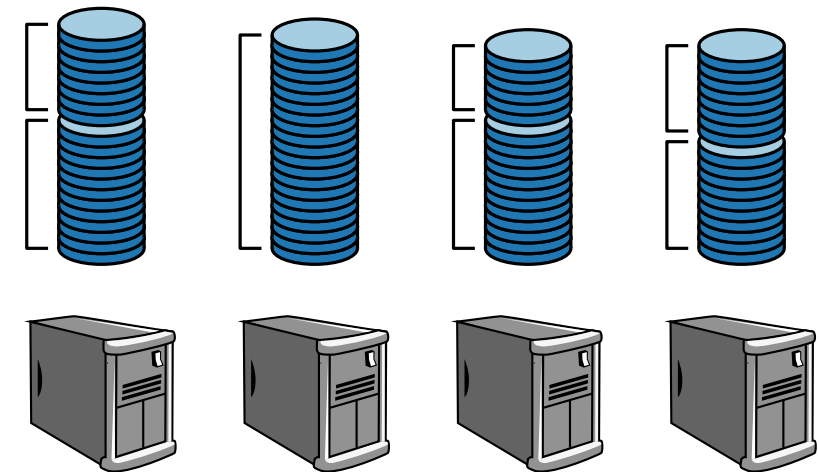
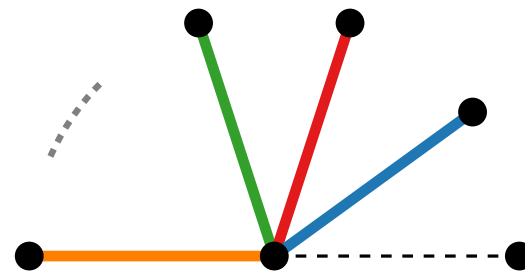
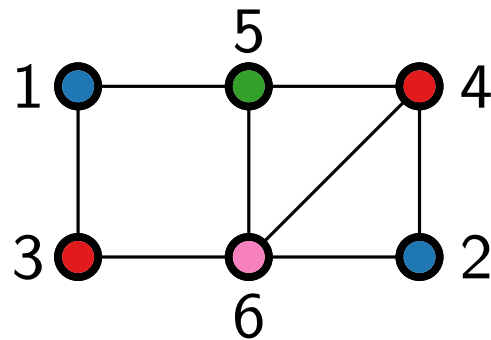


# Advanced Algorithms

## Approximation Algorithms

### Coloring and Scheduling Problems

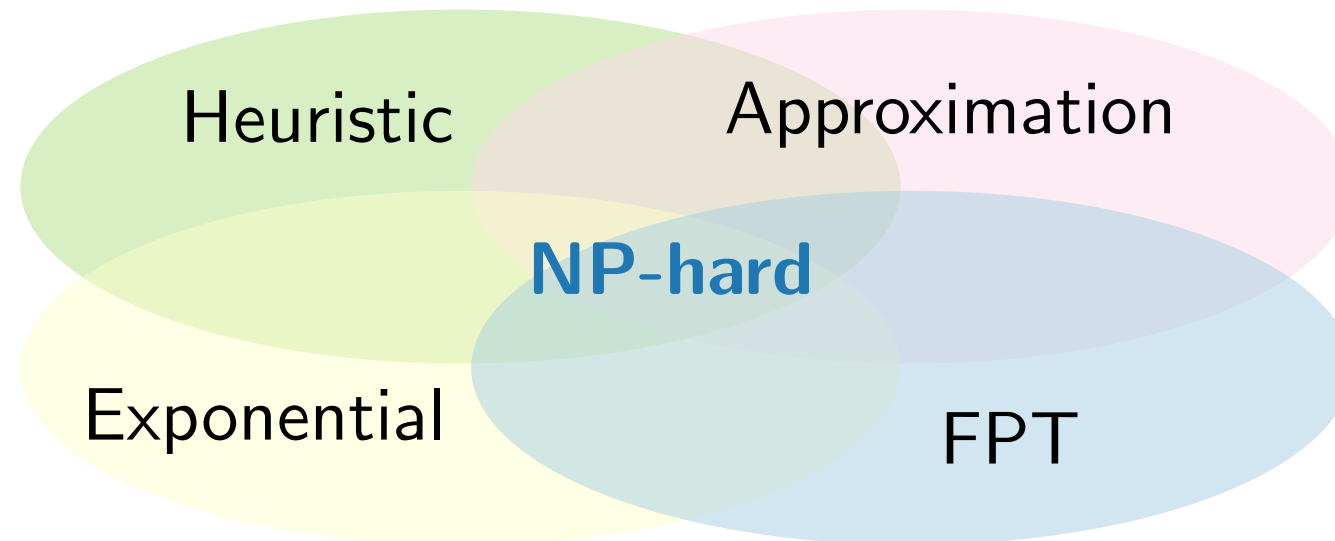
Johannes Zink · WS23/24



# Dealing with NP-Hard Optimization Problems

What should we do?

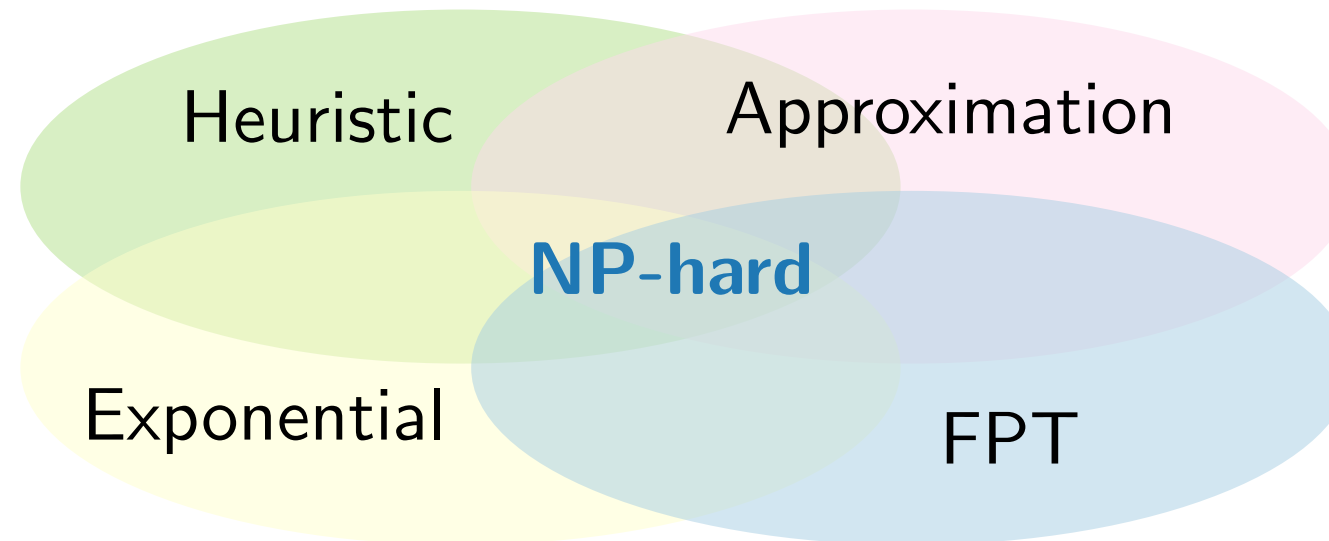
- Sacrifice optimality for speed
  - Heuristics
  - Approximation algorithms
- Optimal solutions
  - Exact exponential-time algorithms
  - Fine-grained analysis – parameterized algorithms



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PTAS  
(*polynomial-time  
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# Approximation with Additive Guarantee

## Definition.

Let  $\Pi$  be an optimization problem,  
let  $\mathcal{A}$  be a polynomial-time algorithm for  $\Pi$ ,  
let  $I$  be an instance of  $\Pi$ , and  
let  $\text{ALG}(I)$  be the value of the objective function of  
the solution that  $\mathcal{A}$  computes given  $I$ .

Then  $\mathcal{A}$  is called an **approximation algorithm with additive guarantee**  $\delta$  (which can depend on  $I$ ) if

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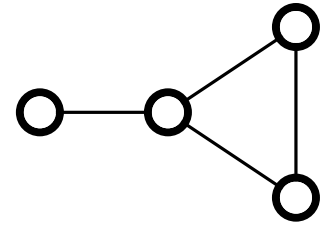
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- Most problems that we know do not admit an approximation algorithm with additive guarantee.

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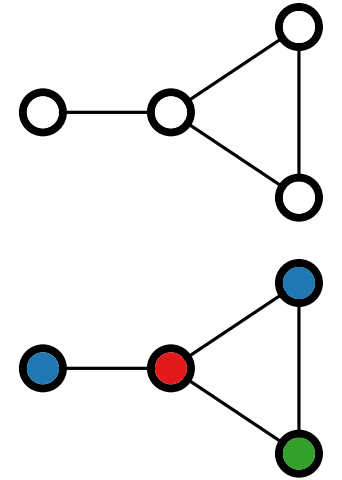
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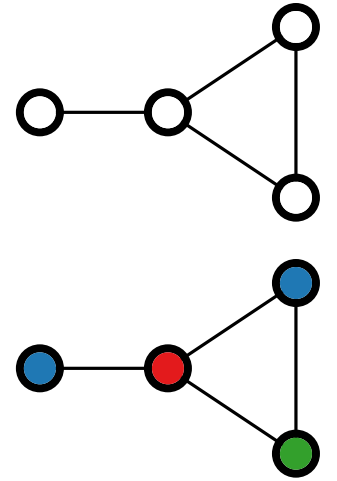


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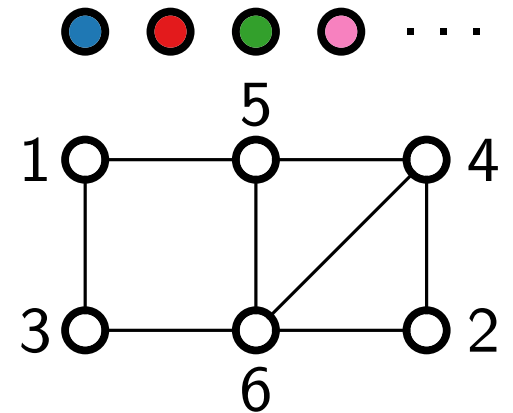
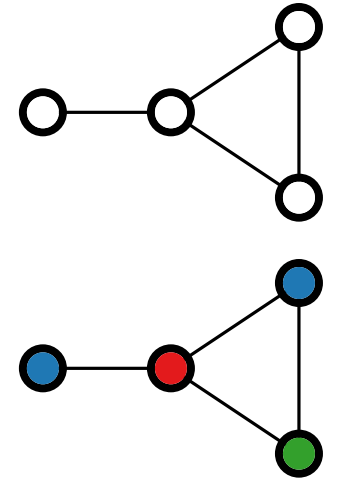
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Color vertices in some order with the lowest feasible color.



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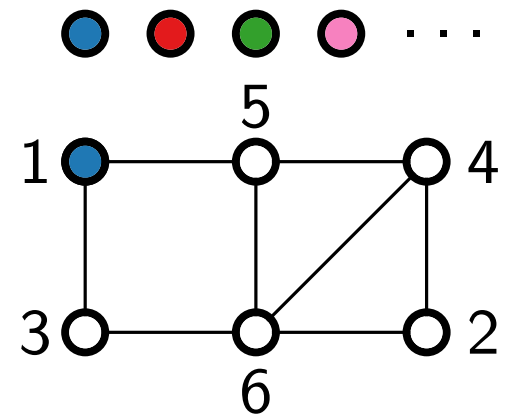
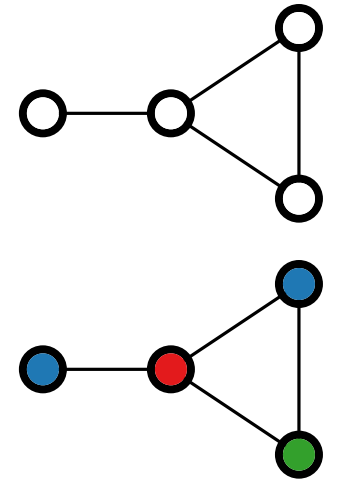
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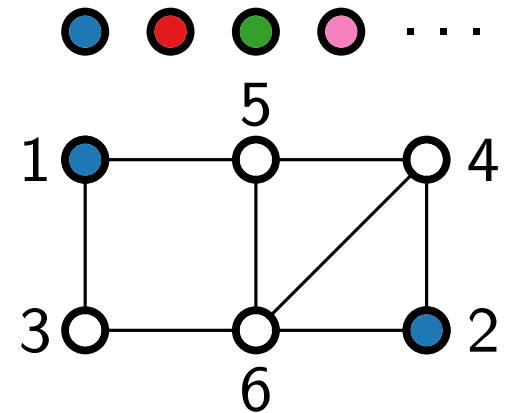
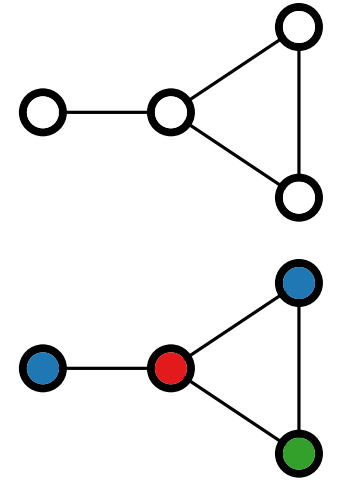
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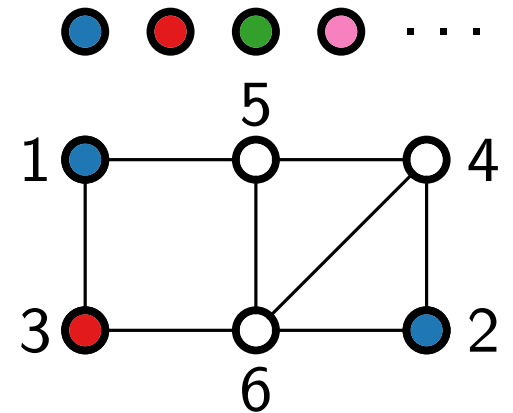
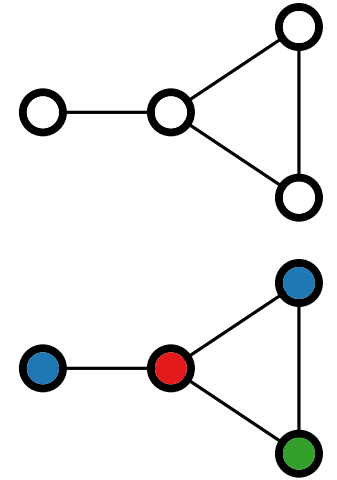
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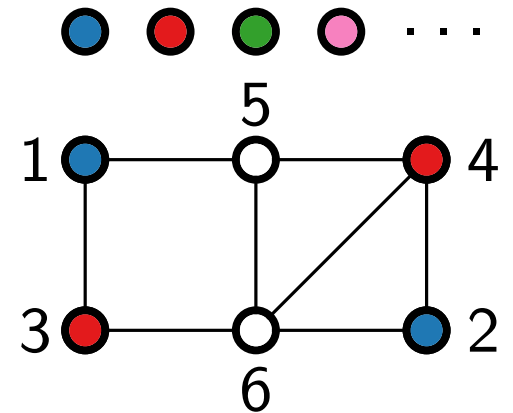
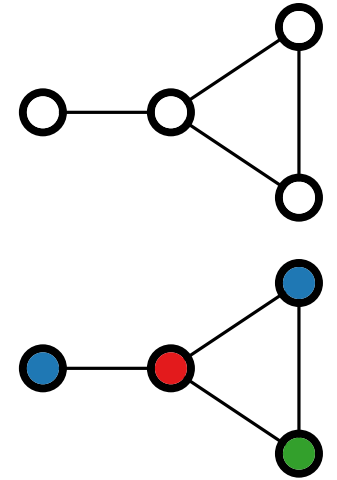
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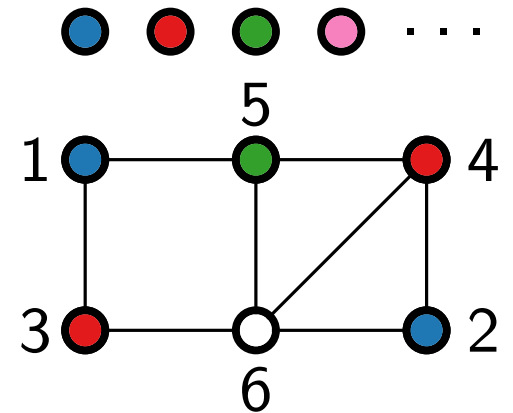
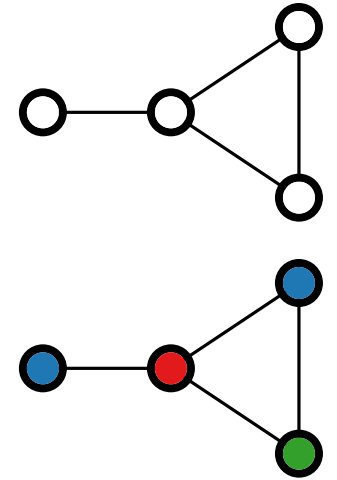
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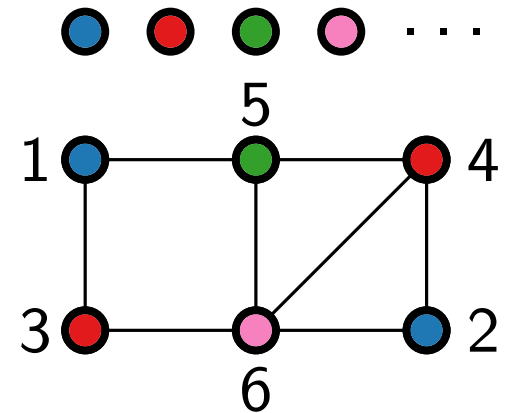
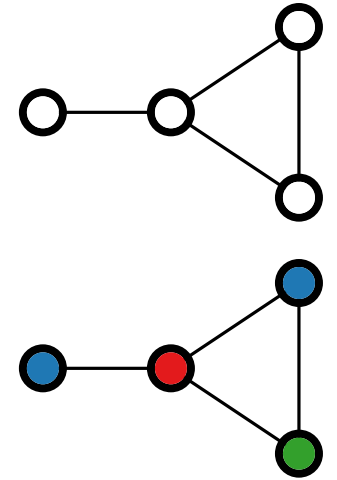
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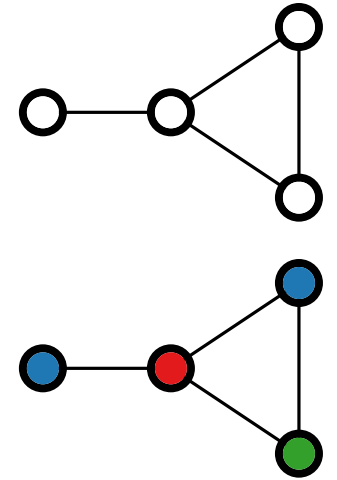


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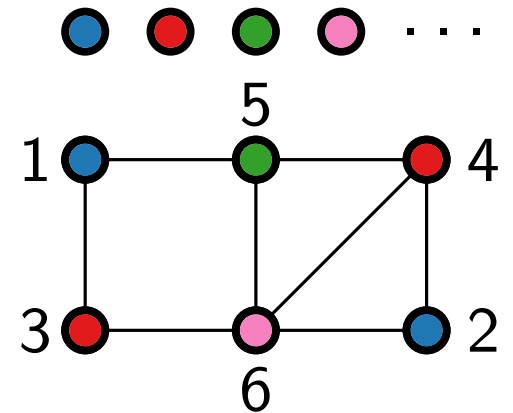
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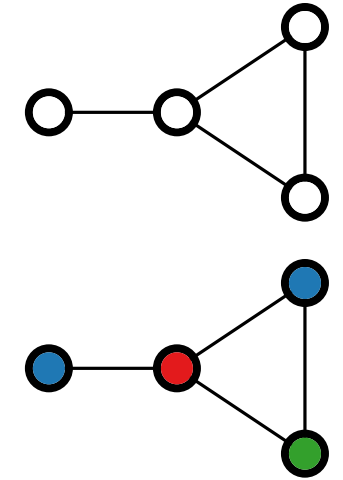
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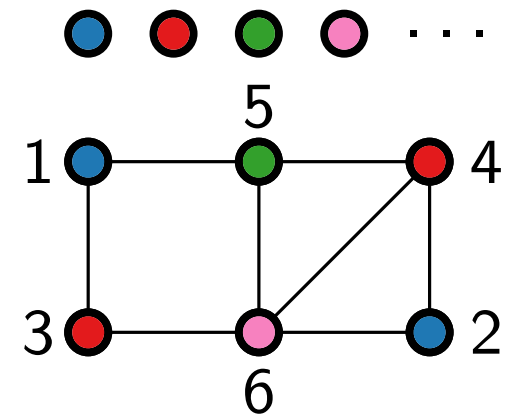
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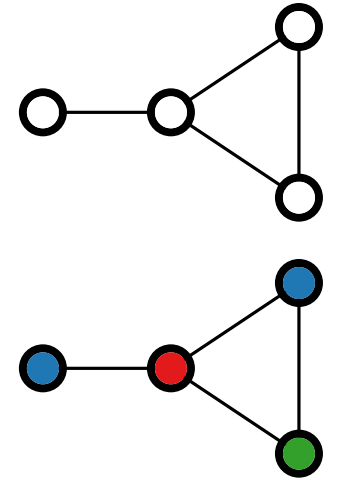
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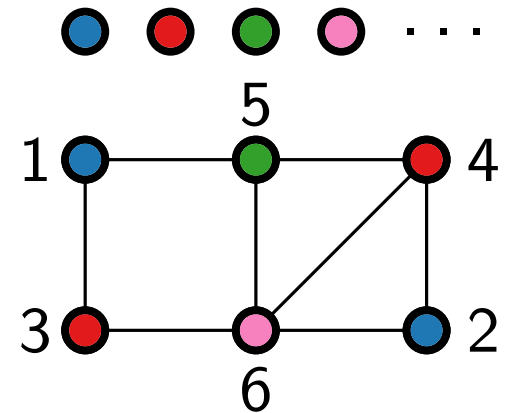
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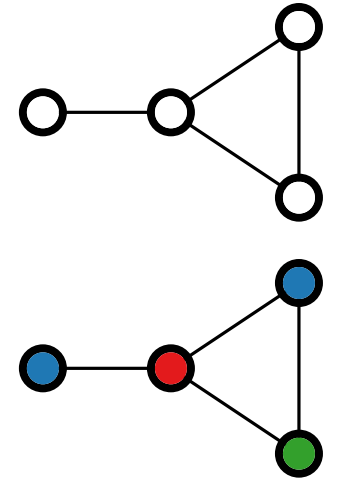
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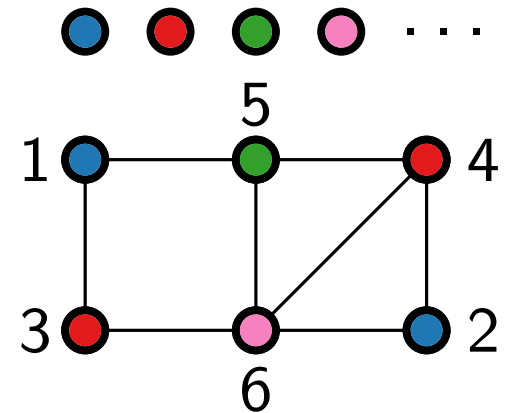
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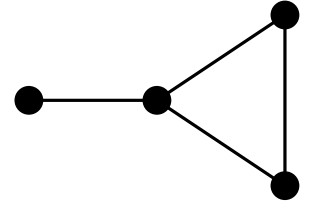
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We can even get  $\Delta - 2$  if we return a 2-coloring whenever  $G$  is bipartite.

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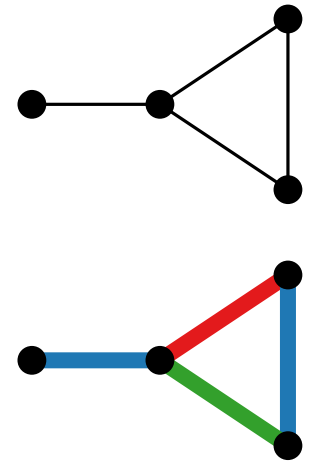




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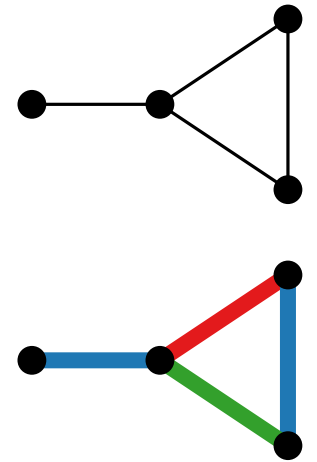


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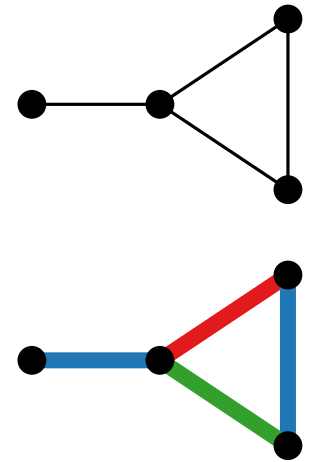


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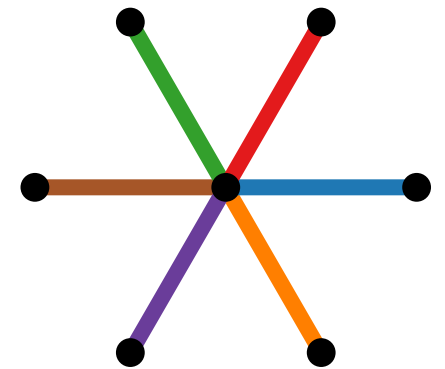
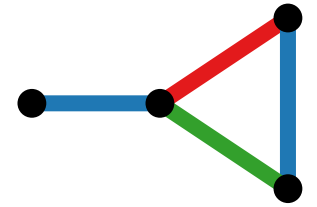
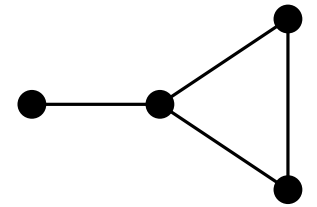


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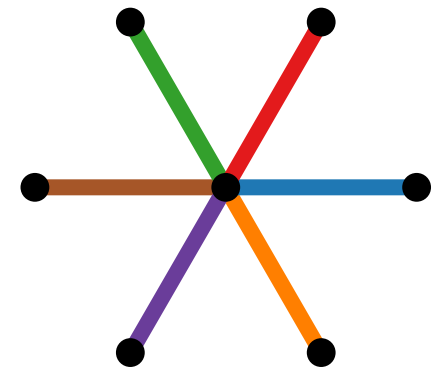
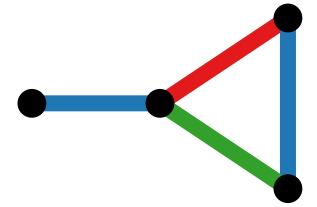
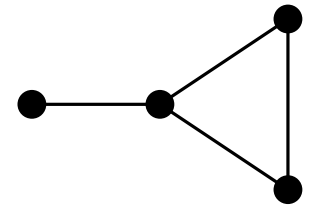


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- We show that  $\chi'(G) \leq \Delta + 1$ .



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## Vizing's Theorem.

For every graph  $G = (V, E)$  with maximum degree  $\Delta$ , it holds that  $\Delta \leq \chi'(G) \leq \Delta + 1$ .



Vadim G. Vizing  
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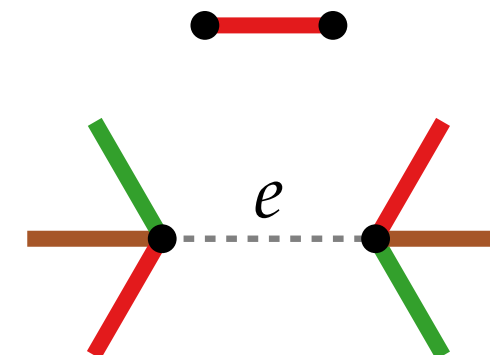
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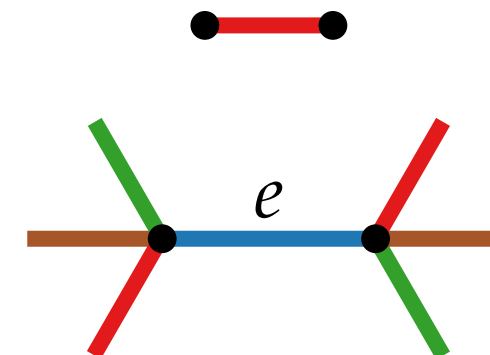
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- If  $\Delta(G) > \Delta(G - e)$ , color  $e$  with color  $\Delta(G) + 1$ .
- If  $\Delta(G) = \Delta(G - e)$ , change the coloring such that  $u$  and  $v$  miss the same color  $\alpha$ .



Vadim G. Vizing  
(Kiev 1937 – 2017 Odessa)

# Minimum Edge Coloring – Upper Bound

## Vizing's Theorem.

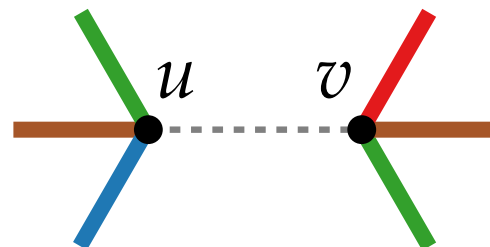
For every graph  $G = (V, E)$  with maximum degree  $\Delta$ , it holds that  $\Delta \leq \chi'(G) \leq \Delta + 1$ .

**Proof** by induction on  $m = |E|$ .

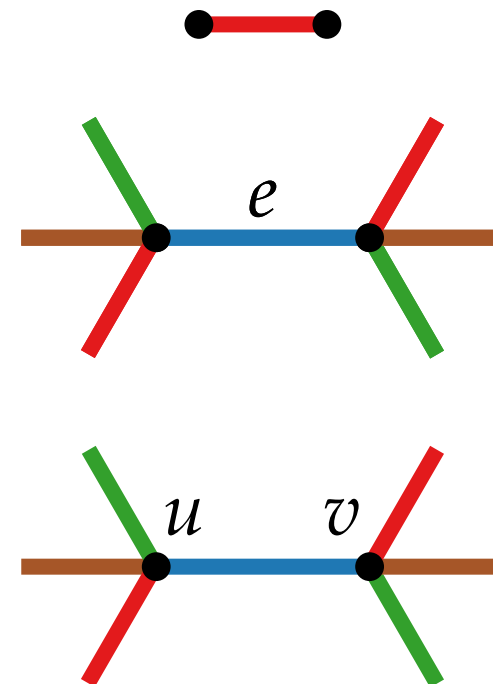
- Base case  $m = 1$  is trivial.

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- By induction,  $G - e$  has a  $(\Delta(G - e) + 1)$ -edge coloring.
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- Then color  $e$  with  $\alpha$ .



Lemma 2  
(next slide)



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# Minimum Edge Coloring – Recoloring

## Lemma 2.

Let  $G$  be a graph with a  $(\Delta + 1)$ -edge coloring  $c$ ,  
let  $u, v$  be non-adjacent vertices with  $\deg(u), \deg(v) < \Delta$ .  
Then  $c$  can be changed s.t.  $u$  and  $v$  miss the same color.

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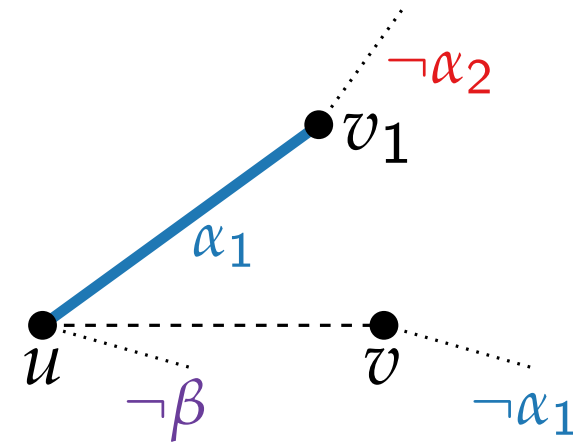
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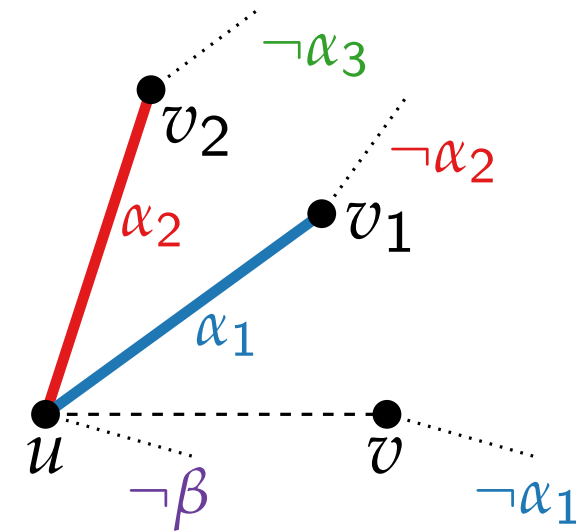
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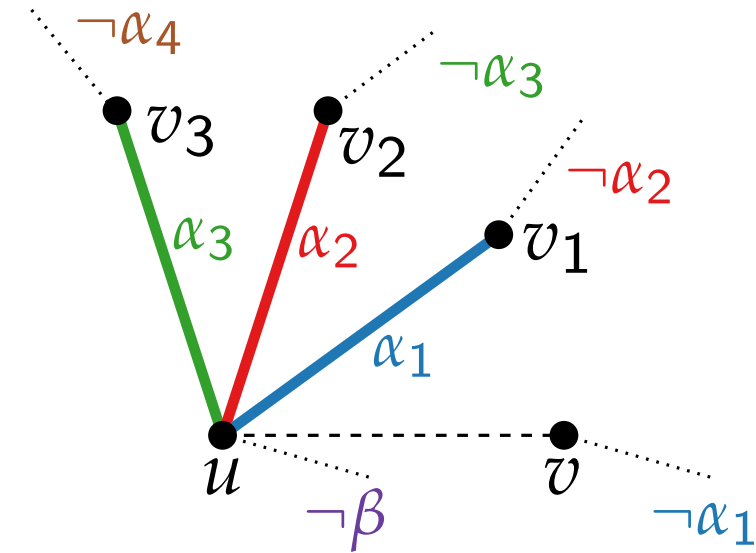
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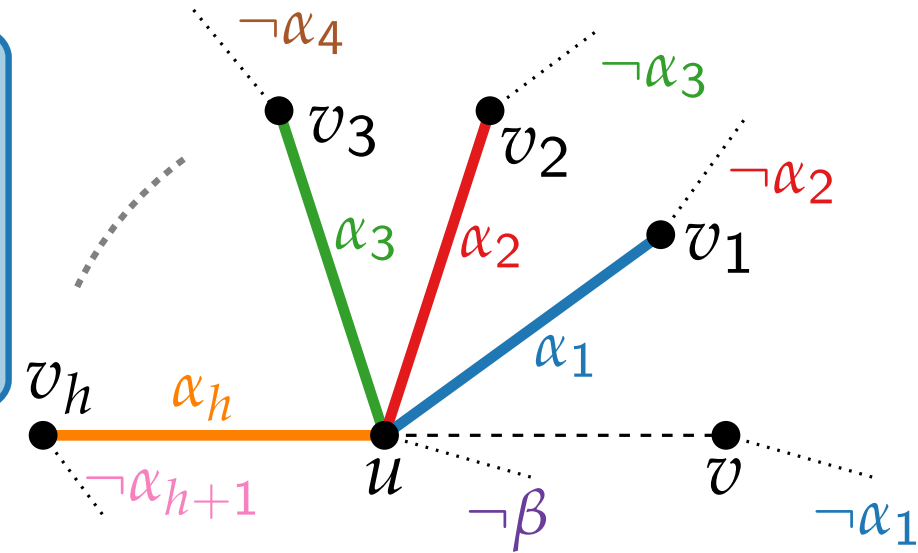
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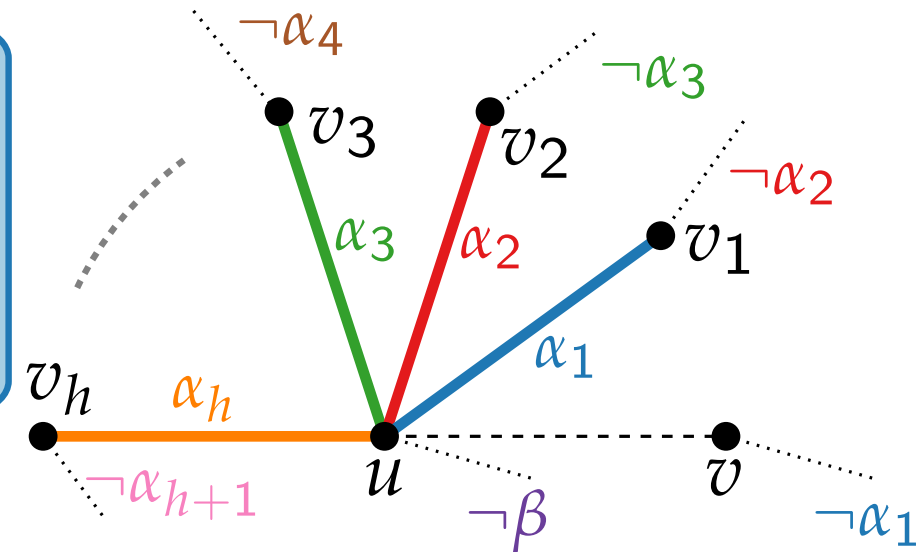
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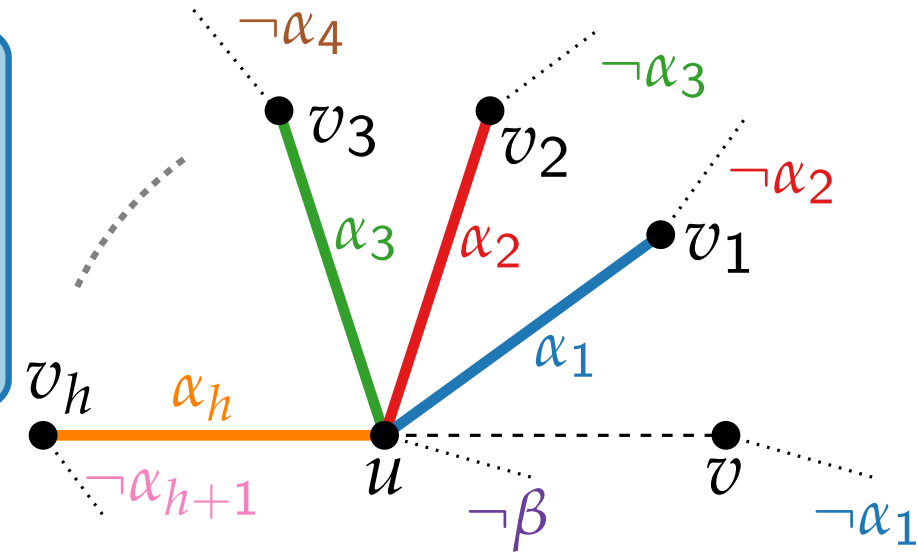
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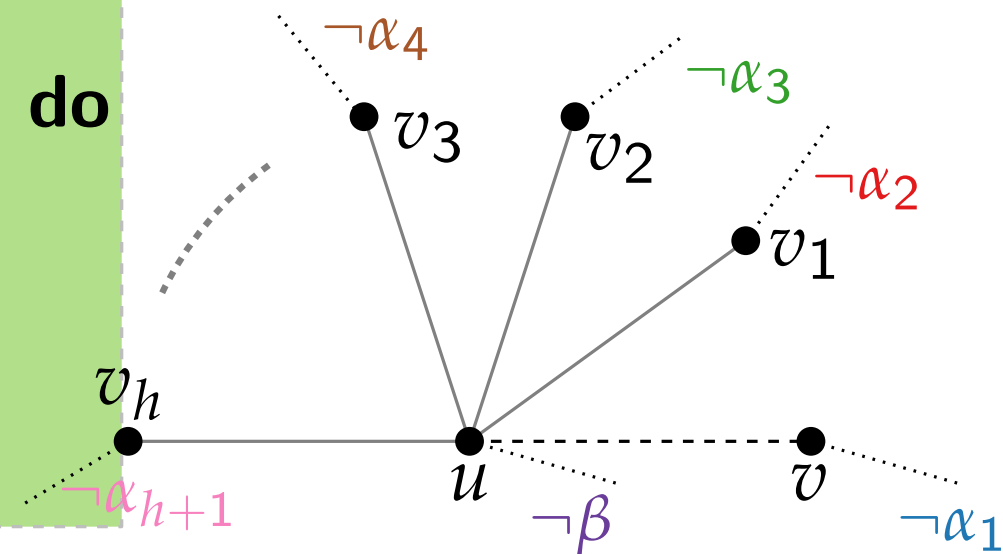
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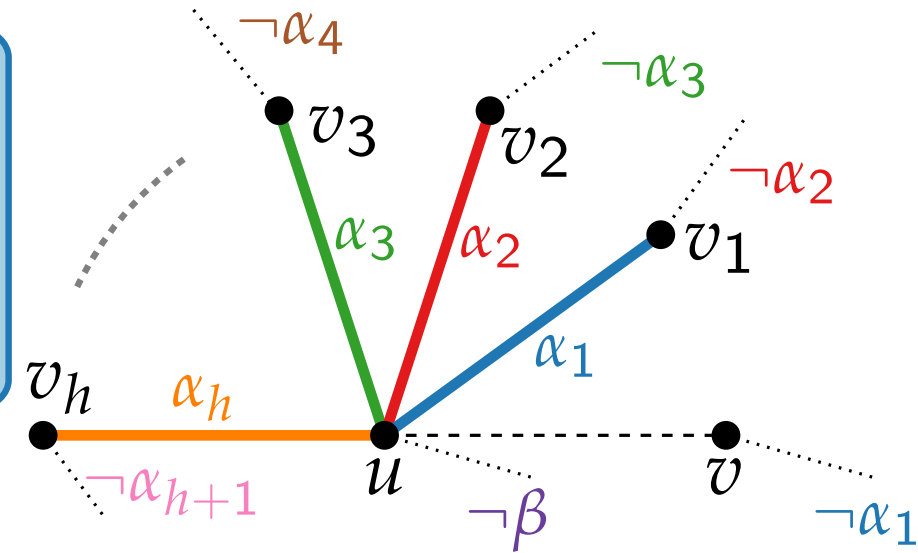
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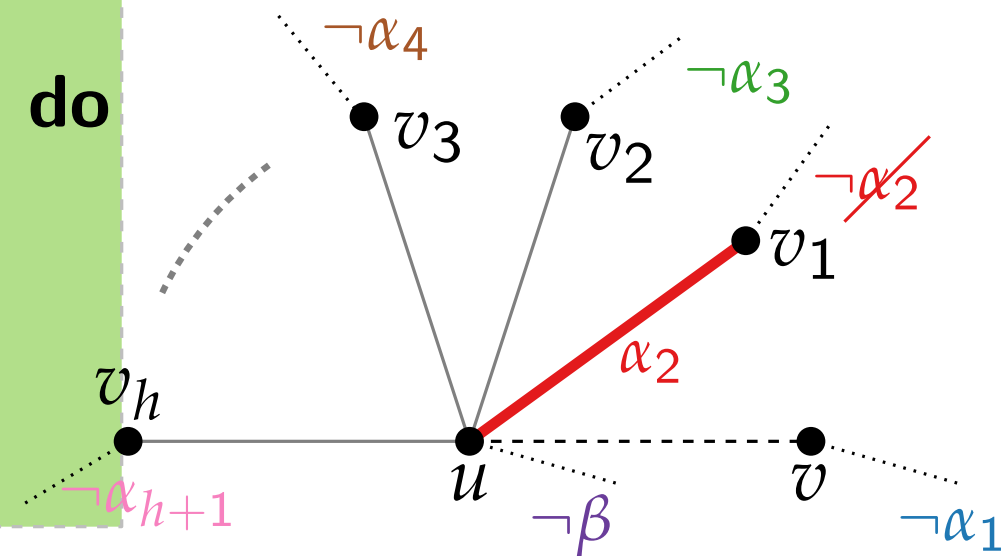
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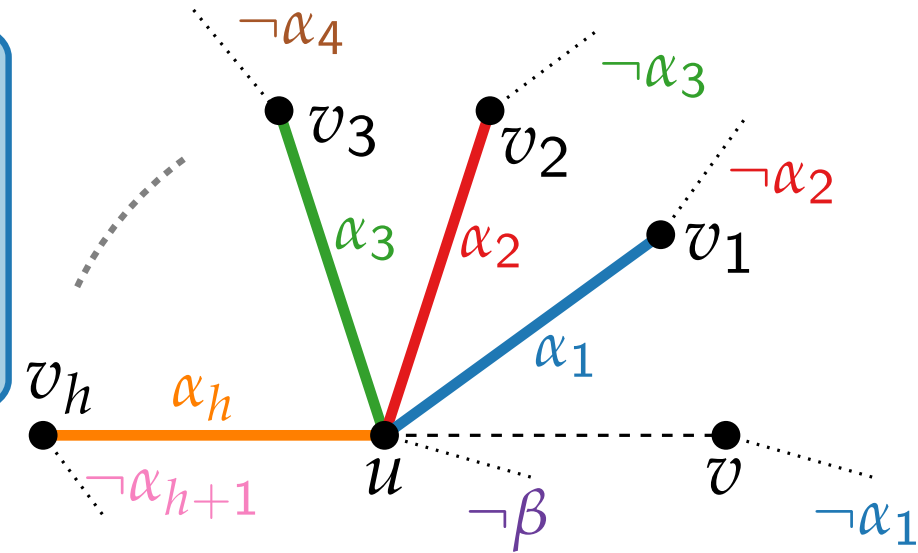
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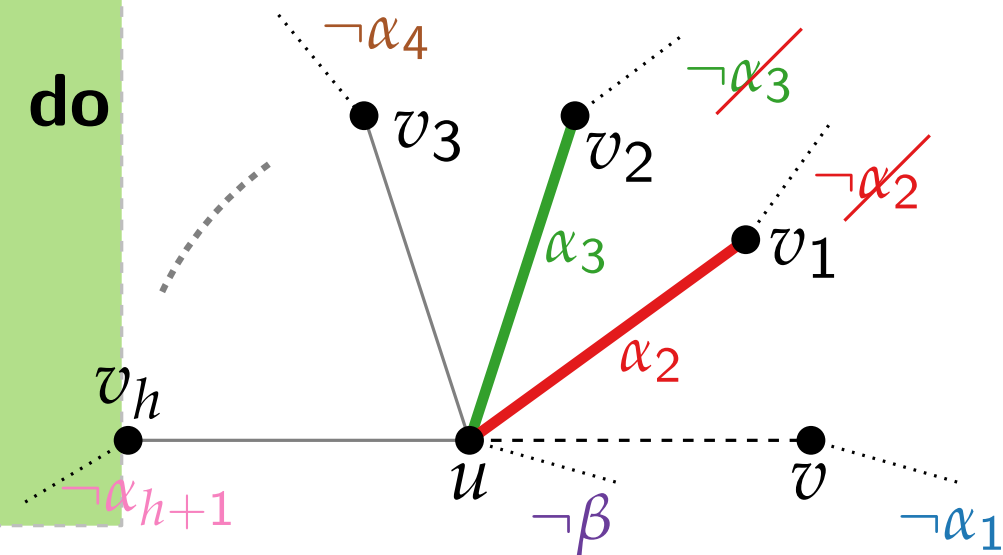
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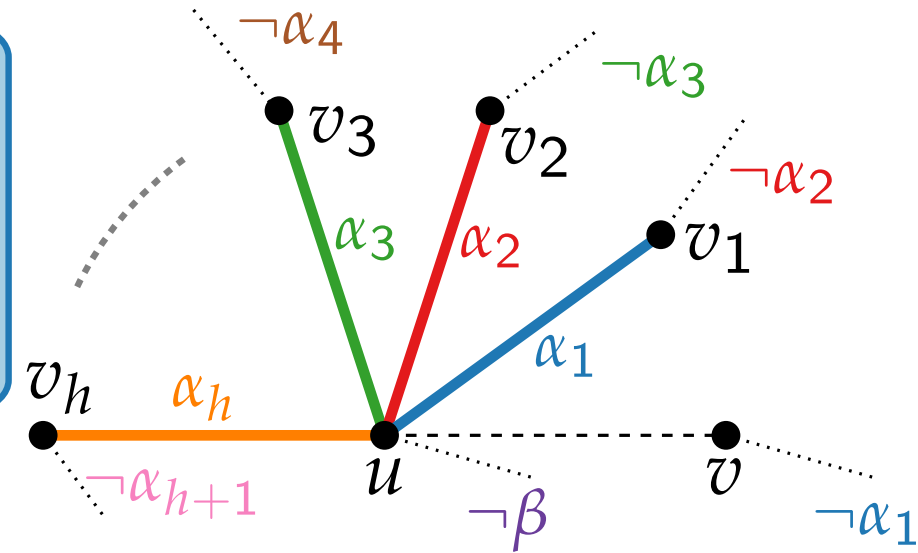
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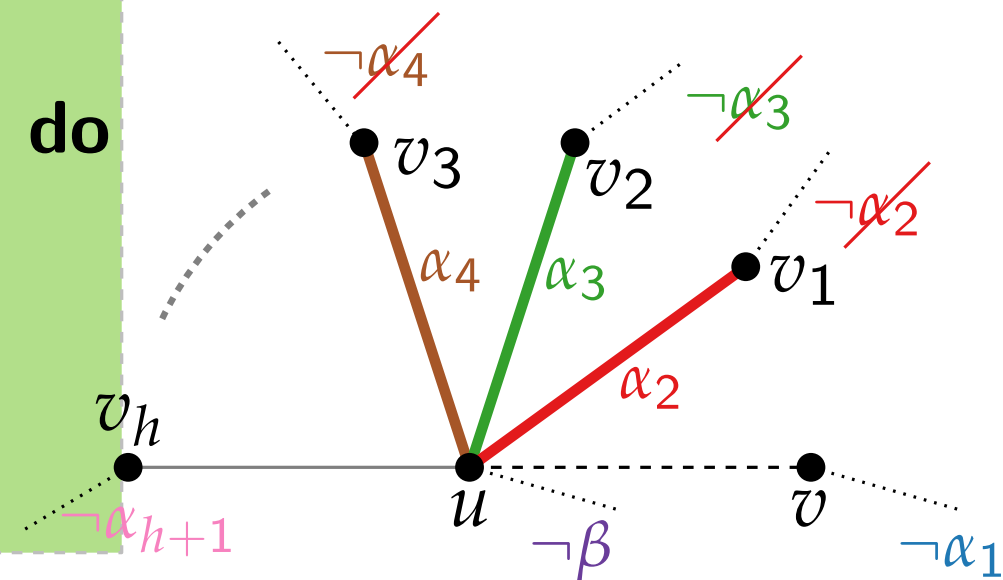
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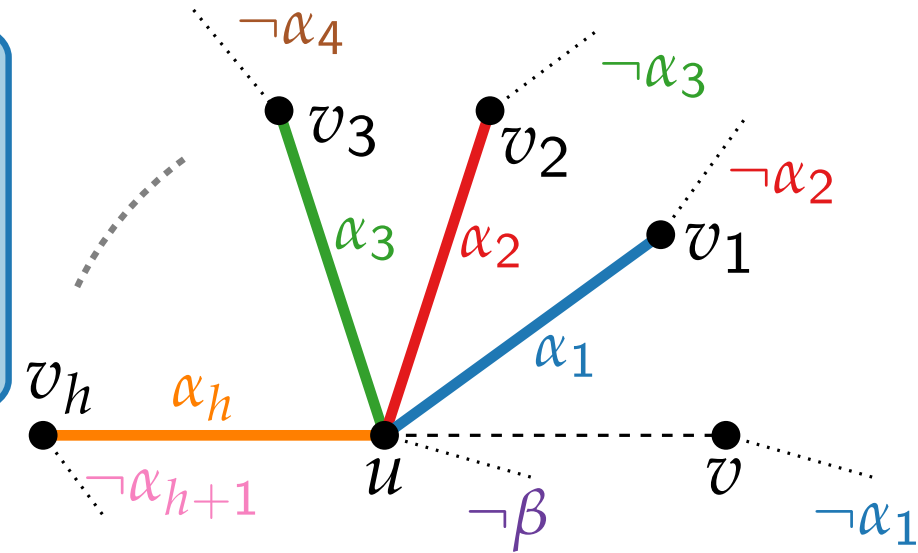
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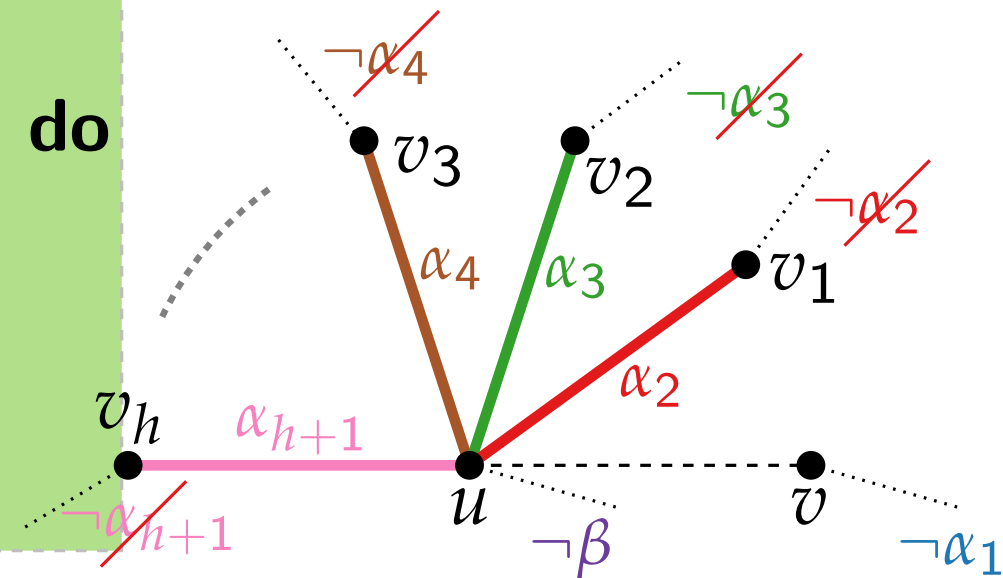
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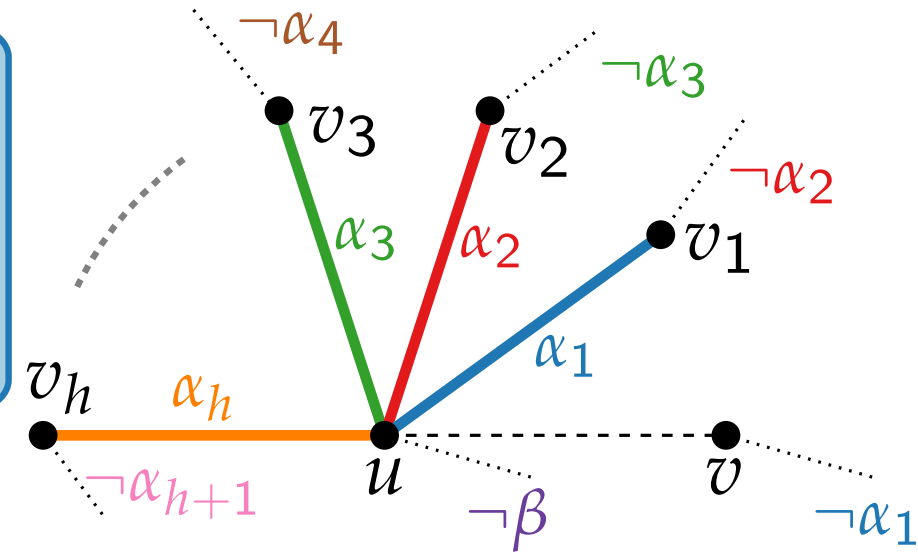
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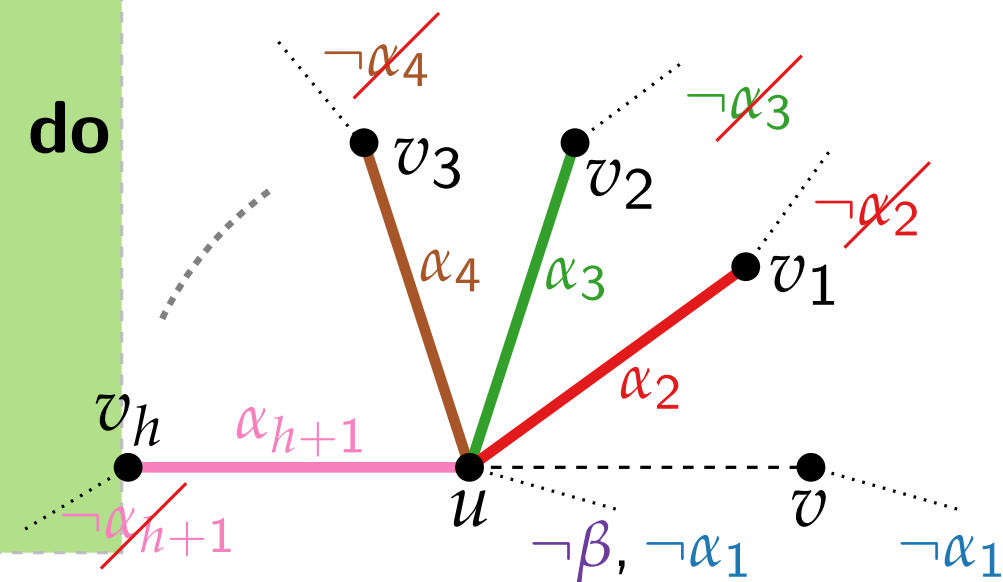
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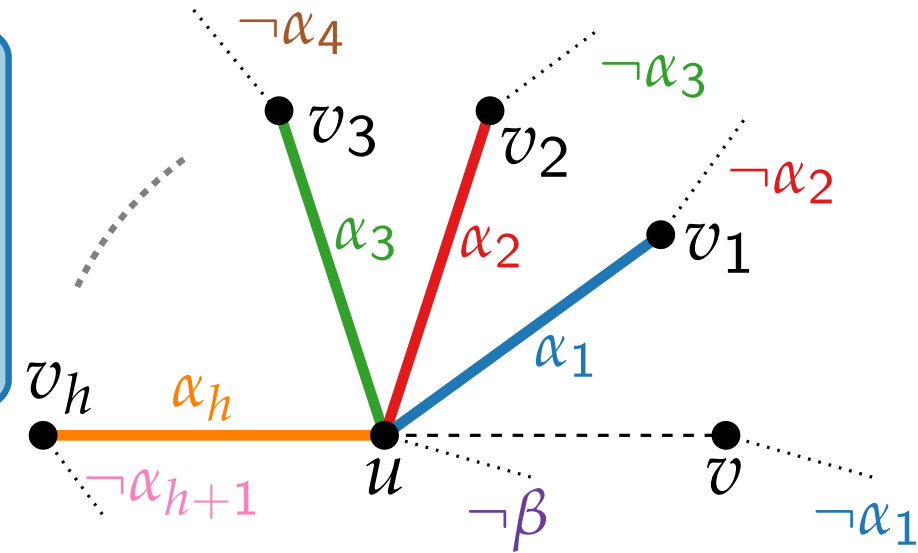
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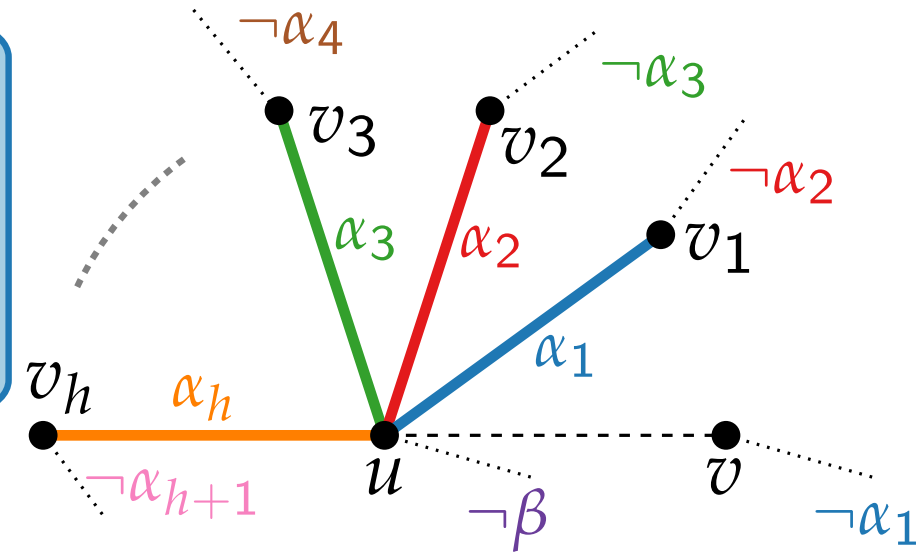
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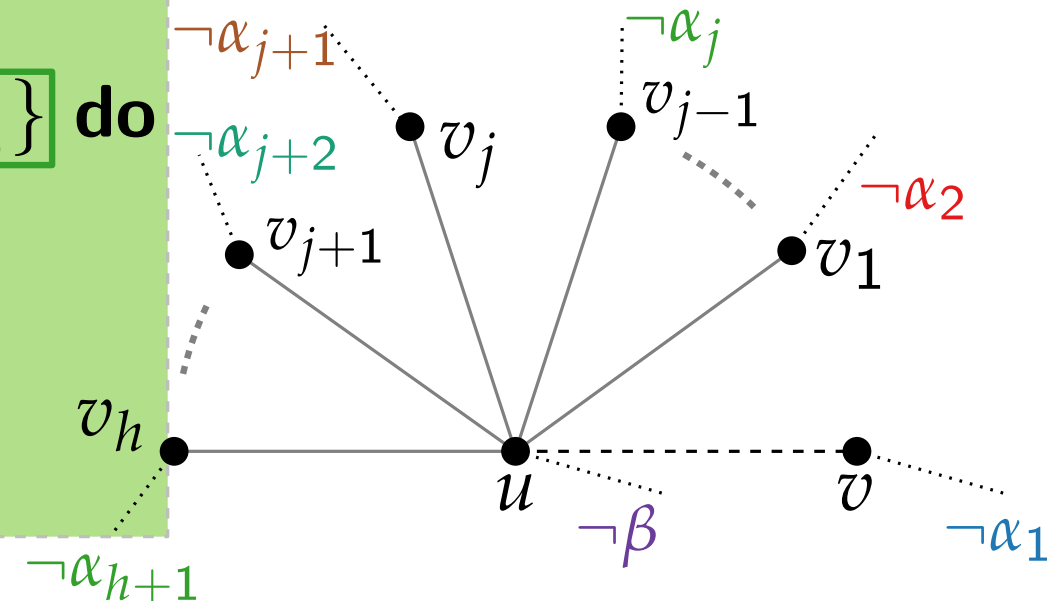
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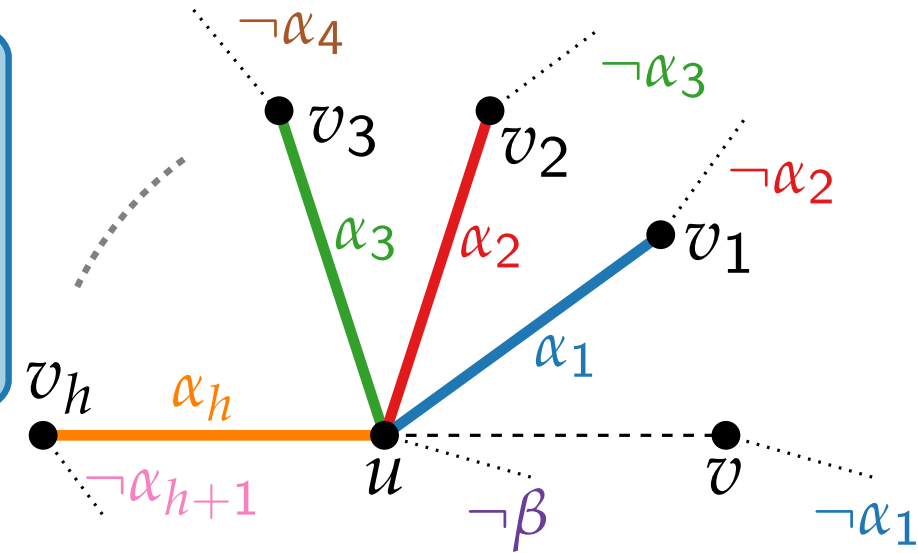
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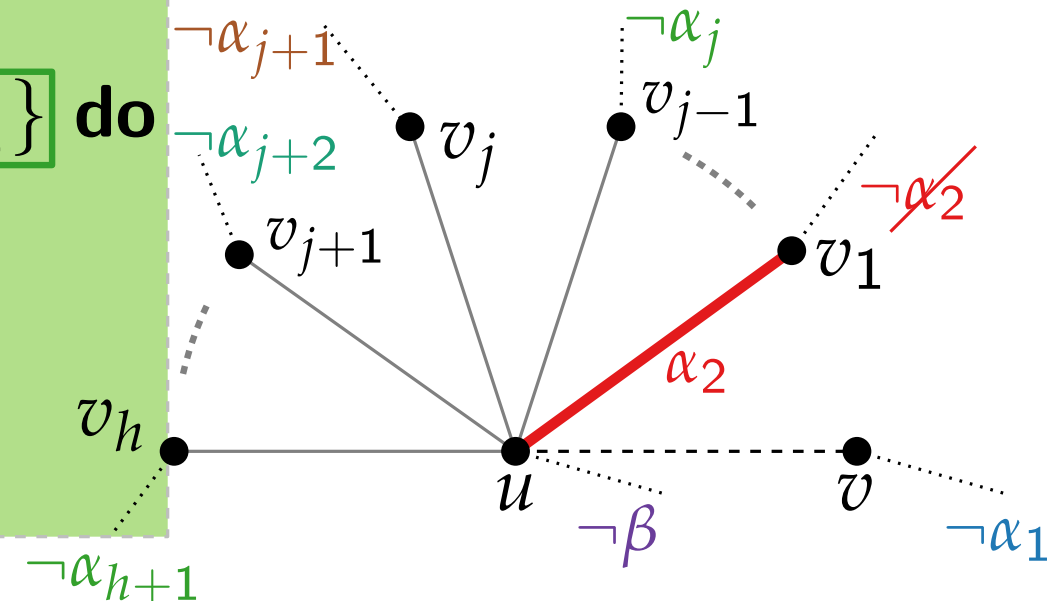
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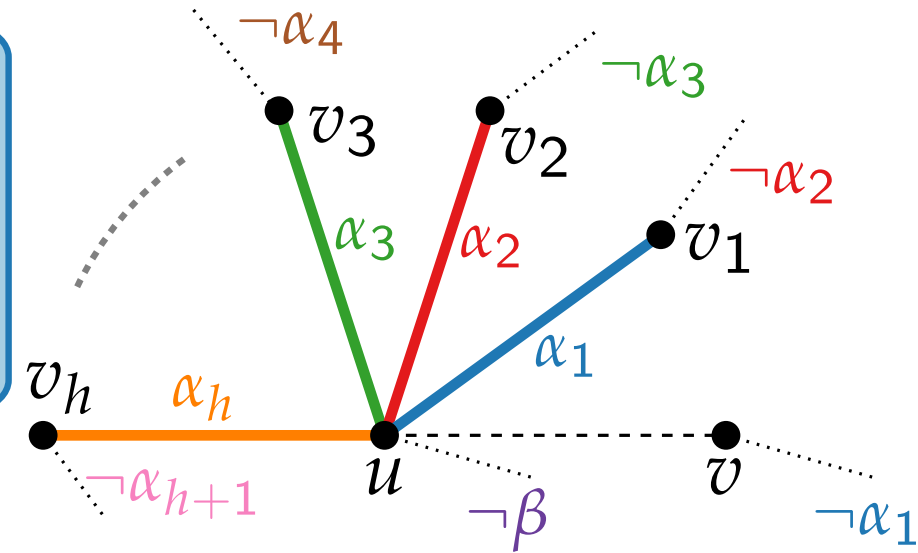
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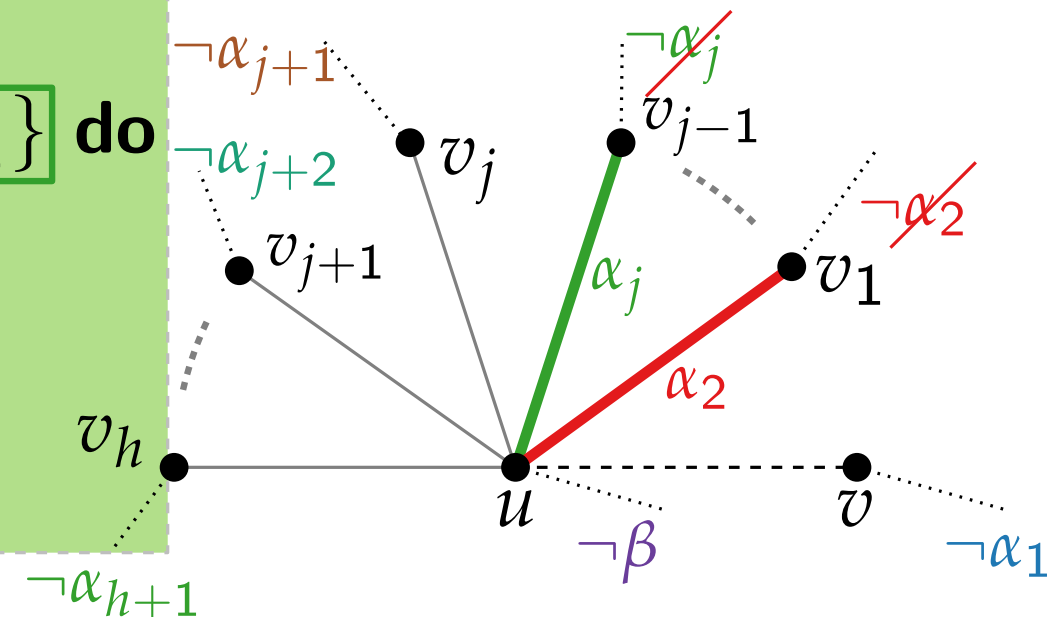
$\alpha_{i+1} \leftarrow$  min color missing at  $w$

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**return**  $v_1, \dots, v_i; \alpha_1, \dots, \alpha_{i+1}$



Case 2:  $\alpha_{h+1} = \alpha_j, j < h$ .



# Minimum Edge Coloring – Recoloring

## Lemma 2.

Let  $G$  be a graph with a  $(\Delta + 1)$ -edge coloring  $c$ , let  $u, v$  be non-adjacent vertices with  $\deg(u), \deg(v) < \Delta$ . Then  $c$  can be changed s.t.  $u$  and  $v$  miss the same color.

**Proof.** Note that every vertex is **missing** a color.

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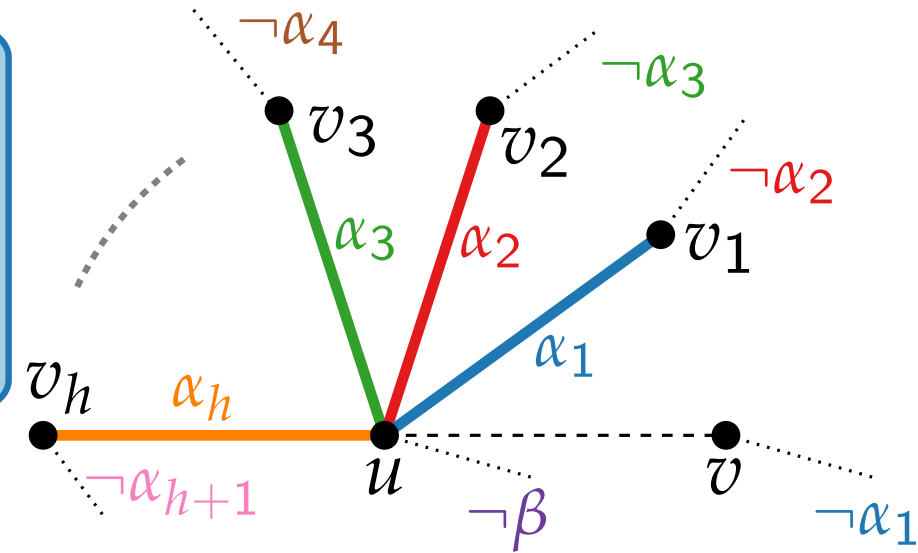
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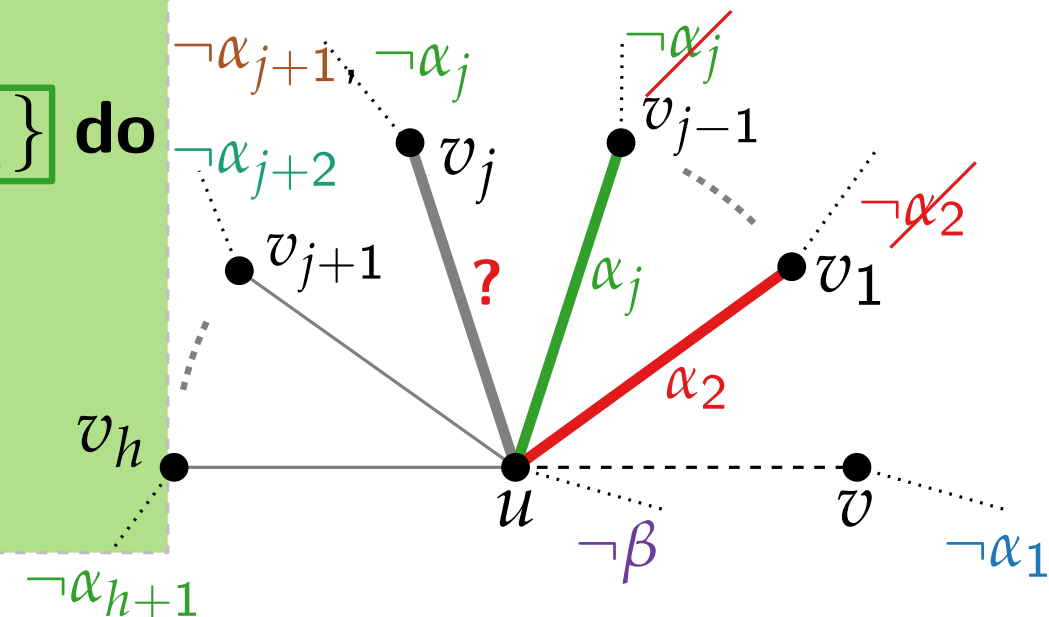
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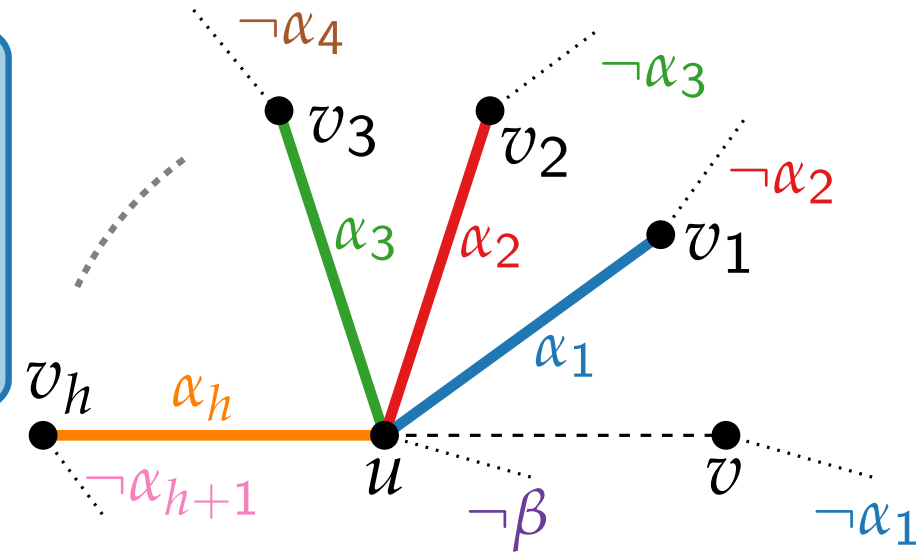
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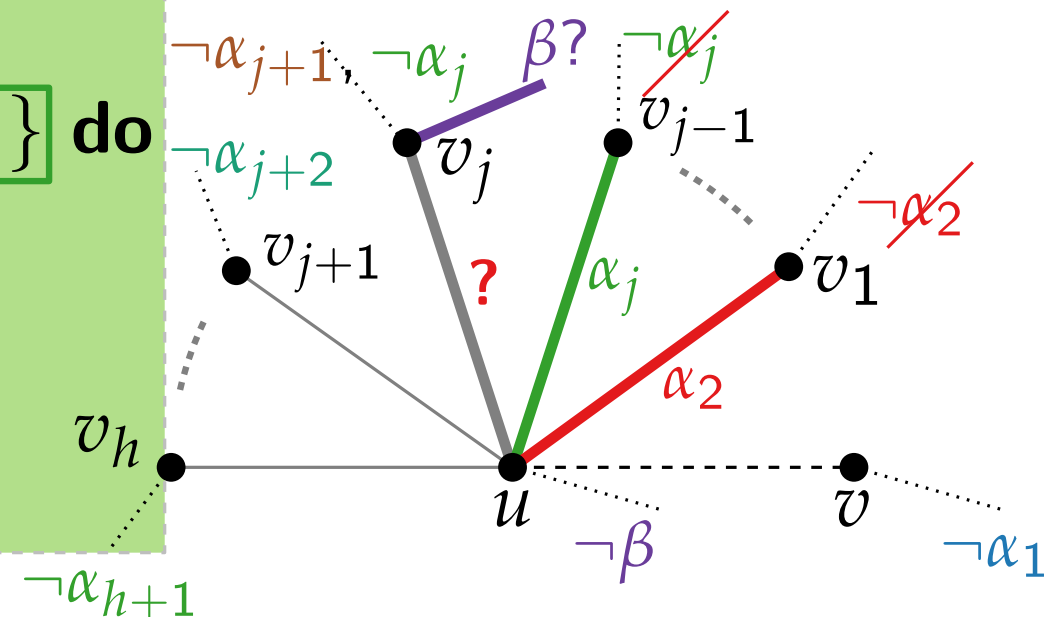
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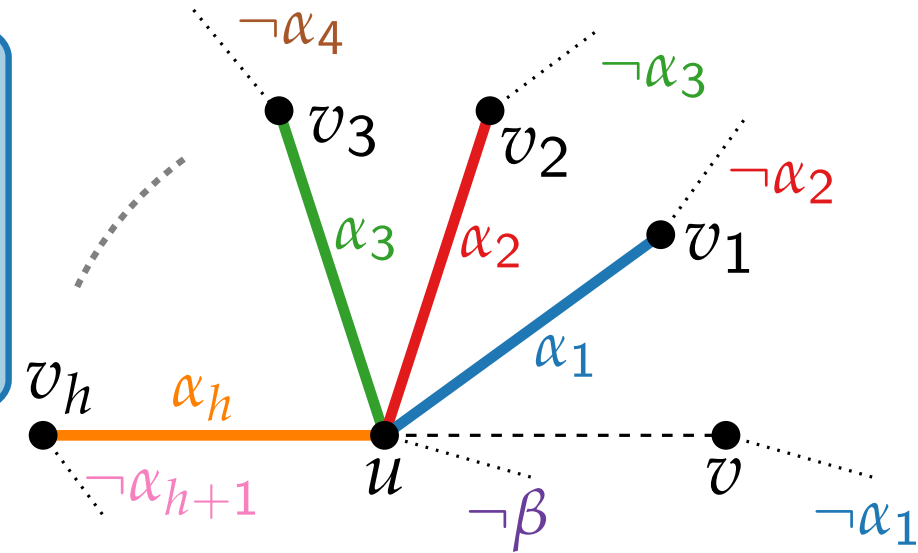
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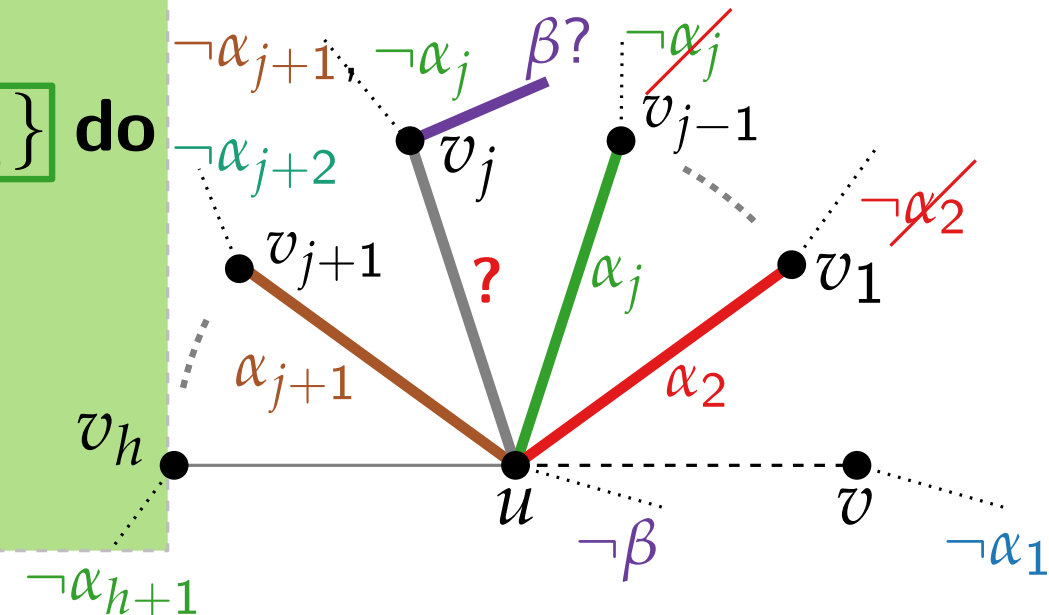
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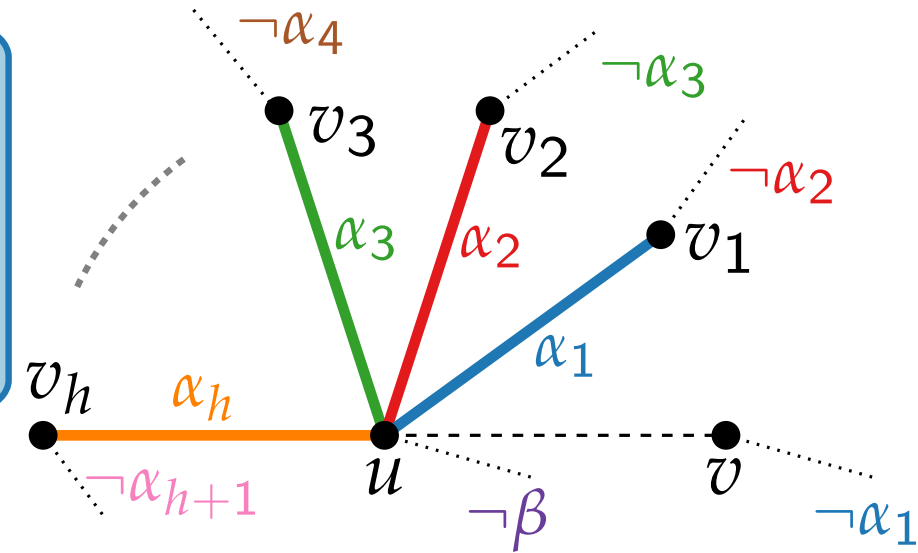
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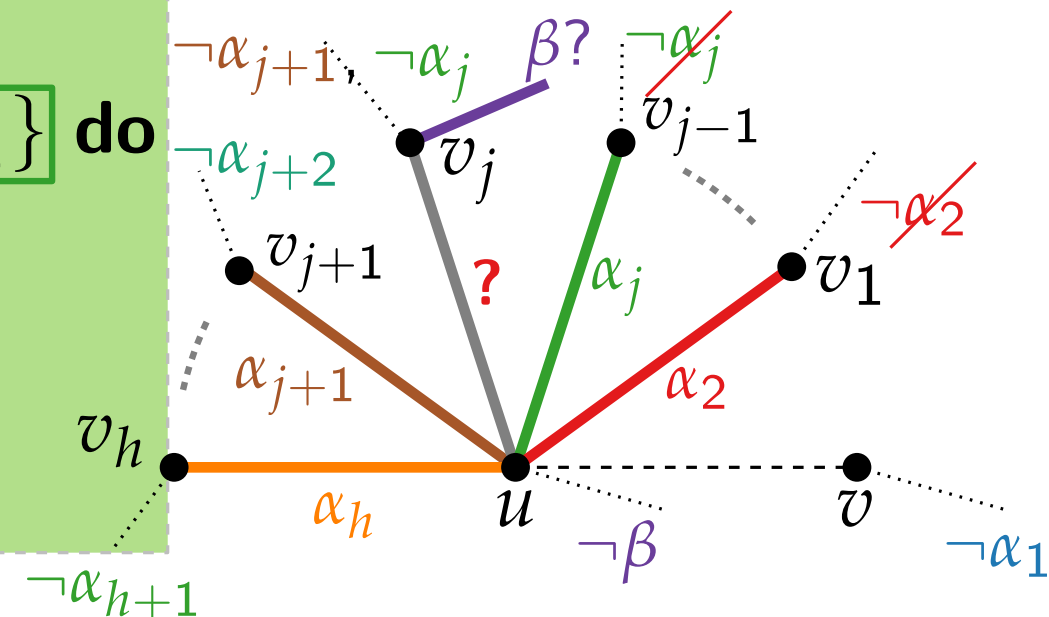
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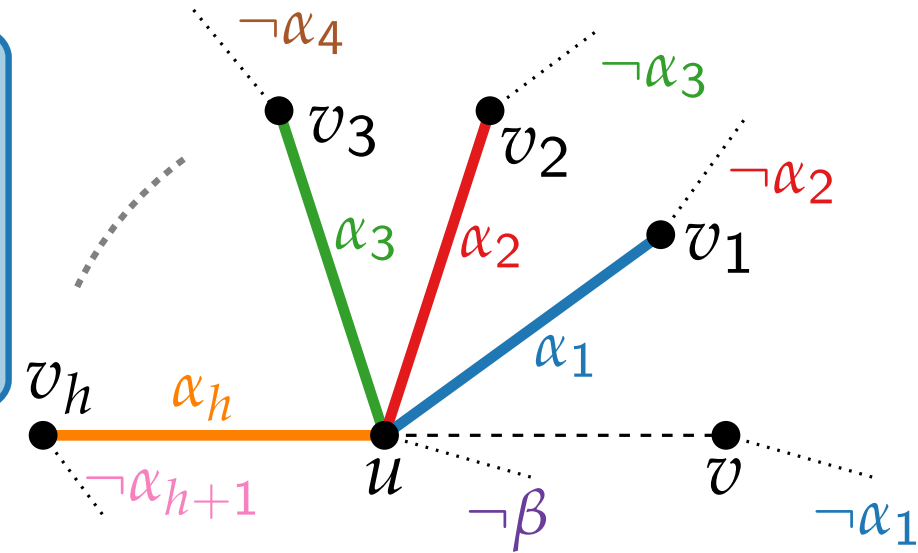
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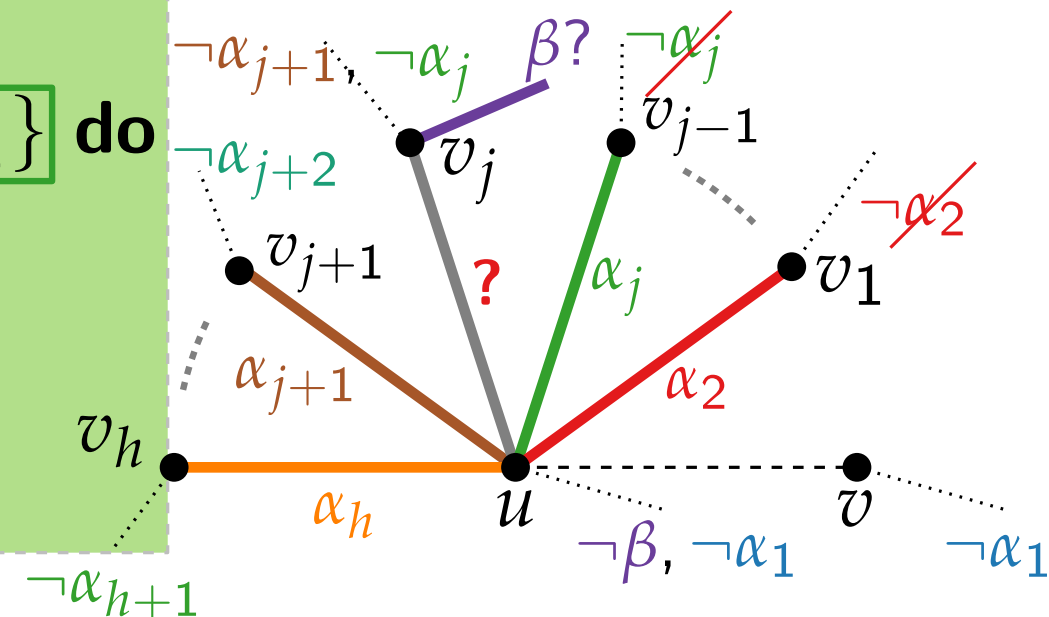
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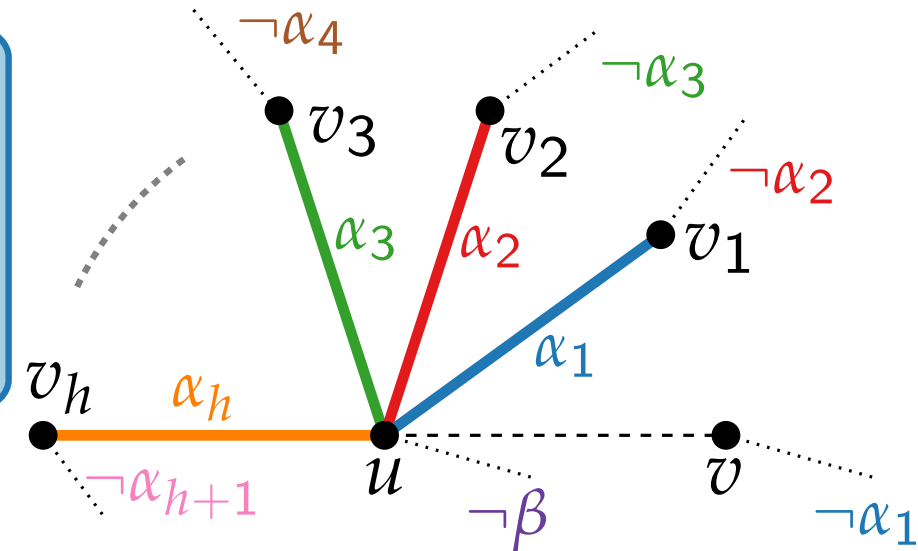
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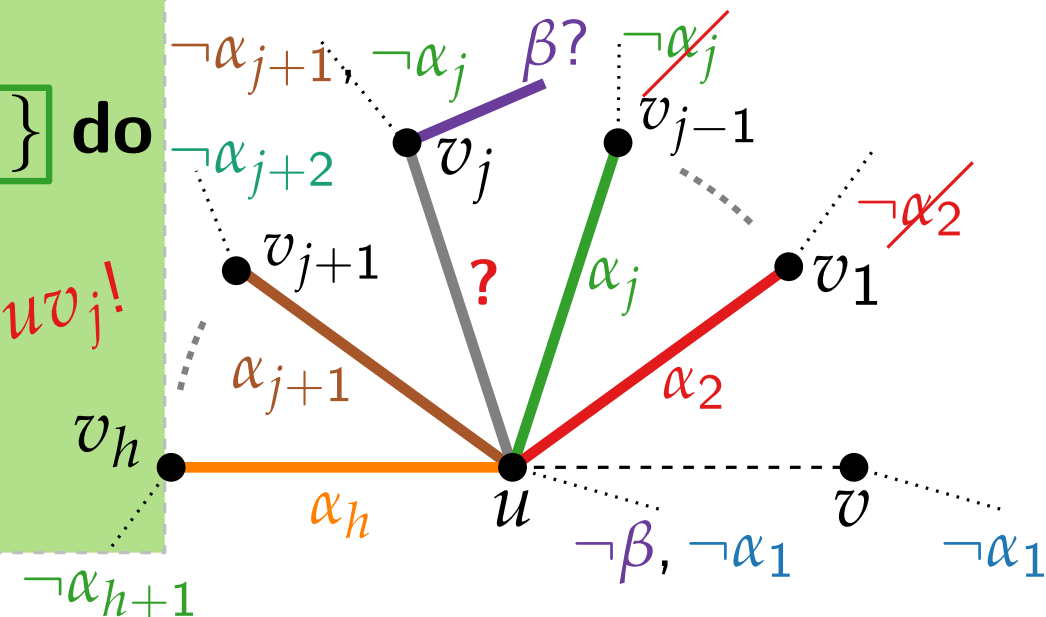
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Need color for edge  $uv_j!$

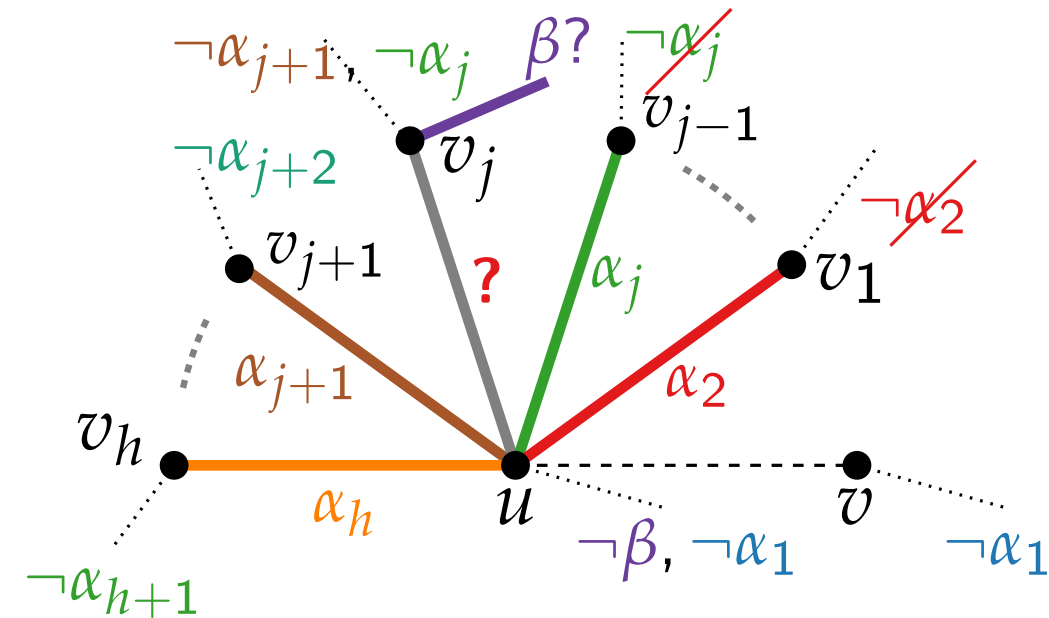


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# Minimum Edge Coloring – Recoloring

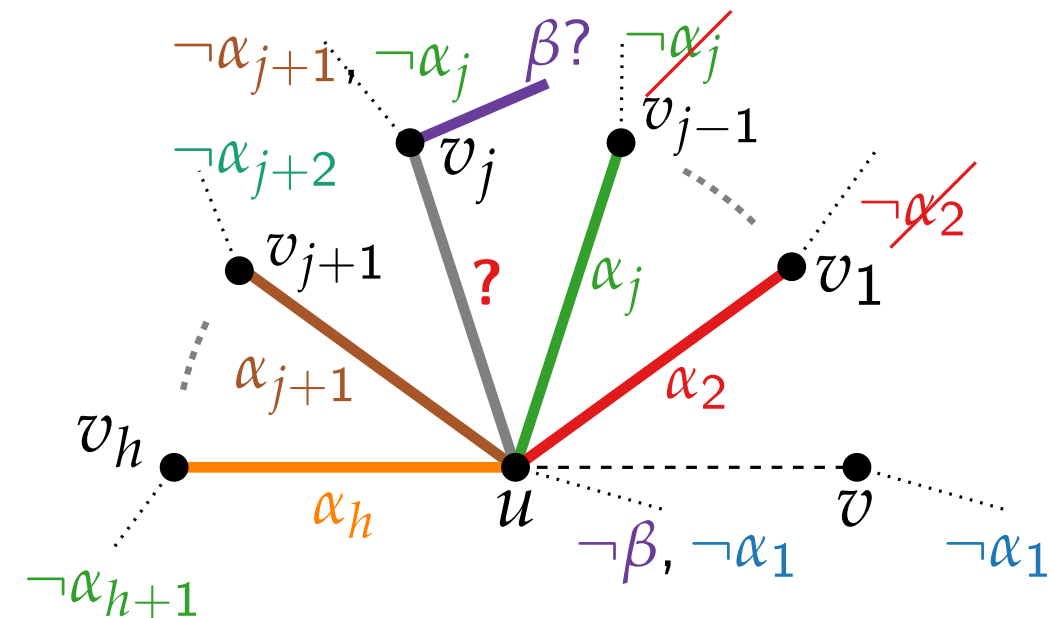
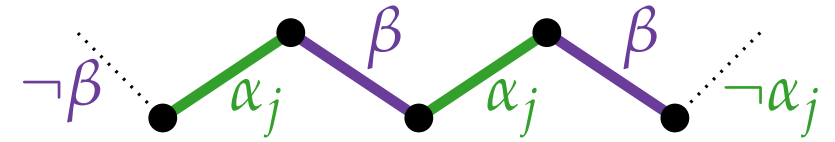
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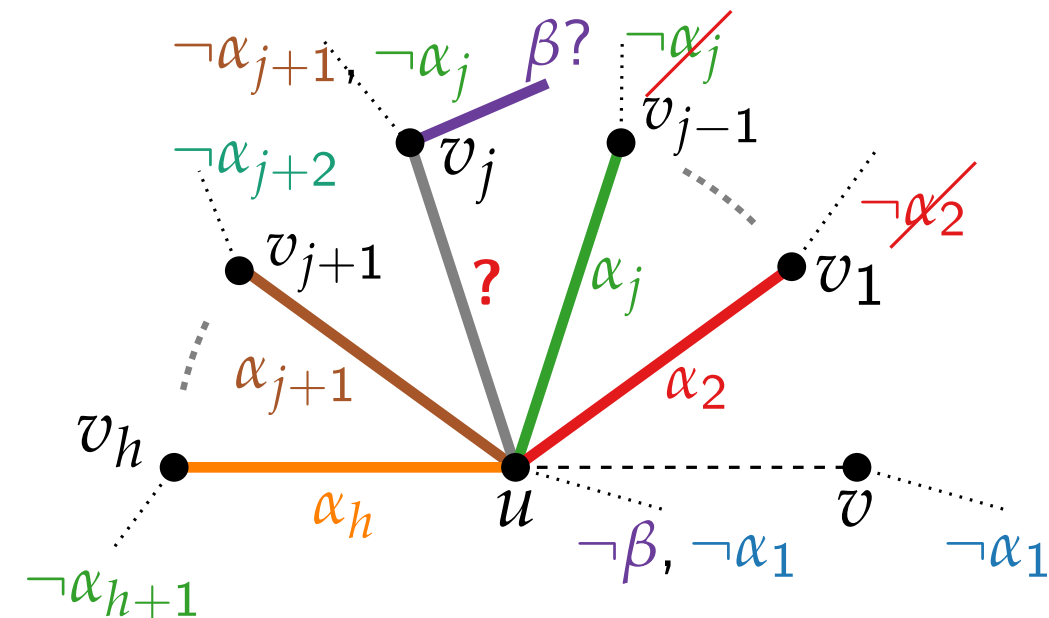
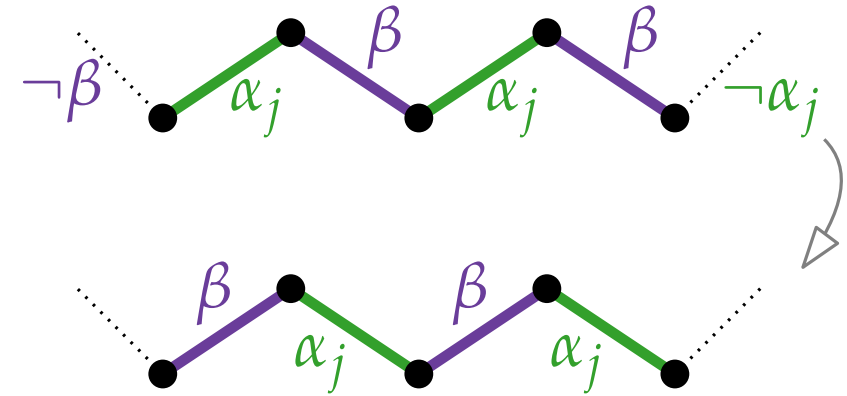
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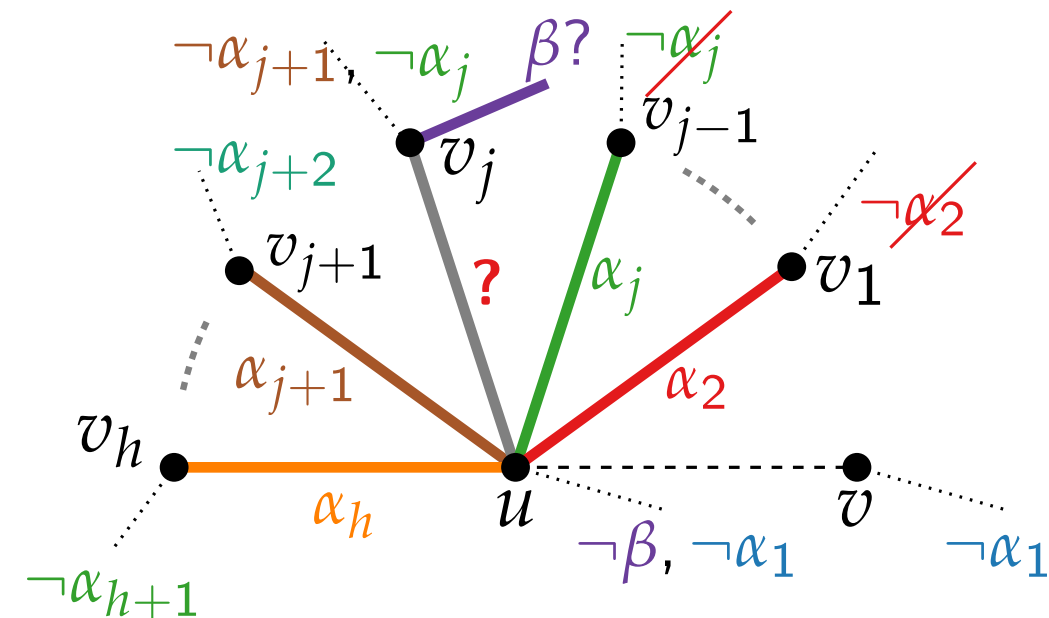
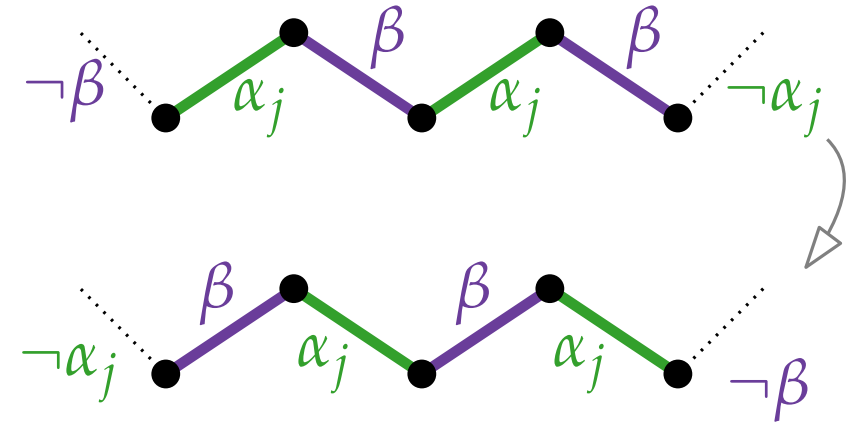
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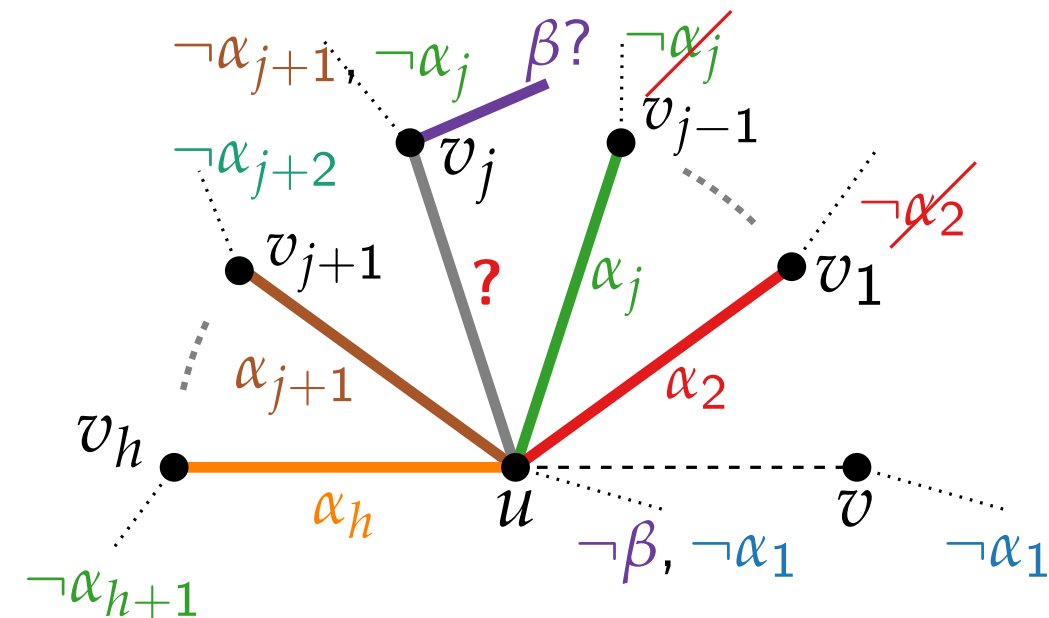
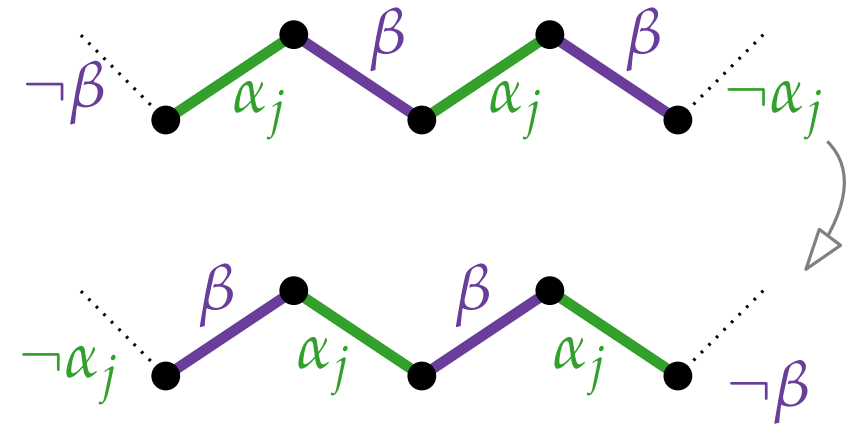




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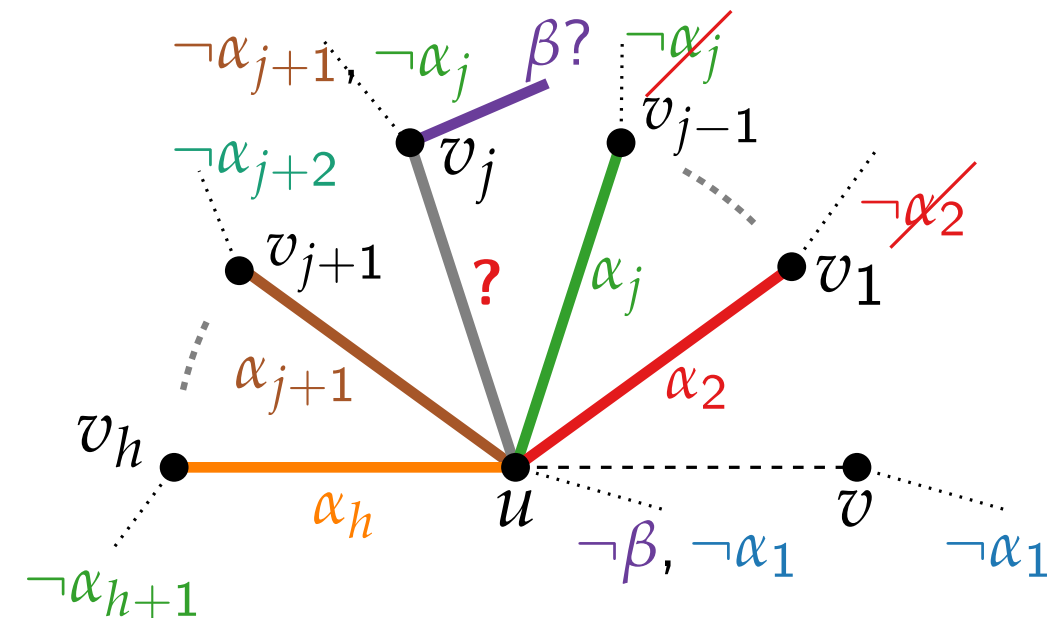
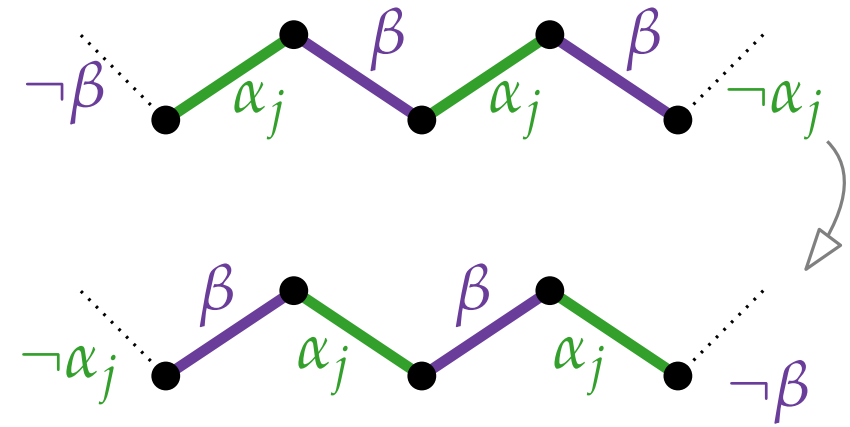
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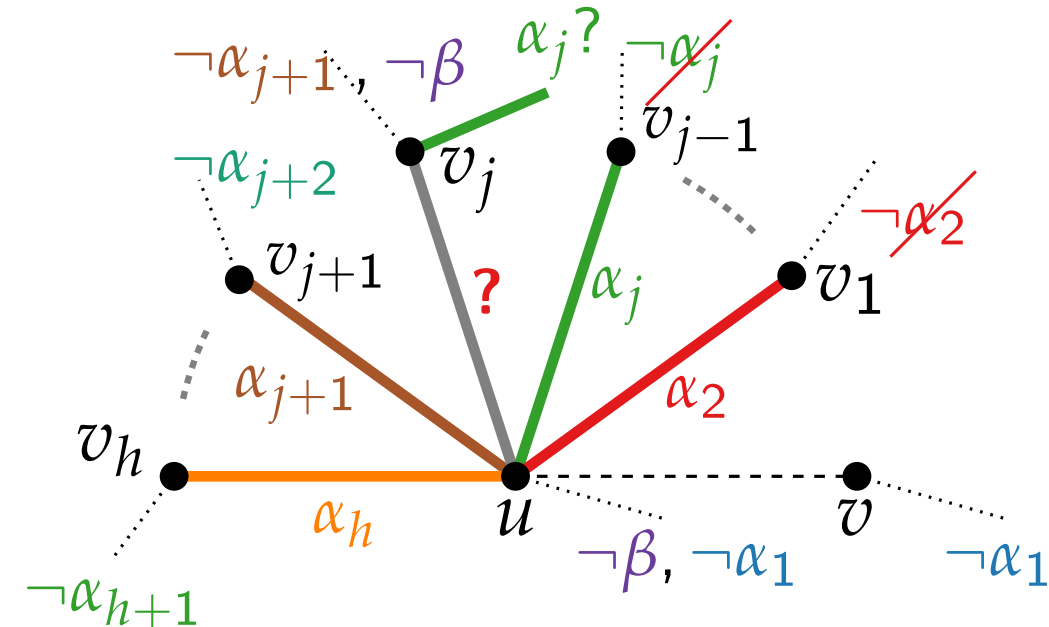
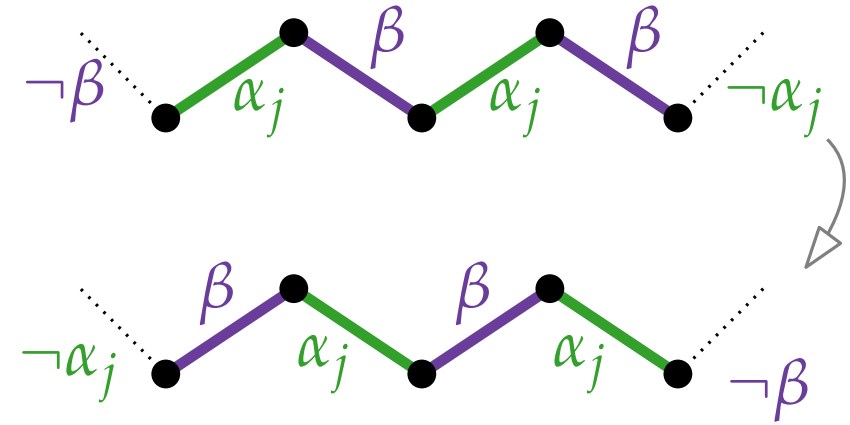
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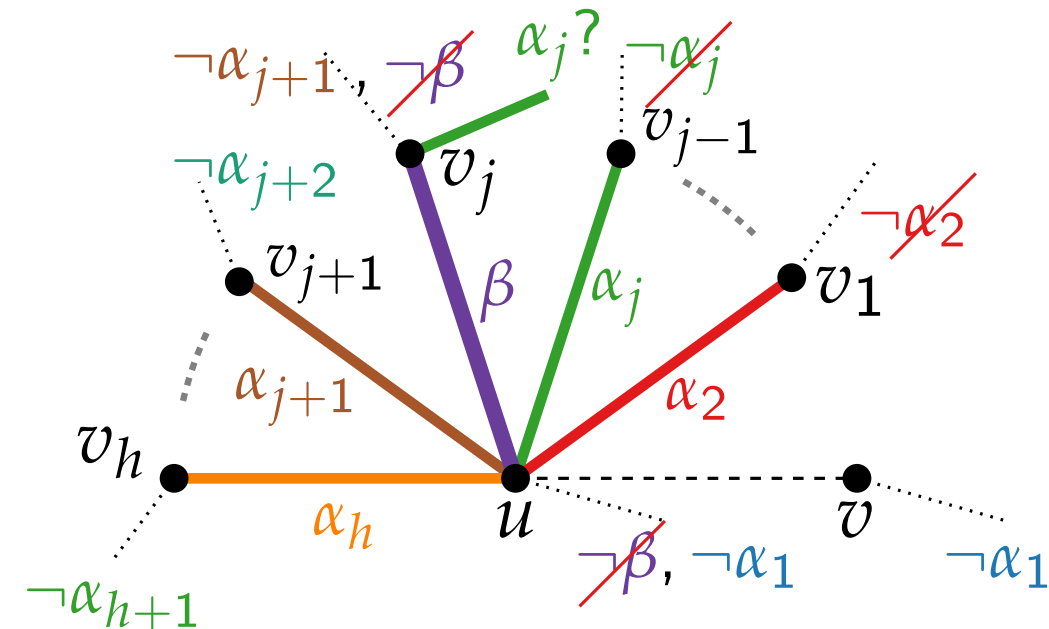
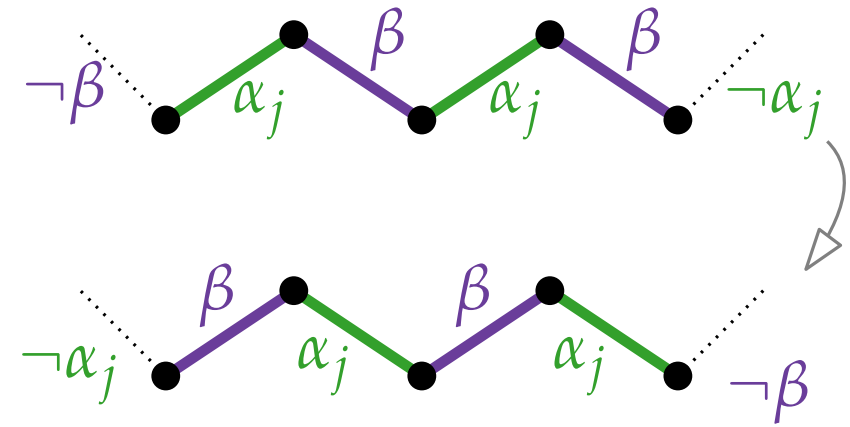
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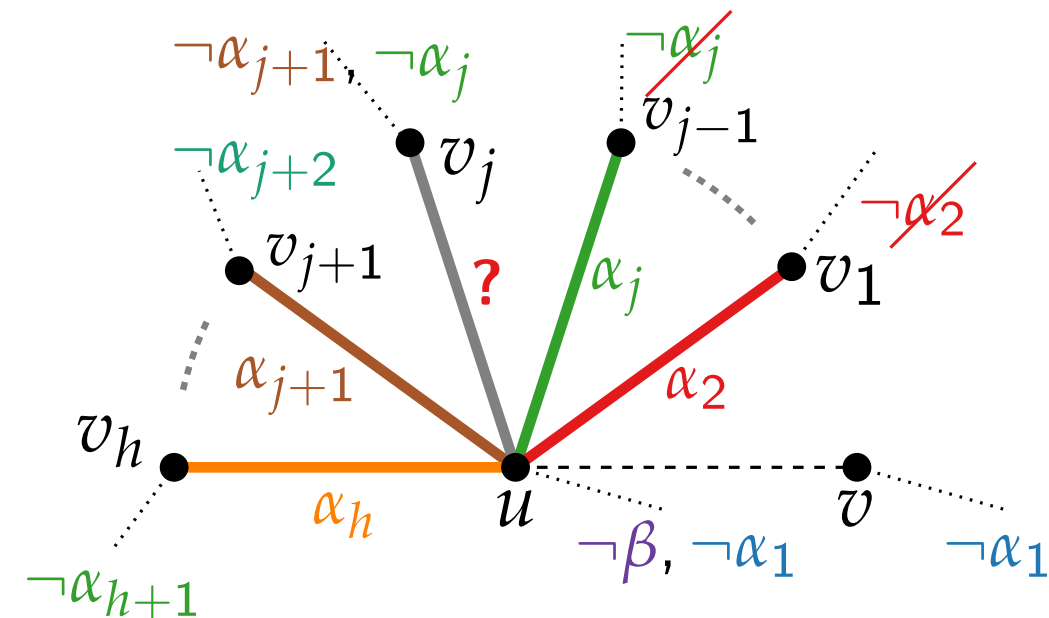
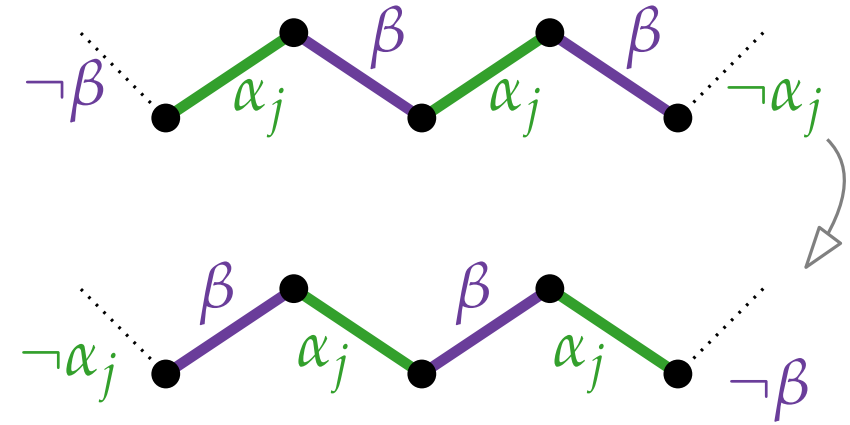
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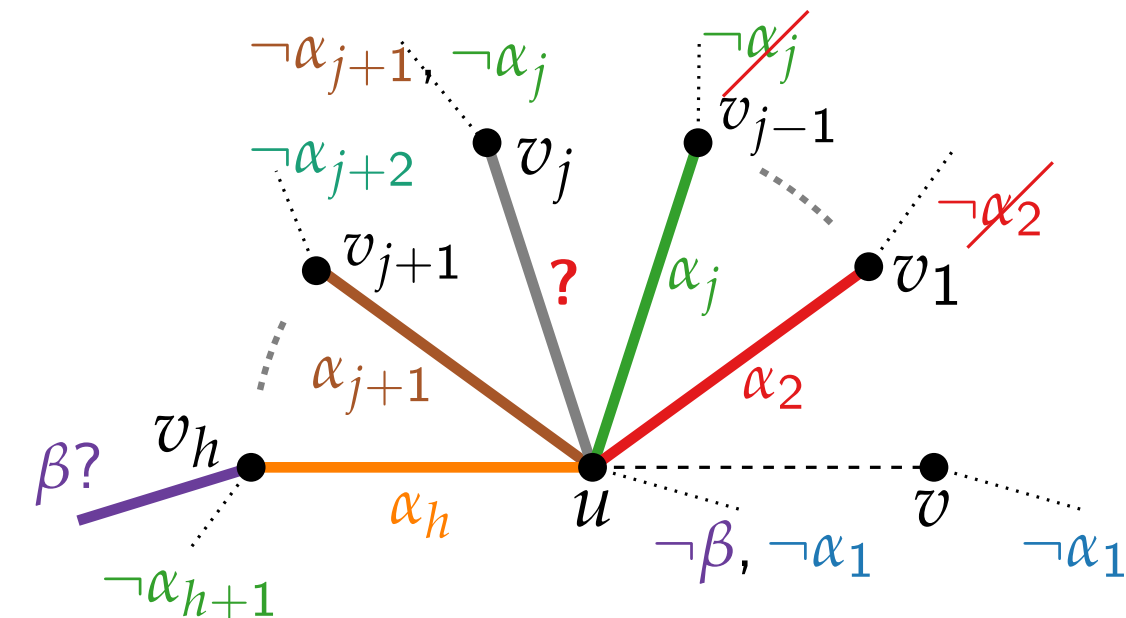
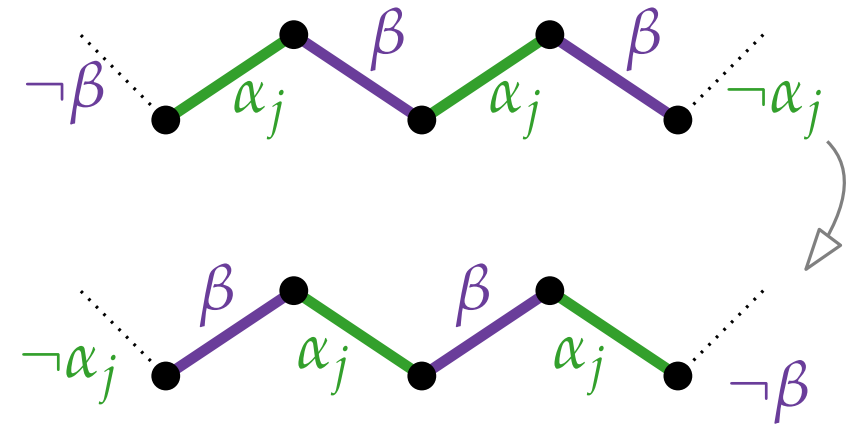
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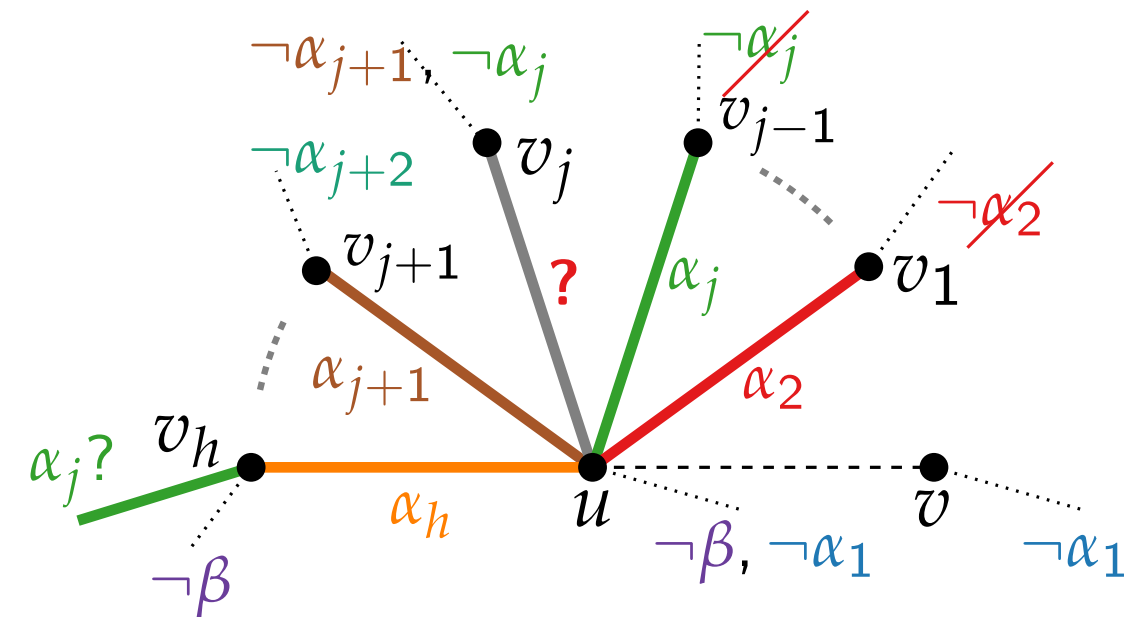
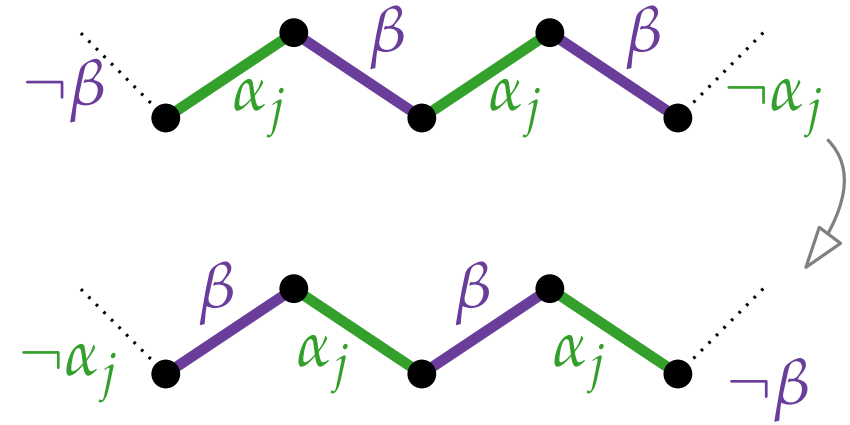
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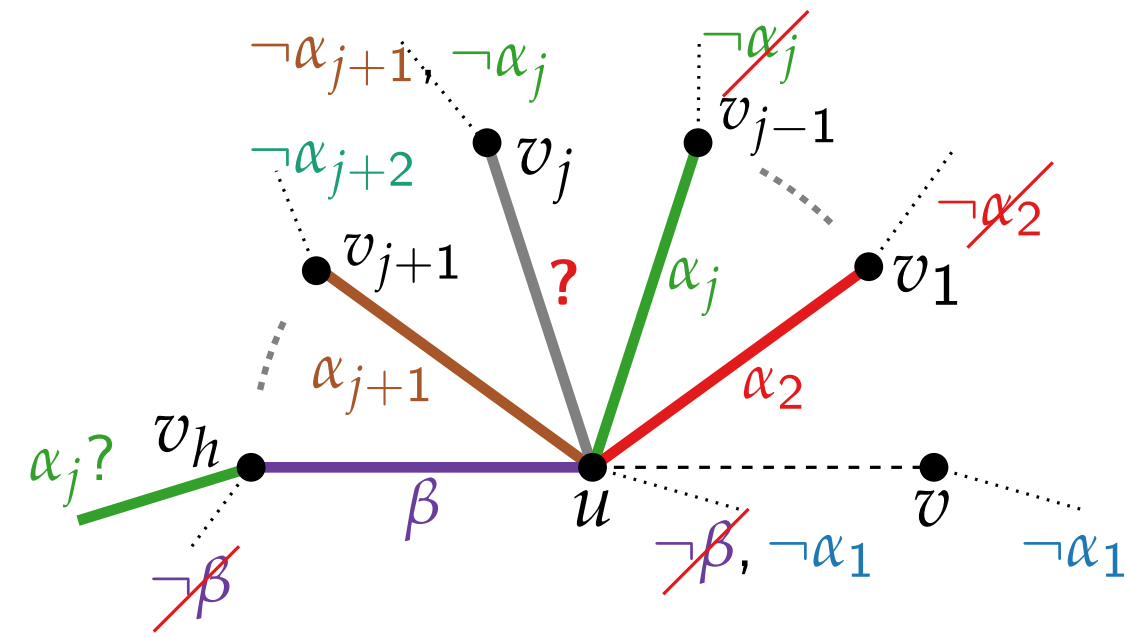
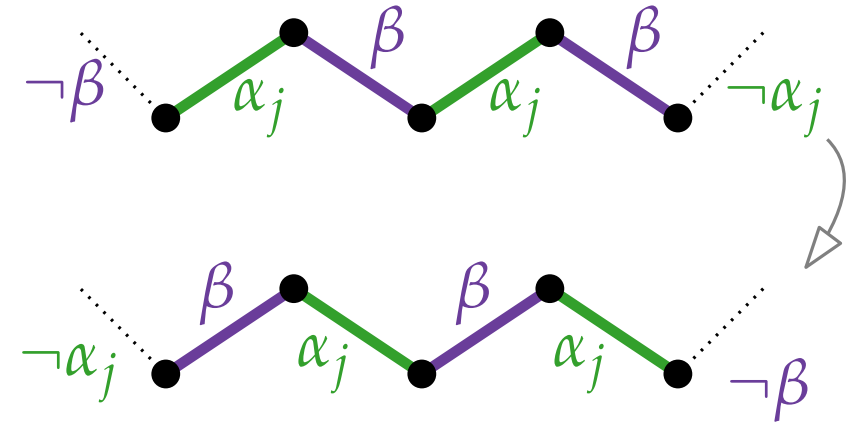
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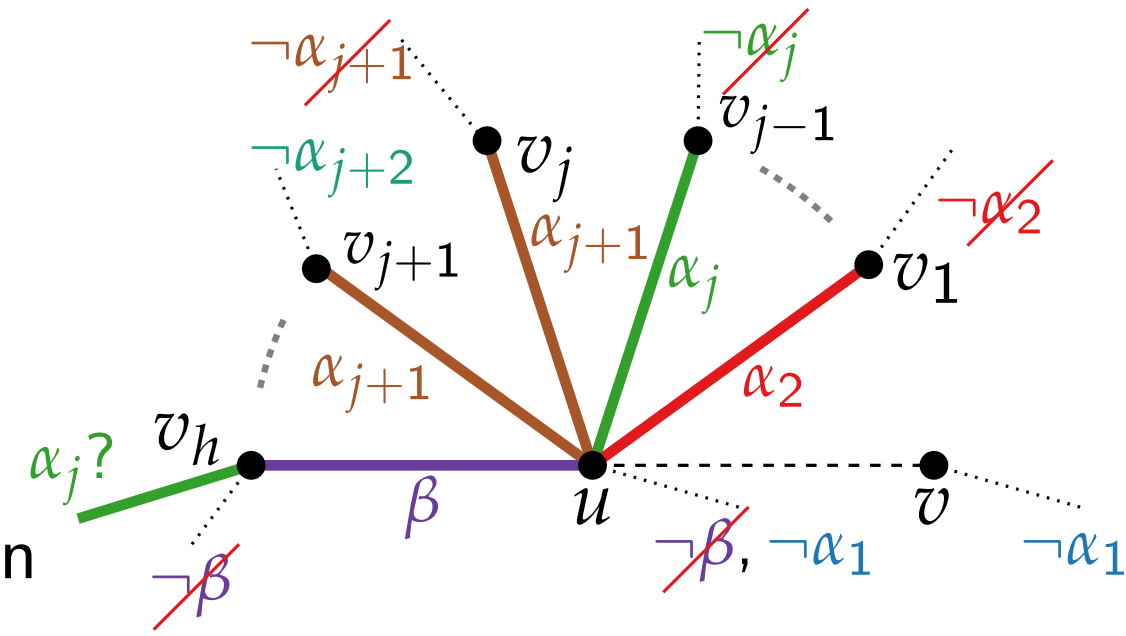
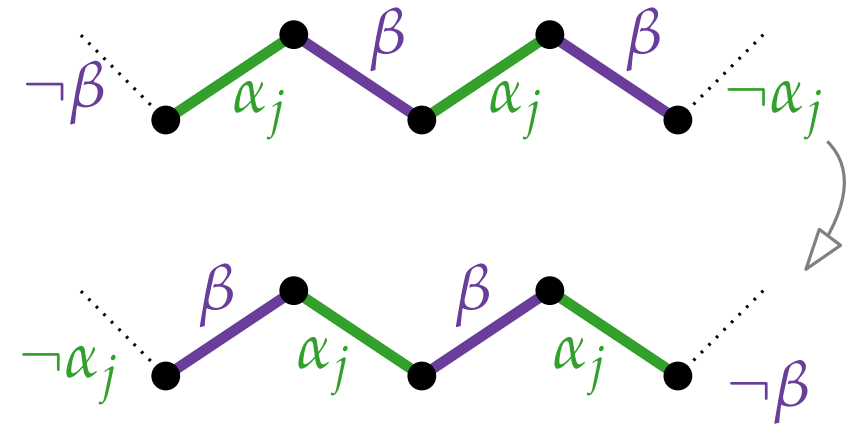




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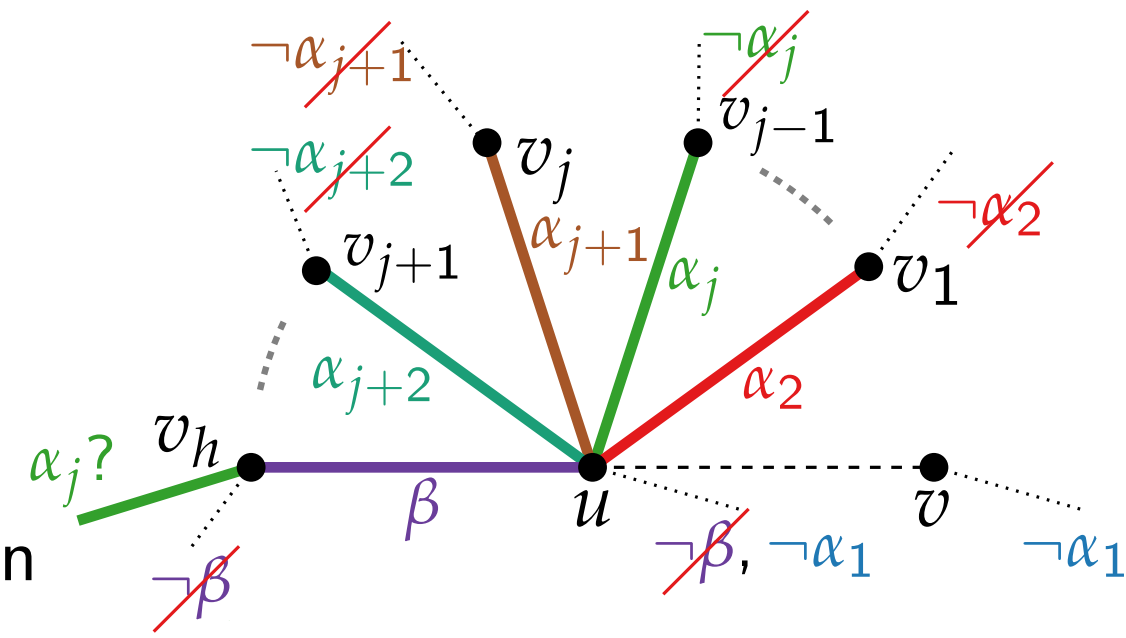
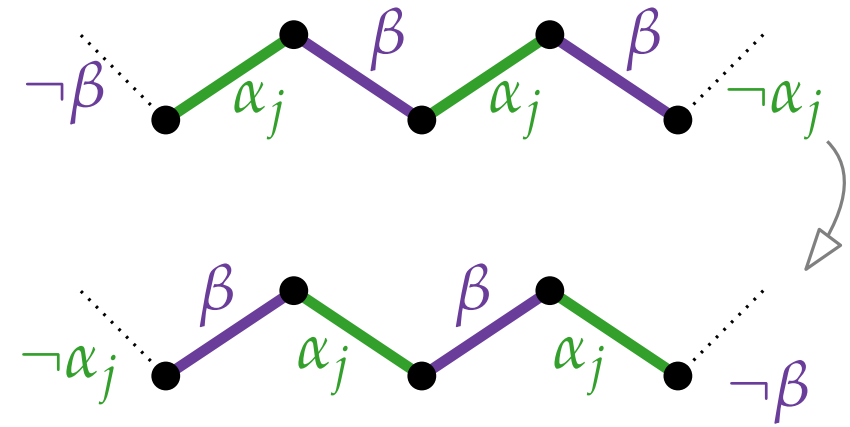
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- What if  $u$  and  $v_j$  are in the same component?
  - re-color component ending at  $v_h$  if there is  $\beta$
  - color  $uv_h$  with  $\beta$ ; color  $uv_j$  with  $\alpha_{j+1}$  and so on



# Minimum Edge Coloring – Recoloring

**Proof** continued for **Case 2**:  $\alpha_{h+1} = \alpha_j$ ,  $j < h$ ,  
and we need to find a color for edge  $uv_j$ .

- Consider subgraph  $G'$  of  $G$  induced by the edges of colors  $\beta$  and  $\alpha_j$ .
- Since  $\Delta(G') \leq 2$ , we can recolor components.
- Nodes  $u$ ,  $v_j$ ,  $v_h$  are all leaves in  $G'$ .  
 $\Rightarrow$  They are not all in the same component of  $G'$ .
- If  $u$  and  $v_j$  are not in the same component:
  - re-color component ending at  $v_j$ ,
  - $v_j$  now misses  $\beta$ ; color  $uv_j$  with  $\beta$ .
- What if  $u$  and  $v_j$  are in the same component?
  - re-color component ending at  $v_h$  if there is  $\beta$
  - color  $uv_h$  with  $\beta$ ; color  $uv_j$  with  $\alpha_{j+1}$  and so on



# Minimum Edge Coloring – Algorithm

```
VizingEdgeColoring(graph  $G$ , coloring  $c \equiv 0$ )
```

```
  if  $E(G) \neq \emptyset$  then
```

```
    Let  $e = uv$  be an arbitrary edge of  $G$ .
```

```
     $G_e \leftarrow G - e$ 
```

```
    VizingEdgeColoring( $G_e, c$ )
```

```
    if  $\Delta(G_e) < \Delta(G)$  then
```

```
      | Color  $e$  with lowest free color.
```

```
    else
```

```
      | Recolor  $G_e$  as in Lemma 2.
```

```
      | Color  $e$  with color now missing at  $u$  and  $v$ .
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# Minimum Edge Coloring – Algorithm

VizingEdgeColoring(graph  $G$ , coloring  $c \equiv 0$ )

**if**  $E(G) \neq \emptyset$  **then**

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**if**  $\Delta(G_e) < \Delta(G)$  **then**

└ Color  $e$  with lowest free color.

**else**

└ Recolor  $G_e$  as in Lemma 2.

└ Color  $e$  with color now missing at  $u$  and  $v$ .

**Theorem 4.**

VIZINGEDGECOLORING is an approximation algorithm with additive approximation guarantee  $ALG(G) - OPT(G) \leq 1$ .

# Approximation with Relative Factor

- An additive approximation guarantee can rarely be achieved; but sometimes, there is a multiplicative approximation!

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## Definition.

Let  $\Pi$  be a minimization problem, and let  $\alpha \in \mathbb{Q}^+$ .

A **factor- $\alpha$  approximation algorithm** for  $\Pi$  is a polynomial-time algorithm  $\mathcal{A}$  that computes, for every instance  $I$  of  $\Pi$ , a solution of value  $\text{ALG}(I)$  such that

$$\frac{\text{ALG}(I)}{\text{OPT}(I)} \leq \alpha.$$

We call  $\alpha$  the **approximation factor** of  $\mathcal{A}$ .

# Approximation with Relative Factor

- An additive approximation guarantee can rarely be achieved; but sometimes, there is a multiplicative approximation!

**Definition.** **maximization**

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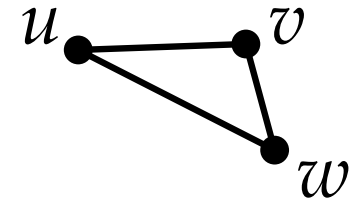
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## 2-Approximation for Metric TSP (from AGT)

**Input.** Complete graph  $G = (V, E)$  and a distance function  $d: E \rightarrow \mathbb{R}_{\geq 0}$  that satisfies the triangle inequality, i.e.,  $\forall u, v, w \in V: d(u, w) \leq d(u, v) + d(v, w)$ .

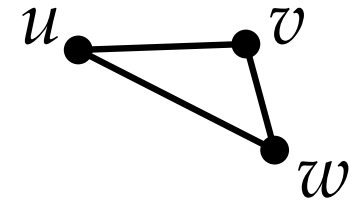




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**Output.** A shortest Hamiltonian cycle in  $G$ .

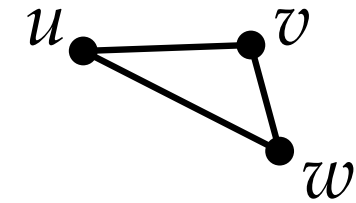


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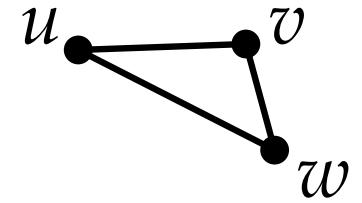
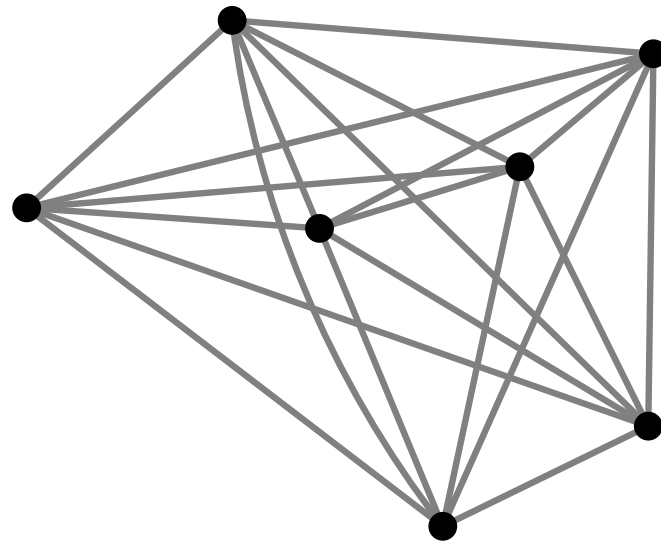


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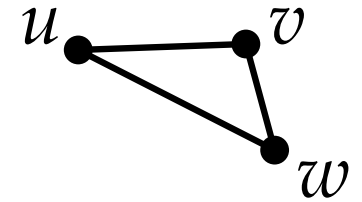
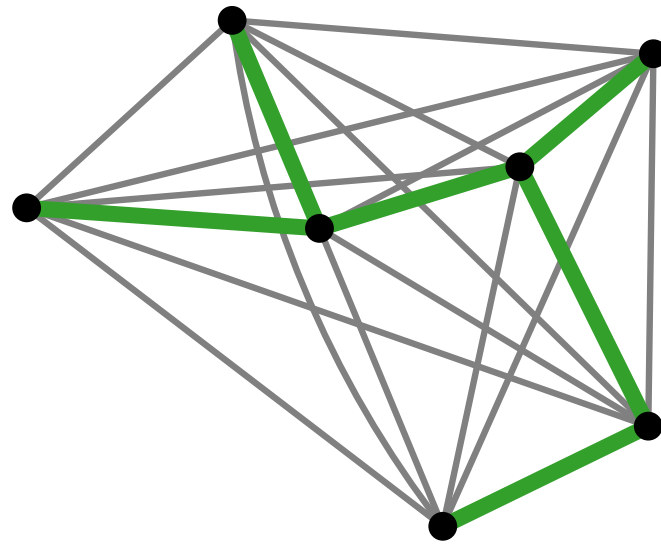
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**Algorithm.**

- Compute MST.



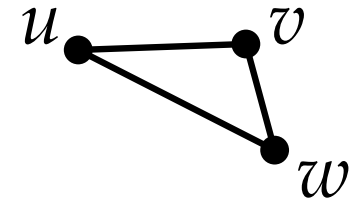
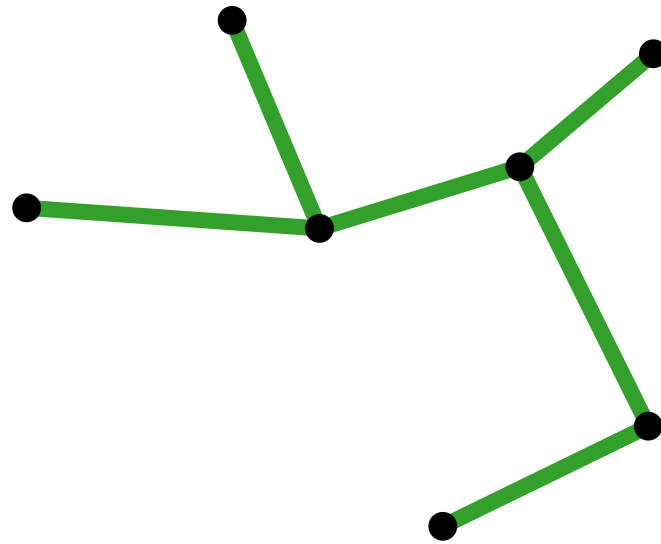
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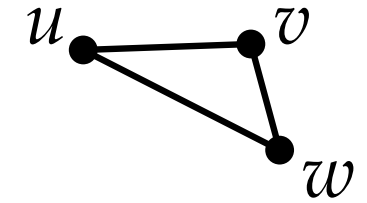
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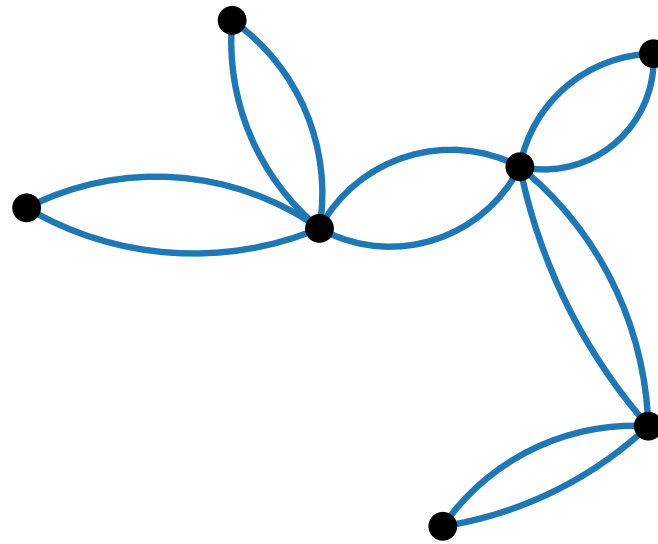
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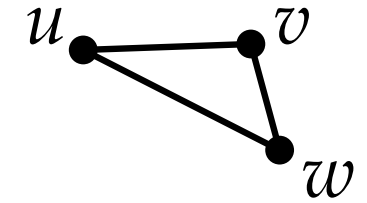
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- Compute MST.
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 $\Rightarrow$  Eulerian cycle



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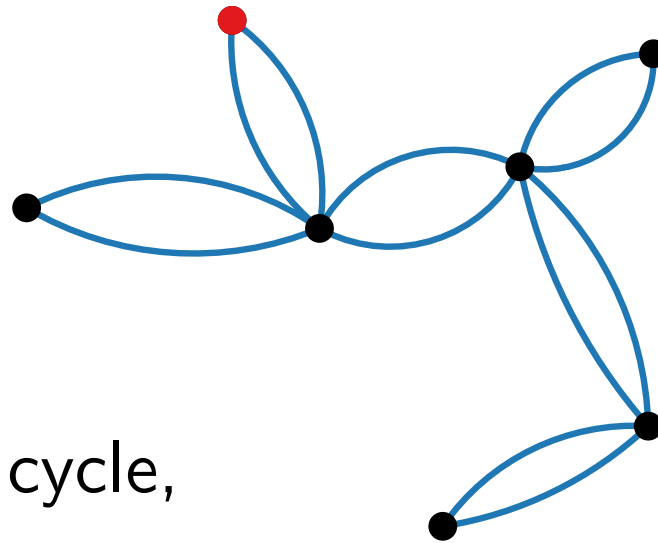
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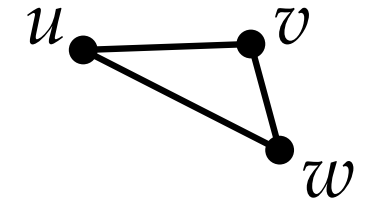
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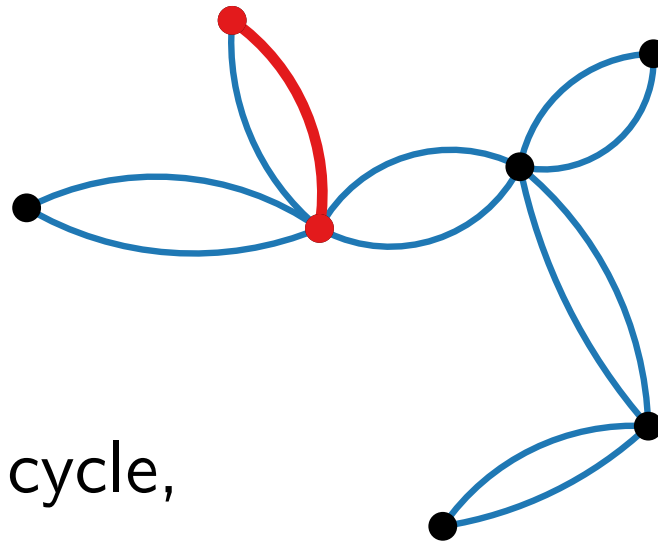
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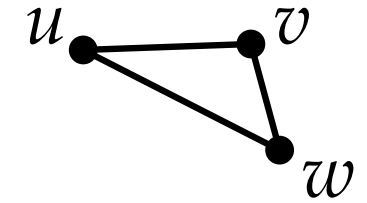
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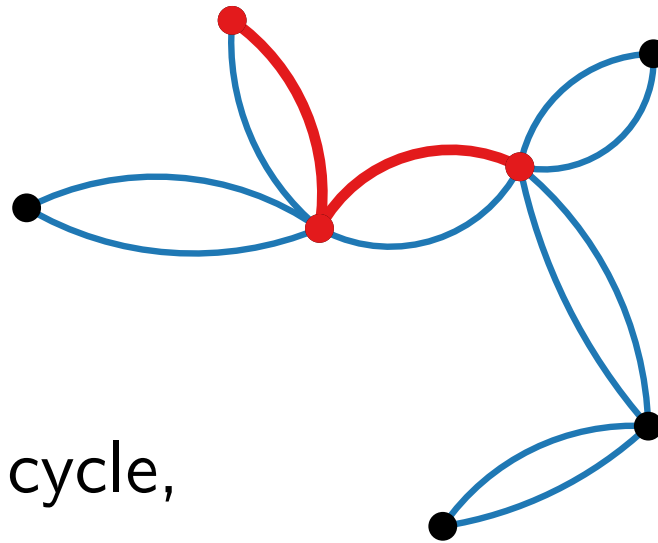
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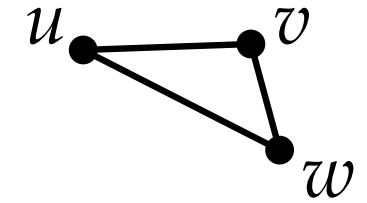
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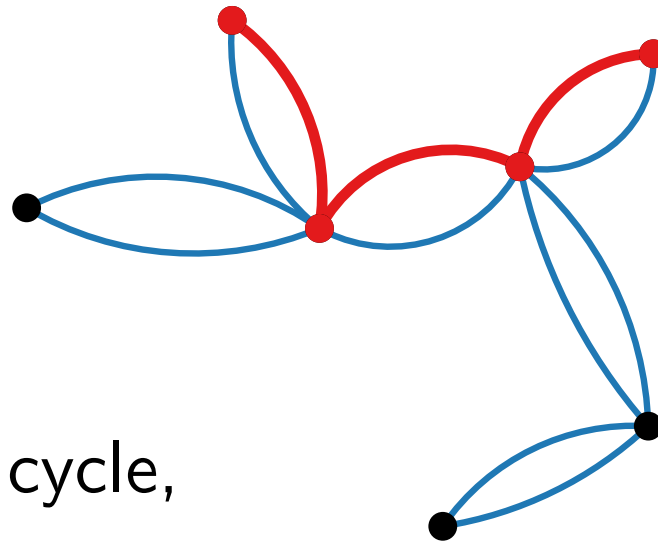
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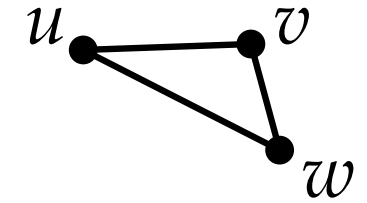
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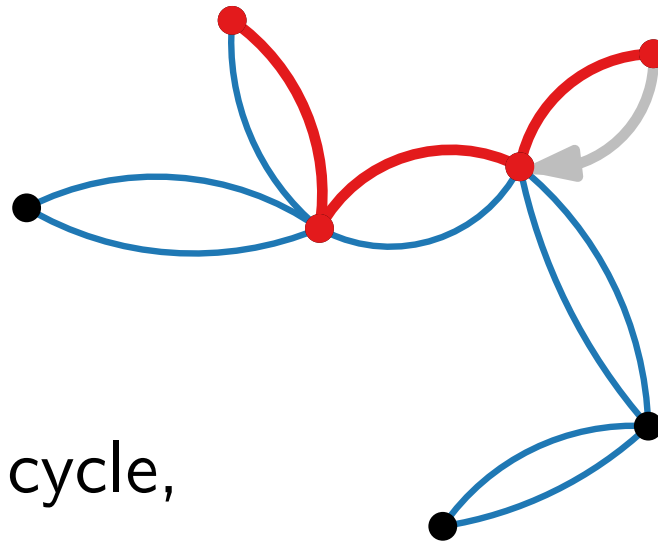
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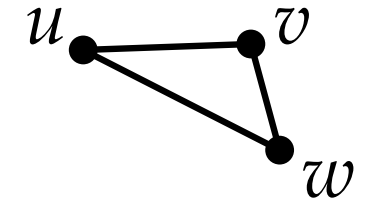
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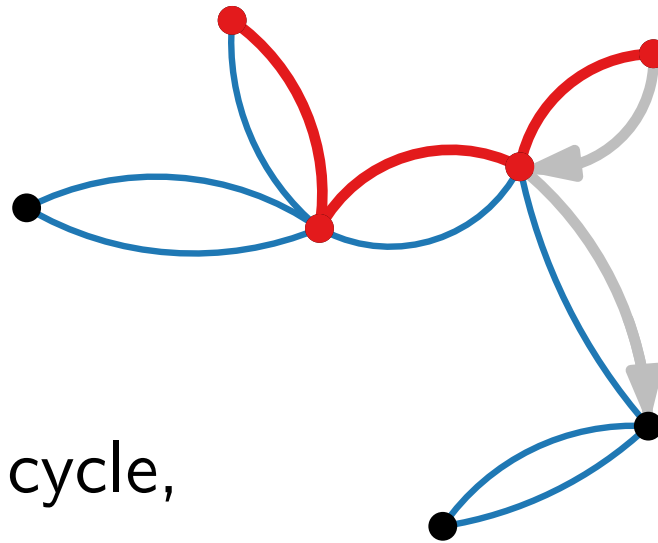
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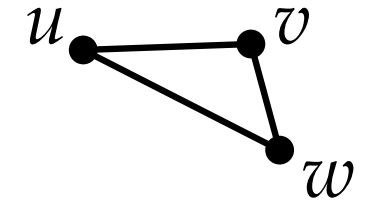
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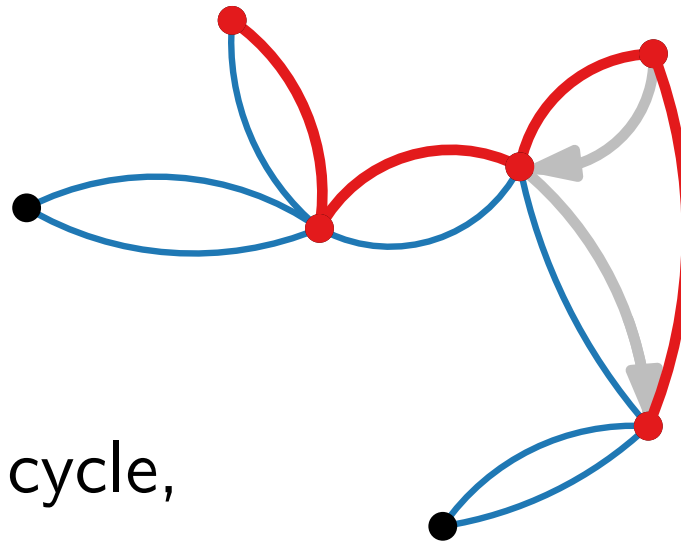
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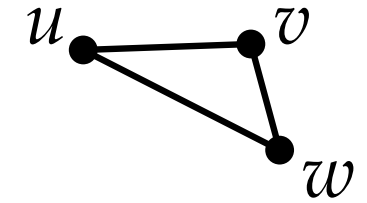
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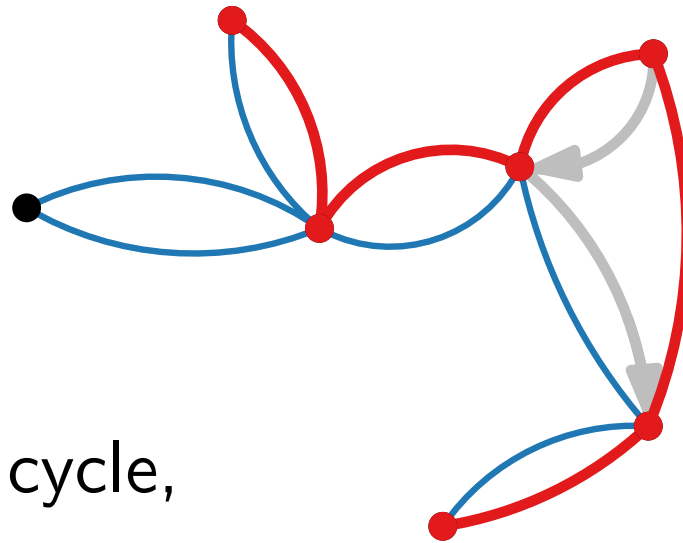
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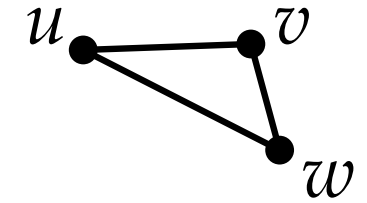
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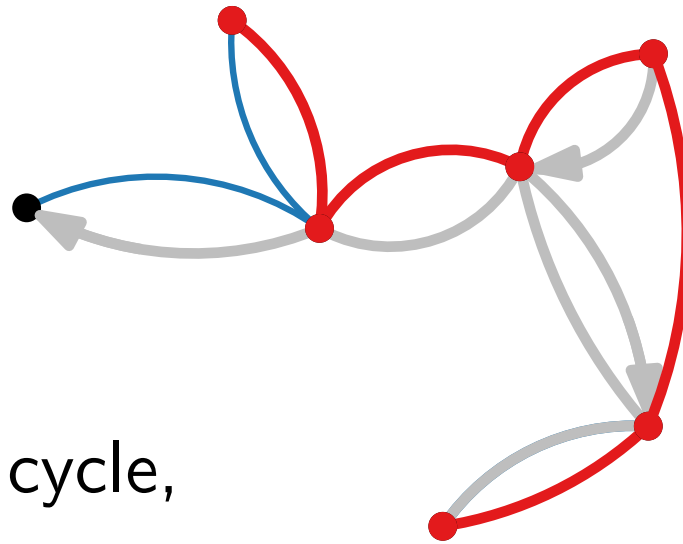
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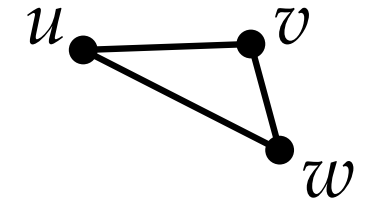
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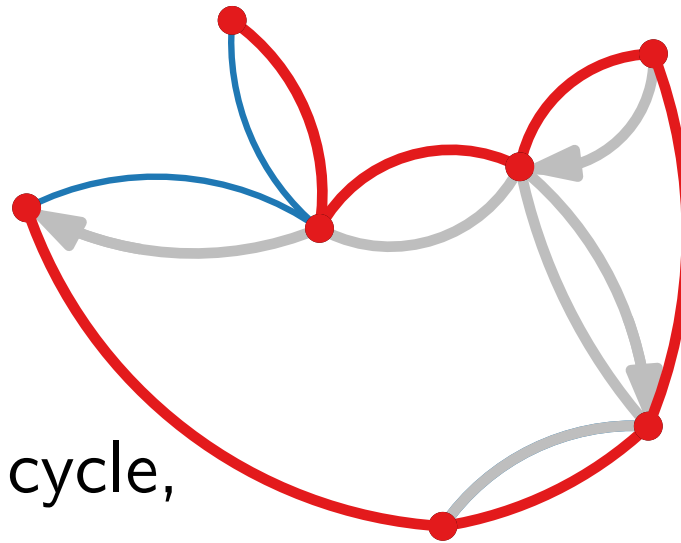
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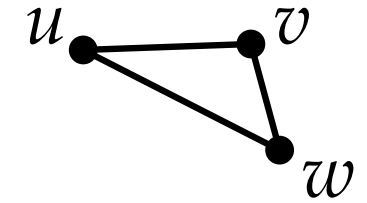
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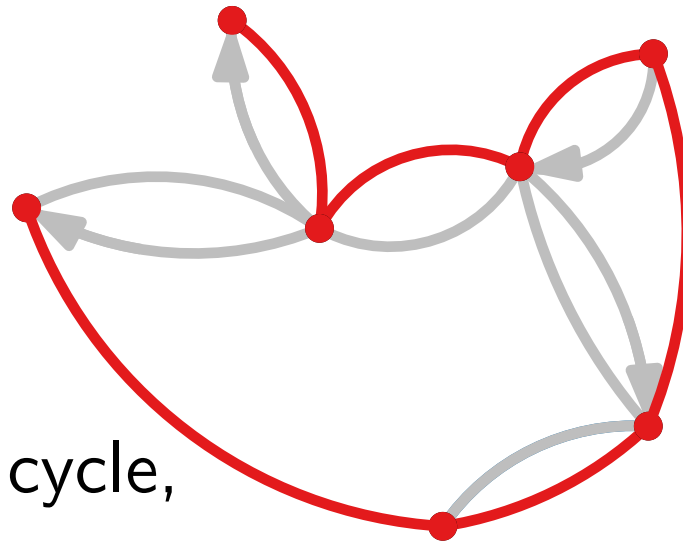
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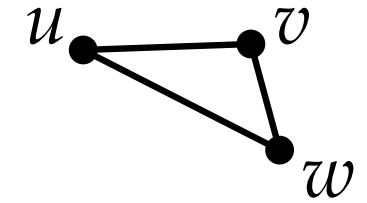
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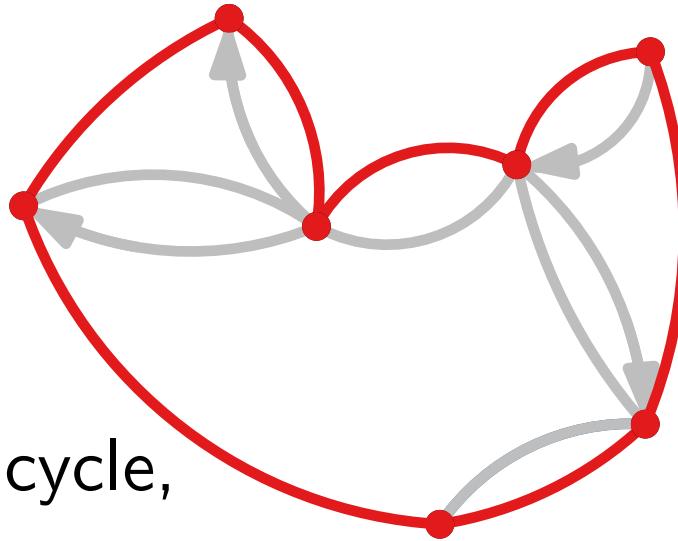
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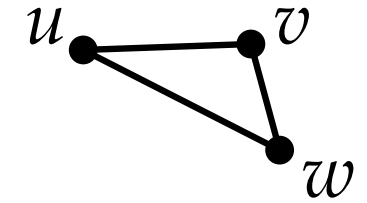
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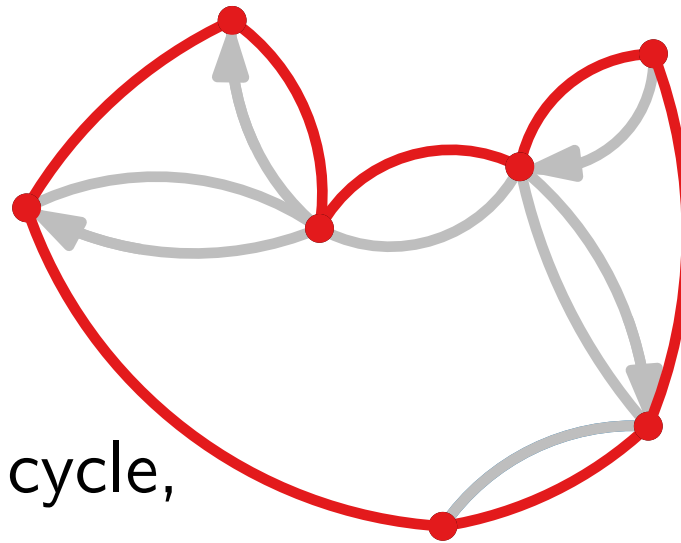
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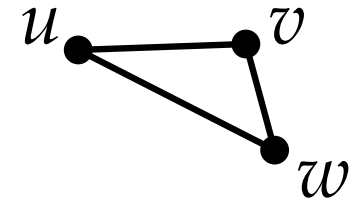


## Theorem 5.

The MST edge doubling algorithm is a 2-approximation algorithm for metric TSP.

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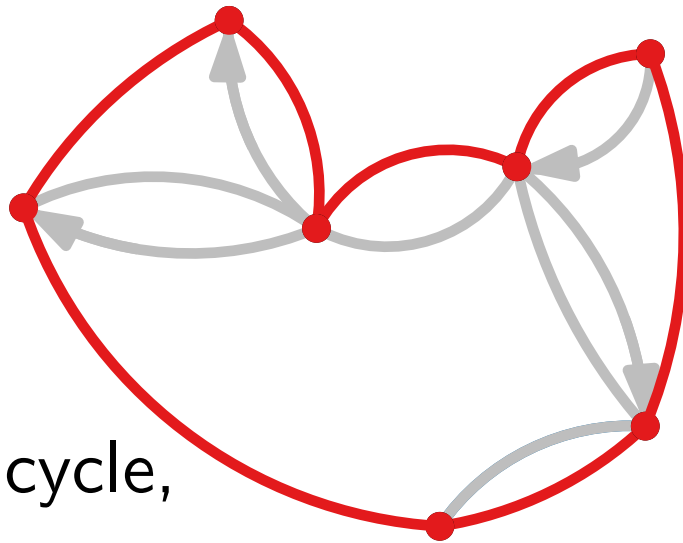
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## Theorem 5.

The MST edge doubling algorithm is a 2-approximation algorithm for metric TSP.

## Proof.

$$\text{ALG} \leq d(\text{cycle}) = 2d(\text{MST}) \leq 2\text{OPT}.$$

# Nearest Addition Algorithm for Metric TSP

NearestAdditionAlgorithm( $G = (V, E), d$ )

Find closest pair, say  $i$  and  $k$ .

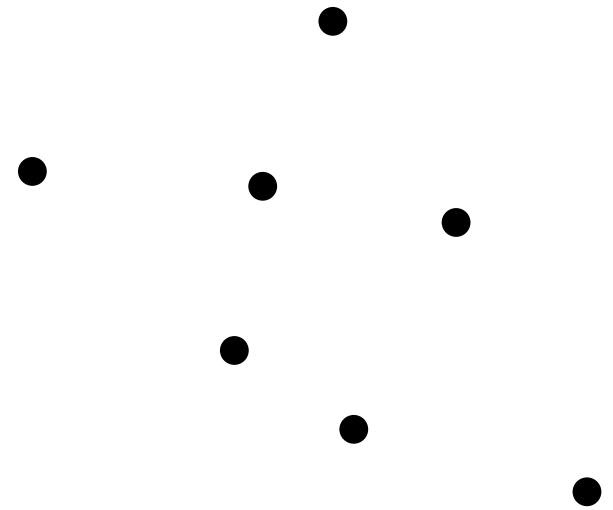
Set tour  $T$  to go from  $i$  to  $k$  to  $i$  (clockwise).

**while**  $T \subsetneq V$  **do**

    Find pair  $(i, j) \in T \times (V \setminus T)$  minimizing  $d(i, j)$ .

    Let  $k$  be vertex after  $i$  in  $T$ .

    Add  $j$  between  $i$  and  $k$ .



# Nearest Addition Algorithm for Metric TSP

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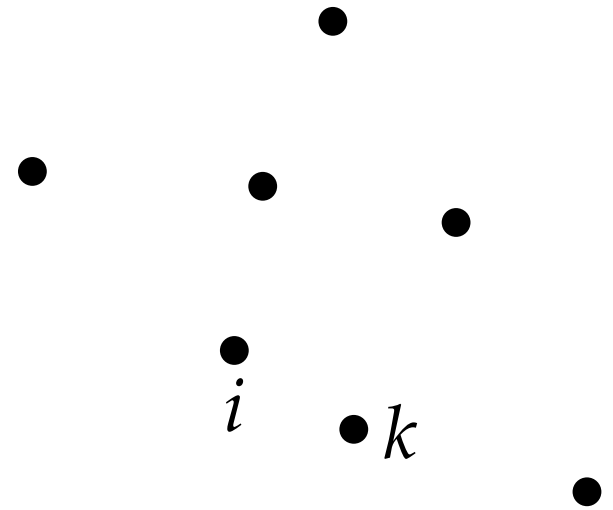
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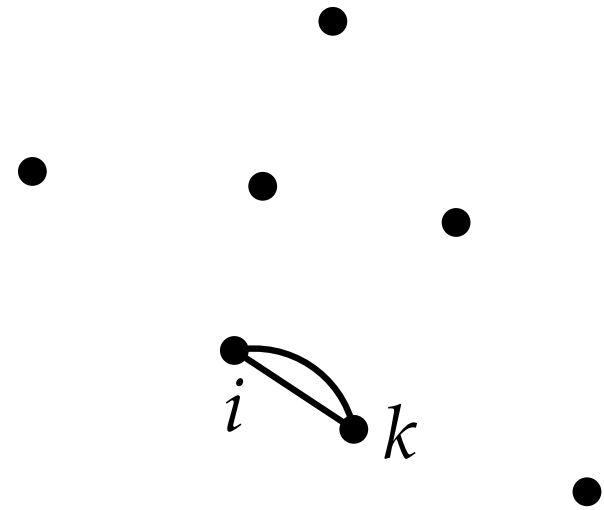
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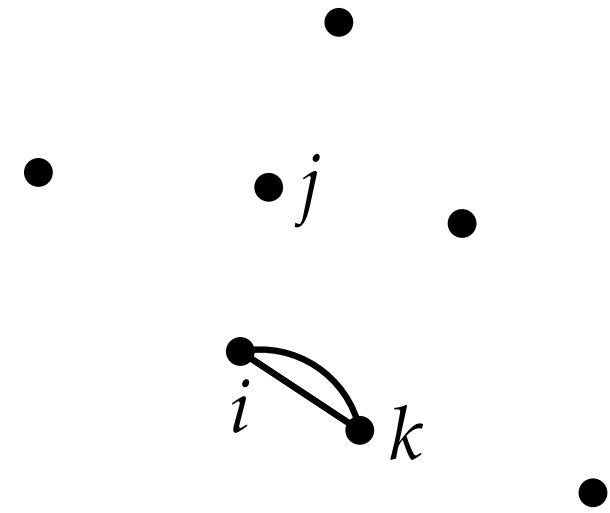
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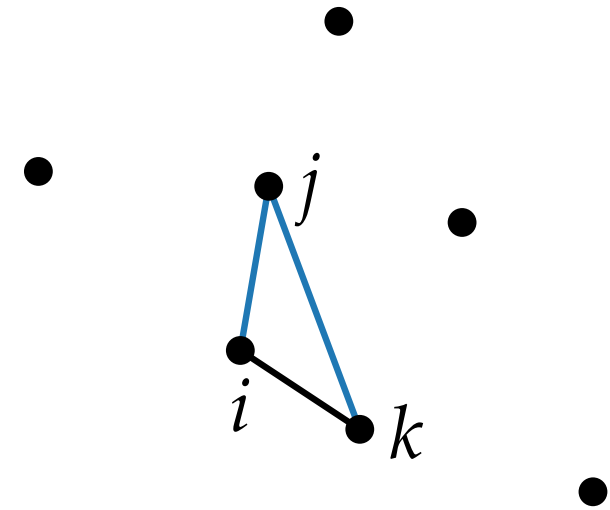
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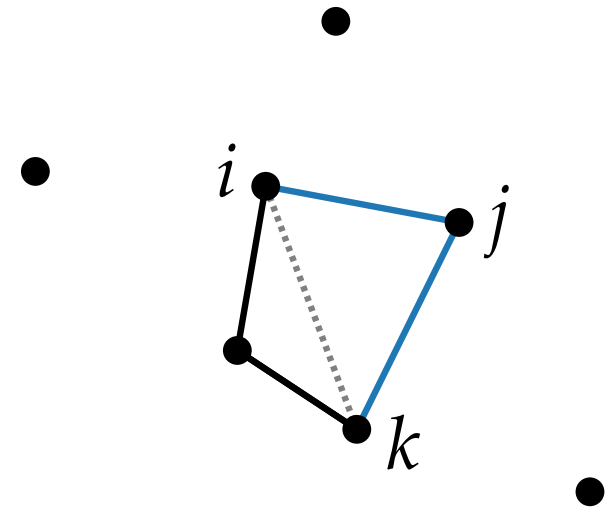
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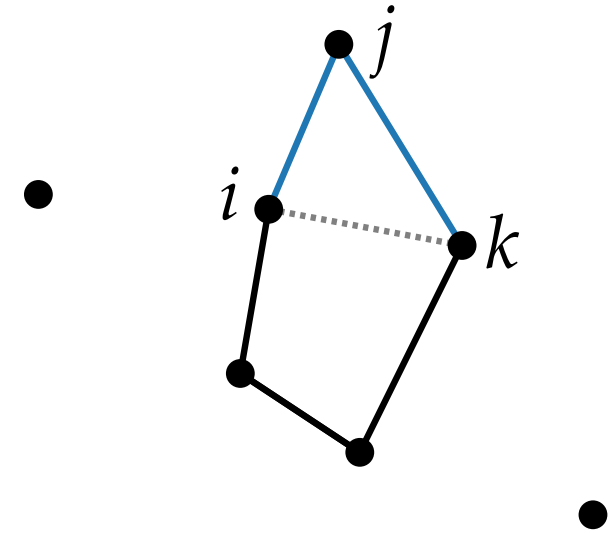
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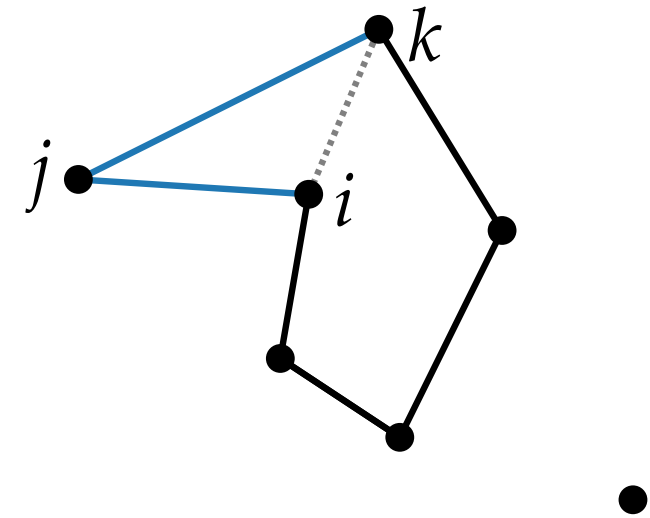
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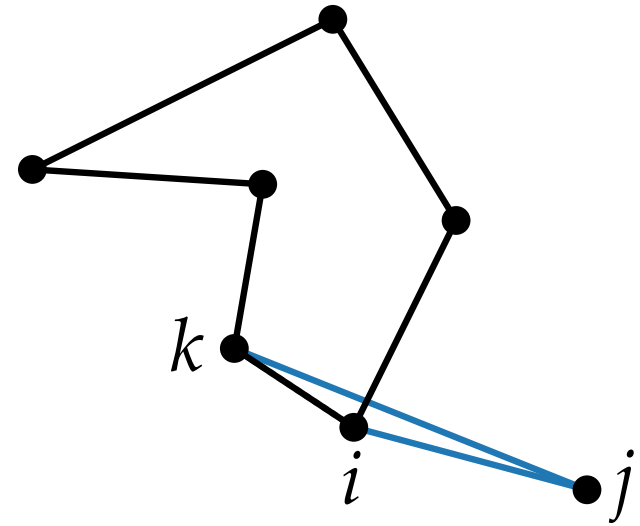
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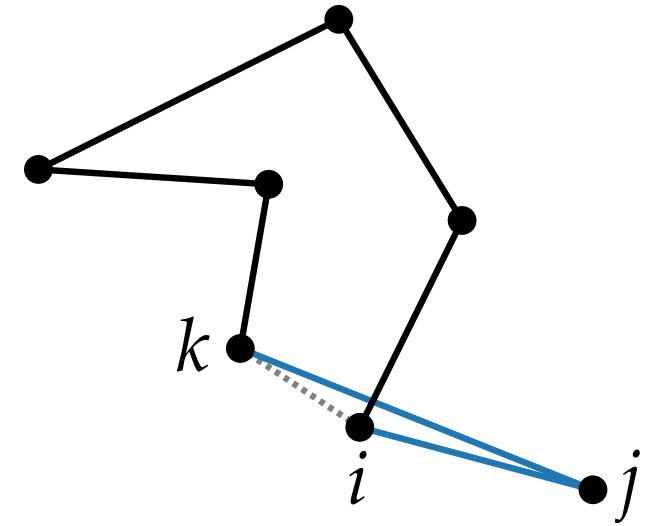
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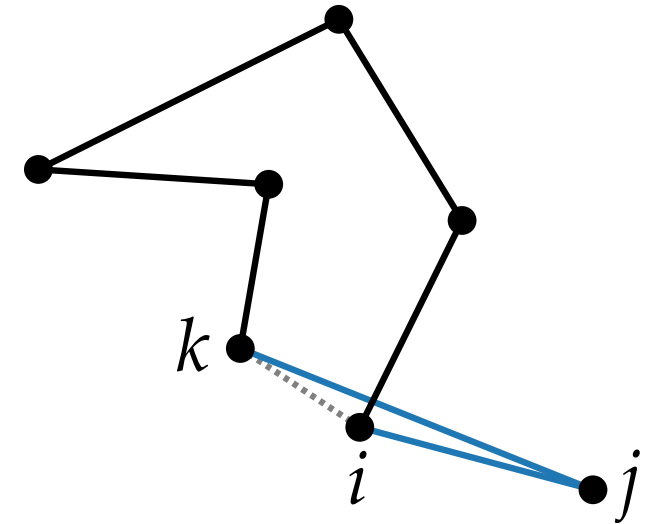
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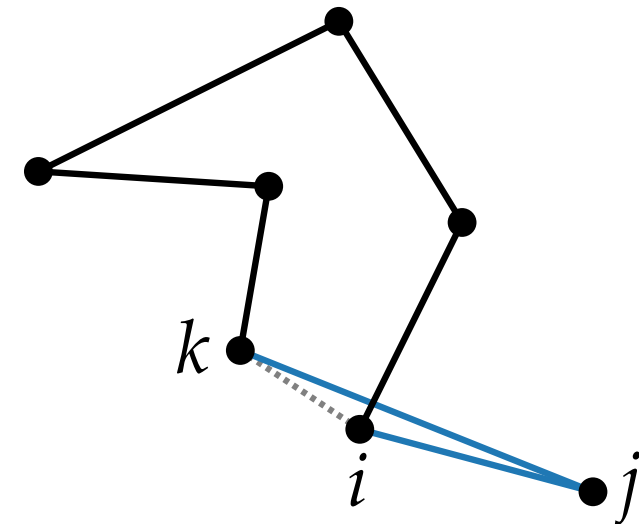
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## Proof.

- Exercise.
- *Hints:* MST and Prim's algorithm.



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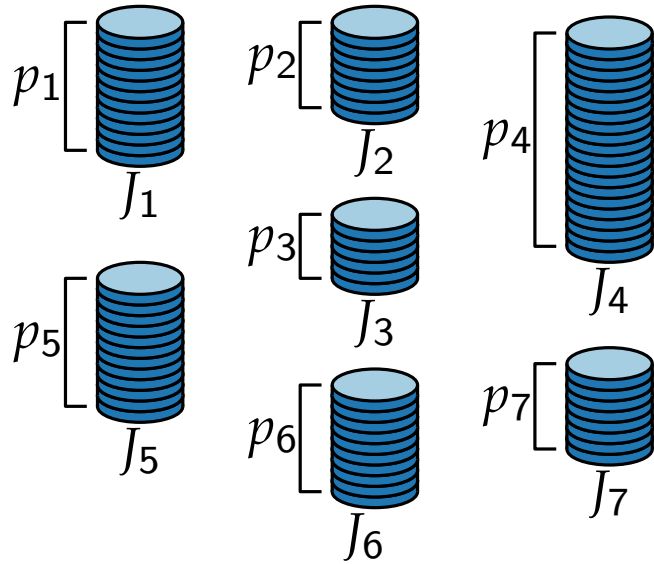
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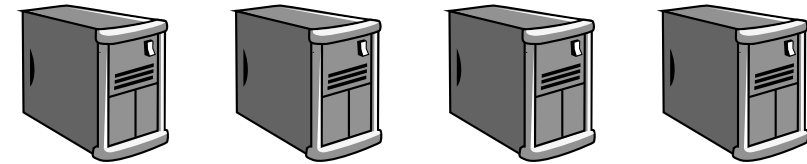
# Multiprocessor Scheduling

## Input.

- $n$  jobs  $J_1, \dots, J_n$  with durations  $p_1, \dots, p_n$ .



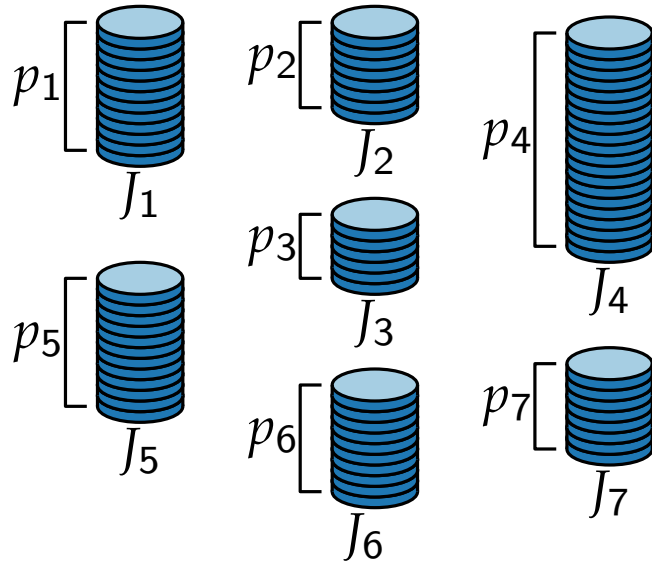
- $m$  identical machines ( $m < n$ )



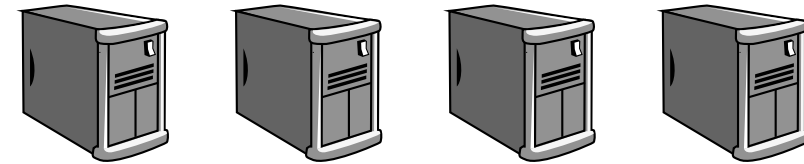
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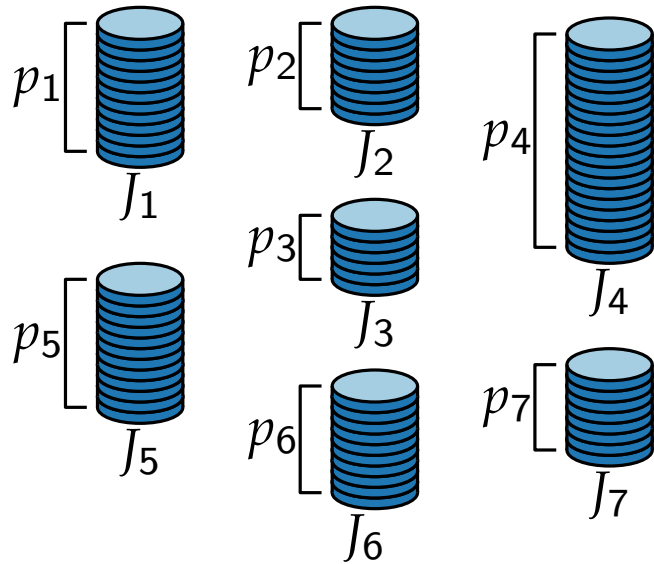
Assignment of jobs to machines such that the time when all jobs have been processed is minimum.

This is called the **makespan** of the assignment.

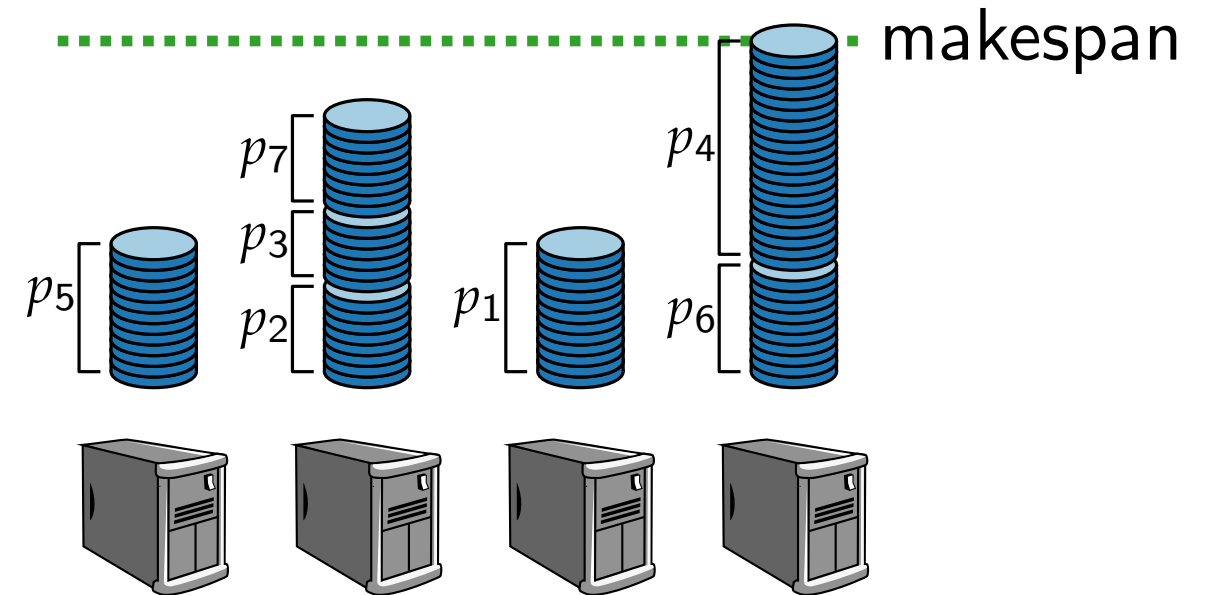
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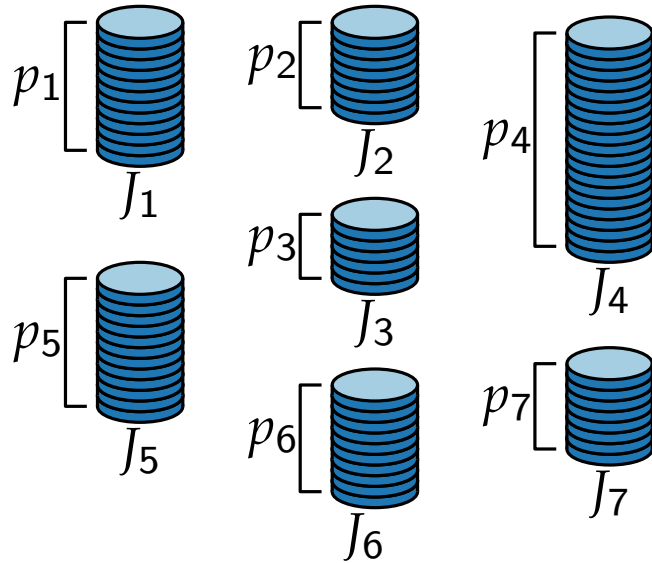
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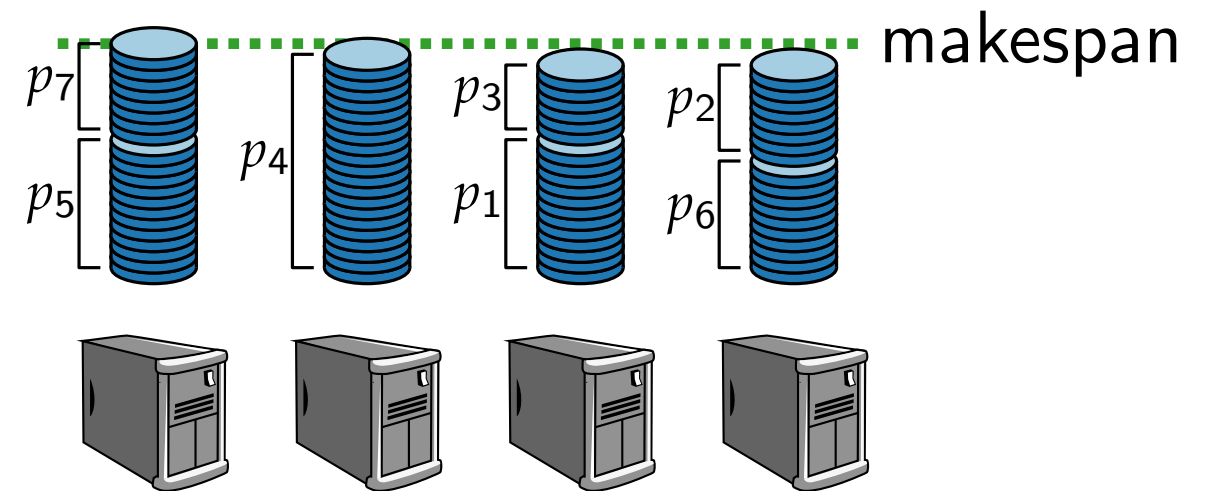
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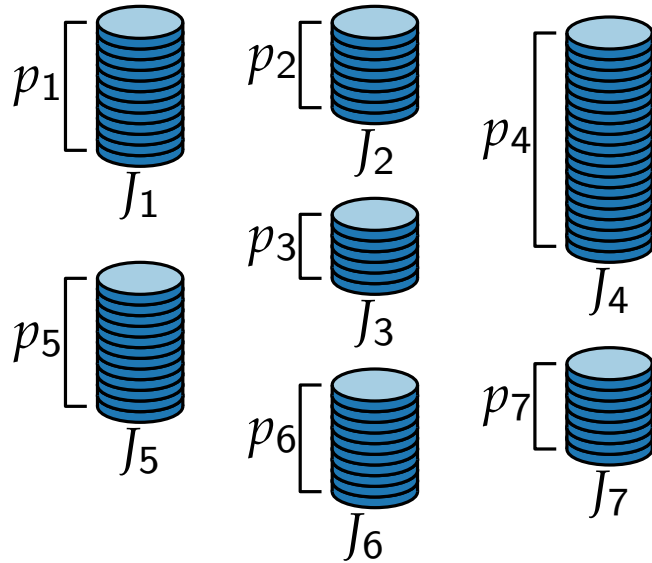
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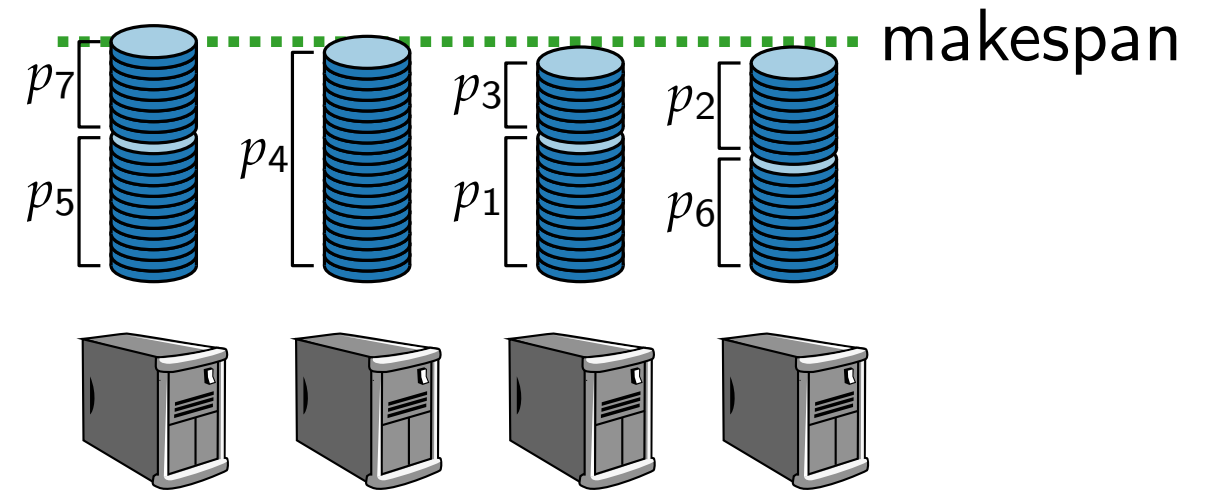
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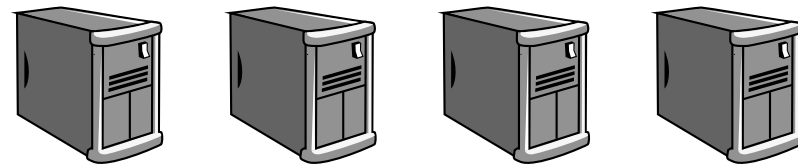
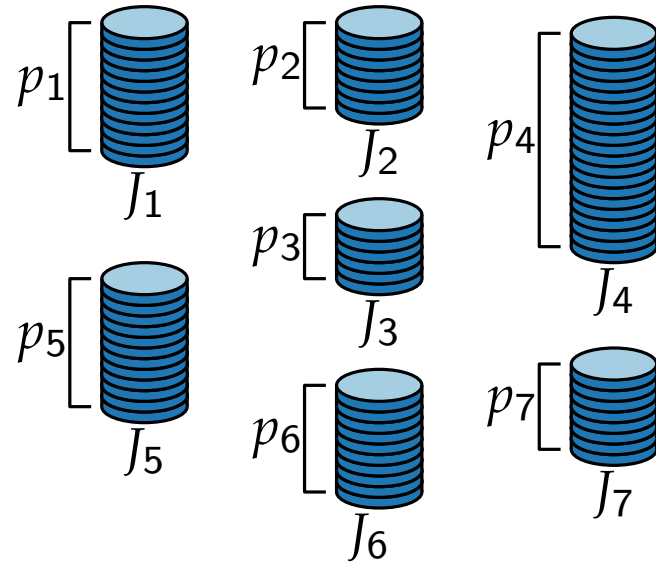
■ Multiprocessor scheduling is NP-hard.

# Multiprocessor Scheduling – List Scheduling

$\text{LISTSCHEDULING}(J_1, \dots, J_n, m)$

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**Example.**

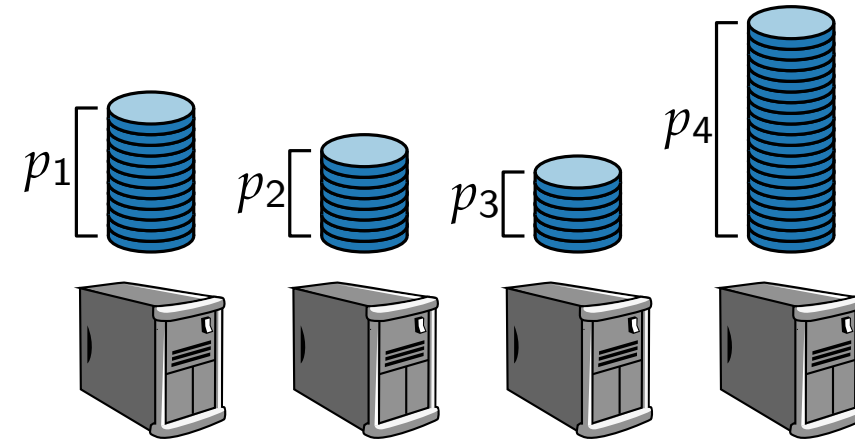
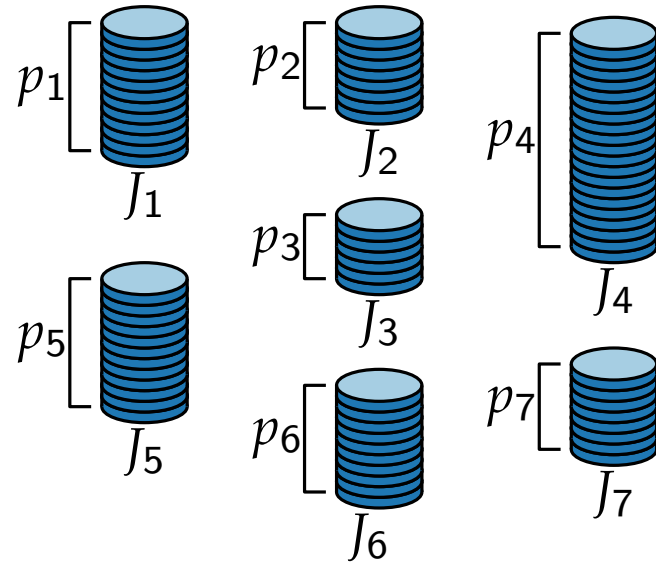


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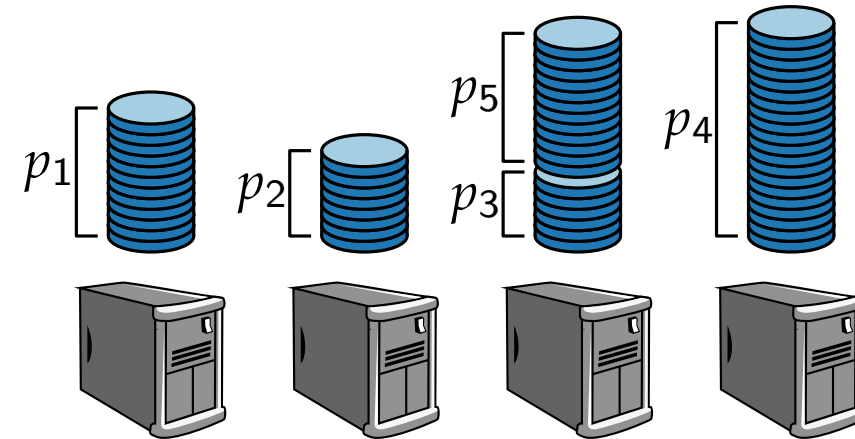
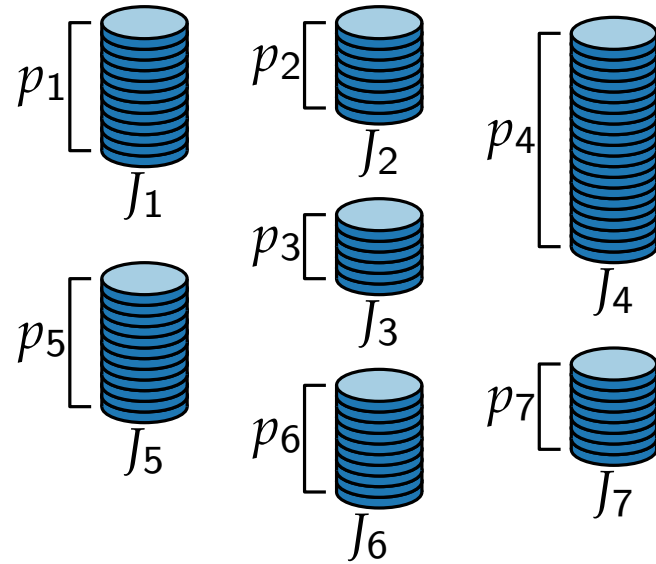
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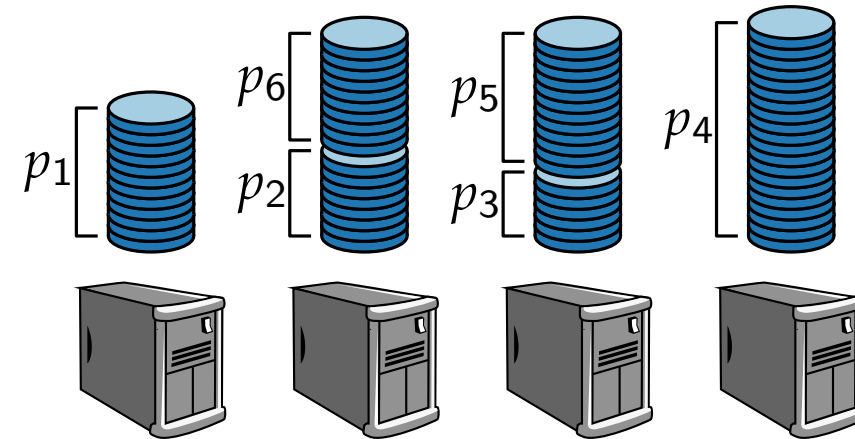
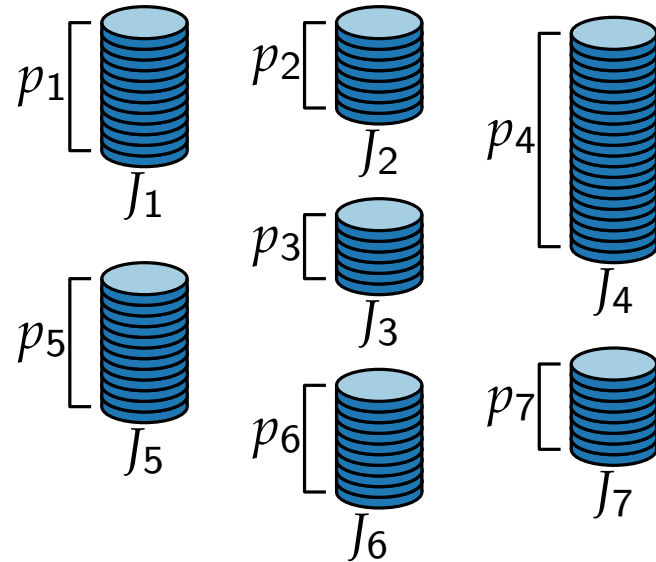
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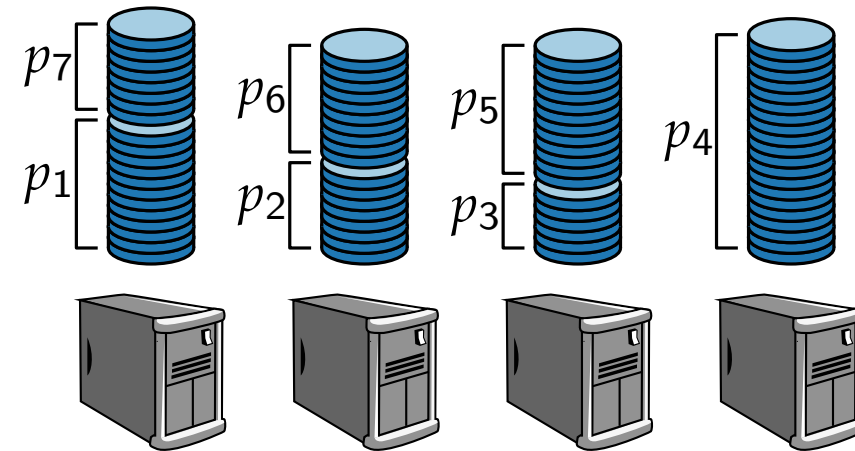
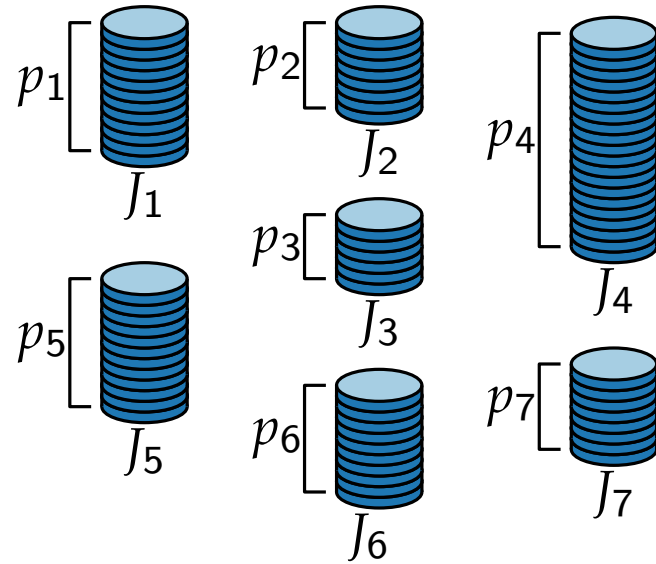
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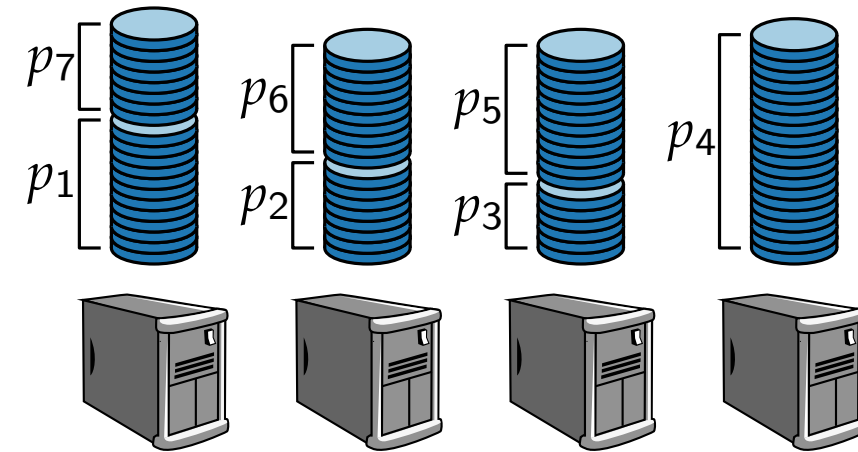
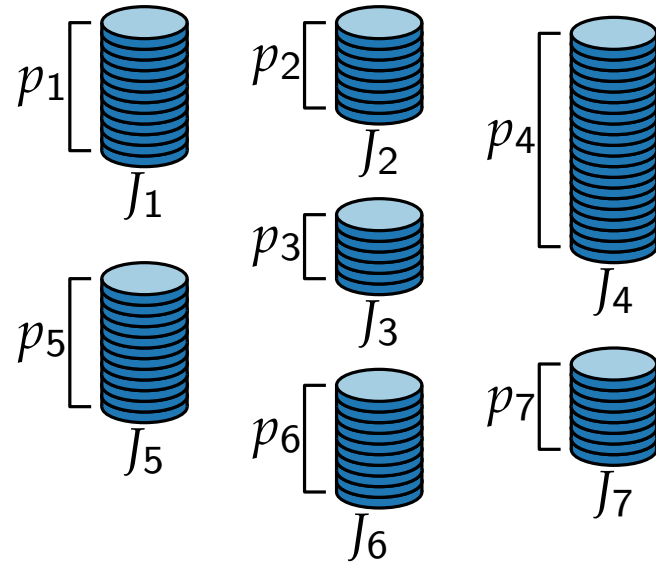


# Multiprocessor Scheduling – List Scheduling

LISTSCHEDULING( $J_1, \dots, J_n, m$ )

Put the first  $m$  jobs on the  $m$  machines.  
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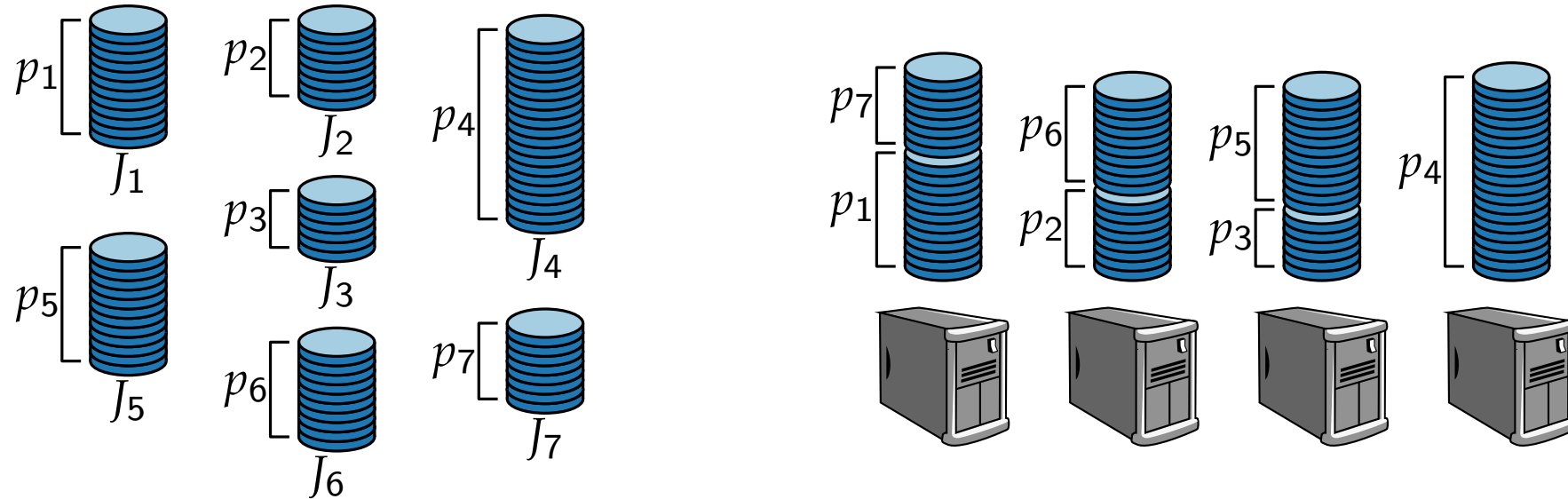
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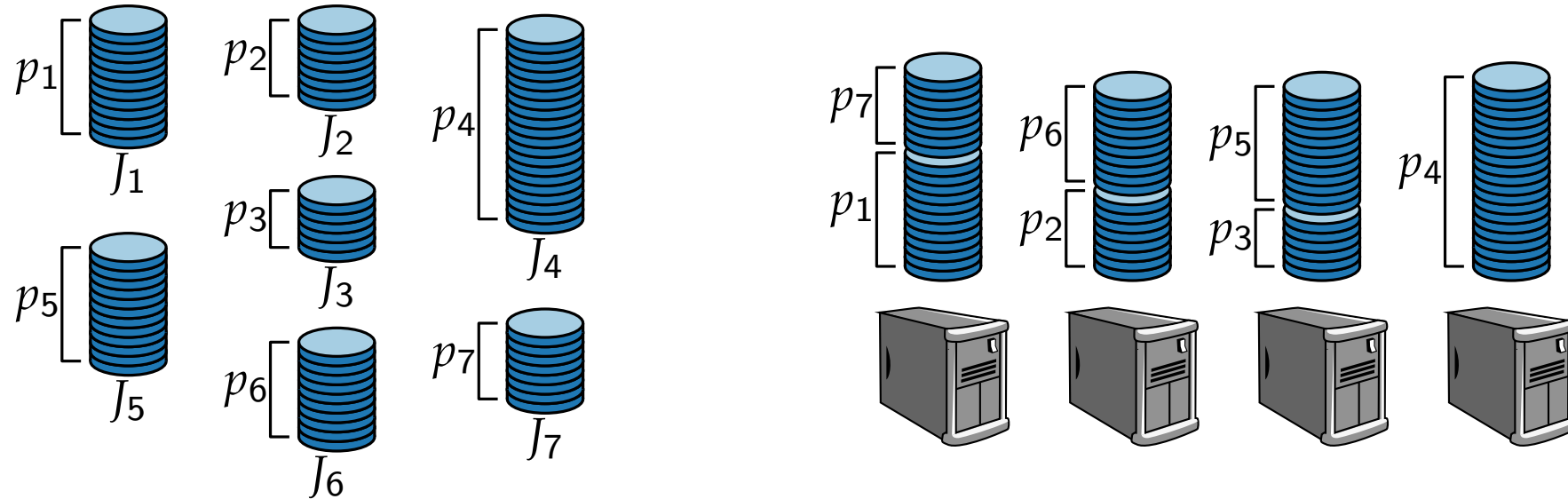
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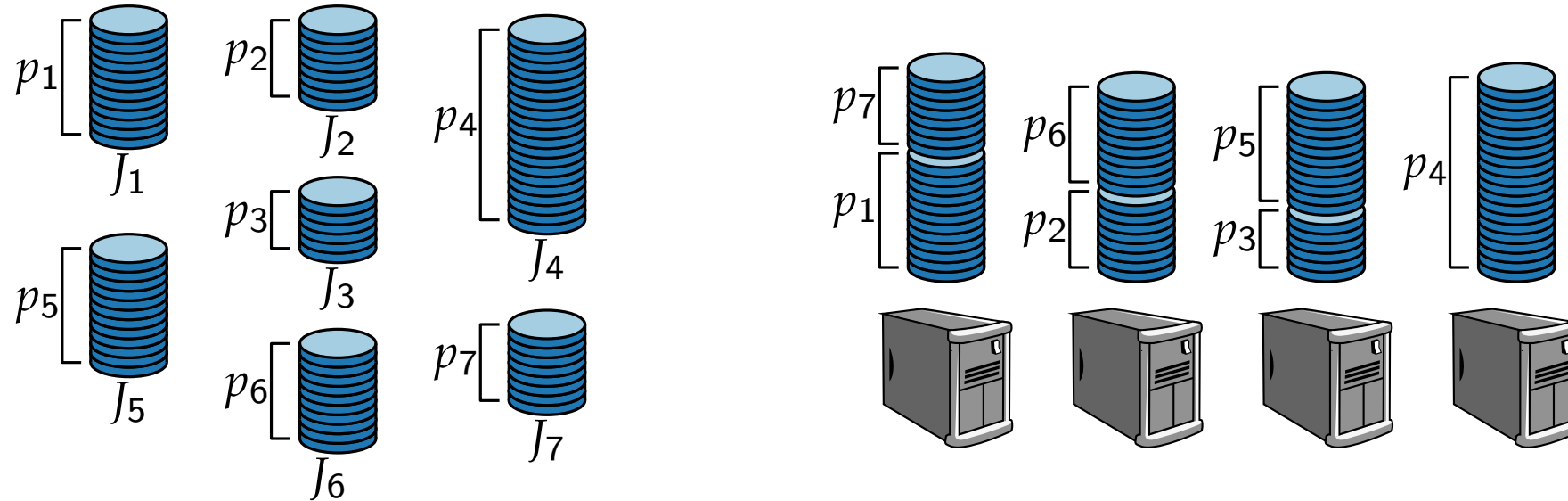
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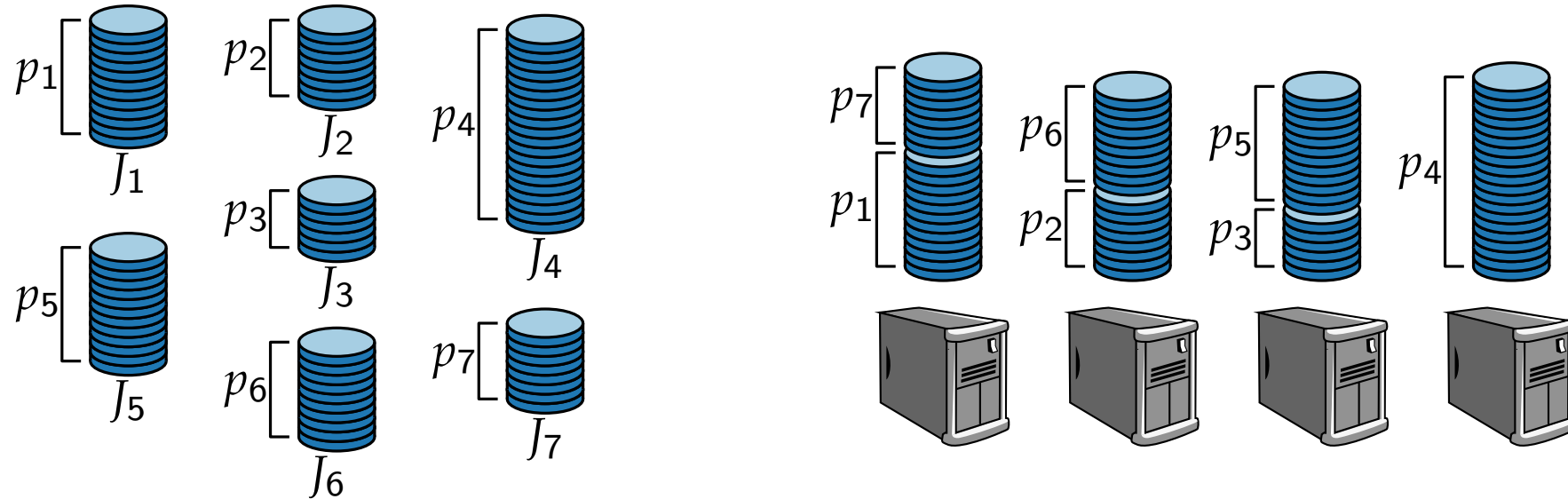
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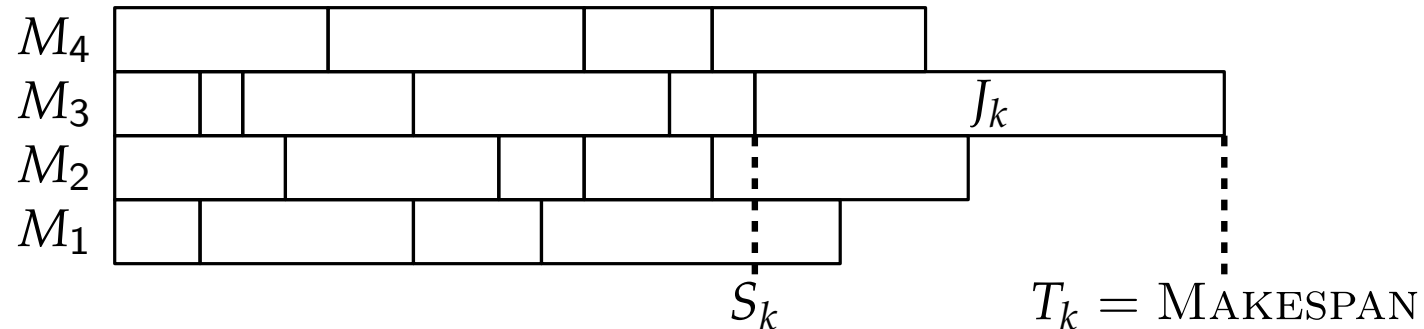
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**Proof.** Let  $J_k = (S_k, T_k)$  be the last job, that is,  $T_k$  determines the makespan.



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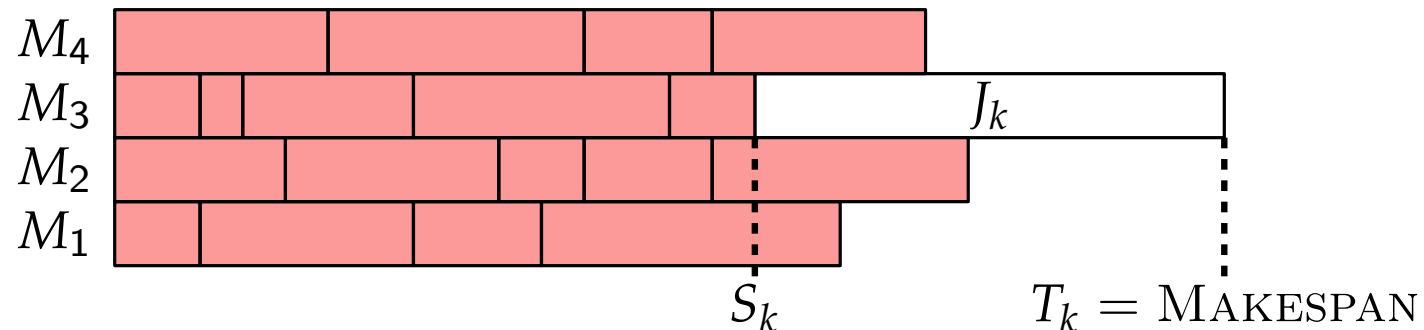
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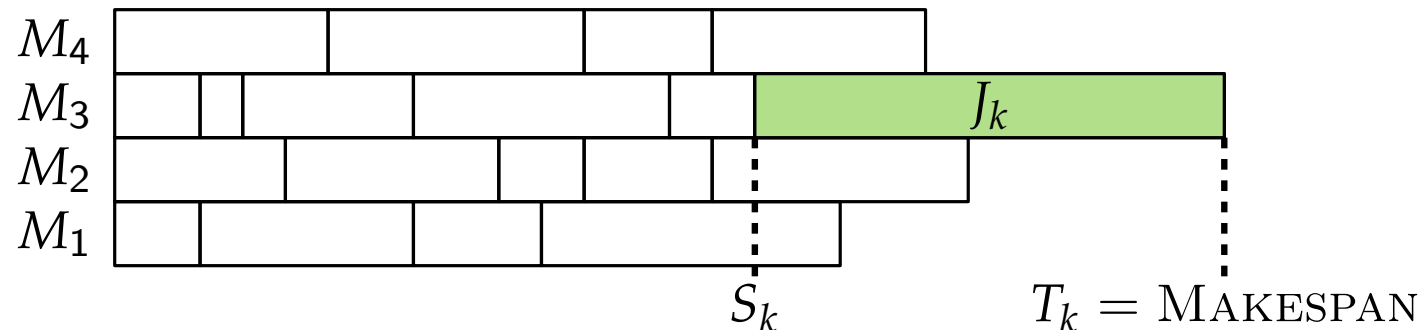
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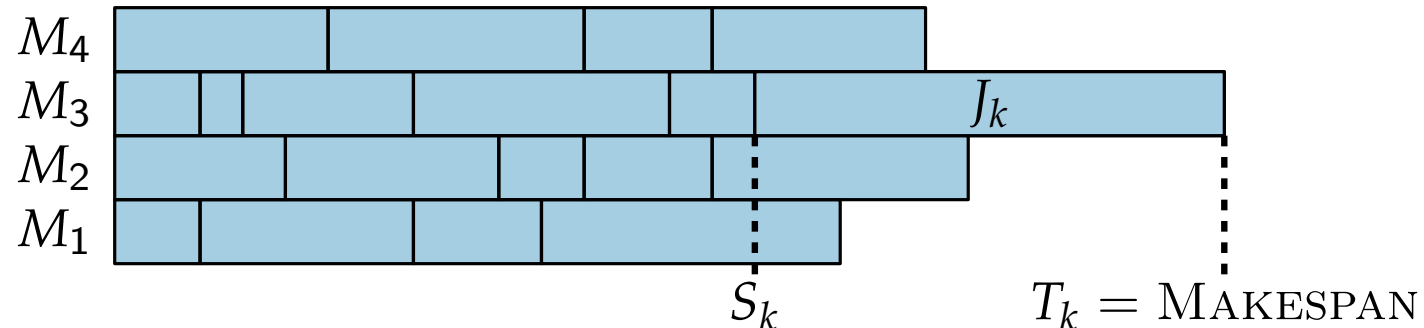
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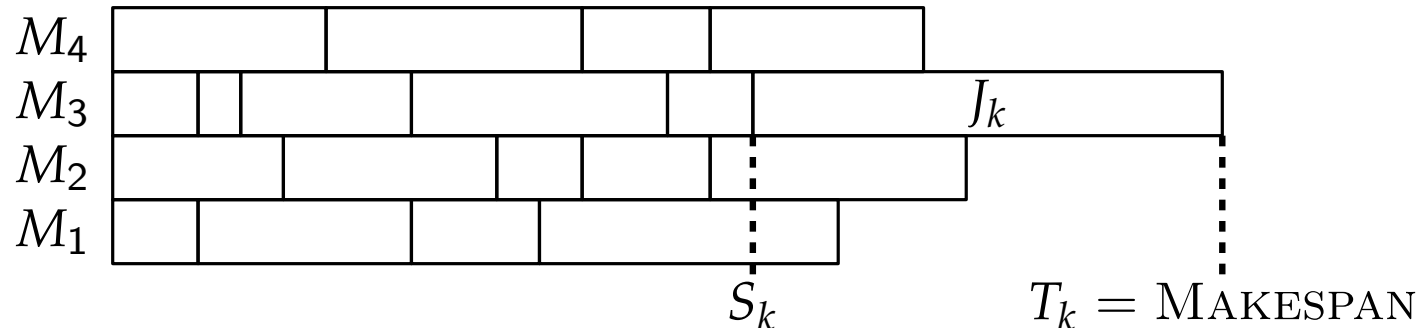
■ Hence:

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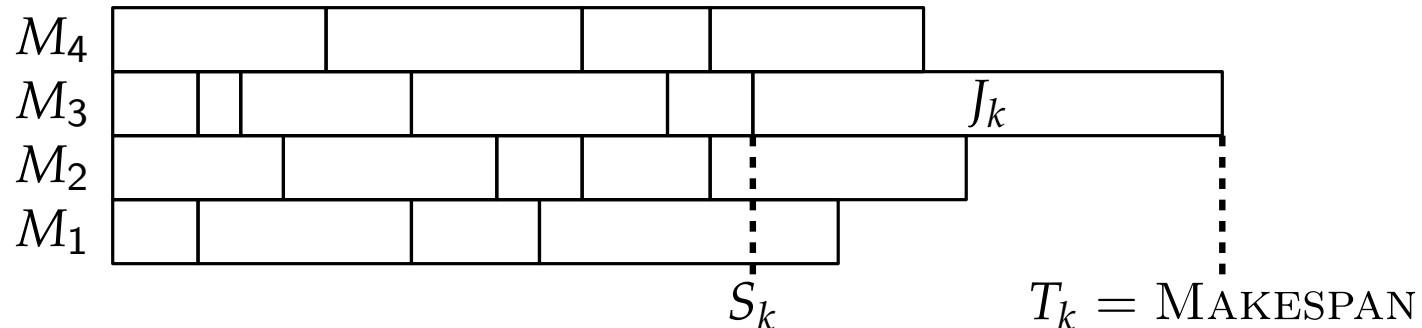
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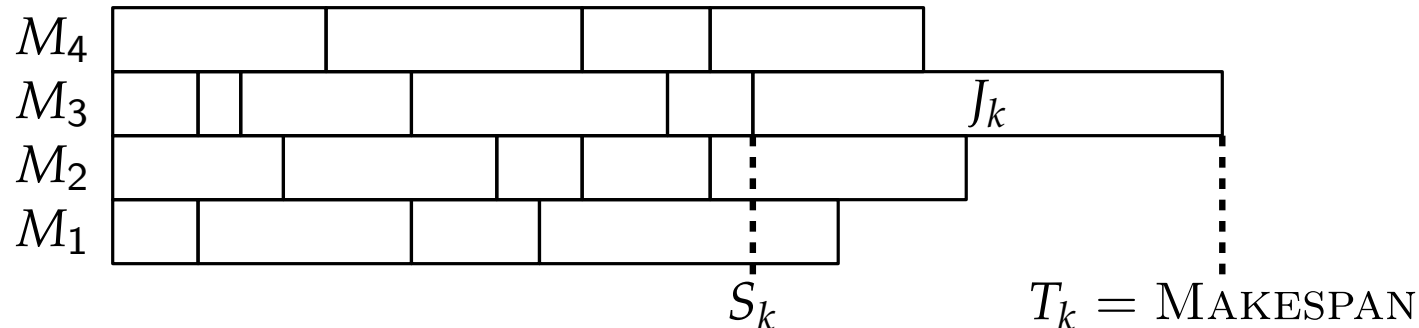
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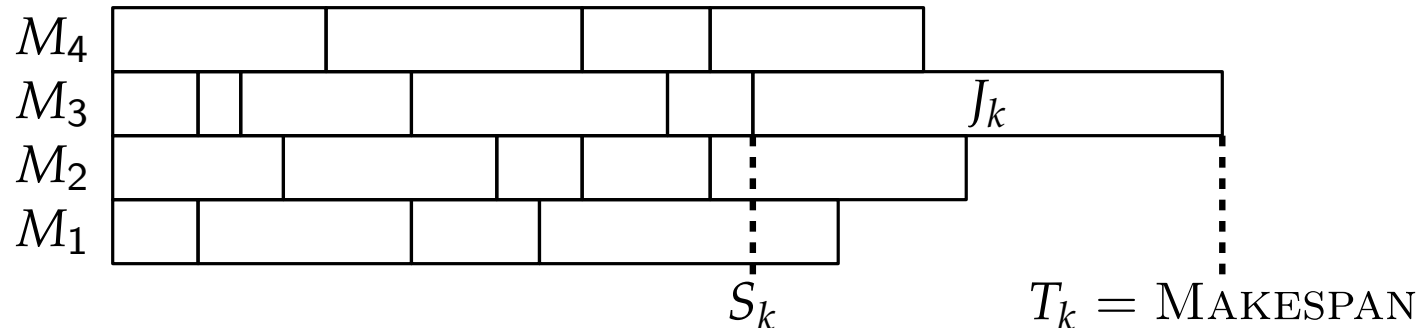
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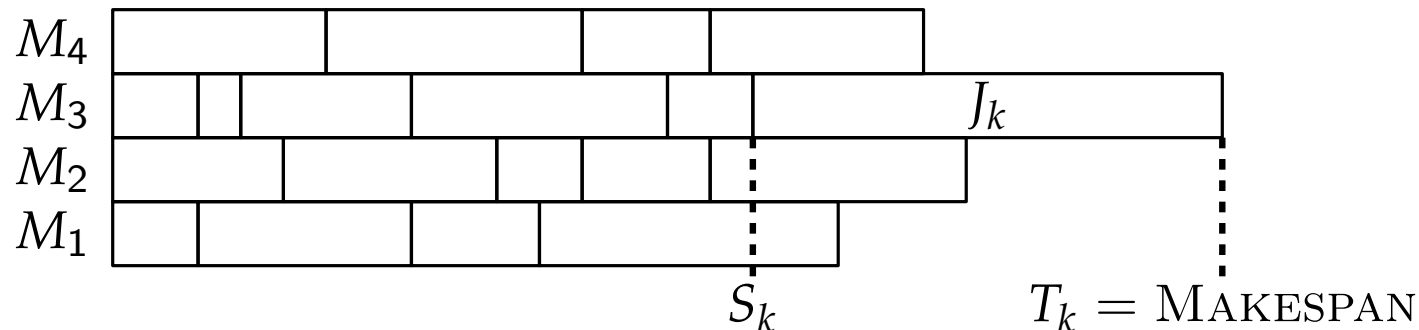
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For a constant  $\ell$  ( $1 \leq \ell \leq n$ ) define the algorithm  $\mathcal{A}_\ell$  as follows.

$\mathcal{A}_\ell(J_1, \dots, J_n, m)$

Sort jobs in descending order of runtime.

Schedule the  $\ell$  longest jobs  $J_1, \dots, J_\ell$  optimally.

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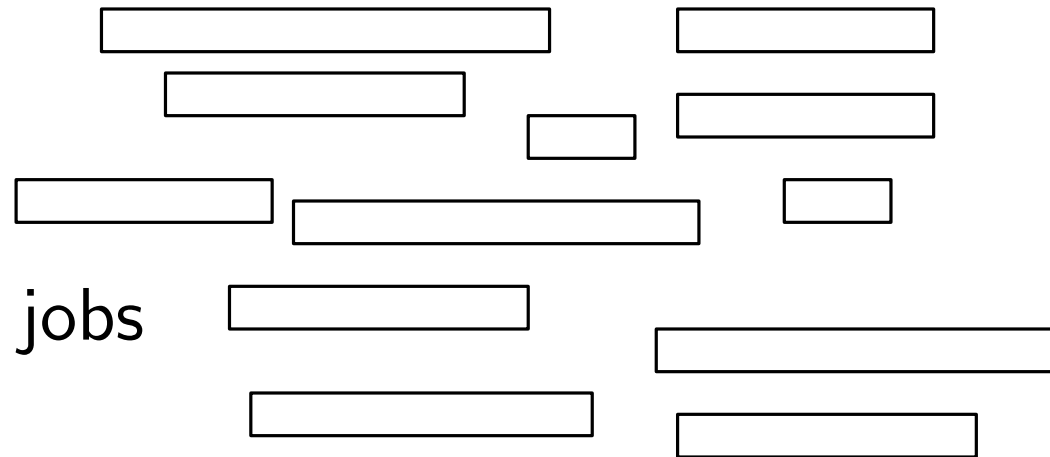
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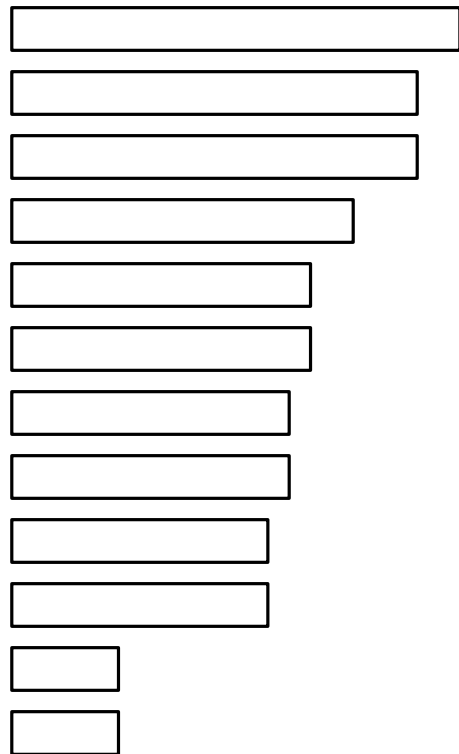
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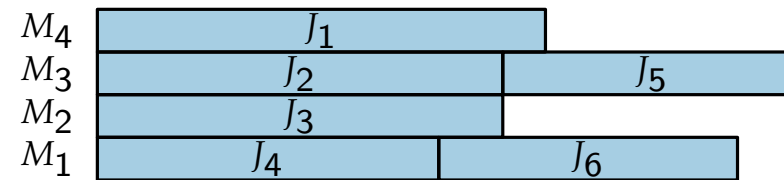
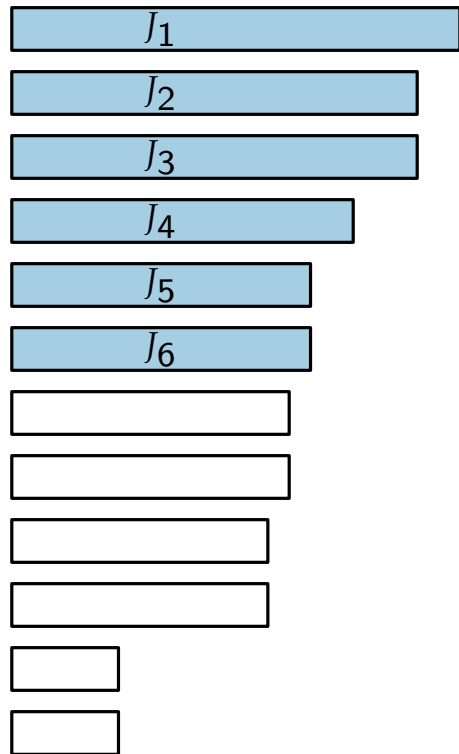
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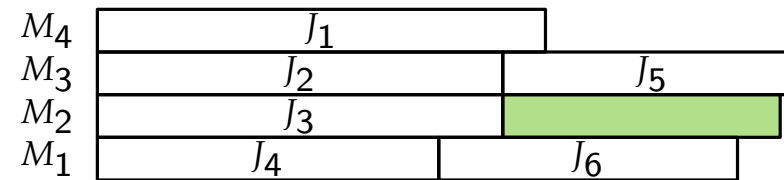
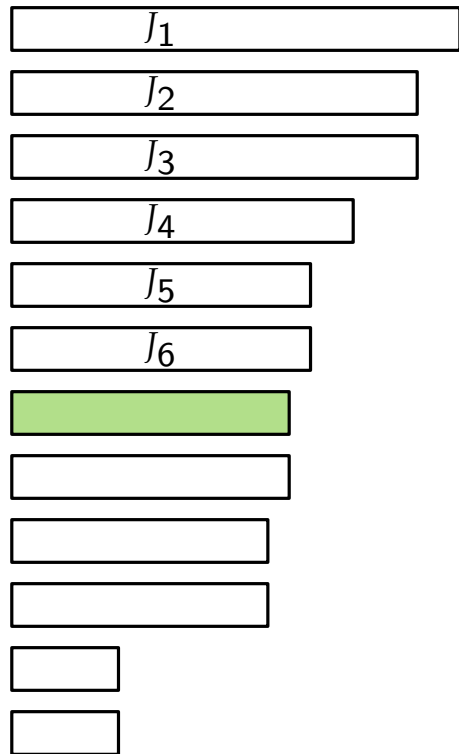
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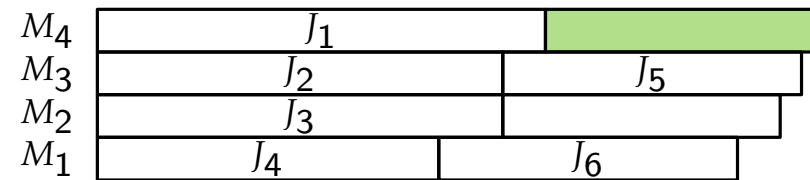
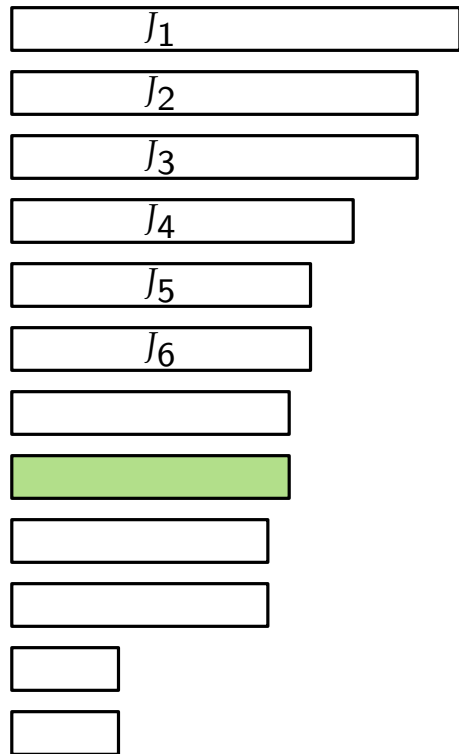
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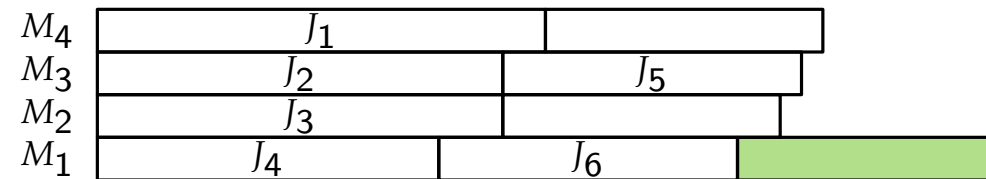
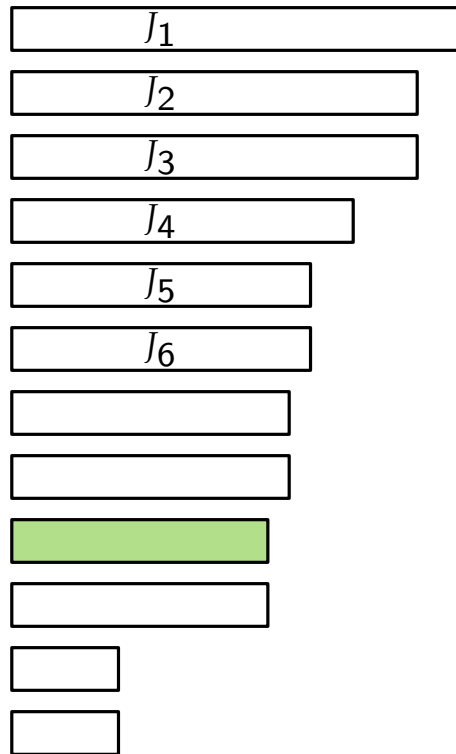
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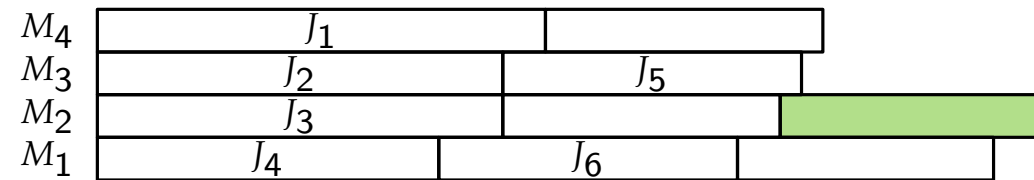
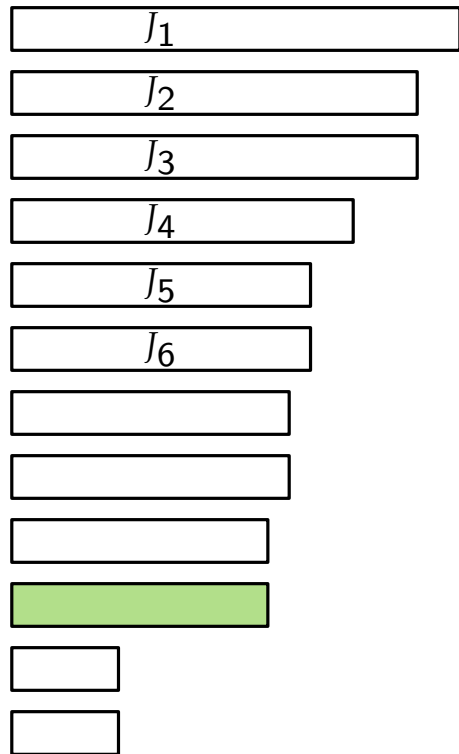
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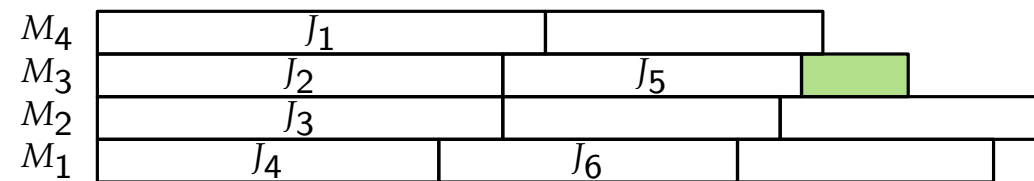
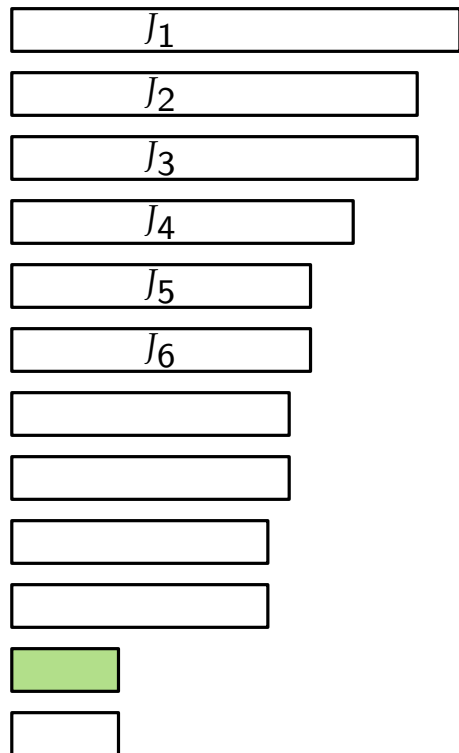
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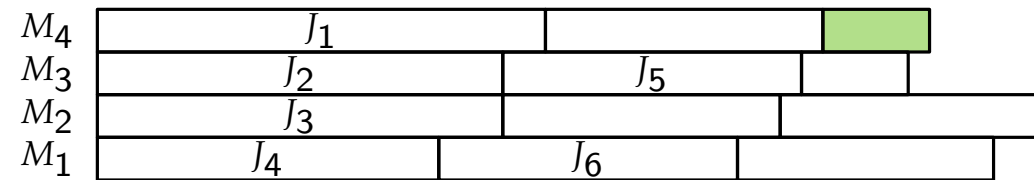
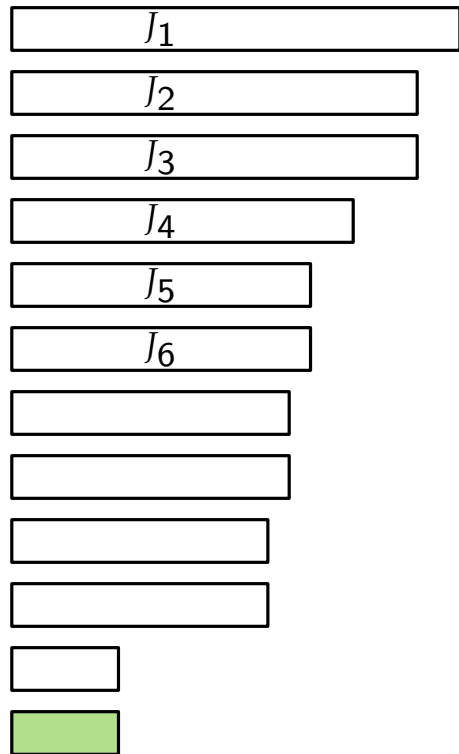
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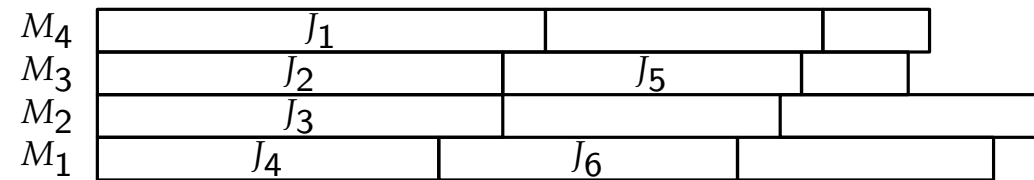
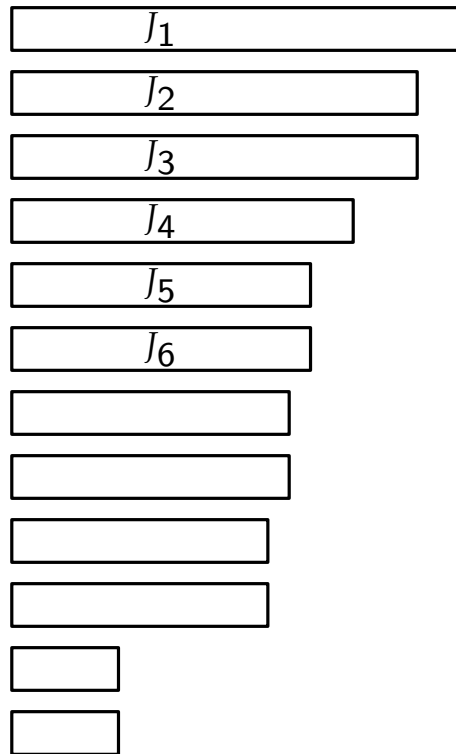
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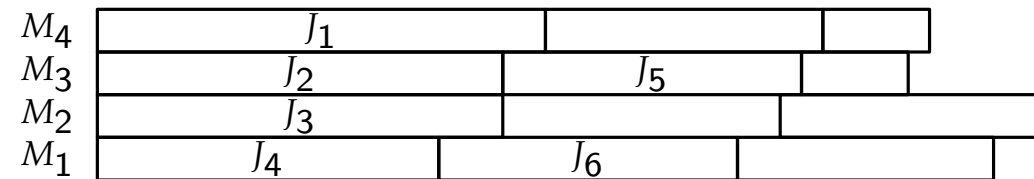
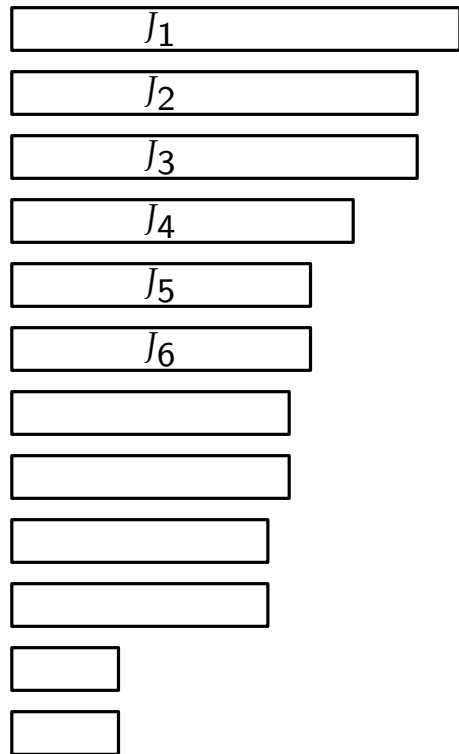
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■ Polynomial time for constant  $\ell$ :  
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## Example.

$\ell = 6$

sorted jobs



# Multiprocessor Scheduling – PTAS

For a constant  $\ell$  ( $1 \leq \ell \leq n$ ) define the algorithm  $\mathcal{A}_\ell$  as follows.

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- $\{\mathcal{A}_\varepsilon \mid \varepsilon > 0\}$  is not an FPTAS since the running time is not polynomial in  $\frac{1}{\varepsilon}$ .

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# Multiprocessor Scheduling – PTAS (Proof)

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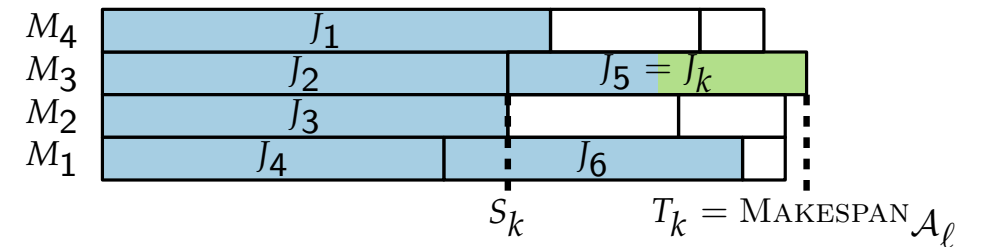
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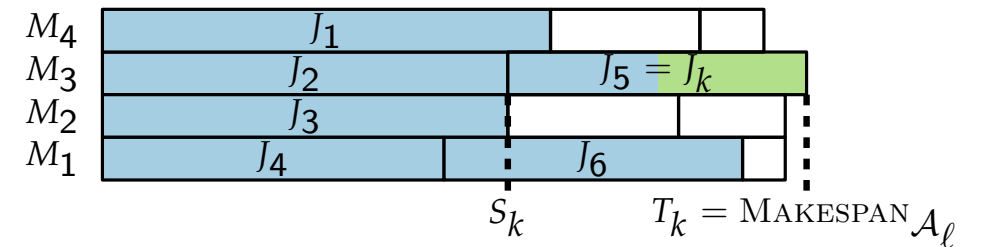
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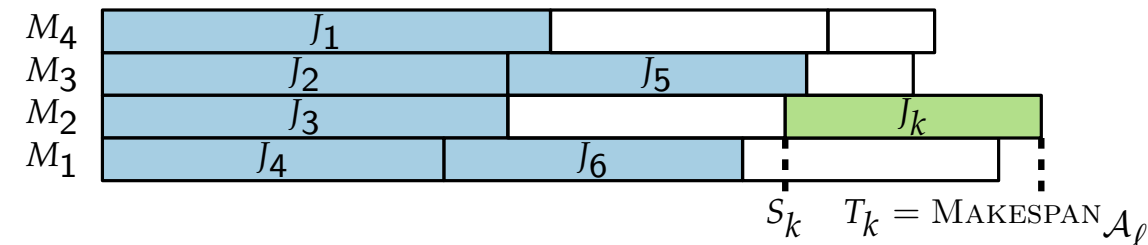
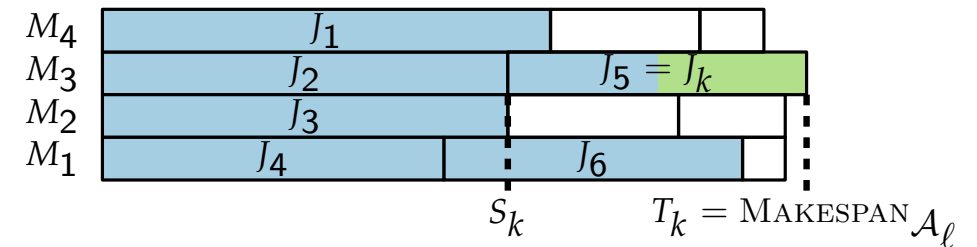
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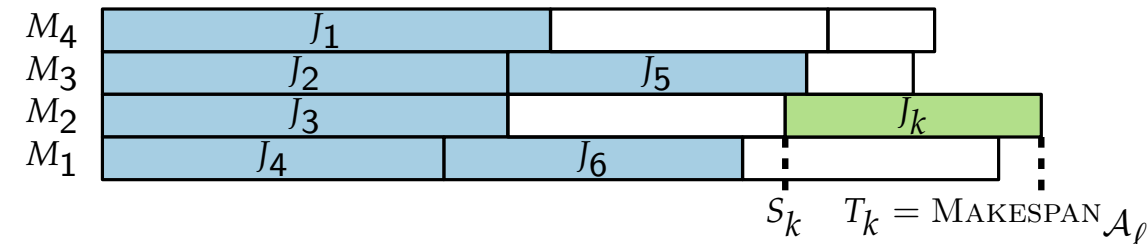
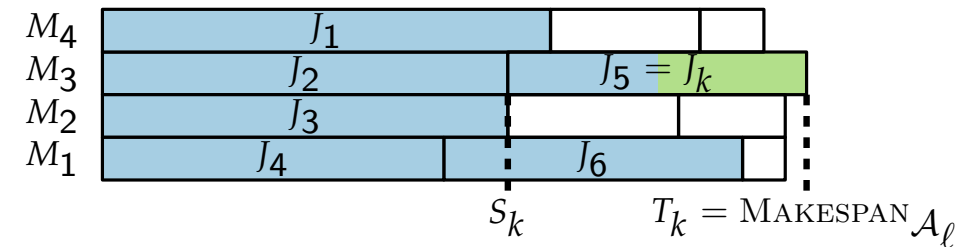
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- Similar analysis to LISTSCHEDULING
- Use that there are  $\ell + 1$  jobs that are at least as long as  $J_k$  (including  $J_k$ ).



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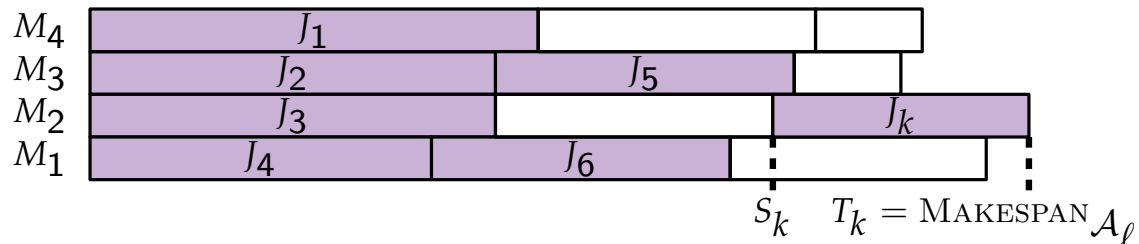
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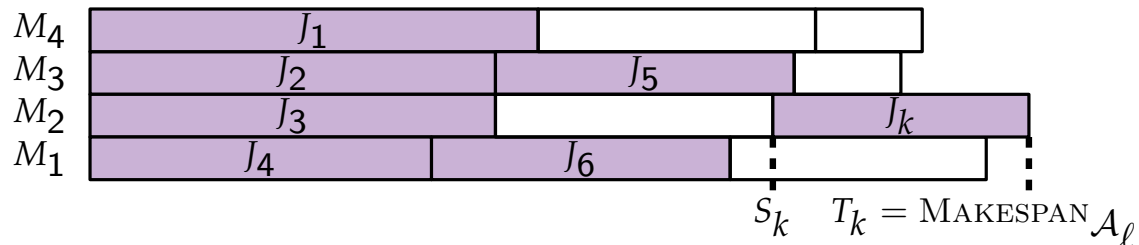
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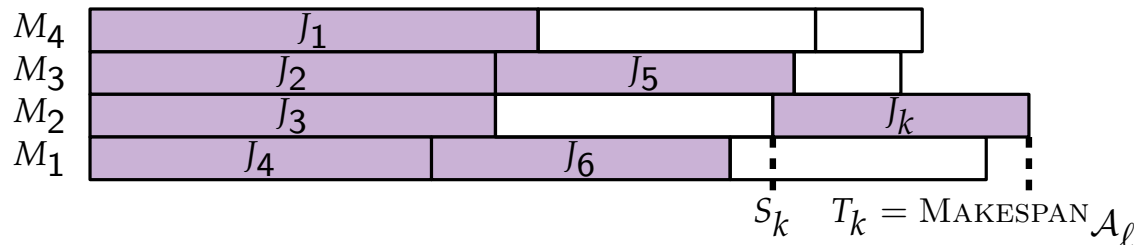
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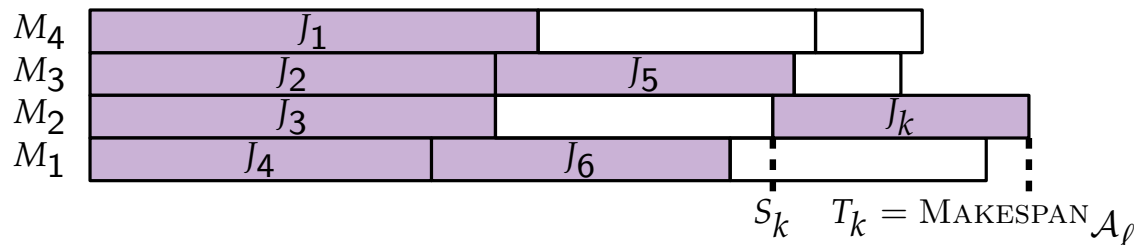
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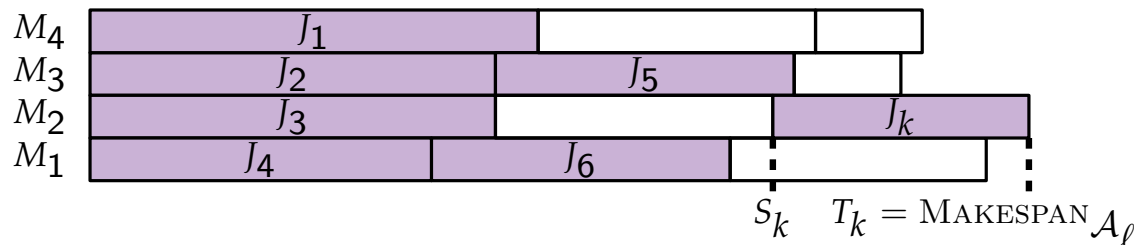
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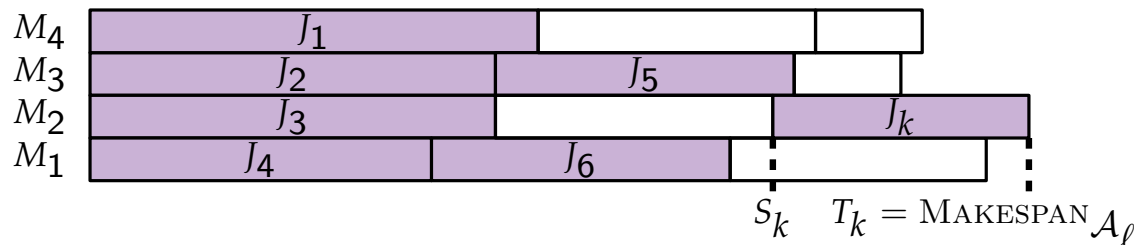
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$T_{\text{OPT}} \geq p_k \cdot \left(1 + \lfloor \frac{\ell}{m} \rfloor\right)$  one machine has this many jobs\* each has length  $\geq p_k$

■ \* on average, each machine has more than  $\frac{\ell}{m}$  of the  $\ell + 1$  jobs

■ at least one machine achieves the average



$$T_k = S_k + p_k$$

$$\leq \frac{1}{m} \cdot \sum_{i \neq k} p_i + p_k$$

$$= \frac{1}{m} \cdot \sum_{i=1}^m p_i + \left(1 - \frac{1}{m}\right) \cdot p_k$$

$$\leq T_{\text{OPT}} + \left(1 - \frac{1}{m}\right) \cdot T_{\text{OPT}}$$

can we do better?



# Multiprocessor Scheduling – PTAS (Proof)

## Theorem 8.

For constant  $1 \leq \ell \leq n$ , the algorithm  $\mathcal{A}_\ell$  is a  $1 + \frac{1 - \frac{1}{m}}{1 + \lfloor \frac{\ell}{m} \rfloor}$ -approximation algorithm.

$\mathcal{A}_\ell(J_1, \dots, J_n, m)$

Sort jobs in descending order of runtime.

Schedule the  $\ell$  longest jobs  $J_1, \dots, J_\ell$  optimally.

Use LISTSCHEDULING for the remaining jobs  $J_{\ell+1}, \dots, J_n$ .

## Proof of Case 2.

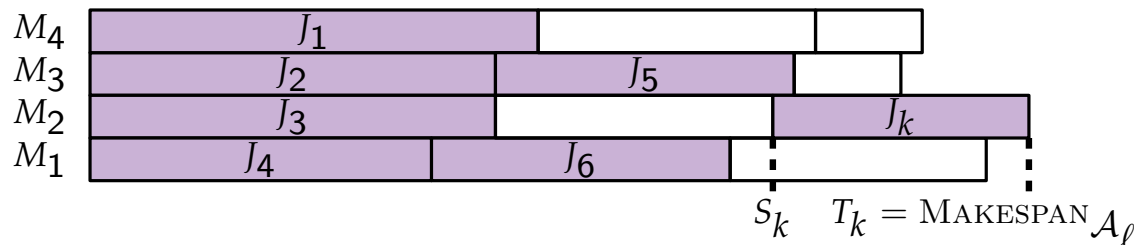
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$$\begin{aligned} T_k &= S_k + p_k \\ &\leq \frac{1}{m} \cdot \sum_{i \neq k} p_i + p_k \\ &= \frac{1}{m} \cdot \sum_{i=1}^m p_i + \left(1 - \frac{1}{m}\right) \cdot p_k \\ &\leq T_{\text{OPT}} + \frac{1 - \frac{1}{m}}{1 + \left\lfloor \frac{\ell}{m} \right\rfloor} \cdot T_{\text{OPT}} \end{aligned}$$

# Discussion

- Only “easy” NP-hard problems admit FPTAS (PTAS).
- Some problems cannot be approximated very well (e.g., Maximum Clique).
- Study of approximability of NP-hard problems yields more fine-grained classifications.

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- Approximation algorithms can be of various types:  
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- Minimum Vertex Coloring on planar graphs can be approximated with an additive approximation guarantee of 2.
- Christofides’ approximation algorithm for Metric TSP has approximation factor 1.5.
- There is a whole lecture on approximation algorithms this semester!  
<https://wuecampus.uni-wuerzburg.de/moodle/course/view.php?id=62943>

# Literature

## Main references

- [Jansen & Margraf, 2008: Ch3]  
“Approximative Algorithmen und Nichtapproximierbarkeit”
- [Williamson & Shmoys, 2011: Ch3]  
“The Design of Approximation Algorithms”

## Another book recommendation:

- [Vazirani, 2013] “Approximation Algorithms”

