

# Approximation Algorithms

## Lecture 9: An Approximation Scheme for EUCLIDEAN TSP

### Part I: The TRAVELING SALESMAN PROBLEM

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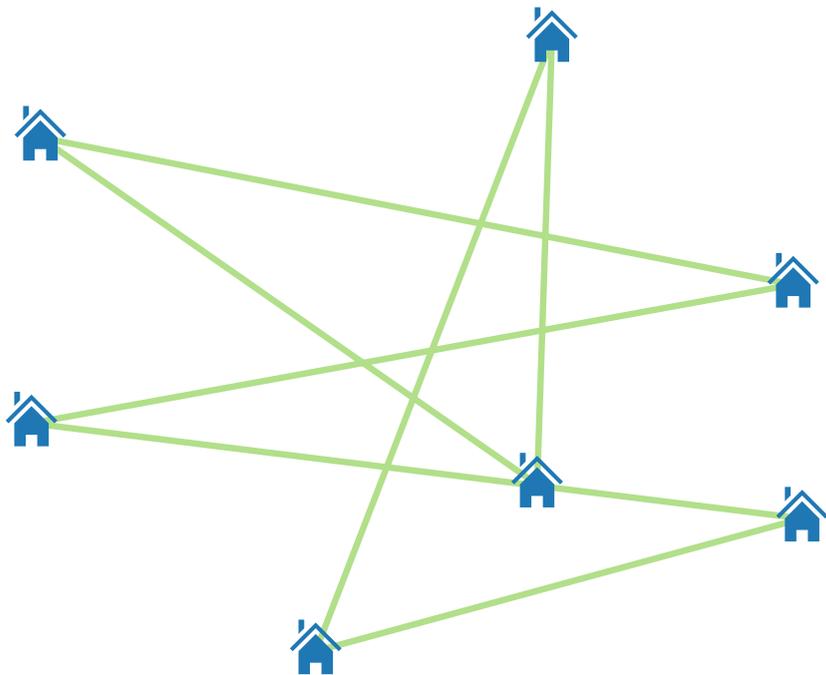


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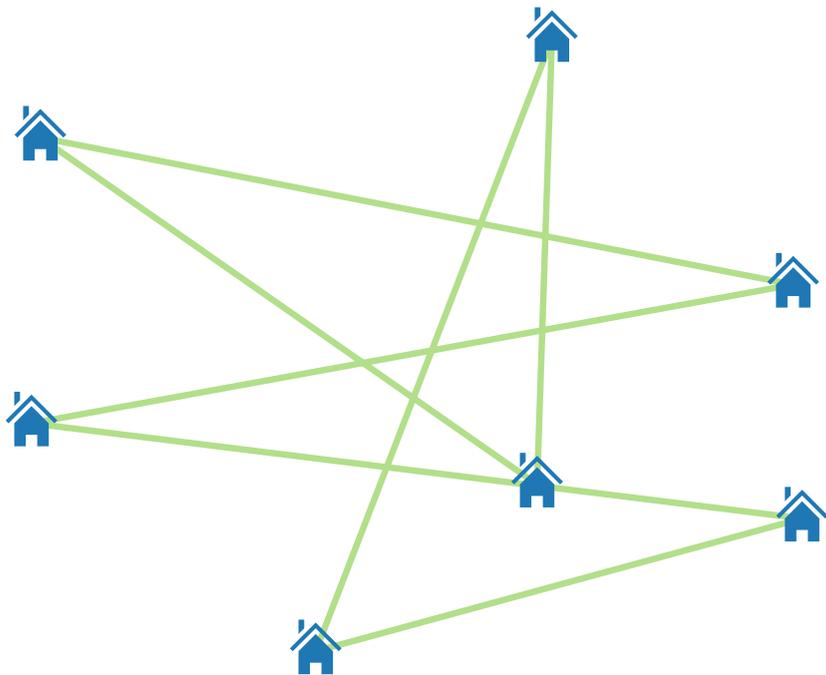


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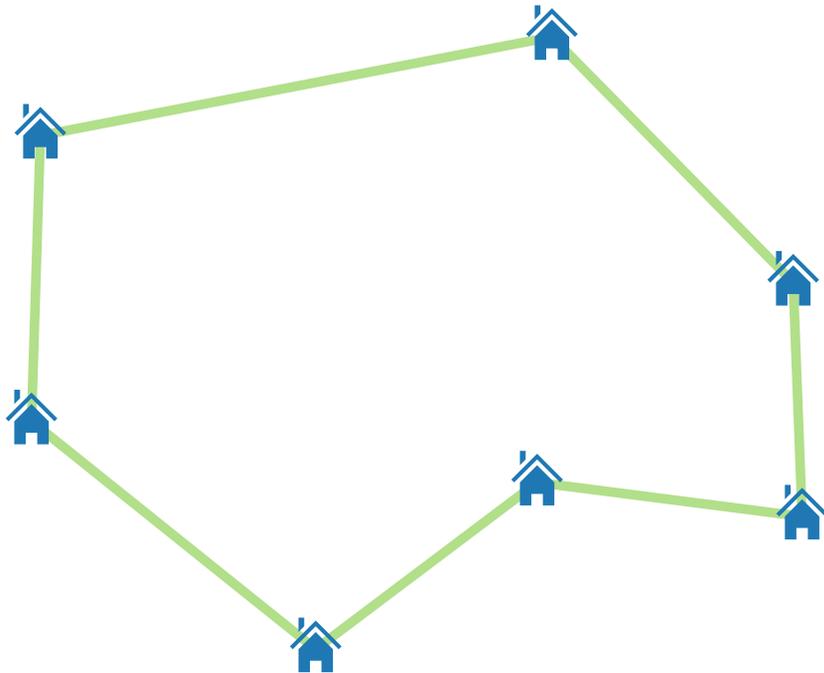


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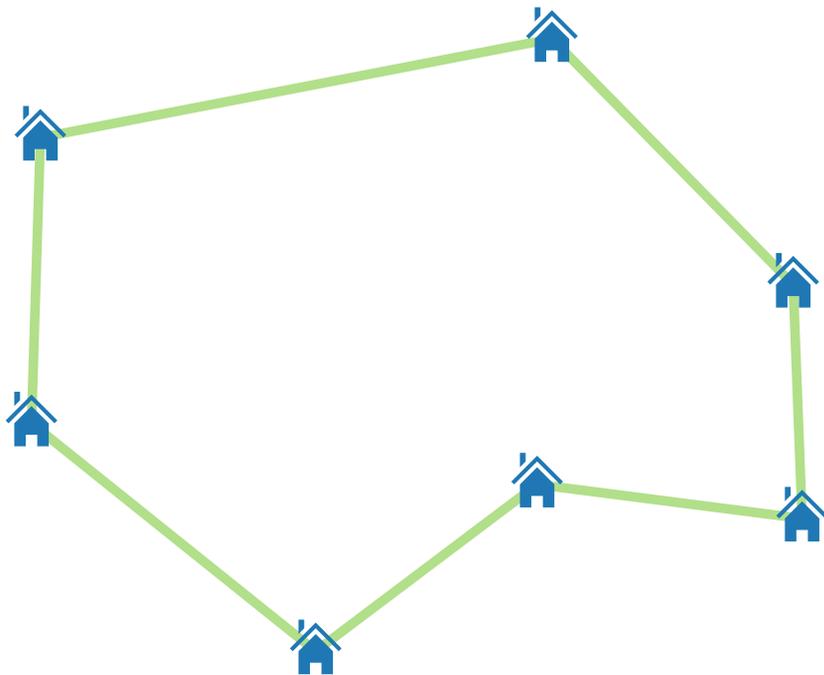


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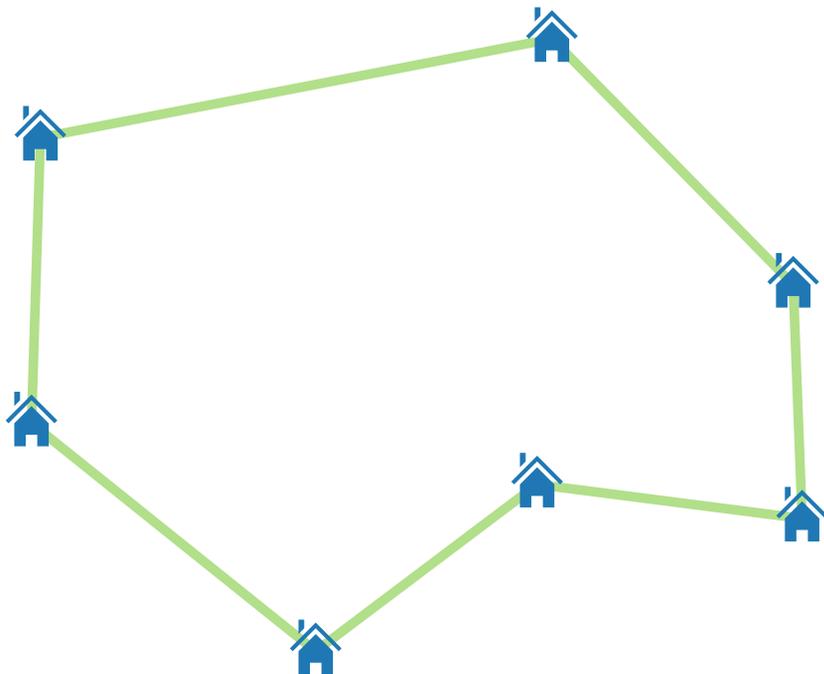
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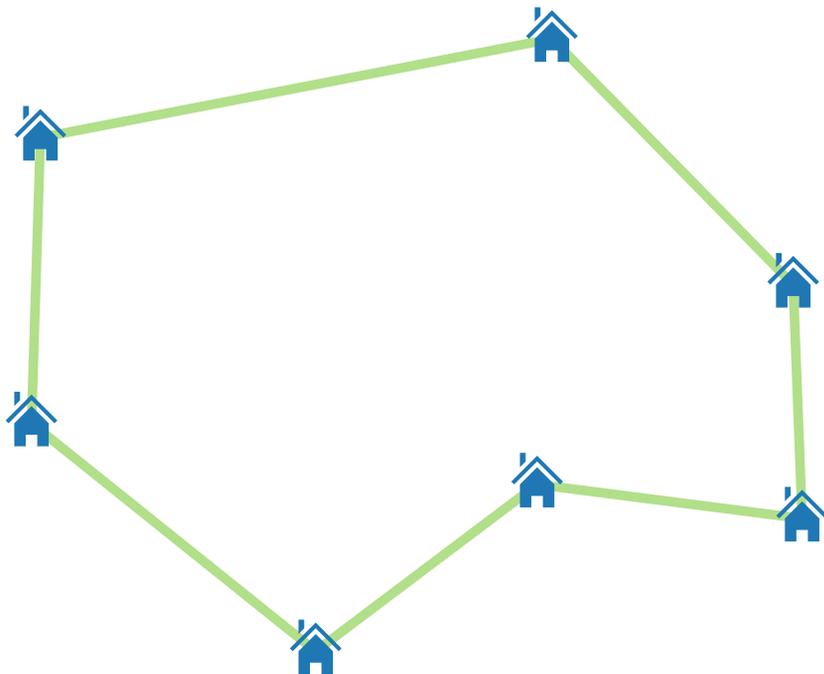
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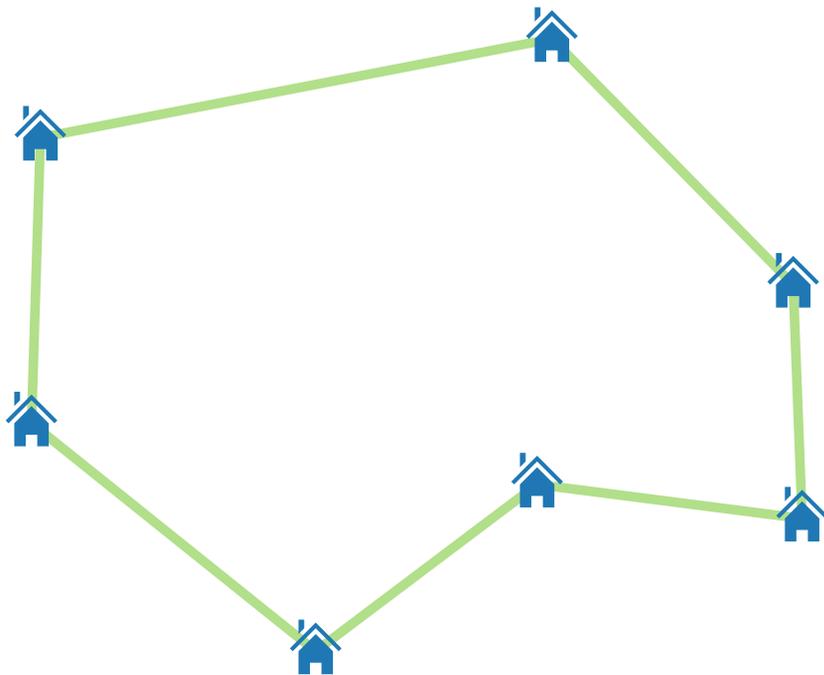
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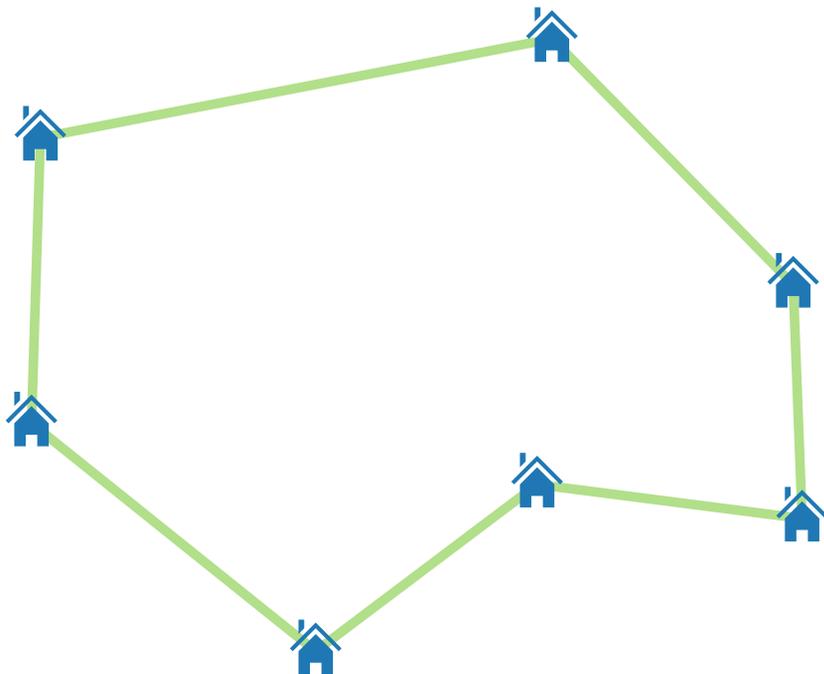
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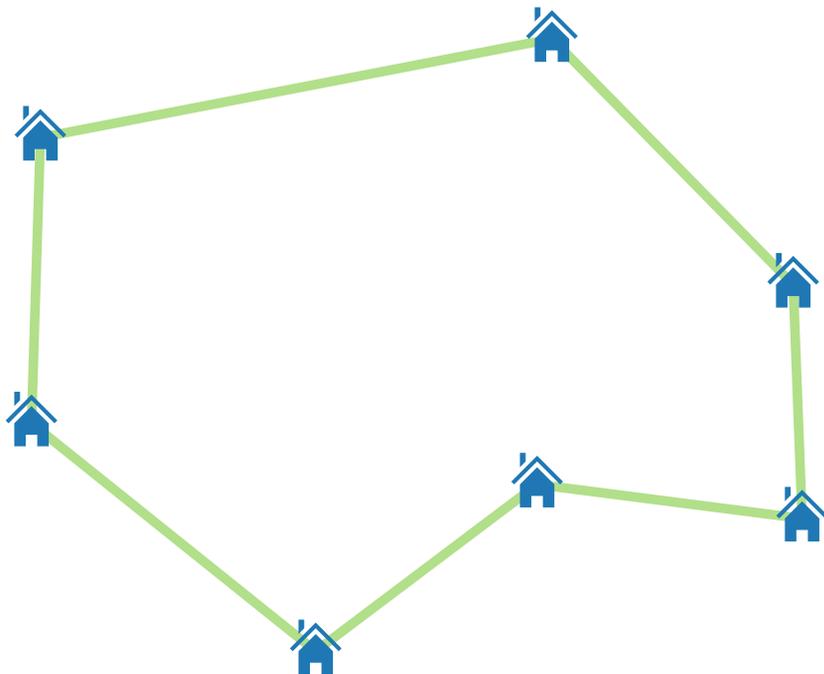
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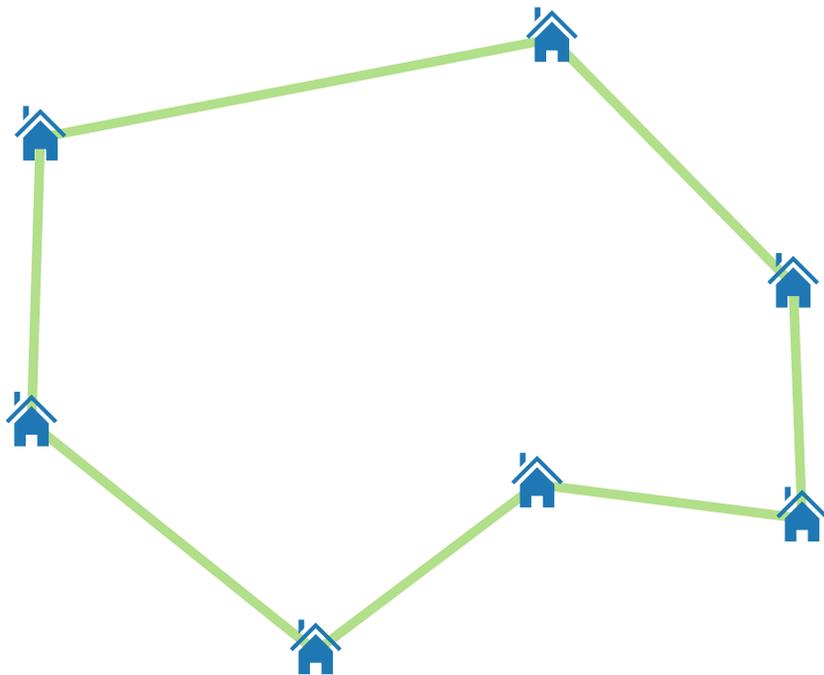
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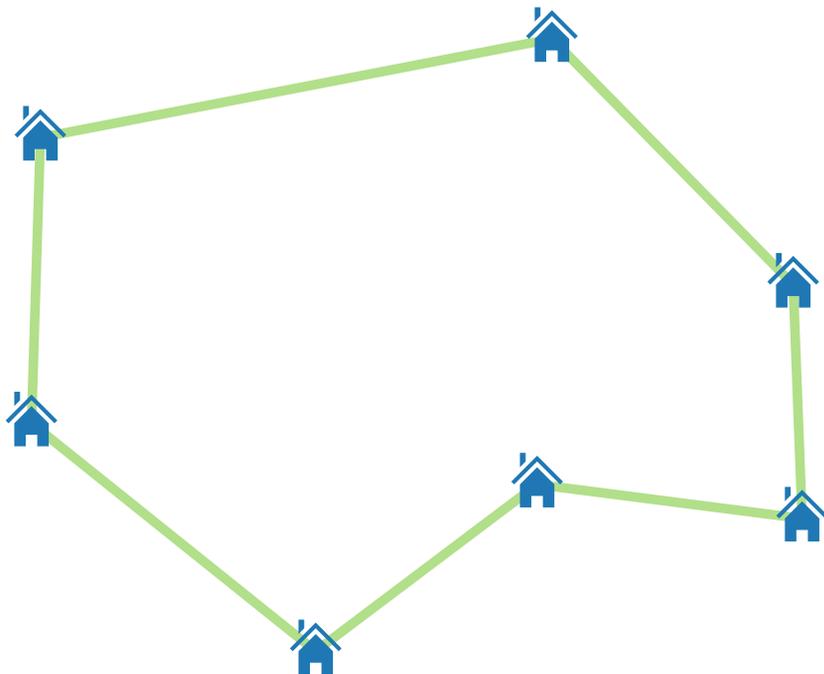
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## Simplifying Assumptions

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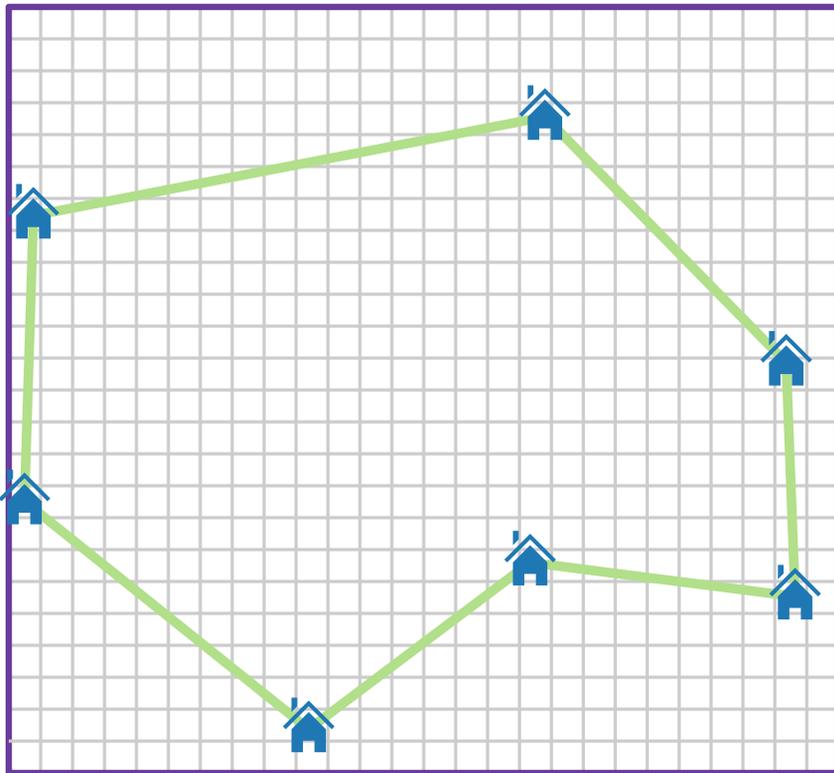
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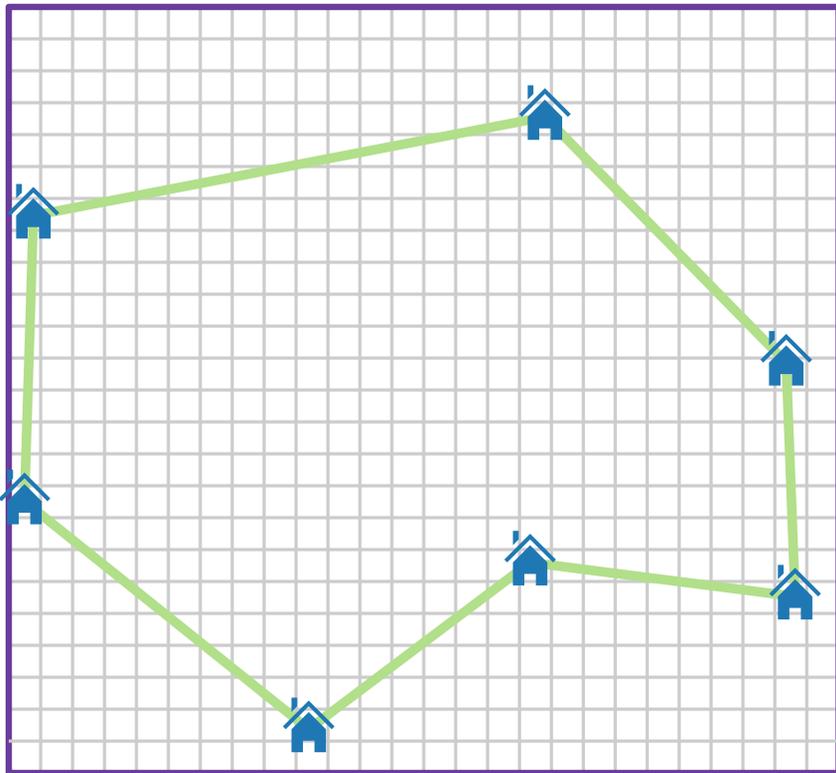
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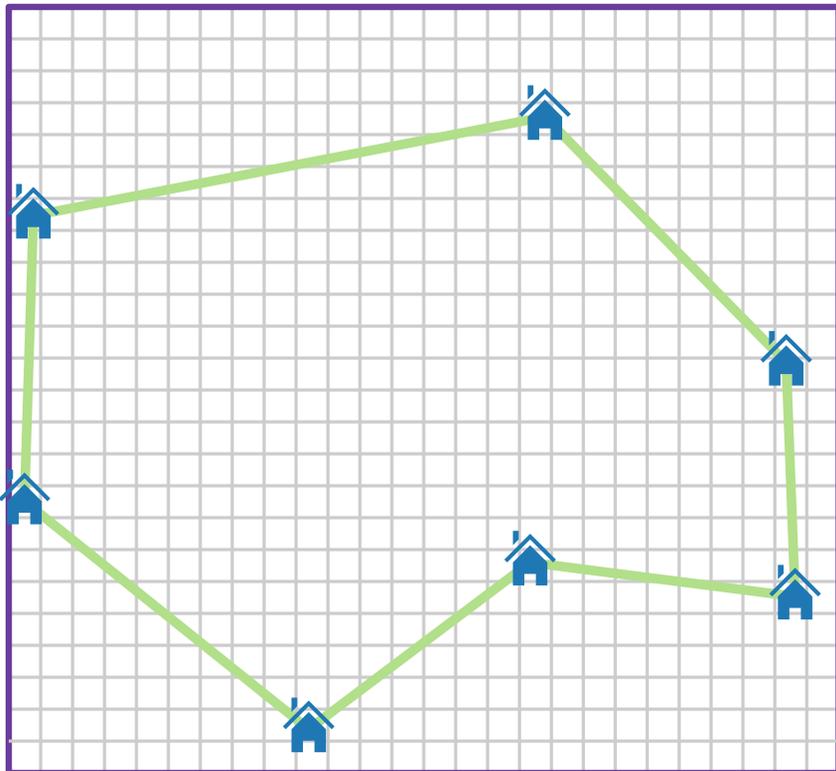
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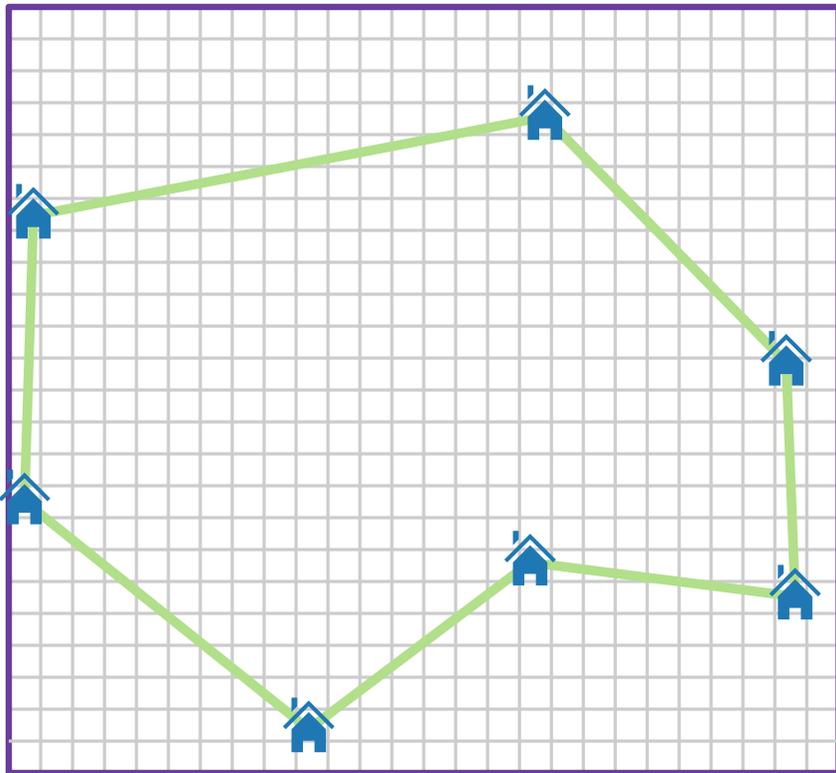
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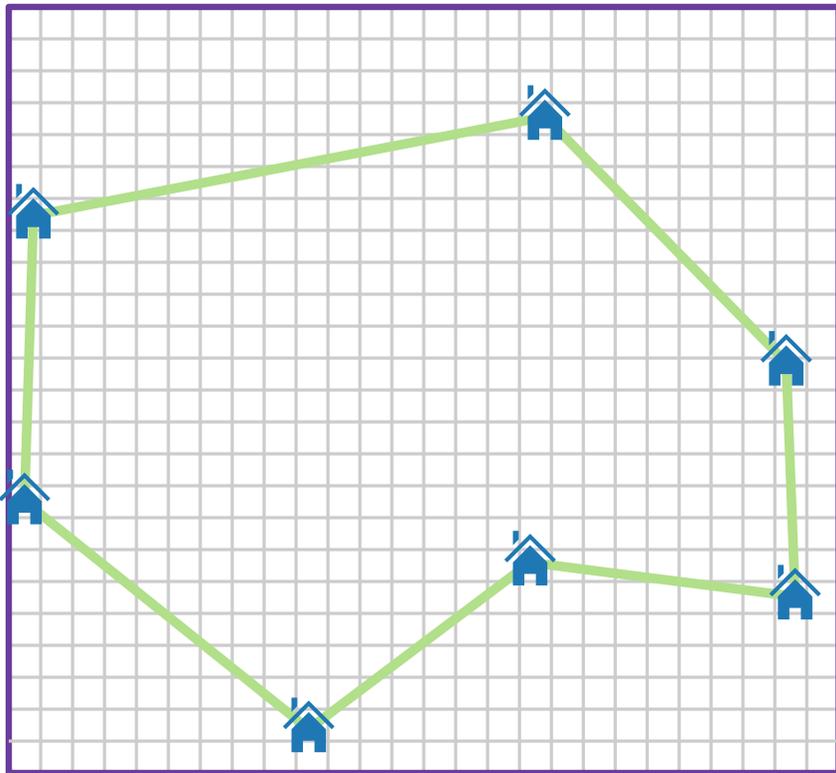
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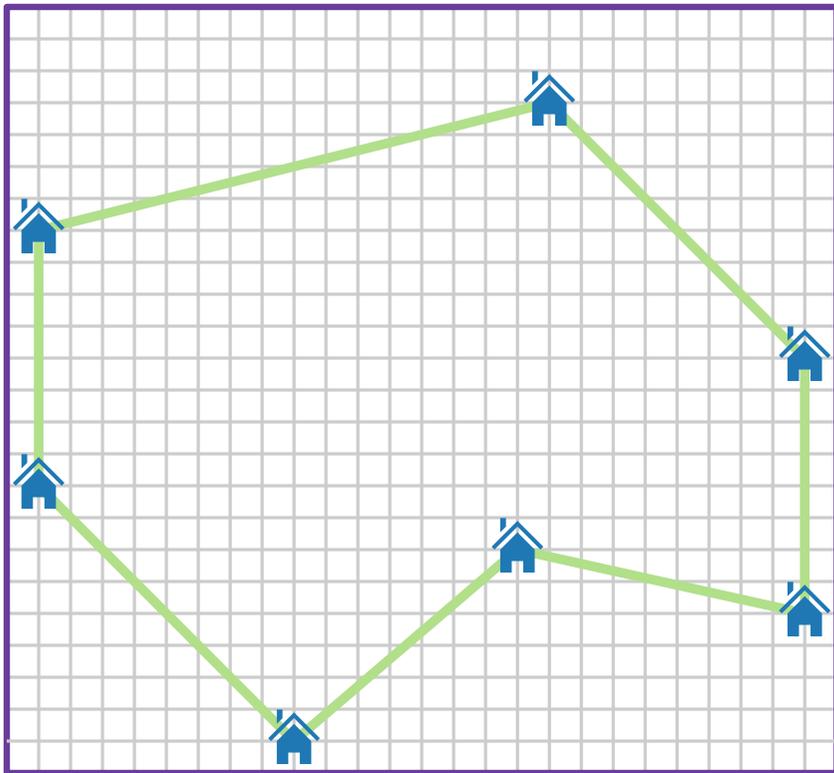
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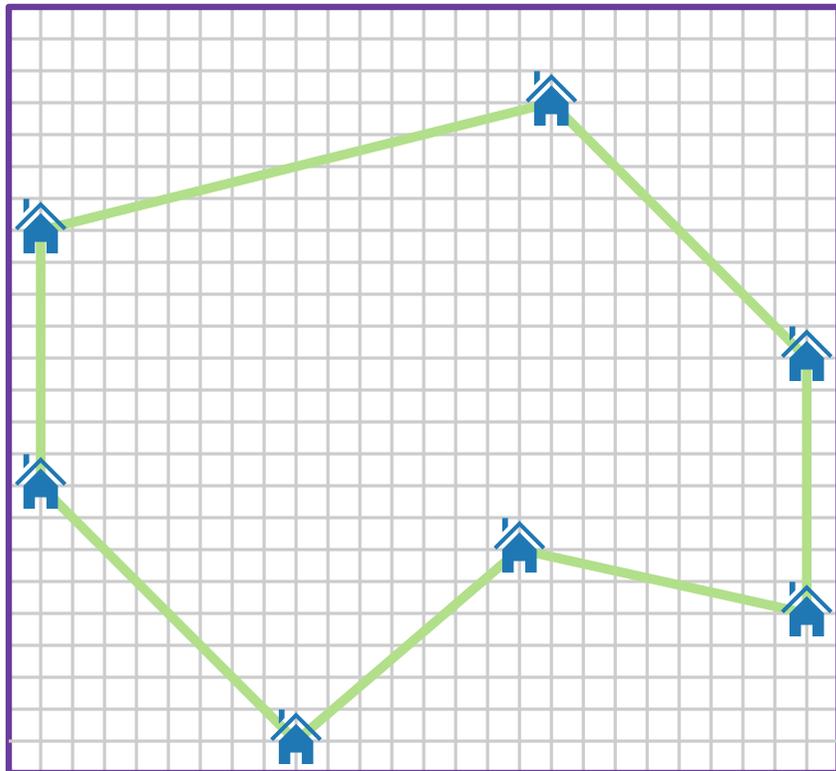
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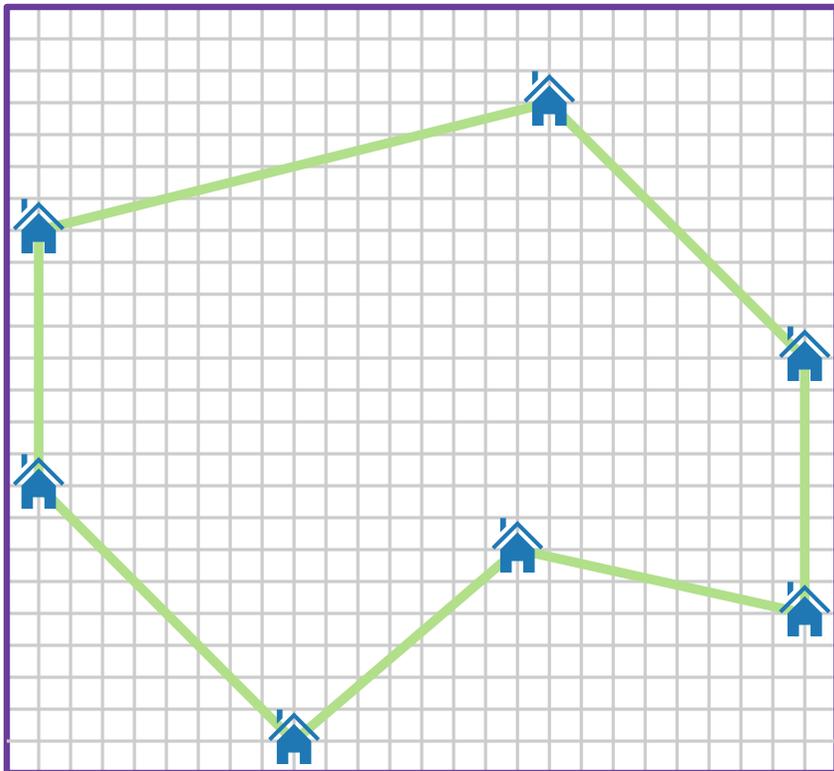
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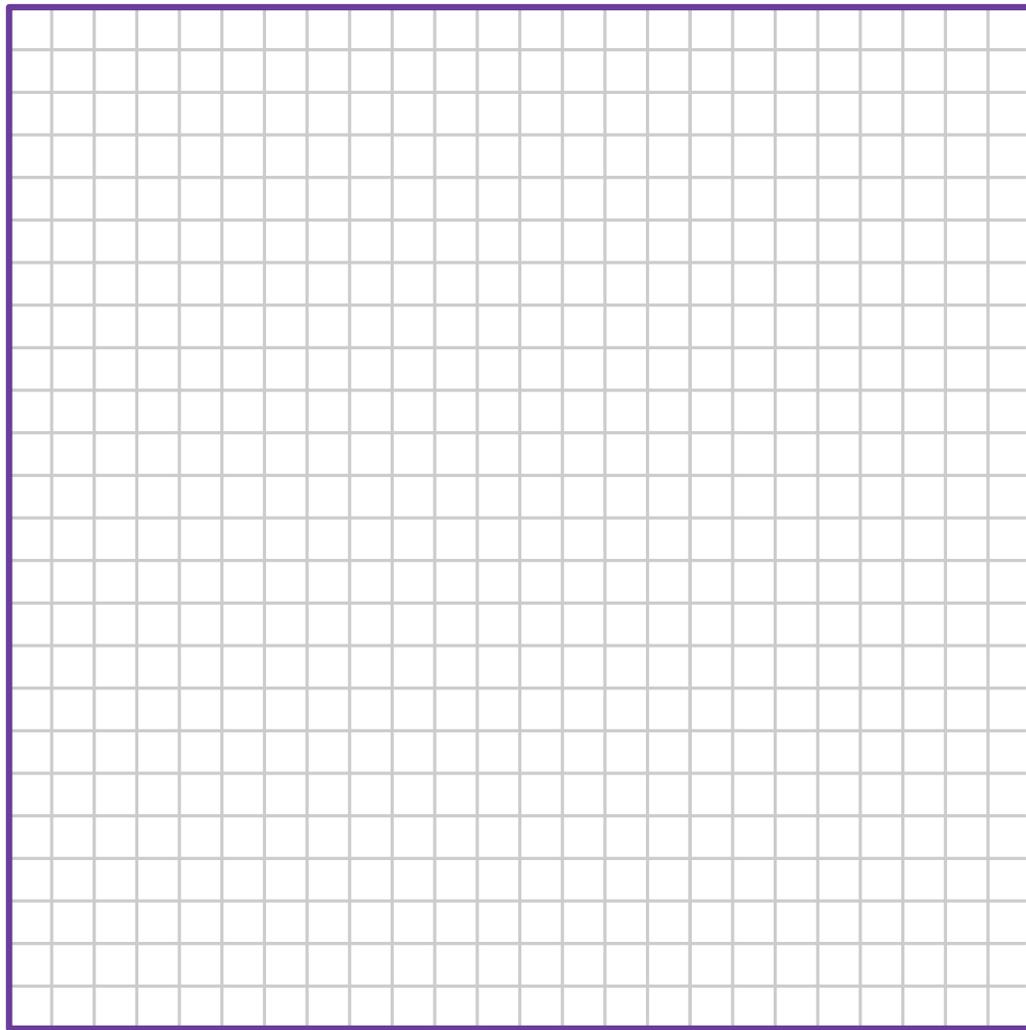
Goal:  
 $(1 + \varepsilon)$ -  
approximation!

# Approximation Algorithms

## Lecture 9: A PTAS for EUCLIDEAN TSP

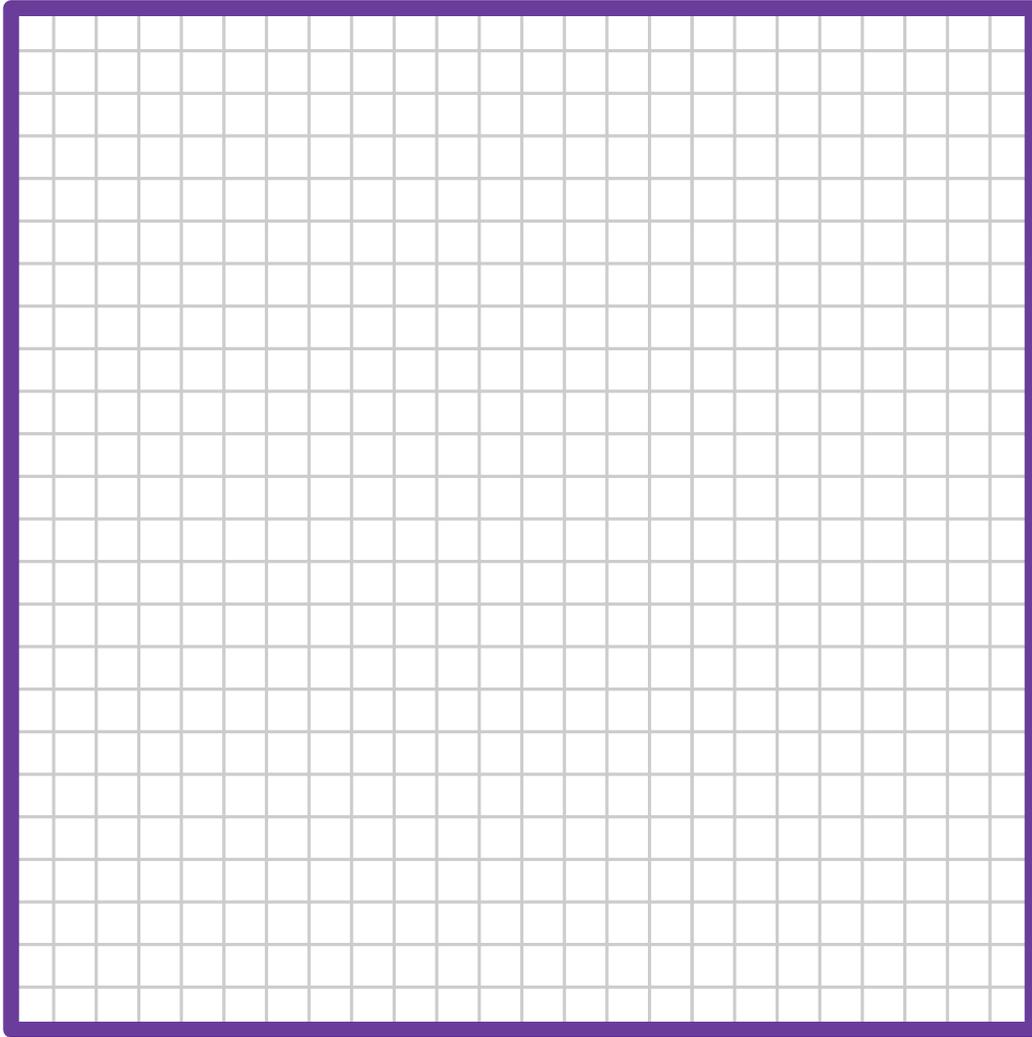
### Part II: Dissection

# Basic Dissection



$$L = 2^k$$

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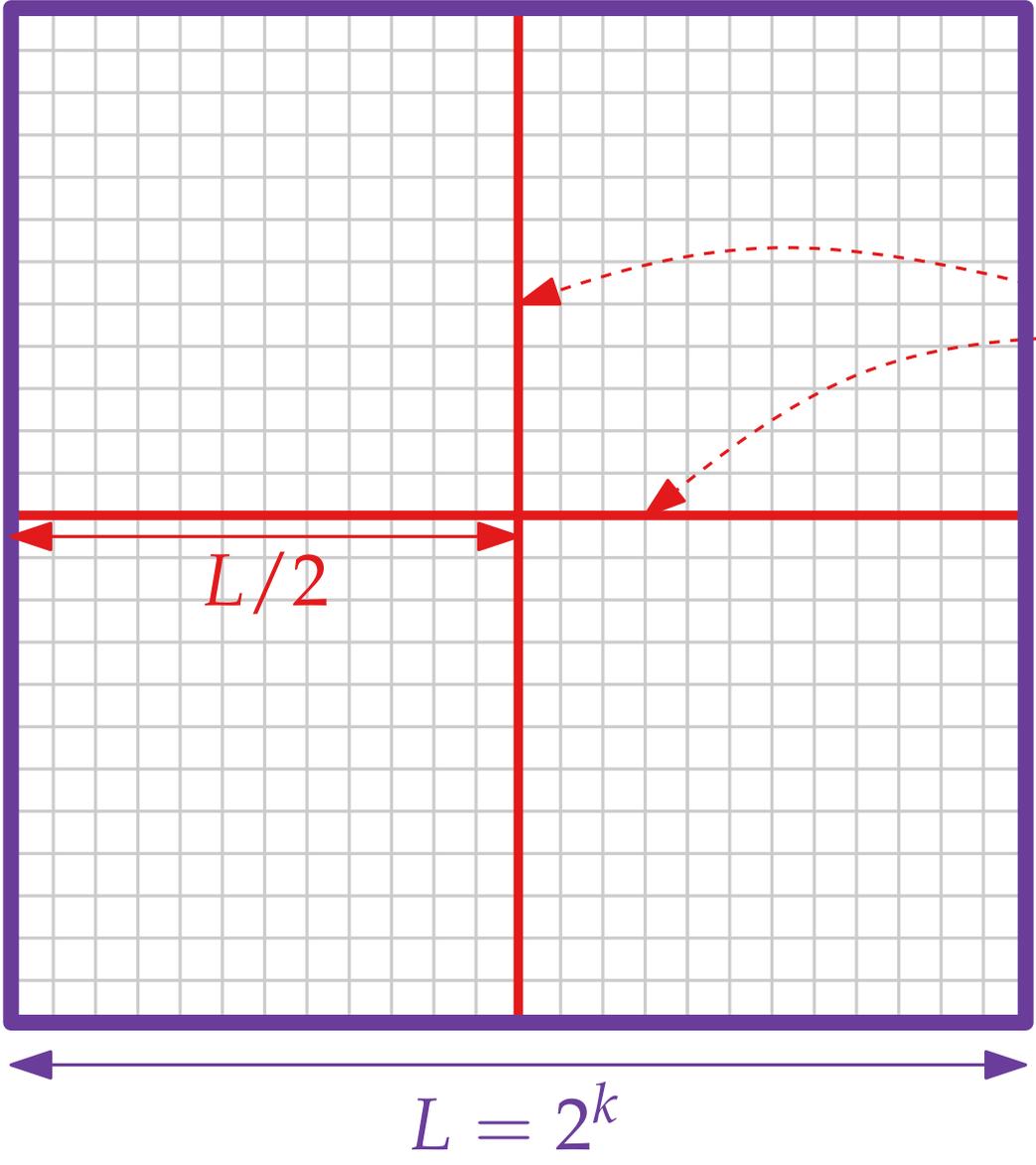


Level 0



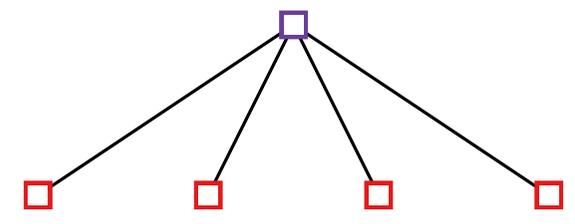
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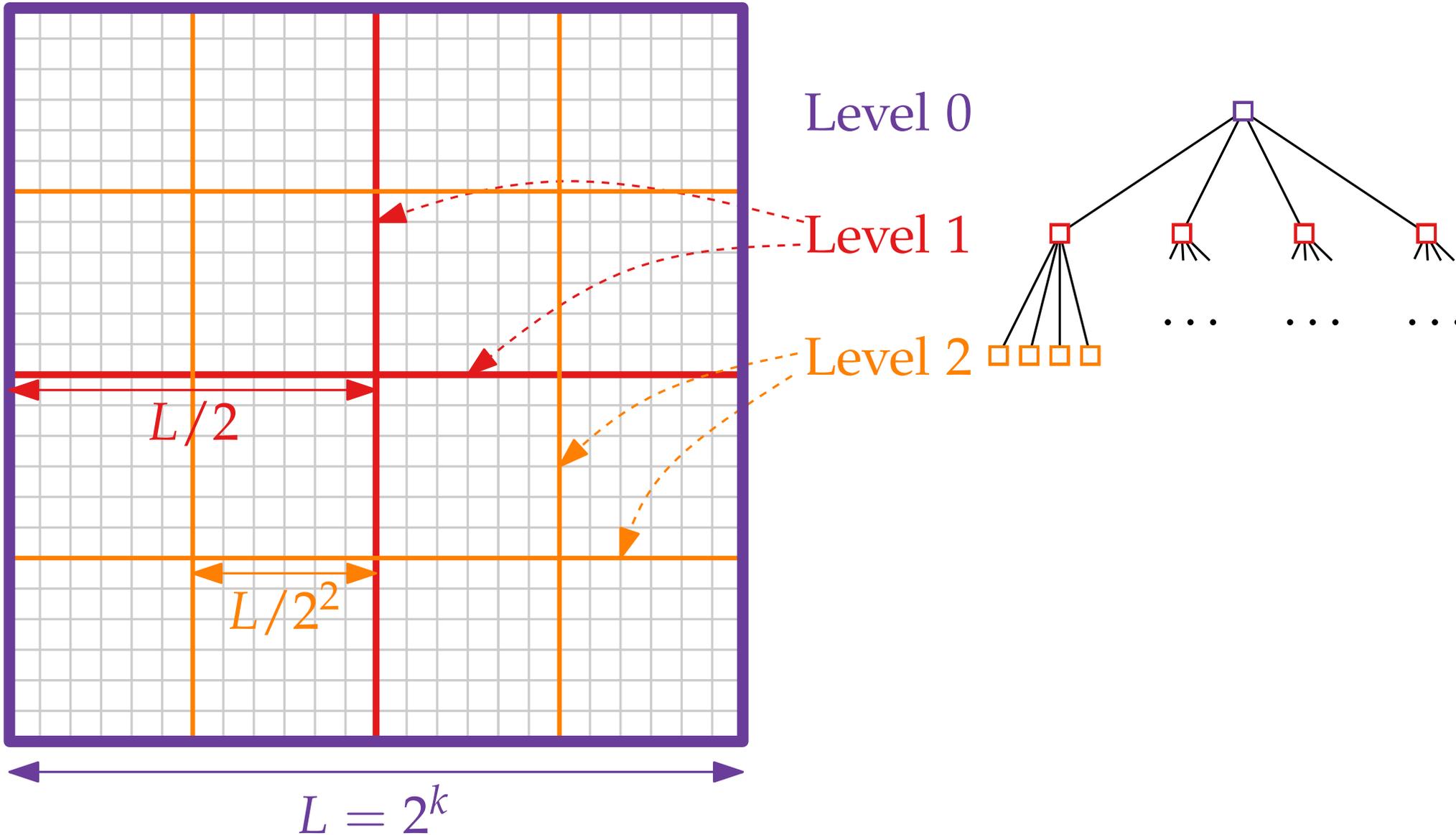


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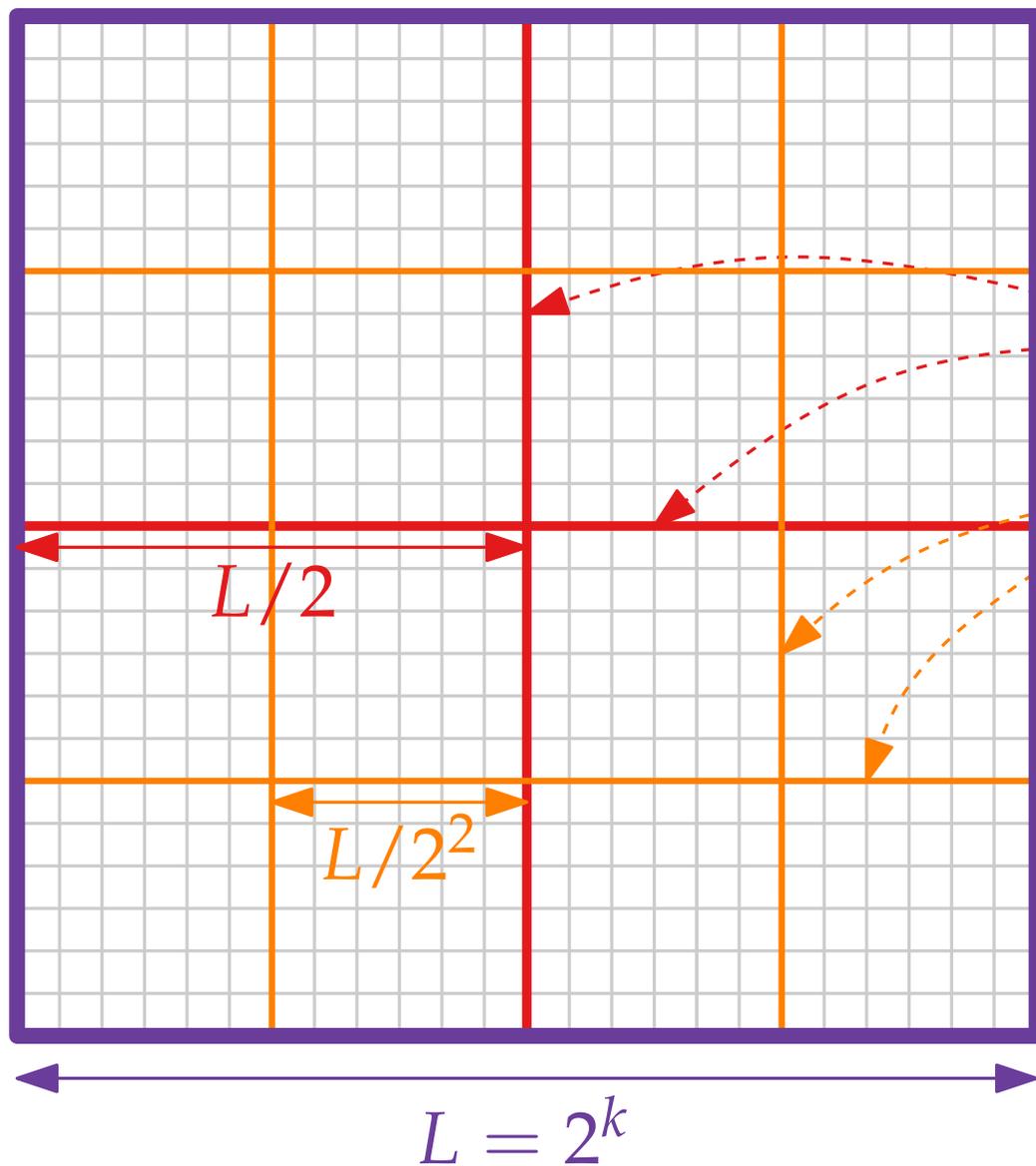
Level 1



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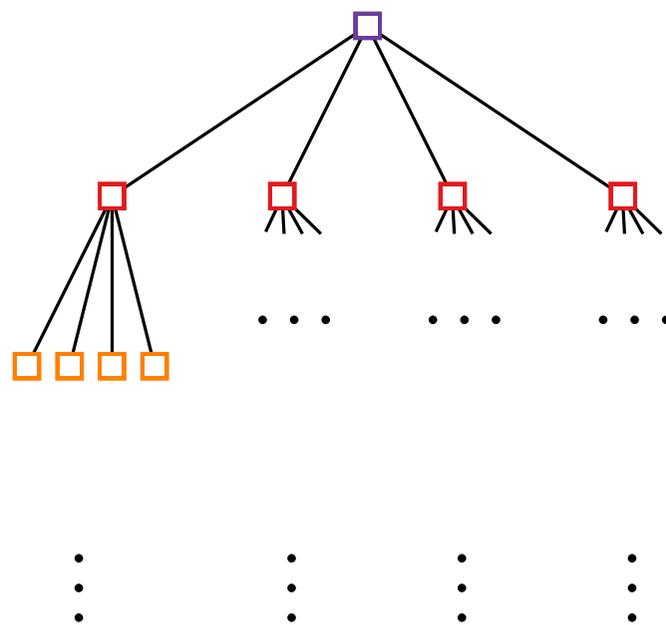
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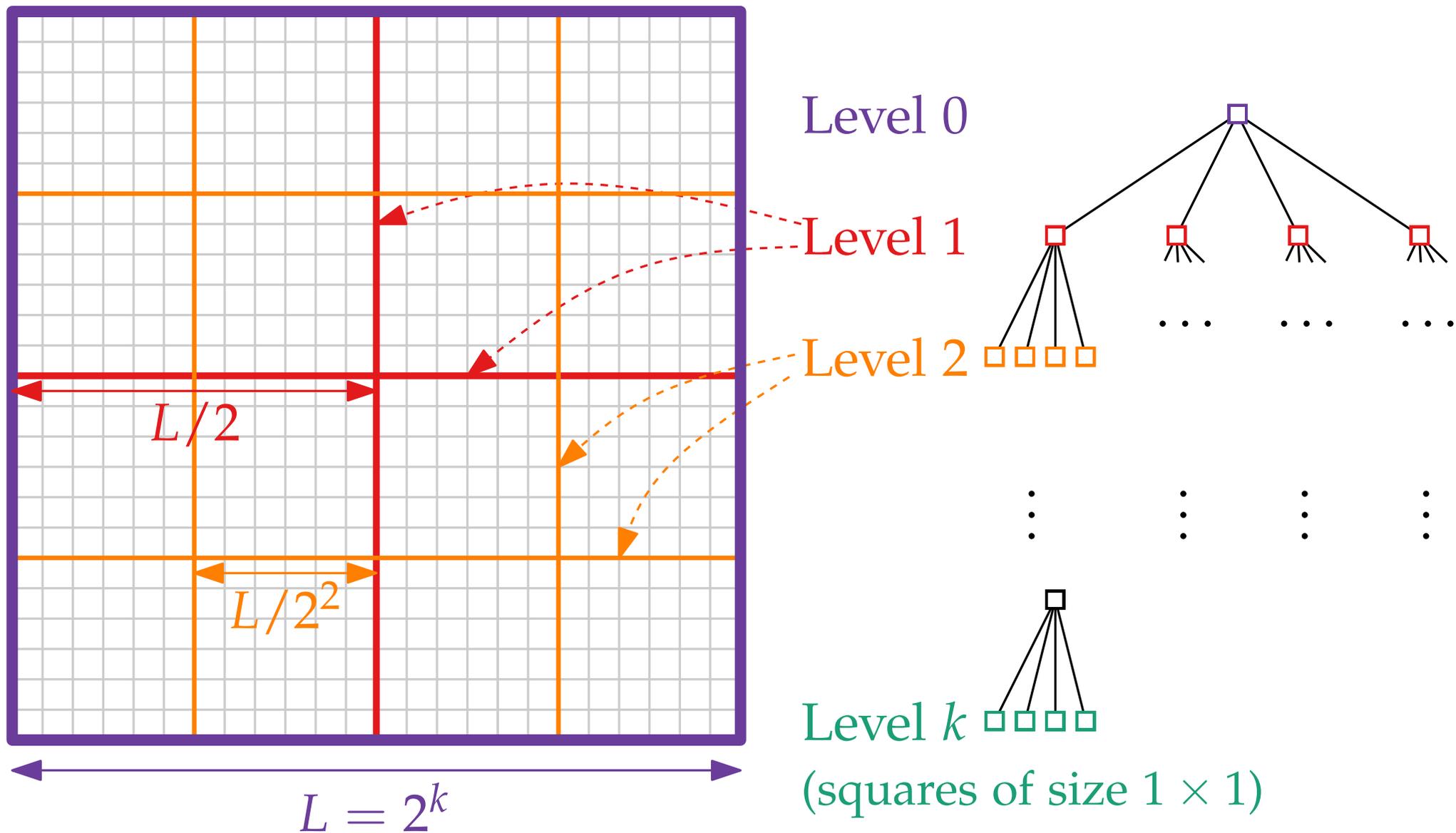
Level 2

Level  $k$

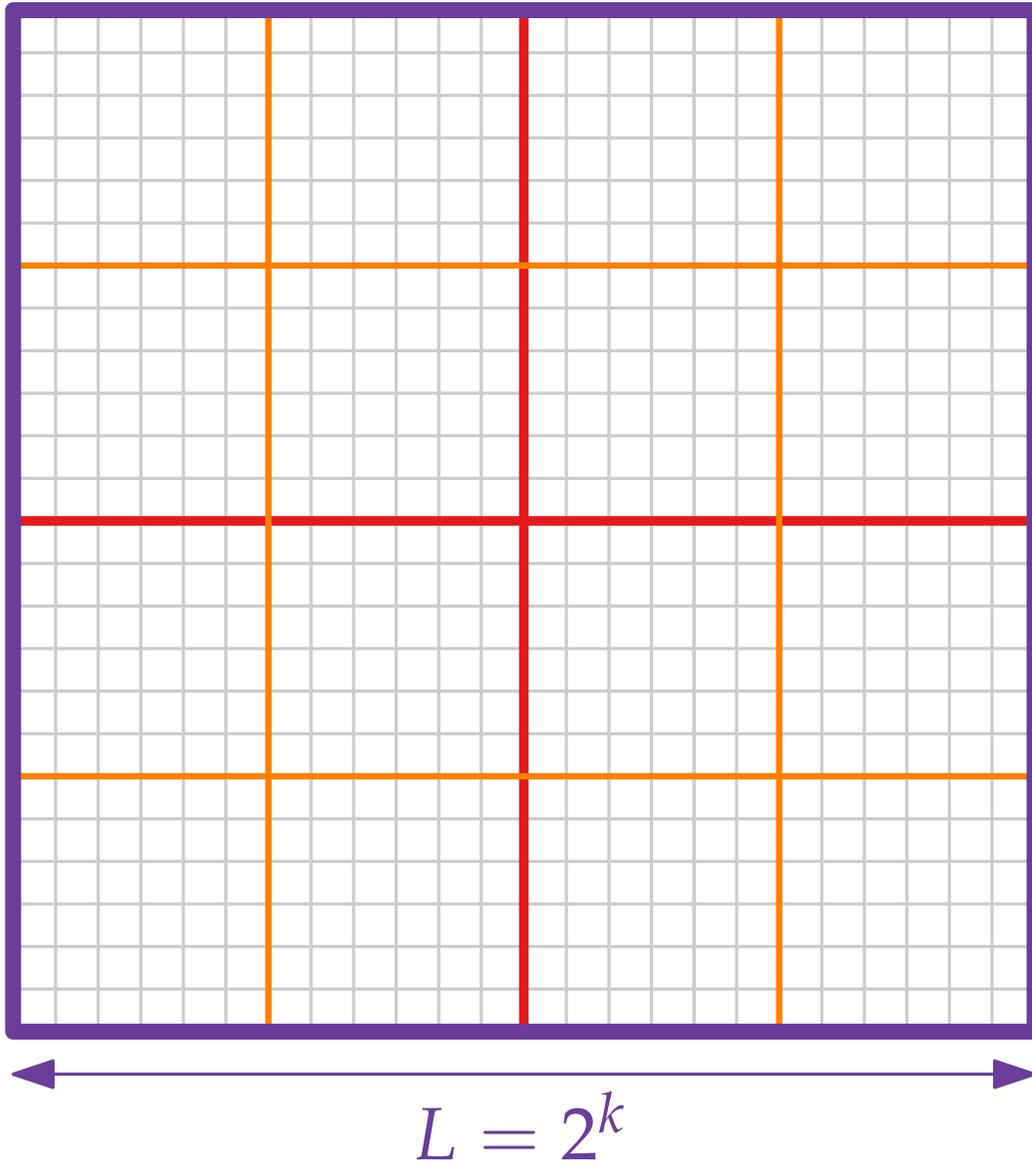
(squares of size )



# Basic Dissection

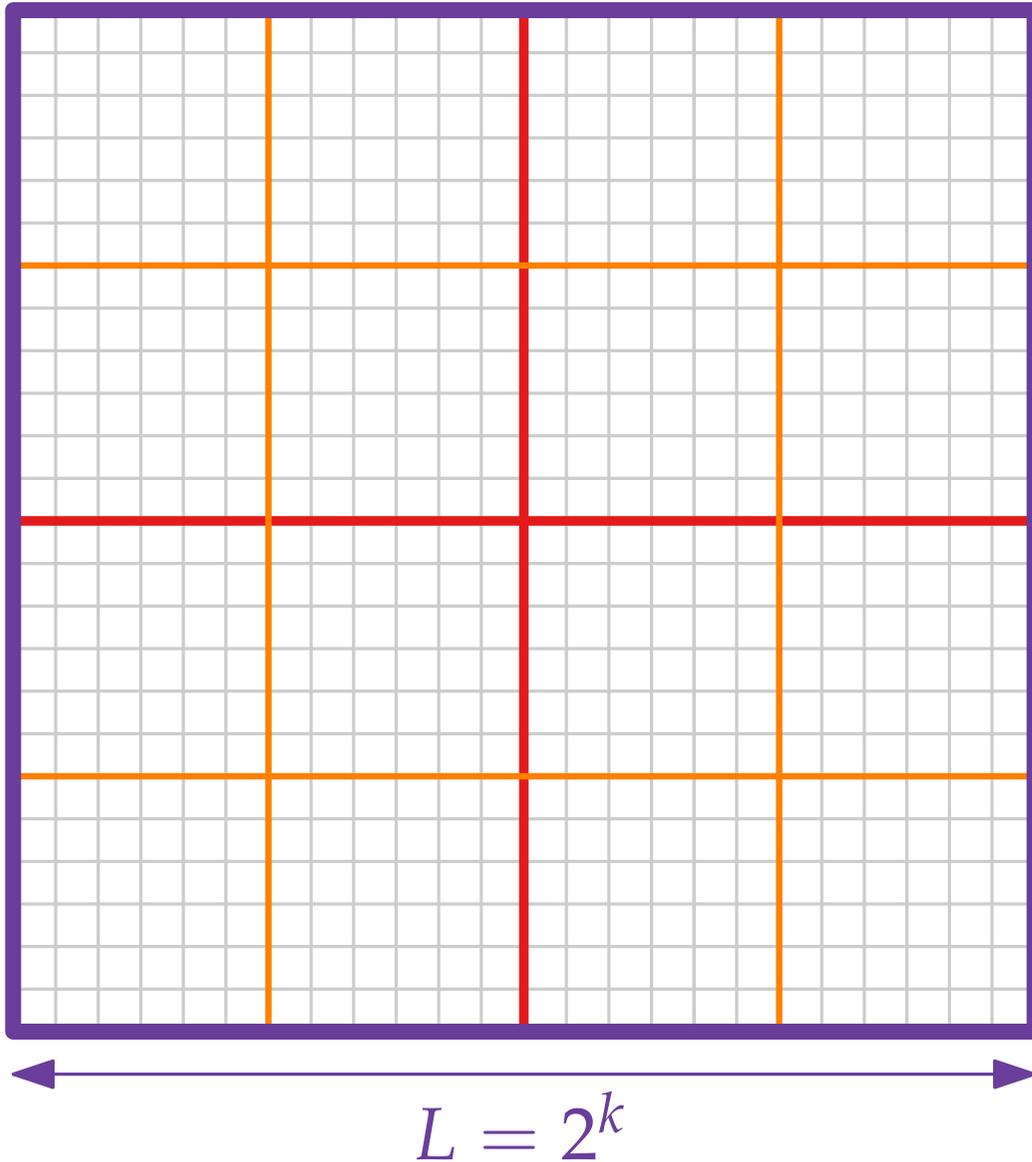


# Portals



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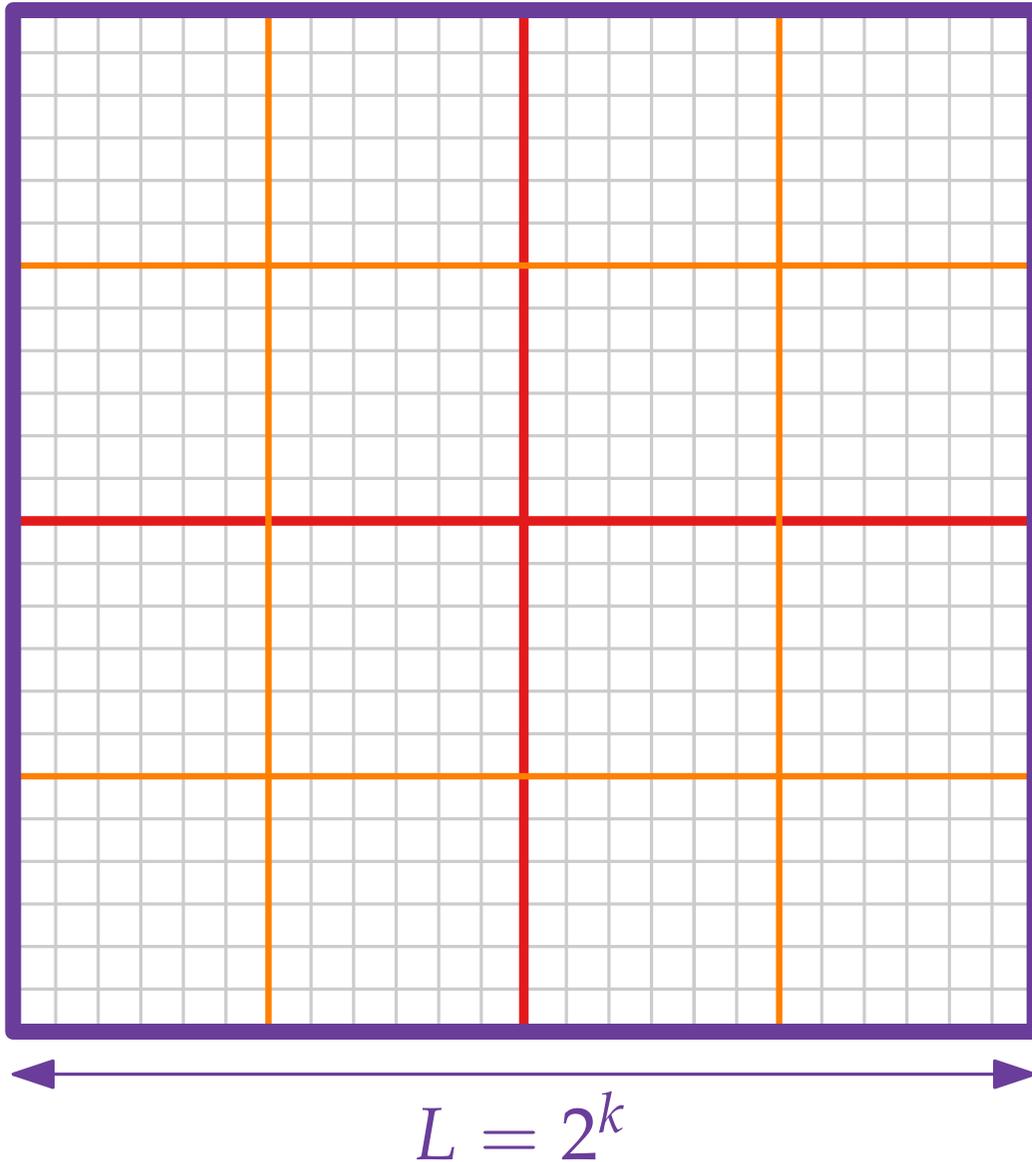
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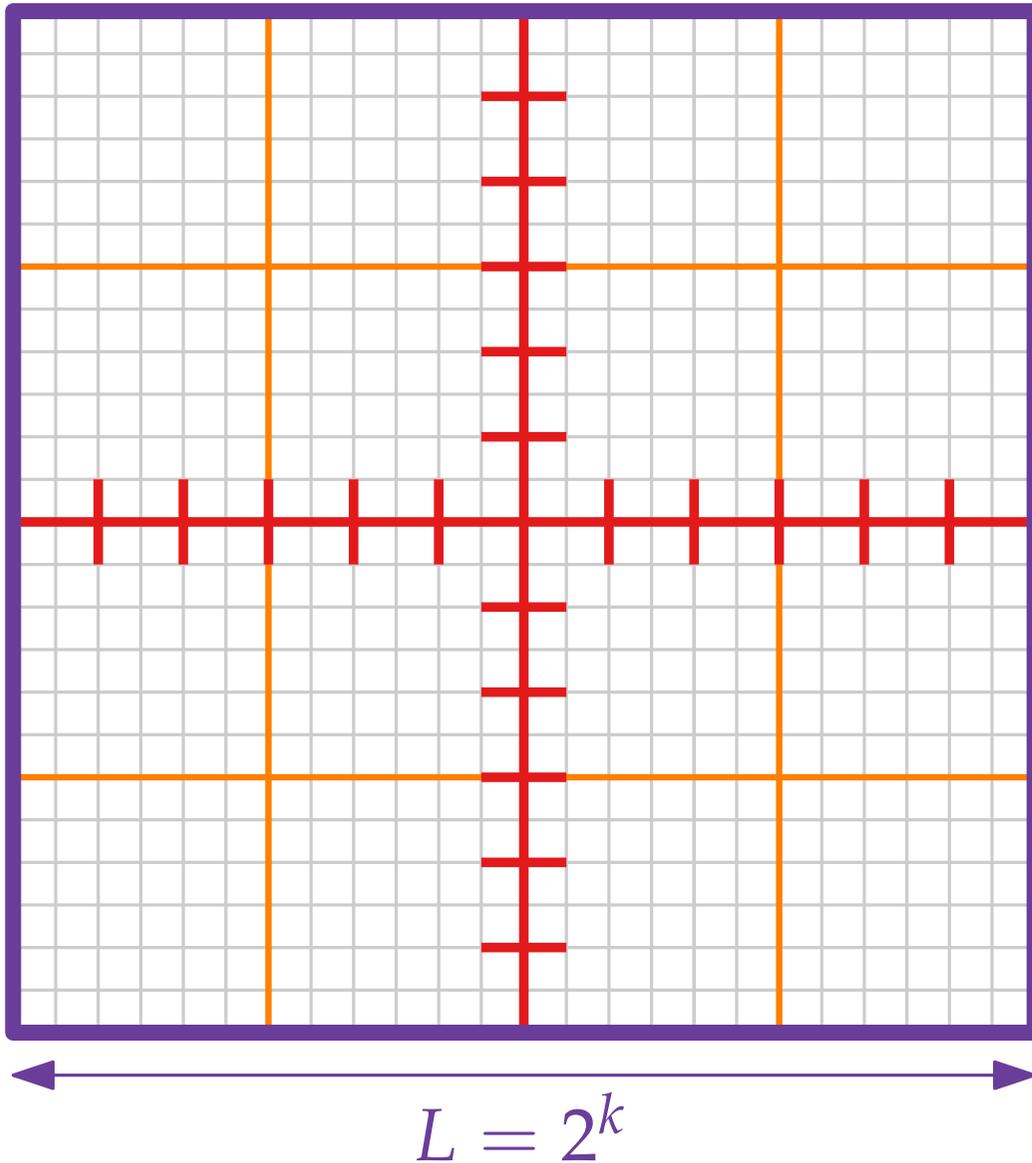
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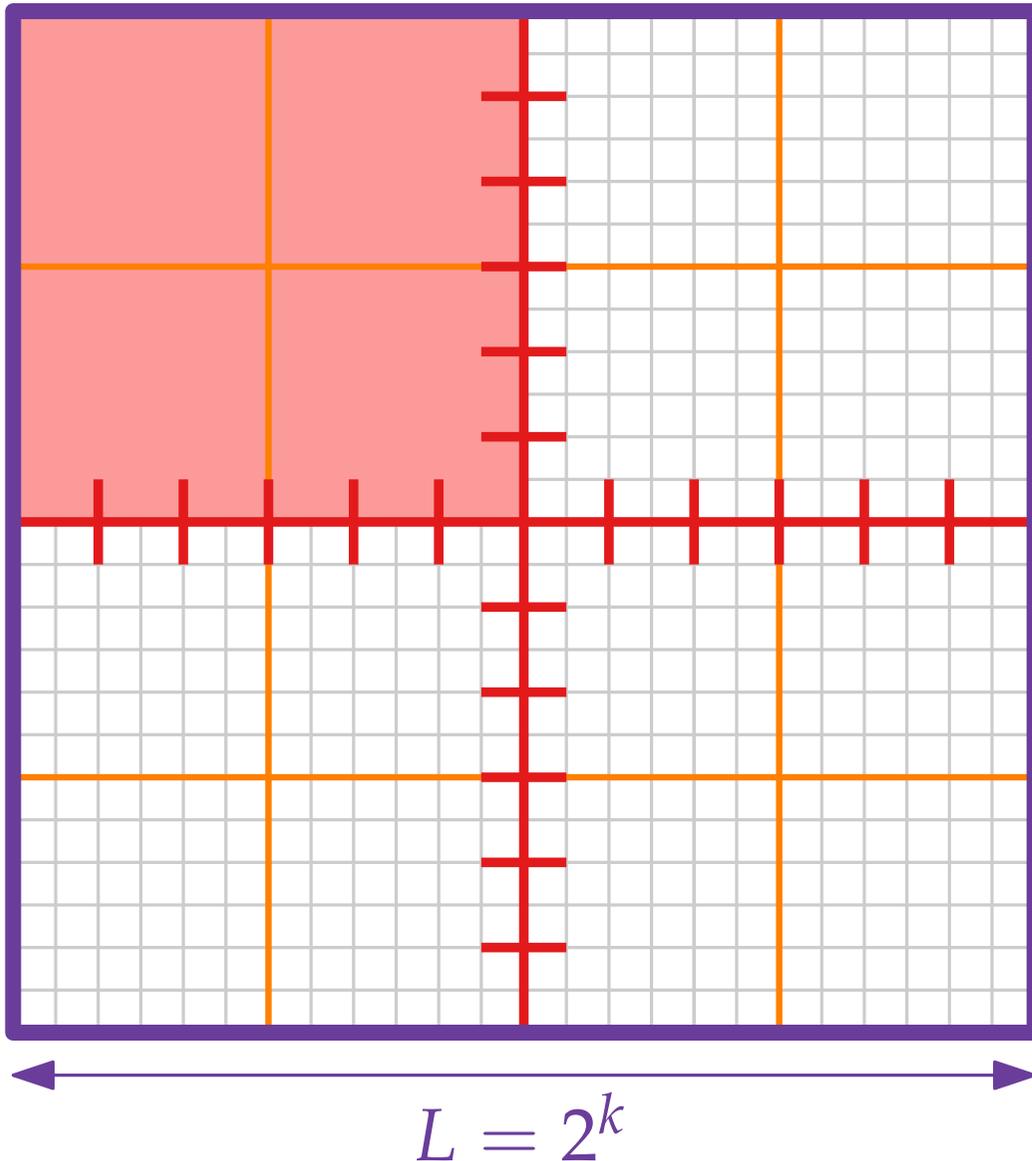


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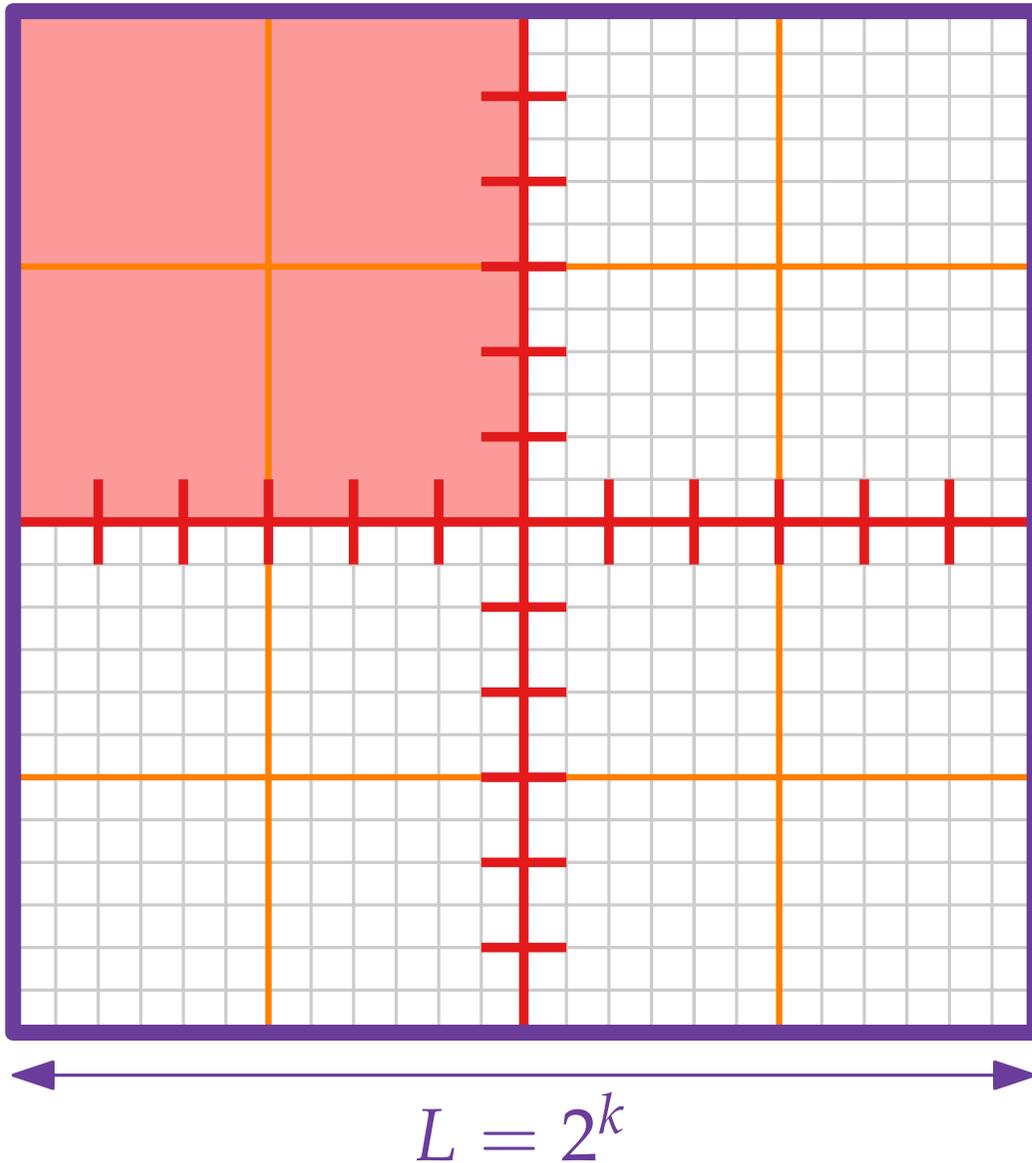


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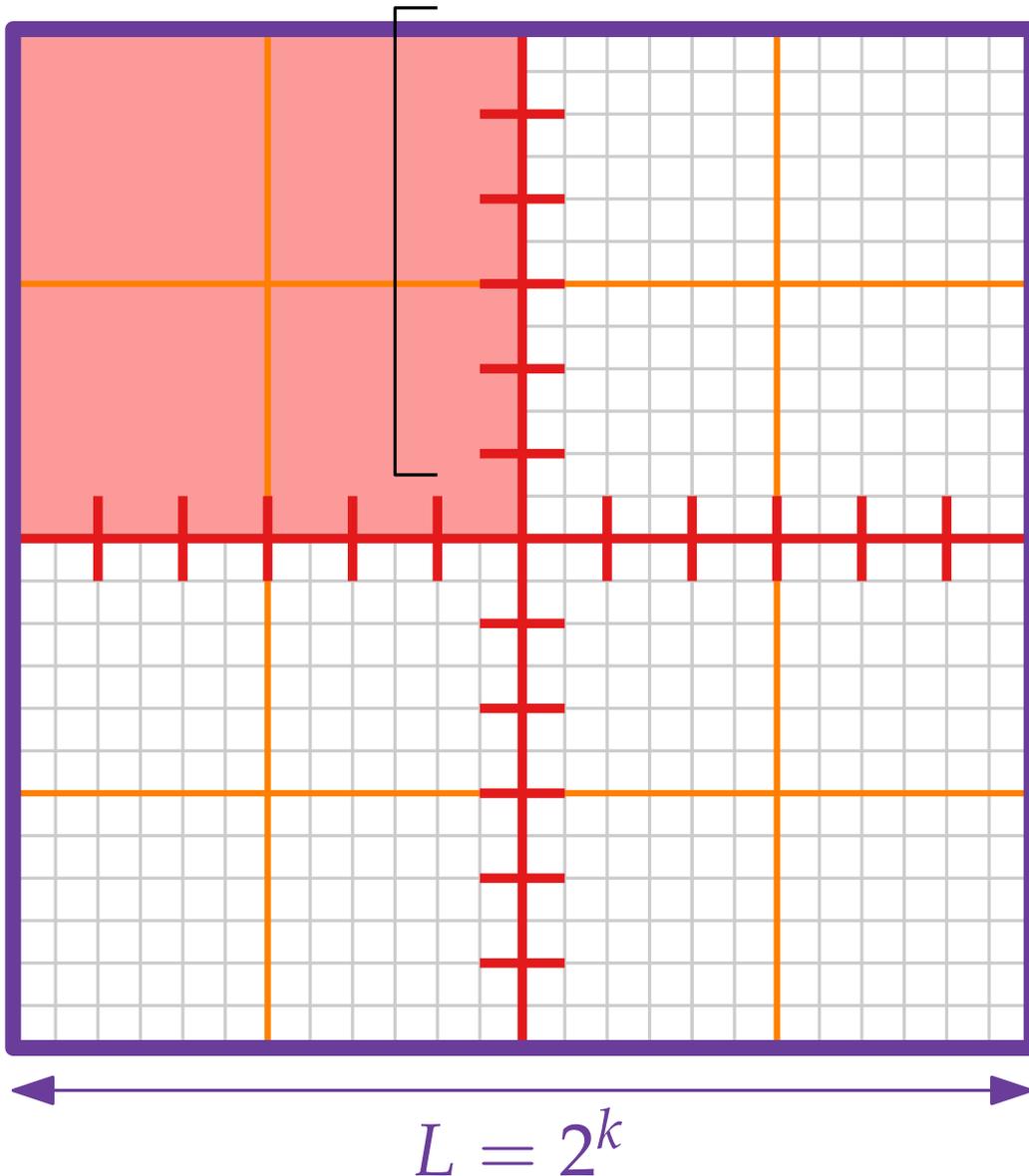


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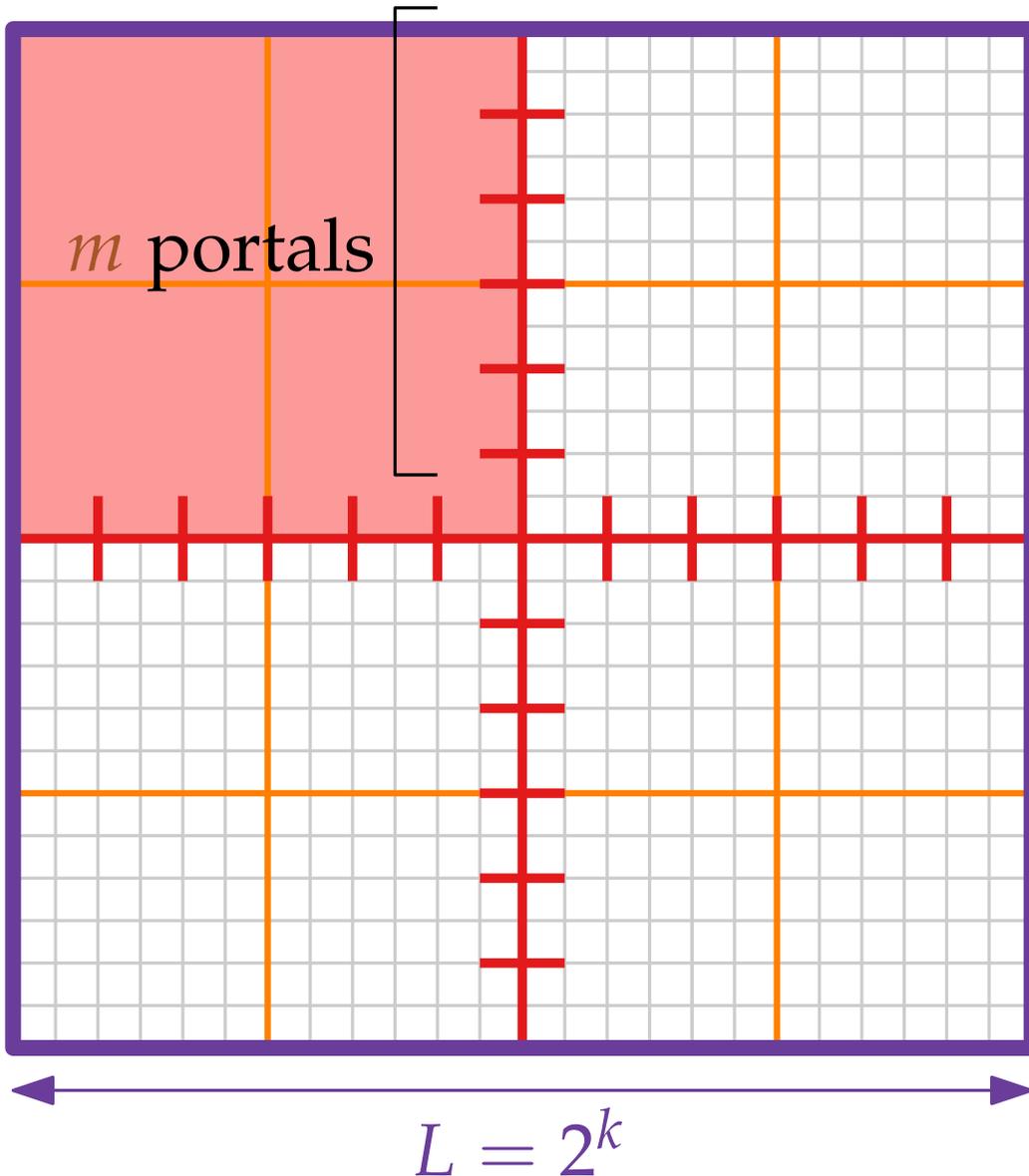


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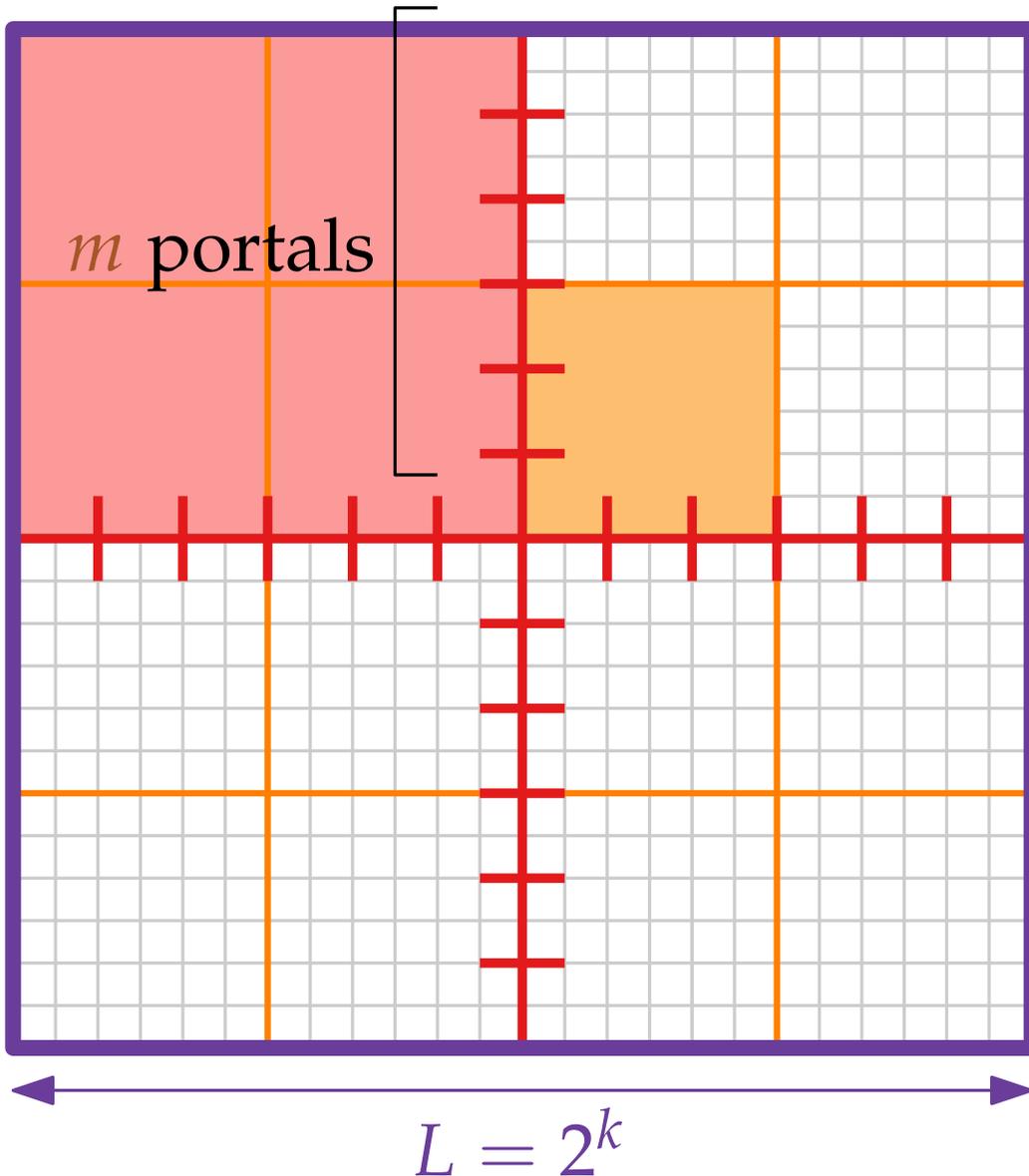


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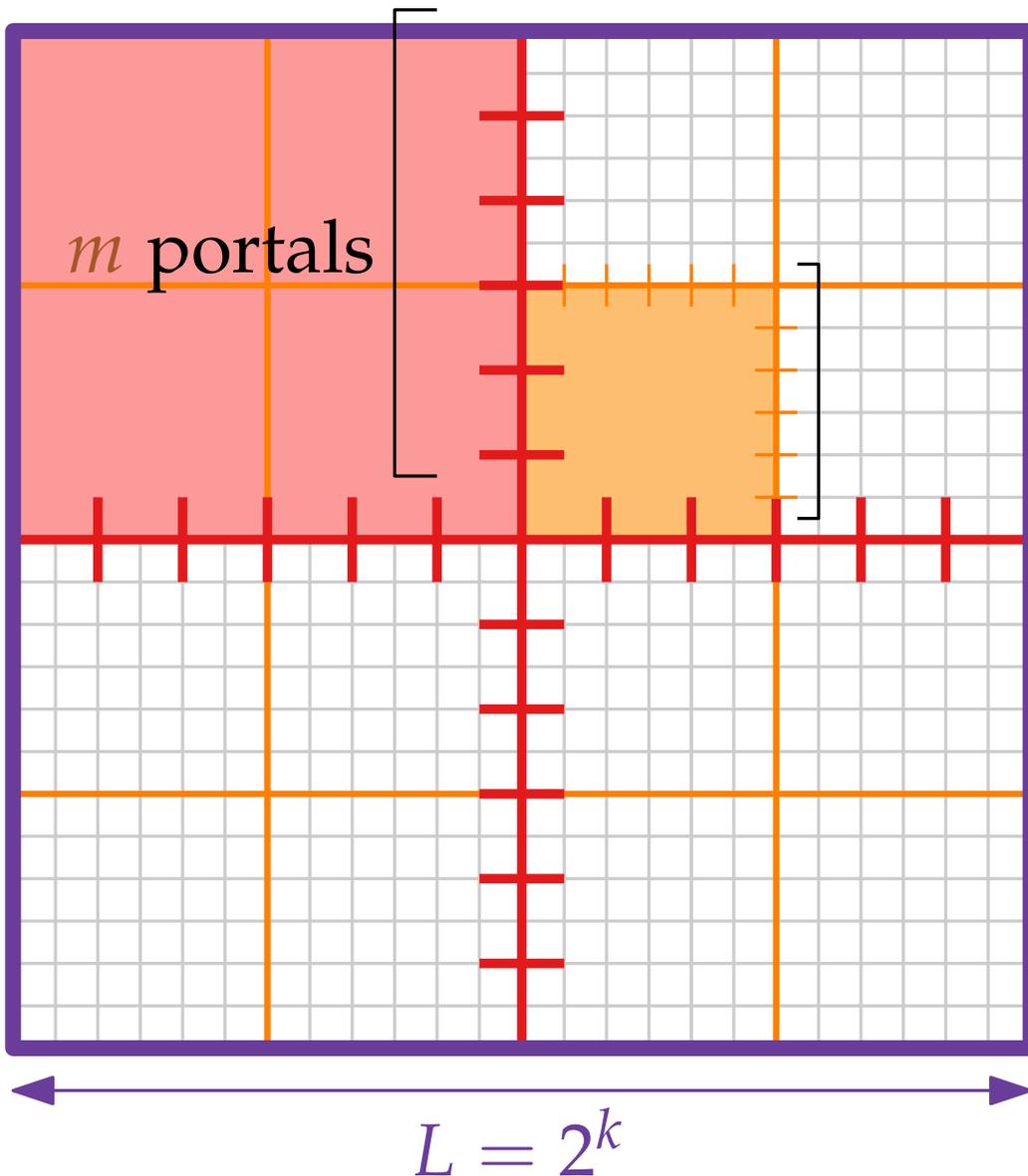


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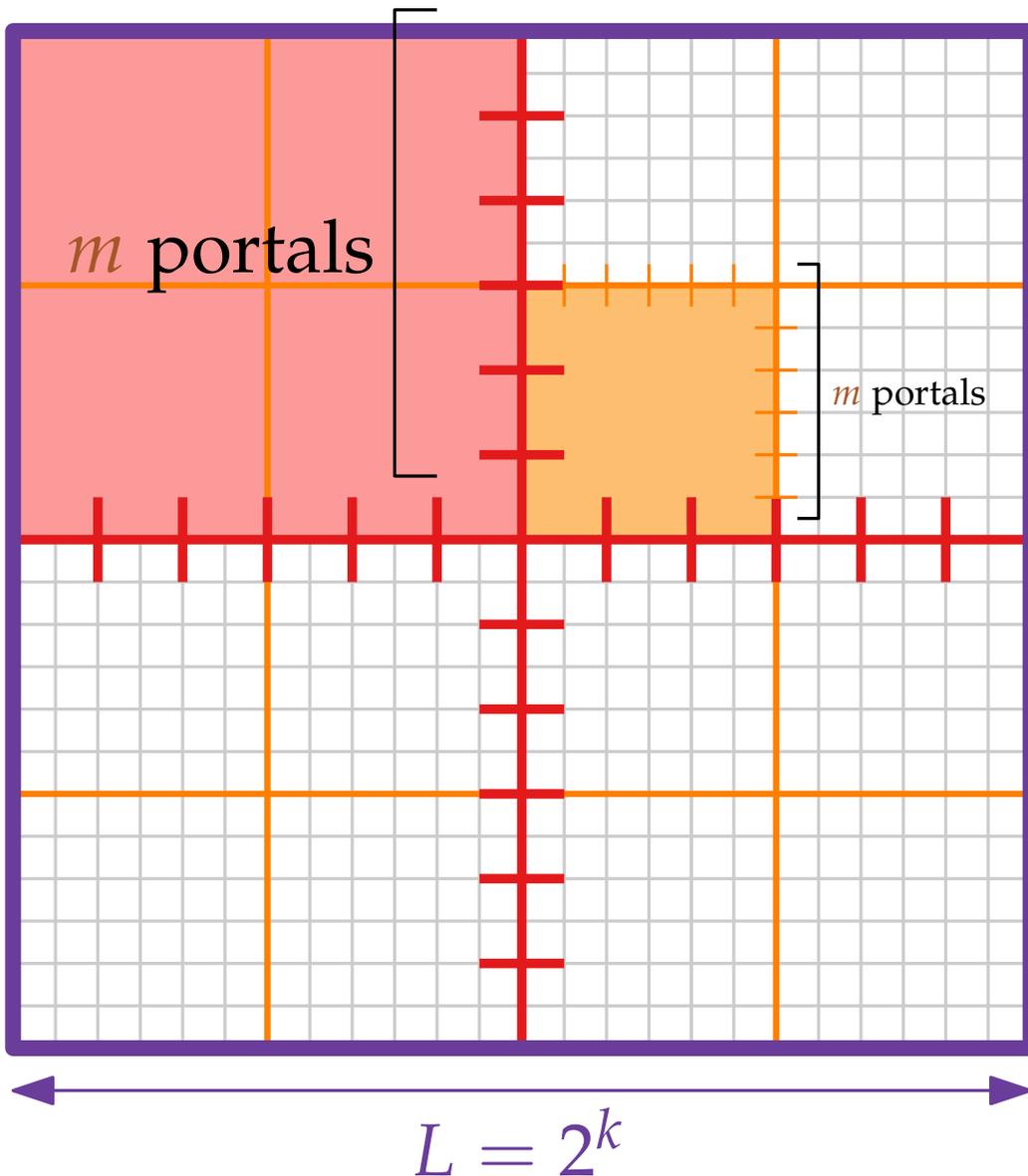


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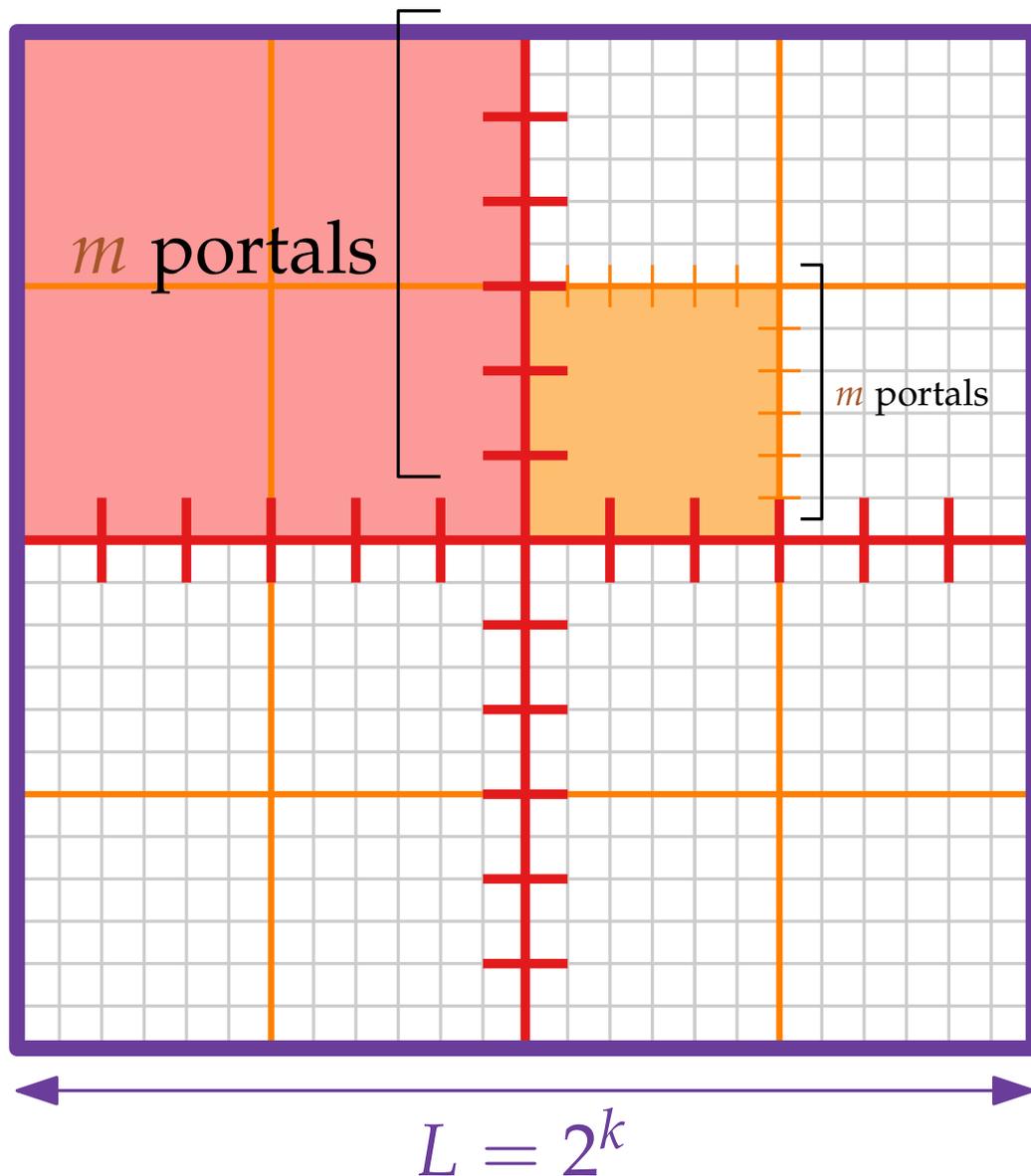


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# Portals



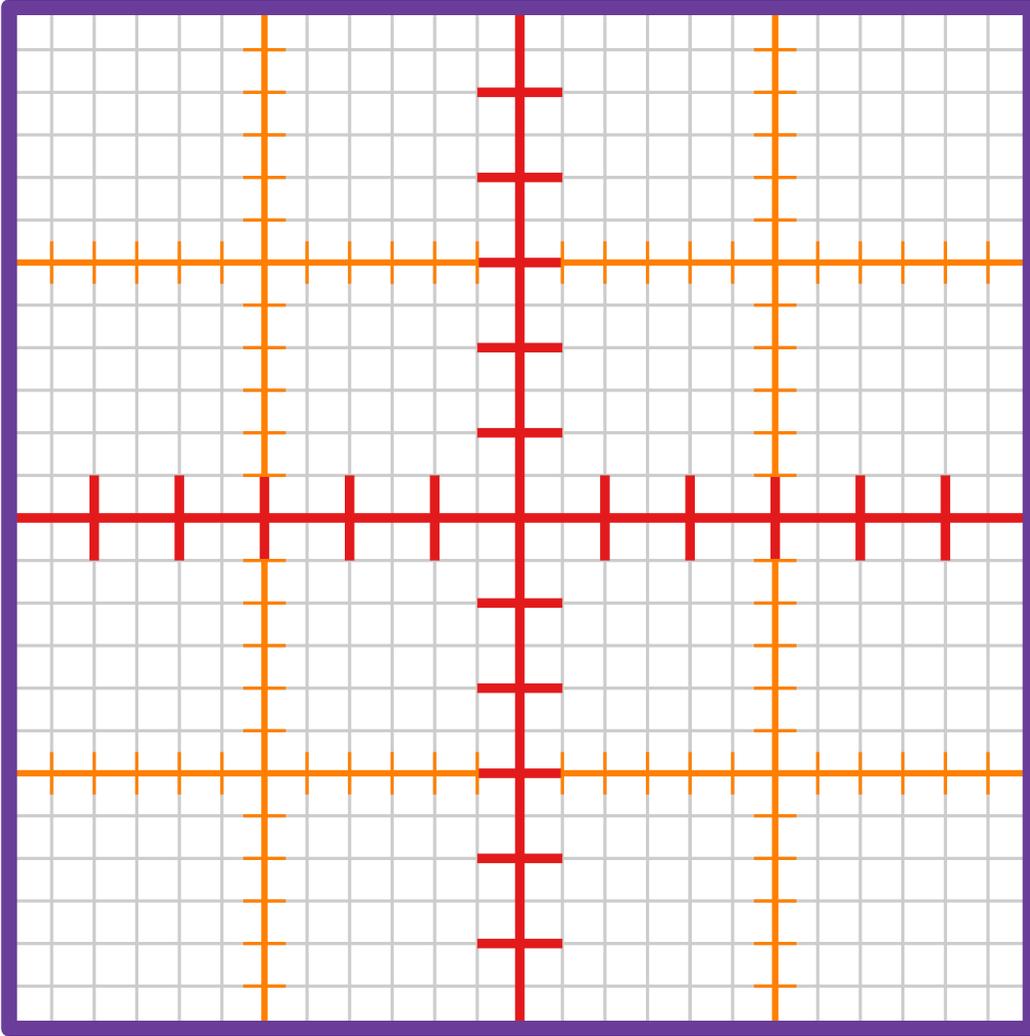
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- Every level- $i$  square has size  $L/2^i \times L/2^i$ .
- A level- $i$  square has  $\leq 4m$  portals on its boundary.

# Approximation Algorithms

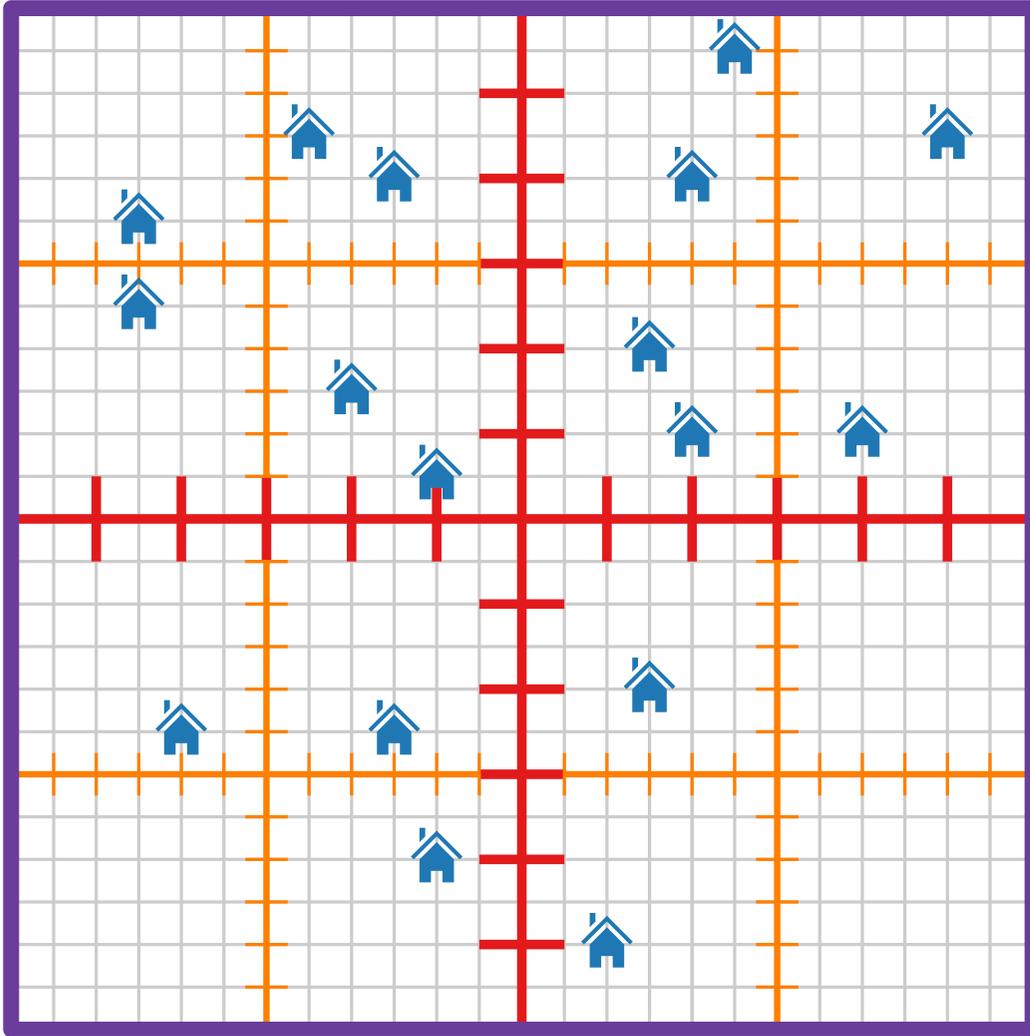
## Lecture 9: A PTAS for EUCLIDEAN TSP

### Part III: Well-Behaved Tours

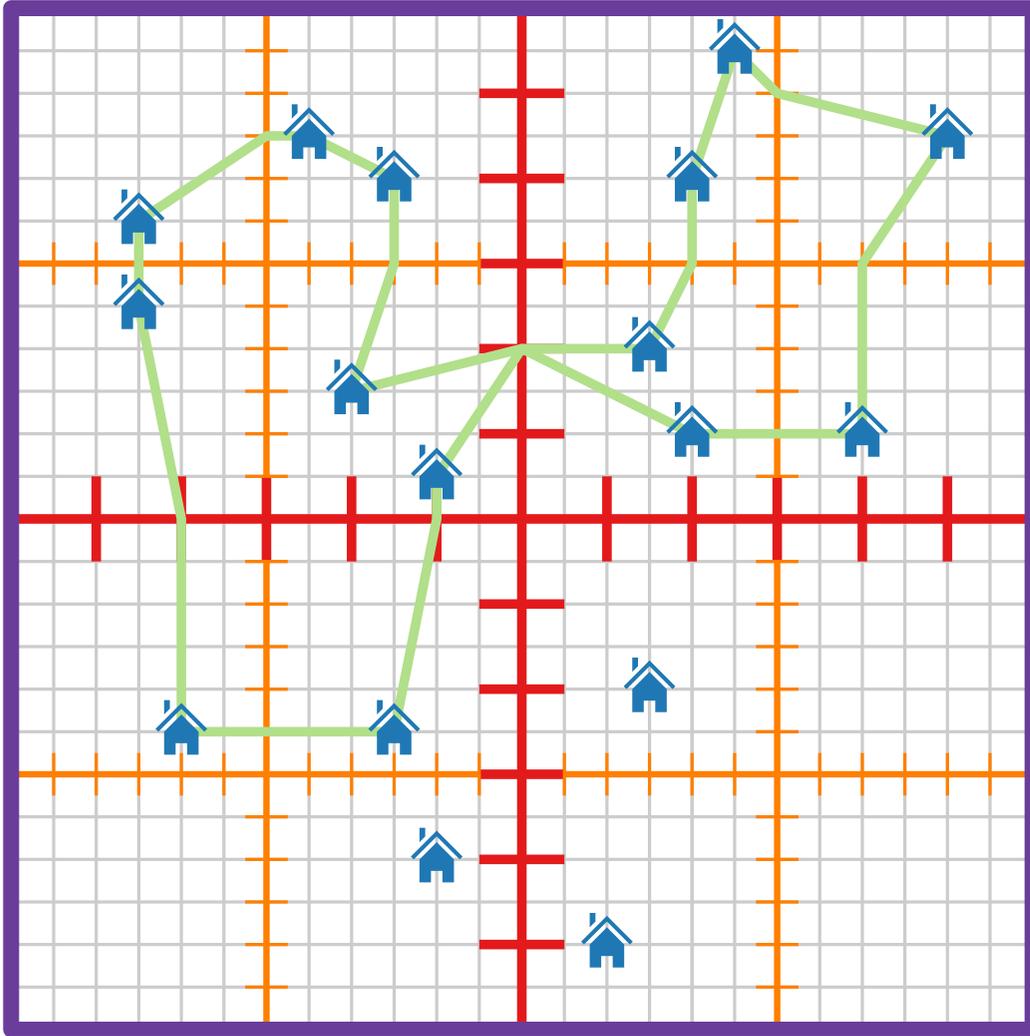
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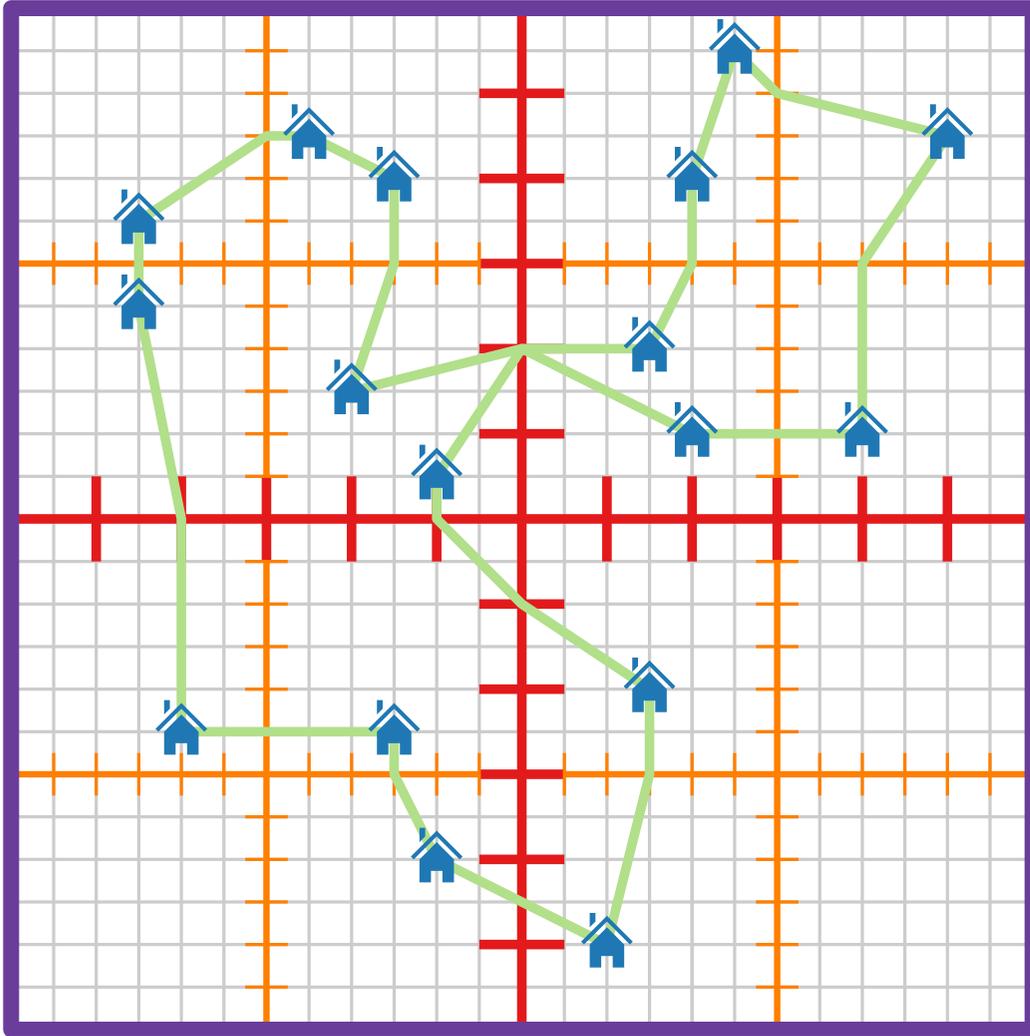
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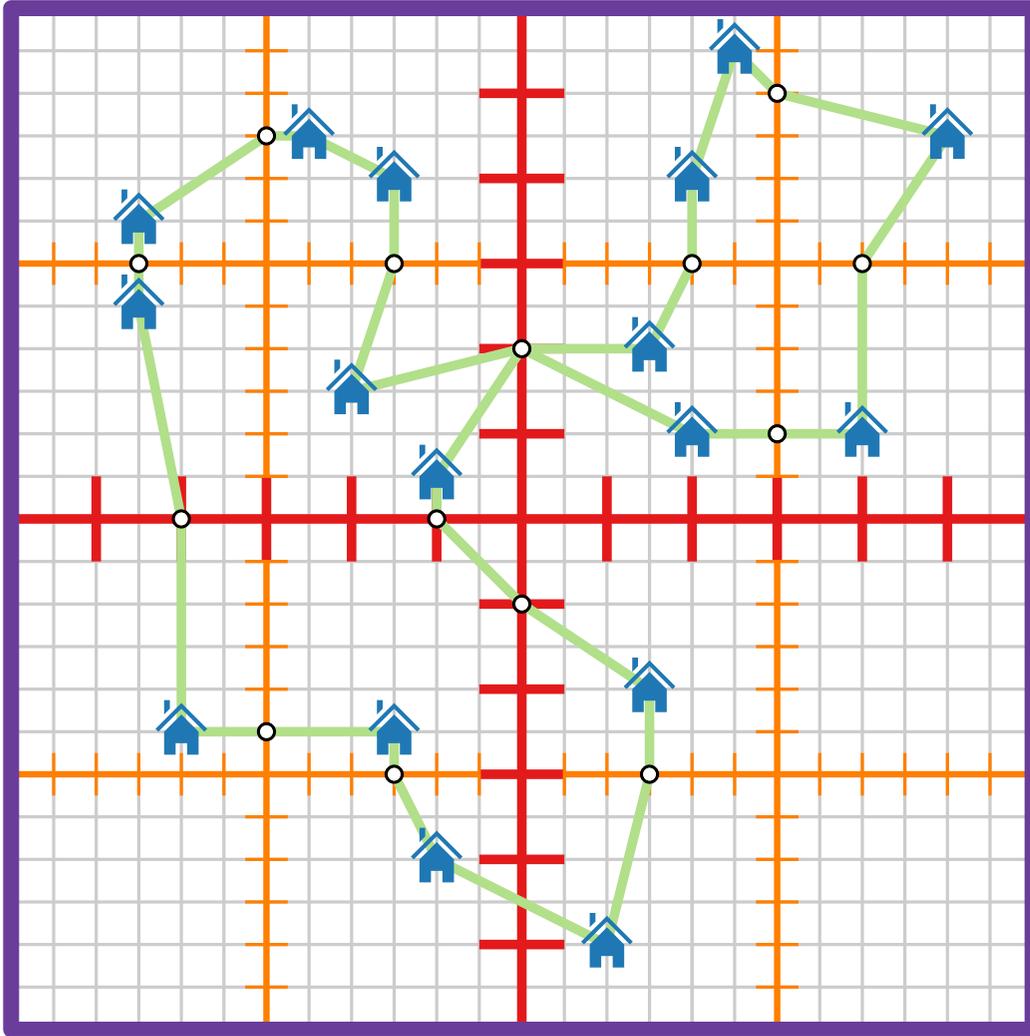
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A tour is *well-behaved* if

- it involves all houses

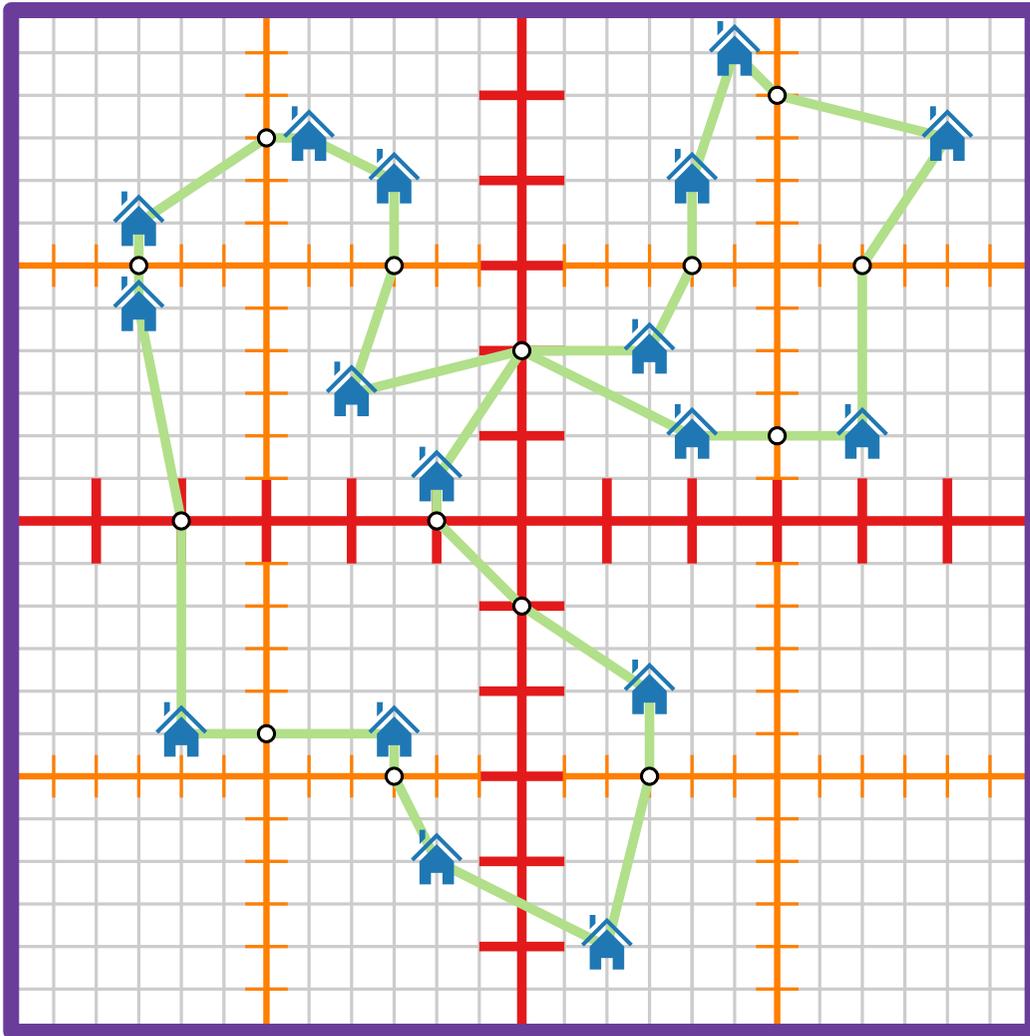
# Well-Behaved Tours



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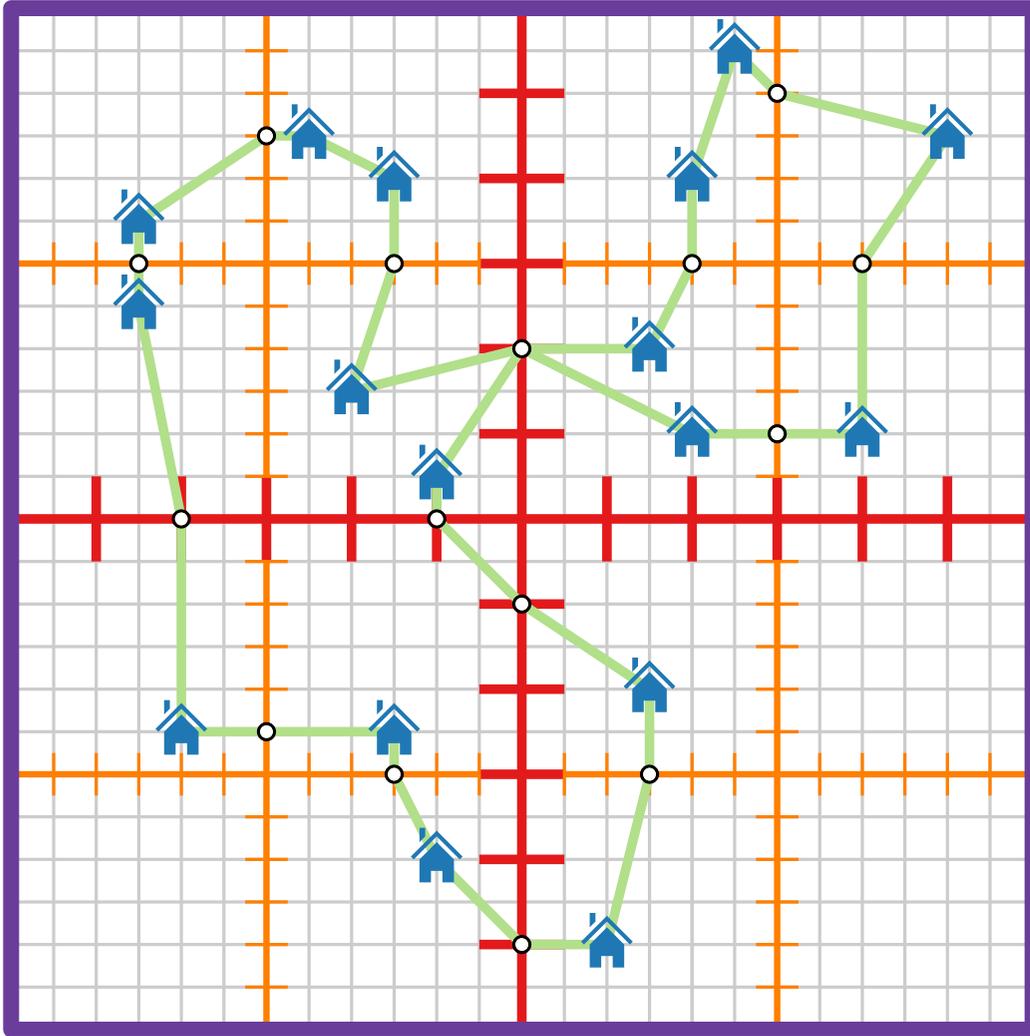
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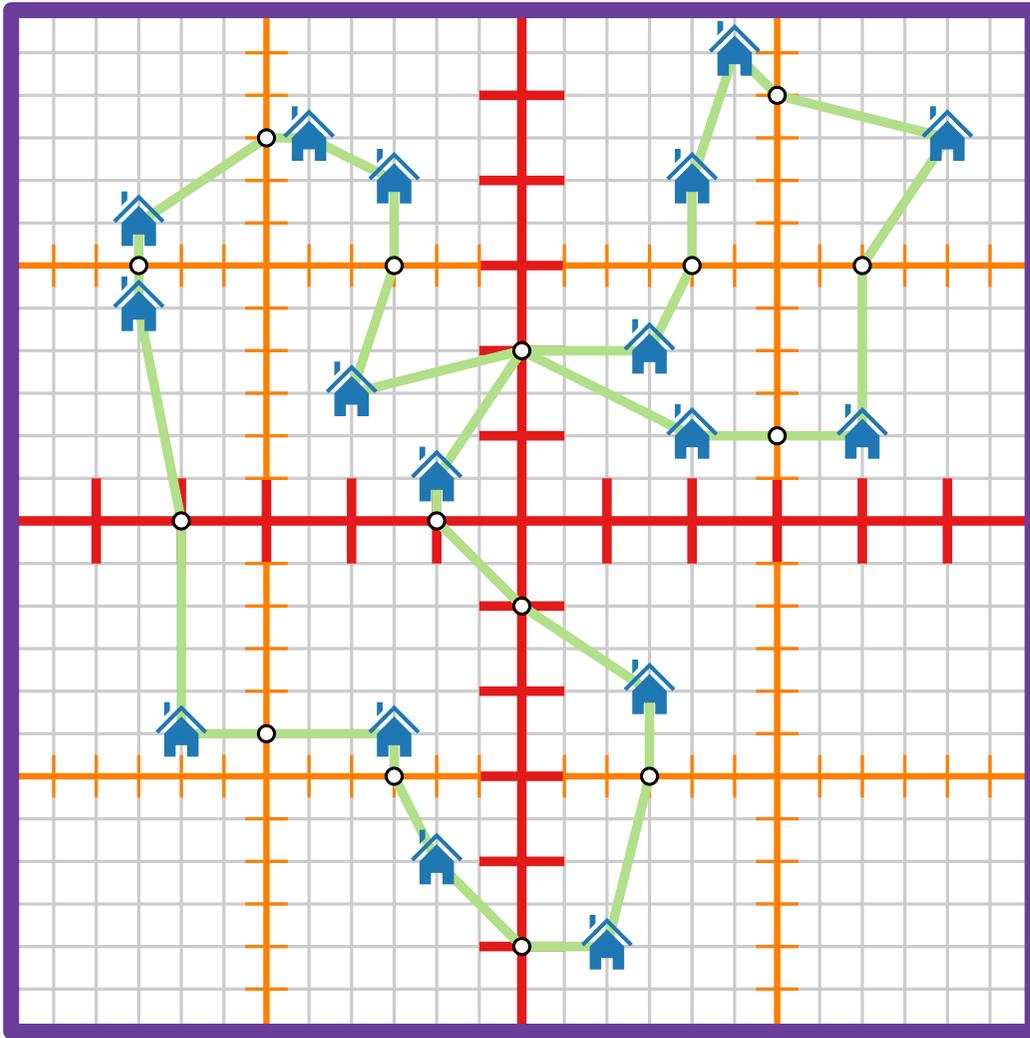
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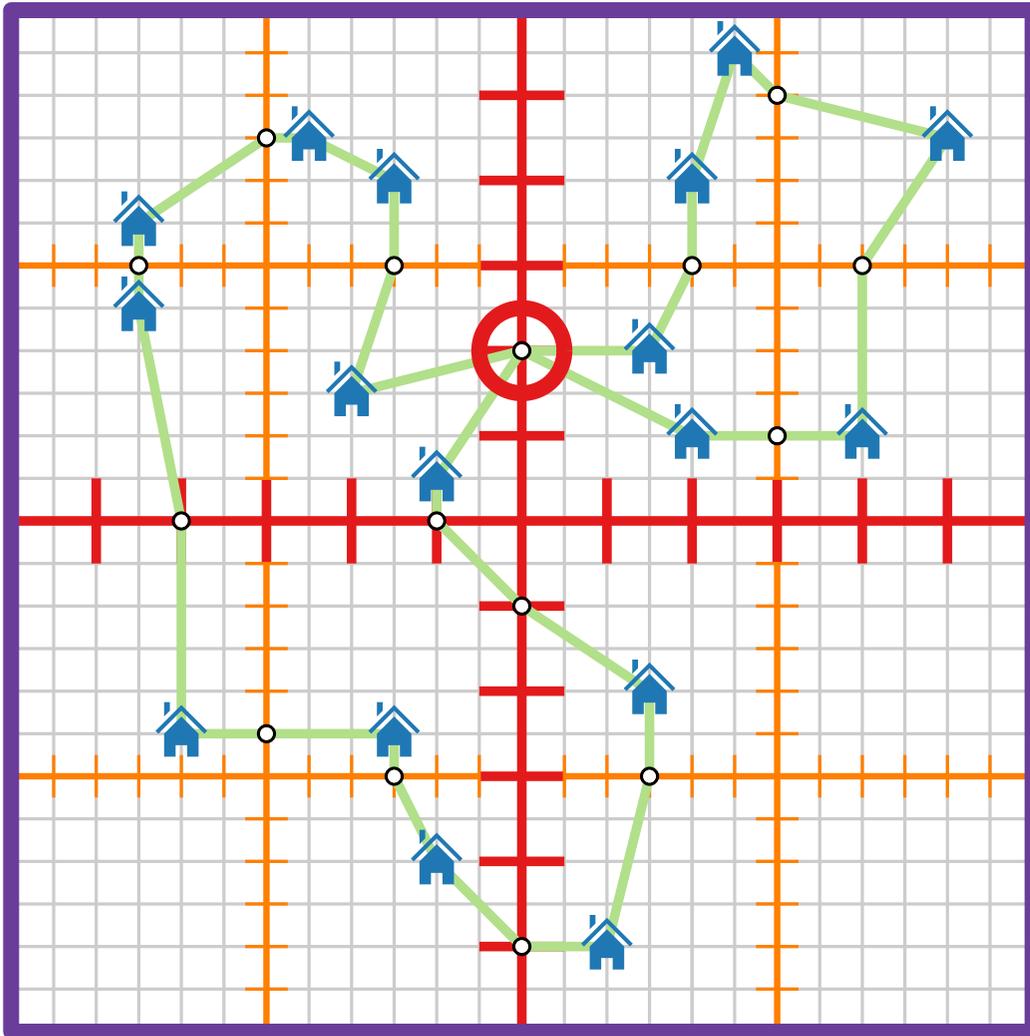
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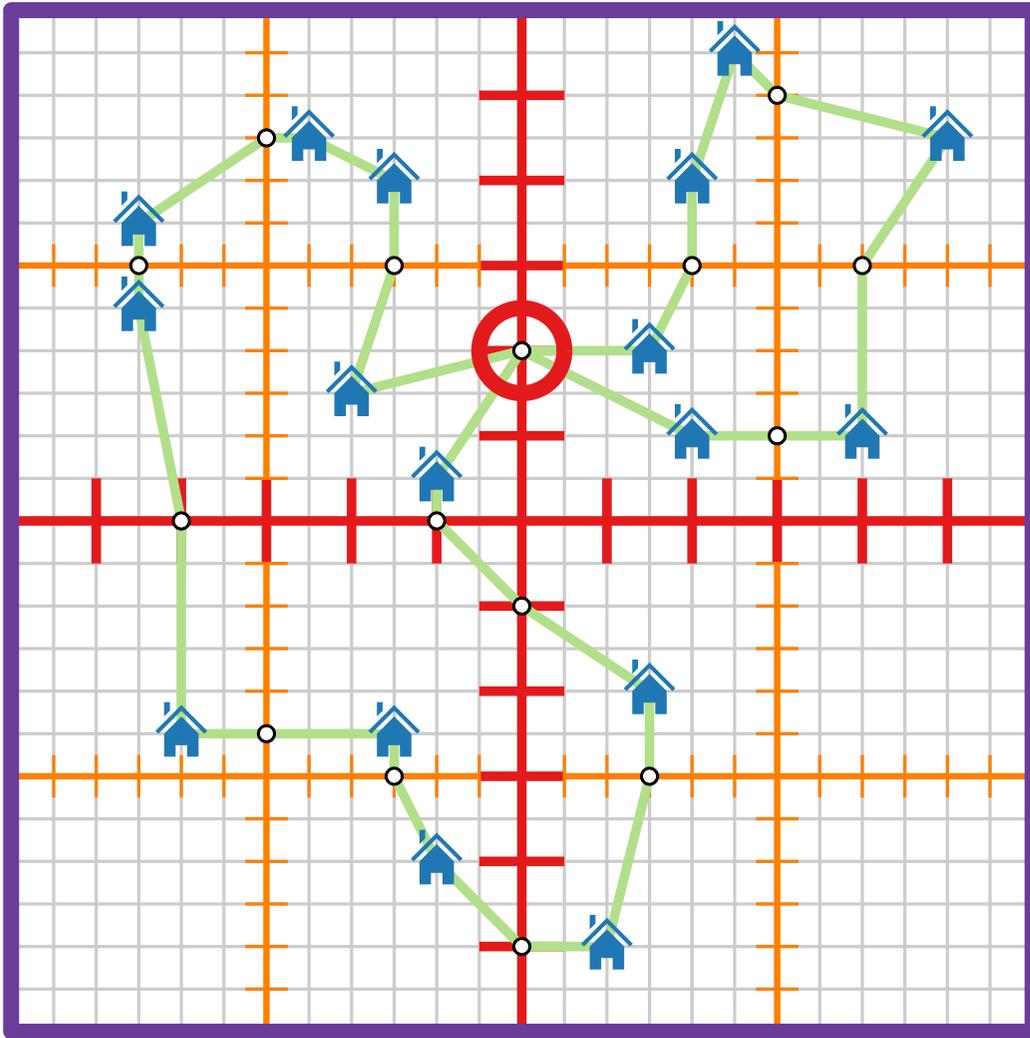
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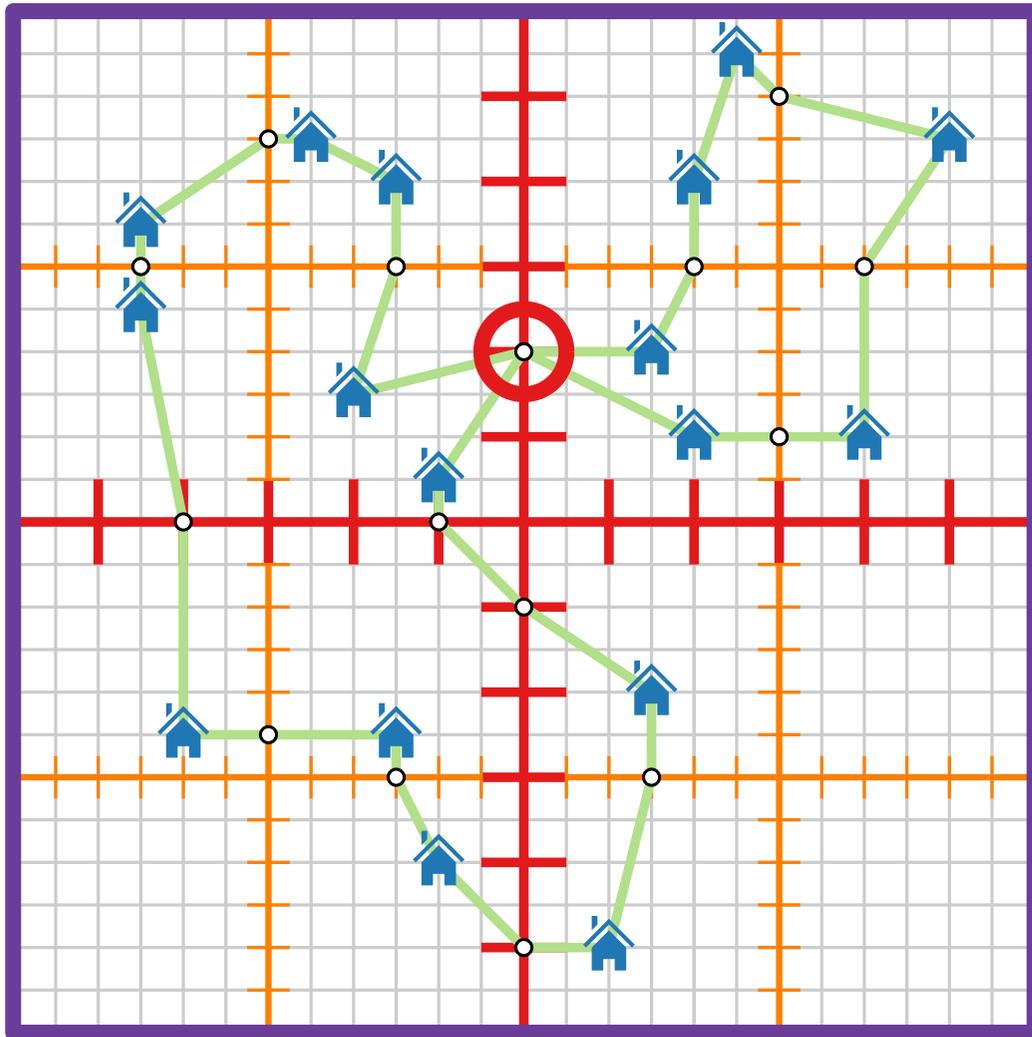


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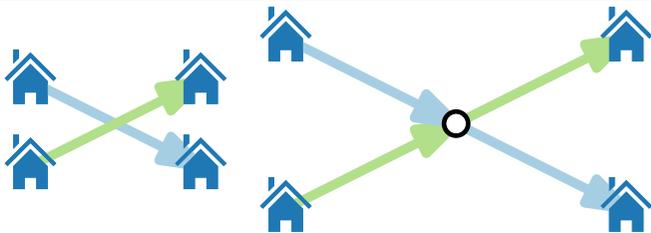
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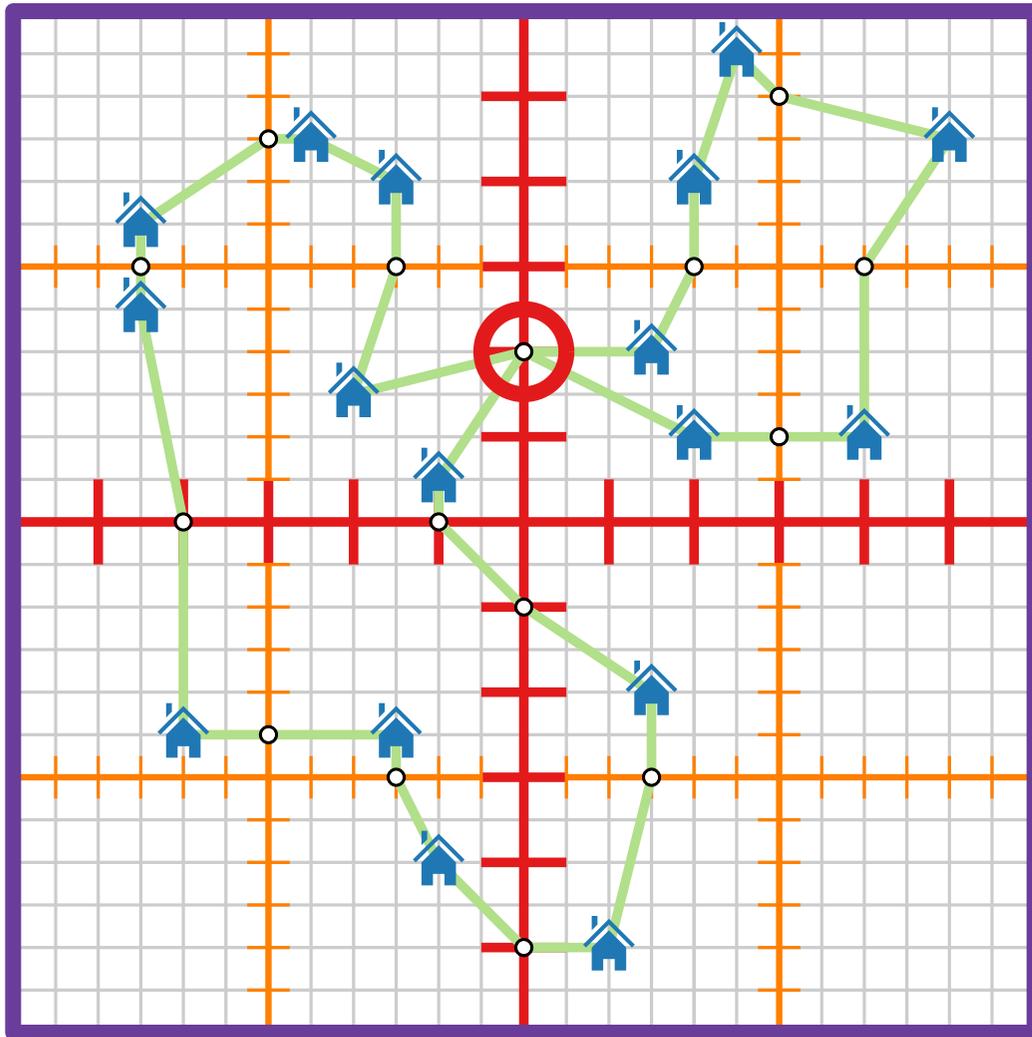
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Crossing



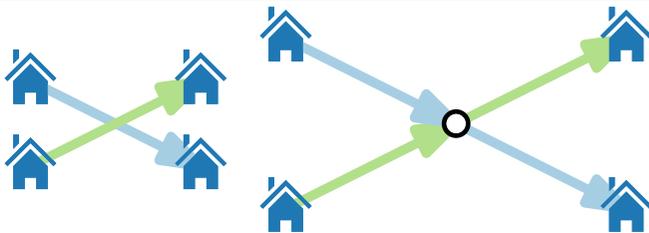
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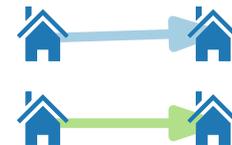
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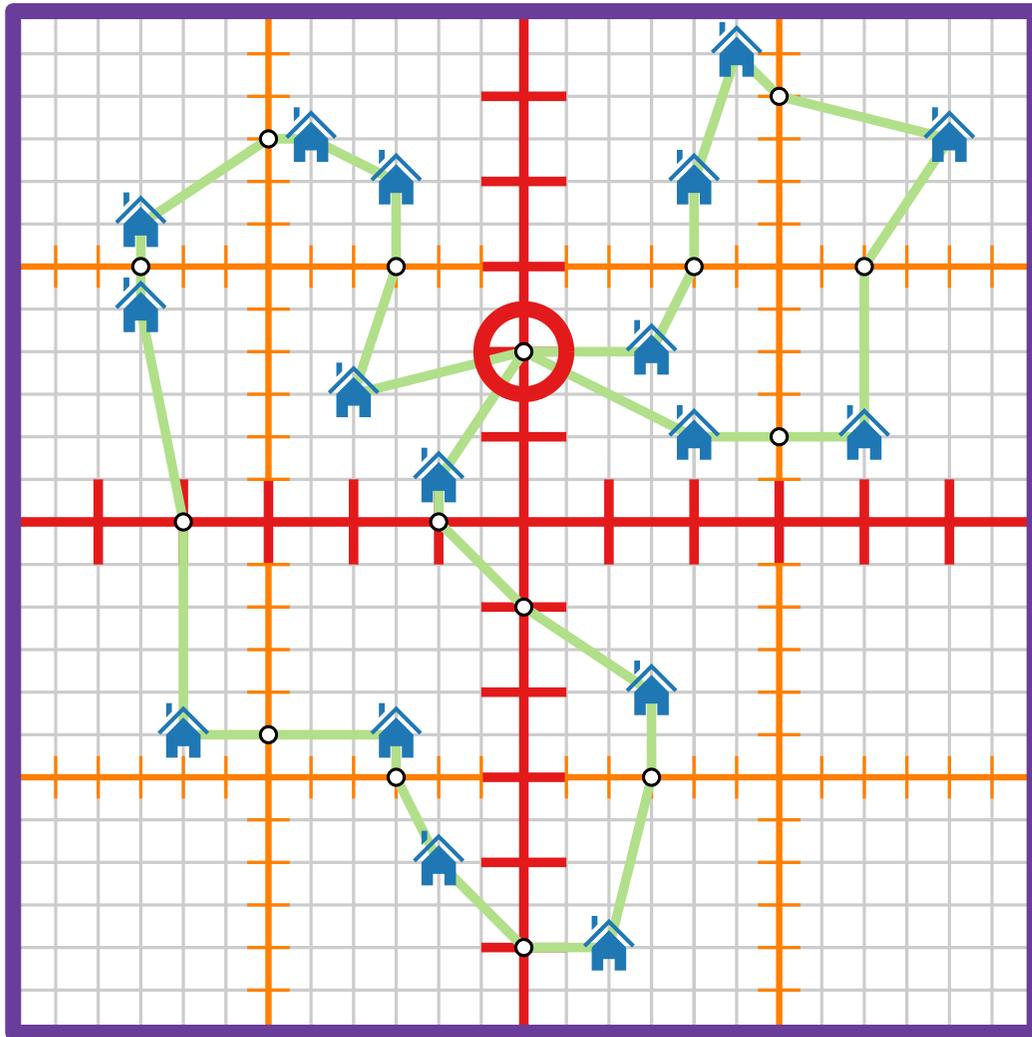
Crossing



No crossing



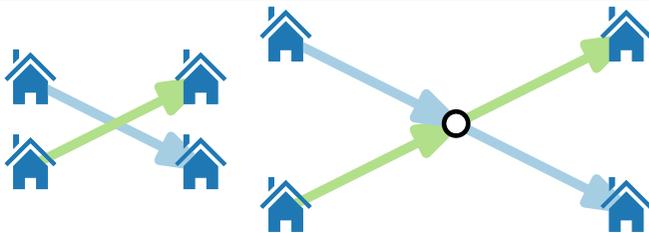
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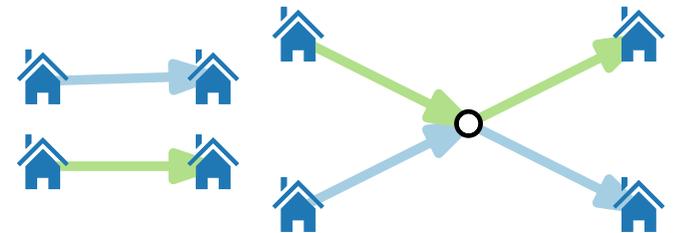
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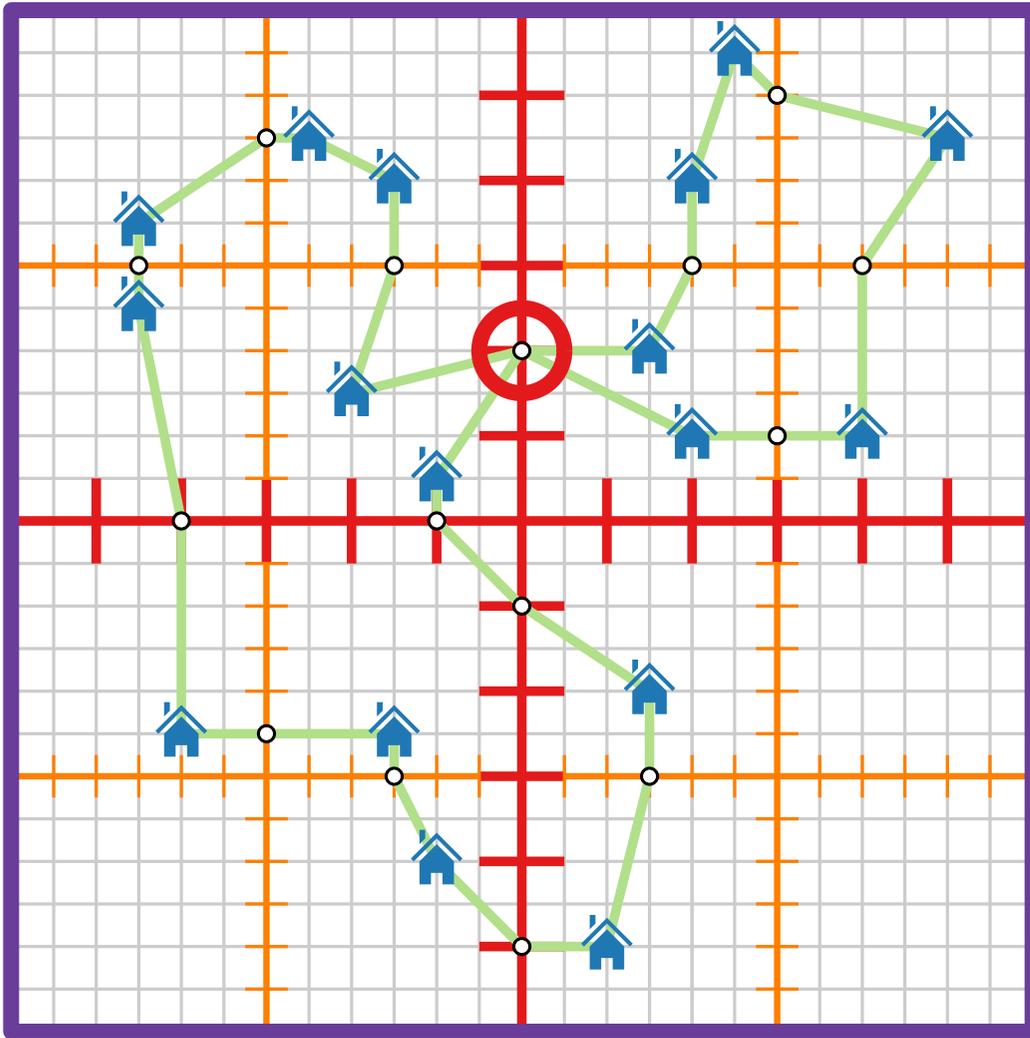
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# Well-Behaved Tours



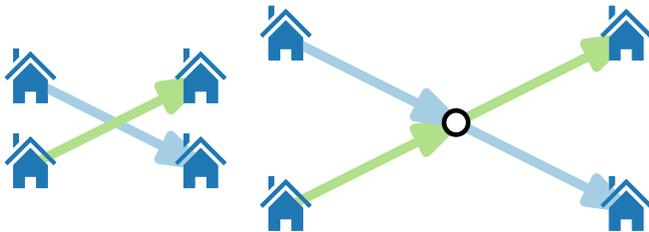
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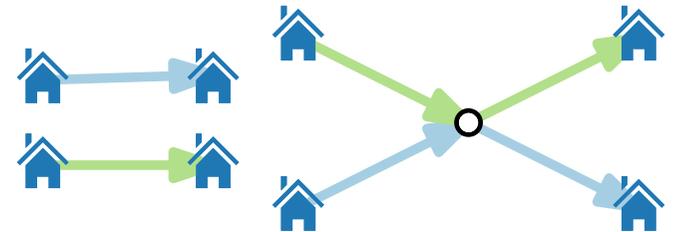
W.l.o.g. (**homework**):

No portal visited more than twice

Crossing



No crossing



# Computing a Well-Behaved Tour

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**Lemma.** An optimal well-behaved tour can be computed in  $2^{O(m)} = n^{O(1/\varepsilon)}$  time.

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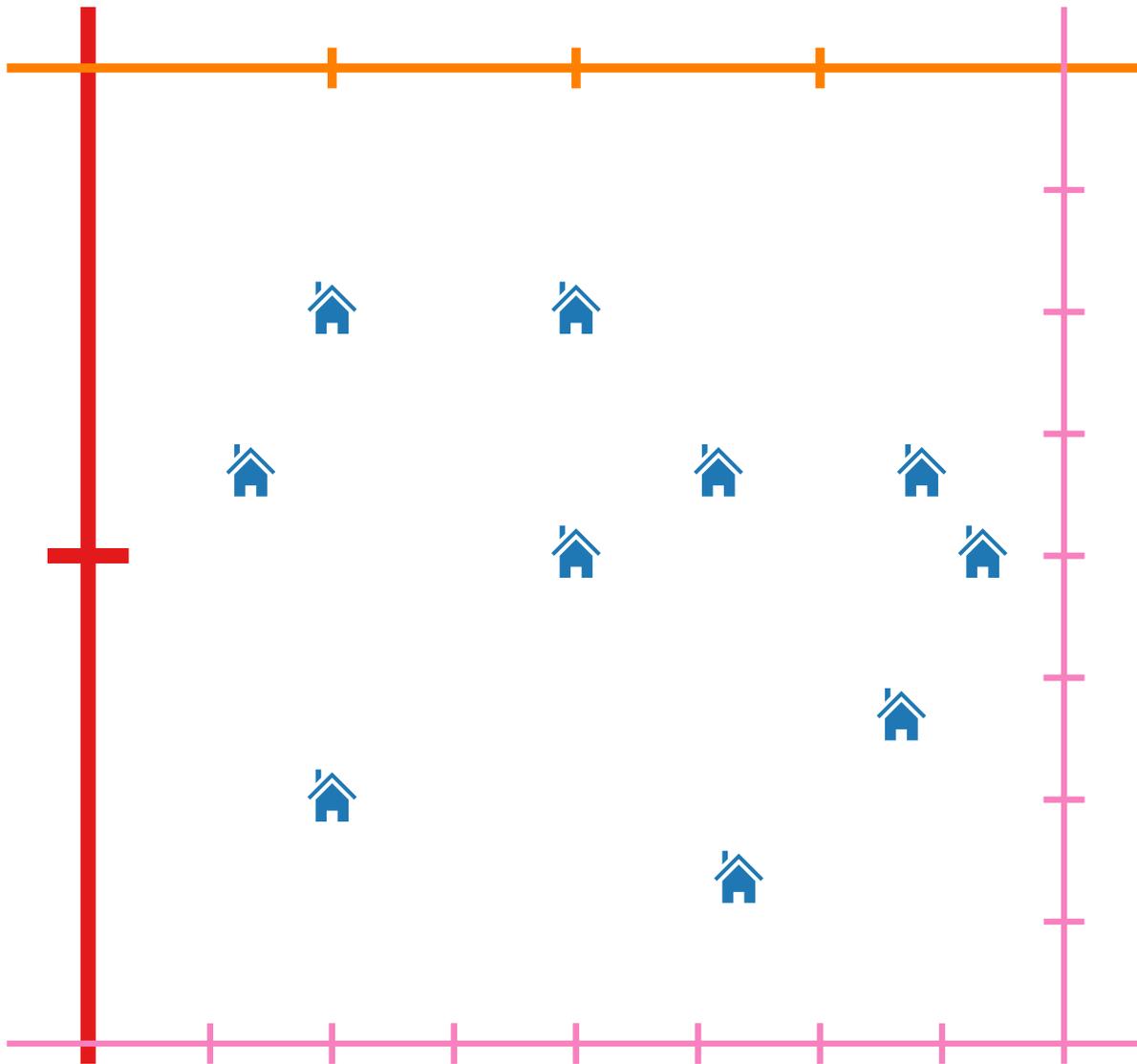
- Dynamic programming!
- Compute sub-structure of an optimal tour for each square in the dissection tree.
- These solutions can be efficiently propagated bottom-up through the dissection tree.

# Approximation Algorithms

## Lecture 9: A PTAS for EUCLIDEAN TSP

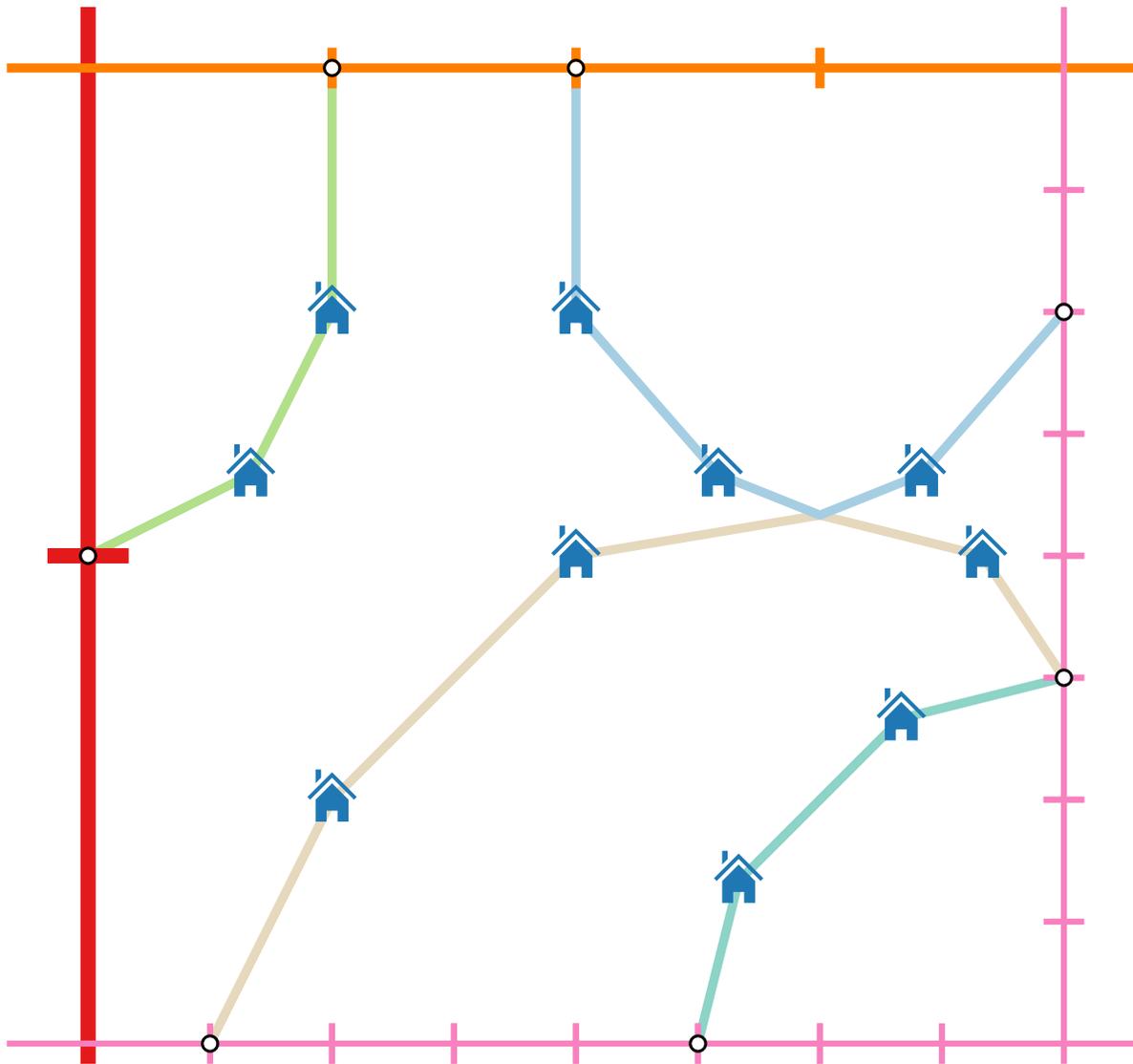
### Part IV: Dynamic Program

# Dynamic Program (I)



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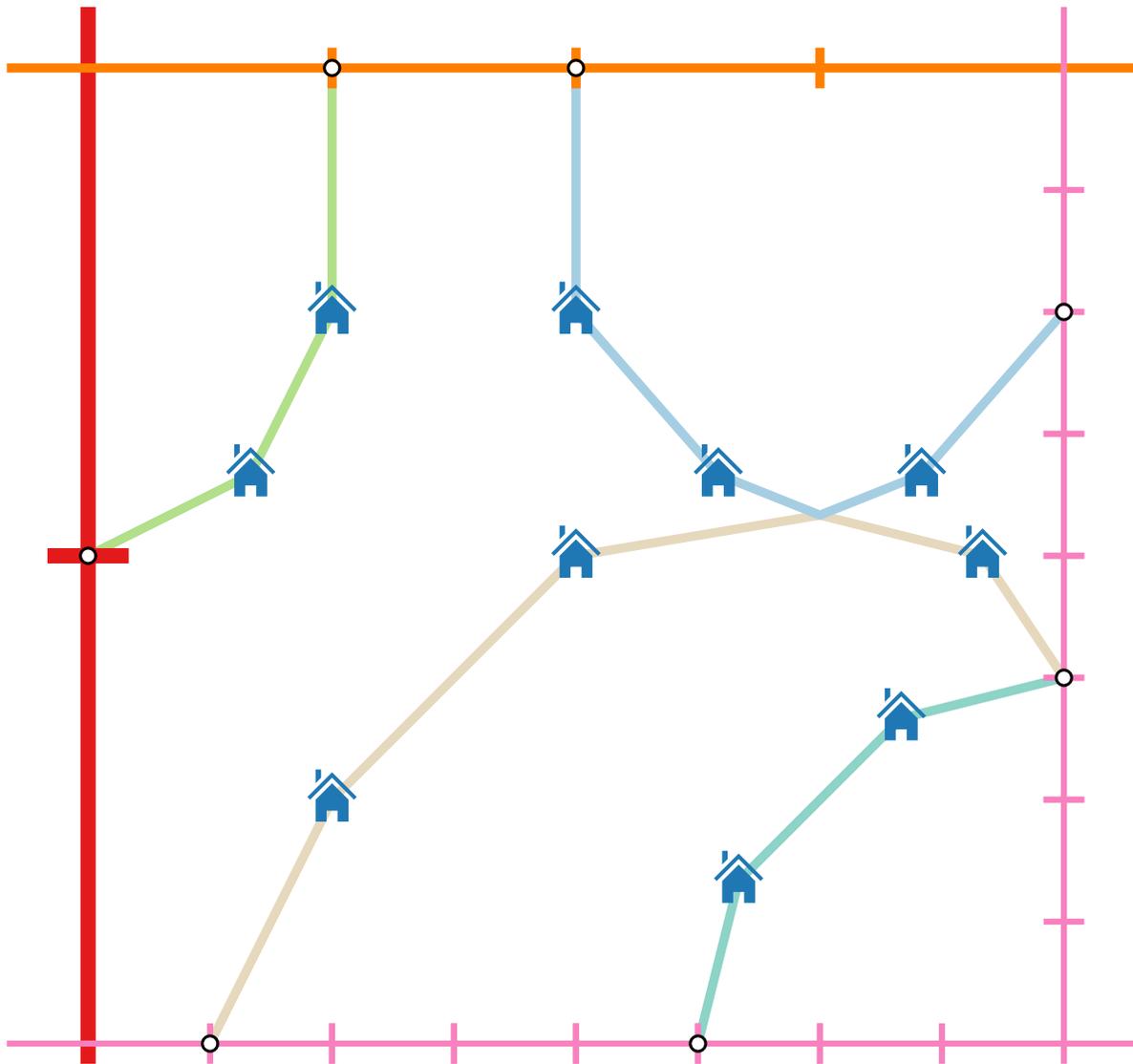
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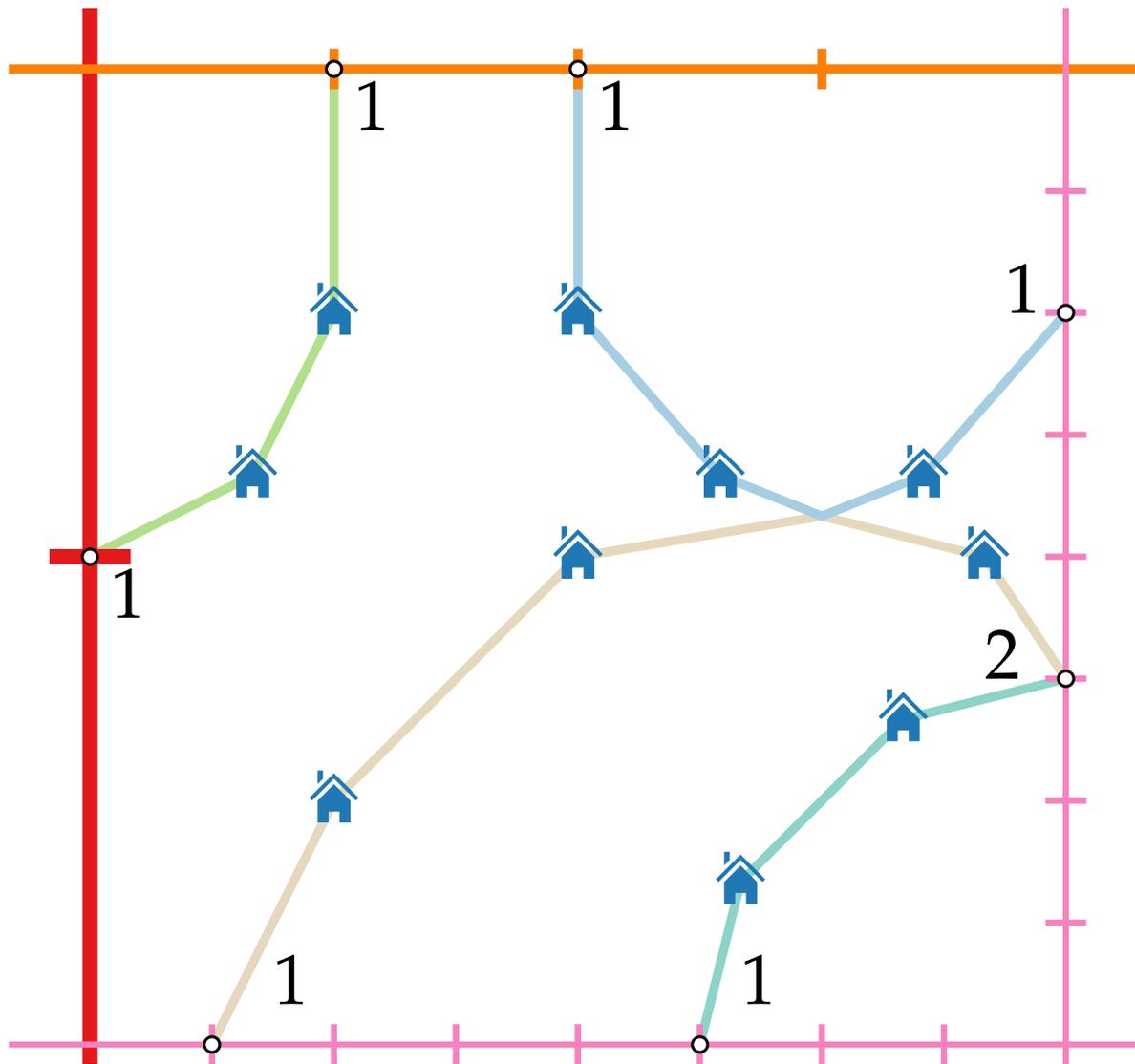


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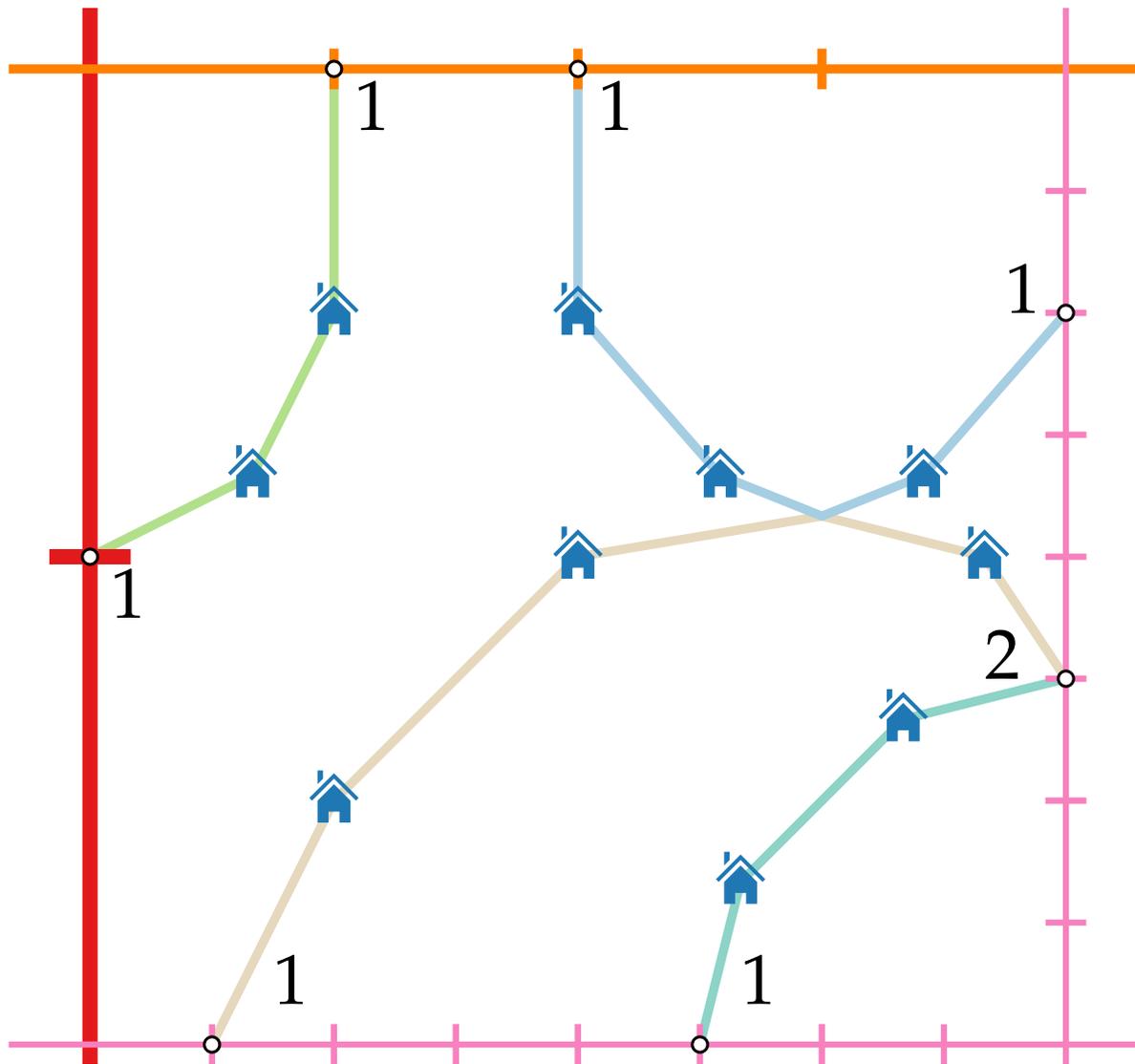
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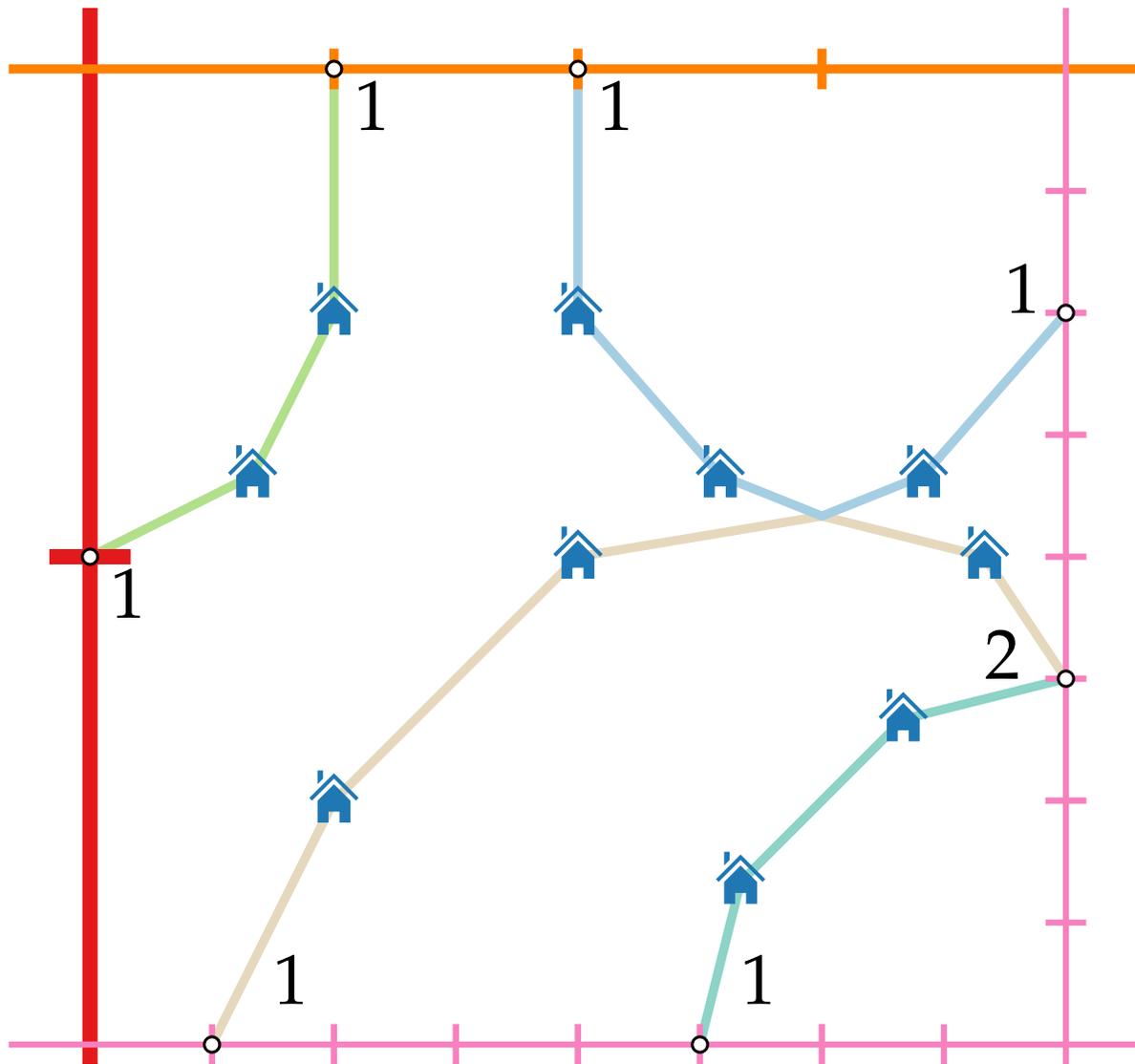
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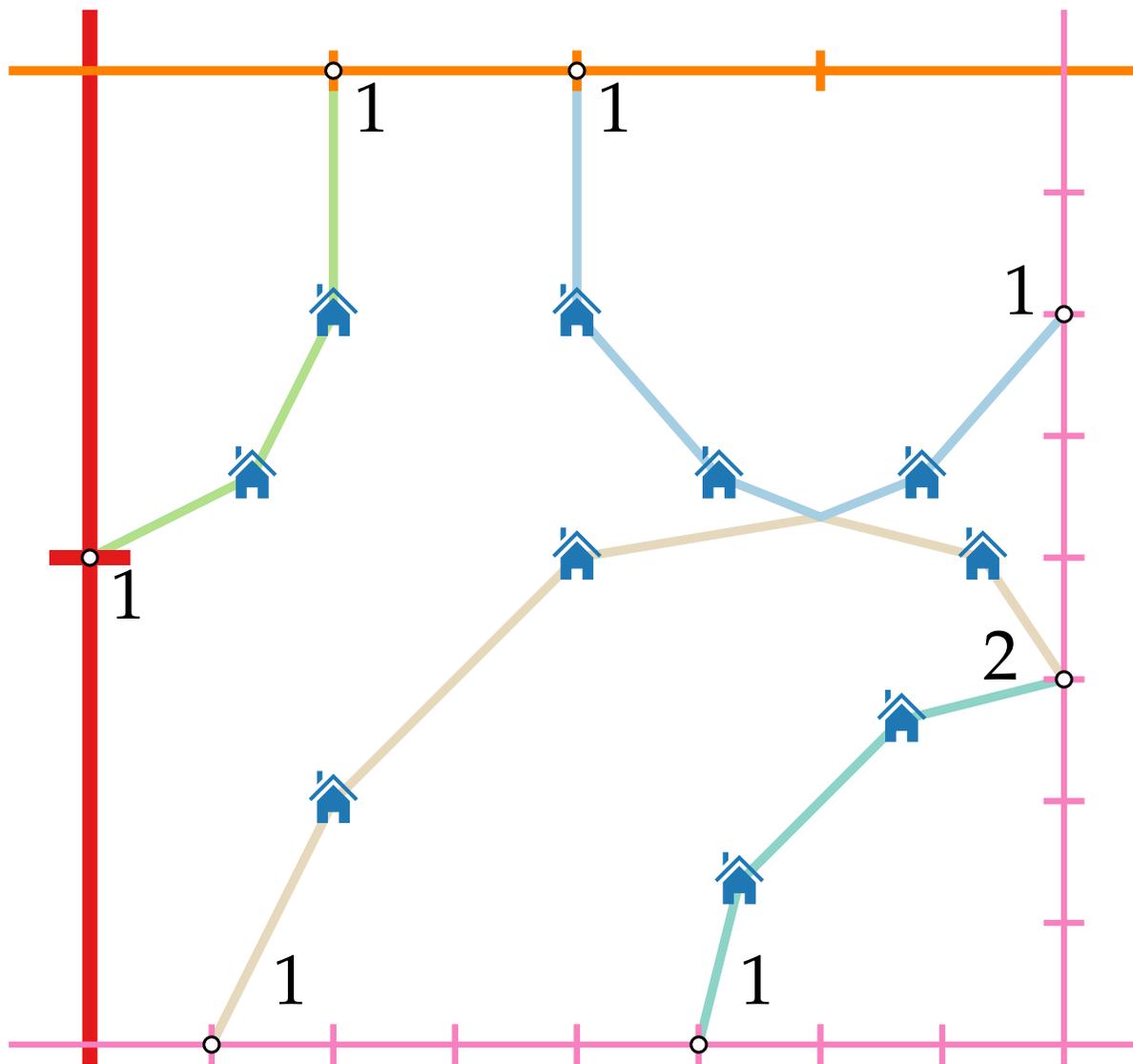
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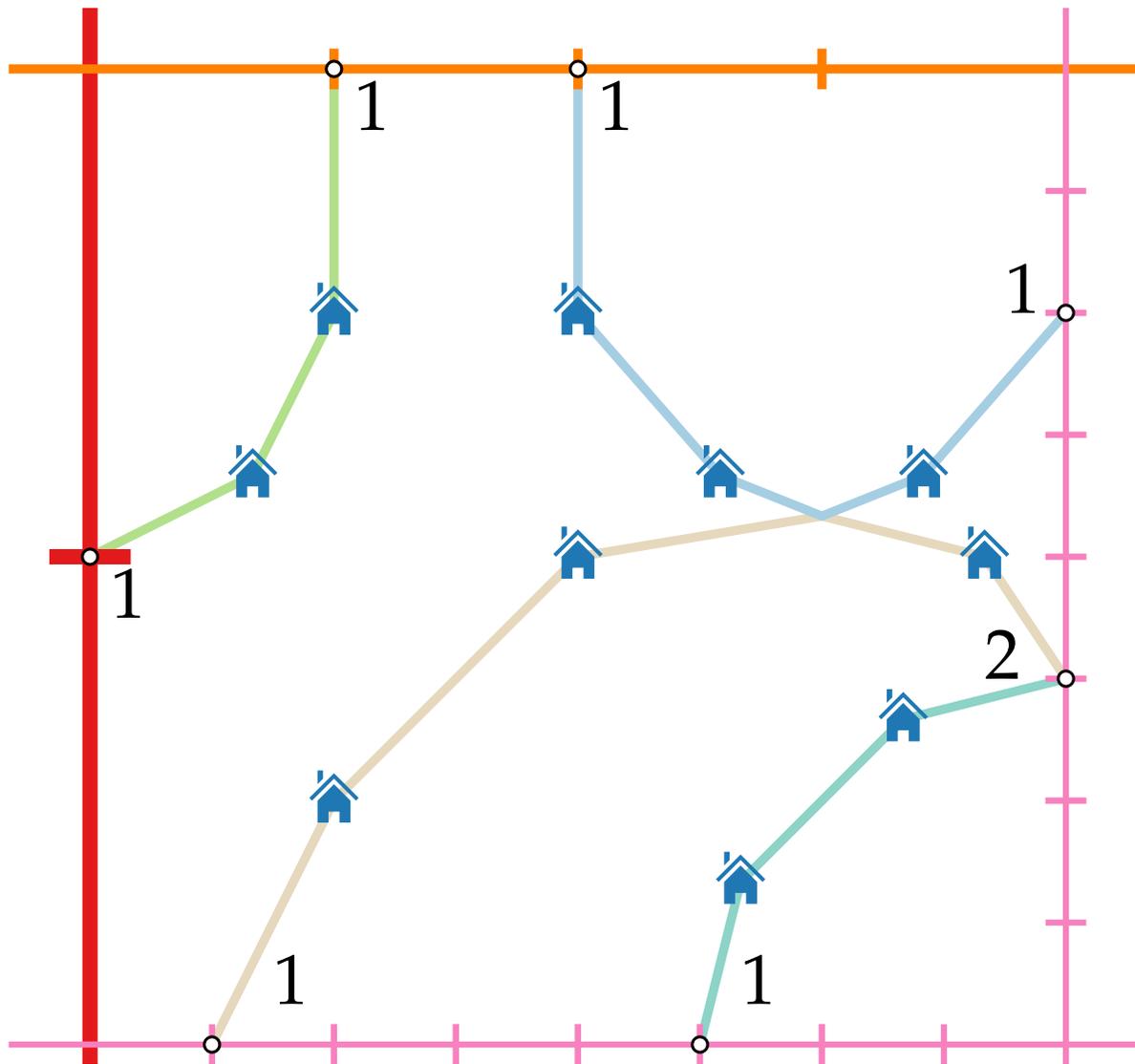
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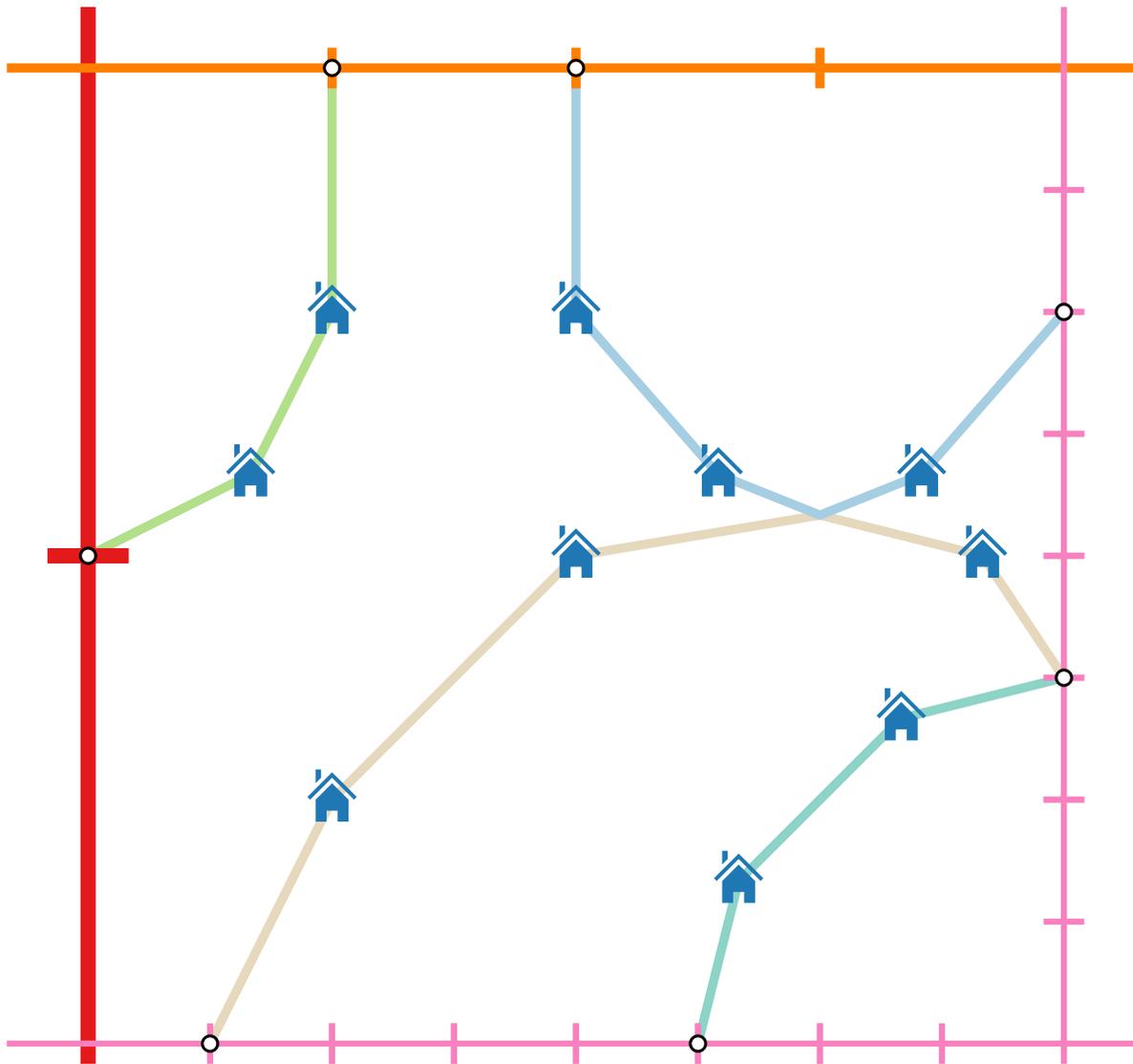
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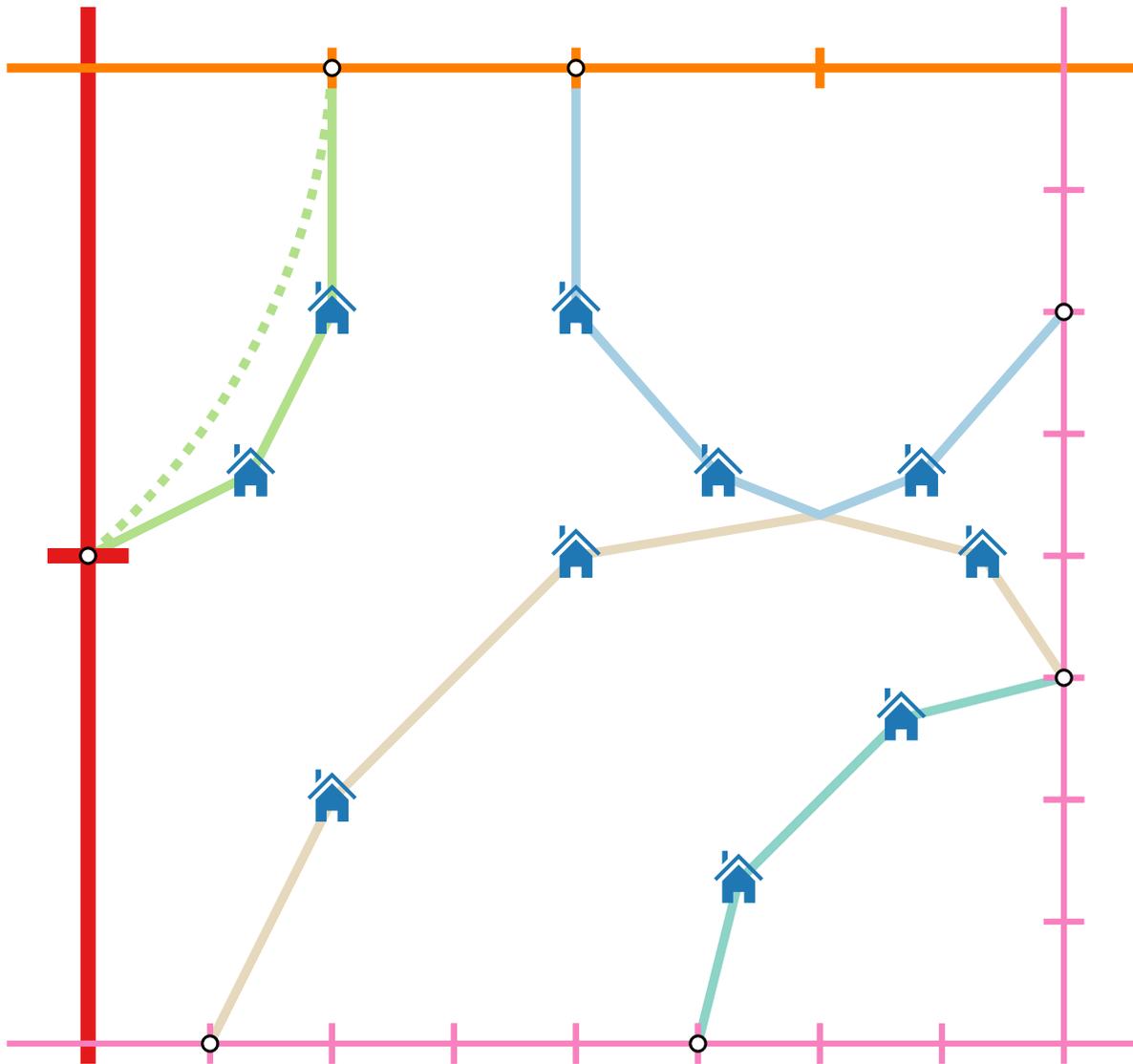
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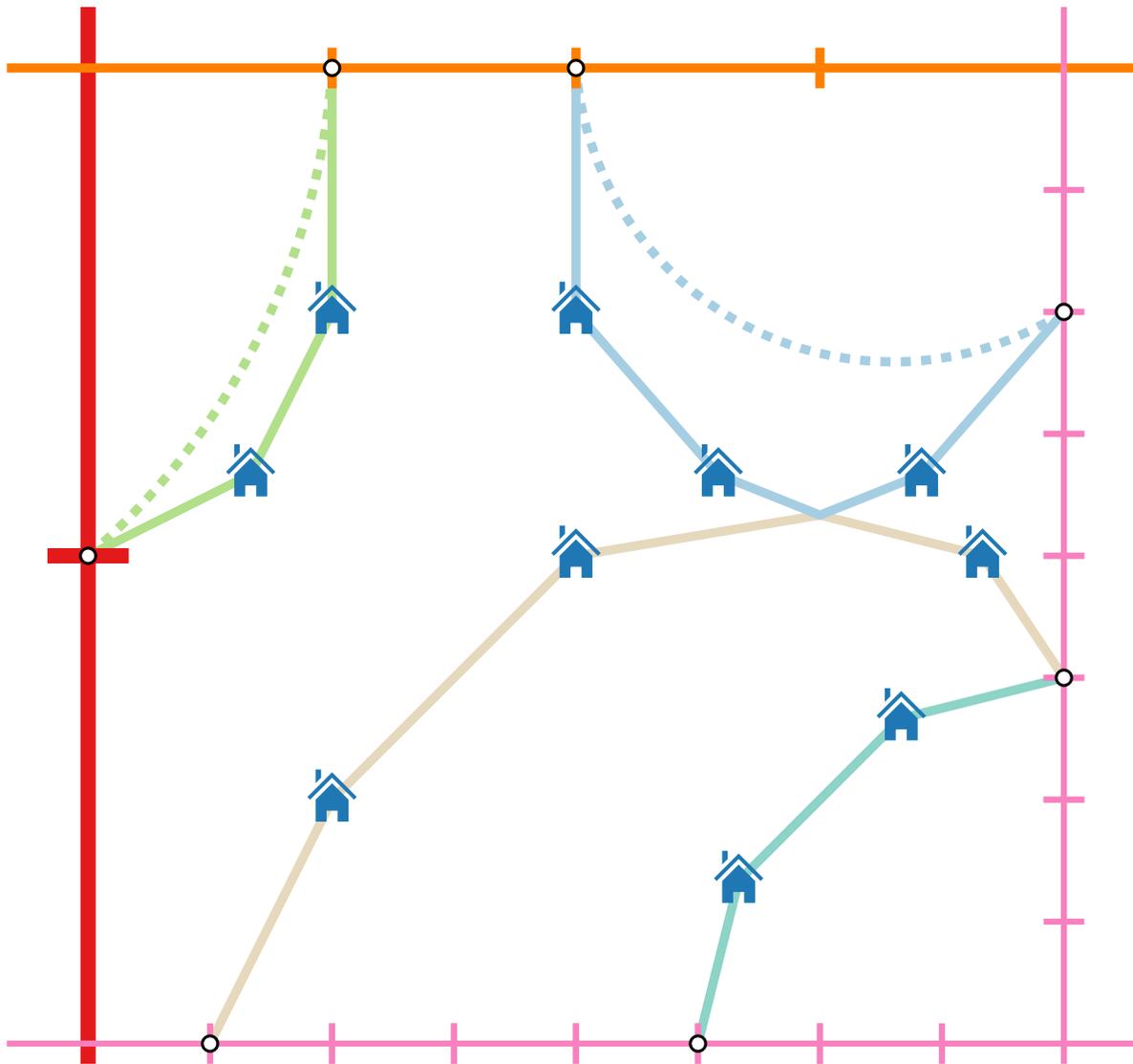
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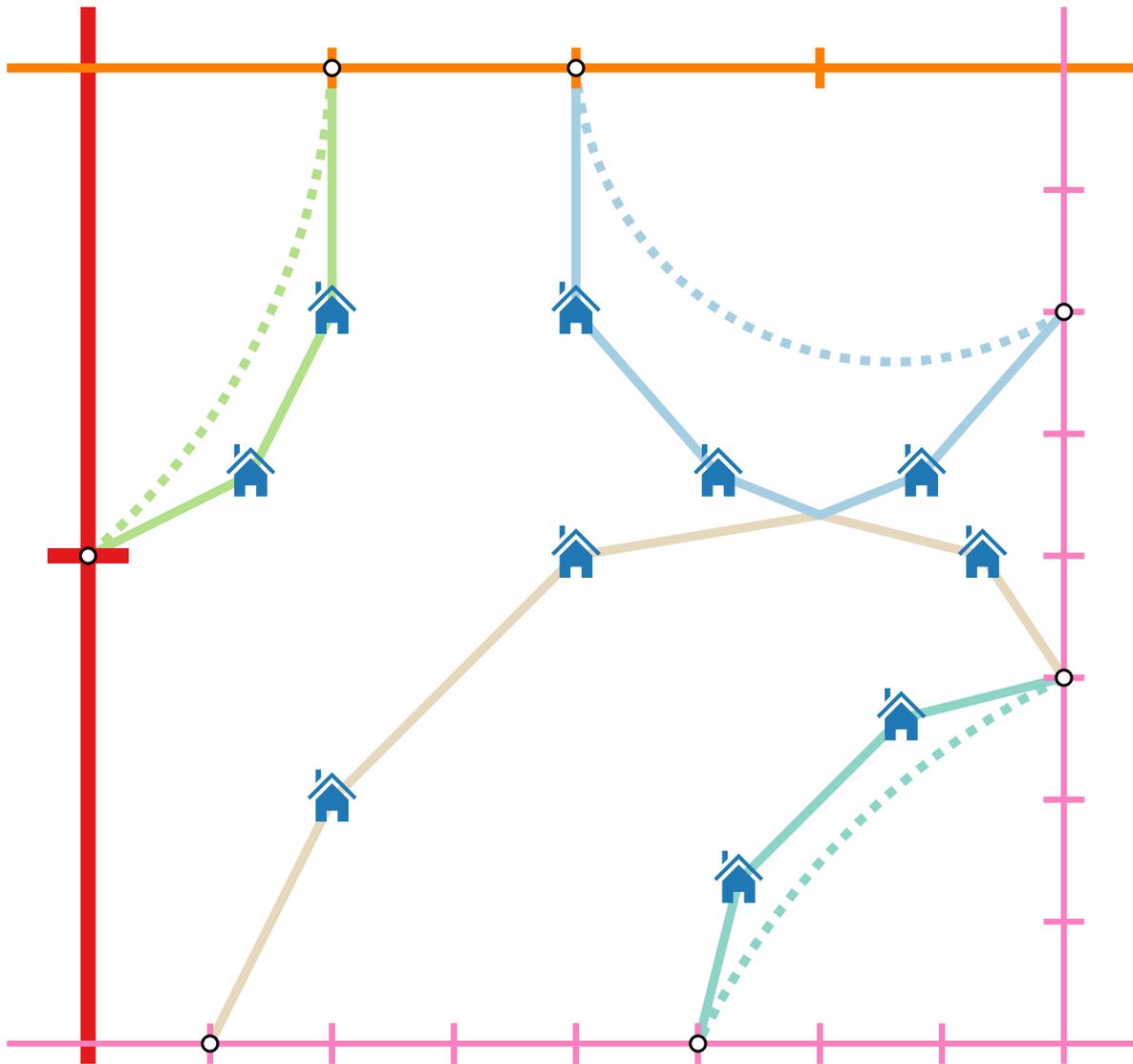
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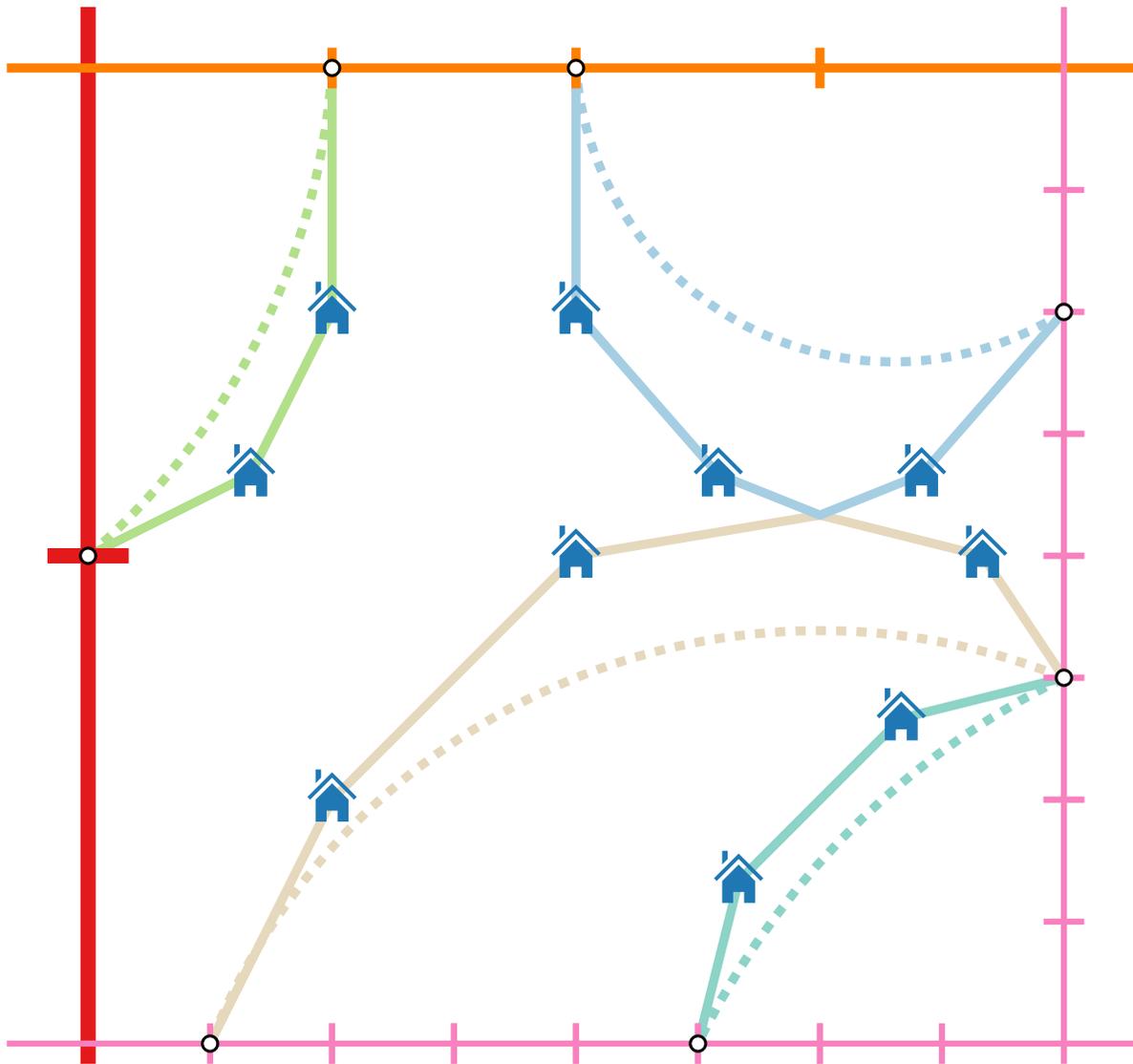
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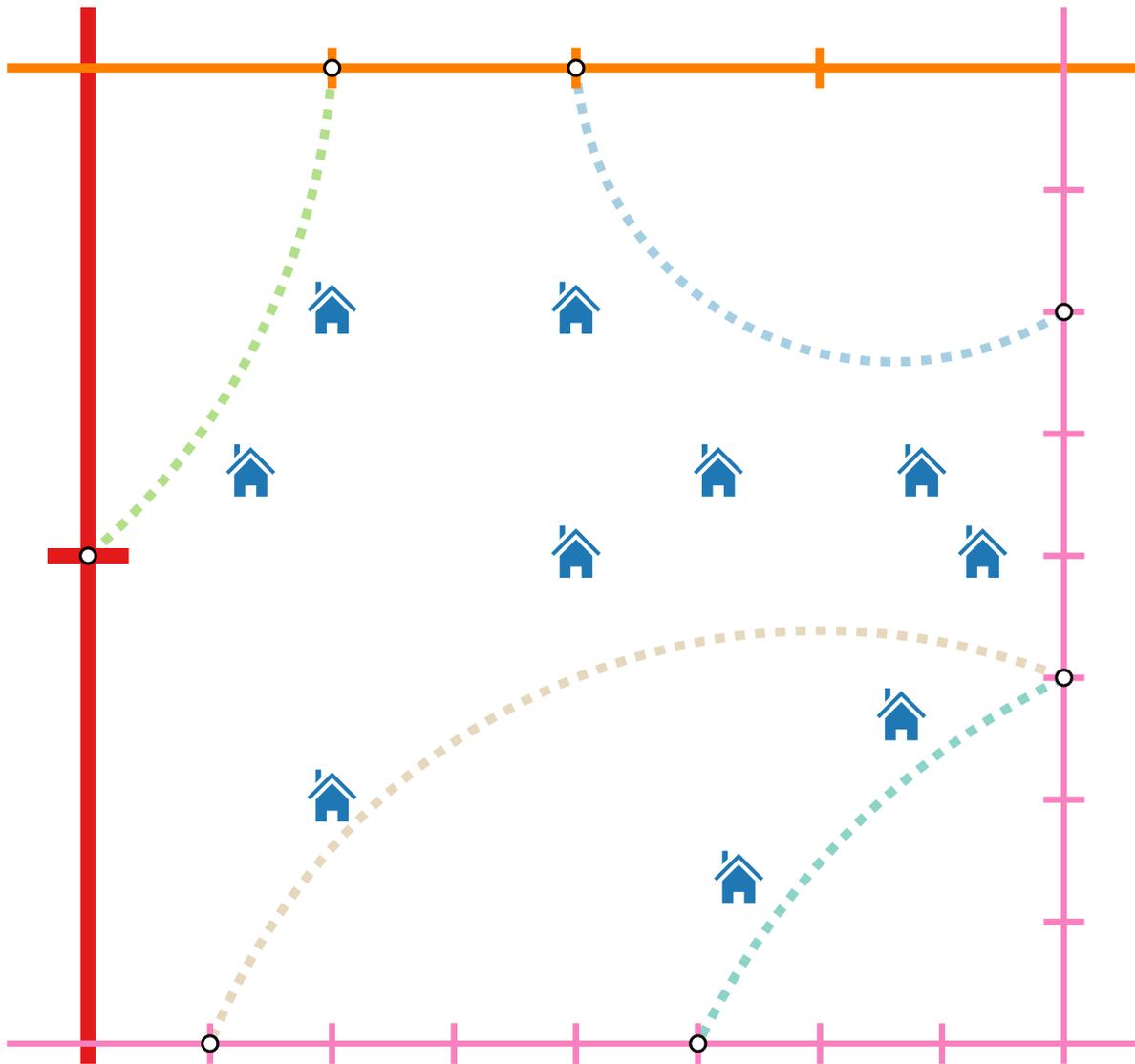
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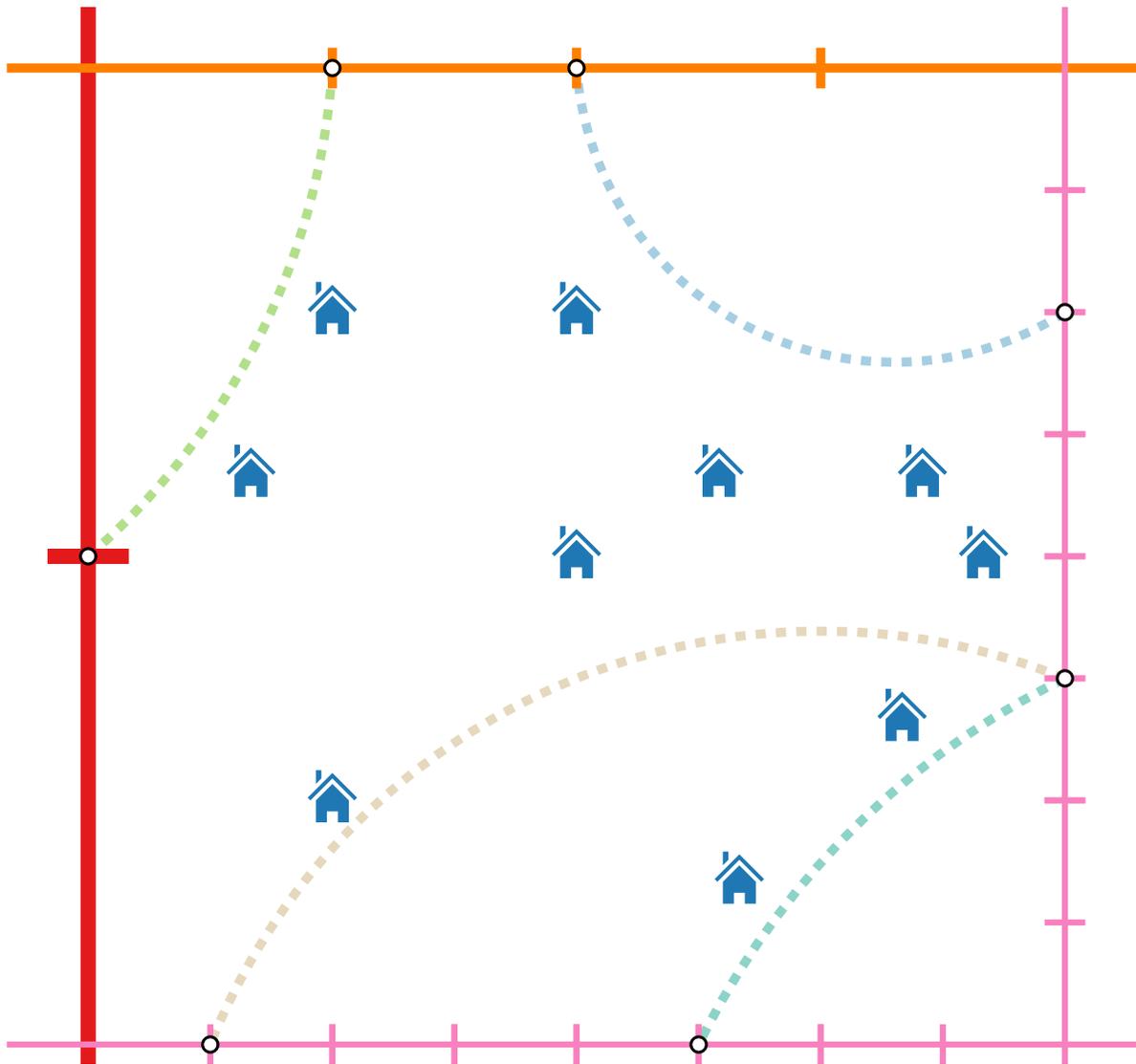
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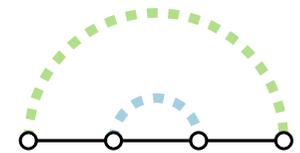
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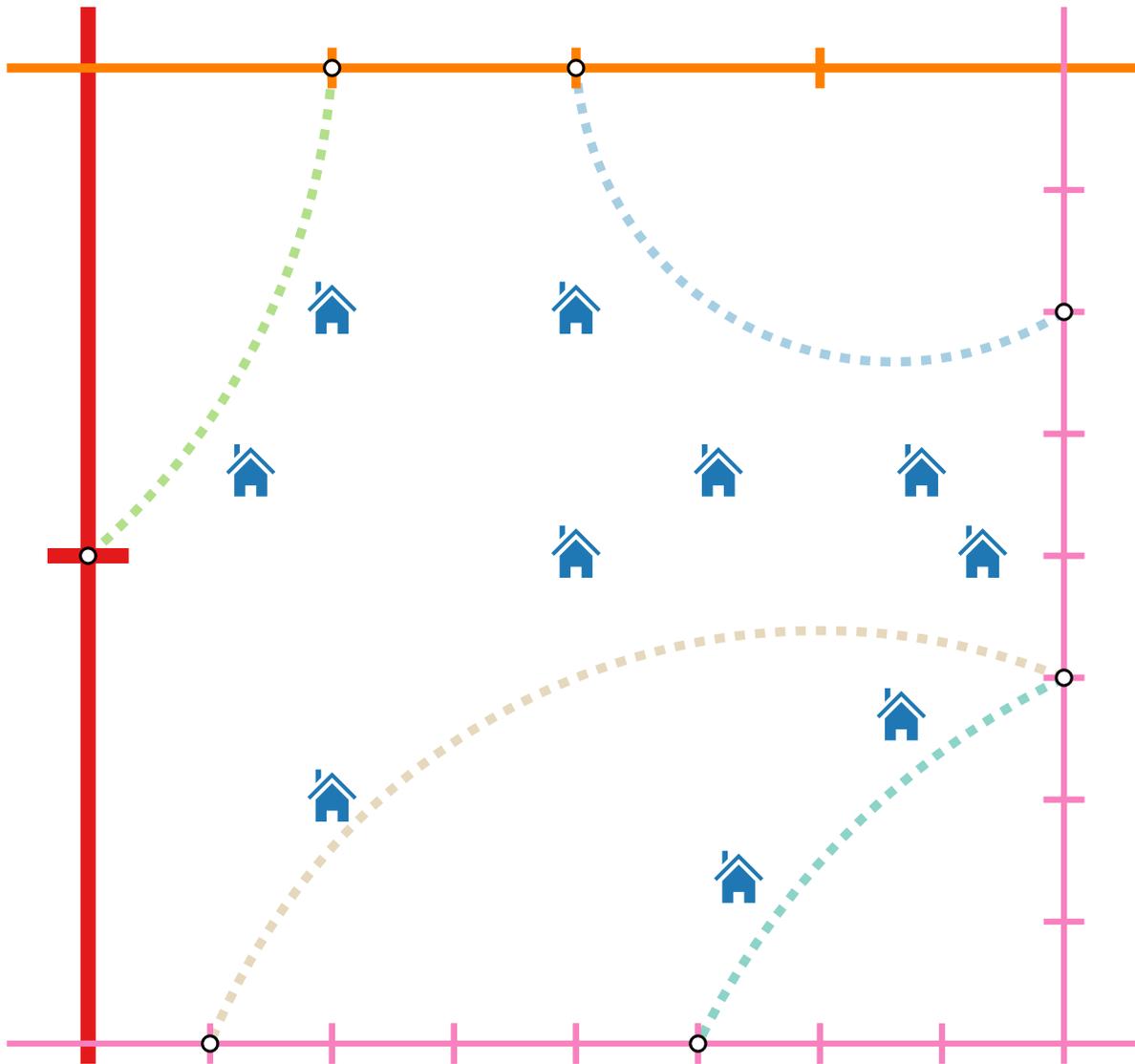


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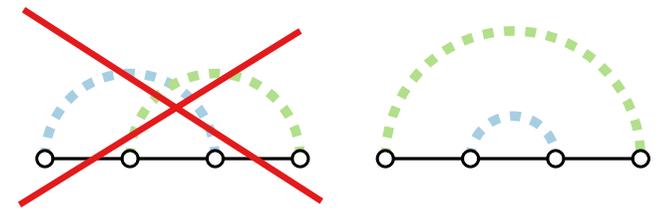


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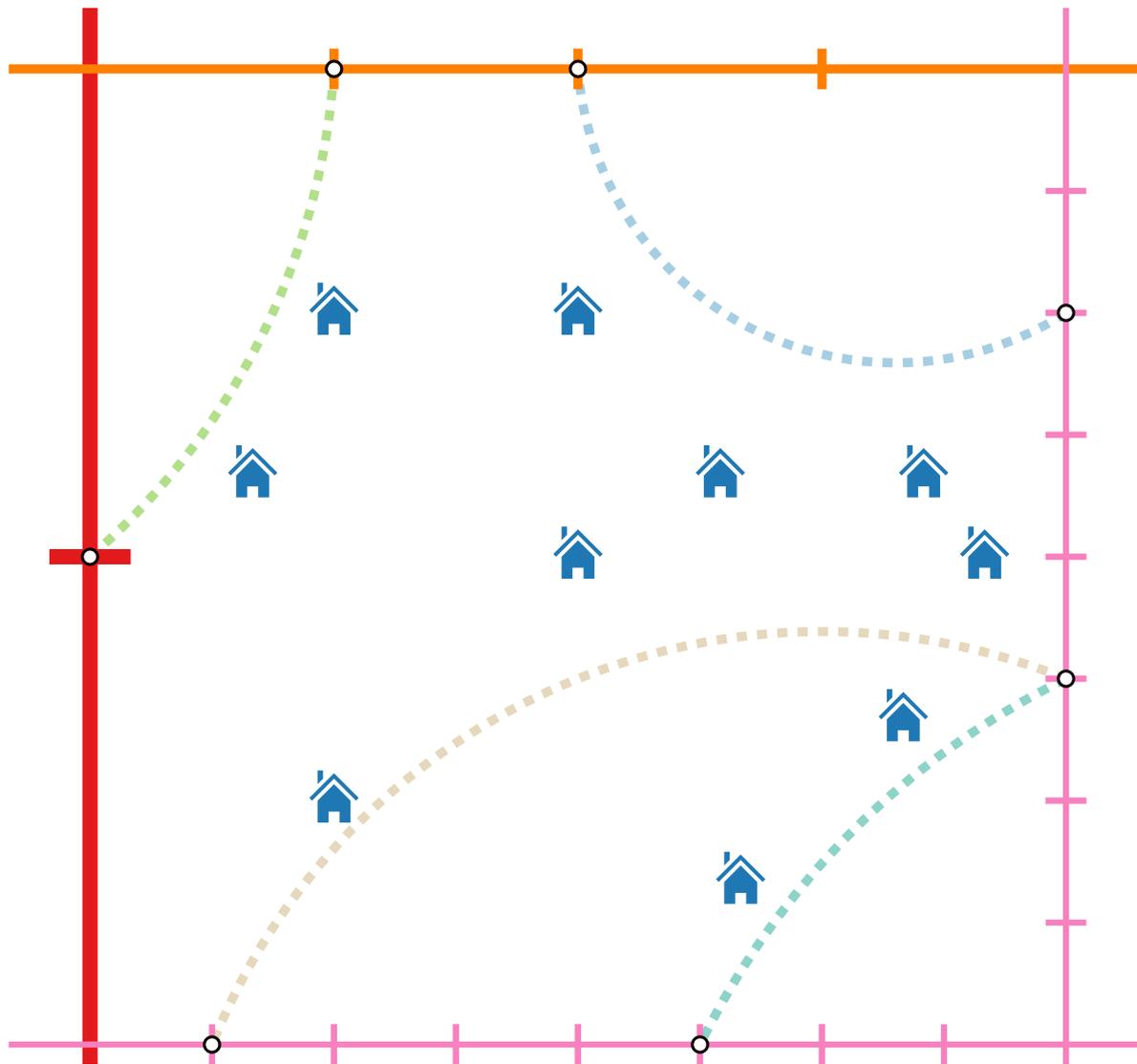


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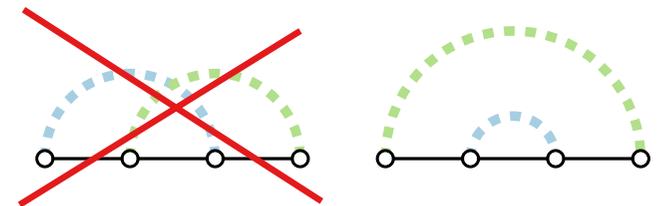
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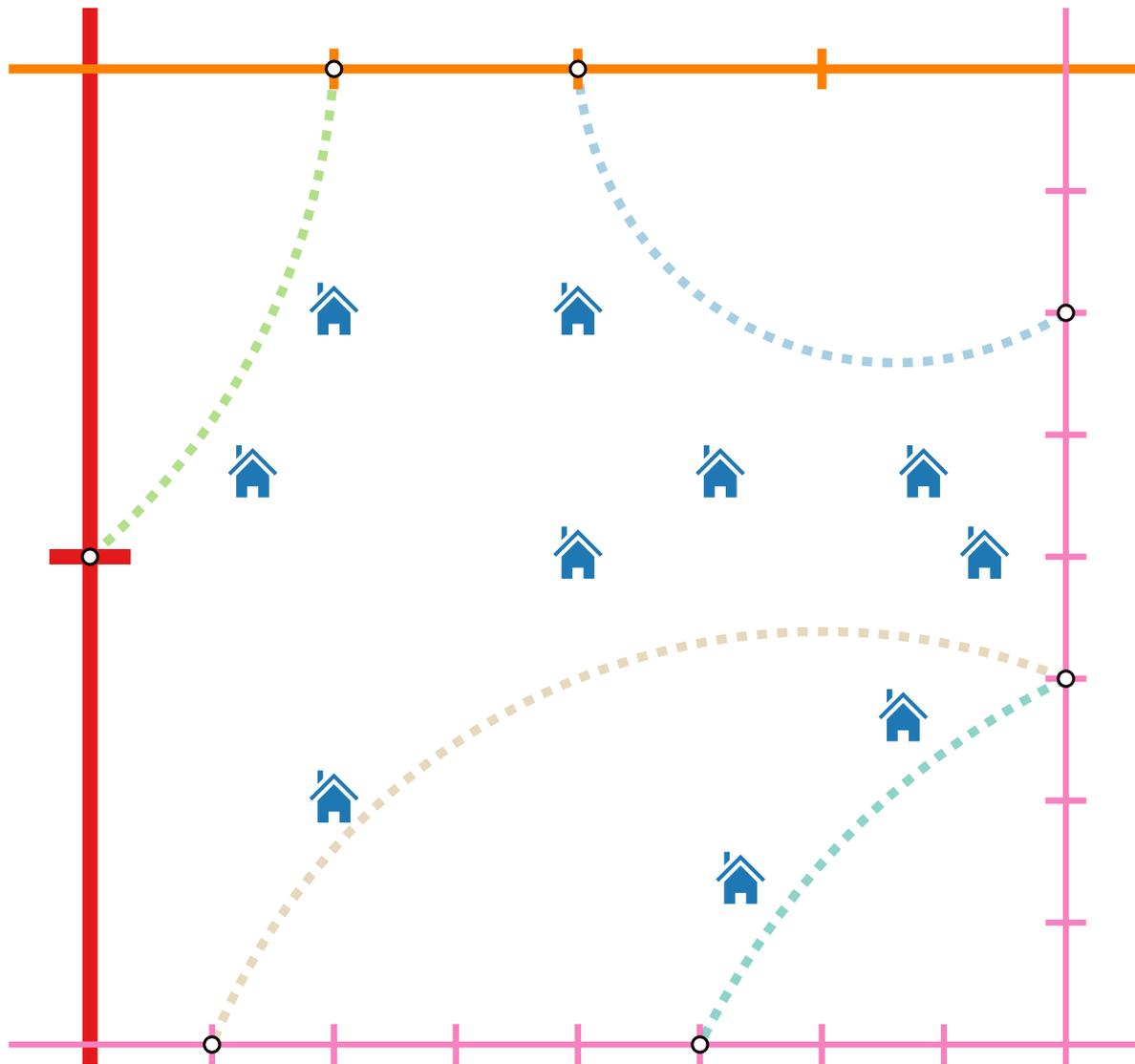
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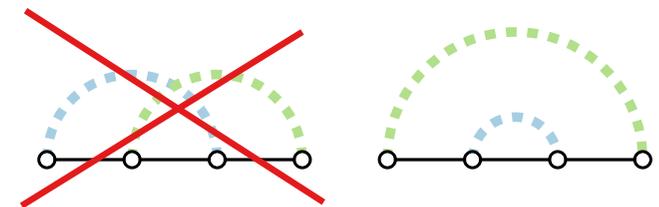


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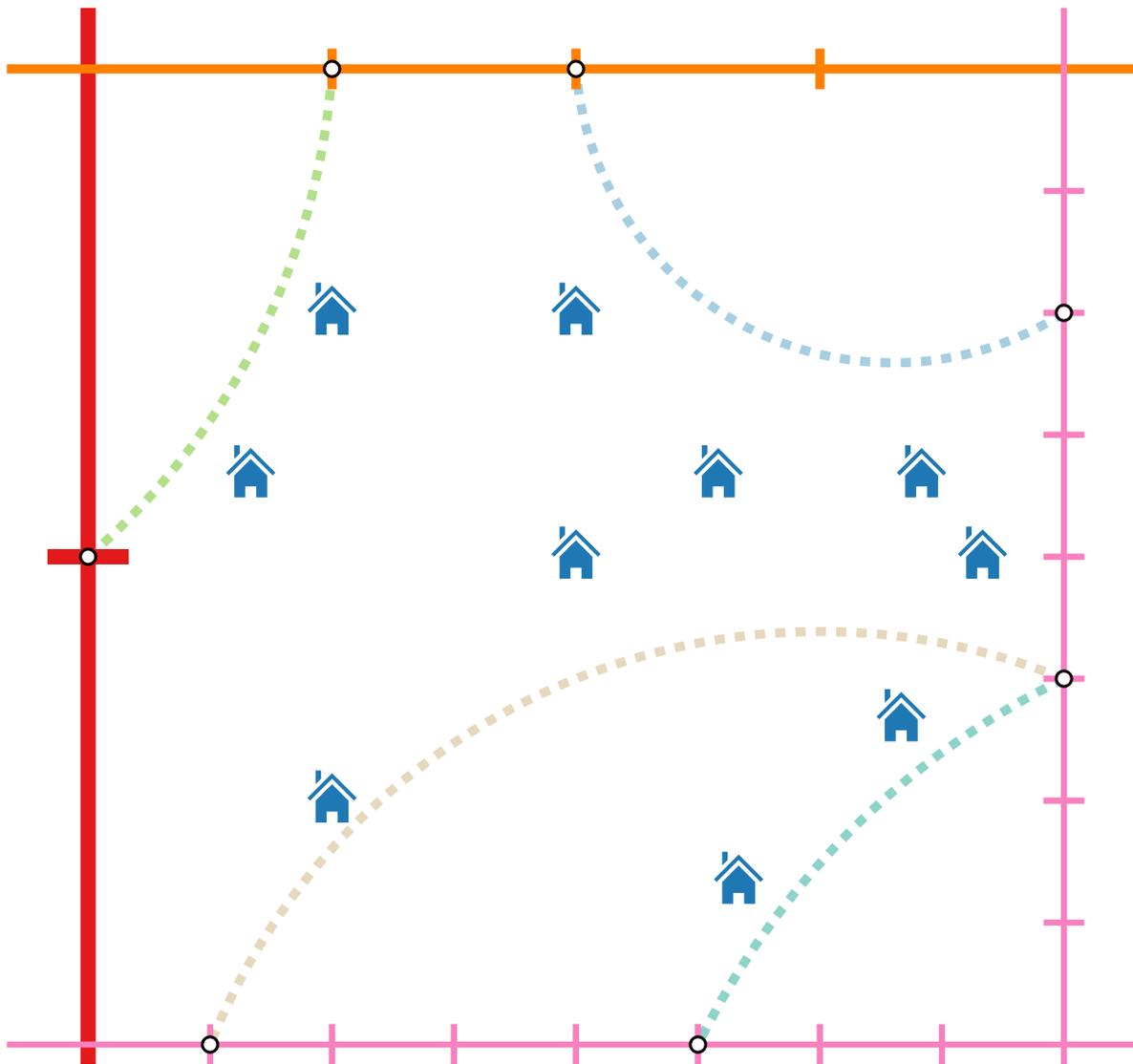
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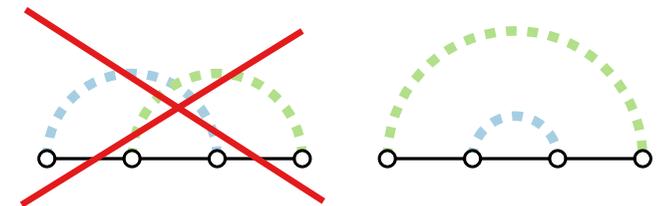
$\underbrace{\hspace{10em}}$   
#visit vectors

# Dynamic Program (I)



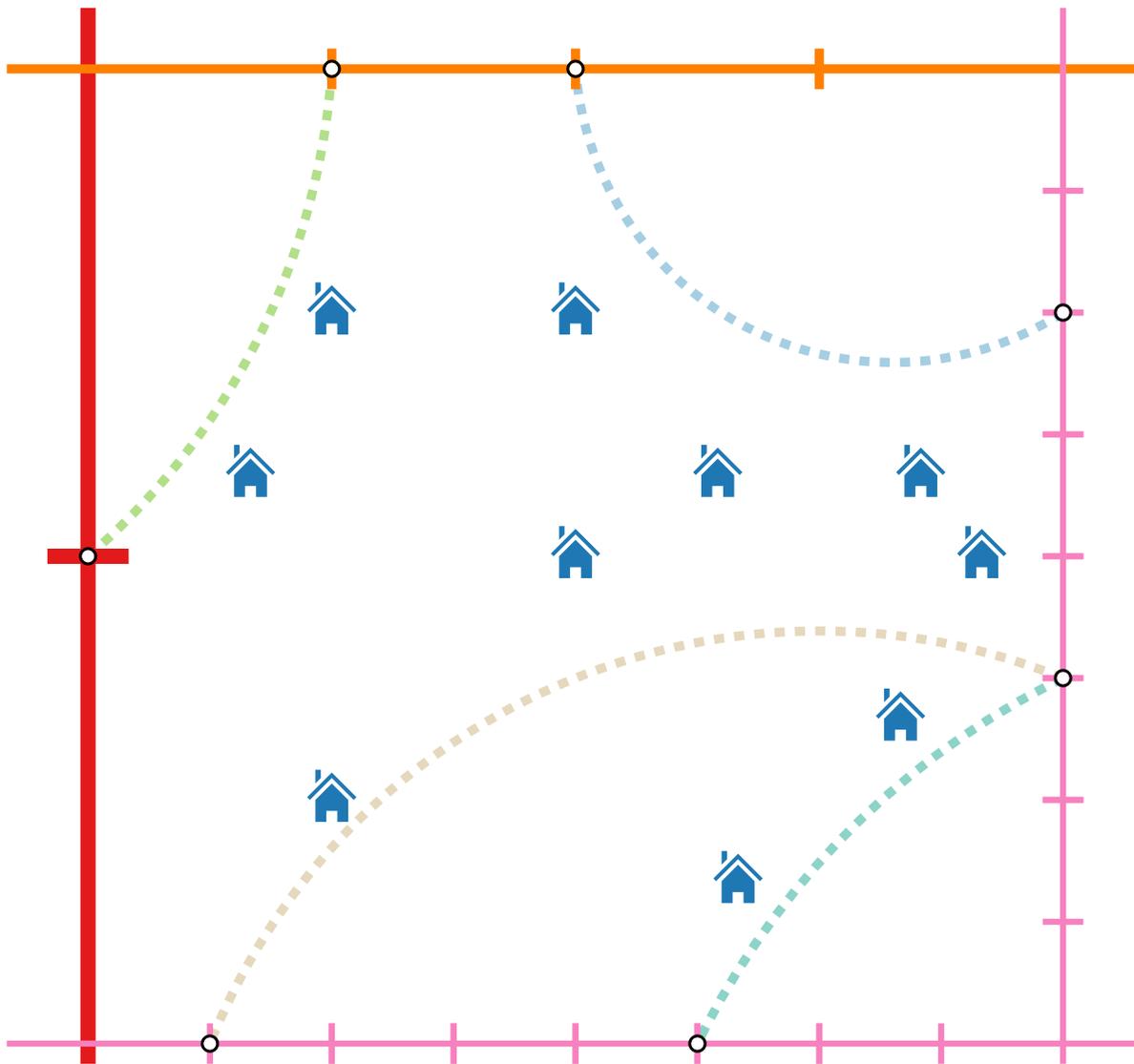
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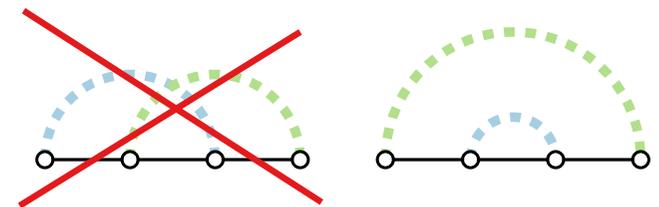
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 #visit vectors    #realizable pairings

# Dynamic Program (I)



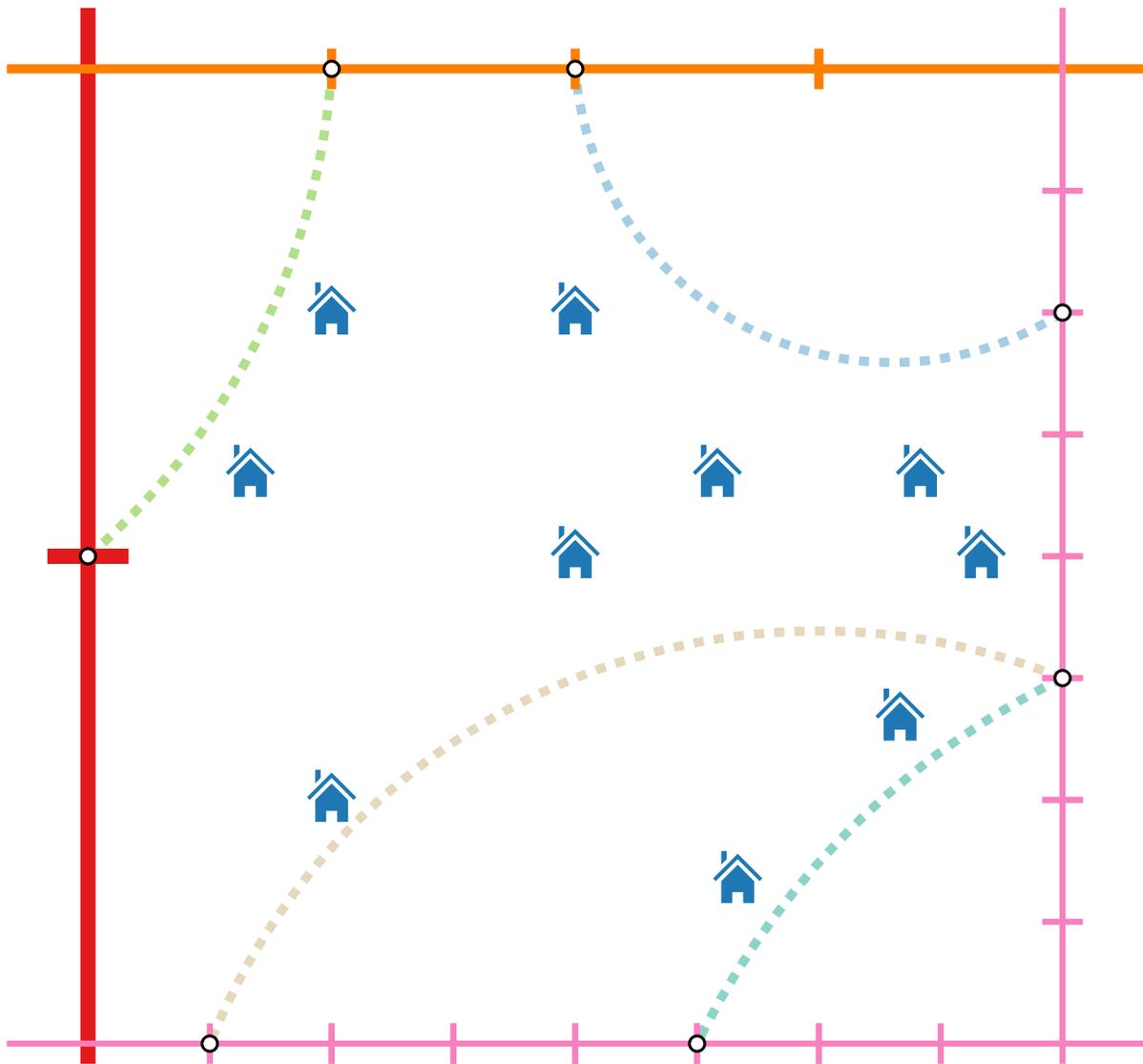
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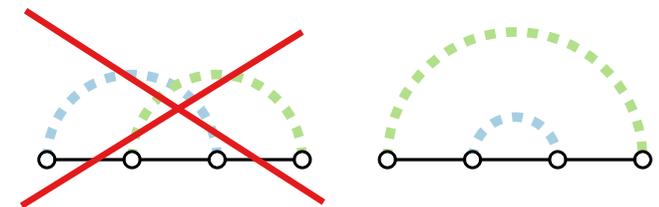
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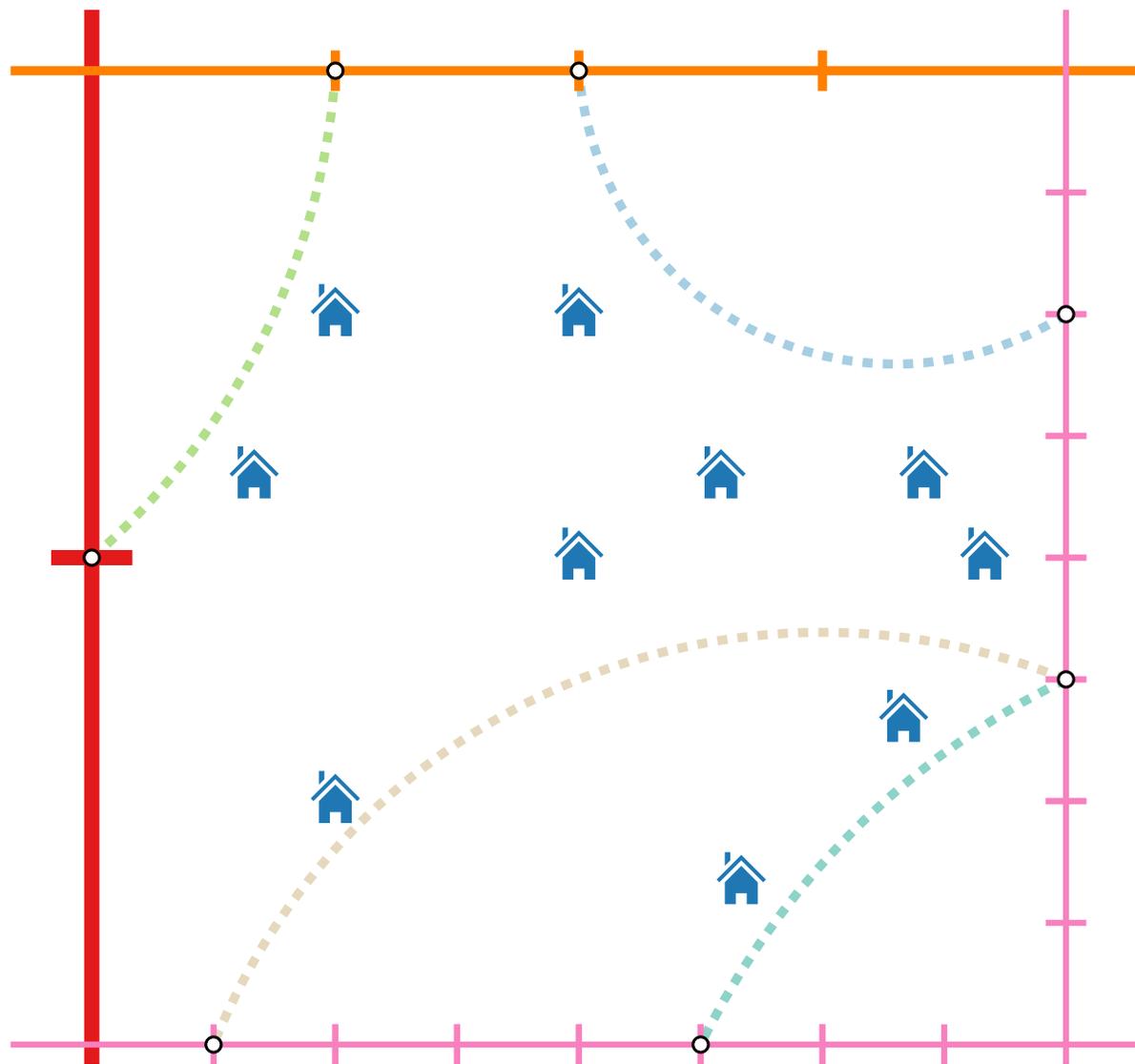
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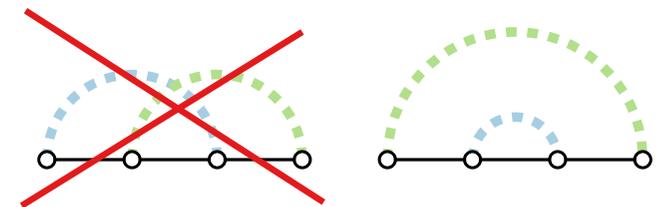
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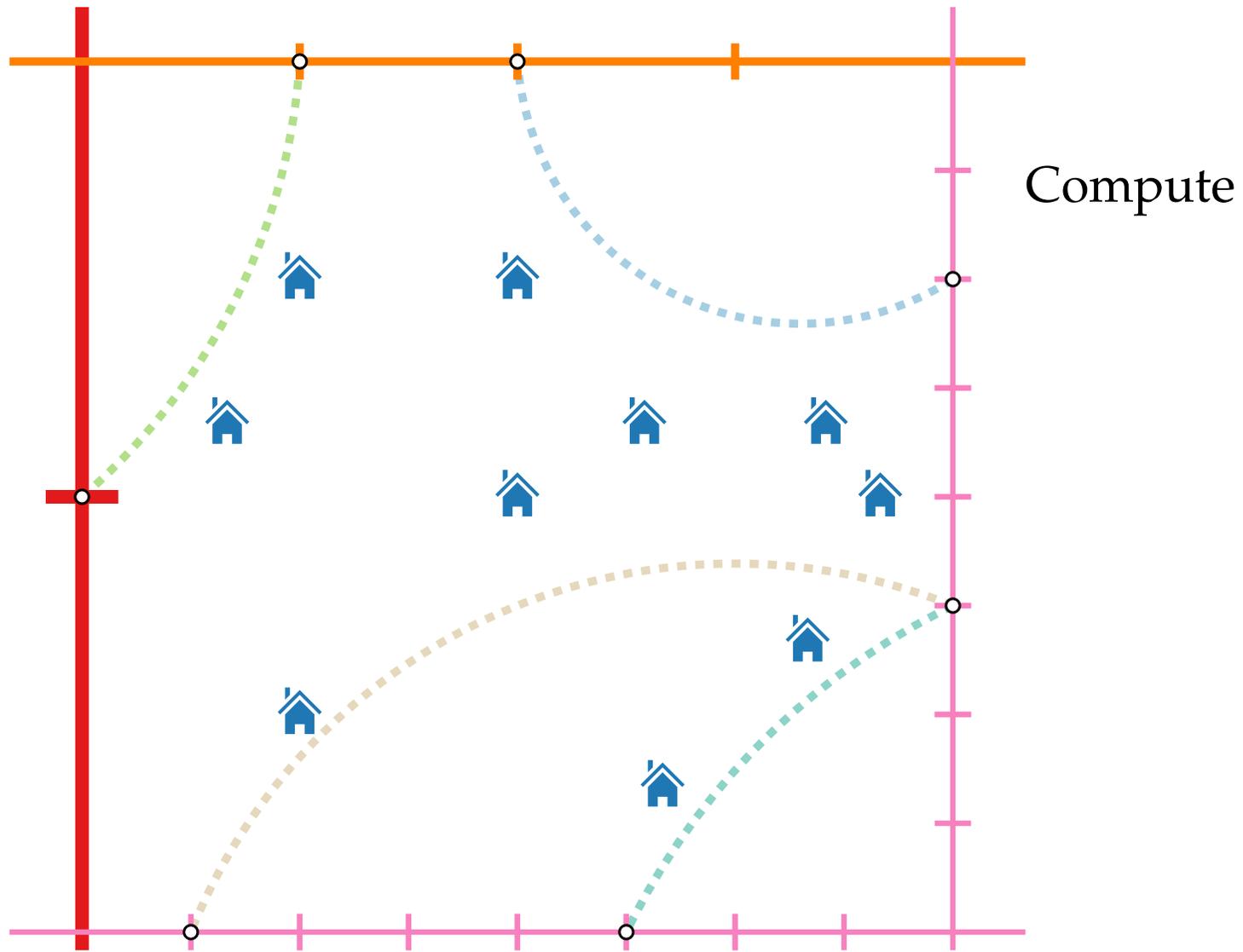
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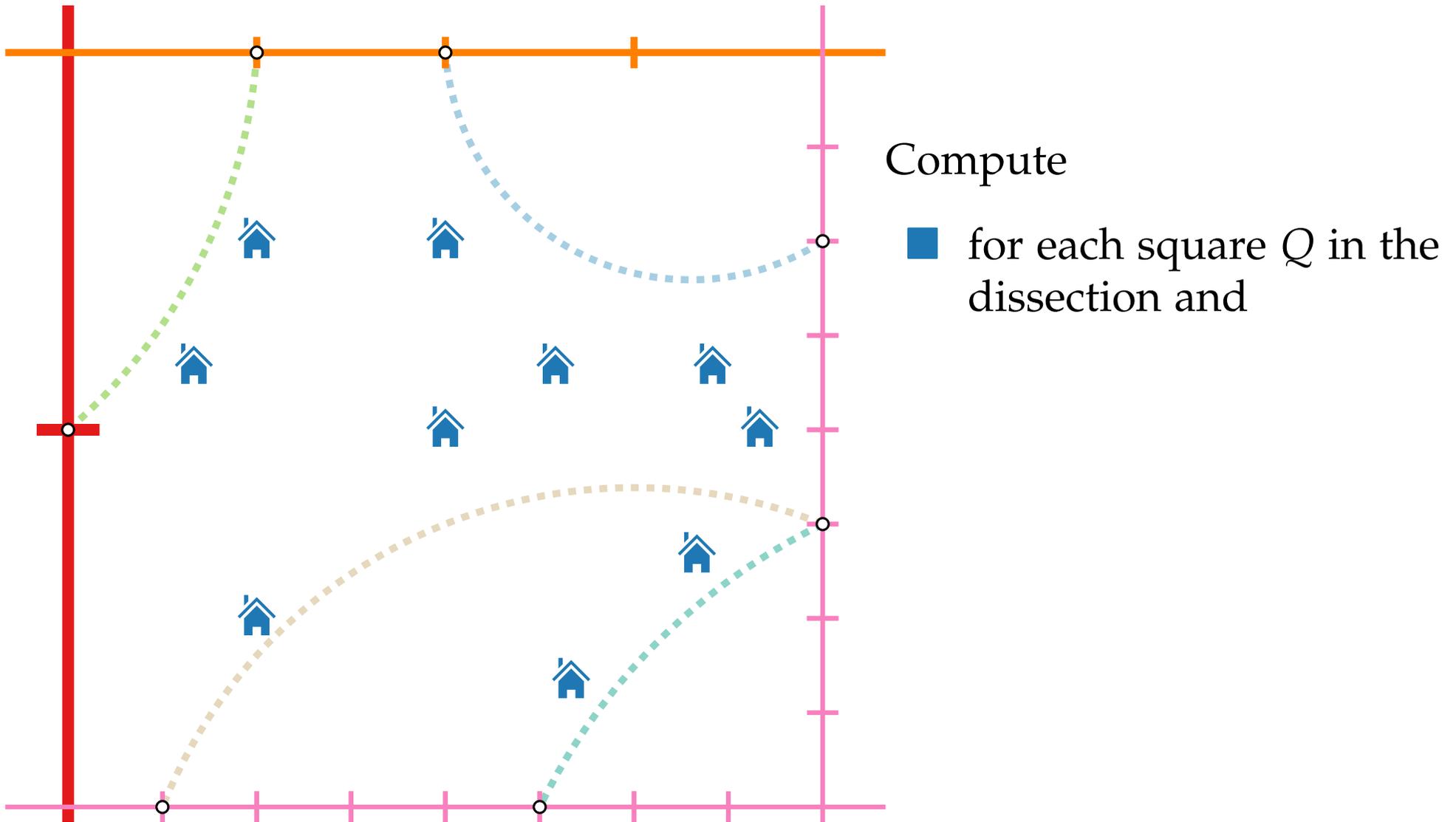


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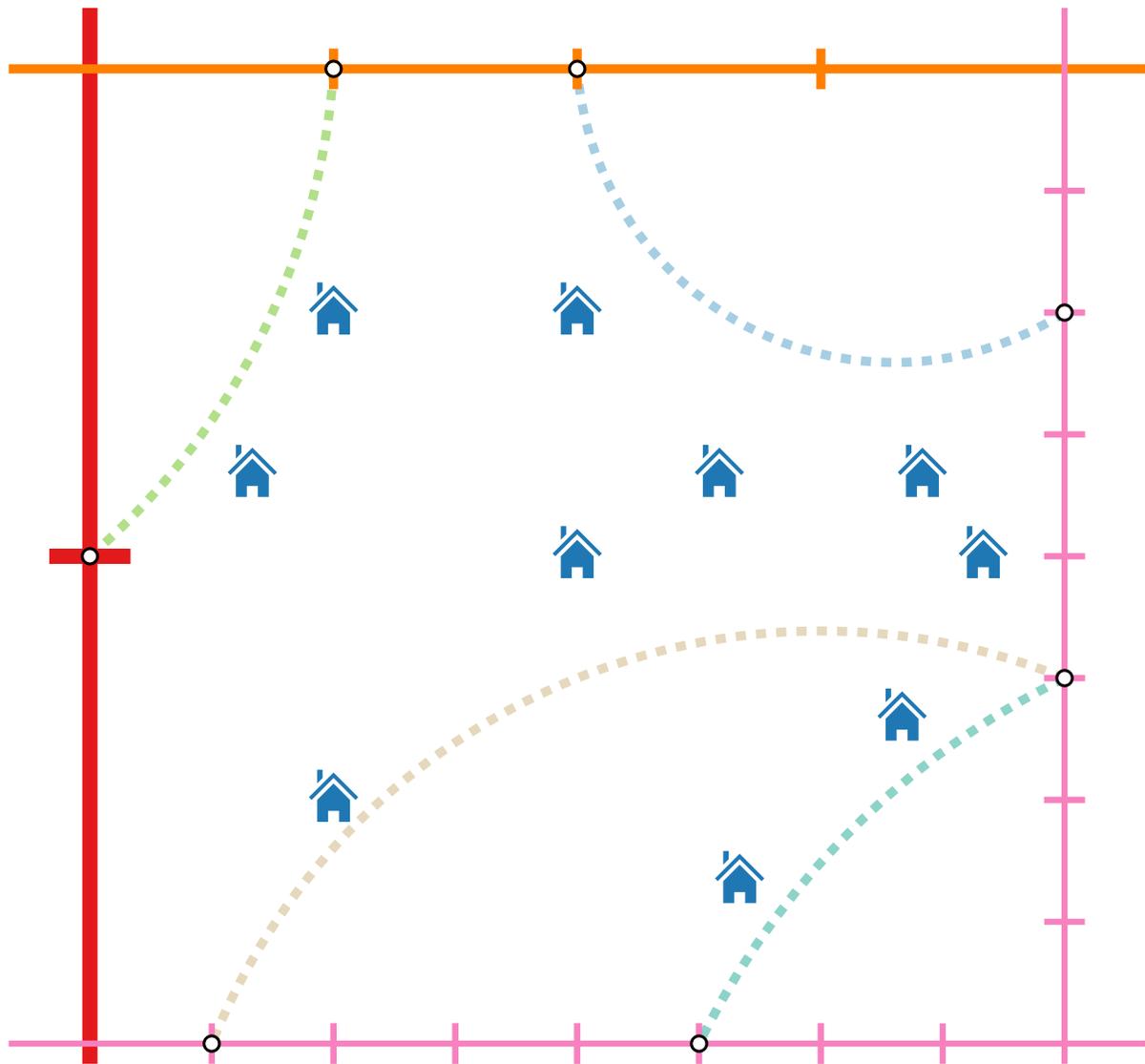
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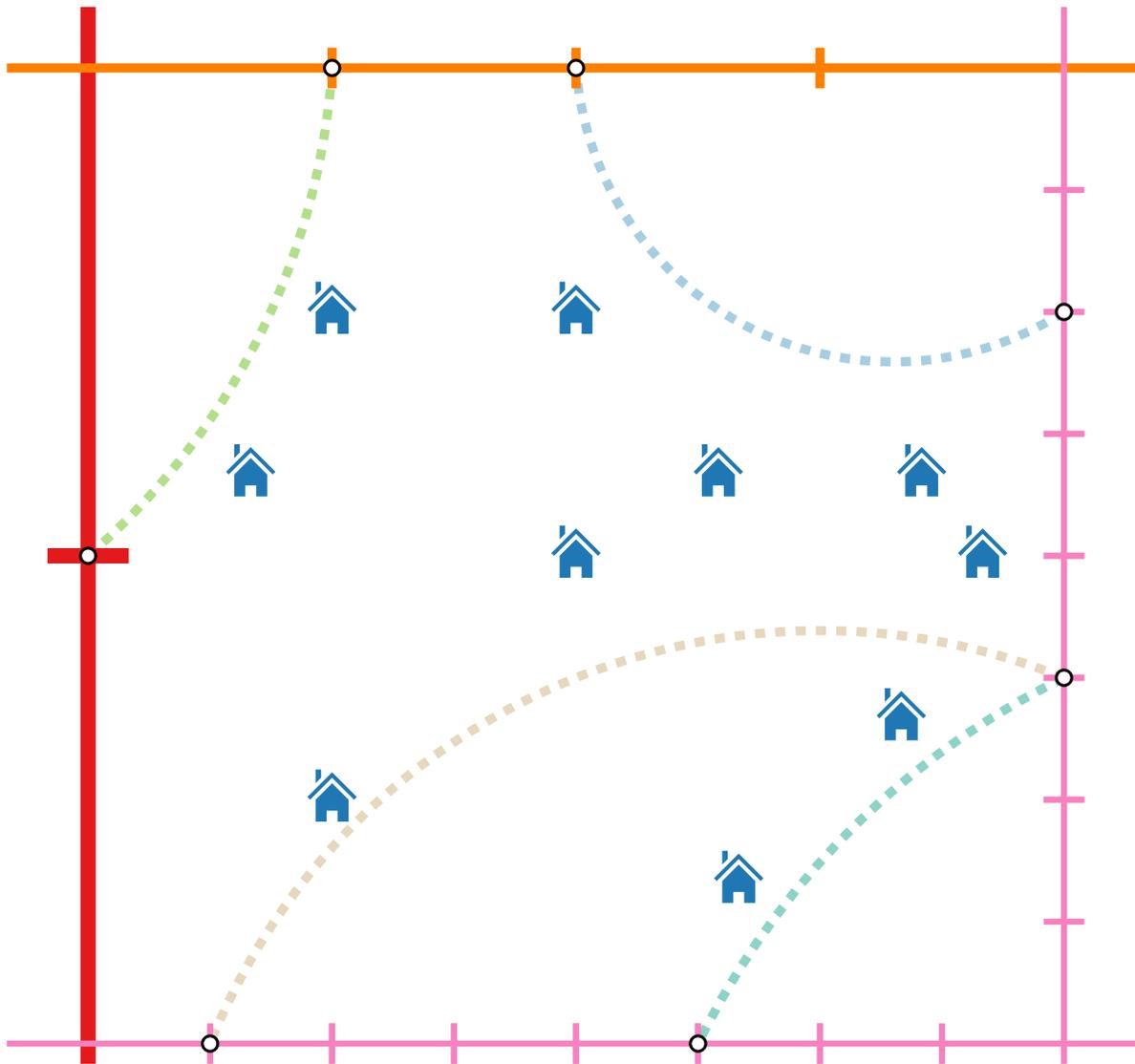
# Dynamic Program (II)



Compute

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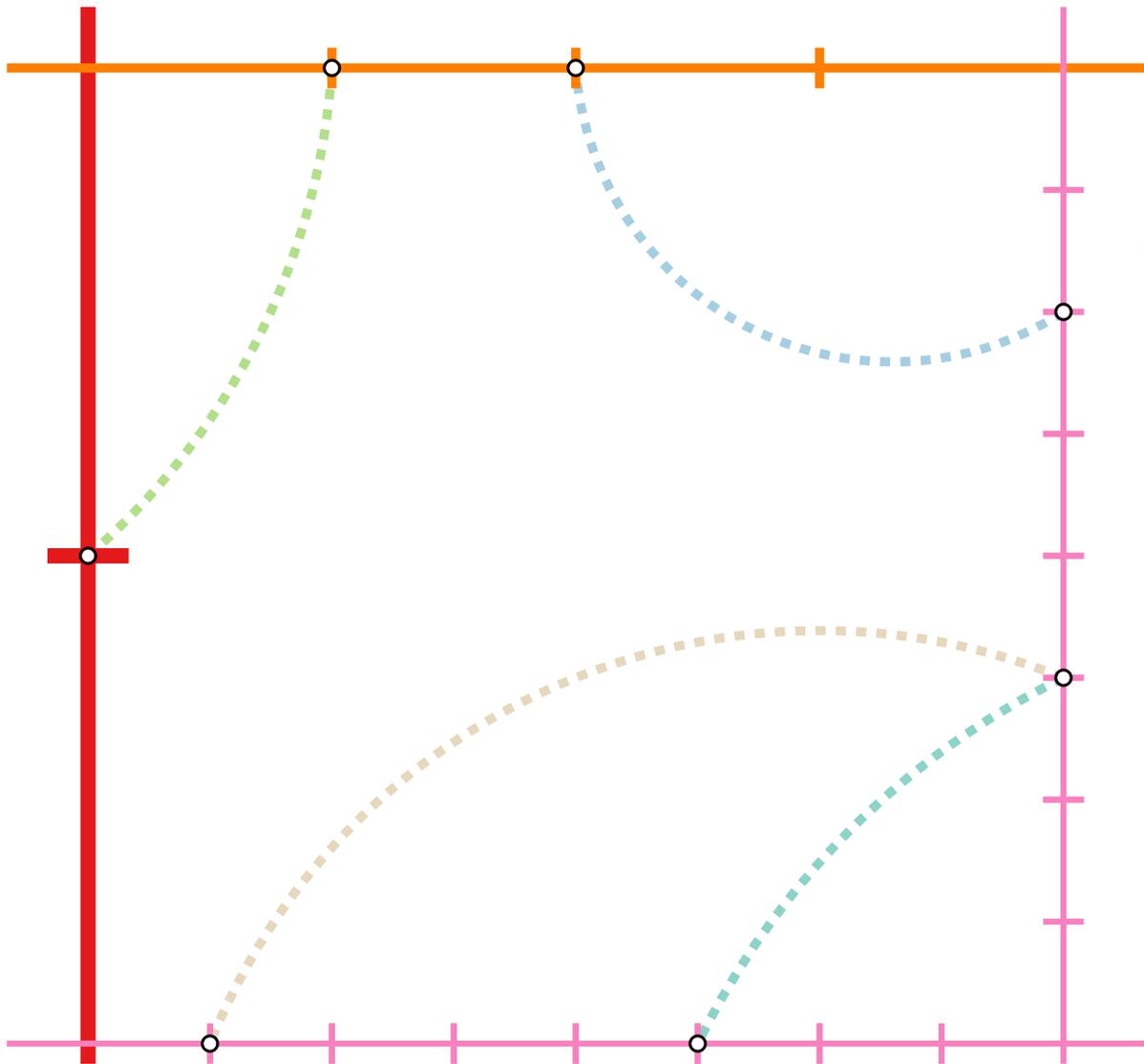


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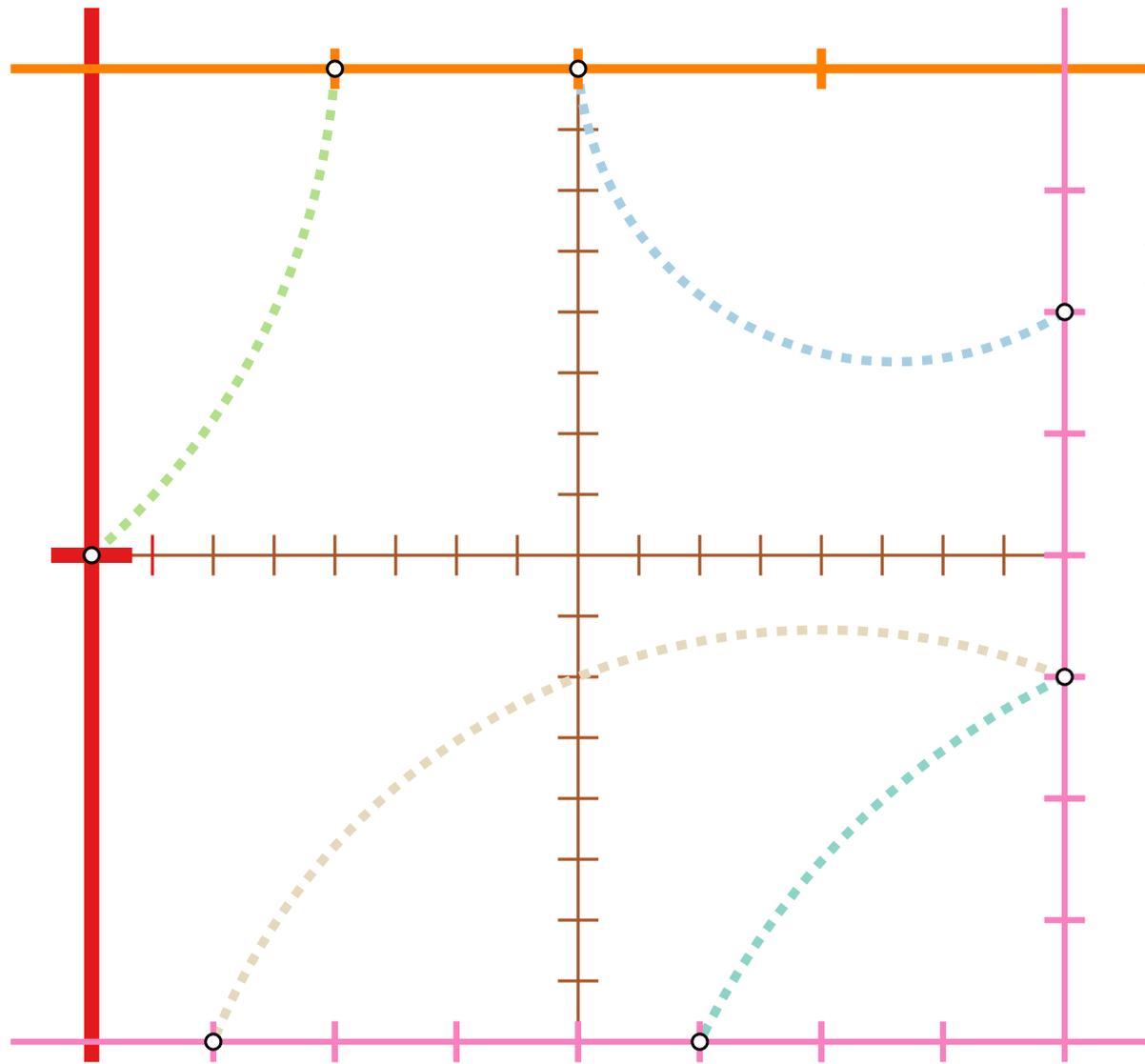
an optimal path cover that respects  $P$ .

# Dynamic Program (III)



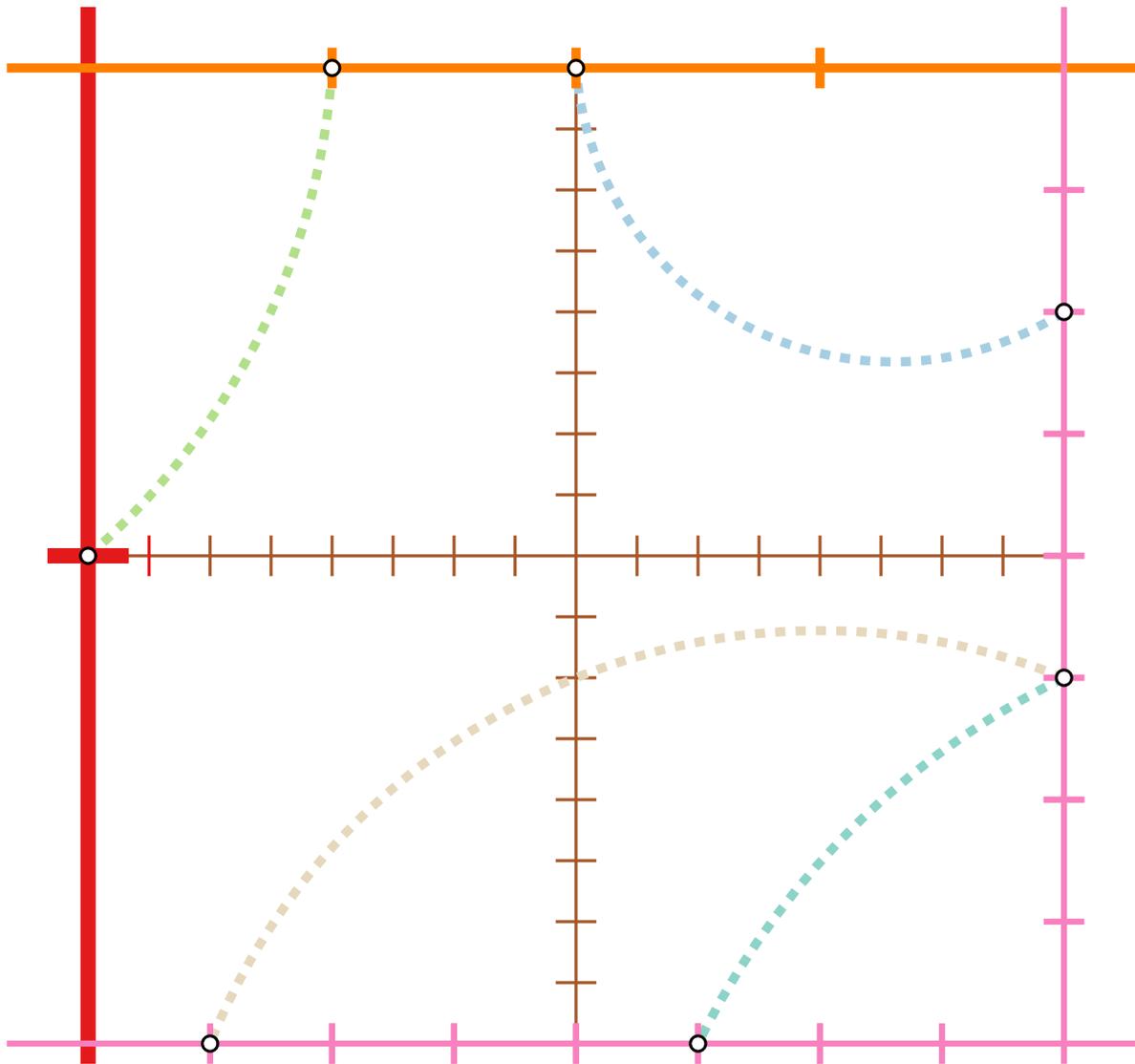
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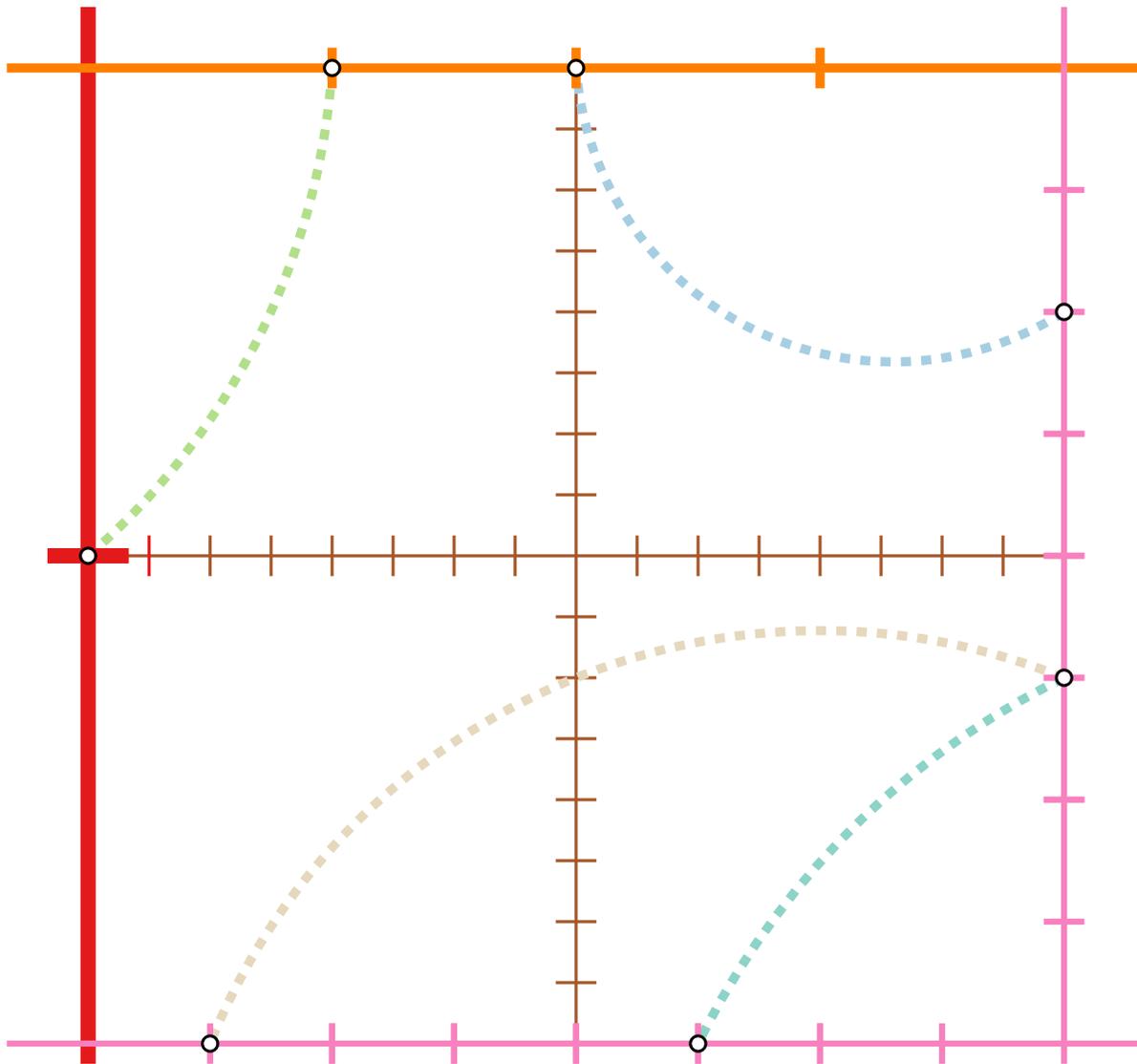


For a given square  $Q$  and pairing  $P$ :

■ Iterate over all

crossing-free pairings of the child squares.

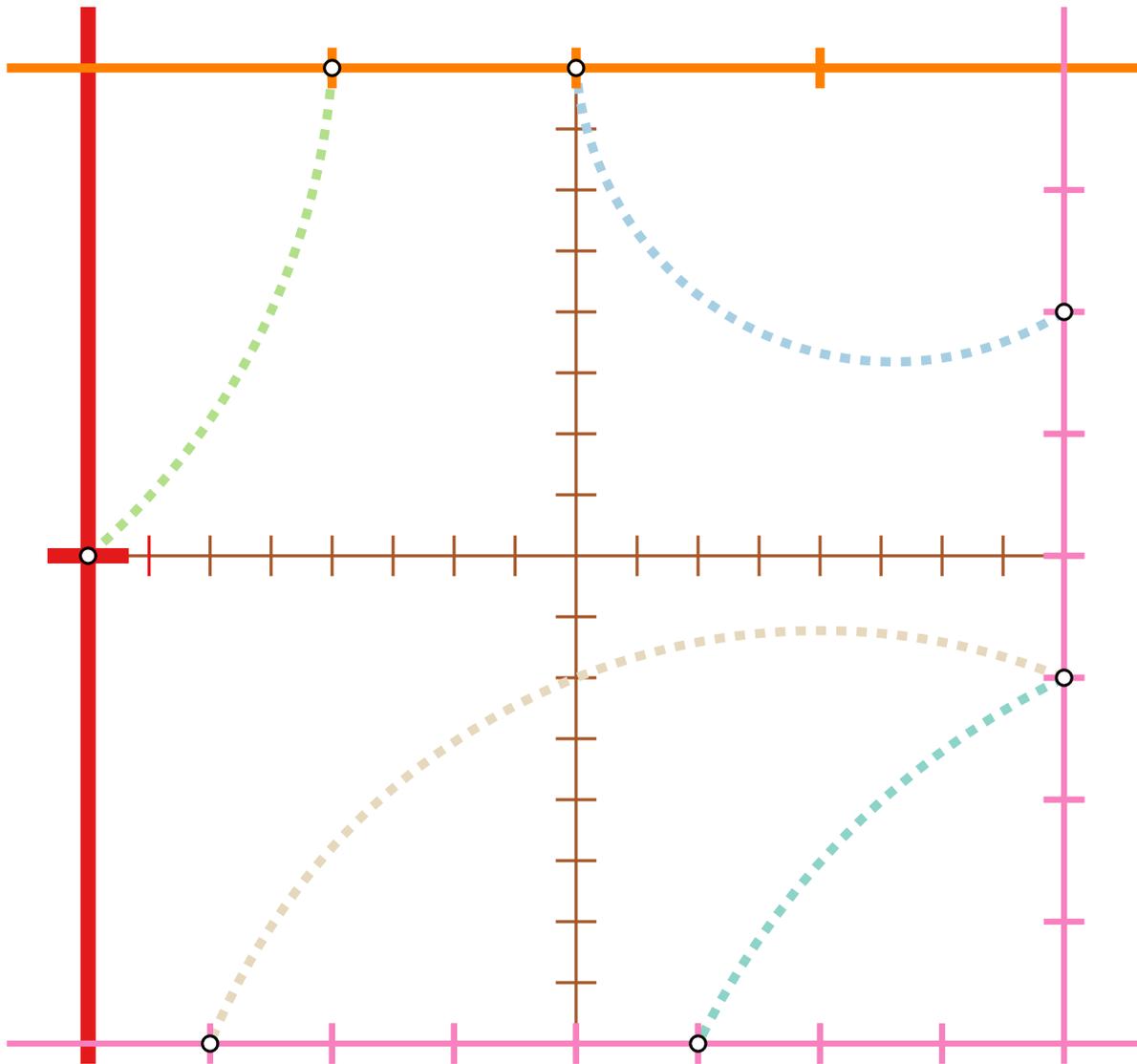
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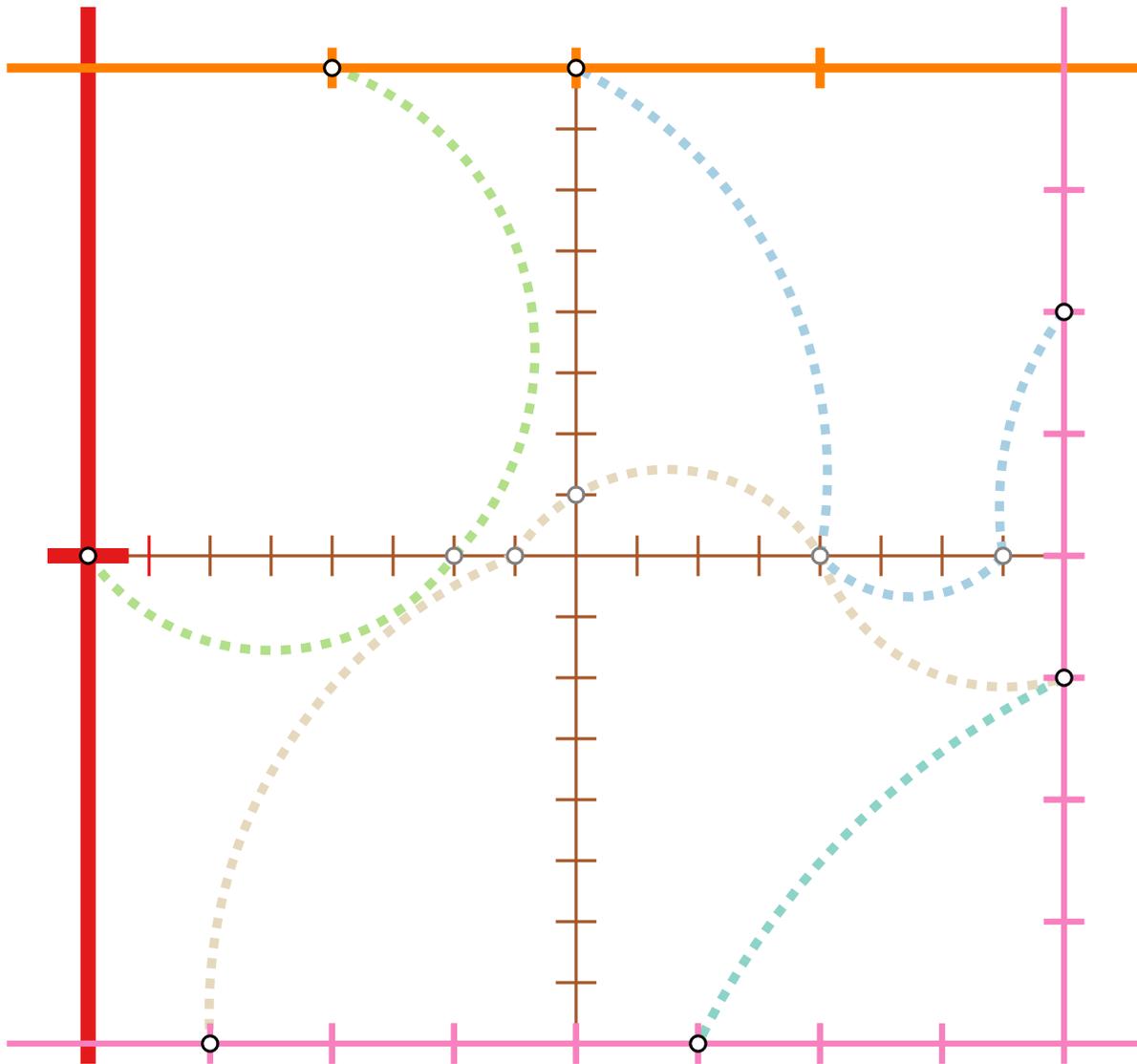
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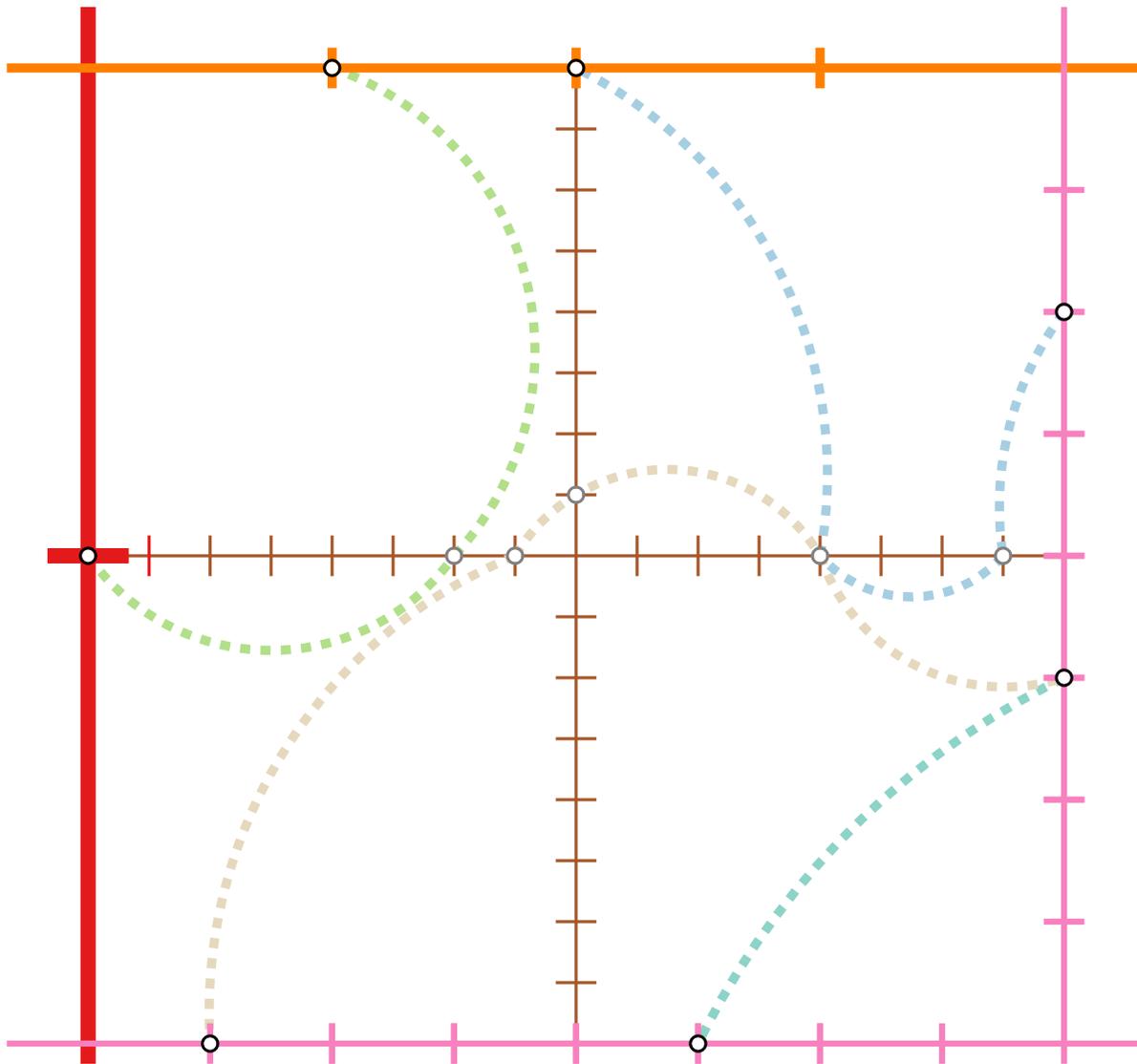
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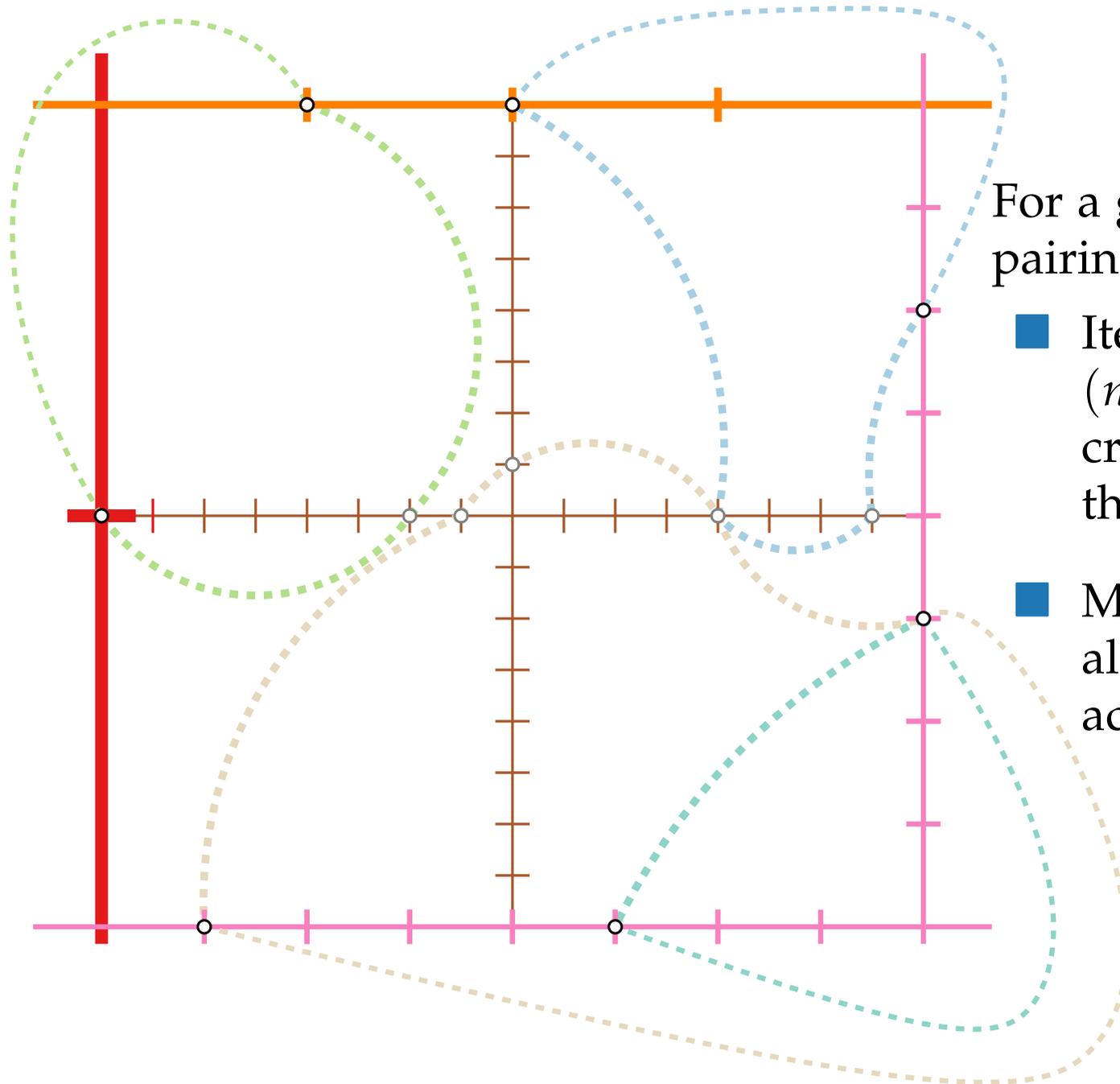
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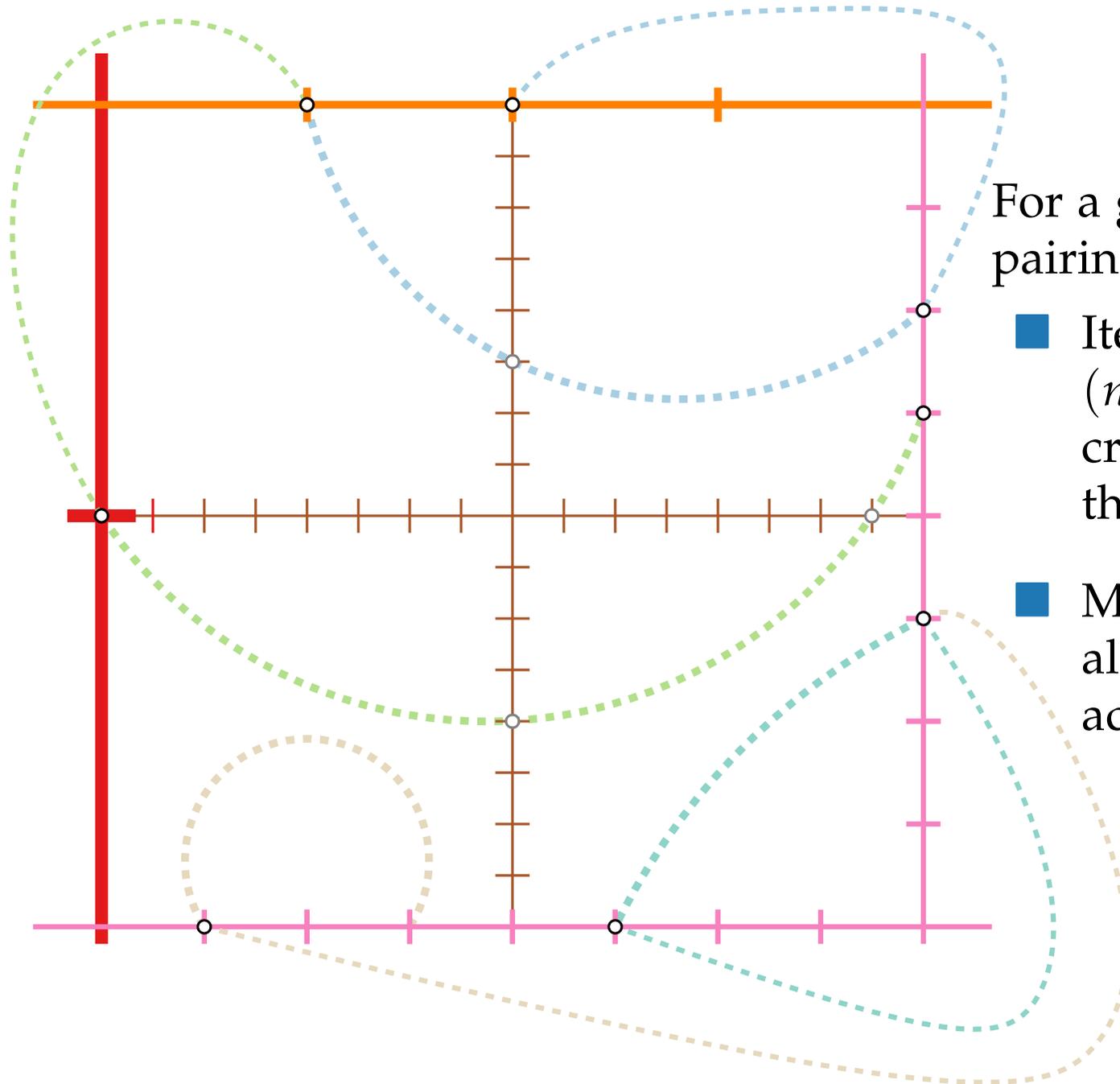
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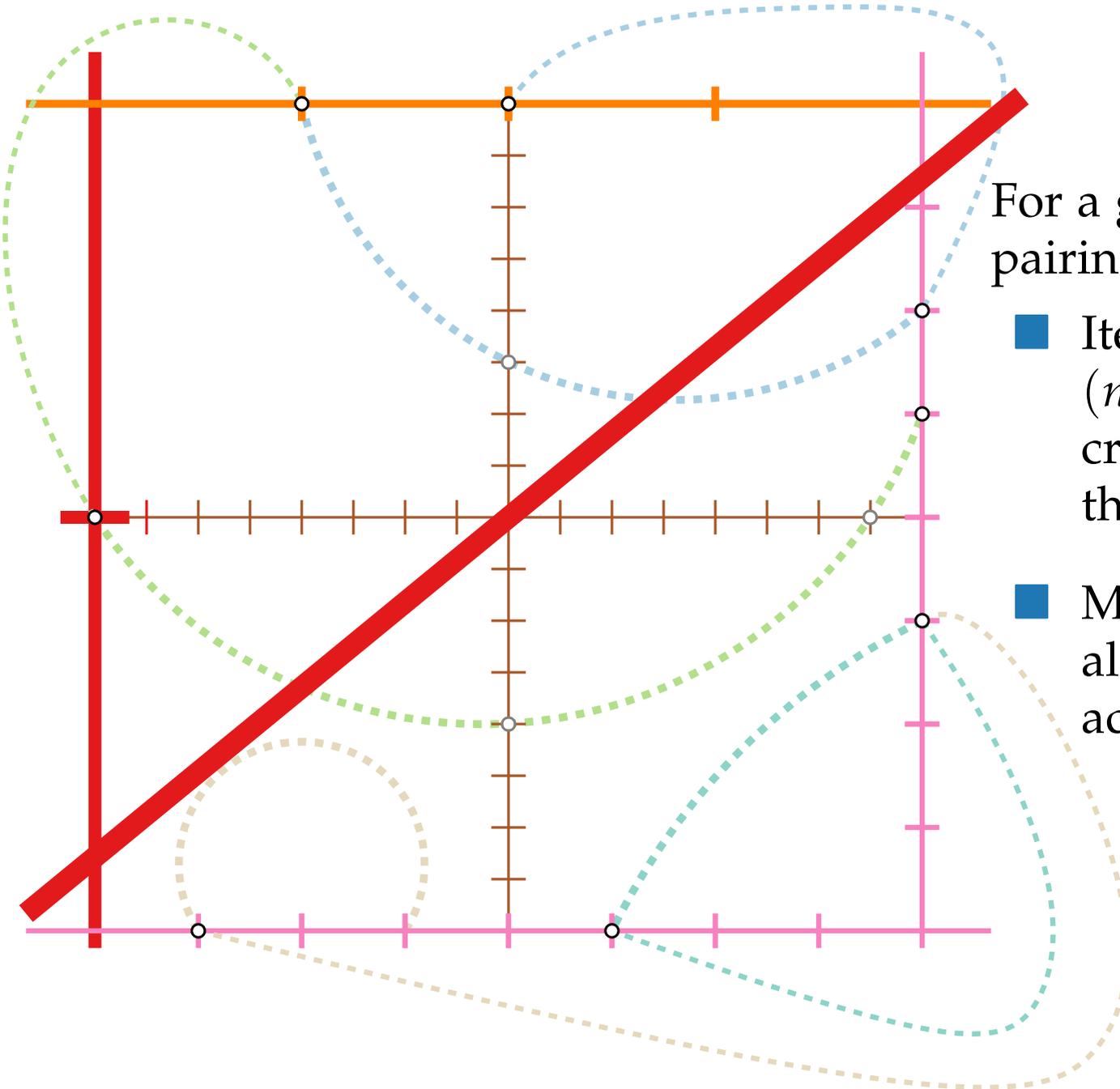
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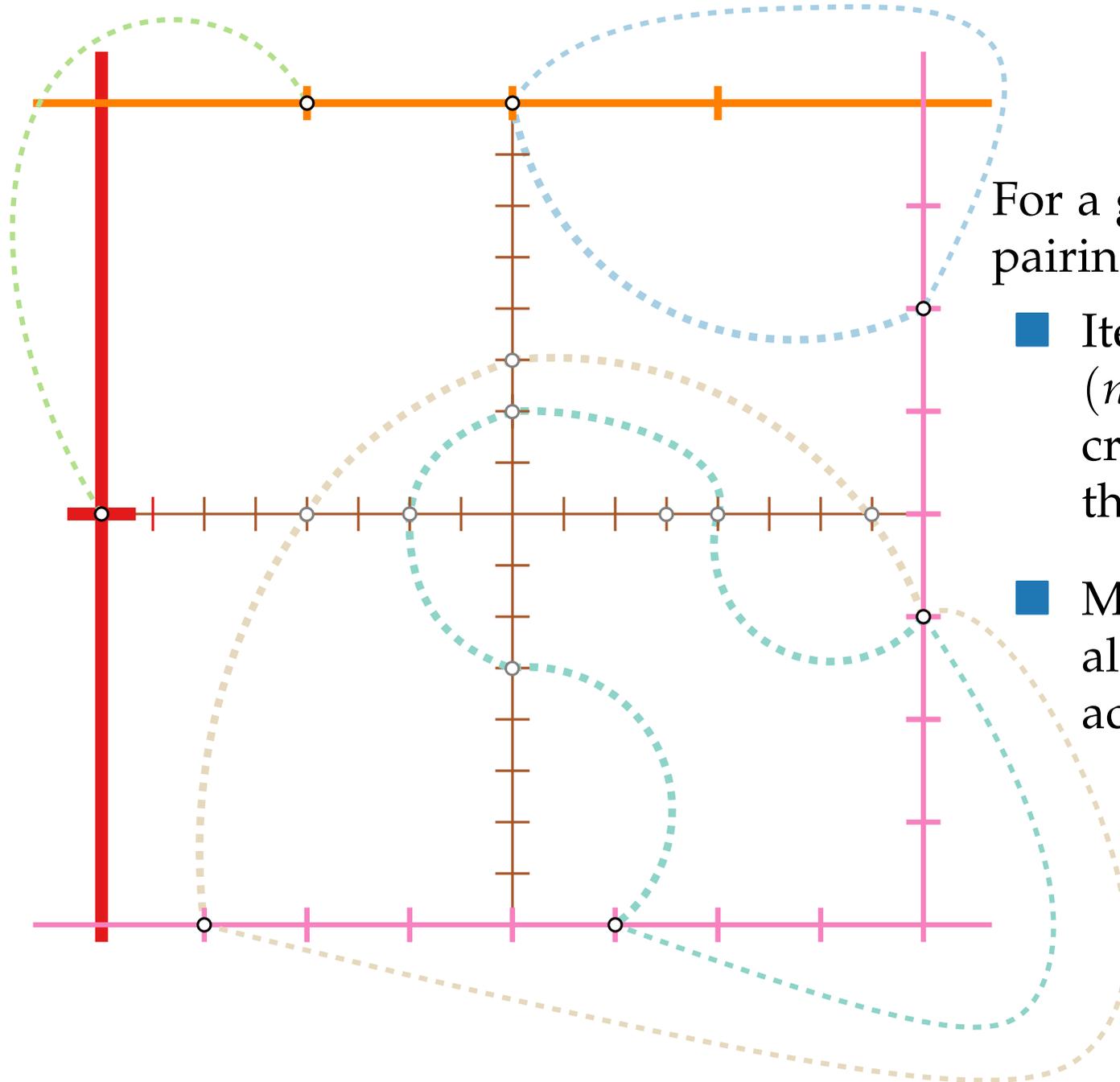
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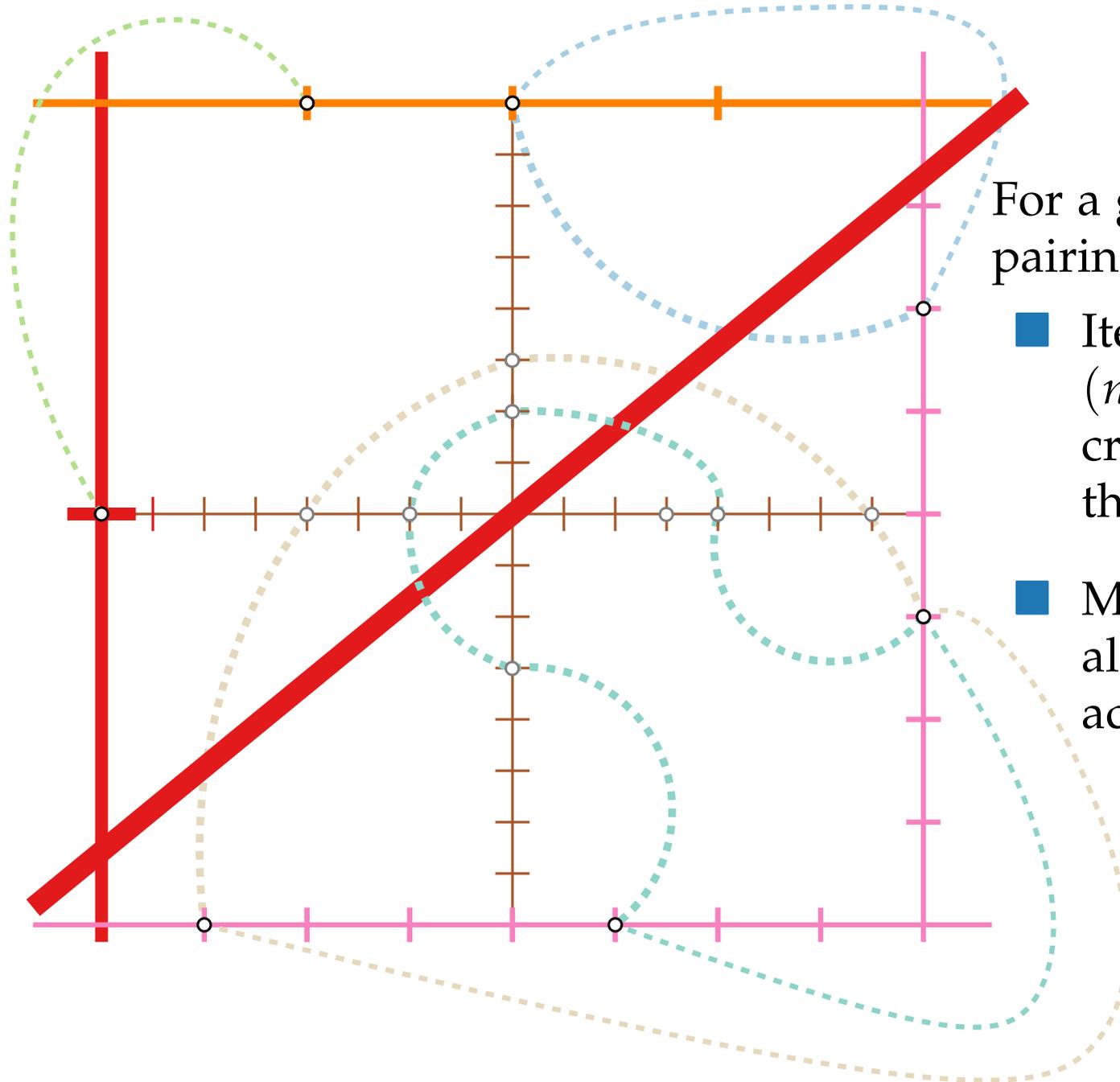
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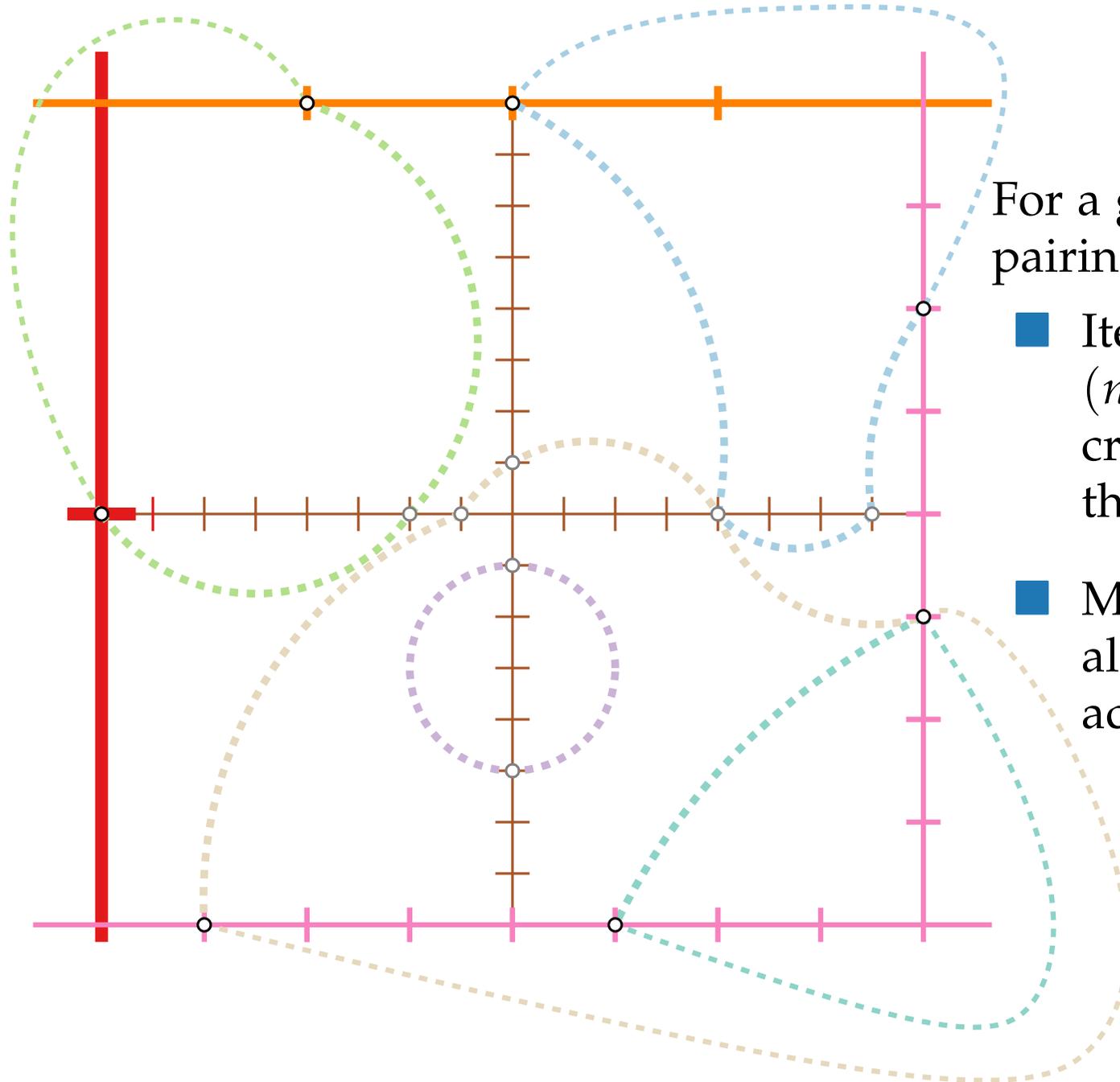
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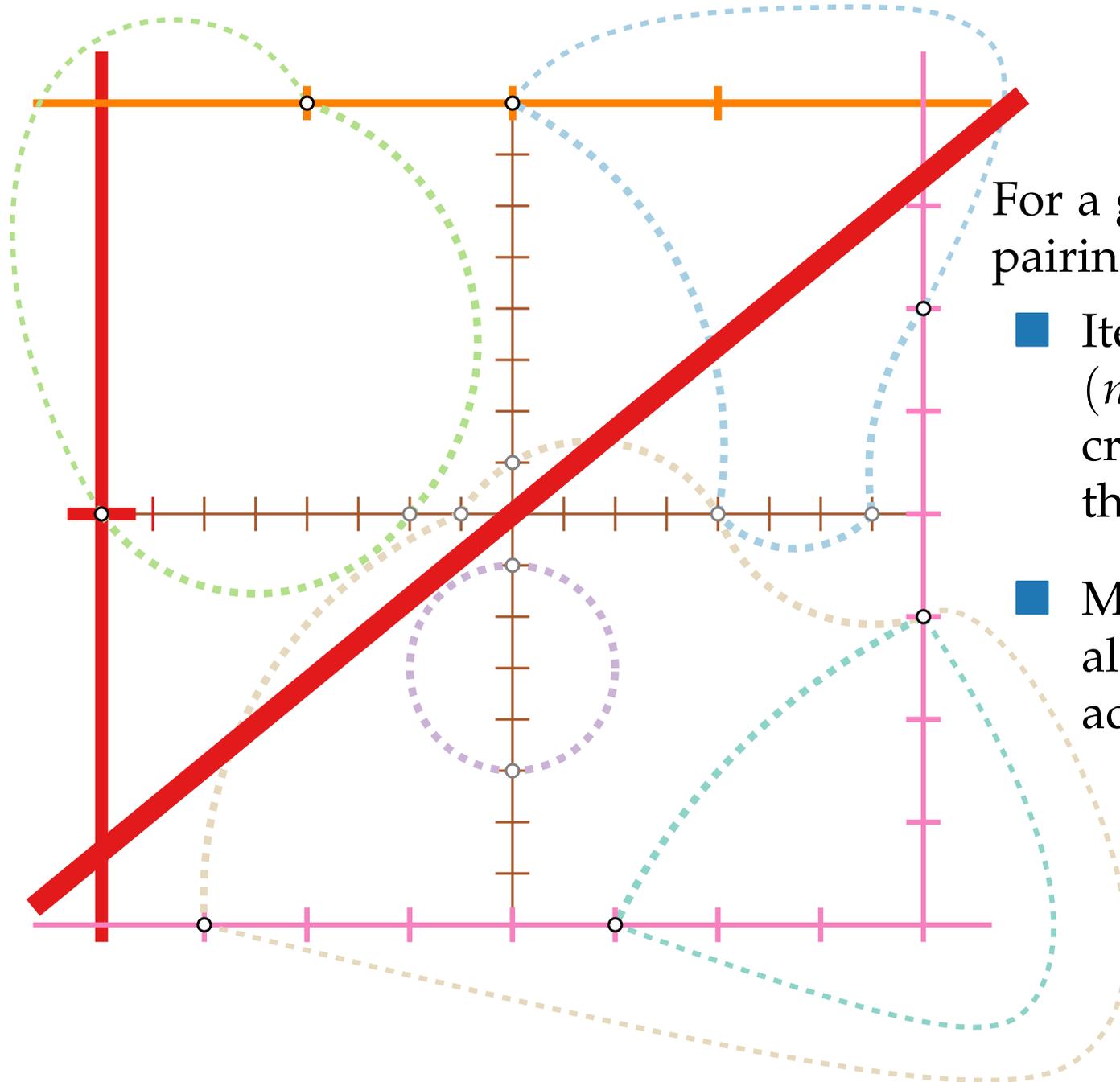
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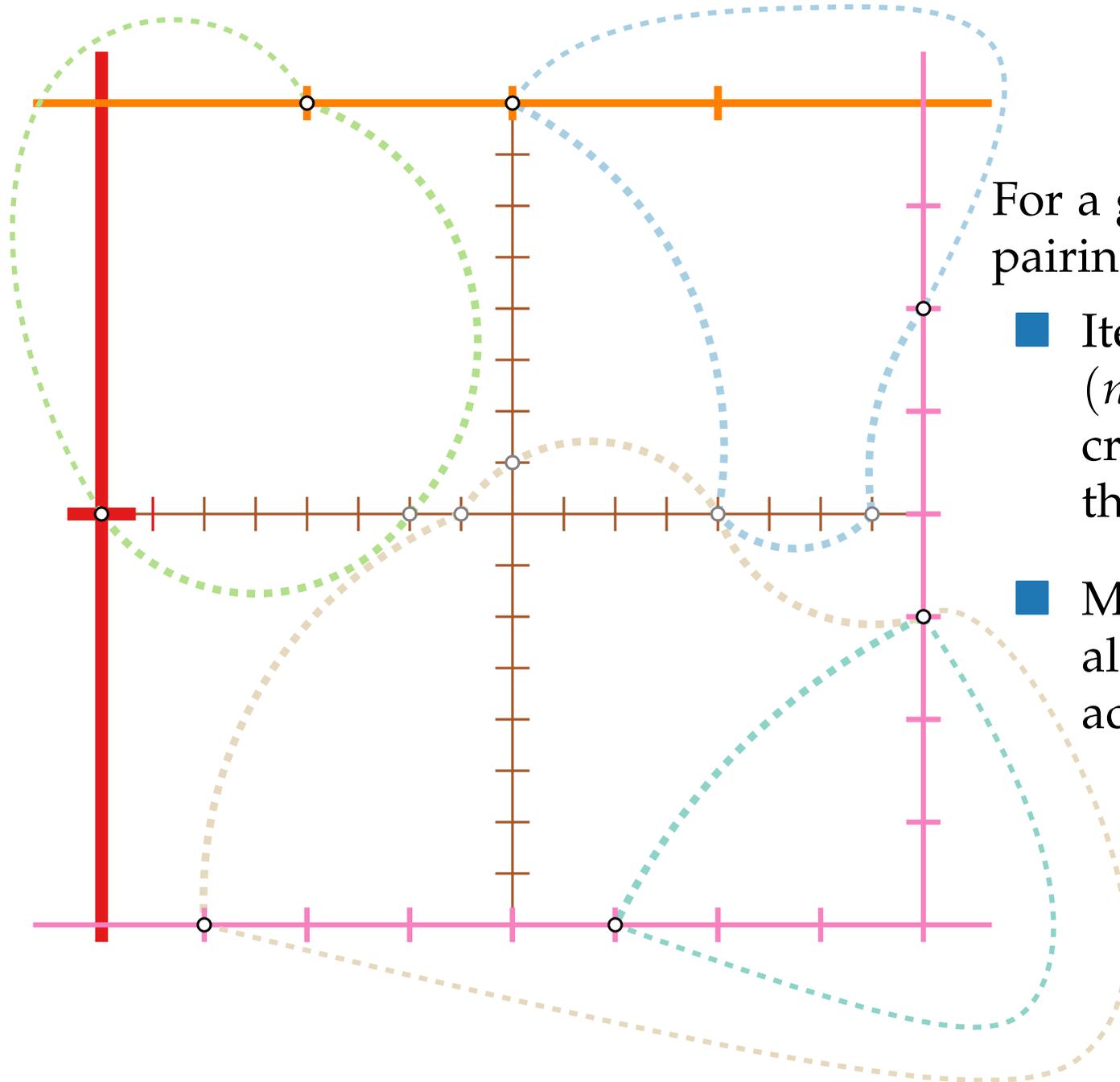
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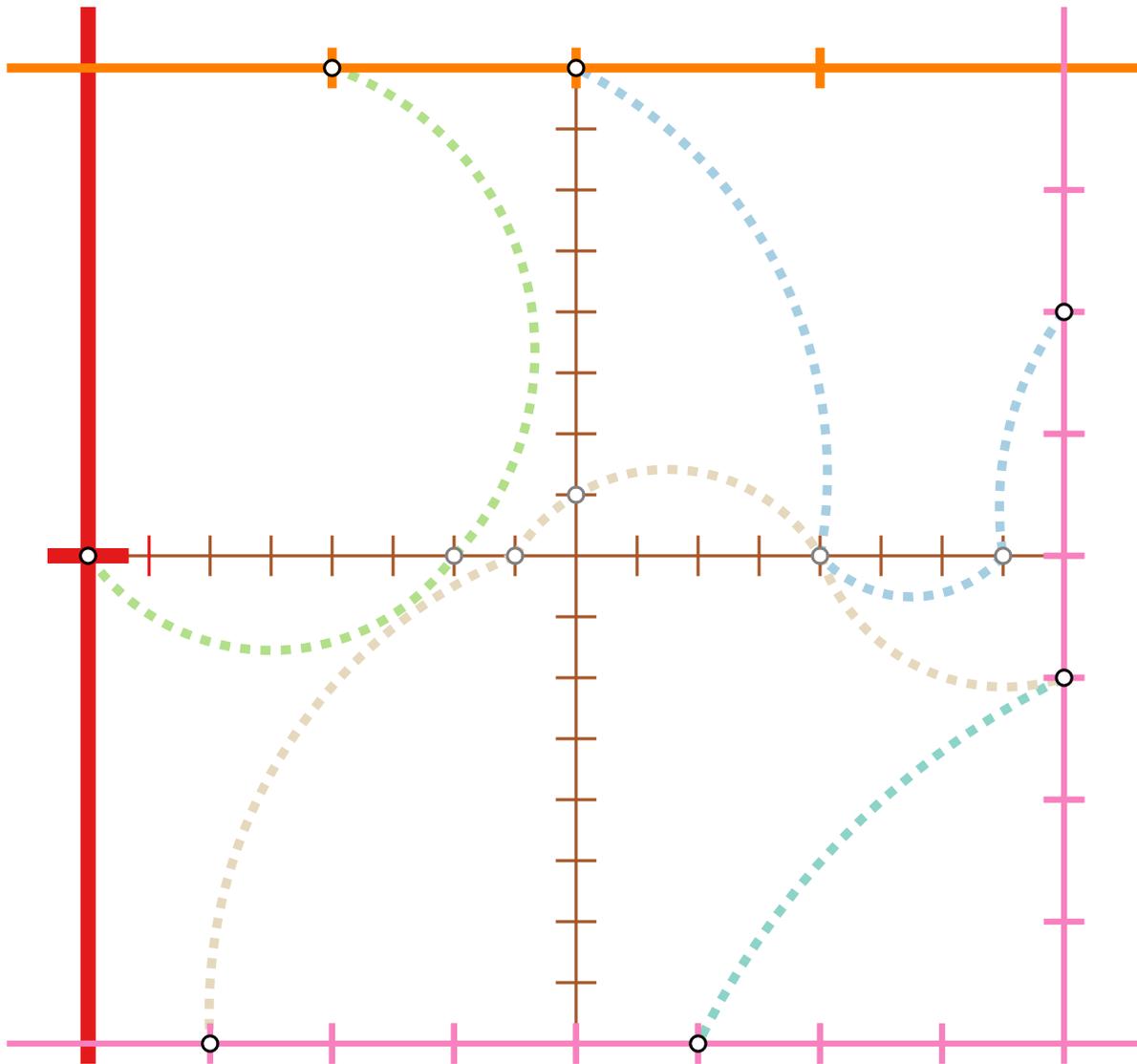
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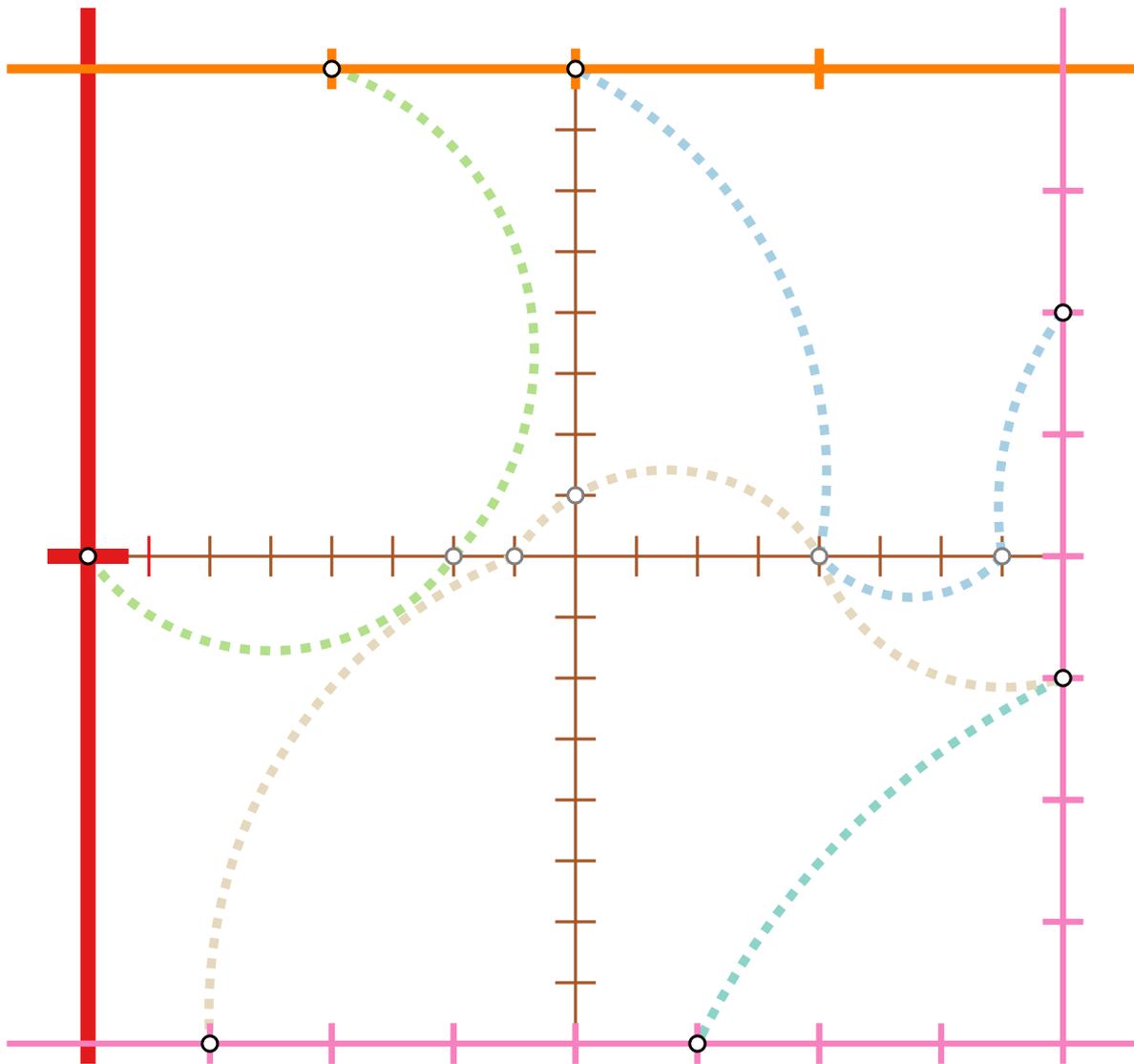
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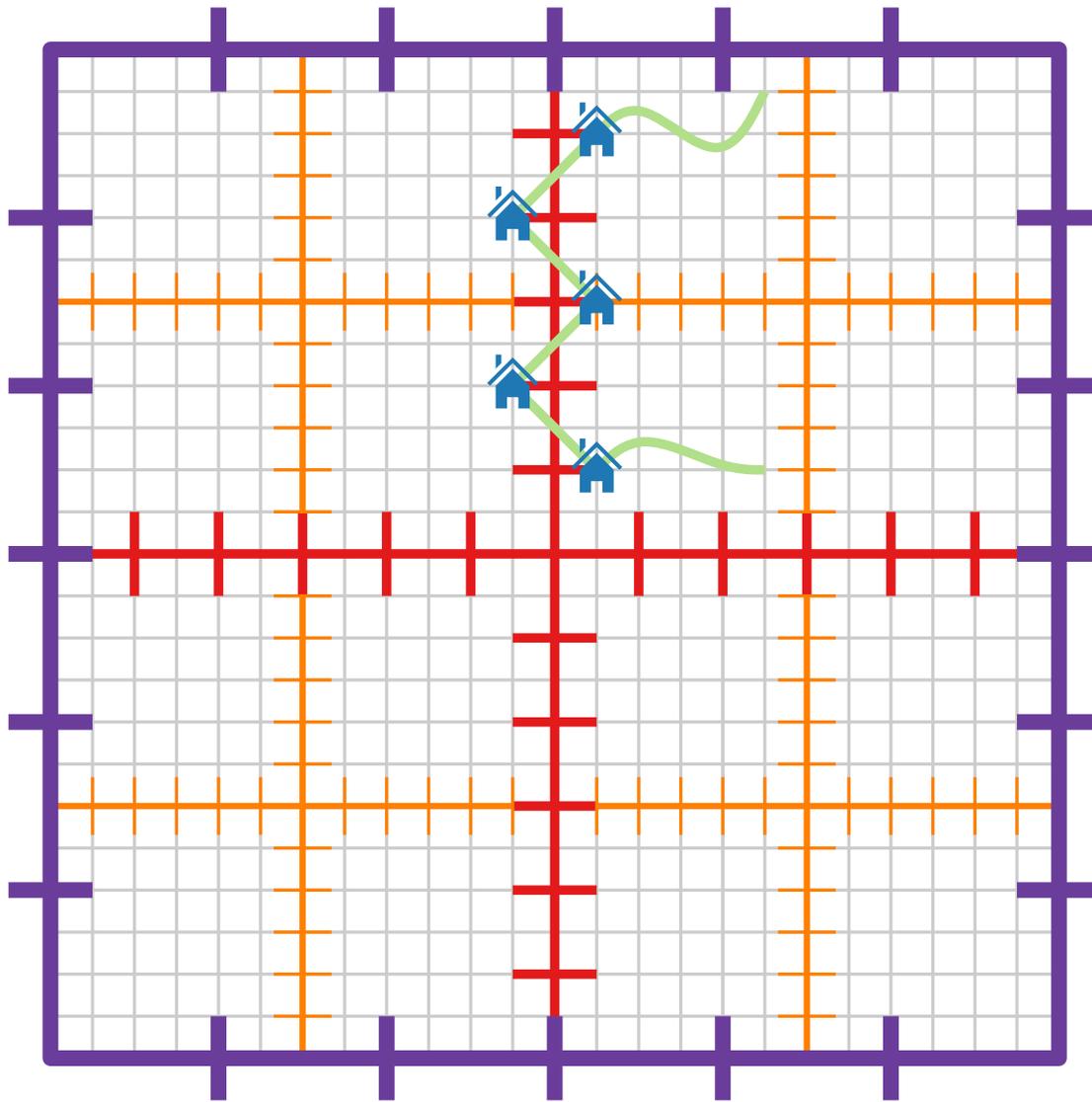
**Lemma.** An optimal well-behaved tour can be computed in  $2^{O(m)} = n^{O(1/\varepsilon)}$  time.

# Approximation Algorithms

## Lecture 9: A PTAS for EUCLIDEAN TSP

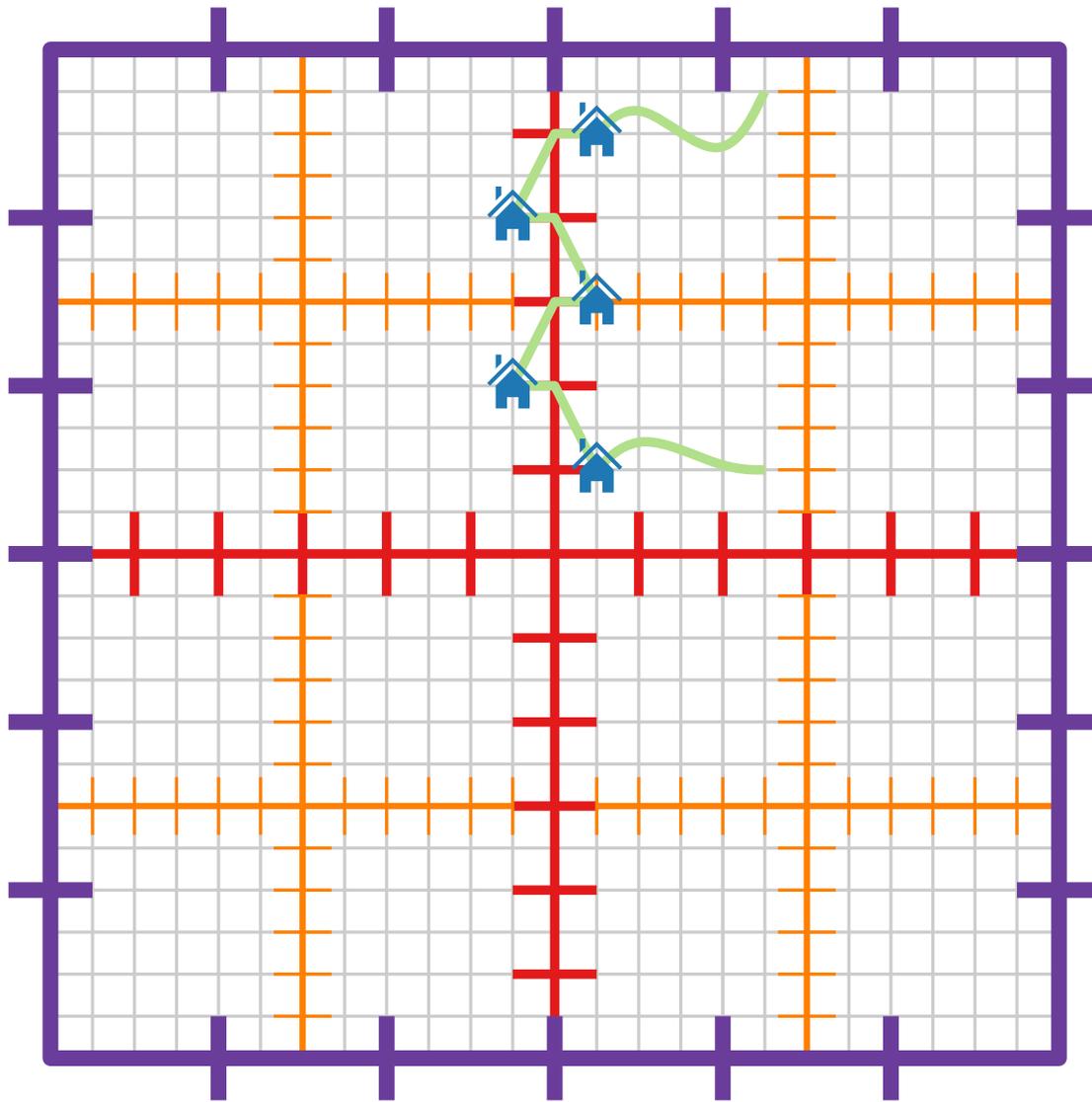
### Part V: Shifted Dissections

# Shifted Dissections



- The best well-behaved tour can be a bad approximation.

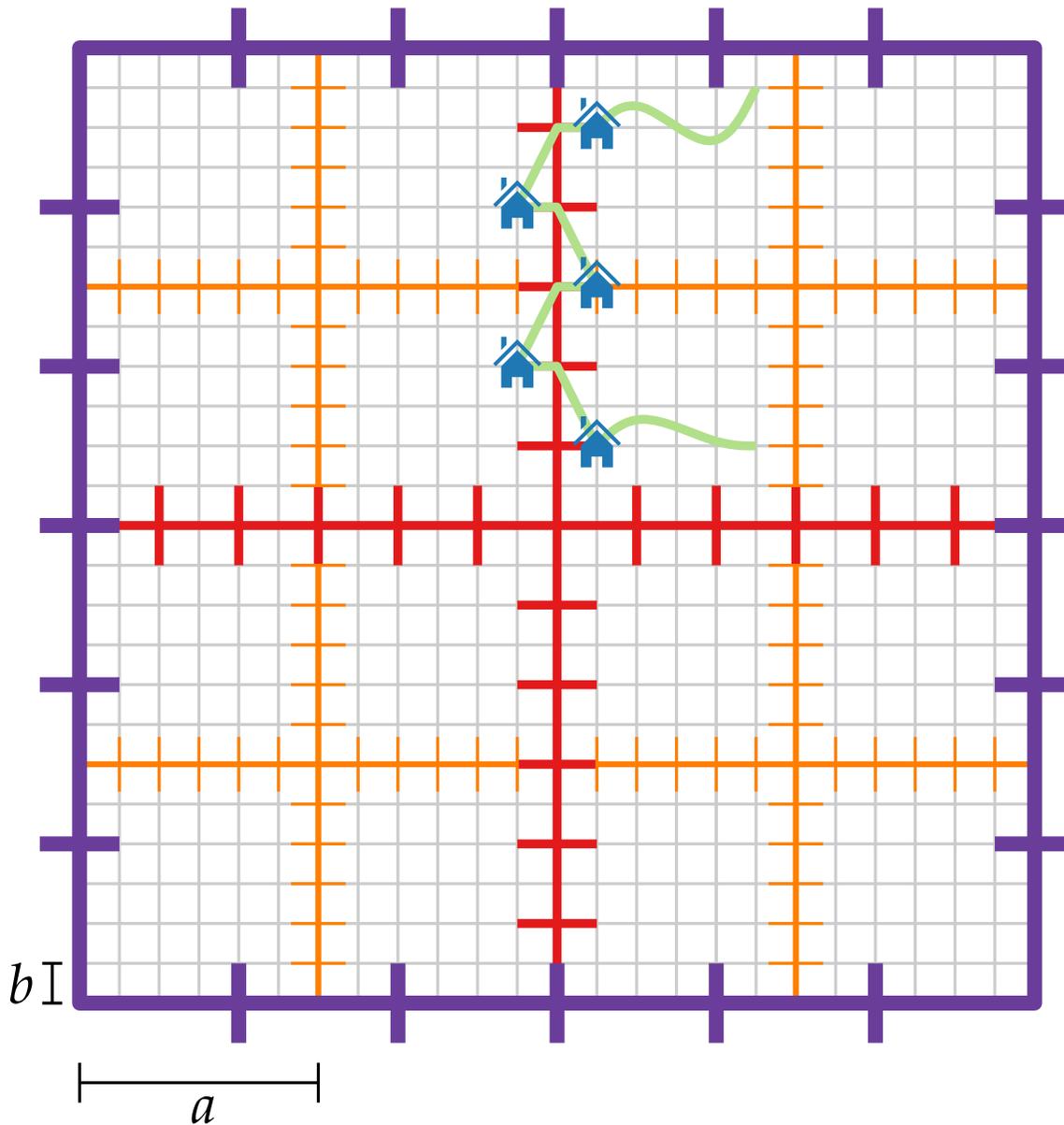
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# Shifted Dissections



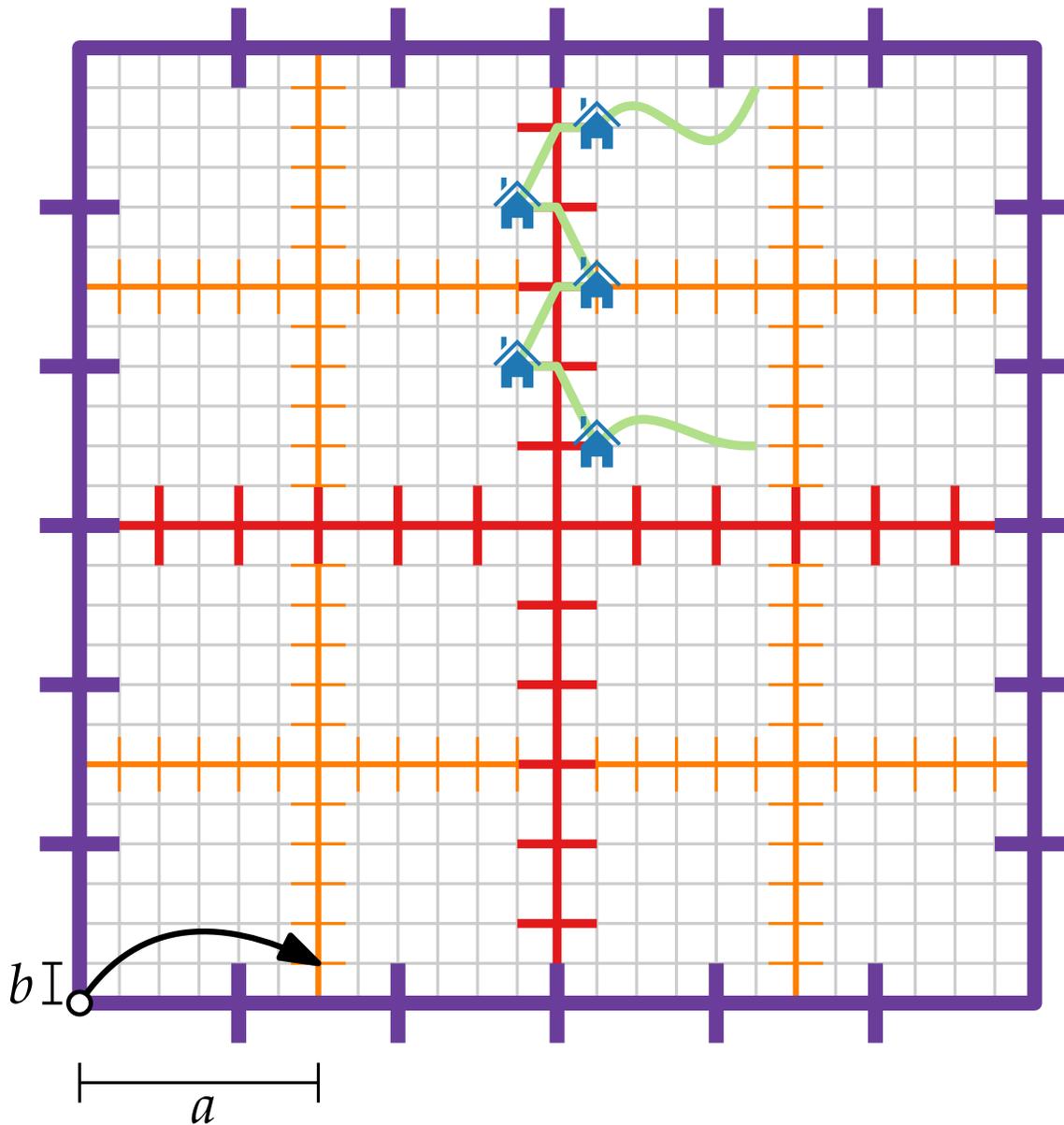
■ The best well-behaved tour can be a bad approximation.

■ Consider an  $(a, b)$ -shifted dissection:

$$x \mapsto (x + a) \bmod L$$

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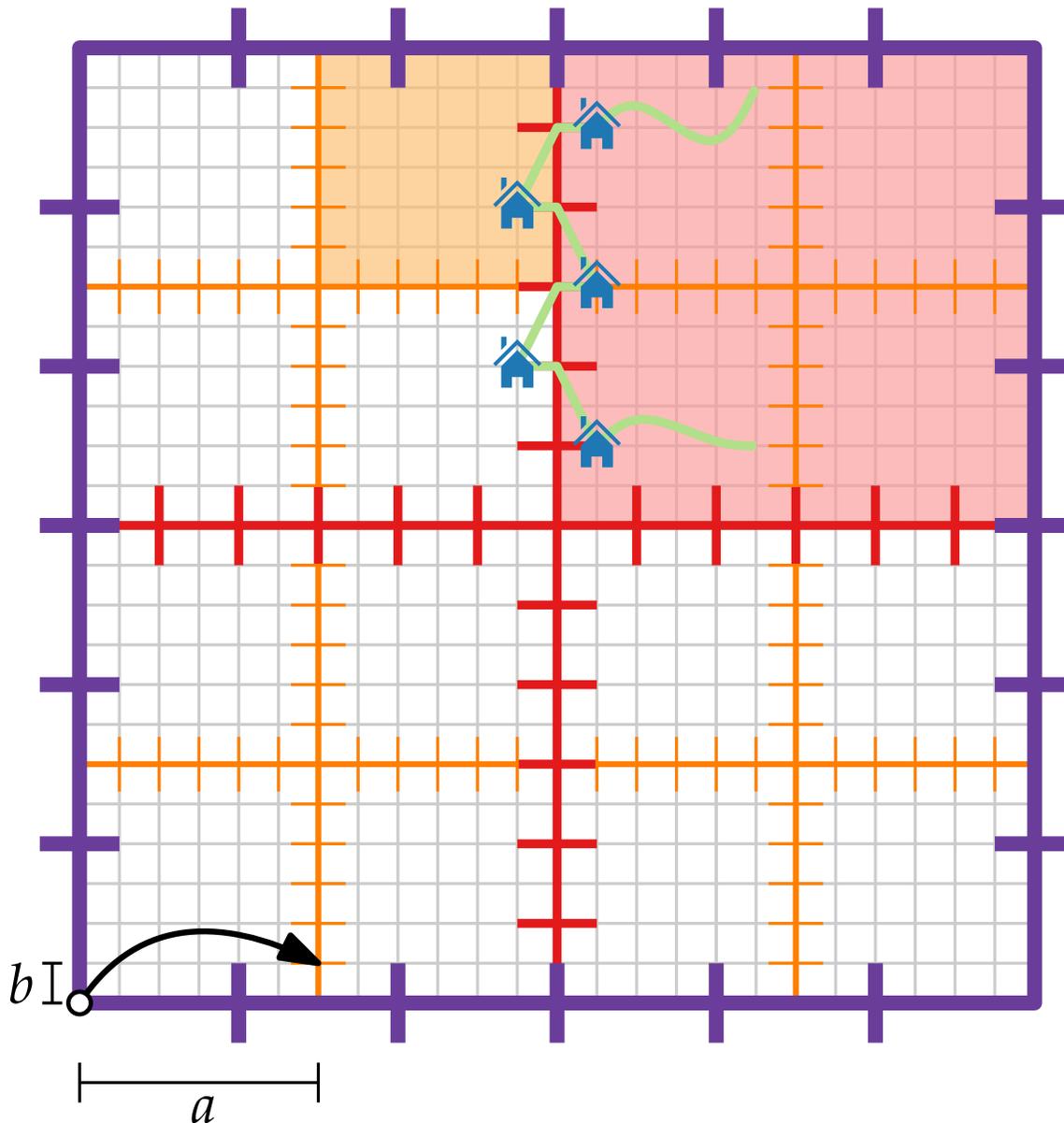


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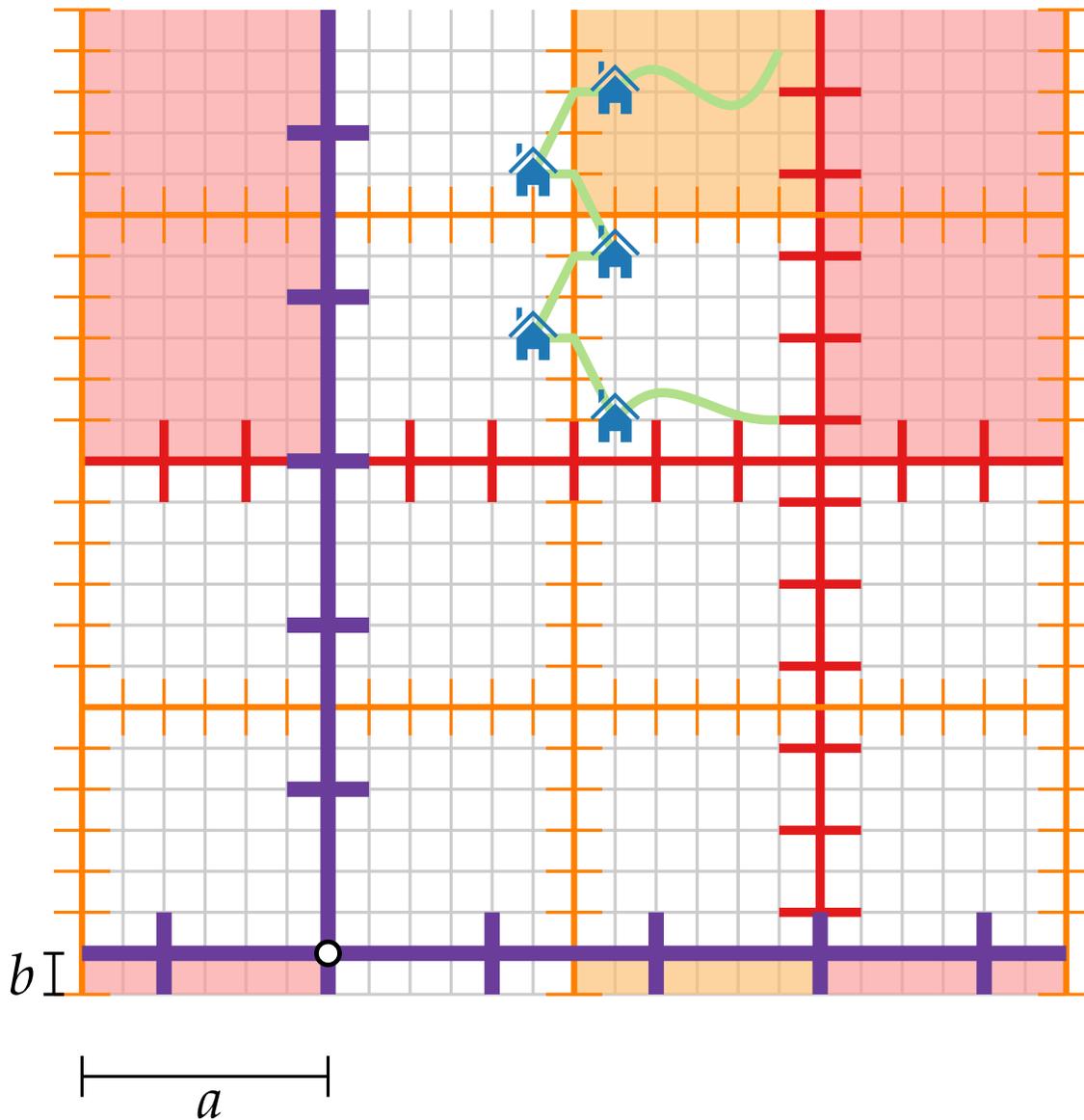
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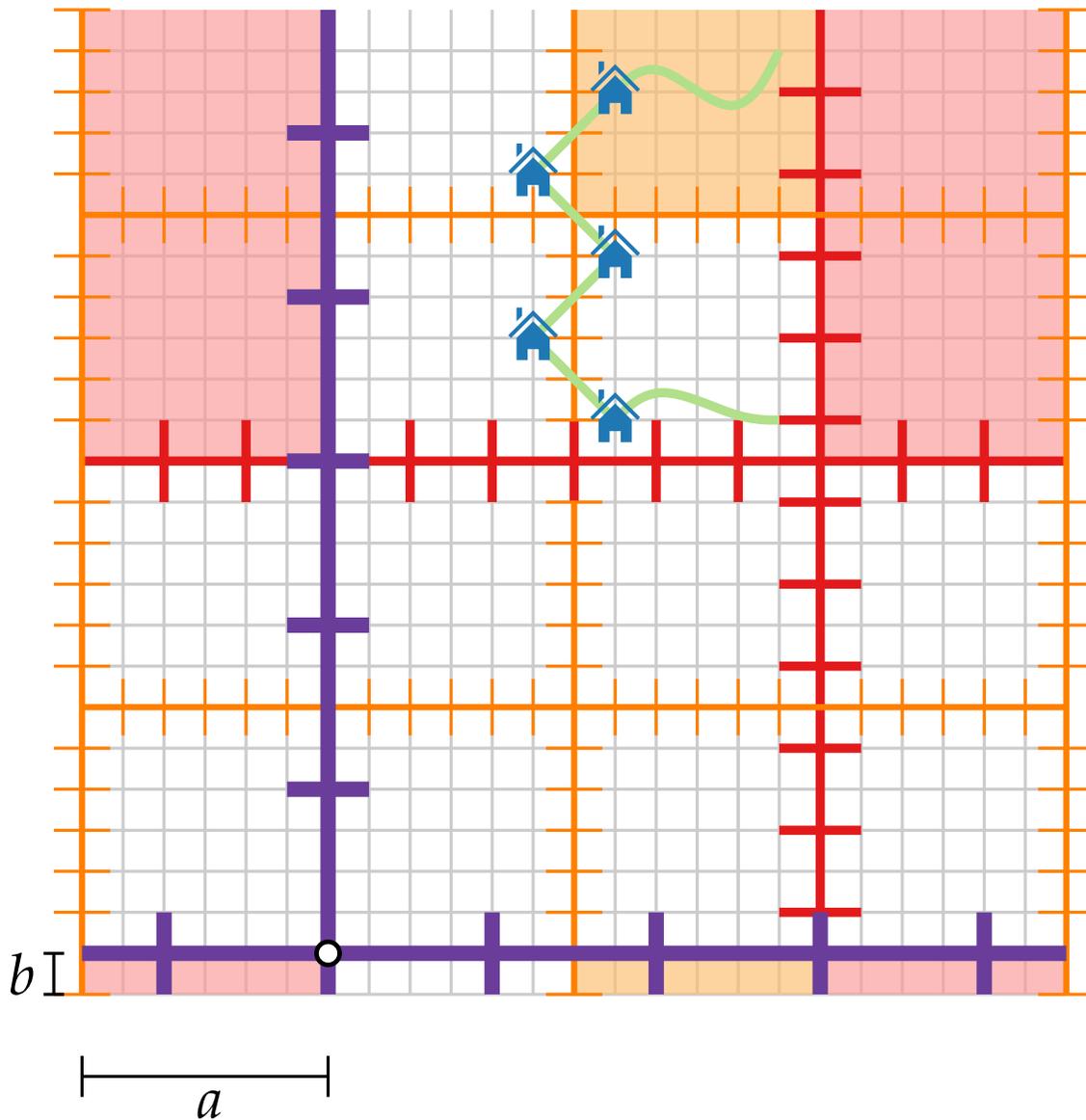


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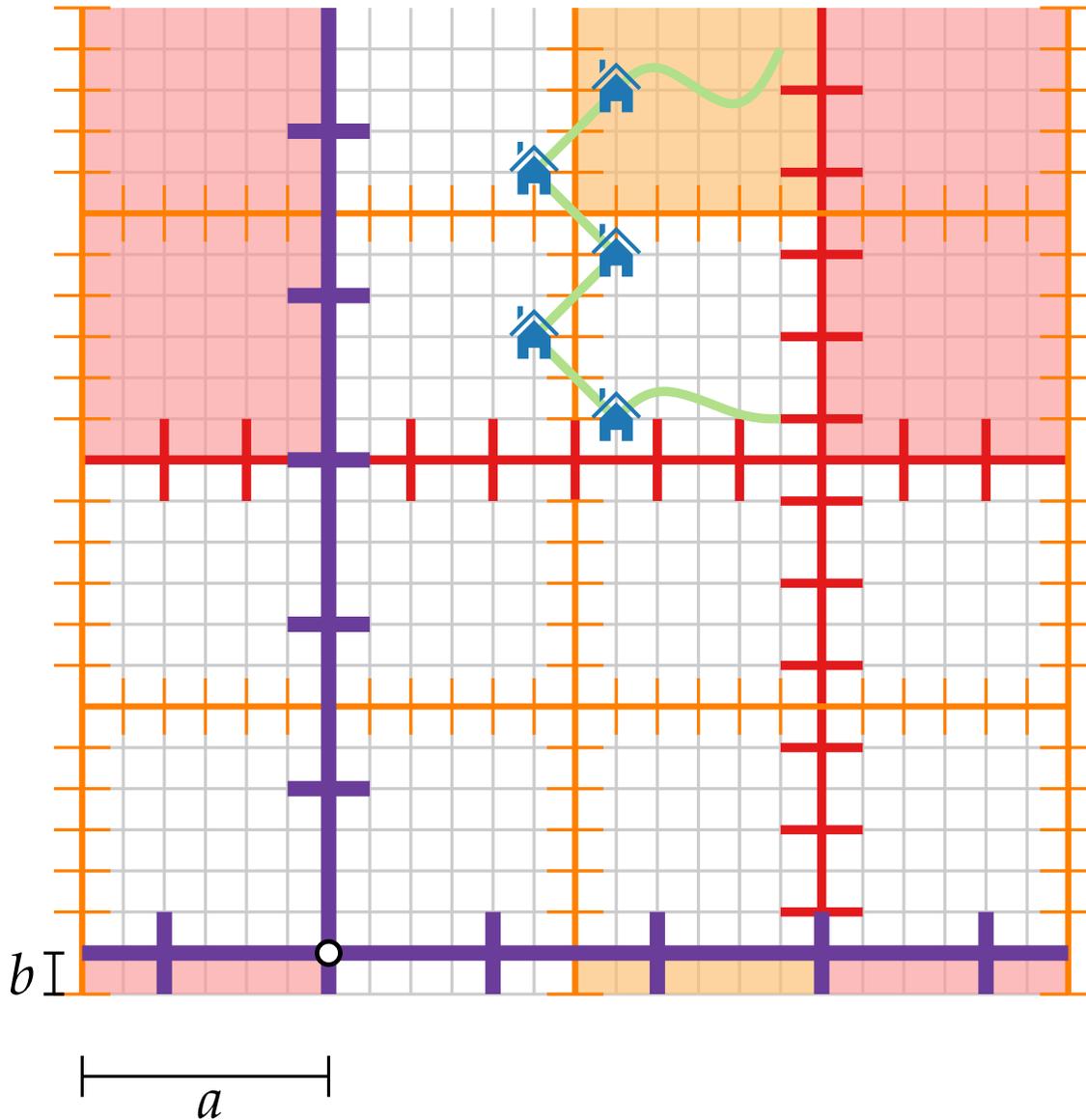


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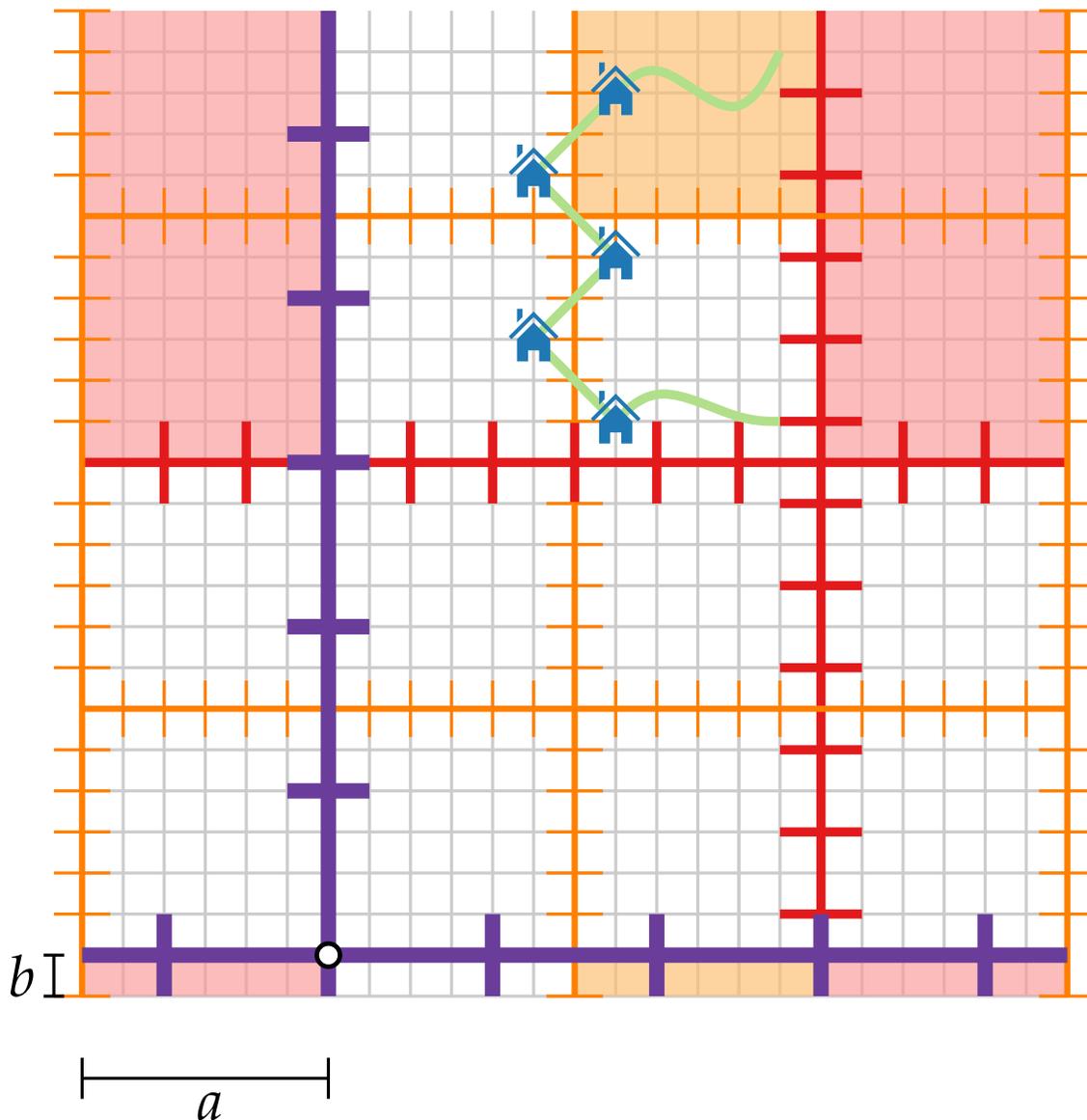
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- Squares in the dissection tree are “wrapped around”.
- Dynamic program must be modified accordingly.

# Shifted Dissections (II)

**Lemma.** Let  $\pi$  be an optimal tour, and let  $N(\pi)$  be the number of crossings of  $\pi$  with the lines of the  $(L \times L)$ -grid.

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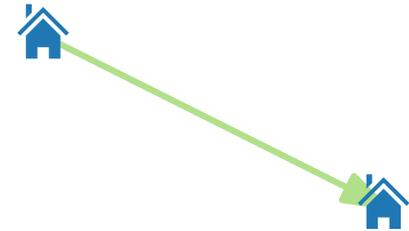
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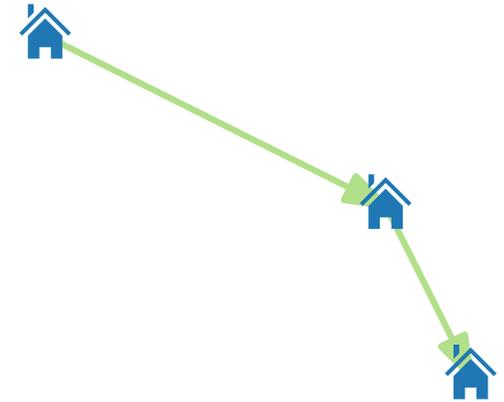


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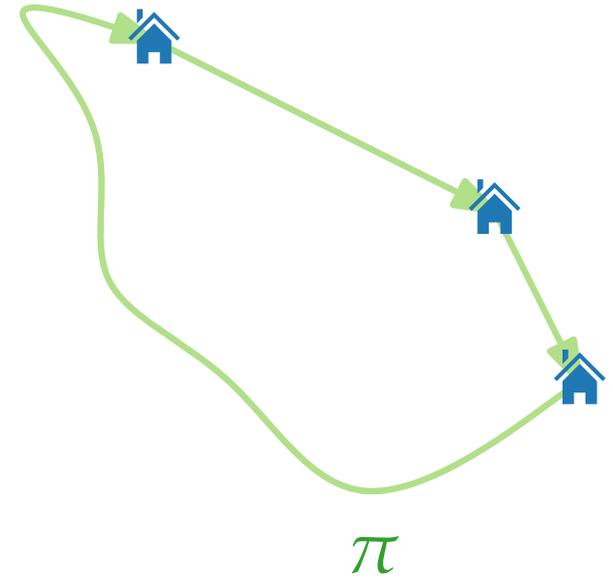


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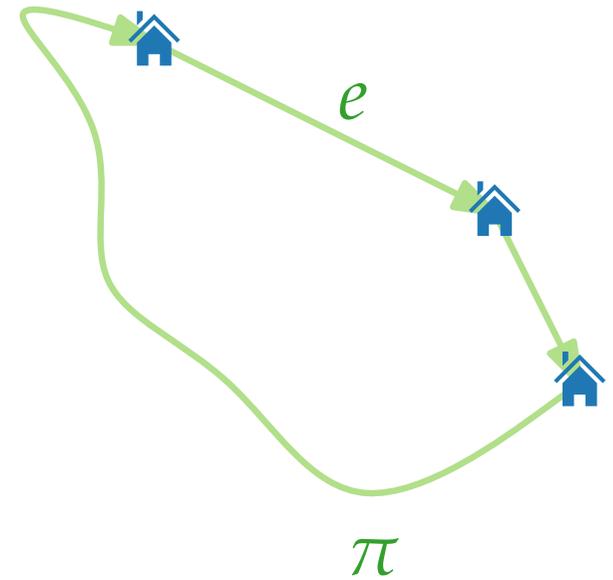
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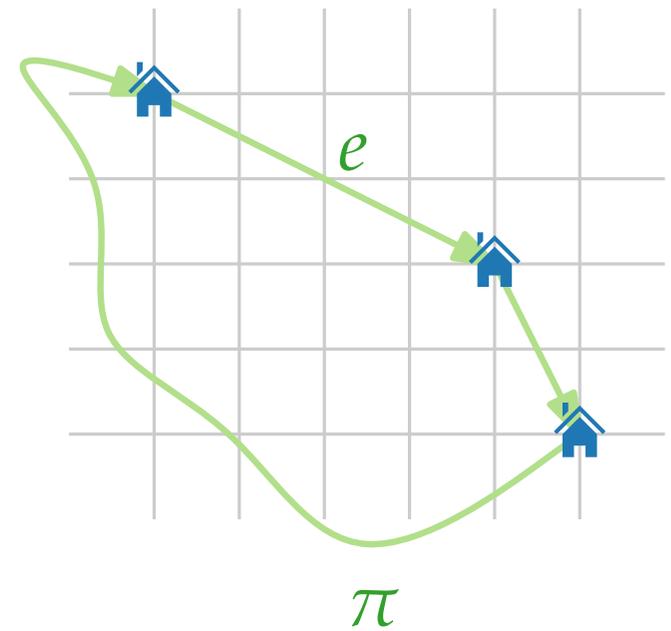
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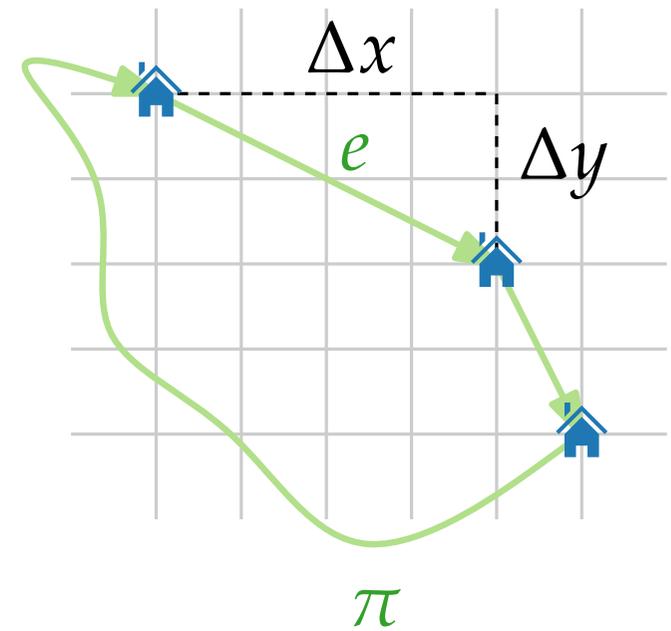
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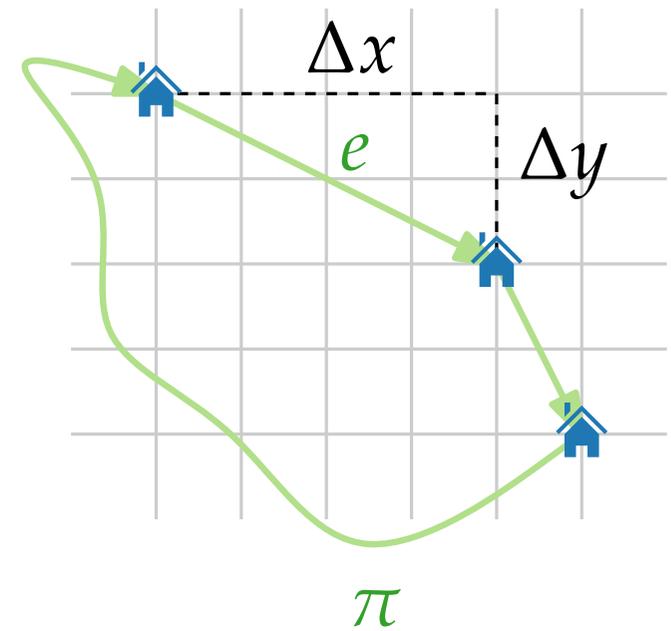


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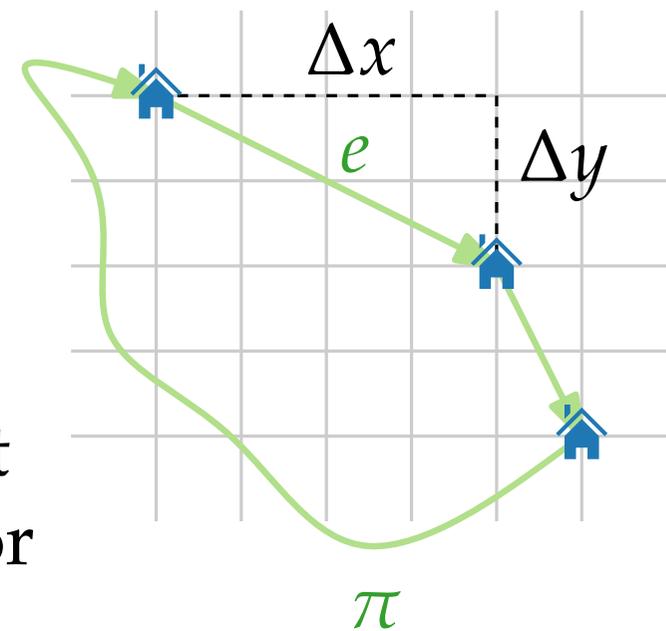


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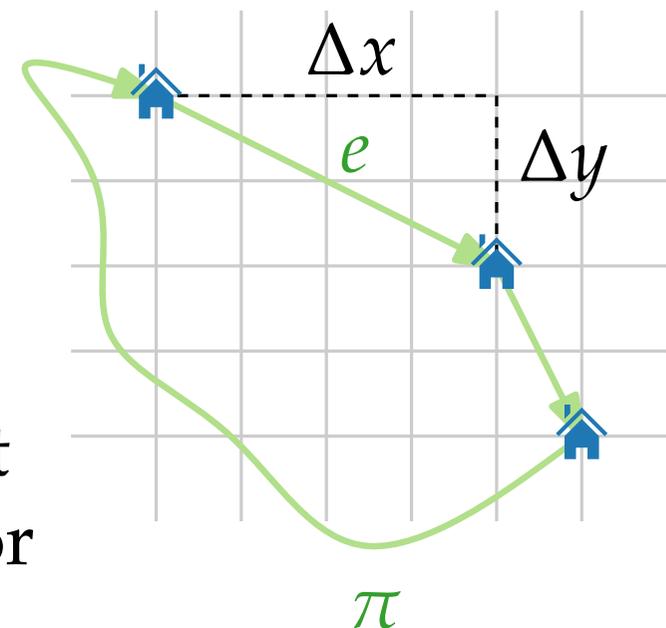


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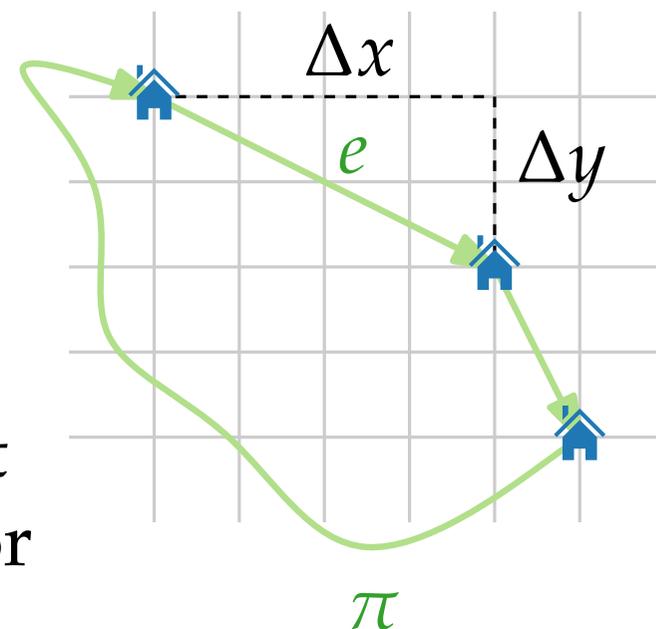


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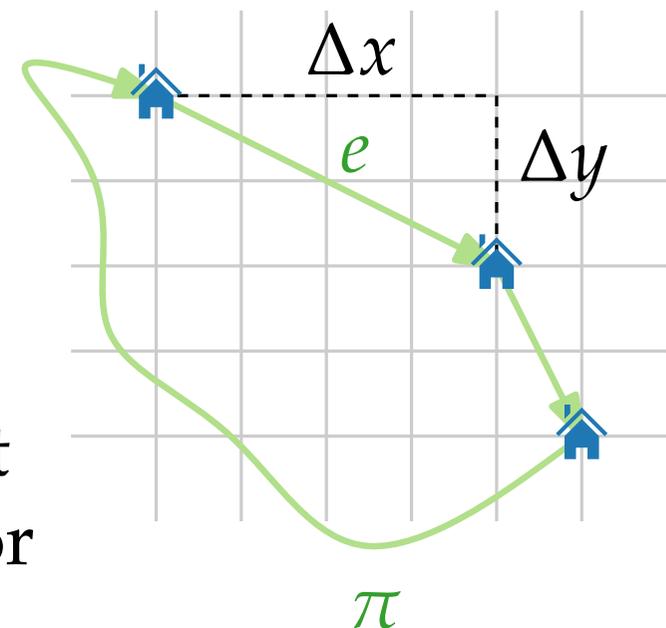


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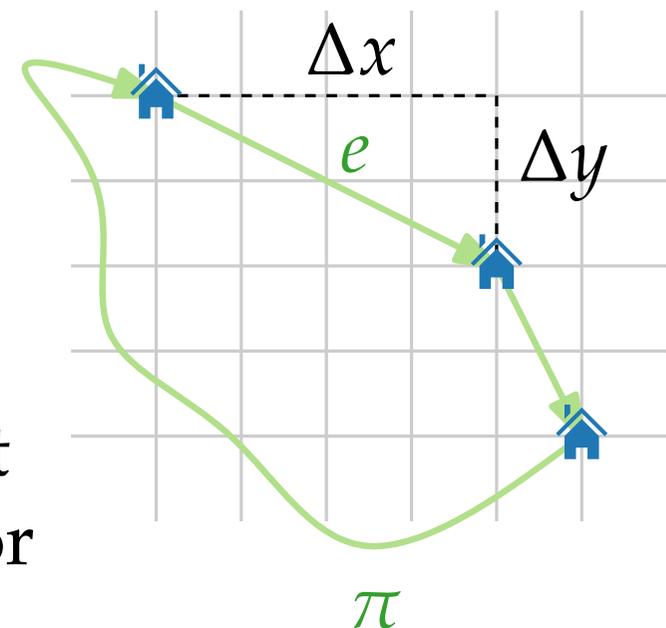


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- $N_e^2 \leq (\Delta x + \Delta y)^2 \leq 2(\Delta x^2 + \Delta y^2) = 2|e|^2$ .
- $N(\pi) = \sum_{e \in \pi} N_e \leq \sum_{e \in \pi} \sqrt{2|e|^2} = \sqrt{2} \cdot \text{OPT}$ .

□

# Approximation Algorithms

## Lecture 9: A PTAS for EUCLIDEAN TSP

### Part VI: Approximation Factor

# Shifted Dissections (III)

**Theorem.** Let  $a, b \in [0, L - 1]$  be chosen independently and uniformly at random.

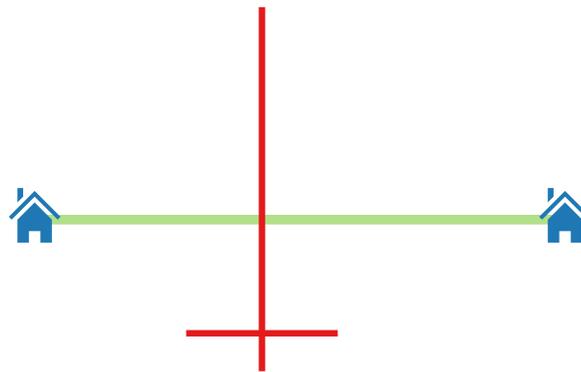
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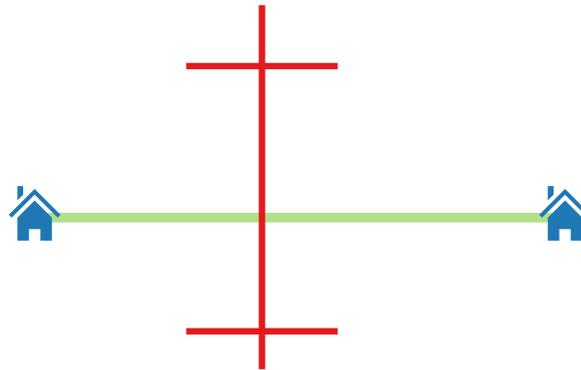
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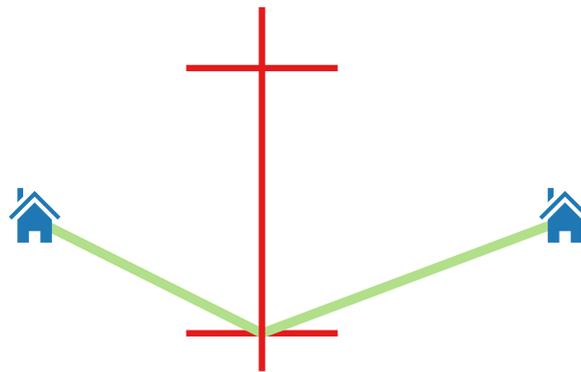
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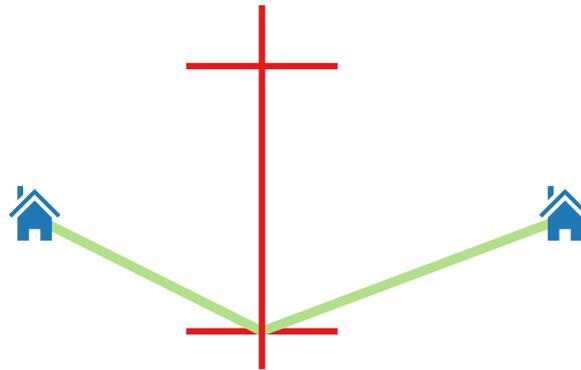
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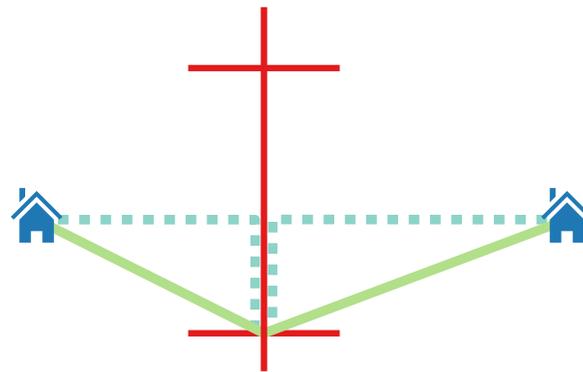


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- Summing over all  $N(\pi) \leq \sqrt{2} \cdot \text{OPT}$  intersection points and applying linearity of expectation yields the claim.

# Polynomial-Time Approximation Scheme

**Theorem.** Let  $a, b \in [0, L - 1]$  be chosen independently and uniformly at random. Then the expected cost of an optimal well-behaved tour with respect to the  $(a, b)$ -shifted dissection is  $\leq (1 + 2\sqrt{2}\varepsilon)\text{OPT}$ .

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# Literature

- William J. Cook: Pursuit of the Traveling Salesman: Mathematics at the Limits of Computation. Princeton University Press, 2011.

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