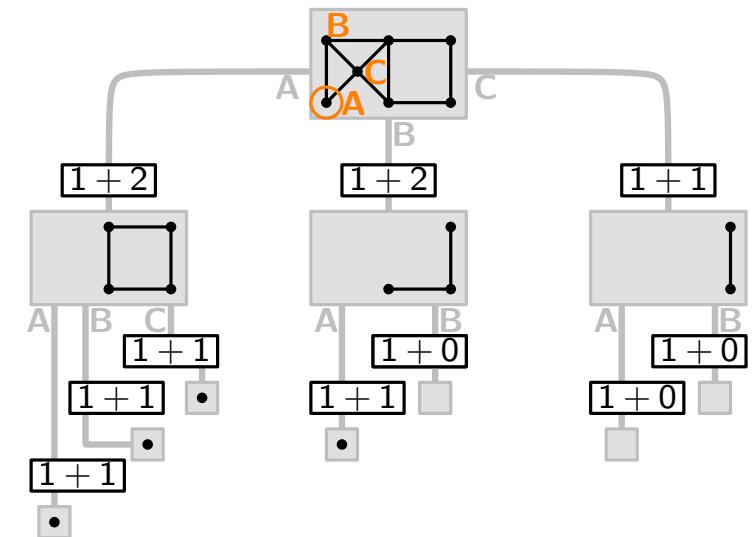
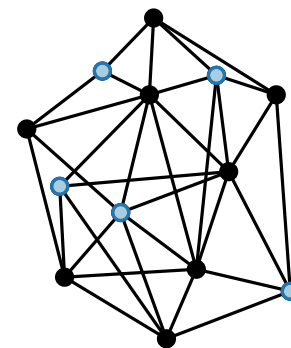
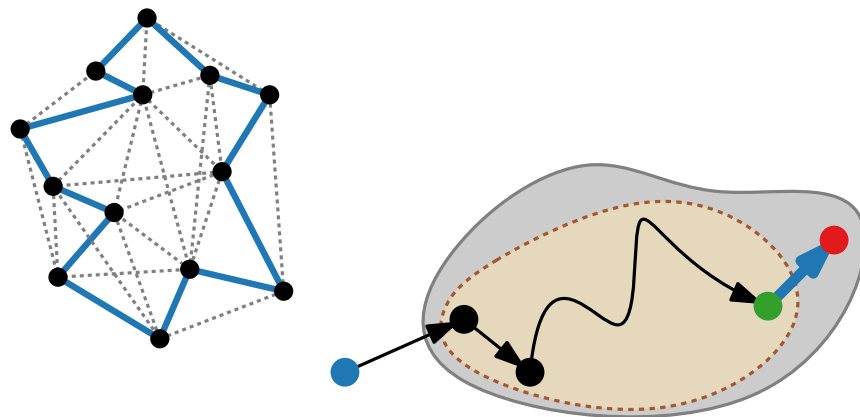


Advanced Algorithms

Exact Algorithms for NP-hard Problems

TRAVELING SALESMAN PROBLEM and MAXIMAL INDEPENDENT SET

Diana Sieper · WS22

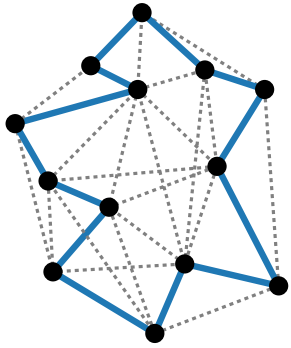


Examples of NP-hard Problems

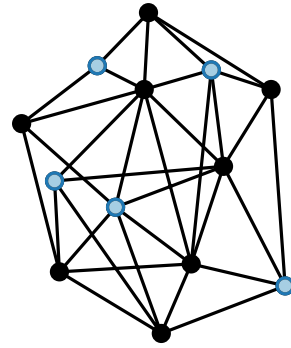
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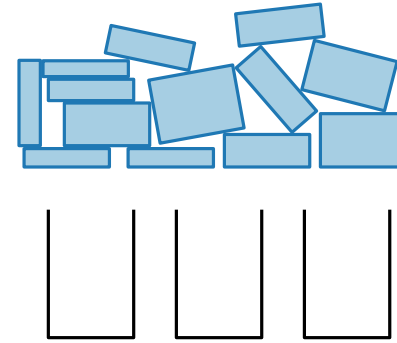
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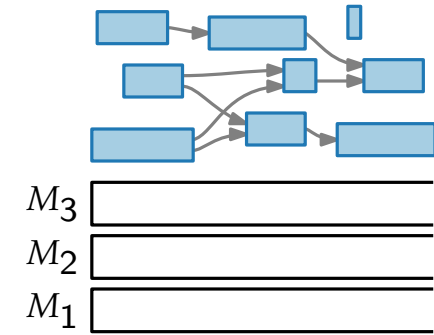
TSP



MIS



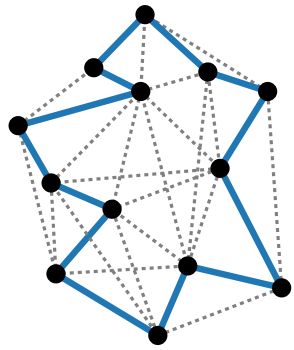
Bin Packing



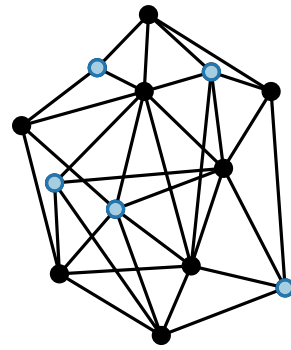
Scheduling

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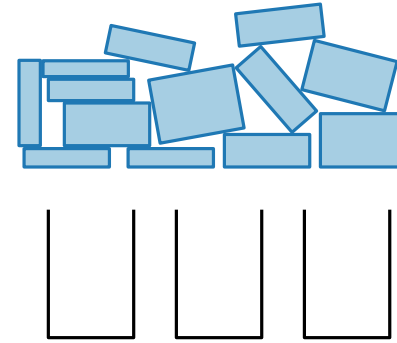
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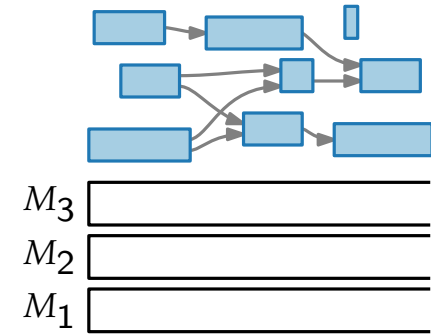
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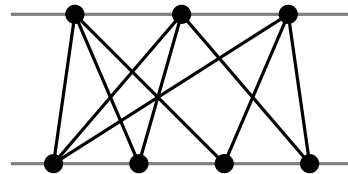


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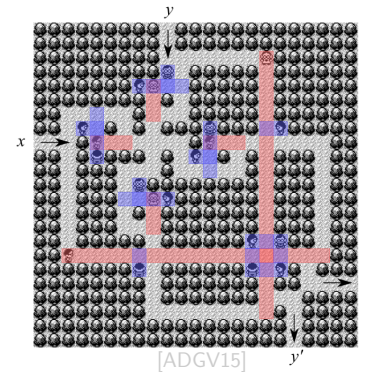
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...

SAT



Graph Drawing



Games

...

Formal View on NP-Hardness

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Misconceptions about NP-Hardness

Common misconceptions [Mann '17]

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- For solving NP-hard problems, the only practical possibility is the use of heuristics.

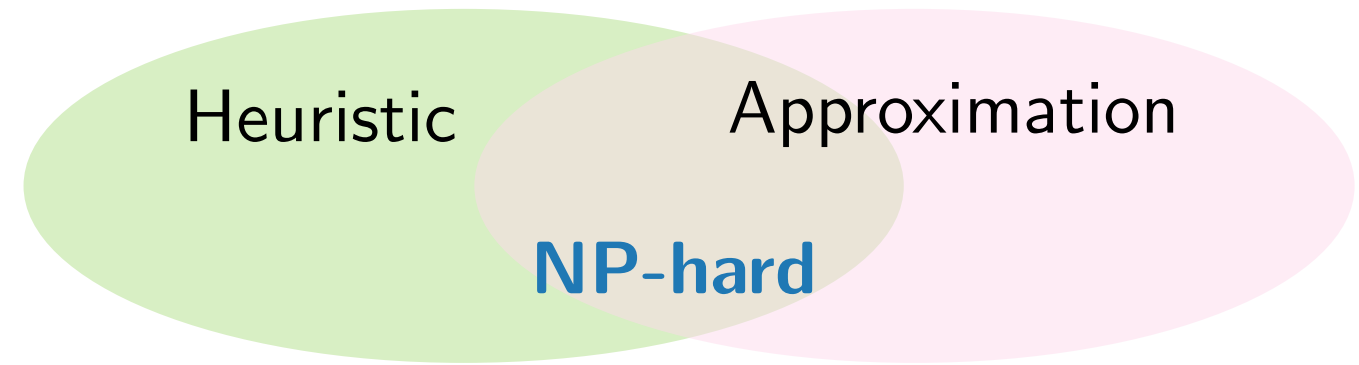
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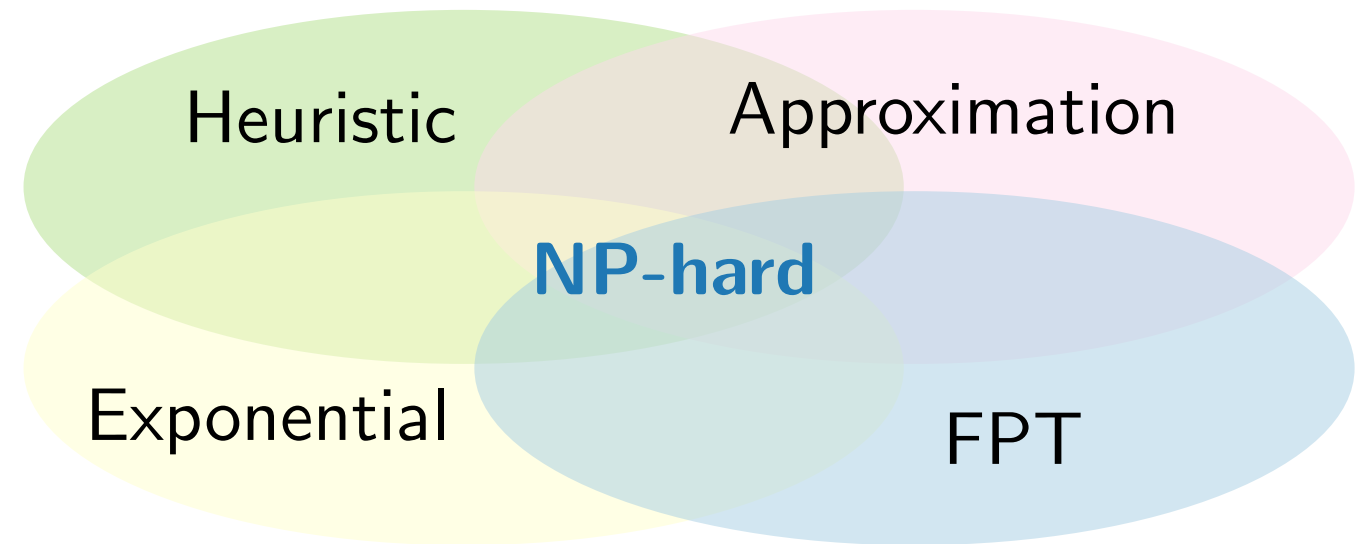
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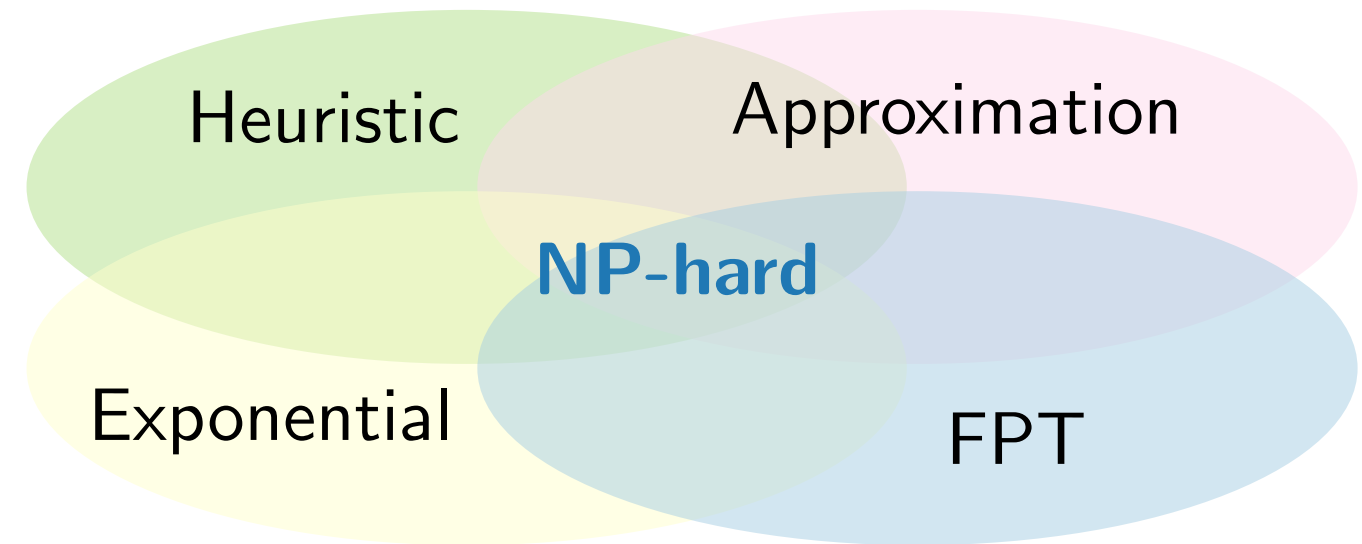
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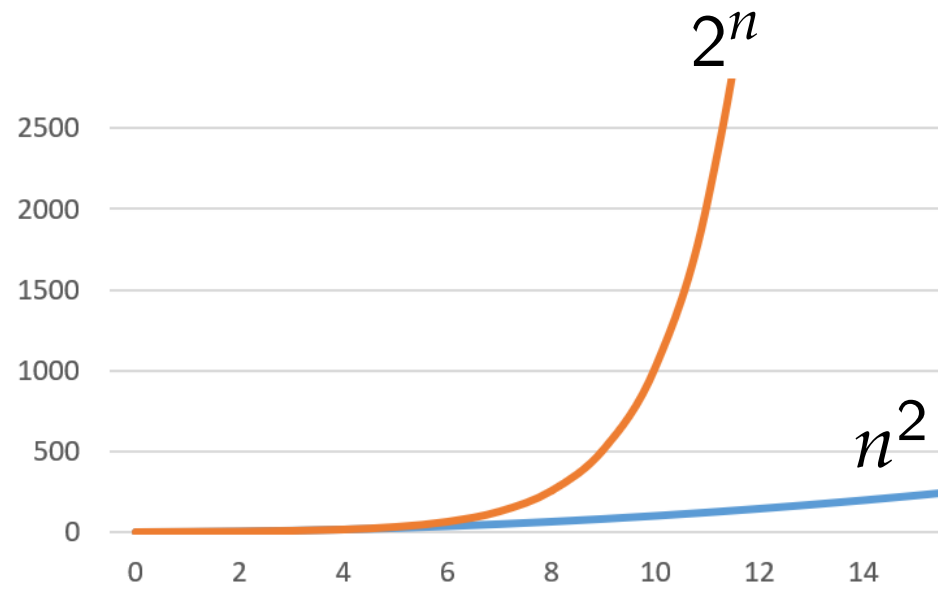
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this lecture

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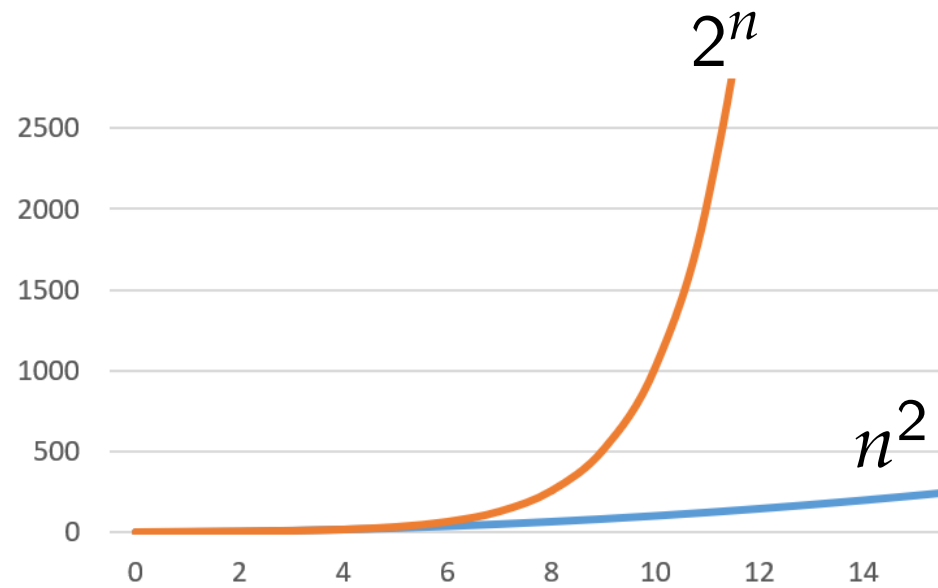
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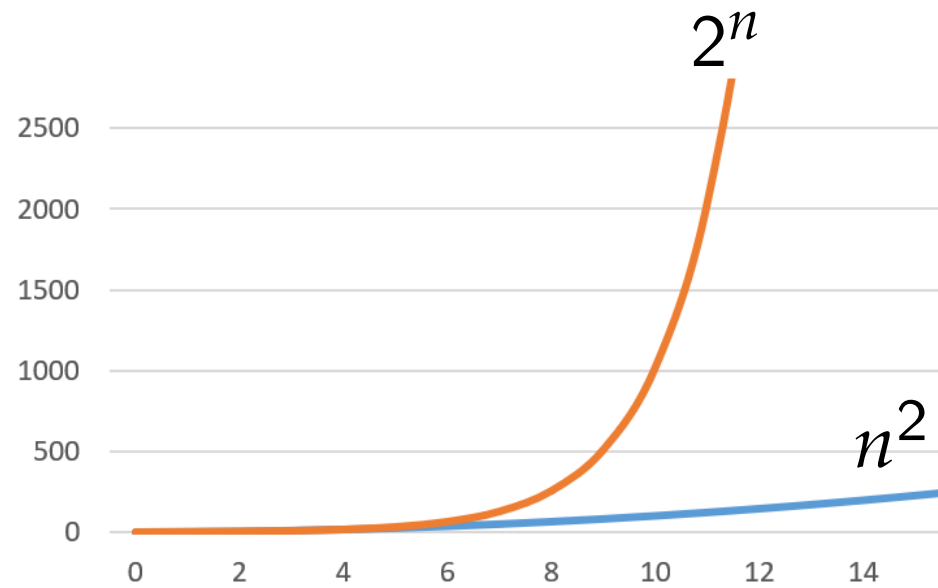


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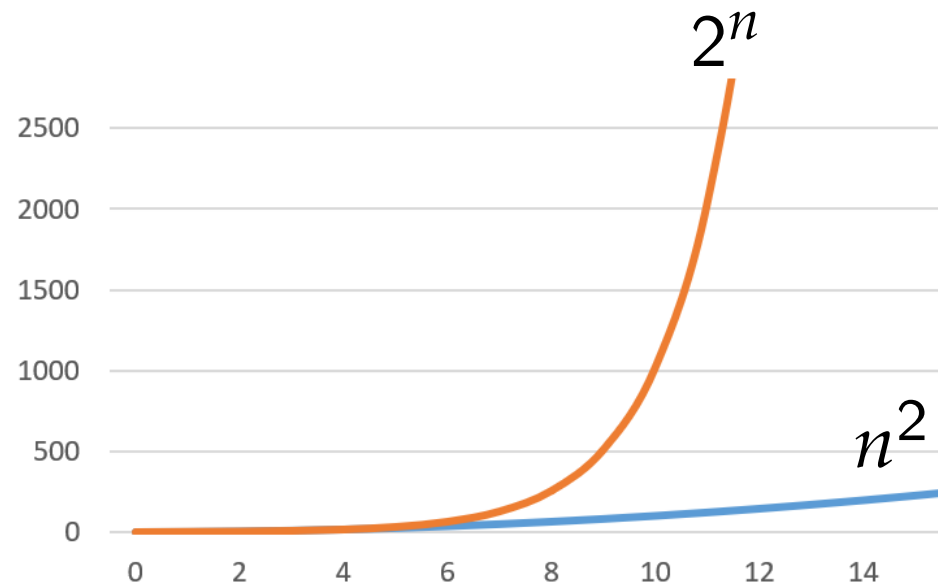
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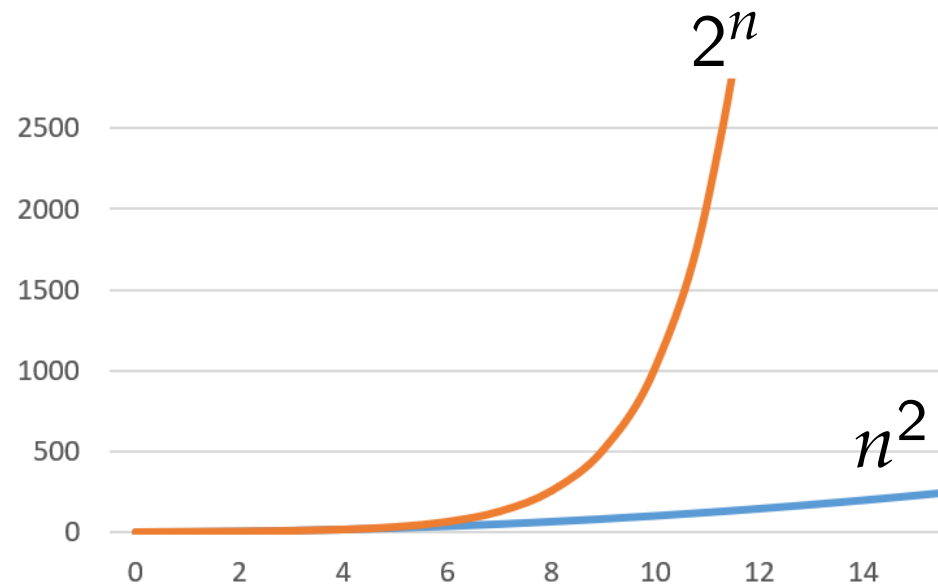
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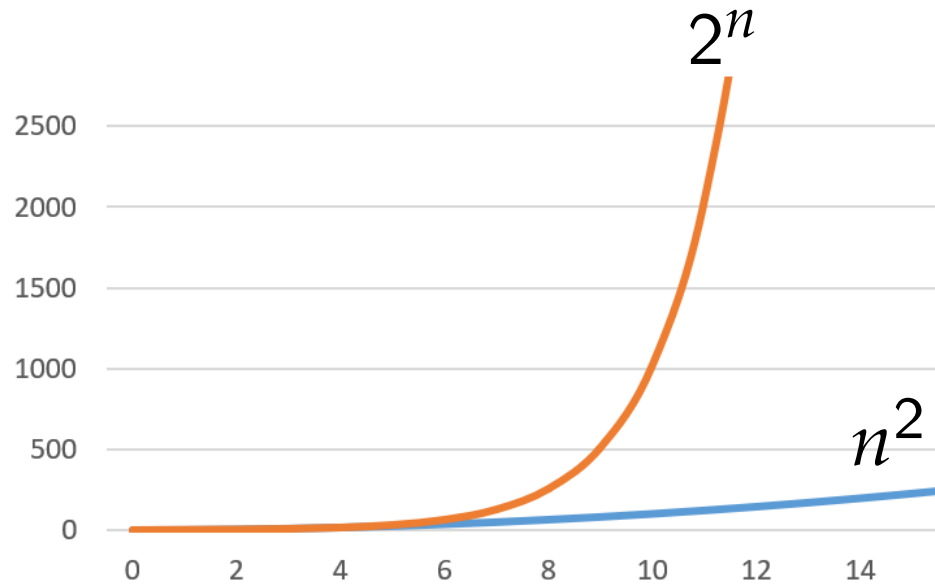
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 - TSP solvable exactly for $n \leq 2000$ and specialized instances with $n \leq 85900$

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- Reducing the base of the runtime to $b < a$ results in a *multiplicative* increase:

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■ SAT: No better algorithm than trivial brute-force search known.

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- typical result

Approach	Runtime in \mathcal{O} -Notation	\mathcal{O}^* -Notation
Brute-Force	$\mathcal{O}(2^n)$	$\mathcal{O}^*(2^n)$
Algorithm A	$\mathcal{O}(1.5^n \cdot n)$	$\mathcal{O}^*(1.5^n)$
Algorithm B	$\mathcal{O}(1.4^n \cdot n^2)$	$\mathcal{O}^*(1.4^n)$

Traveling Salesperson Problem (TSP)

Input. Distinct cities $\{v_1, v_2, \dots, v_n\}$ with distances $d(c_i, c_j) \in \mathbb{Q}_{\geq 0}$;
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Brute-force.

- Try all permutations and pick the one with smallest weight.
- Runtime: $\Theta(n! \cdot n) = n \cdot 2^{\Theta(n \log n)}$

TSP – Dynamic Programming

Bellman-Held-Karp Algorithm

Idea.

- Reuse optimal substructures with dynamic programming.



Richard M. Karp



Richard E. Bellman

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●
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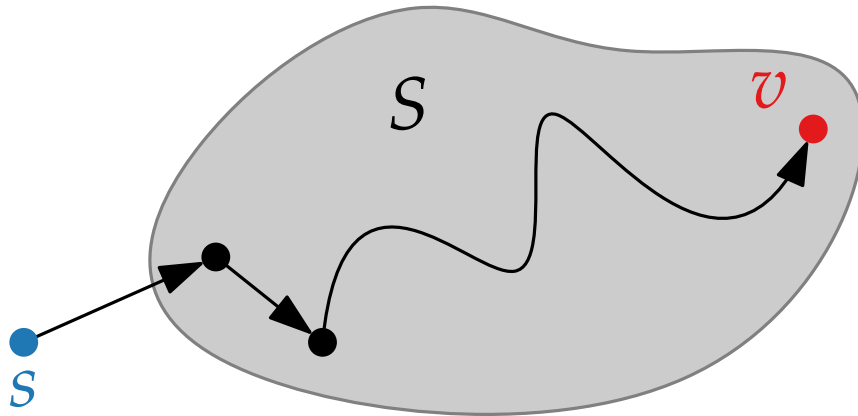
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$\text{OPT}[S, v]$ = length of a shortest s - v -path that visits precisely the vertices of $S \cup \{s\}$.



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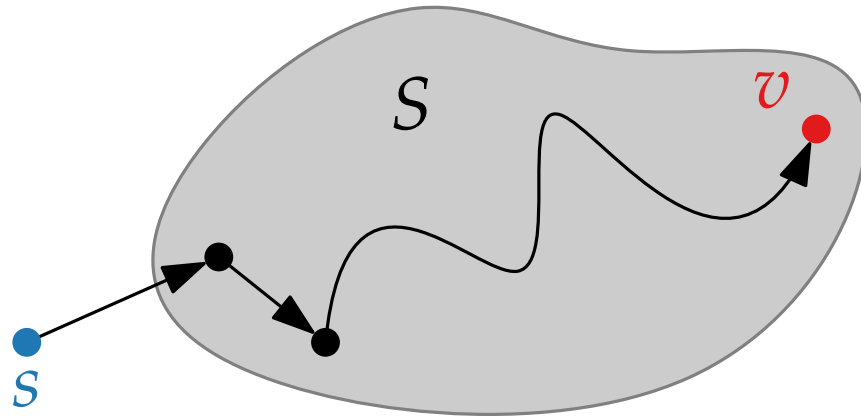
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- Use $\text{OPT}[S - v, u]$ to compute $\text{OPT}[S, v]$.



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Details.

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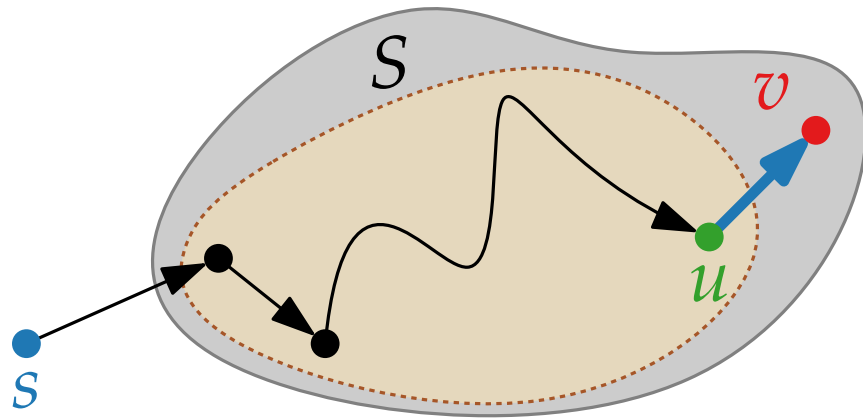
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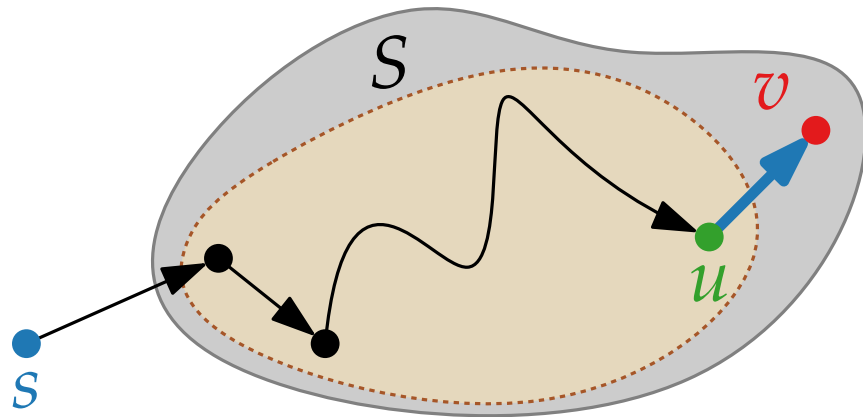


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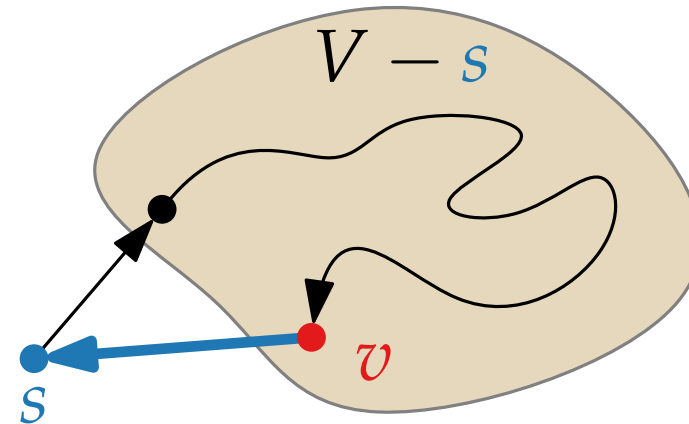
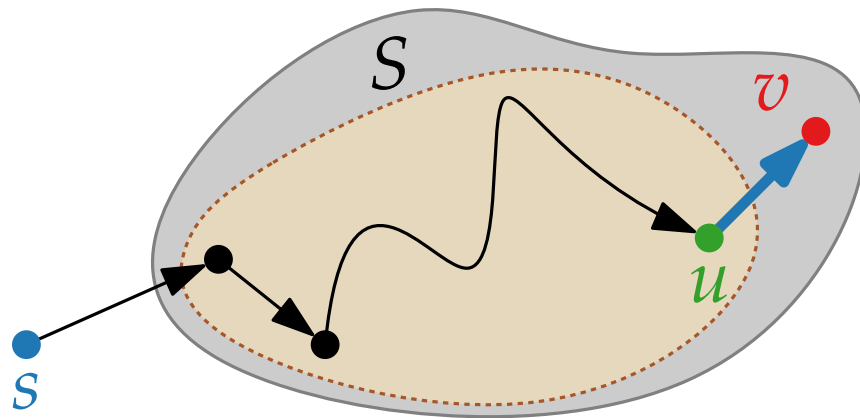


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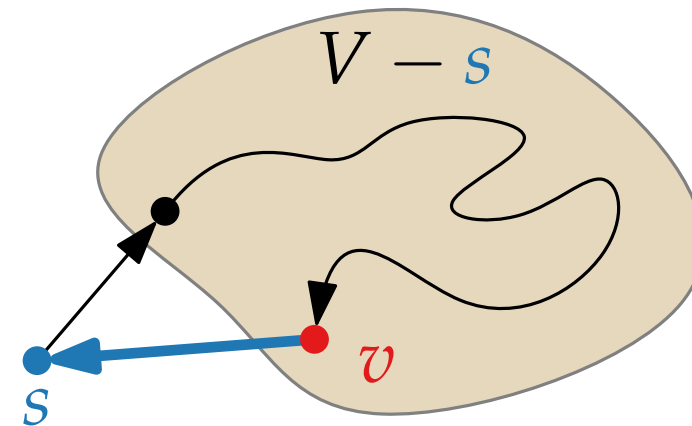
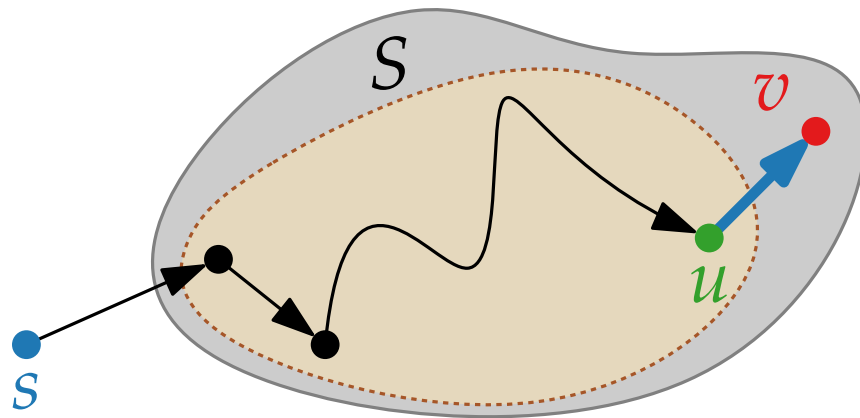
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Algorithm Bellmann-Held-Karp(G, c)

foreach $v \in V - s$ **do**

└ $\text{OPT}[\{v\}, v] = c(s, v)$

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TSP – Dynamic Programming

Pseudocode.

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- Or actually better? What table values do we need to store?

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- DP algorithm that runs in $\mathcal{O}^*(2^n)$ time and $\mathcal{O}(2^n \cdot n)$ space
- Brute-force runs in $2^{\mathcal{O}(n \log n)}$ time
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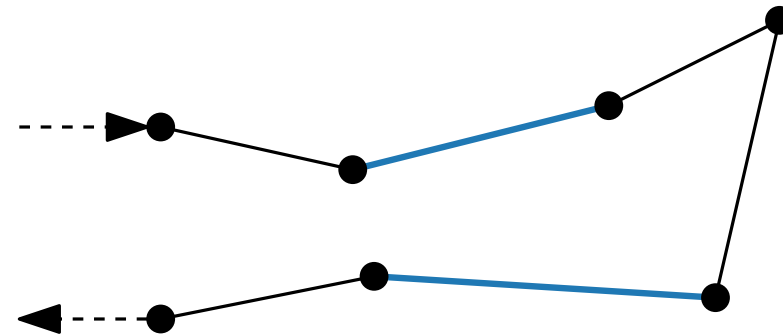
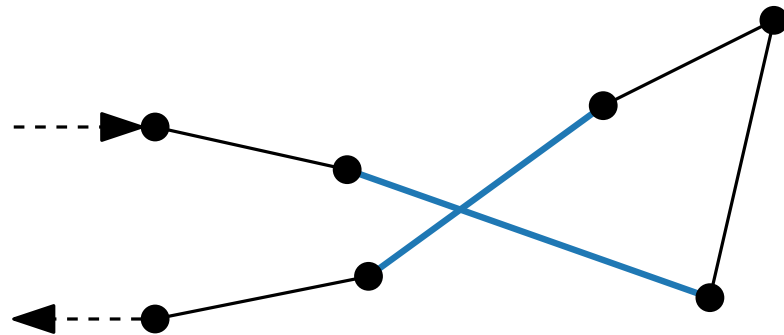
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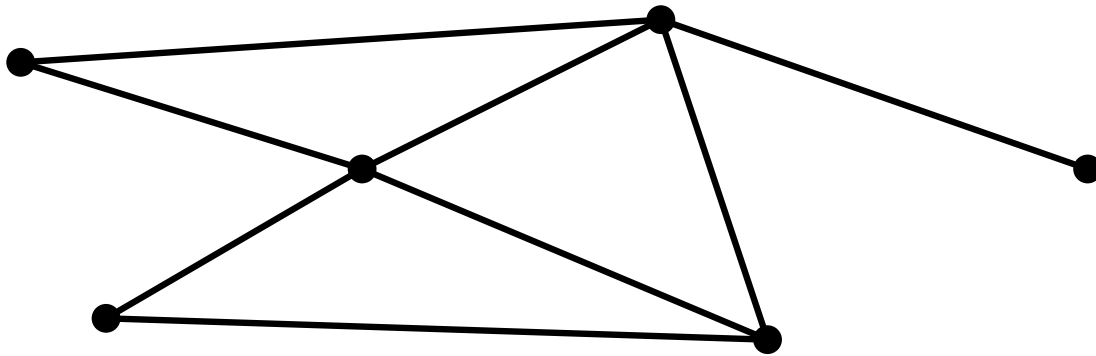
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- In practice, one successful approach is to start with a greedily computed Hamiltonian cycle and then use 2-OPT and 3-OPT swaps to improve it.



Maximum Independent Set (MIS)

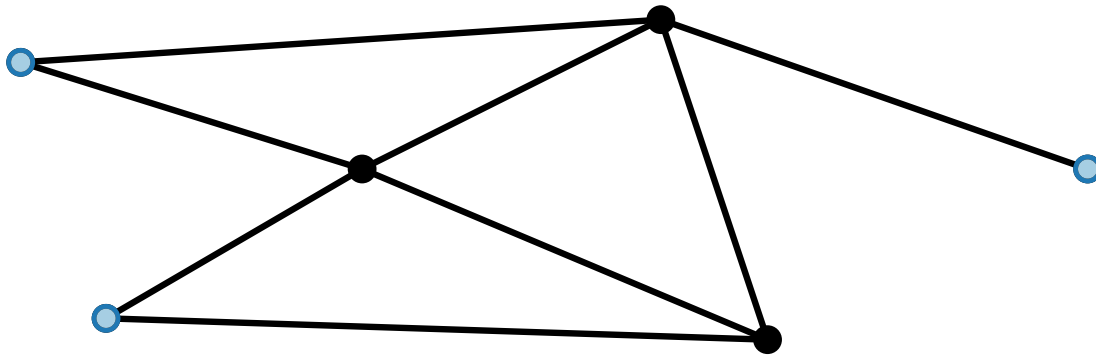
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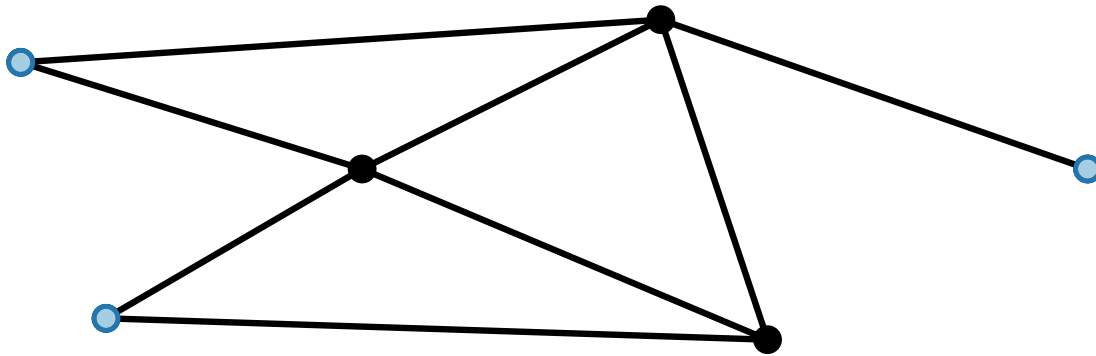
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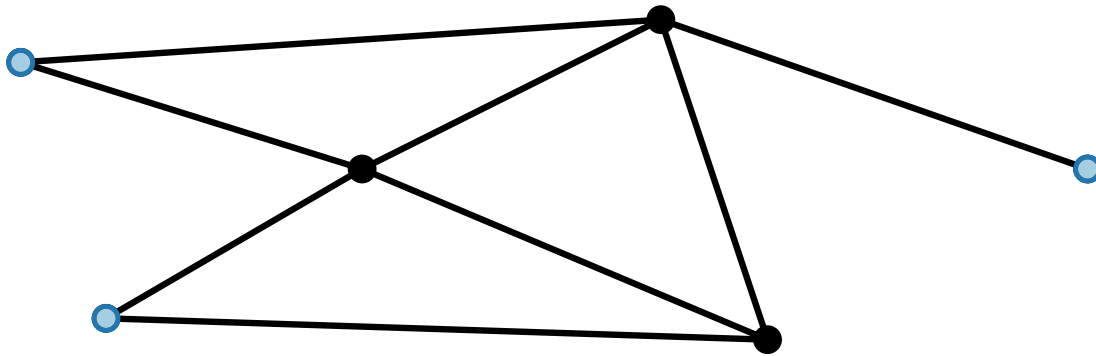
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Naive MIS branching.

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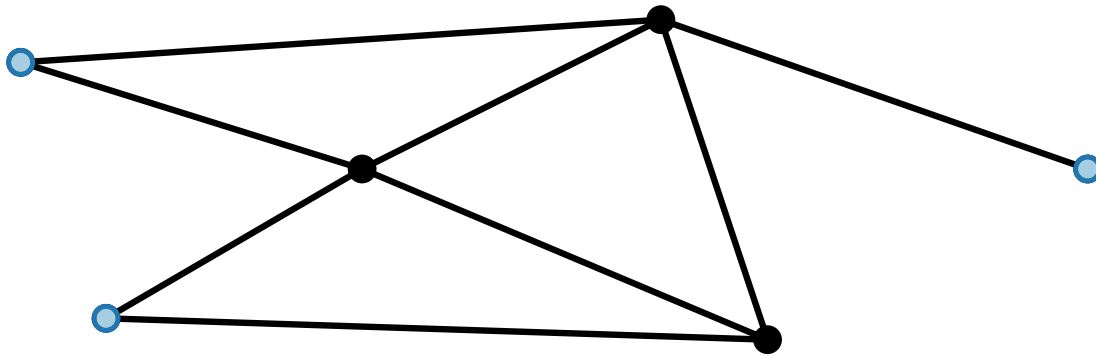
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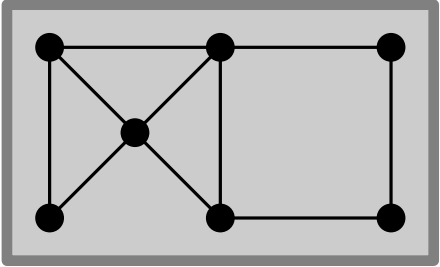
Algorithm NaiveMIS(G)

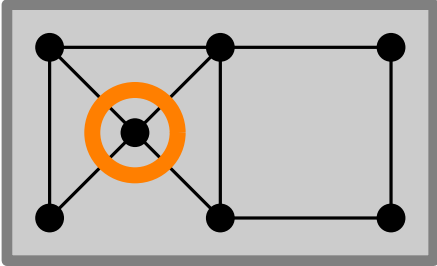
if $V = \emptyset$ **then**

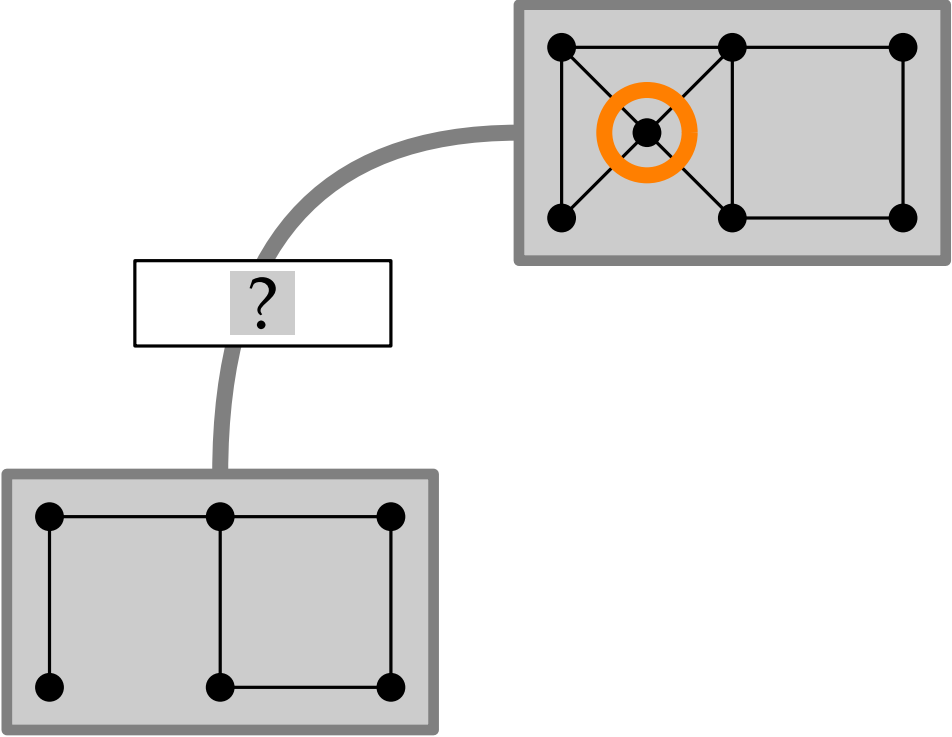
└ **return** 0

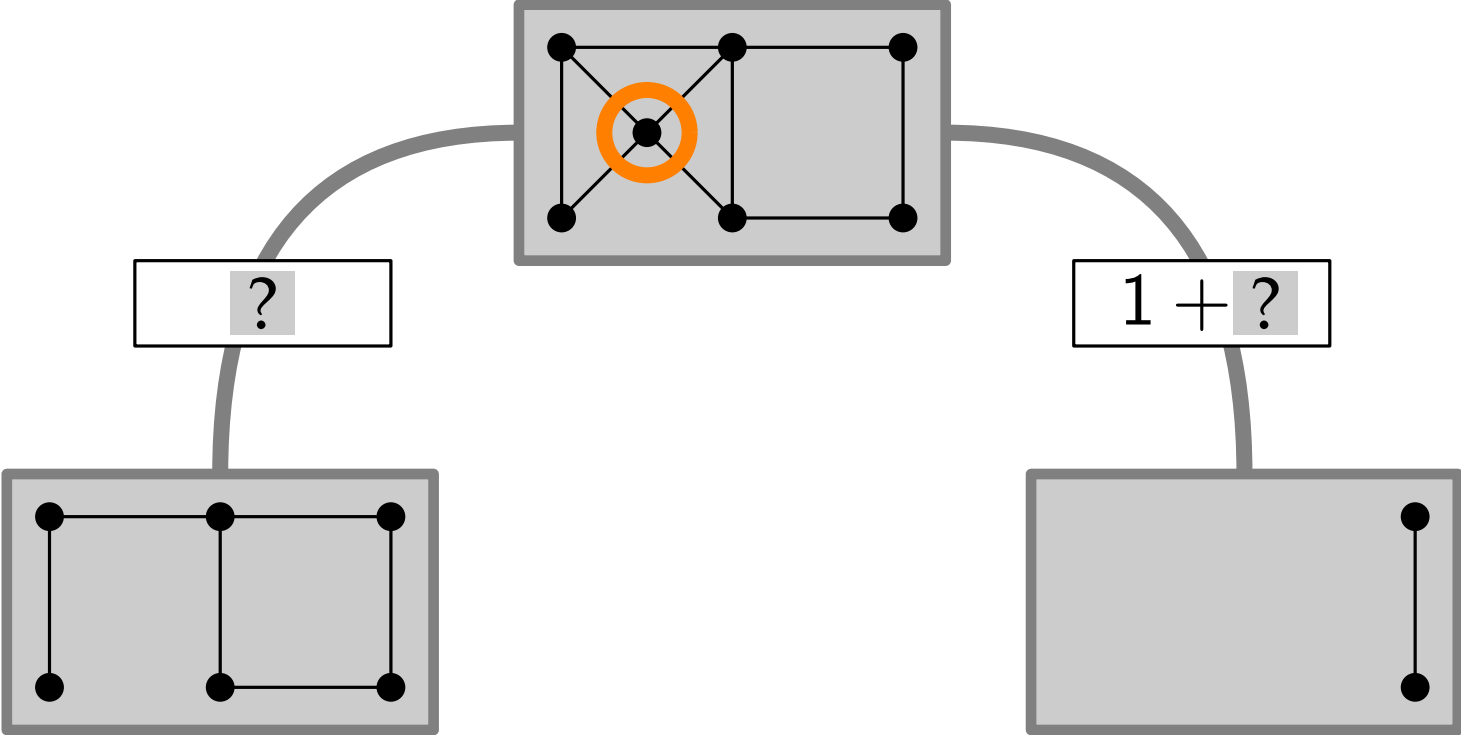
$v \leftarrow$ arbitrary vertex in $V(G)$

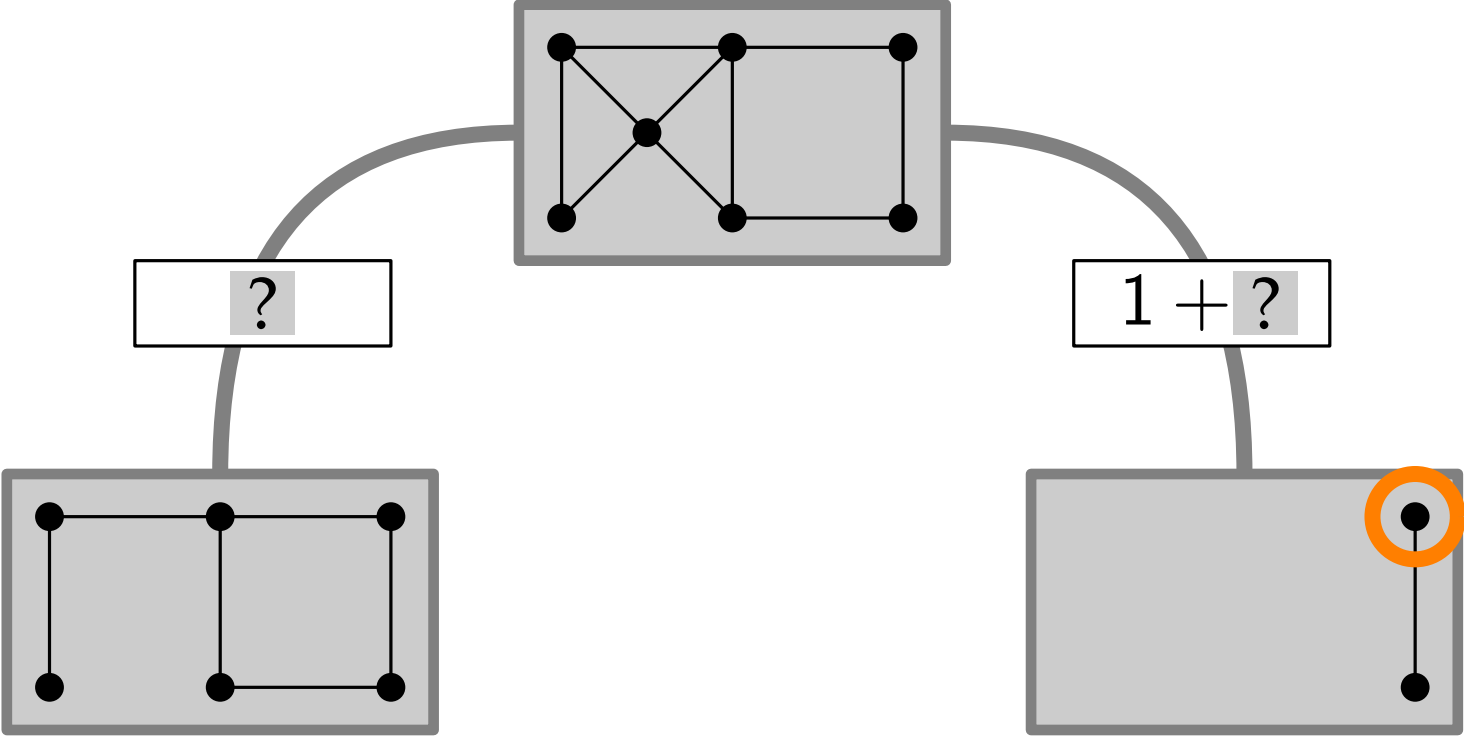
return $\max\{1 + \text{NaiveMIS}(G - N(v) - \{v\}),$
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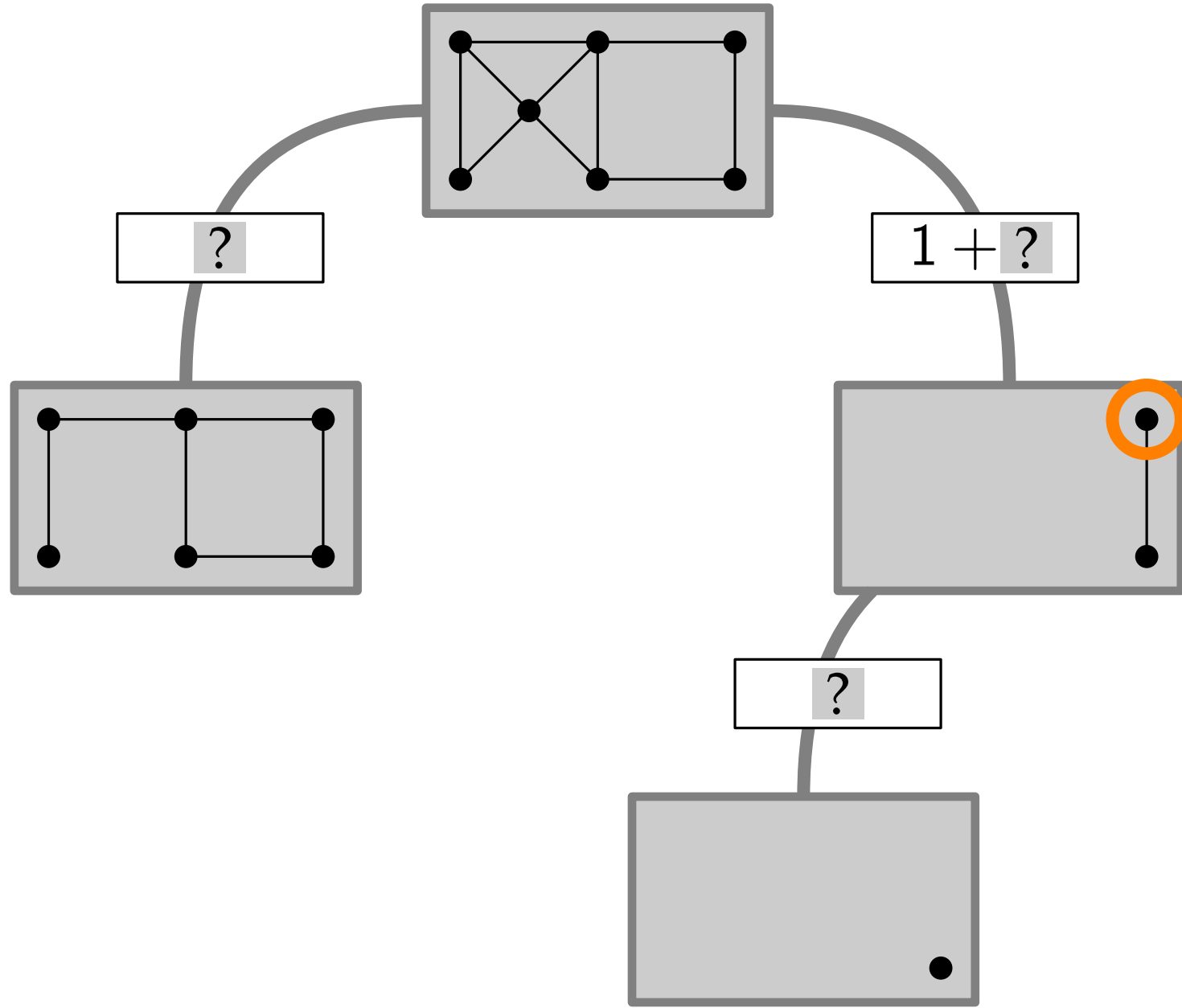


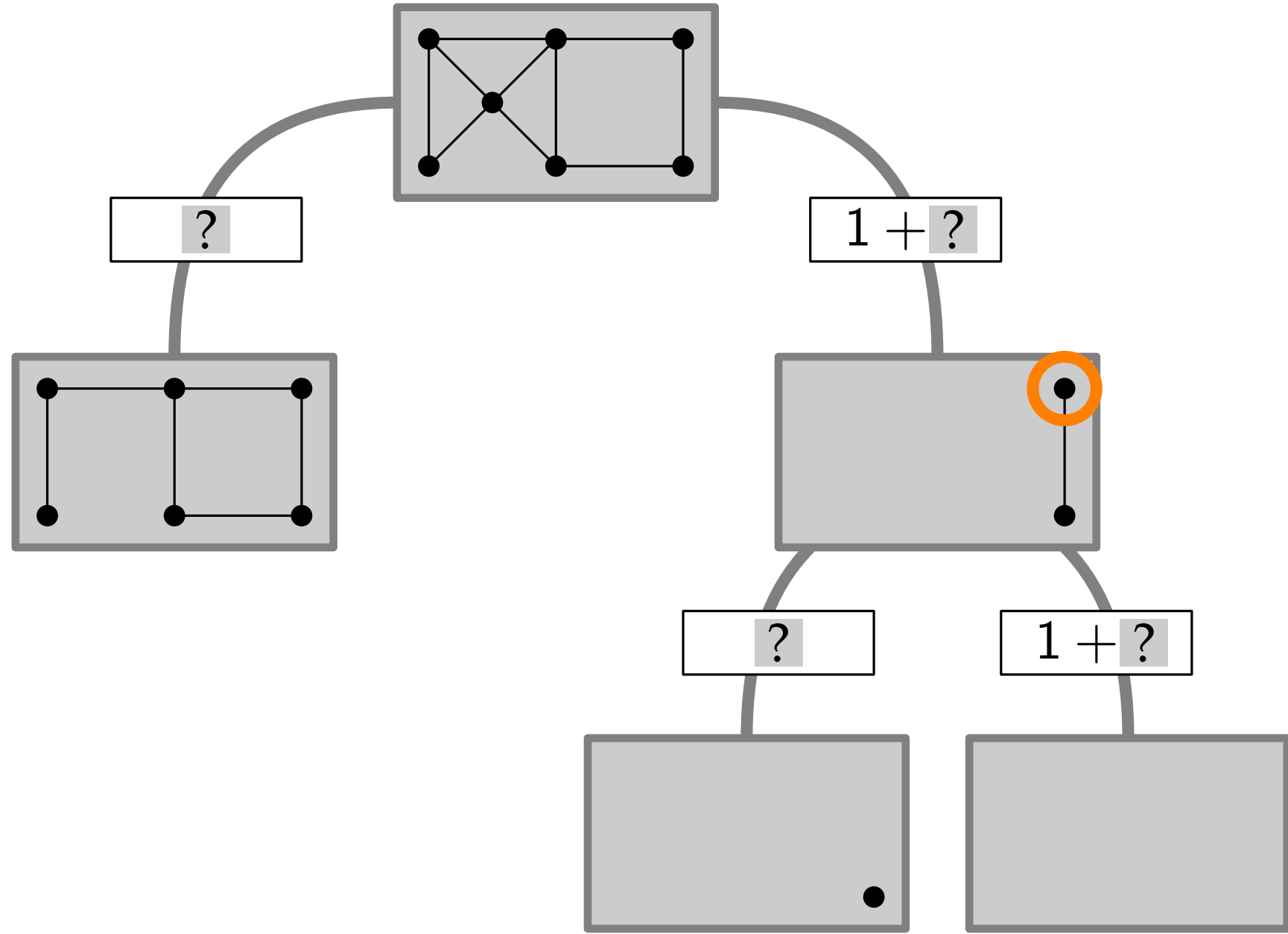


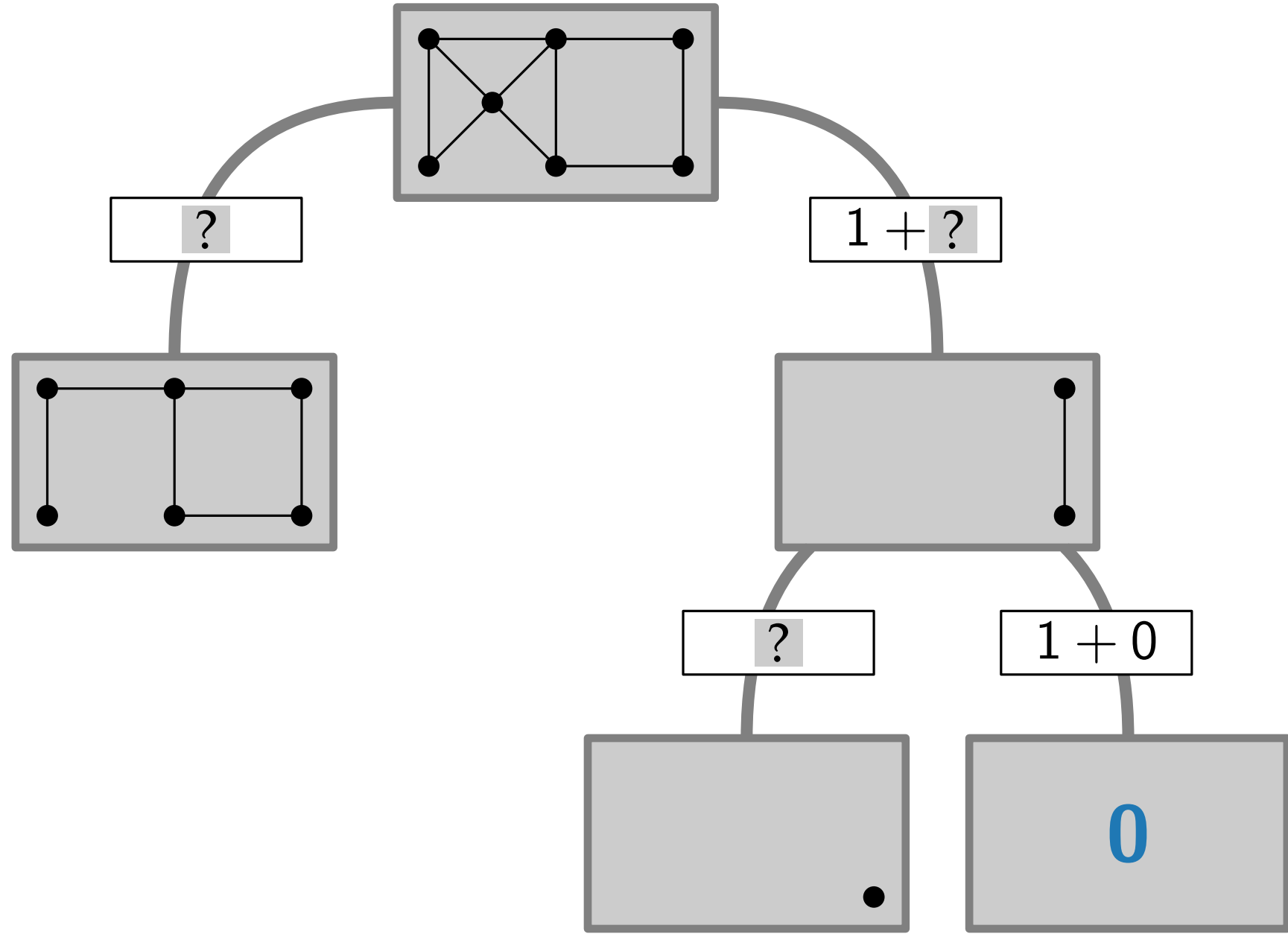


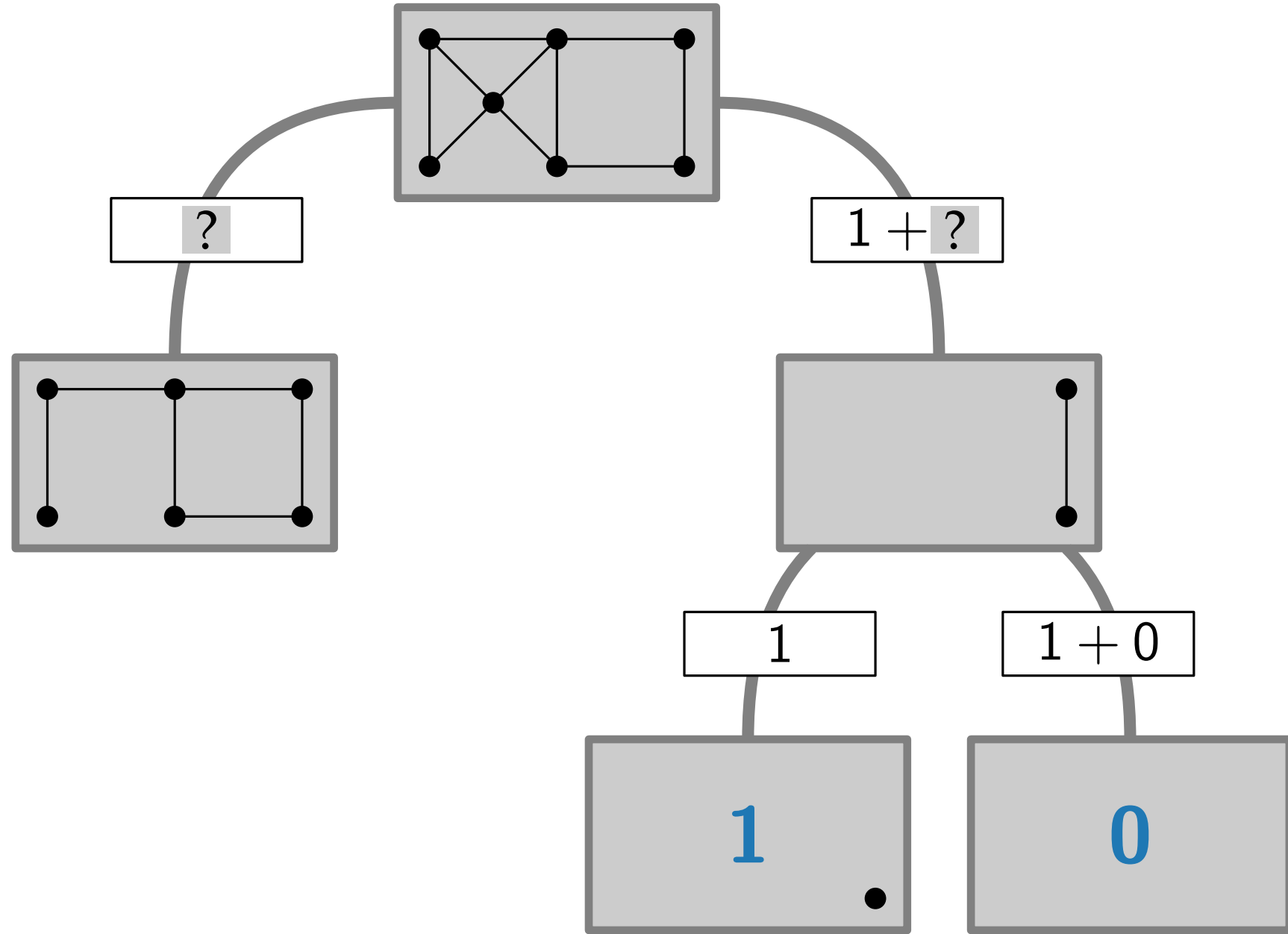


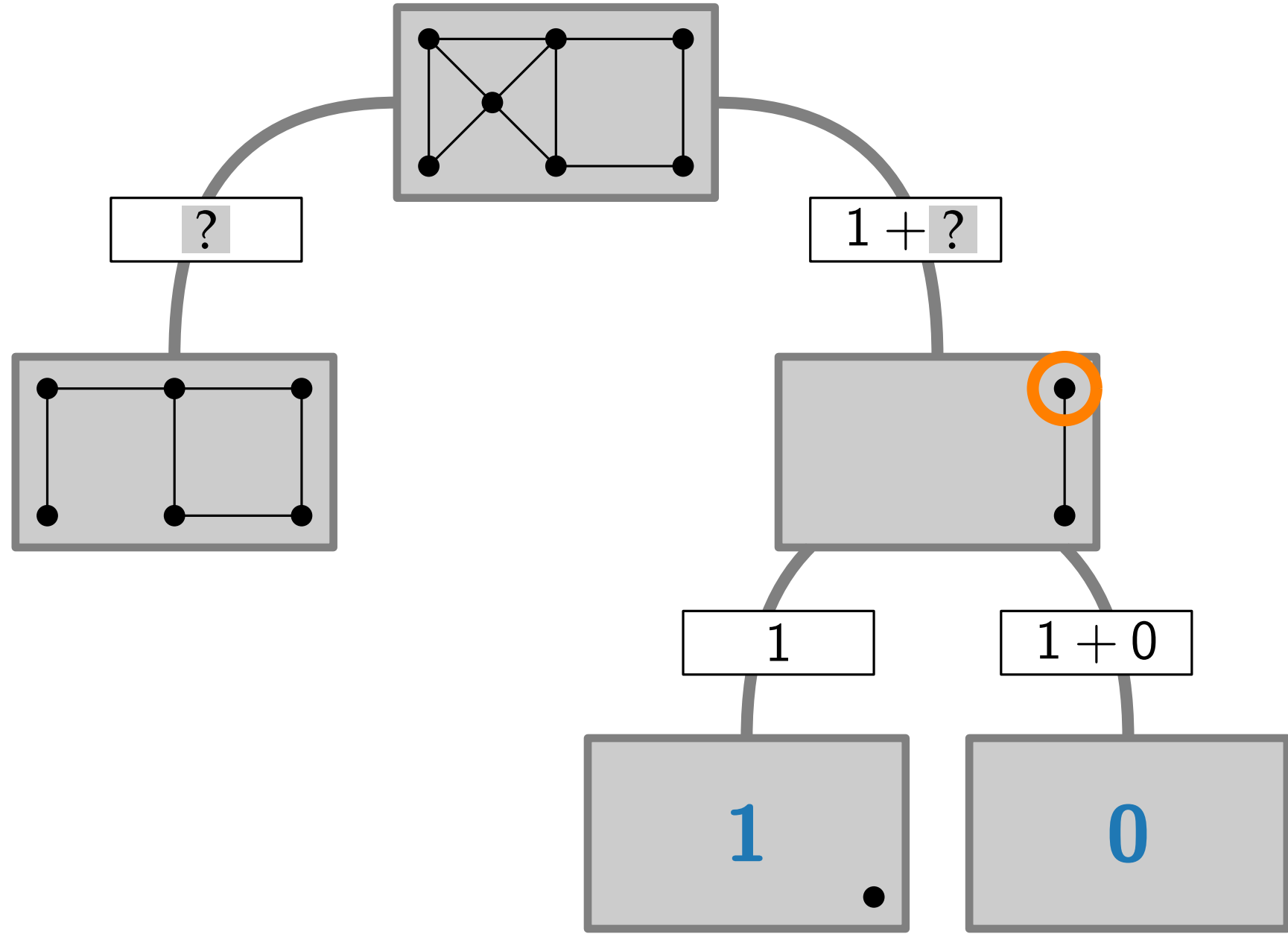


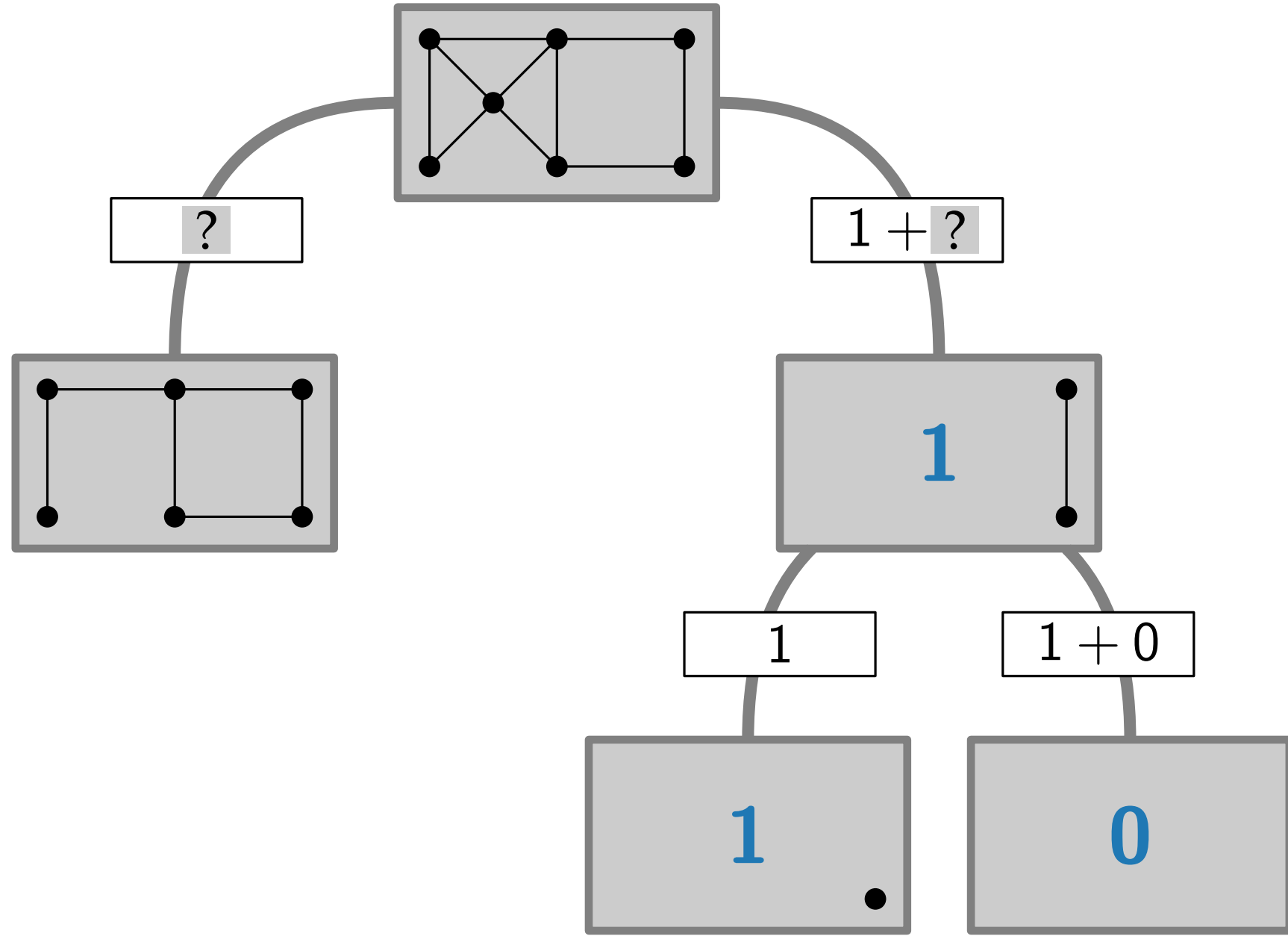


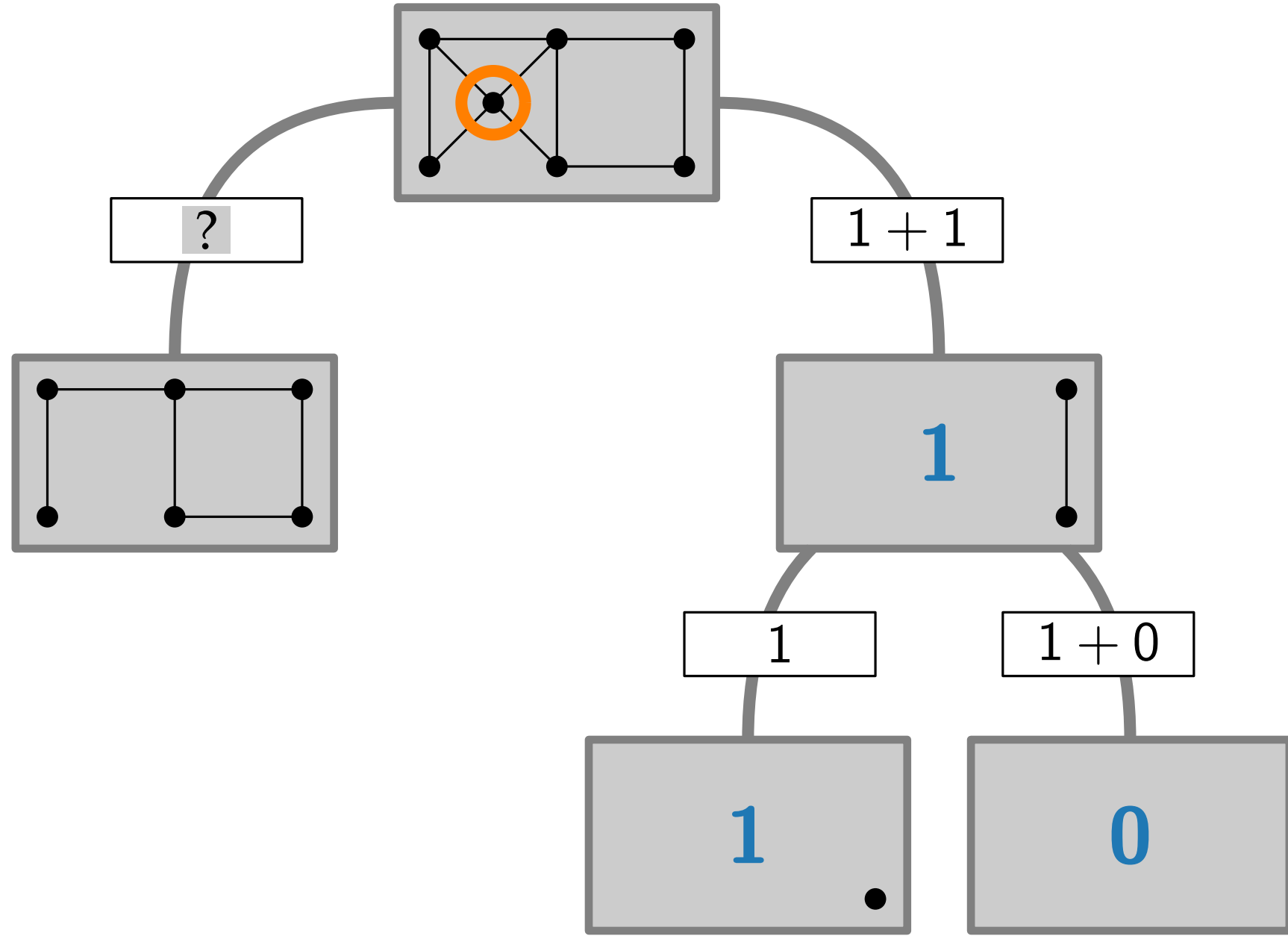


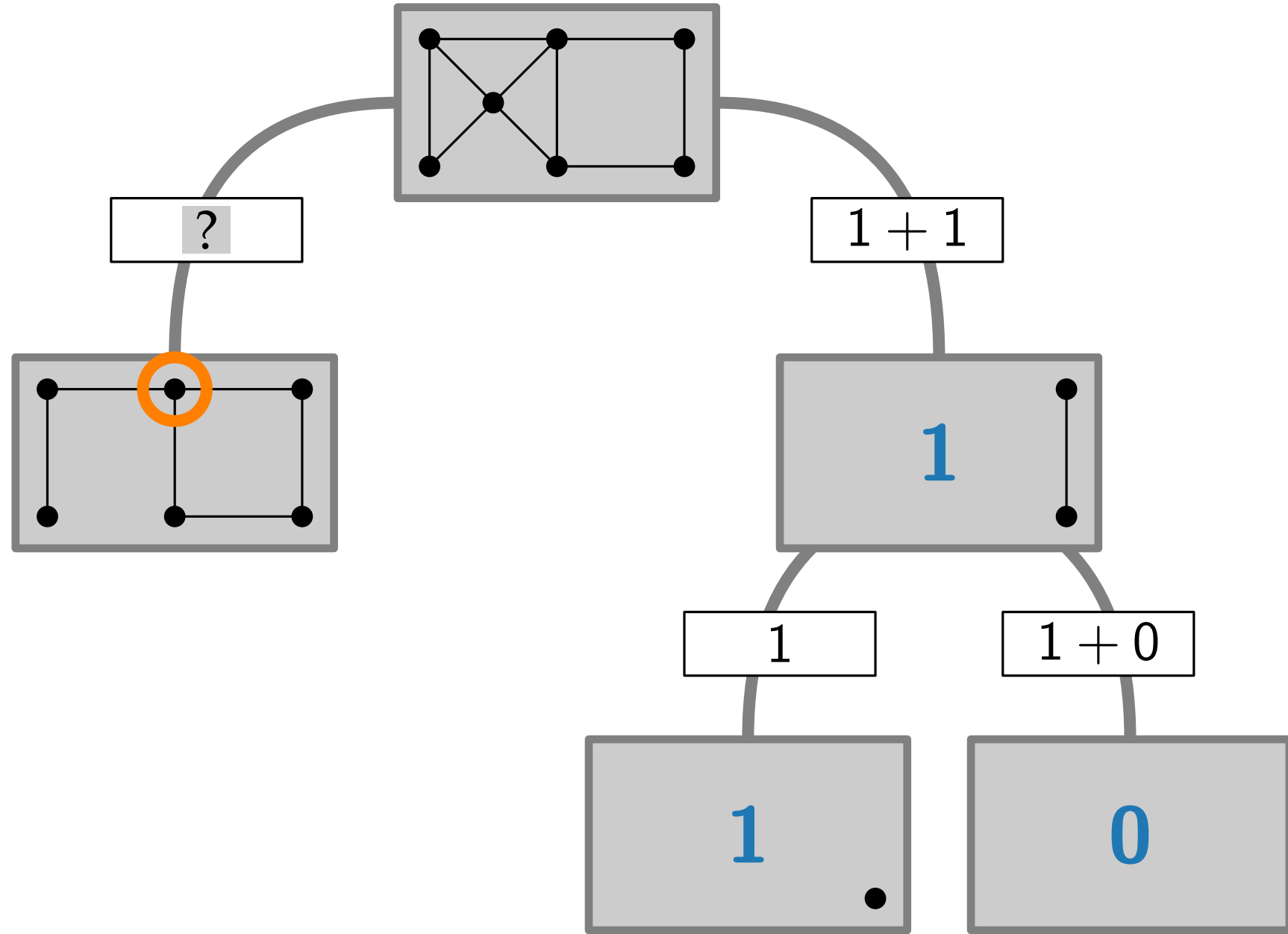


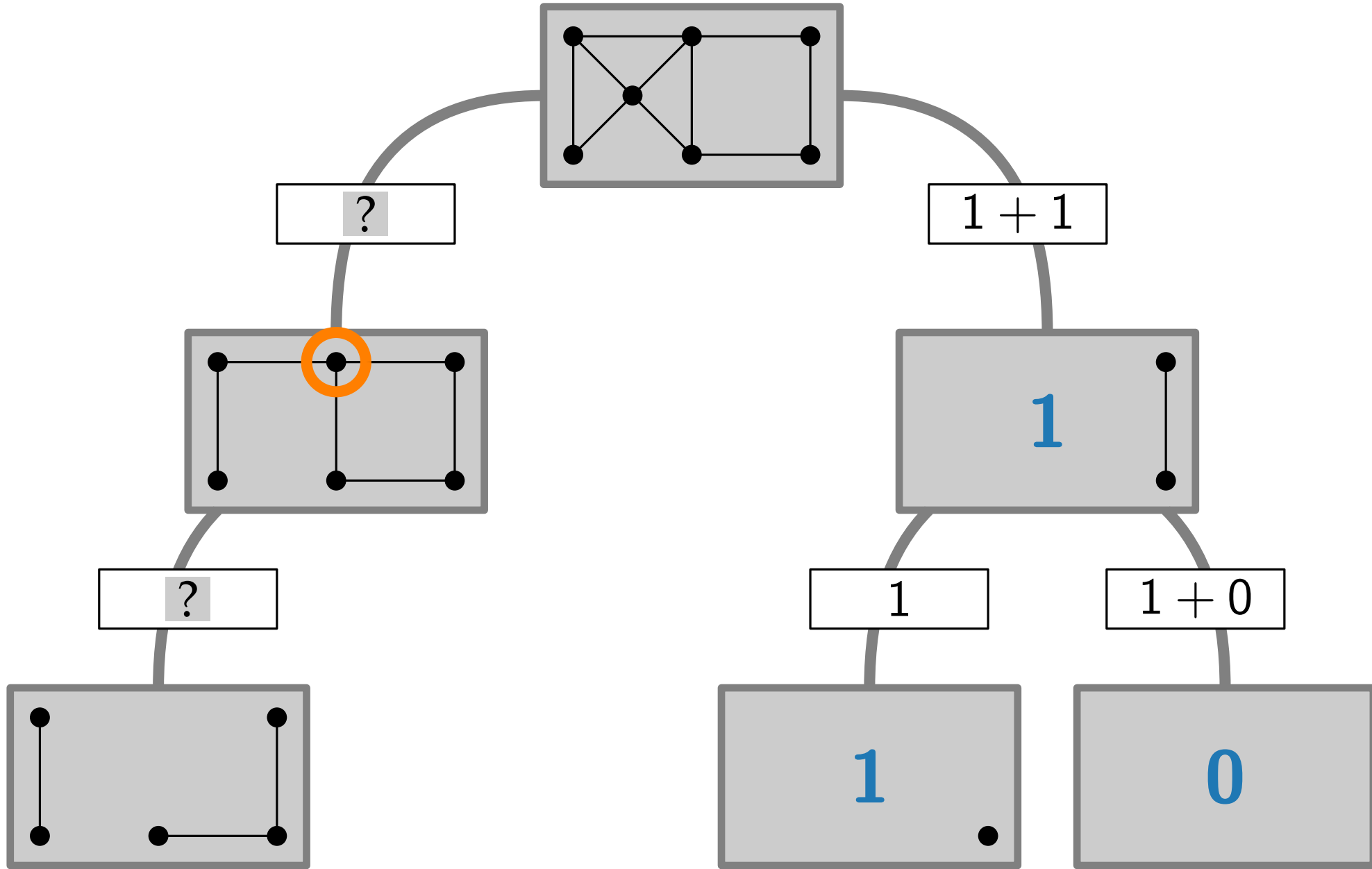


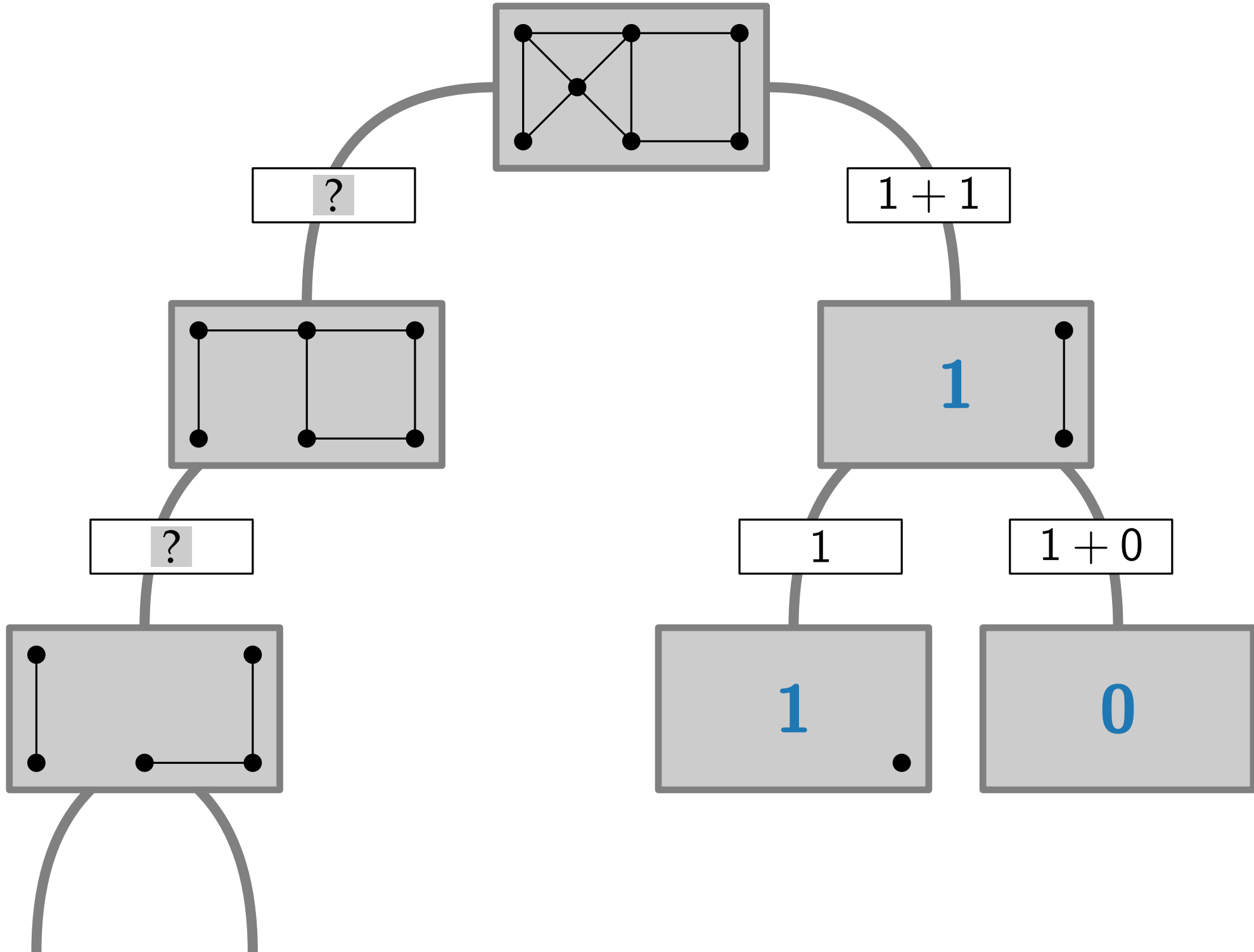


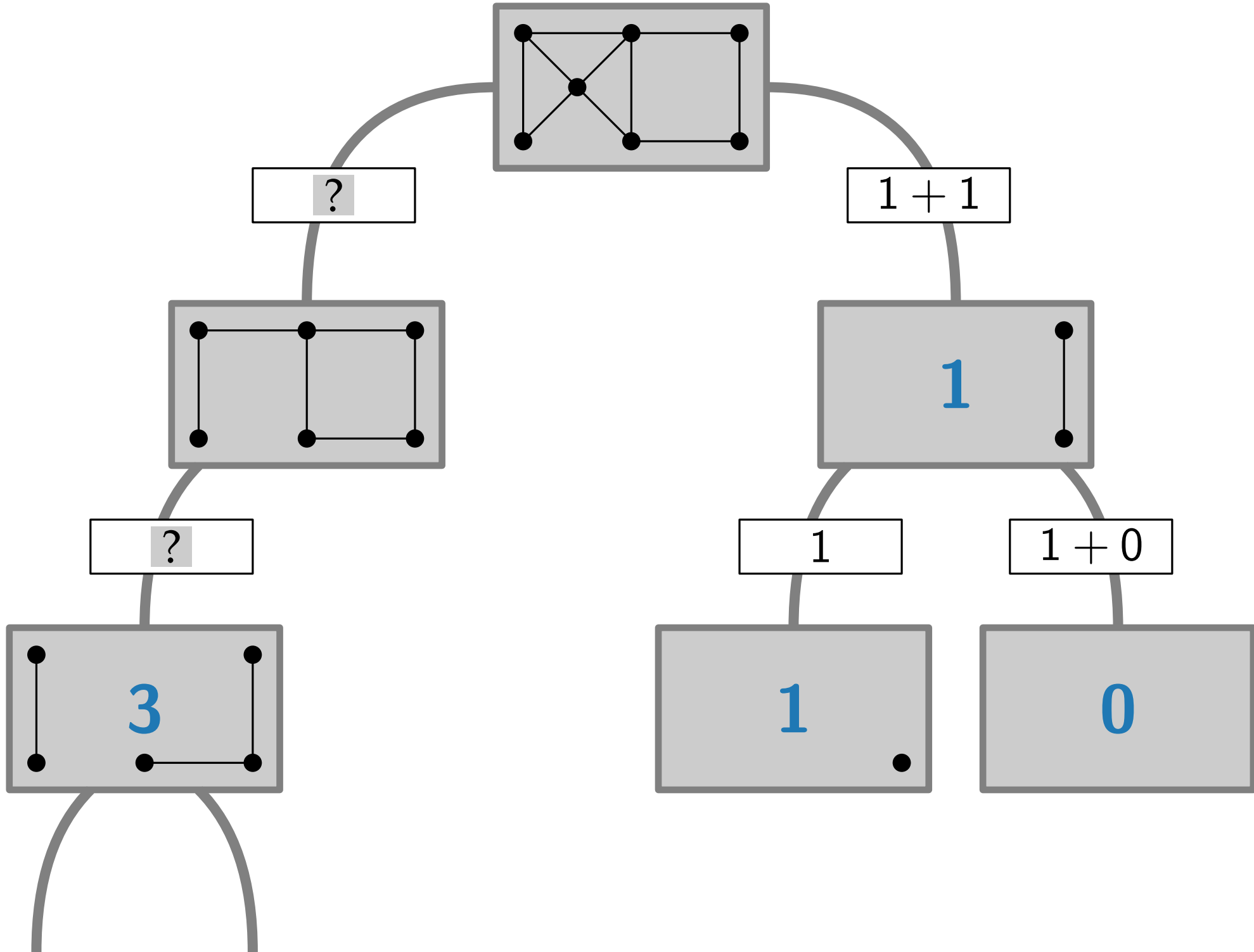


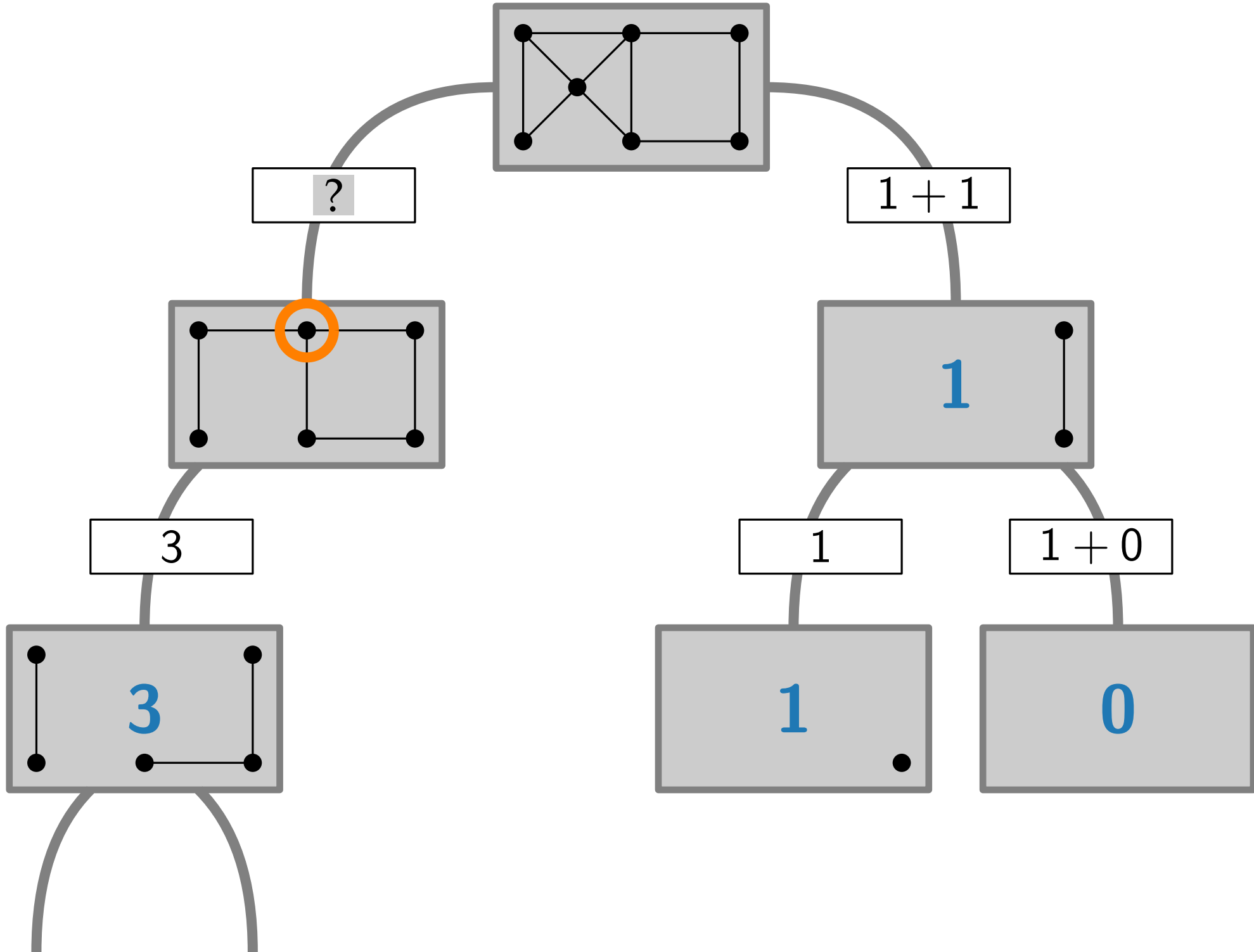


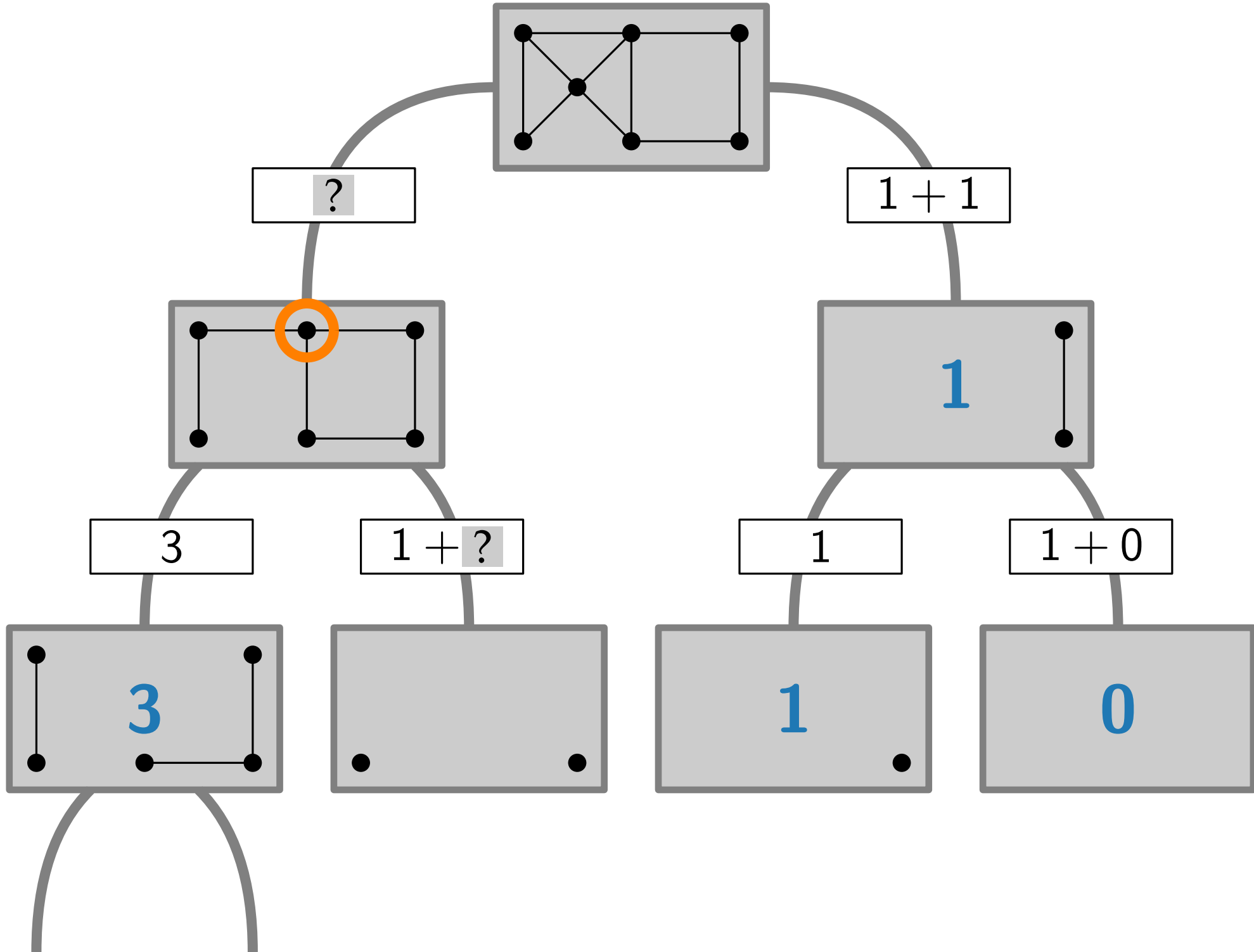


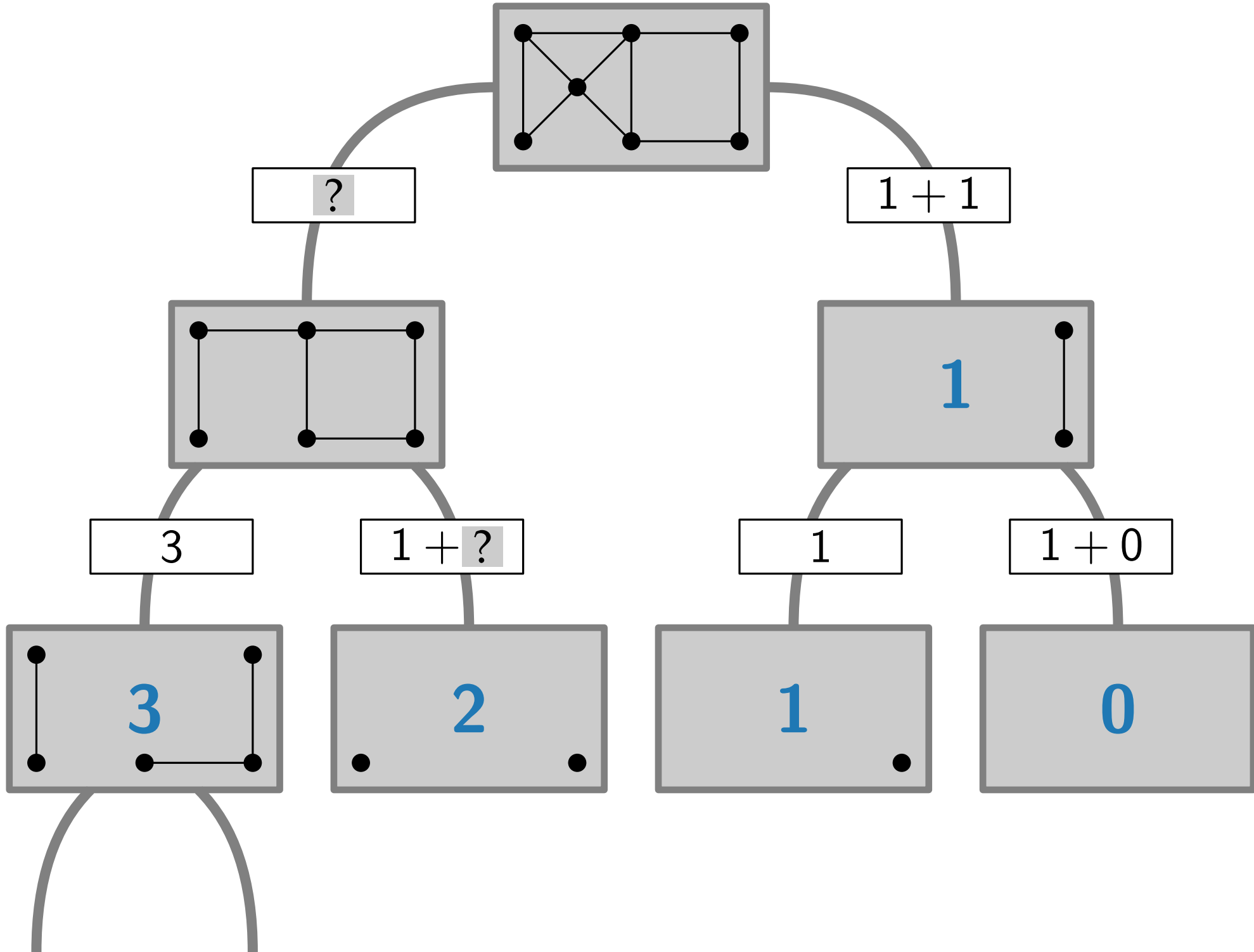


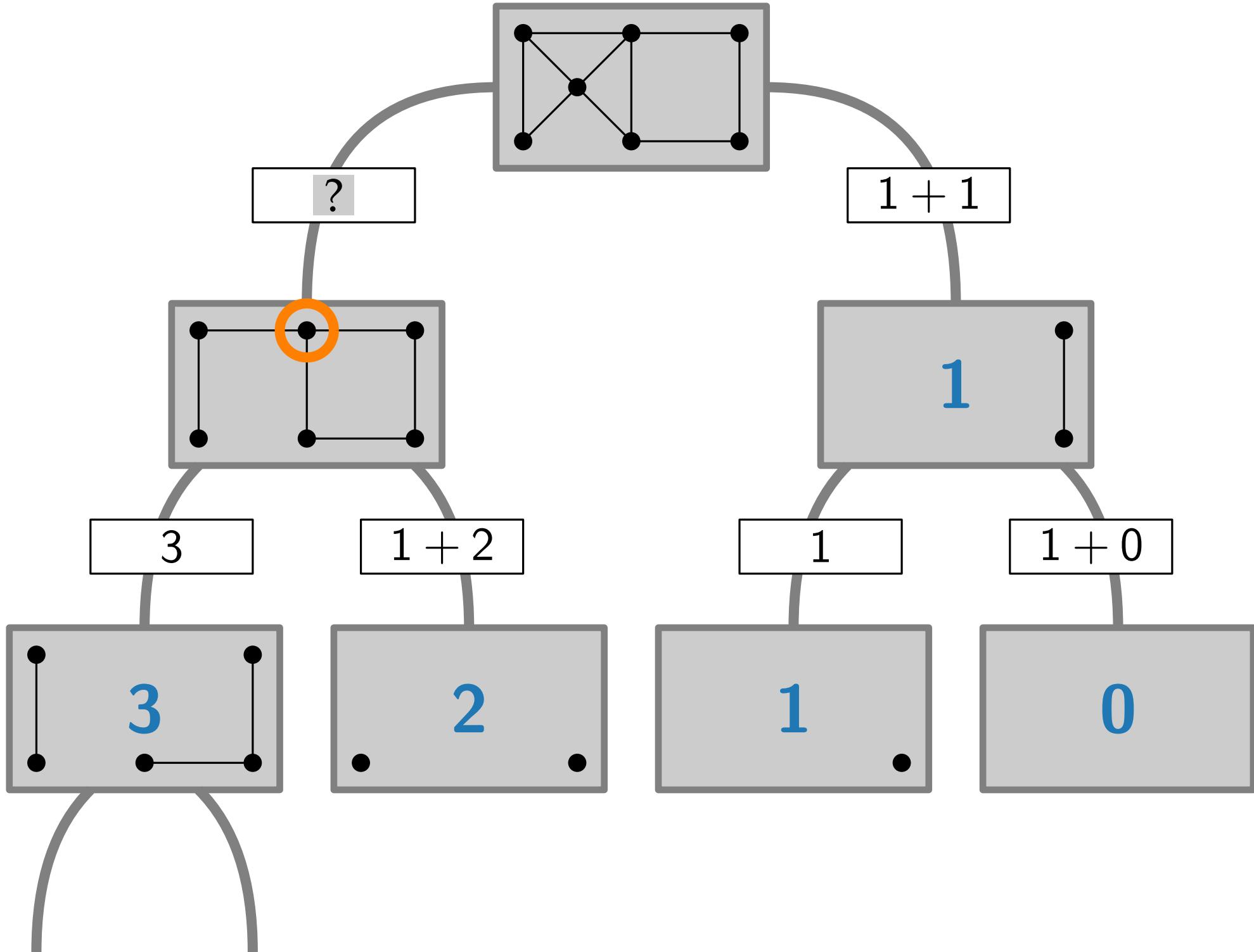


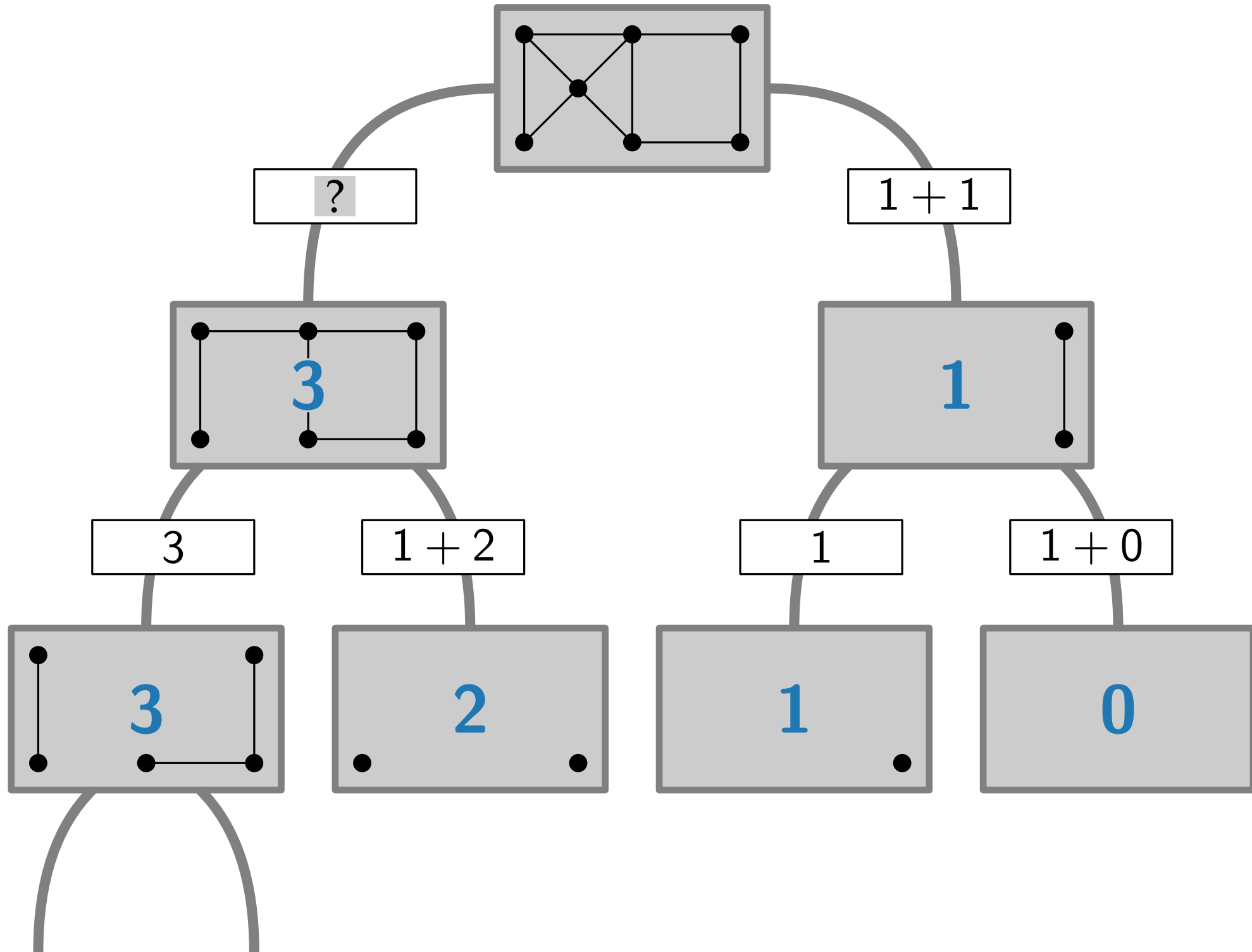


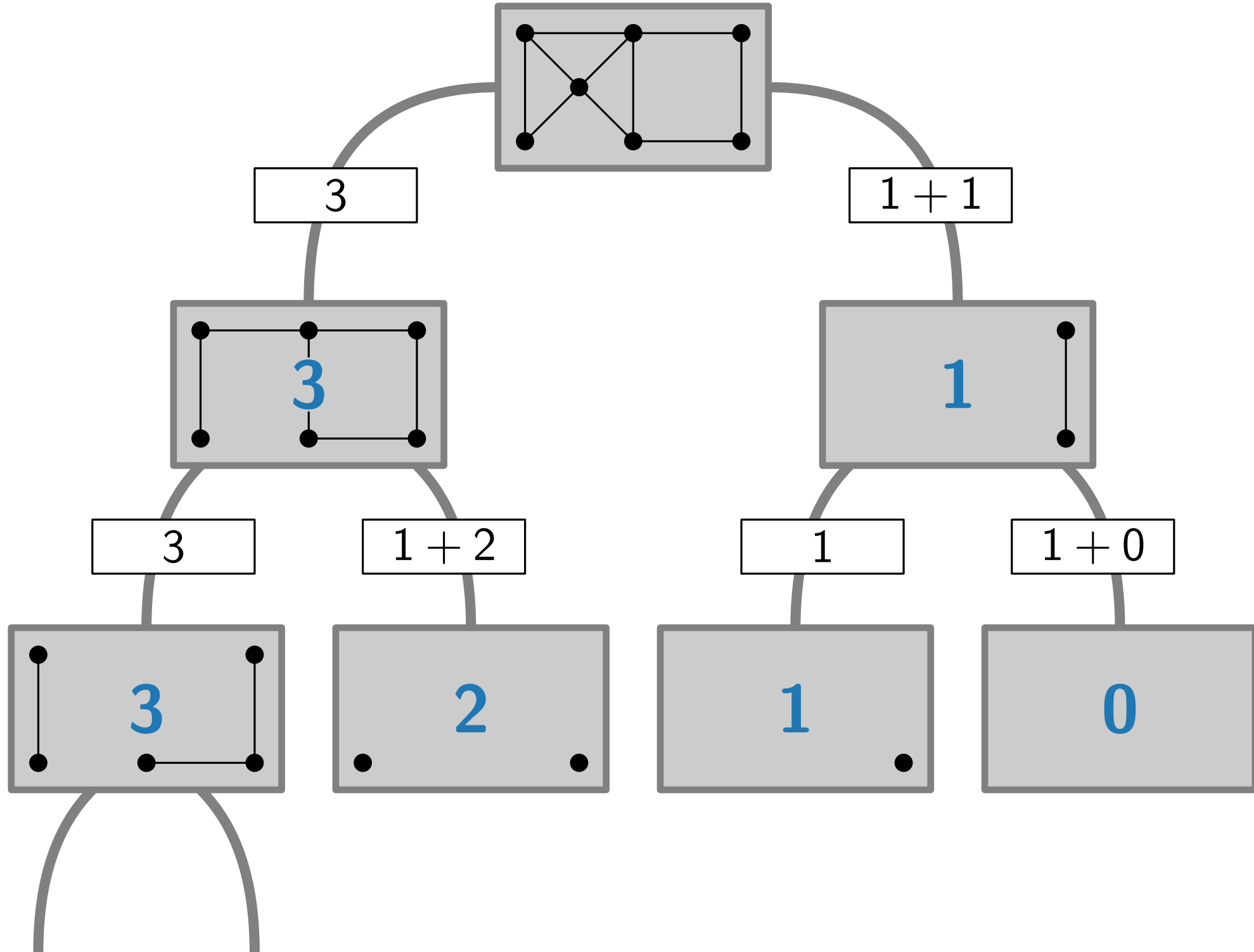


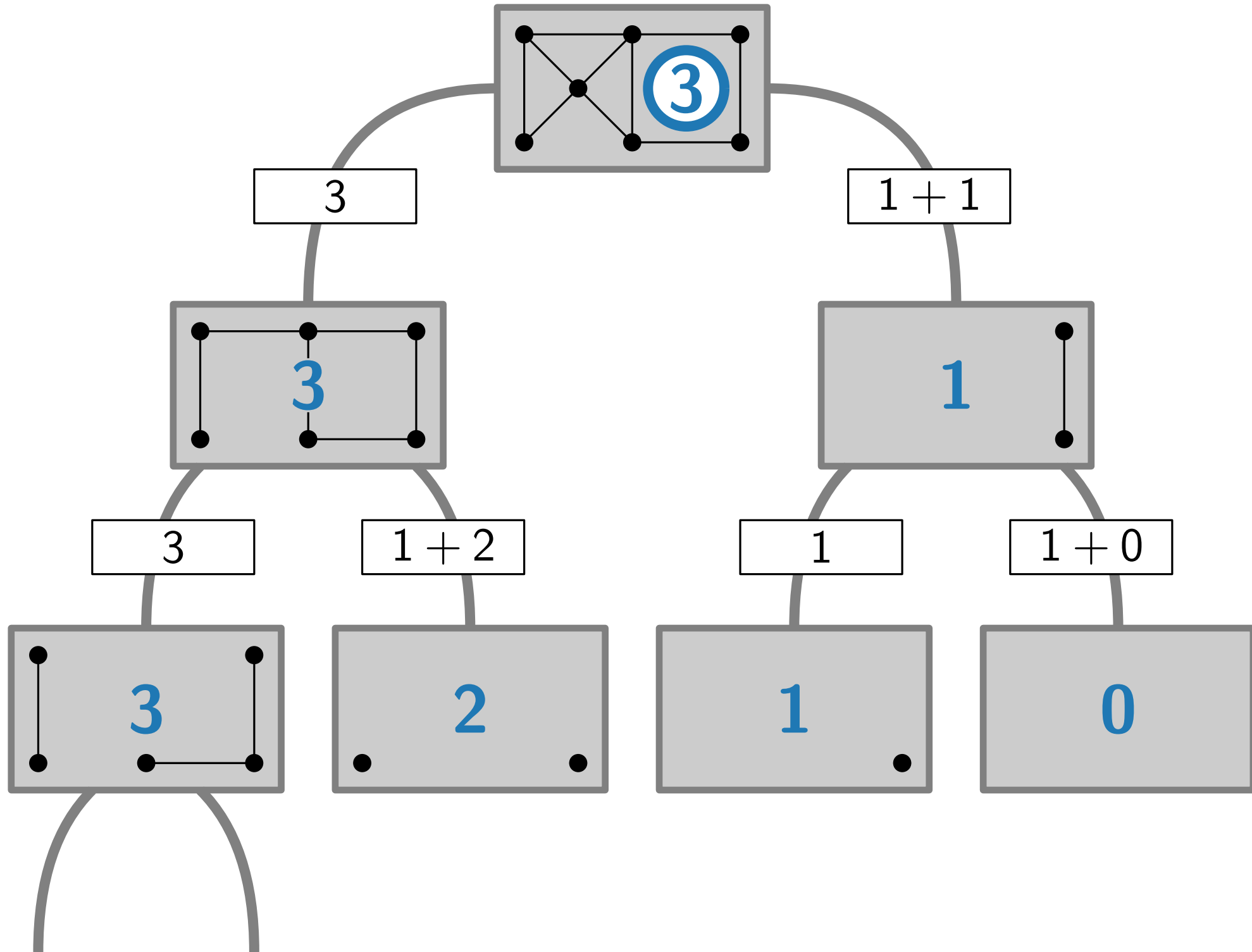












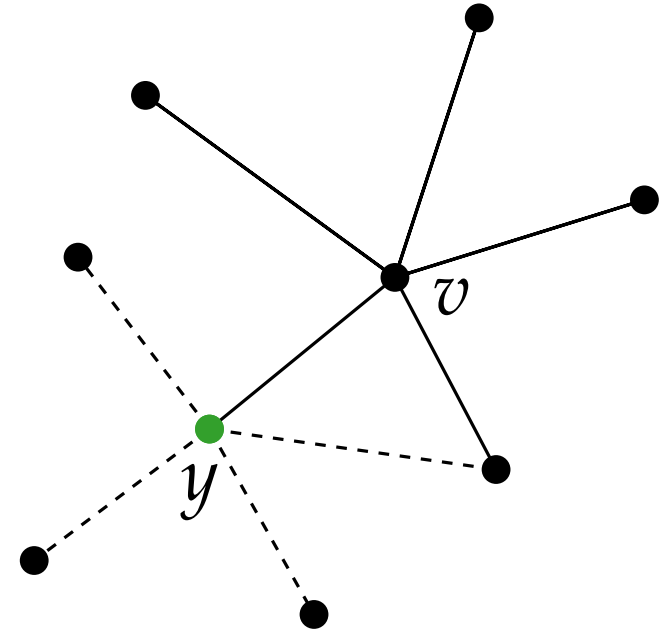
MIS – Smarter Branching

Lemma.

Let U be a maximum independent set in G . Then for each $v \in V$:

1. $v \in U \Rightarrow N(v) \cap U = \emptyset$
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Thus, $N[v] := N(v) \cup \{v\}$ contains some $y \in U$ and no other vertex of $N[y]$ is in U .



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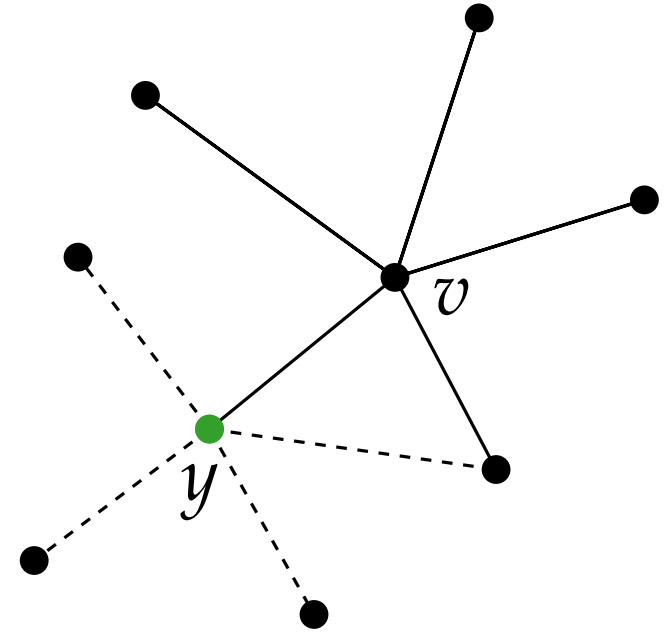
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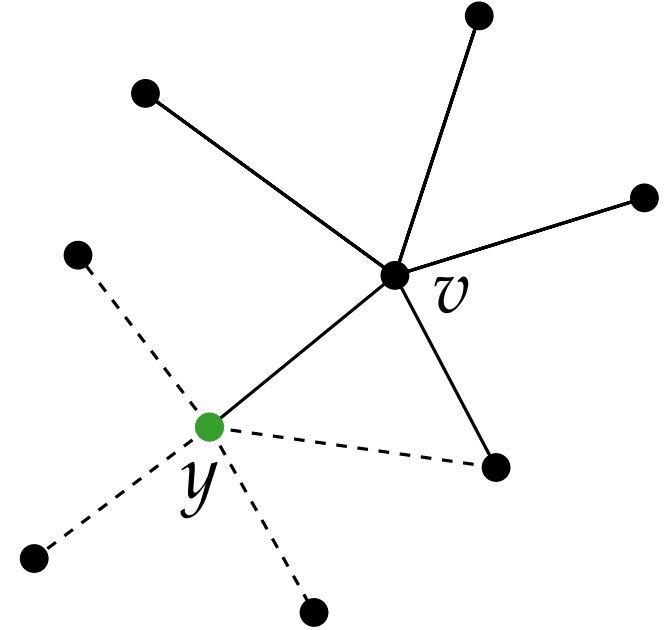
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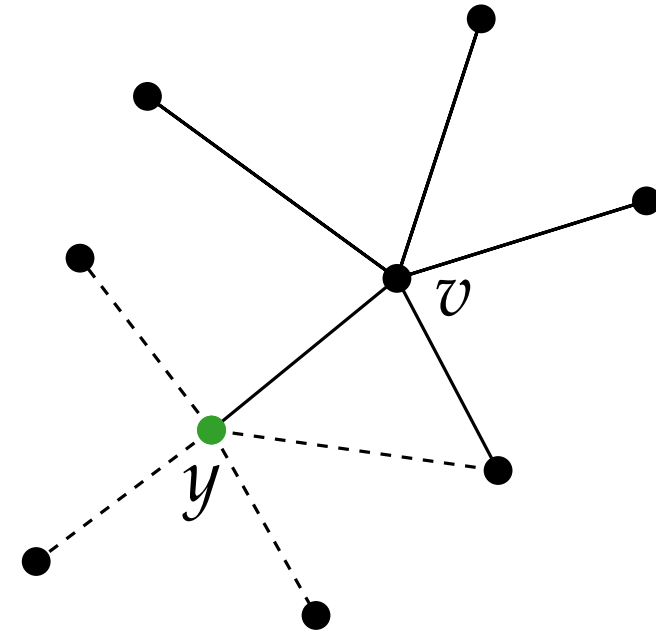
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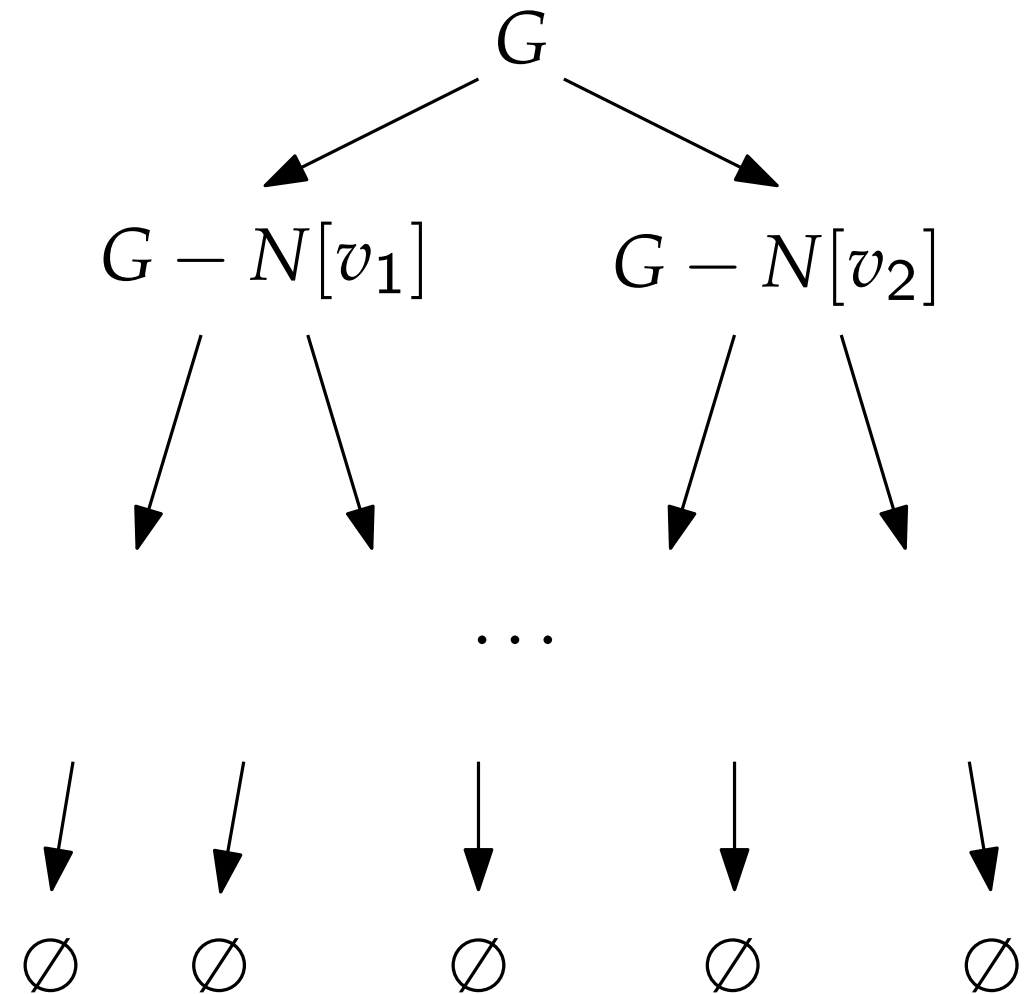
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- Correctness follows from Lemma.
- We prove a runtime of $\mathcal{O}^*(3^{n/3}) = \mathcal{O}^*(1.4423^n)$.

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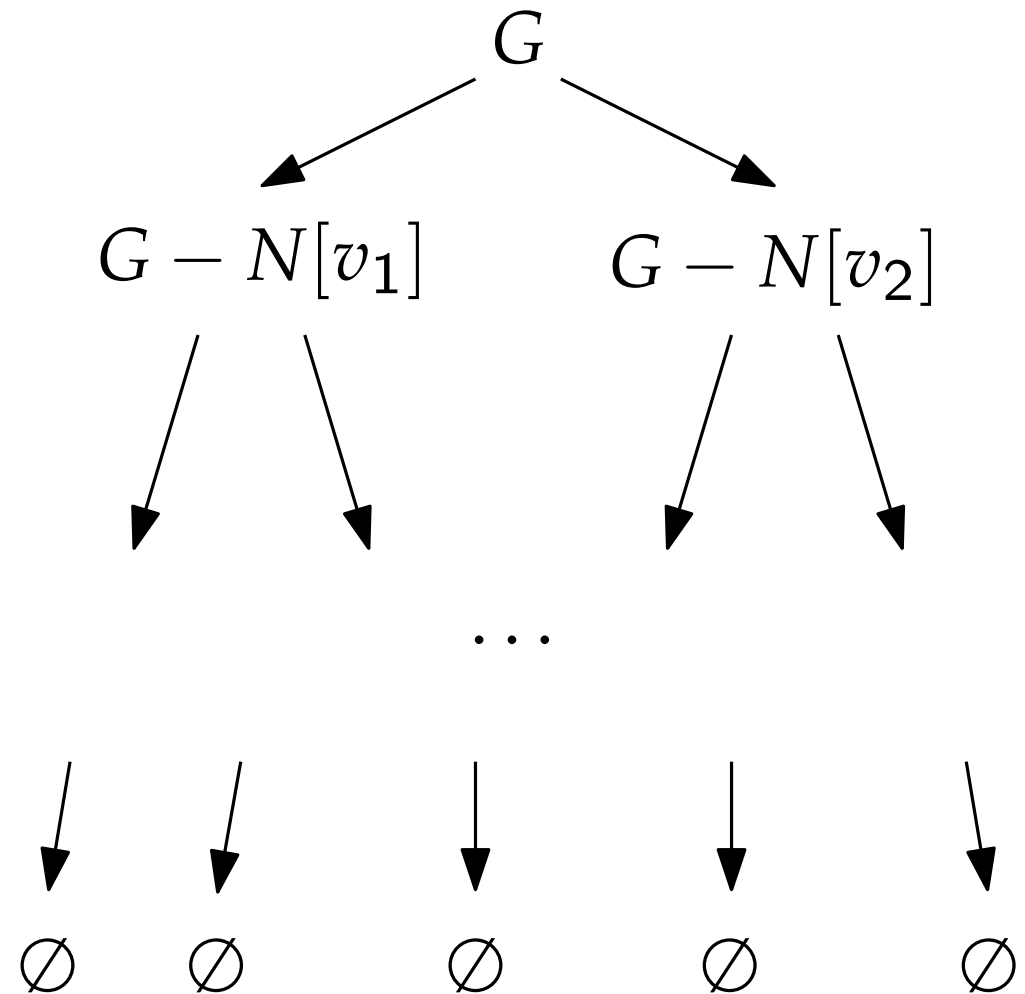
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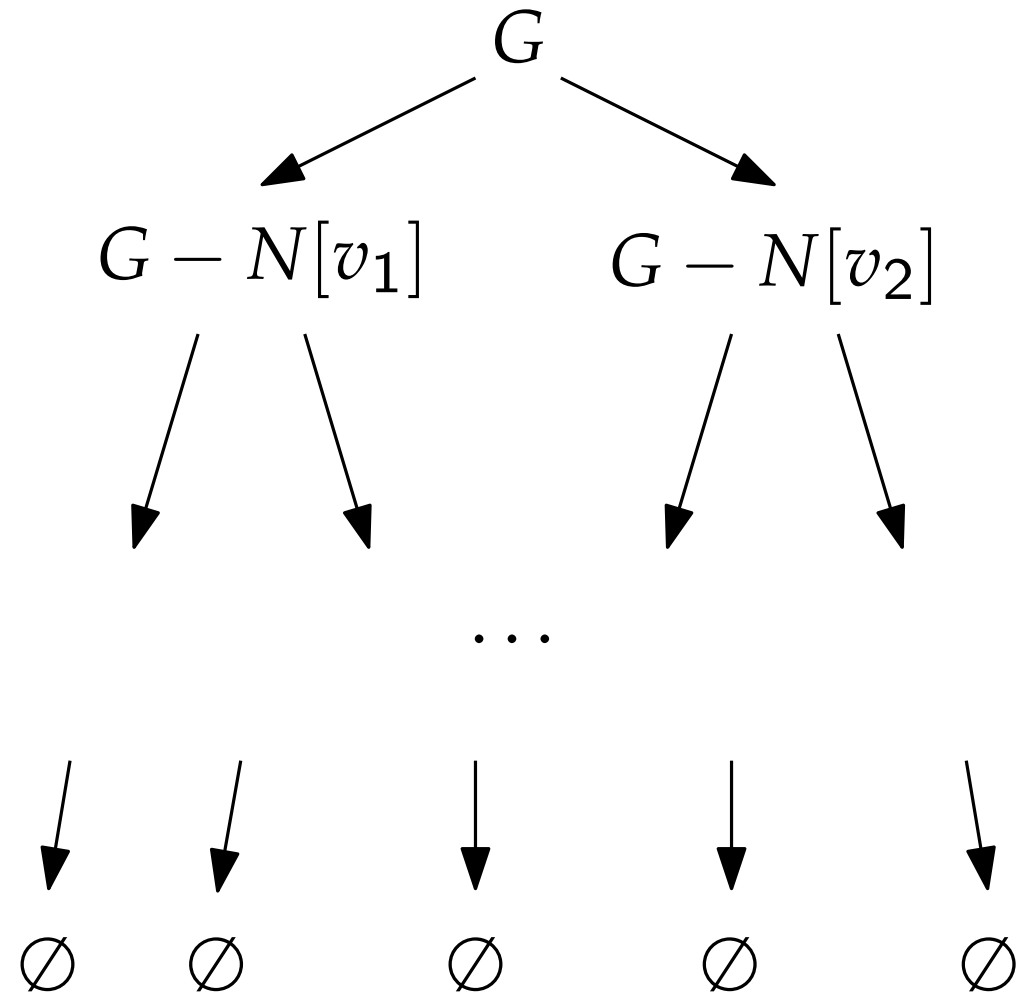
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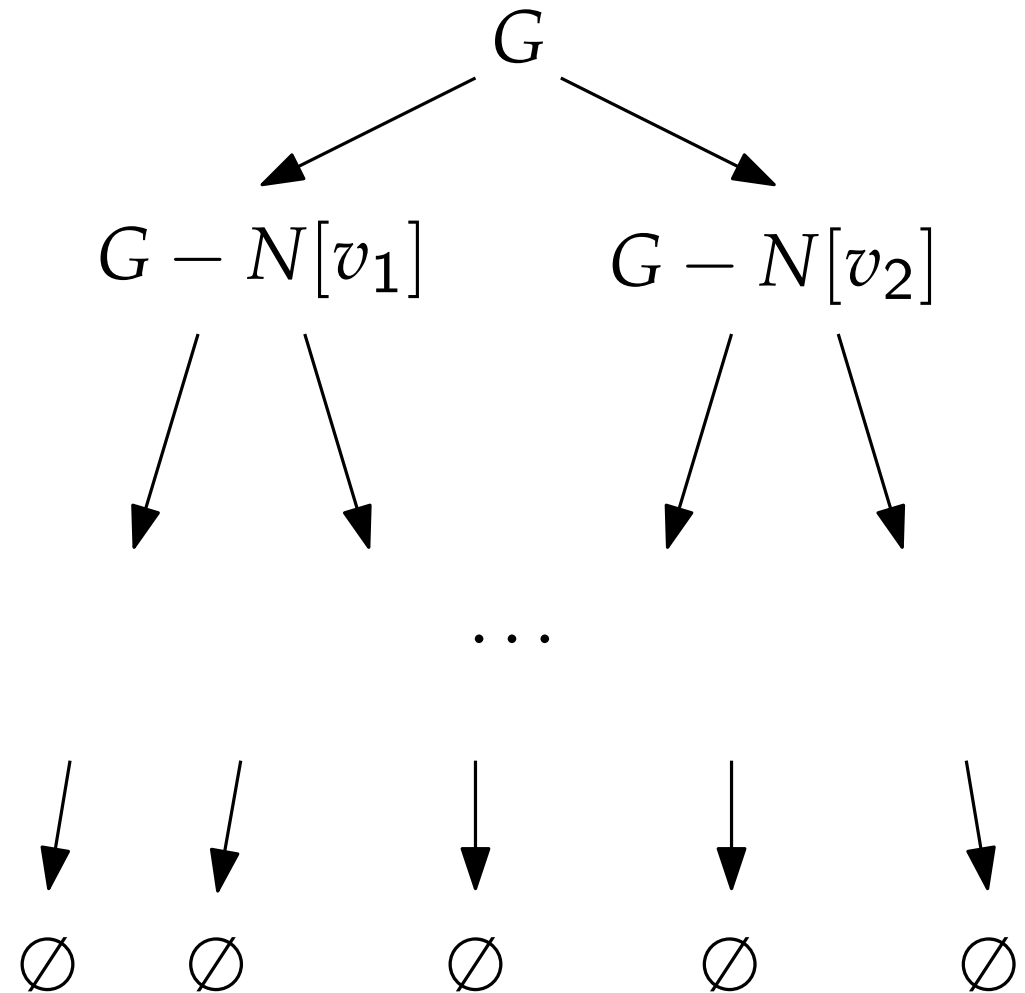
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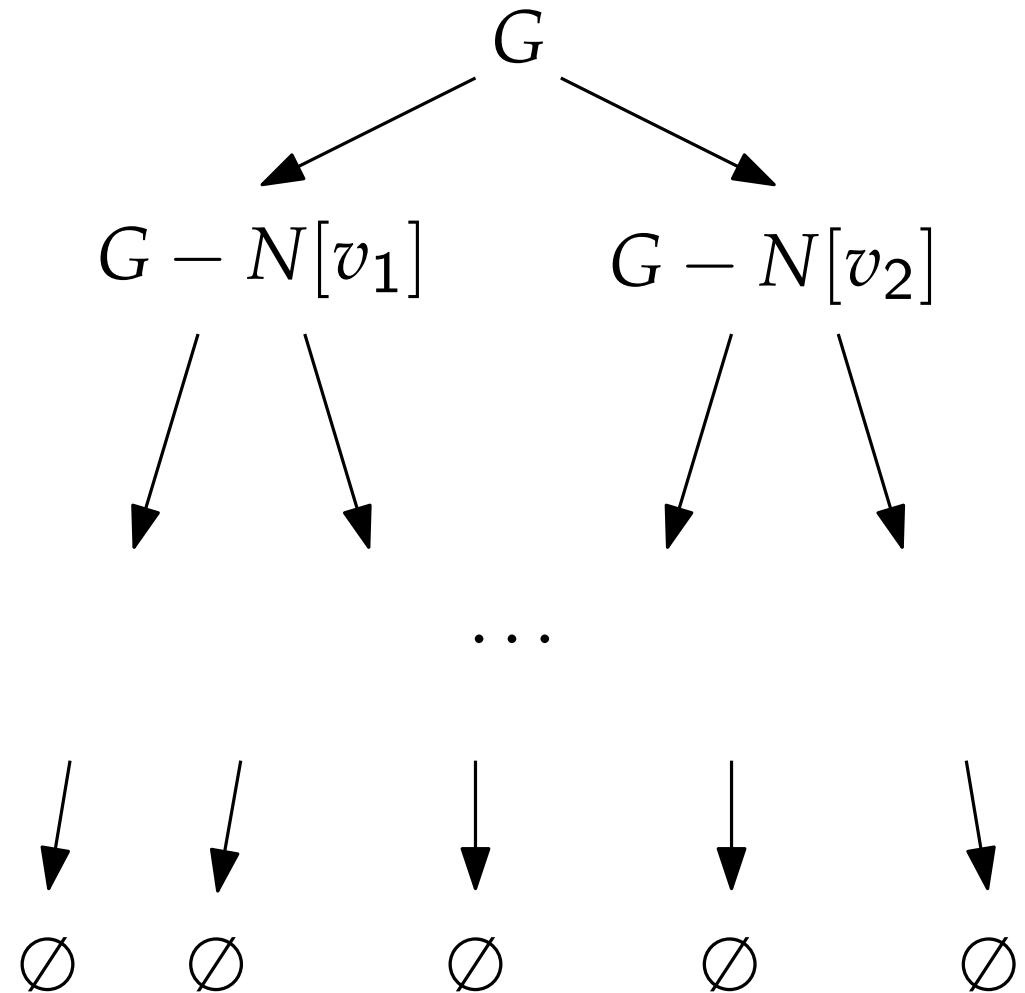
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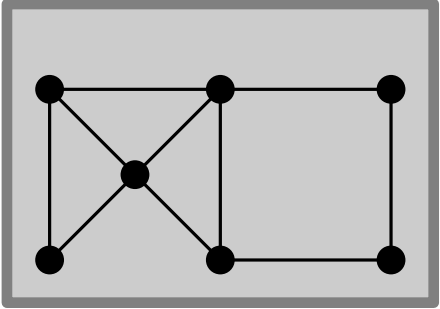
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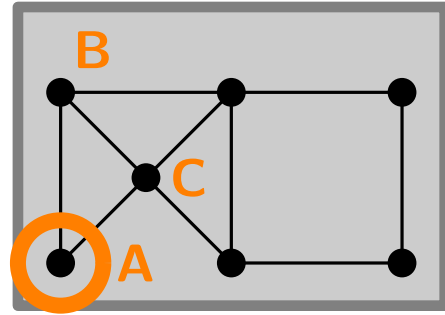
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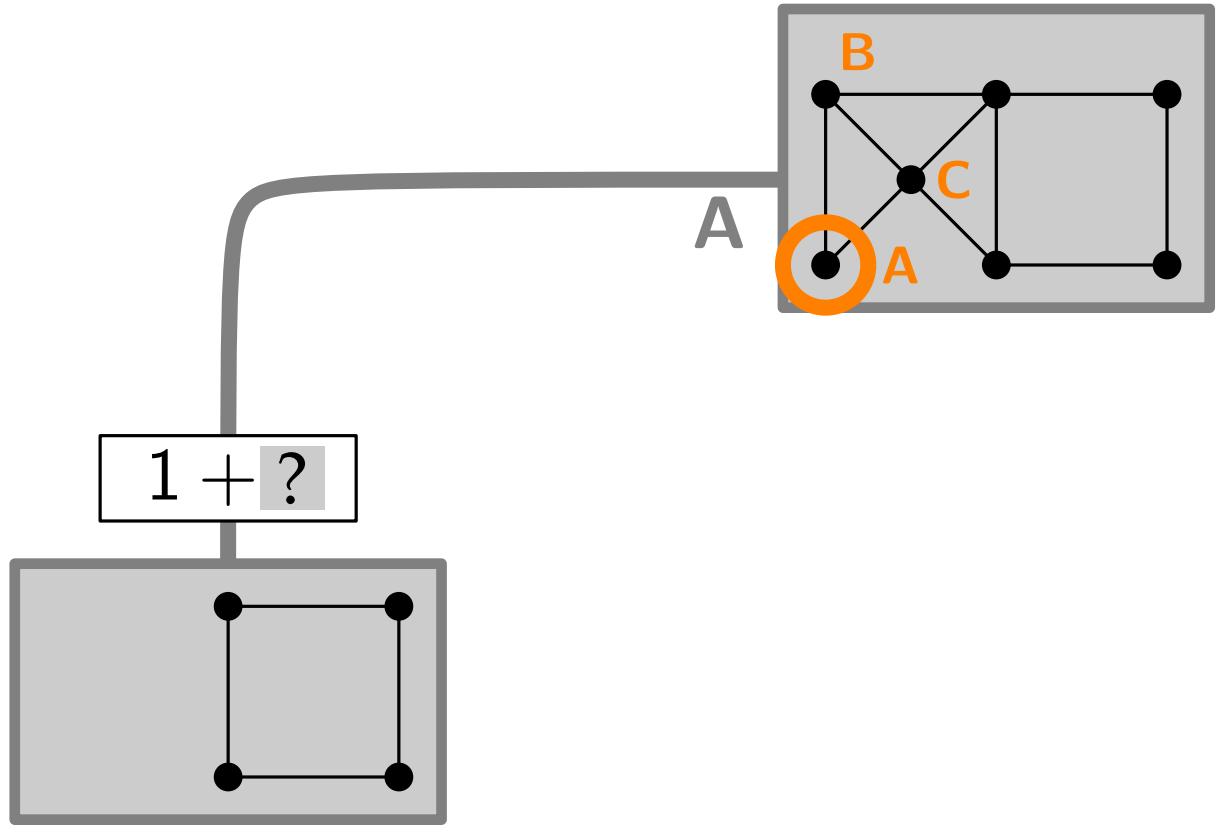
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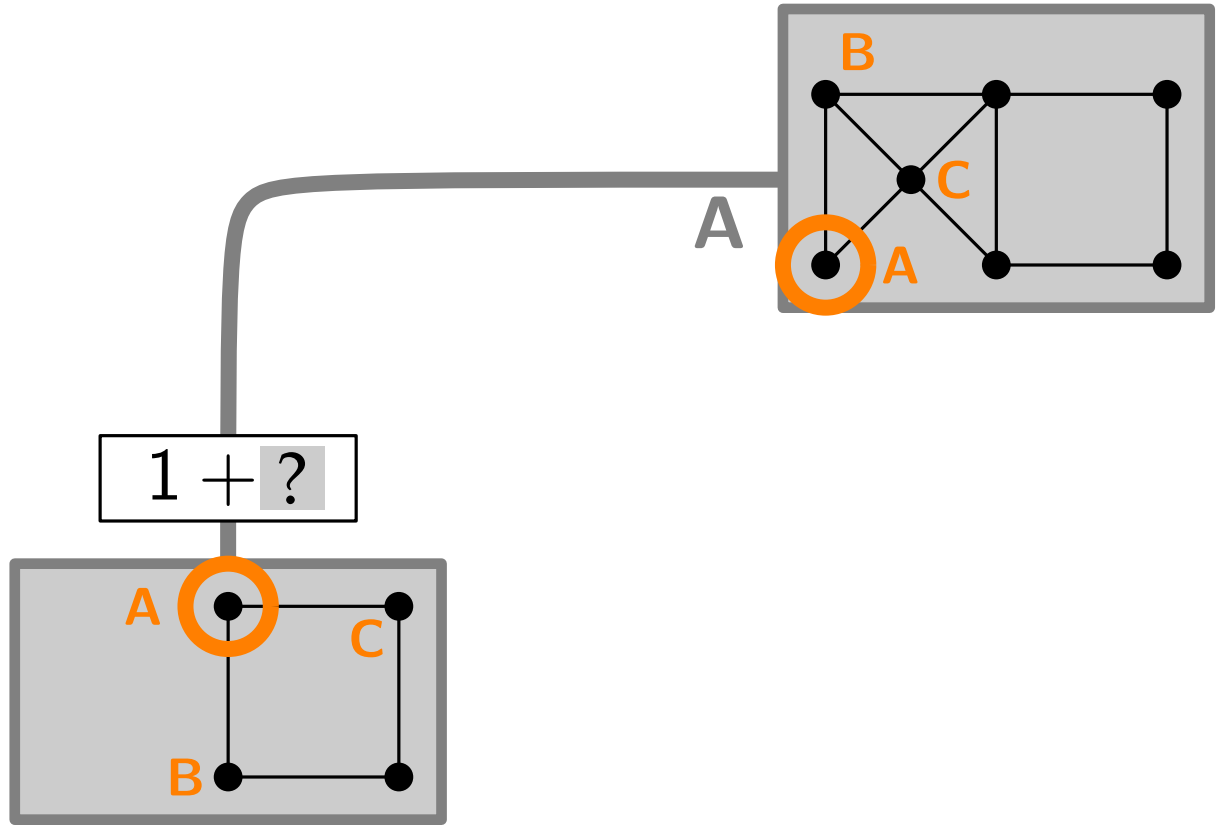
- Let's consider an example run.

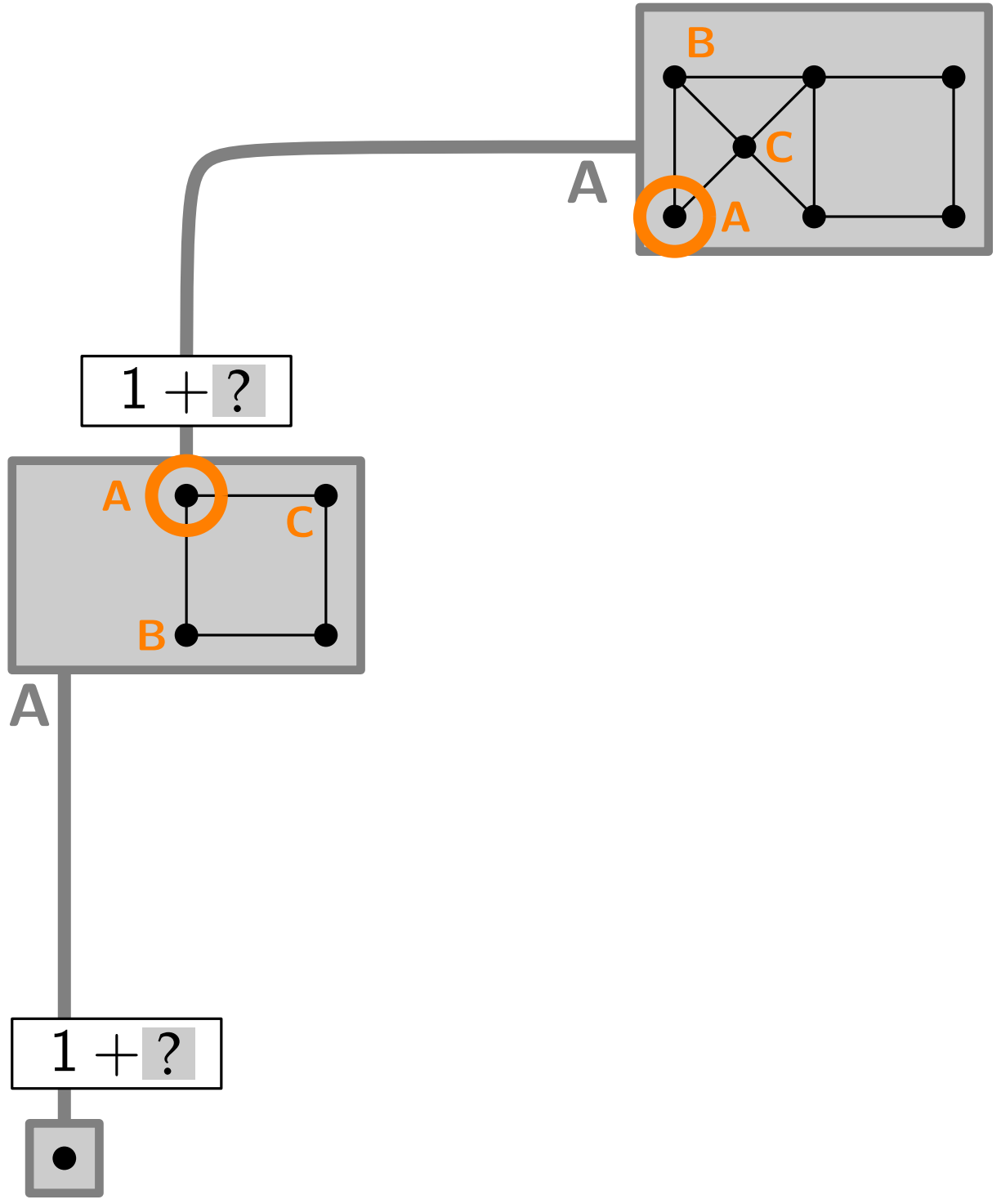


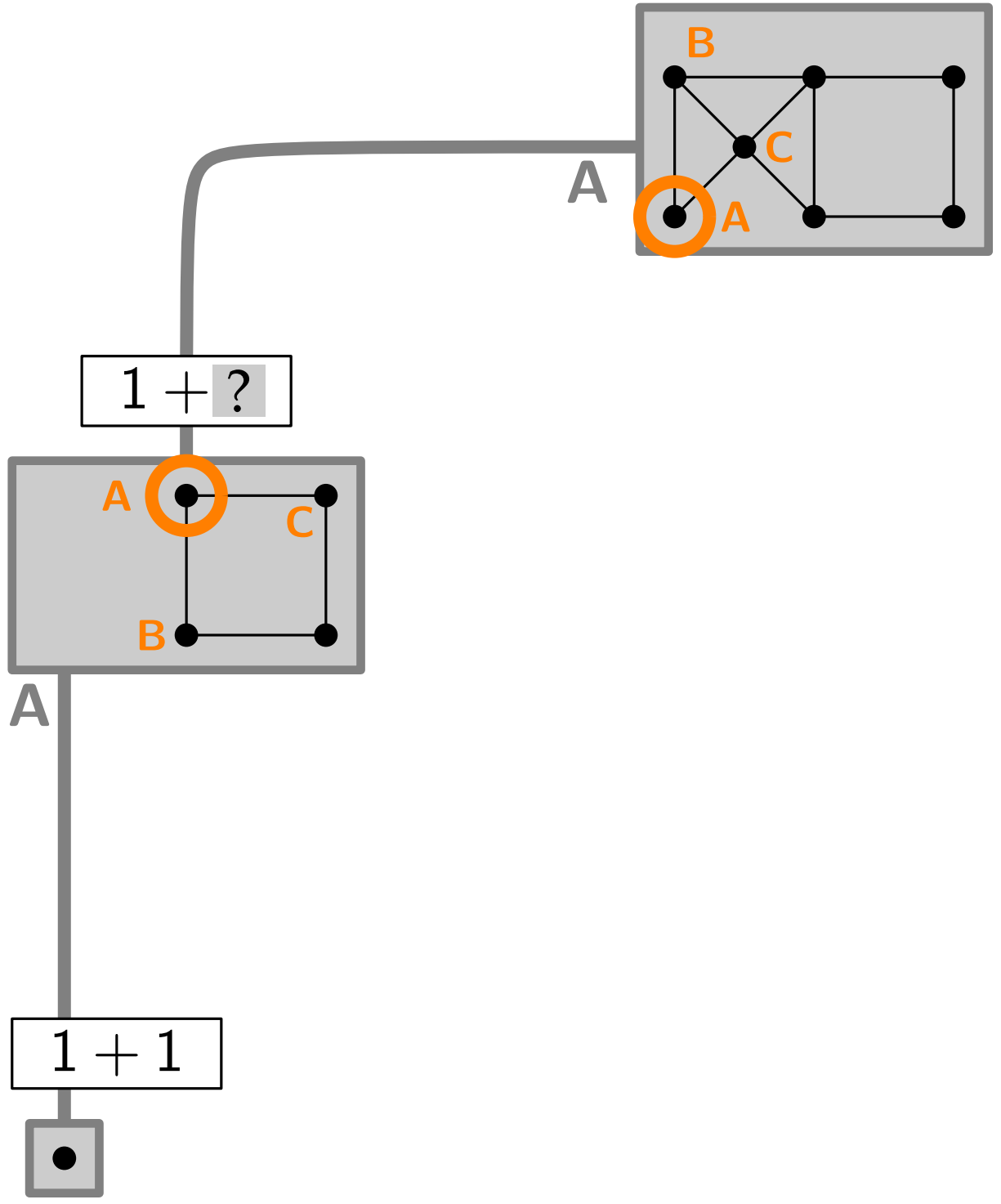


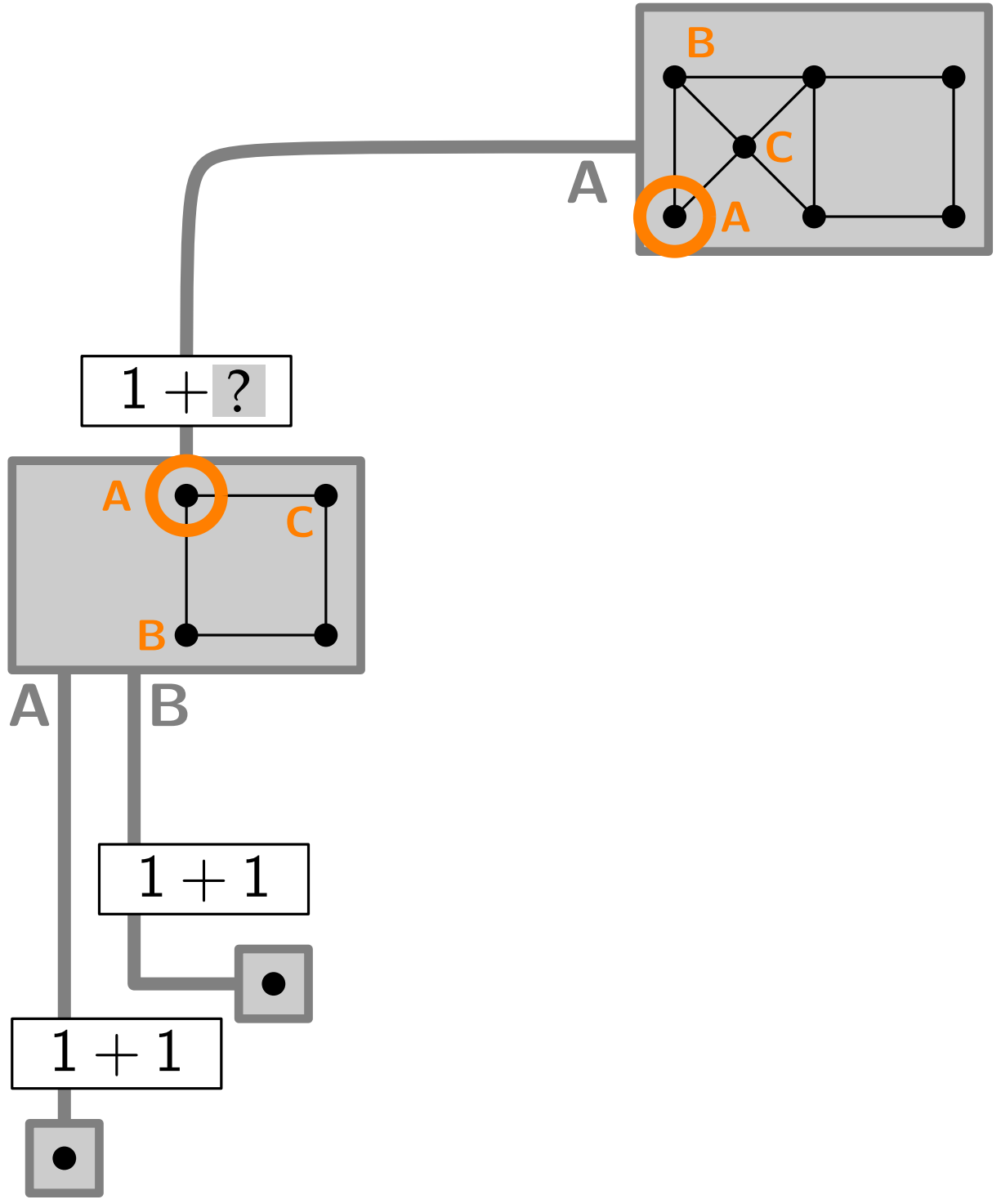


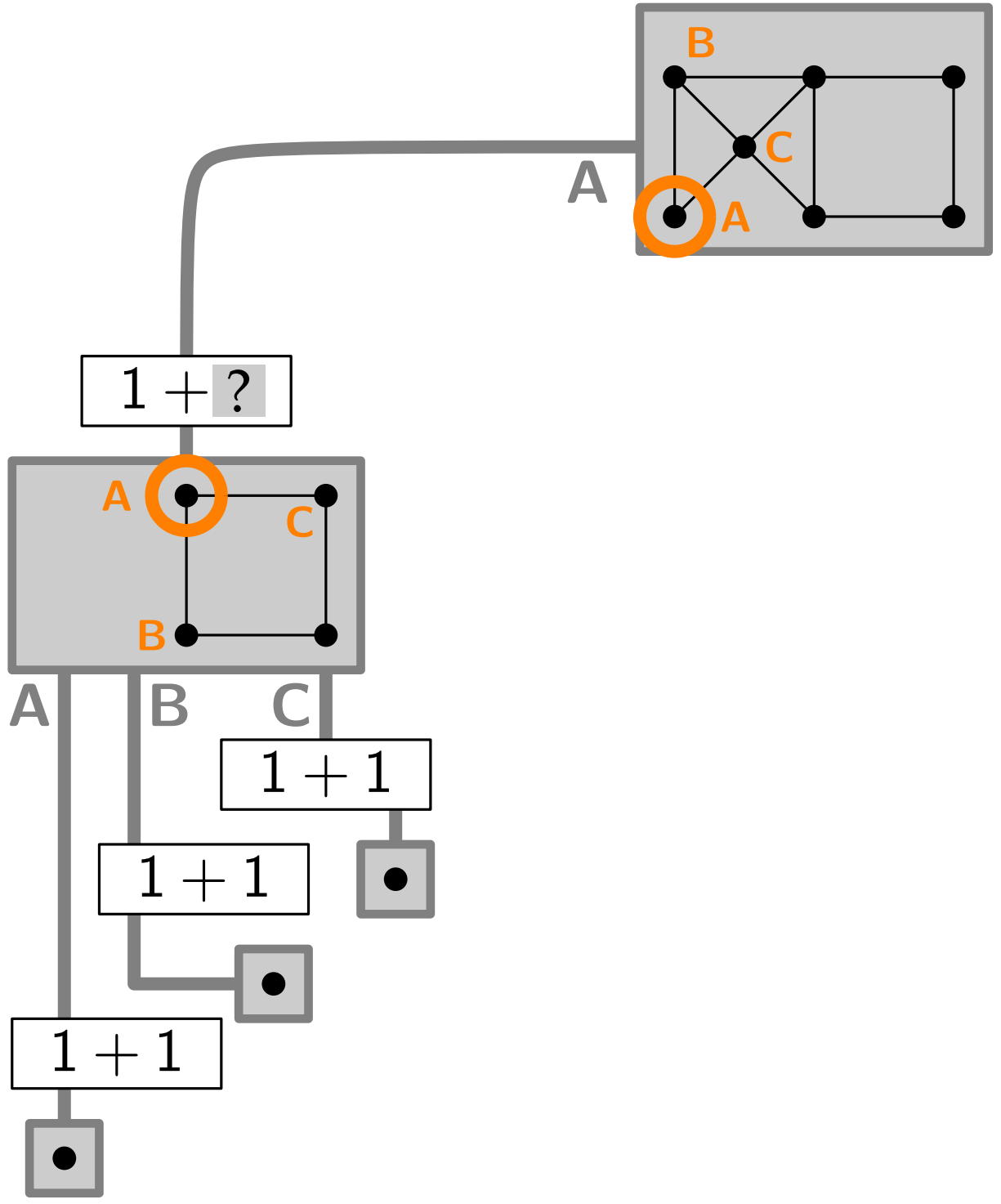


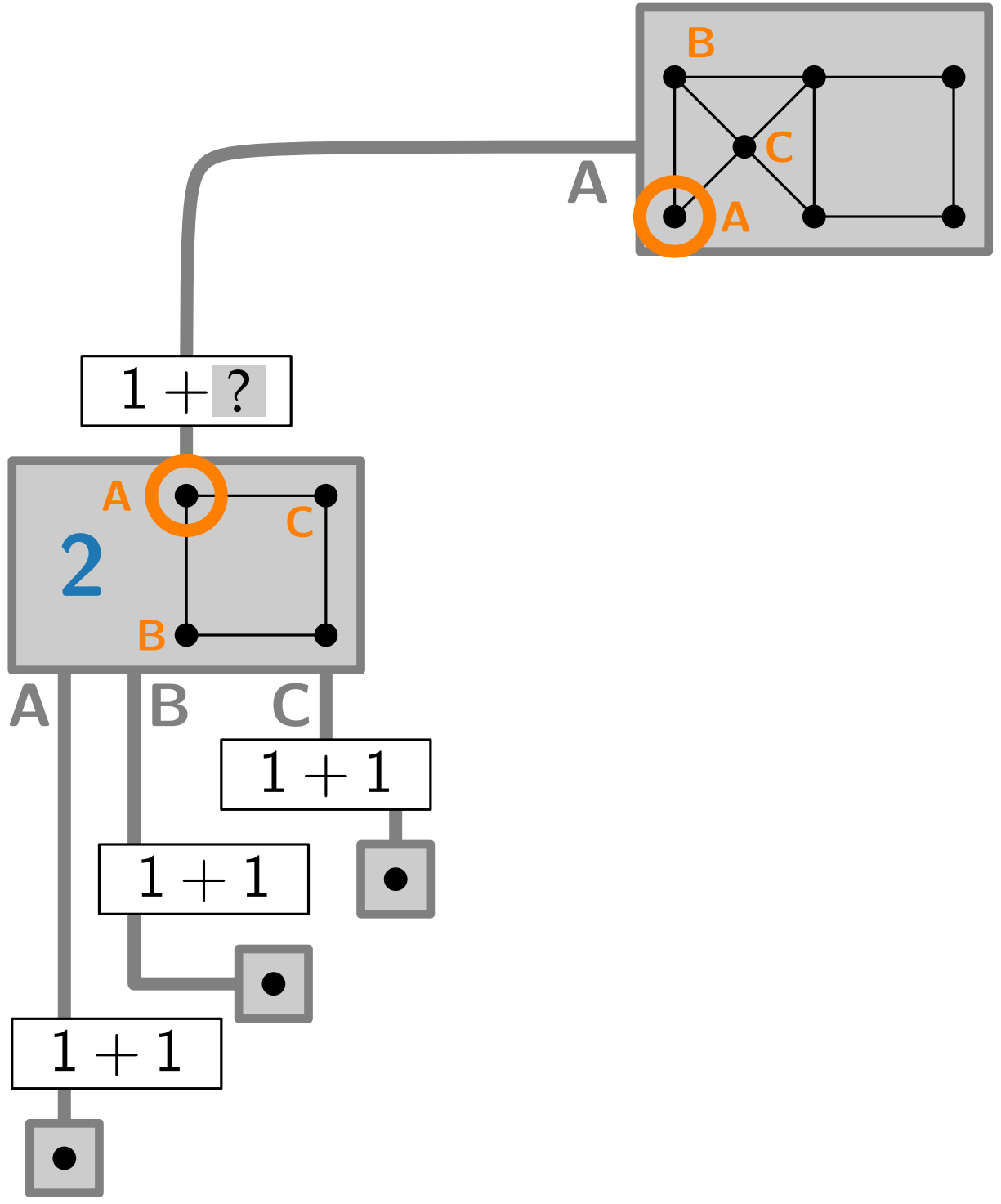


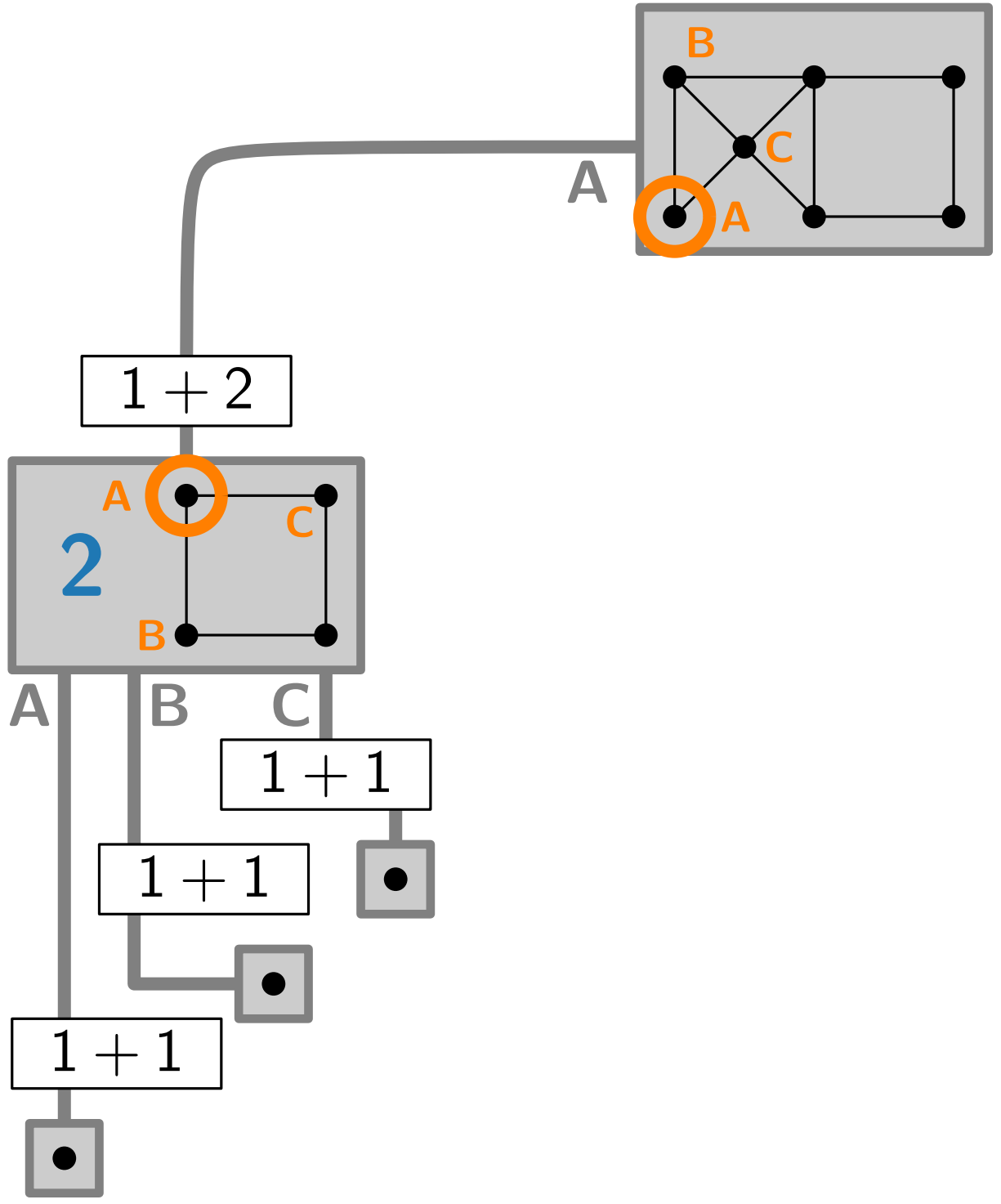


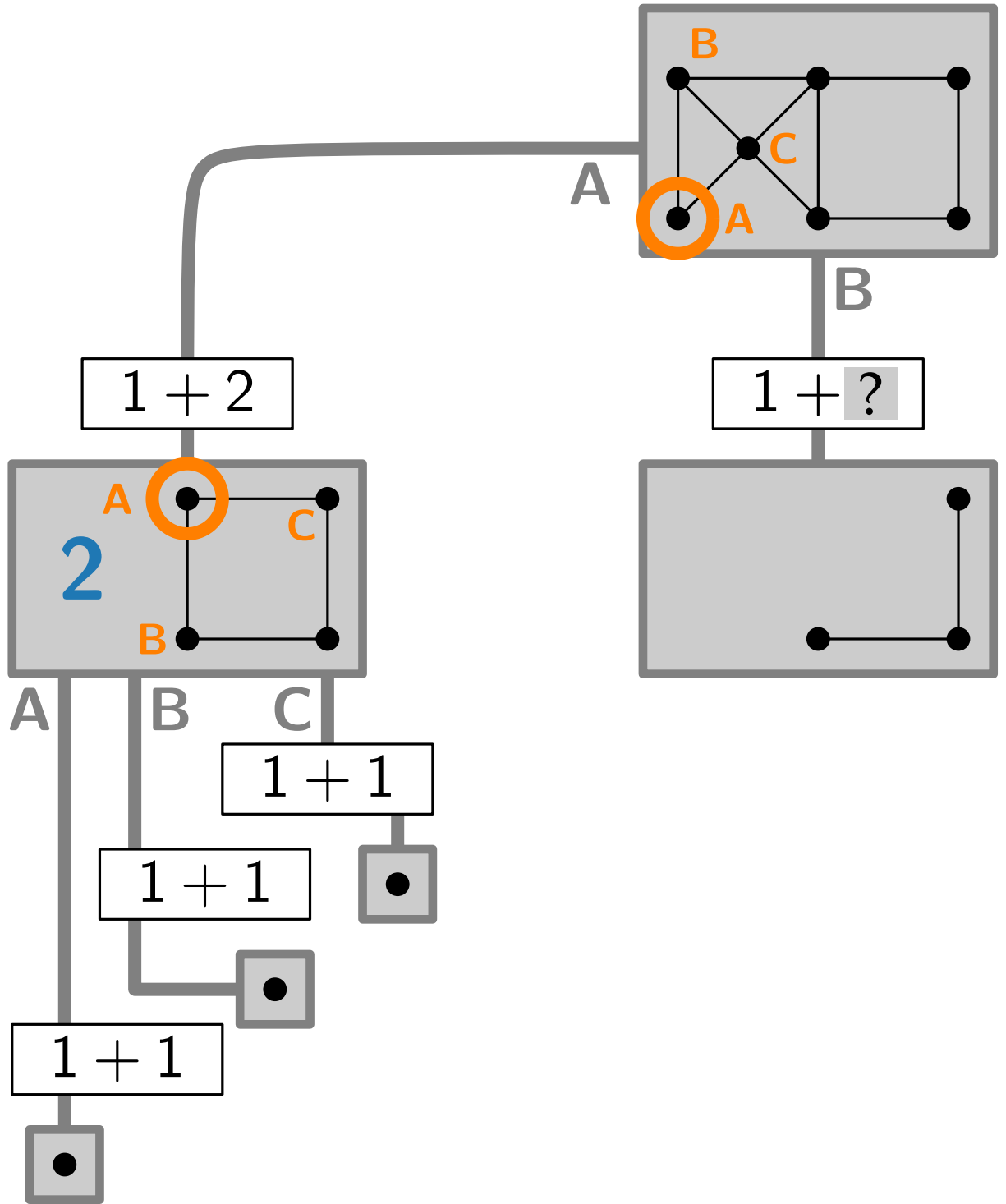


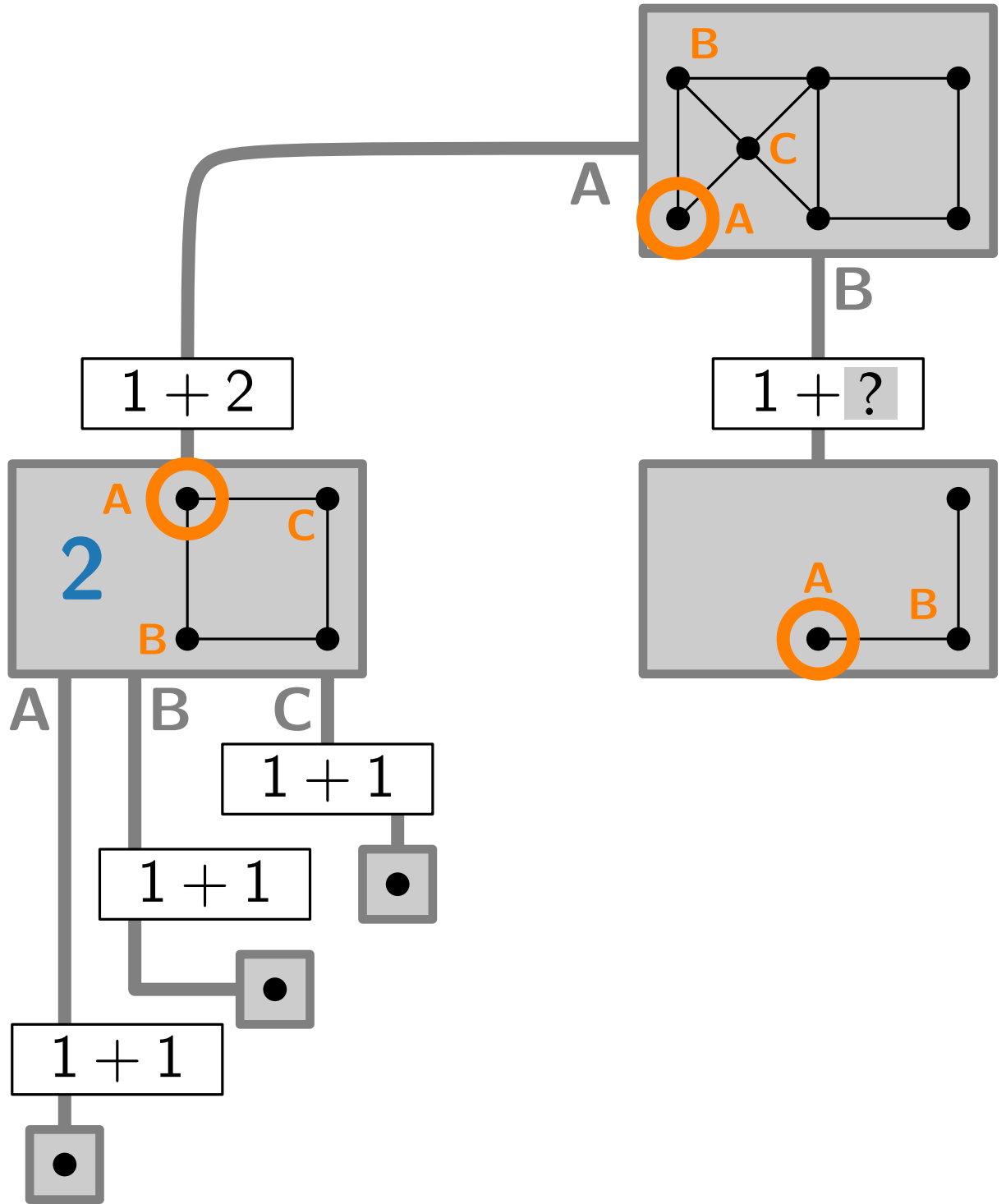


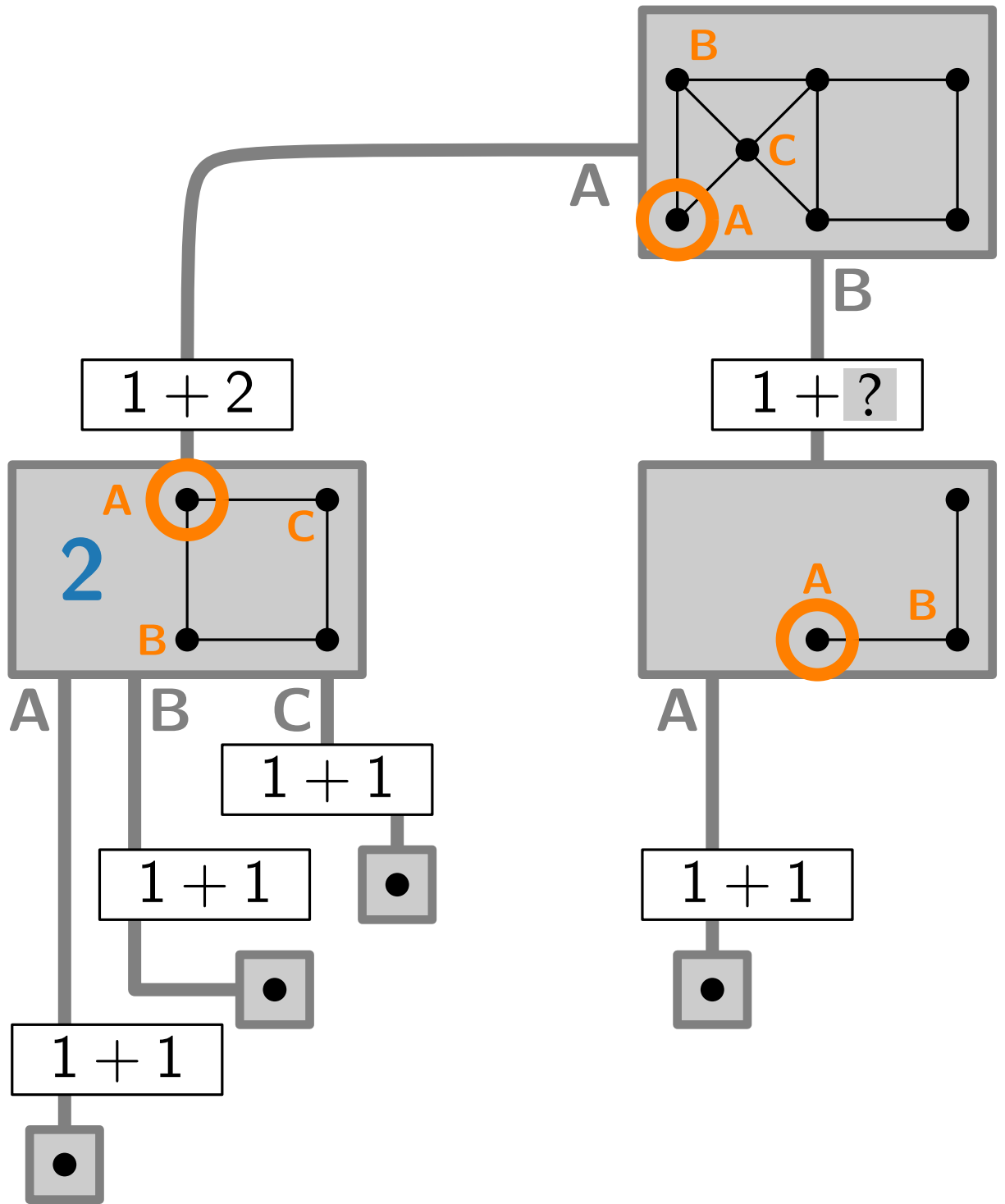


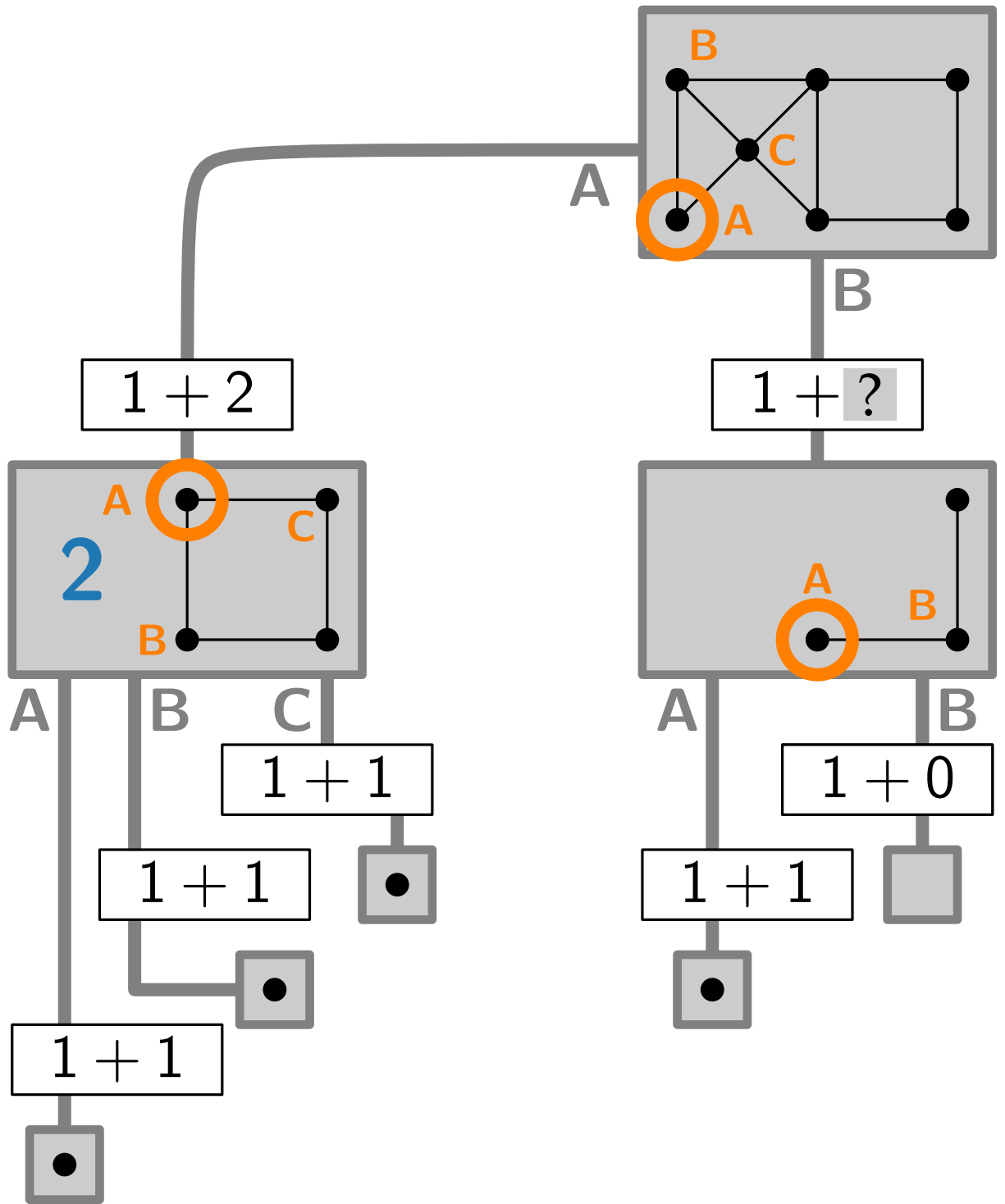


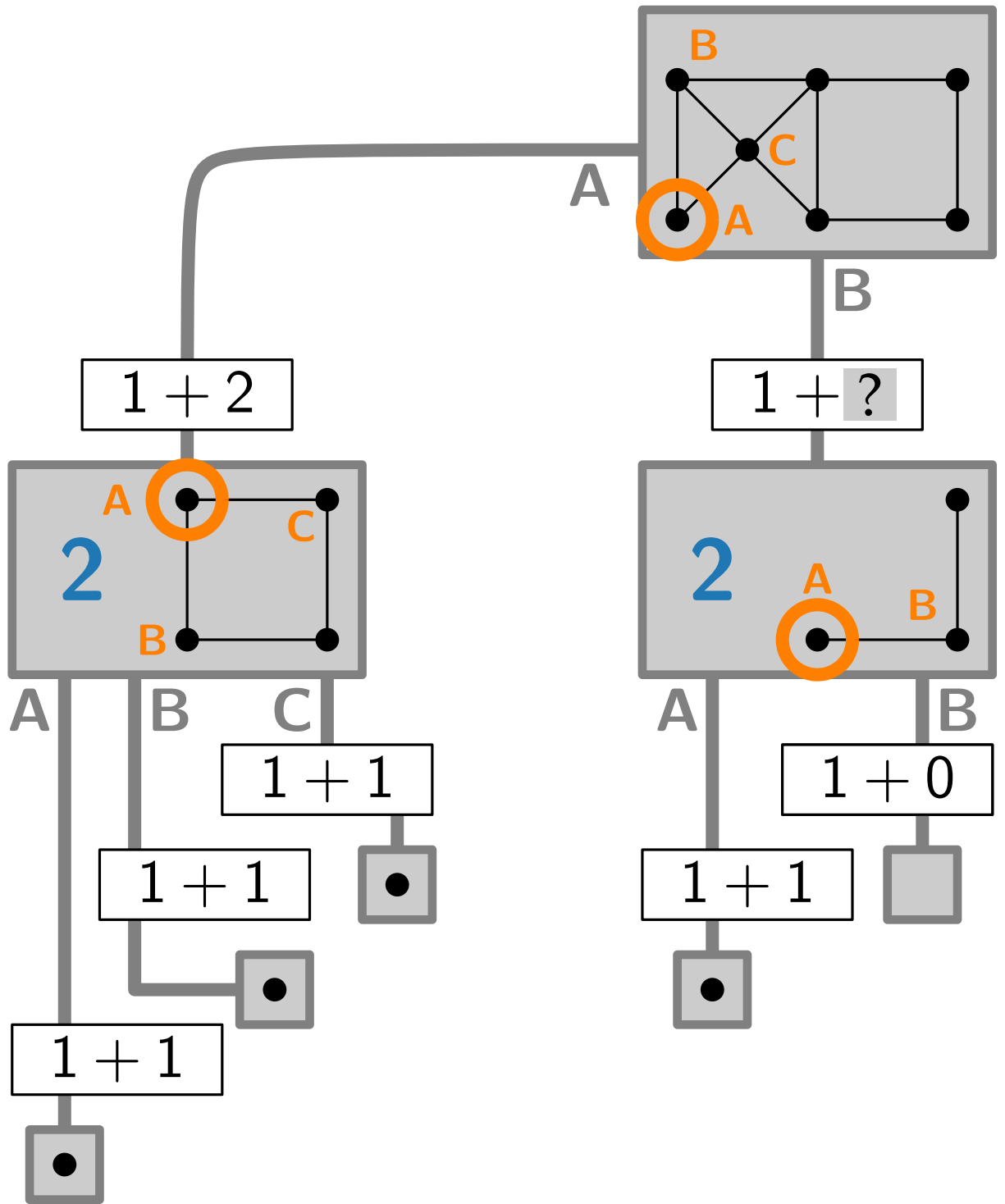


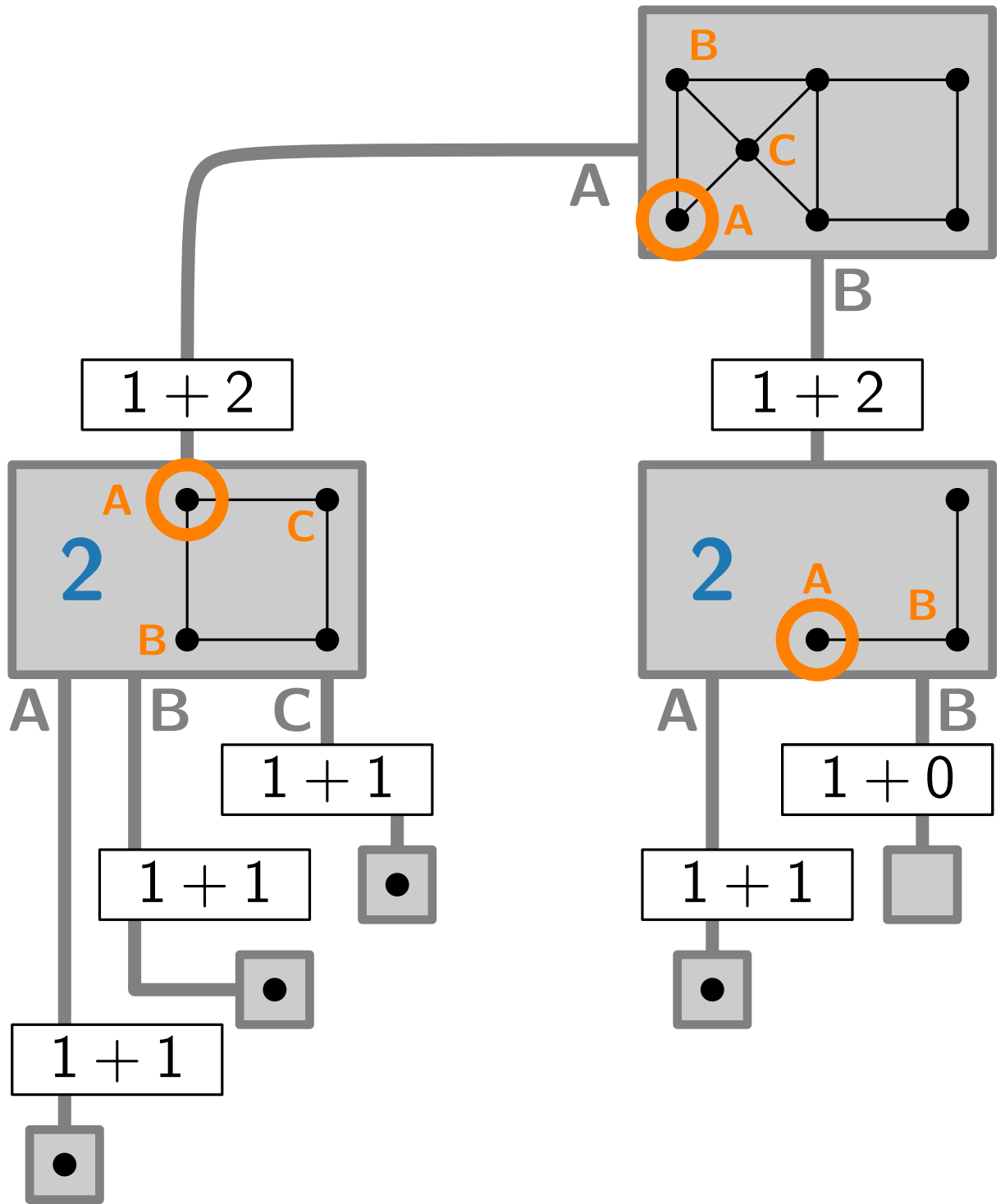


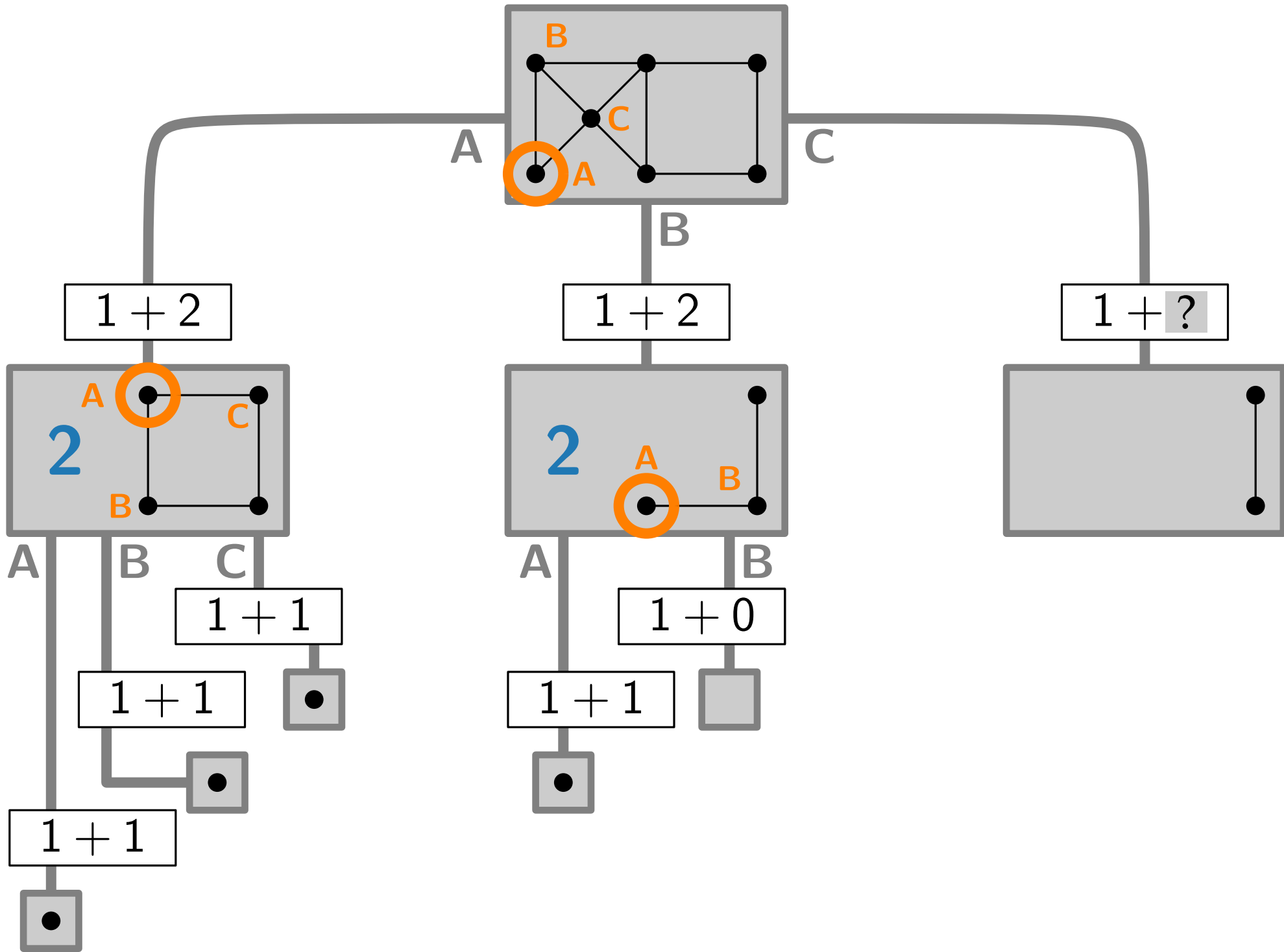


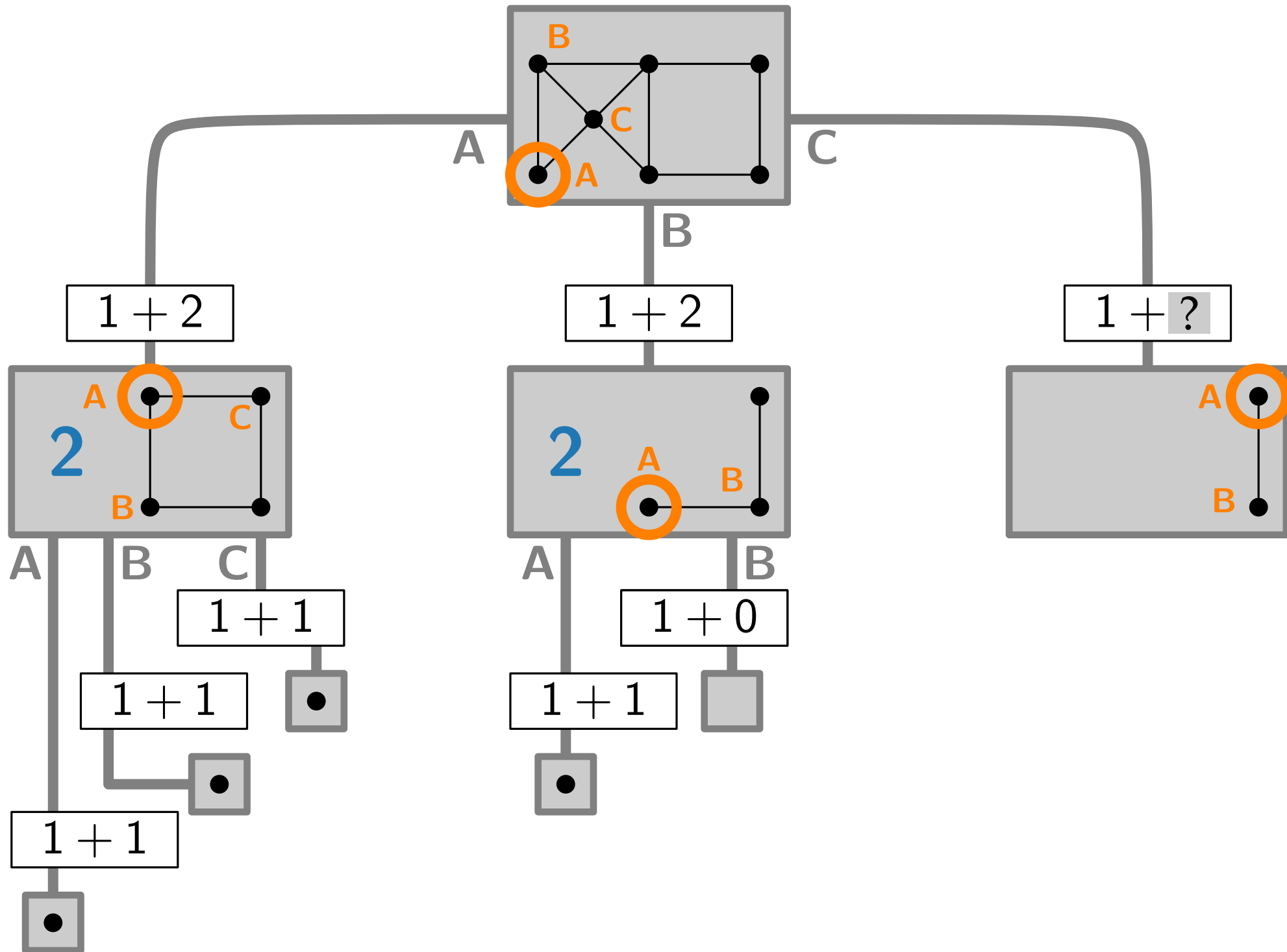


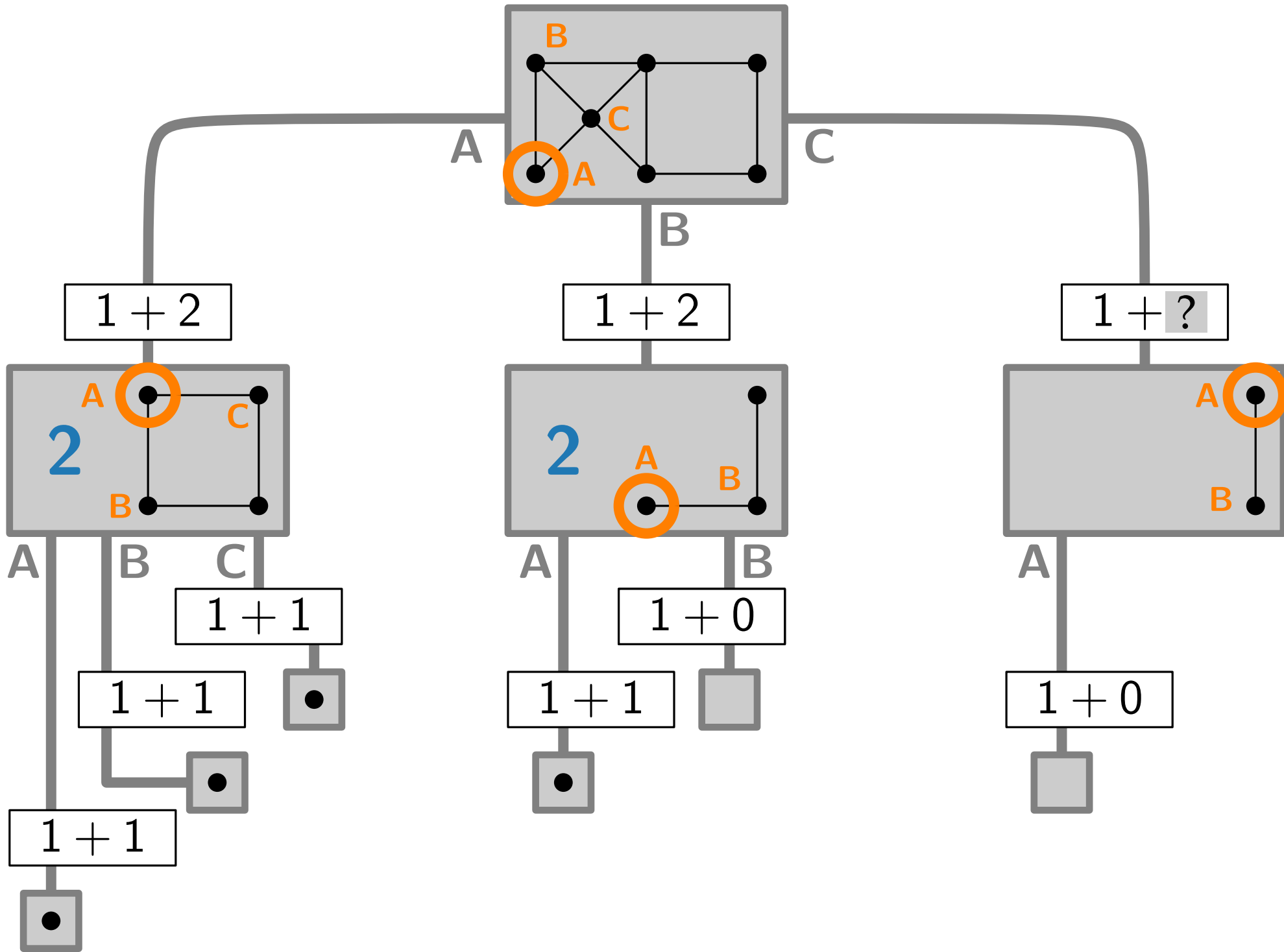


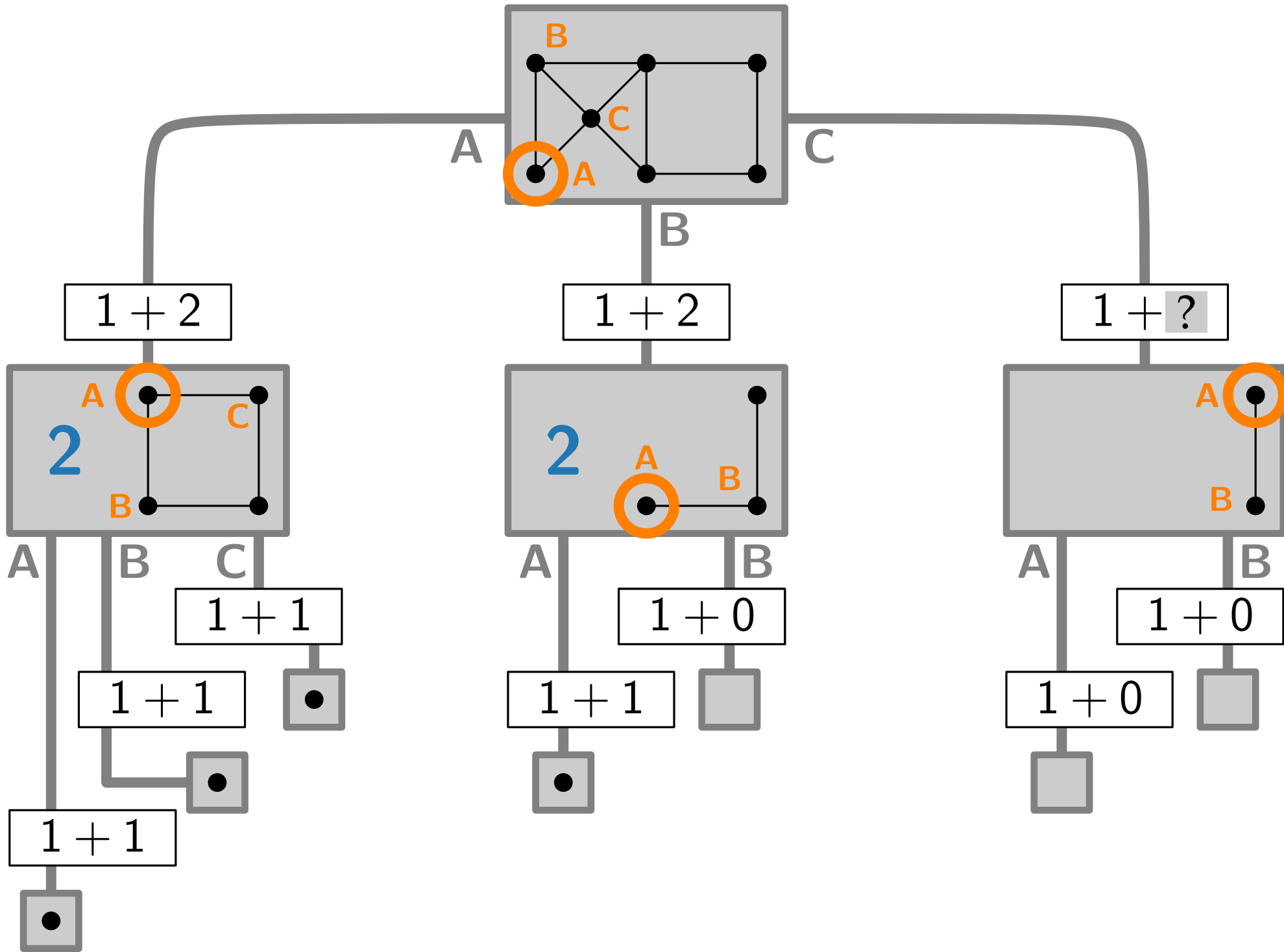


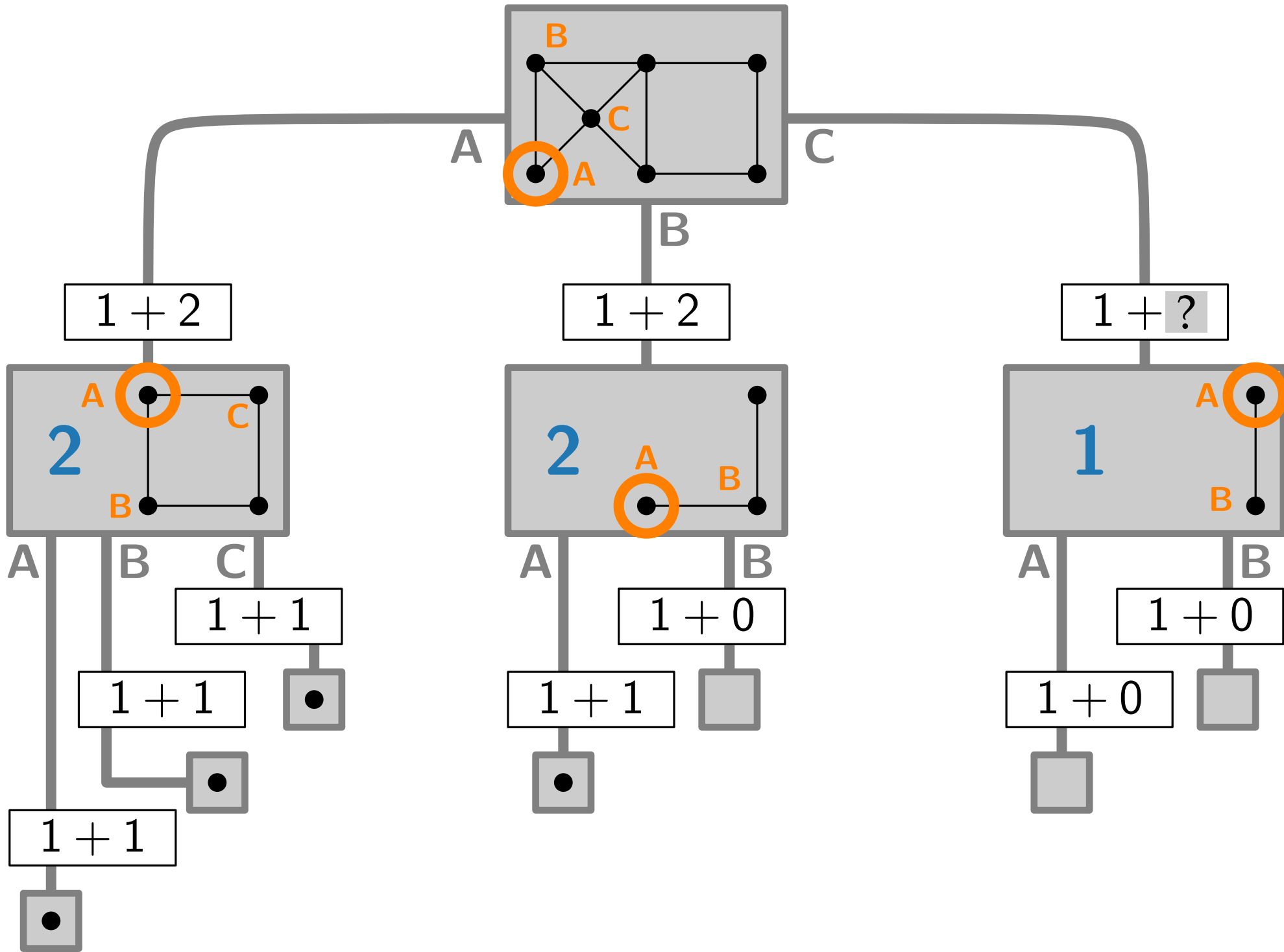


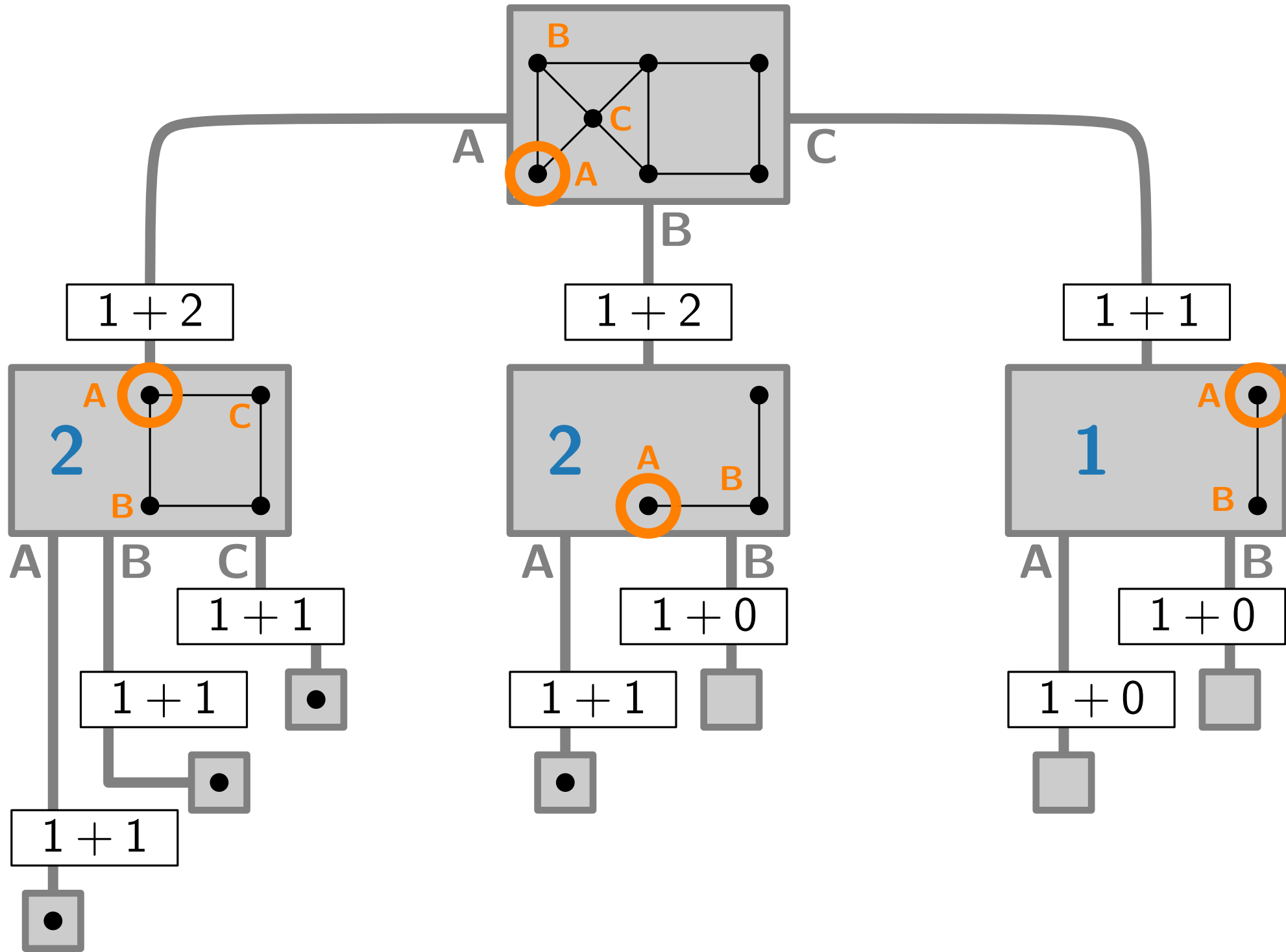


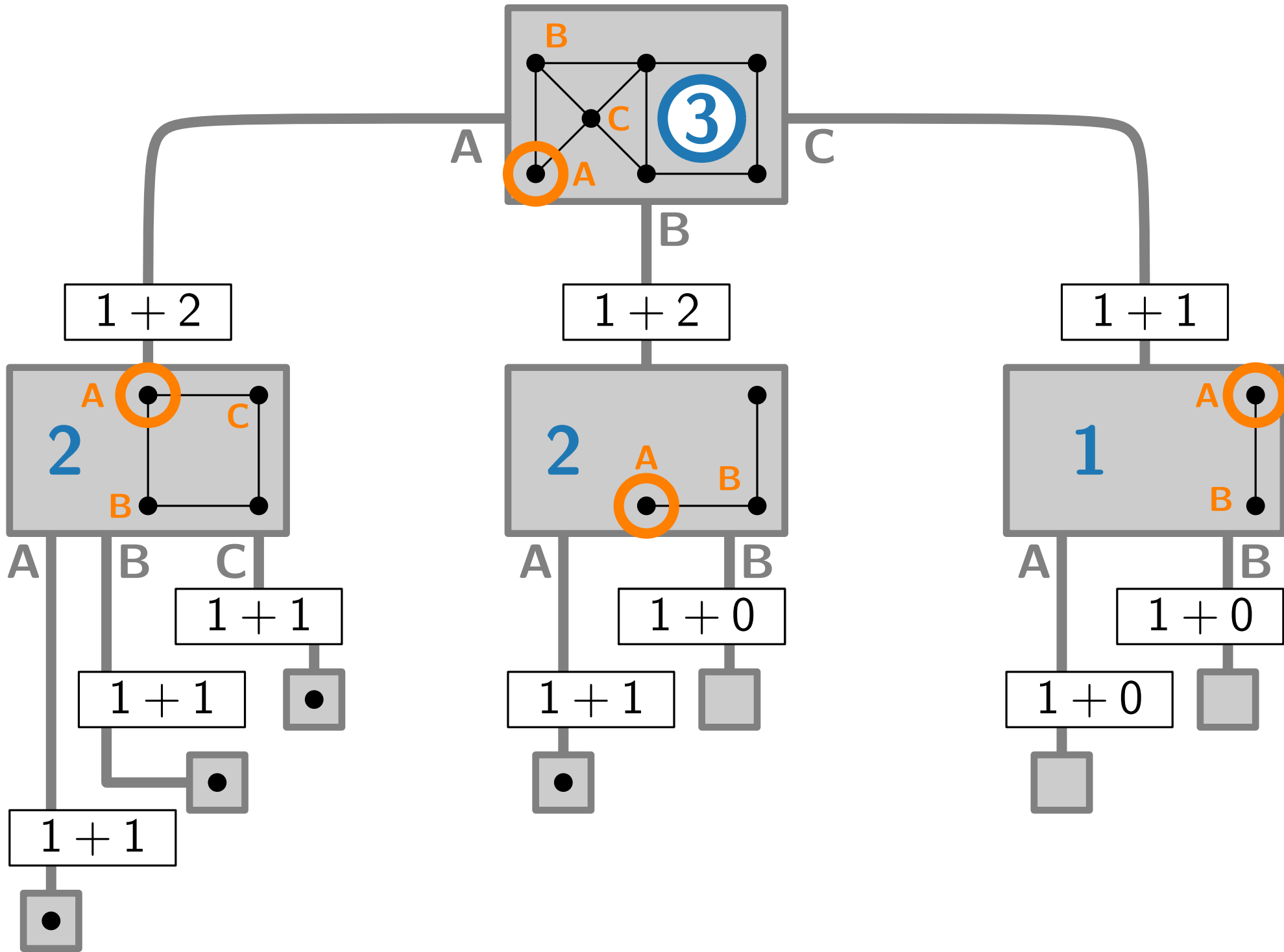












MIS – Runtime Analysis

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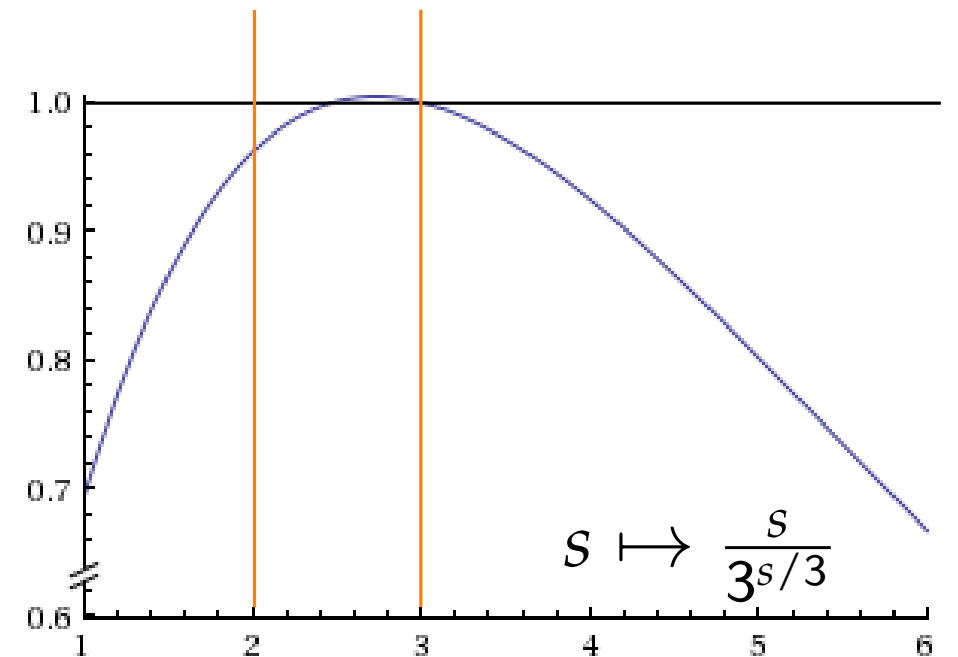
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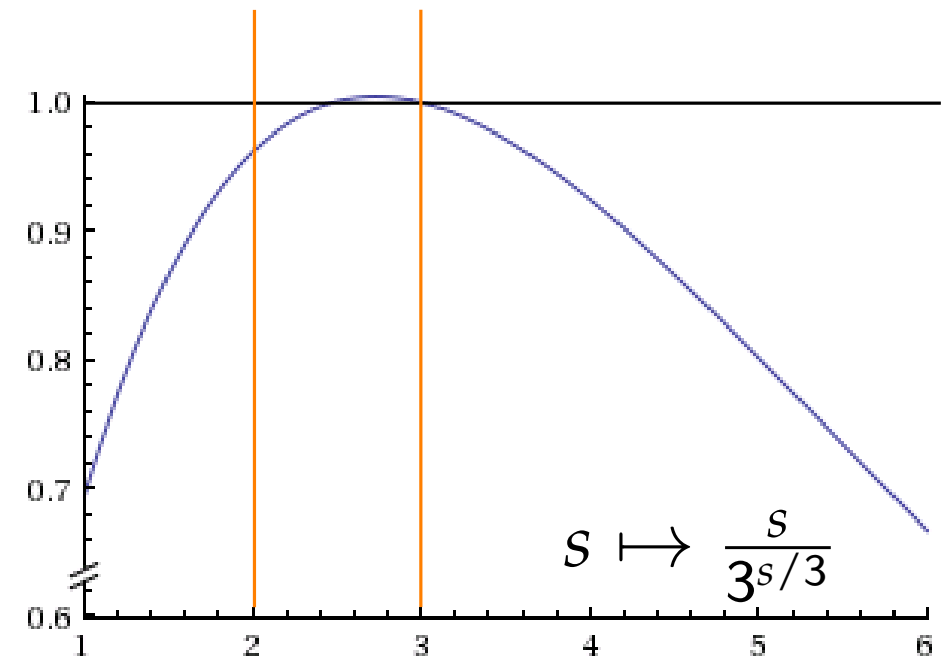
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$$B(n) \in O^*(\sqrt[3]{3}^n) \subset O^*(1.44225^n)$$



MIS – Discussion

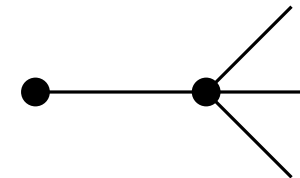
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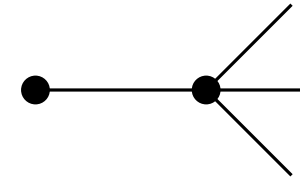
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- **Exercise:** Edge-branching for MIS



Literature

Main source:

- [Fomin, Kratsch Ch1] “Exact Exponential Algorithms”

Referenced papers:

- [ADMV '15] Classic Nintendo Games are (Computationally) Hard
- [Mann '17] The Top Eight Misconceptions about NP-Hardness