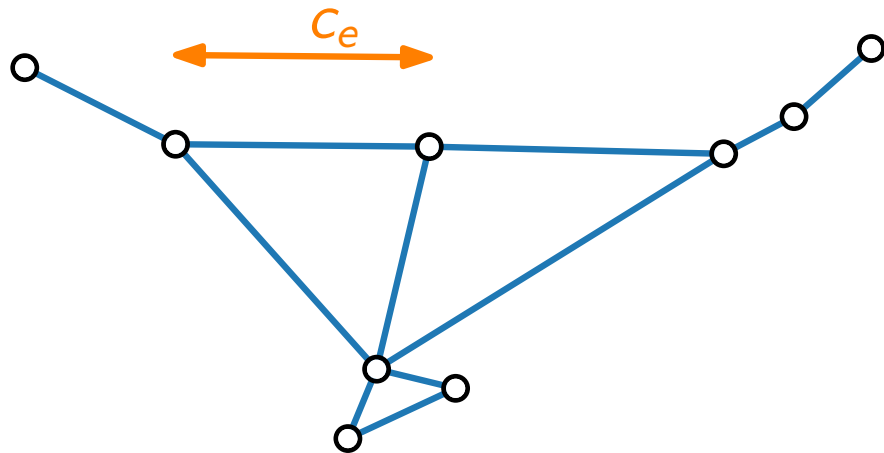
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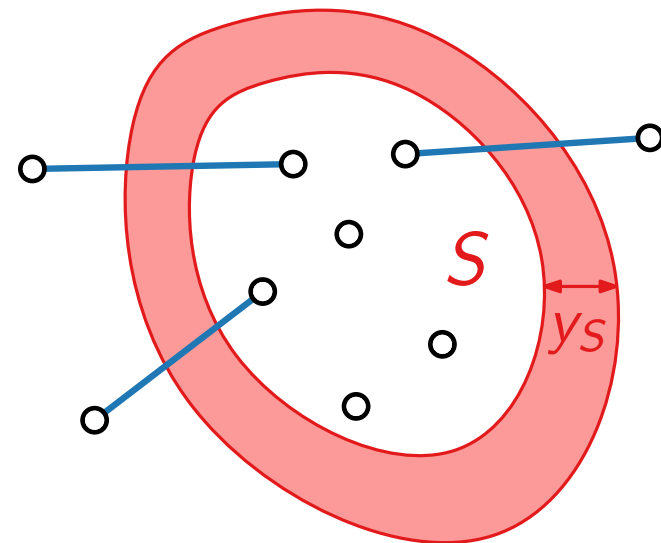
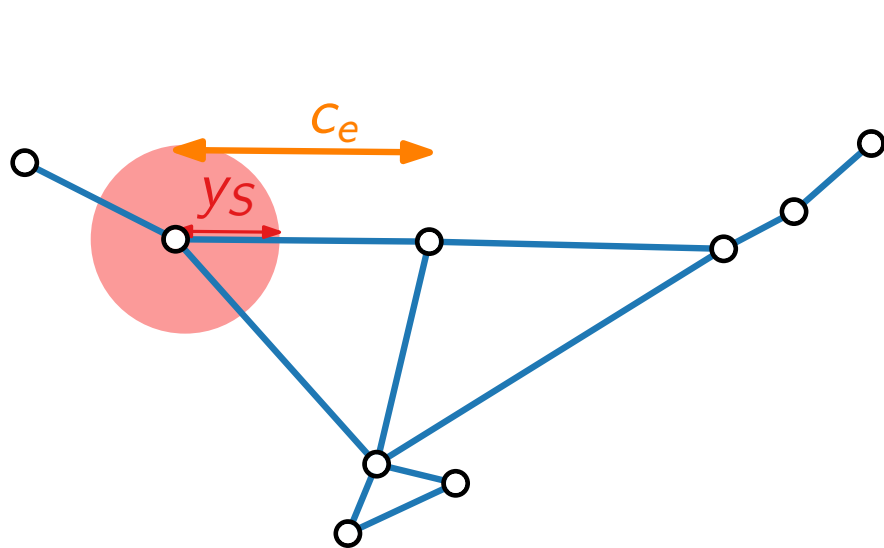
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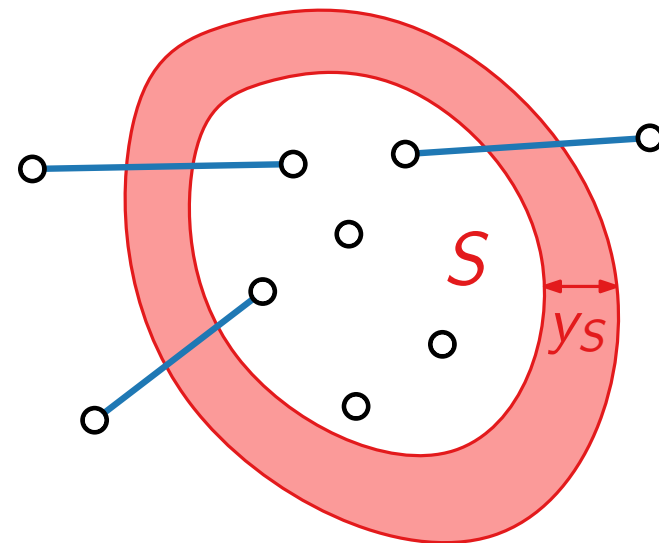
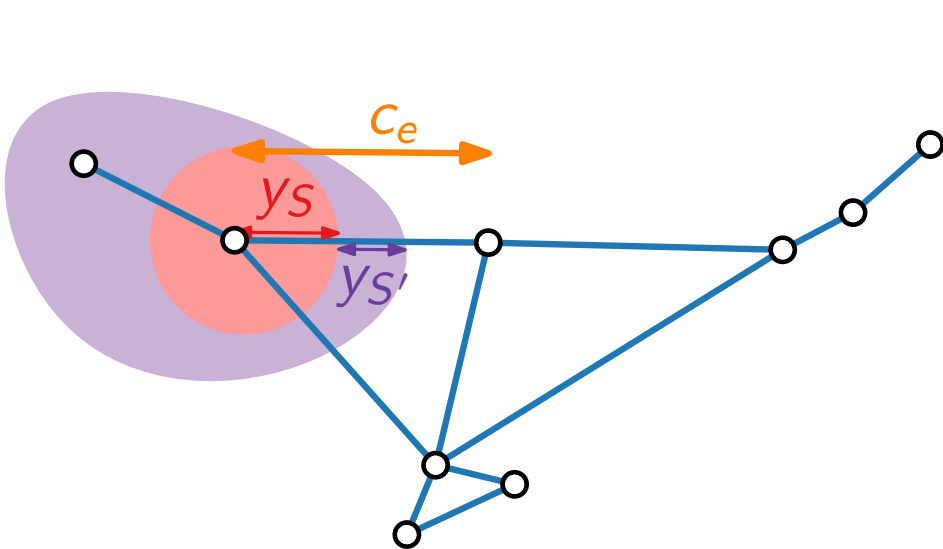
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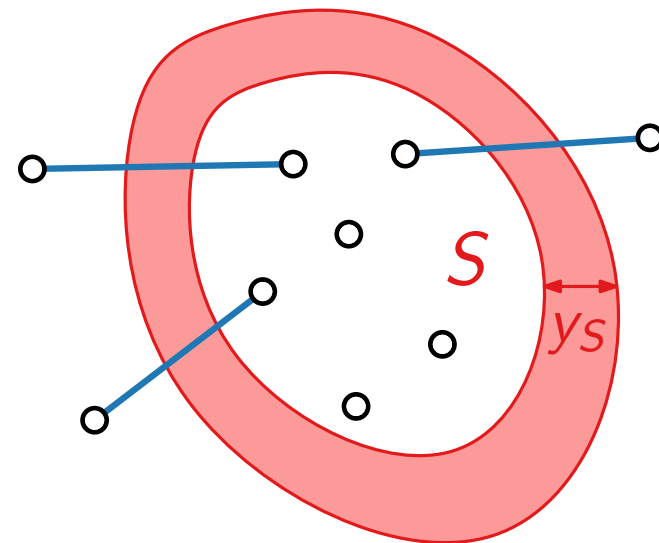
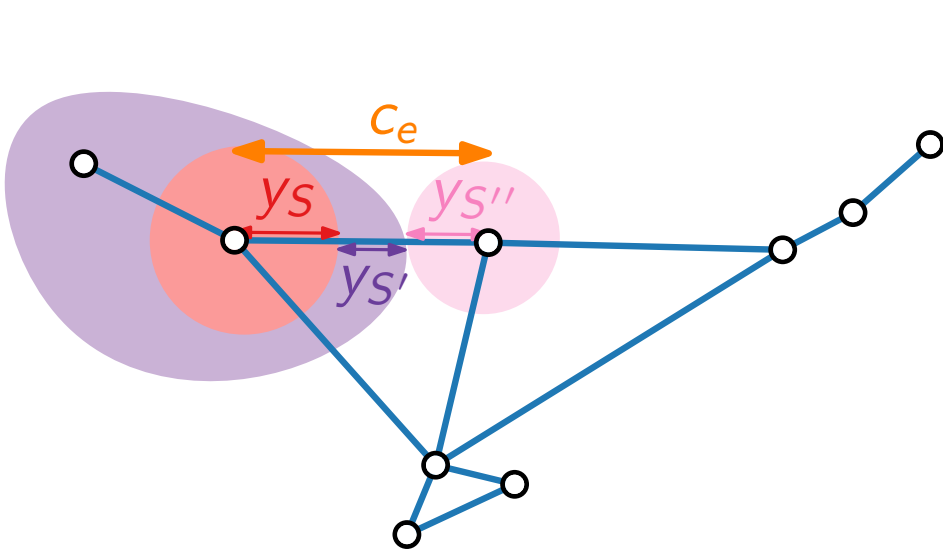
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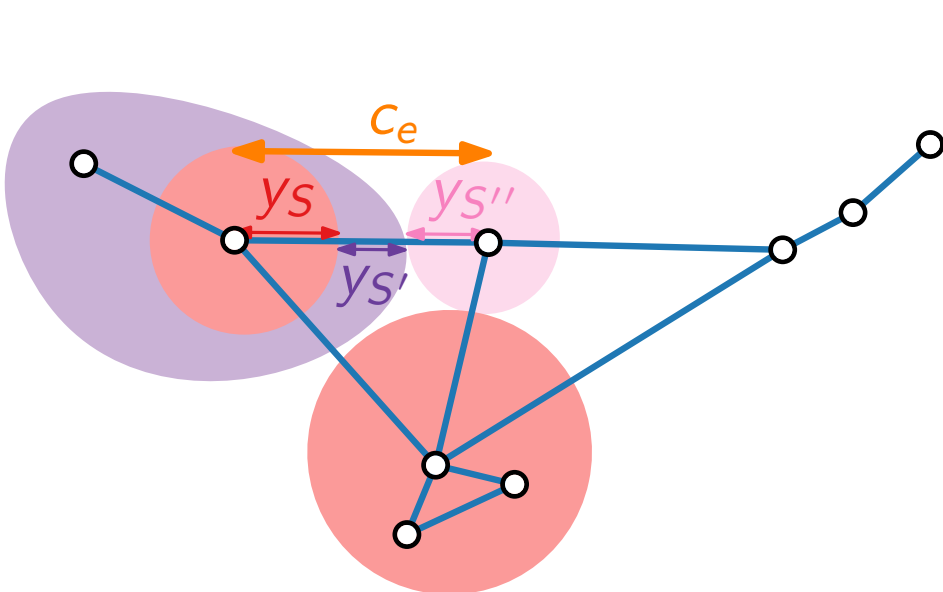
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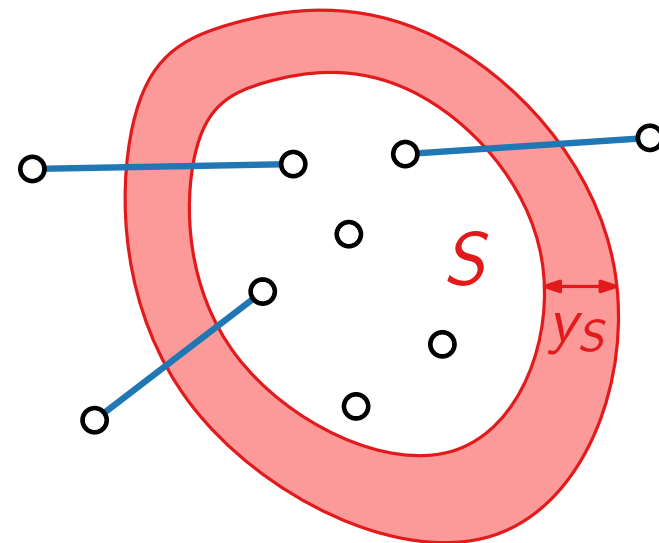
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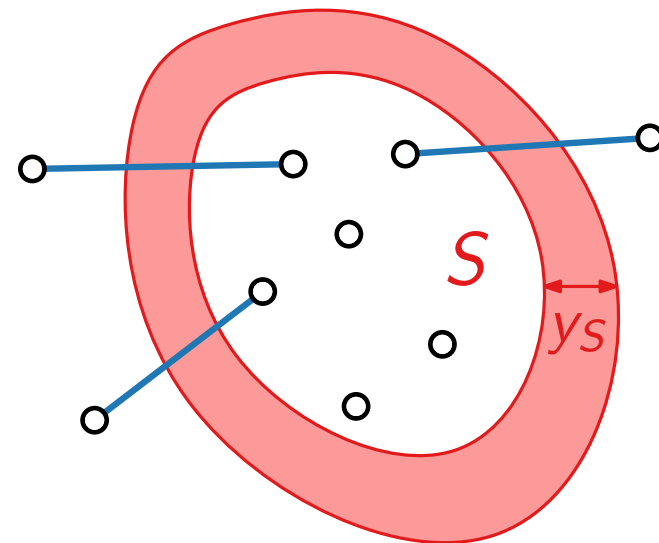
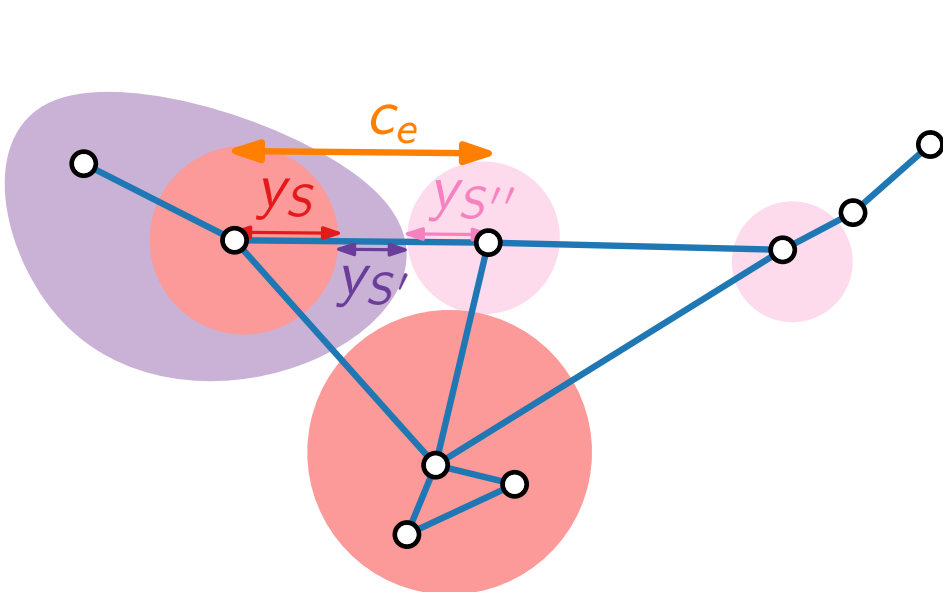


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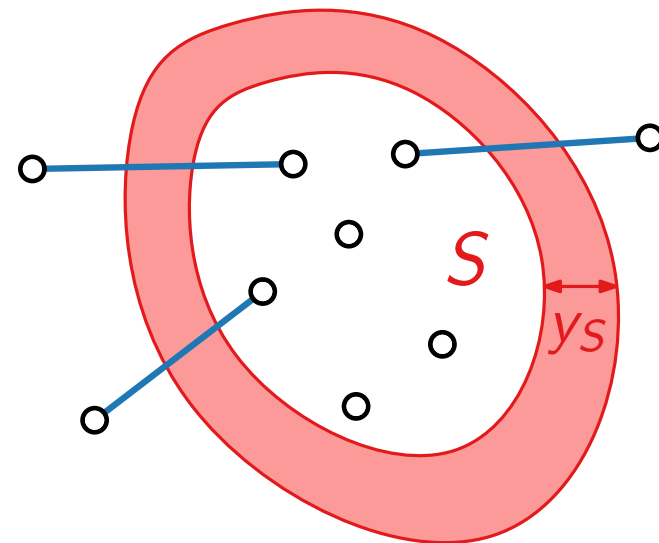
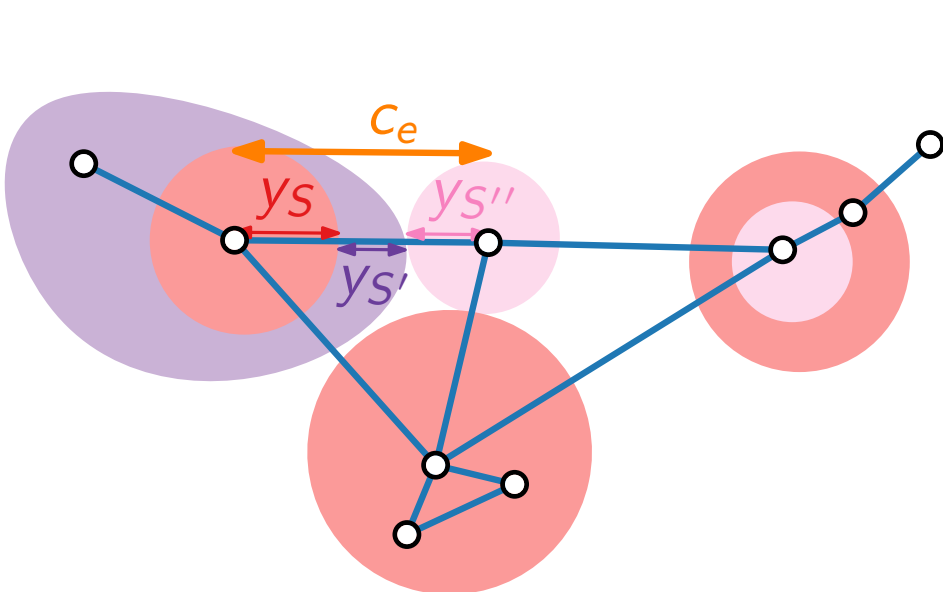
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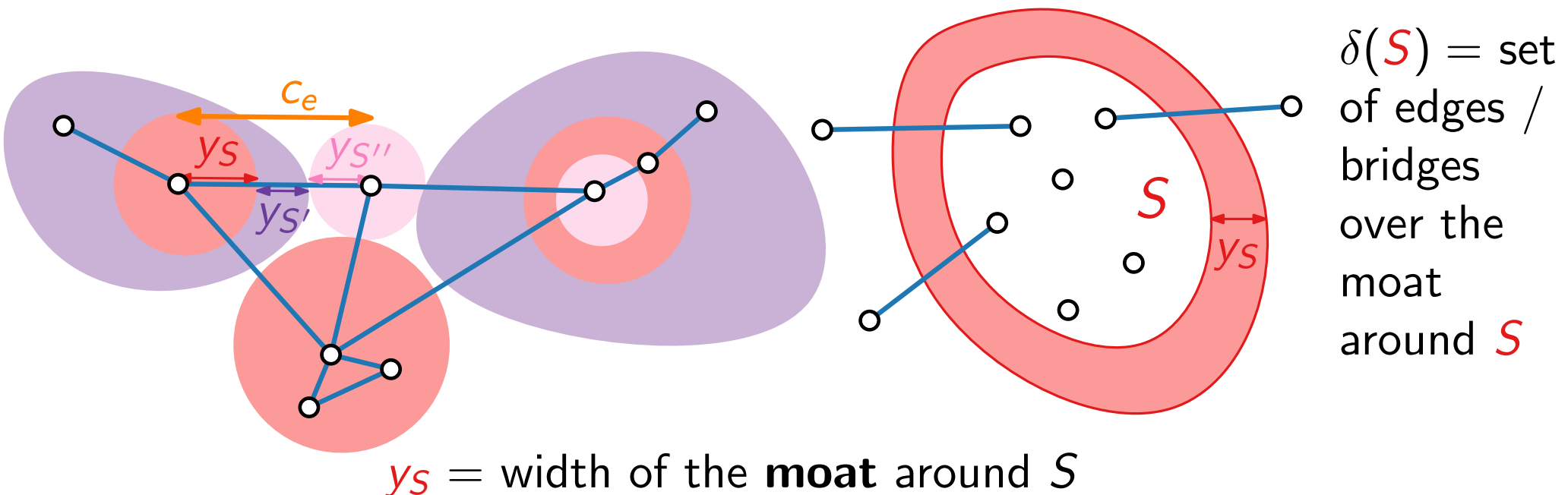
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# Approximation Algorithms

Lecture 12:

STEINERFOREST via Primal–Dual

Part III:

A First Primal–Dual Approach

# Complementary Slackness (Reminder)

$$\begin{array}{ll} \text{minimize} & c^T x \\ \text{subject to} & Ax \geq b \\ & x \geq 0 \end{array}$$

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**Theorem.** Let  $x = (x_1, \dots, x_n)$  and  $y = (y_1, \dots, y_m)$  be valid solutions for the primal and dual program (resp.). Then  $x$  and  $y$  are optimal if and only if the following conditions are met:

**Primal CS:**

For each  $j = 1, \dots, n$ : either  $x_j = 0$  or  $\sum_{i=1}^m a_{ij} y_i = c_j$

**Dual CS:**

For each  $i = 1, \dots, m$ : either  $y_i = 0$  or  $\sum_{j=1}^n a_{ij} x_j = b_i$



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How do we iteratively improve the dual solution?

- Increase  $y_C$  (until some edge in  $\delta(C)$  becomes critical)!



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Trick: Handle all  $y_S$  with  $y_S = 0$  implicitly.

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$\Rightarrow$  Increase  $y_C$  for all active components  $C$  simultaneously!

# Approximation Algorithms

Lecture 12:

STEINERFOREST via Primal–Dual

Part IV:

Primal–Dual with Synchronized Increases

# Primal–Dual with Synchronized Increases

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$y \leftarrow 0$ ,  $F \leftarrow \emptyset$ ,  $\ell \leftarrow 0$

**while**  $\exists (s, t) \in R$  not connected in  $(V(G), F)$  **do**

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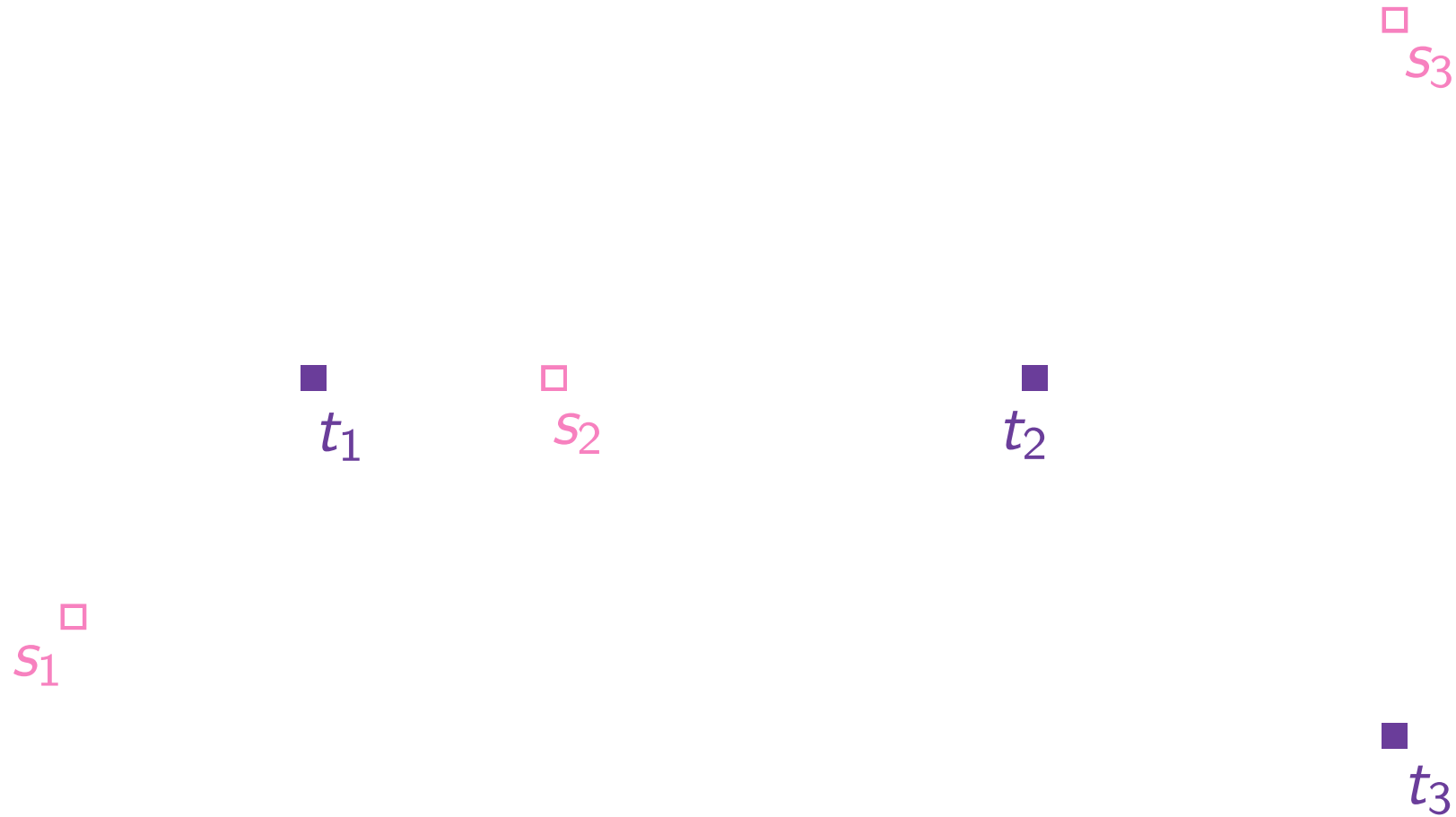
**if**  $F' \setminus \{e_j\}$  is feasible solution **then**

$F' \leftarrow F' \setminus \{e_j\}$

**return**  $F'$

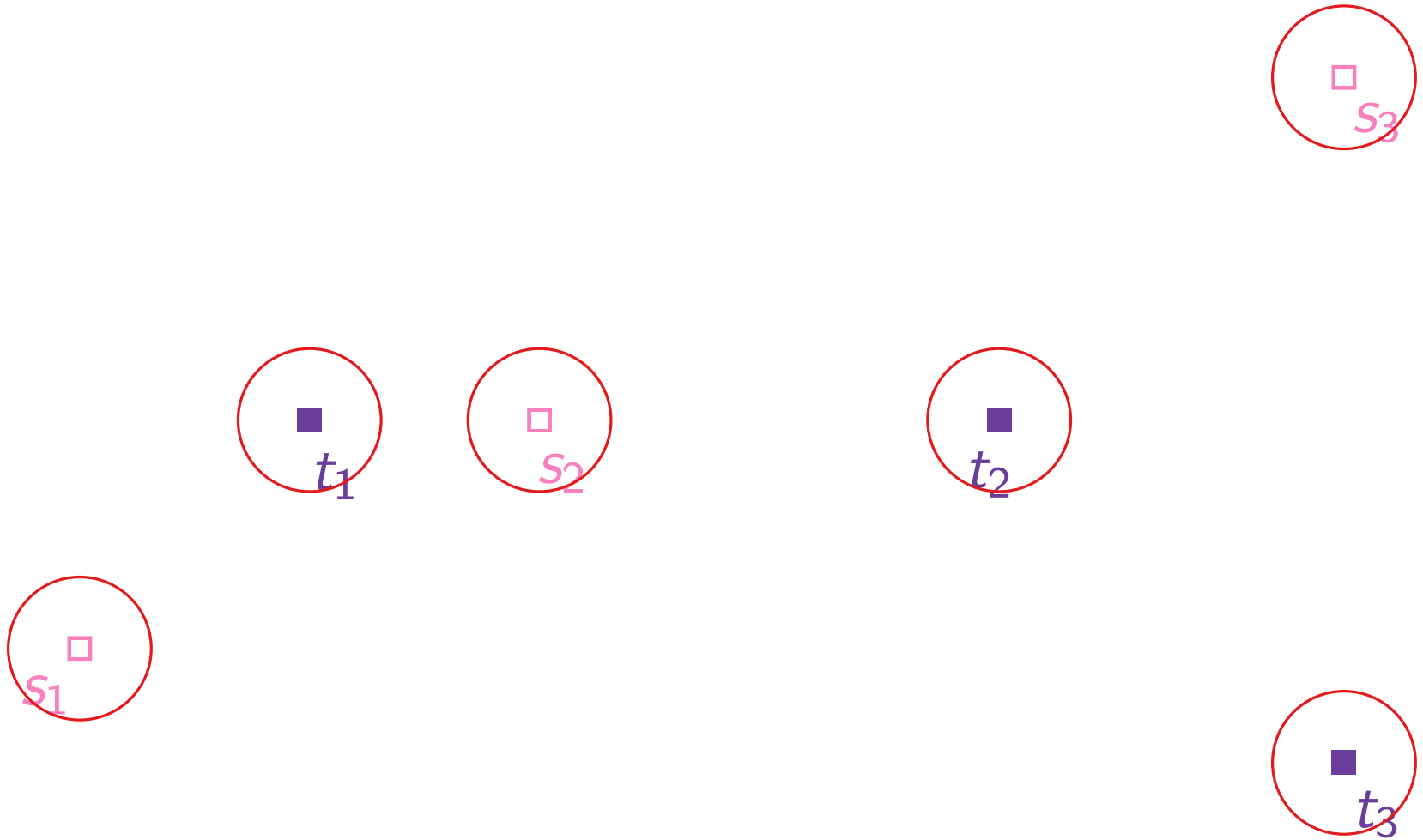
# Illustration

$G = K_6$  with Euclidean edge costs



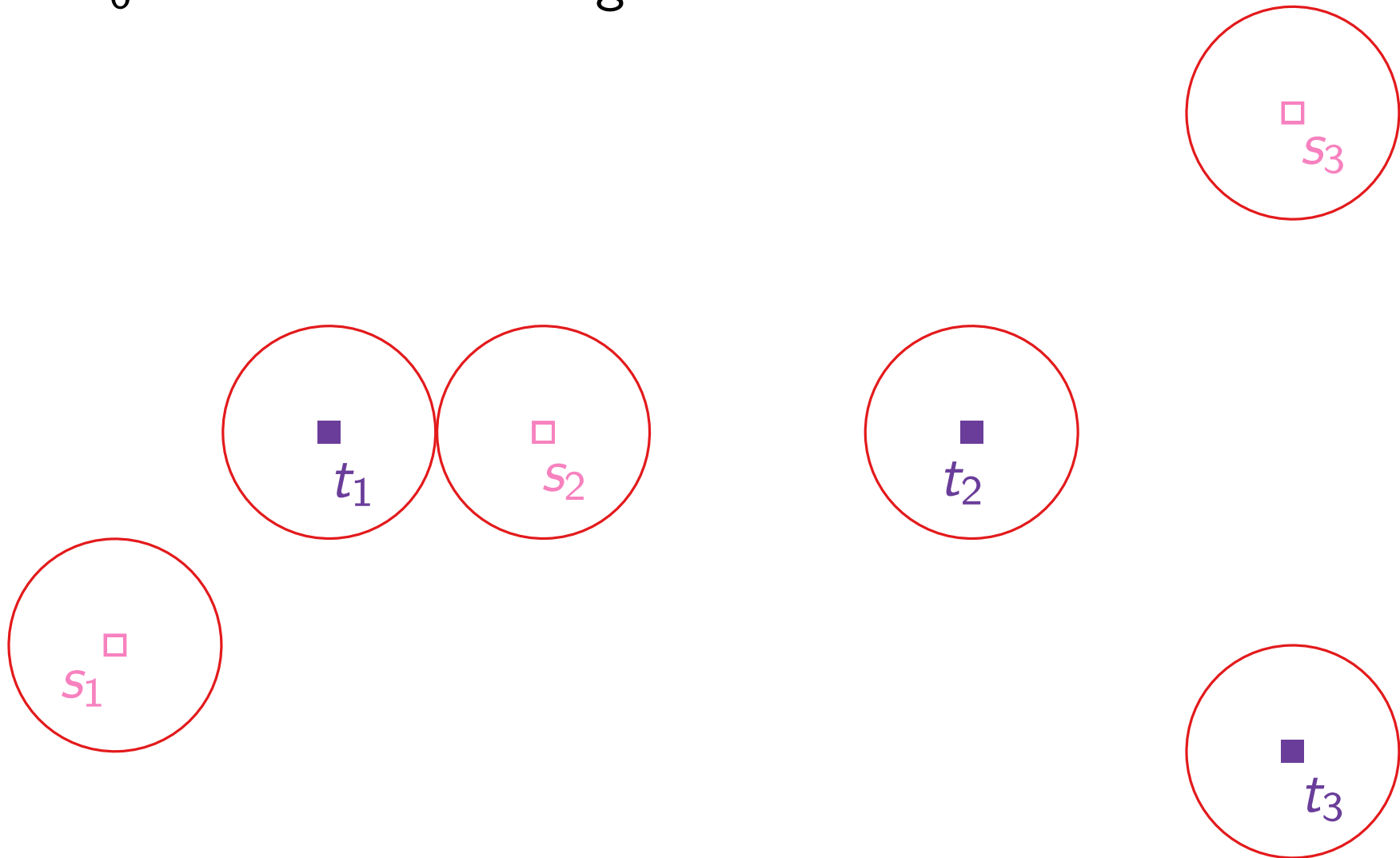
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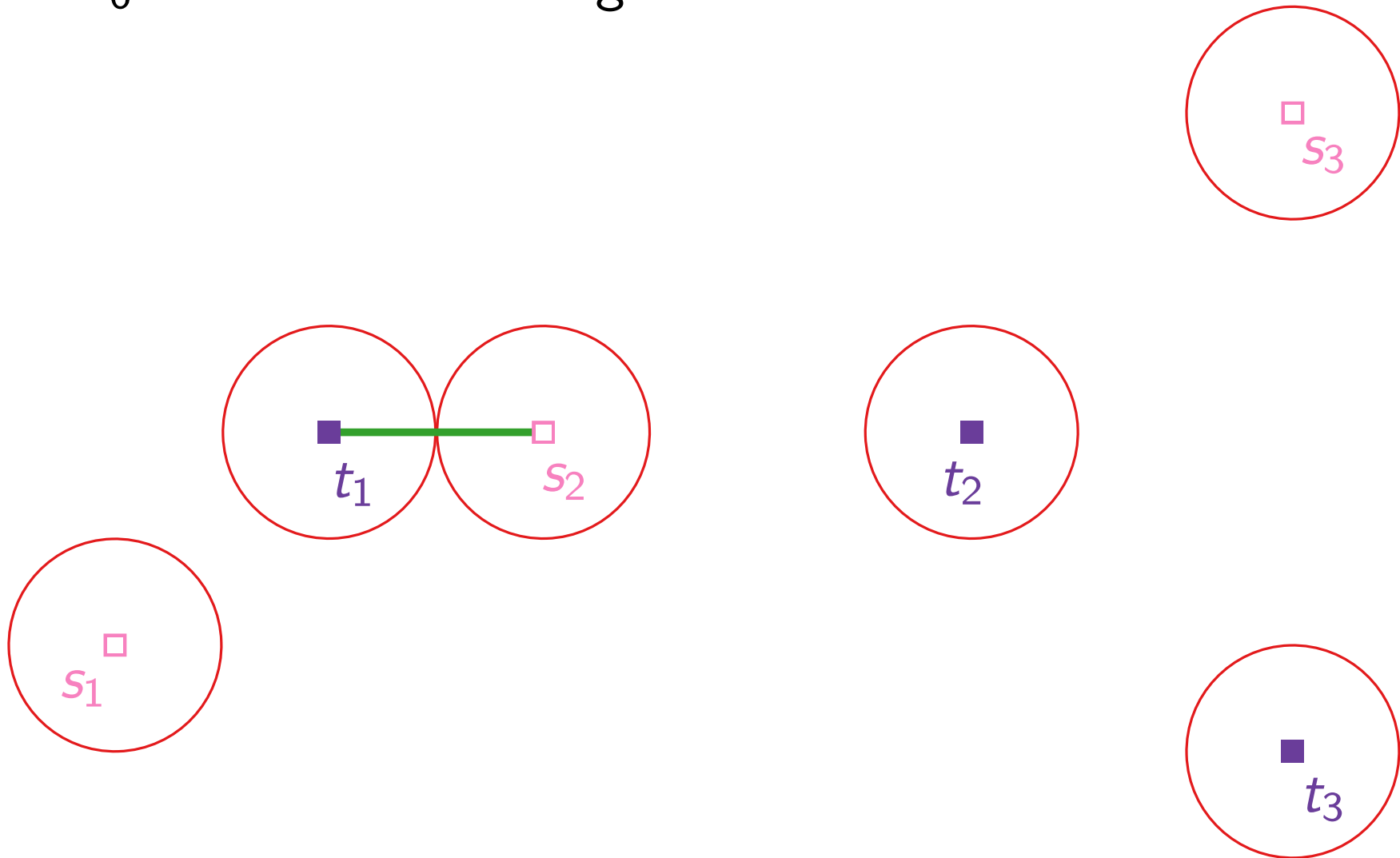
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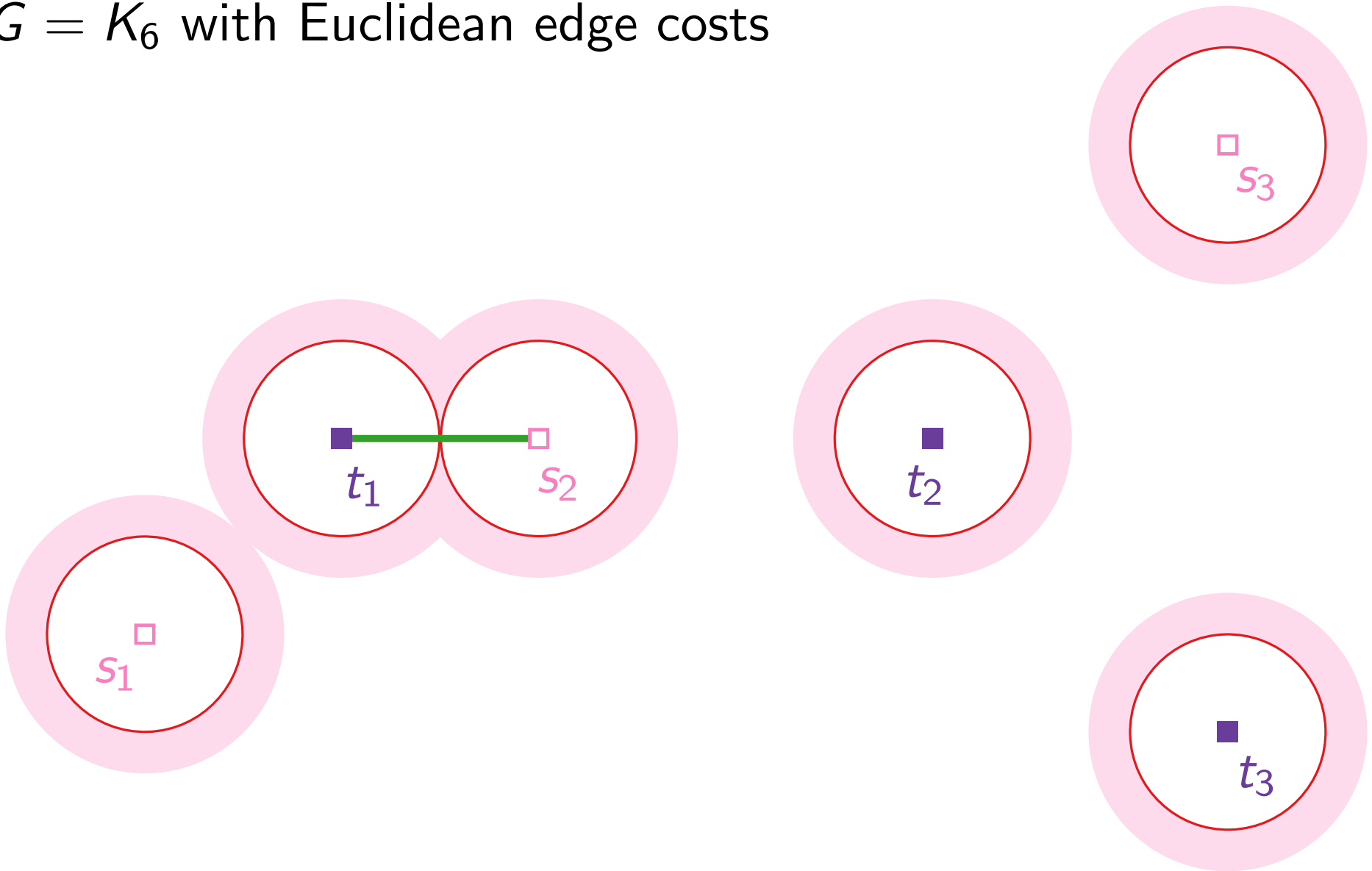
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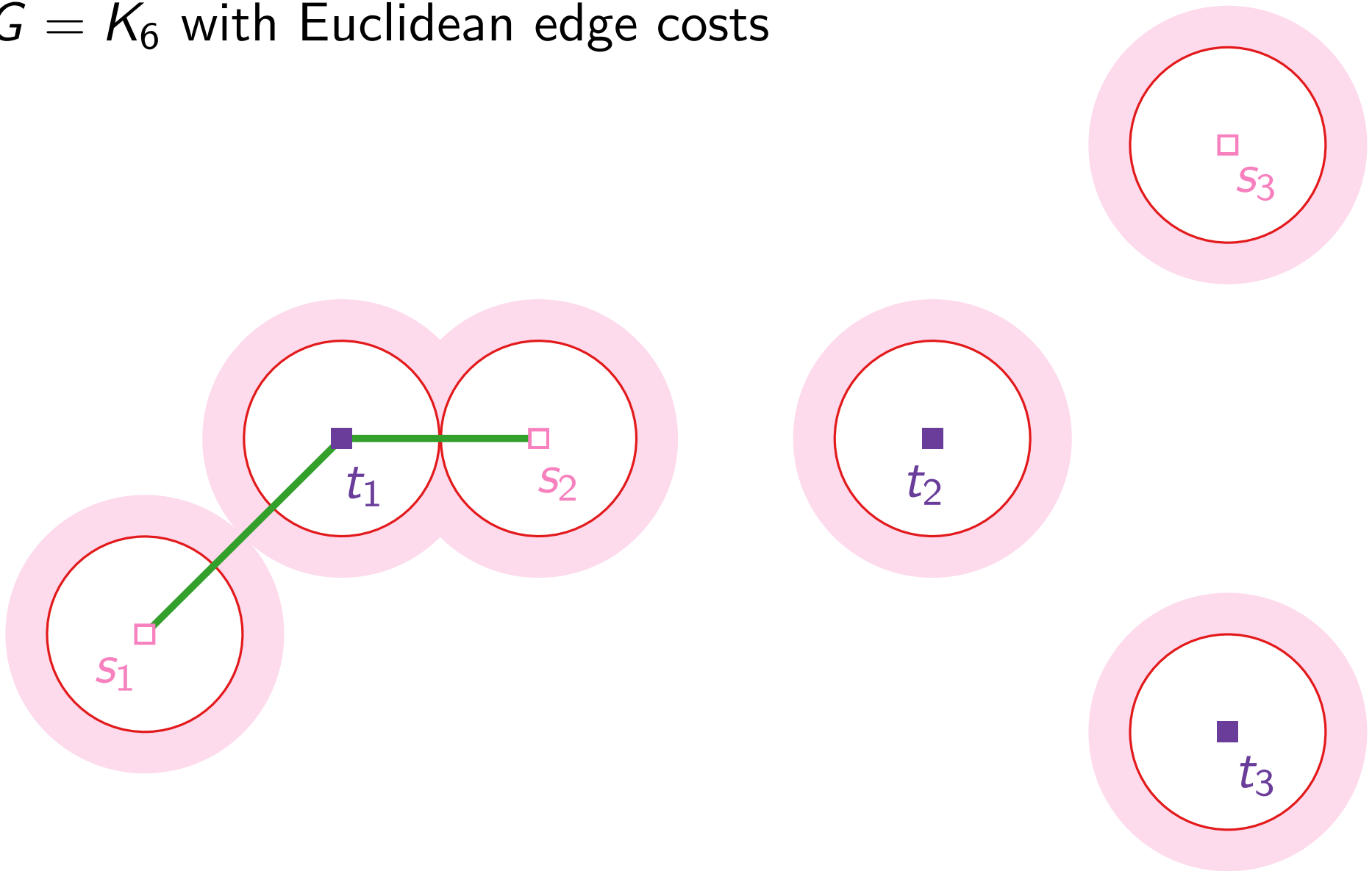
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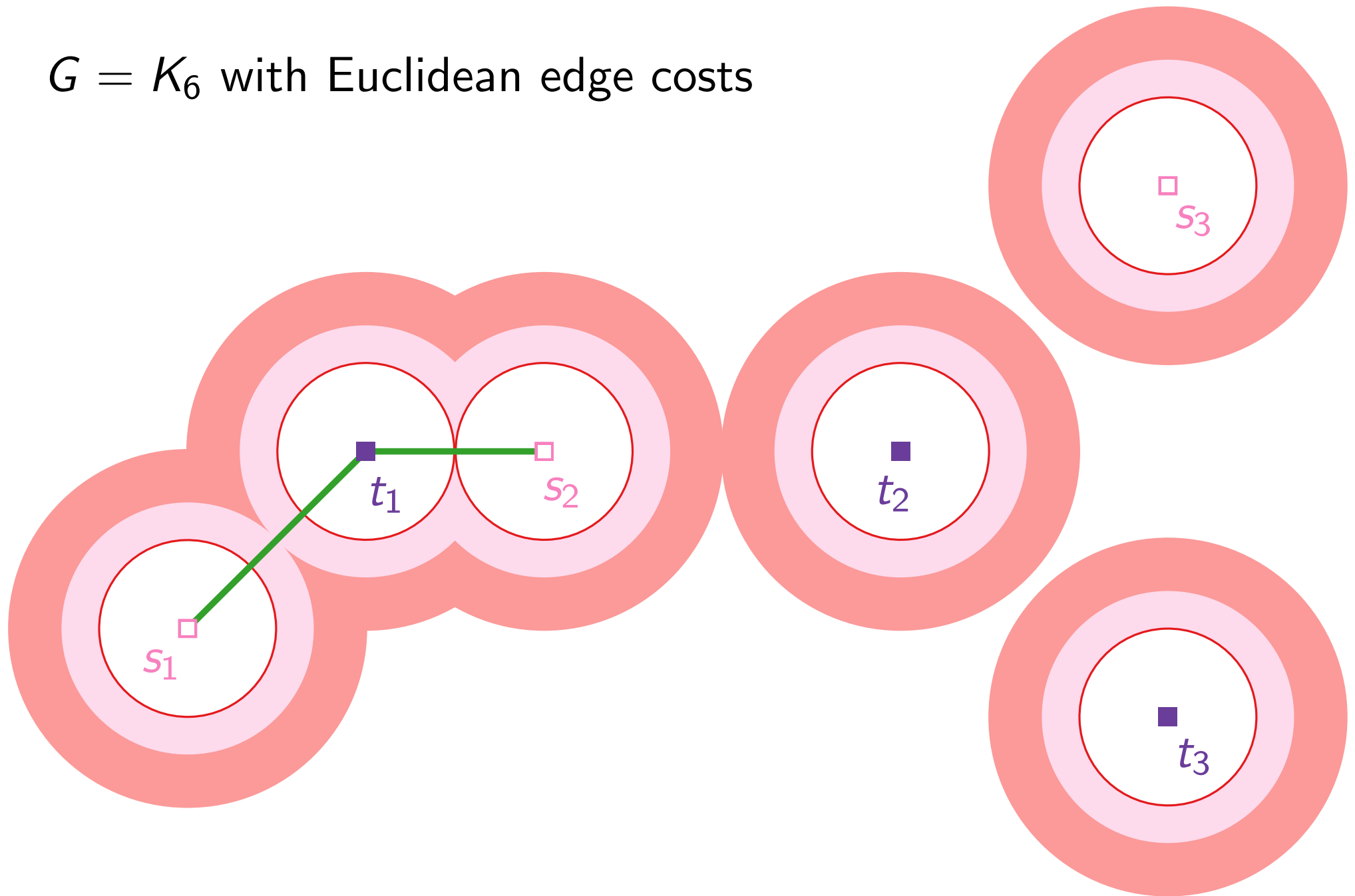
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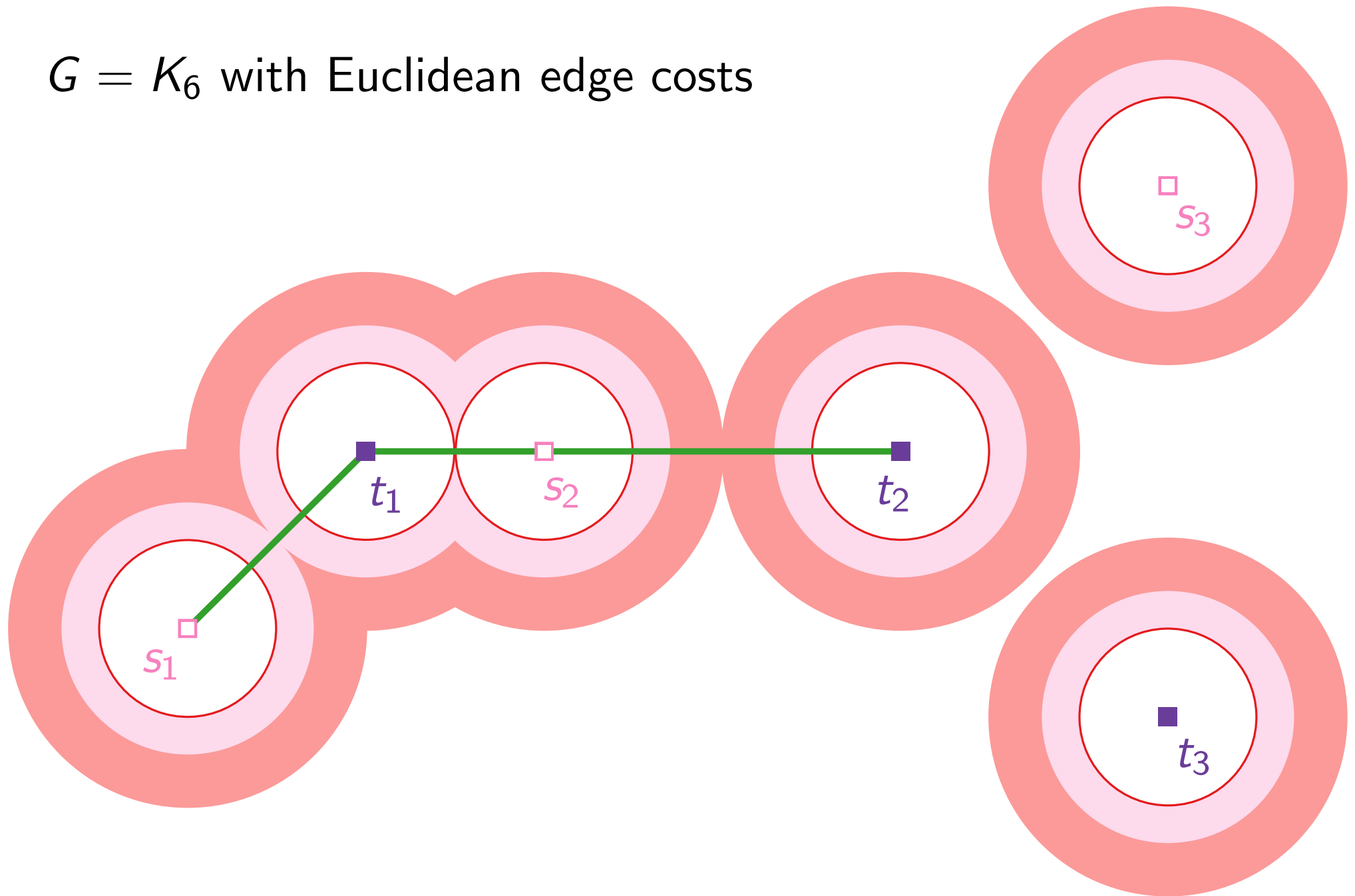
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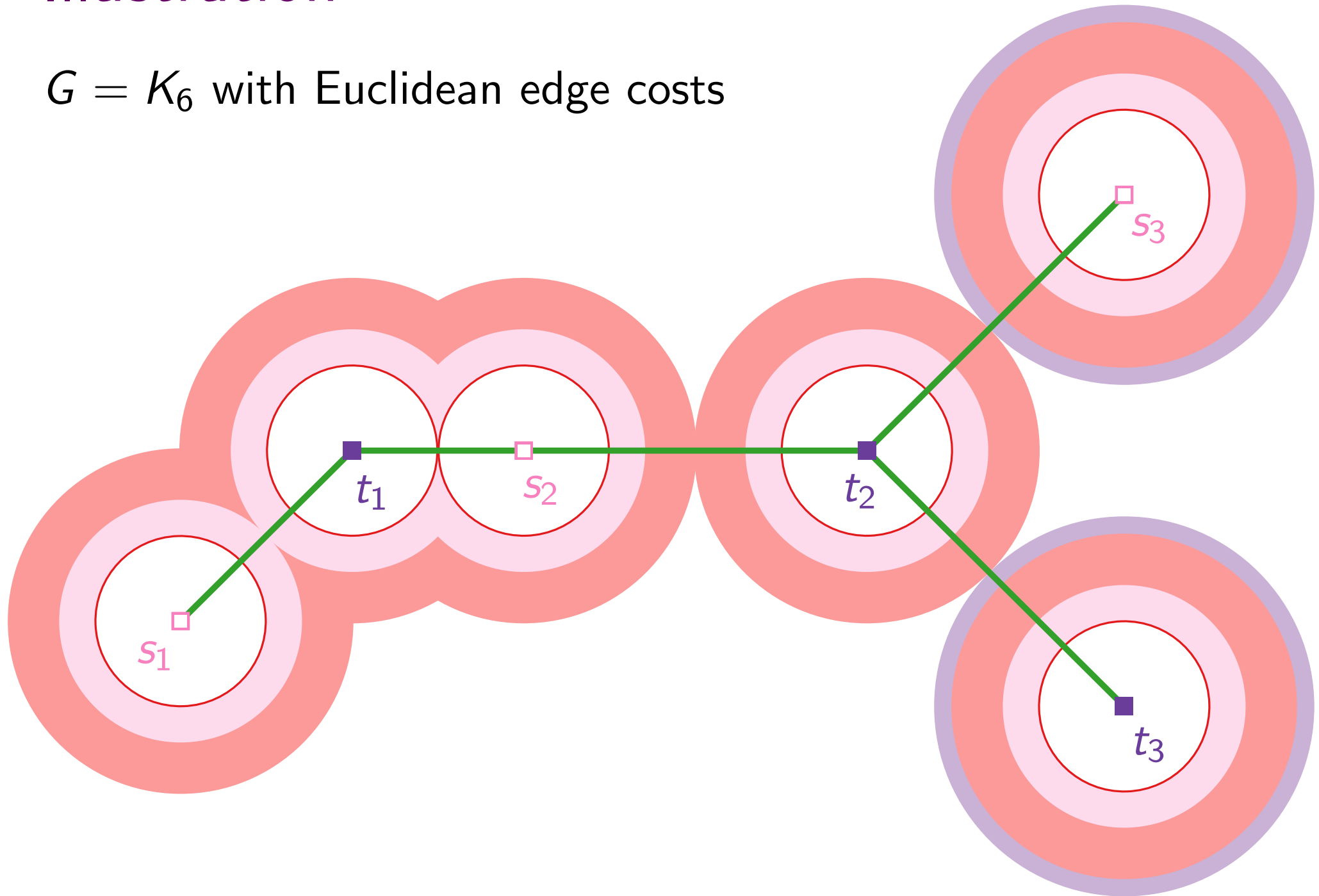
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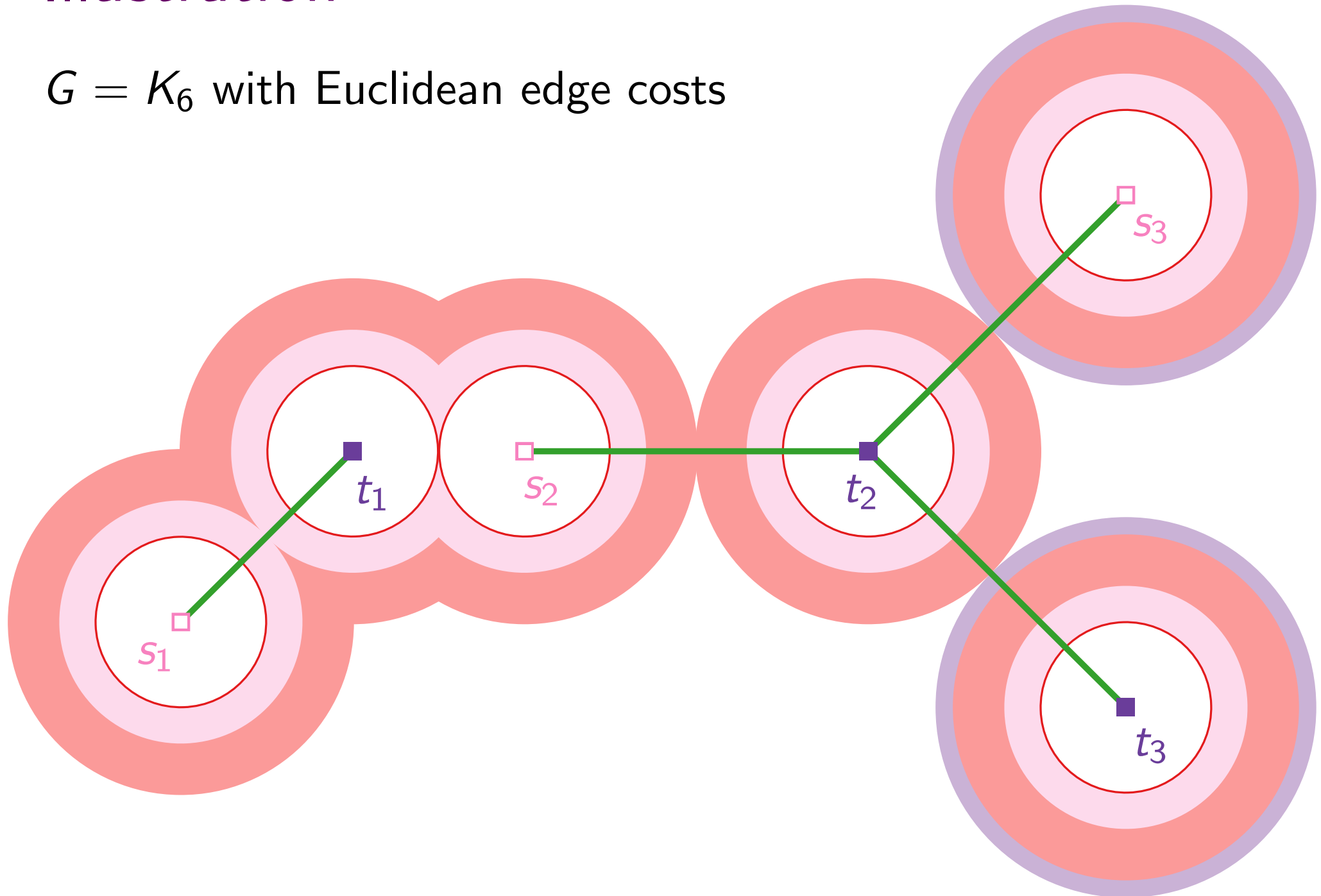
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# Approximation Algorithms

Lecture 12:

STEINERFOREST via Primal–Dual

Part V:

Structure Lemma

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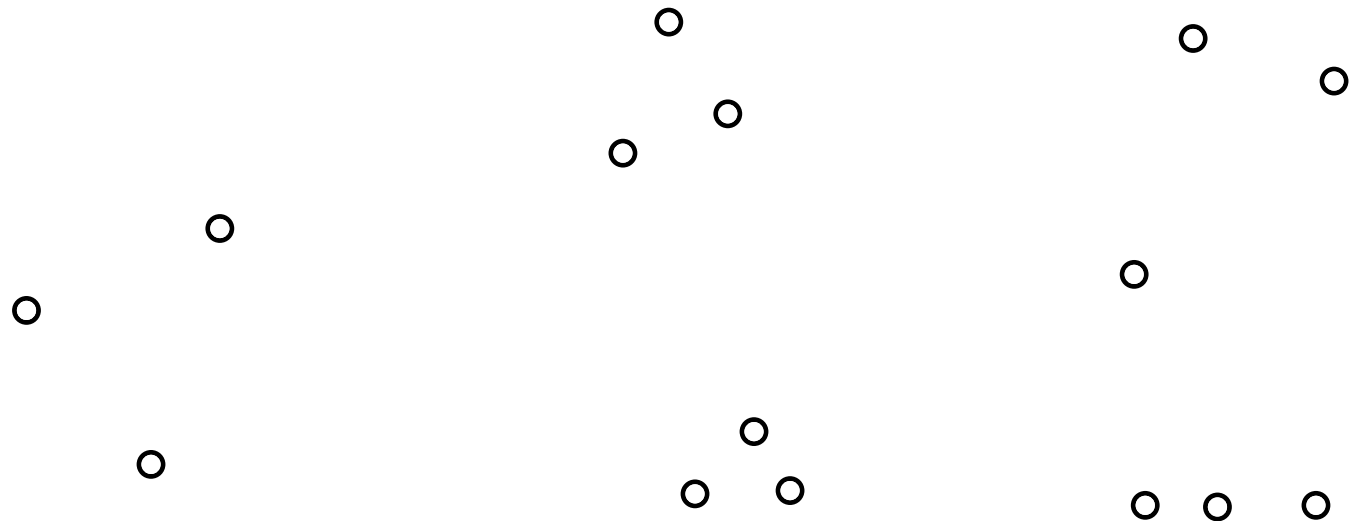
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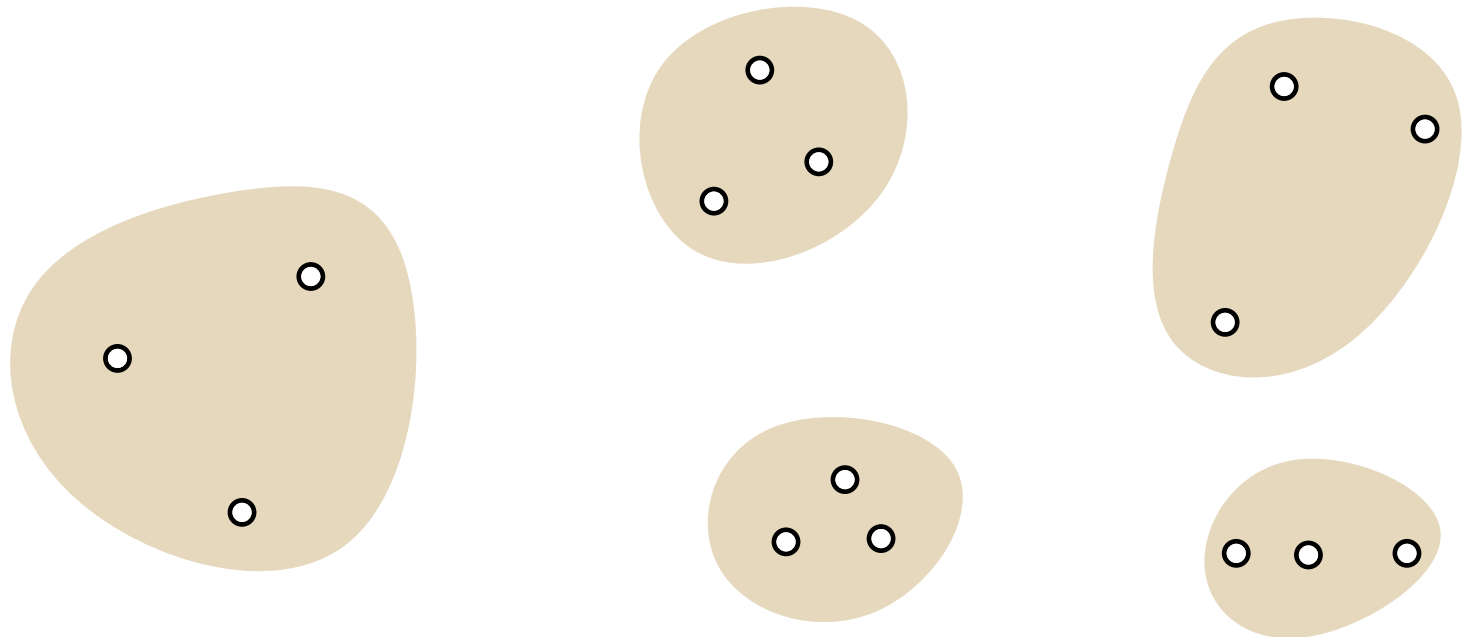


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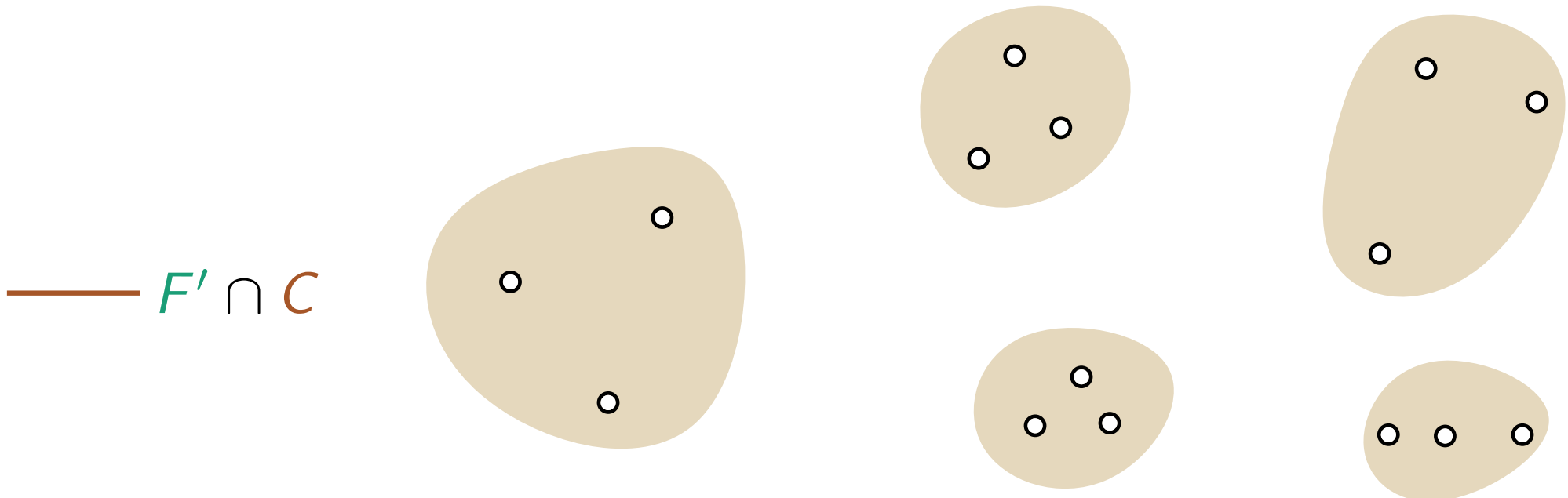


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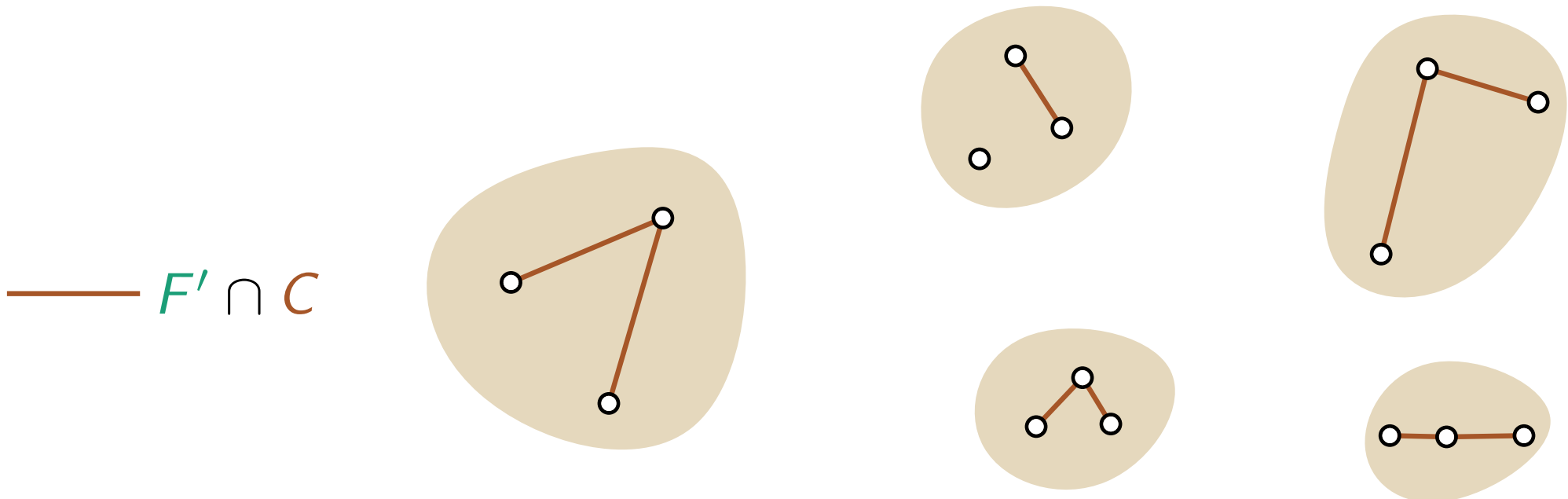


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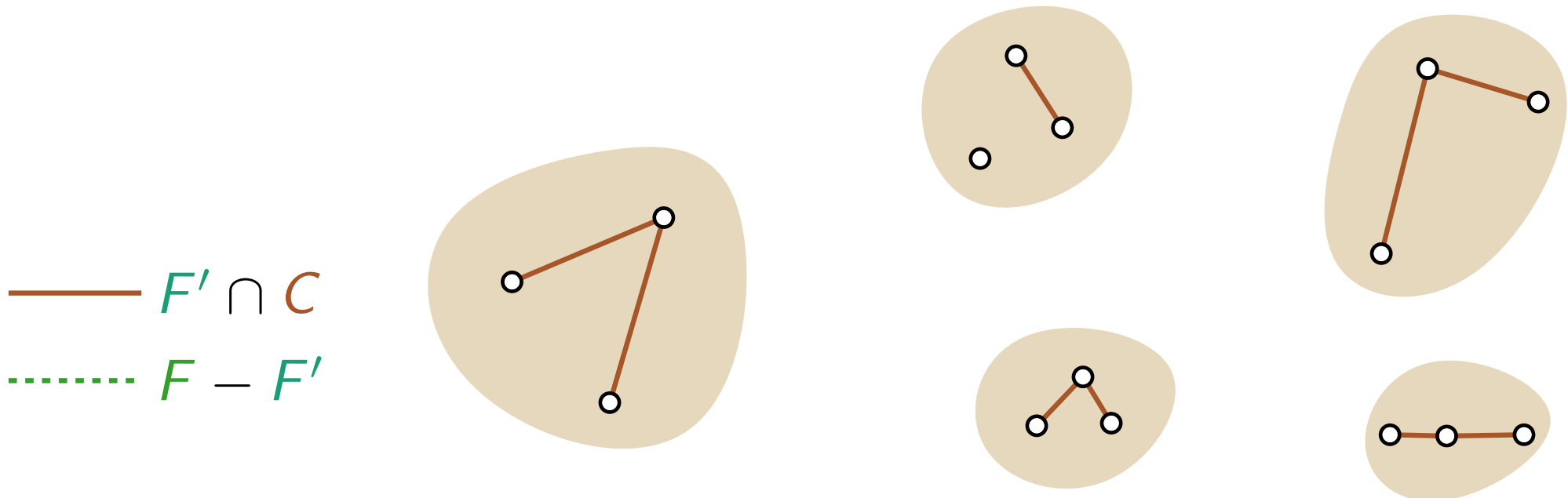


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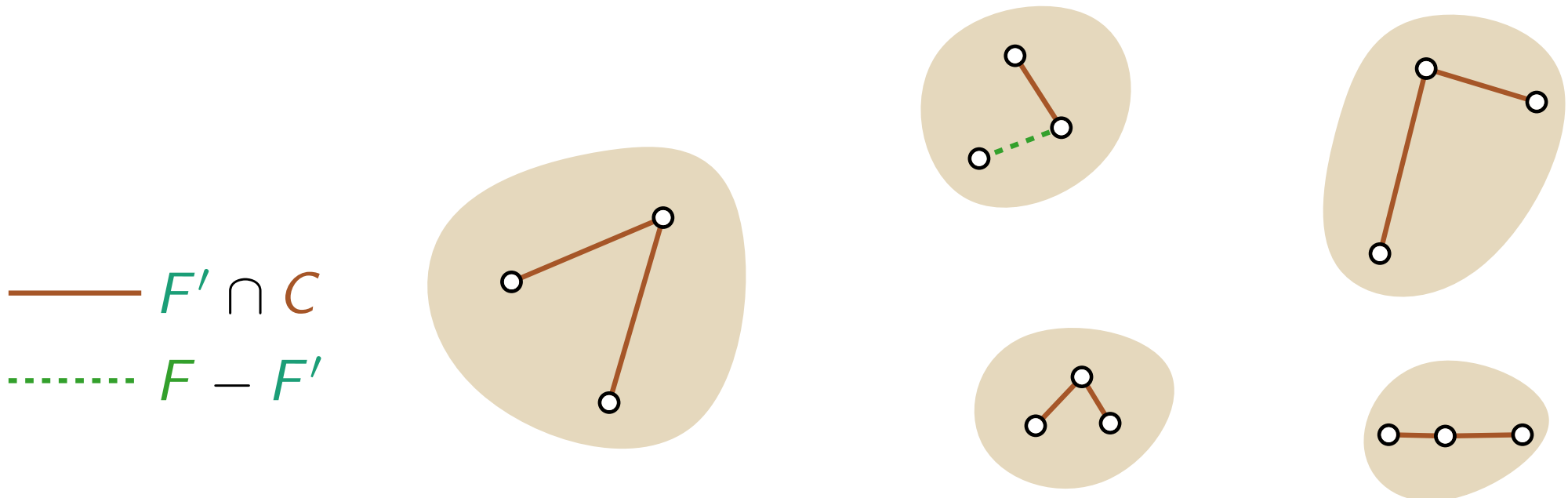


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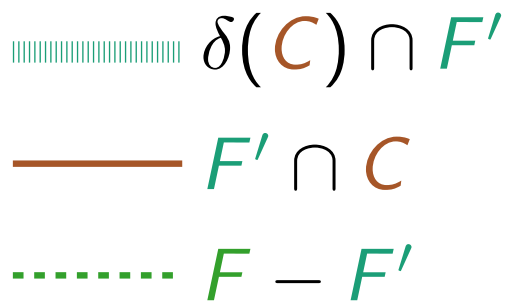





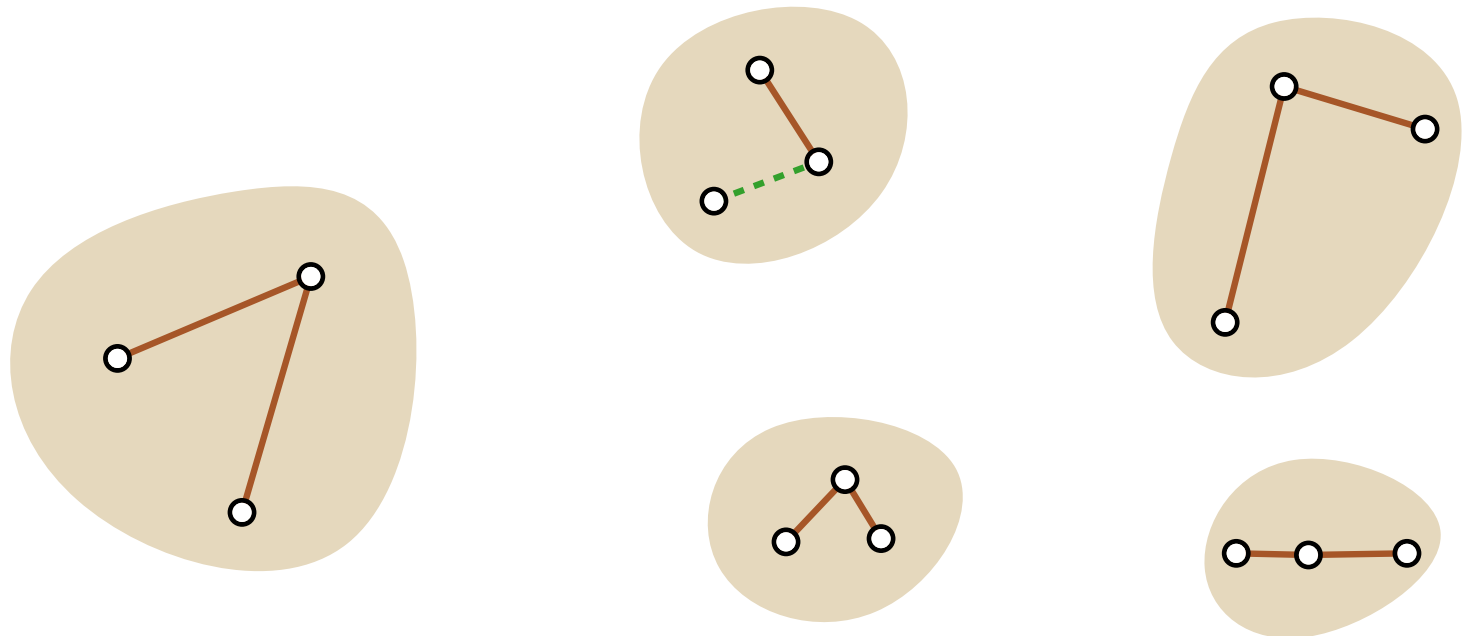
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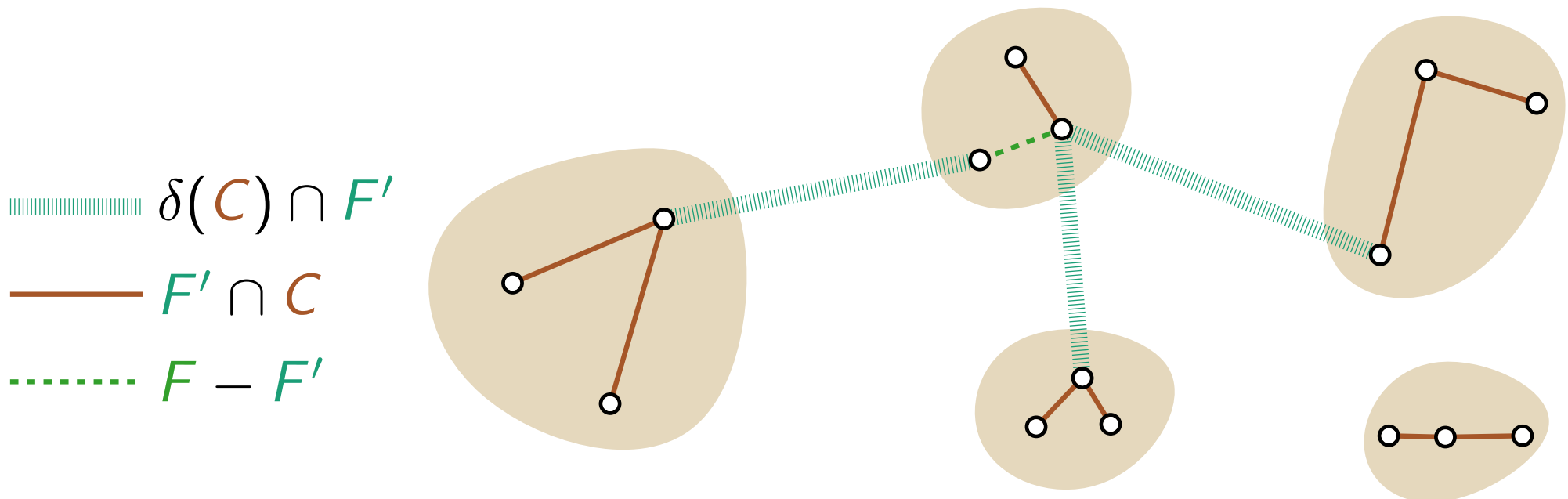


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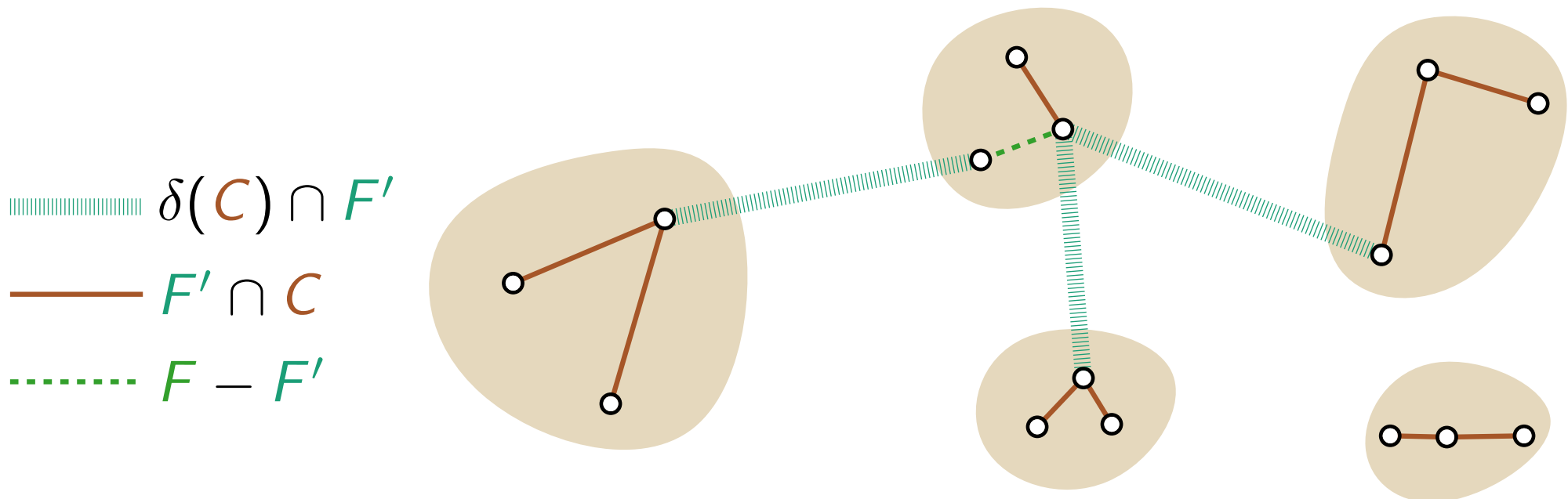
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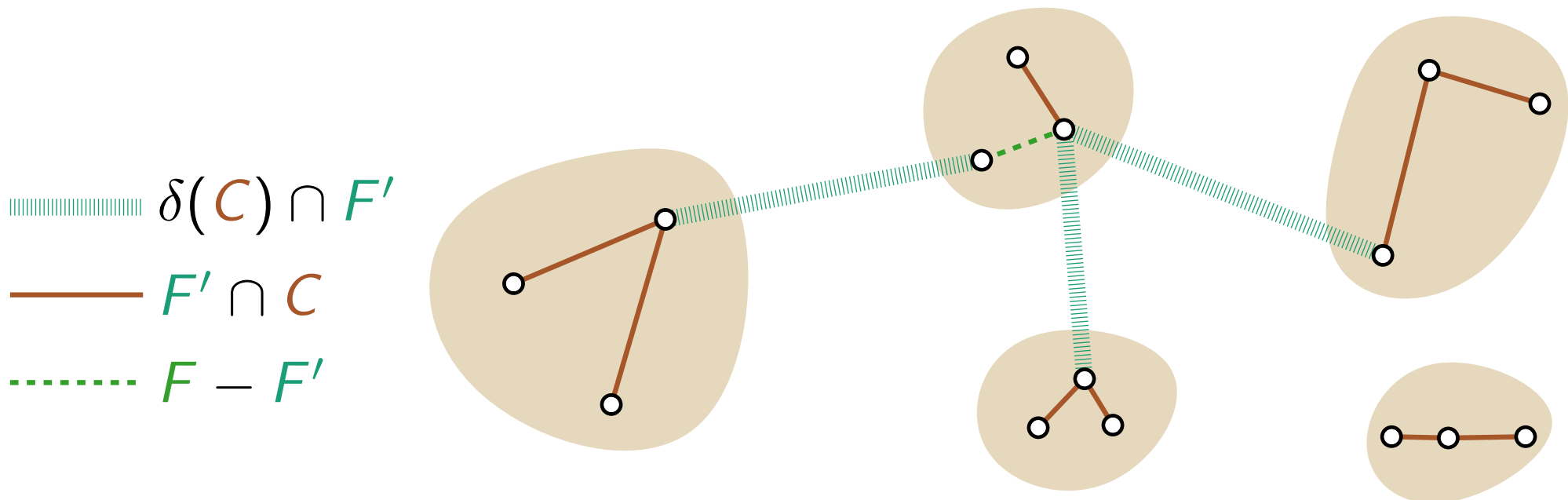
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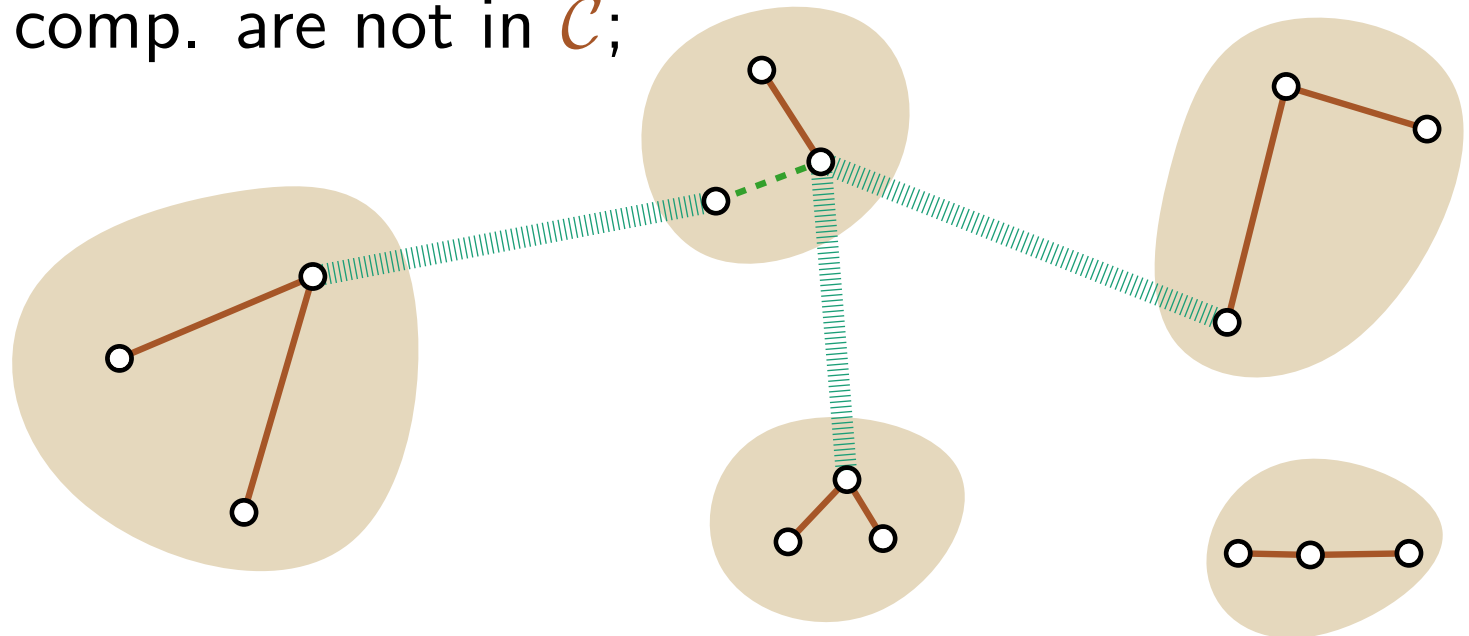
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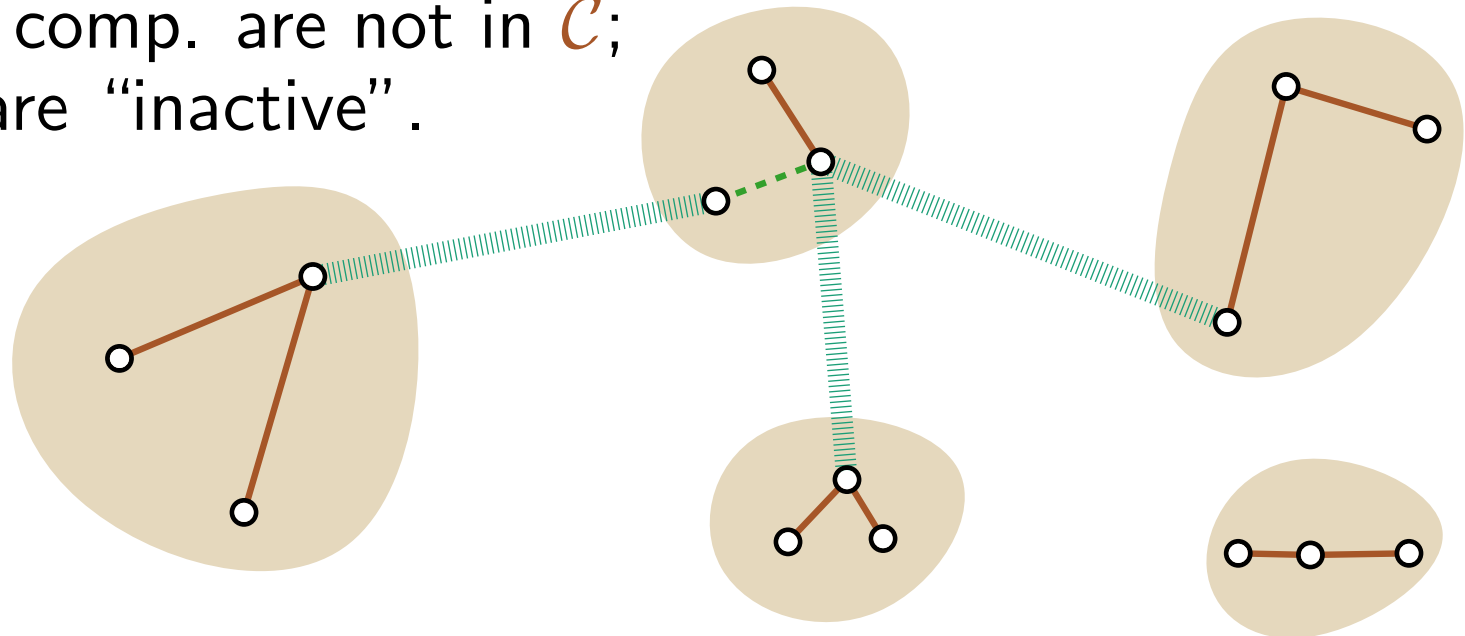
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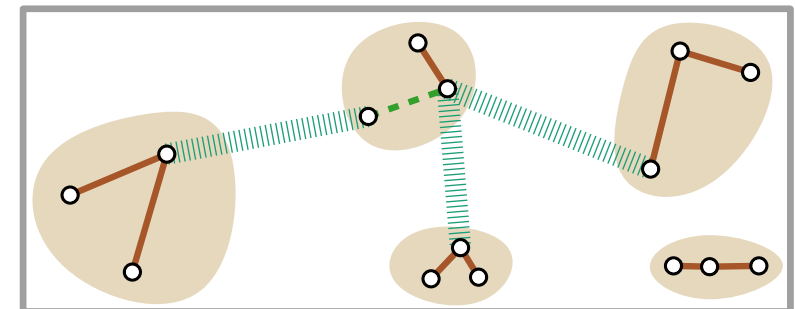


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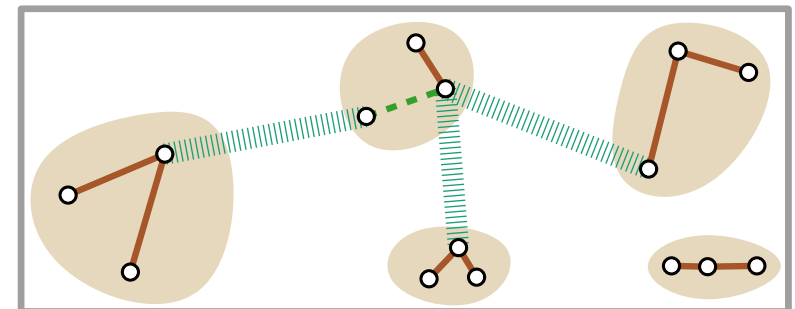
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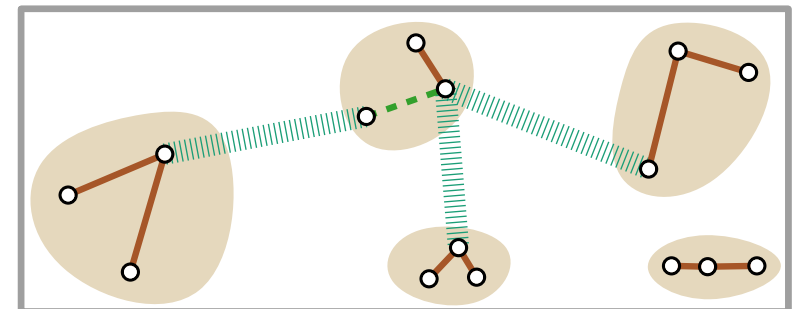
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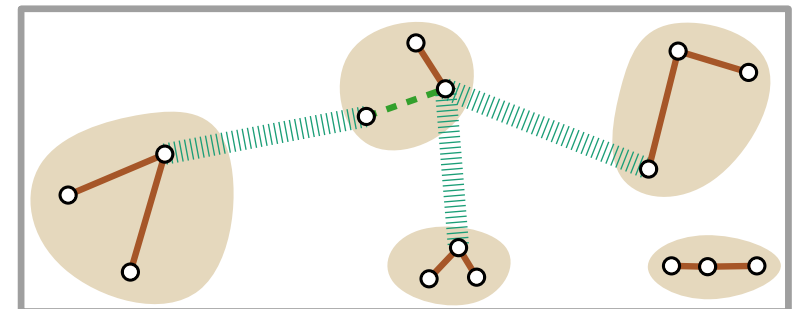
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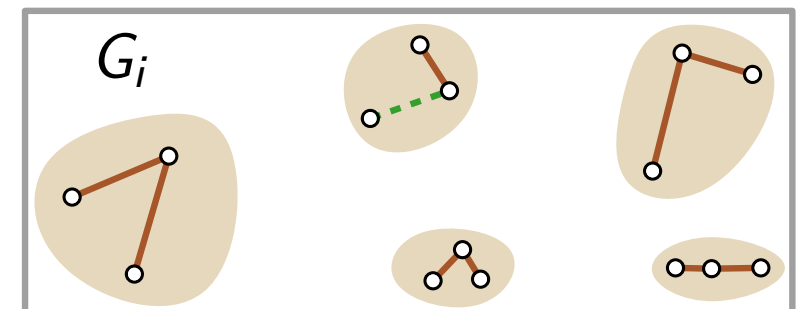
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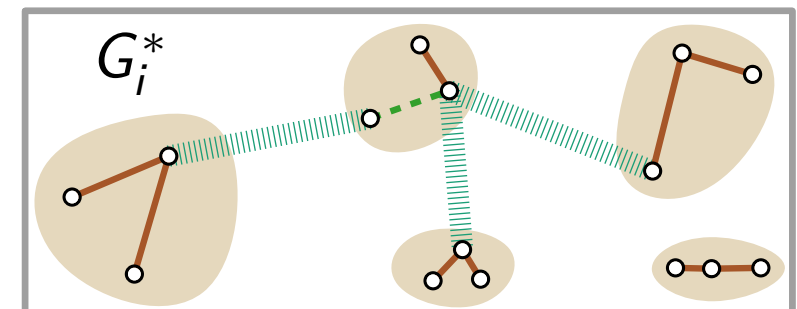
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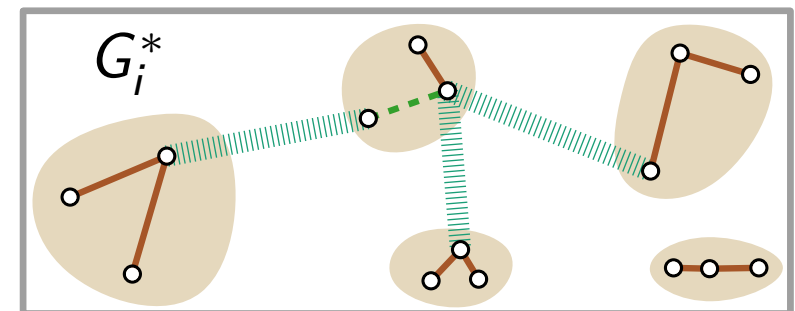
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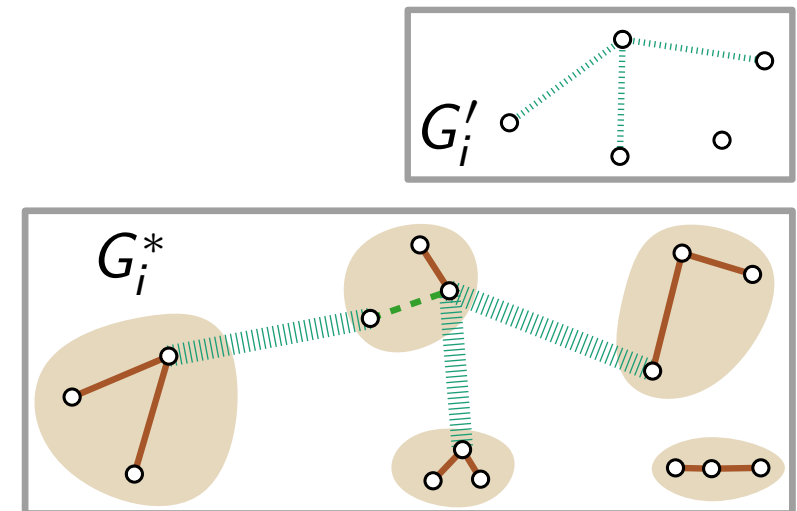
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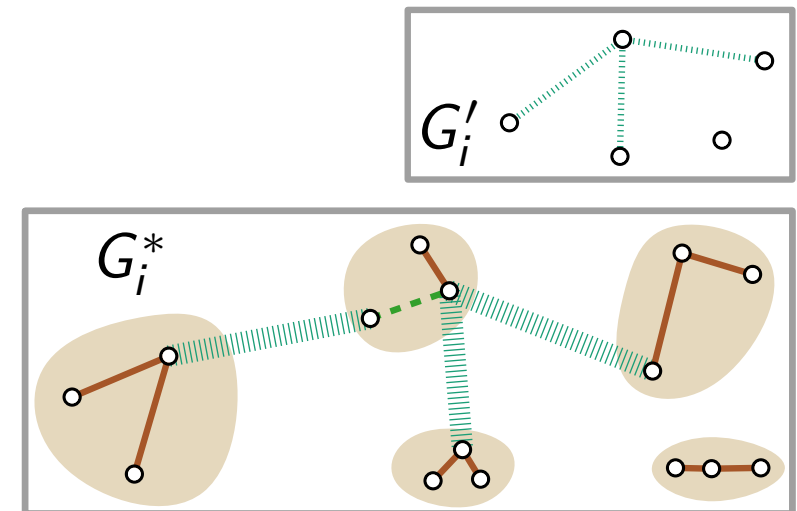
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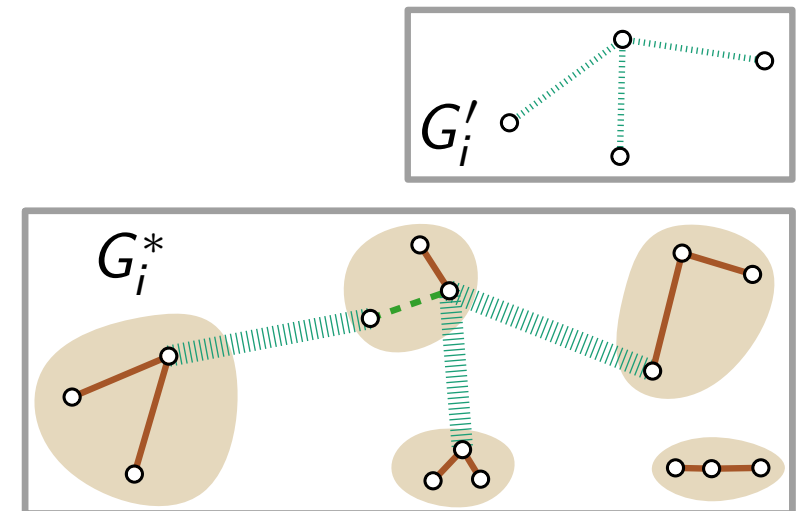
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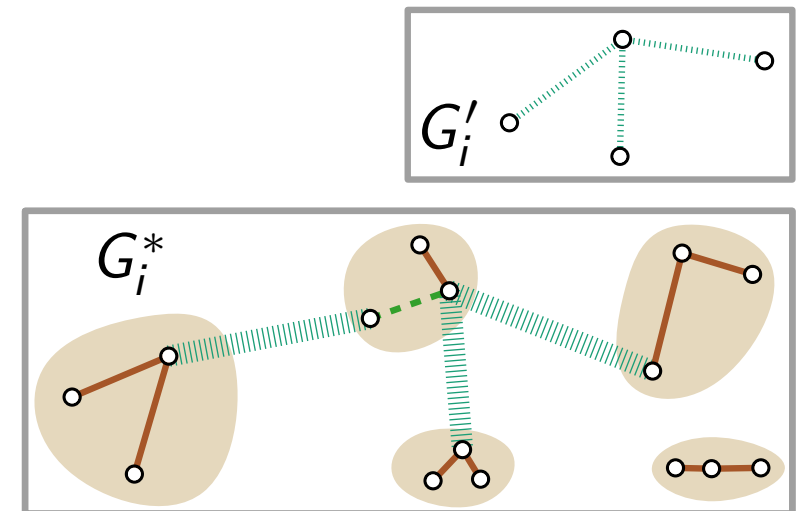
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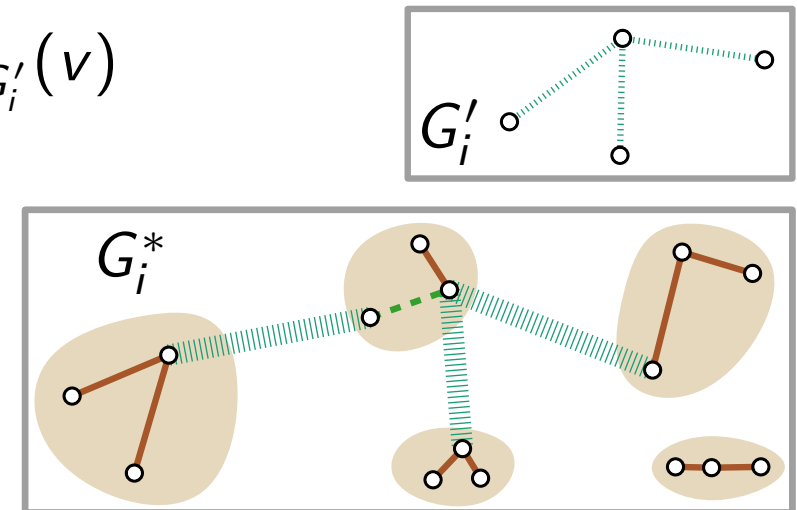
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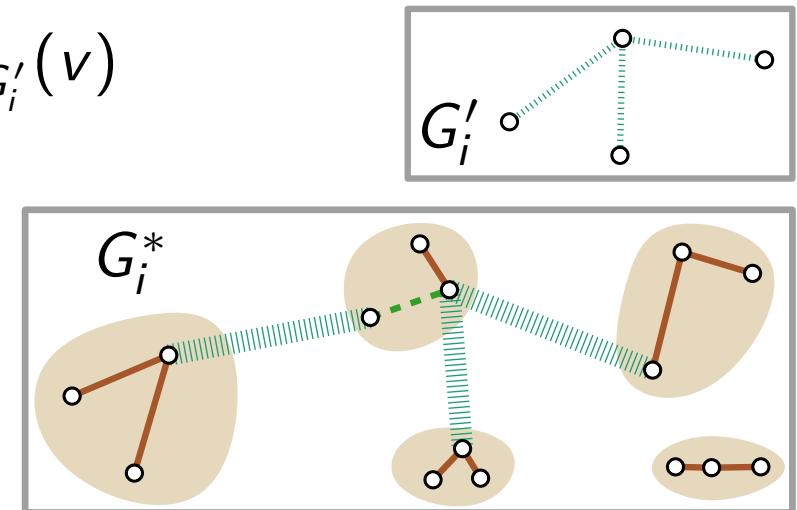
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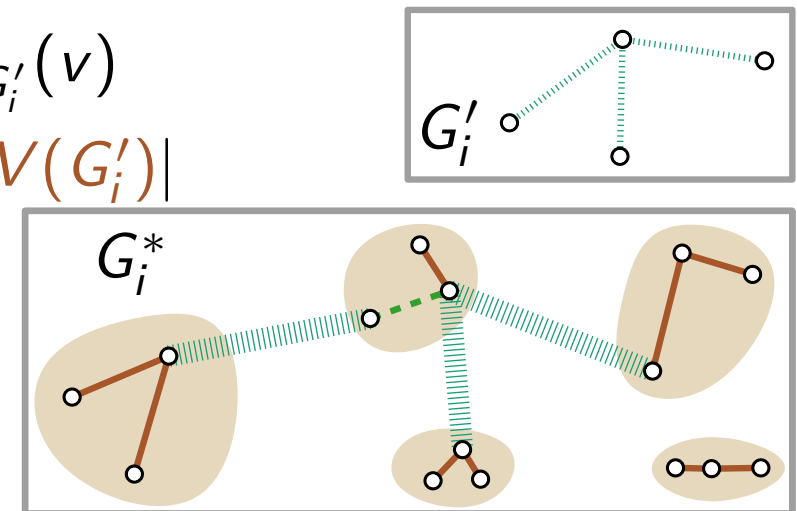
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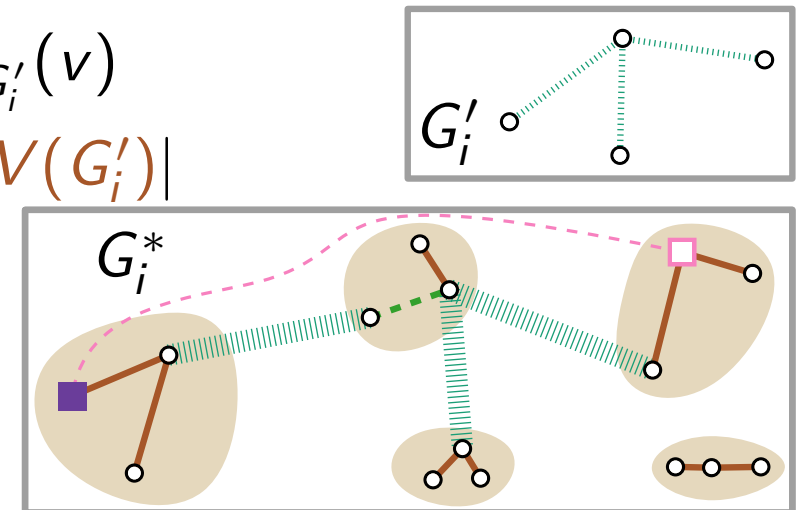
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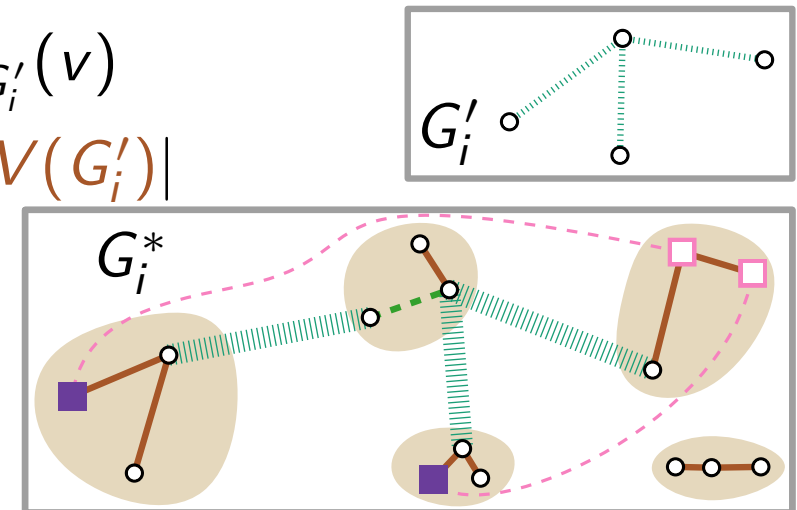
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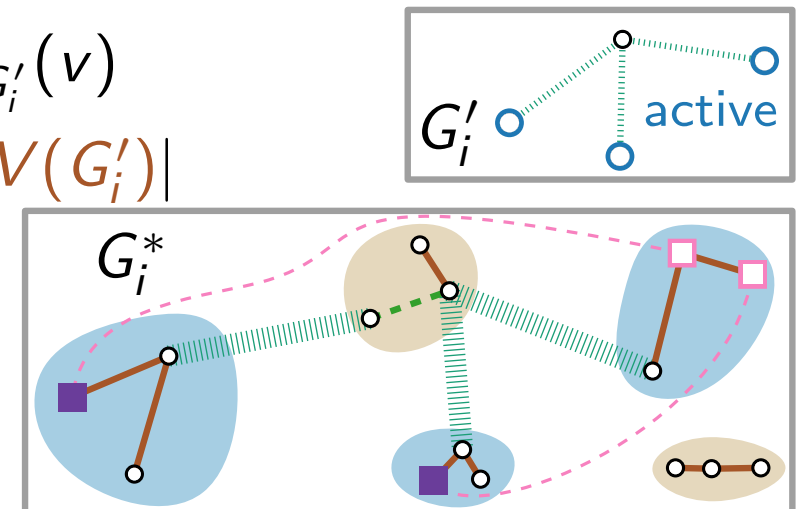
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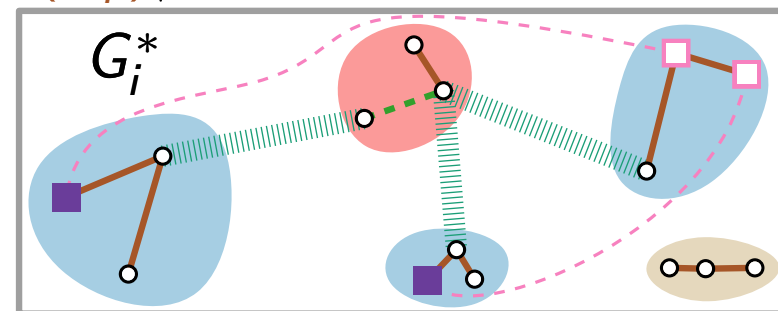
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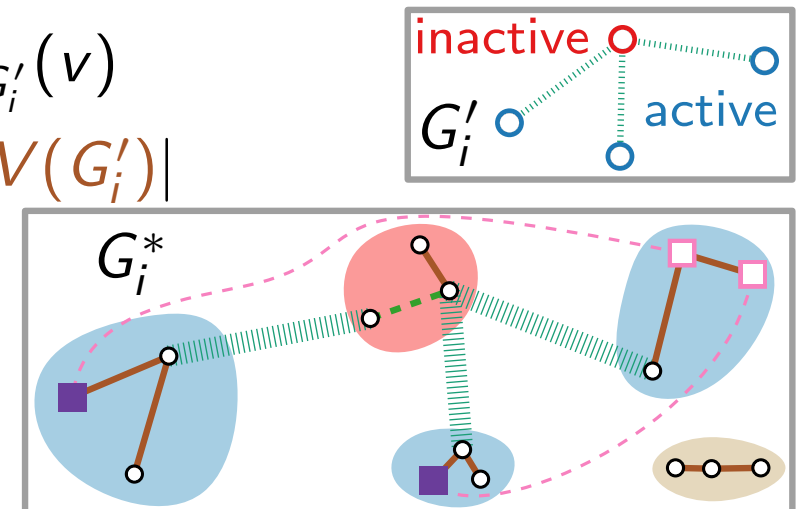
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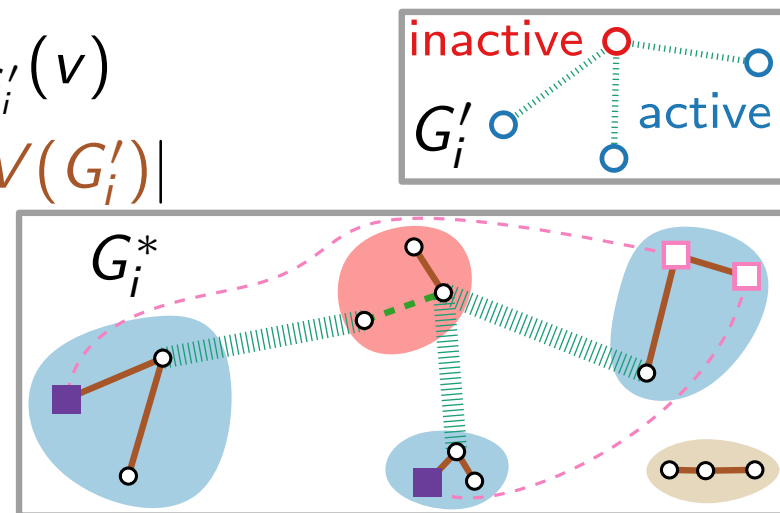
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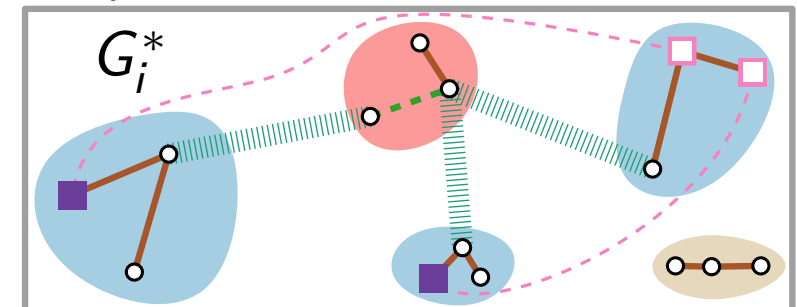
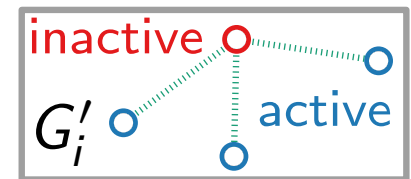
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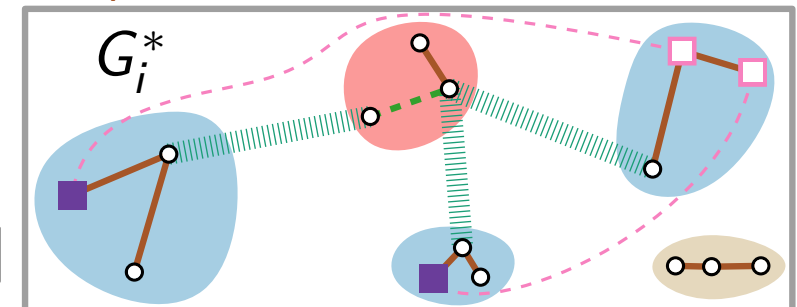
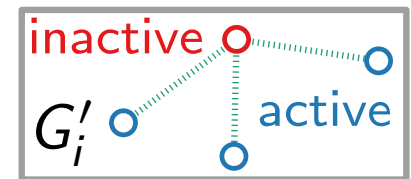
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# Approximation Algorithms

Lecture 12:

STEINERFOREST via Primal–Dual

Part VI:  
Analysis

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From that, the claim of the theorem follows.

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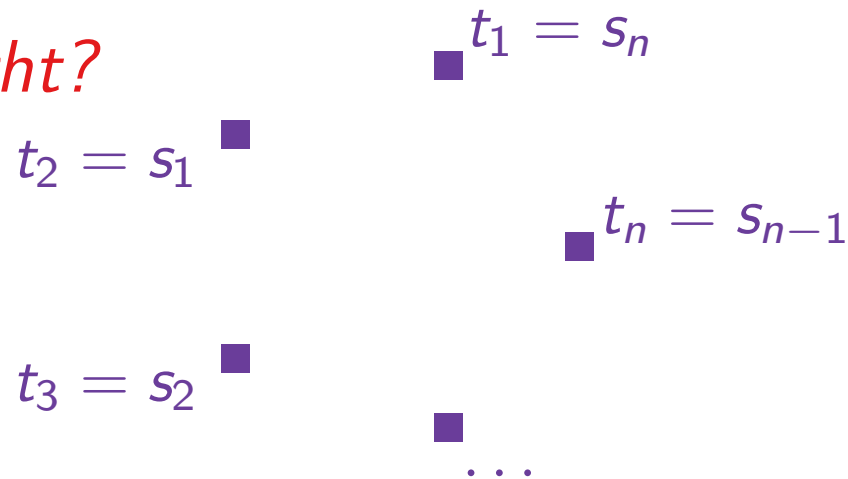
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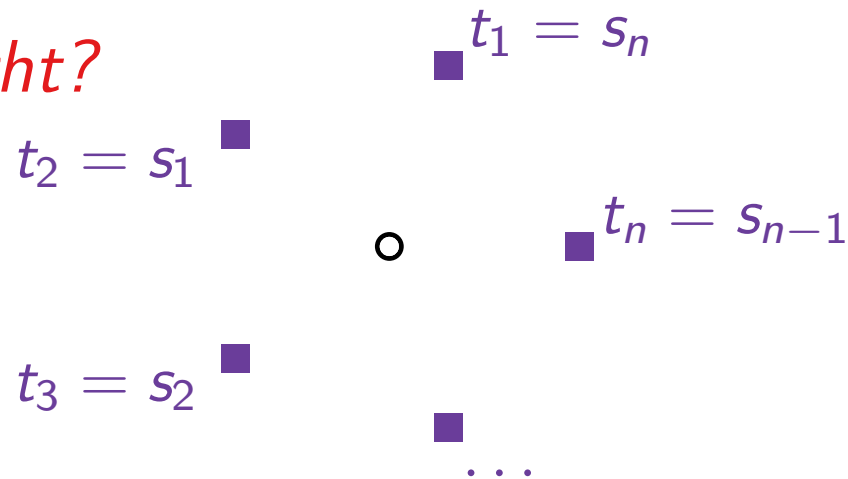




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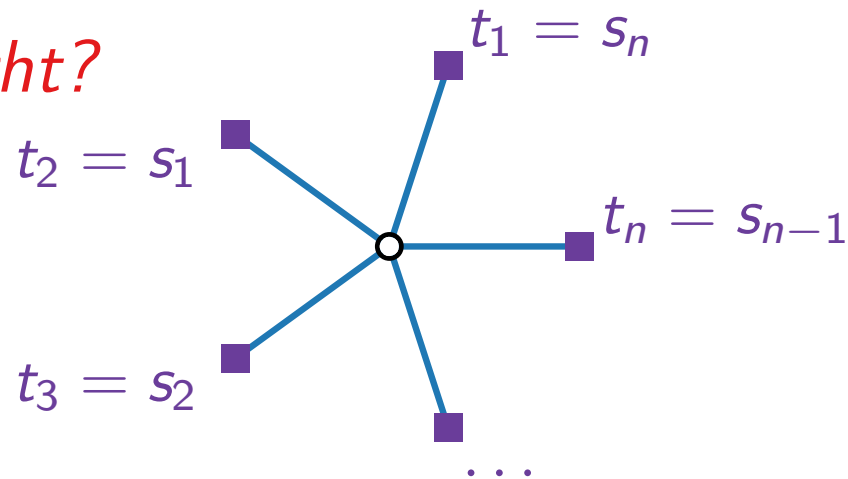
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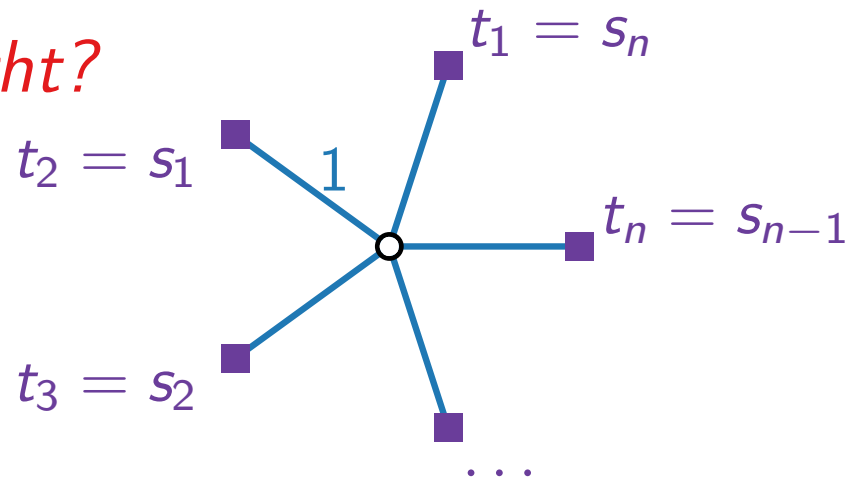
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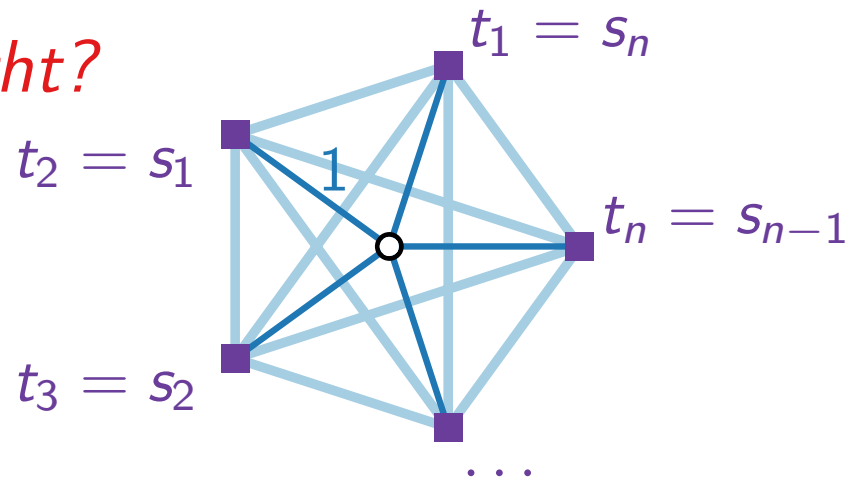
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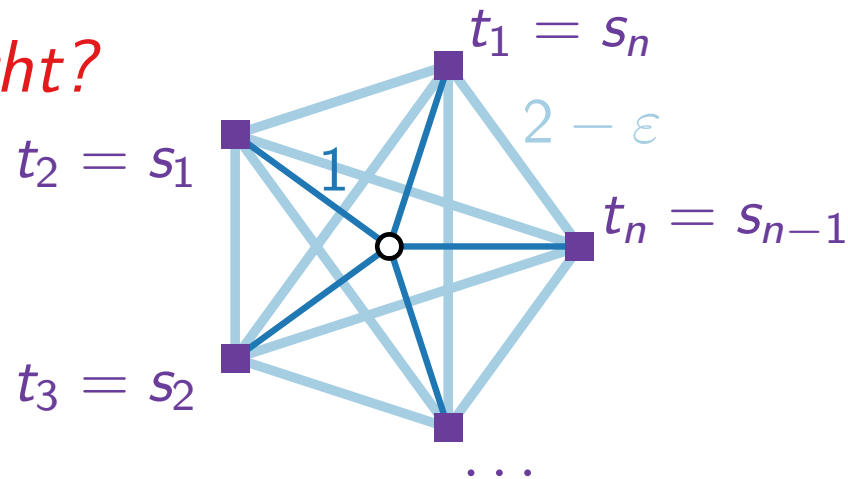
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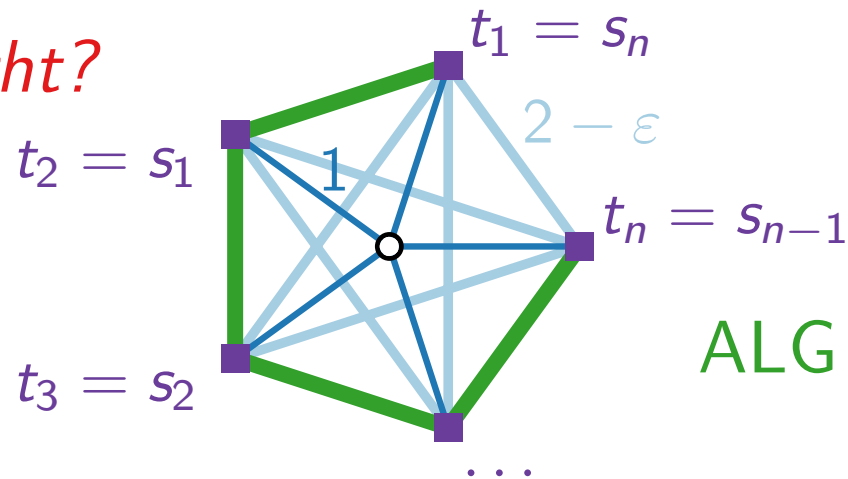
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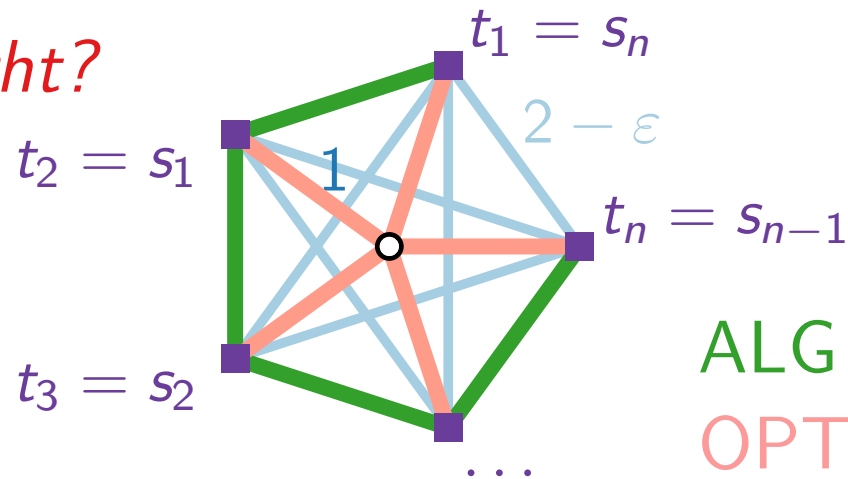
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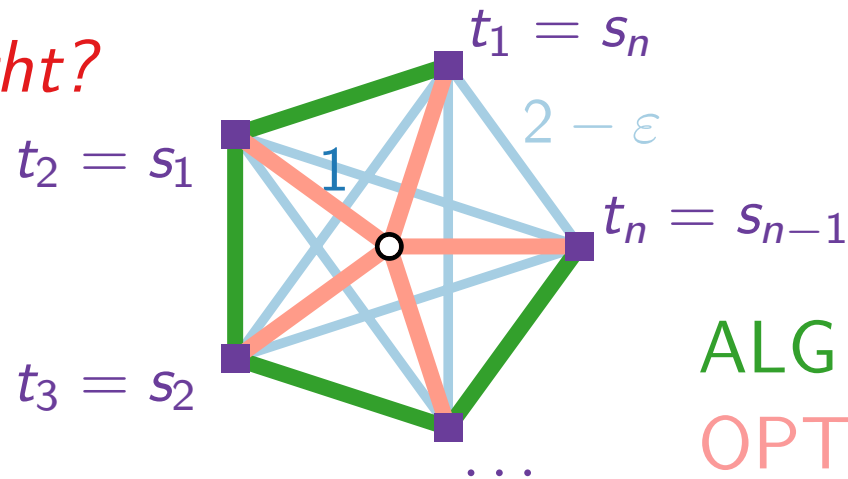
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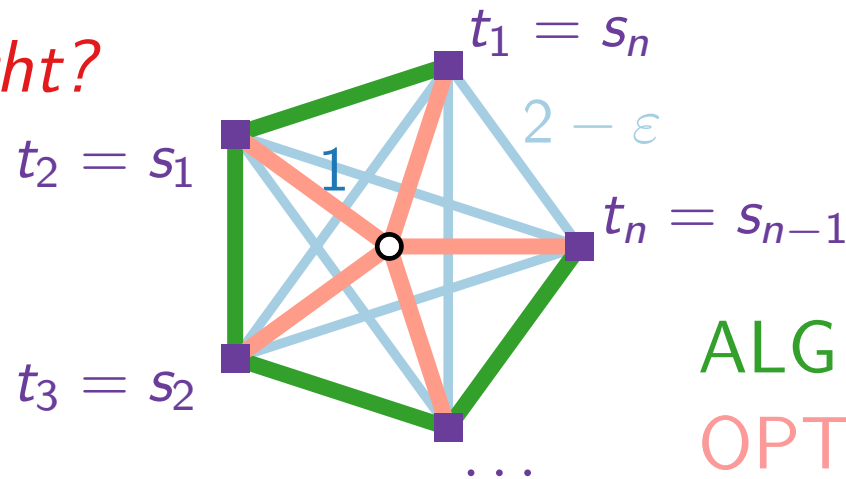
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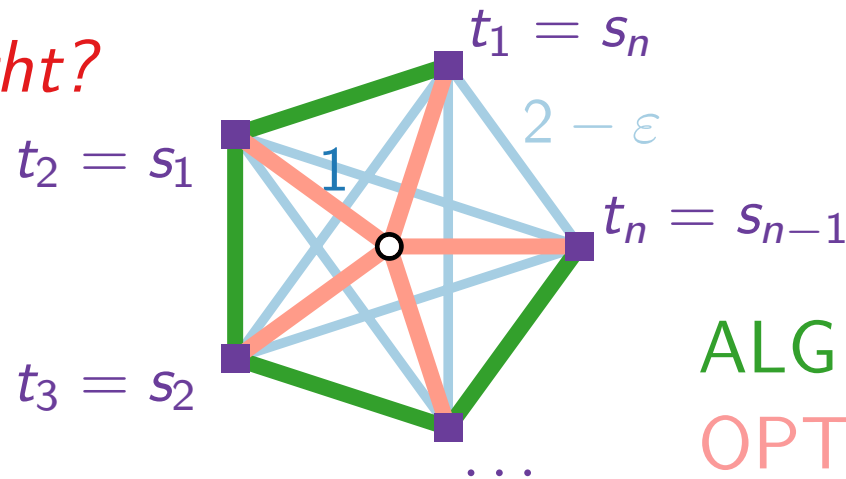
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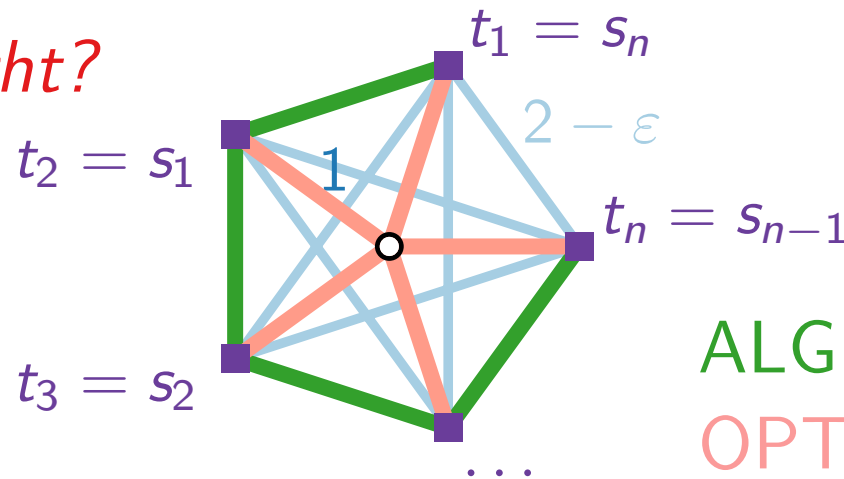
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