

Approximation Algorithms

Lecture 9: An Approximation Scheme for EUCLIDEAN TSP

Part I: The TRAVELING SALESMAN PROBLEM

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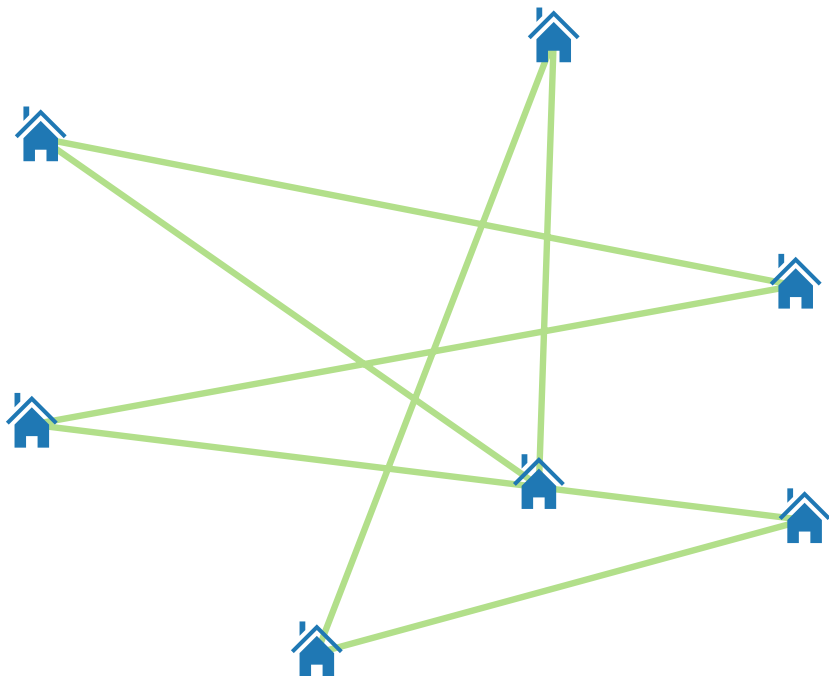


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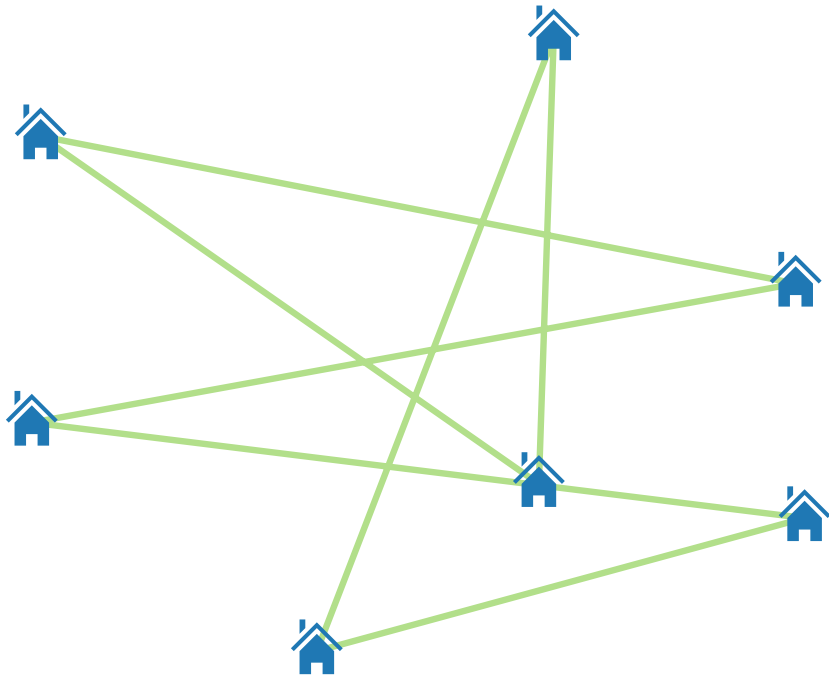


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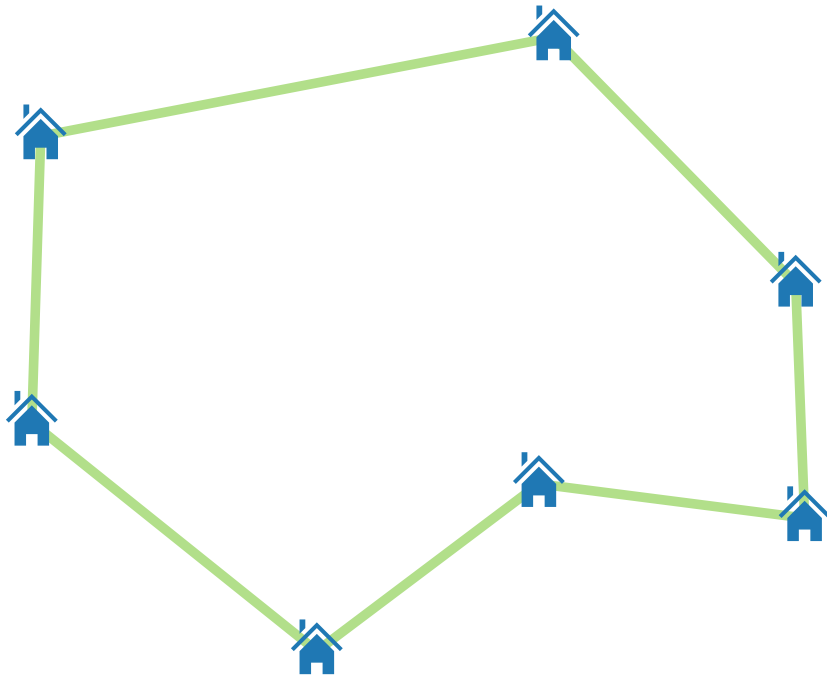


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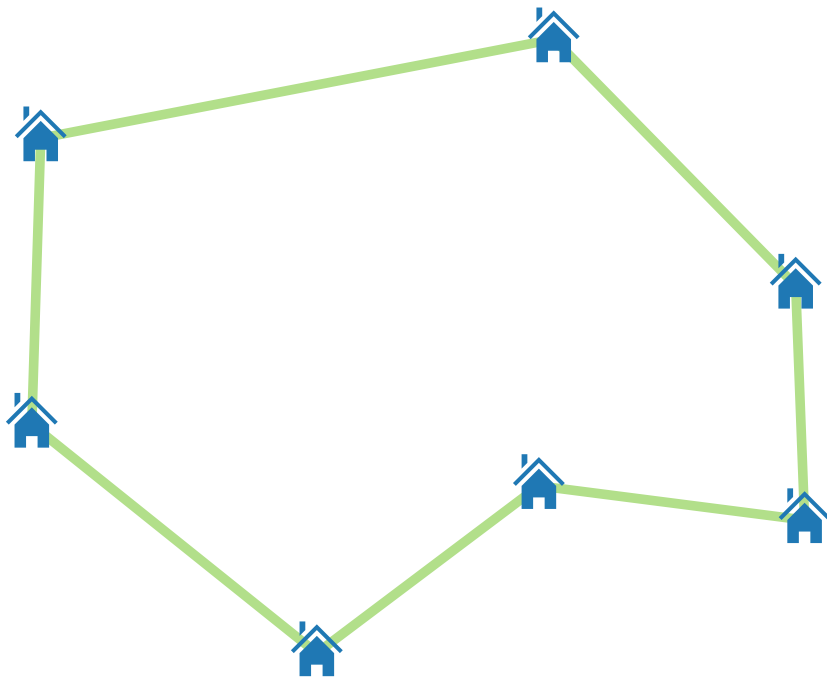


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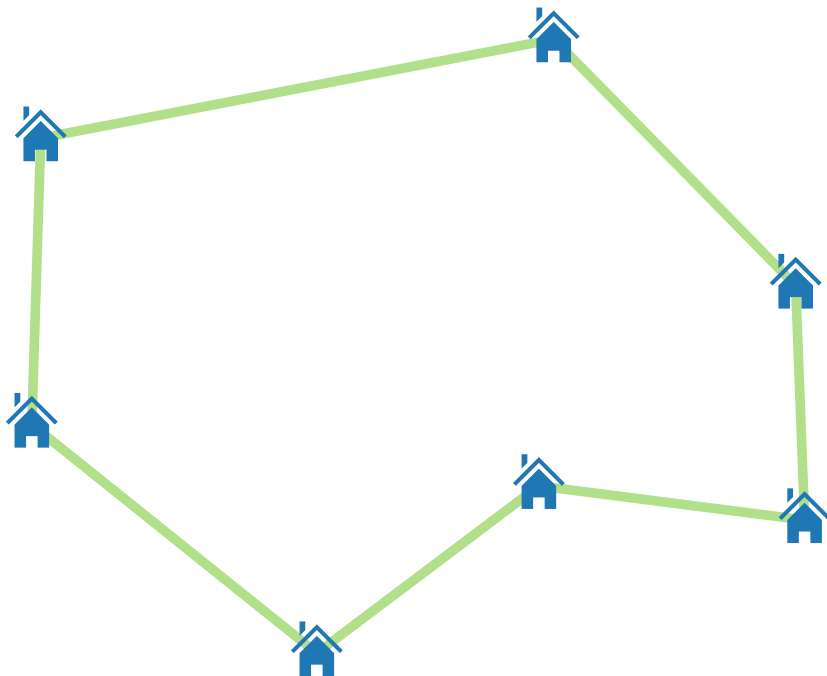
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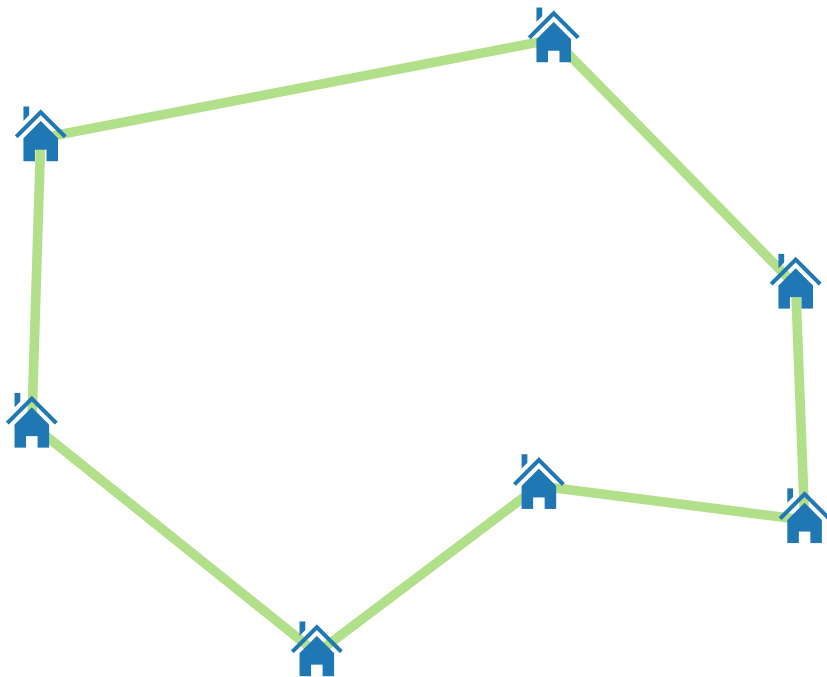
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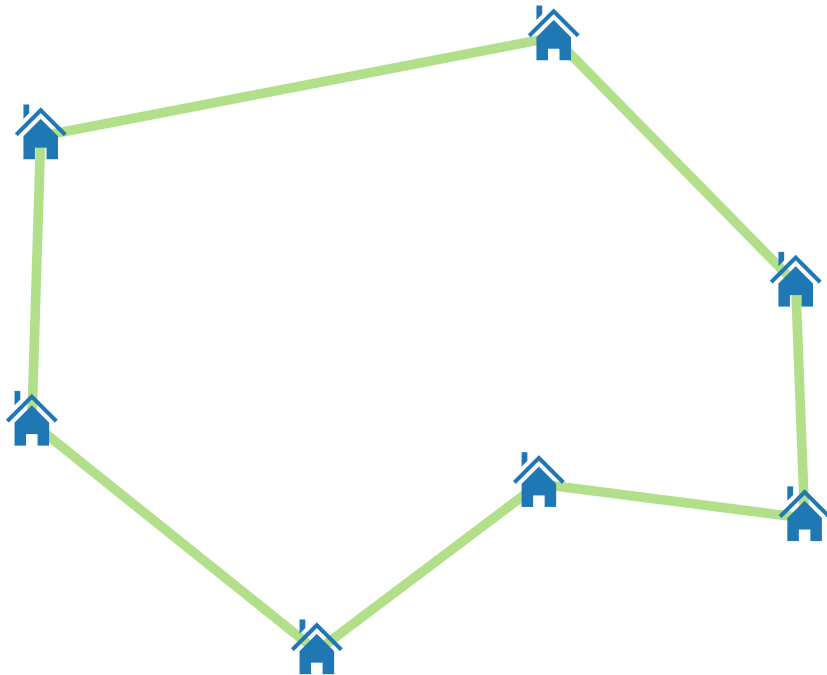
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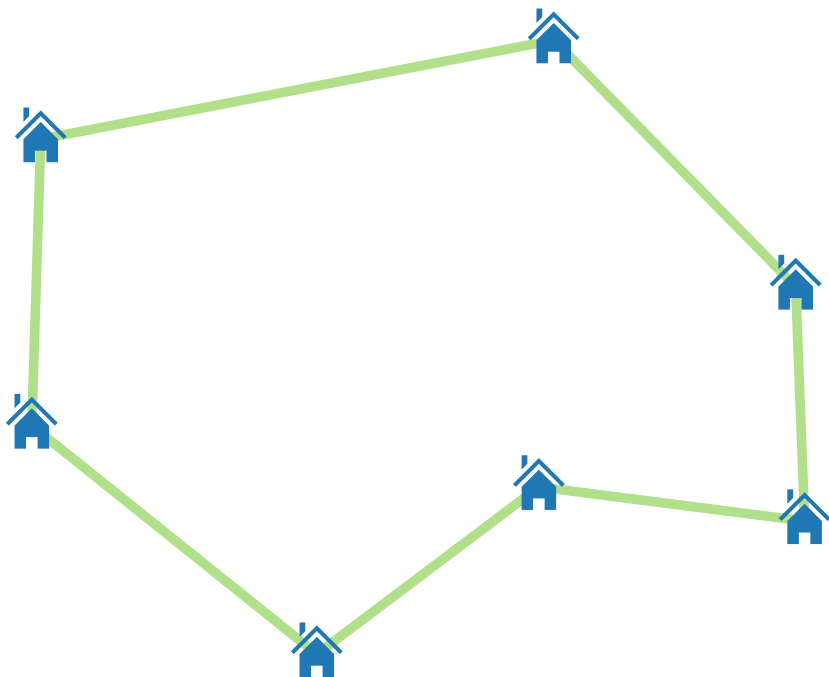
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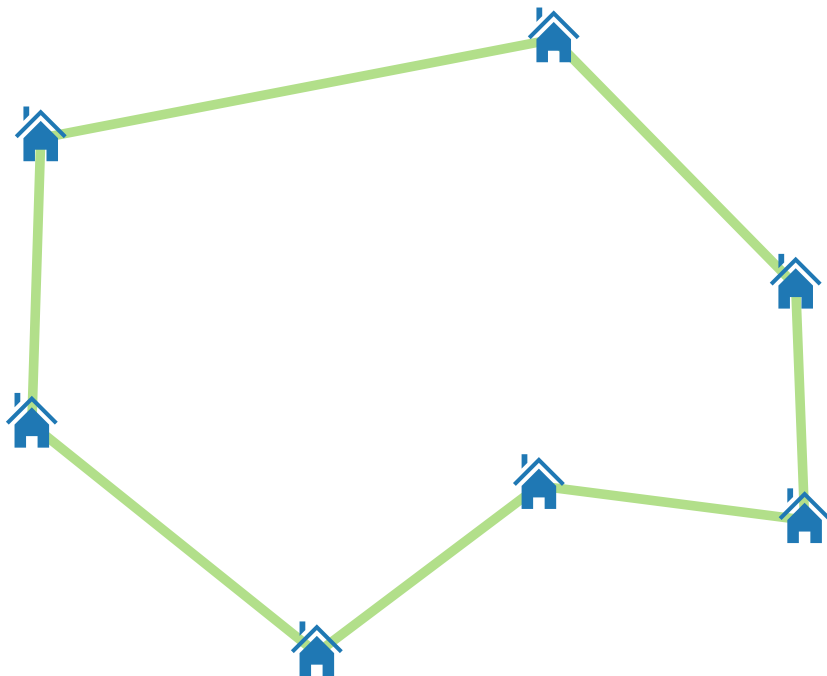
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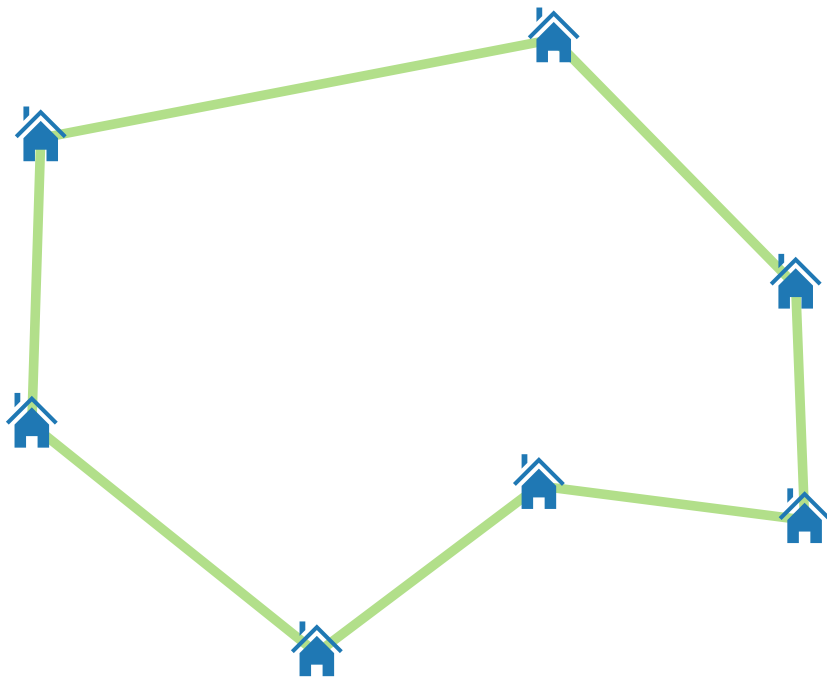
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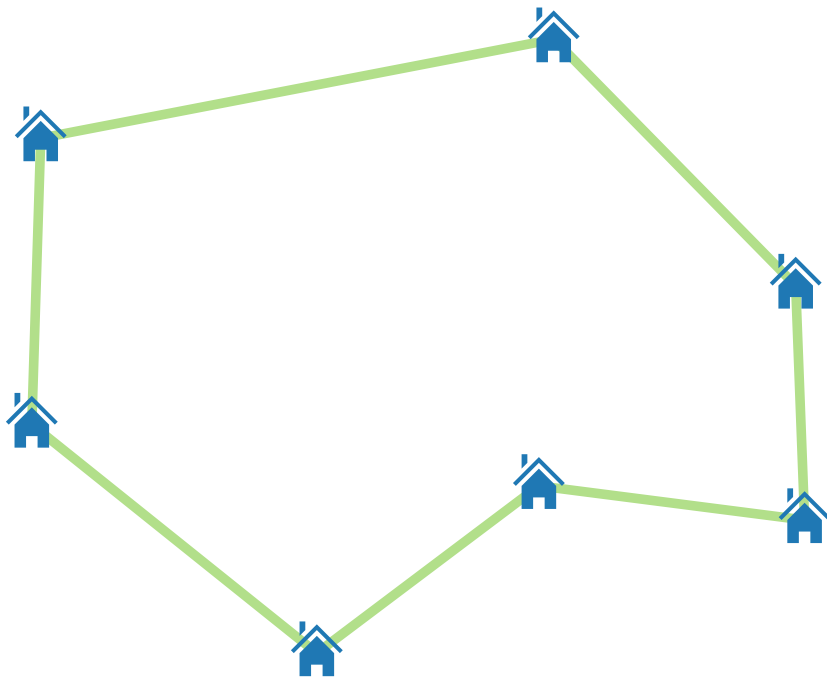
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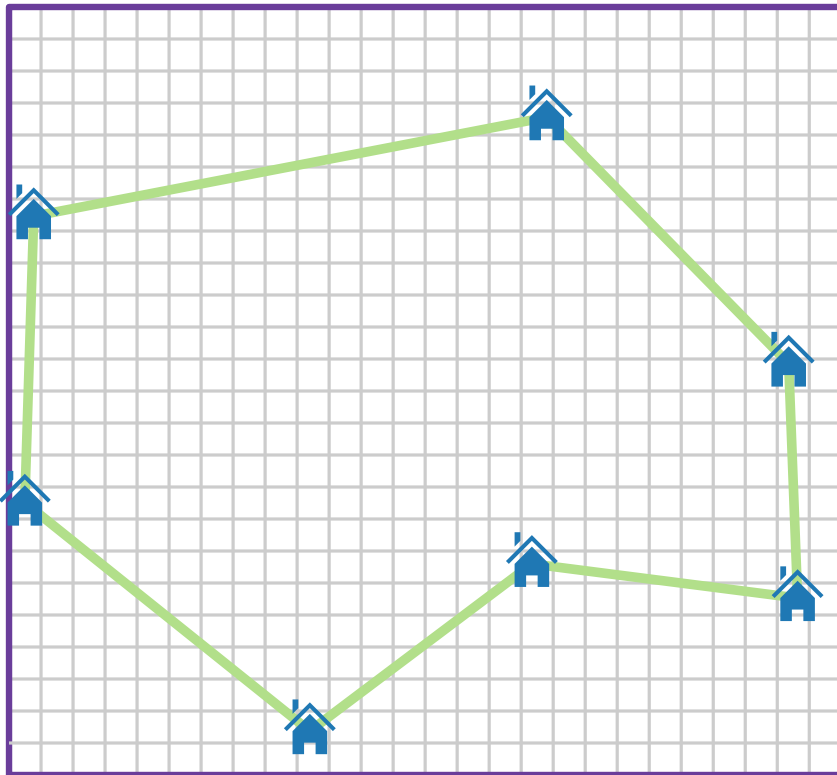
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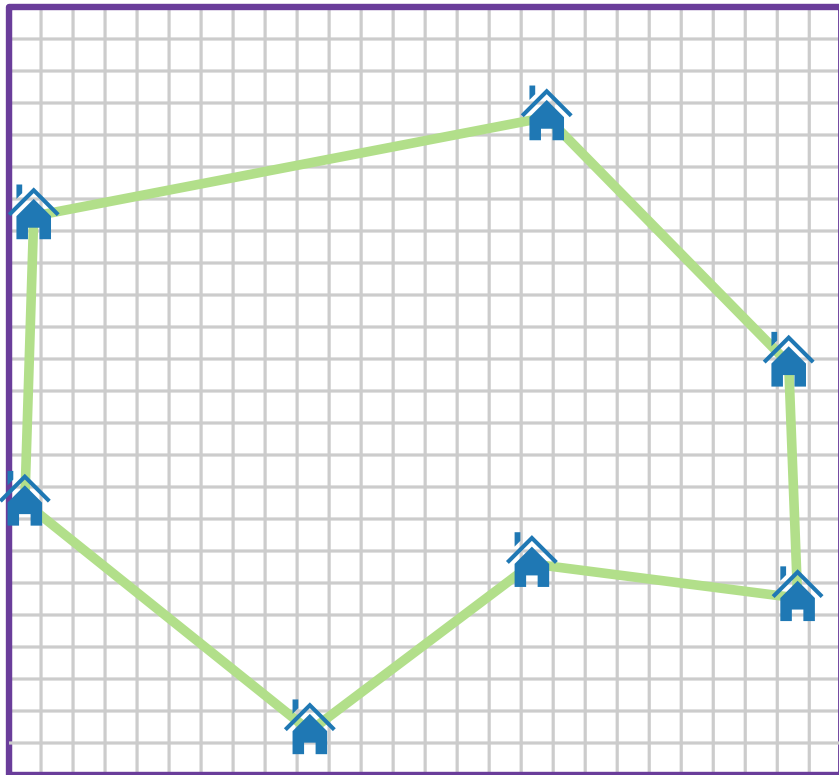
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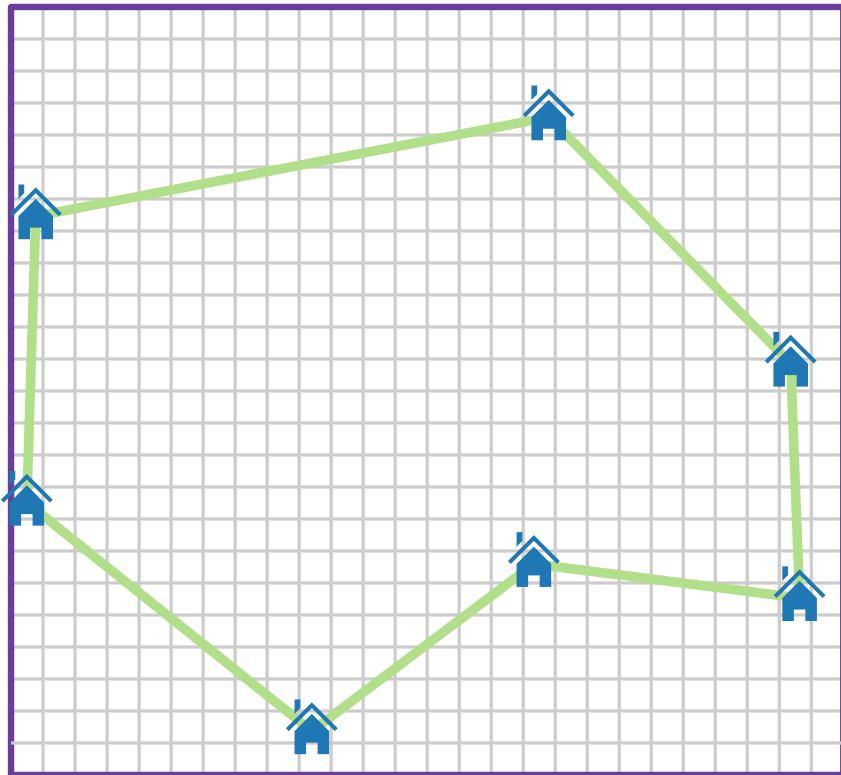
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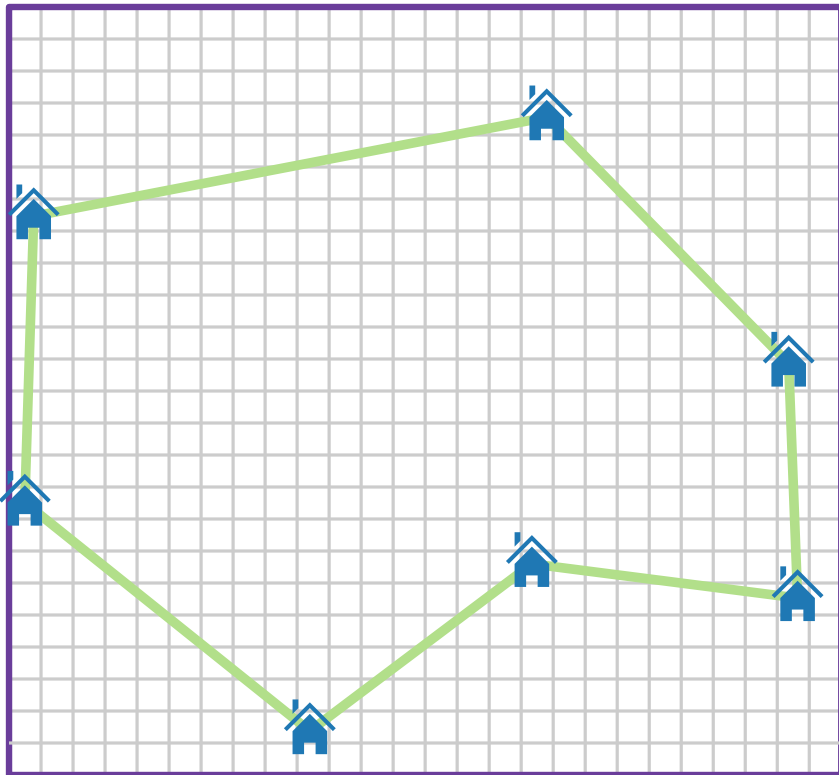
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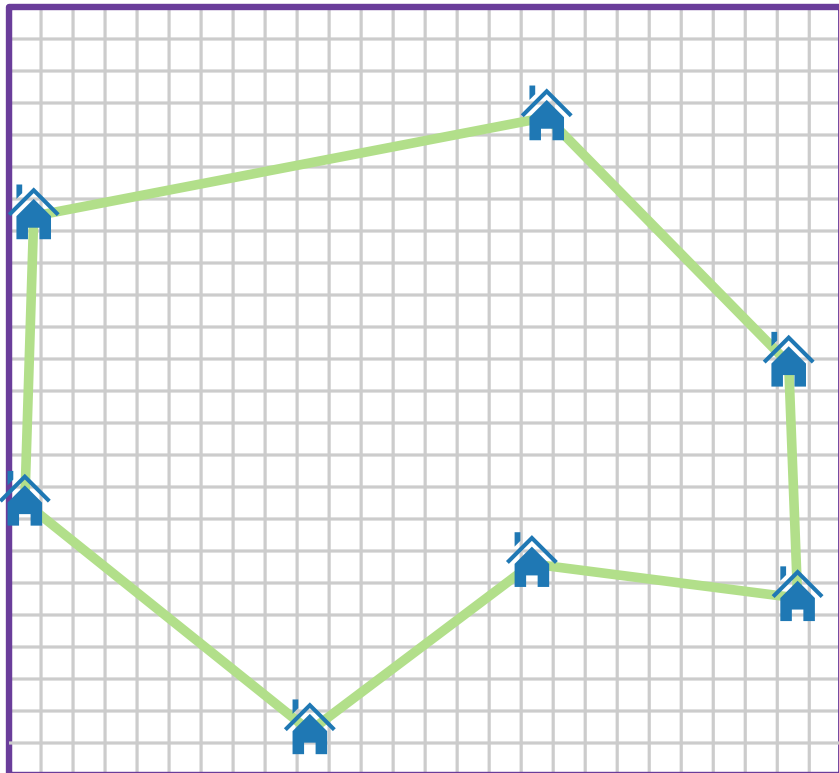
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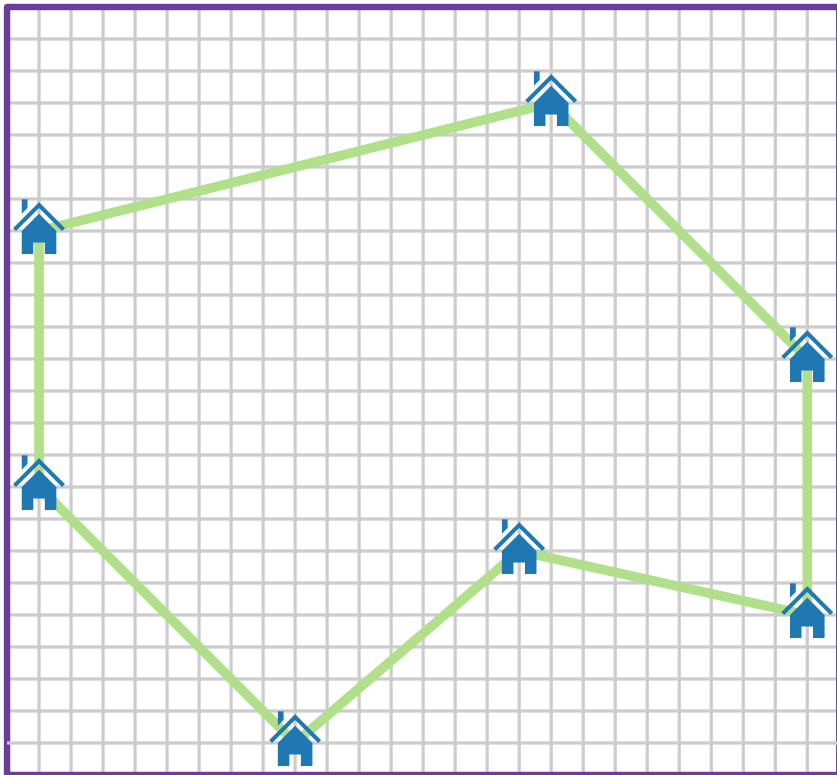
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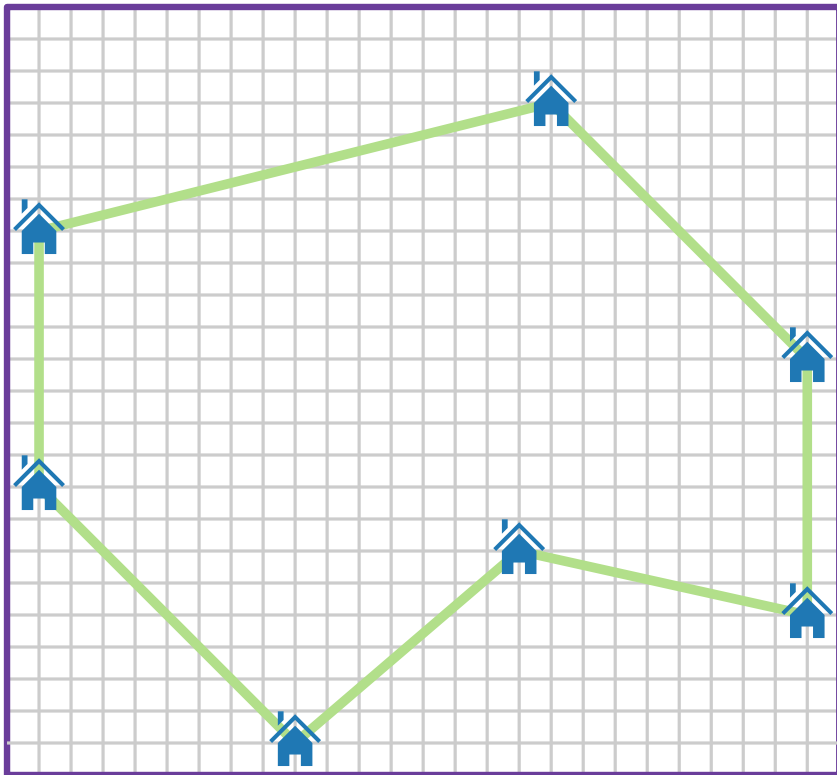
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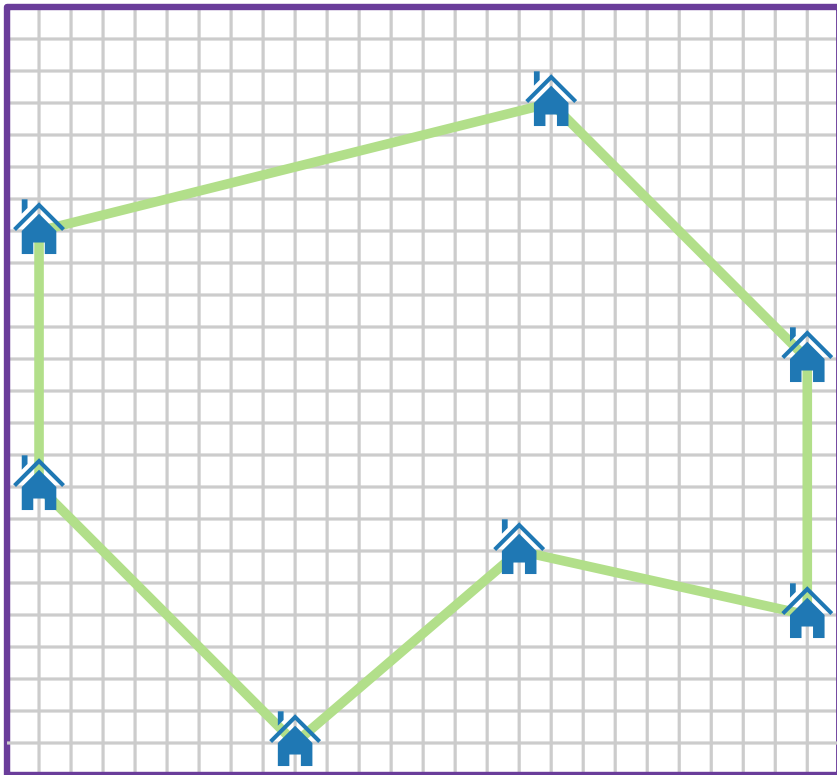
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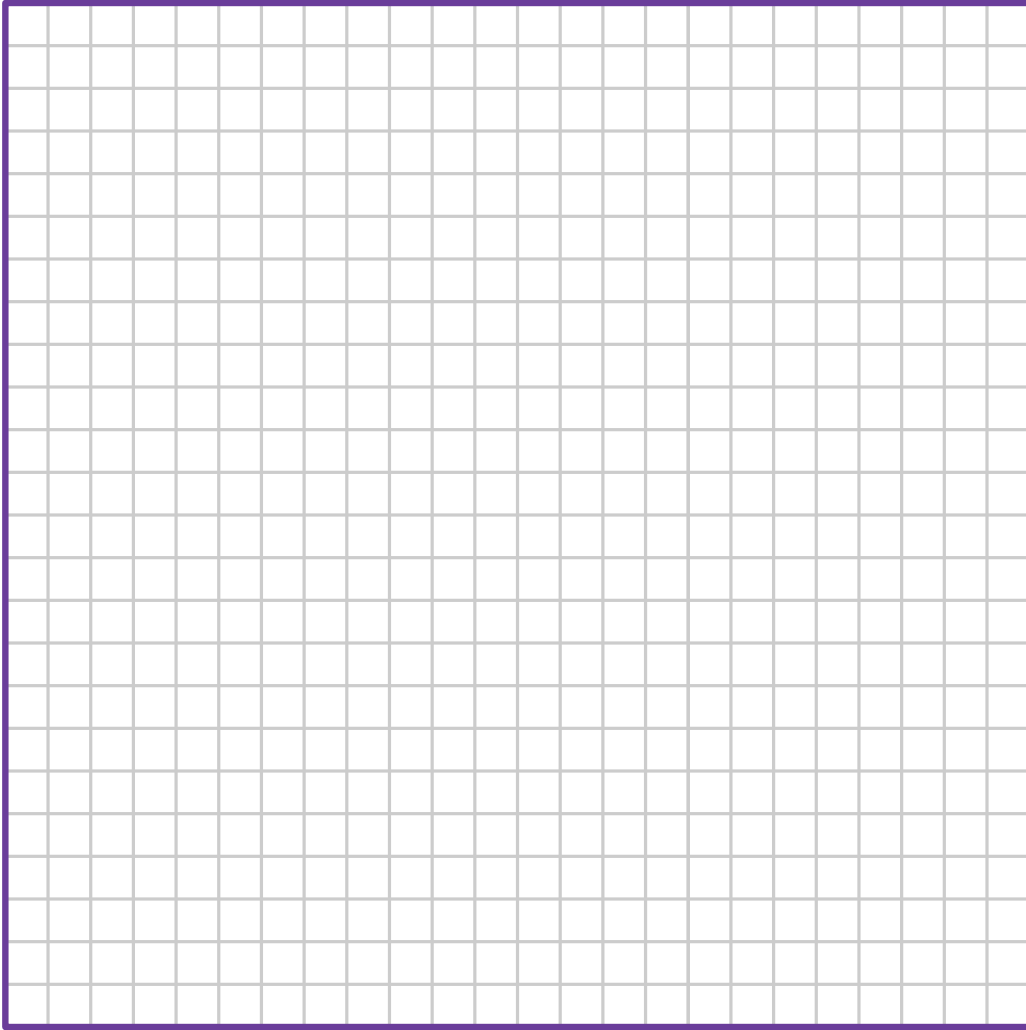
Goal:
 $(1 + \varepsilon)$ -
approximation!

Approximation Algorithms

Lecture 9: A PTAS for EUCLIDEAN TSP

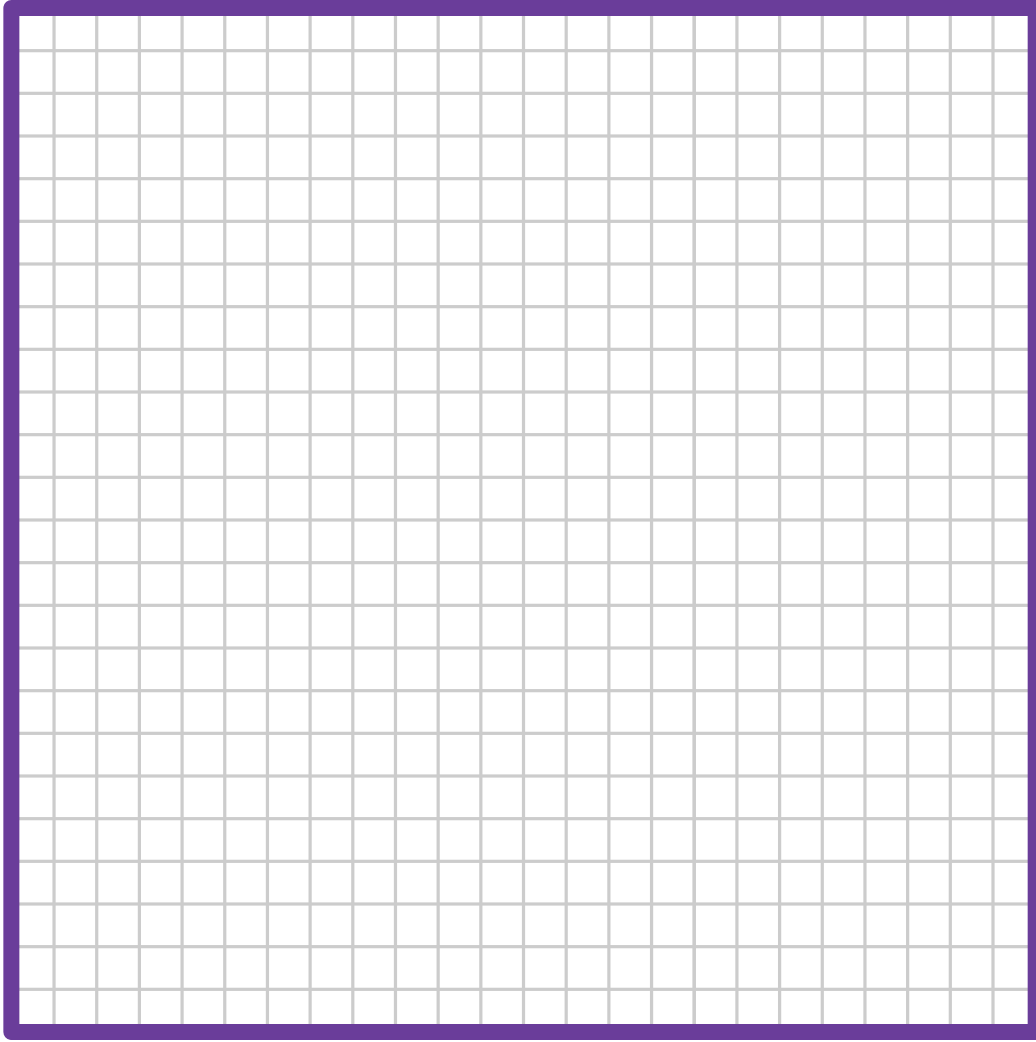
Part II: Dissection

Basic Dissection



$$L = 2^k$$

Basic Dissection

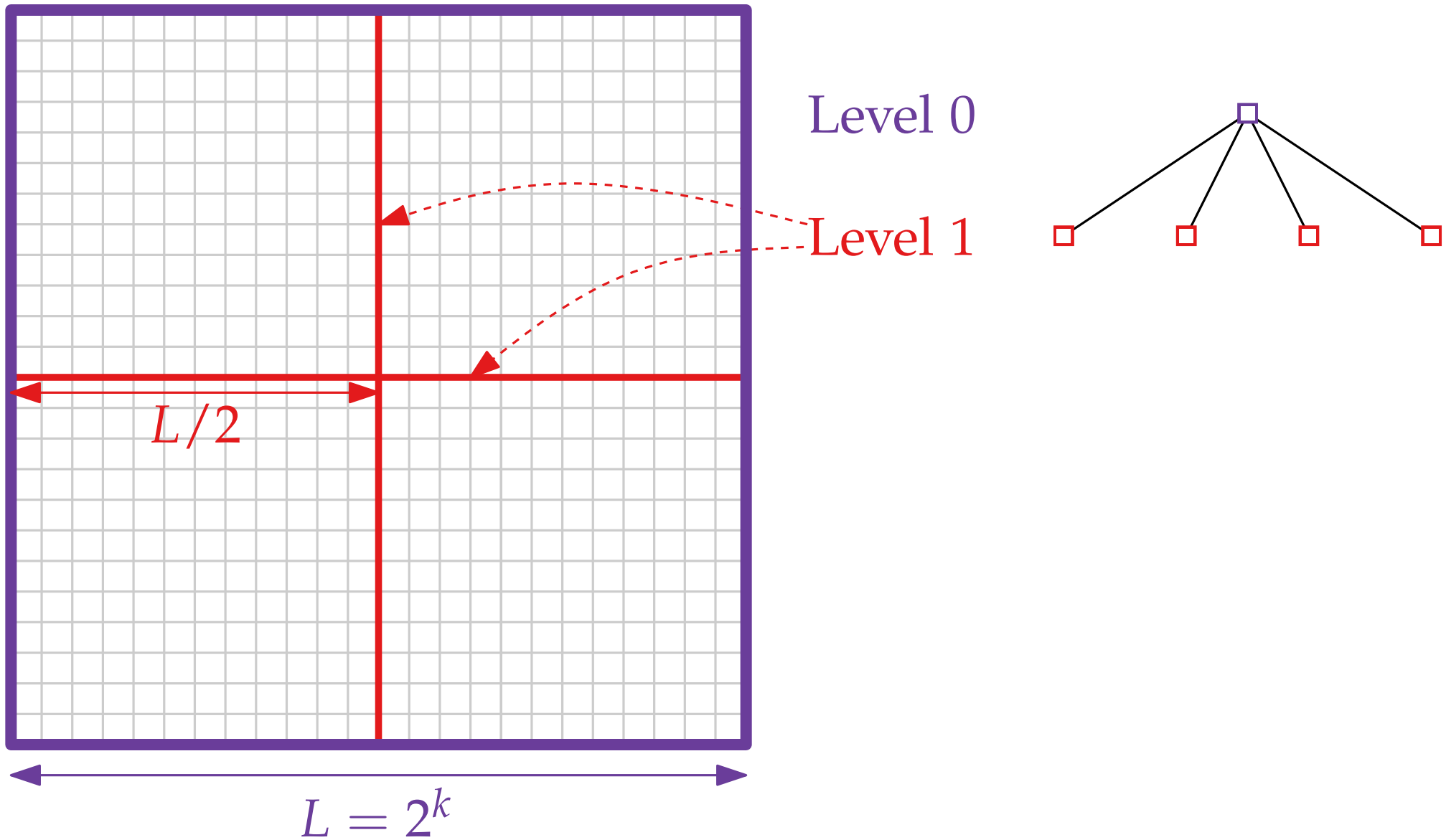


Level 0

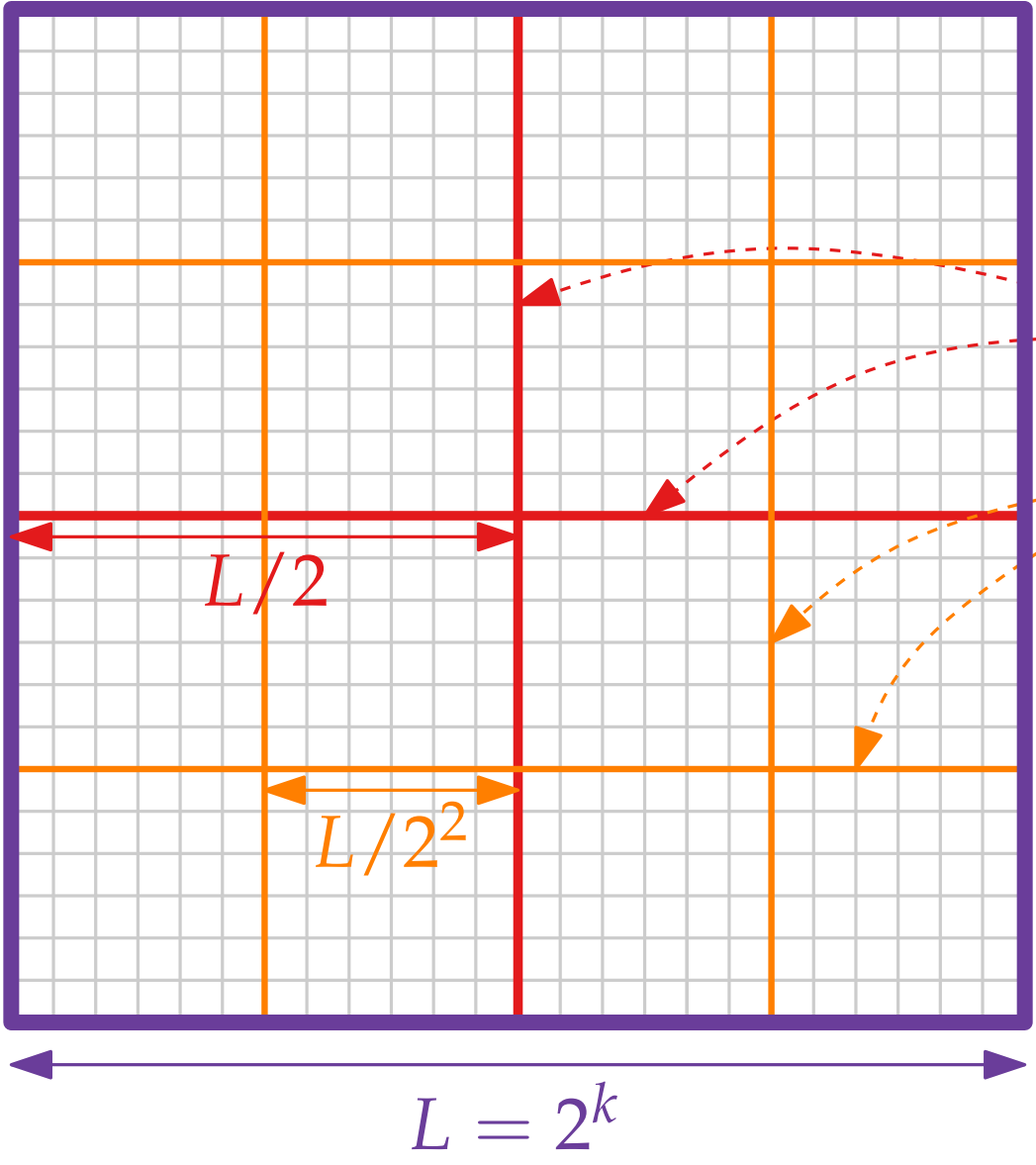


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Basic Dissection



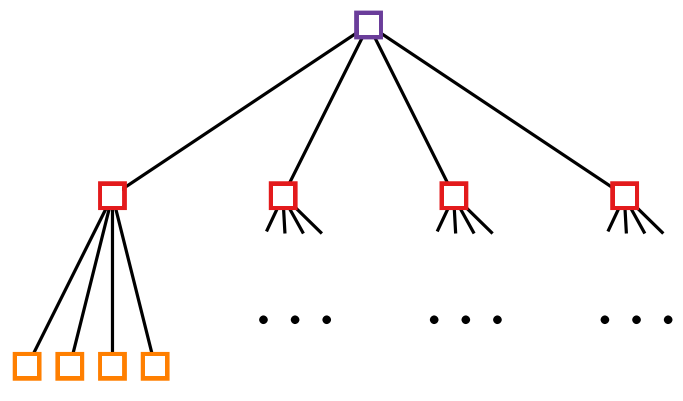
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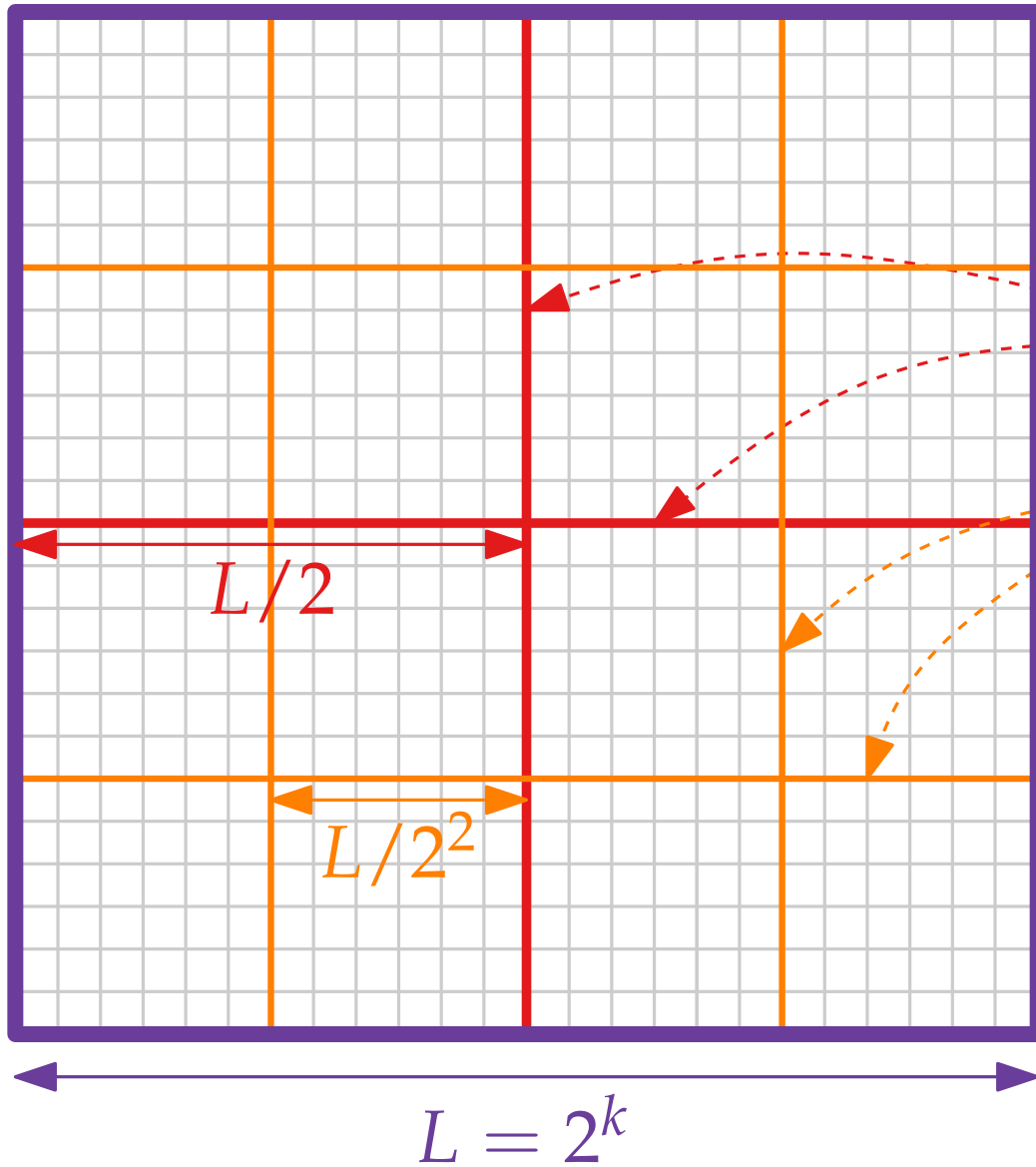
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Level 1

Level 2



Basic Dissection



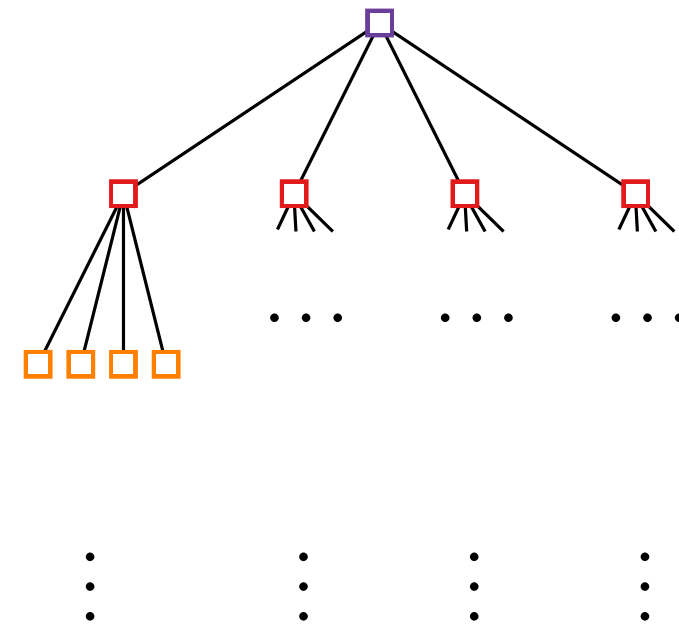
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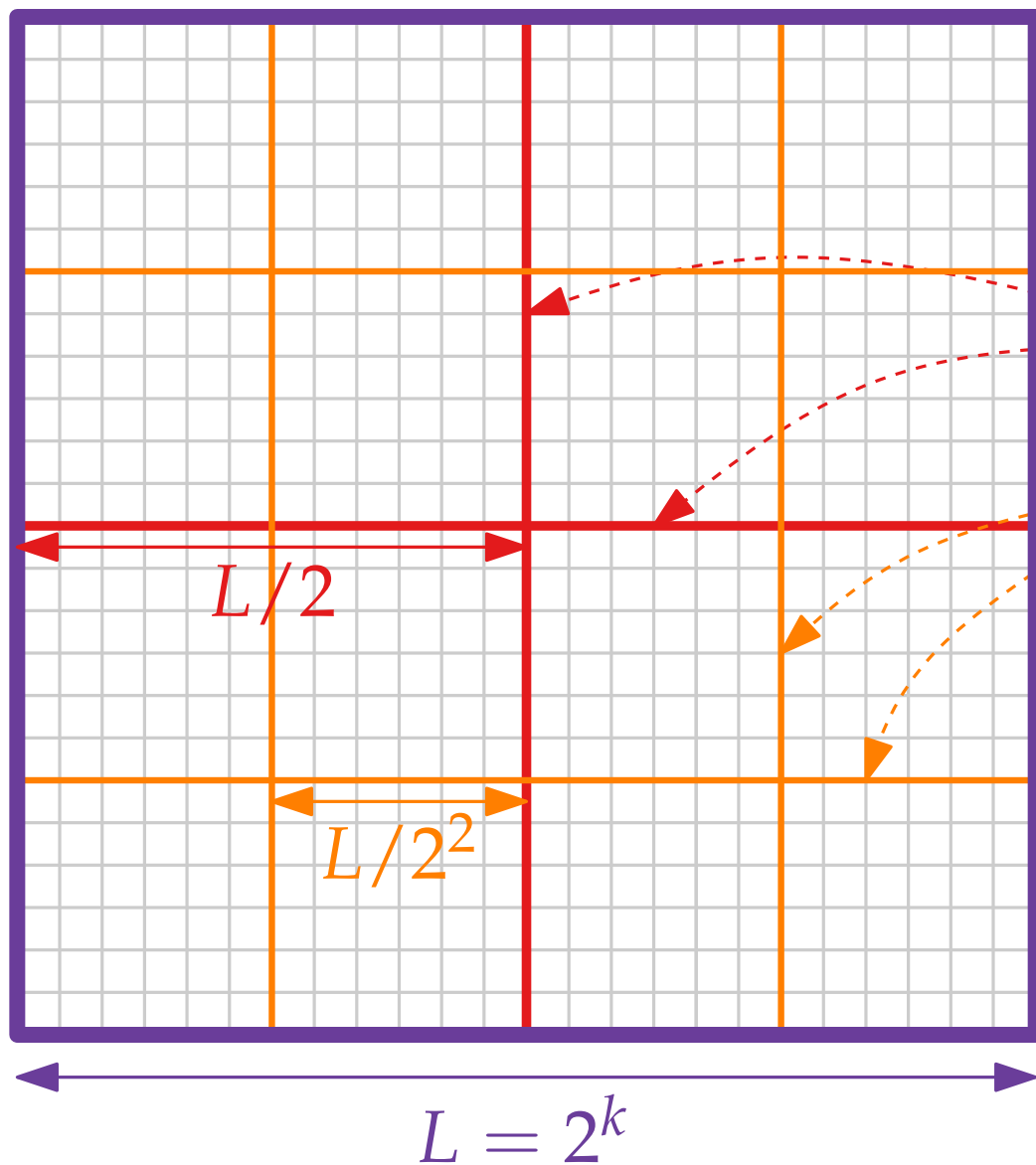
Level 2

Level k

(squares of size)



Basic Dissection



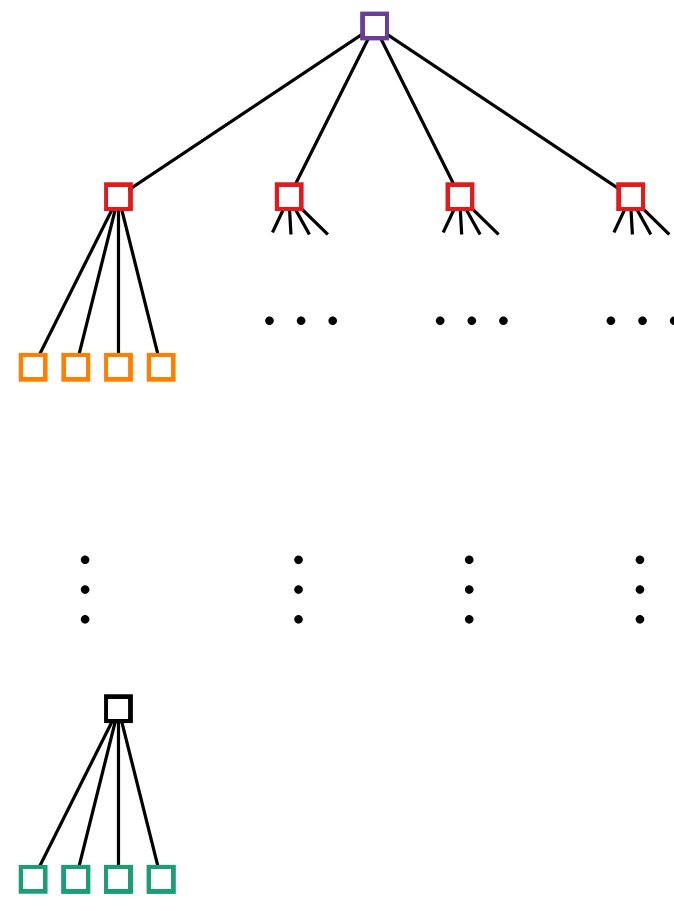
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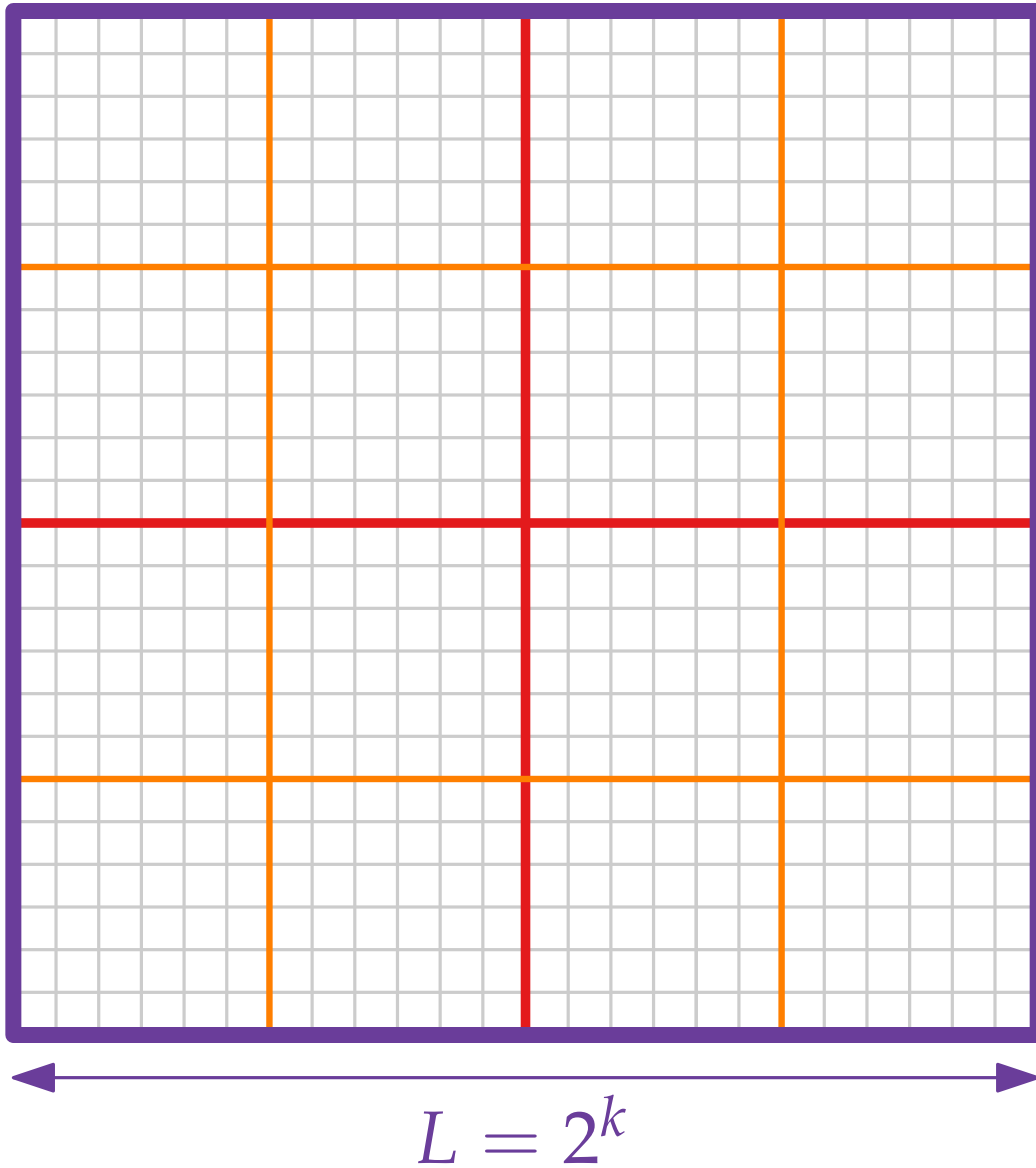
Level 2

Level k

(squares of size 1×1)

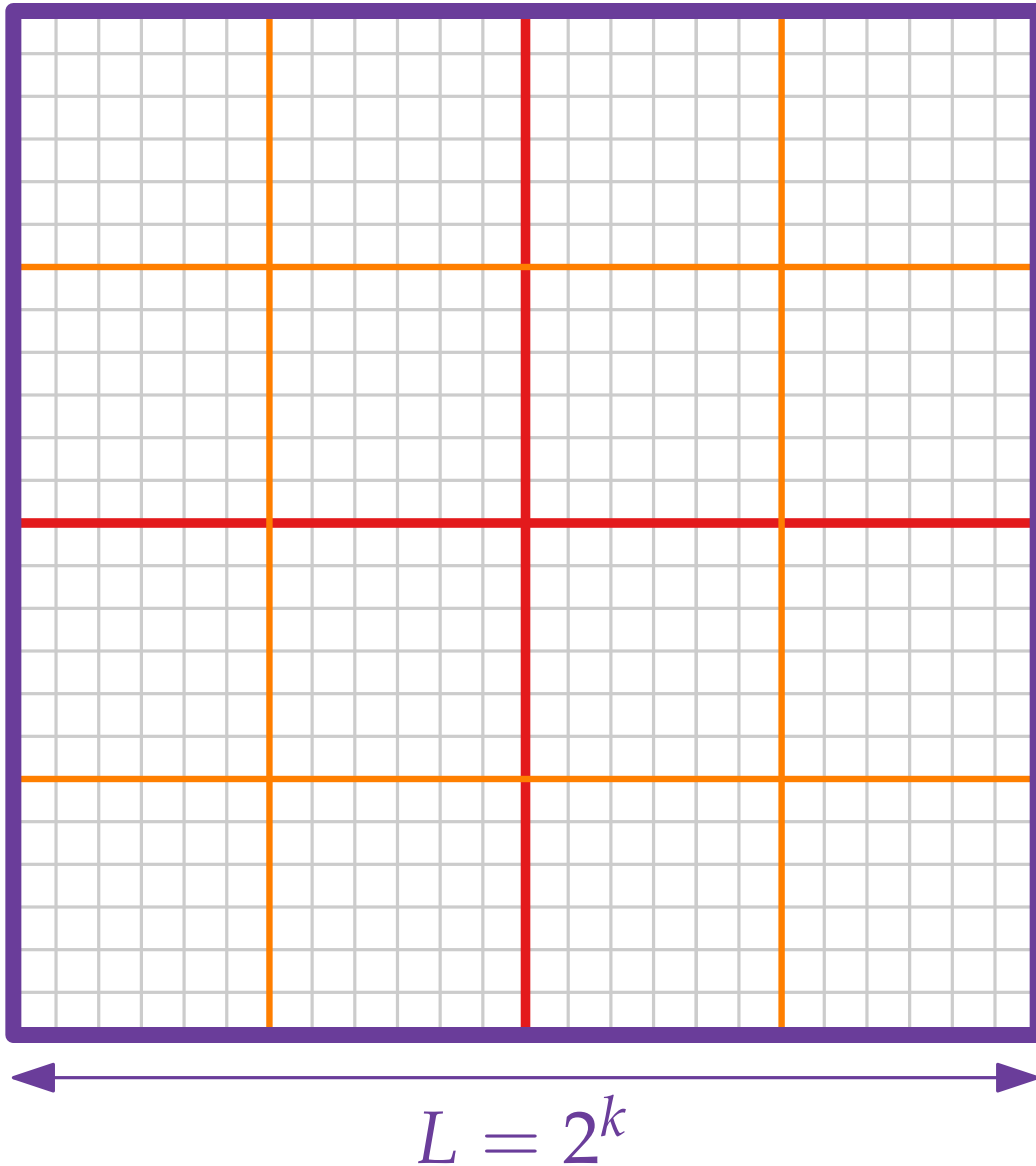


Portals



- Let m be a power of 2 in the interval $[k/\varepsilon, 2k/\varepsilon]$.

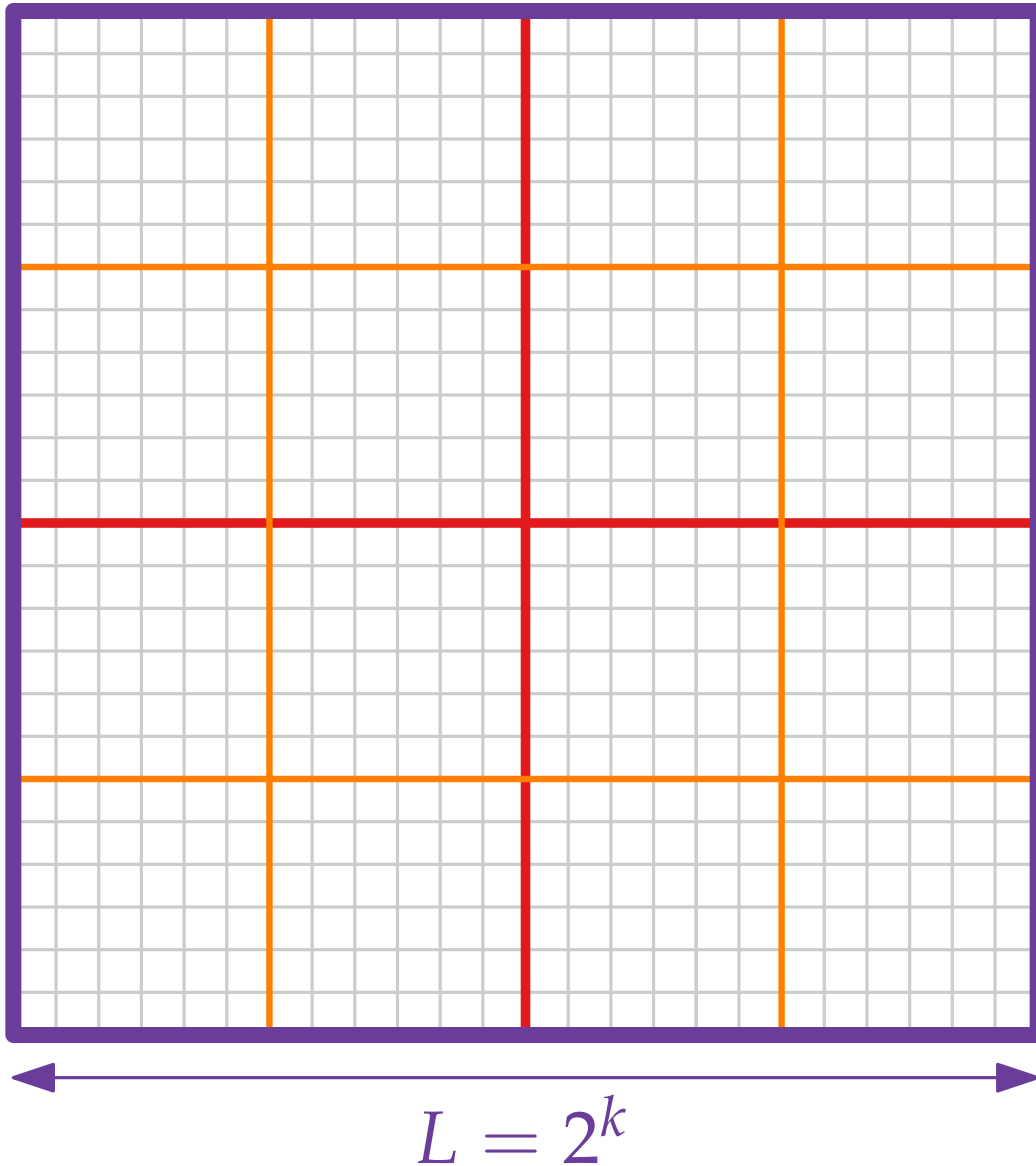
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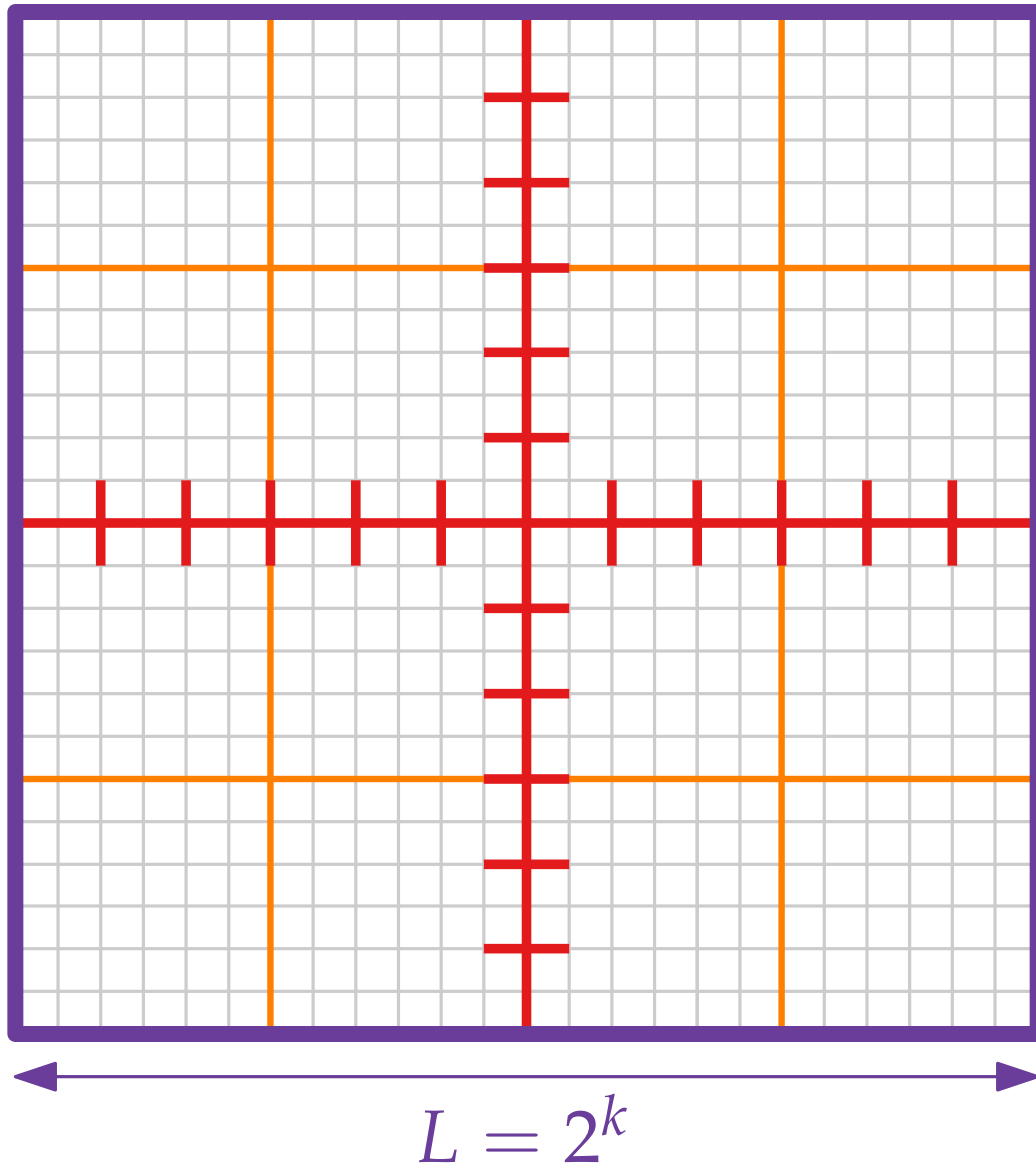
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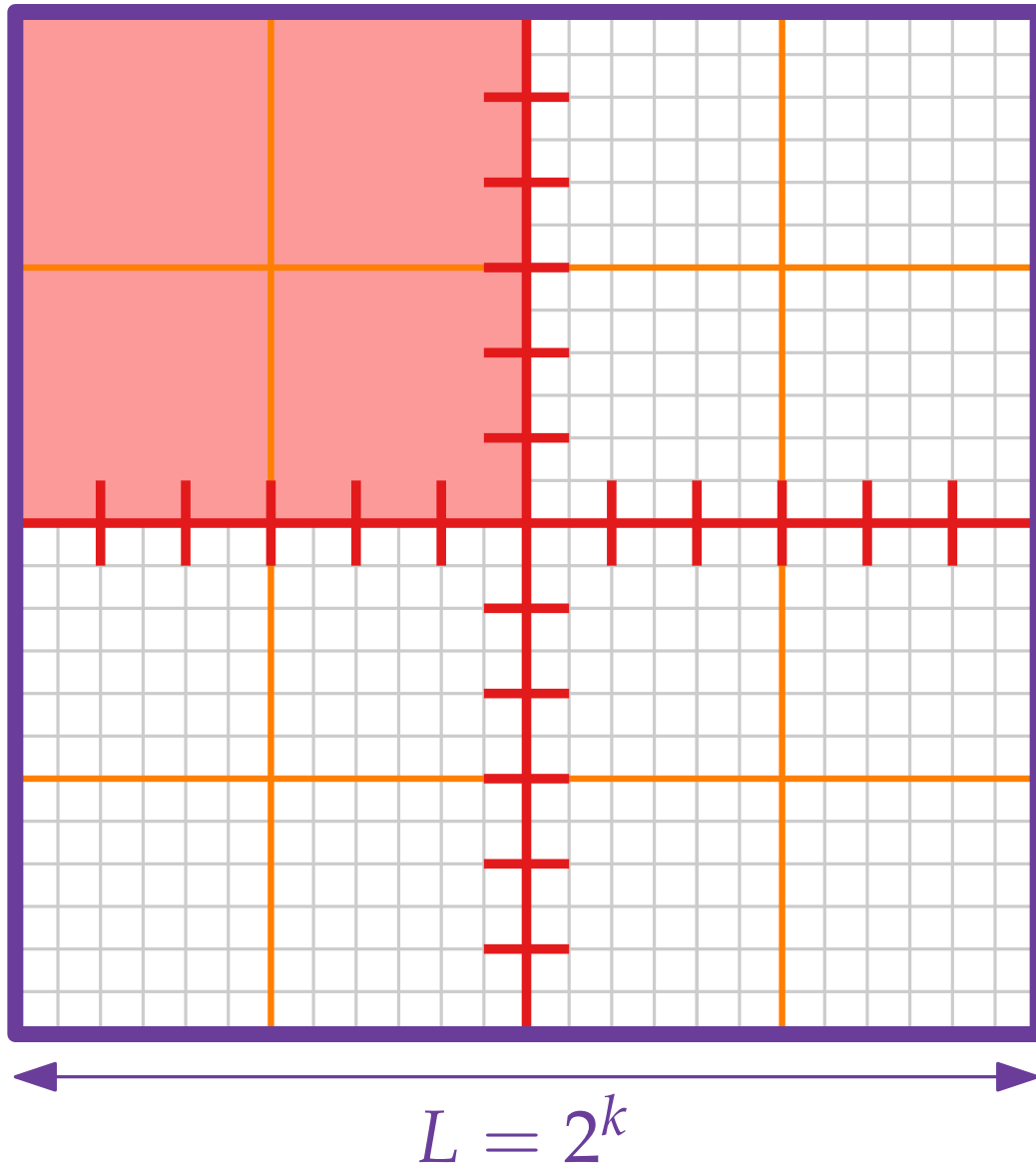


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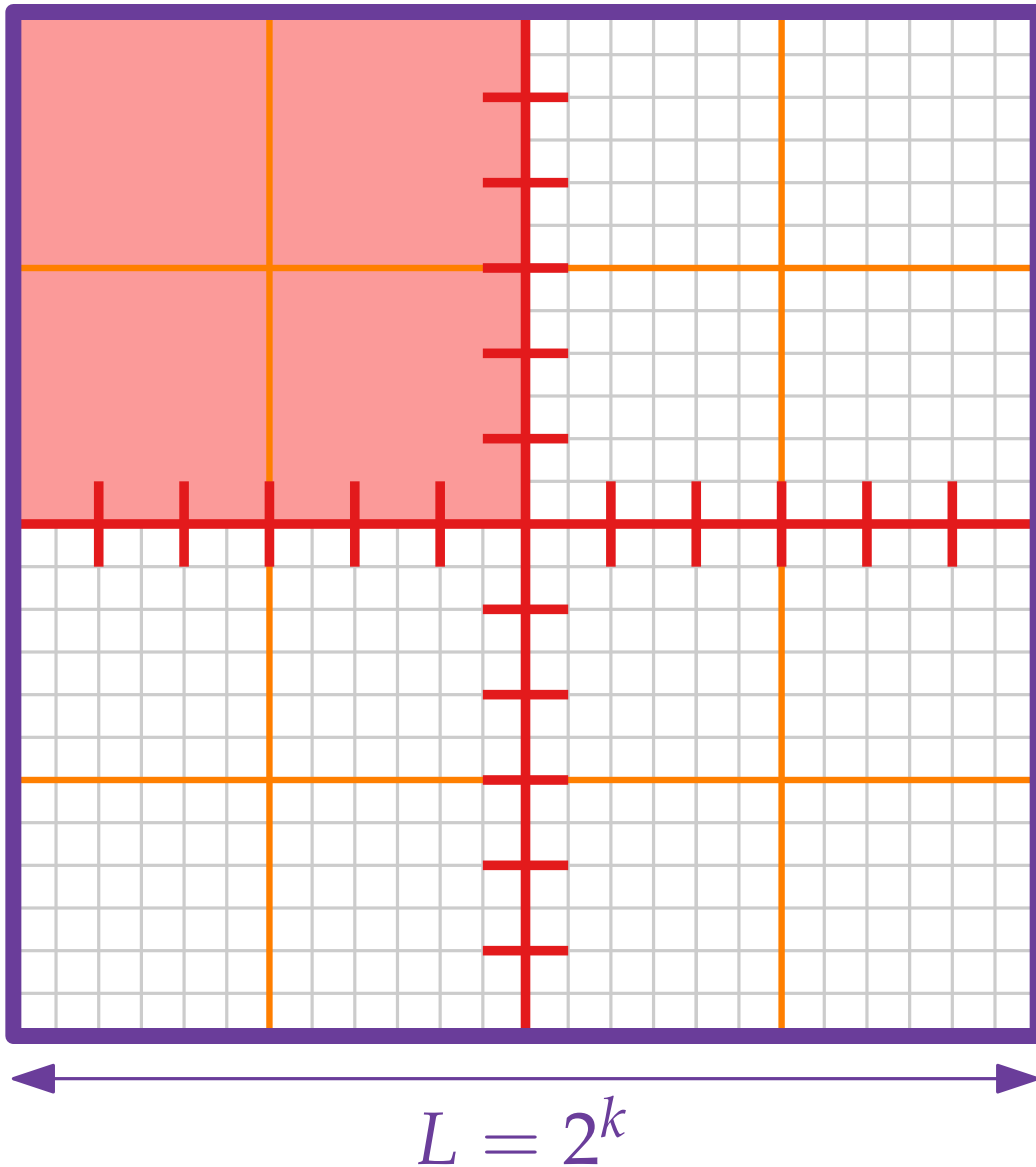


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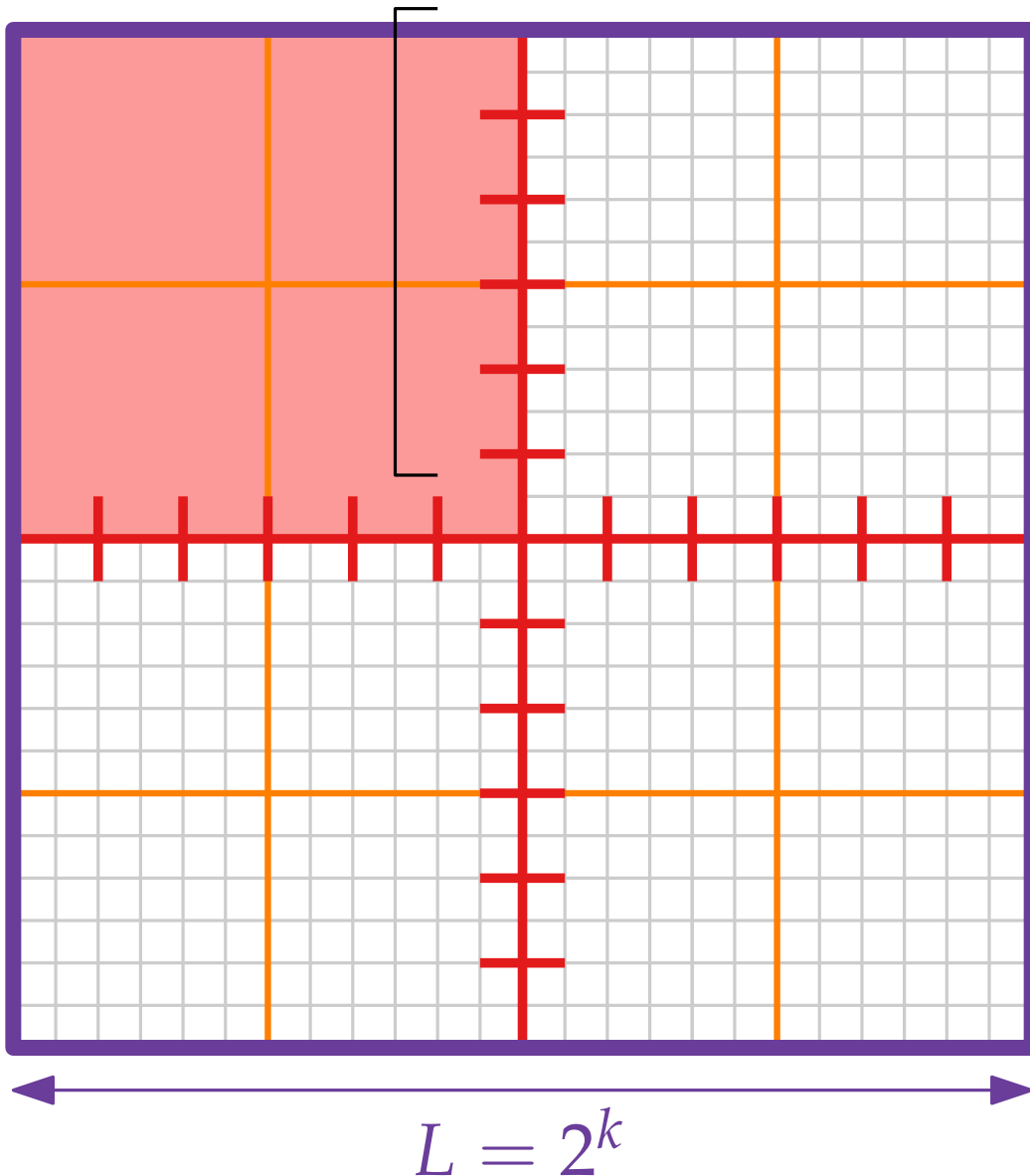


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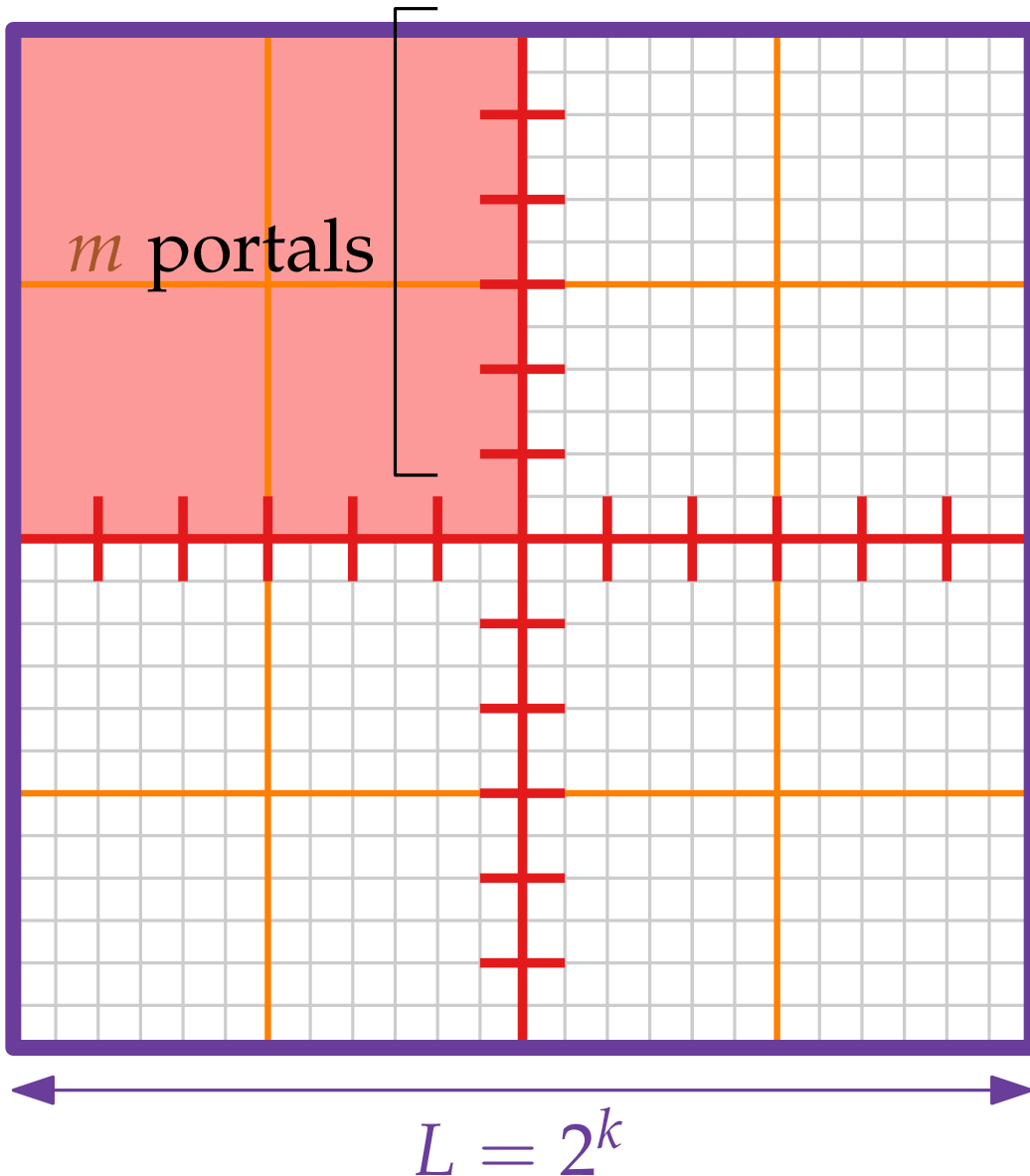


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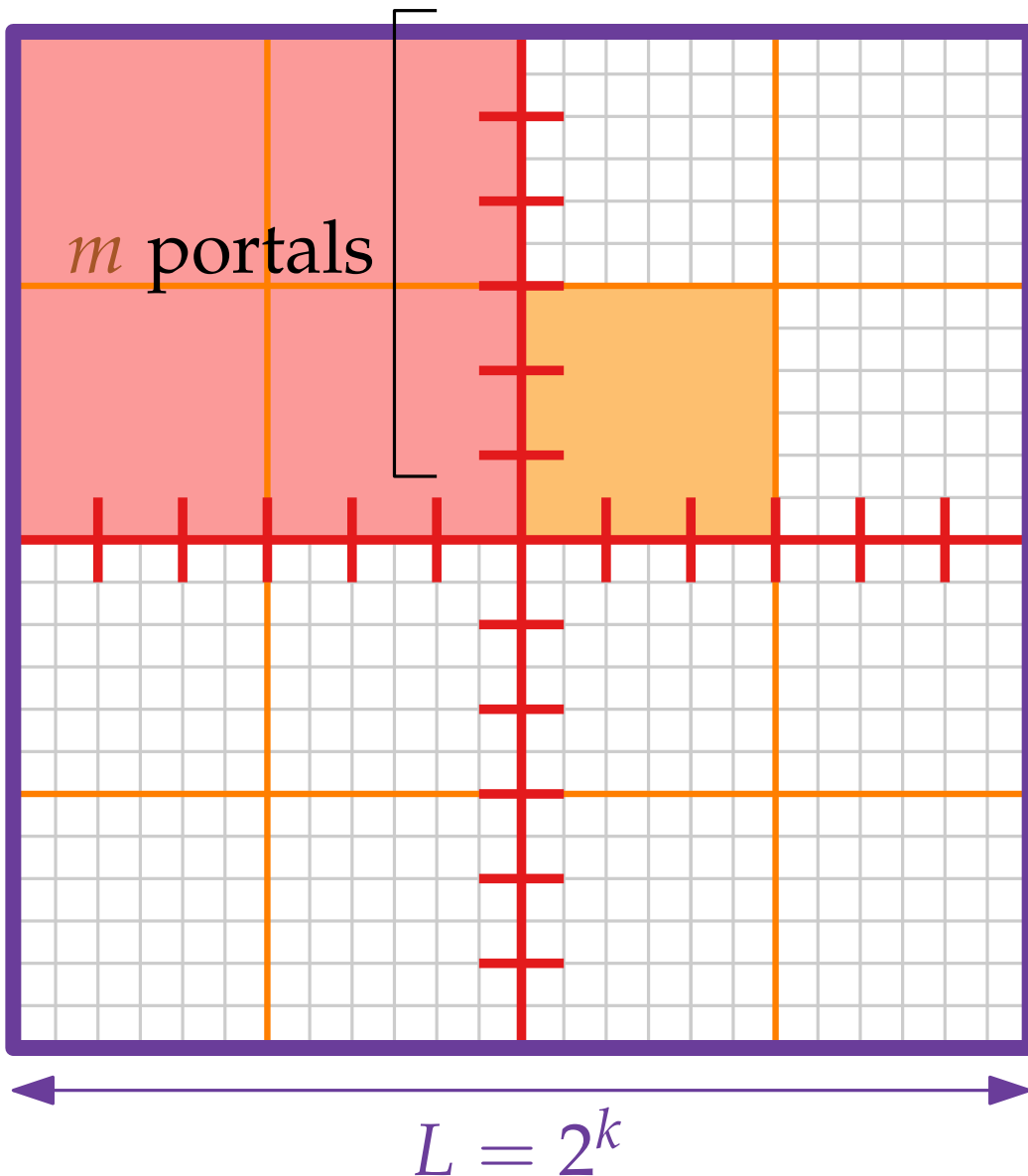


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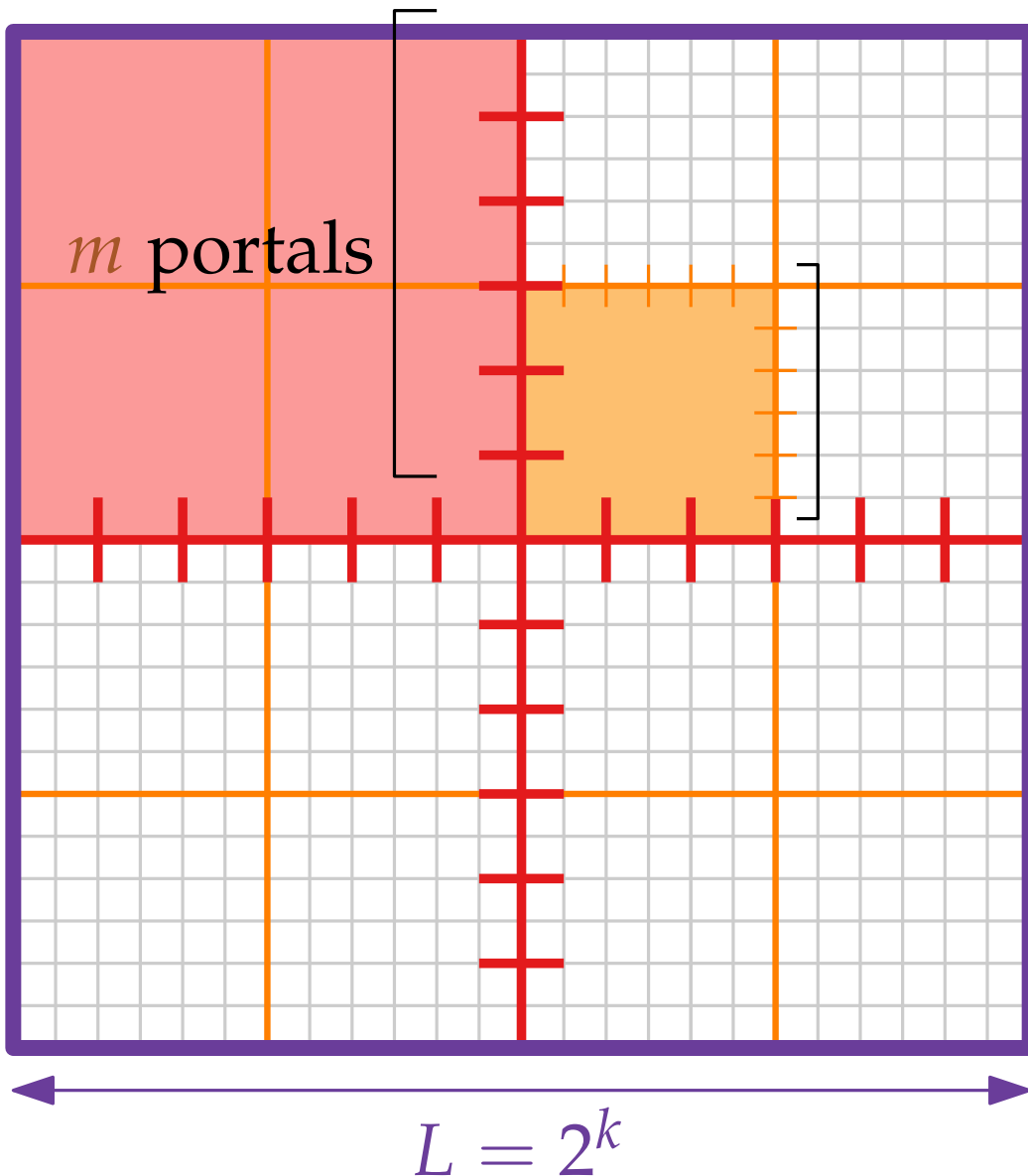


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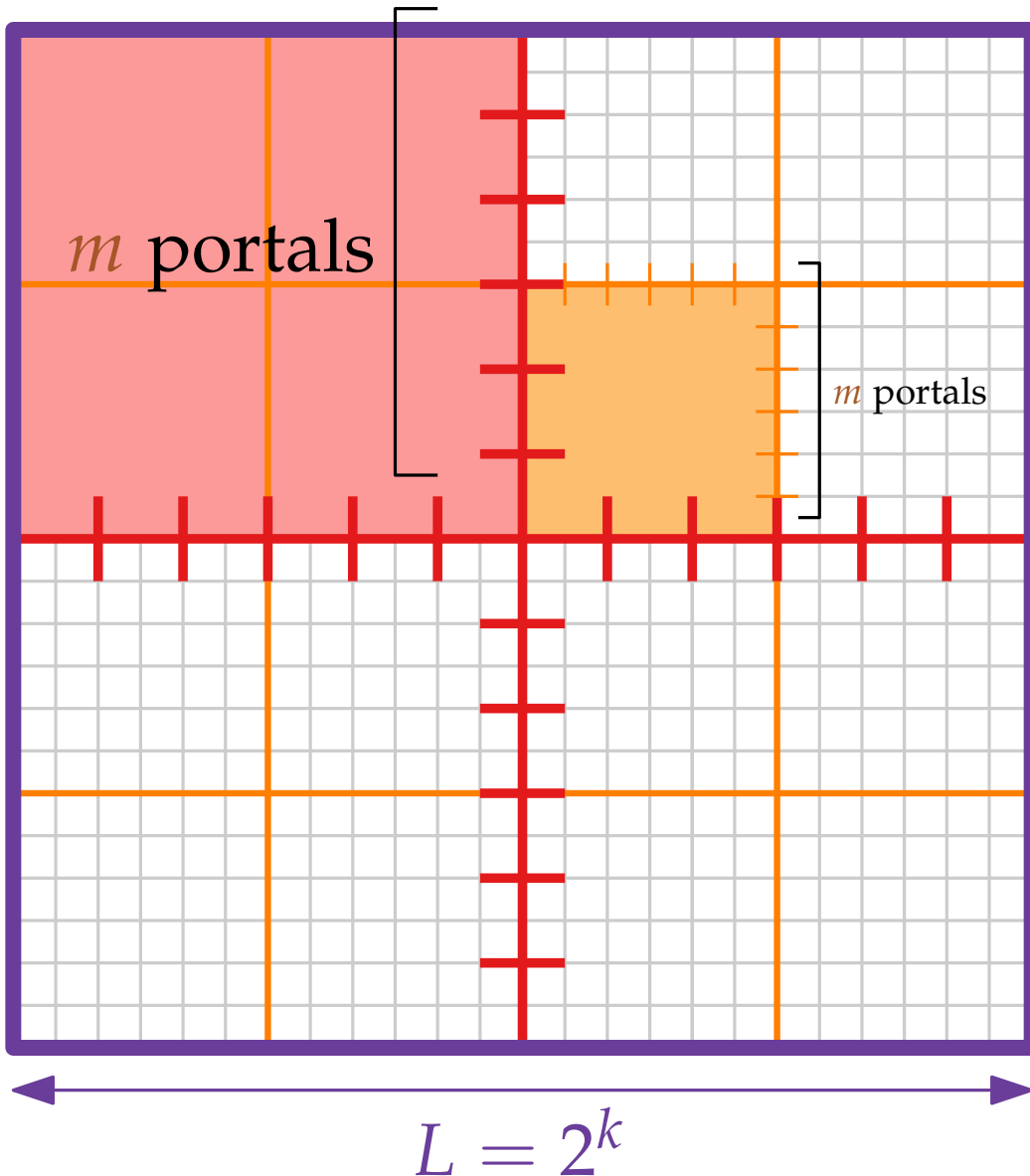


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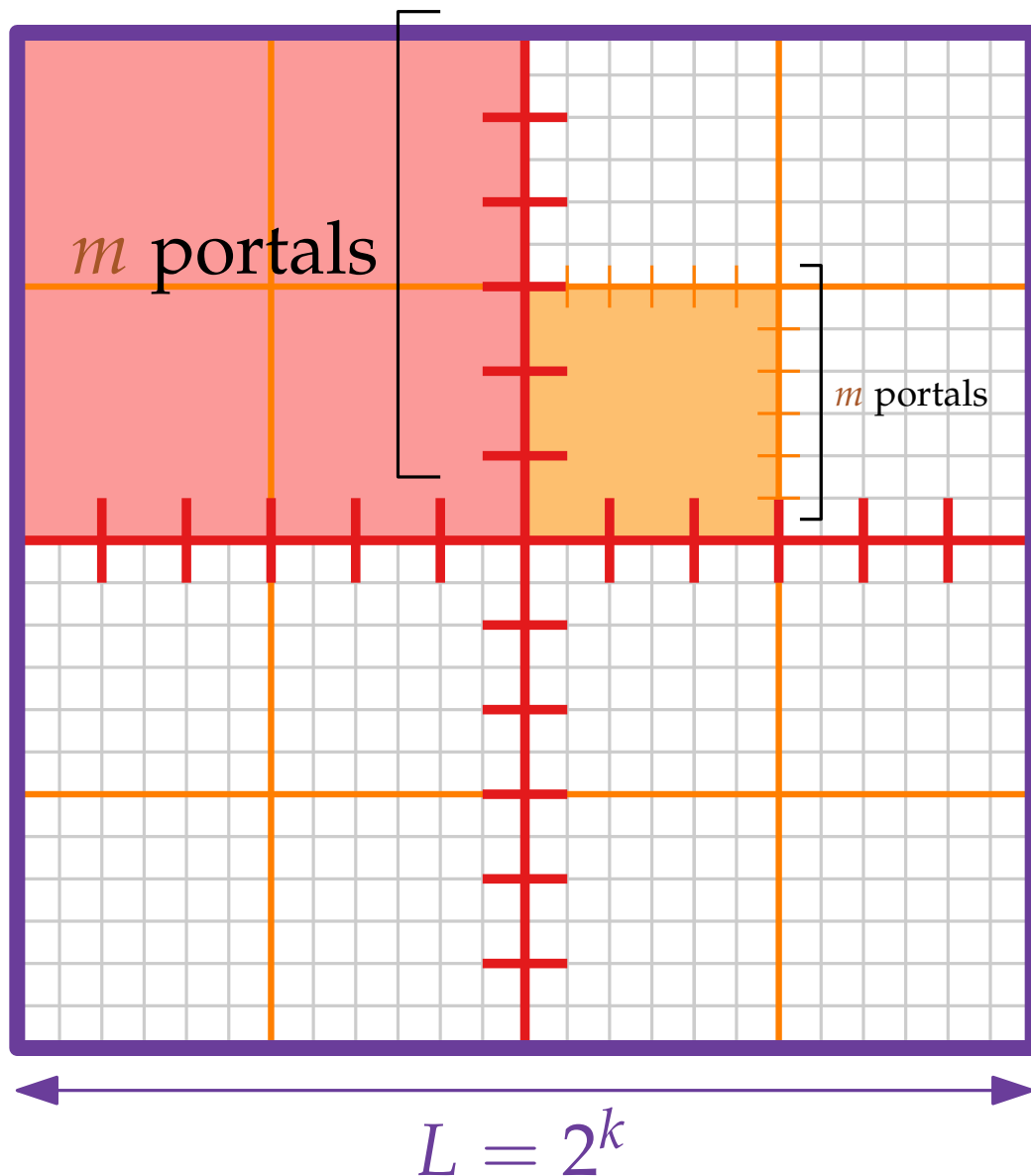


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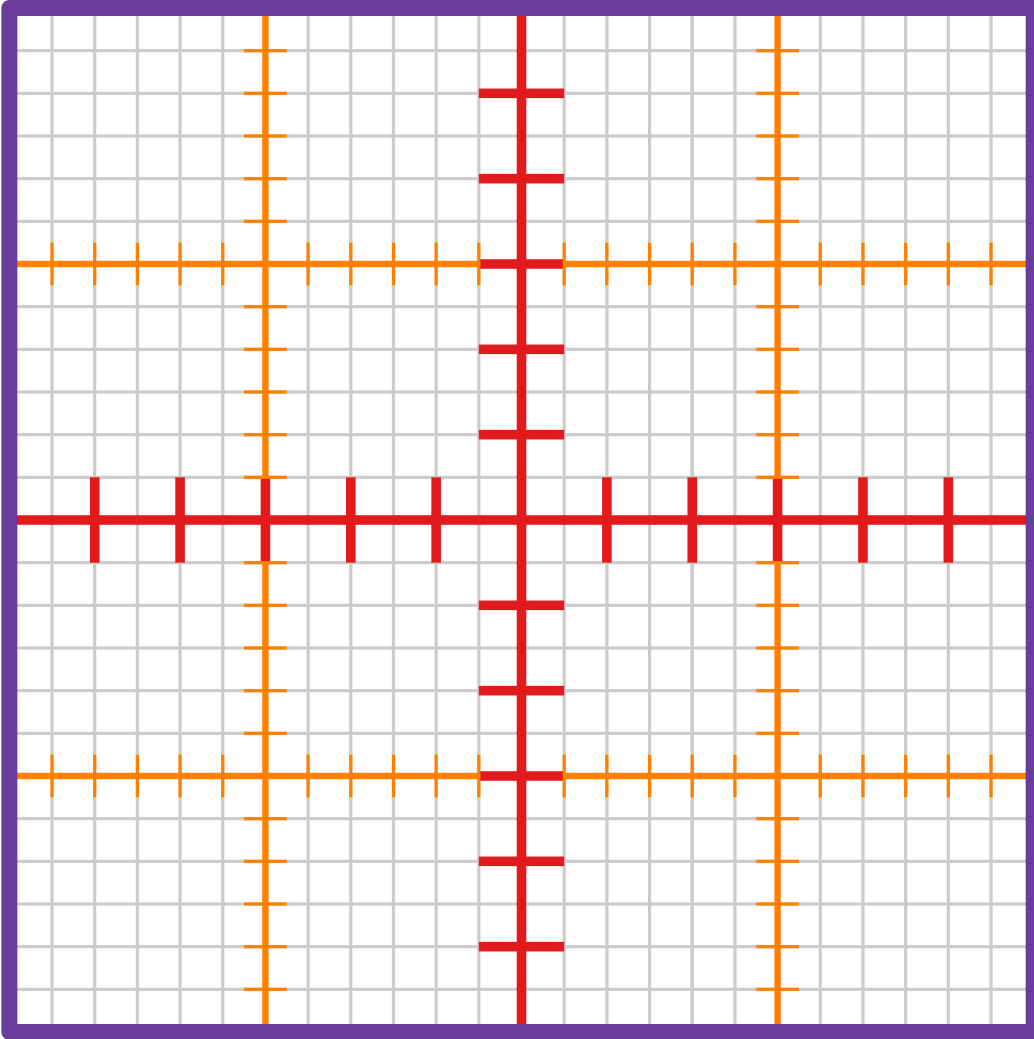
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- Every level- i square has size $L/2^i \times L/2^i$.
- A level- i square has $\leq 4m$ portals on its boundary.

Approximation Algorithms

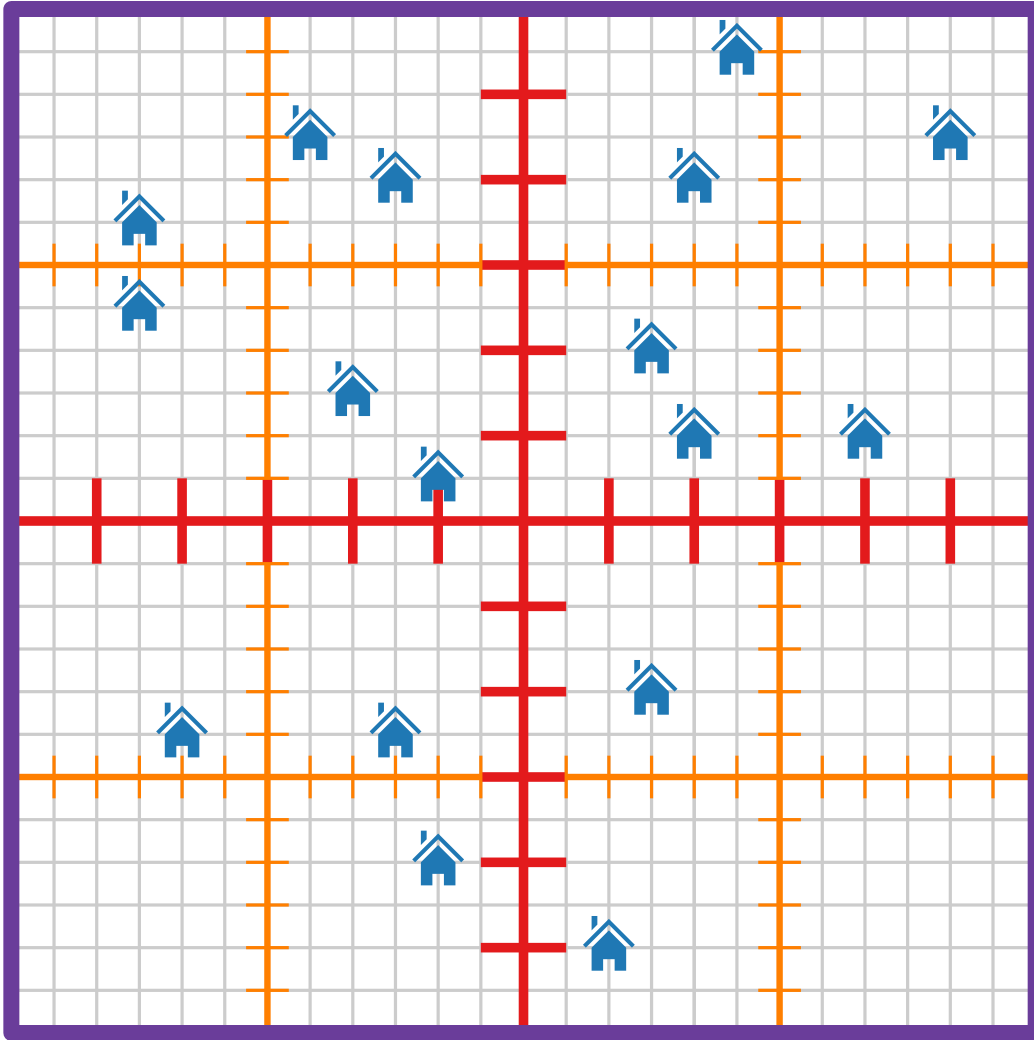
Lecture 9: A PTAS for EUCLIDEAN TSP

Part III: Well-Behaved Tours

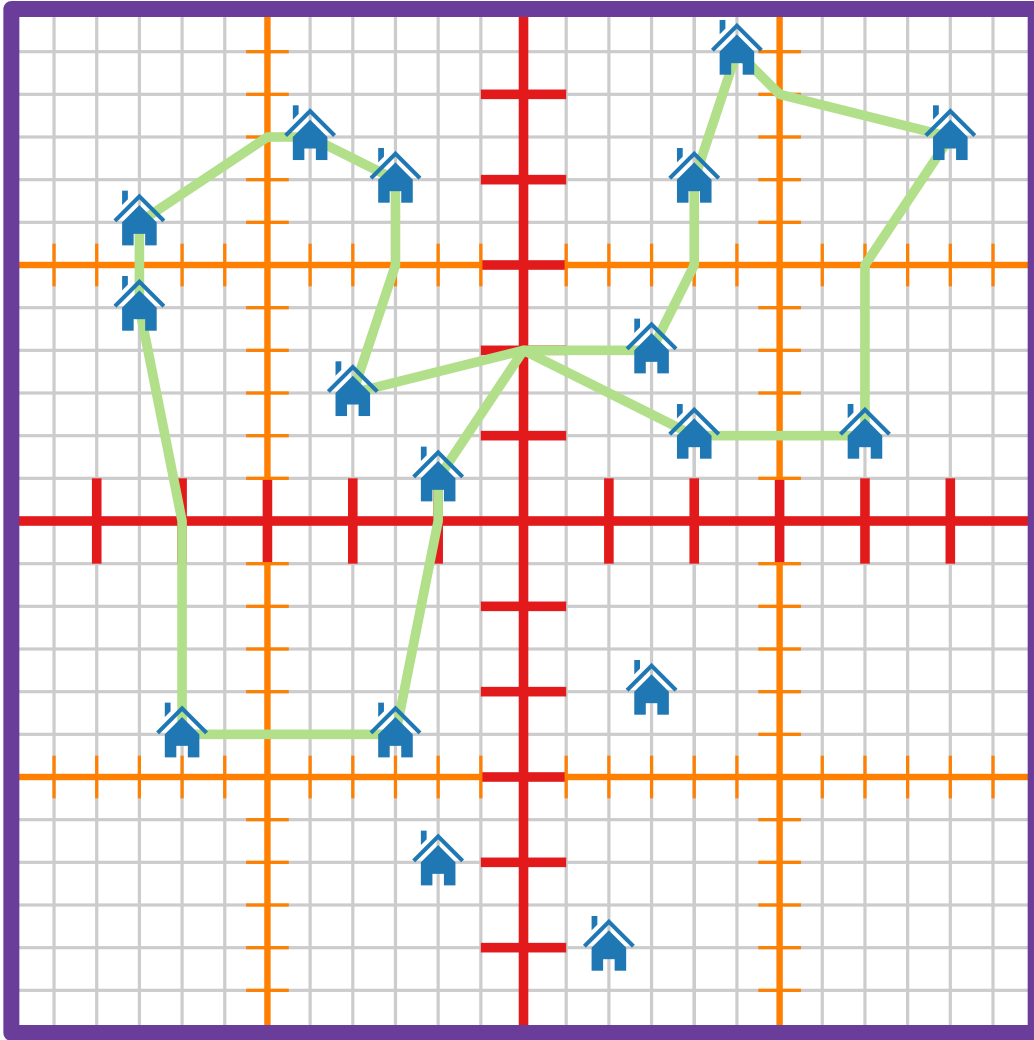
Well-Behaved Tours



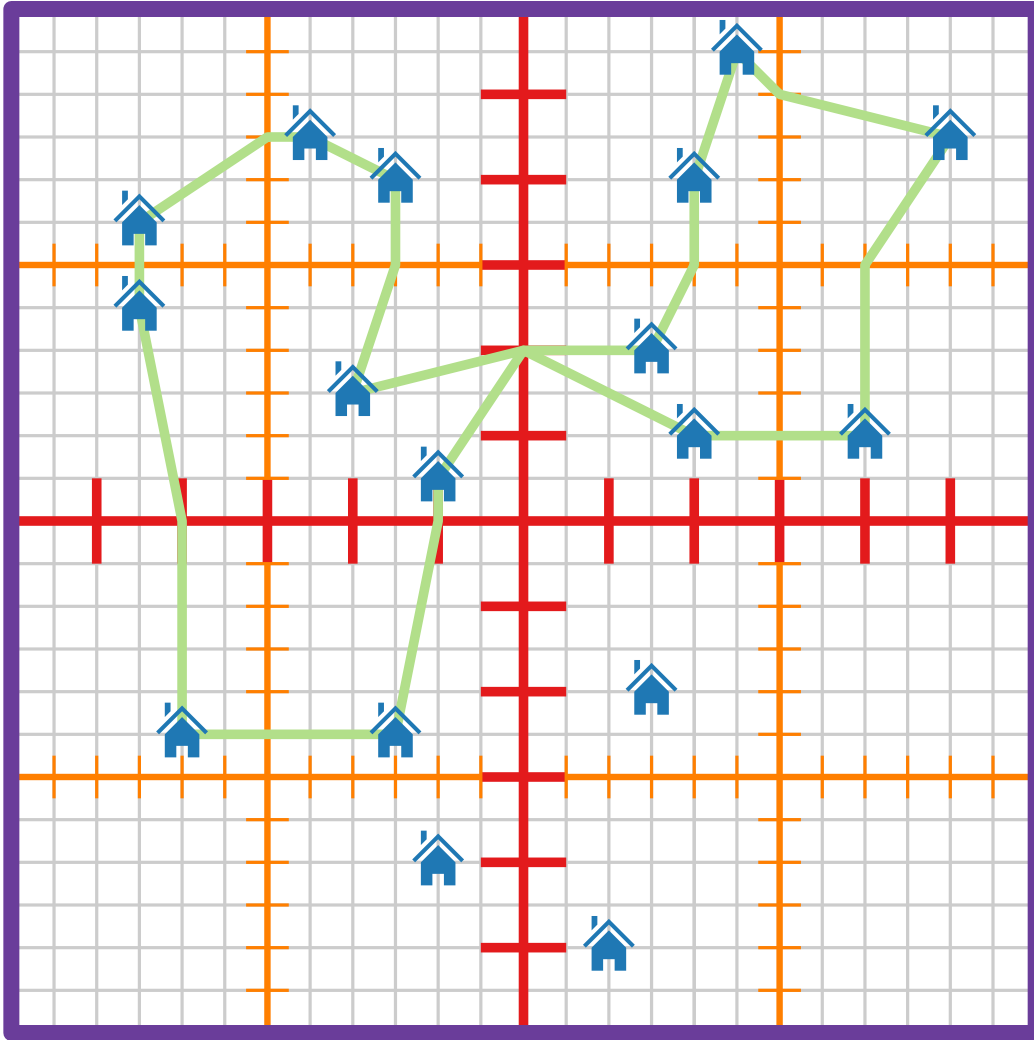
Well-Behaved Tours



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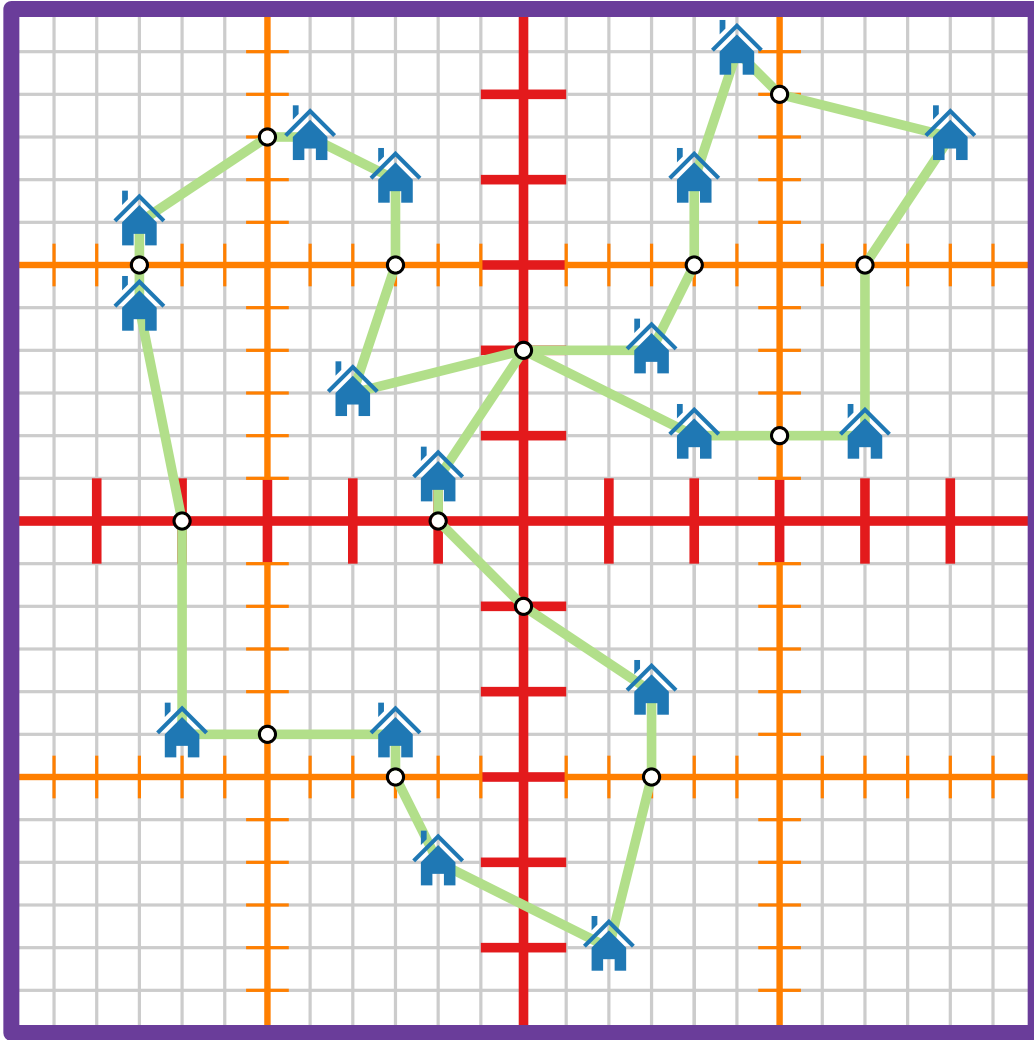
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A tour is *well-behaved* if

- it involves all houses

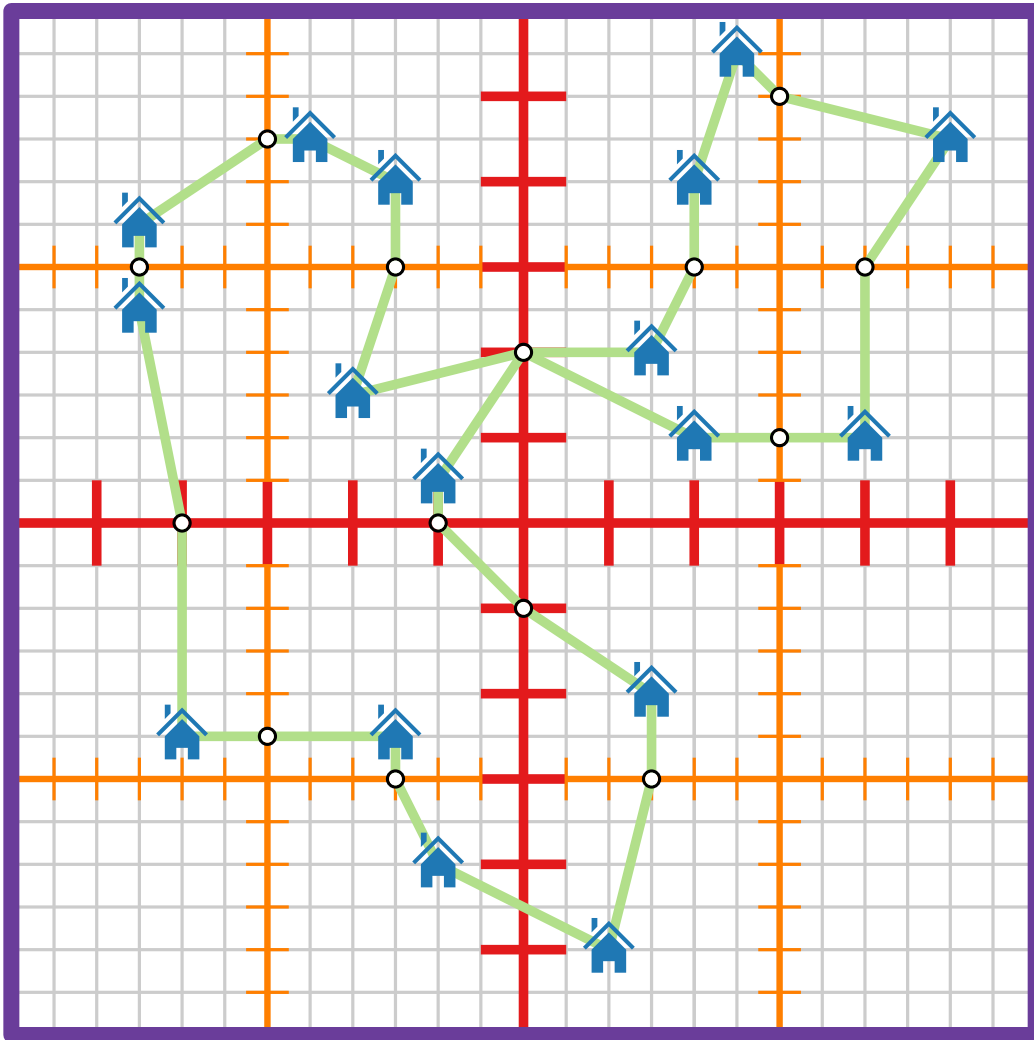
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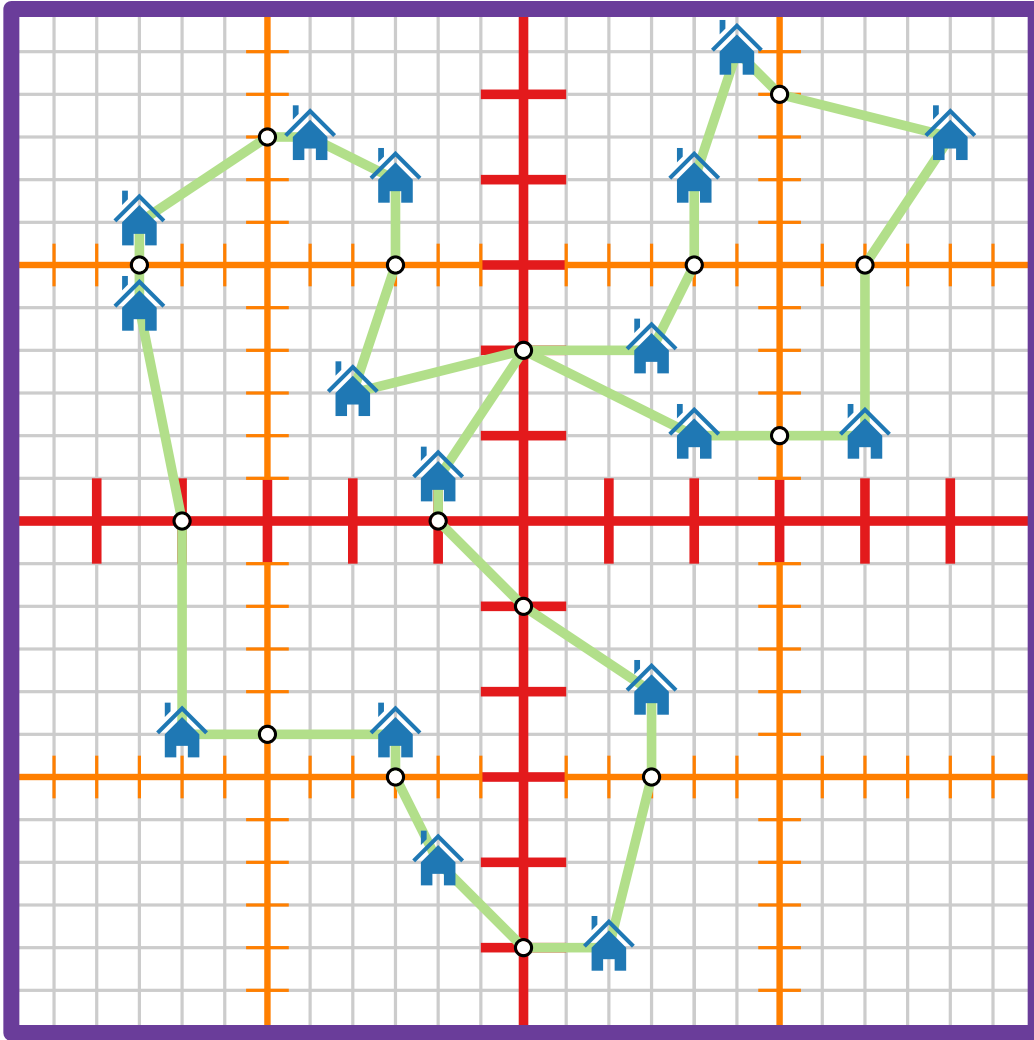
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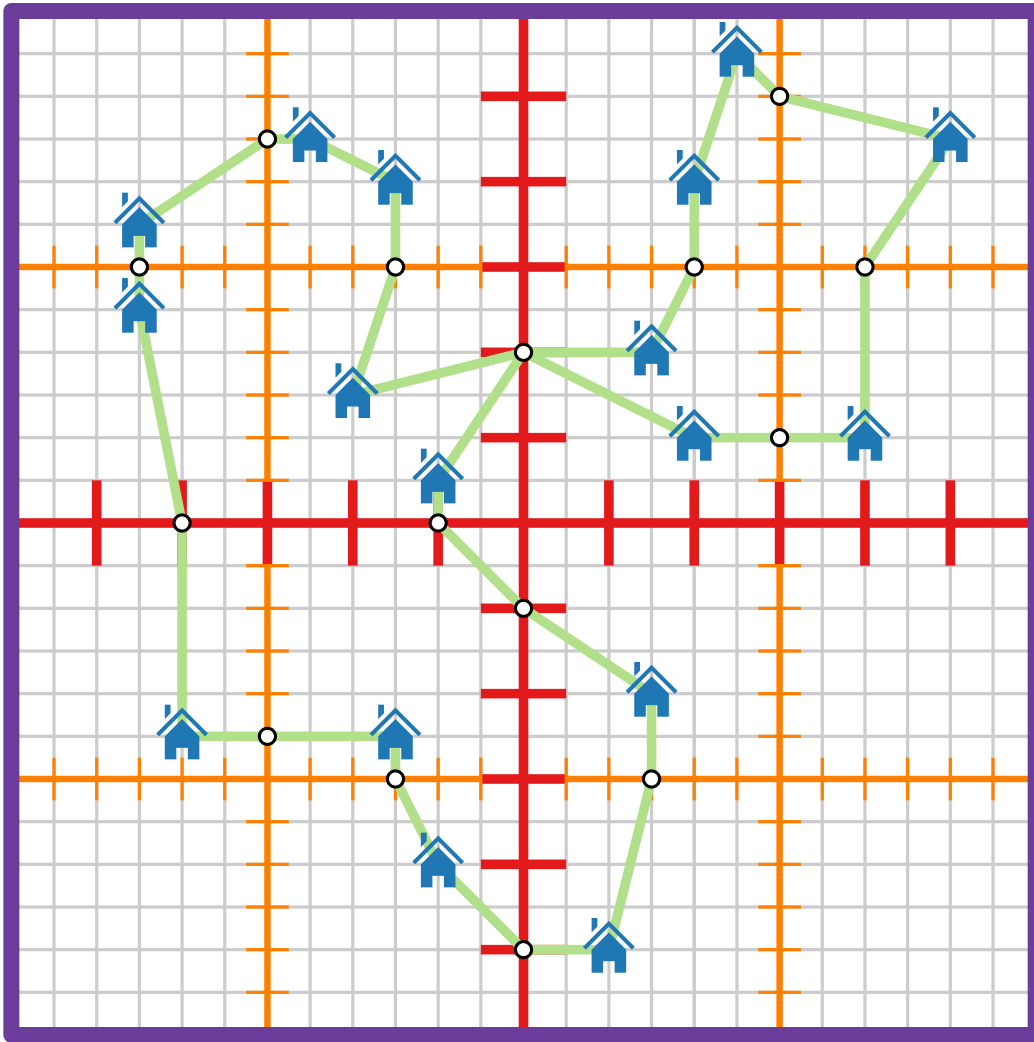
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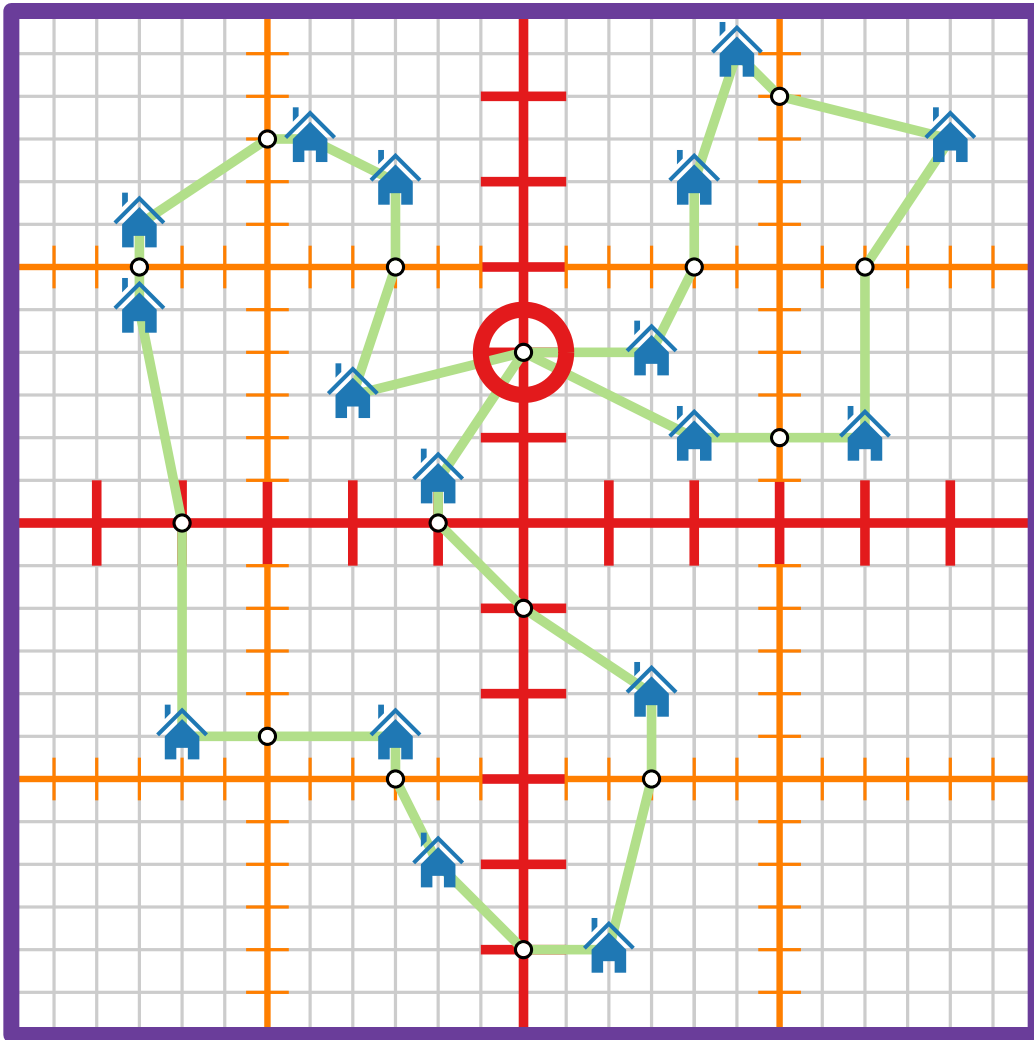
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- it is crossing-free.

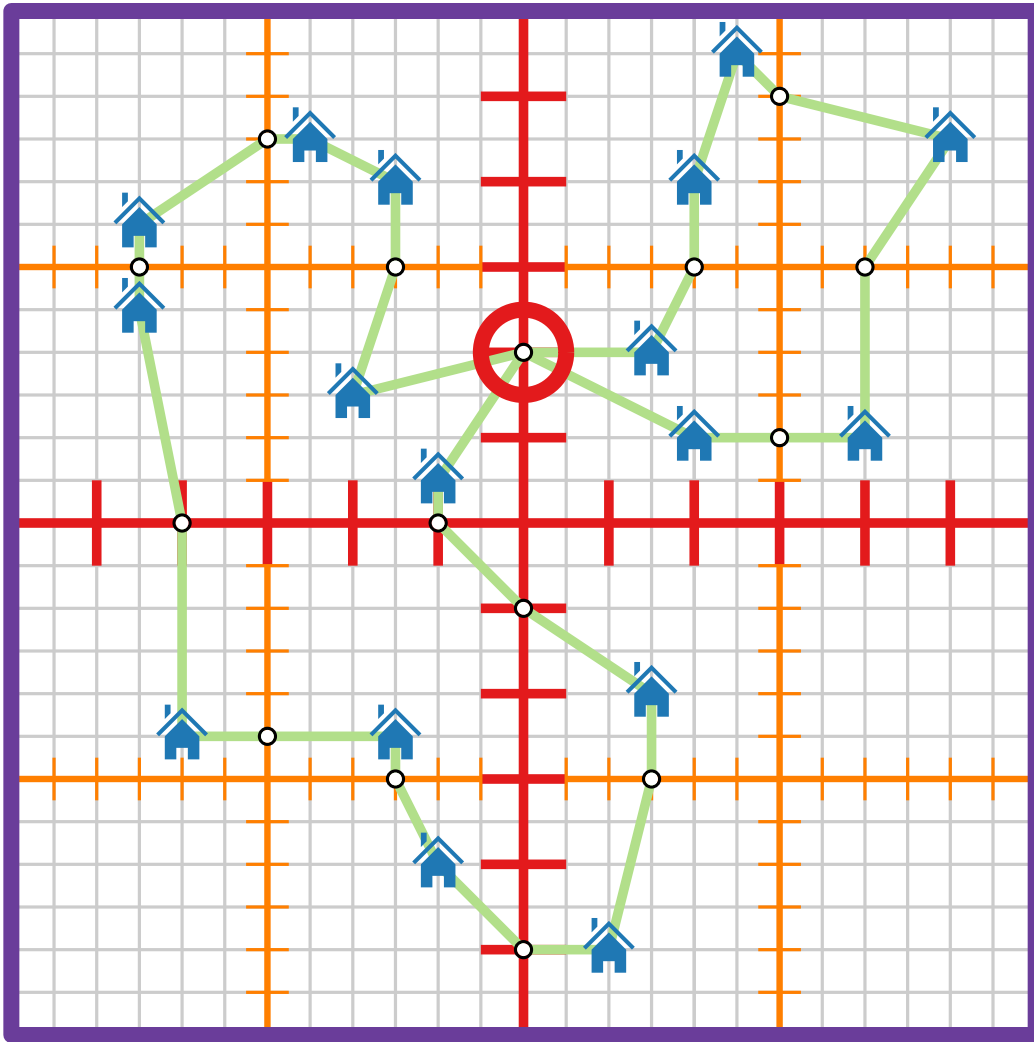
Well-Behaved Tours



A tour is *well-behaved* if

- it involves all houses and a subset of the portals,
- no edge of the tour crosses a line of the basic dissection,
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Well-Behaved Tours

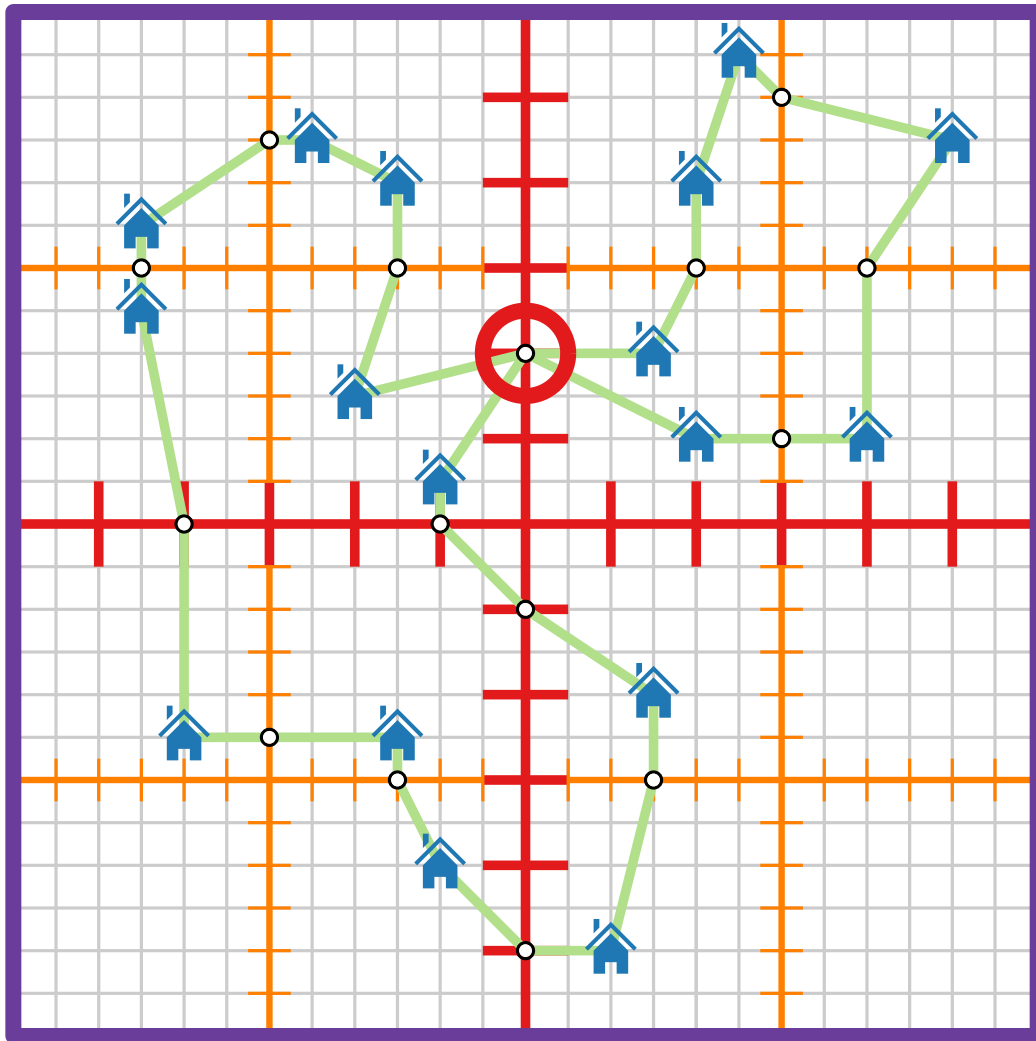


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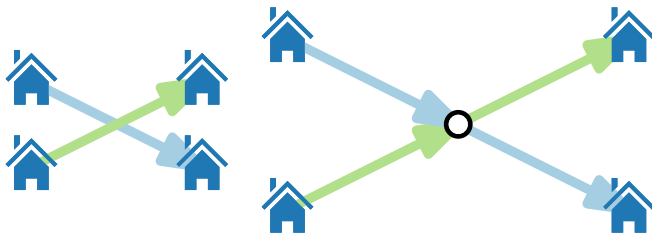
Well-Behaved Tours



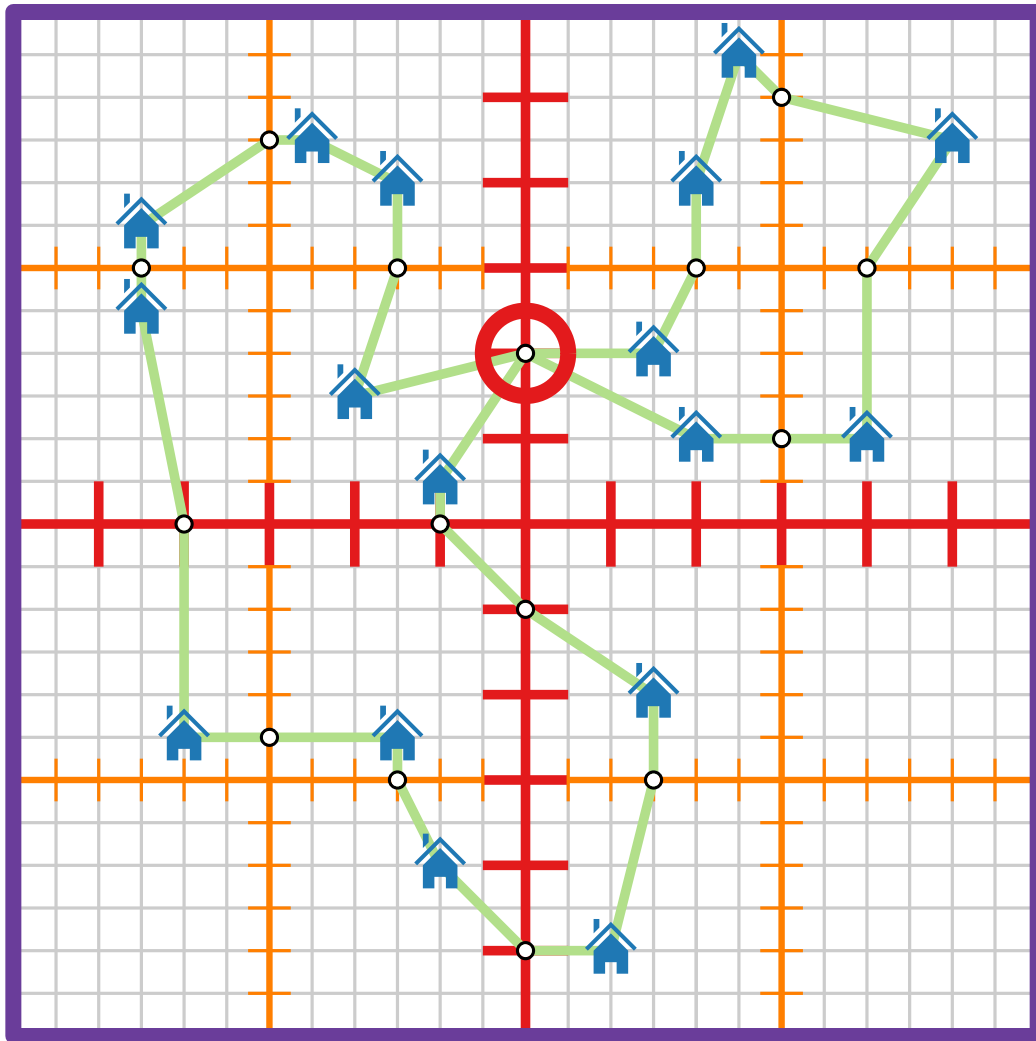
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Crossing



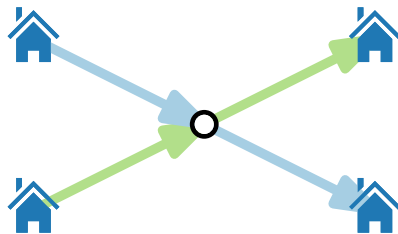
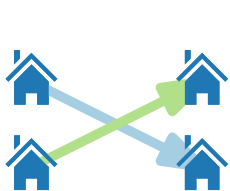
Well-Behaved Tours



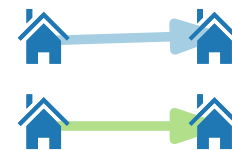
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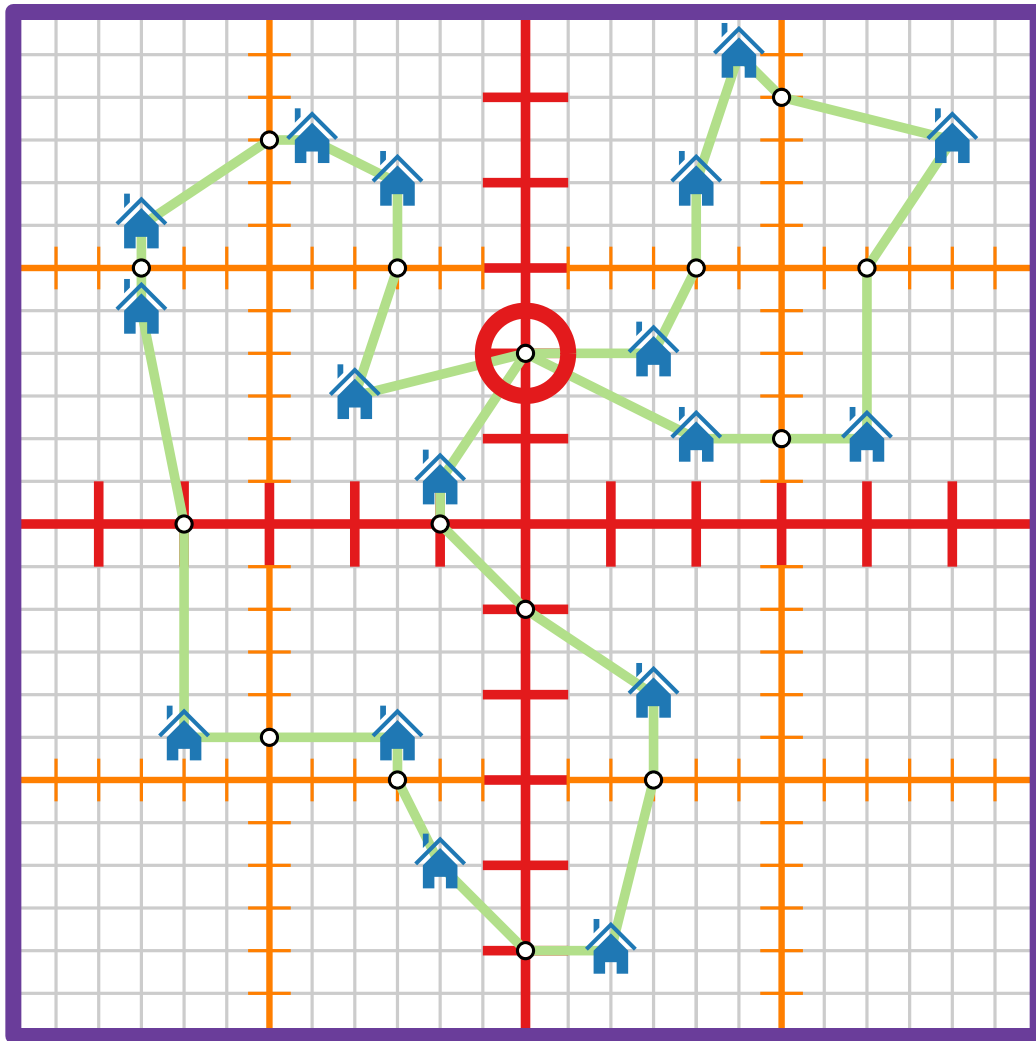
Crossing



No crossing



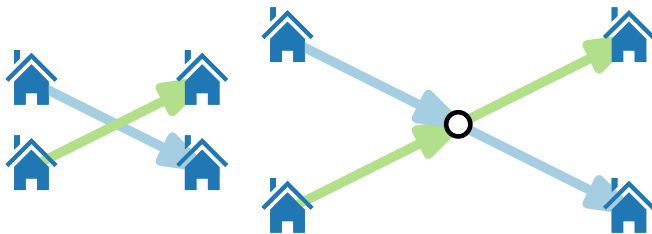
Well-Behaved Tours



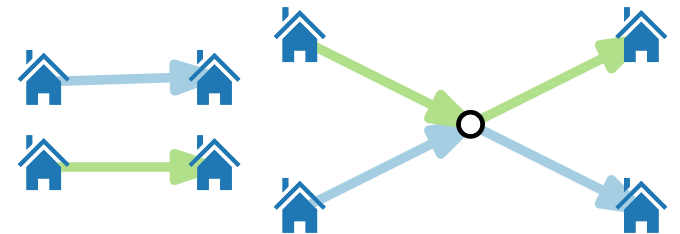
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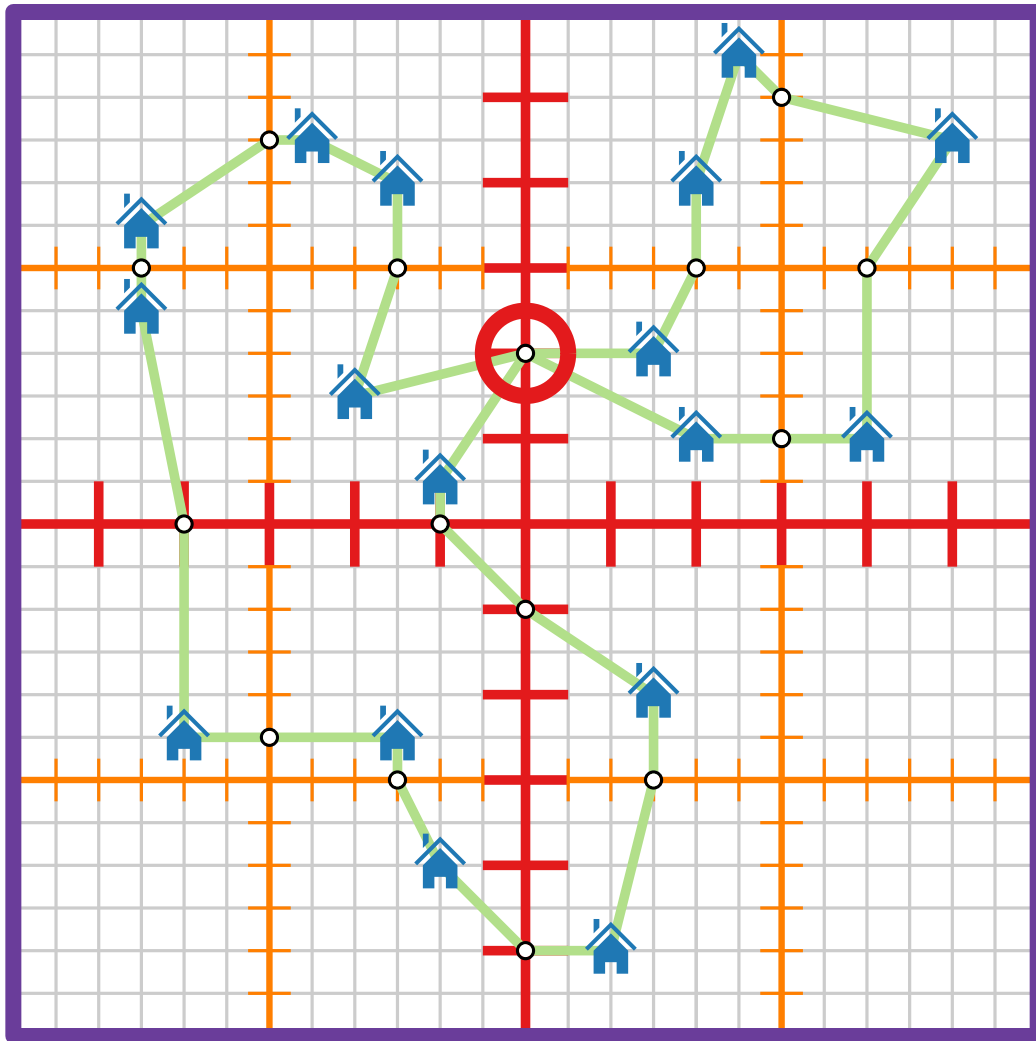
Crossing



No crossing



Well-Behaved Tours



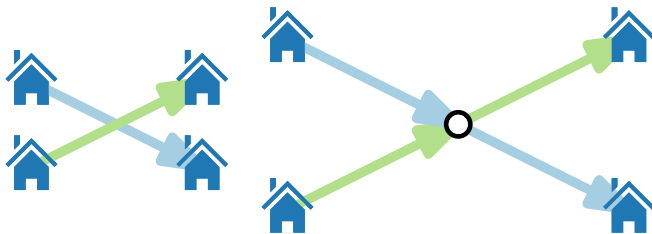
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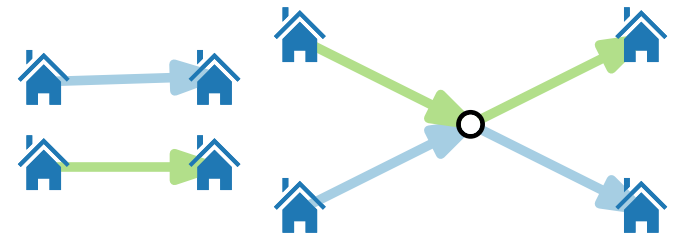
W.l.o.g. (**homework**):

No portal visited more than twice

Crossing



No
crossing



Computing a Well-Behaved Tour

Computing a Well-Behaved Tour

Lemma. An optimal well-behaved tour can be computed in $2^{O(m)} = n^{O(1/\varepsilon)}$ time.

Computing a Well-Behaved Tour

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Sketch.



Computing a Well-Behaved Tour

Lemma. An optimal well-behaved tour can be computed in $2^{O(m)} = n^{O(1/\varepsilon)}$ time.

Sketch. ■ Dynamic programming!



Computing a Well-Behaved Tour

Lemma. An optimal well-behaved tour can be computed in $2^{O(m)} = n^{O(1/\varepsilon)}$ time.

- Sketch.**
- Dynamic programming!
 - Compute sub-structure of an optimal tour for each square in the dissection tree.



Computing a Well-Behaved Tour

Lemma. An optimal well-behaved tour can be computed in $2^{O(m)} = n^{O(1/\varepsilon)}$ time.

- Sketch.**
- Dynamic programming!
 - Compute sub-structure of an optimal tour for each square in the dissection tree.
 - These solutions can be efficiently propagated bottom-up through the dissection tree.

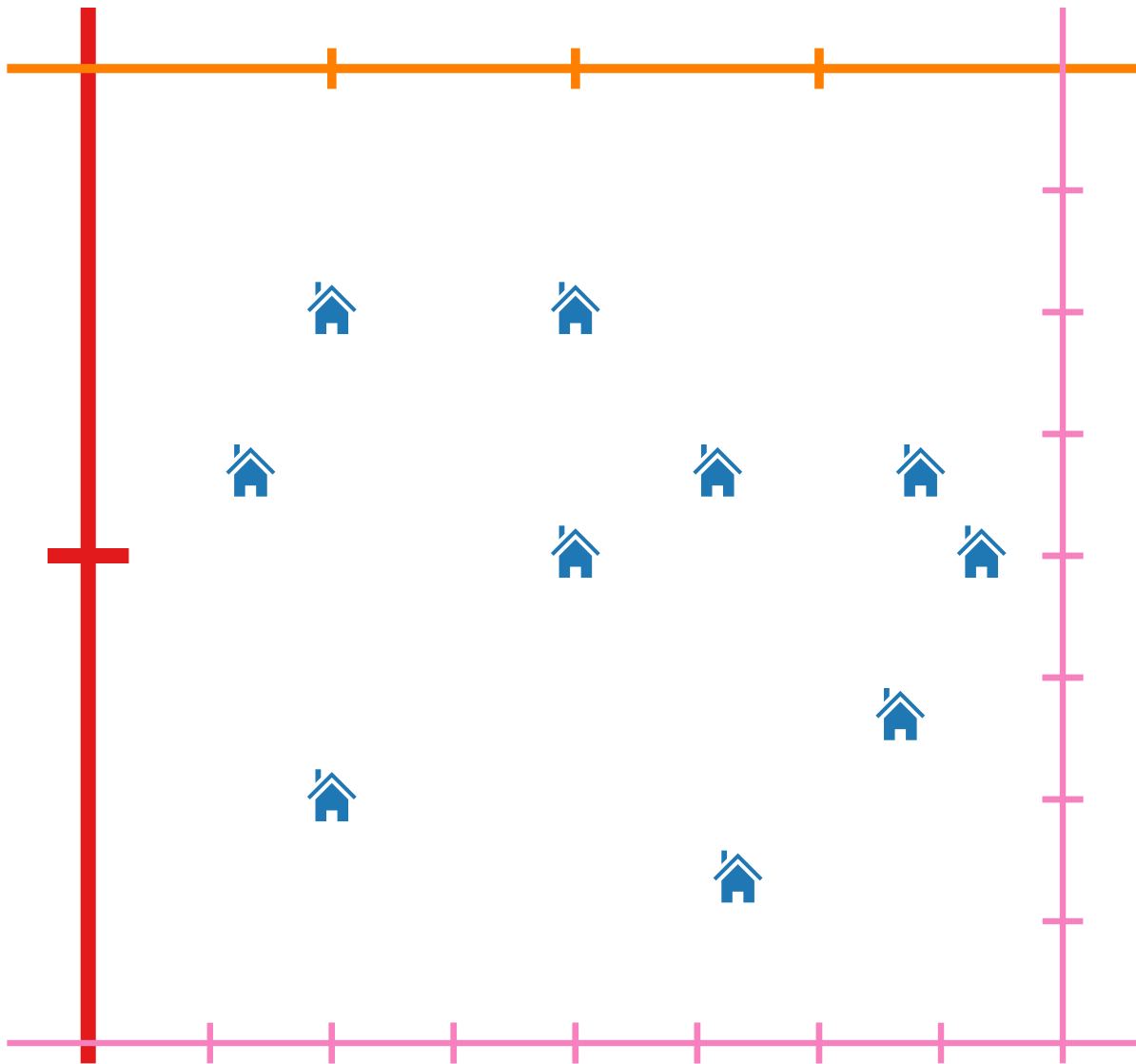


Approximation Algorithms

Lecture 9: A PTAS for EUCLIDEAN TSP

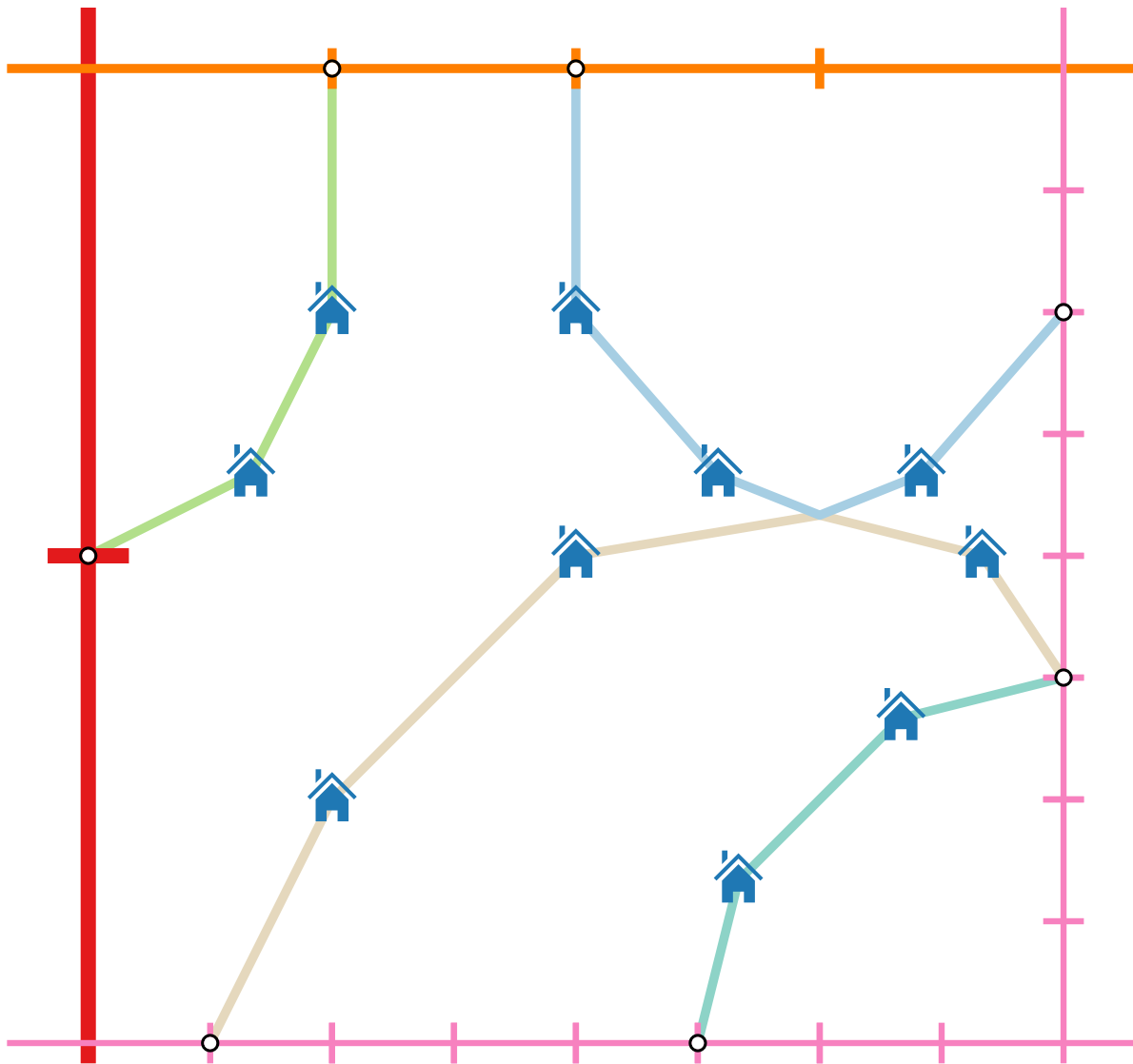
Part IV: Dynamic Program

Dynamic Program (I)



Each well-behaved tour induces the following in each square Q of the dissection:

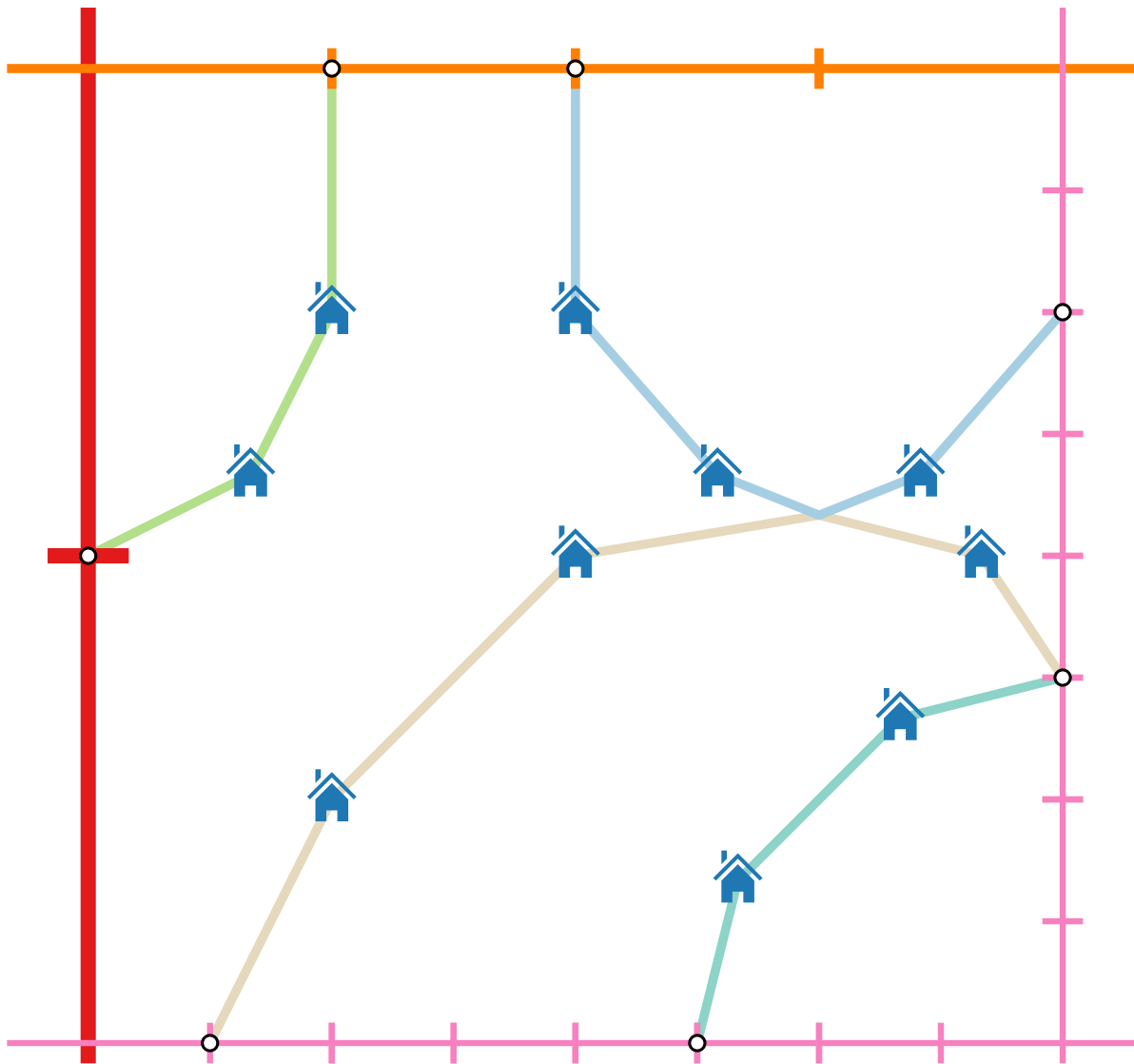
Dynamic Program (I)



Each well-behaved tour induces the following in each square Q of the dissection:

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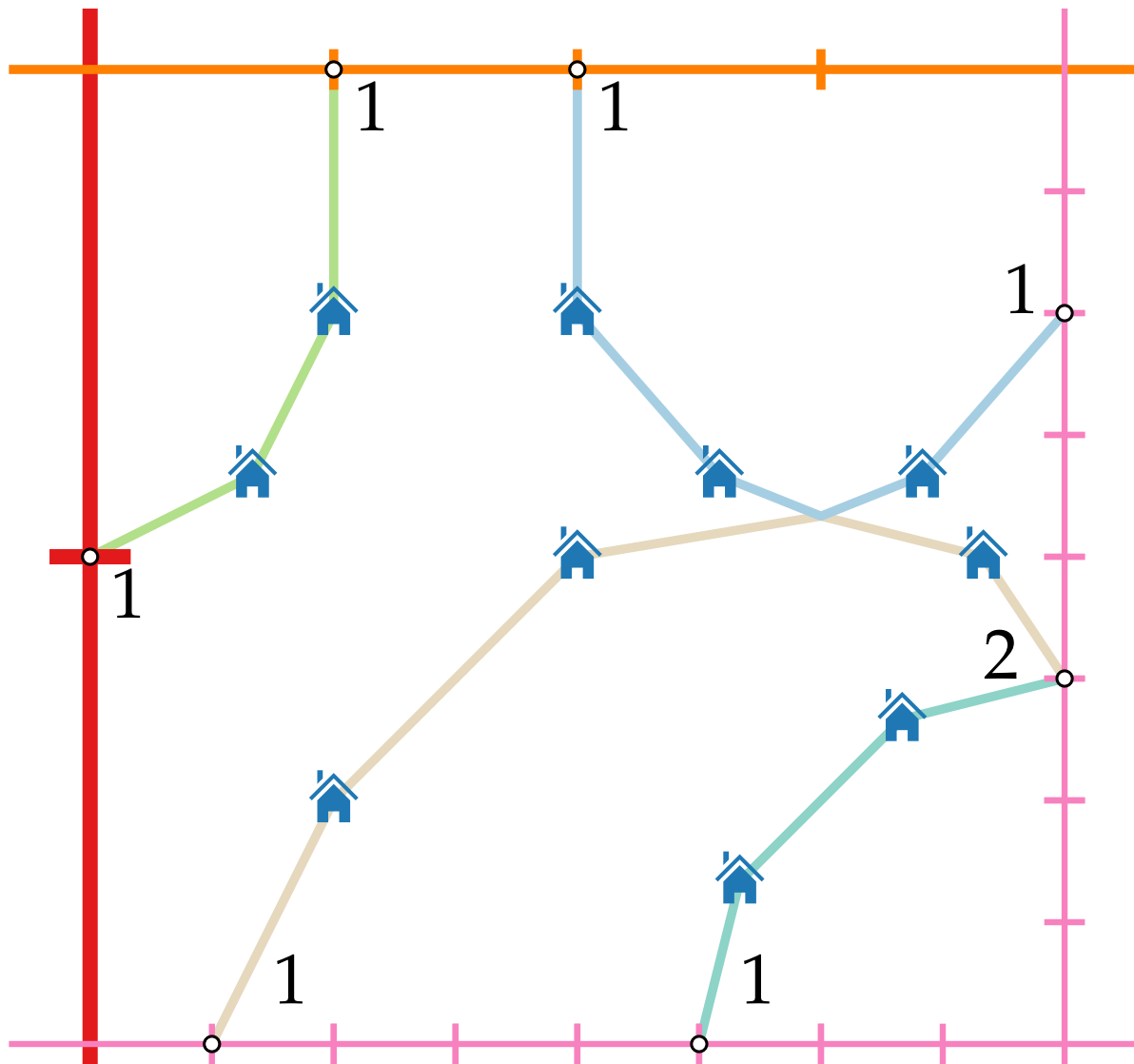
Dynamic Program (I)



Each well-behaved tour induces the following in each square Q of the dissection:

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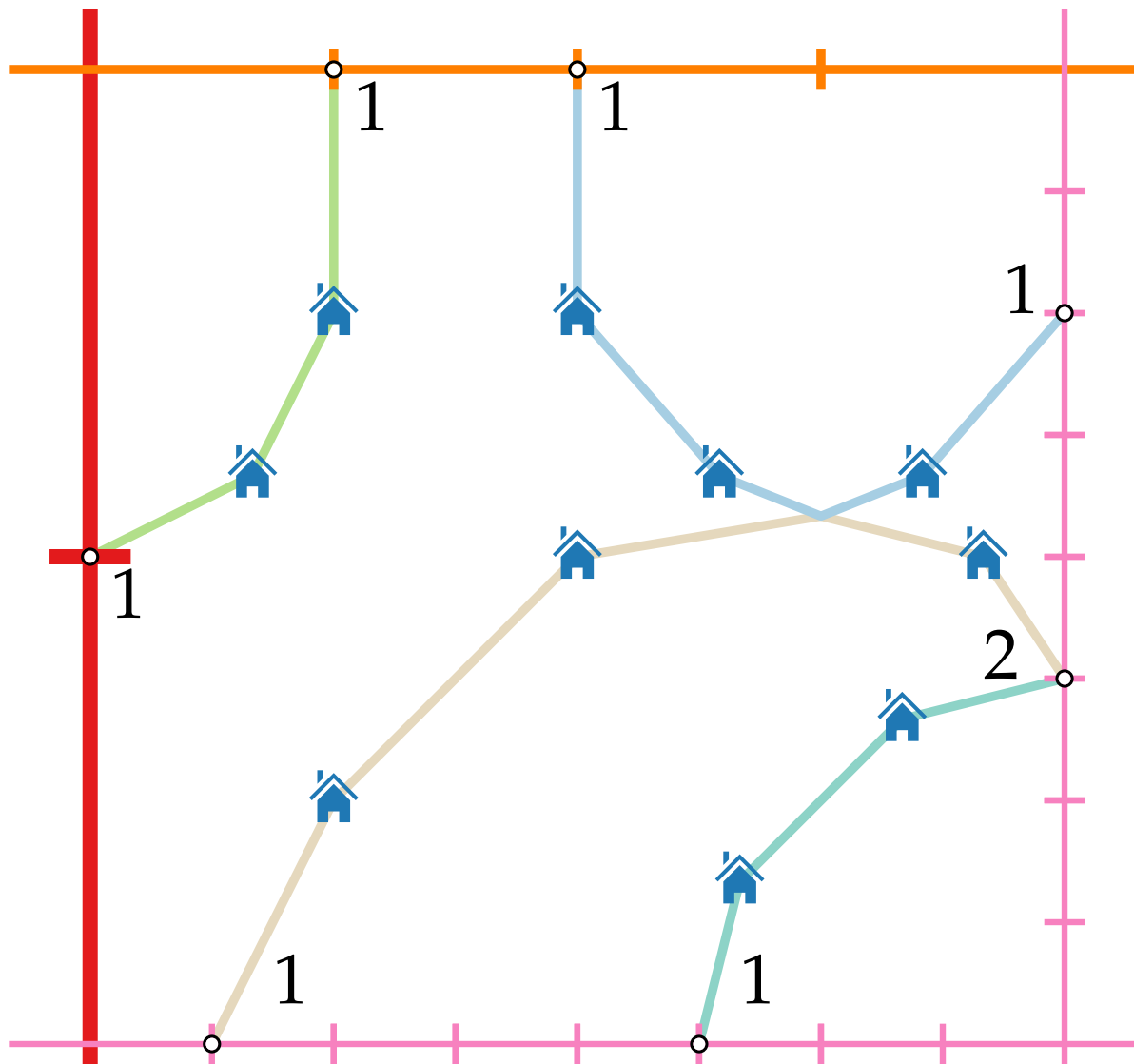
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Dynamic Program (I)



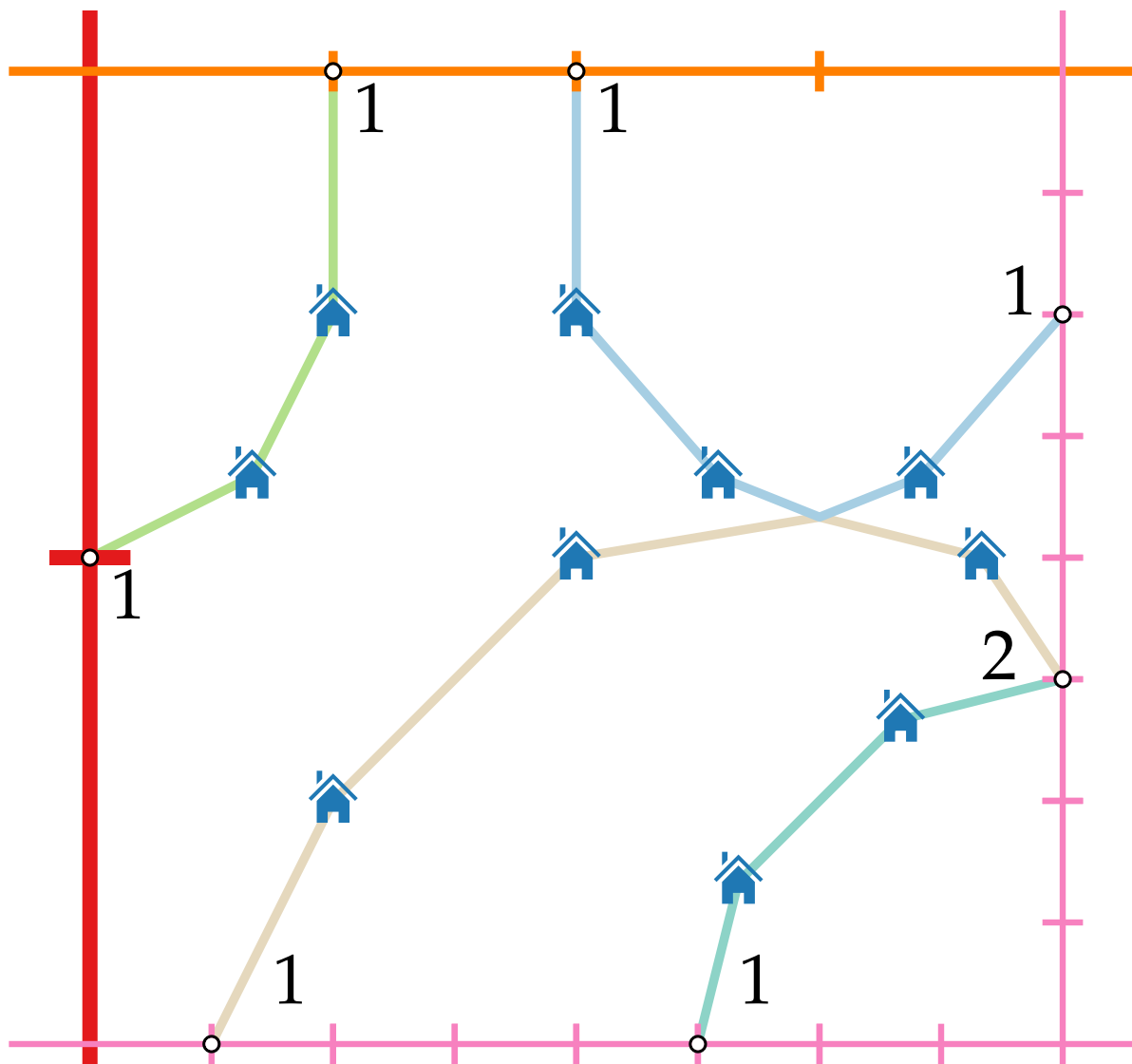
\Rightarrow max.

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possibilities

Dynamic Program (I)



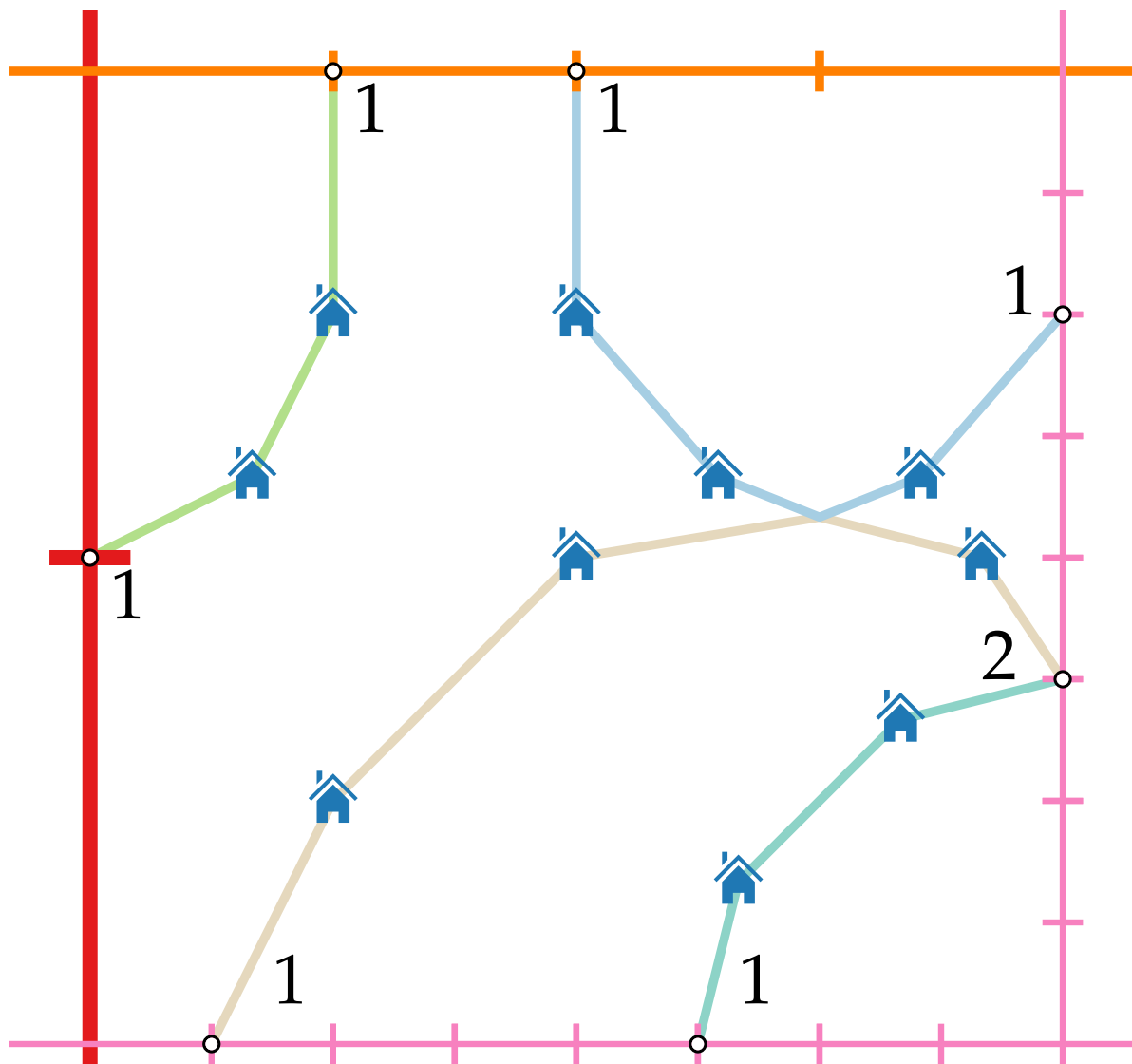
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$\Rightarrow \max. 3^{4m} \in$

possibilities

Dynamic Program (I)



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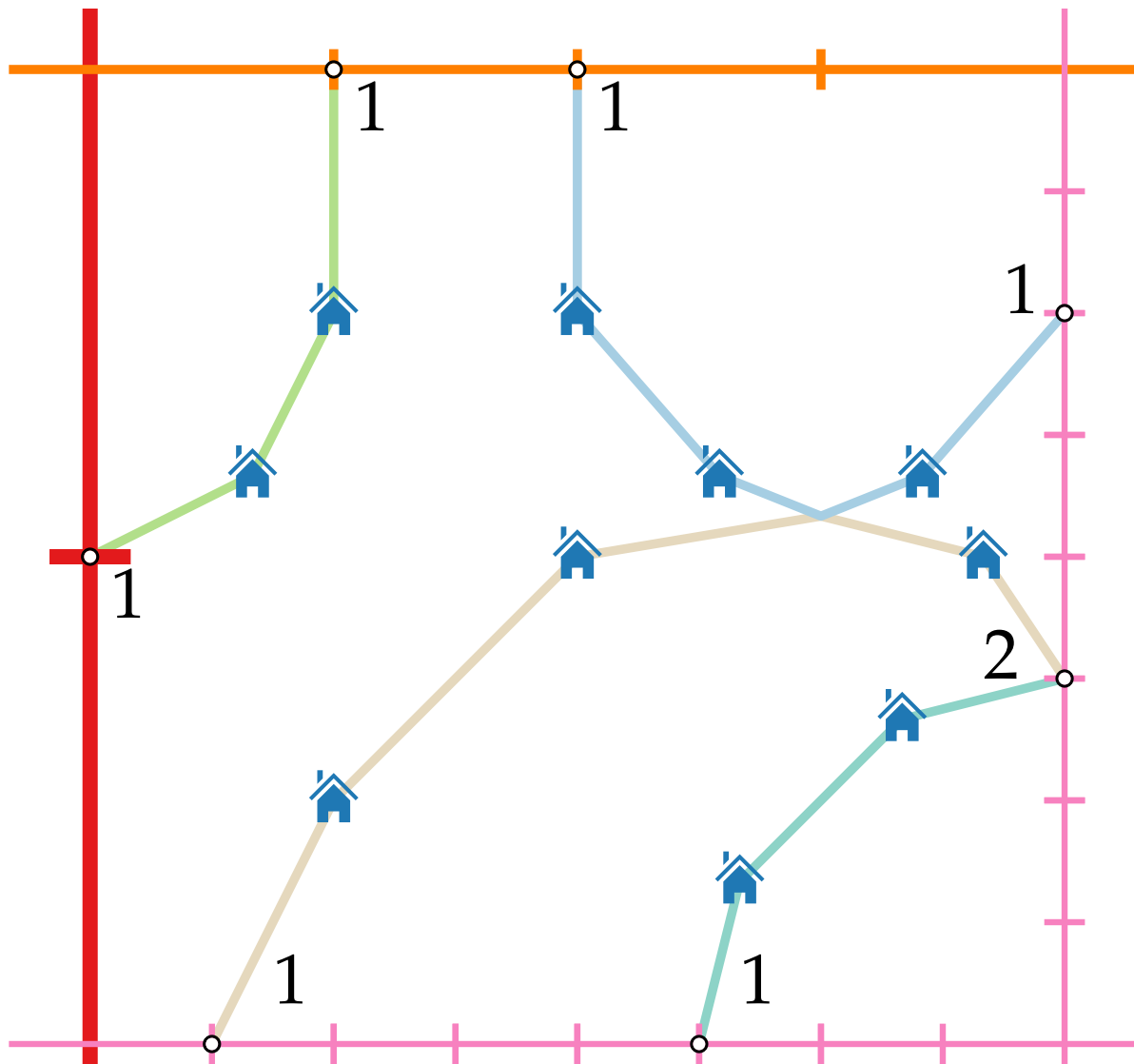
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$m = O((\log n)/\epsilon)$

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Dynamic Program (I)



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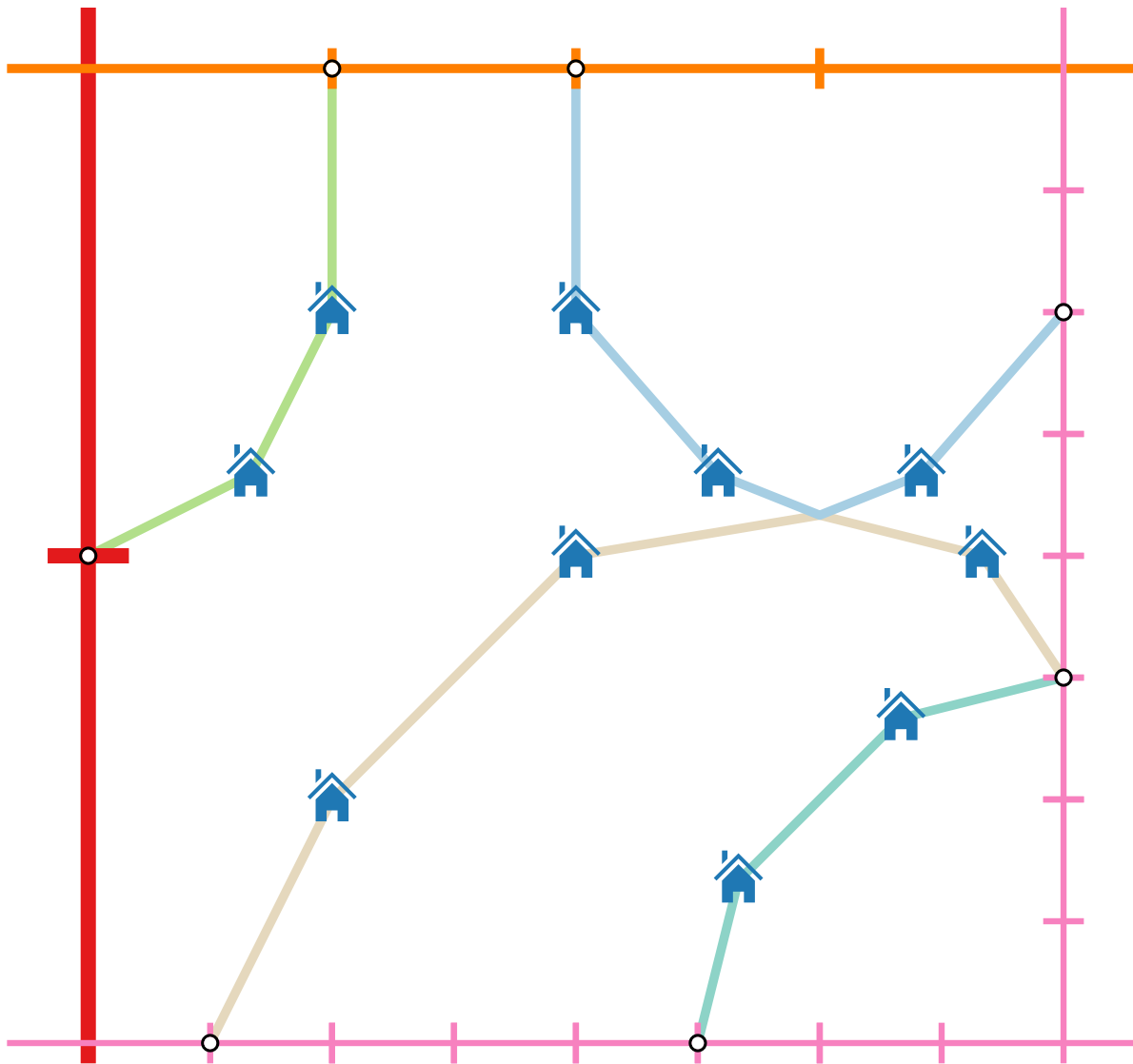
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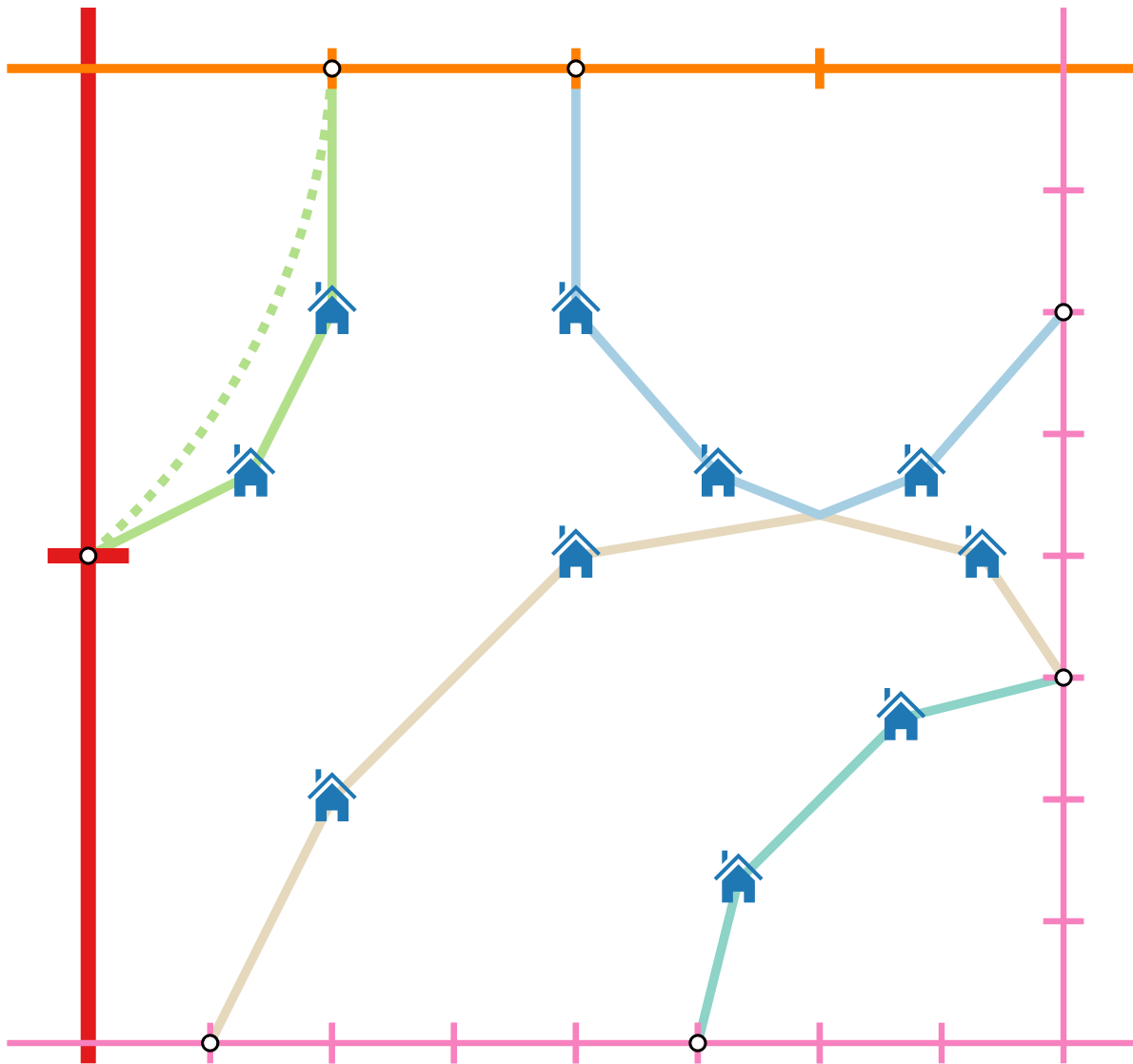
Dynamic Program (I)



Each well-behaved tour induces the following in each square Q of the dissection:

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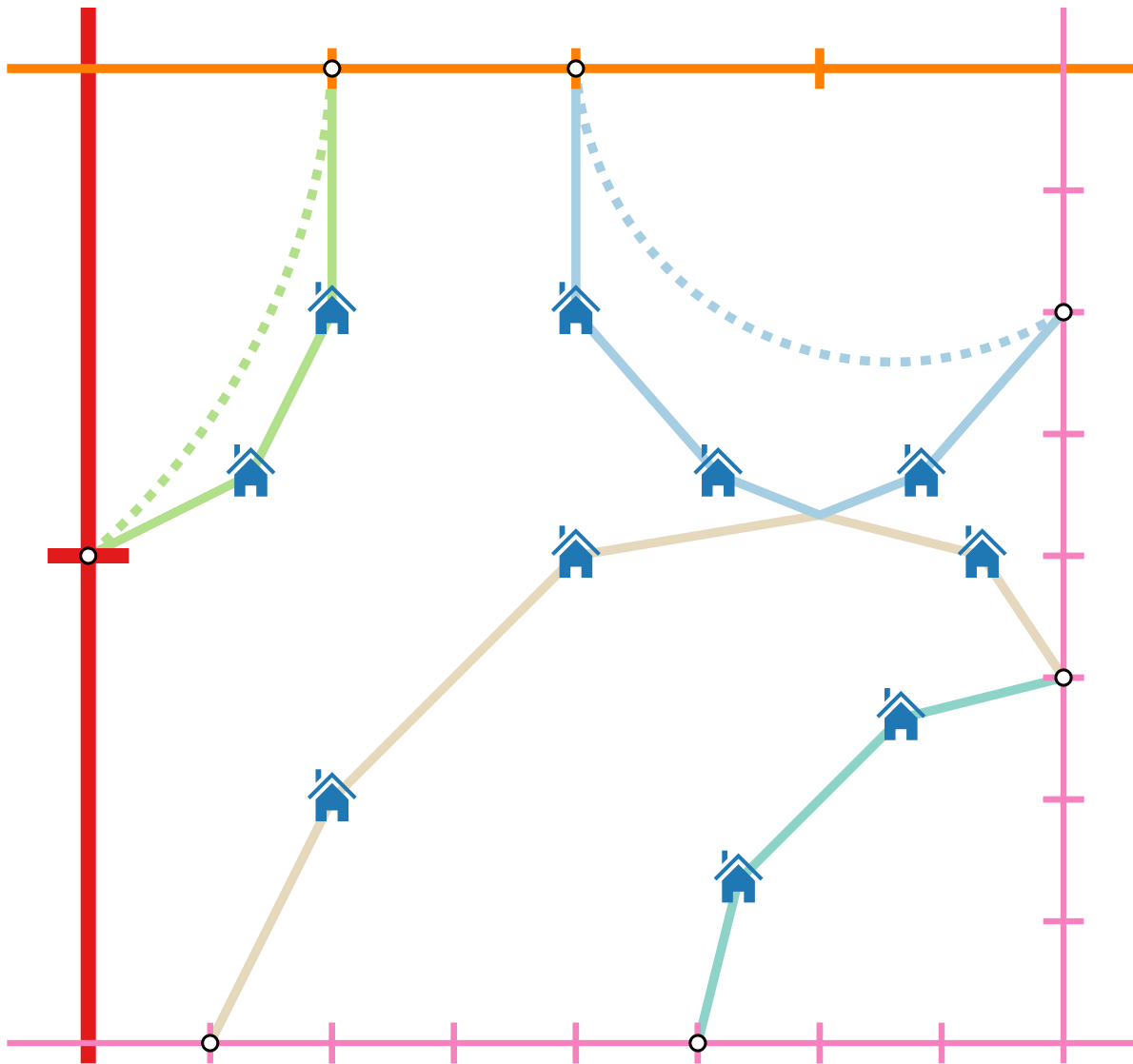
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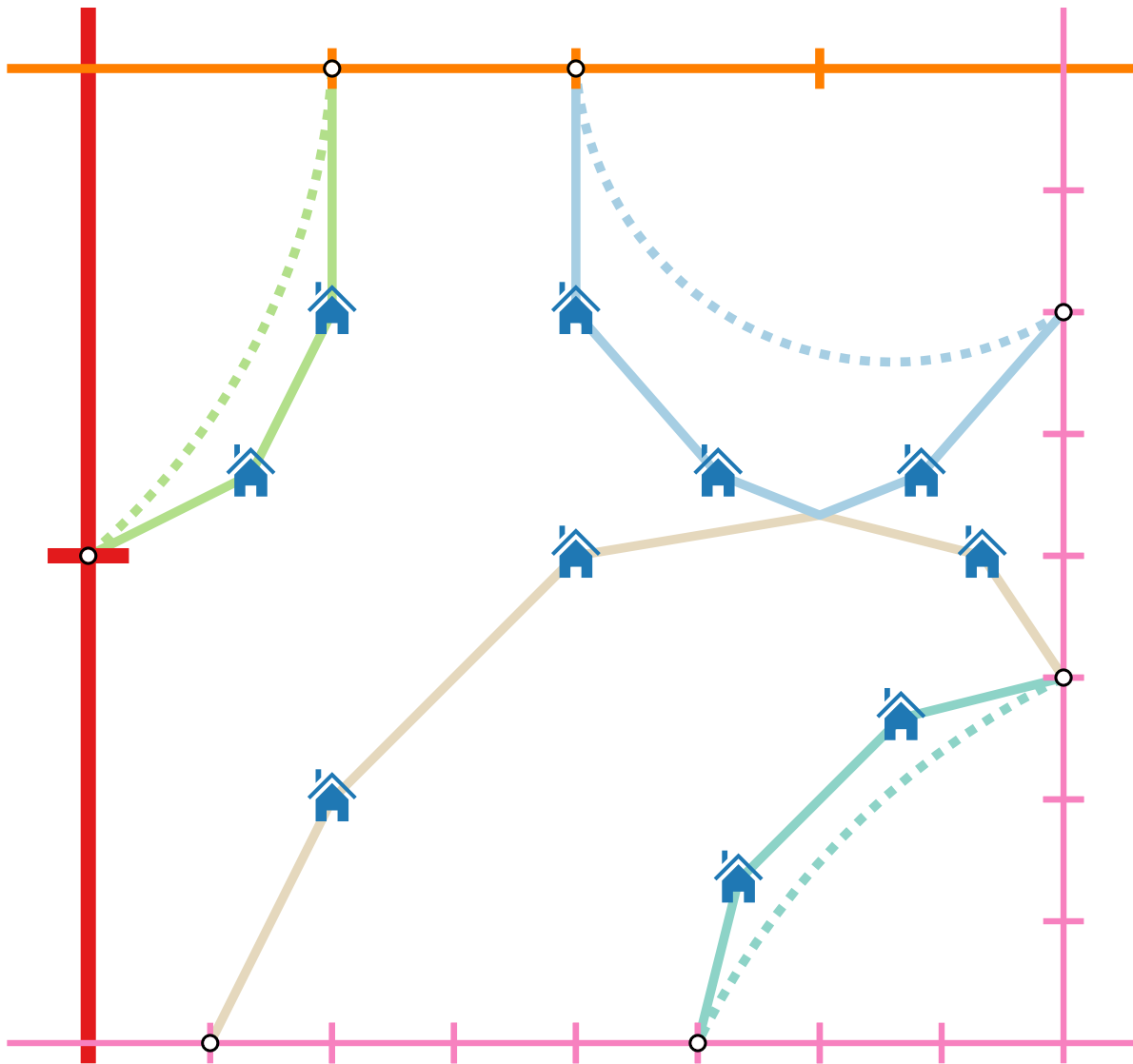
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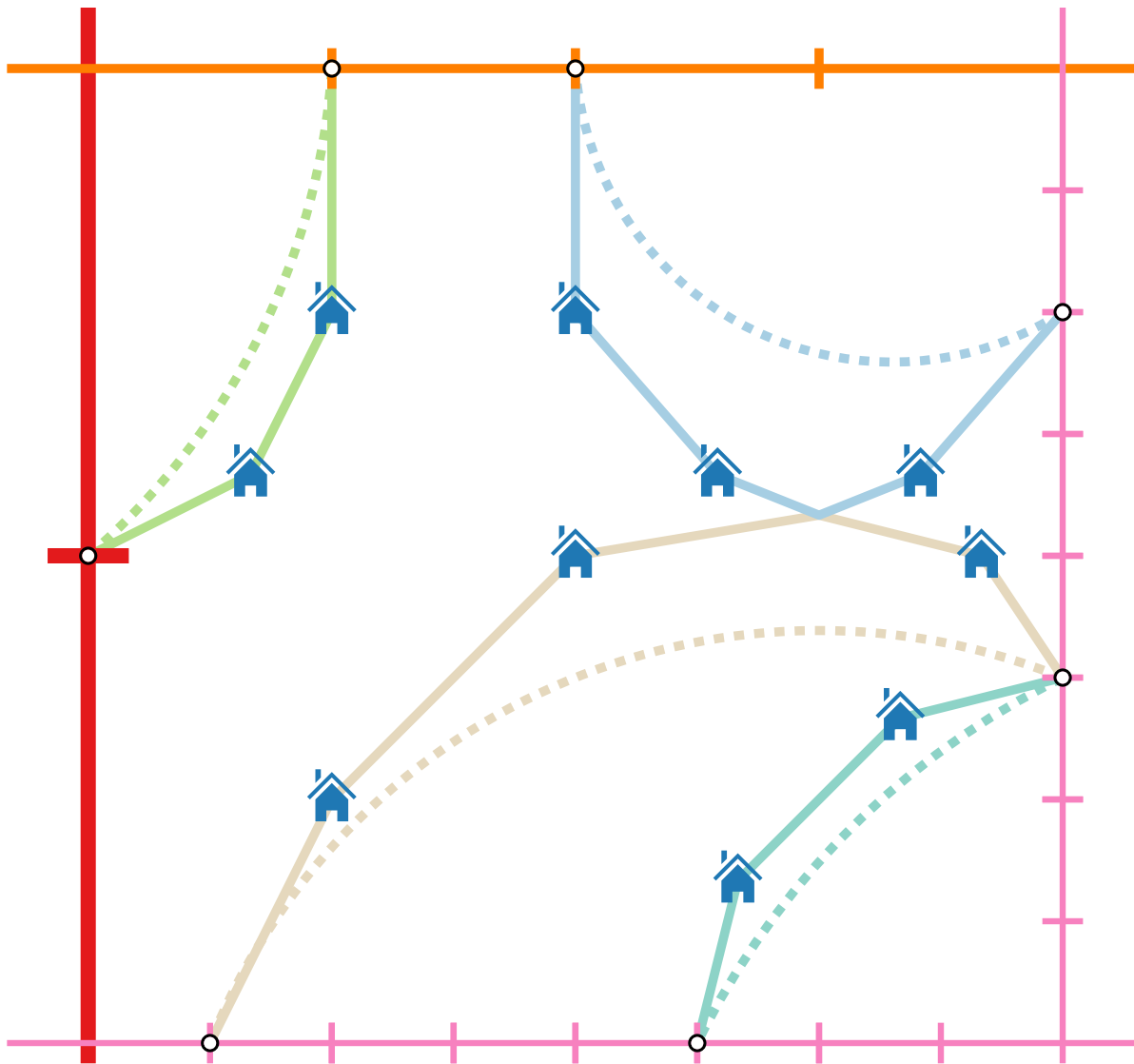
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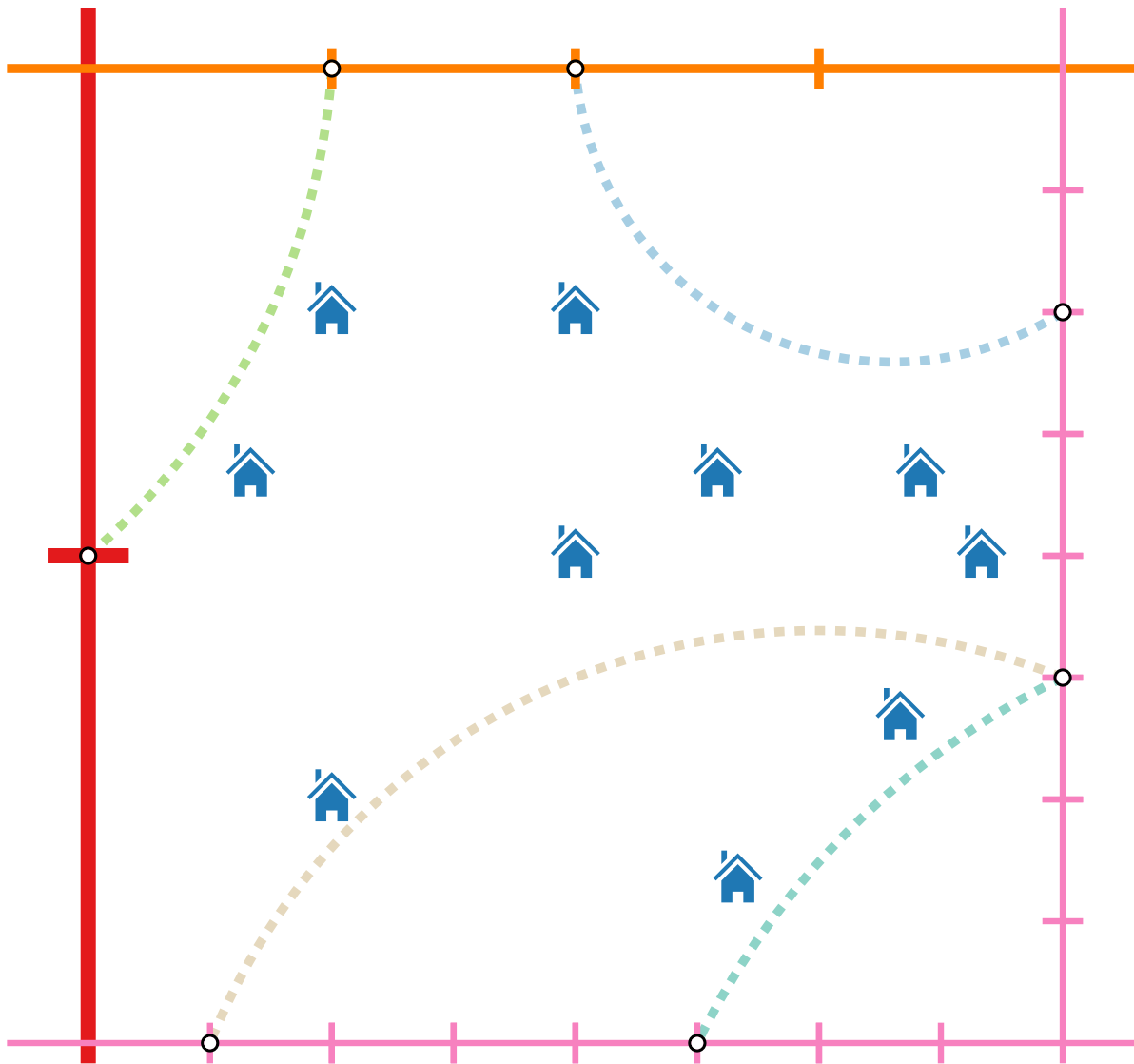
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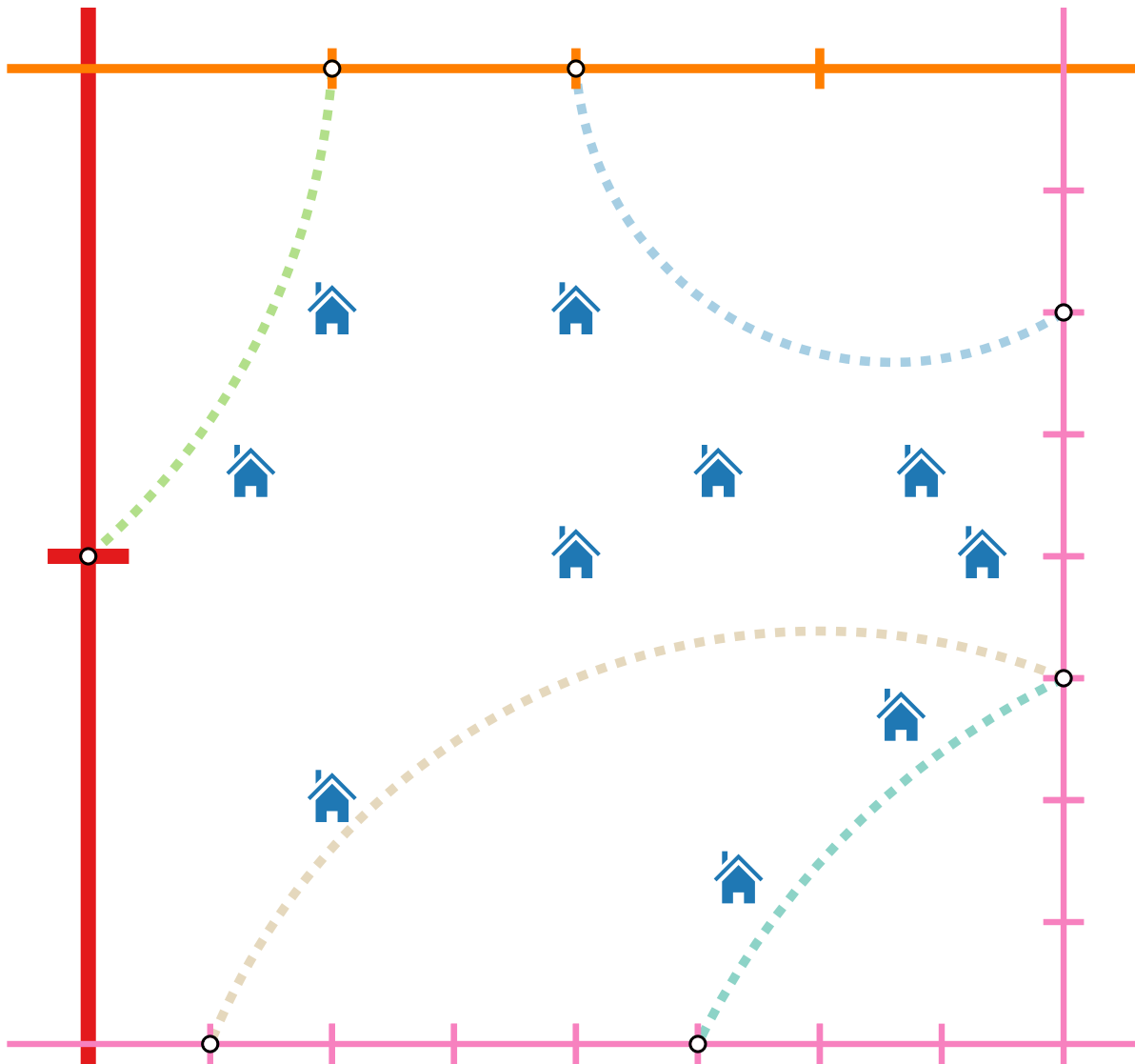
Dynamic Program (I)



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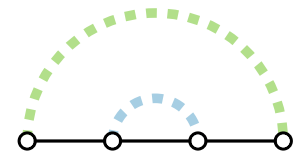
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Dynamic Program (I)

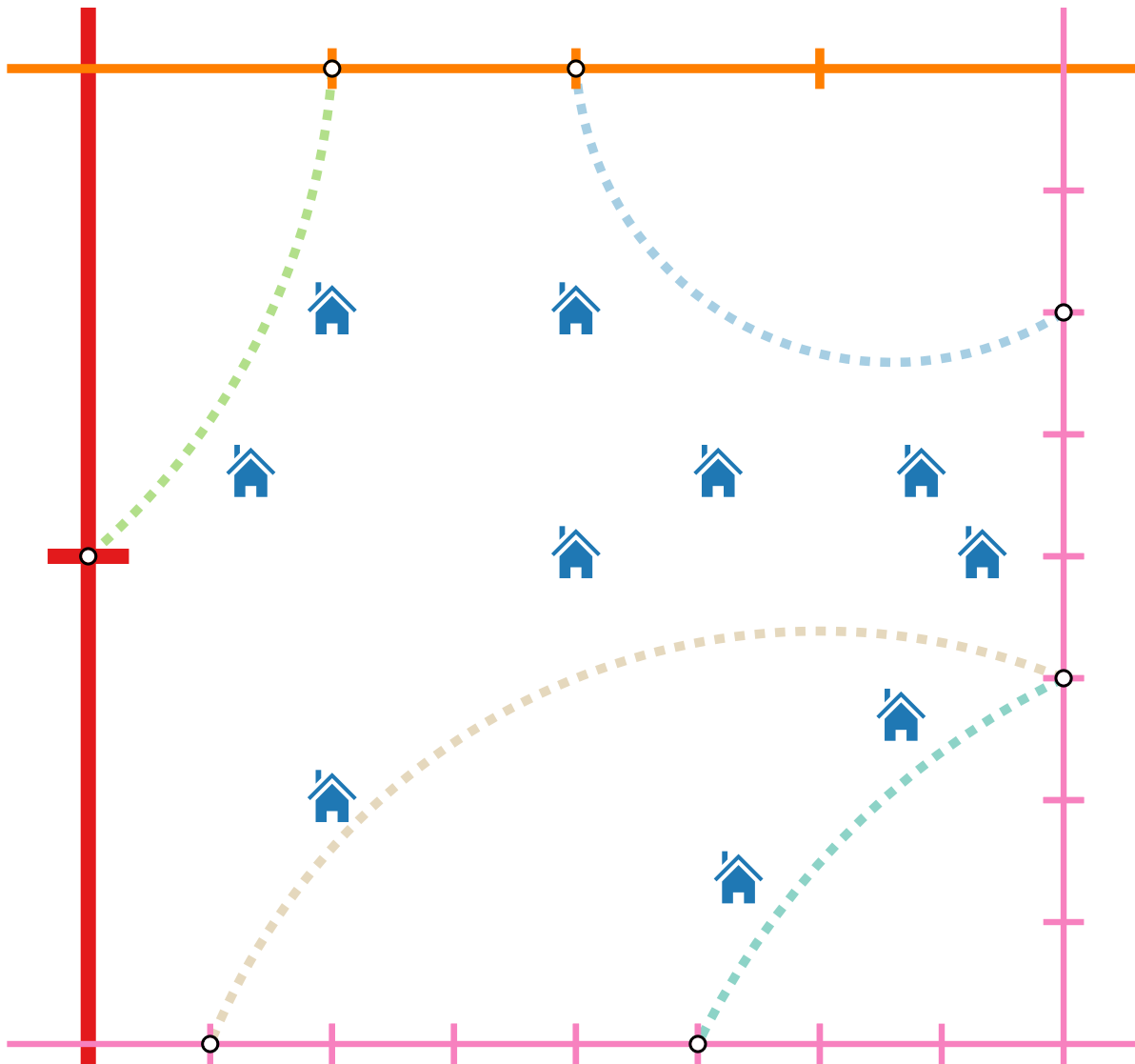


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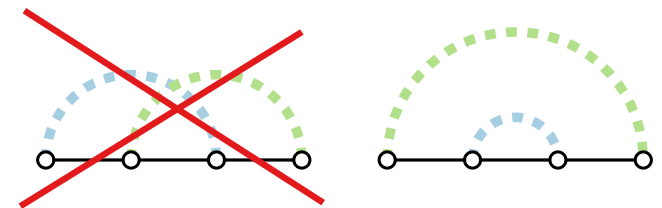


Dynamic Program (I)

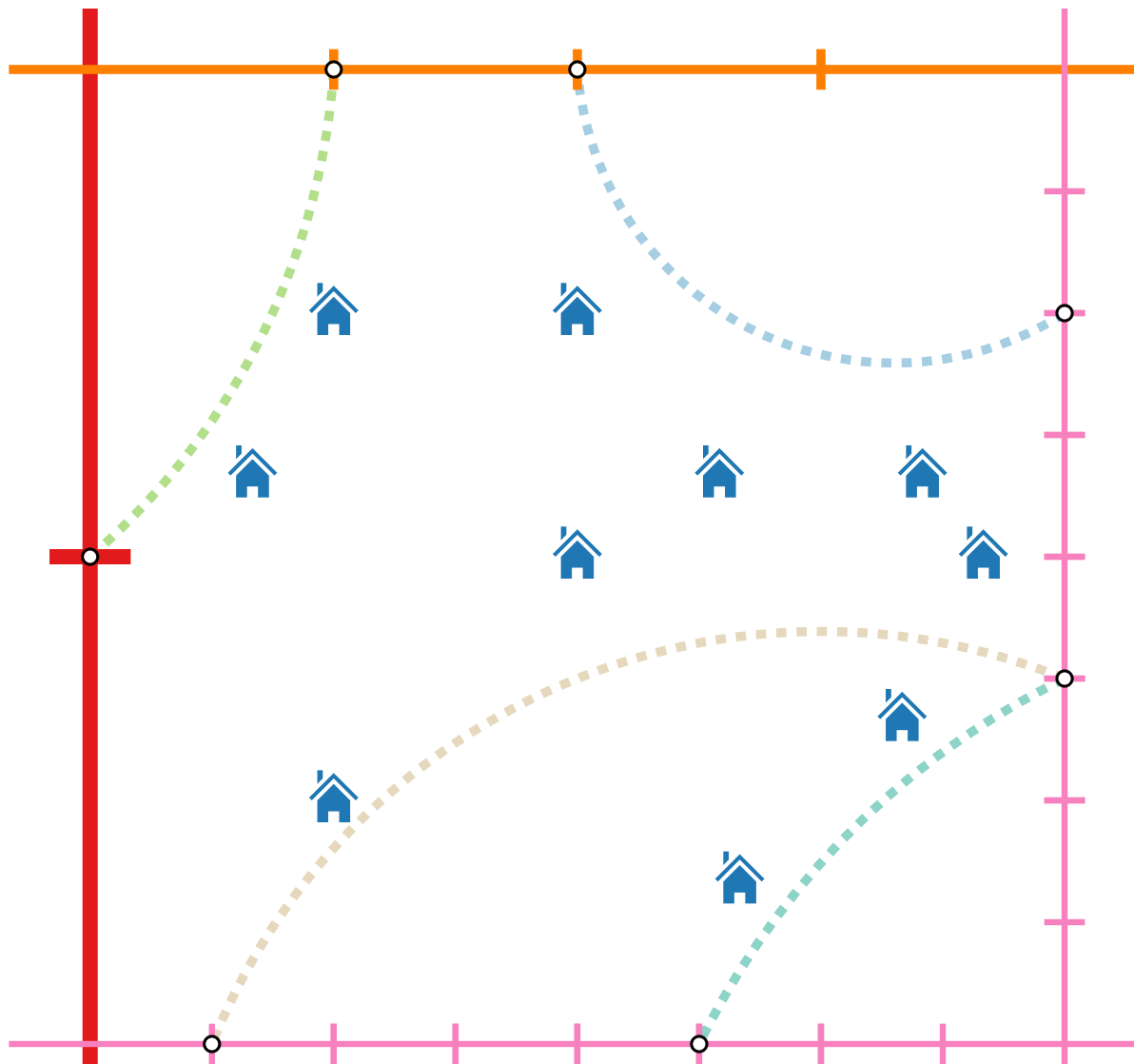


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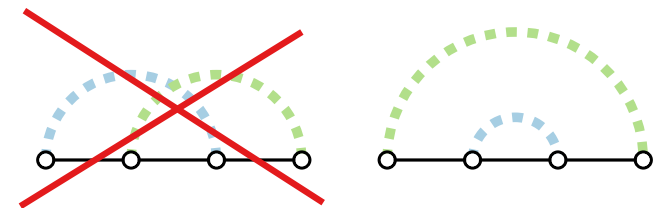
Dynamic Program (I)



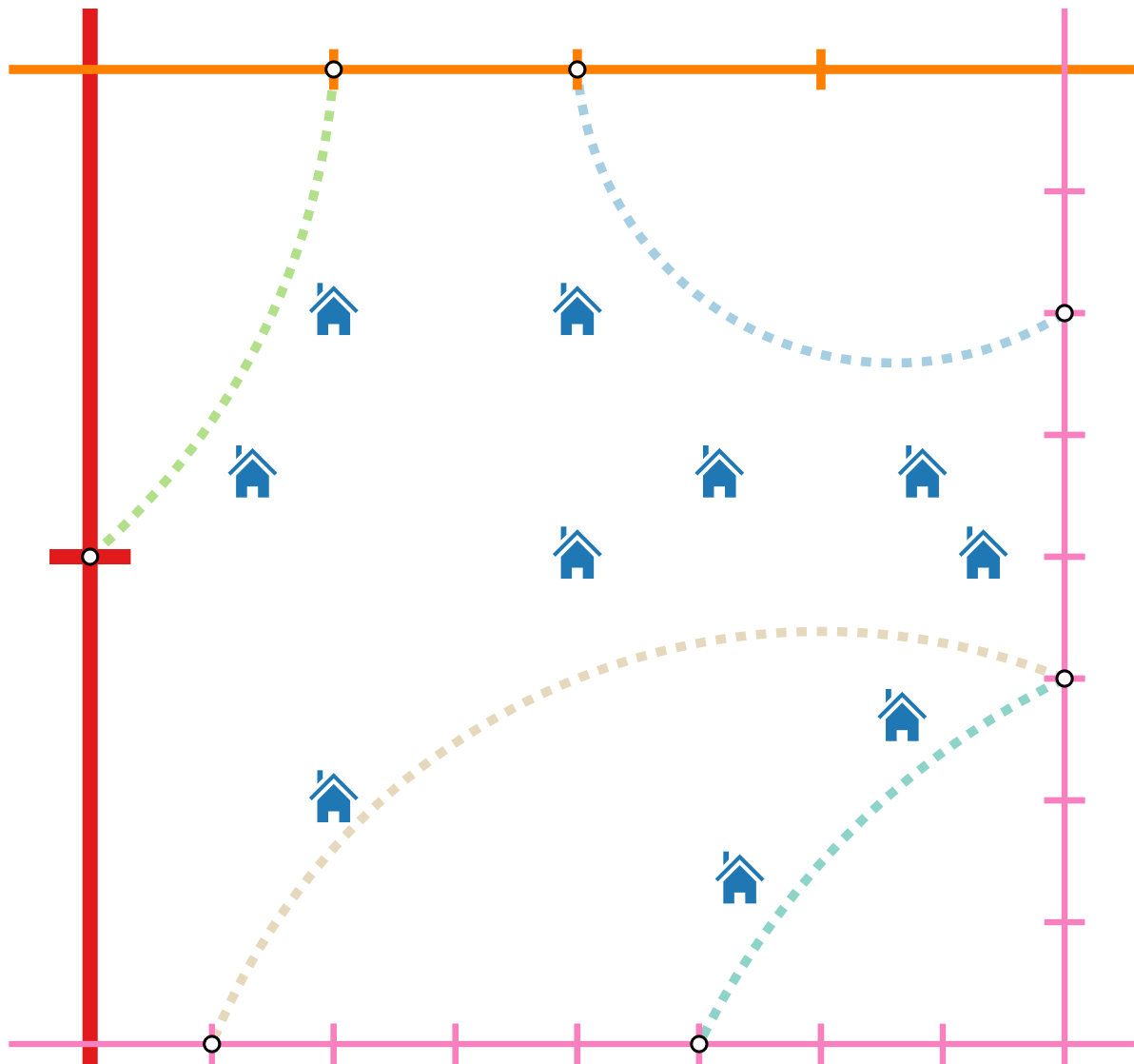
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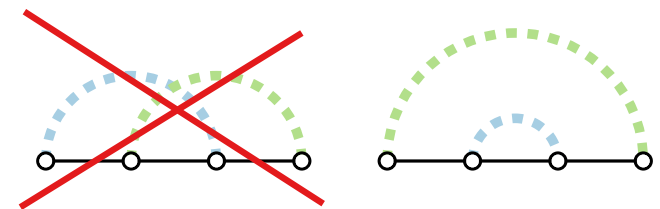


Dynamic Program (I)



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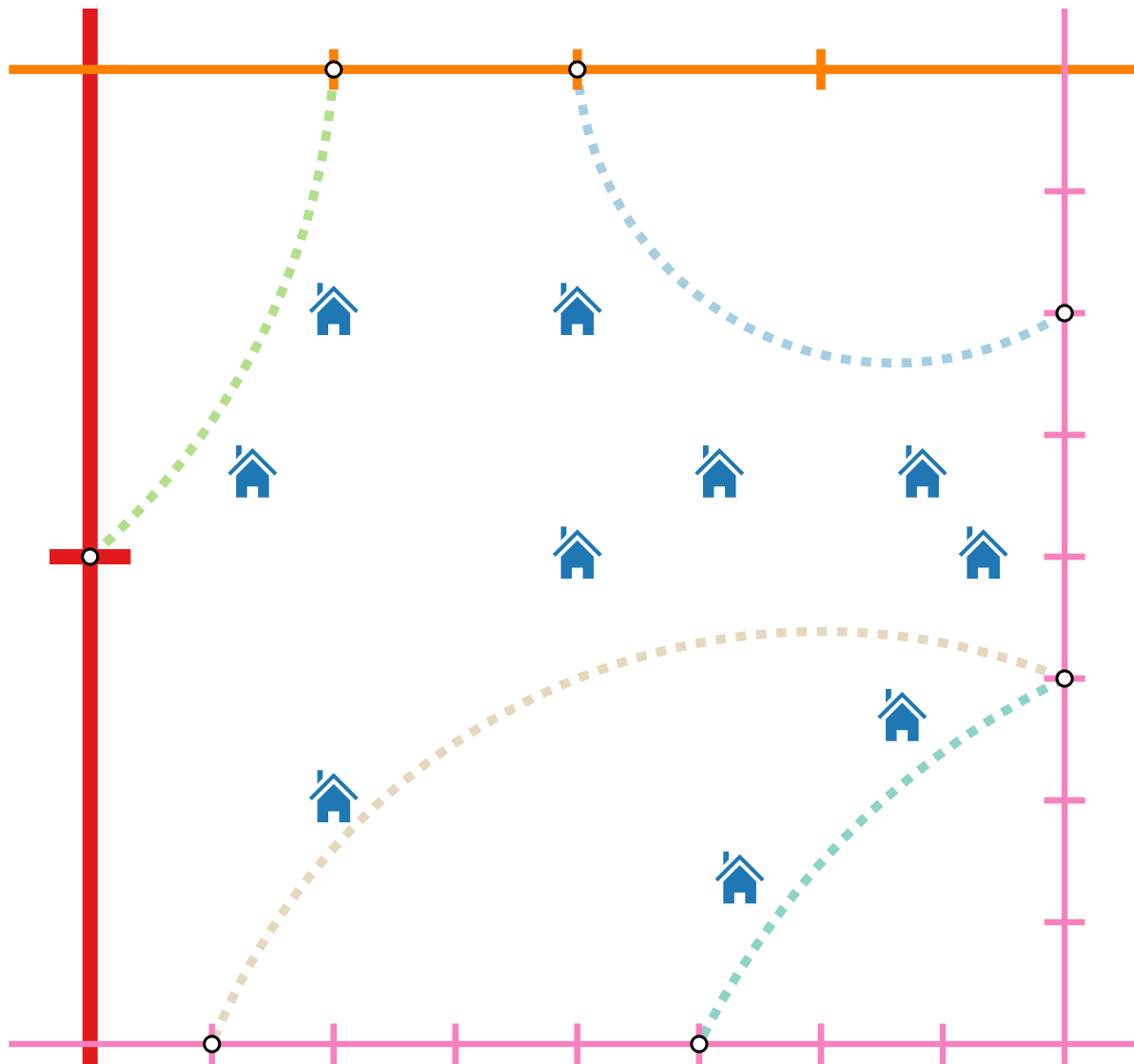
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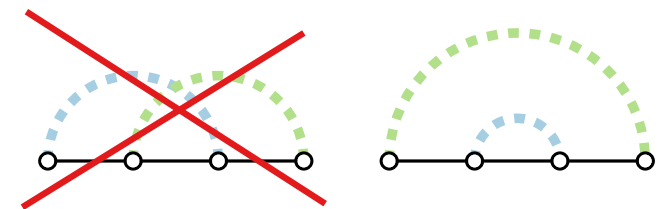
$\underbrace{\hspace{2cm}}$
#visit vectors

Dynamic Program (I)



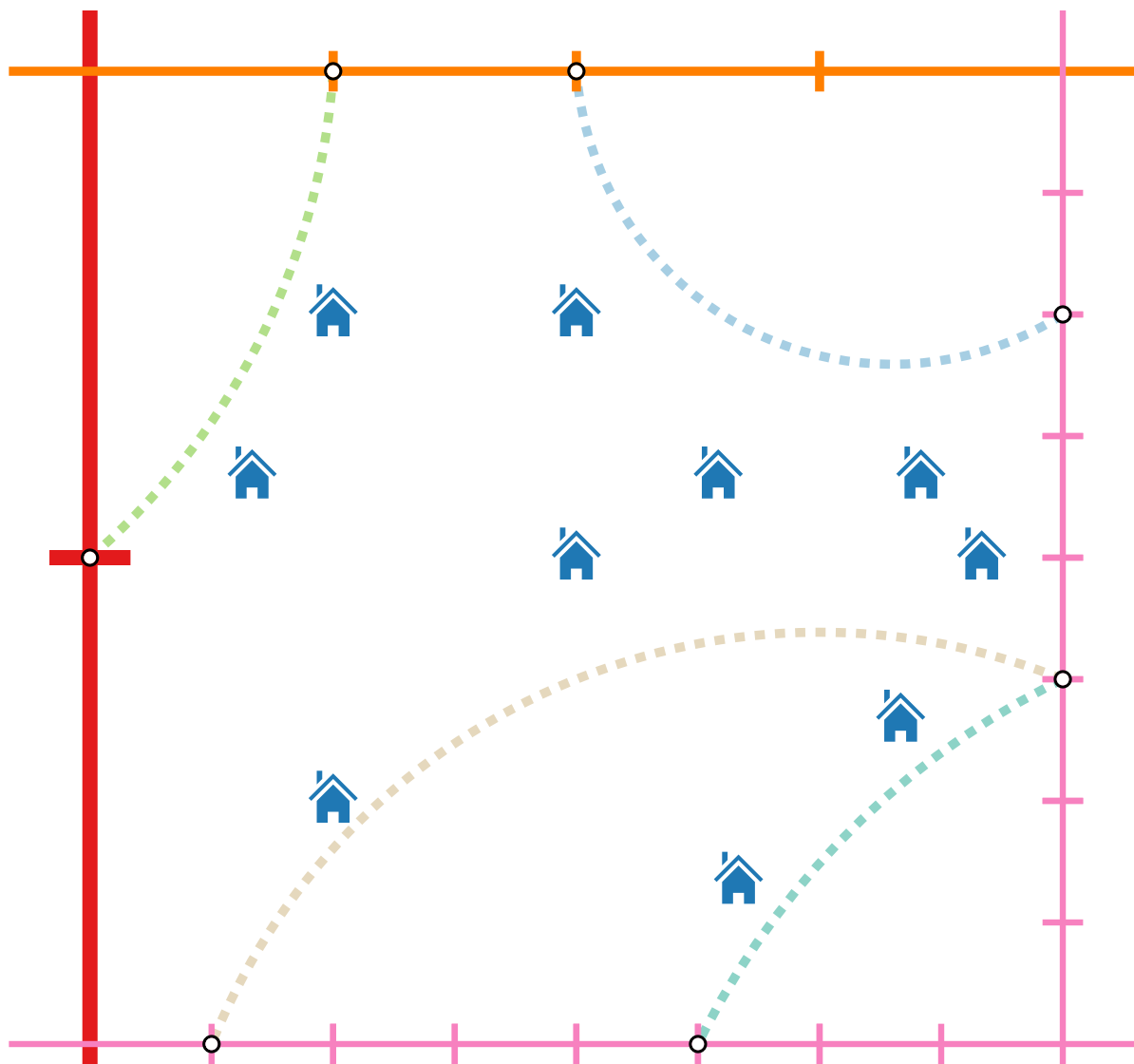
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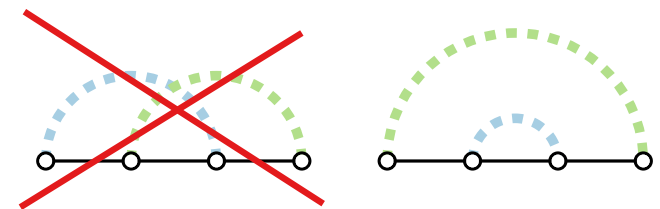
$\Rightarrow \max.$ $\underbrace{\hspace{2cm}}$ \times $\underbrace{\hspace{2cm}}$
 #visit vectors #realizable pairings

Dynamic Program (I)



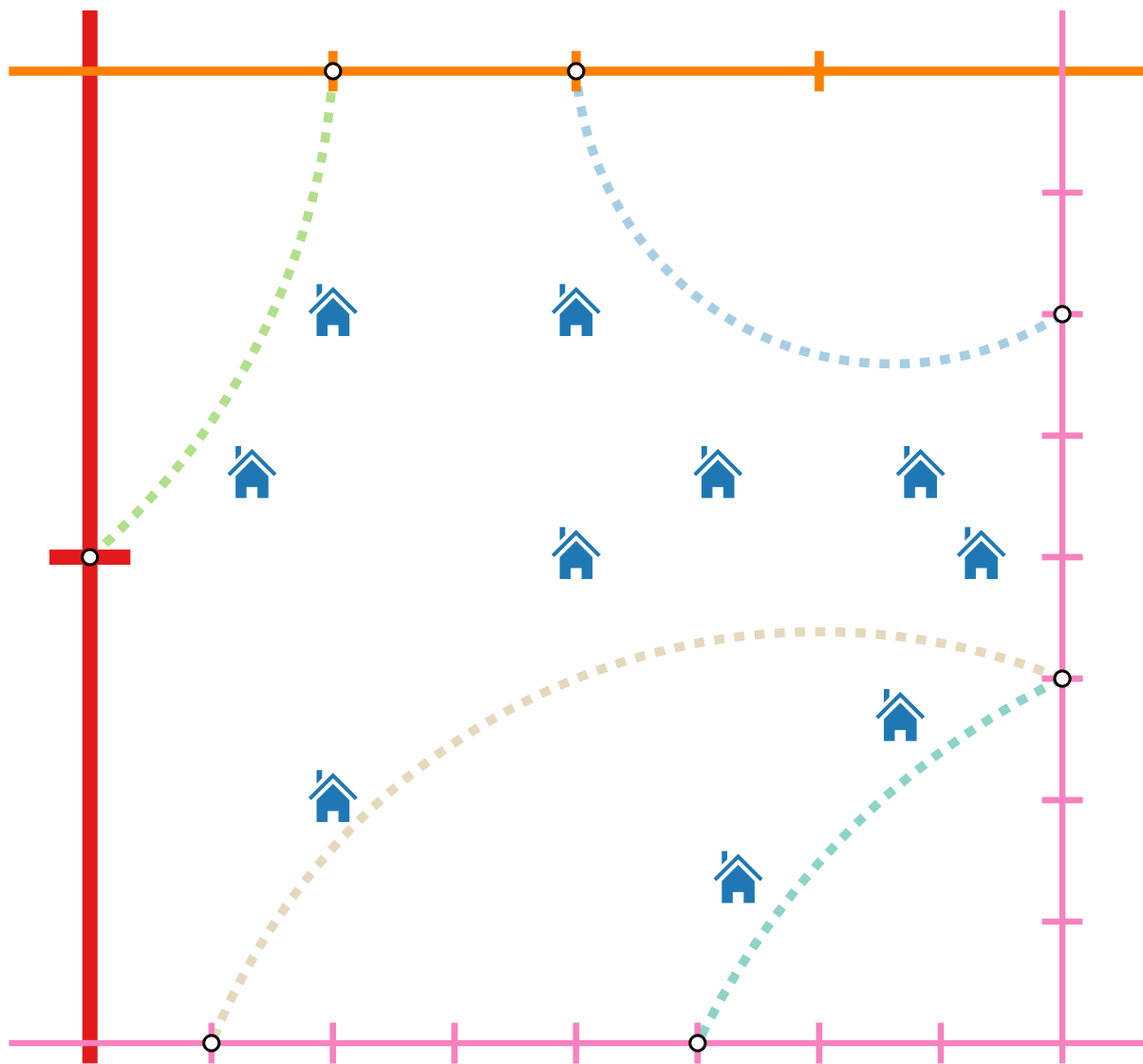
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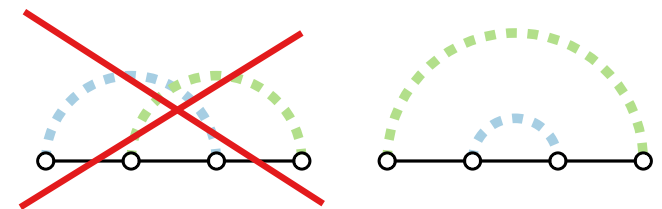
$$\Rightarrow \max. \underbrace{n^{O(1/\varepsilon)}}_{\text{\#visit vectors}} \times \underbrace{\quad}_{\text{\#realizable pairings}}$$

Dynamic Program (I)



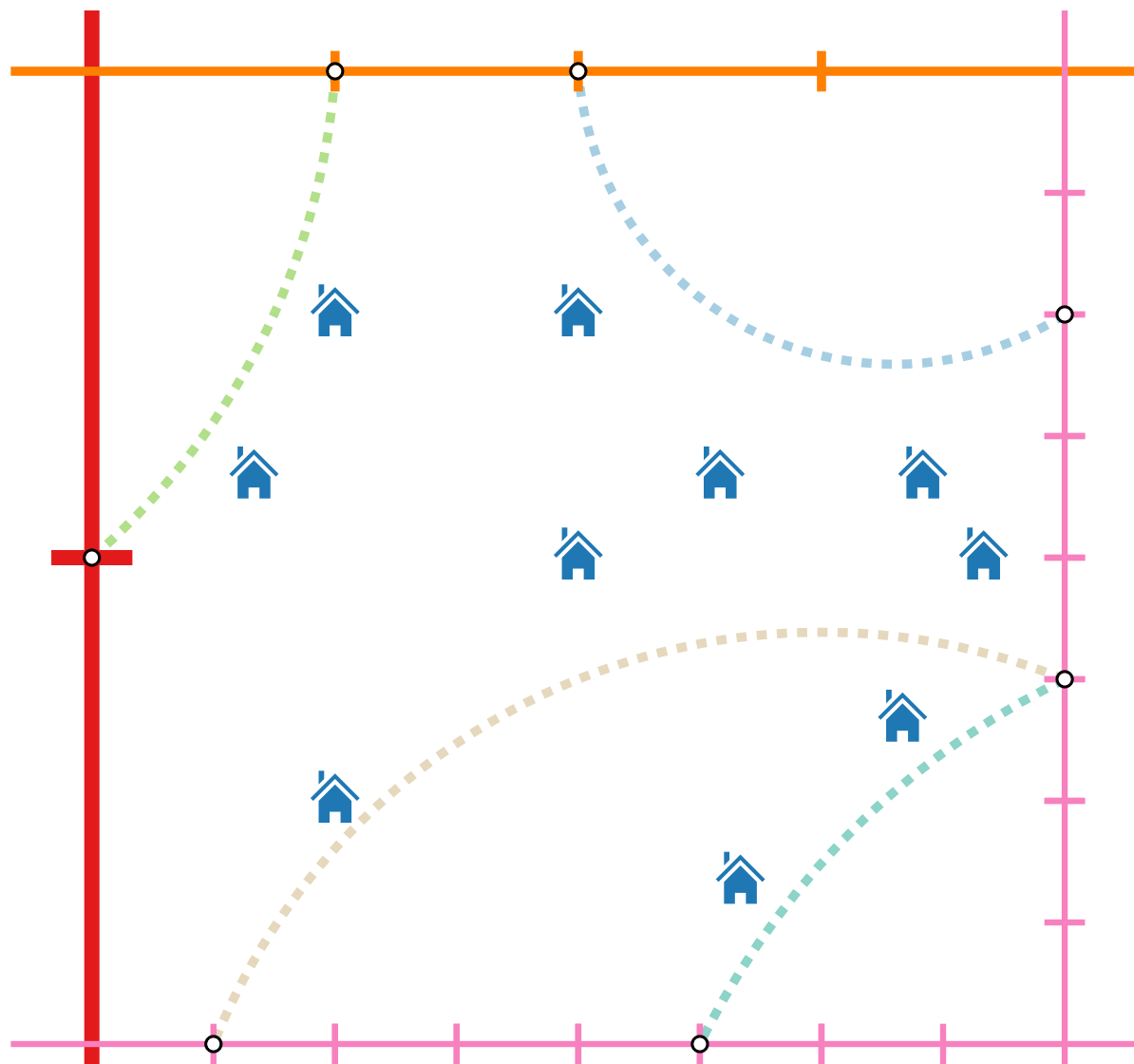
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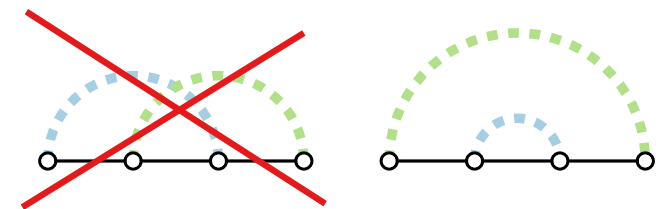
$$\Rightarrow \max. \underbrace{n^{O(1/\varepsilon)}}_{\text{\#visit vectors}} \times \underbrace{2^{O(m)}}_{\text{\#realizable pairings}} =$$

Dynamic Program (I)



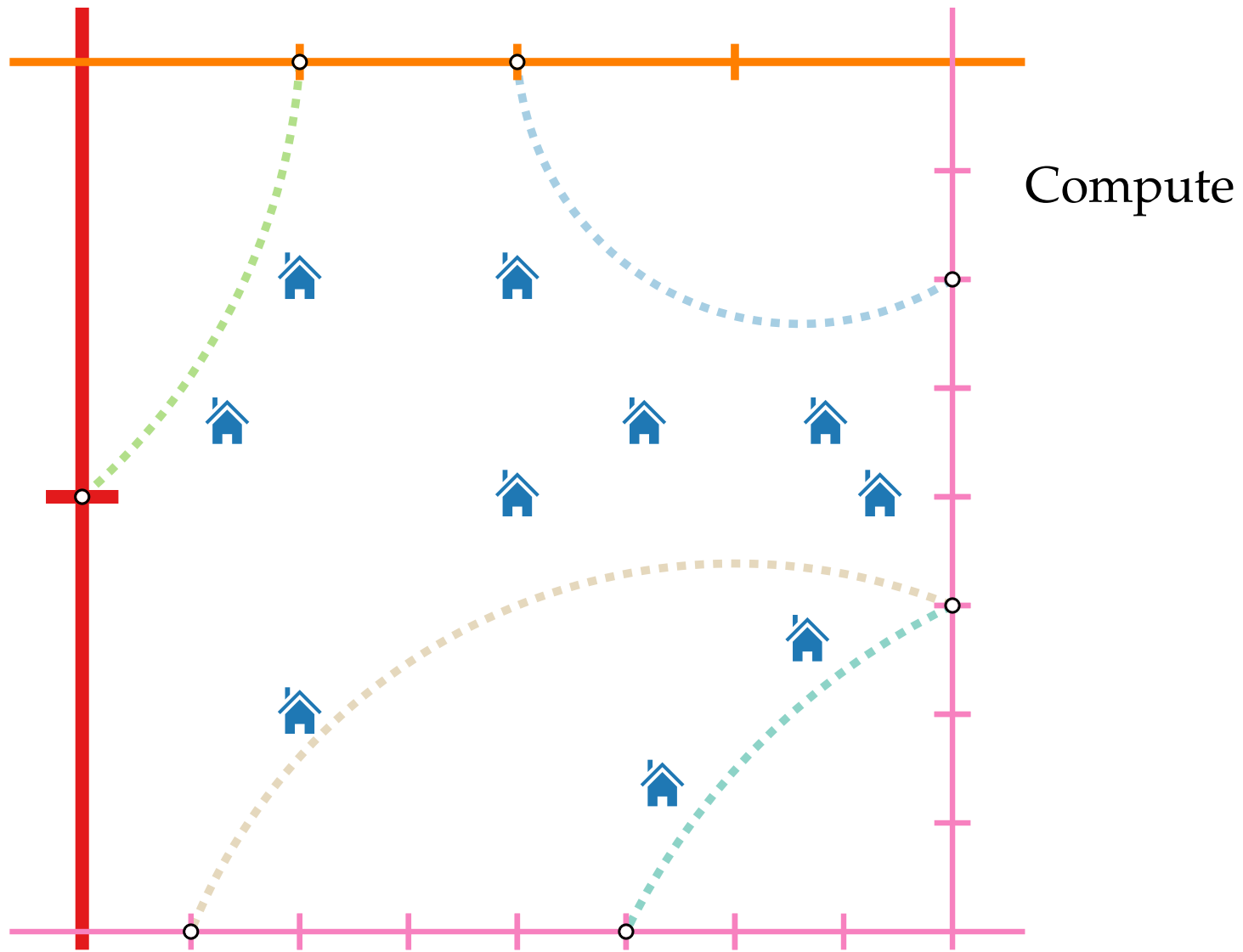
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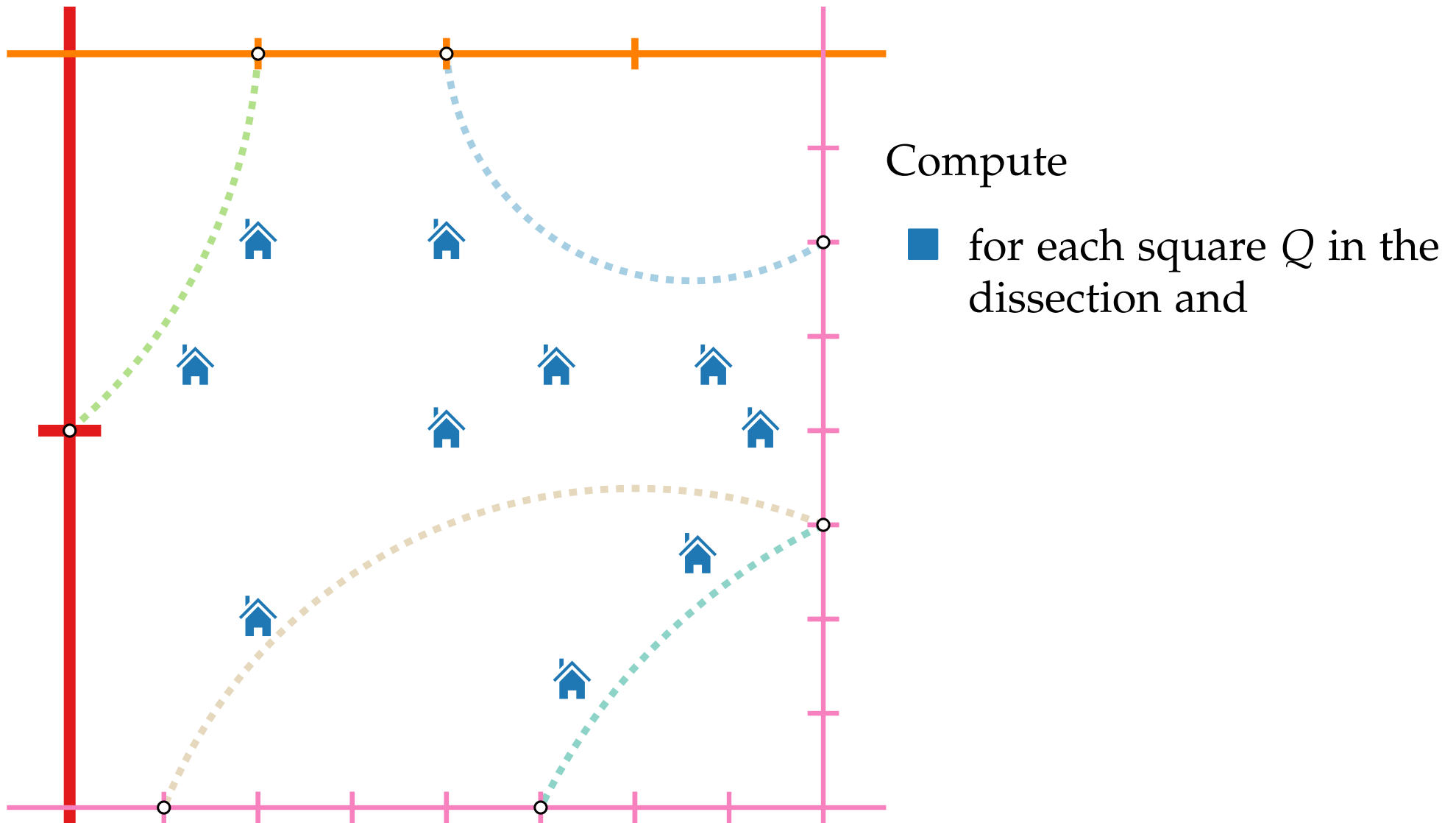


$$\Rightarrow \max. \underbrace{n^{O(1/\varepsilon)}}_{\text{\#visit vectors}} \times \underbrace{2^{O(m)}}_{\text{\#realizable pairings}} = n^{O(1/\varepsilon)} \text{ crossing-free pairings}$$

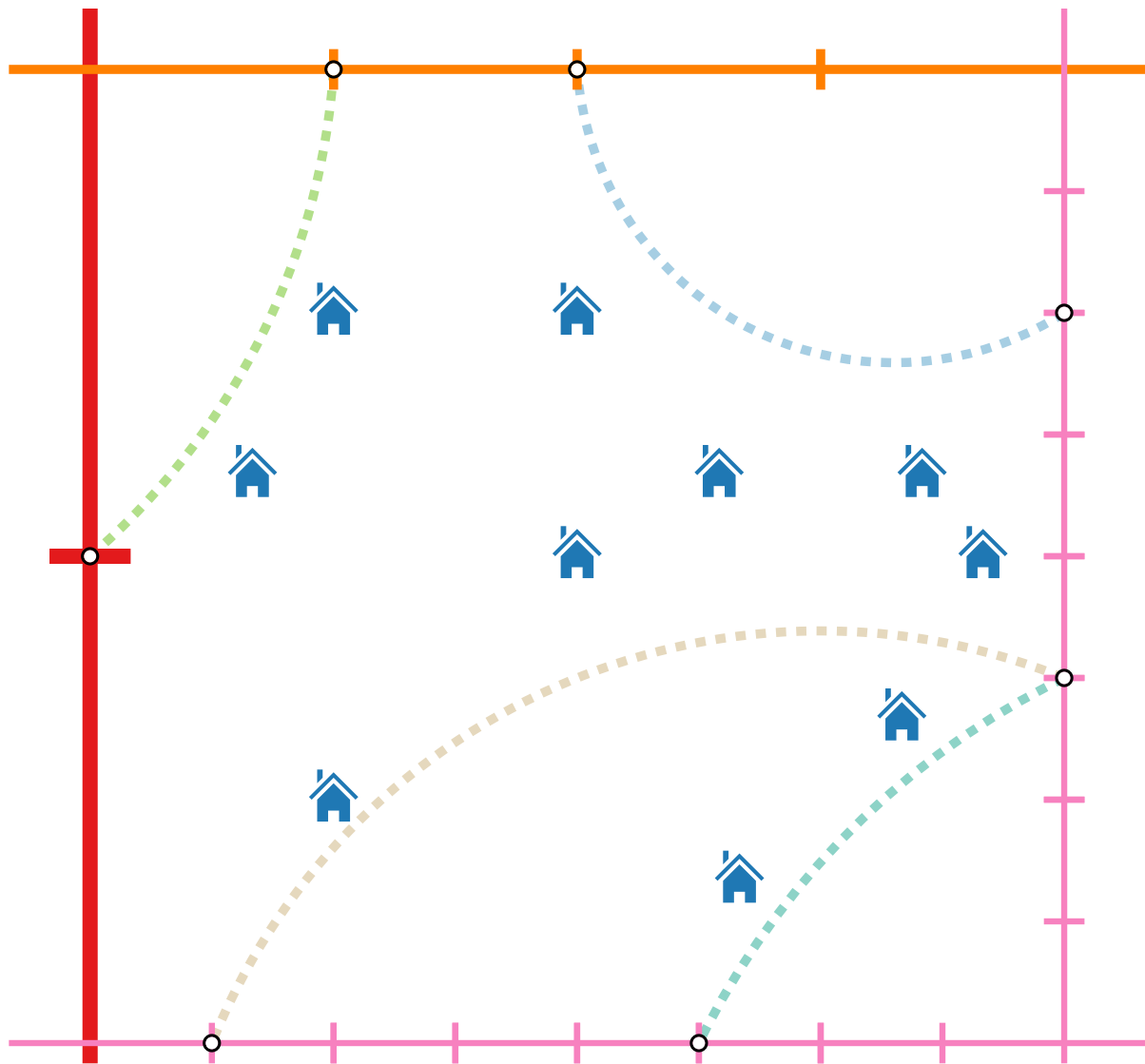
Dynamic Program (II)



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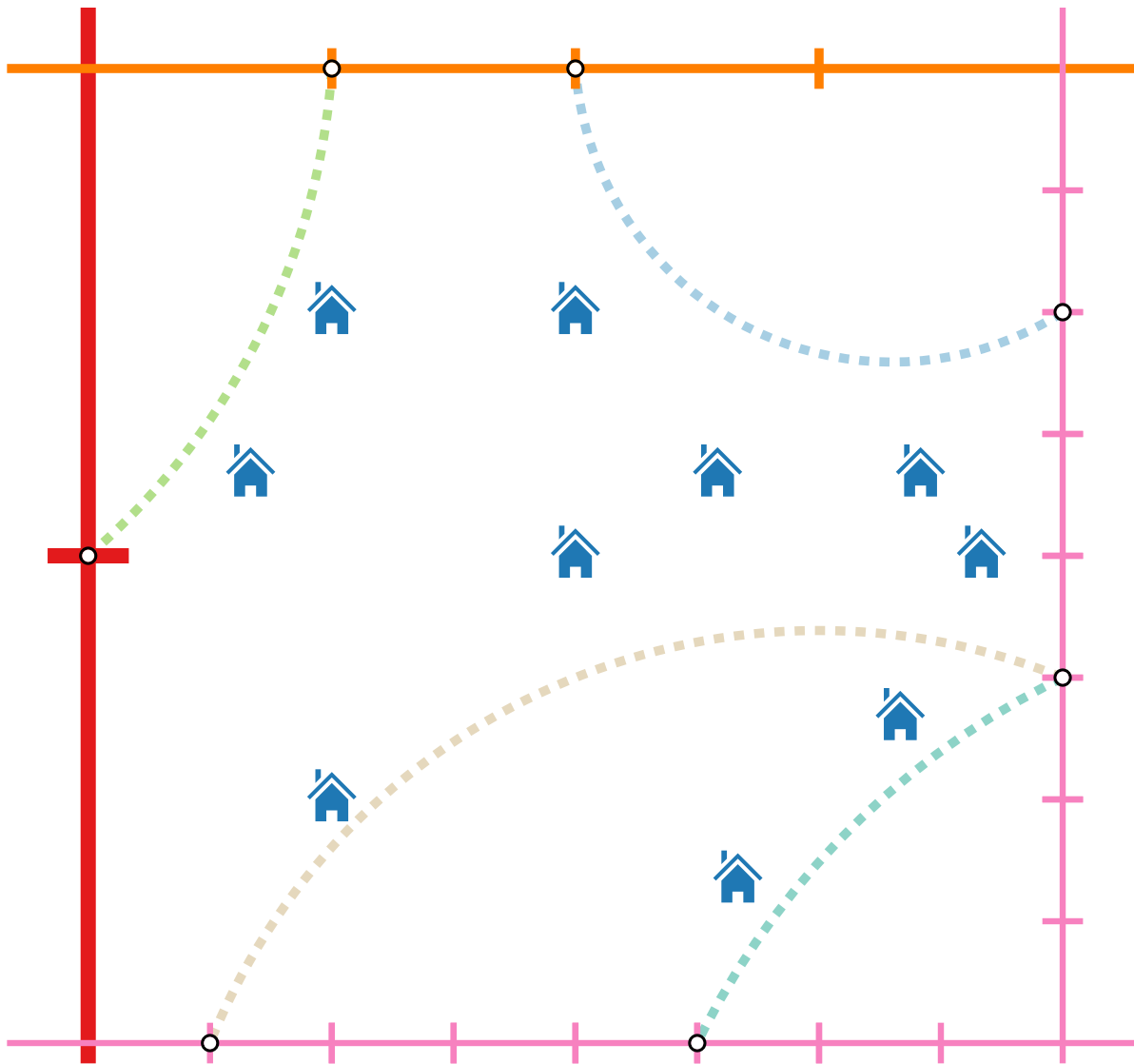
Dynamic Program (II)



Compute

- for each square Q in the dissection and
- for each crossing-free pairing P of Q ,

Dynamic Program (II)

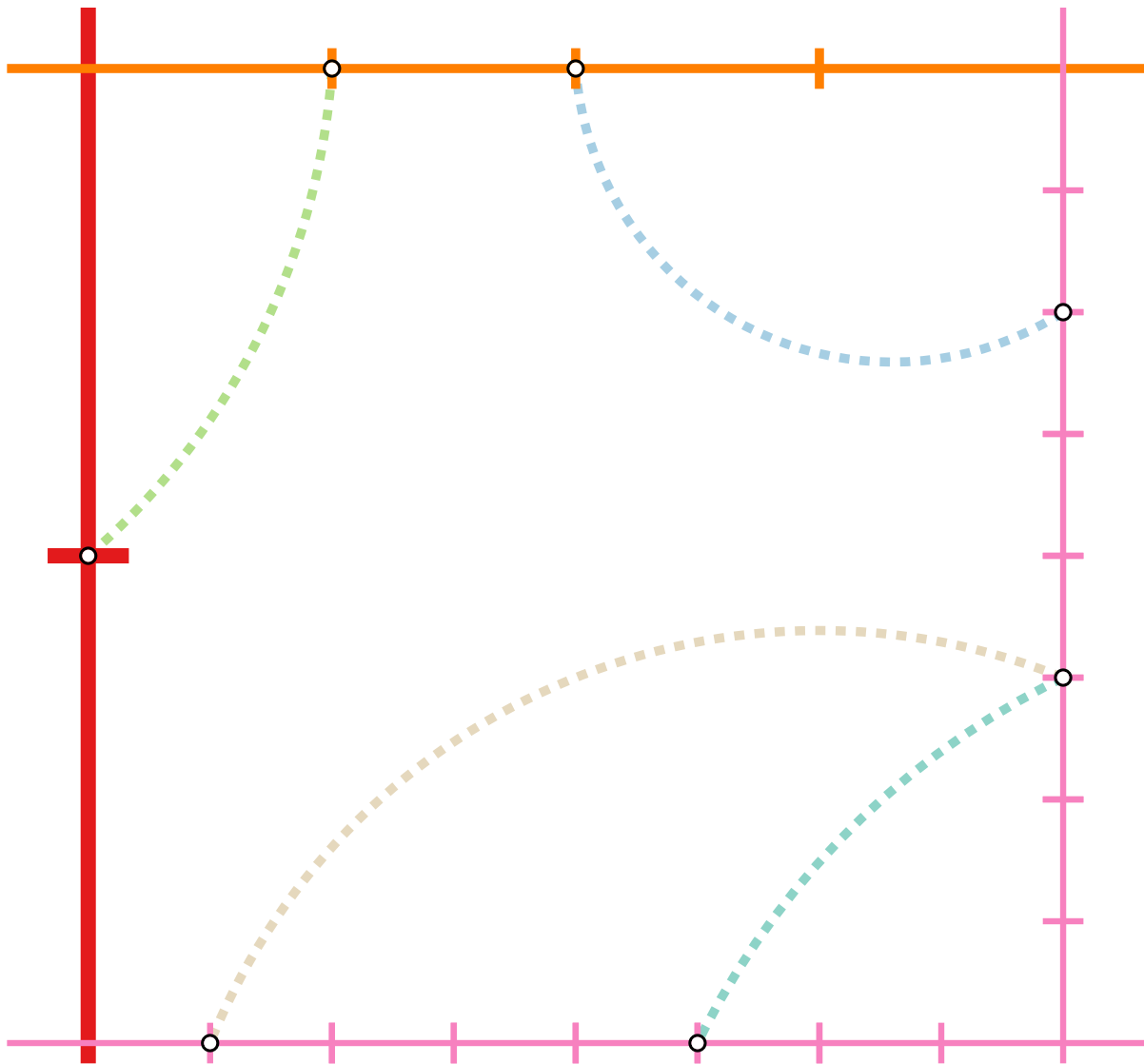


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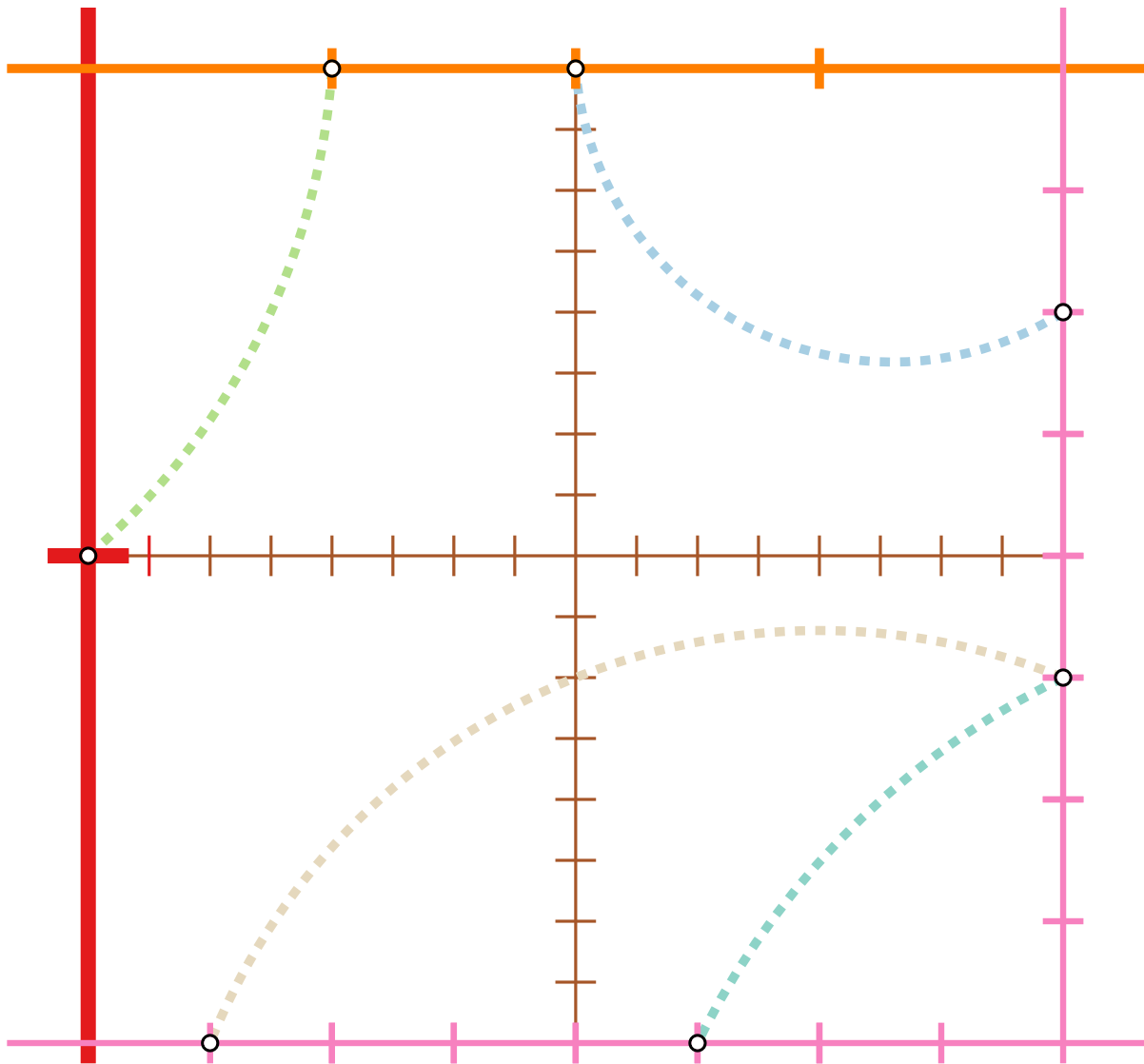
an optimal path cover that respects P .

Dynamic Program (III)



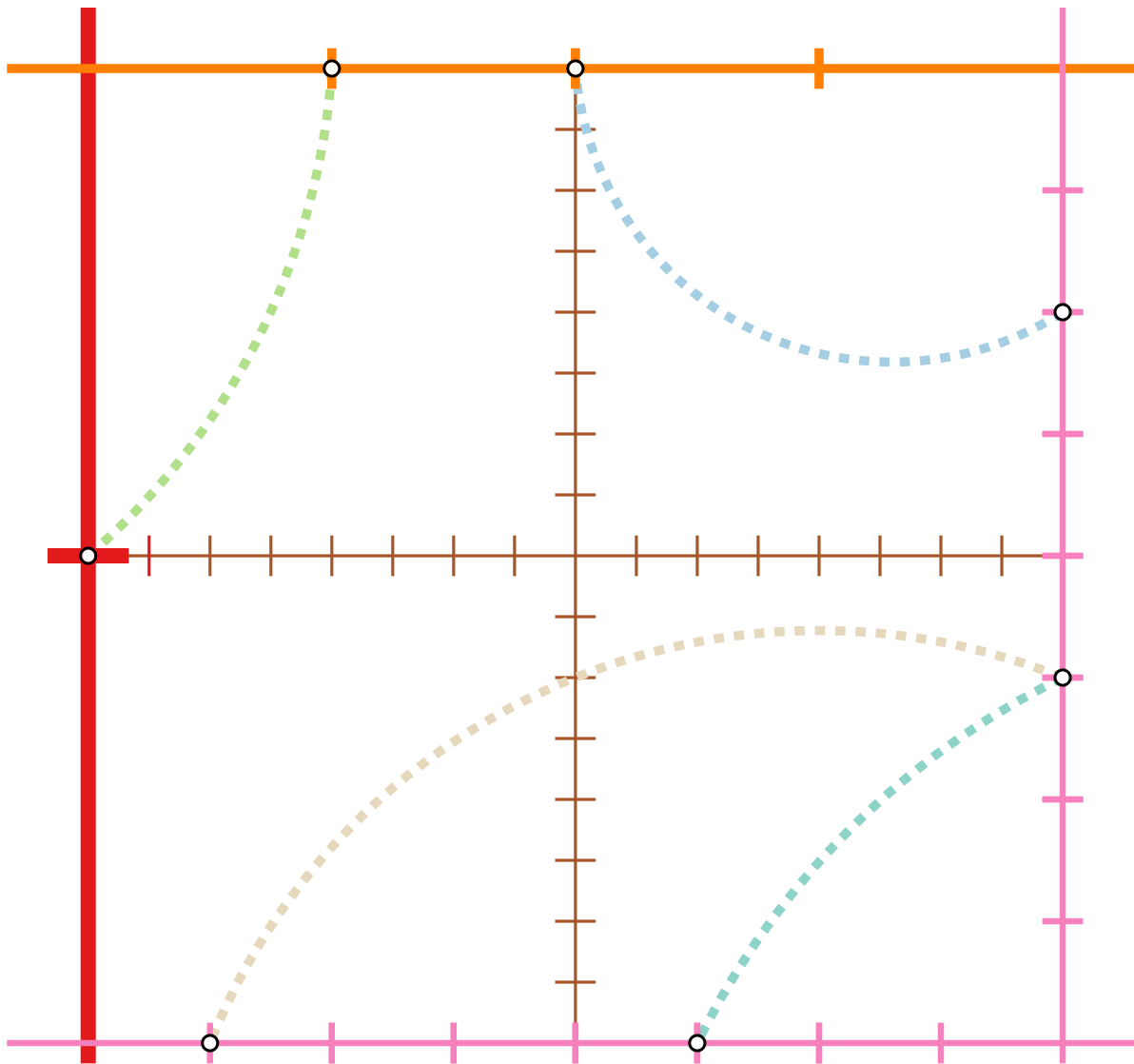
For a given square Q and pairing P :

Dynamic Program (III)



For a given square Q and pairing P :

Dynamic Program (III)

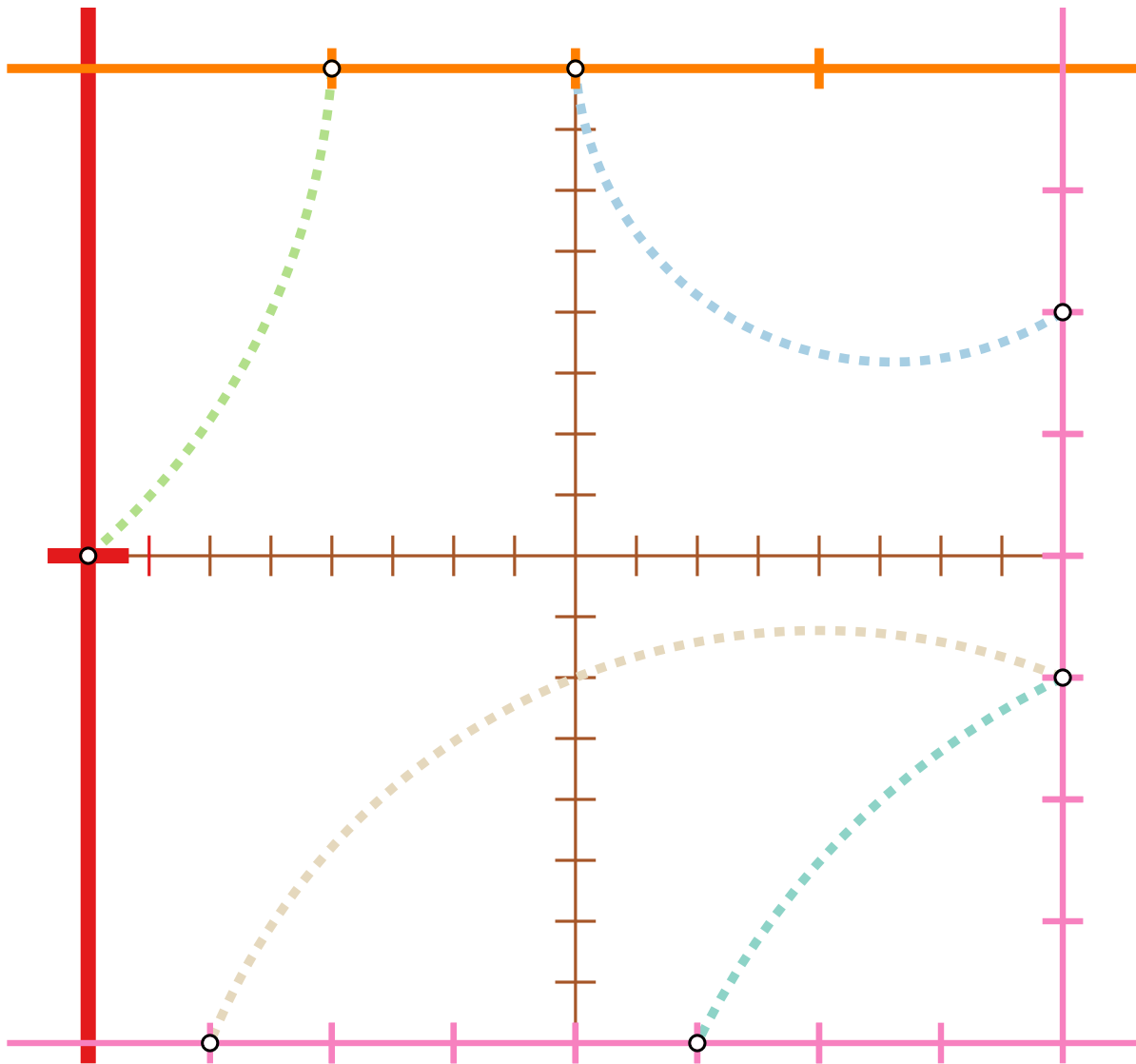


For a given square Q and pairing P :

■ Iterate over all

crossing-free pairings of the child squares.

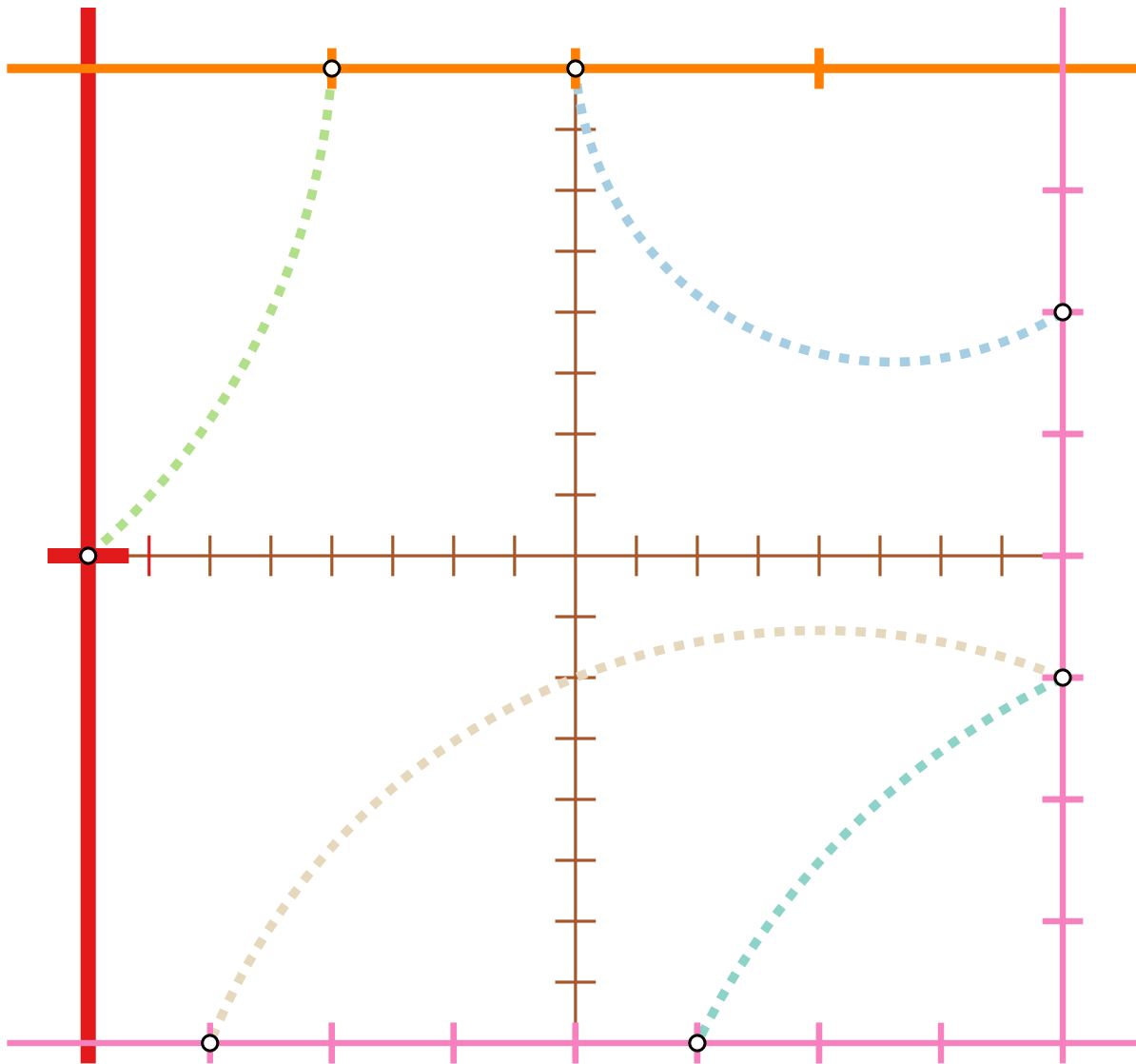
Dynamic Program (III)



For a given square Q and pairing P :

- Iterate over all $(n^{O(1/\varepsilon)})^4 =$ crossing-free pairings of the child squares.

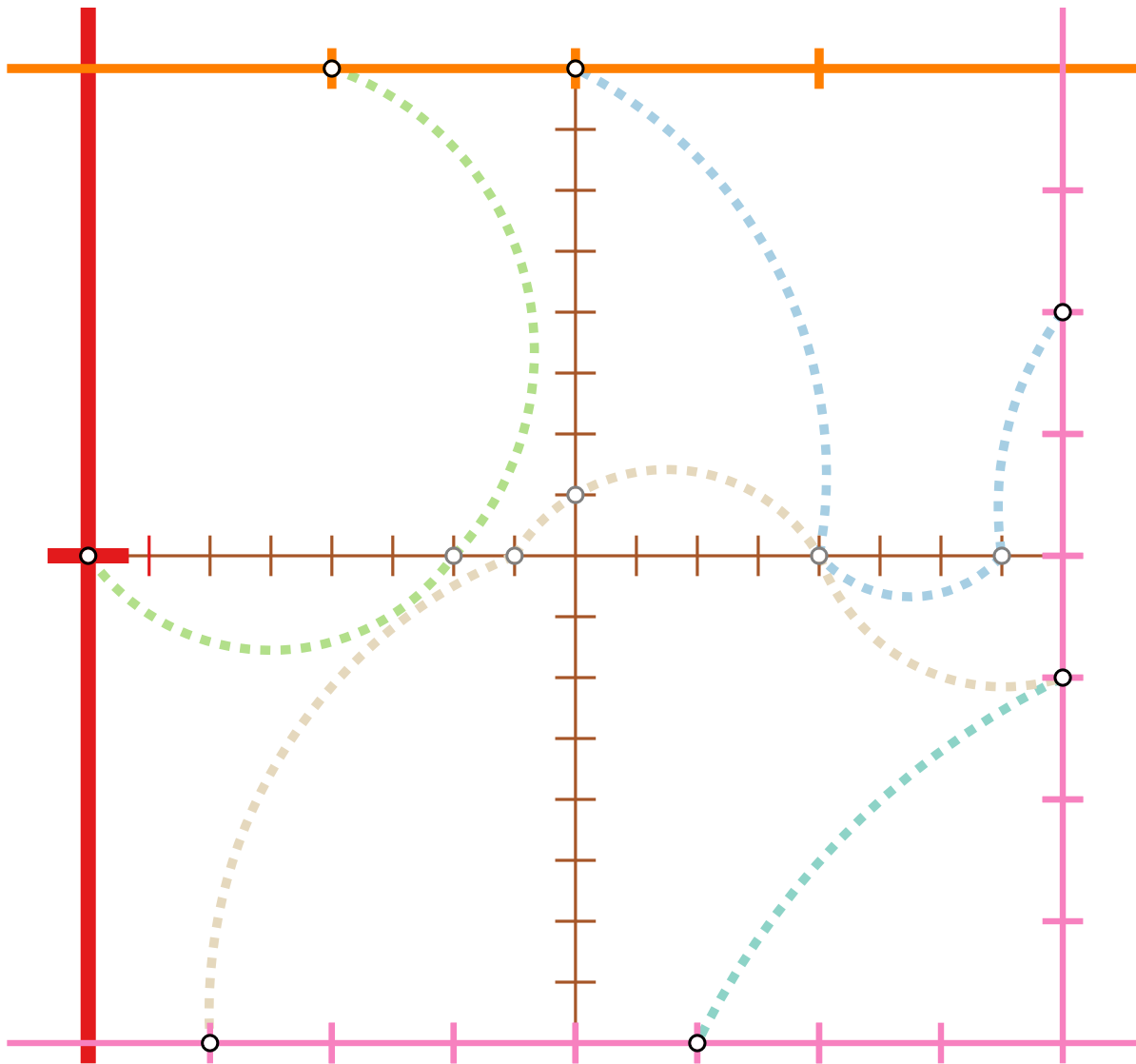
Dynamic Program (III)



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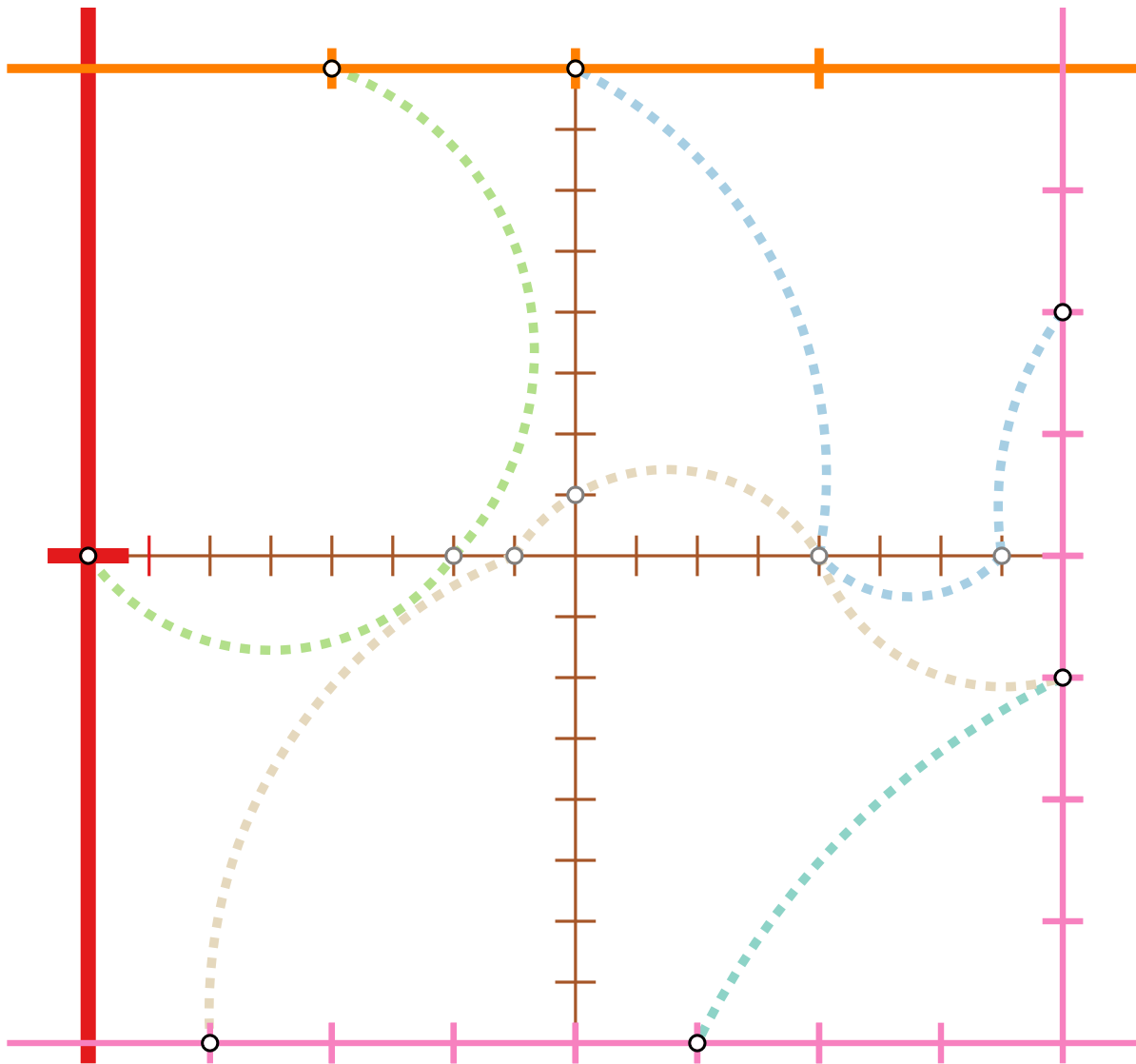
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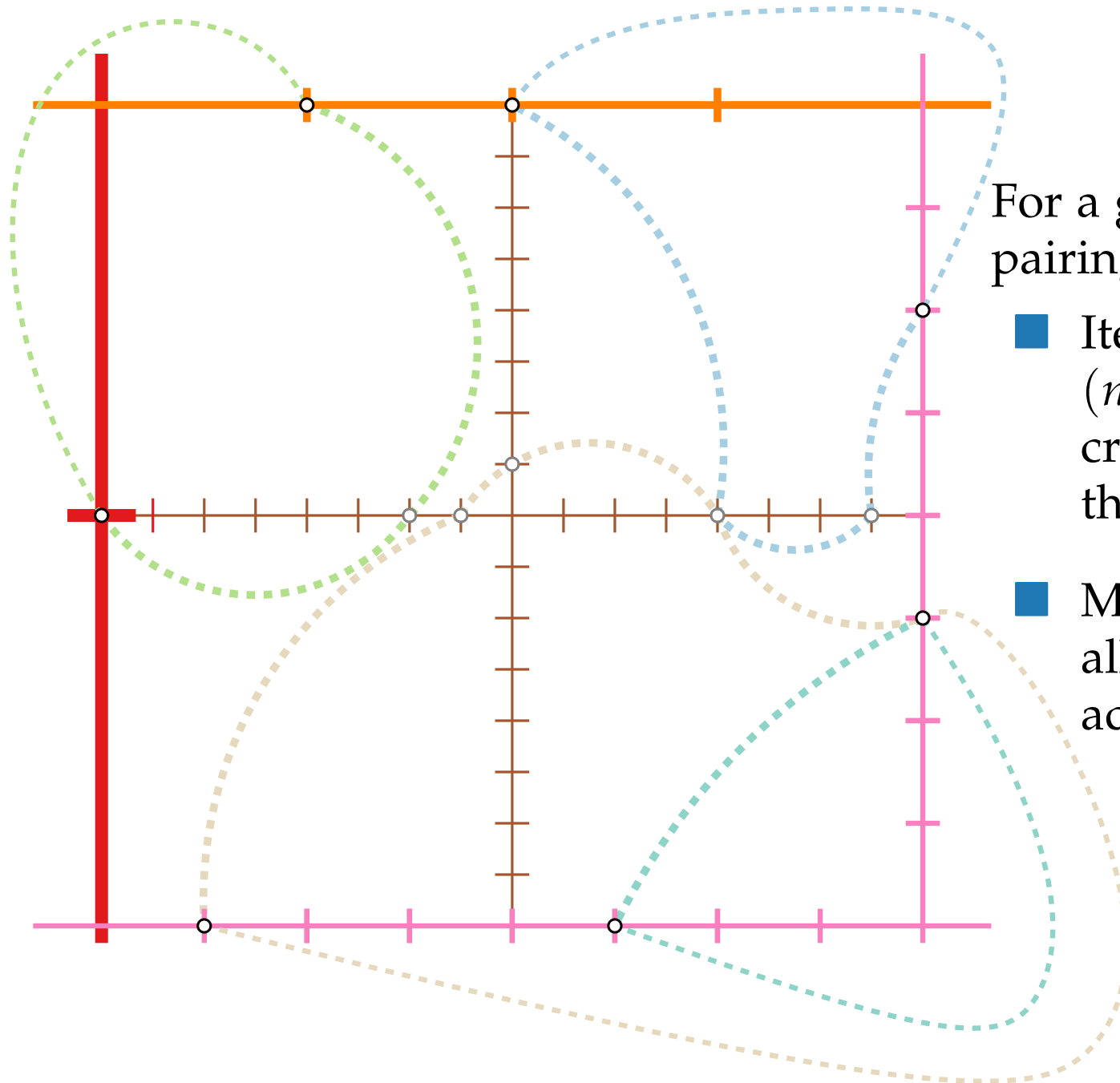
Dynamic Program (III)



For a given square Q and pairing P :

- Iterate over all $(n^{O(1/\varepsilon)})^4 = n^{O(1/\varepsilon)}$ crossing-free pairings of the child squares.
- Minimize the cost over all such pairings that additionally respect P .

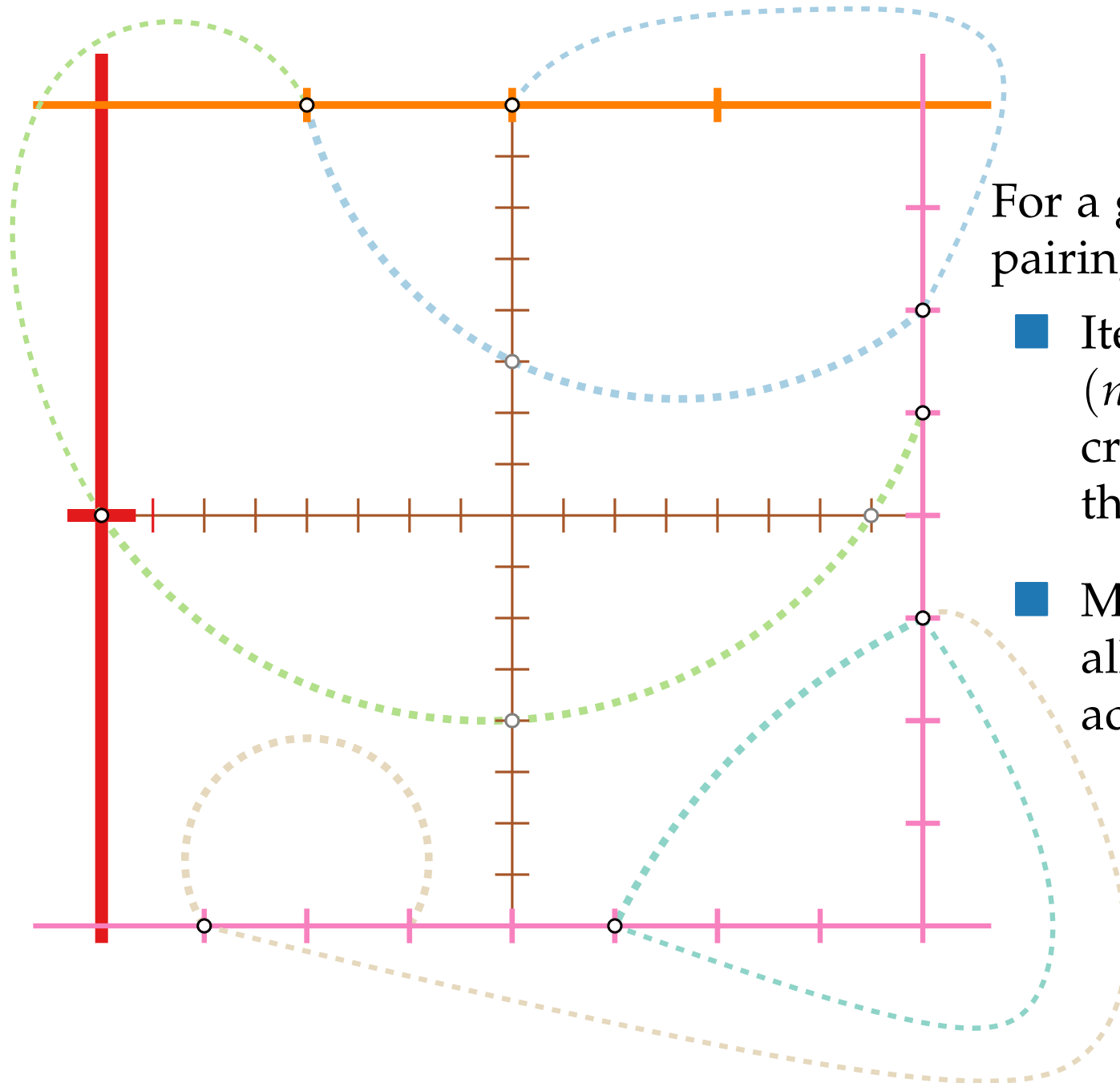
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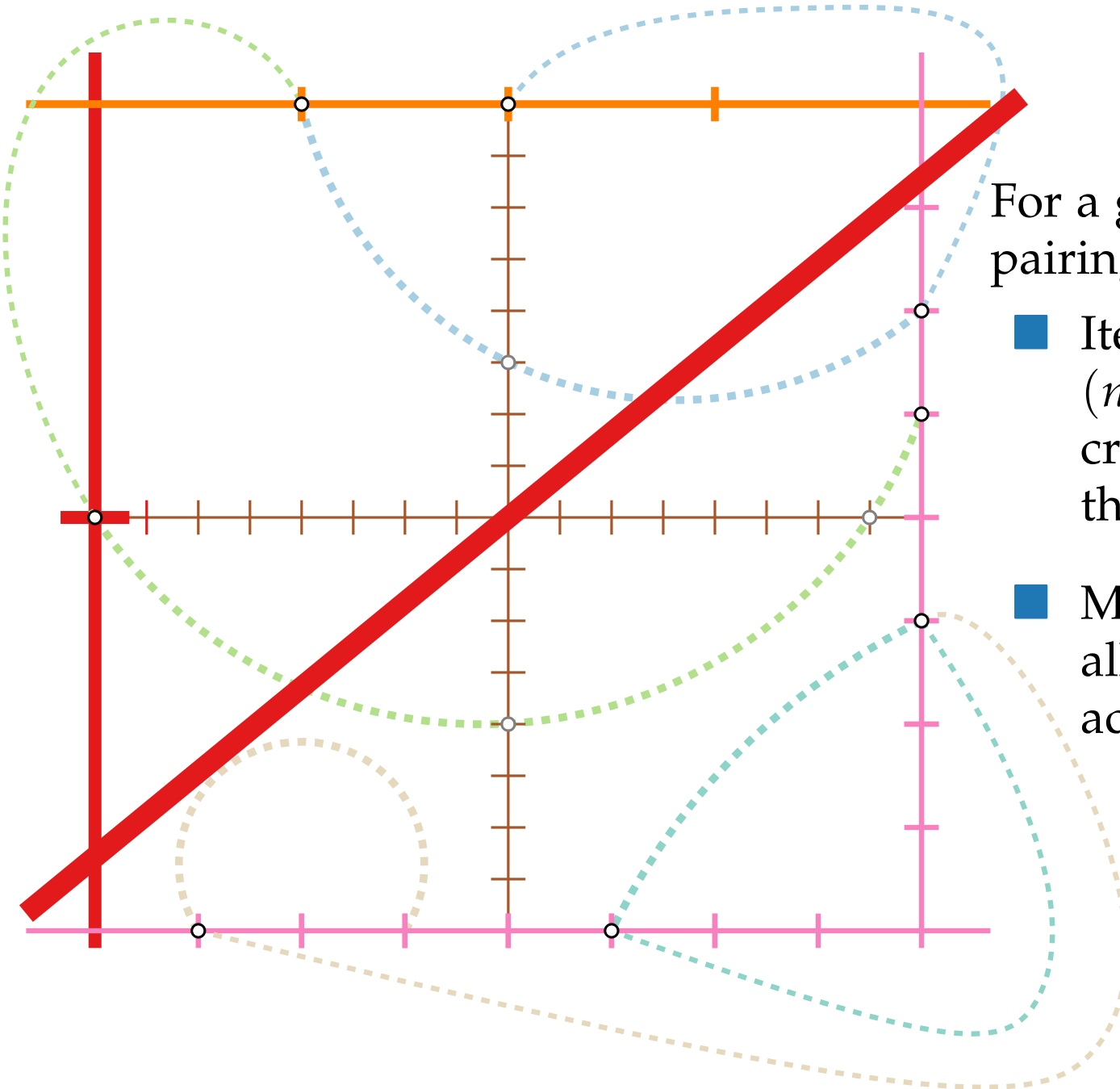
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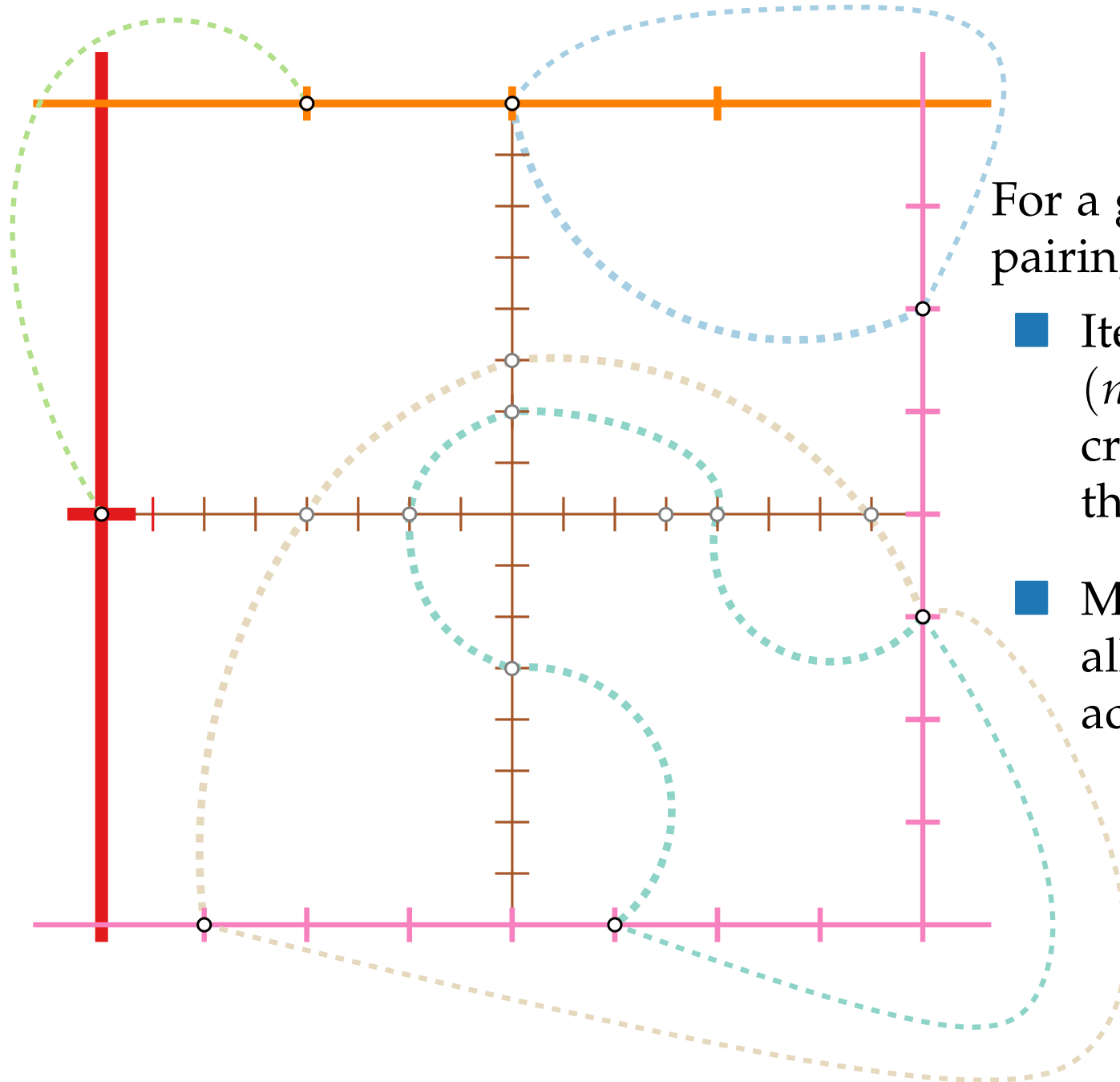
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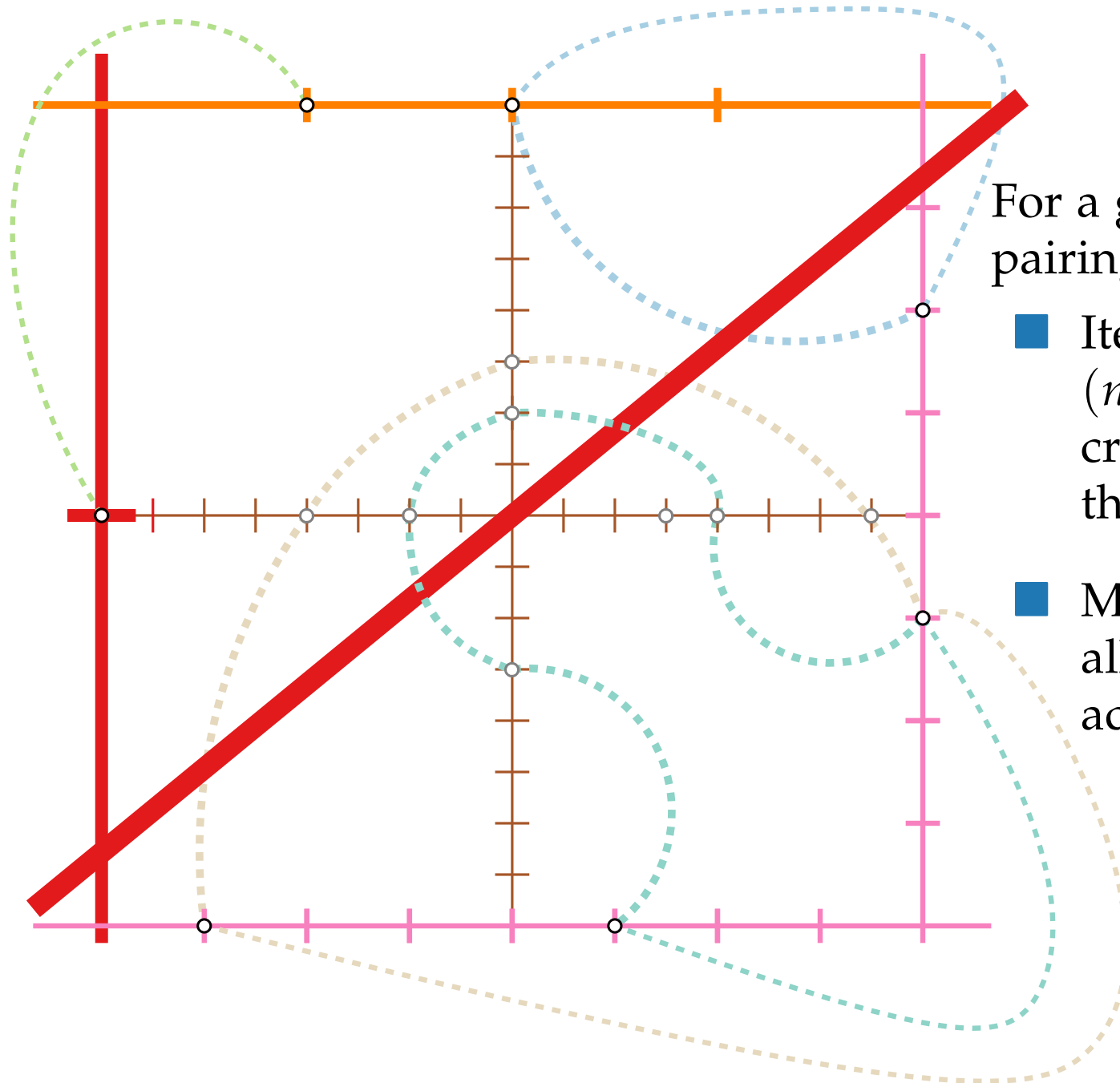
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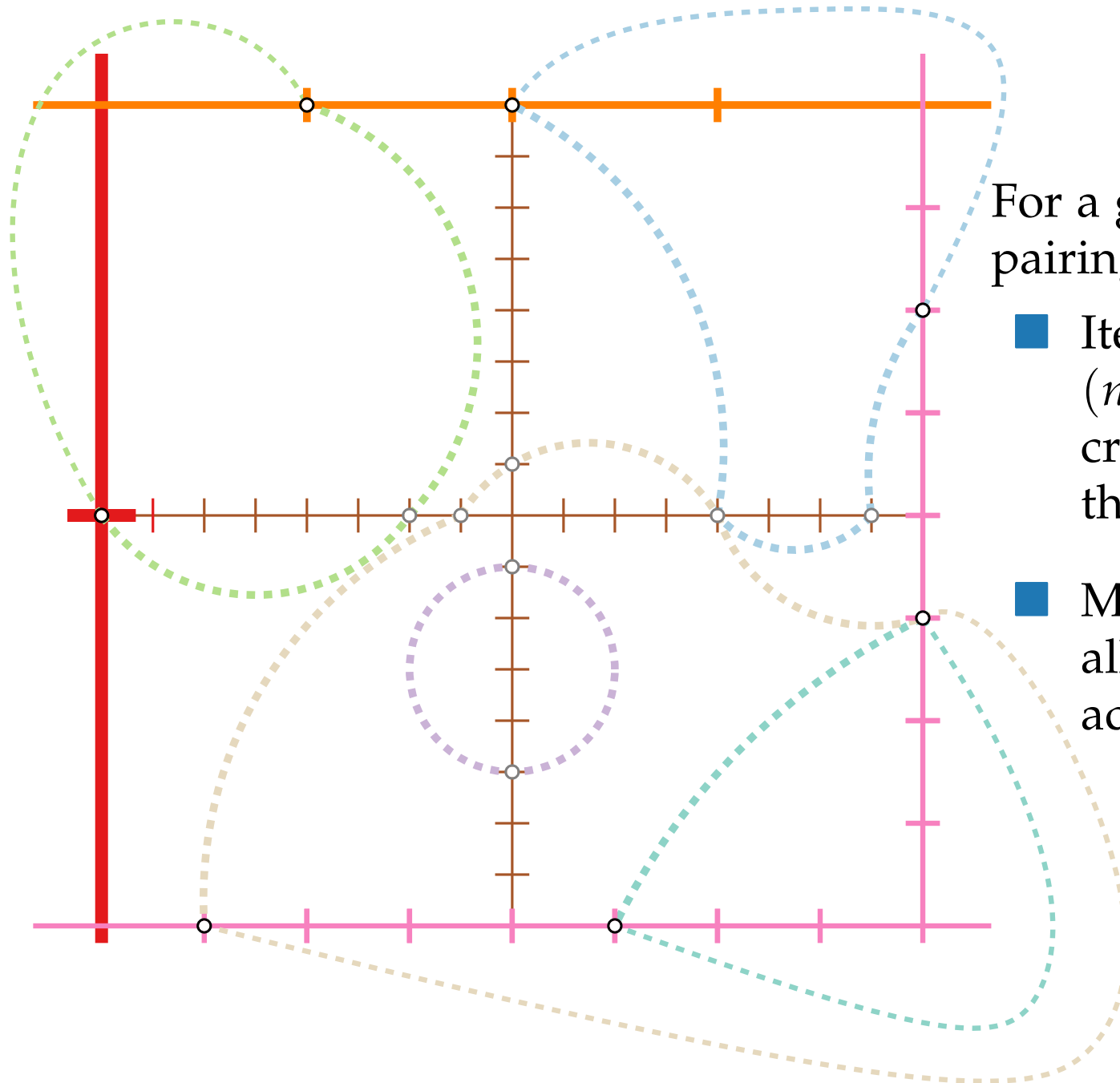
Dynamic Program (III)



For a given square Q and pairing P :

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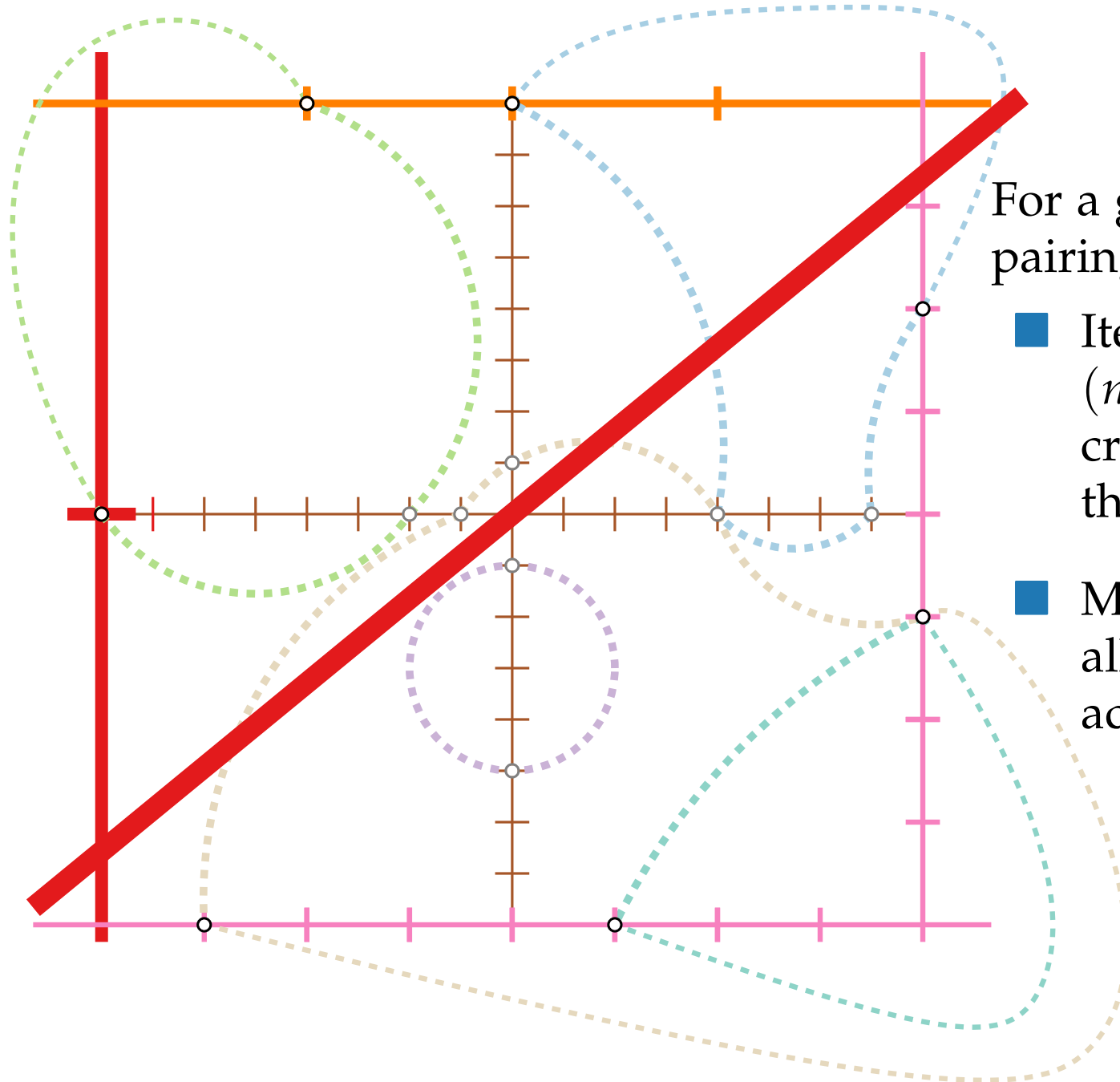
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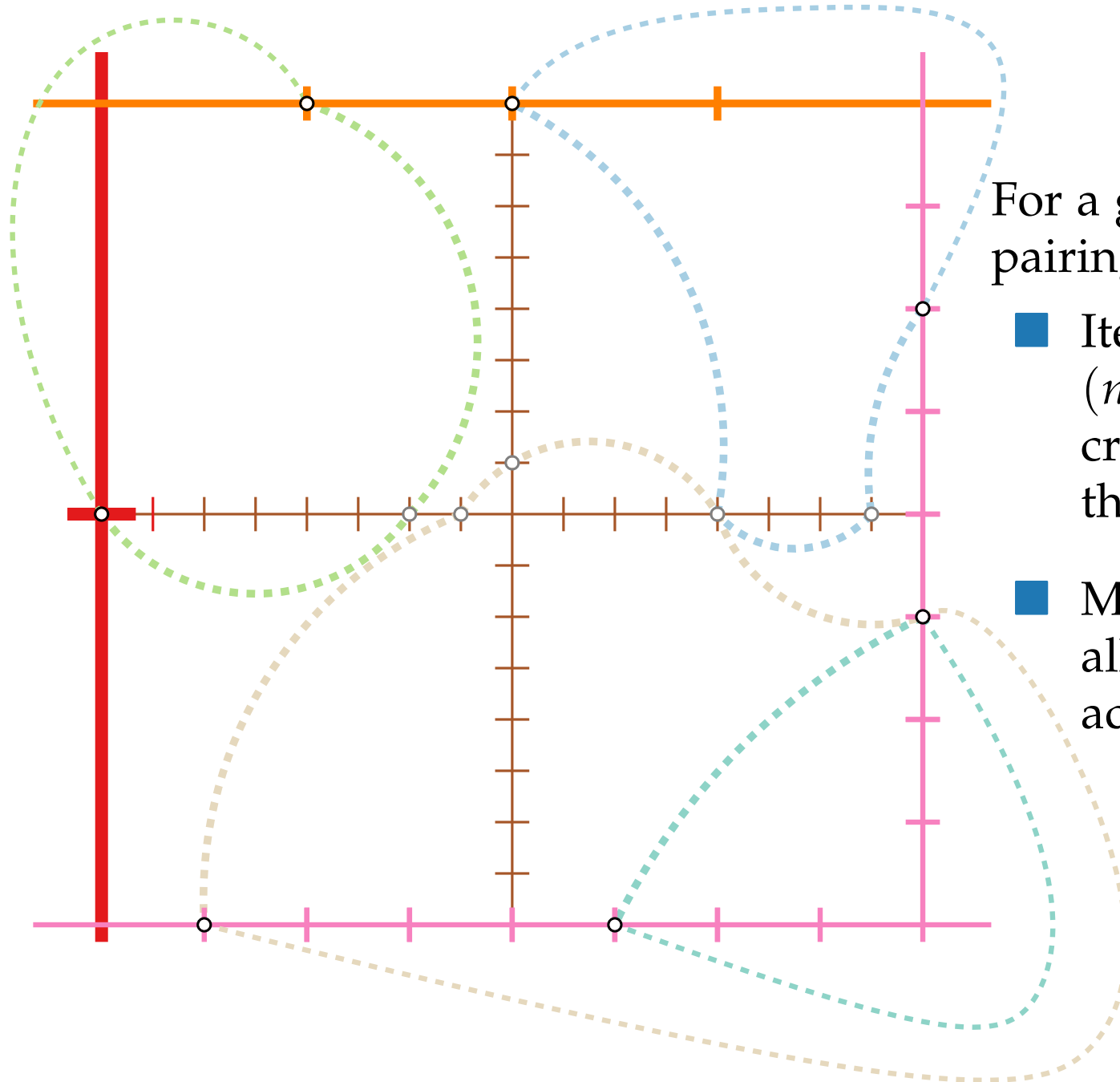
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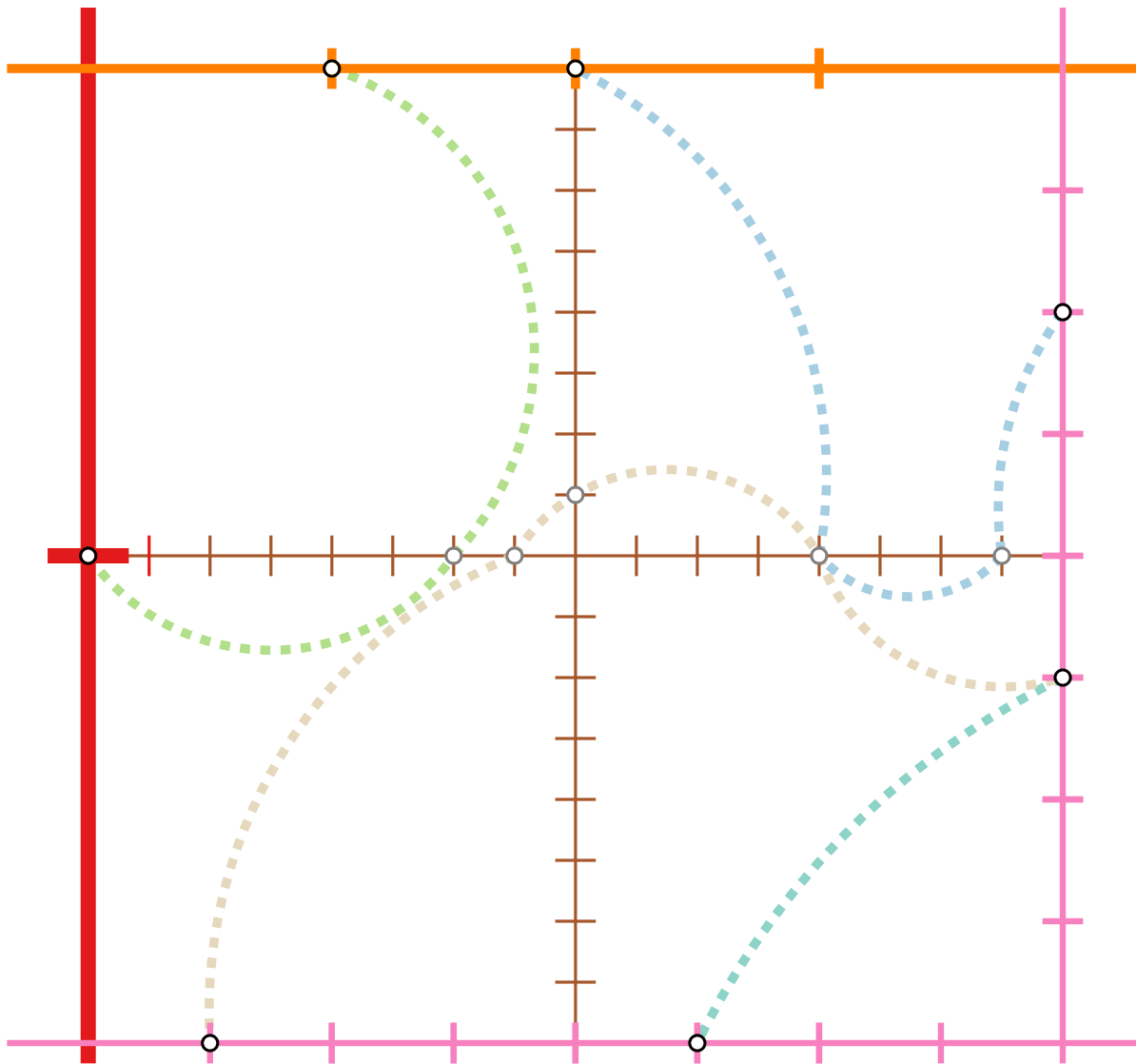
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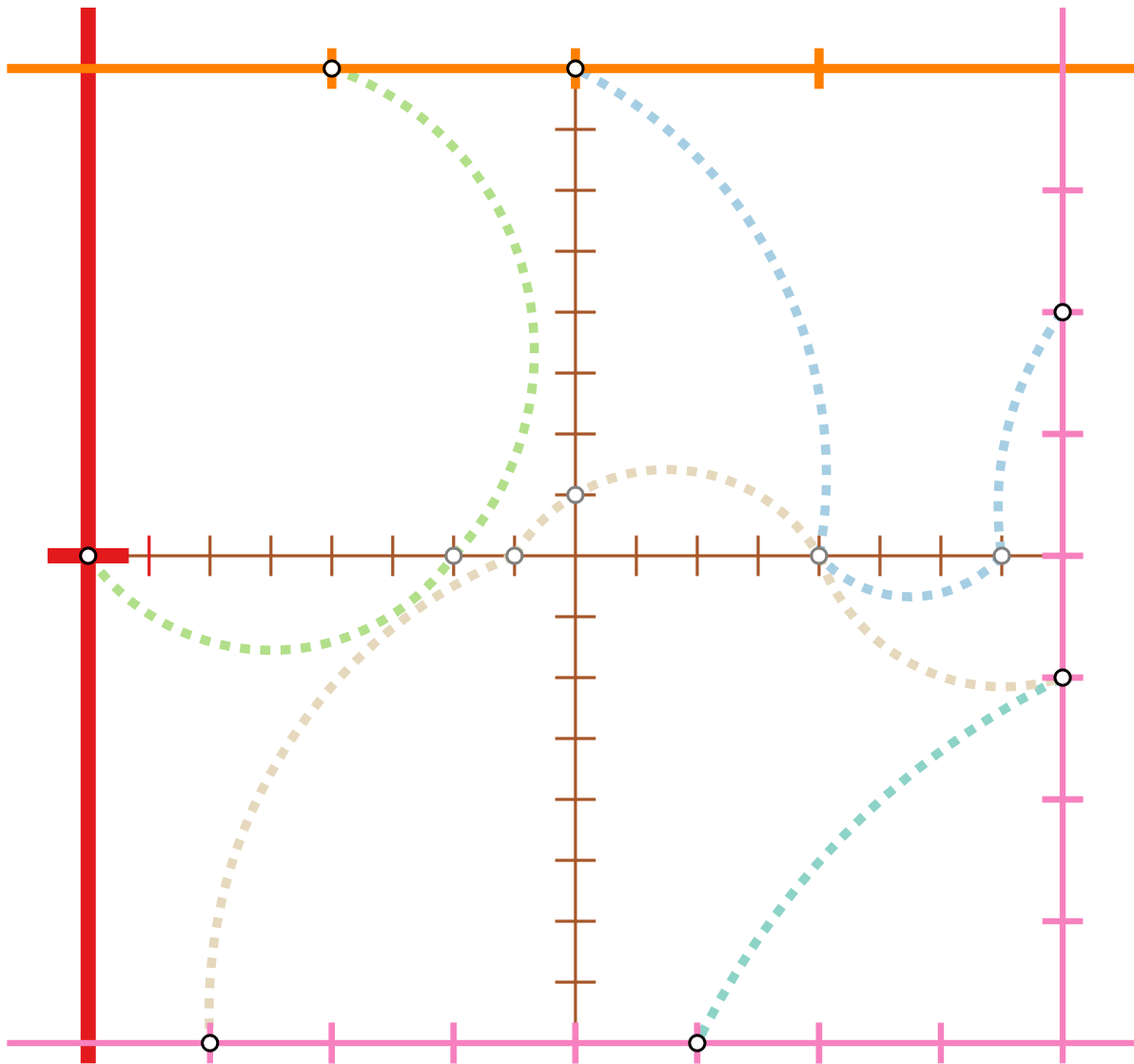
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- Correctness follows by induction.

Dynamic Program (III)



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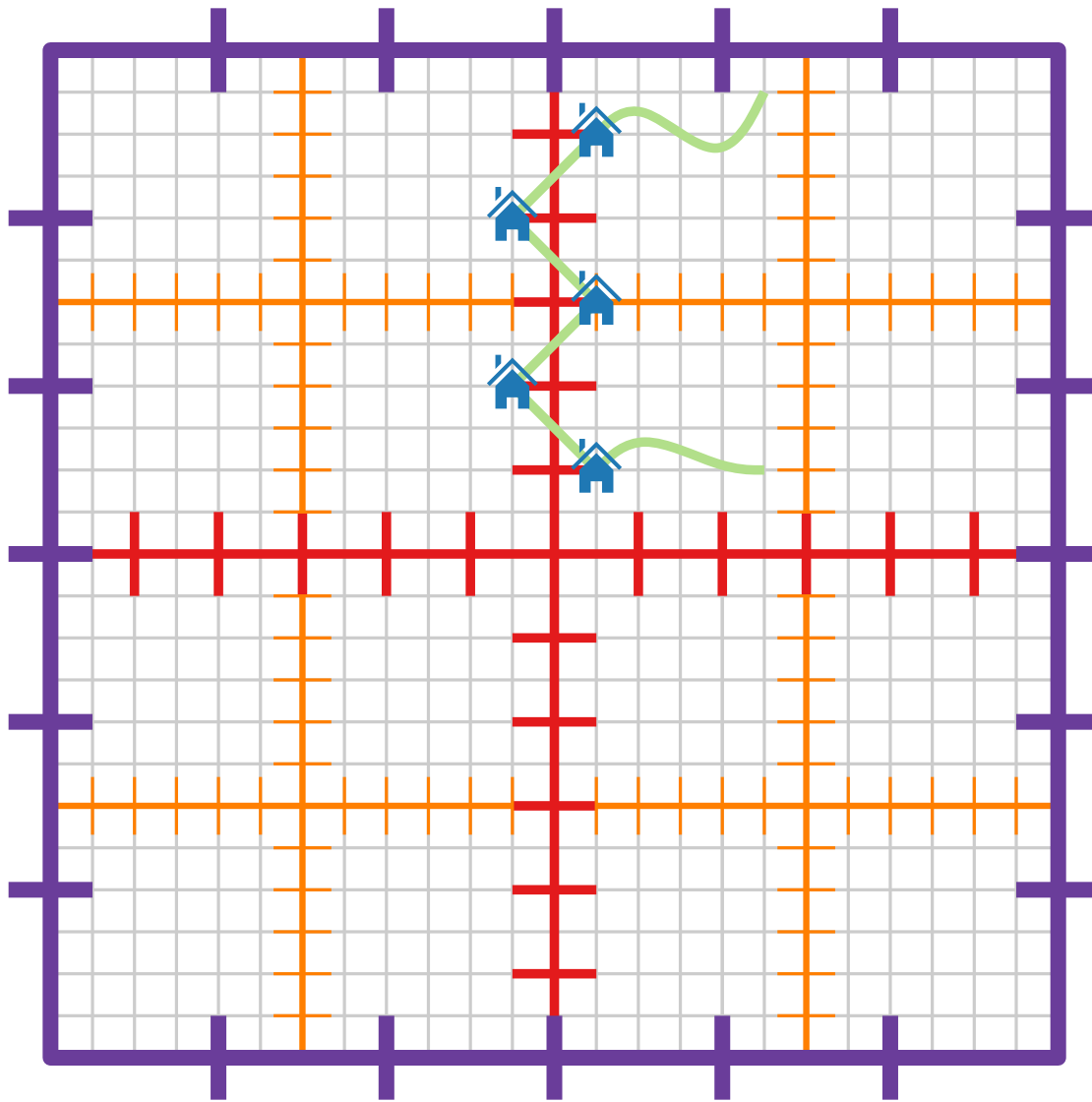
Lemma. An optimal well-behaved tour can be computed in $2^{O(m)} = n^{O(1/\varepsilon)}$ time.

Approximation Algorithms

Lecture 9: A PTAS for EUCLIDEAN TSP

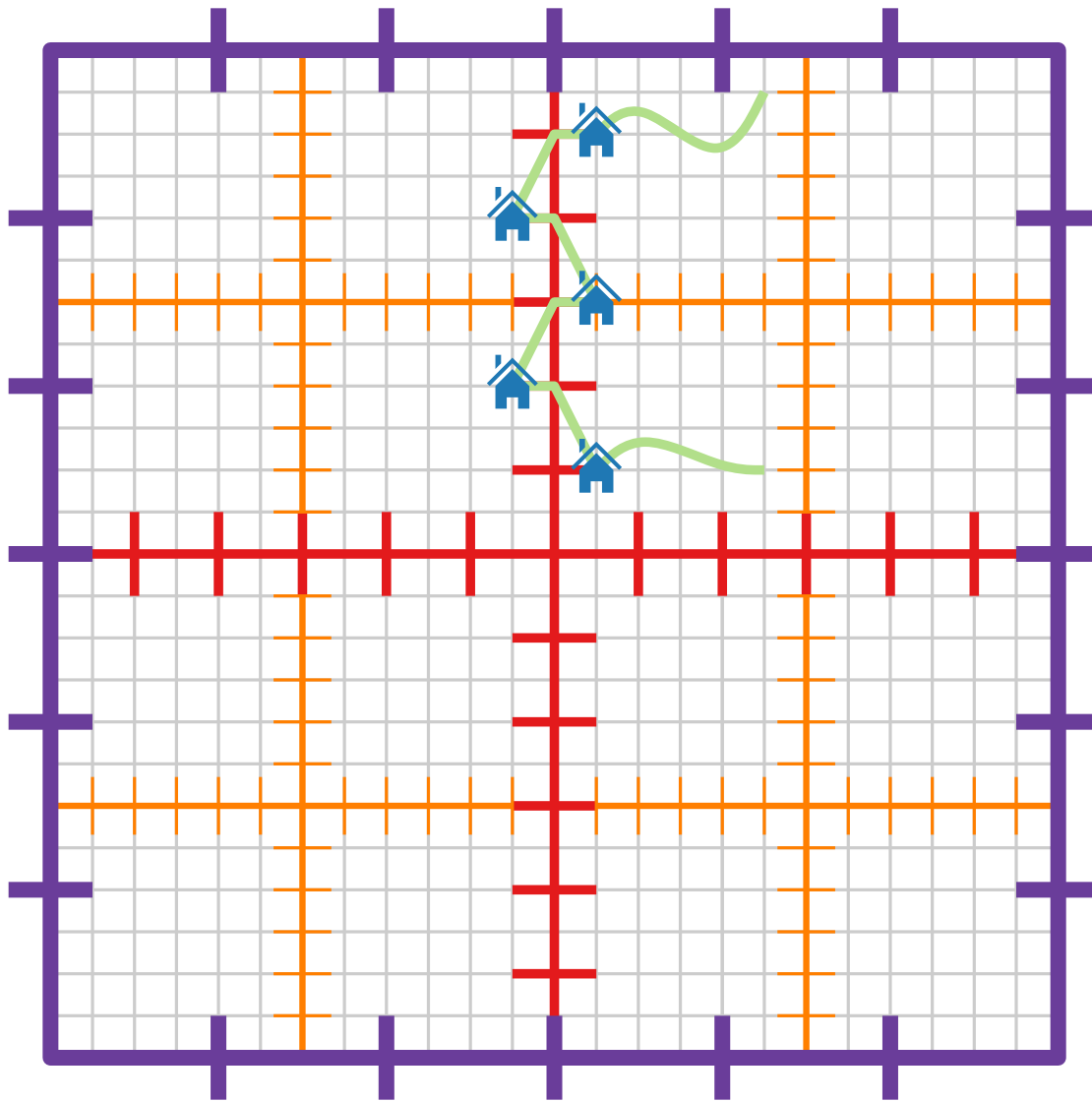
Part V: Shifted Dissections

Shifted Dissections



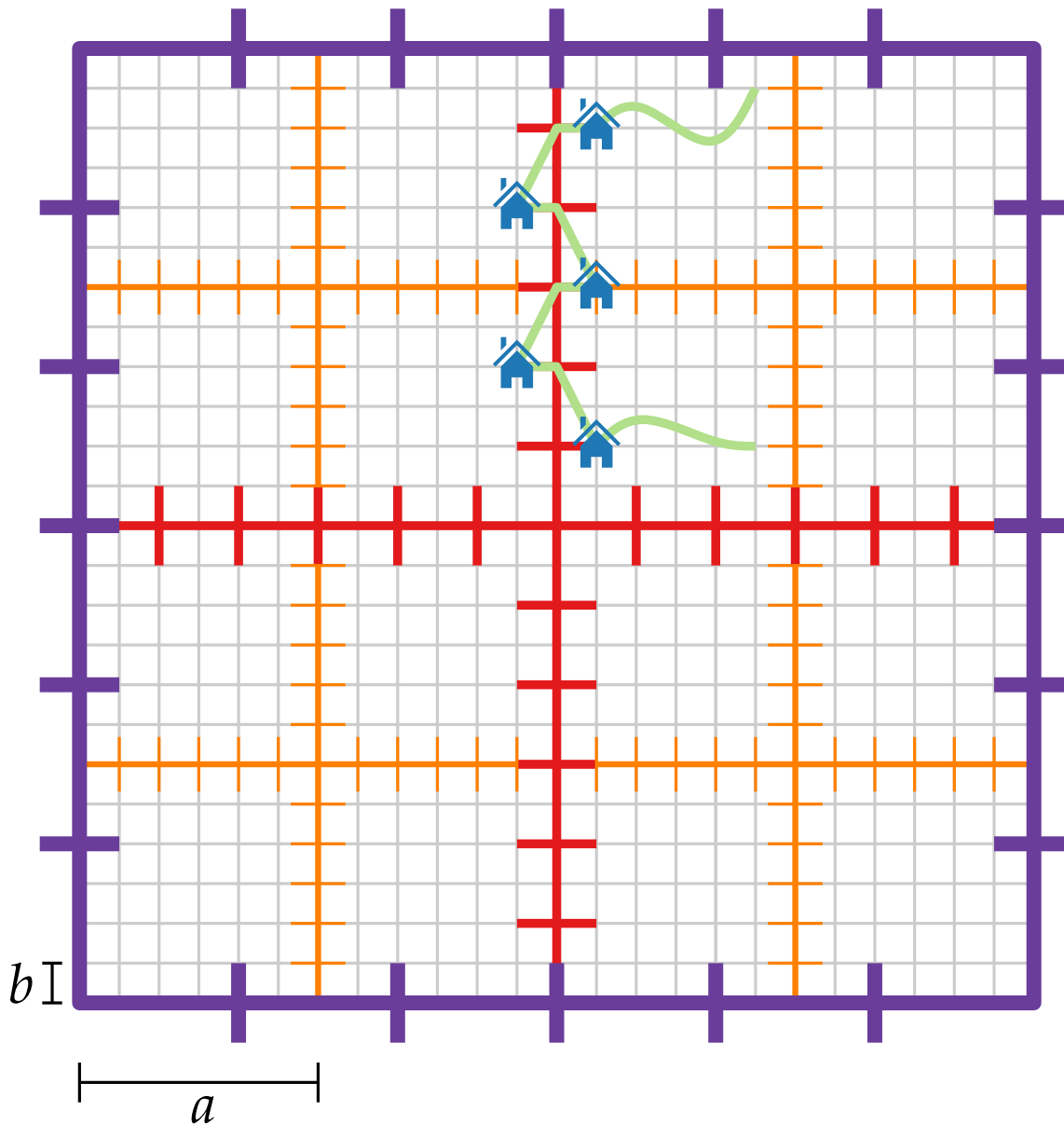
- The best well-behaved tour can be a bad approximation.

Shifted Dissections



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Shifted Dissections

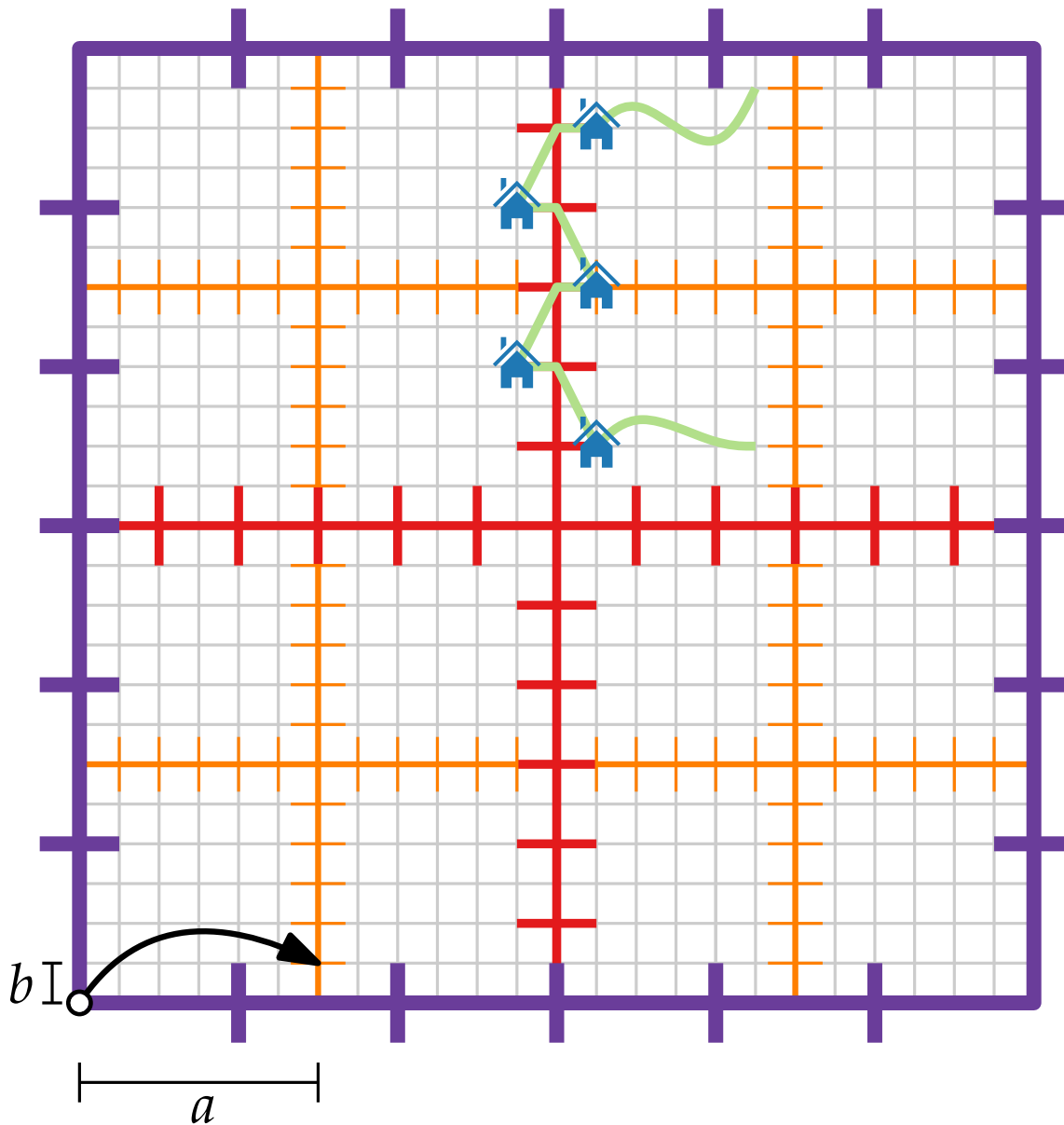


- The best well-behaved tour can be a bad approximation.
- Consider an (a, b) -shifted dissection:

$$x \mapsto (x + a) \bmod L$$

$$y \mapsto (y + b) \bmod L$$

Shifted Dissections

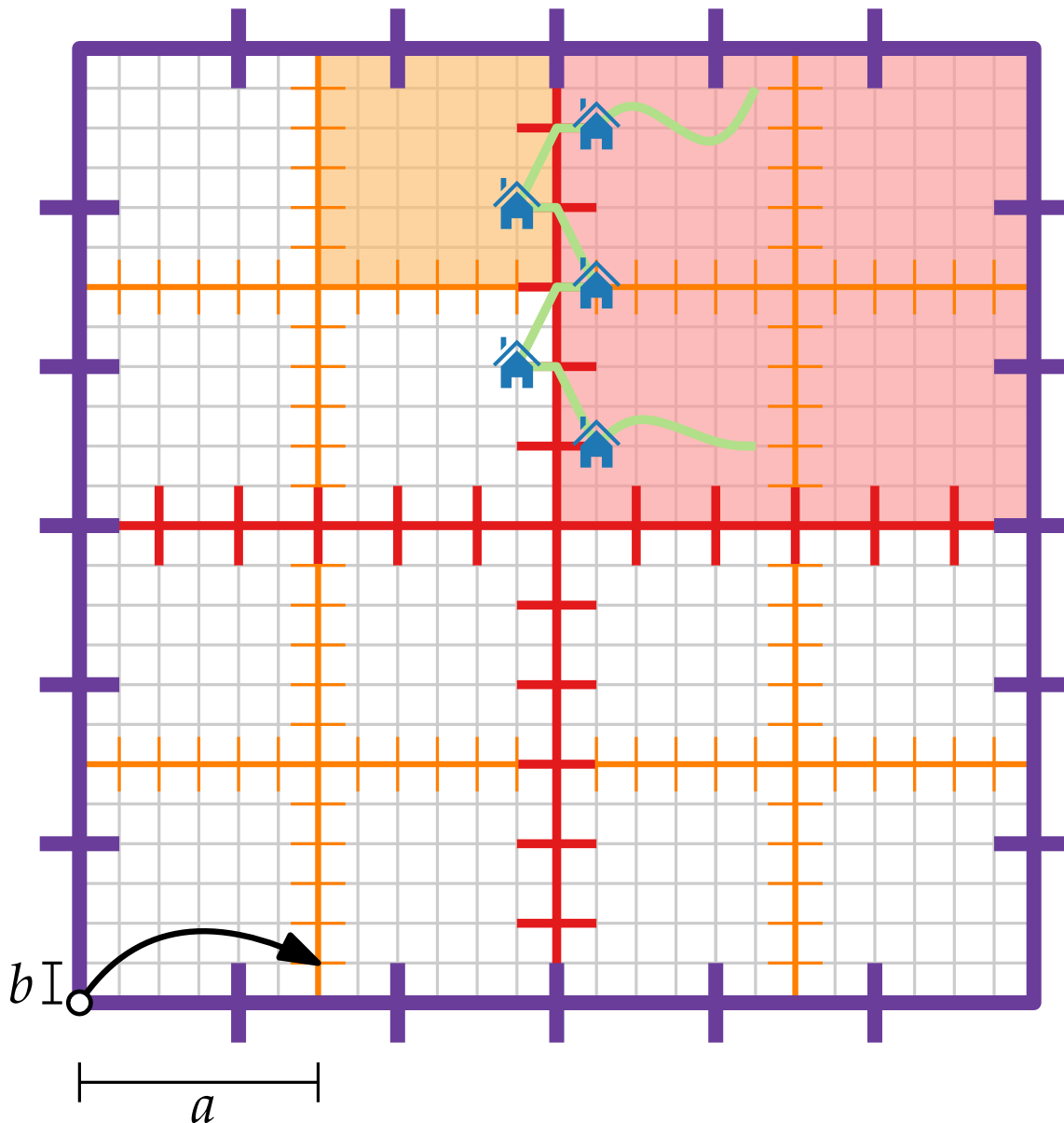


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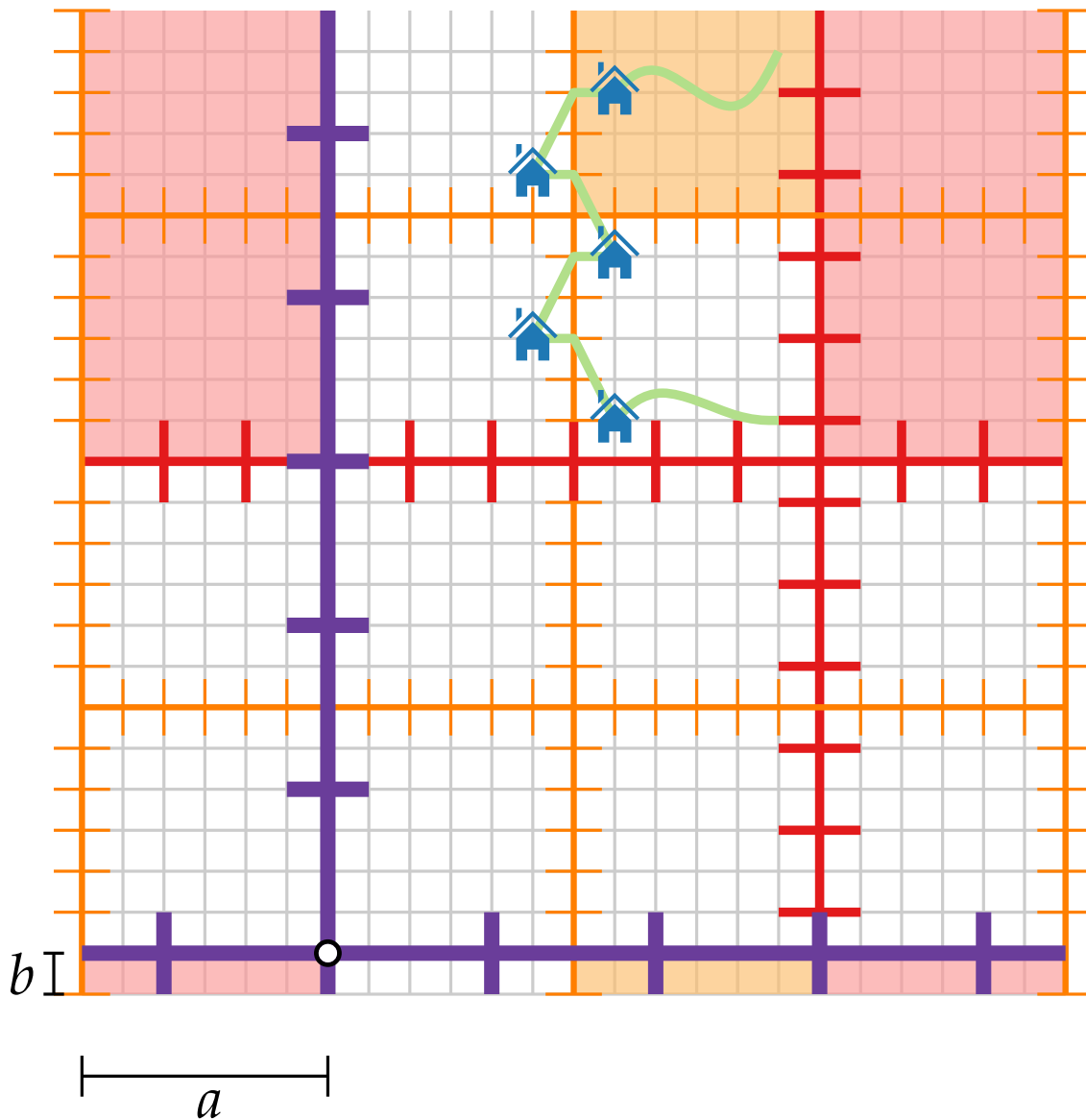
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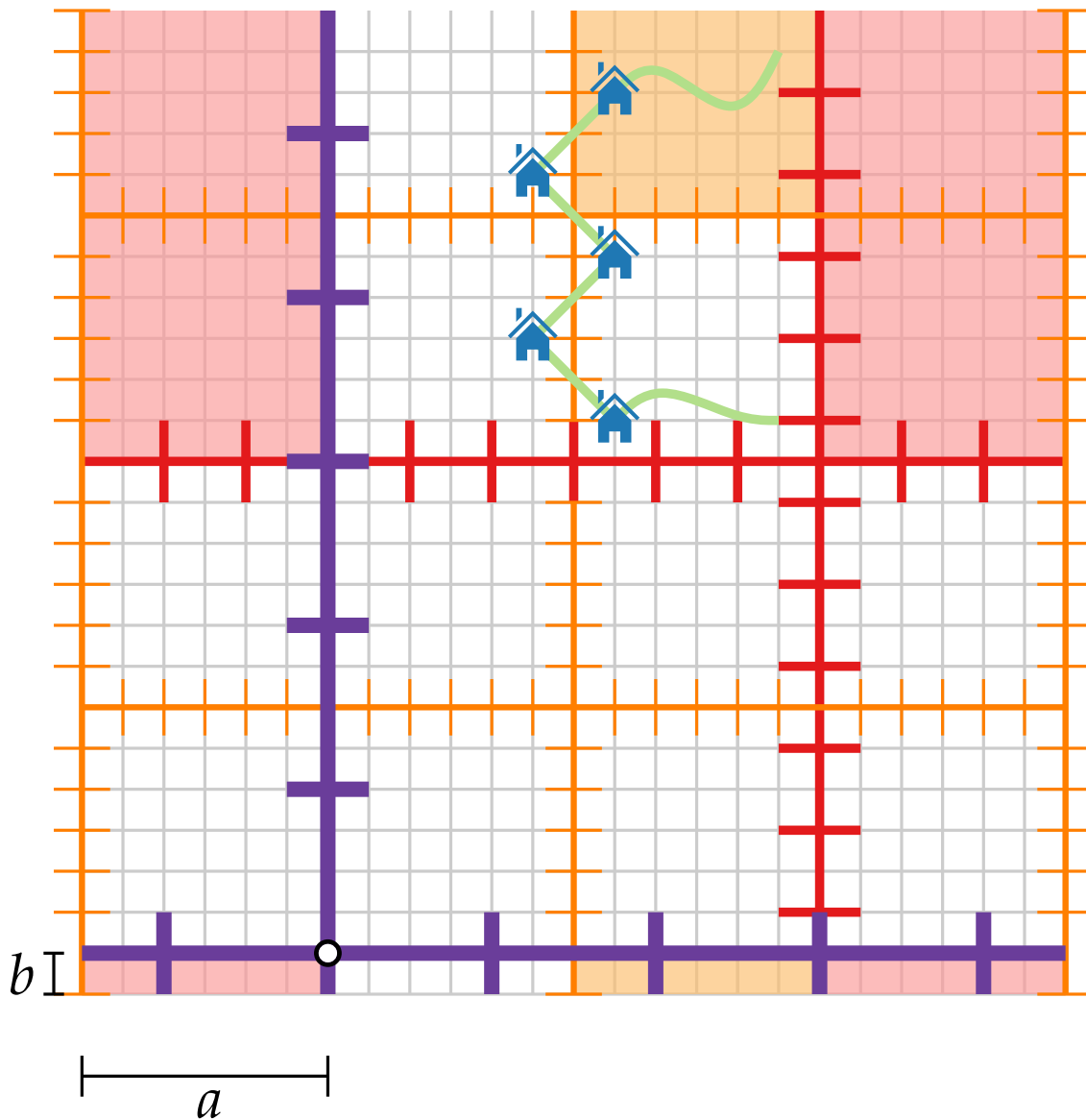


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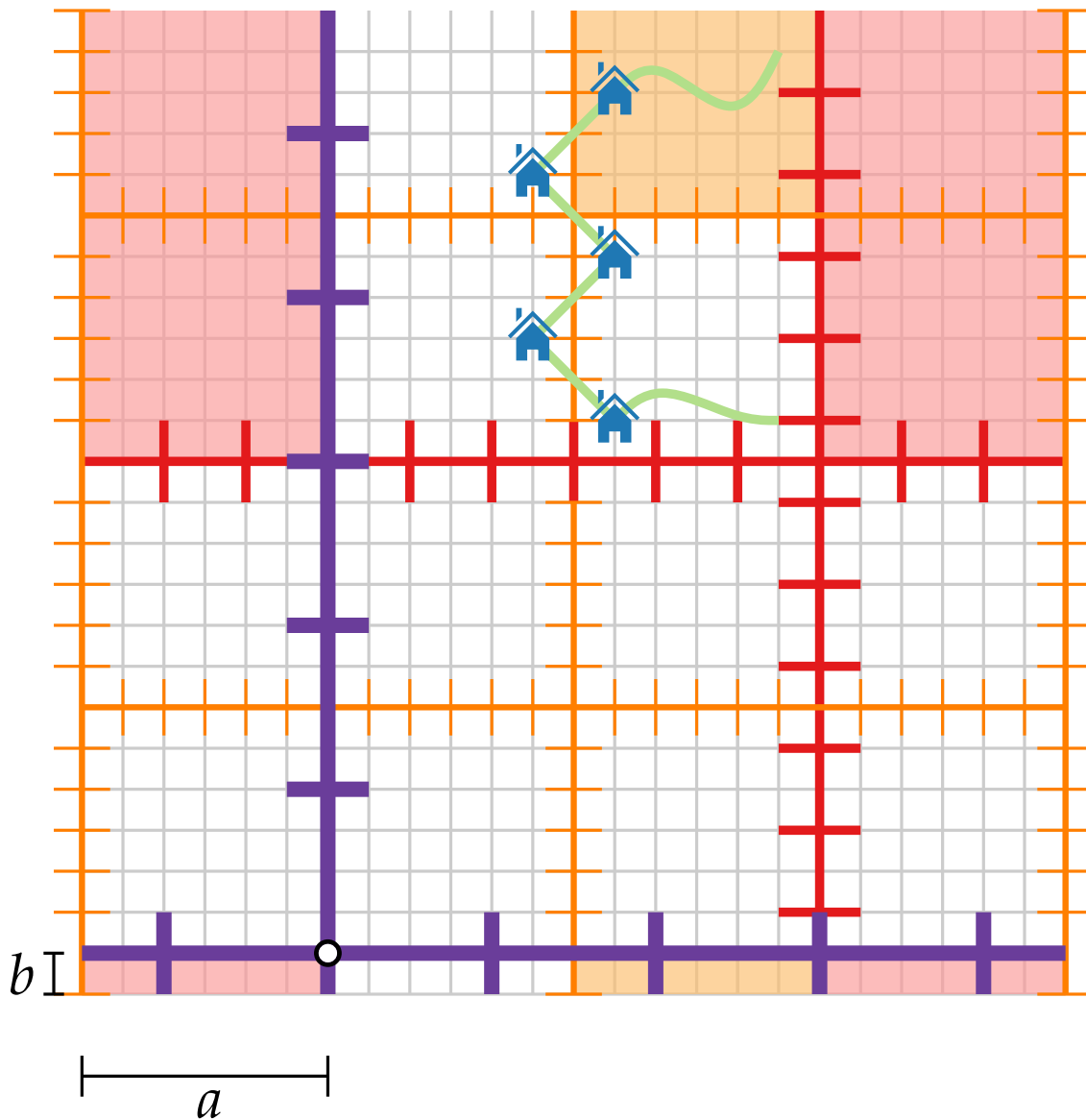


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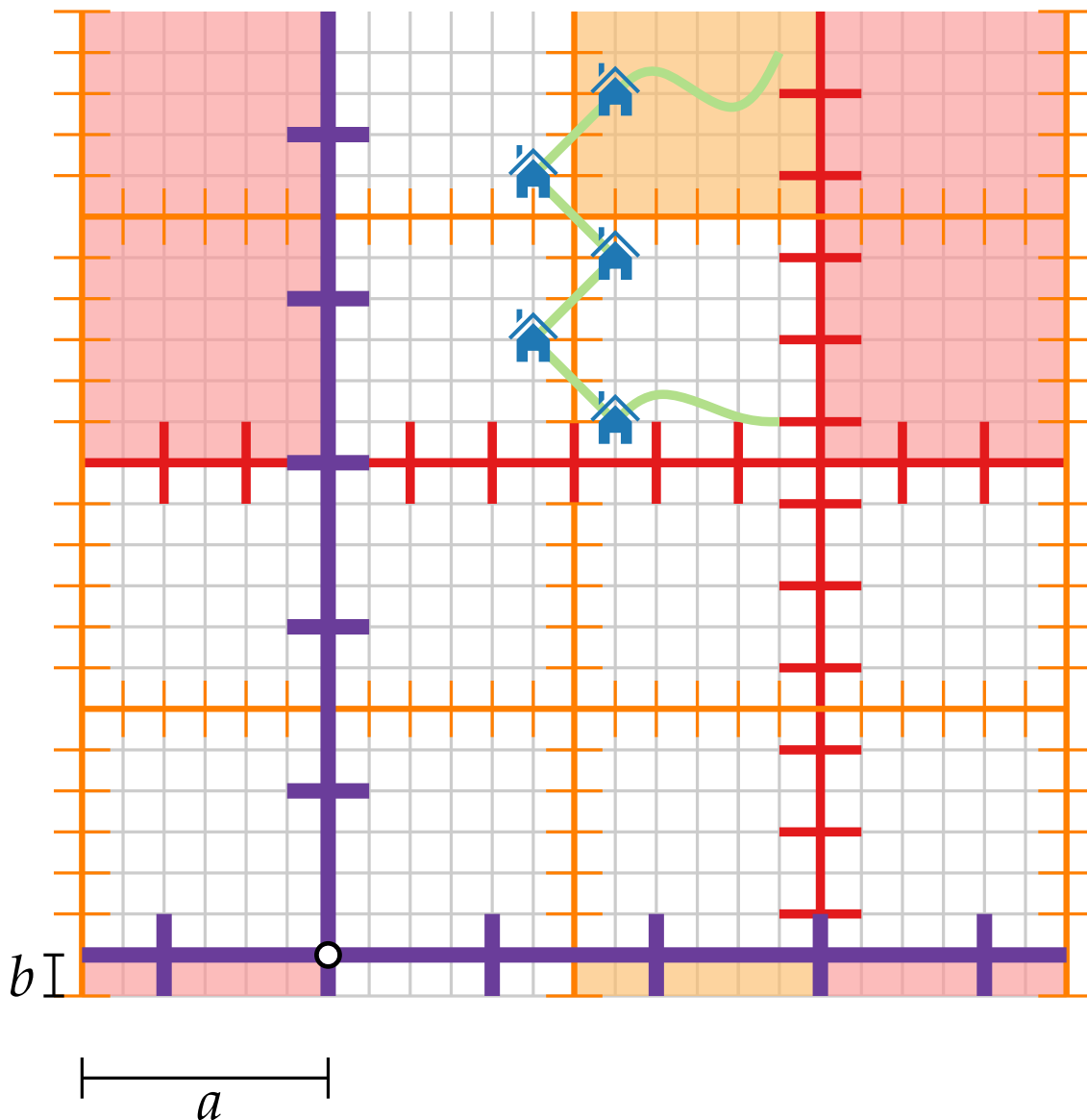
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■ Squares in the dissection tree are “wrapped around”.

Shifted Dissections



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- Consider an (a, b) -shifted dissection:

$$x \mapsto (x + a) \bmod L$$

$$y \mapsto (y + b) \bmod L$$

- Squares in the dissection tree are “wrapped around”.
- Dynamic program must be modified accordingly.

Shifted Dissections (II)

Lemma. Let π be an optimal tour, and let $N(\pi)$ be the number of crossings of π with the lines of the $(L \times L)$ -grid.

Shifted Dissections (II)

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Shifted Dissections (II)

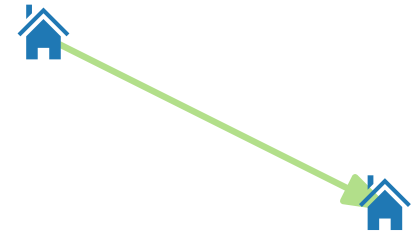
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Proof. ■ Consider a tour as an ordered cyclic sequence.

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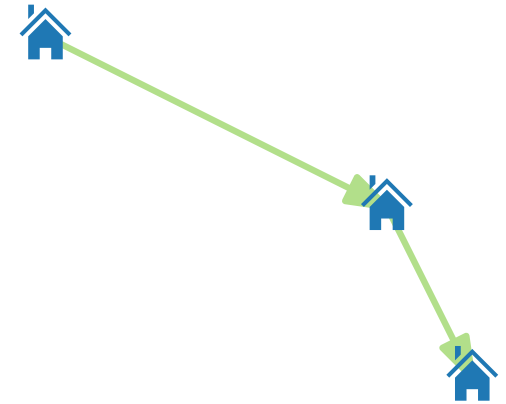


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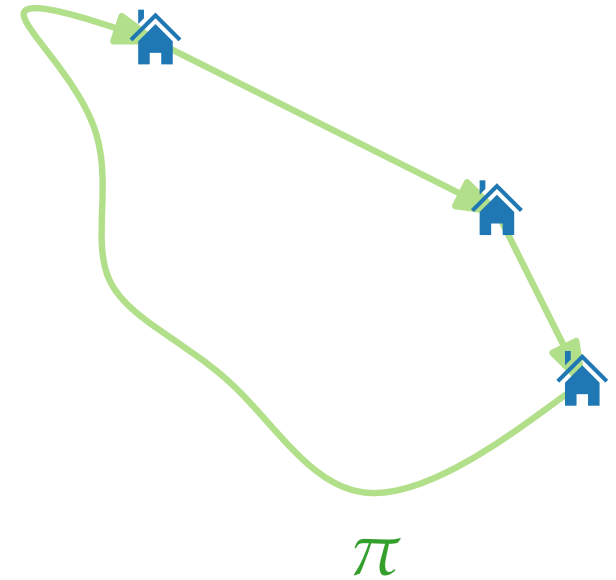


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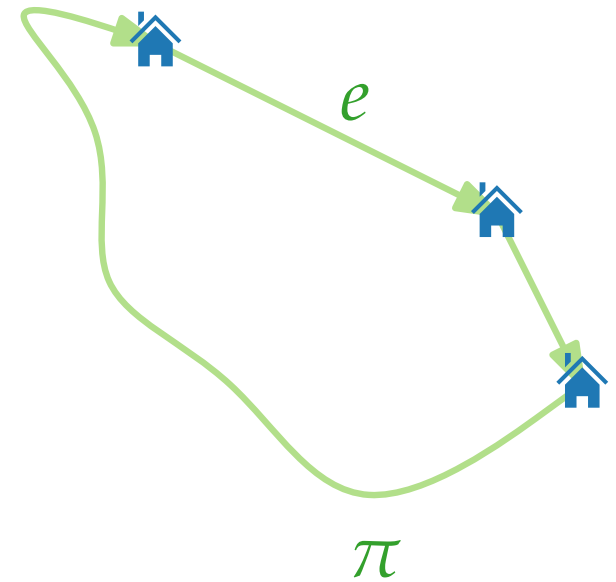
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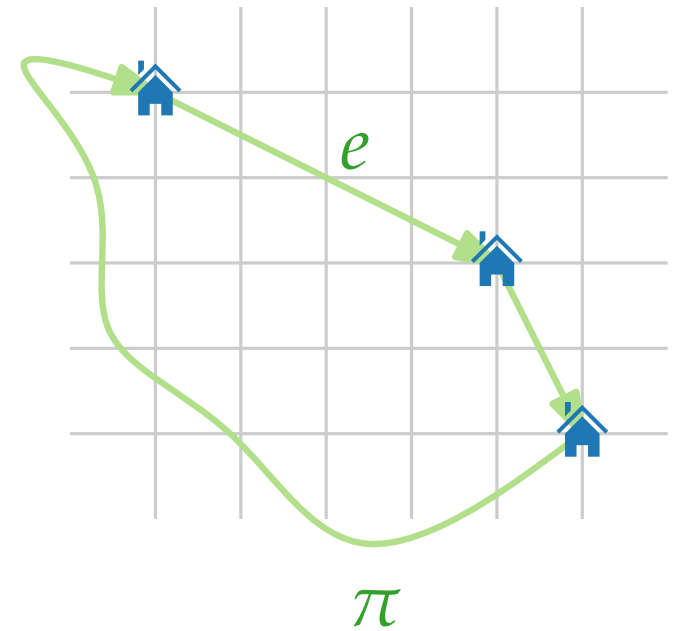
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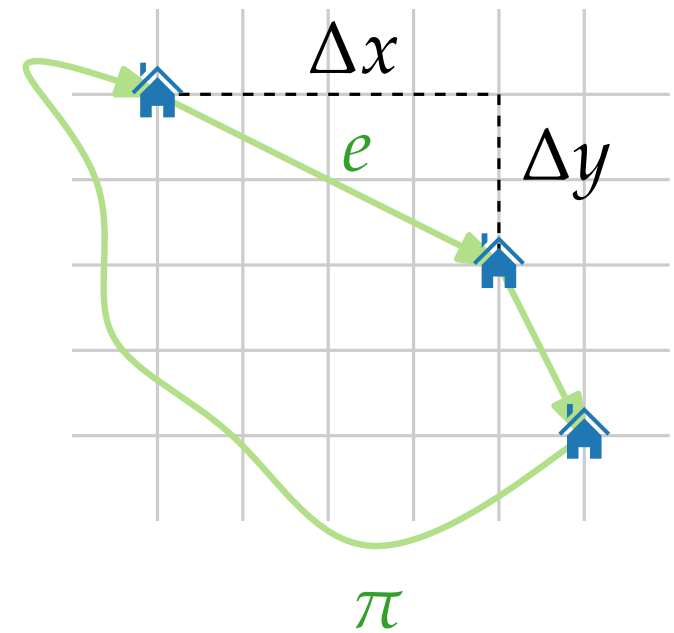
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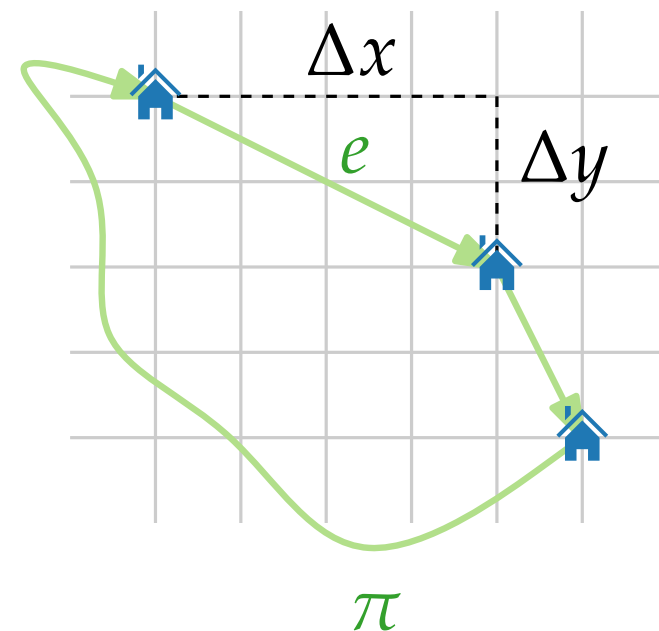


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Proof.

- Consider a tour as an ordered cyclic sequence.
- Each edge e generates $N_e \leq \Delta x + \Delta y$ crossings.

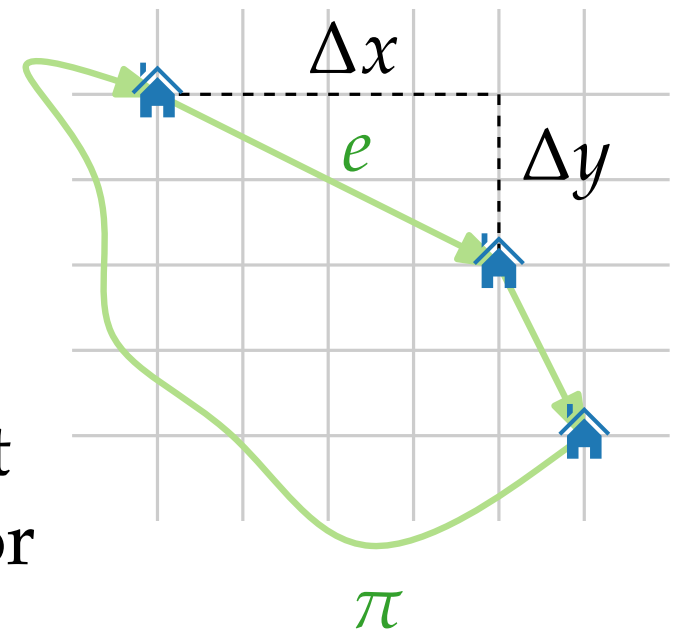


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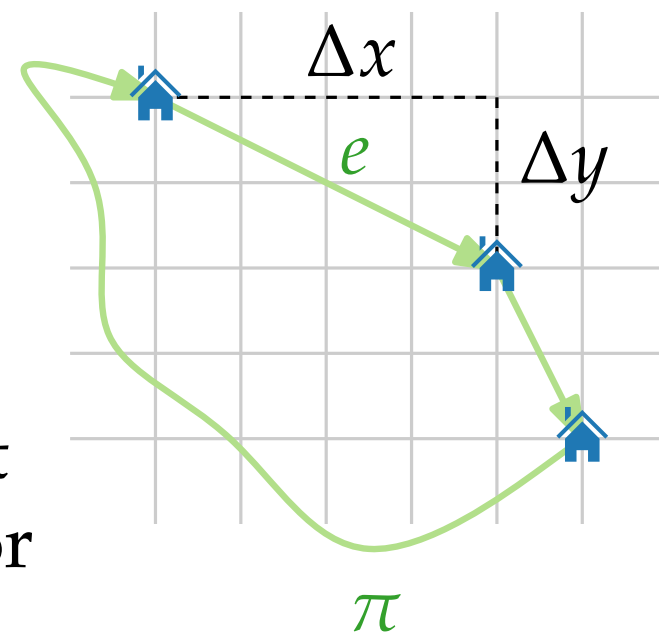


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- $N_e^2 \leq$

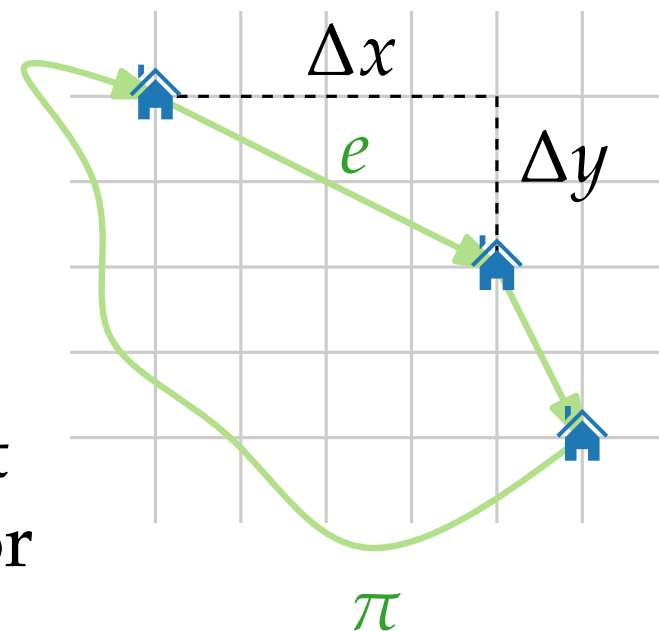


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- Each edge e generates $N_e \leq \Delta x + \Delta y$ crossings.
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- $N_e^2 \leq (\Delta x + \Delta y)^2 \leq$

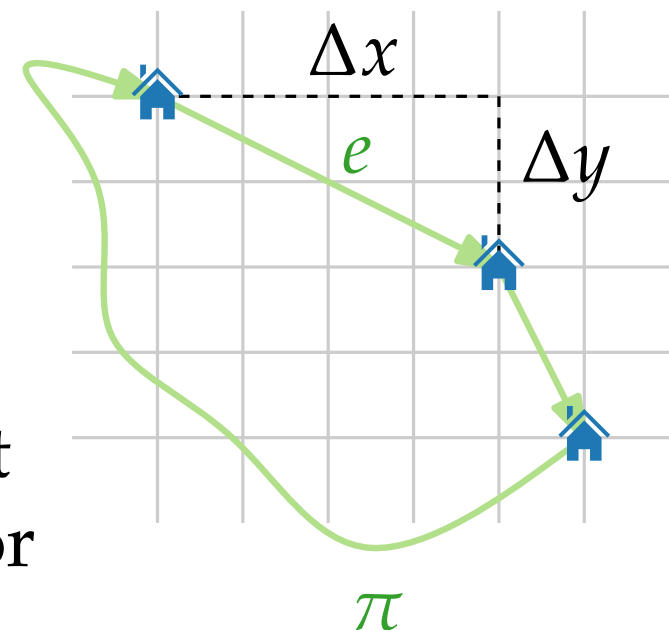


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Proof.

- Consider a tour as an ordered cyclic sequence.
- Each edge e generates $N_e \leq \Delta x + \Delta y$ crossings.
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$$0 \leq (\Delta x - \Delta y)^2$$

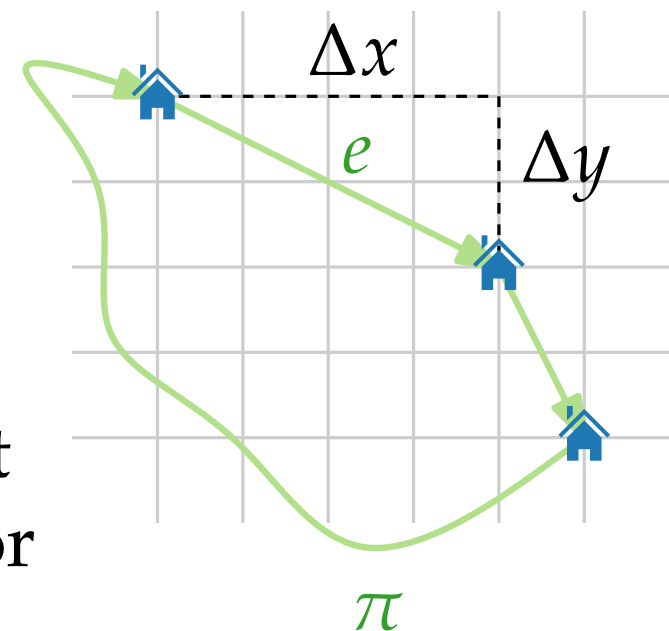
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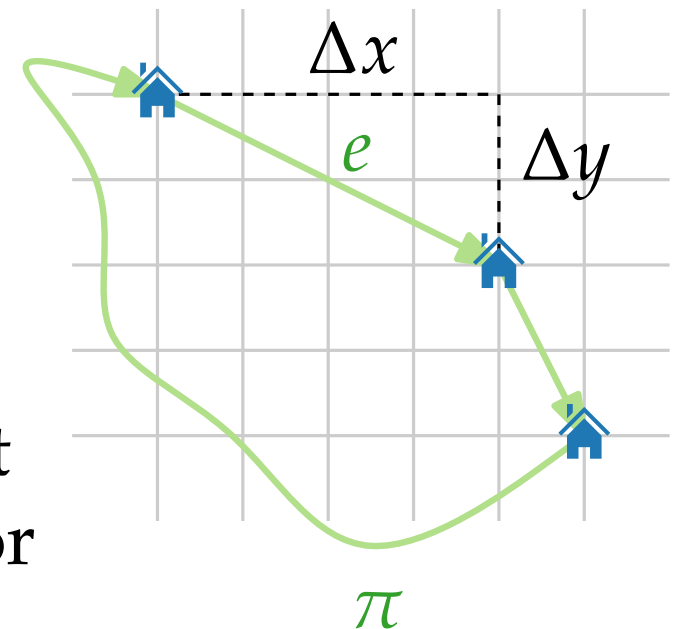
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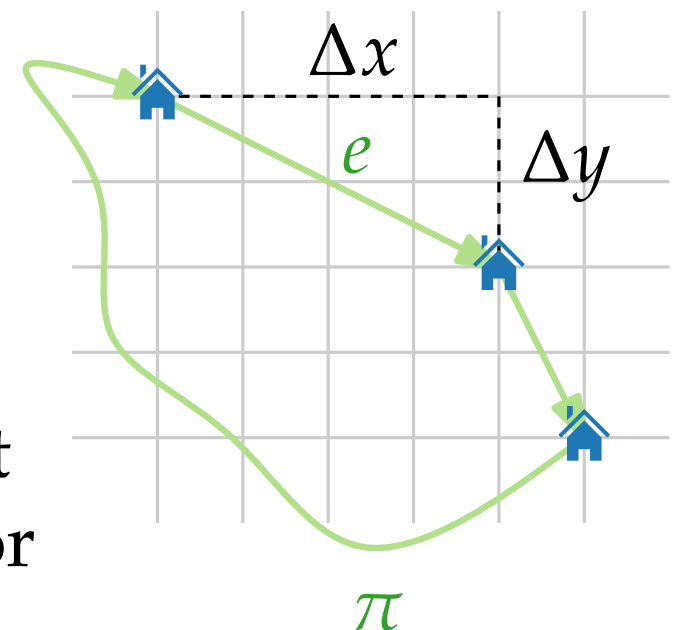
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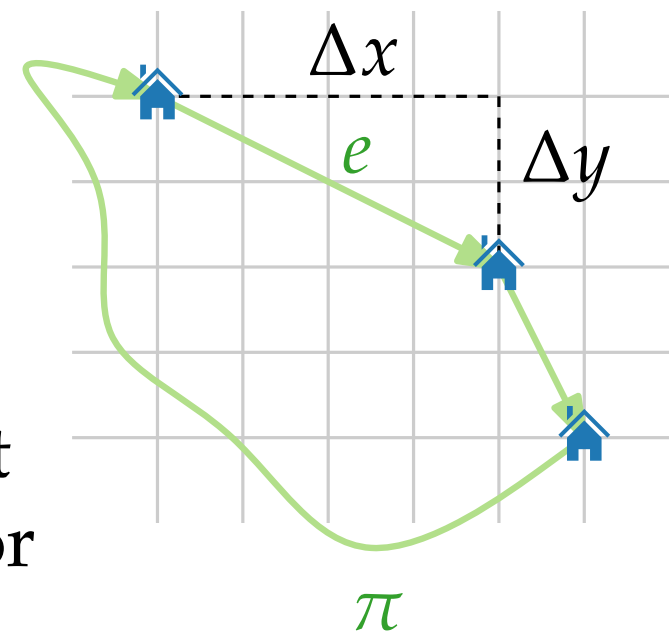
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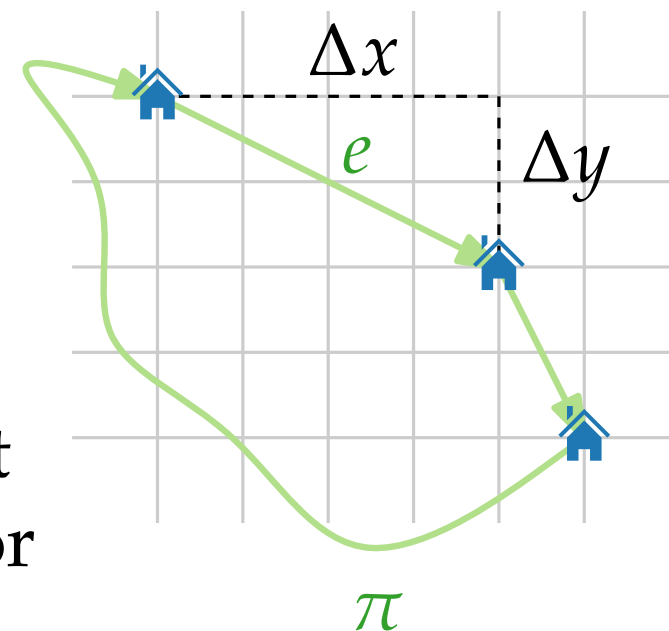
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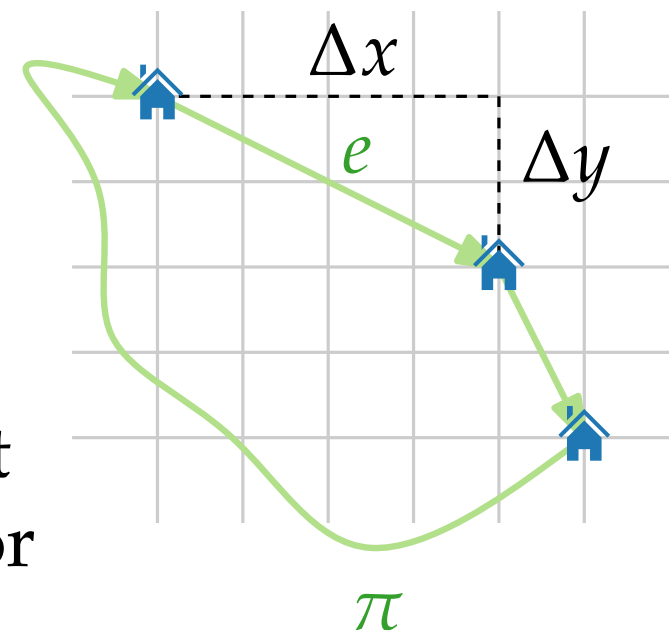
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□

Approximation Algorithms

Lecture 9: A PTAS for EUCLIDEAN TSP

Part VI: Approximation Factor

Shifted Dissections (III)

Theorem. Let $a, b \in [0, L - 1]$ be chosen independently and uniformly at random.

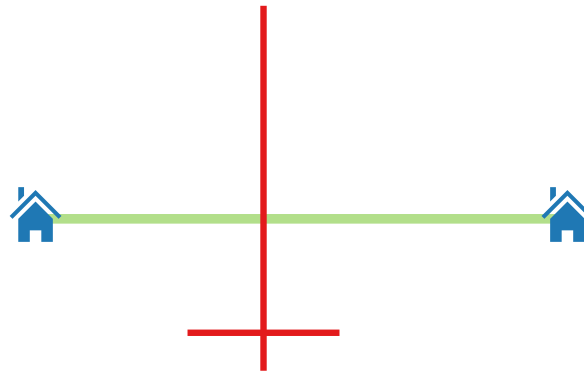
Shifted Dissections (III)

Theorem. Let $a, b \in [0, L - 1]$ be chosen independently and uniformly at random. Then the expected cost of an optimal well-behaved tour with respect to the (a, b) -shifted dissection is $\leq (1 + 2\sqrt{2}\varepsilon)\text{OPT}$.

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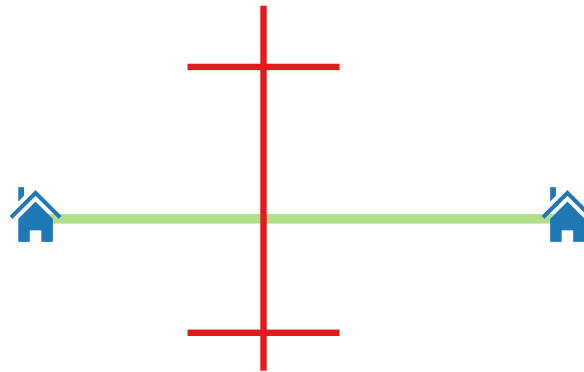
Proof. Consider optimal tour π .



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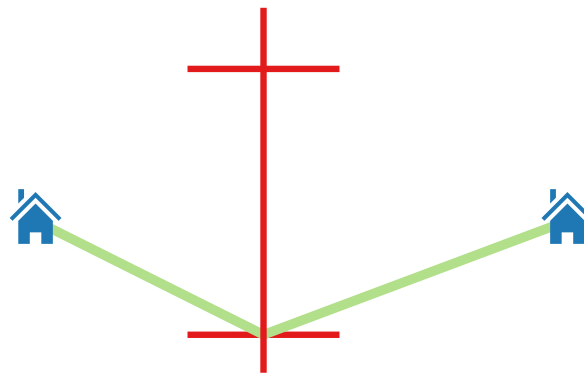
Proof. Consider optimal tour π . Make π well-behaved by moving each intersection point with the $(L \times L)$ -grid to the nearest portal.



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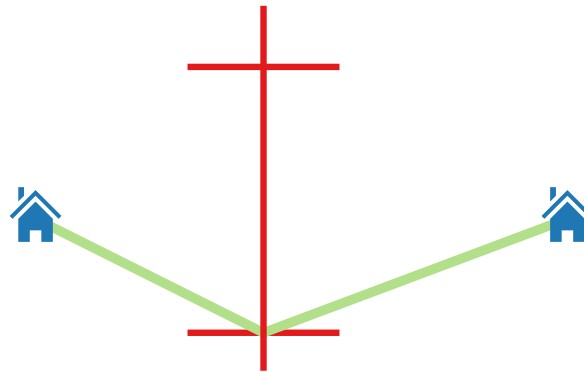
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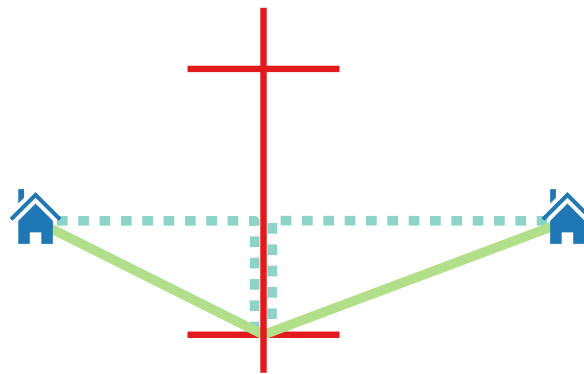


Detour per intersection \leq inter-portal distance.

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- Consider an intersection point between π and a line l of the $(L \times L)$ -grid.

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- Consider an intersection point between π and a line l of the $(L \times L)$ -grid.
- With probability *at most* $\frac{1}{L}$, the line l is a level- i line.

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- With probability *at most* $2^i / L$, the line l is a level- i line.

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- Consider an intersection point between π and a line l of the $(L \times L)$ -grid.
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Shifted Dissections (III)

- Consider an intersection point between π and a line l of the $(L \times L)$ -grid.
- With probability *at most* $2^i / L$, the line l is a level- i line.
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Shifted Dissections (III)

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- Thus, the expected increase in tour length due to this intersection is at most:

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 \Rightarrow Increase in tour length $\leq L / (2^i m)$ (inter-portal distance).
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- Summing over all $N(\pi) \leq \sqrt{2} \cdot \text{OPT}$ intersection points and applying linearity of expectation yields the claim.

Polynomial-Time Approximation Scheme

Theorem. Let $a, b \in [0, L - 1]$ be chosen independently and uniformly at random. Then the expected cost of an optimal well-behaved tour with respect to the (a, b) -shifted dissection is $\leq (1 + 2\sqrt{2}\varepsilon)\text{OPT}$.

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