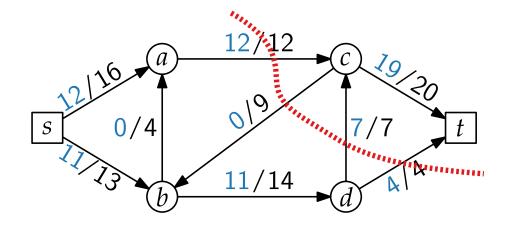


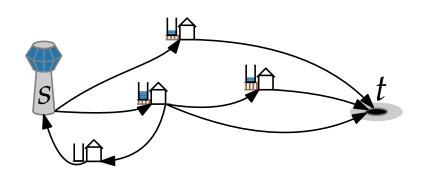
# Advanced Algorithms

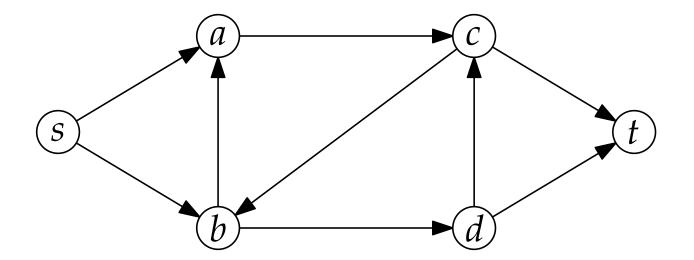
# Maximum flow problem

Push-relabel algorithm

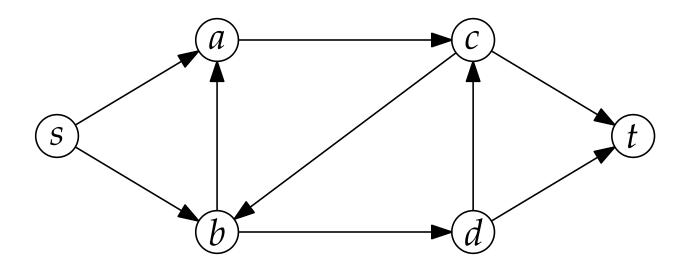
Jonathan Klawitter · WS20





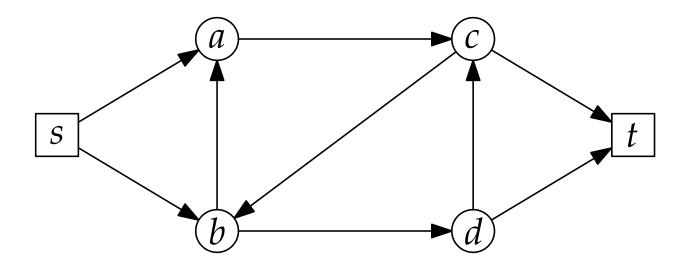


A flow network G = (V, E) is a digraph with



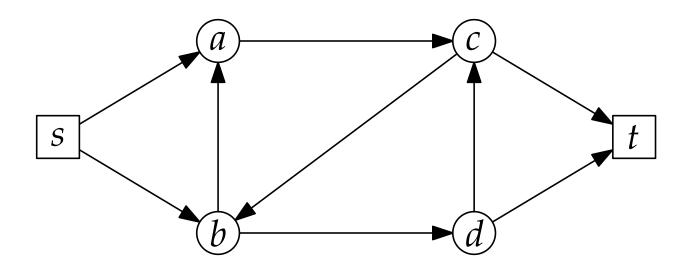
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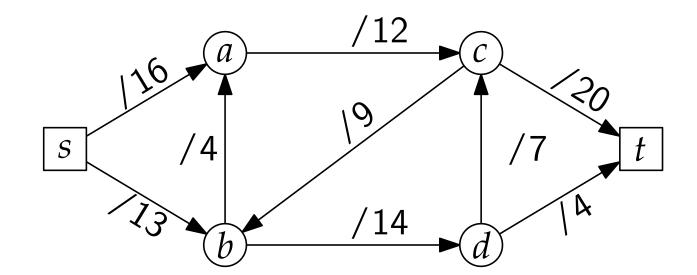
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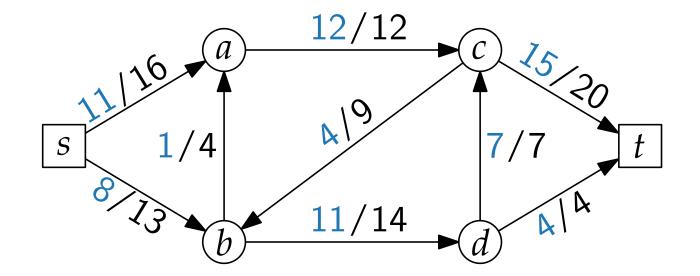


A flow network G = (V, E) is a digraph with

- $\blacksquare$  unique source s and sink t,
- no antiparallel edges, and
- **a capacity**  $c(u, v) \ge 0$  for every  $(u, v) \in E$ .



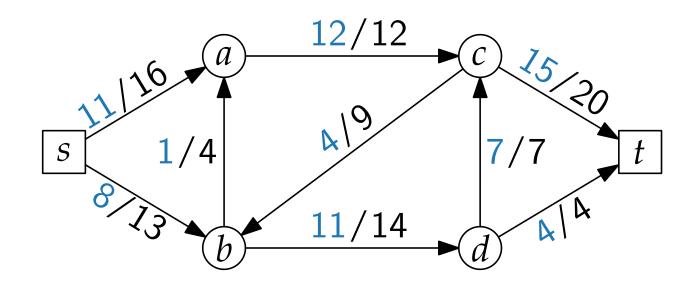
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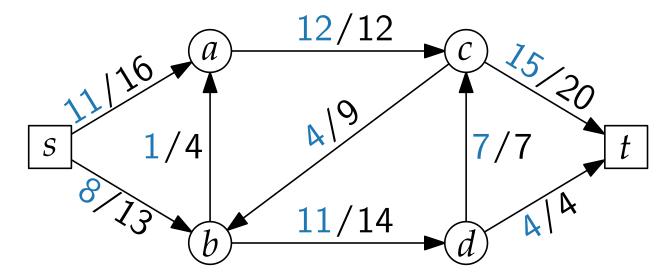


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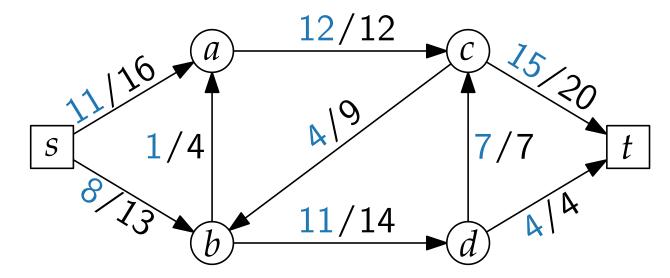


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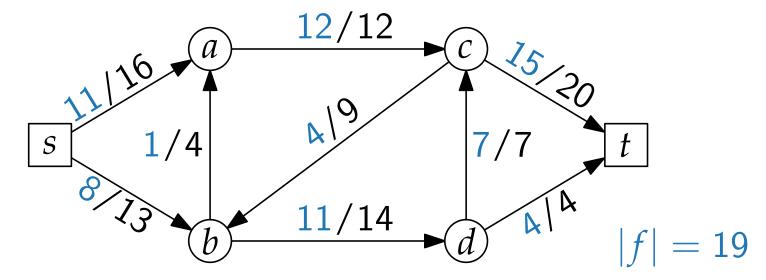
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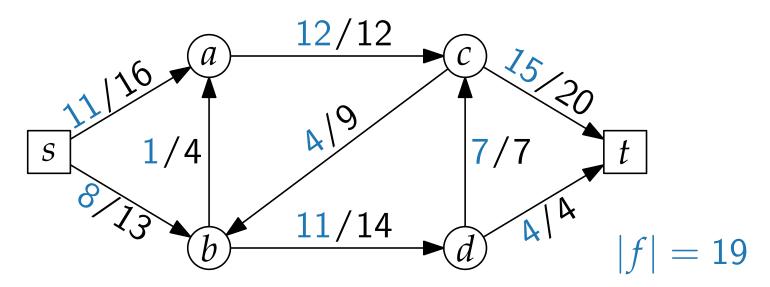
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#### Maximum flow problem.

Given a flow network G with source s and sink t, find a flow of maximum value.

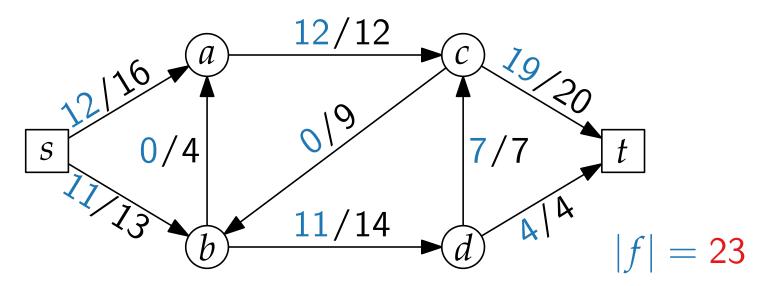
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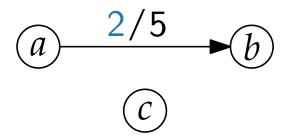


#### Maximum flow problem.

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$$|f| = \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s).$$

How much may flow change?



### How much may flow change?

Given G and f, the **residual capacity**  $c_f$  for a pair  $u, v \in V$  is

$$c_f(u,v) = \begin{cases} c(u,v) - f(u,v) & \text{if } (u,v) \in E \\ f(v,u) & \text{if } (v,u) \in E \\ 0 & \text{otherwise.} \end{cases}$$

$$c_f(a,b) = 3$$

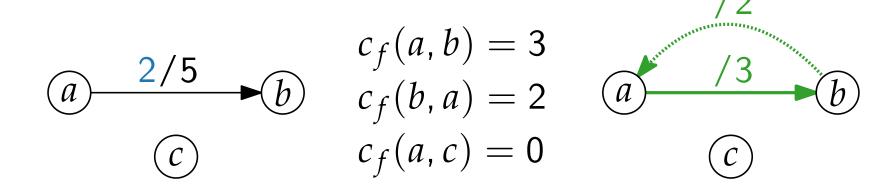
$$c_f(b,a) = 2$$

$$c_f(a,c) = 0$$

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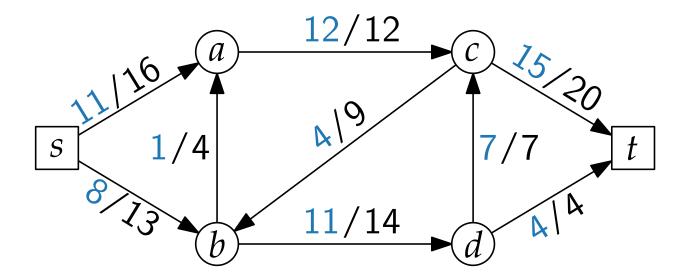
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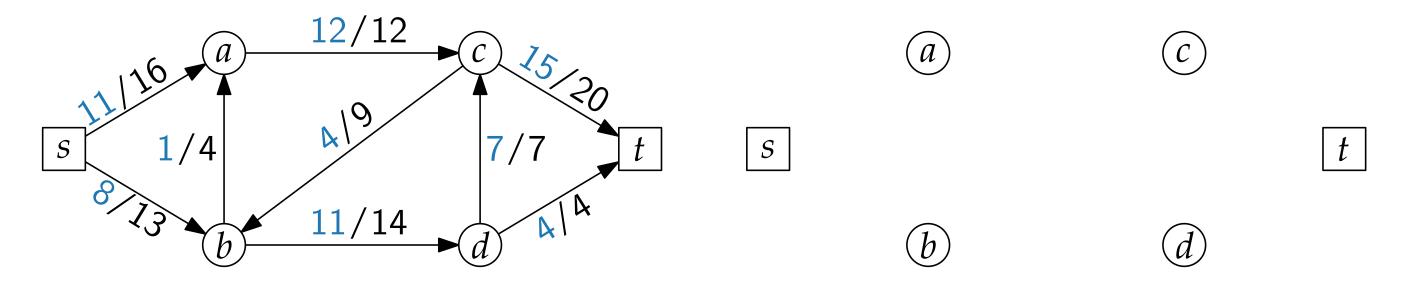
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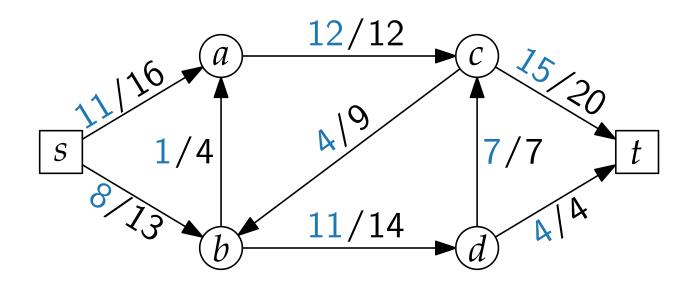
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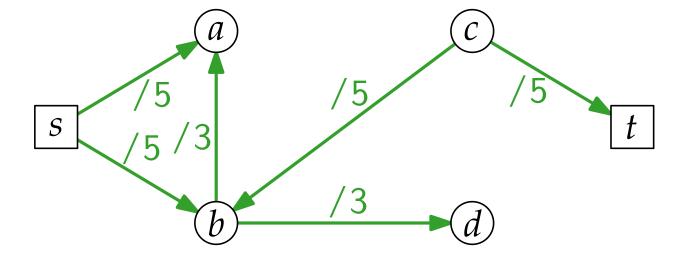
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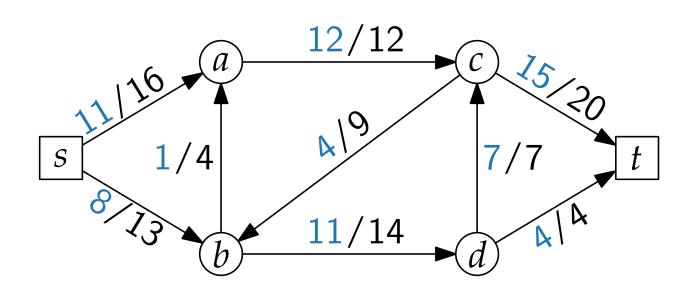




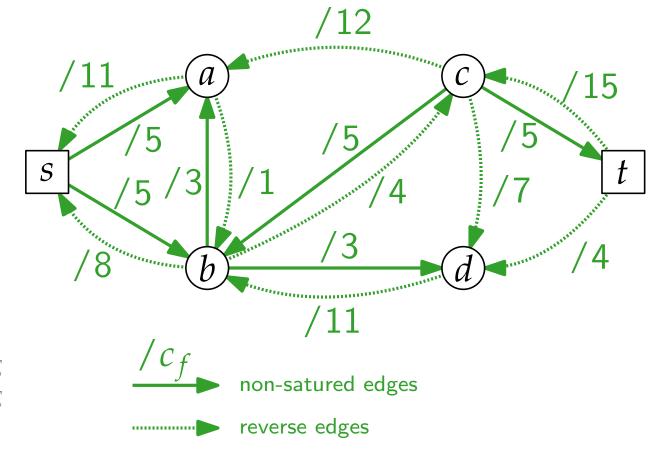
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$$\frac{/c_f}{}$$
 non-satured edges

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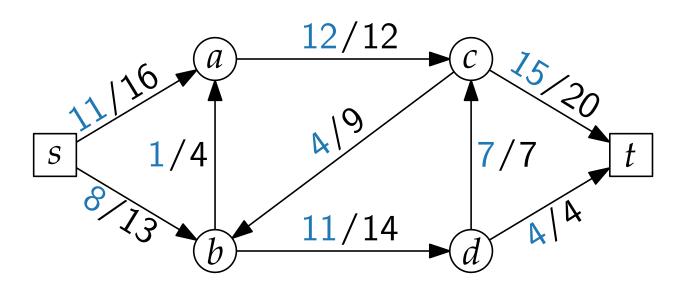
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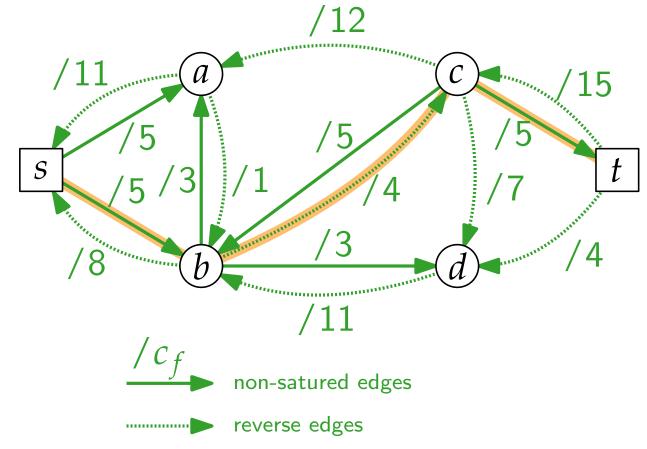
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An augmenting path is an st-path in  $G_f$ .



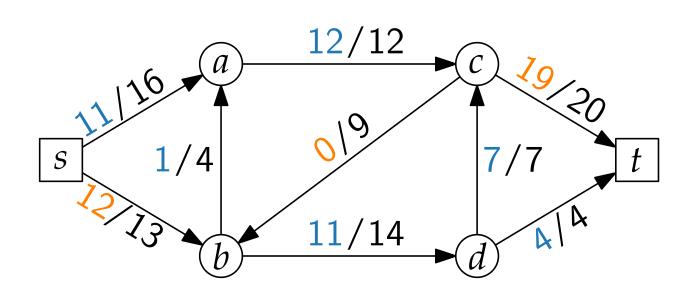
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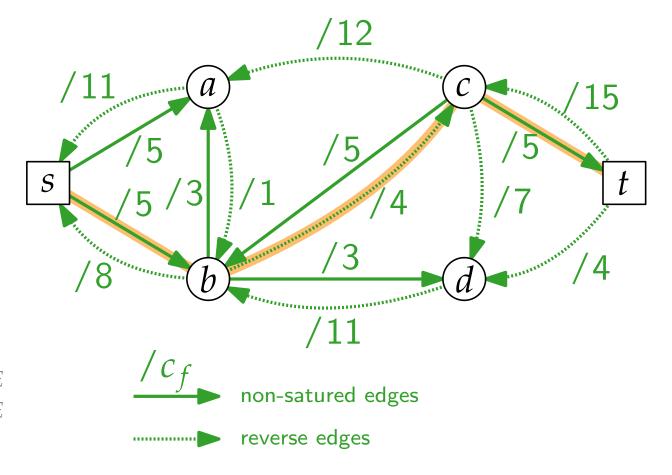
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An augmenting path is an st-path in  $G_f$ .  $\Rightarrow$  use to increase f



$$c_f(u,v) = \begin{cases} c(u,v) - f(u,v) & \text{if } (u,v) \in E \\ f(v,u) & \text{if } (v,u) \in E \\ 0 & \text{otherwise.} \end{cases}$$



## Ford-Folkerson and Edmons-Karp algorithms

```
FordFulkerson(G = (V, E), c, s, t)
 foreach uv \in E do
                               } initialising zero flow
  | f_{uv} \leftarrow 0
 while G_f contains augmenting path p do
    \Delta \leftarrow \min_{uv \in p} c_f(uv) } residucal capacity of p
    foreach uv \in p do
       if uv \in E then
     return f
                                 return max flow
```

## Ford-Folkerson and Edmons-Karp algorithms

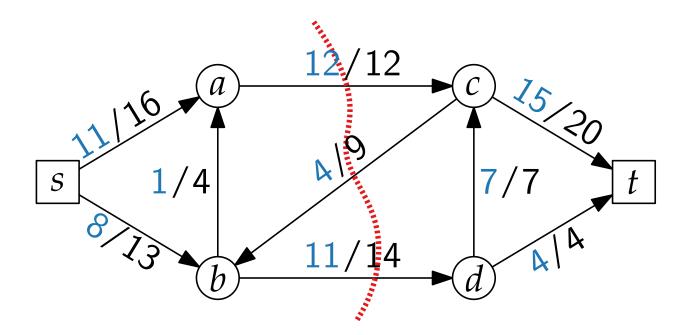
```
EdmondsKarp
FordFulkerson(G = (V, E), c, s, t)
  foreach uv \in E do uv \leftarrow 0
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      foreach uv \in p do
         if uv \in E then
      | f_{uv} \leftarrow f_{uv} + \Delta
else
| f_{vu} \leftarrow f_{vu} - \Delta
                                       \rangle augmentation along p
```

## Ford-Folkerson and Edmons-Karp algorithms

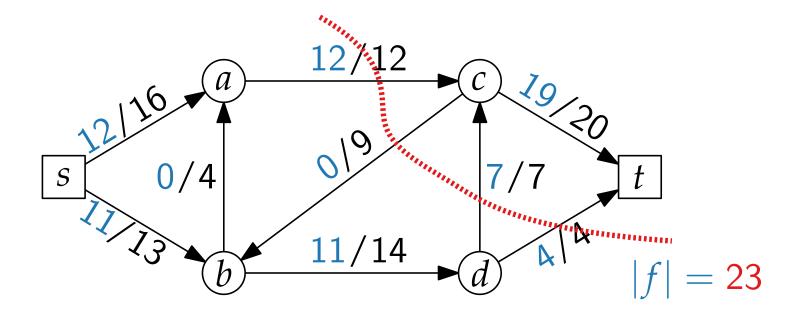
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FordFulkerson(G = (V, E), c, s, t)
 \Delta \leftarrow \min_{uv \in p} c_f(uv) } residucal capacity of p
   foreach uv \in p do
   return f
                       return max flow
```

Ford-Folkerson runs in  $\mathcal{O}(|E||f^*|)$  and Edmons-Karp in  $\mathcal{O}(|V||E|^2)$  time.

# Max-flow min-cut theorem



# Max-flow min-cut theorem

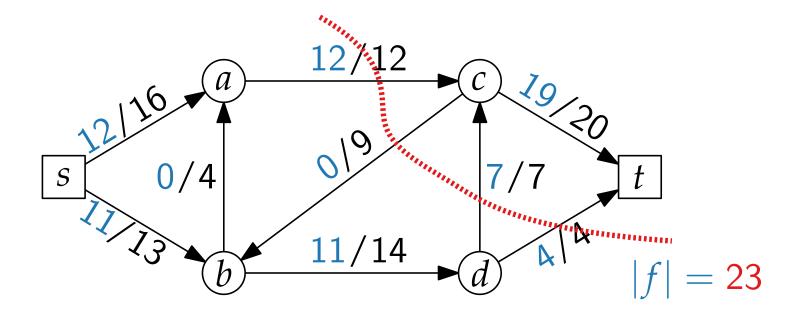


## Max-flow min-cut theorem

#### Theorem.

For a flow f in a flow network G, the following conditions are equivalent:

- f is a maximum flow in G.
- lacksquare  $G_f$  contains no augmenting paths.
- |f| = c(S, T) for some cut (S, T) of G.



#### A New Approach to the Maximum-Flow Problem

ANDREW V. GOLDBERG

Massachusetts Institute of Technology, Cambridge, Massachusetts

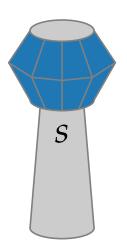
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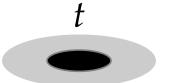
ROBERT E. TARJAN

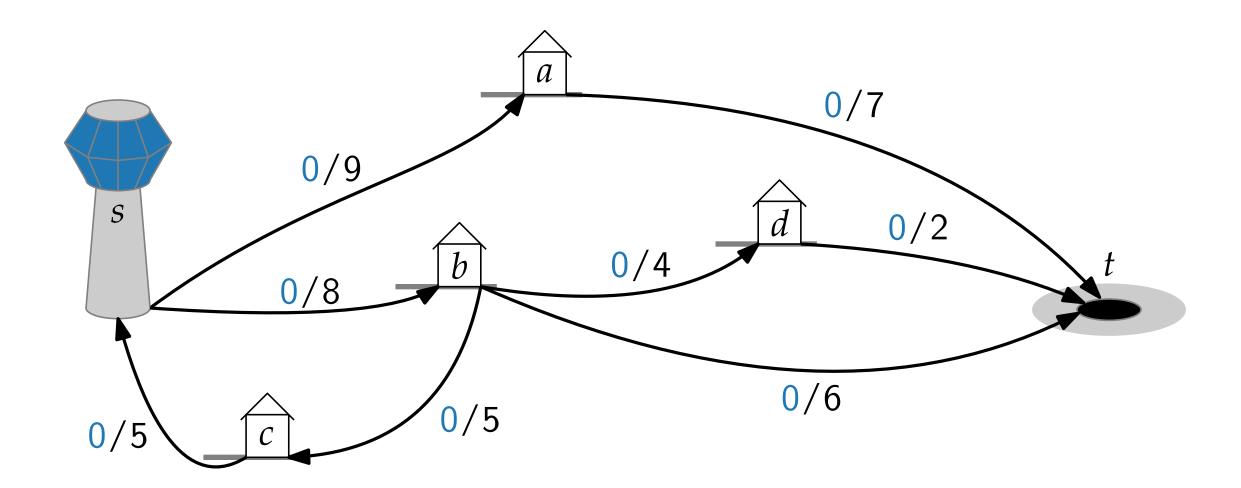
Princeton University, Princeton, New Jersey, and AT&T Bell Laboratories, Murray Hill, New Jersey

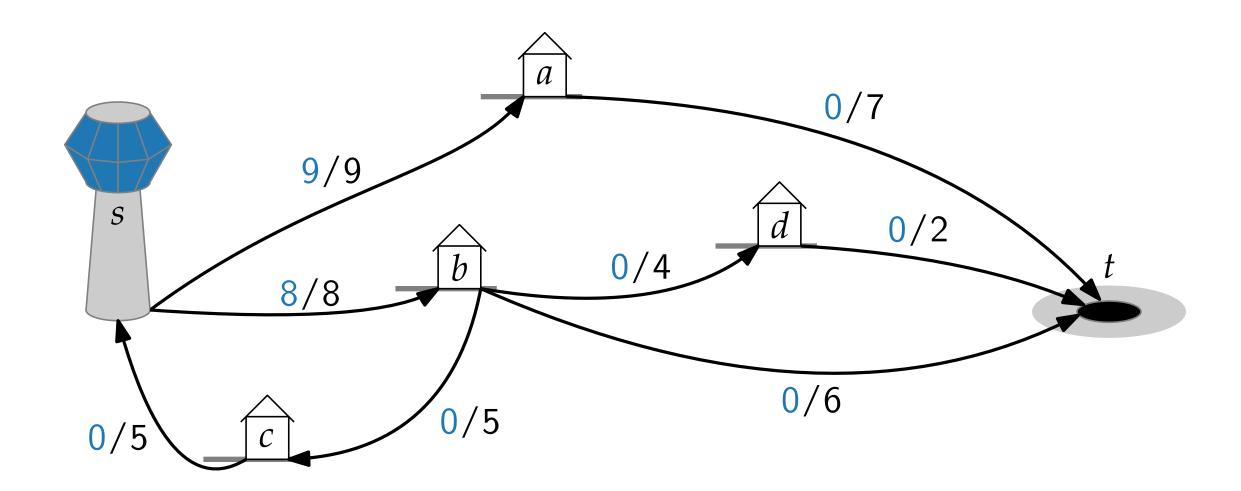
Abstract. All previously known efficient maximum-flow algorithms work by finding augmenting paths, either one path at a time (as in the original Ford and Fulkerson algorithm) or all shortest-length augmenting paths at once (using the layered network approach of Dinic). An alternative method based on the *preflow* concept of Karzanov is introduced. A preflow is like a flow, except that the total amount

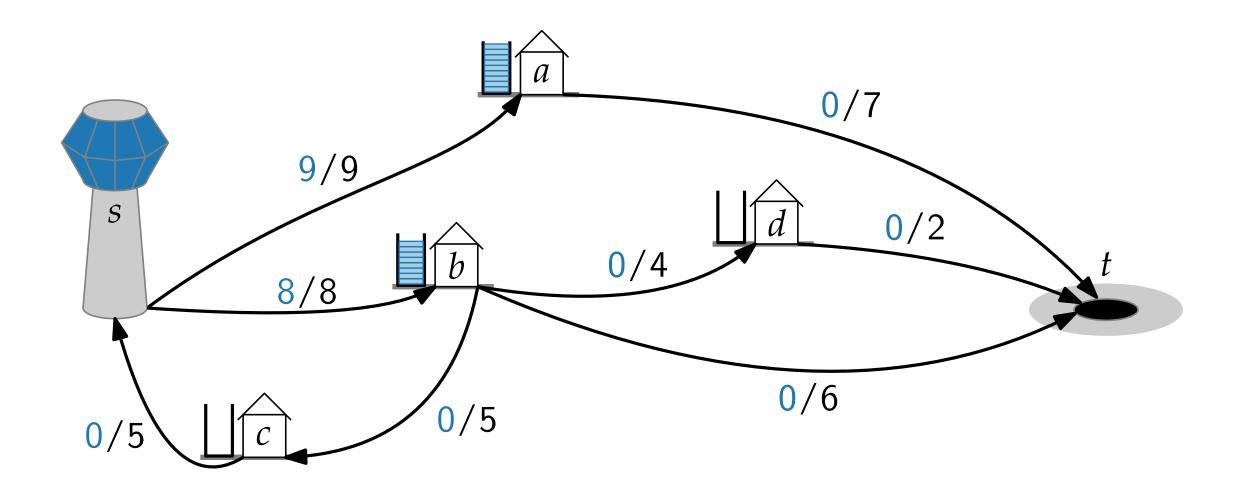
for the next phase. Our algorithm abandons the idea of finding a flow in each phase and also abandons the idea of global phases. Instead, our algorithm maintains a preflow in the original network and pushes local flow excess toward the sink along what it estimates to be shortest paths in the residual graph. This pushing of flow changes the residual graph, and paths to the sink may become saturated. Excess that cannot be moved to the sink is returned to the source, also along estimated shortest paths. Only when the algorithm terminates does the preflow become a flow, and then it is a maximum flow.

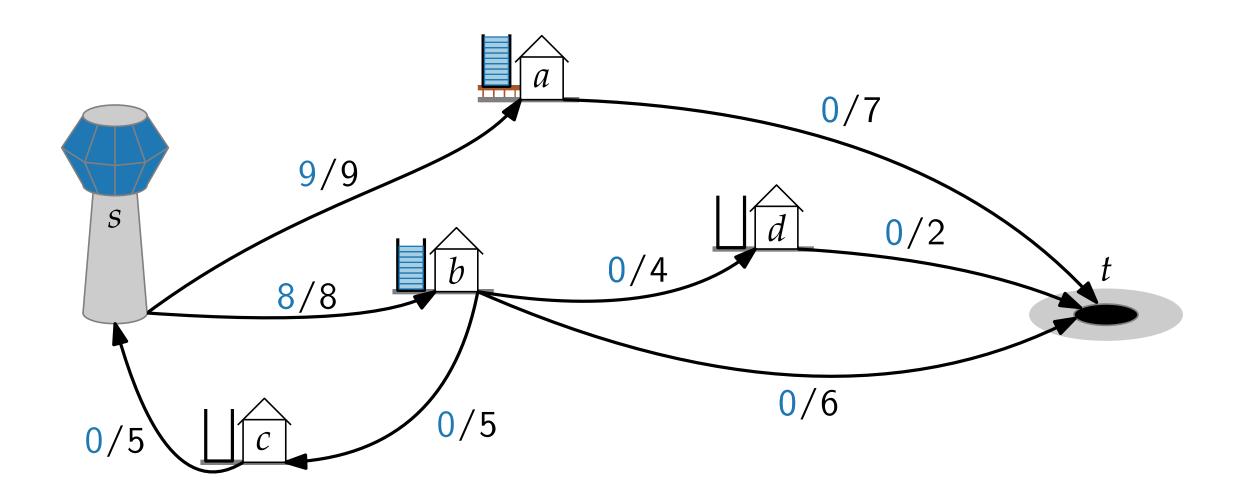


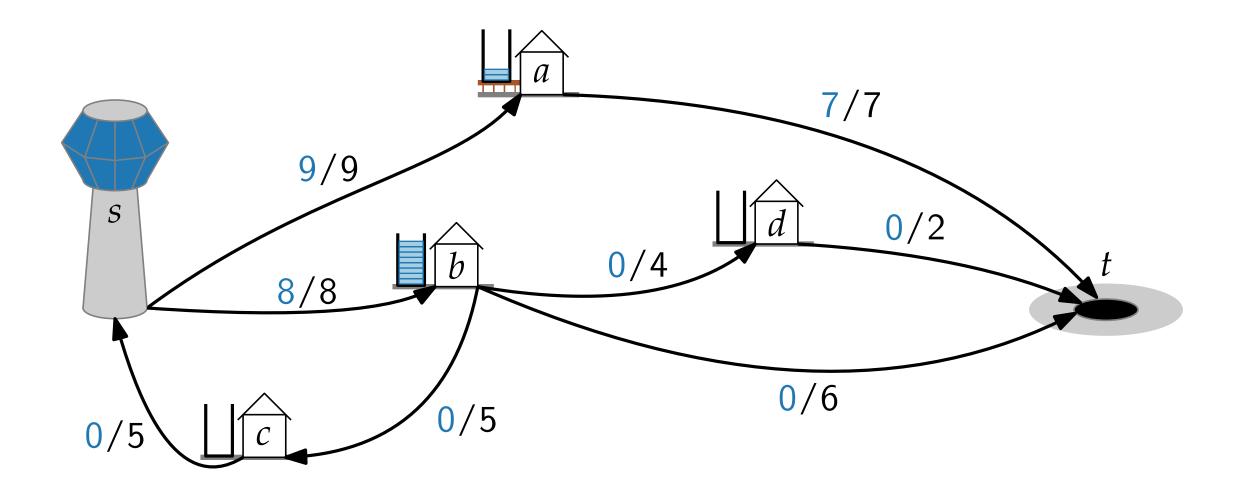


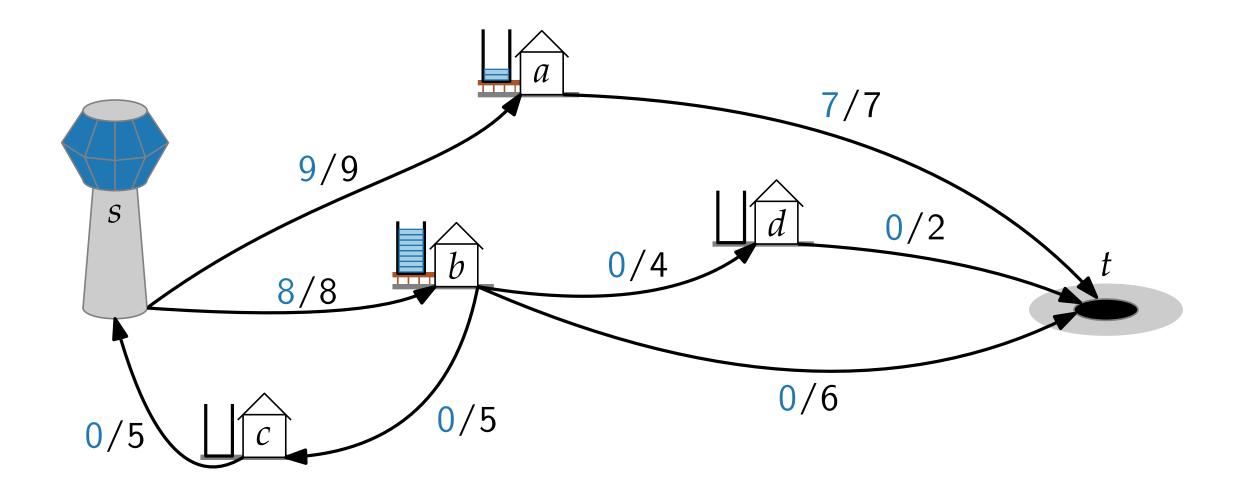


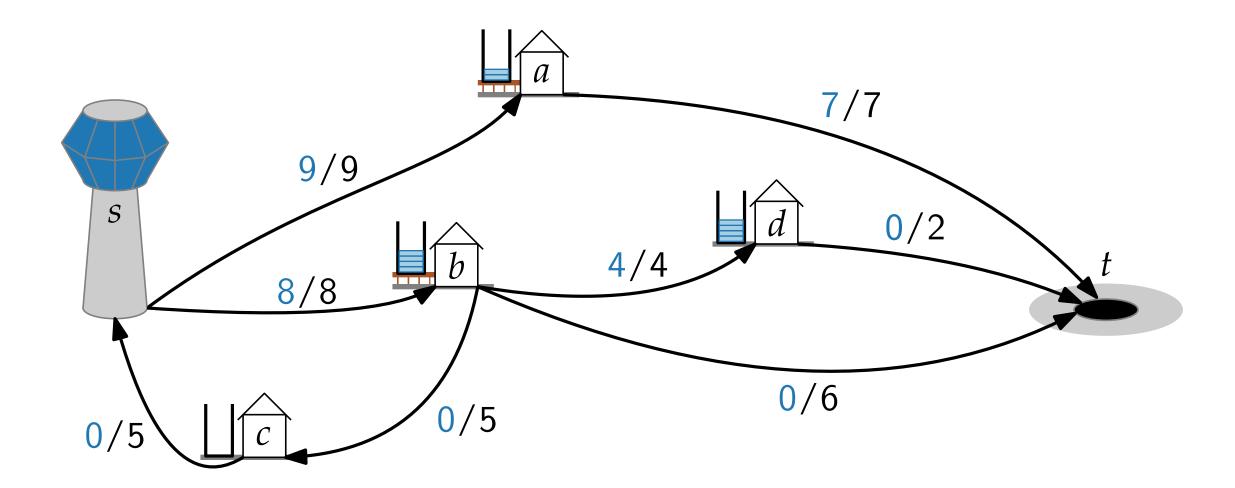


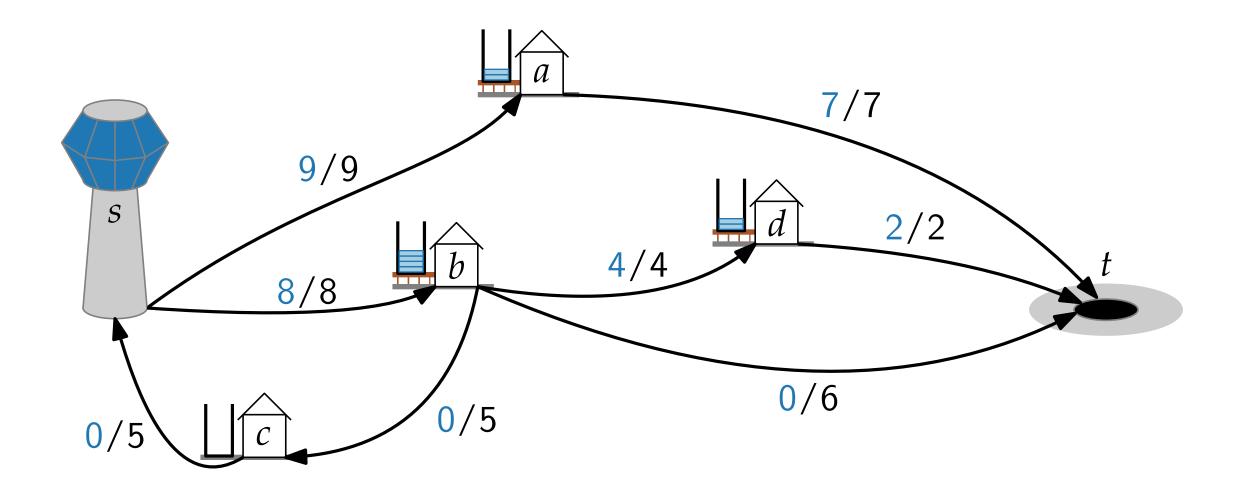


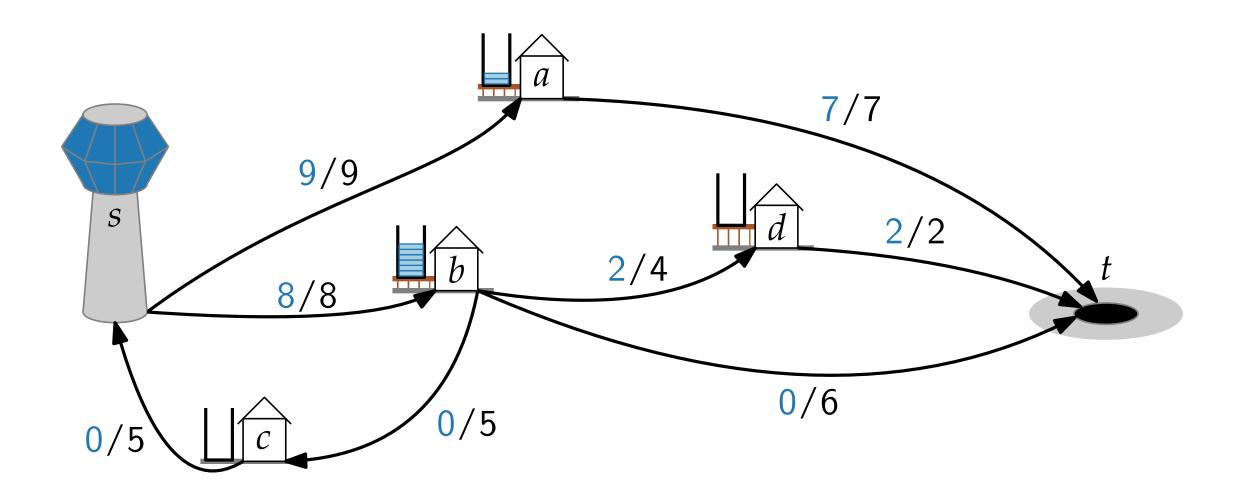


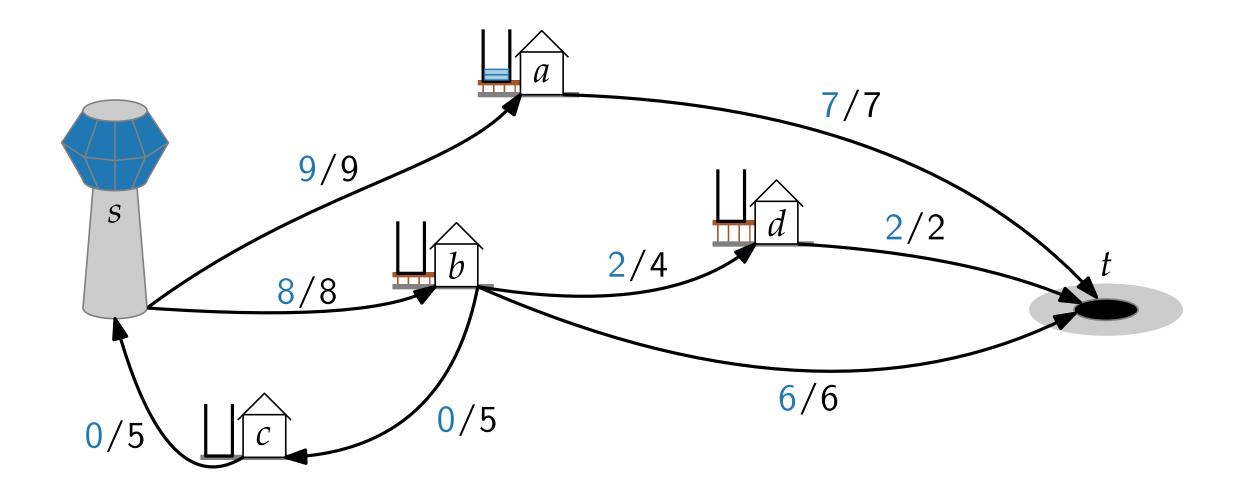


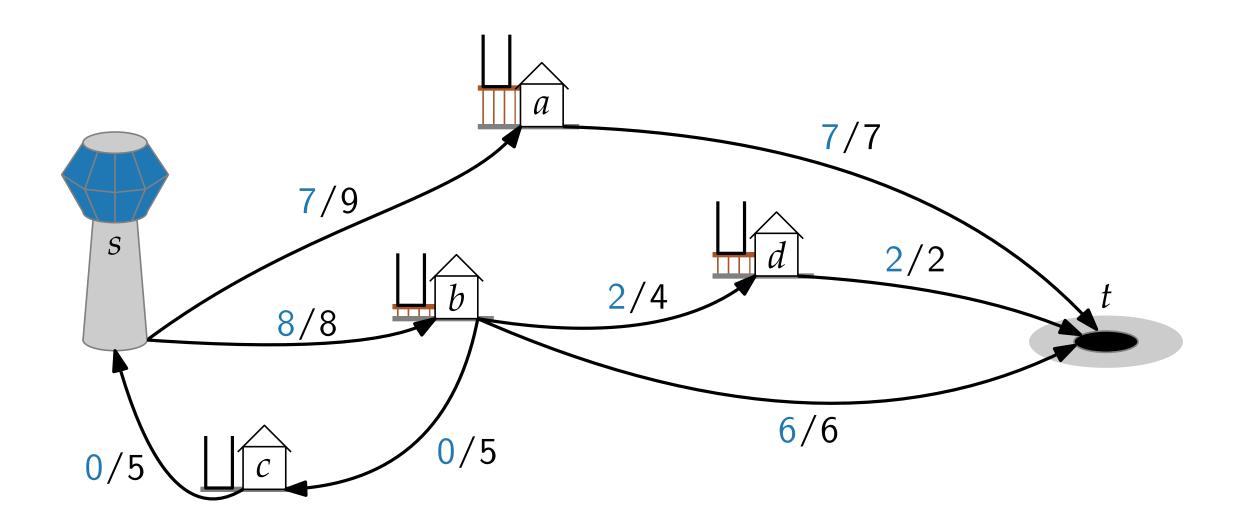






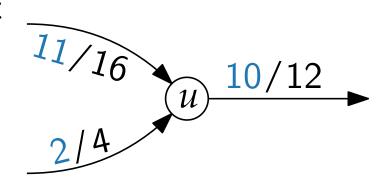






A **preflow** in G is a real-value function  $f: V \times V \to \mathbb{R}$  that satisfies the capacity constraint and, for all  $u \in V \setminus \{s\}$ ,

$$\sum_{v \in V} f(v, u) - \sum_{v \in V} f(u, v) \ge 0.$$

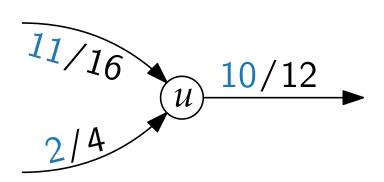


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The excess flow of a vertex u is

$$e(u) = \sum_{v \in V} f(v, u) - \sum_{v \in V} f(u, v).$$



$$e(u) = 3$$

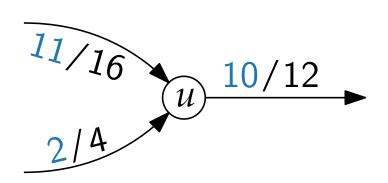
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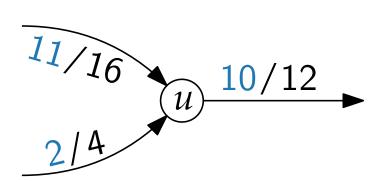
A vertex u is called **overflowing**, when e(u) > 0.



$$e(u) = 3$$

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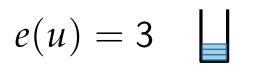
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A vertex u is called **overflowing**, when e(u) > 0.

For a flow network G with preflow f, a **height function** is a function  $h: V \to \mathbb{N}$  such that

- $\blacksquare h(s) = |V|,$
- h(t) = 0, and
- $h(u) \le h(v) + 1$  for every residual edge  $(u, v) \in E_f$ .





Push(u, v)

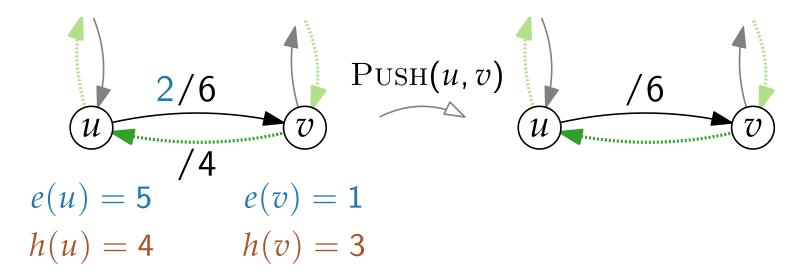
**Condition:** u is overflowing,  $c_f(u,v) > 0$ , and h(u) = h(v) + 1

**Effect:** Push  $min(e(u), c_f(u, v))$  overflow from u to v

Push(u, v)

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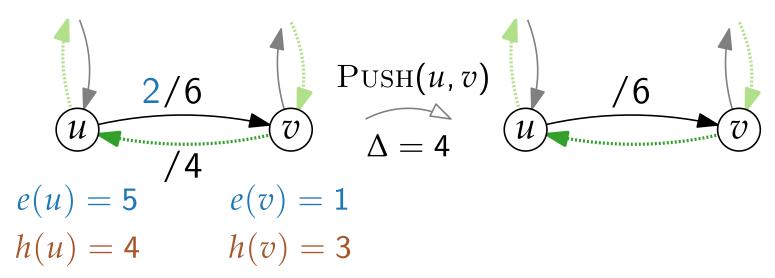


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 $\Delta \leftarrow \min(e(u), c_f(u, v))$ 



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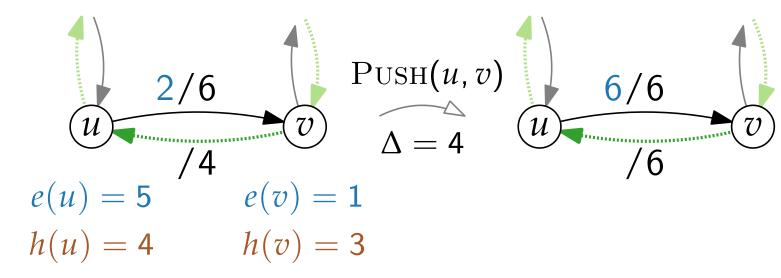
$$\Delta \leftarrow \min(e(u), c_f(u, v))$$

if 
$$(u, v) \in E$$
 then

$$f(u.v) \leftarrow f(u,v) + \Delta$$

### else

$$f(v.u) \leftarrow f(v,u) - \Delta$$



Push(u, v)

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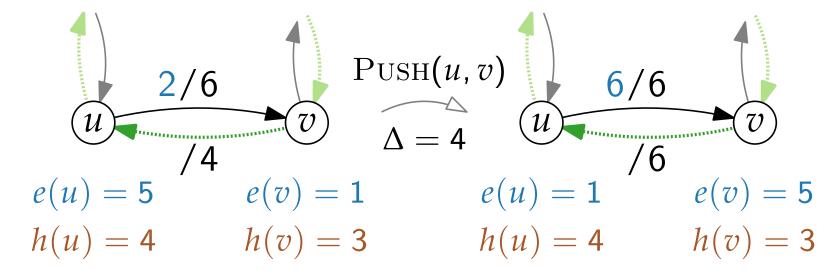
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### else

$$f(v.u) \leftarrow f(v,u) - \Delta$$

$$e(u) \leftarrow e(u) - \Delta$$

$$e(v) \leftarrow e(v) + \Delta$$



## Relabel operation

```
Relabel(u)

Condition: u is overflowing and h(u) \le h(v) for all v \in V with (u, v) \in E_f

Effect: Increase the height of u
h(u) \leftarrow 1 + \min\{h(v) : (u, v) \in E_f\}
```

## Relabel operation

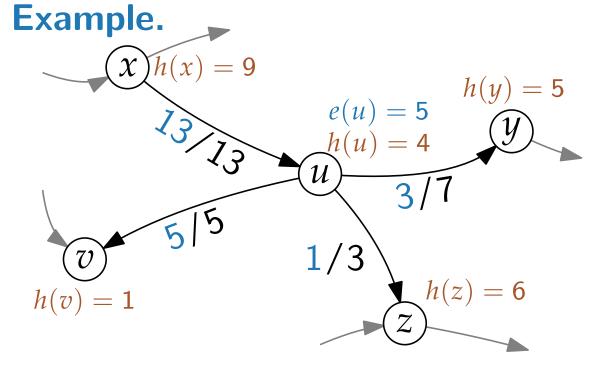
Relabel(u)

Condition: u is overflowing and

 $h(u) \leq h(v)$  for all  $v \in V$  with  $(u, v) \in E_f$ 

**Effect:** Increase the height of *u* 

$$h(u) \leftarrow 1 + \min\{h(v) : (u, v) \in E_f\}$$



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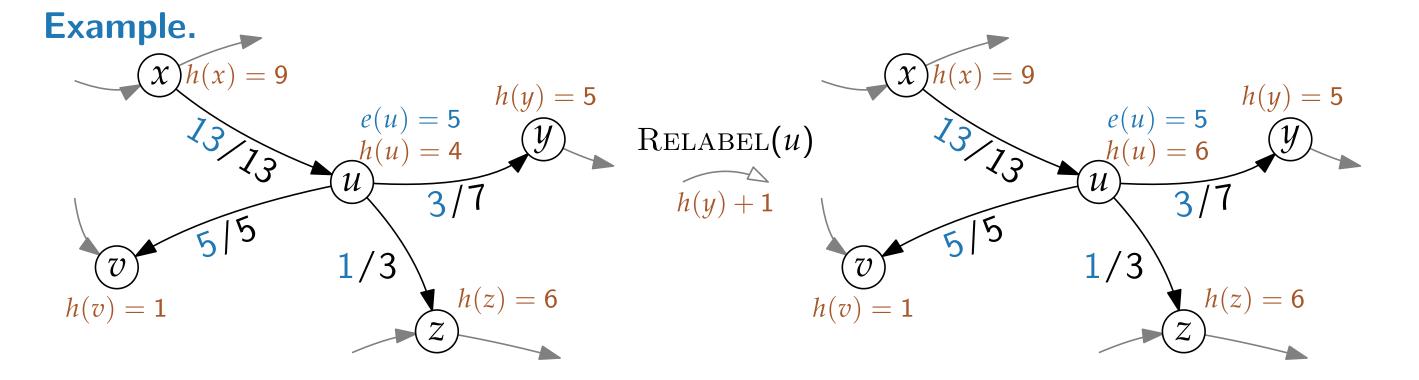
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# Push-Relabel algorithm

```
Push-Relabel(G)
InitPreflow(G, s)
while there exists an applicable
Push or Relabel operation x do
apply x
```

## PUSH-RELABEL algorithm

Push-Relabel(G)
InitPreflow(G, s)
while there exists an applicable
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## InitPreflow(G, s)

$$h(v) \leftarrow 0, e(v) \leftarrow 0 \quad \forall v \in V$$
  
 $h(s) \leftarrow |V|$   
 $f(u, v) \leftarrow 0 \quad \forall (u, v) \in E$   
**for** each  $v$  adjacent to  $s$  **do**  
 $|f(s, v) \leftarrow c(s, v)|$   
 $e(v) \leftarrow c(s, v)$ 

## PUSH-RELABEL algorithm

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INITPREFLOW (G, s)

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- initialises heights
- pushes max flow over all outgoing edges of s

## Correctness

### Part 1.

If the algorithm terminates, the preflow is maximum flow.

- If an overflowing vertex exists, the algorithm can continue.
- The algorithm maintains f as a preflow and h as a height function.
- Sink t is not reachable from source s in  $G_f$ .

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- The algorithm maintains f as a preflow and h as a height function.
- Sink t is not reachable from source s in  $G_f$ .

### Part 2.

The algorithm terminates and the heights stay finite.

- Find upper bound on heights.
- Find upper bound for calls of Relabel.
- Find upper bound for calls of Push.

### Lemma 1.

If a vertex u is overflowing, either a push or a relabel operation applies to u.

#### **Height function:**

- h(s) = |V|,
- h(t) = 0, and
- $h(u) \le h(v) + 1$  for every residual edge  $(u, v) \in E_f$ .

### Push(u,v)

Condition: 
$$u$$
 is overflowing,  $c_f(u,v) > 0$ , and  $h(u) = h(v) + 1$   $\Delta \leftarrow \min(e(u), c_f(u,v))$  if  $(u,v) \in E$  then  $| f(u.v) \leftarrow f(u,v) + \Delta$  else  $| f(v.u) \leftarrow f(v,u) + \Delta$   $e(u) \leftarrow e(u) - \Delta$   $e(v) \leftarrow e(v) + \Delta$ 

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Assuming h(u) is valid, we have

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Therefore, Relabel(u) is applicable.

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### Lemma 2.

The push-relabel algorithm maintains a preflow f.

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# Maintaining the preflow

### Lemma 2.

The push-relabel algorithm maintains a preflow f.

### Proof.

- INITPREFLOW initialises a preflow f.  $\checkmark$
- $\blacksquare$  Relabel(u) doesn't affect f.  $\checkmark$
- ightharpoonup Push(u, v) maintains f as a preflow.  $\checkmark$

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  - If (u, v) removed from  $E_f$ , then  $\checkmark$ .
- $\blacksquare$  Relabel(u) leaves h a height function.  $\checkmark$ 
  - $(u,v) \in E_f$ , then  $h(u) \le h(v) + 1$
  - $(w, u) \in E_f$ , then h(w) < h(u) + 1

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# Reachability of the sink

## Lemma 4.

During the push-relabel algorithm, there is no path from s to t in  $G_f$ .

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During the push-relabel algorithm, there is no path from s to t in  $G_f$ .

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Suppose there is a path  $s=v_0,v_1,\ldots,v_k=t$  in  $G_f$ . Then

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But then and since  $k \leq |V| - 1$ , follows h(s) < |V|.

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  - $\Rightarrow$  By the Max-Flow Min-Cut Theorem, the flow f is a maximum flow.

# Correctness

# Part 1. $\checkmark$

If the algorithm terminates, the preflow is maximum flow.

- If an overflowing exists, the algorithm can continue.
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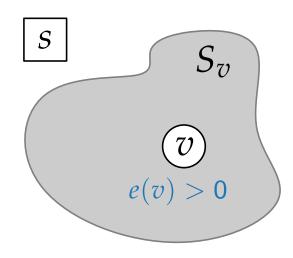
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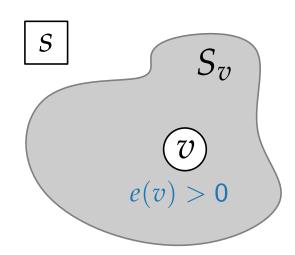


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- Since f a preflow and  $s \notin S_v$ , we have  $\sum e(w) \ge 0$ .

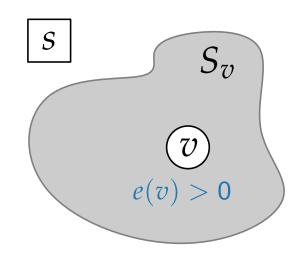
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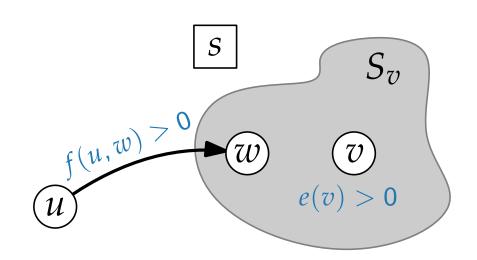
- $\blacksquare$   $S_v \leftarrow$  vertices reachable from v in  $G_f$ .
- Suppose  $v \notin S_v$ .
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- Since  $v \in S_v$ , we even have  $\sum_{w \in S_v} e(w) > 0$ .



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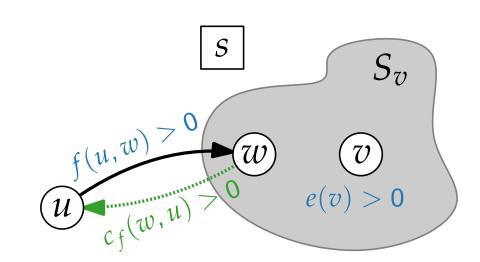
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- There is edge (u, w) with  $u \notin S_v$ ,  $w \in S_v$  and f(u, w) > 0.
- But then  $c_f(w, u) > 0$ , meaning u is reachable from v. X



# Lemma 7.

During the push-relable algorithm, we have  $h(v) \leq 2|V|-1$  for all  $v \in V$ .

#### **Height function:**

- h(s) = |V|,
- h(t) = 0, and
- $h(u) \le h(v) + 1$  for every residual edge  $(u, v) \in E_f$ .

#### Relabel(u)

**Condition:** u is overflowing,  $h(u) \le h(v) \ \forall v \in V$  with  $(u, v) \in E_f$   $h(u) \leftarrow 1 + \min\{h(v) : (u, v) \in E_f\}$ 

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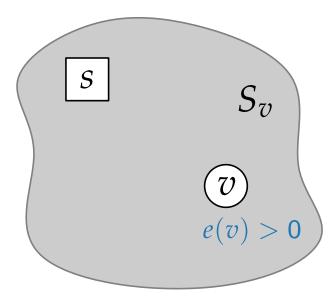
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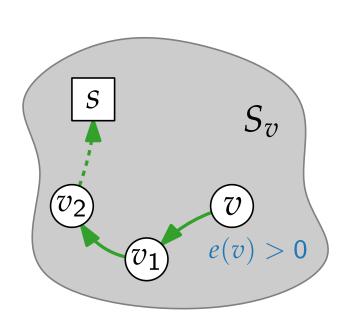
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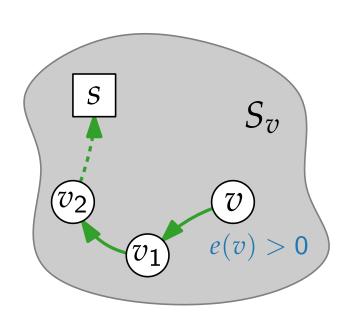
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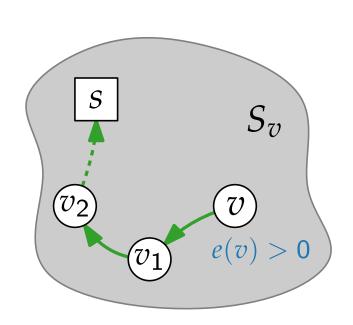
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# Upper bound on height and Relabel operations

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- Since  $k \le |V| 1$ , we have  $h(v) \le h(s) + k \le 2|V| 1$ .

# Corollary 8.

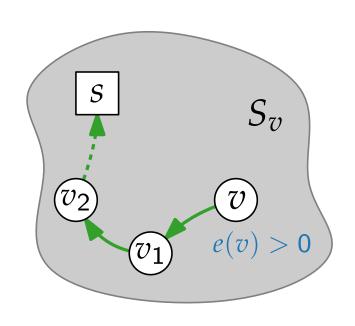
The push-relable algorithm executes at most  $2|V|^2$  Relabel operations.

#### **Height function**:

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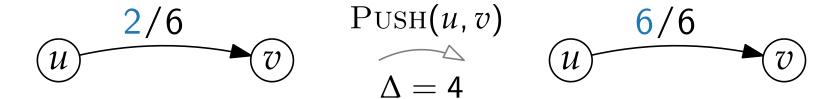
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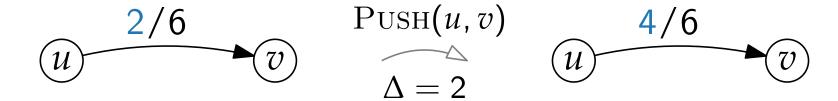
# Saturating and unsaturating Push operations

The operation Push(u, v) is

**saturating**, if afterwards  $c_f(u, v) = 0$ ,



and unsaturating otherwise.



# Lemma 9.

The push-relable algorithm executes at most 2|V||E| saturating Push operations.

```
Push(u, v)

Condition: u is overflowing, c_f(u, v) > 0, and h(u) = h(v) + 1

\Delta \leftarrow \min(e(u), c_f(u, v))

if (u, v) \in E then
| f(u.v) \leftarrow f(u, v) + \Delta
else
| f(v.u) \leftarrow f(v, u) + \Delta
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Push(u, v)...
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- There are at most 2|V|-1 sat. Push operations for edge (u,v).

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Push(u, v)...
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The push-relable algorithm executes at most  $4|V|^2|E|$  unsaturating Push ops.

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Consider 
$$\mathcal{H} = \sum_{\substack{v \in V \setminus \{s,t\}, \\ v \text{ overflowing}}} h(v)$$
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- By Lemma 8, all saturating Push ops. increases  $\mathcal{H}$  by at most  $(2|V|-1)\cdot 2|V||E|$ .

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- An unsaturating Push(u, v) decrease  $\mathcal{H}$  by at least 1, since  $h(u) h(v) \geq 1$ .

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# Termination of the algorithm

### Theorem 5.

If the push-relabel algorithm terminates, the computed preflow f is a maximum flow.

# Theorem 11.

The push-relabel algorithm terminates after  $\mathcal{O}(|V|^2|E|)$  valid Push or Relabel ops.

#### Proof.

Follows by Corollary 8 and Lemma 9+10.

# **Implementation**

The actual running time depends on the selection order of overflowing vertices:

# **■** FIFO implementation:

Pick overflowing vertex by *first-in-first-out* principle:  $\mathcal{O}(|V|^3)$  running time.

with dynamic trees:  $\mathcal{O}(|V||E|\log\frac{|V|^2}{|E|})$ 

# Highest label:

For Push select highest overflowing vertex:  $\mathcal{O}(|V|^2|E|^{\frac{1}{2}})$ 

# Excess scaling:

For Push(u, v) choose edge (u, v) such that u is overflowing, e(u) is sufficiently high and e(v) sufficiently small:  $\mathcal{O}(|E| + |V|^2 \log C)$ , where  $C = \max_{(u,v) \in E} c(u,v)$ 

# Discussion

- The push-relabel method offers an alternative framework to the Ford-Folkerson method to develope algorithms that solve the maximum flow problem.
- Push-relabel algorithms are regarded as benchmarks for maximum flow algorithms.
- In practice, heuristics are used to improve the performance of push-relabel algorithms. Any ideas?
- The algorithm can be extended to solve the minimum cost flow problem.

# Literature

#### Main source:

- [CLRS Ch26] ← Cormen et al. "Introduction to Algorithms"
  Original papers:
- [Goldberg, Tarjan '88] A new approach to the maximum-flow problem Links:
- MaxFlow Ford-Folkerson and Edmonds-Karp animations https://visualgo.net/en/maxflow